

# AVA analysis as an unsupervised machine learning problem

Ben Bougher, October 26th 2016

## Why machine learning?

Machine learning should be applied to a problem when:

- There exists an underlying but unknown relationship between input and output.
- There is no known physical model to describe the relationship, or there are too many unrealistic assumptions and approximations.

Supervised learning:

- Most high profile applications are supervised learning.
- Requires large database of truth data for training.

Unsupervised learning:

- Learn latent relationships directly from the data.

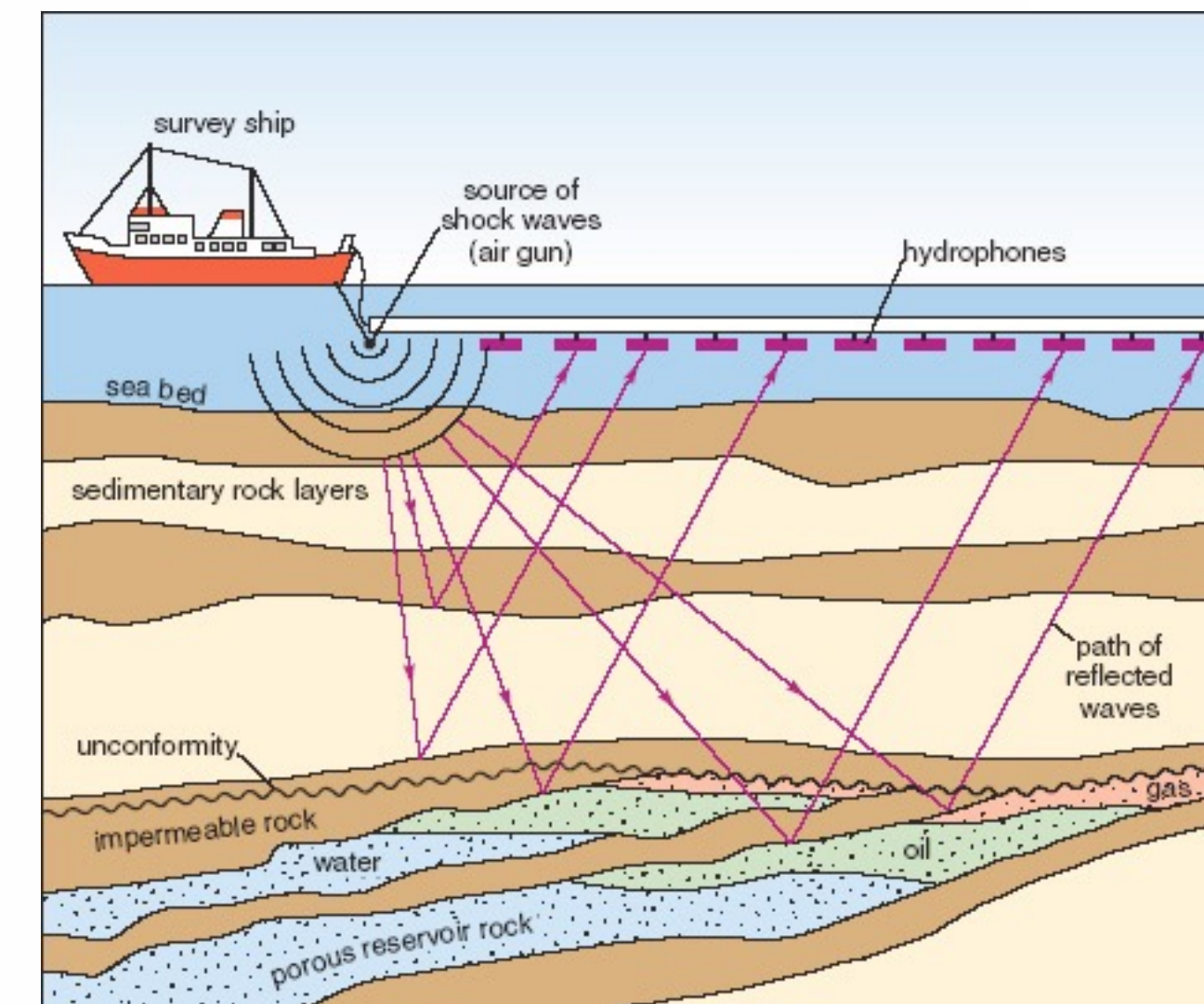
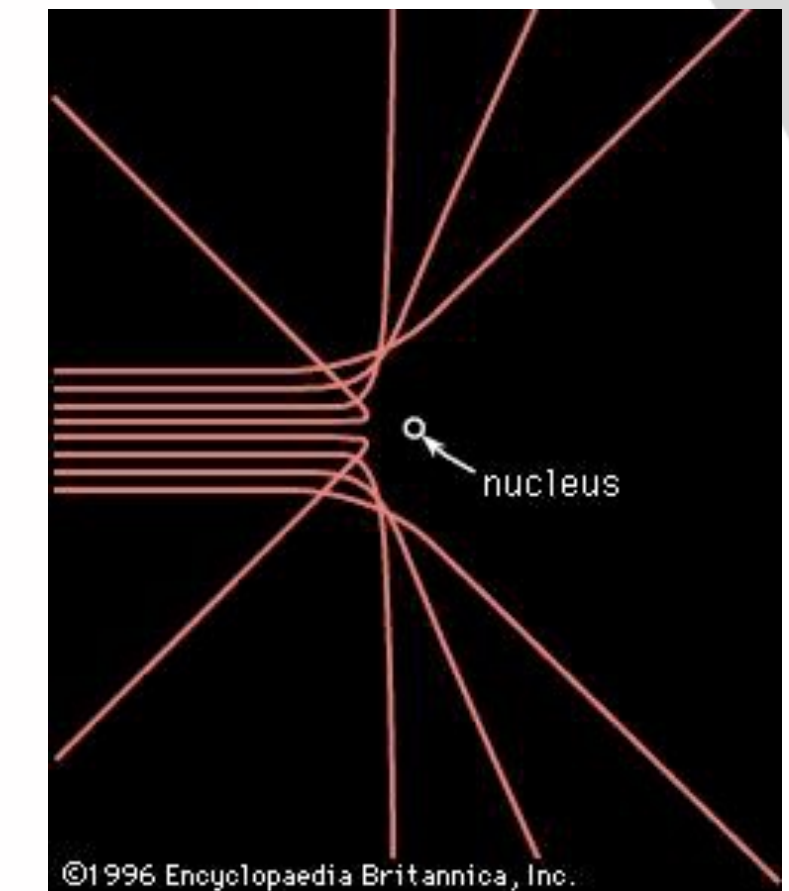
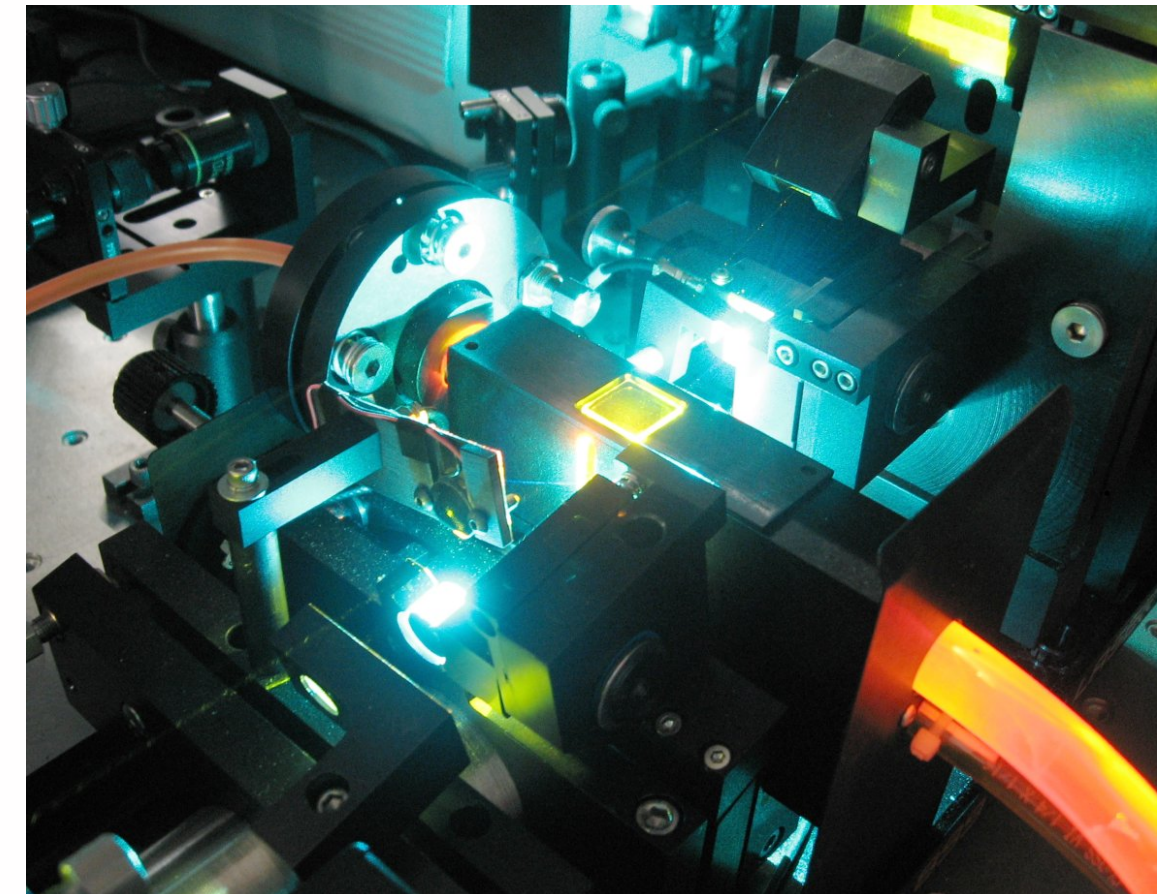
# Scattering physics

Ubiquitous in experimental physics.

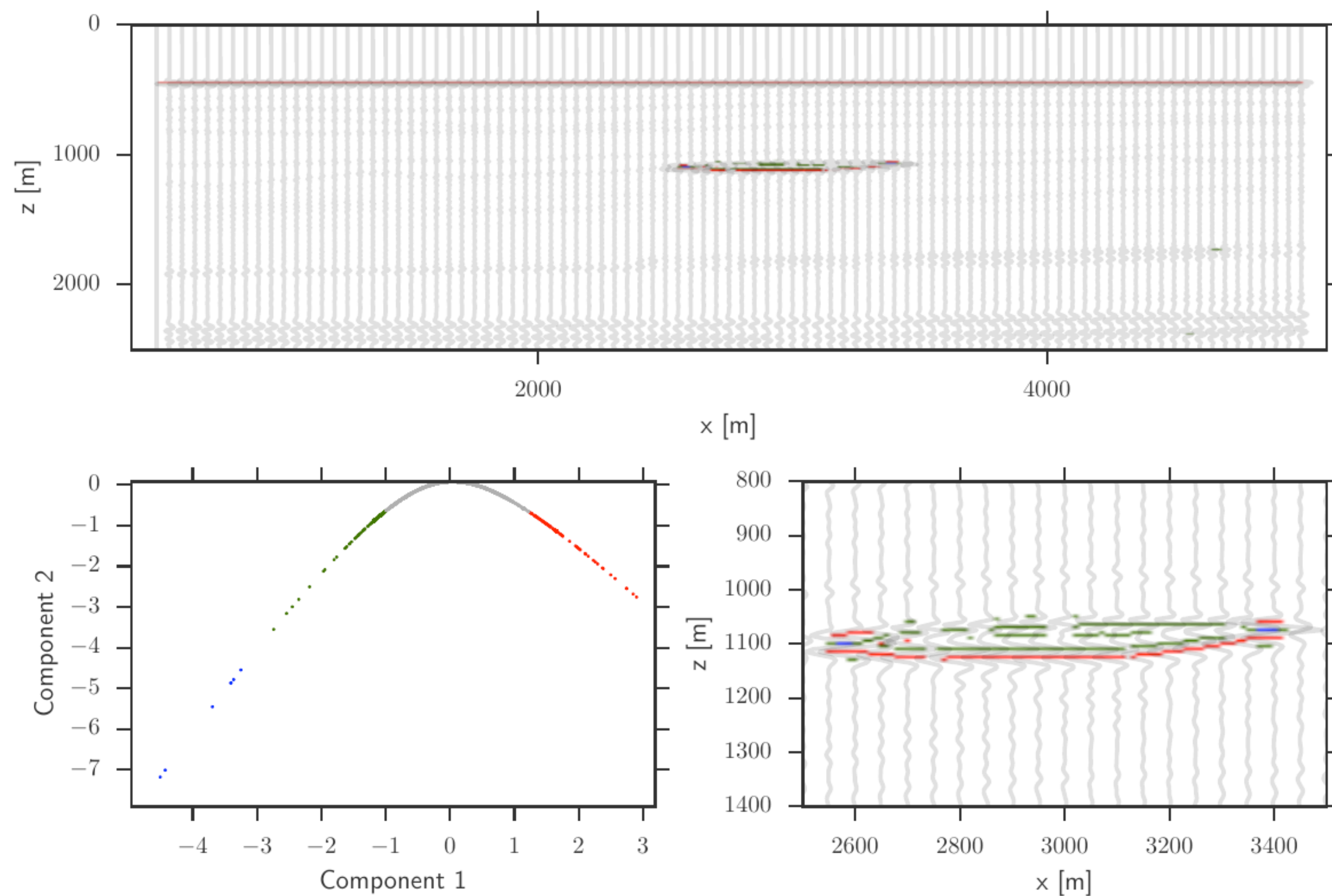
Measure the scattering pattern from a known source incident on a material.

Performed in highly controlled and calibrated laboratories (laser sources, temperature controlled, vacuums, etc...).

**Reflection seismology is a scattering experiment in an uncontrolled environment.**



# Reflection seismology as an unsupervised learning problem



## Problem:

Automatically segment potential hydrocarbon reserves from seismic images

## Approaches:

Physics driven (conventional)  
Data driven (thesis contributions)

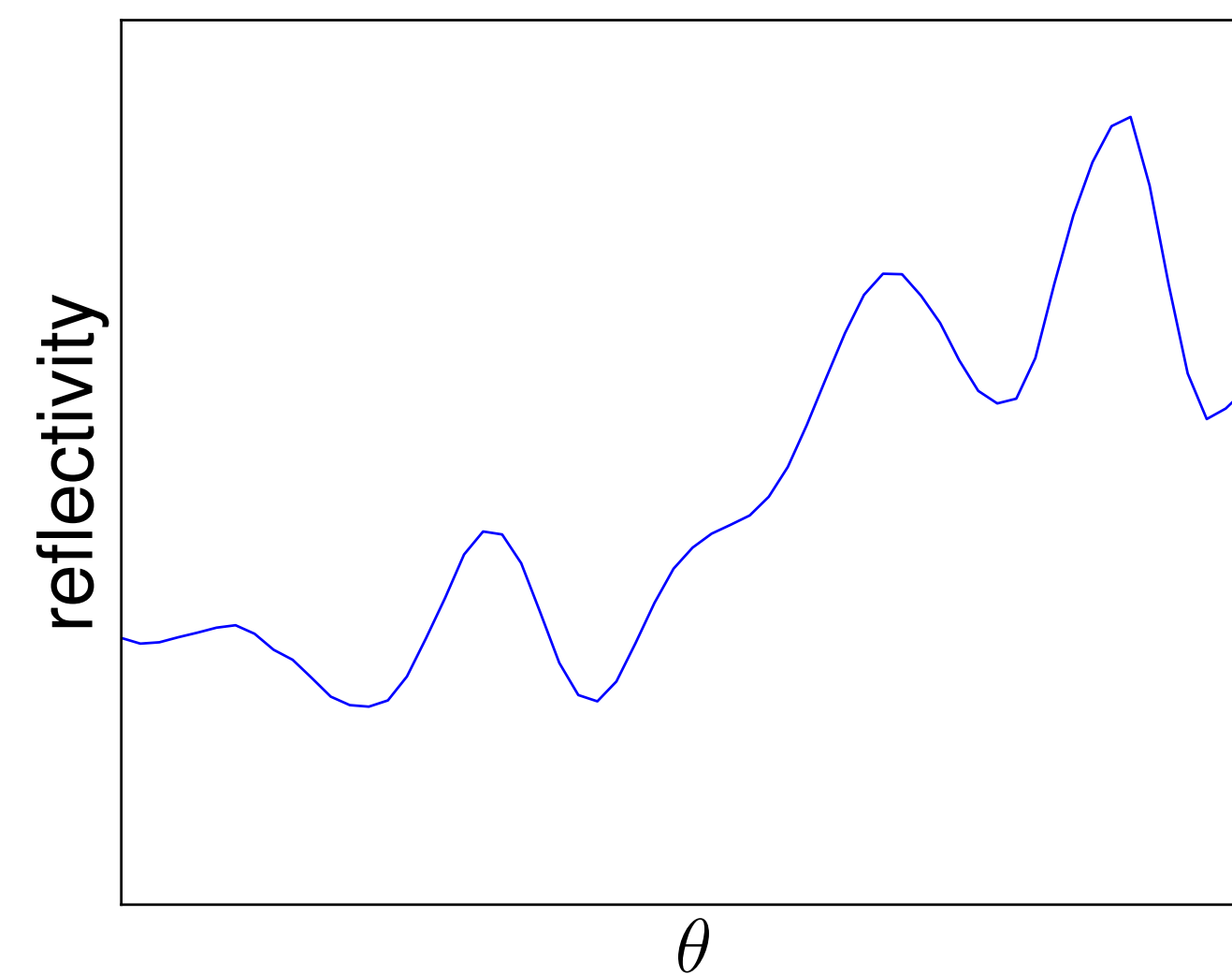
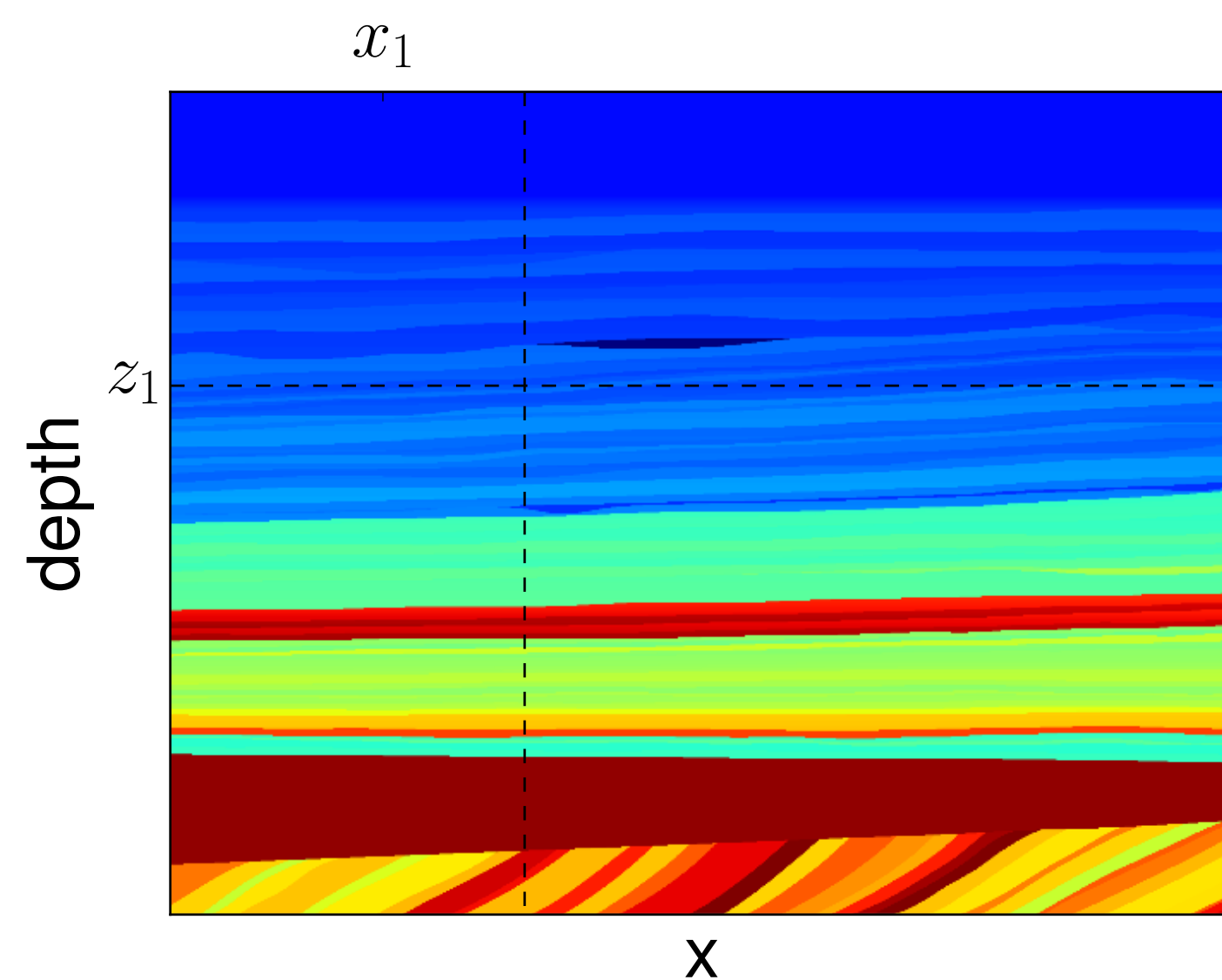
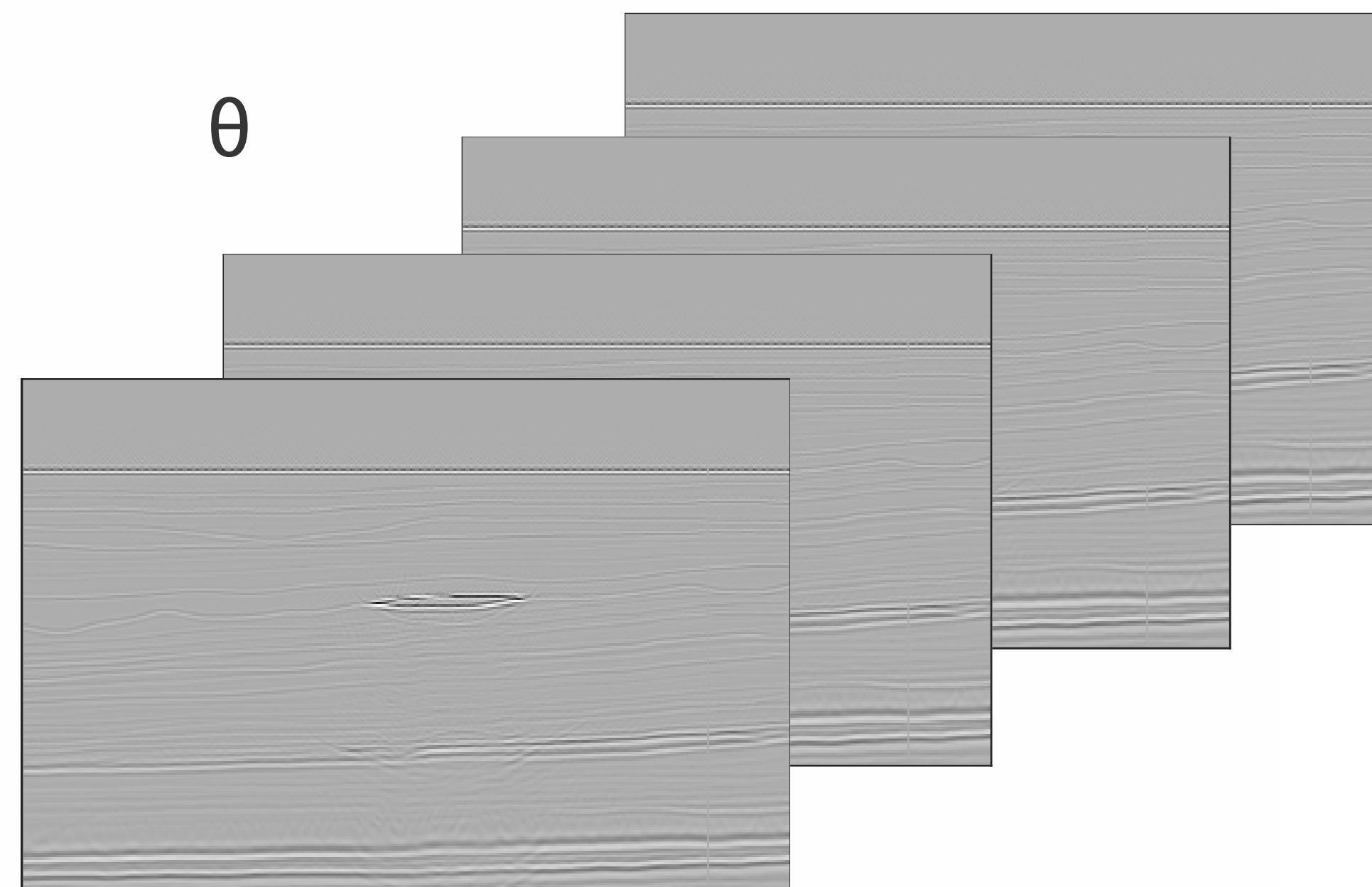
# Angle domain common image gathers

## Problem:

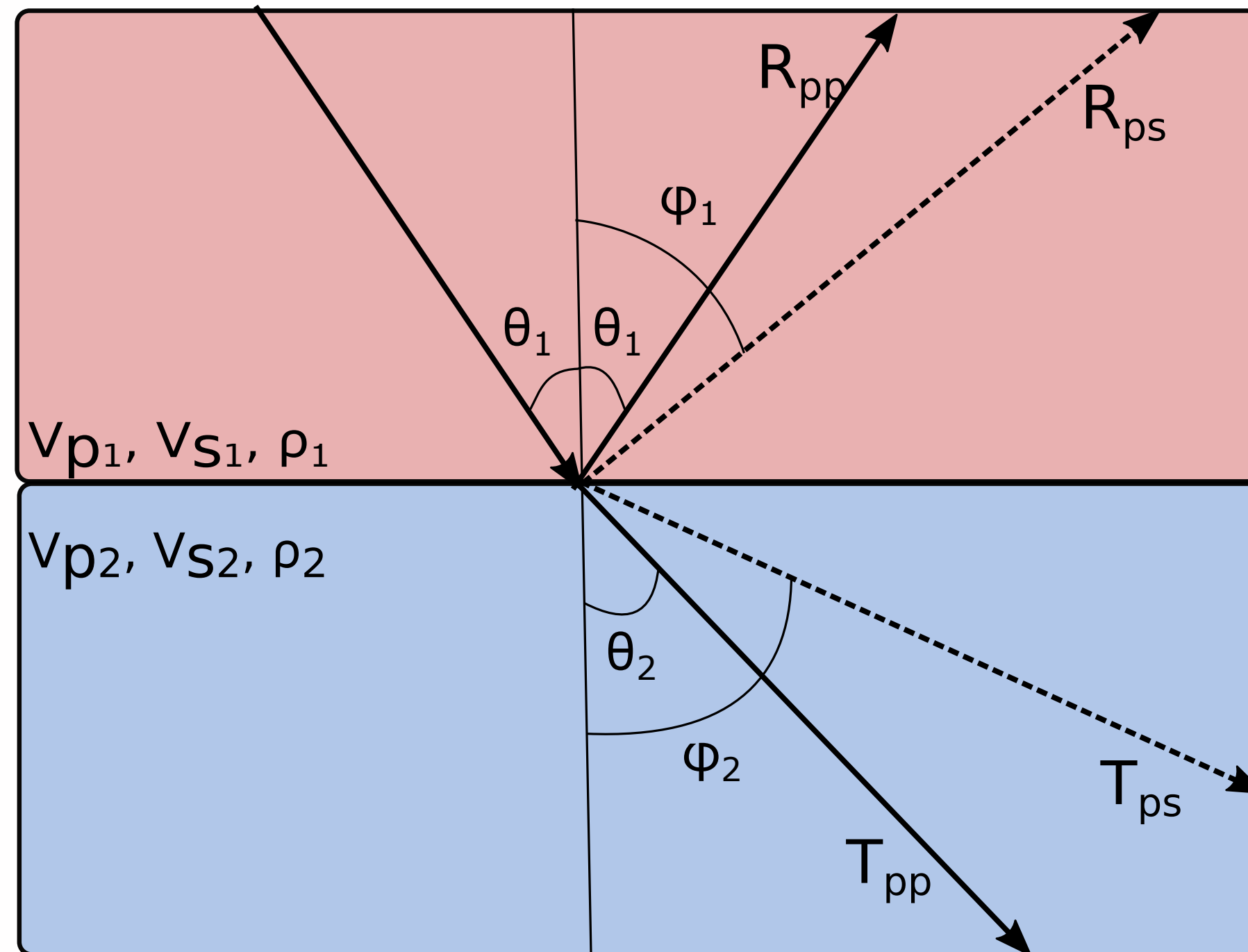
Need angle dependent reflectivity responses

## Solution:

Angle domain common image gather migration



# Scattering theory (Zoeppritz)



## Problem:

Relate angle dependent reflectivity to rock physics.

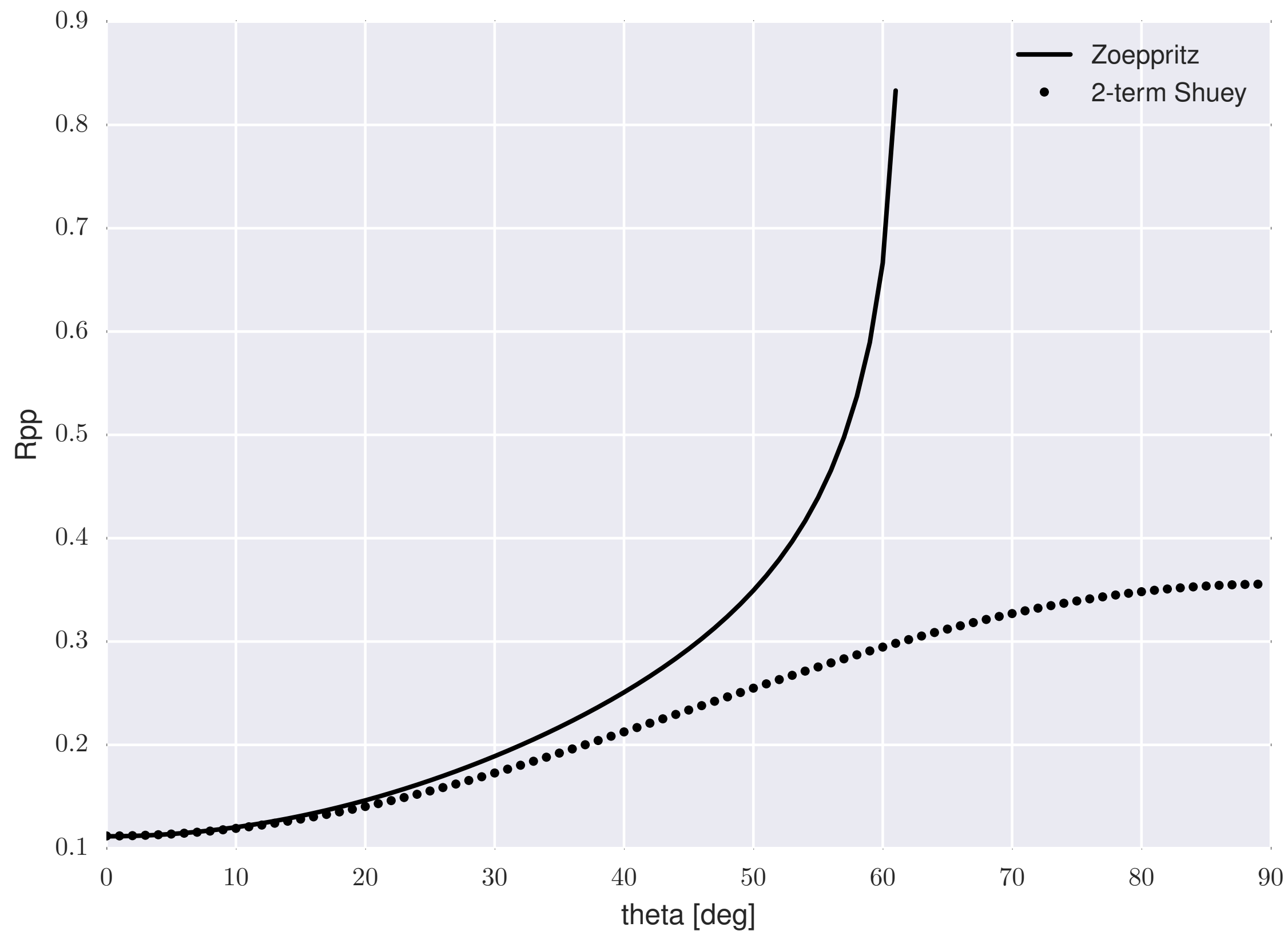
**Assumption:** Ray theory approximation.

**Solution:**  $R(\theta) \propto V_P, V_S, \rho$

**Problem:** Non-linear, not useful for inversion.

$$\begin{bmatrix} R_{PP} \\ R_{PS} \\ T_{PP} \\ T_{PS} \end{bmatrix} = \begin{bmatrix} -\sin \theta_1 & -\cos \phi_1 & \sin \theta_2 & \cos \phi_2 \\ \cos \theta_1 & -\sin \phi_1 & \cos \theta_2 & -\sin \phi_2 \\ \sin 2\theta & \frac{V_{P1}}{V_{S1}} \cos 2\phi_1 & \frac{\rho_2 V_{S2}^2 V_{P1}}{\rho_1 V_{S1}^2 V_{P2}} \cos 2\theta_1 & \frac{\rho_2 V_{S2} V_{P1}}{\rho_1 V_{S1}^2} \cos 2\phi_2 \\ -\cos \phi_2 & \frac{V_{S1}}{V_{P1}} \sin 2\phi_1 & \frac{\rho_2 V_{P2}}{\rho_1 V_{P1}} & \frac{\rho_2 V_{S2}}{\rho_1 V_{P1}} \sin 2\phi_2 \end{bmatrix}^{-1} \begin{bmatrix} \sin \theta_1 \\ \cos \theta_1 \\ \sin 2\theta_1 \\ \cos 2\phi_1 \end{bmatrix}$$

# Scattering theory (Shuey)



$$R_{pp}(\theta) = i(\Delta V_P, \Delta \rho) + g(\Delta V_P, \Delta V_S, \Delta \rho) \sin^2 \theta$$

$$i(\Delta V_P, \Delta \rho) = \frac{1}{2} \left( \frac{\Delta V_P}{\langle V_P \rangle} + \frac{\Delta \rho}{\langle \rho \rangle} \right)$$

$$g(\Delta V_P, \Delta V_S, \Delta \rho) = \frac{1}{2} \frac{\Delta V_P}{\langle V_P \rangle} - 2 \frac{\langle V_S \rangle^2}{\langle V_P \rangle^2} \left( \frac{\Delta \rho}{\langle \rho \rangle} + 2 \frac{\Delta V_S}{\langle V_S \rangle} \right)$$

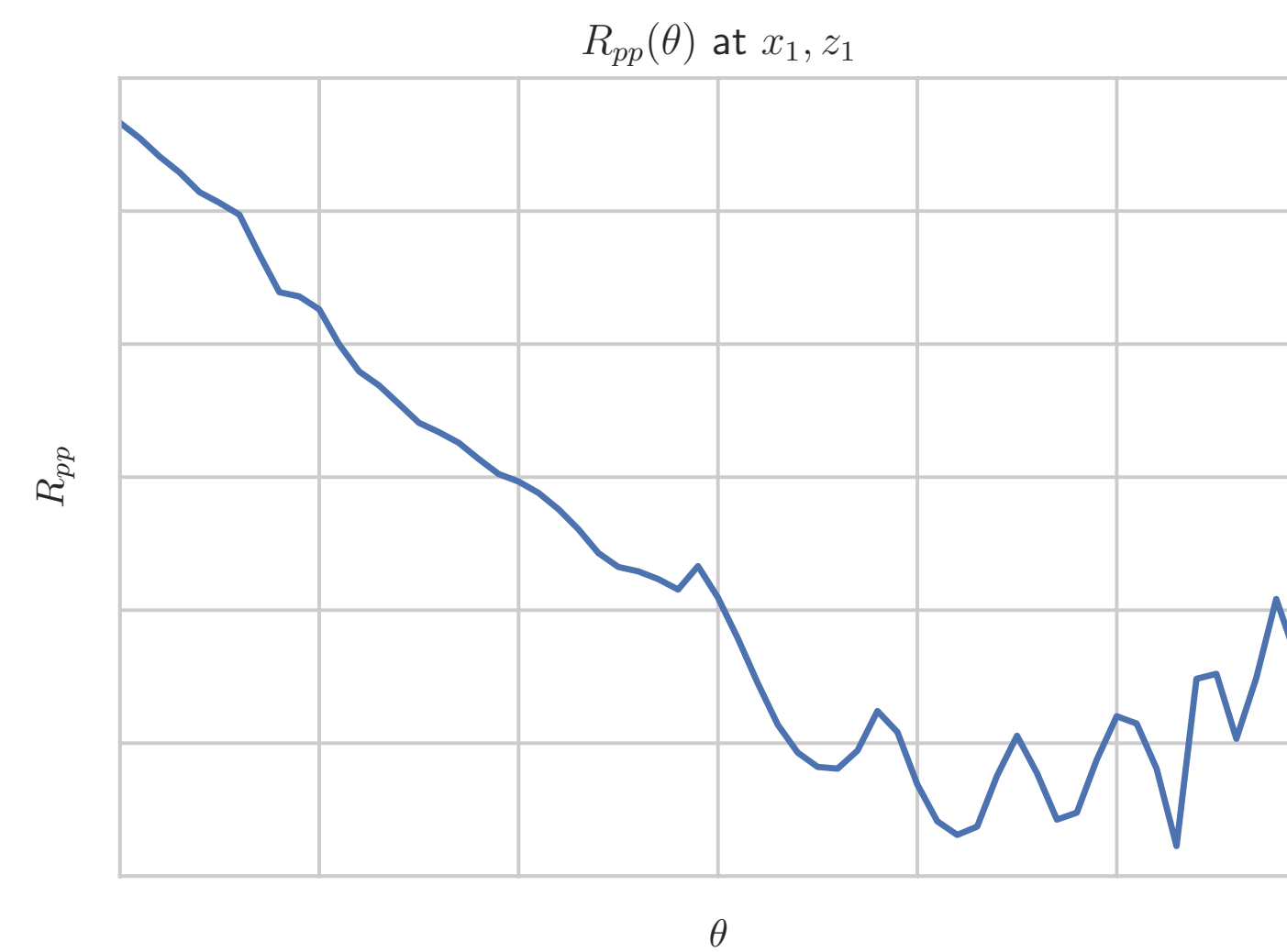
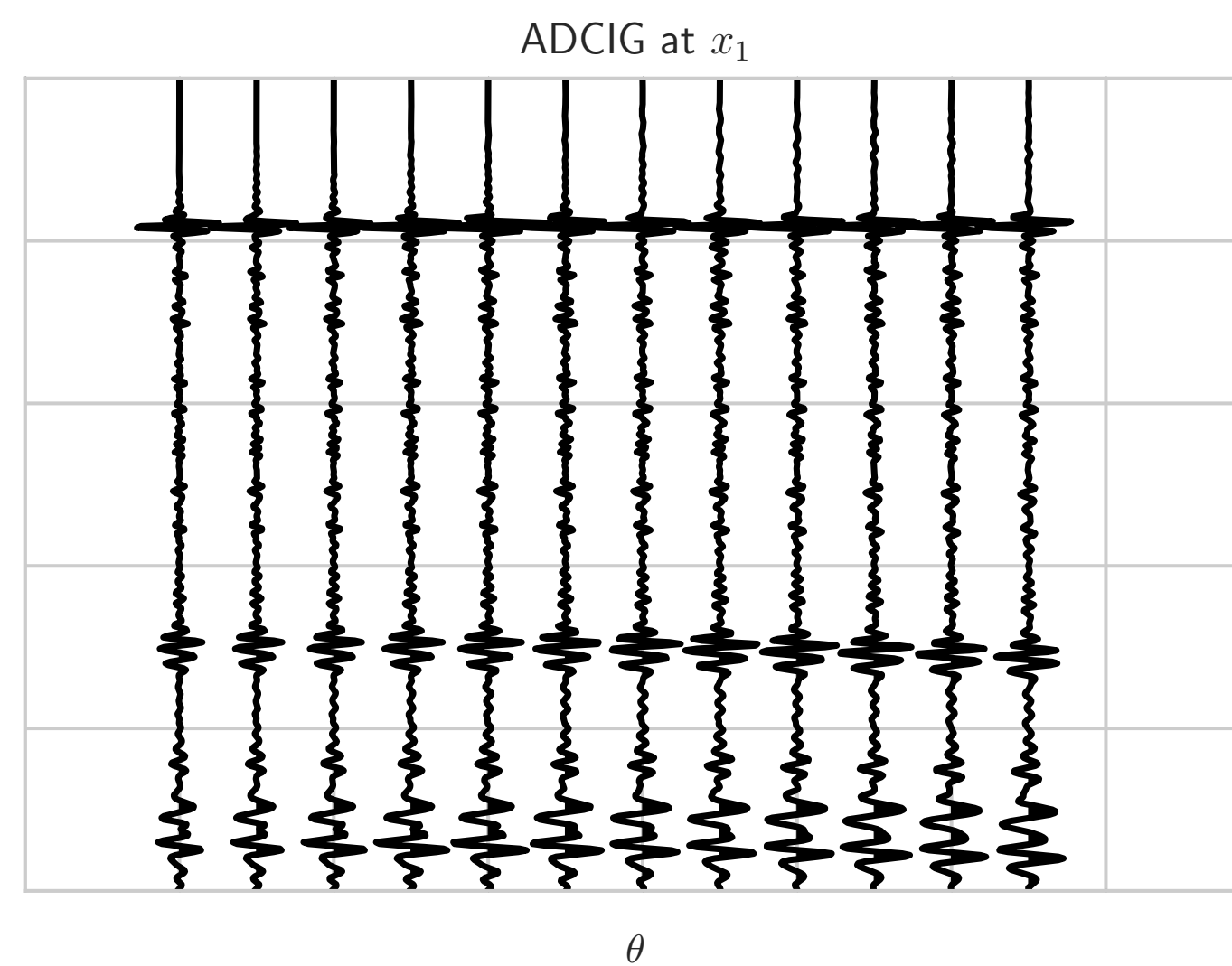
## Limitations:

Small perturbations over a background trend, valid < 30 degrees

## Benefits:

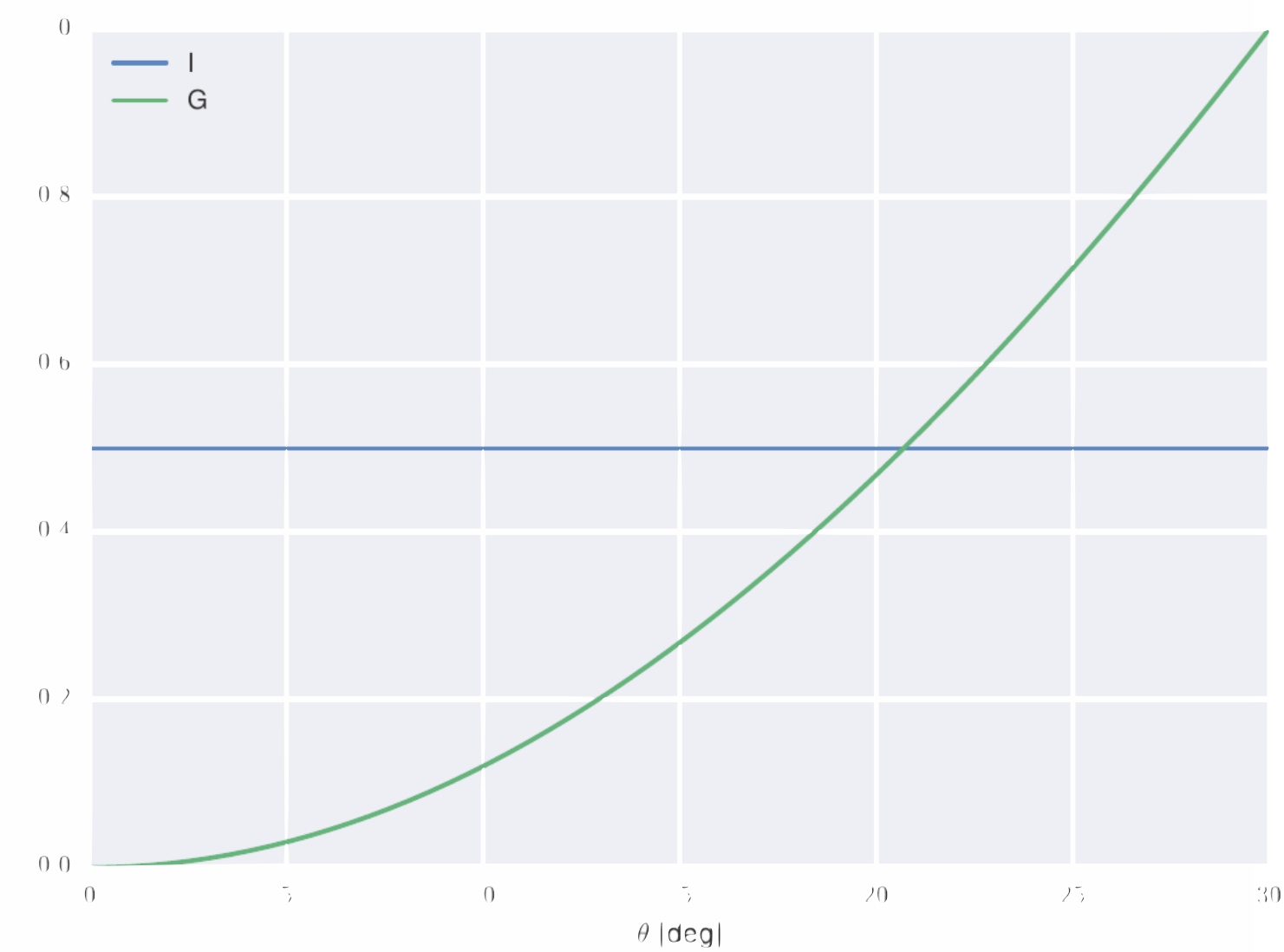
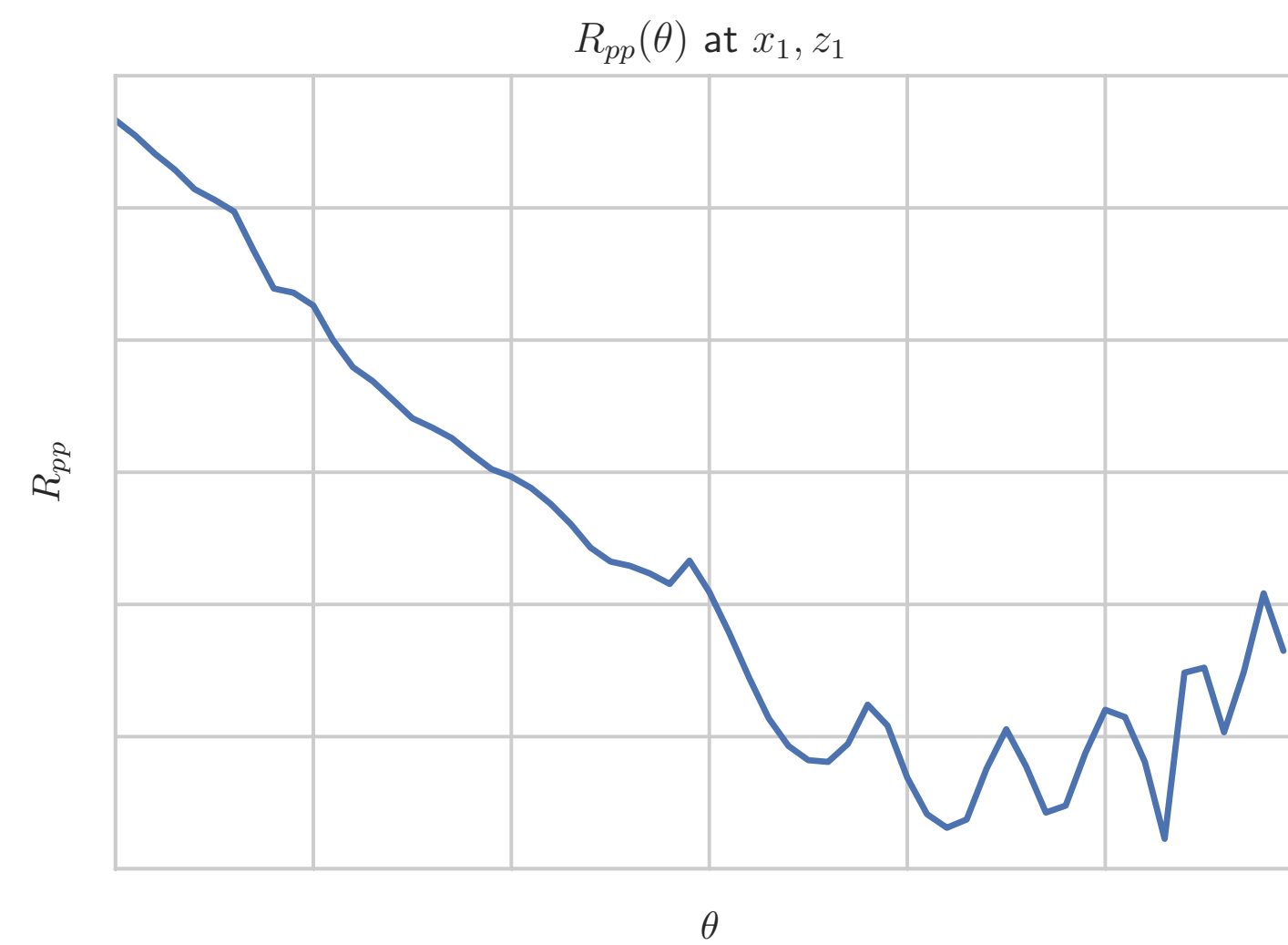
Linear for i and g, invert using simple least squares

# Shuey term inversion as a projection



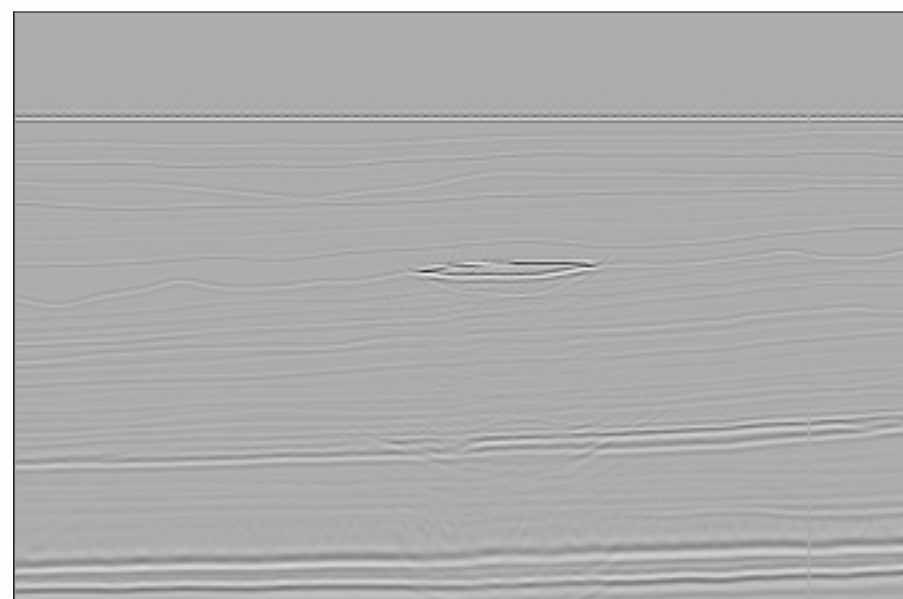


# Shuey term inversion as a projection

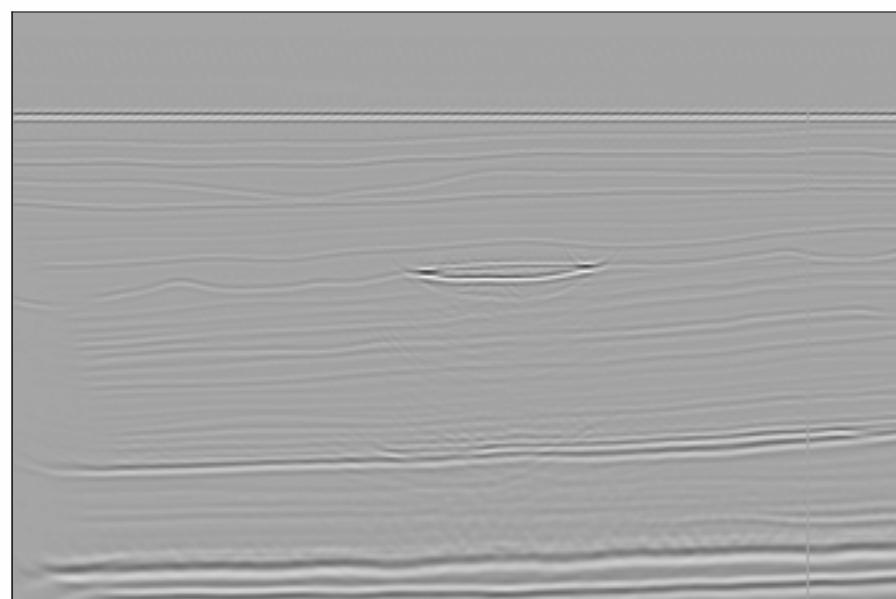
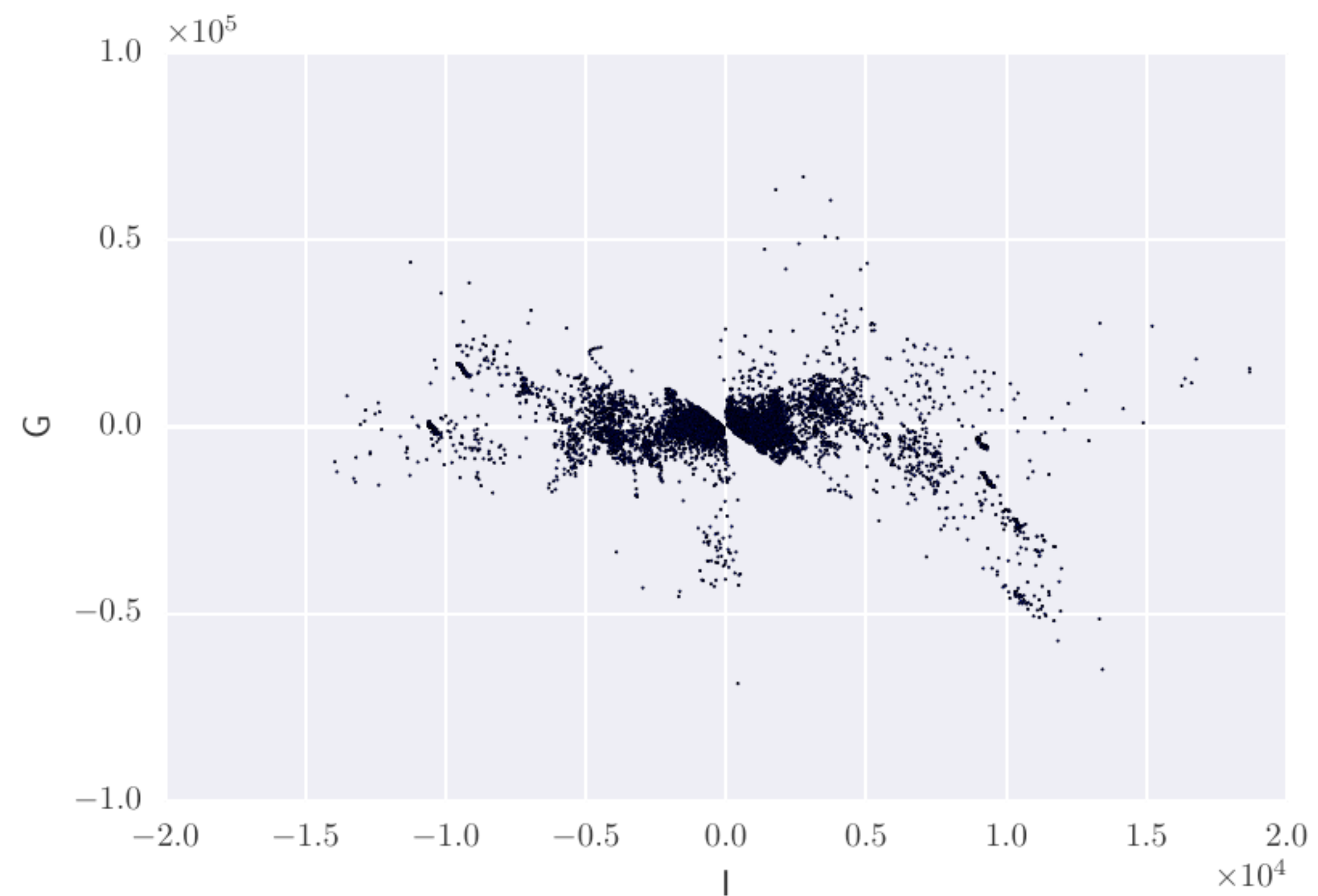
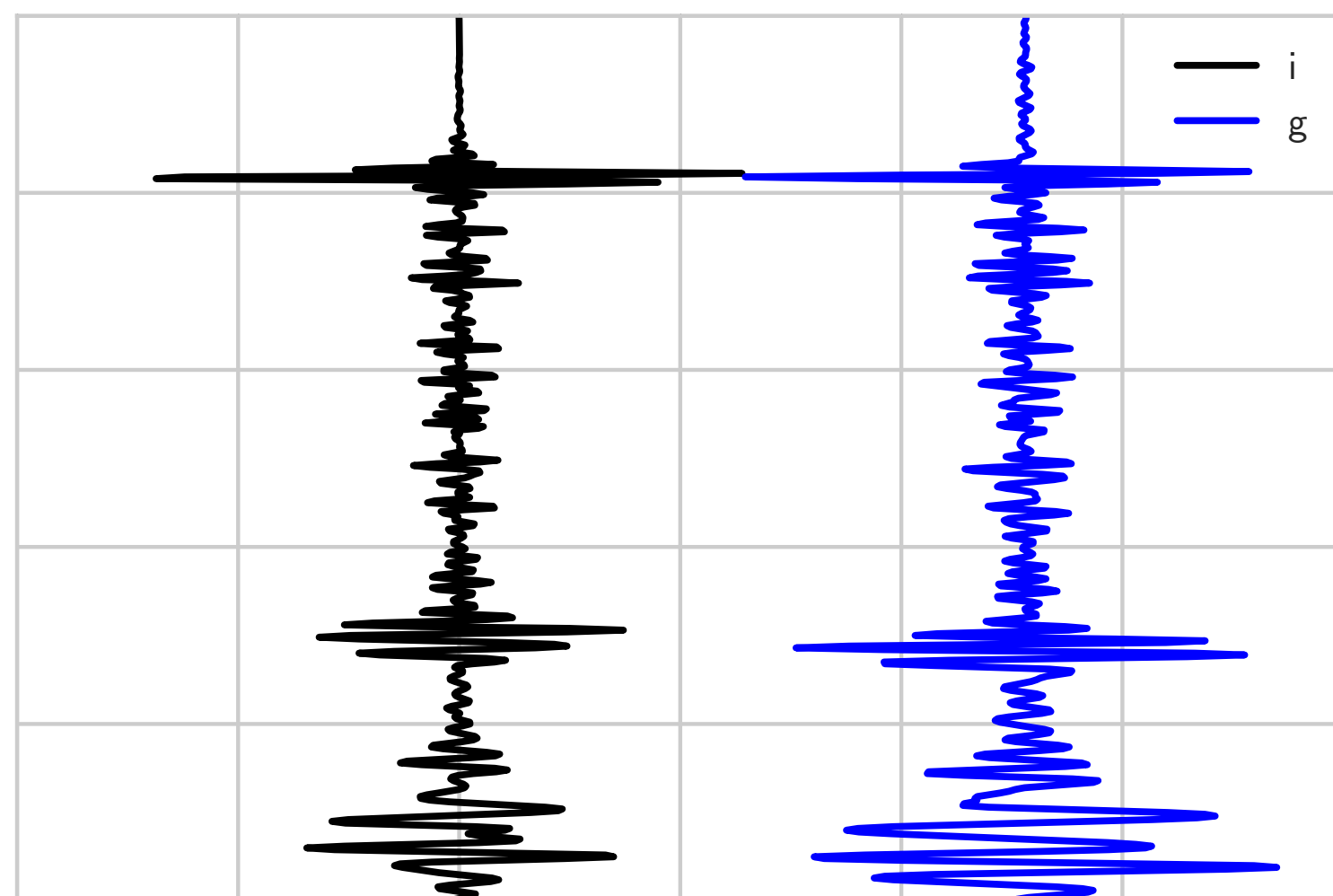


# Shuey term inversion as a projection

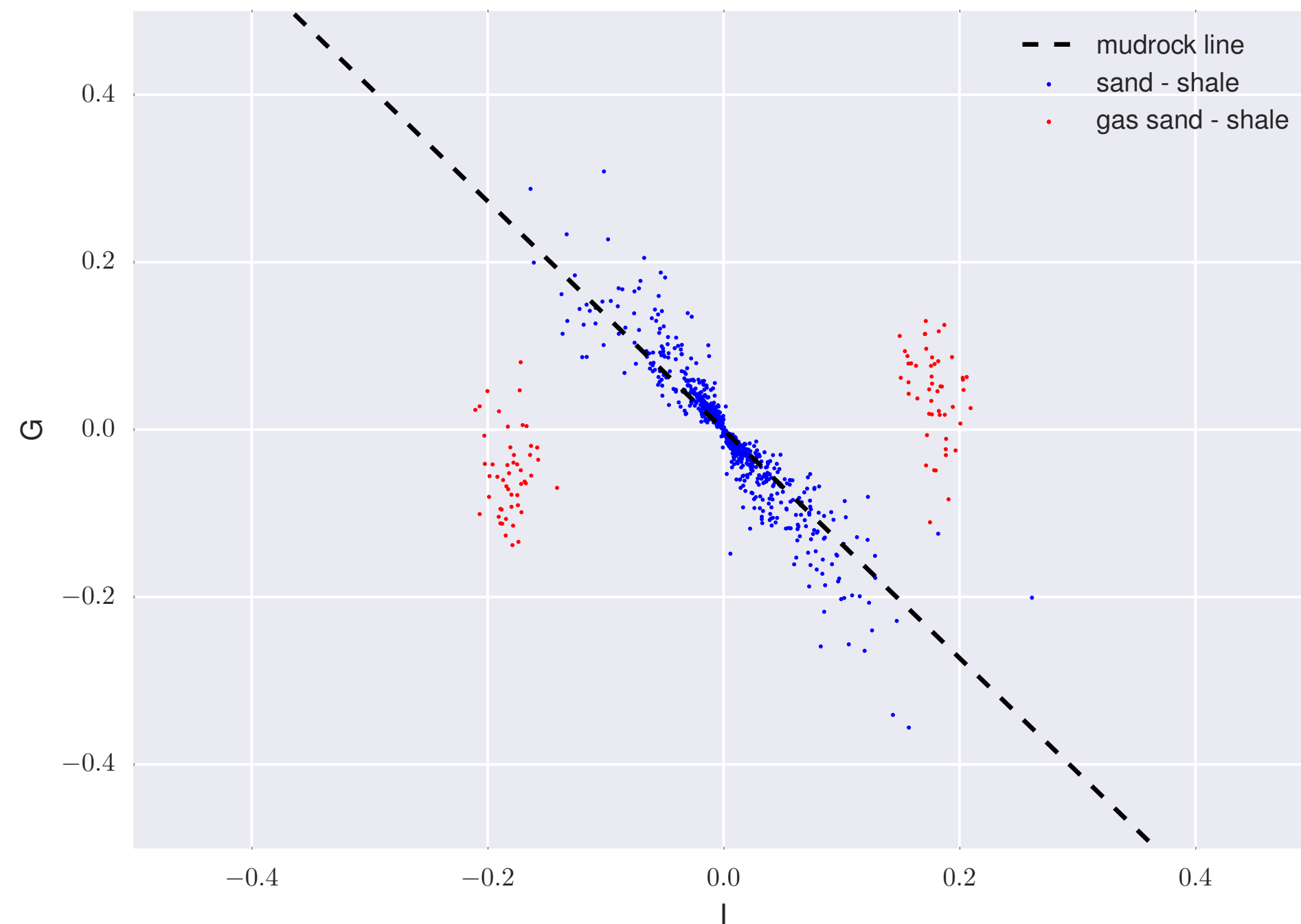
i



gg

i,g at  $x_1$ 

## Relation to hydrocarbons



$$\frac{\Delta\rho}{\langle\rho\rangle} \propto k \frac{\Delta V_P}{\langle V_P\rangle}$$

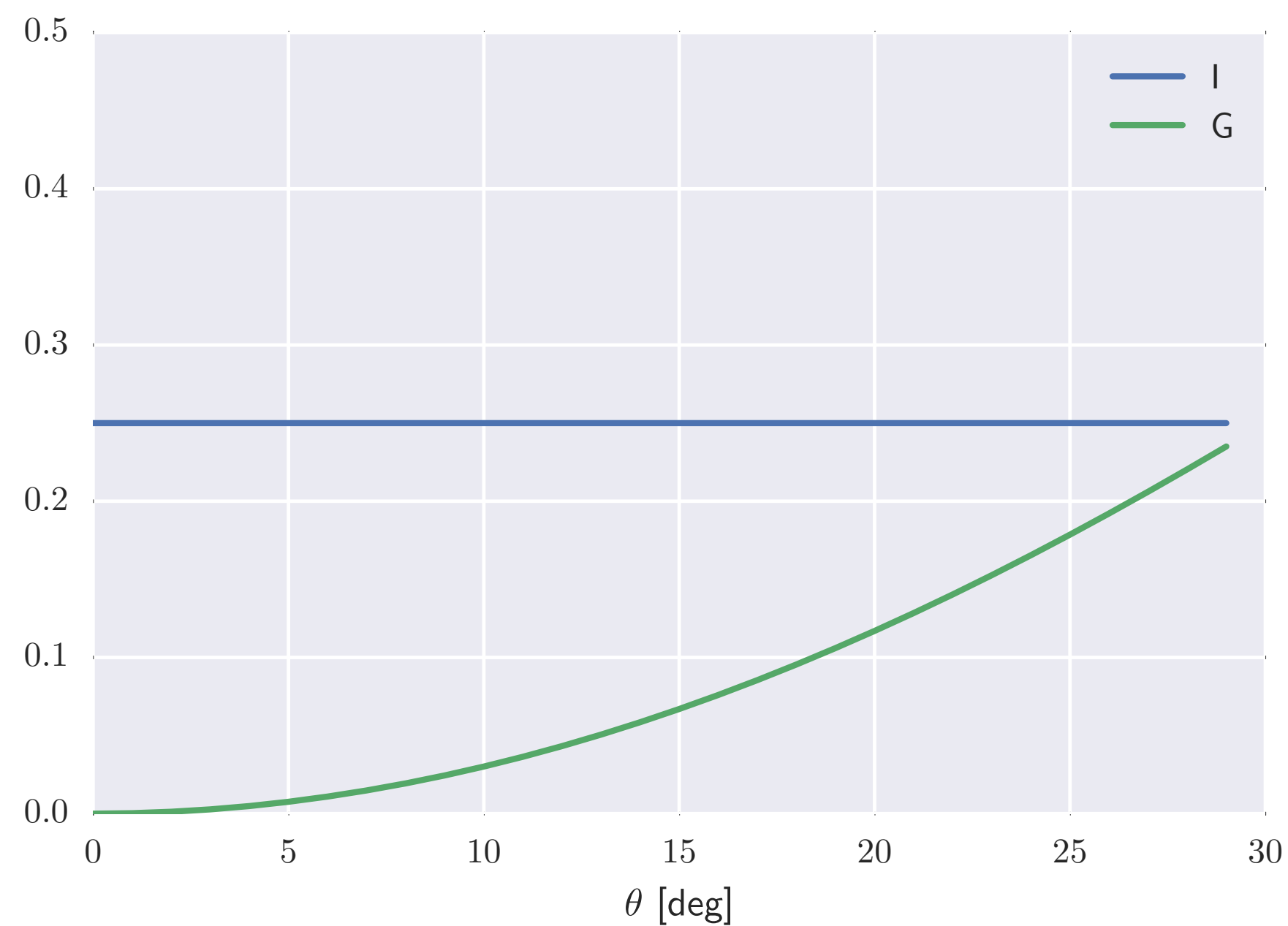
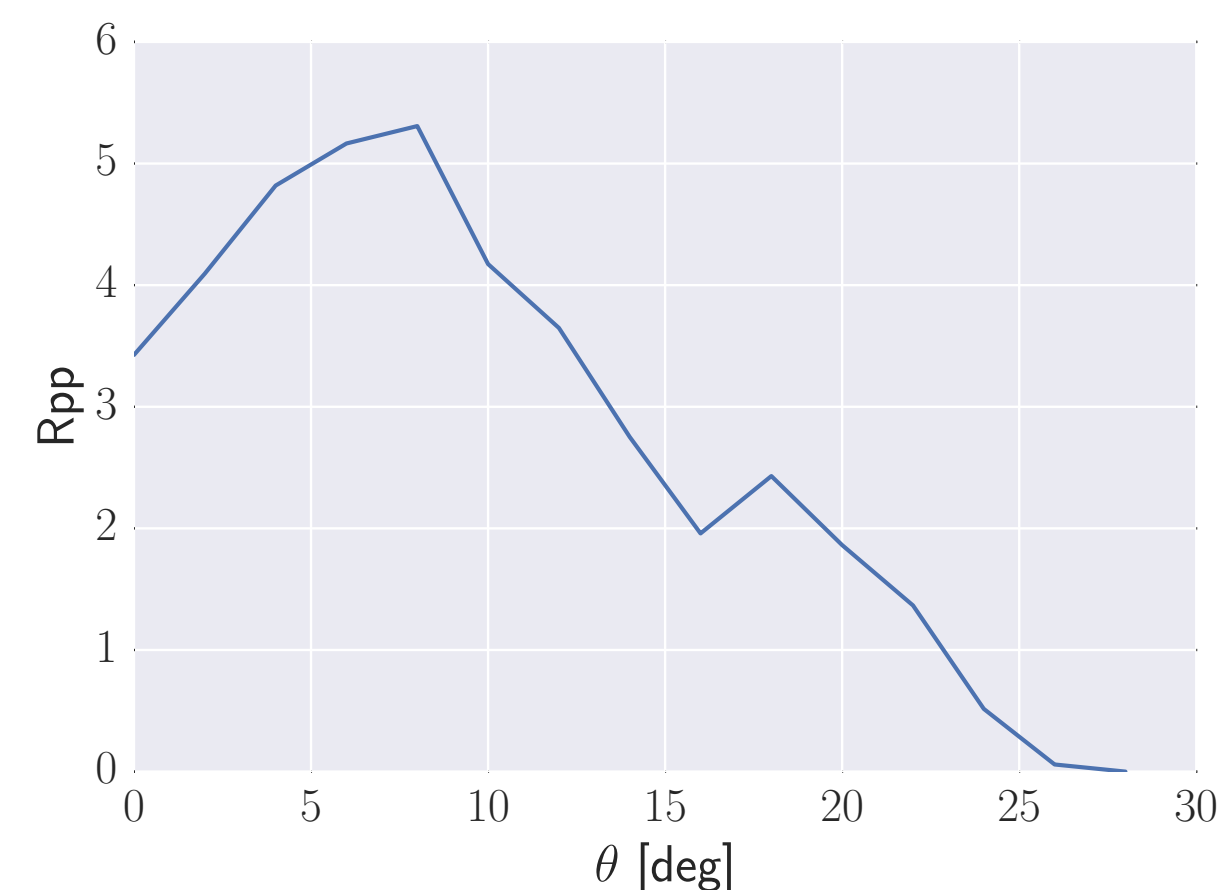
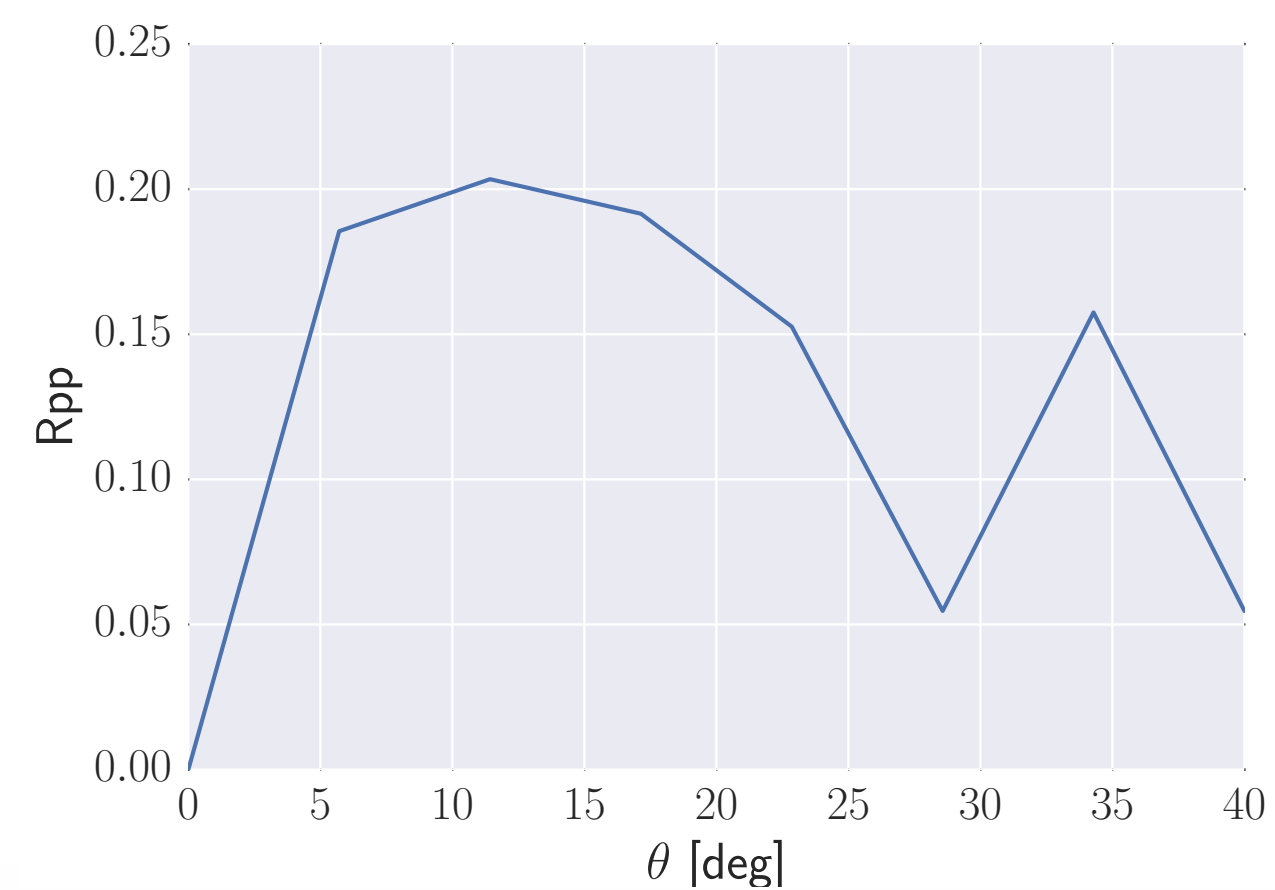
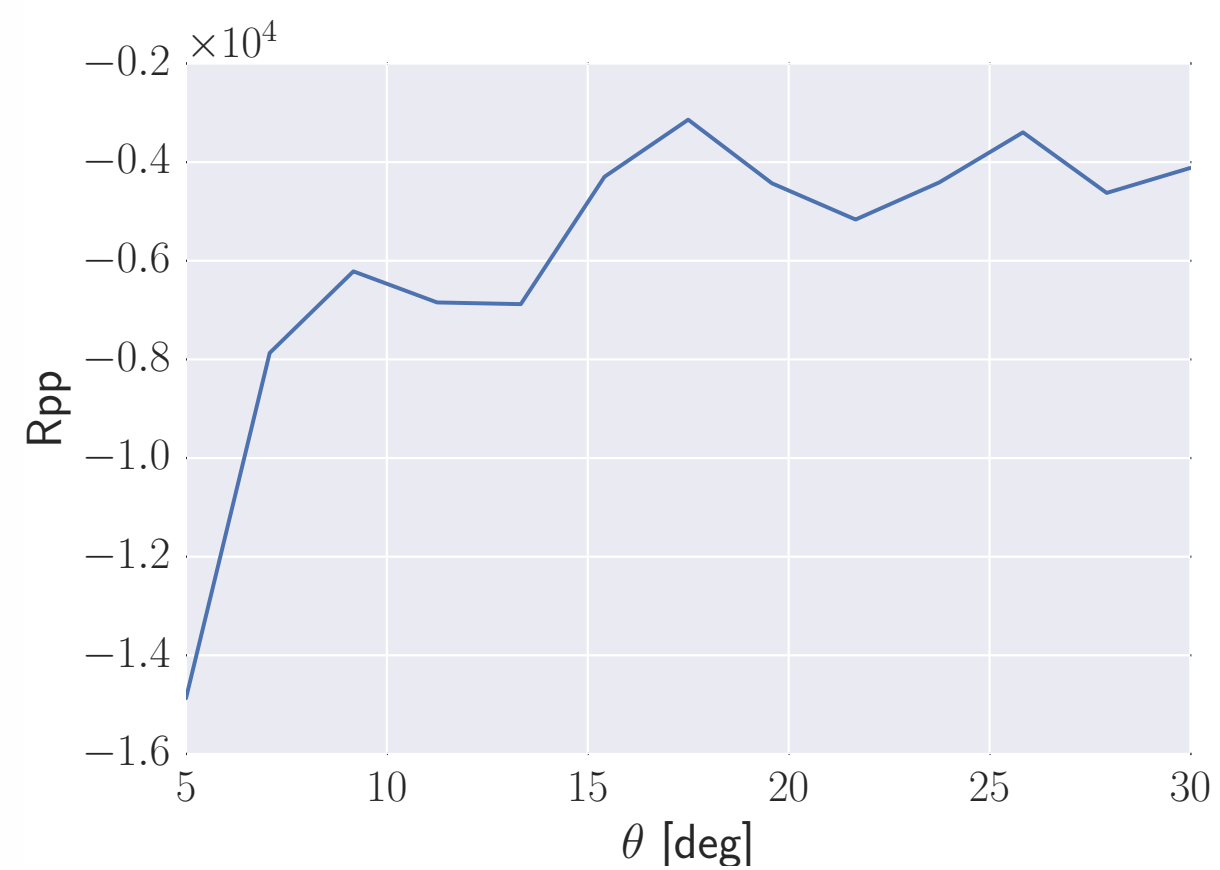
$$V_P = mV_S + c$$

$$g = \frac{i}{1+k} \left[ 1 - 4 \frac{\langle V_S \rangle}{\langle V_P \rangle} \left( \frac{2}{m} + k \frac{\langle V_S \rangle}{\langle V_P \rangle} \right) \right]$$

**Hydrocarbon reserves are found from outliers of a crossplot!**

\*m, c, k are geological parameters determined empirically from well logs/laboratory measurements

# Reality bites



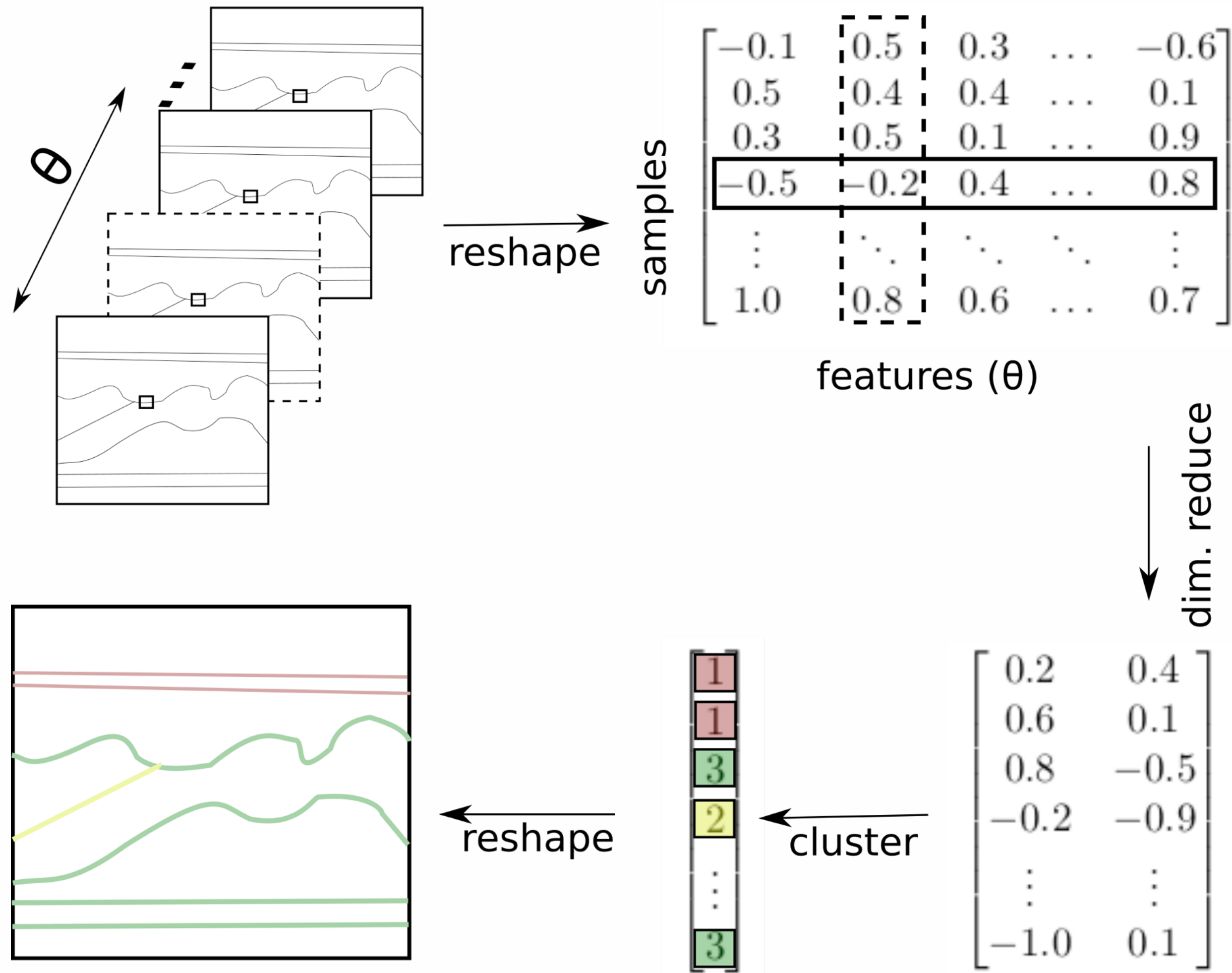
## Problem:

Shuey components can't explain all the features in real data!

## Solution:

Use unsupervised machine learning to find better projections.

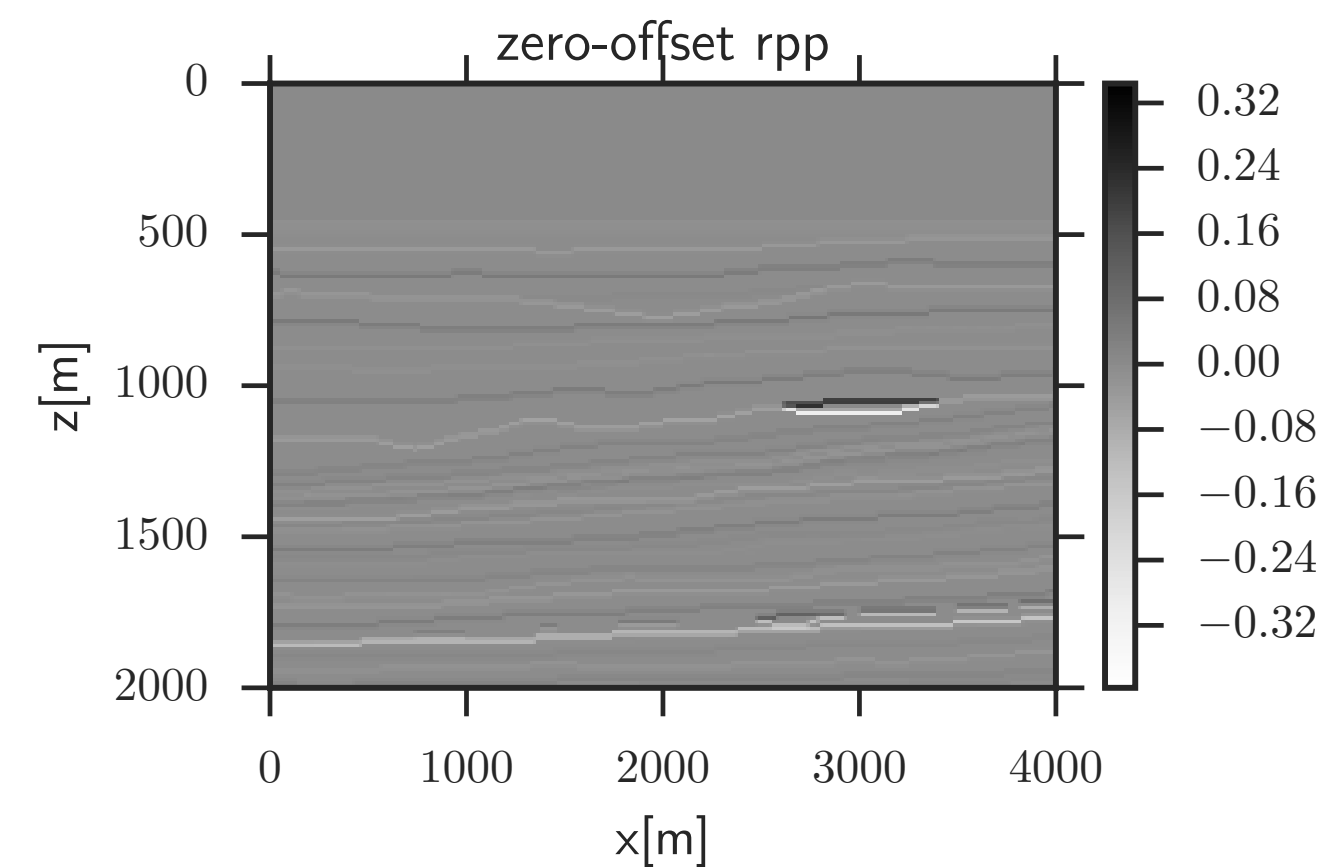
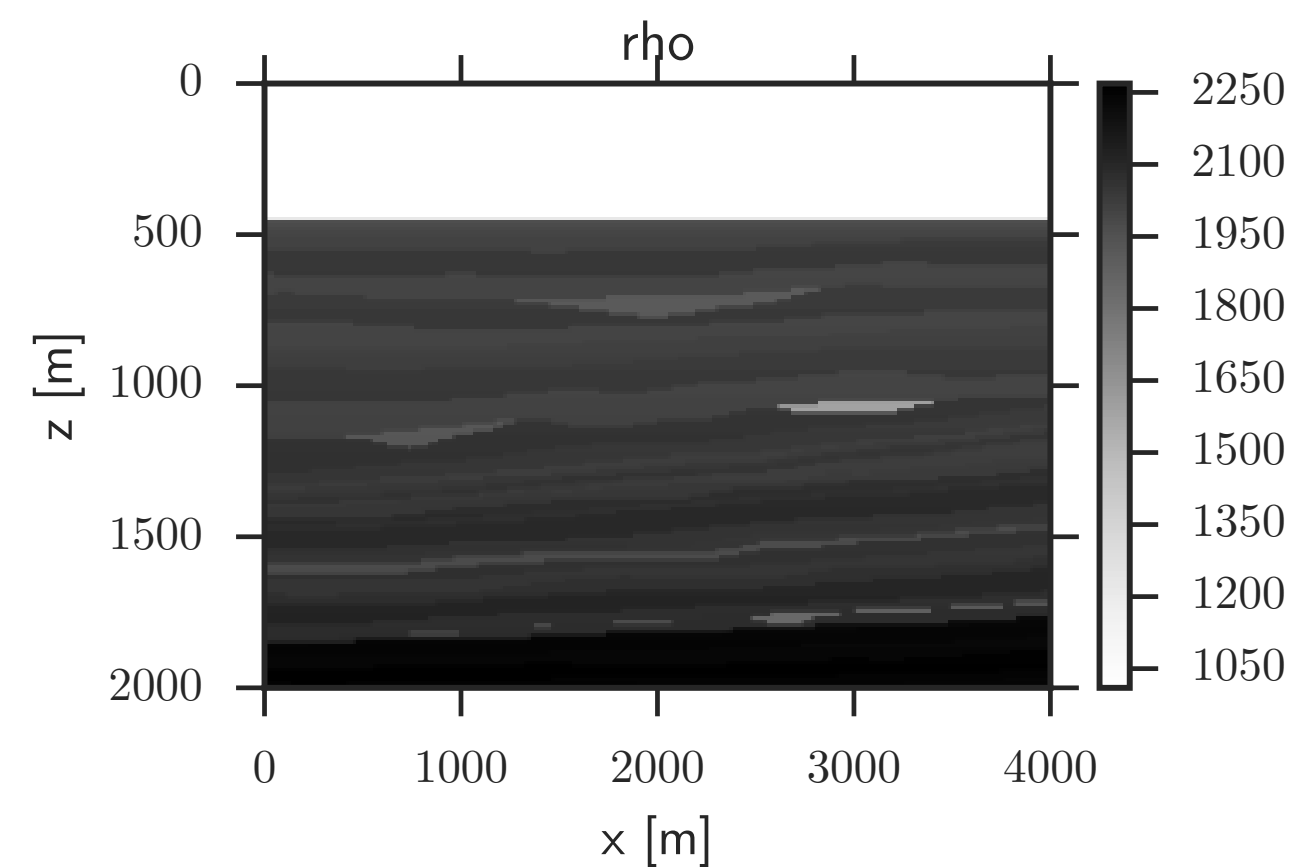
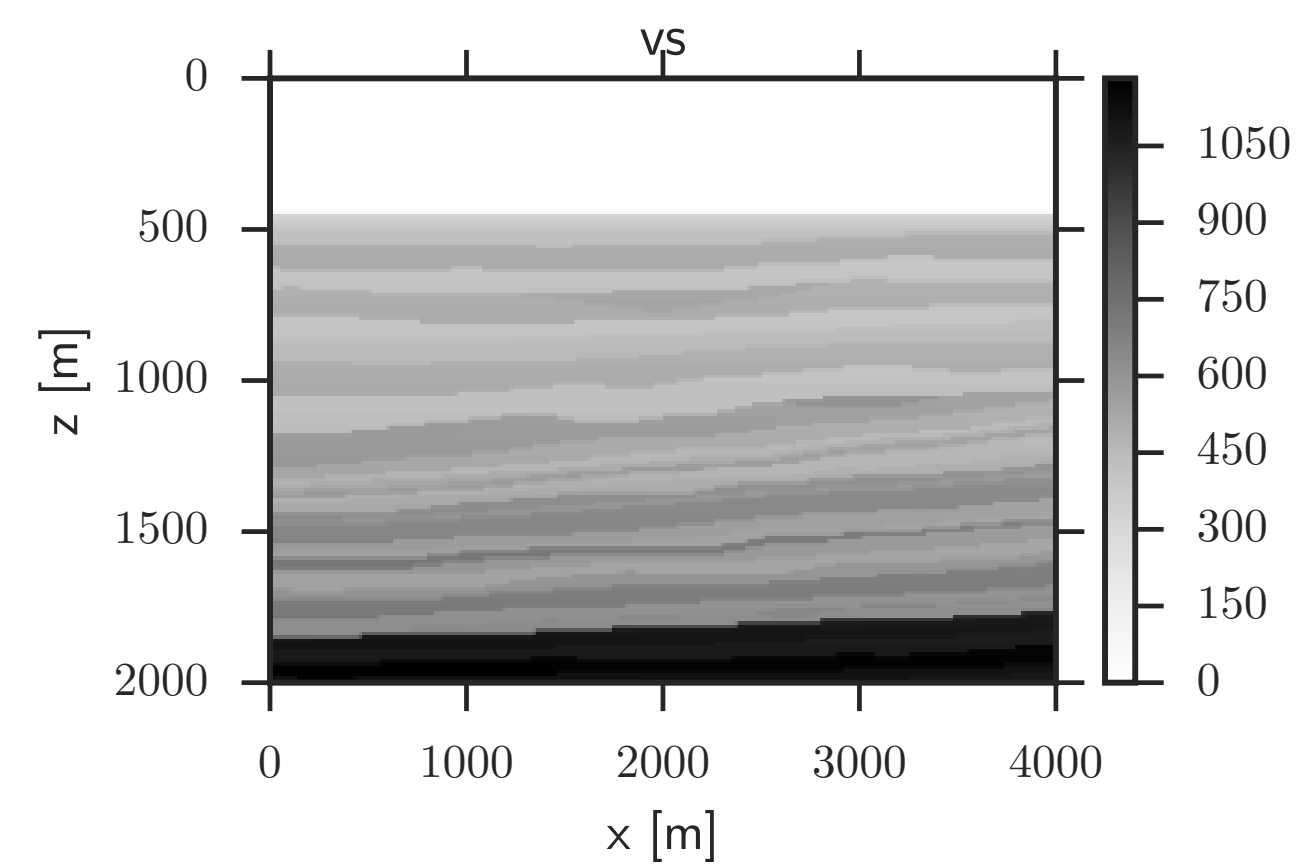
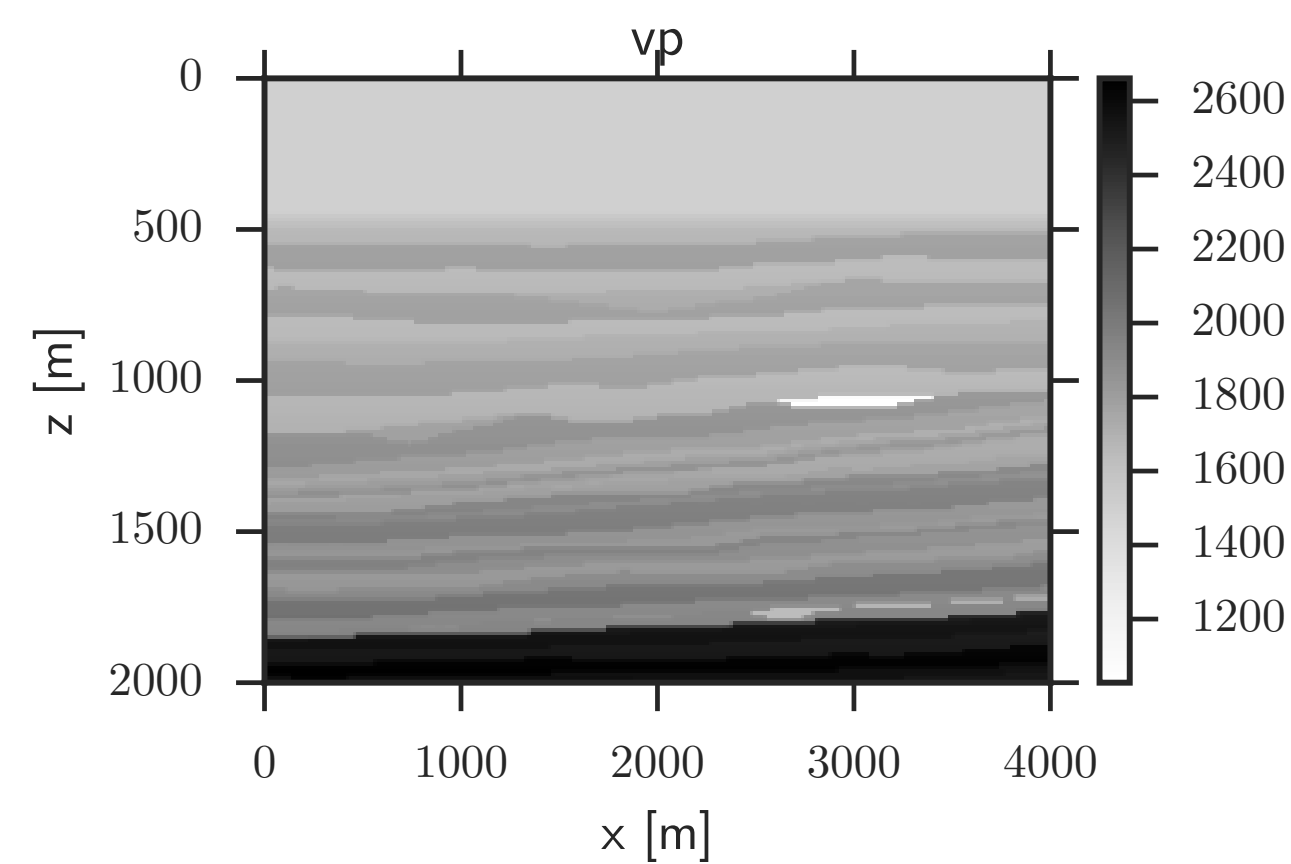
# Unsupervised learning problem



$$X \in \mathbb{R}^{n \times d}$$

n is number of samples in the image,  
d is the number of angles

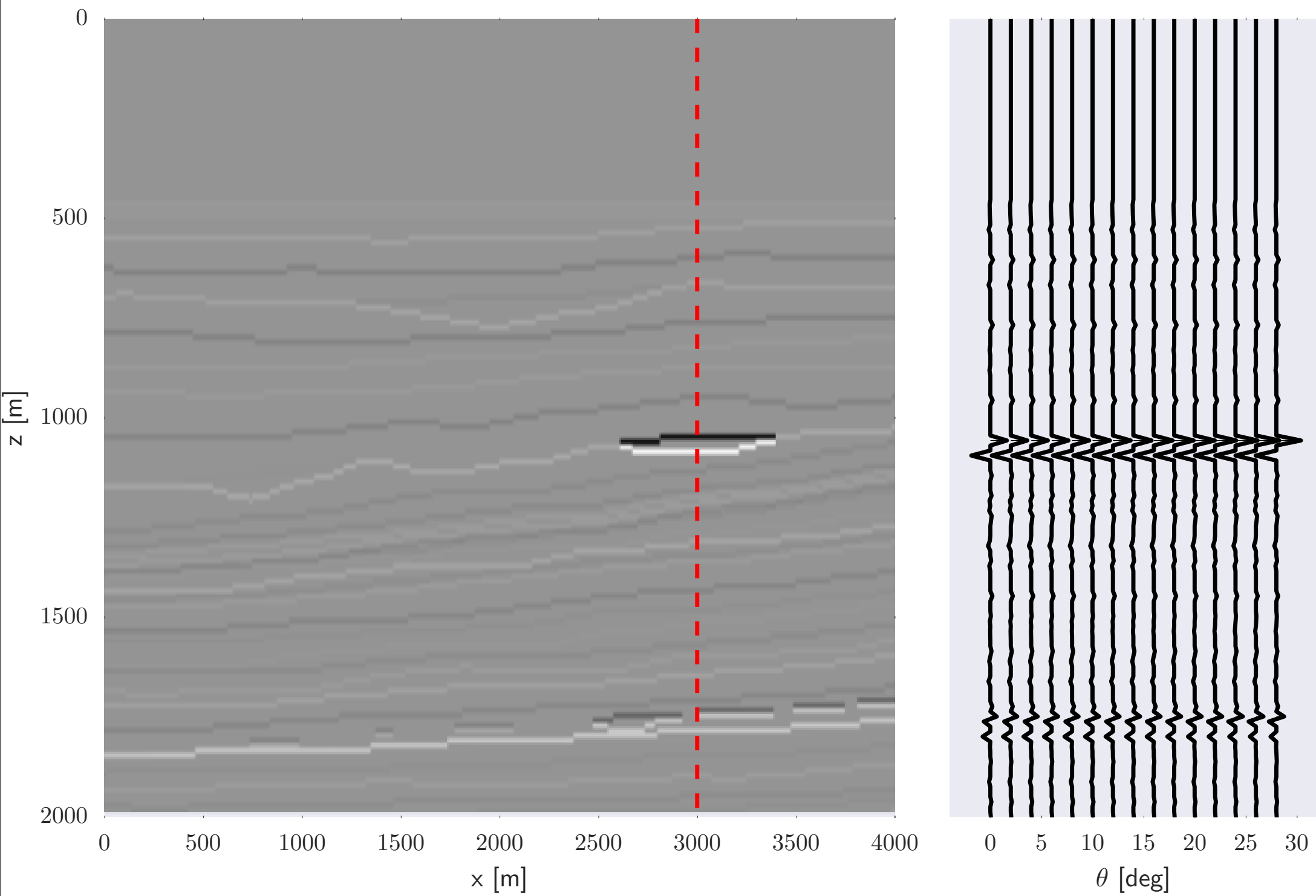
# Marmousi II data



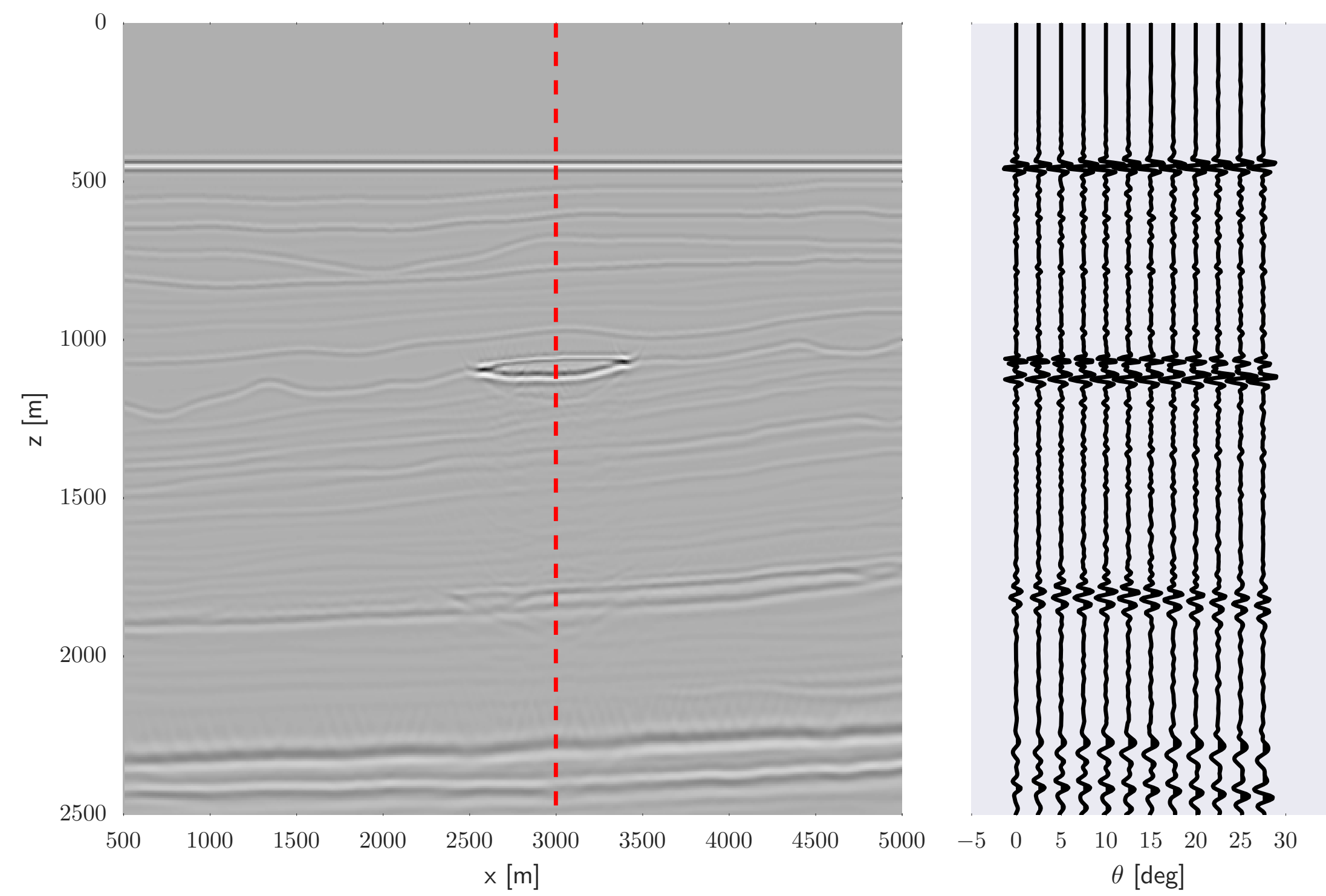
Specifically made for testing  
amplitude vs. offset analysis

Contains gas-saturated sand

# Seismic modeling



Physically consistent with  
Zoeppritz



Migrated visco-acoustic  
survey

## Principle component analysis (PCA)

Eigendecomposition of the covariance matrix:

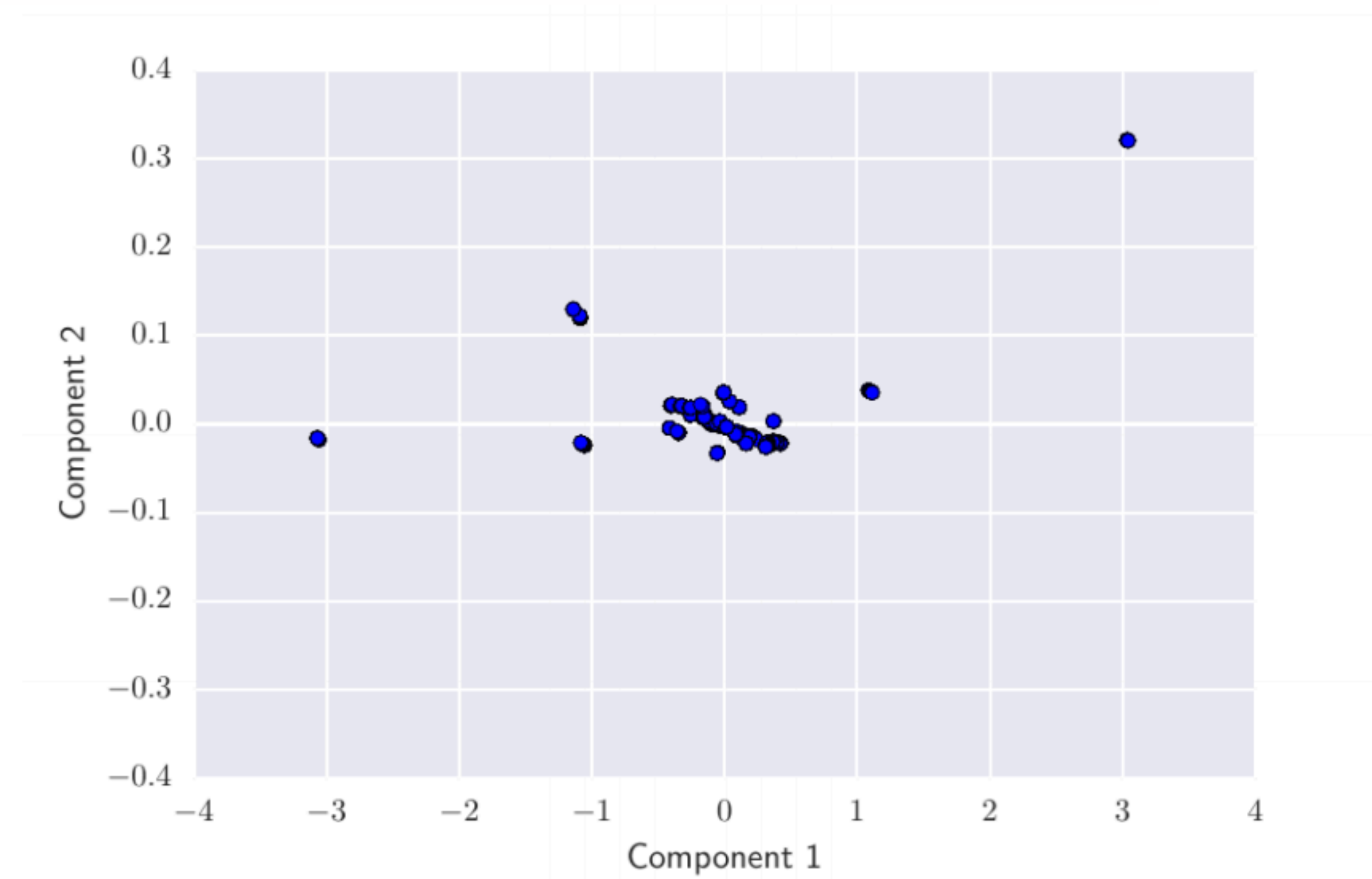
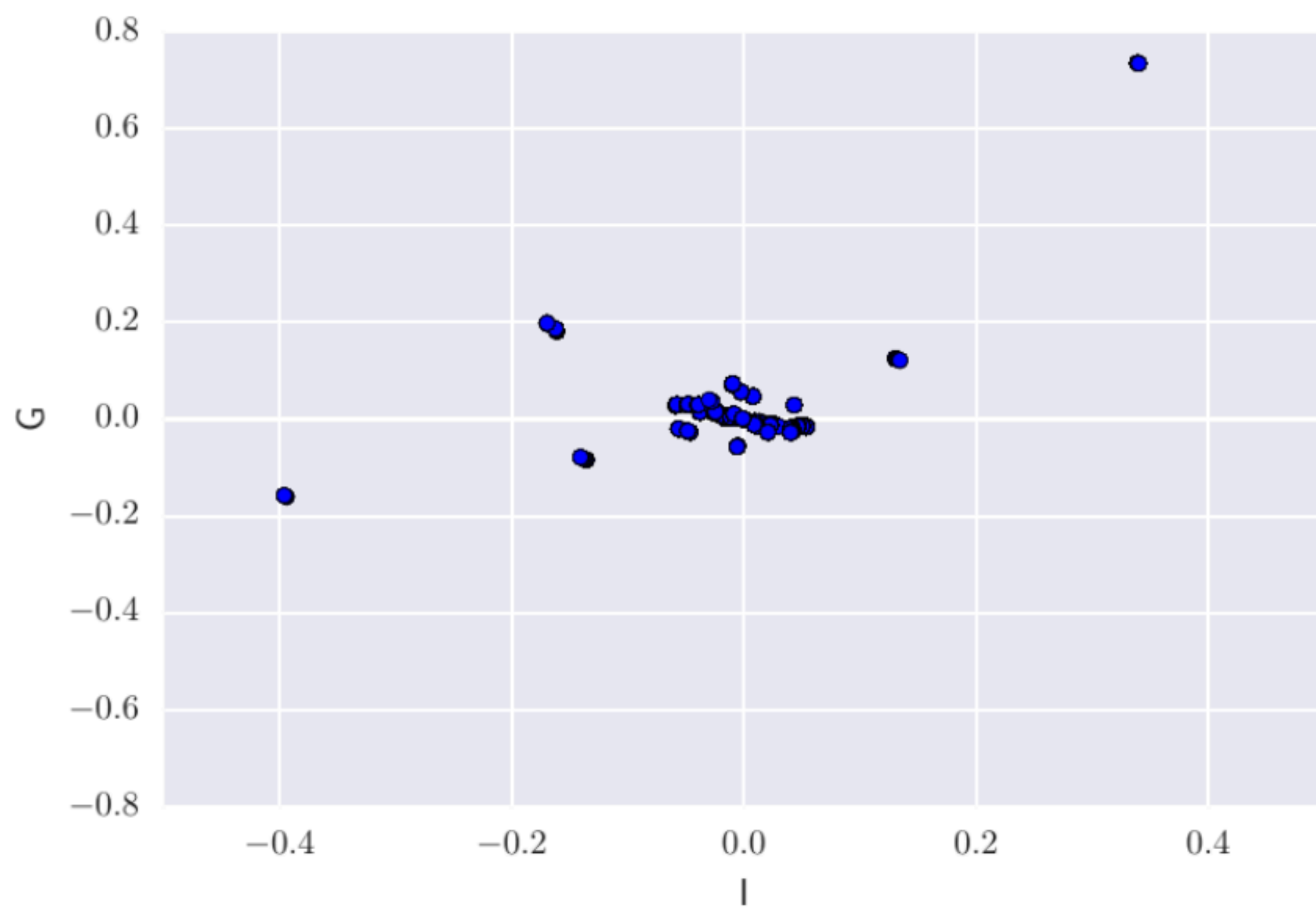
$$C = X^T X = \frac{1}{n} \sum_i^n \mathbf{x}_i \mathbf{x}_i^T$$

Project onto the eigenvectors with the two largest eigenvalues.

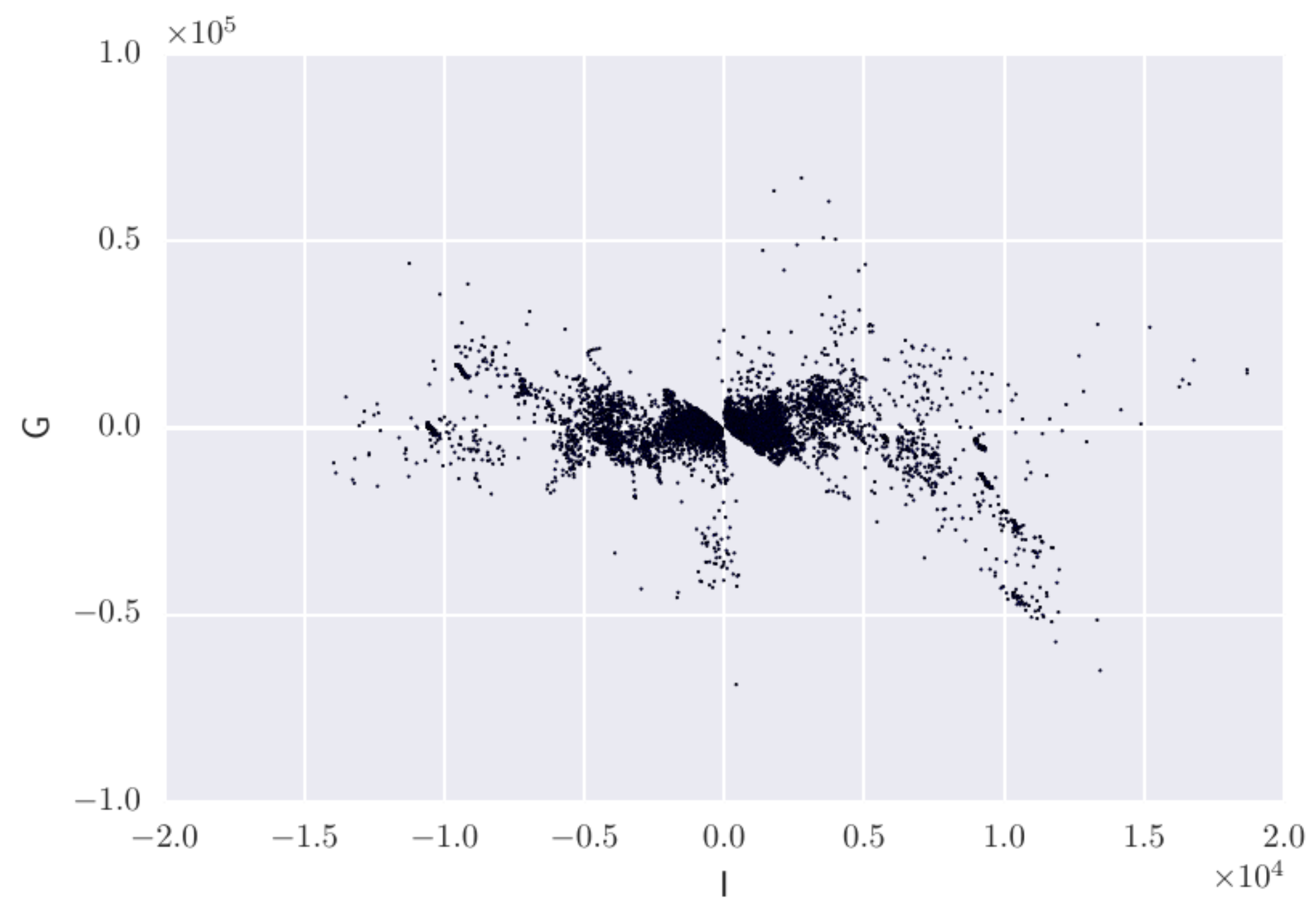
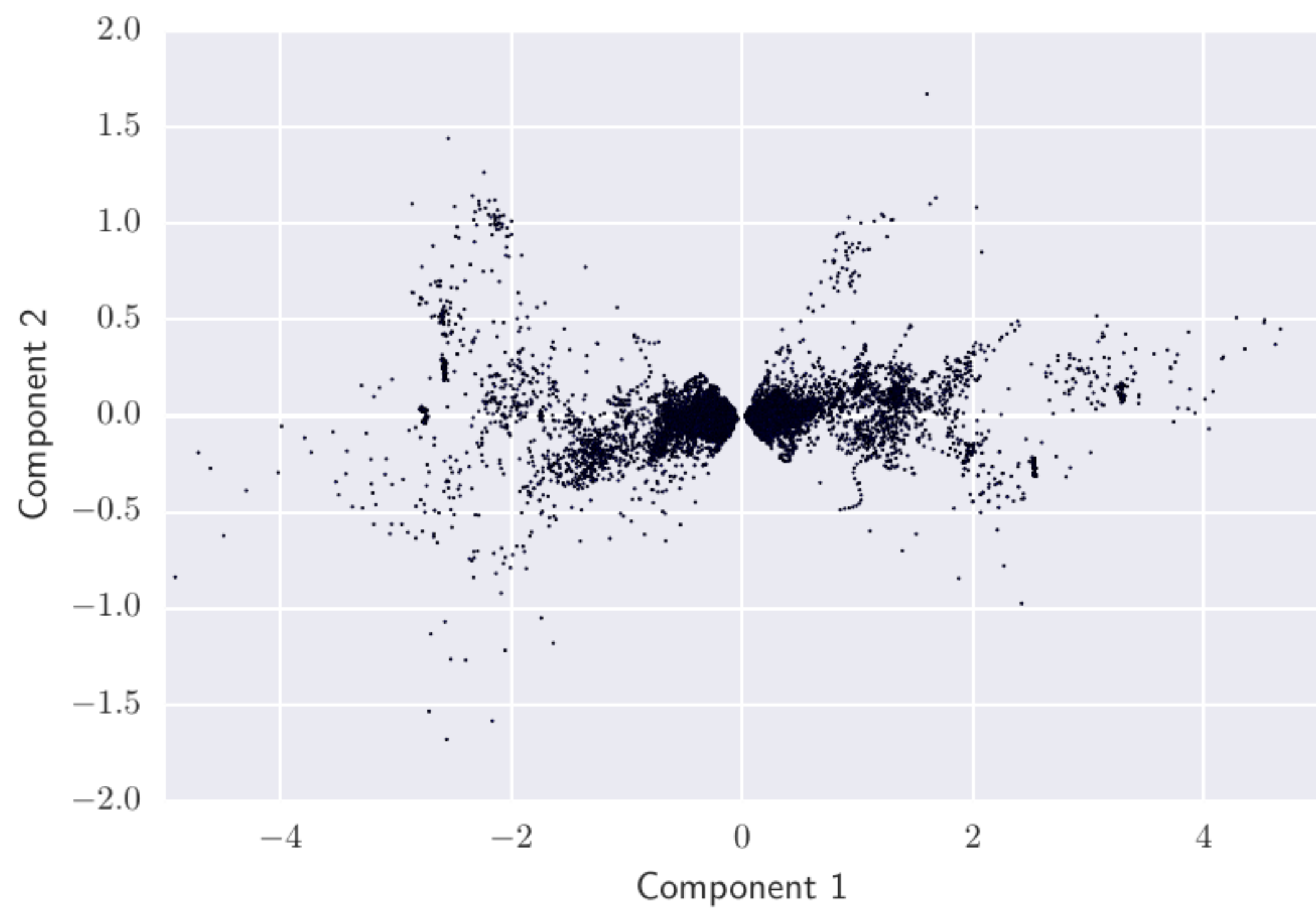
Maximizes the variance (a measure of information).



# Crossplots of physically consistent data



# Crossplots of migrated data



# Kernel PCA

## **Problem:**

Find a non-linear projection that provides better discrimination of trends and outliers.

## **Solution:**

Use the “kernel-trick” to compute PCA in a high-dimensional non-linear feature space

## Kernel trick

PCA can be calculated from the Gramian inner product matrix:

$$XX^T = \begin{pmatrix} \langle \mathbf{x}_1, \mathbf{x}_1 \rangle & \langle \mathbf{x}_1, \mathbf{x}_2 \rangle & \dots & \langle \mathbf{x}_1, \mathbf{x}_n \rangle \\ \langle \mathbf{x}_2, \mathbf{x}_1 \rangle & \langle \mathbf{x}_2, \mathbf{x}_2 \rangle & \dots & \langle \mathbf{x}_2, \mathbf{x}_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{x}_n, \mathbf{x}_1 \rangle & \langle \mathbf{x}_n, \mathbf{x}_2 \rangle & \dots & \langle \mathbf{x}_n, \mathbf{x}_n \rangle \end{pmatrix}$$

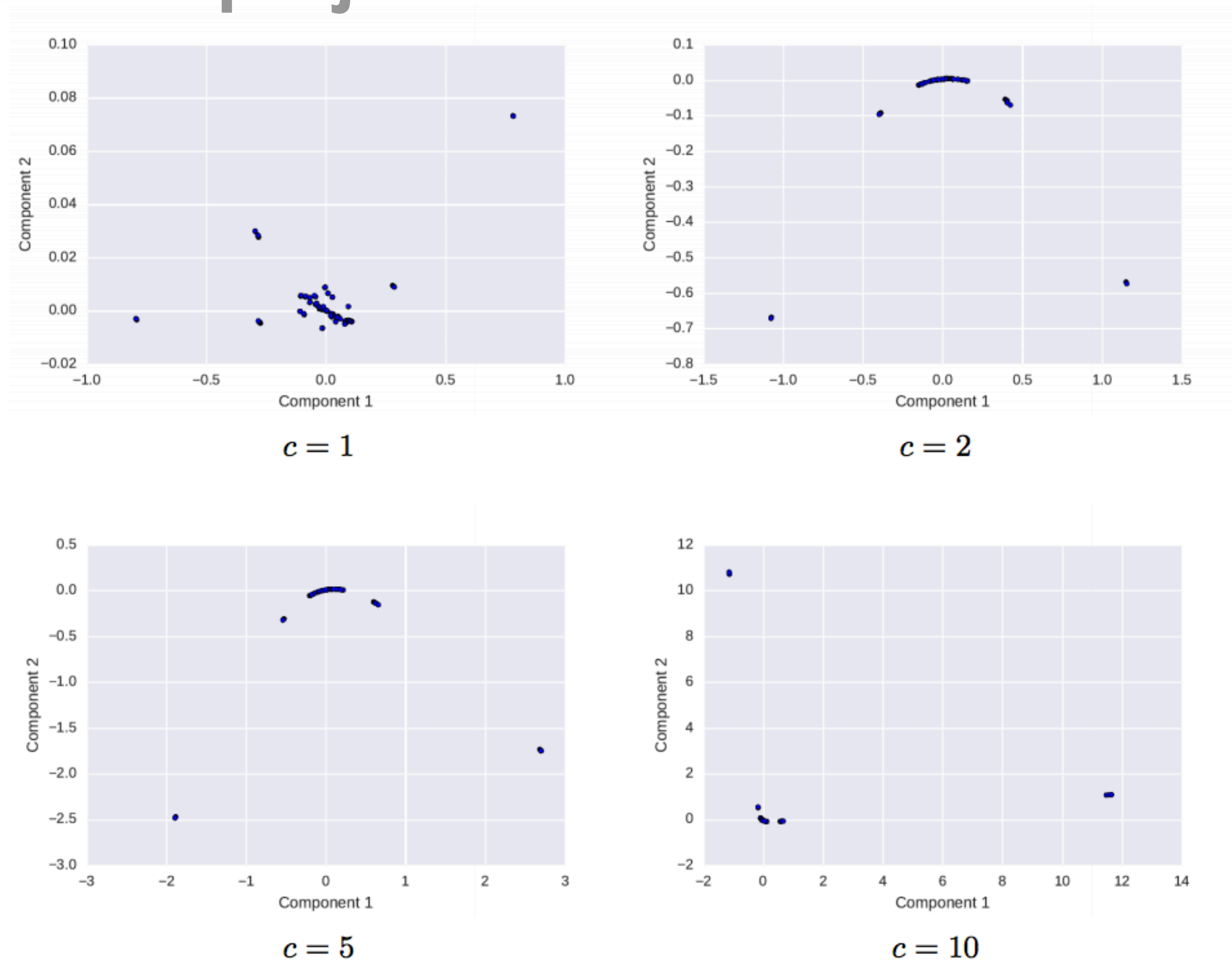
Replace  $\langle \mathbf{x}_i, \mathbf{x}_j \rangle$  with a kernel  $\kappa(\mathbf{x}_i, \mathbf{x}_j)$

$$\kappa(\mathbf{x}_i, \mathbf{x}_j) = (\mathbf{x}_i^T \mathbf{x}_j + b)^c = \langle \phi(\mathbf{x}_i), \phi(\mathbf{x}_j) \rangle$$

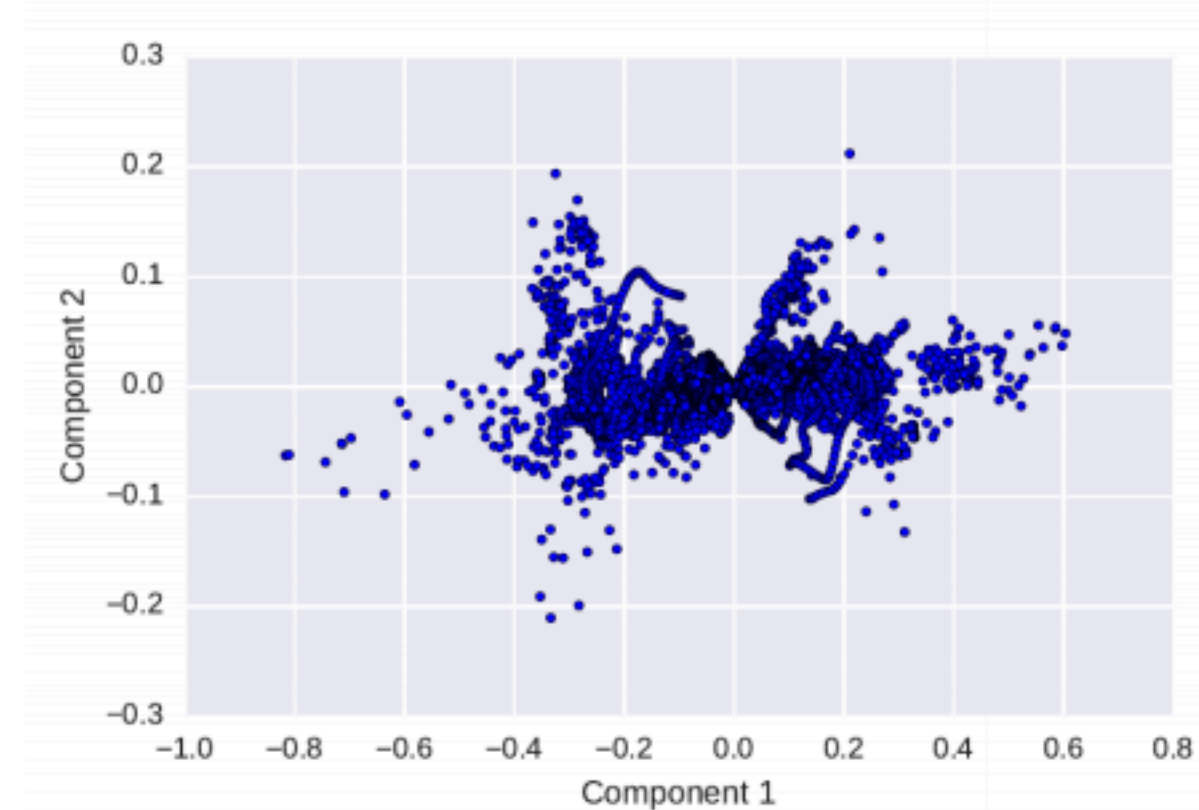
Example  $c=2, b=1$

$$\phi(\mathbf{x}) = [1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2]$$

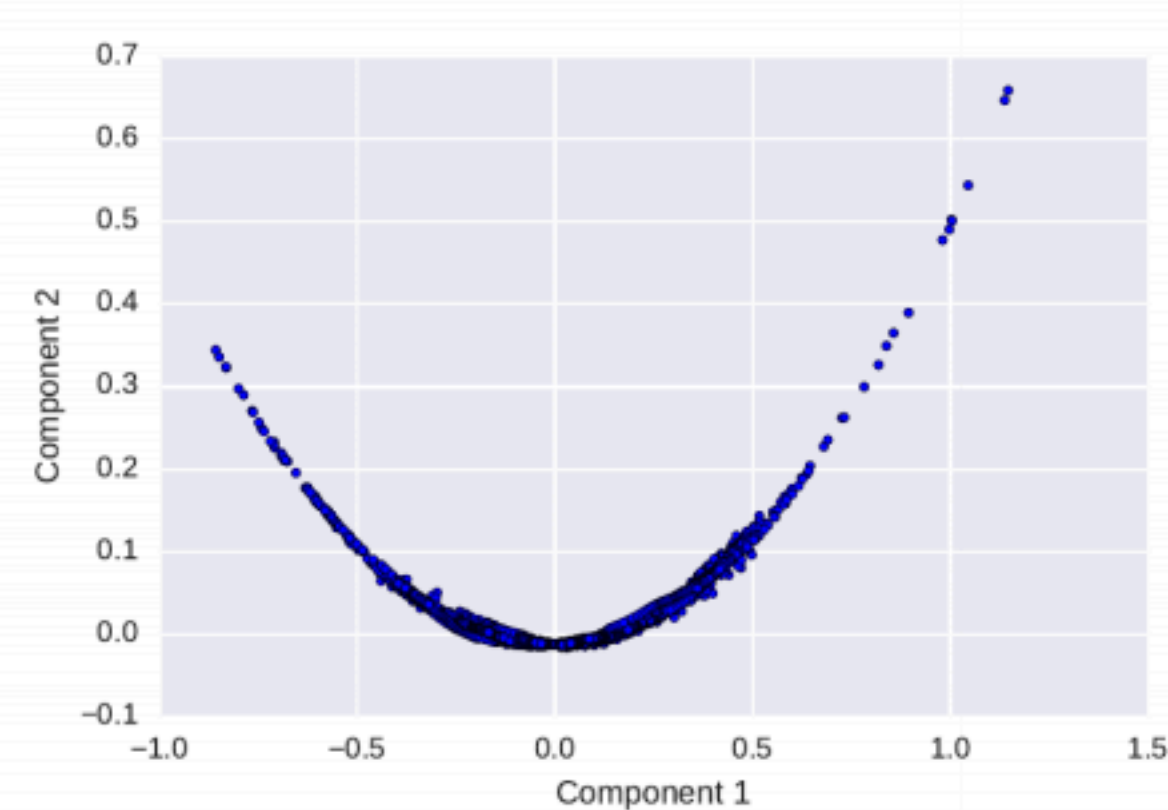
# Kernel PCA projections for consistent data



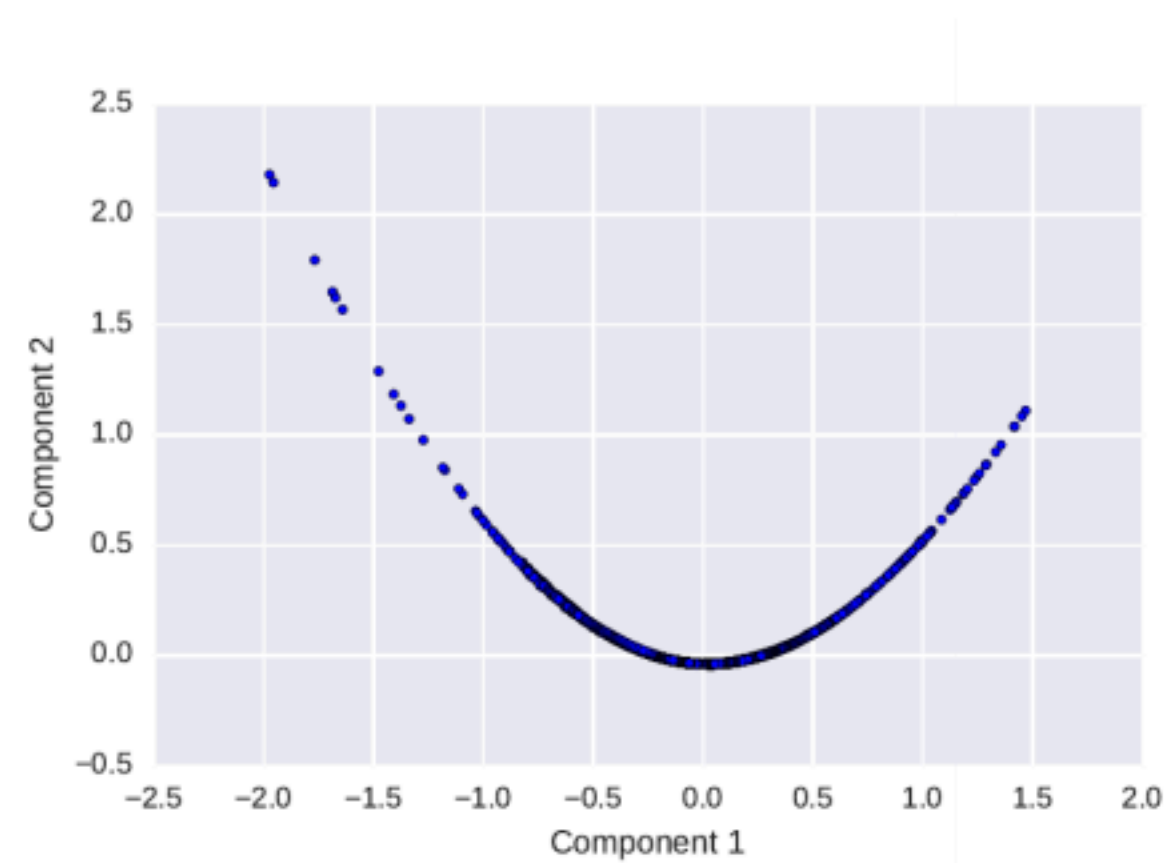
# Kernel PCA projections for migrated data



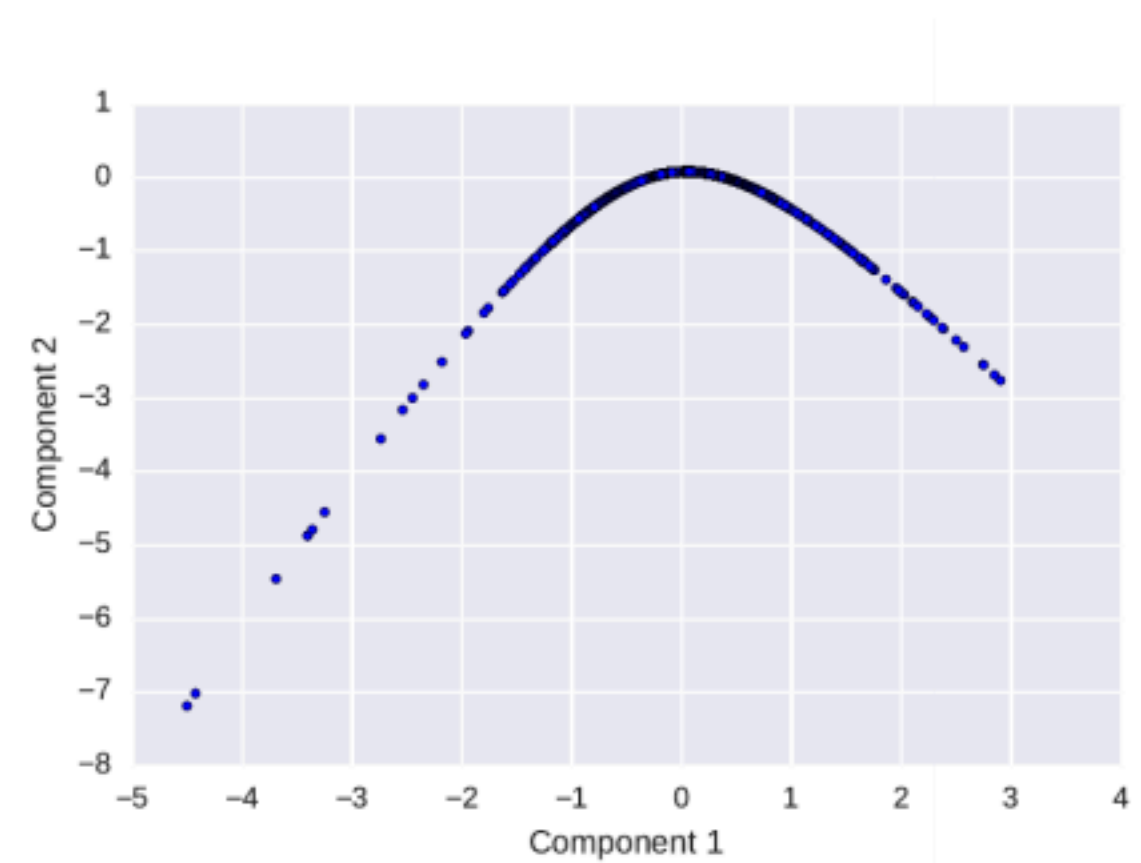
$c = 1$



$c = 2$



$c = 5$



$c = 10$

## Recap

**Situation:** Finding outlying responses in projected seismic data.

**Problem:** Physical projection can not explain the features in real data.

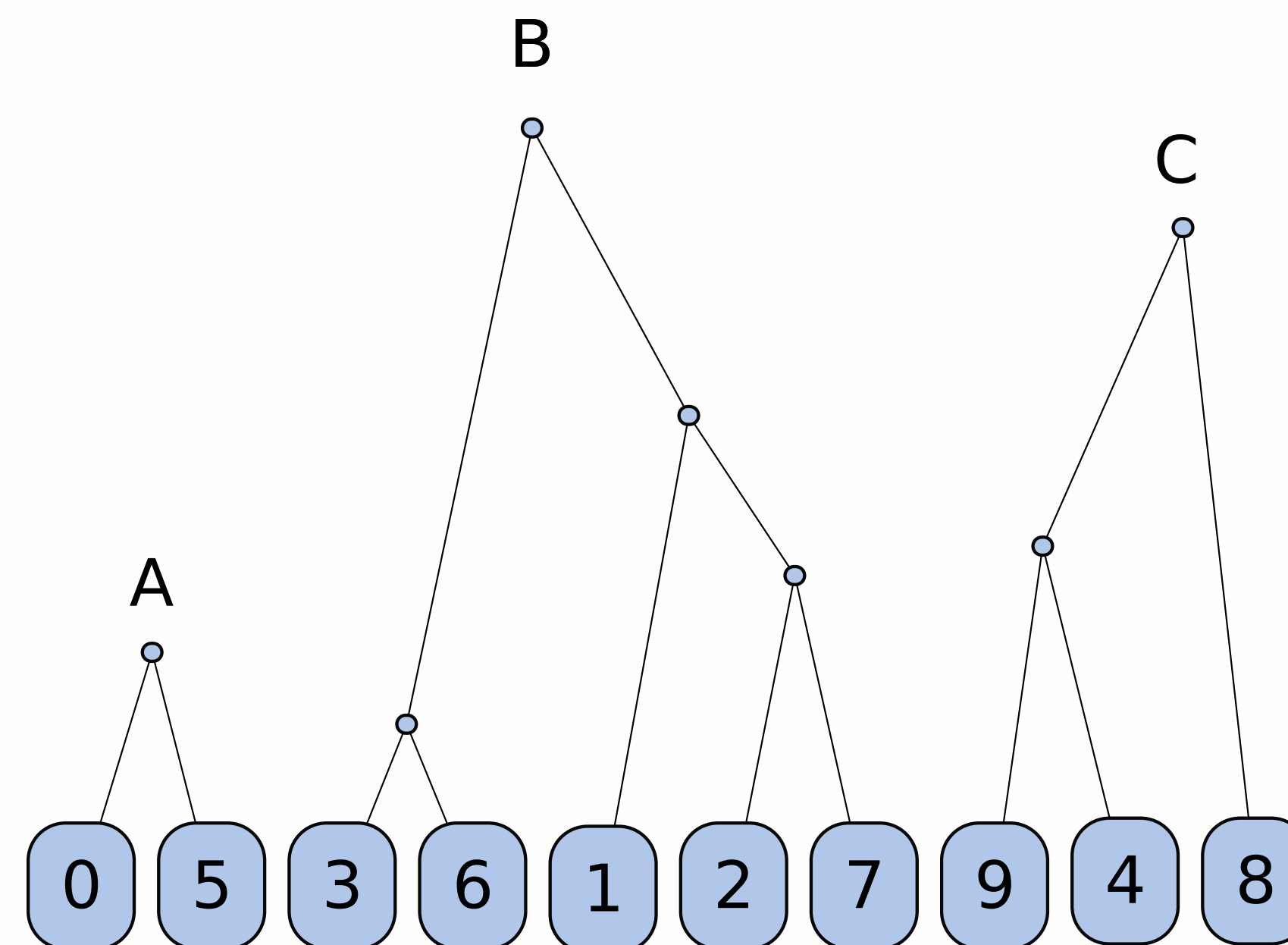
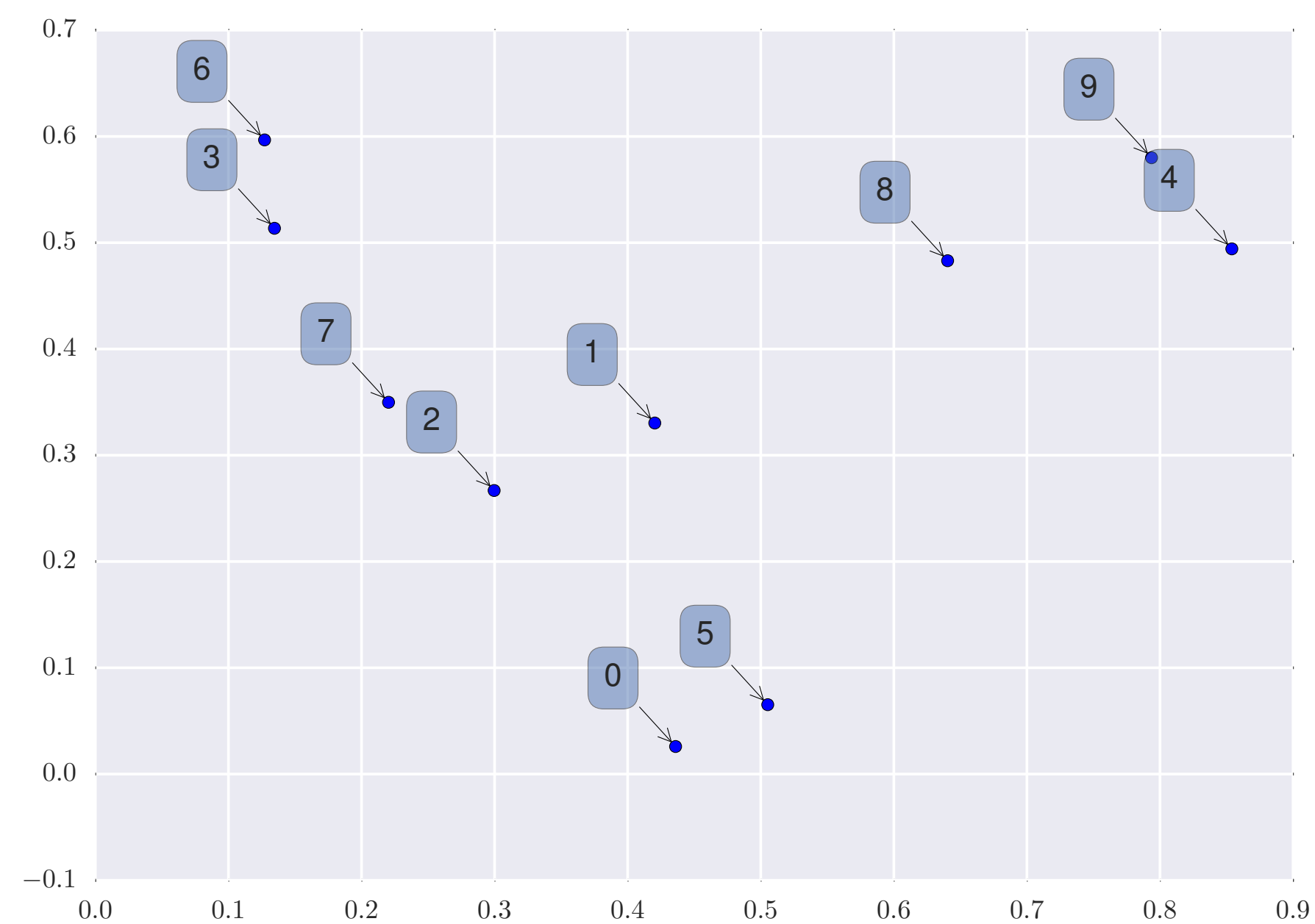
**Solution:** Use principle component-based projections.

### **Assessment:**

- PCA is equivalent for physically consistent data.
- PCA is more robust to processing/acquisition artifacts.
- Kernel PCA makes outliers linearly separable from the background.
- Lost direct link to rock physics.

**Next:** Automatic segmentation (clustering)

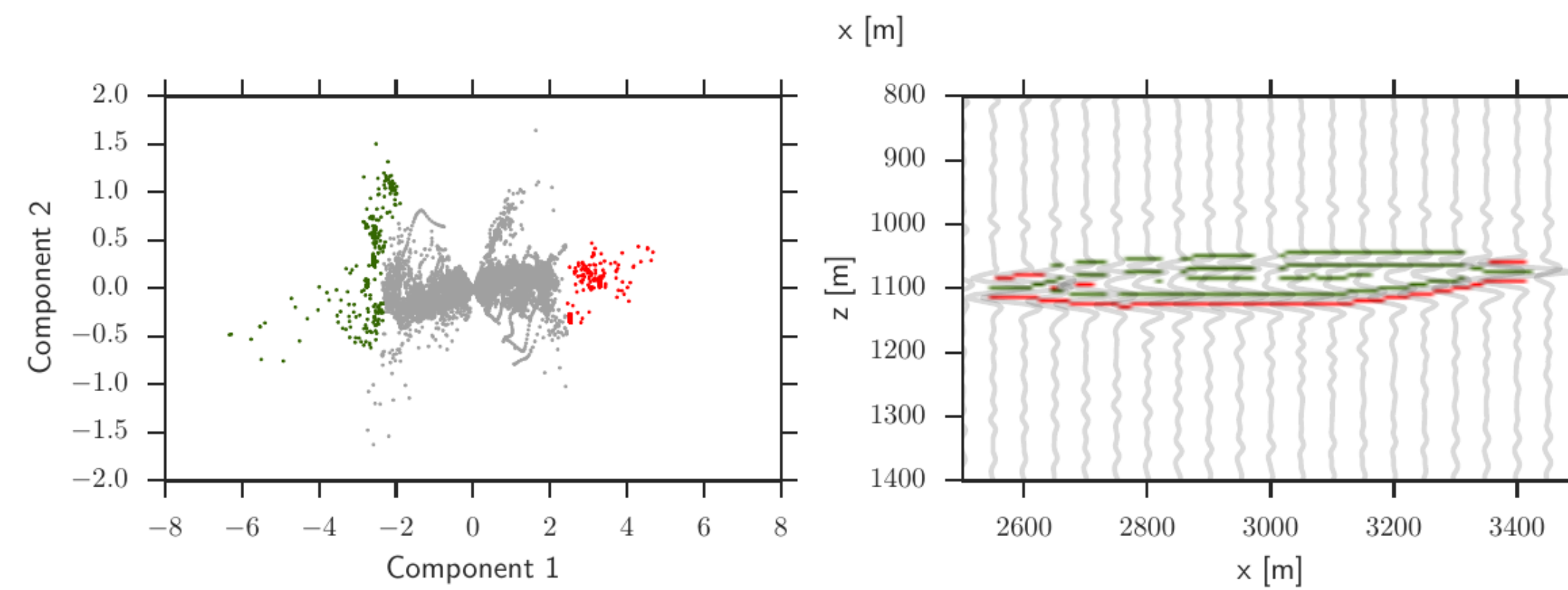
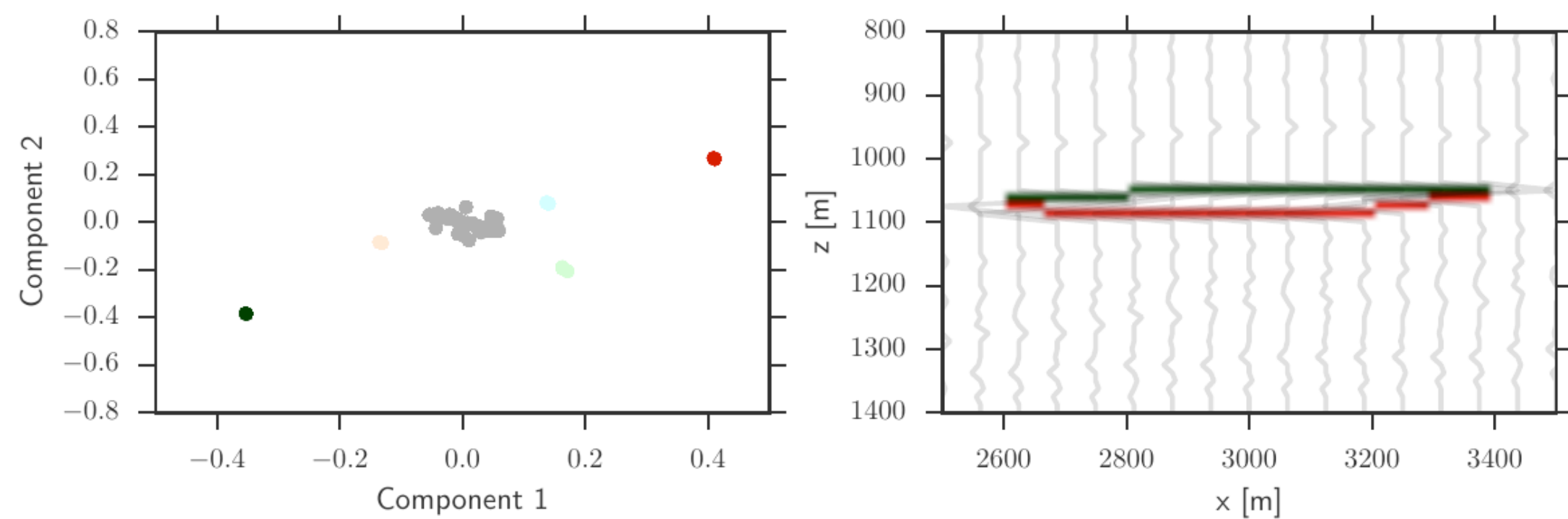
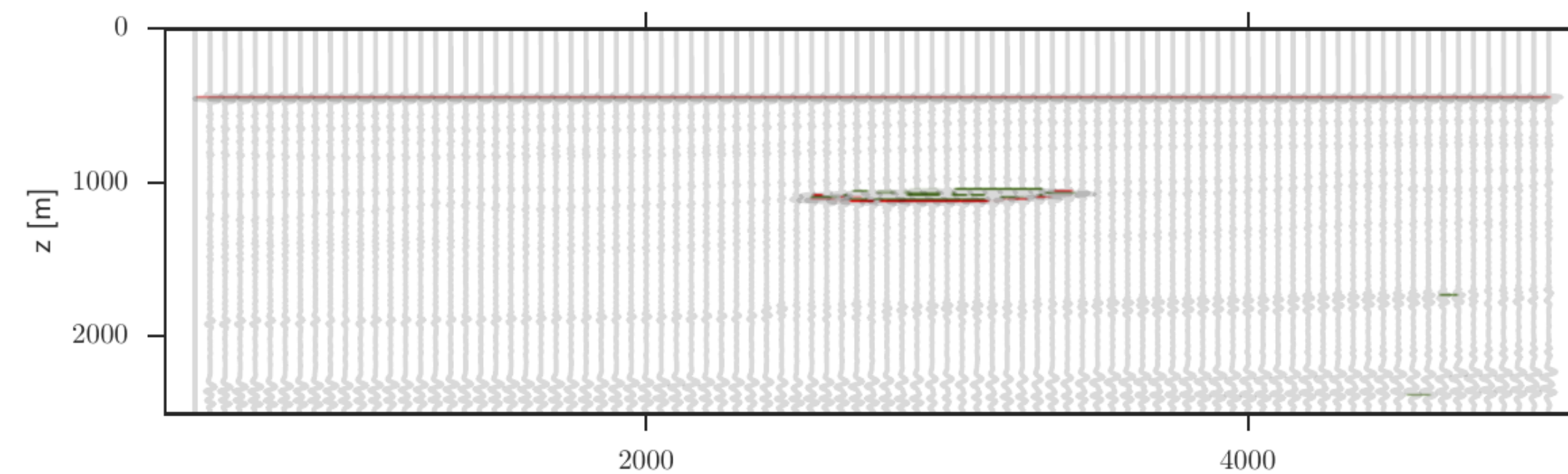
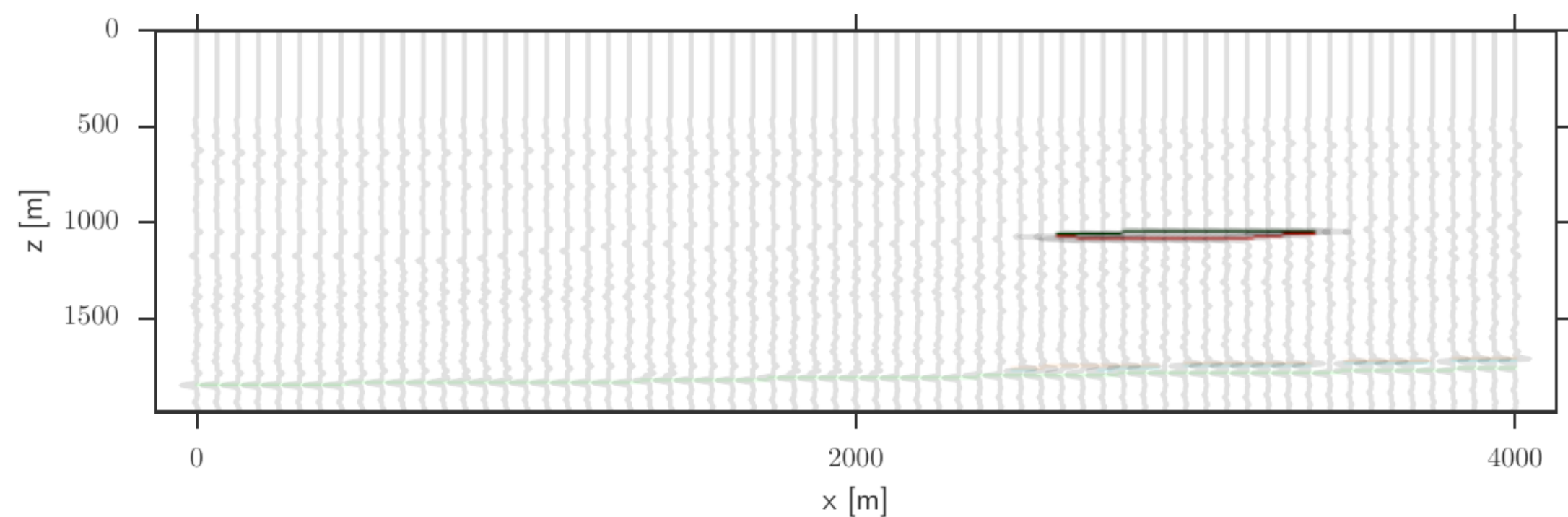
# Hierarchical clustering



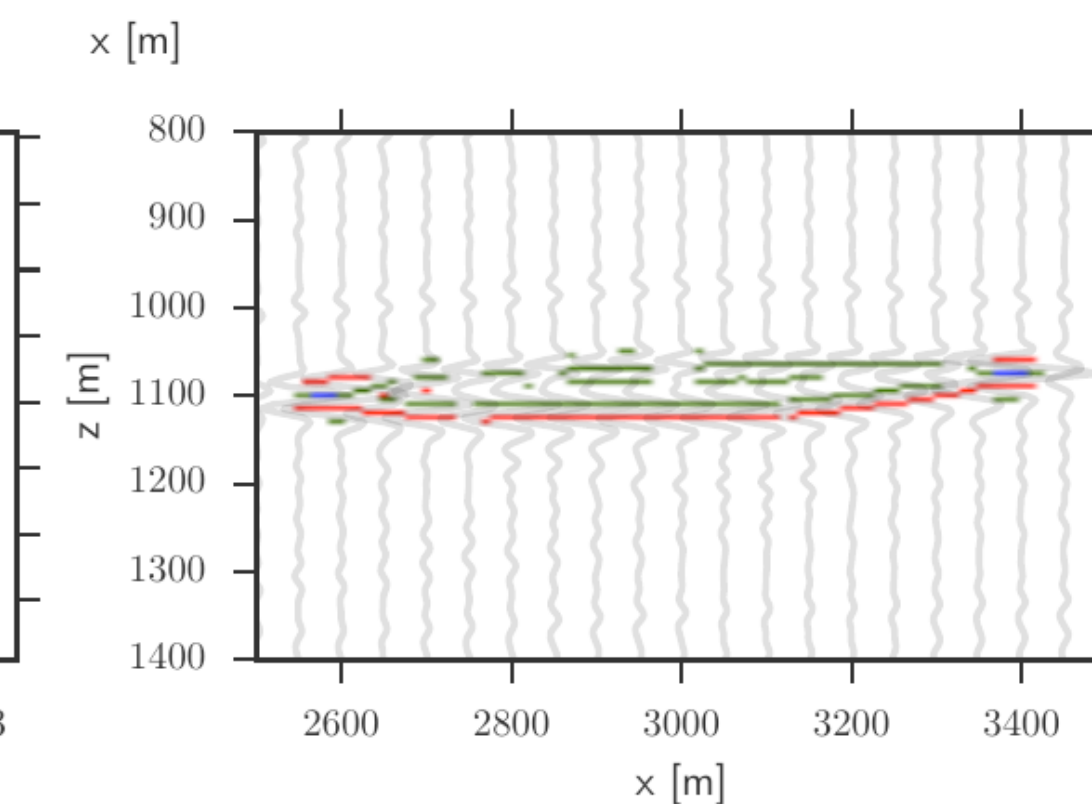
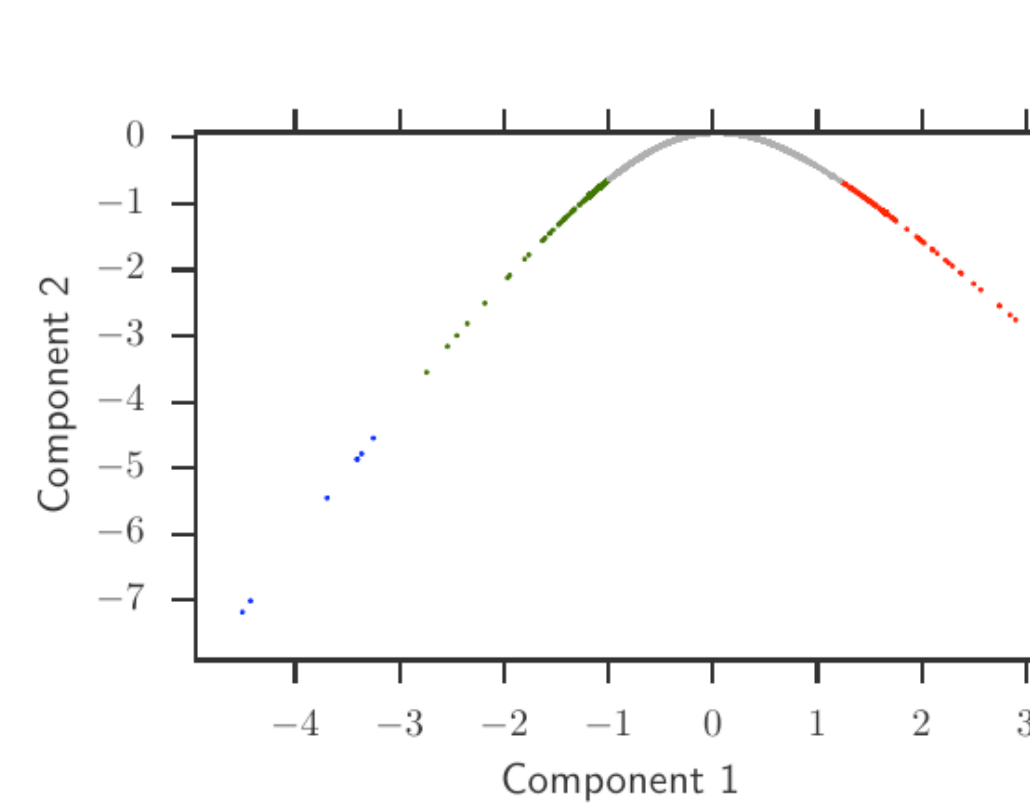
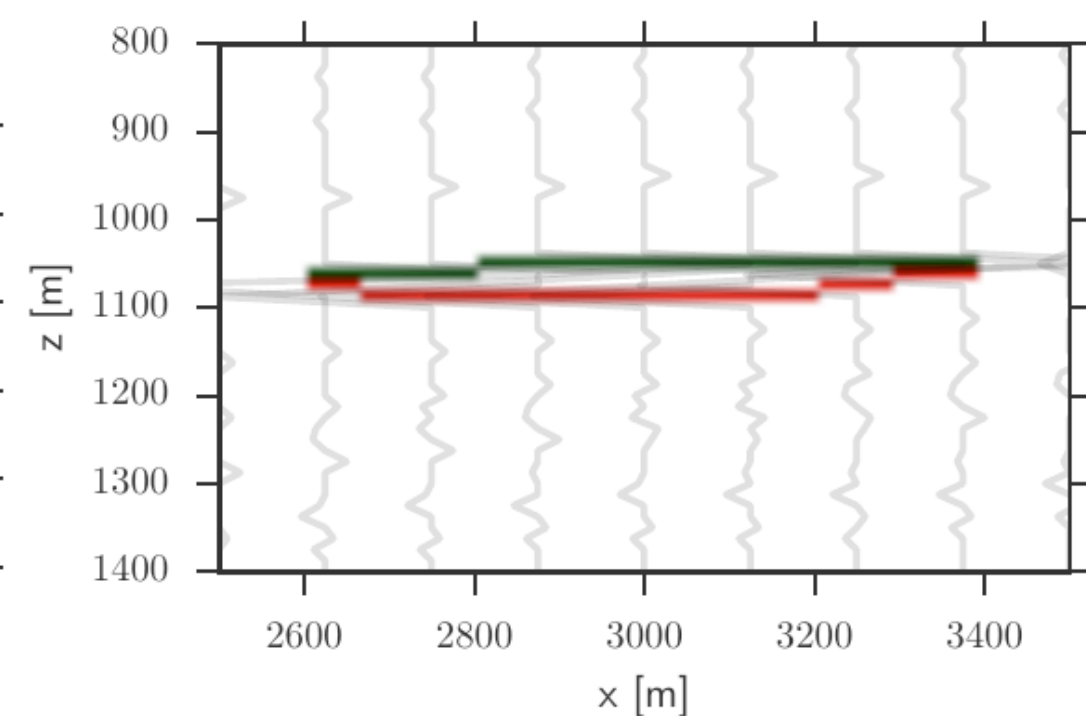
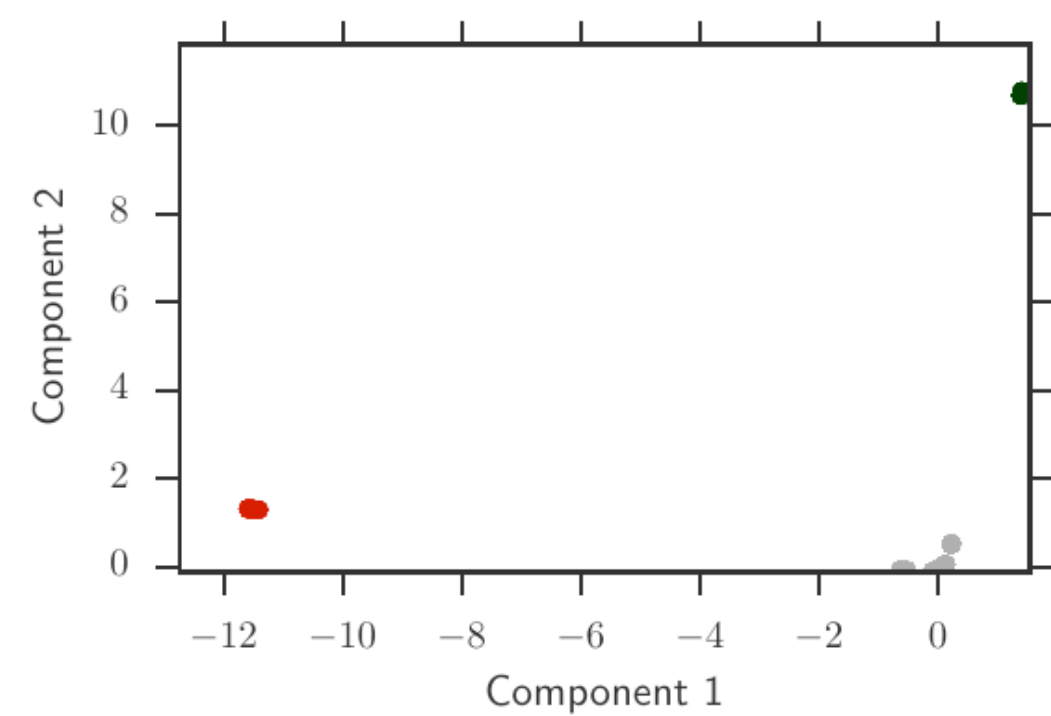
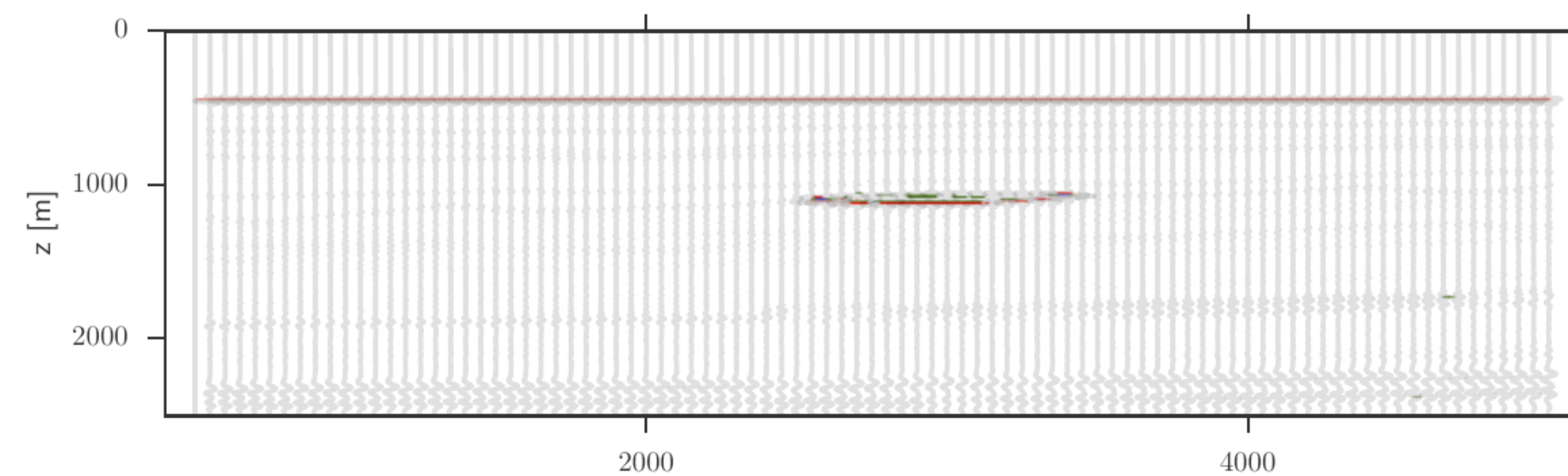
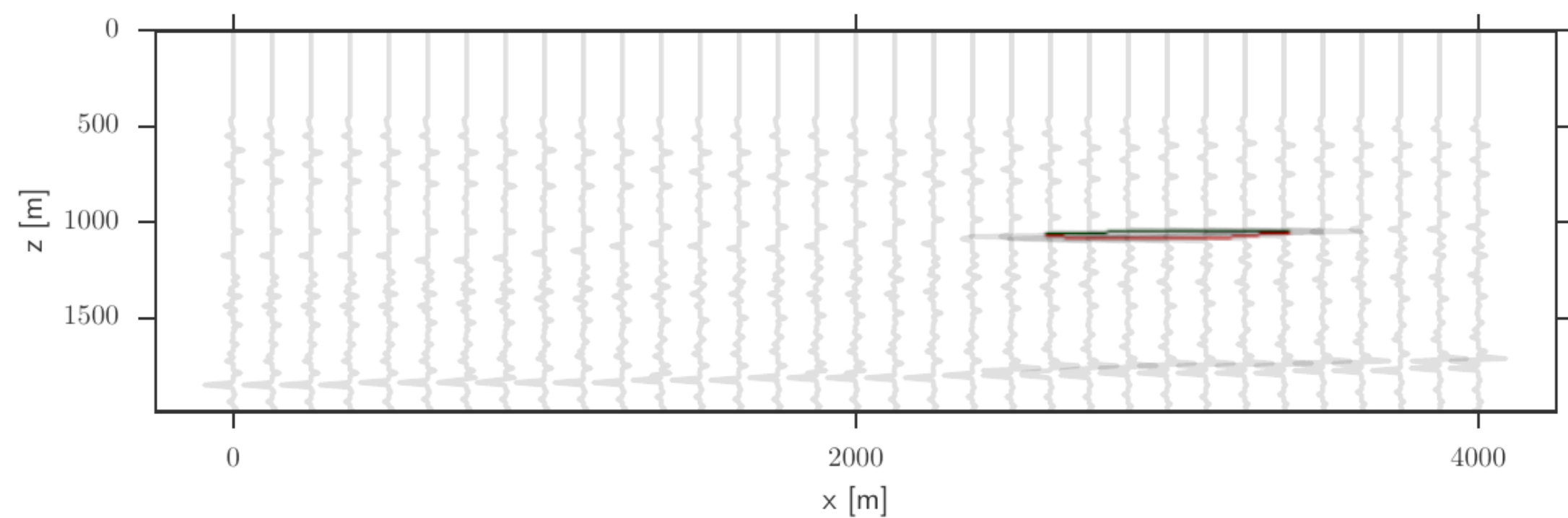
**BIRCH clustering, developed specifically for clustering large databases**



# Results - PCA



# Results - Kernel PCA



## Summary

### **Successes:**

Each projection could segment the reservoir.

Kernel PCA provided advantageous multivariate geometries (linearly separable).

### **Challenges:**

Manual tuning of clustering parameters.

Kernel PCA is expensive and lacks interpretation.

## Robust PCA

### **Problem:**

Find a sparse set of outlying reflectivity responses against a background trend.

### **Assumption:**

The background trend of similar curves is highly redundant, which forms a low rank matrix.

### **Solution:**

$$L + S = X$$

## Convex relaxation

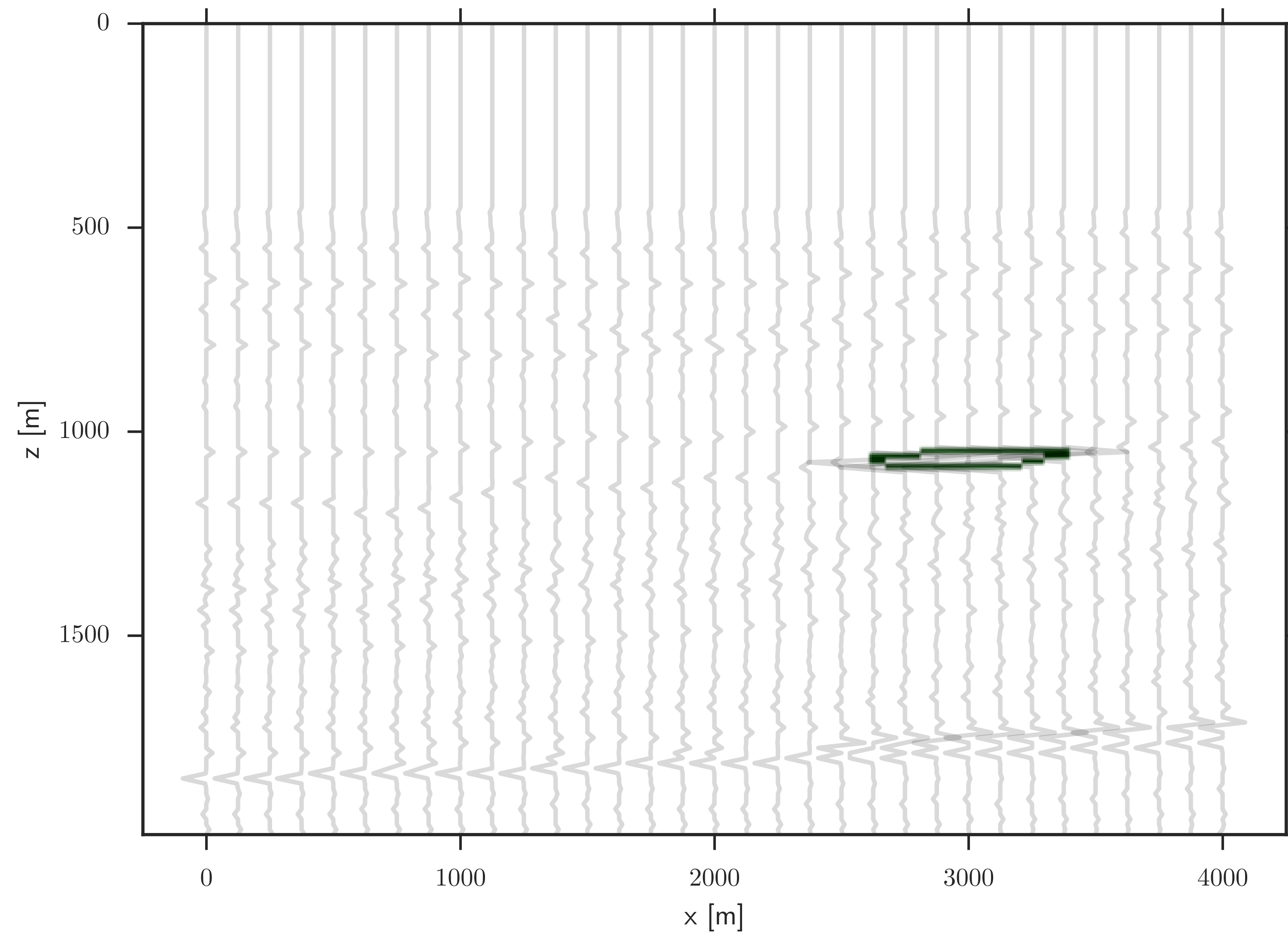
Rewrite with sparsity promoting convex terms:

$$\min_{L,S} \|L\|_* + \lambda \|S\|_{1,\infty} \text{ s.t. } L + S = X$$

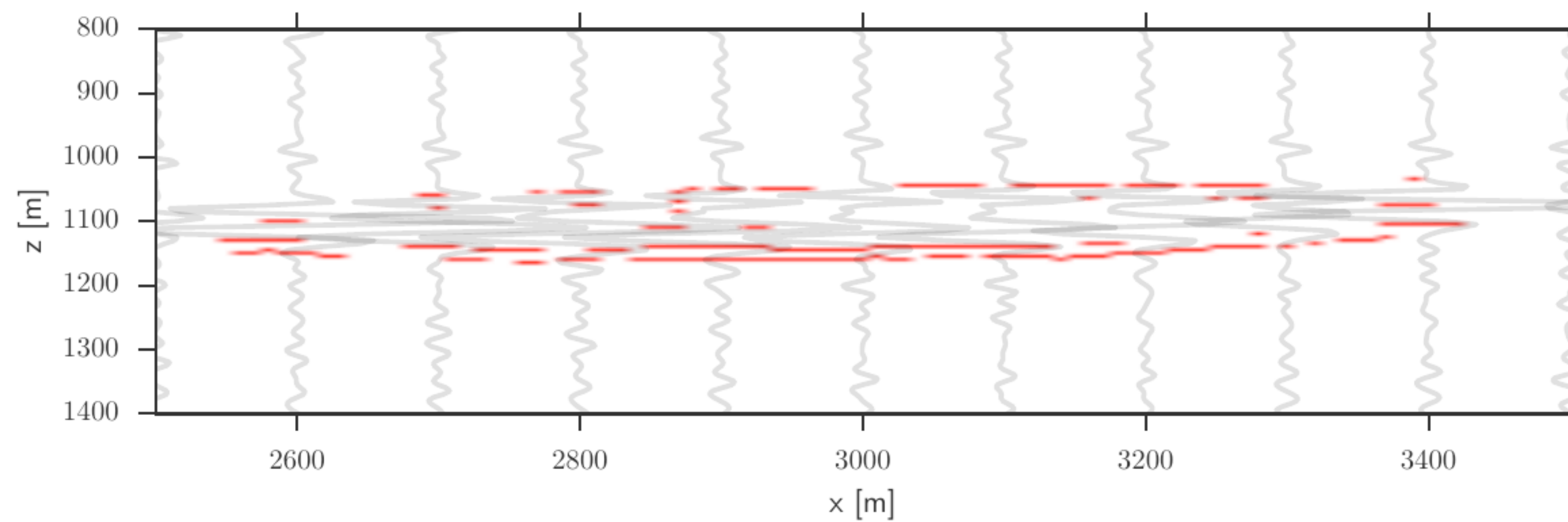
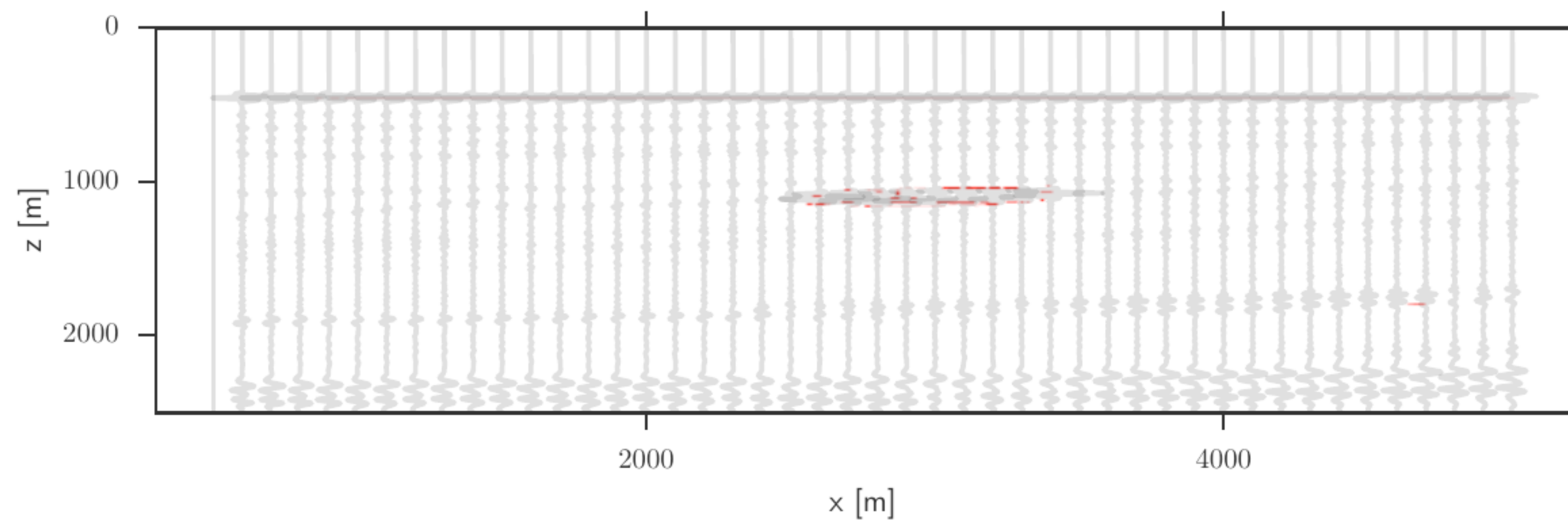
$$\|L\|_* = \text{trace}(\sqrt{L^*L}) = \sum_i \sigma_i = \|\sigma\|_1$$

Solved using alternating direction method of multipliers

# Results - physically consistent data



# Results - migrated seismic



## Summary

### **Successes:**

Segmentation of reservoir in both images.

Physically interpretable segmentation without clustering.

### **Challenges:**

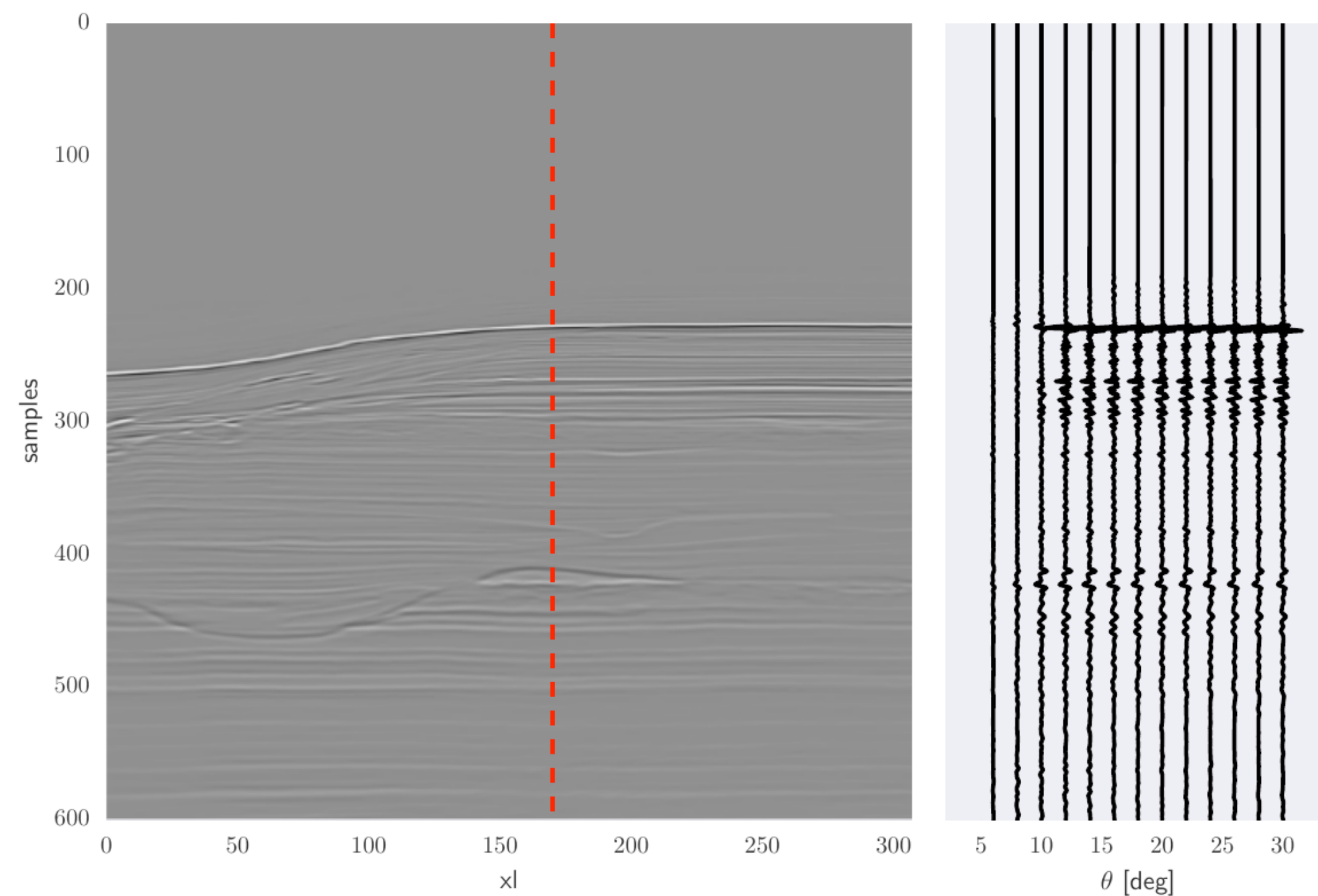
Requires tuning of one optimization trade off parameter.

Convergence sensitive to the rank of outliers, not well understood.



# Comparison on field data

Migrated data provided by BG group to compare algorithms



**Dynamic Intercept Gradient Inversion(DIGI)**

**Previous clustering based approaches were not successful.....**

**Compare robust PCA with BG's DIGI**  
**Extend DIGI to use principle components**

## DIGI-inverse problem

$$\begin{bmatrix} \mathbf{d} \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} W & W \sin^2 \theta \\ \lambda \nabla & \lambda \nabla \\ W(\theta_{me}) \cos(\chi_{me}) & W(\theta_{me}) \sin(\chi_{me}) \end{bmatrix} \begin{bmatrix} \mathbf{i} \\ \mathbf{g} \end{bmatrix}$$

Convolution forward model:  $d(x, t, \theta) = w(x, t, \theta) * r(x, t, \theta)$

- *ill-posed*,  $\lambda \nabla$  term forces a smooth answer

Further augmented by extended elastic reflectivity (EER) term:

$$EER(\chi_{me}) = i \cos(\chi_{me}) + g \sin(\chi_{me})$$

- promotes correlation between  $i$  and  $g$
- $\chi_{me}$  is related a priori geological information

System is solved using the conjugate gradient based algorithm LSQR.

# Minimum energy projection

$$EER(\chi_{me}) = i \cos(\chi_{me}) + g \sin(\chi_{me})$$

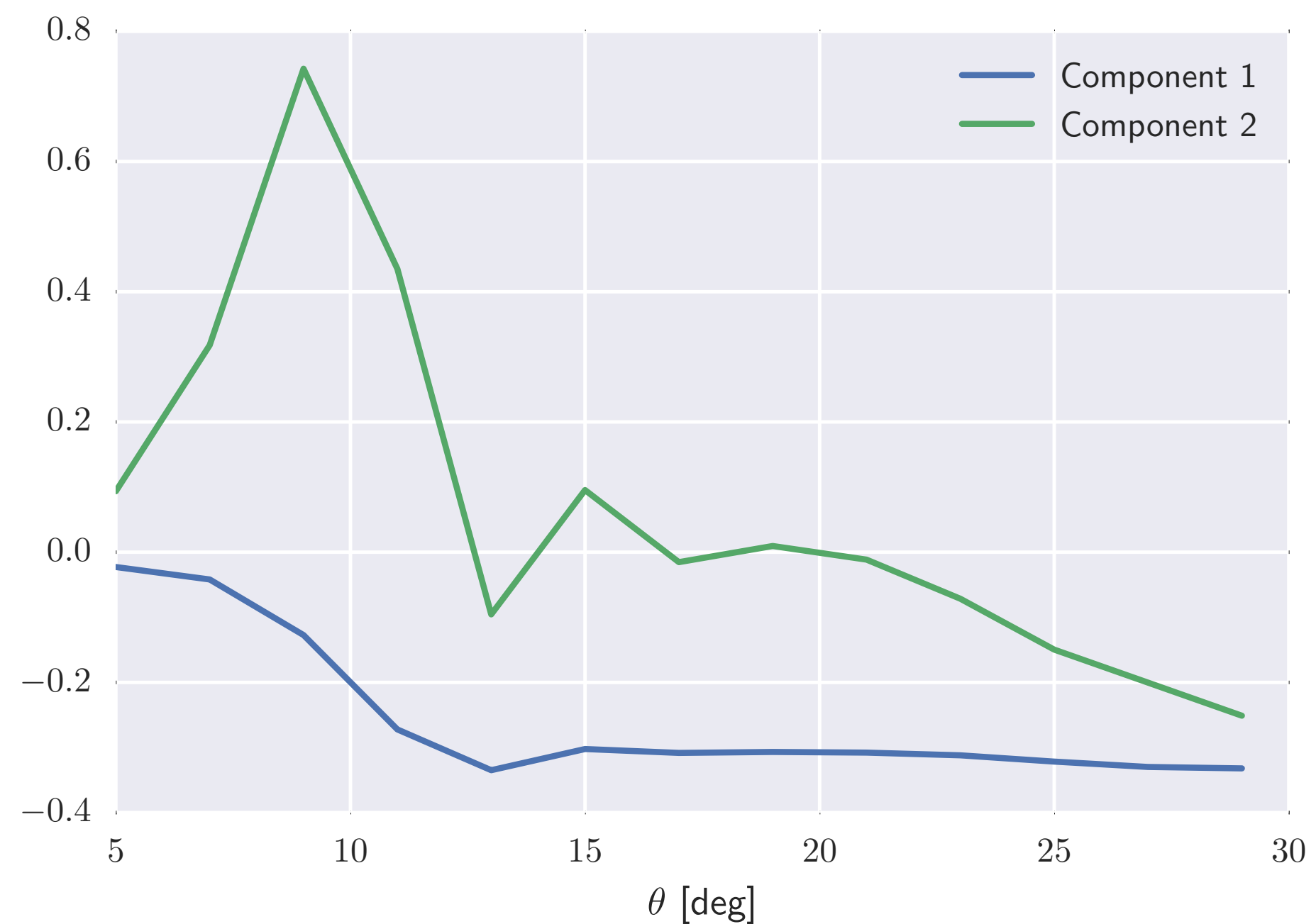
forms an image, where large values correspond to points where  $i$  and  $g$  are not correlated (outliers) along the projection  $\chi_{me}$ .

Thresholding this image results in a segmented image.

## PCA extended DIGI

$$\begin{bmatrix} \mathbf{d} \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} W \mathbf{c}_1 & W \mathbf{c}_2 \\ \lambda \nabla & \lambda \nabla \\ W(\theta_{me}) \cos(\chi_{me}) & W(\theta_{me}) \sin(\chi_{me}) \end{bmatrix} \begin{bmatrix} \mathbf{i} \\ \mathbf{g} \end{bmatrix}$$

Exact same algorithm, but use the principle components extracted directly from the data.



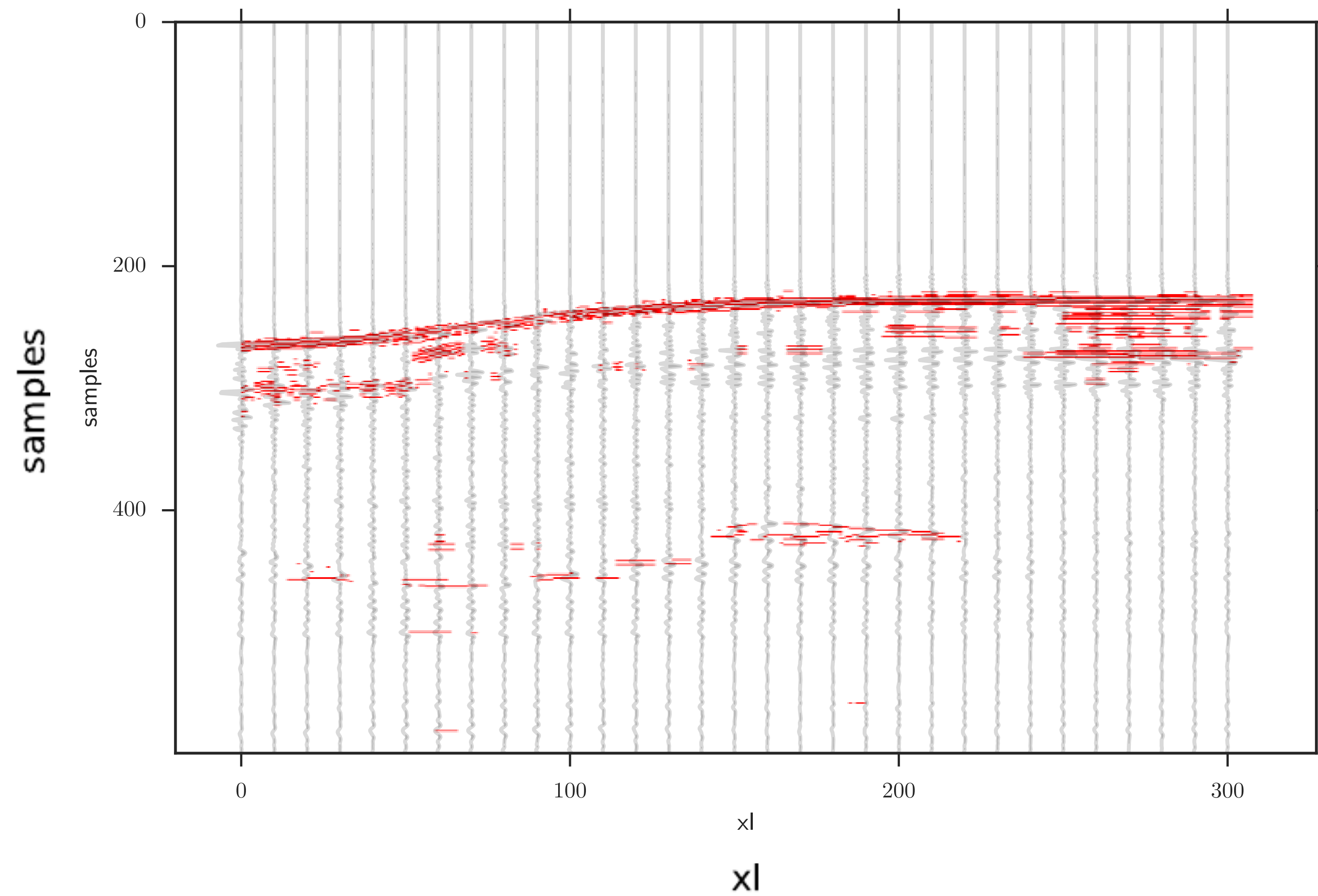
## Comparison method

Manually threshold the image to segment the potential hydrocarbon reserve while maintaining the least amount of spurious segmentation.

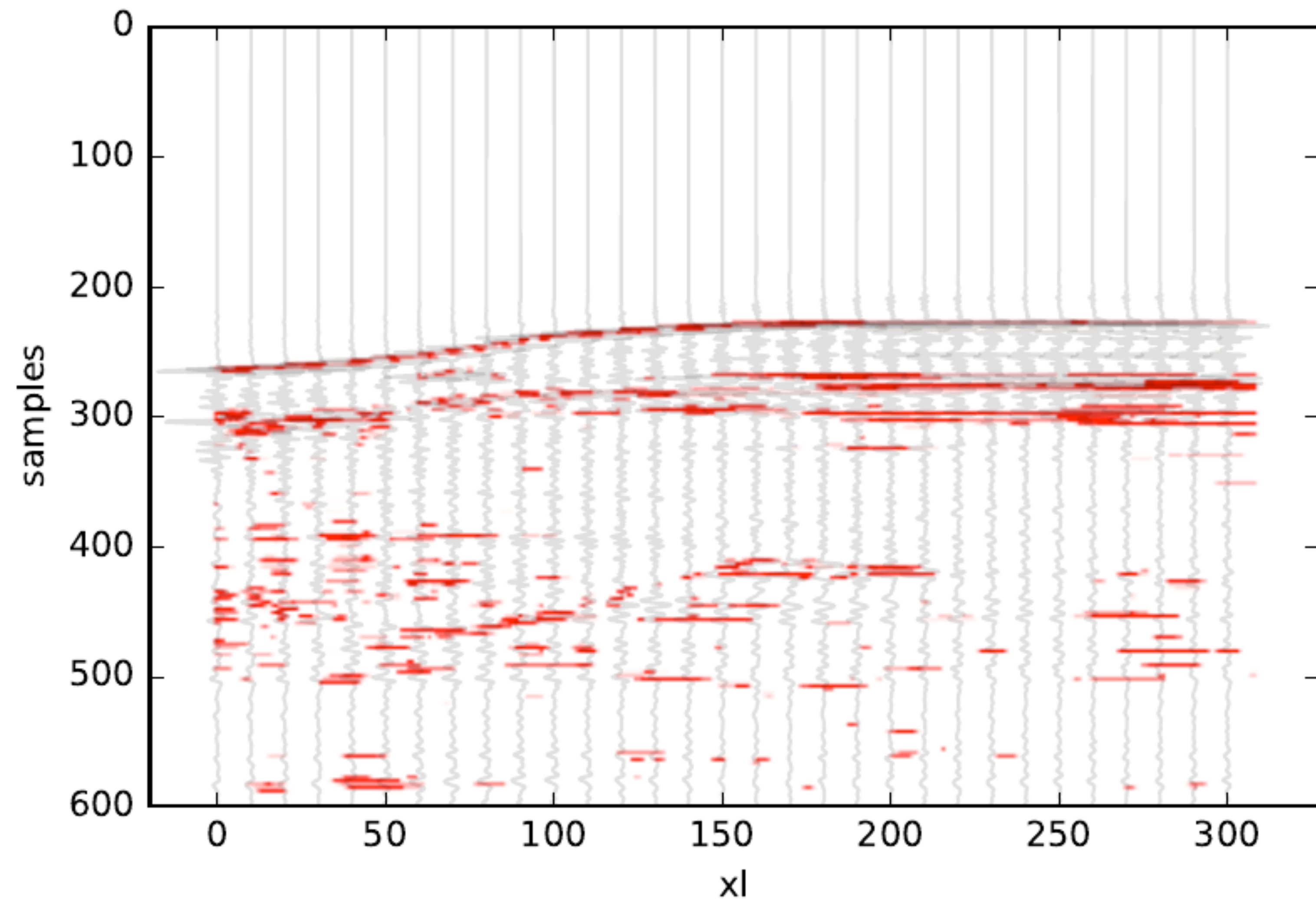
Compare:

- Robust PCA
- DIGI
- PCA extended

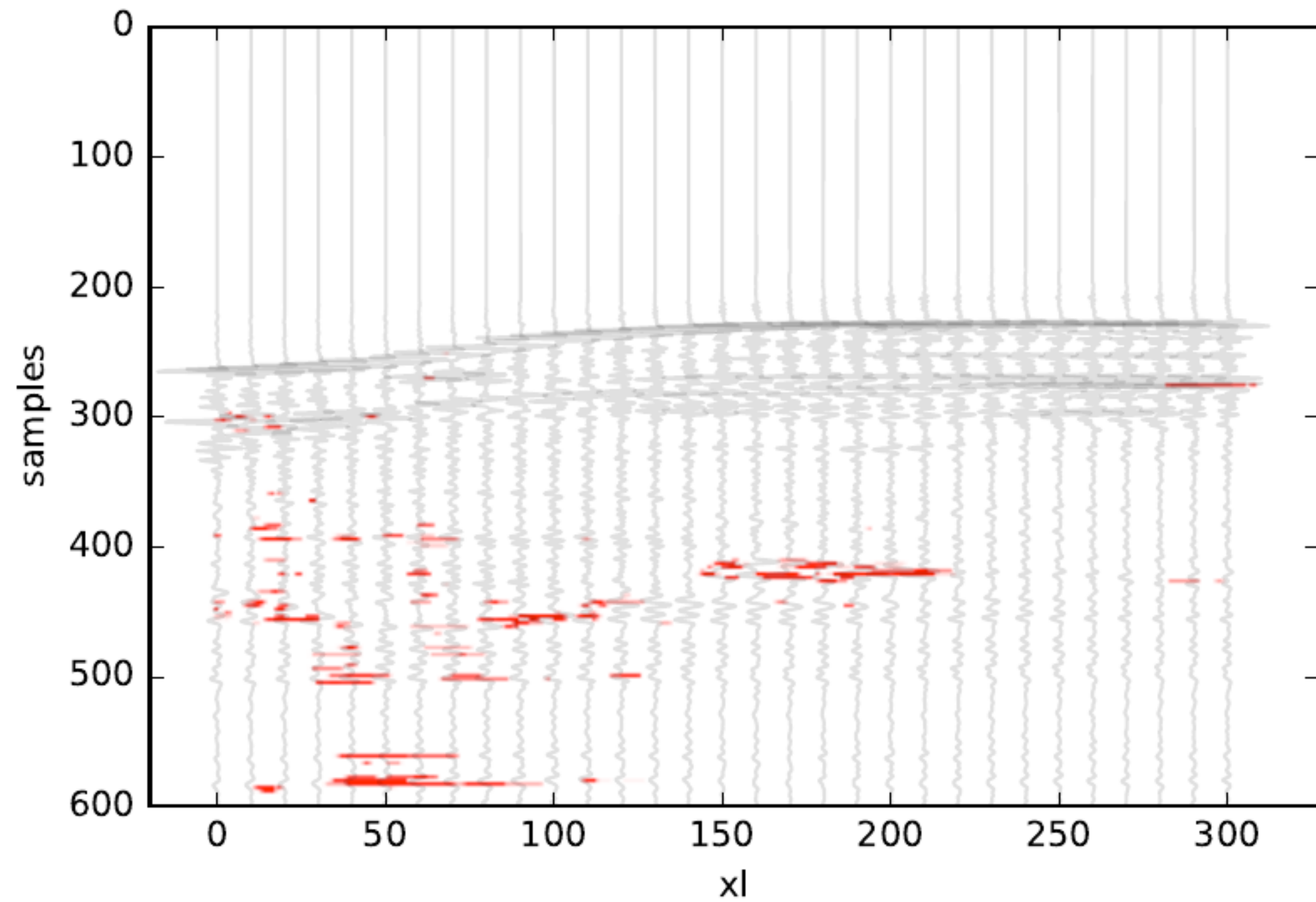
# Results - robust PCA



# Results - DIGI

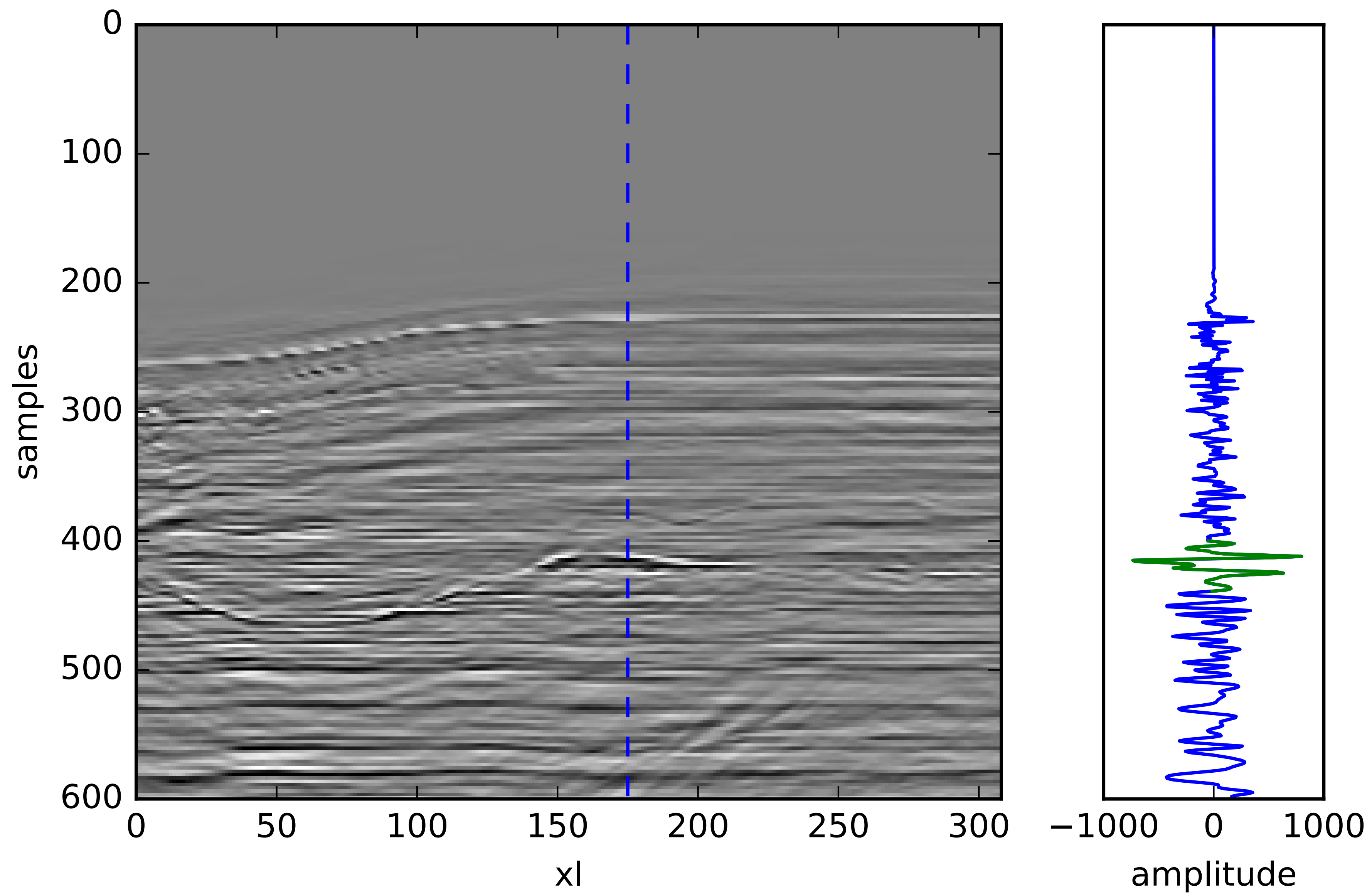


# Results - PCA extend DIGI

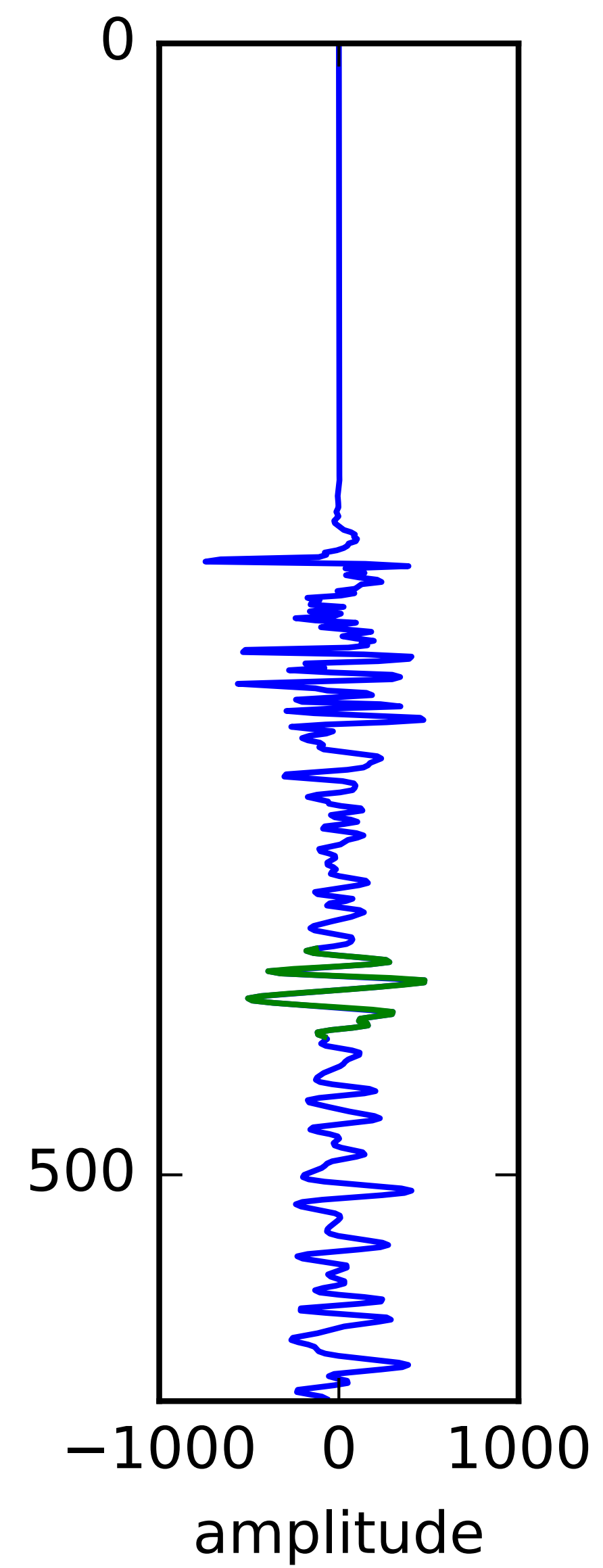
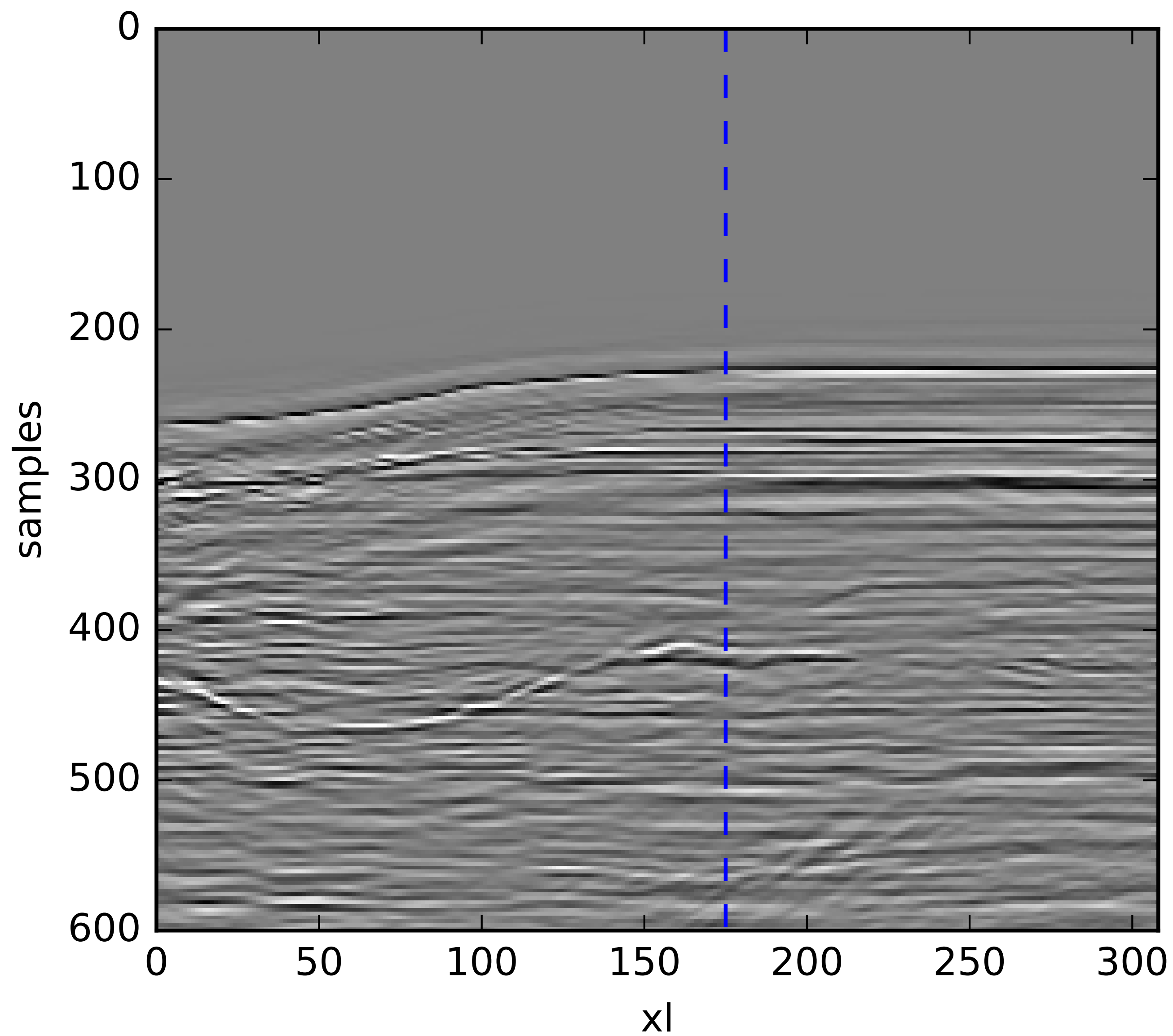




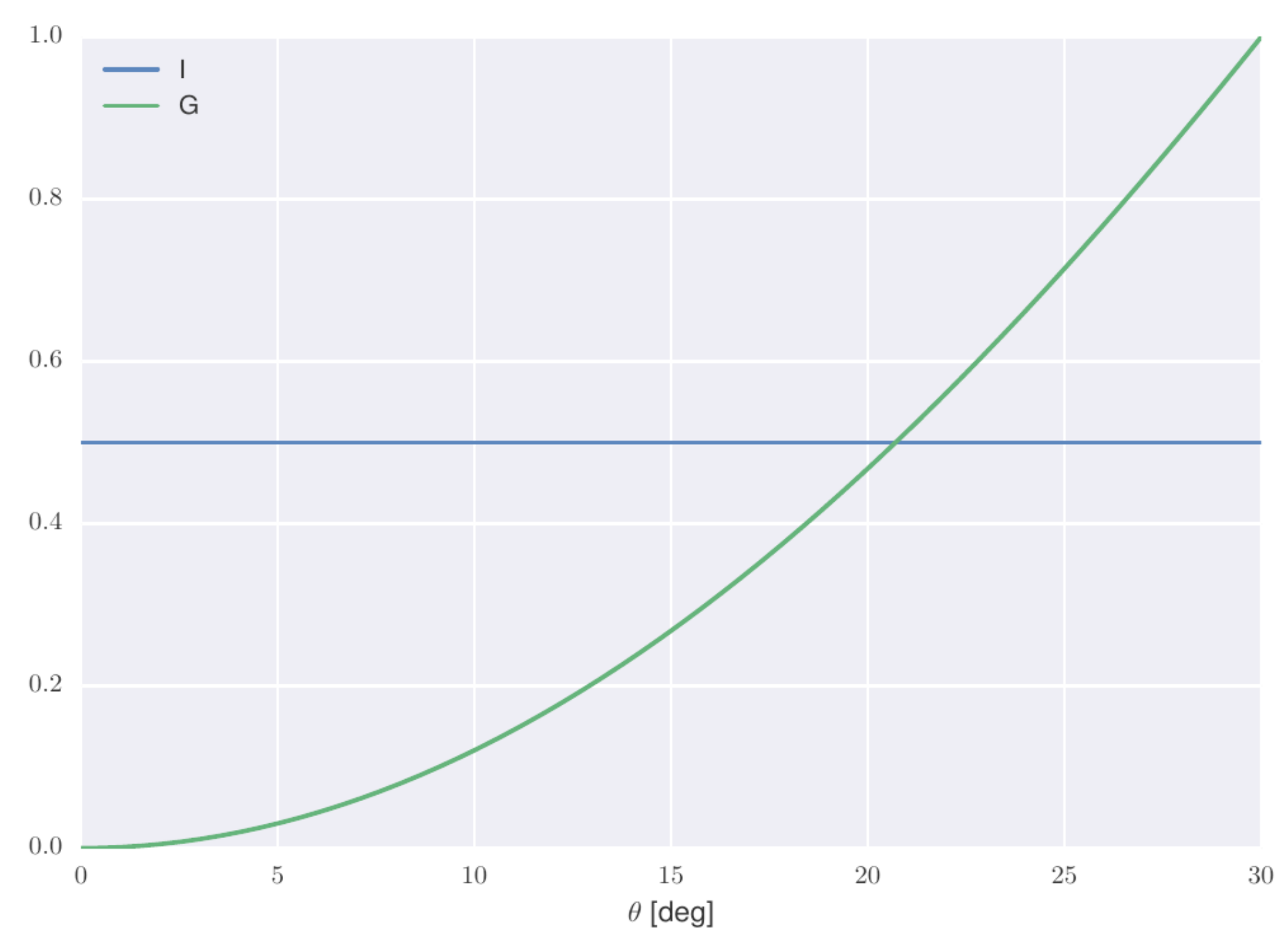
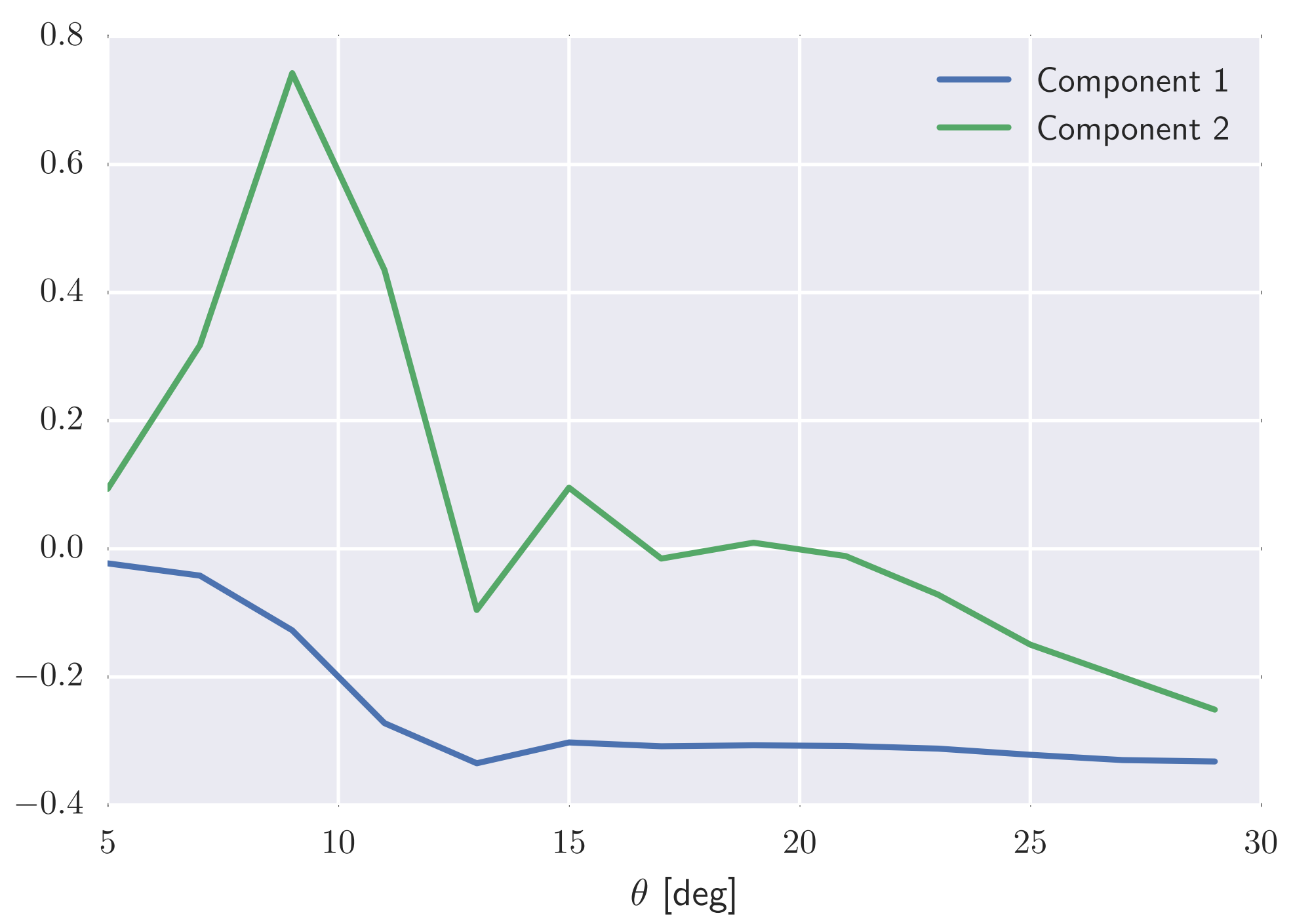
# Results - PCA extended DIGI



# Results - DIGI



# Why the difference?



## Summary

- Robust PCA provided the best image segmentation.
- PCA extended DIGI better separated the potential reservoir from the background trend.
- The extracted principle components showed significantly different shapes than the Shuey vectors.

# Epilogue

## **Outcome:**

Generalized a conventional analysis approach using unsupervised learning models.

Successful in segmented potential hydrocarbon reserves from seismic data

## **Future:**

More data, standardized datasets

Quantitative benchmarks

## References

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