

# Off the grid tensor completion for seismic data interpolation

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# Motivation

## 3D seismic experiments - 5D data

- expensive to acquire, store
- sample at *sub-Nyquist* rates

## Data exhibits *low-rank* structure

- exploit structure for interpolation

## Fully sampled data

- simultaneous sources in wave-equation based inversion
- mitigating multiples

# Motivation

## Standard matrix, tensor completion

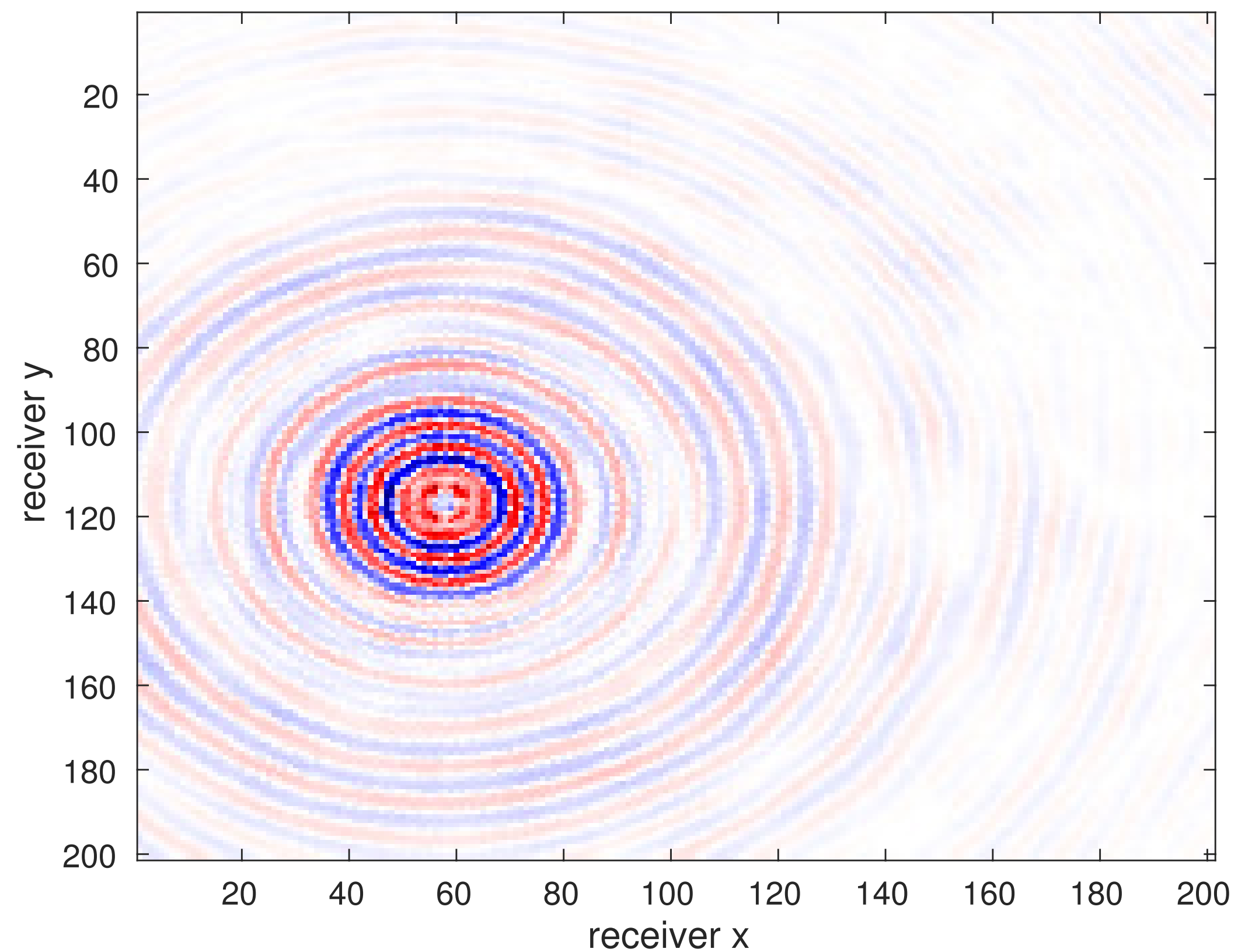
- defined on a regularly spaced grid
- sampling removes points from this regular grid

## Degraded results in practice

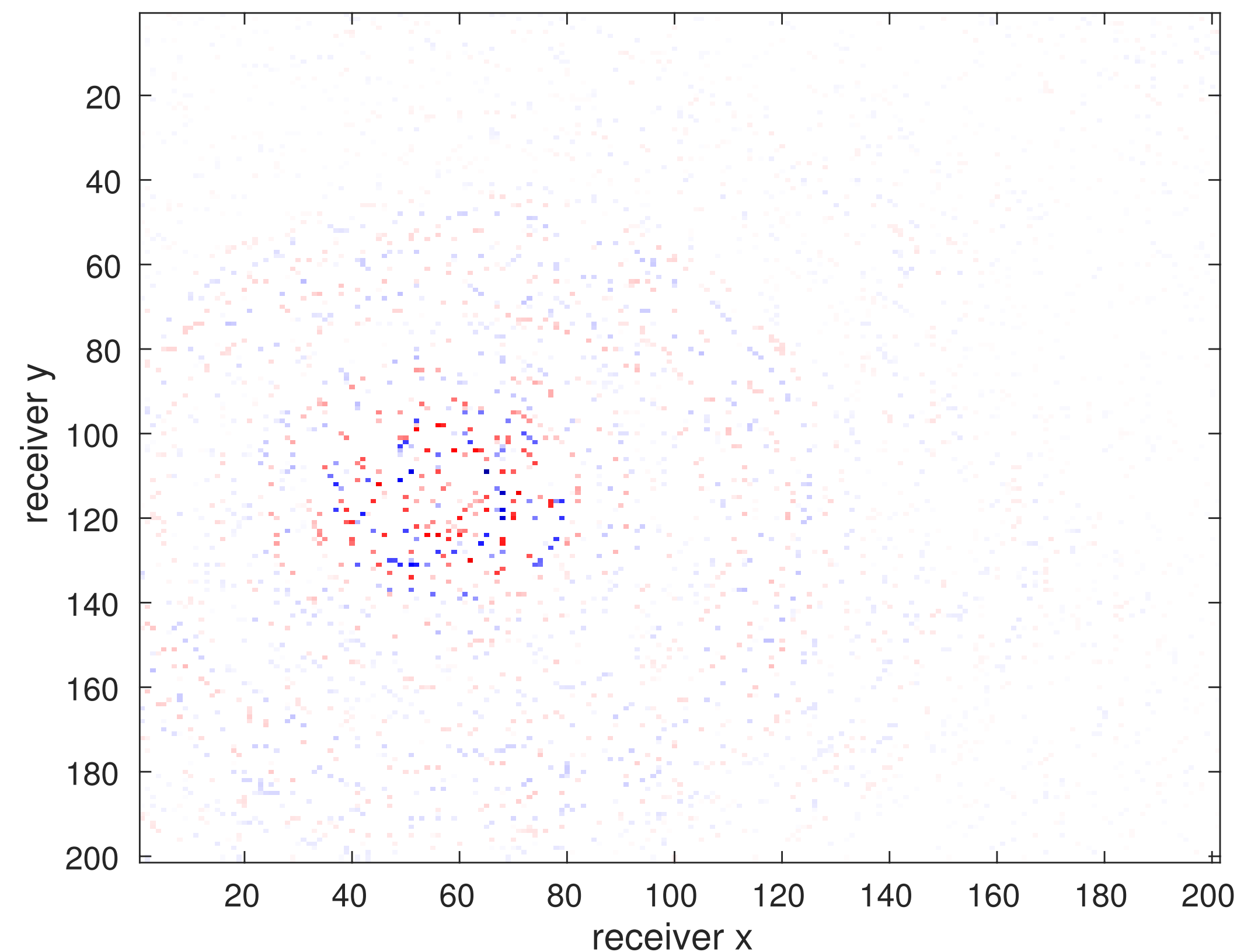
- very difficult to sample regularly in practice
- irregular “off-the-grid” sampling destroys low-rank behaviour

# 7.34 Hz - 90% missing receivers - irregular sampling

*Common source gather*



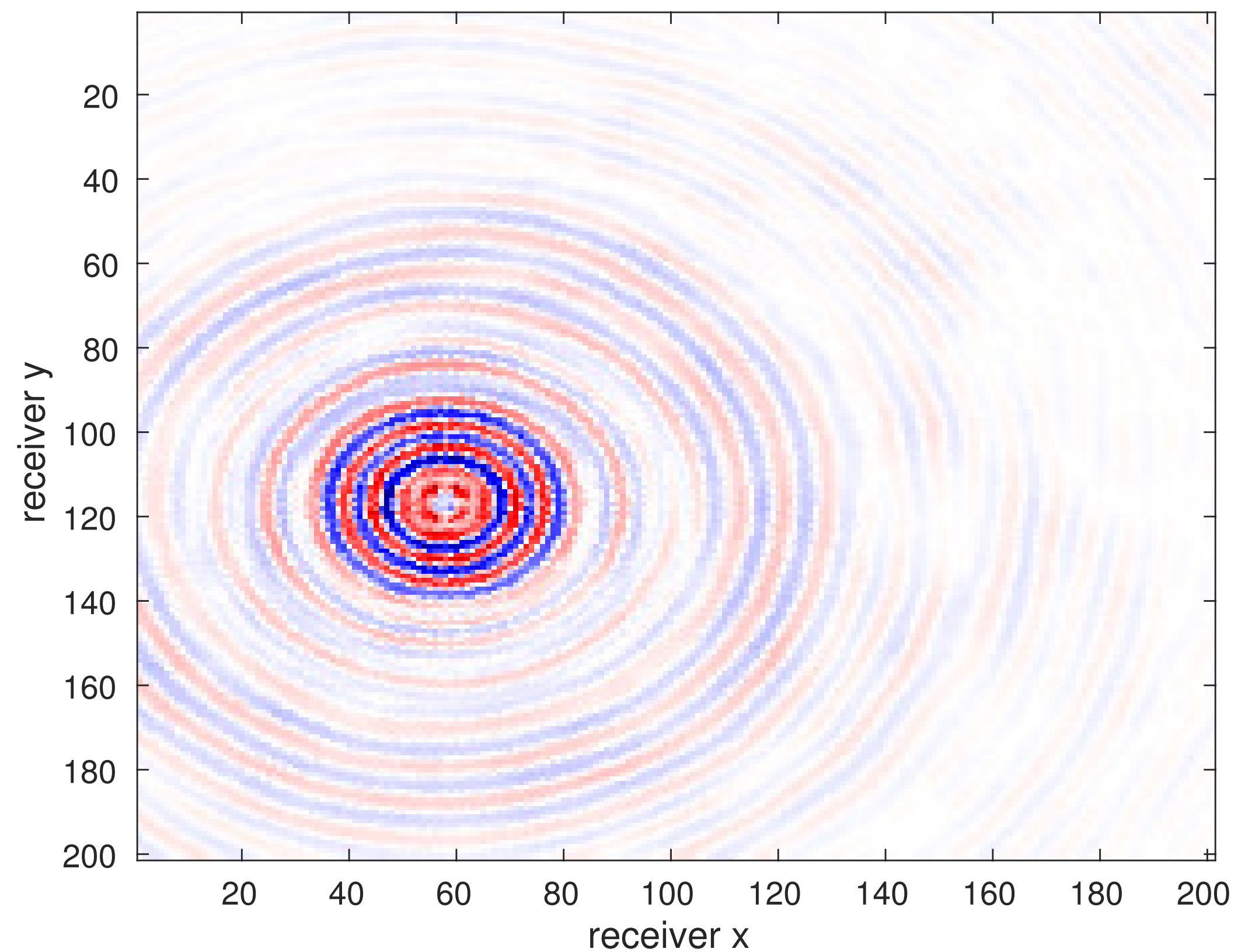
True data



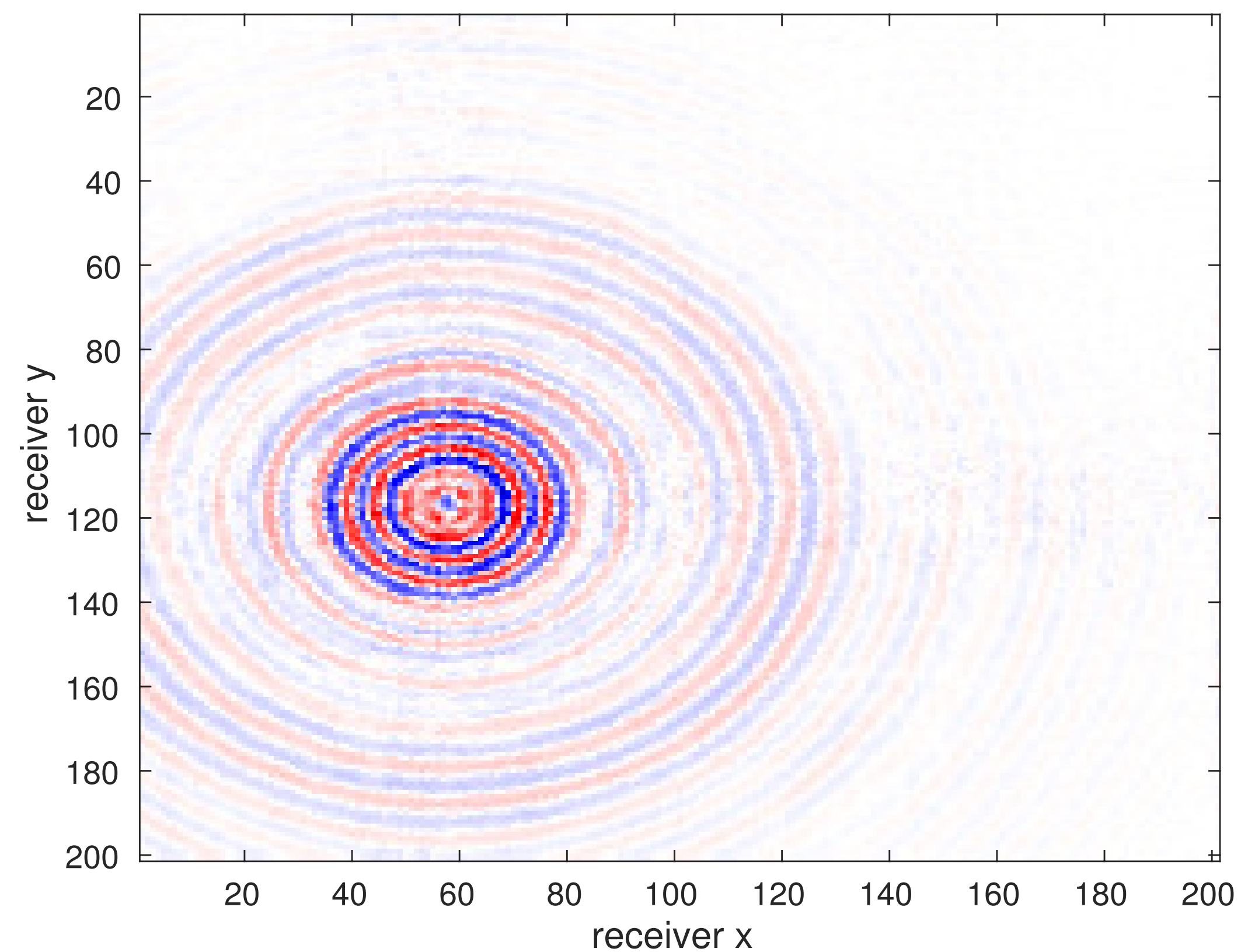
Subsampled data

# 7.34 Hz - 90% missing receivers - irregular sampling

*Common source gather*



True data



Regularized tensor completion

SNR 11 dB

- [1] Kreimer and Sacchi, "A tensor higher-order singular value decomposition for prestack seismic data noise reduction and interpolation." (2012)
- [2] Gao, Vicente, and Sacchi. "Evaluation of a fast algorithm for the eigen-decomposition of large block Toeplitz matrices with application to 5D seismic data interpolation." (2011)
- [3] Da Silva, Kumar, et al, "Efficient matrix completion for seismic data reconstruction." (To appear)

## Context

### Low-rank matrix/tensor completion via *nuclear norm* projection [1]

- Require SVDs on huge data matrices
- Not scalable to large problem sizes

### Data completion via Toeplitz embedding [2]

- Problem size -  $(\# \text{ data points})^2$
- Ad-hoc windowing - can degrade quality, as demonstrated in [3]

## Goals

Review Hierarchical Tucker tensor format, principles of low-rank tensor recovery

Compensate for lack of low-rank behaviour in irregular sampling domain

- Introduce a new domain in which the data is low rank

# Compressive sensing

*with sparsity promotion*

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## Successful reconstruction scheme

### Signal structure

- sparsity

### Sampling

- subsampling decreases sparsity

### Optimization

- look for sparsest solution



# Multidimensional interpolation

*with Hierarchical Tucker*

*Successful reconstruction scheme*

***Signal structure***

- ***Hierarchical Tucker***

Sampling

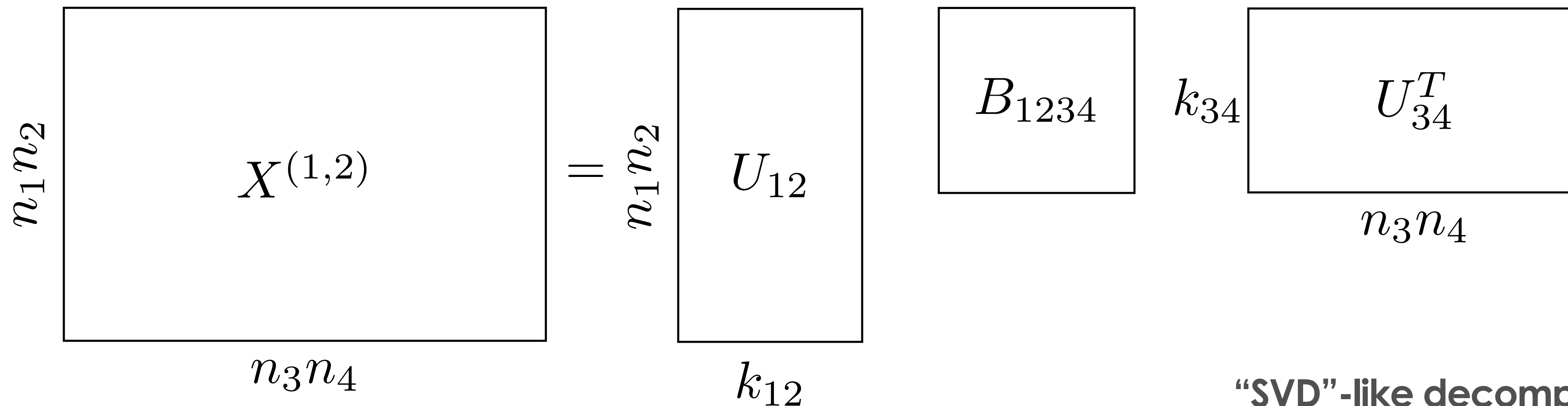
- subsampling, noise increases hierarchical rank

Optimization

- fit data in the Hierarchical Tucker format

# Hierarchical Tucker format

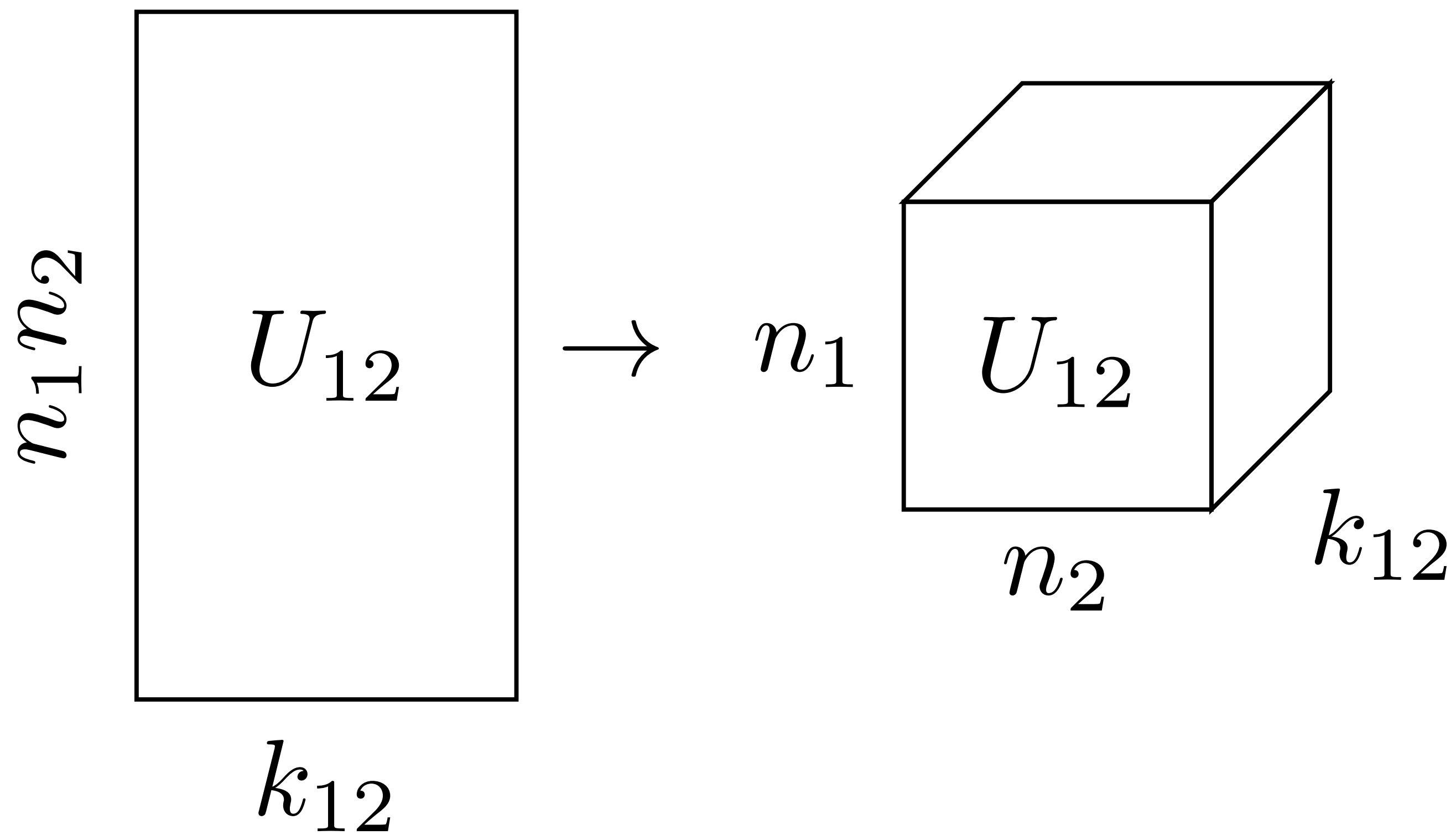
$X - n_1 \times n_2 \times n_3 \times n_4$  tensor



“SVD”-like decomposition

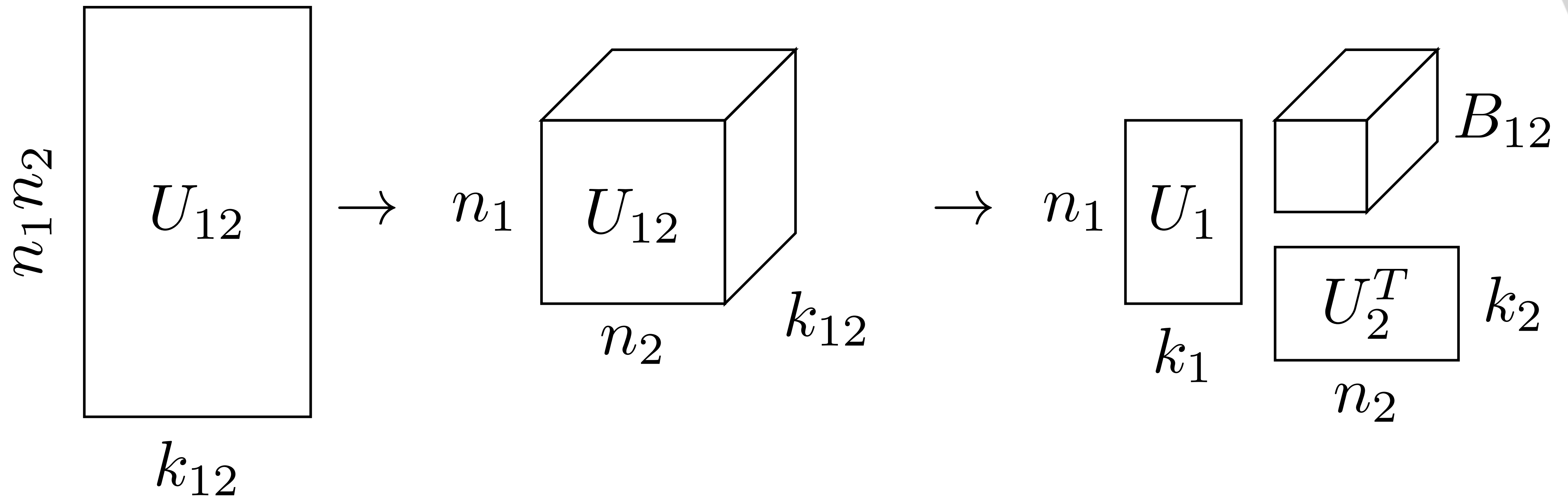
# Hierarchical Tucker format

$X - n_1 \times n_2 \times n_3 \times n_4$  tensor



# Hierarchical Tucker format

$X - n_1 \times n_2 \times n_3 \times n_4$  tensor



## Hierarchical Tucker format

Intermediate matrices don't need to be stored

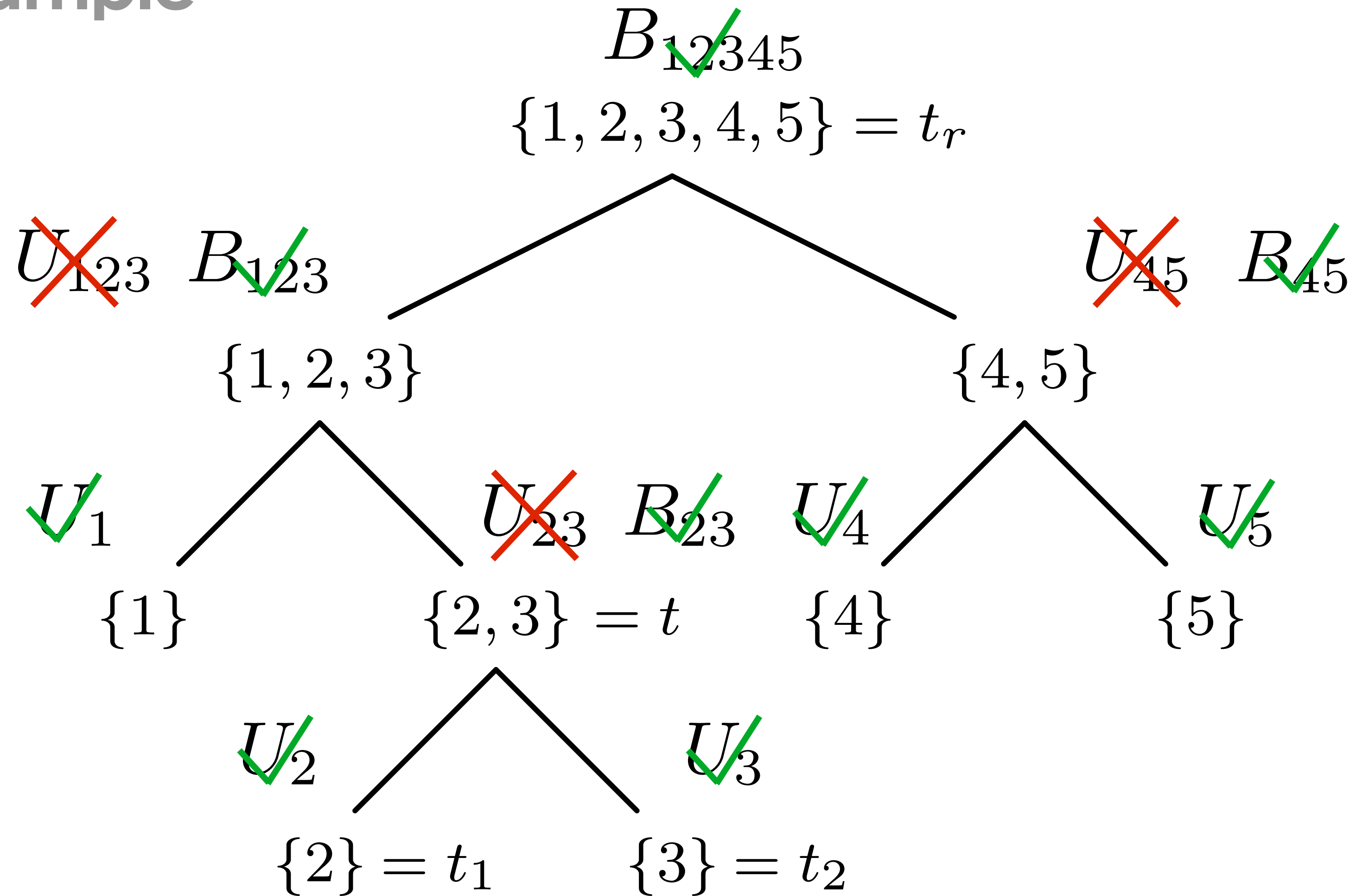
$U_t, B_t$  - small parameter matrices

- specify the tensor completely

*Separating* groups of dimensions from each other

- dimension tree

## Example



## Hierarchical Tucker format

$$\text{Storage} \leq dNK + (d - 2)K^3 + K^2$$

Compare to  $N^d$  storage for the full tensor

Effectively breaking the curse of dimensionality when  $K \ll N$   $d \geq 4$

Low frequency data compresses in HT

## Seismic Hierarchical Tucker

We consider a 3D seismic survey with coordinates  
(src x, src y, rec x, rec y, time)

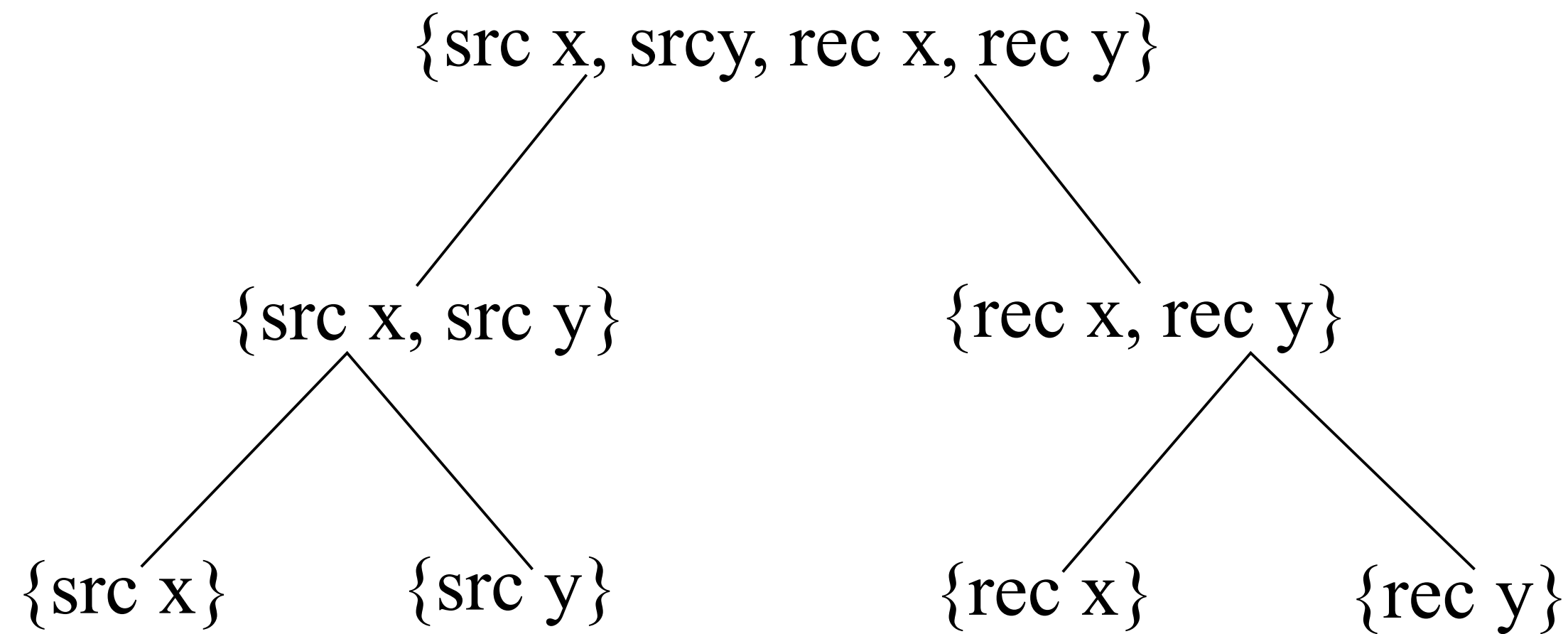
We take a Fourier transform in time and restrict ourselves to a single  
frequency slice



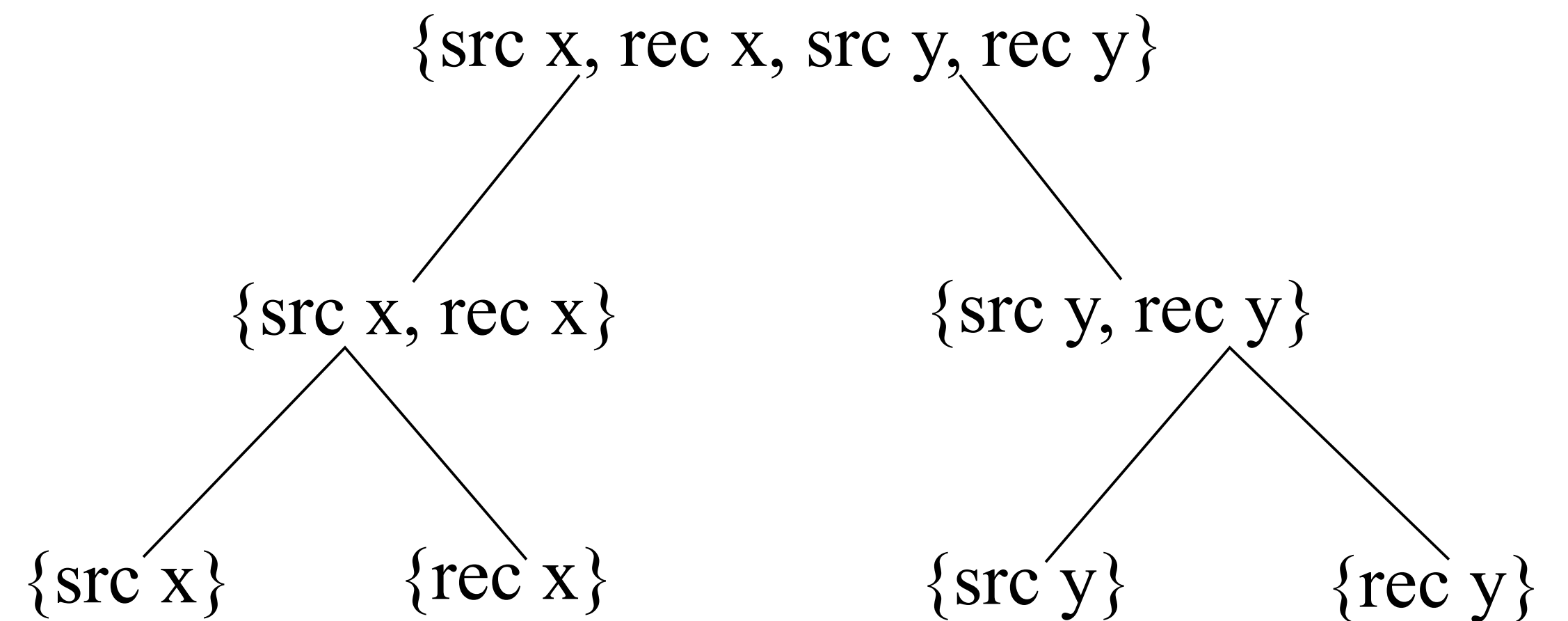
## Seismic Hierarchical Tucker

For a frequency slice with coordinates  $(\text{src } x, \text{src } y, \text{rec } x, \text{rec } y)$ , there are essentially two choices of dimension splitting (by reciprocity)

First explored in [1] - low rank solution operators for wave equations

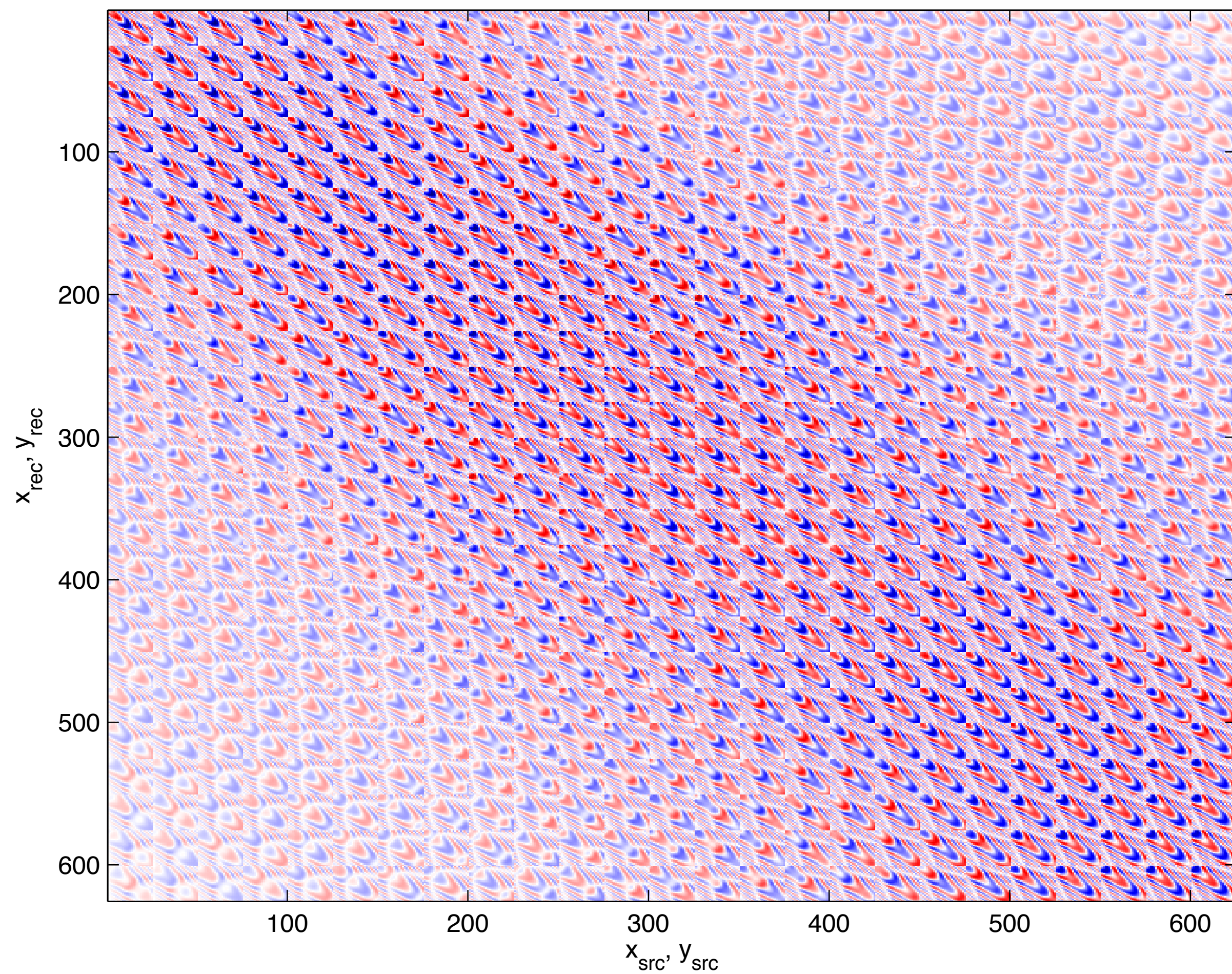


Canonical Decomposition

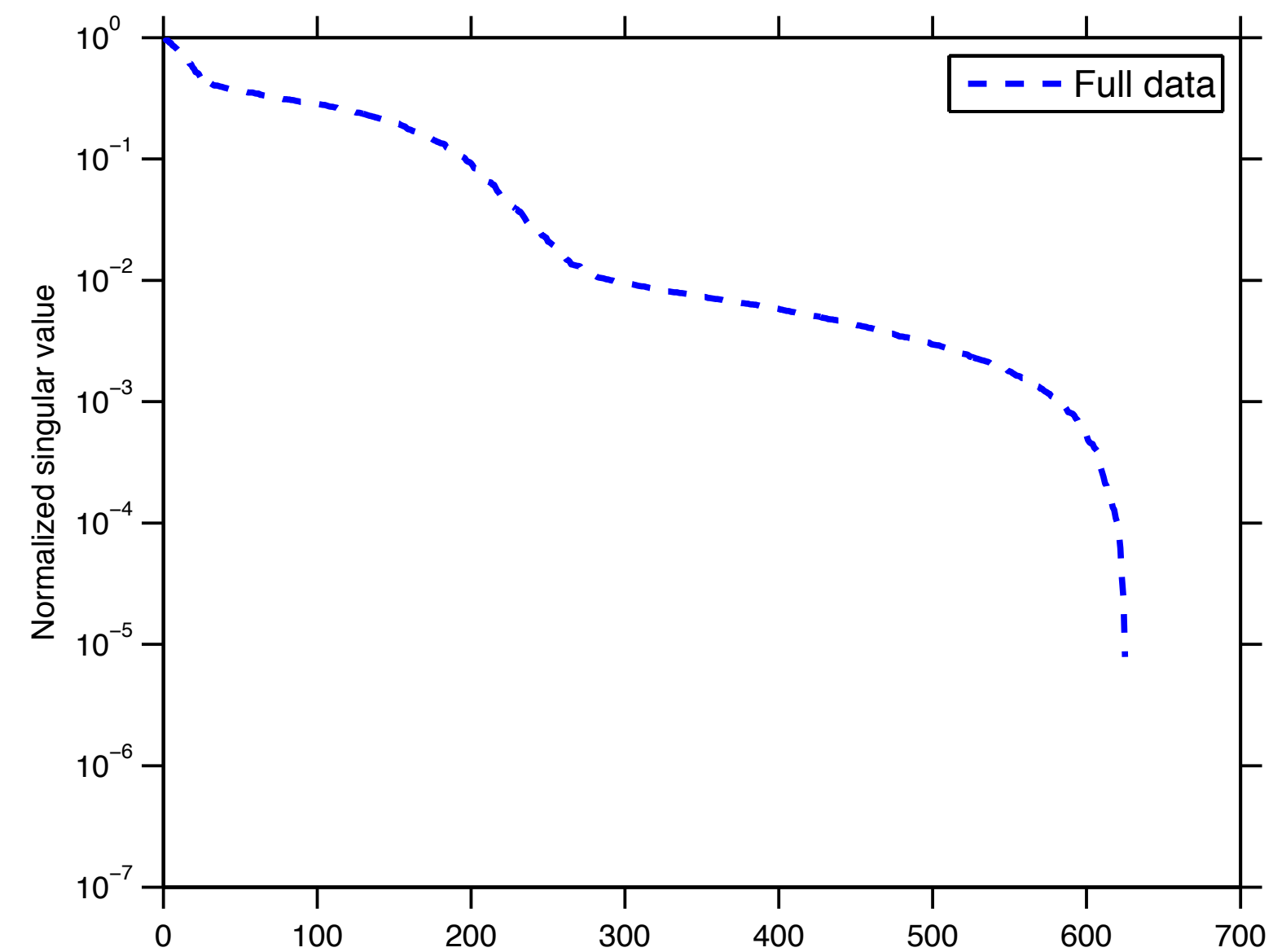
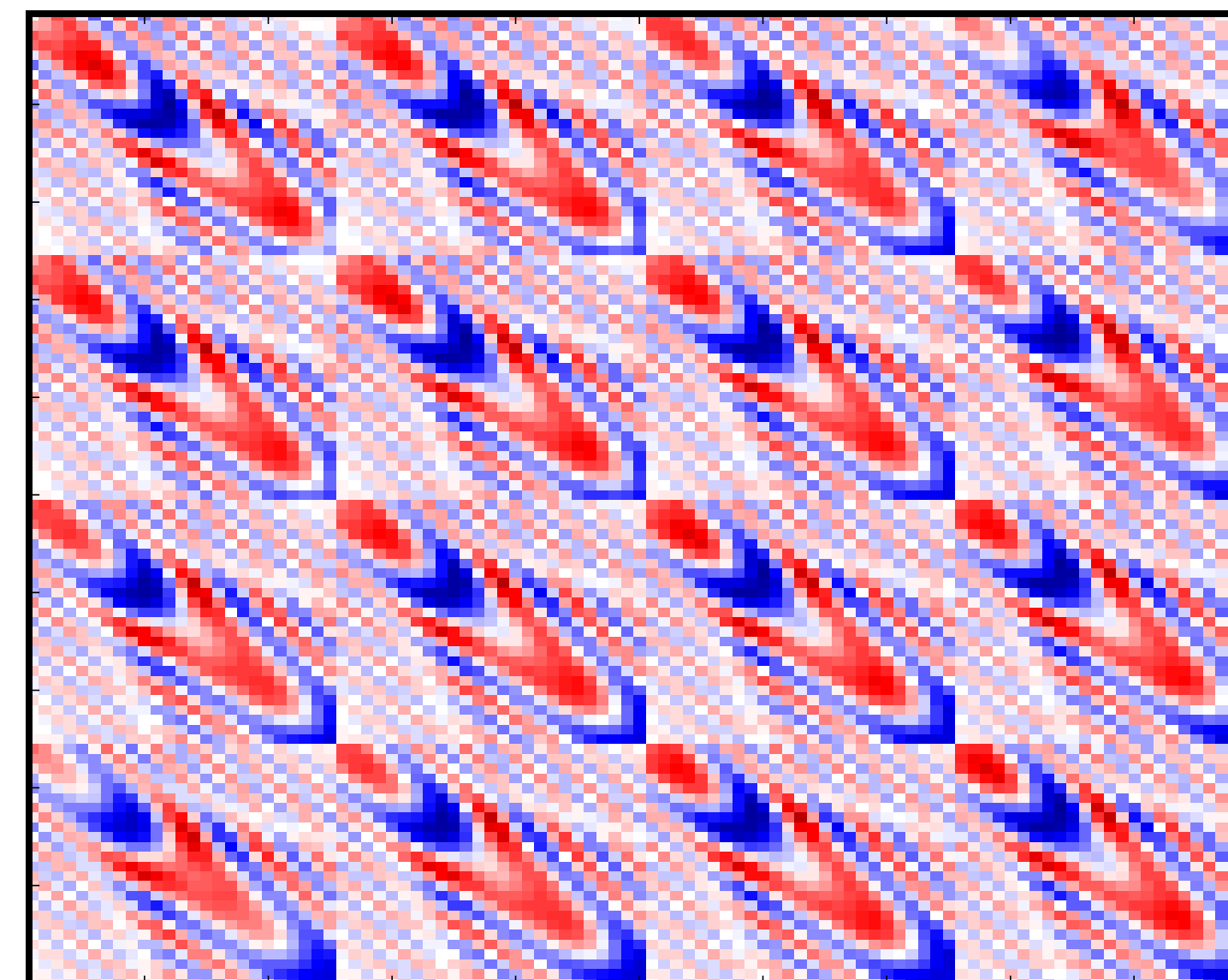


Non-canonical Decomposition

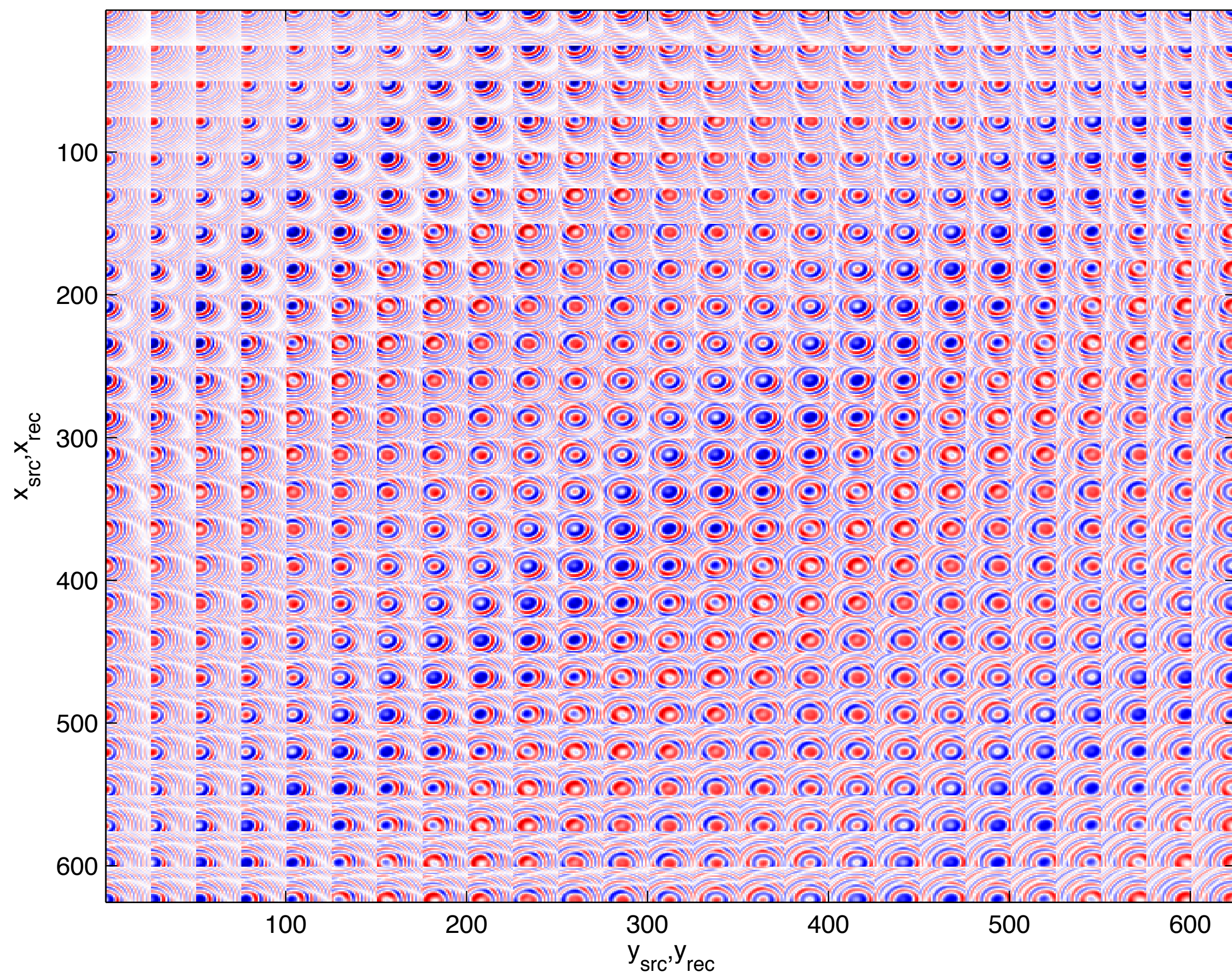
# Matricizations



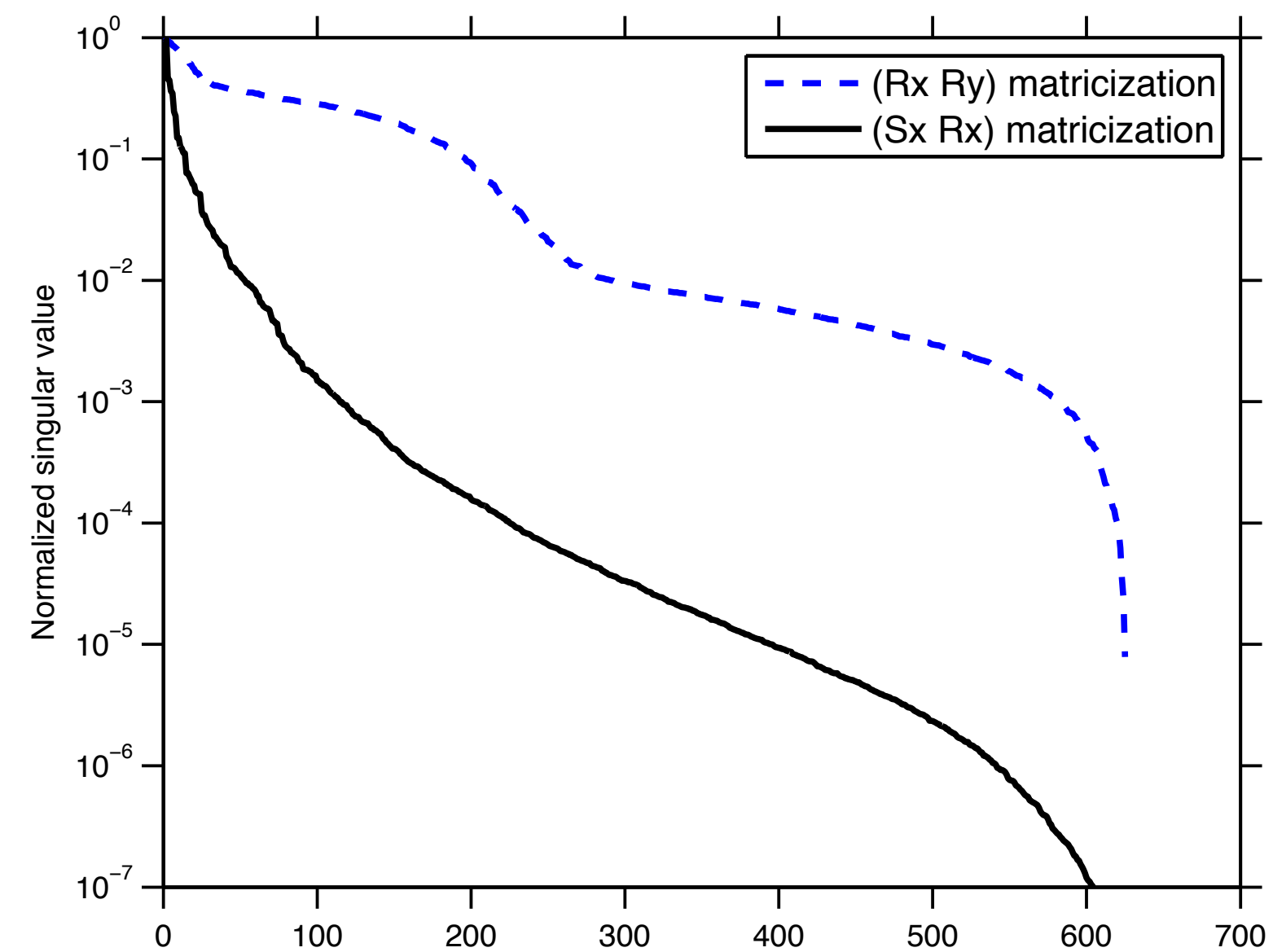
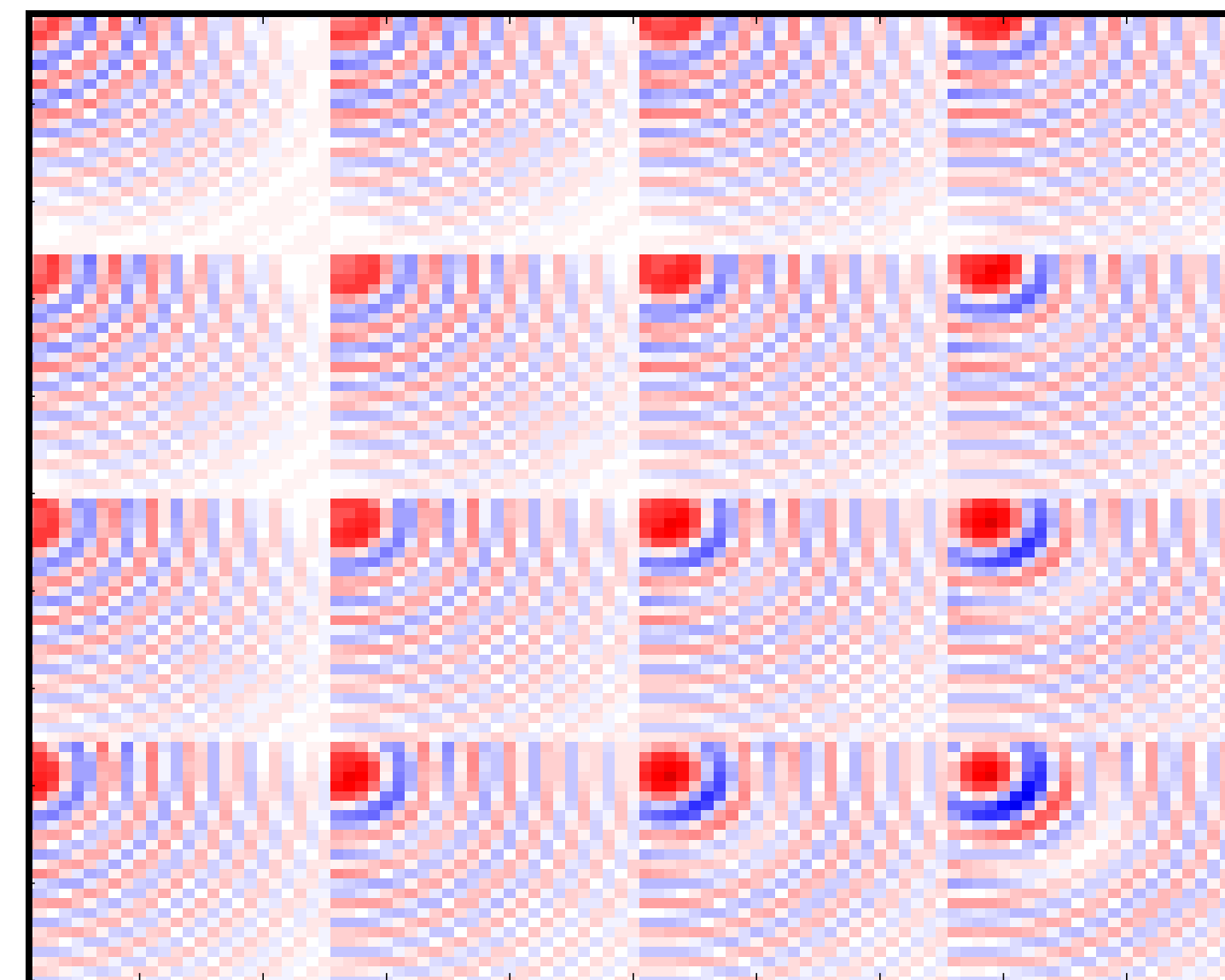
(Rec x, Rec y) matricization - Canonical ordering



# Matricizations



(Src x, Rec x) matricization - Noncanonical ordering



# Multidimensional interpolation

*with Hierarchical Tucker*

*Successful reconstruction scheme*

Signal structure

- Hierarchical Tucker

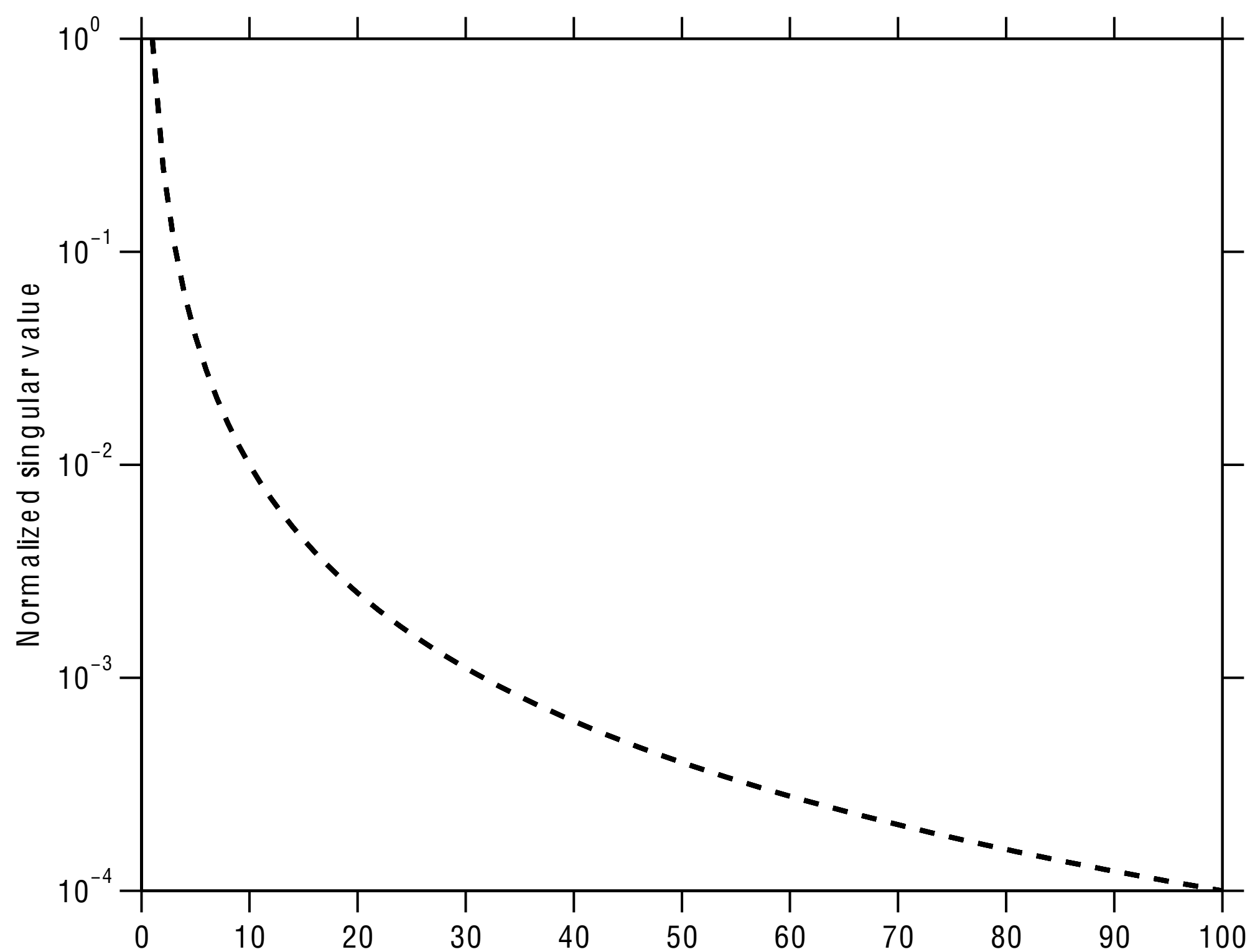
***Sampling***

- ***subsampling, noise increases hierarchical rank***

Optimization

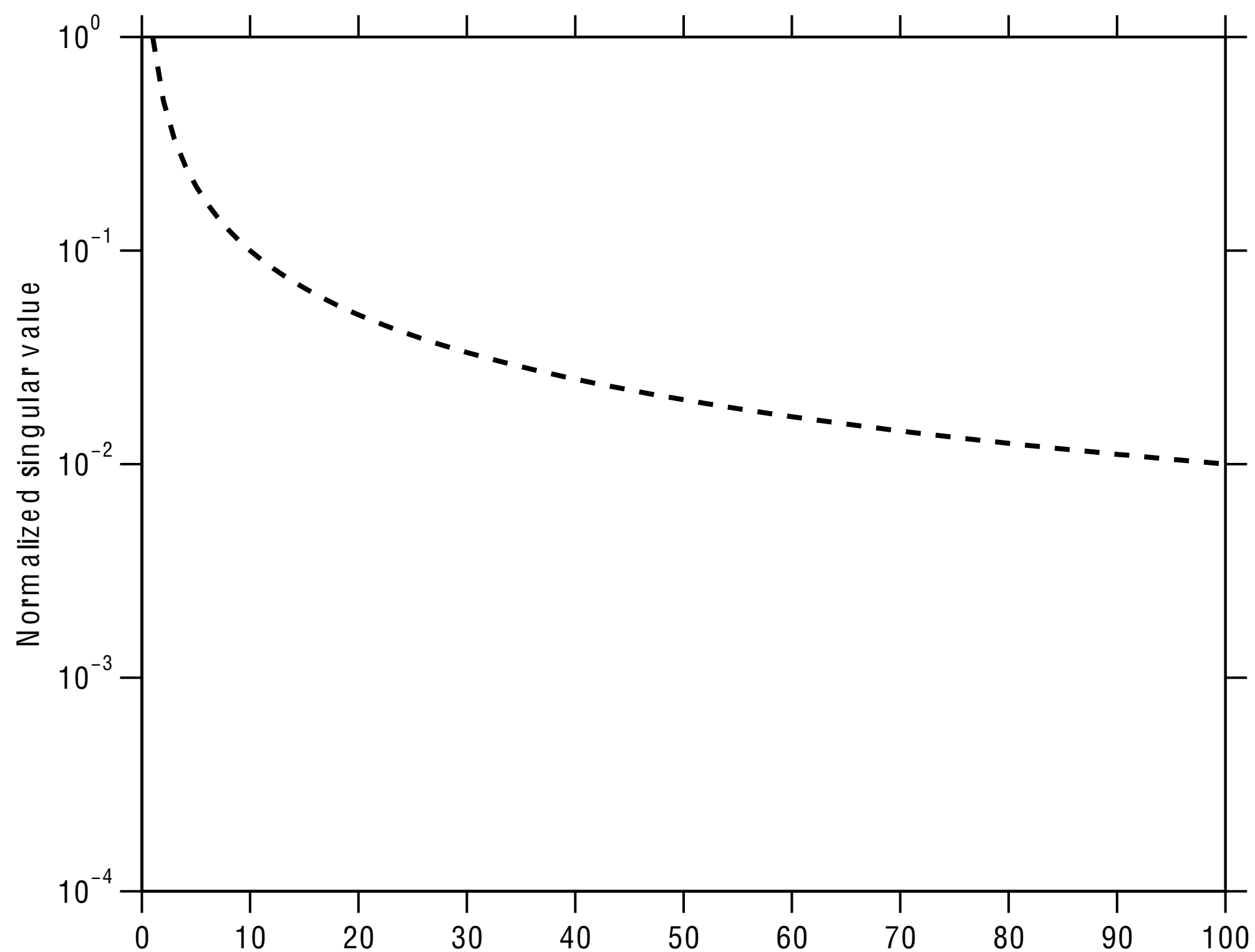
- fit data in the Hierarchical Tucker format

# Matrix Completion

 $X$ 

# Matrix Completion

$$\mathcal{A}(\mathbf{X})$$
$$\begin{bmatrix} * & * & * & 0 & * \\ * & 0 & 0 & * & 0 \\ * & * & * & * & * \\ * & * & 0 & * & * \\ 0 & * & * & * & 0 \end{bmatrix}$$



# Sampling

Sampling  $(x_{\text{src}}, y_{\text{src}}, x_{\text{rec}}, y_{\text{rec}})$  points from the data

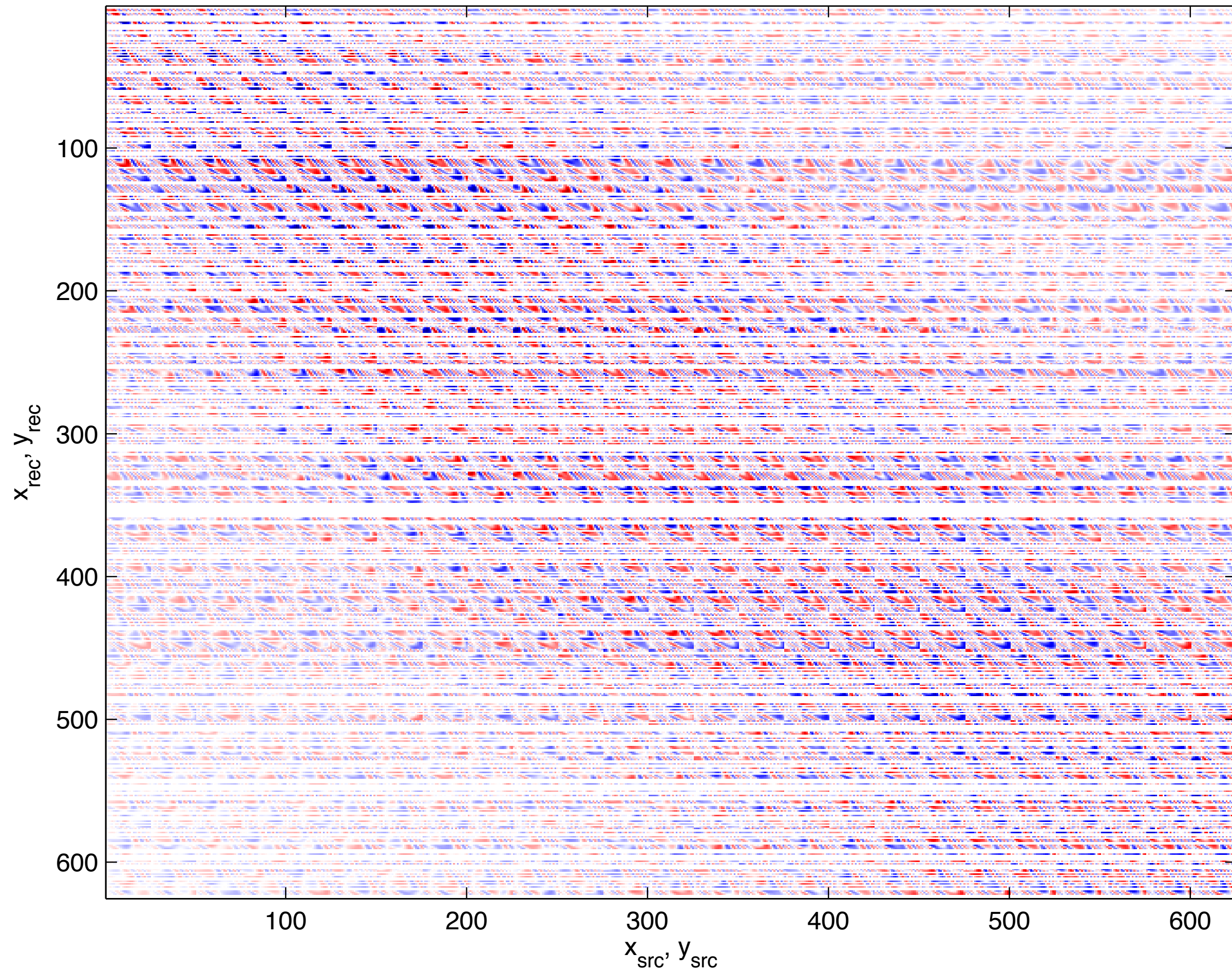
- idealized recovery
- impossible to physically implement

Sampling  $(x_{\text{rec}}, y_{\text{rec}})$  points from the data

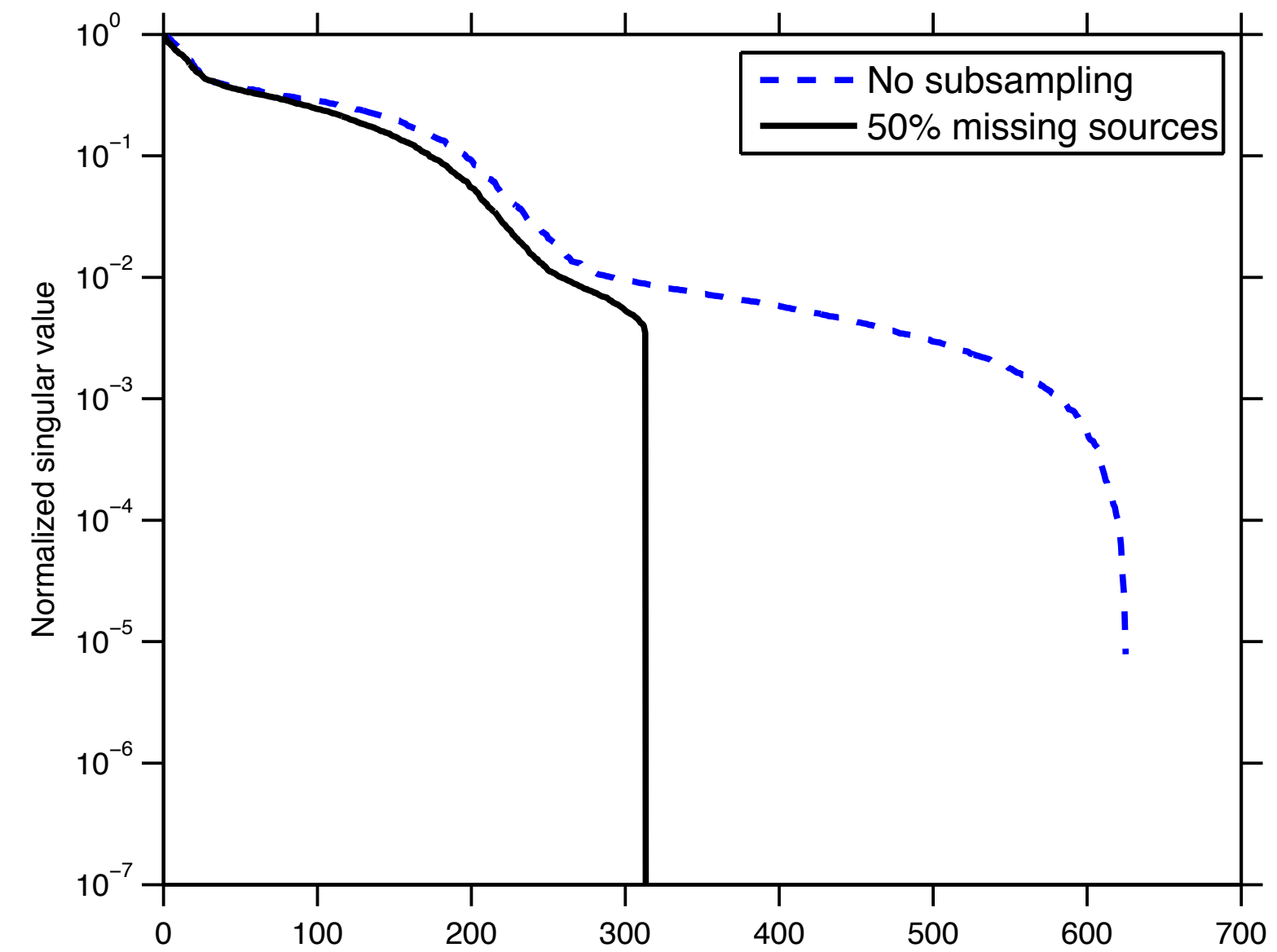
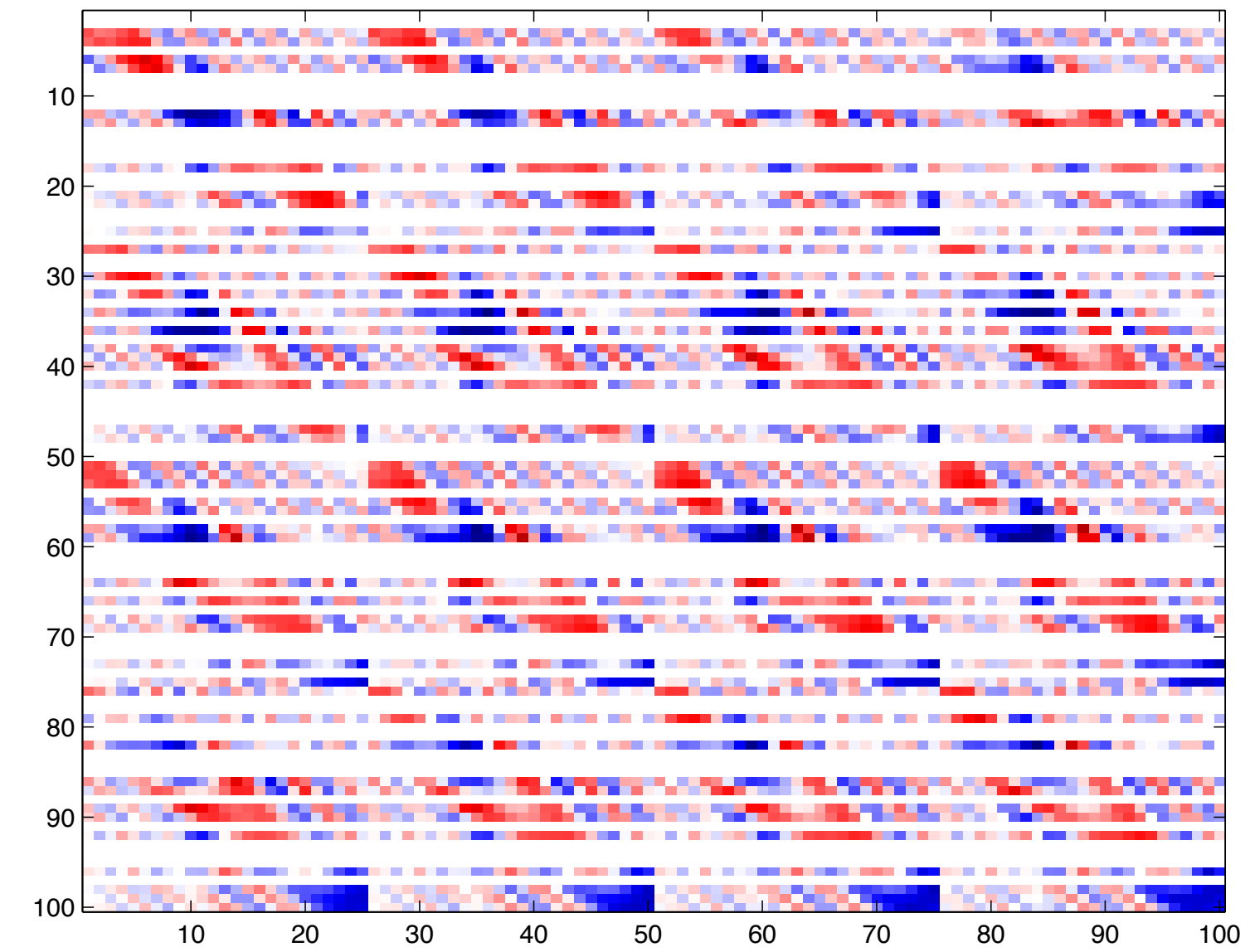
- less idealized
- possible to acquire data - e.g. ocean bottom nodes

# Realistic recovery

50% random receivers removed



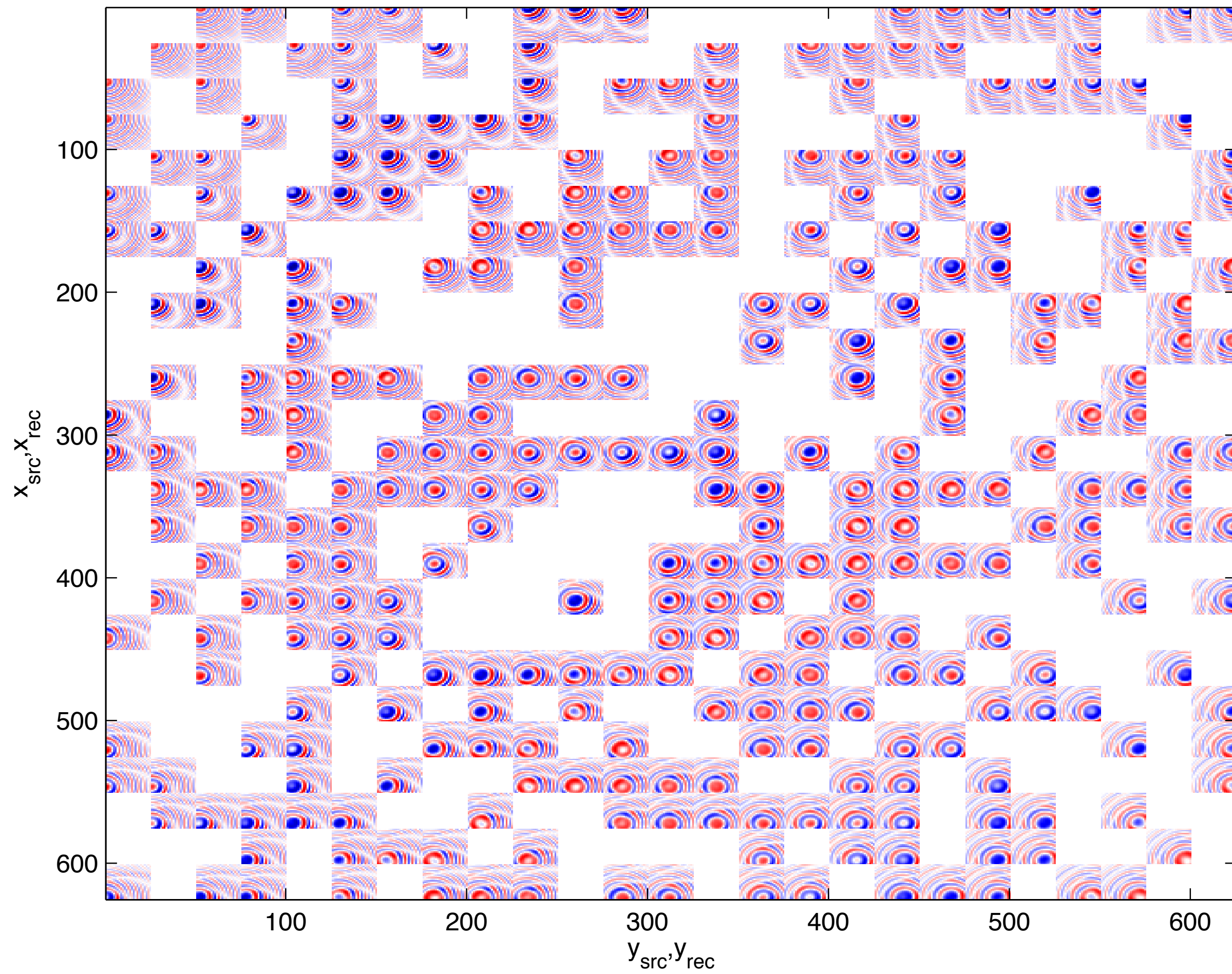
(Rec x, Rec y) matricization - Canonical ordering



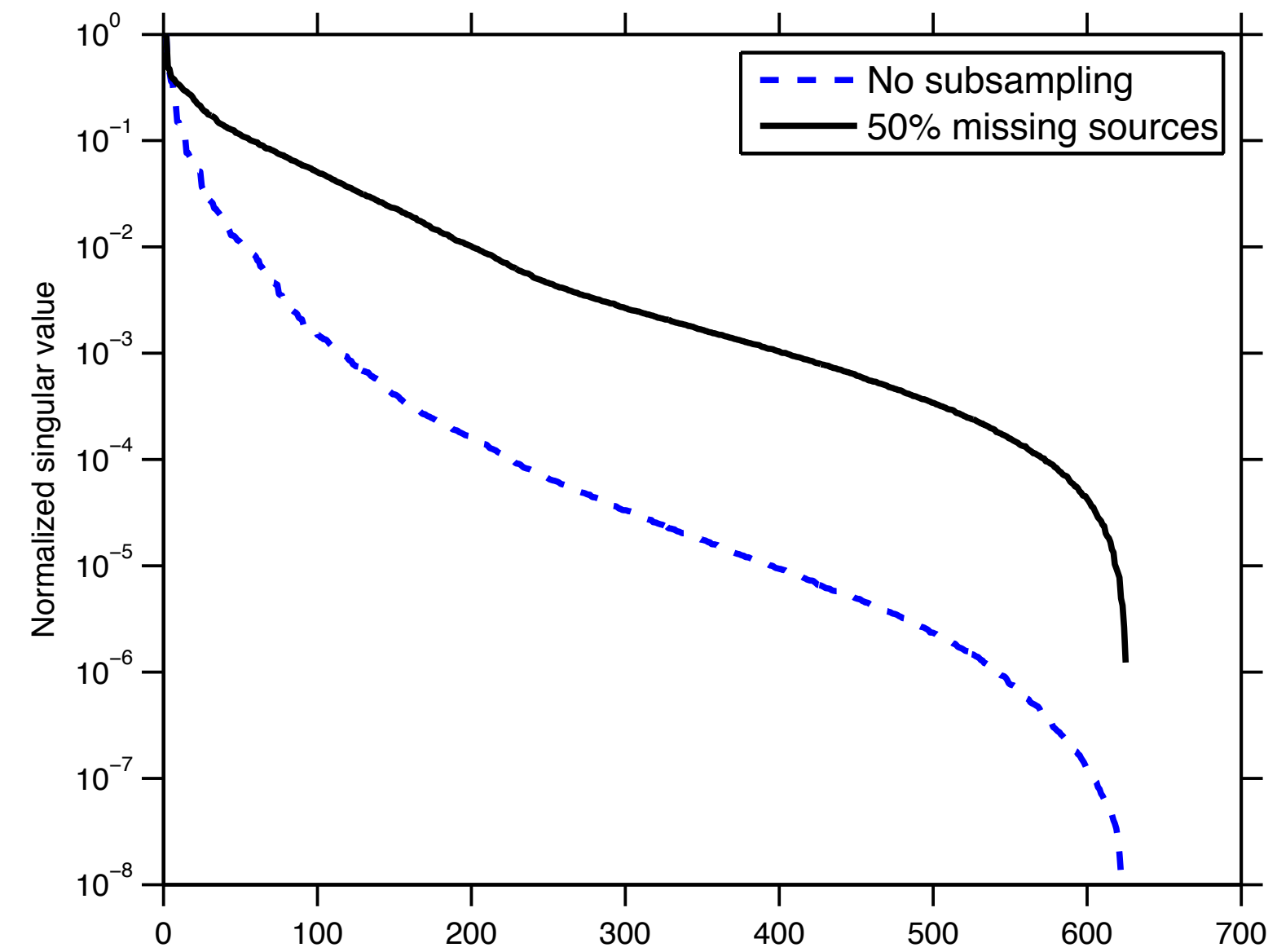
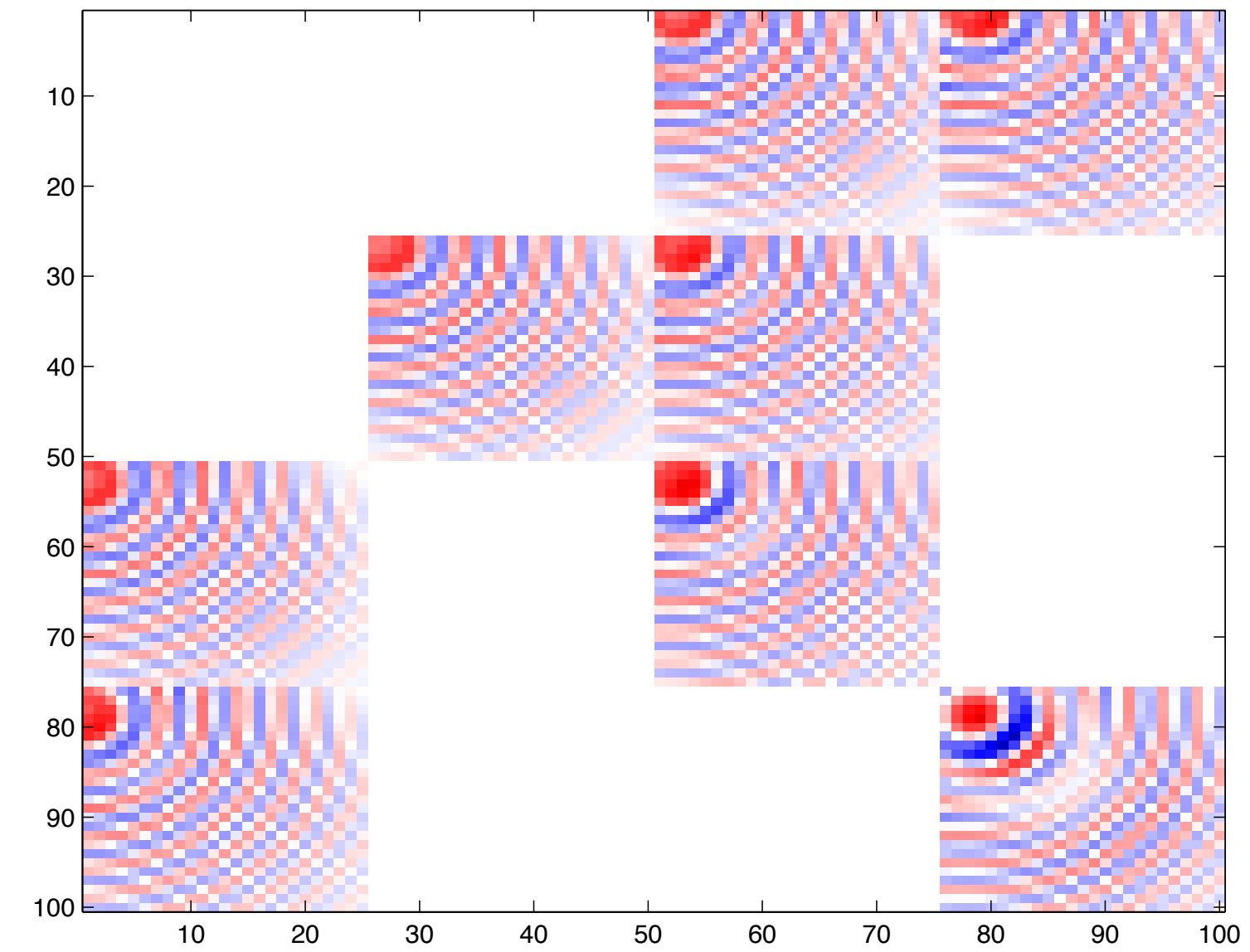


# Realistic recovery

50% random receivers removed



(Src x, Rec x) matricization - Noncanonical ordering



# Data organization

## (rec x, rec y) organization

- High rank
- Missing receivers operator - removes rows
- Poor recovery scenario

## (src x, rec x) organization

- Low rank
- Missing receivers operator - removes blocks
- Closer to ideal recovery scenario

# Nonuniform sampling

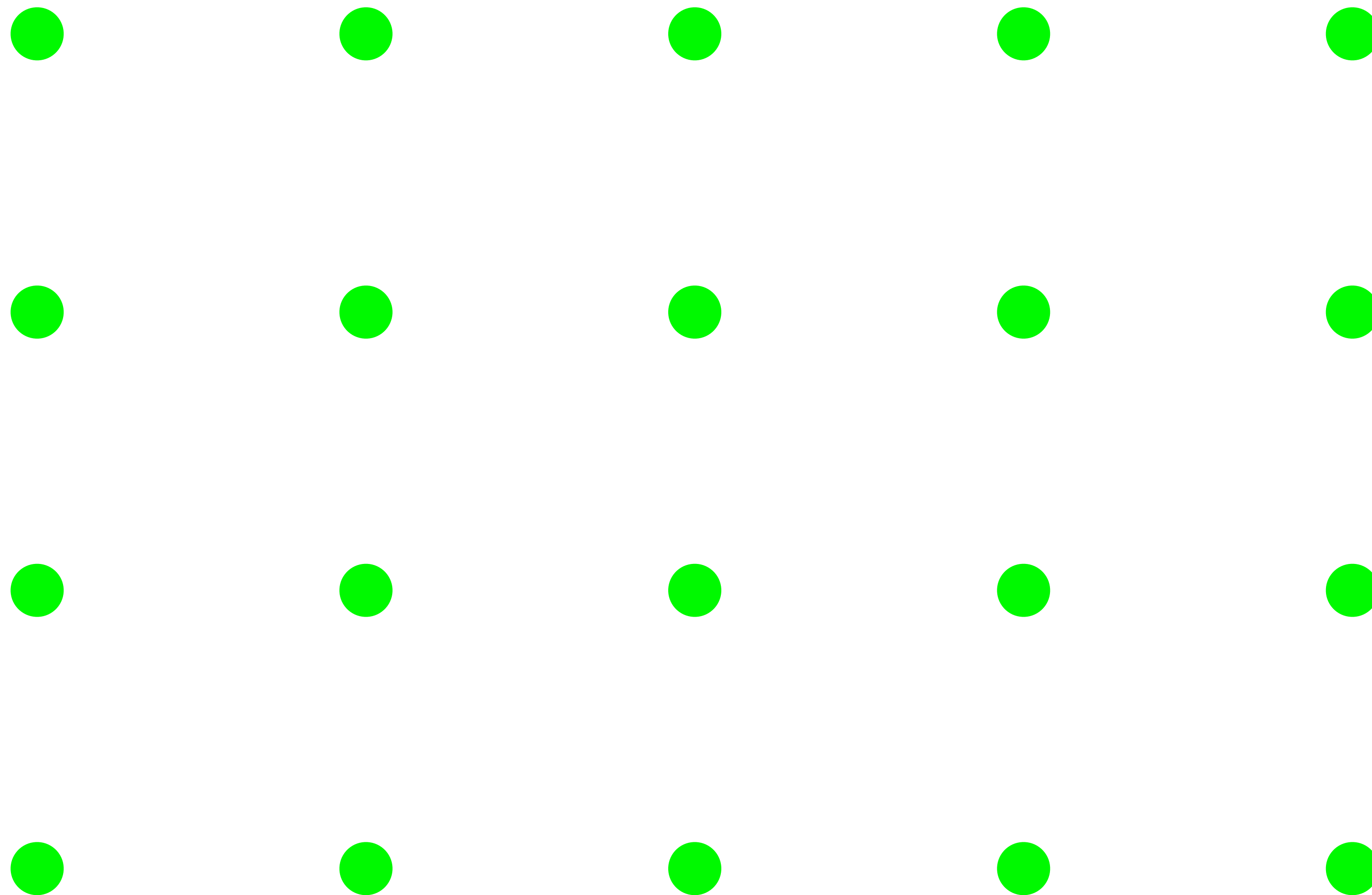
## BG data set

- 68 x 68 sources, 150m spacing
- 401 x 401 receivers, 25m spacing

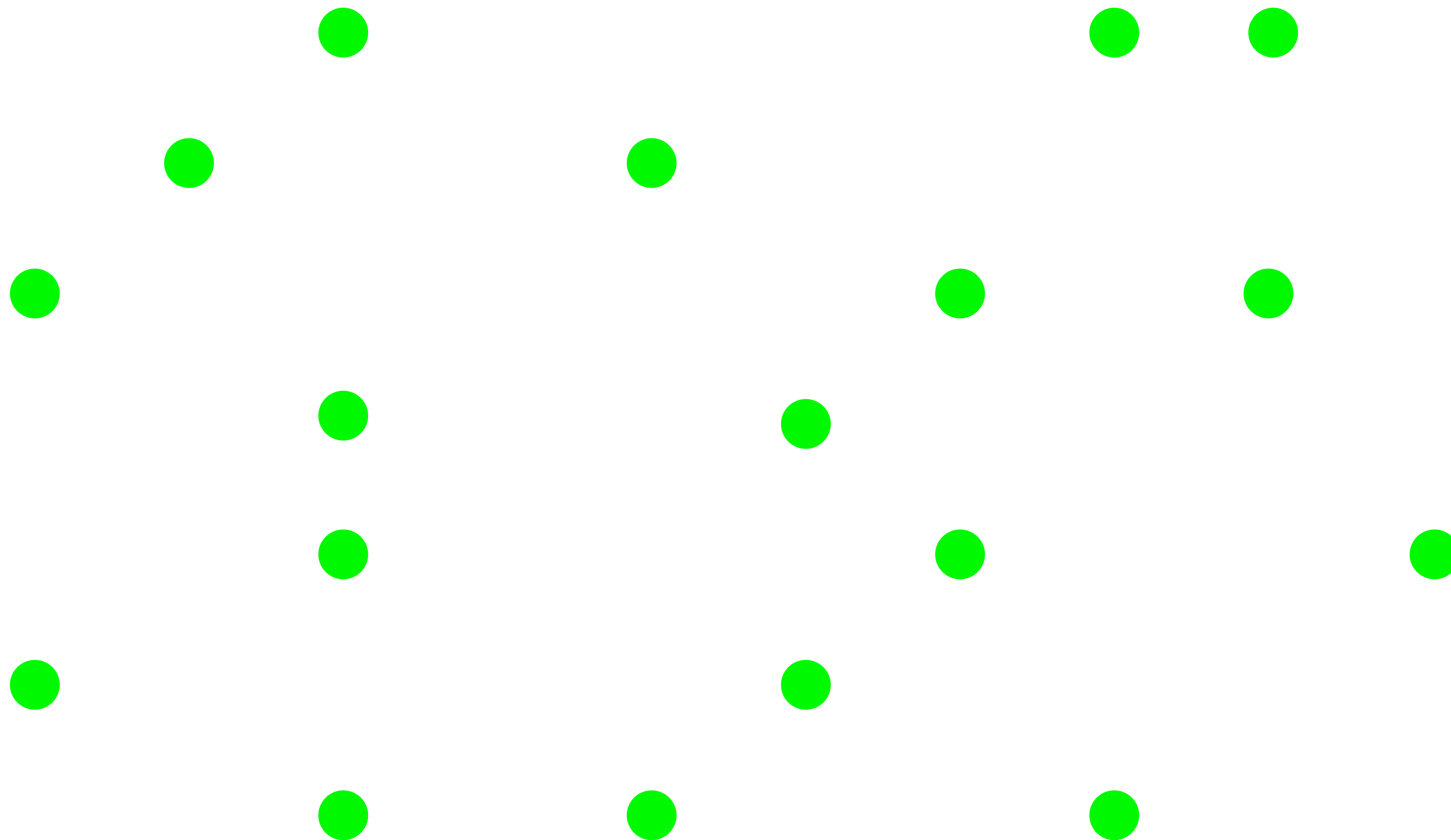
## Consider two sampling situations

- regular 201 x 201 grid, 50m spacing
- irregular 201 x 201 grid
  - random 25m perturbations from the regular 201 x 201 grid
  - load true data from the irregular grid, avoid generating inverse crime data

# Regular grid

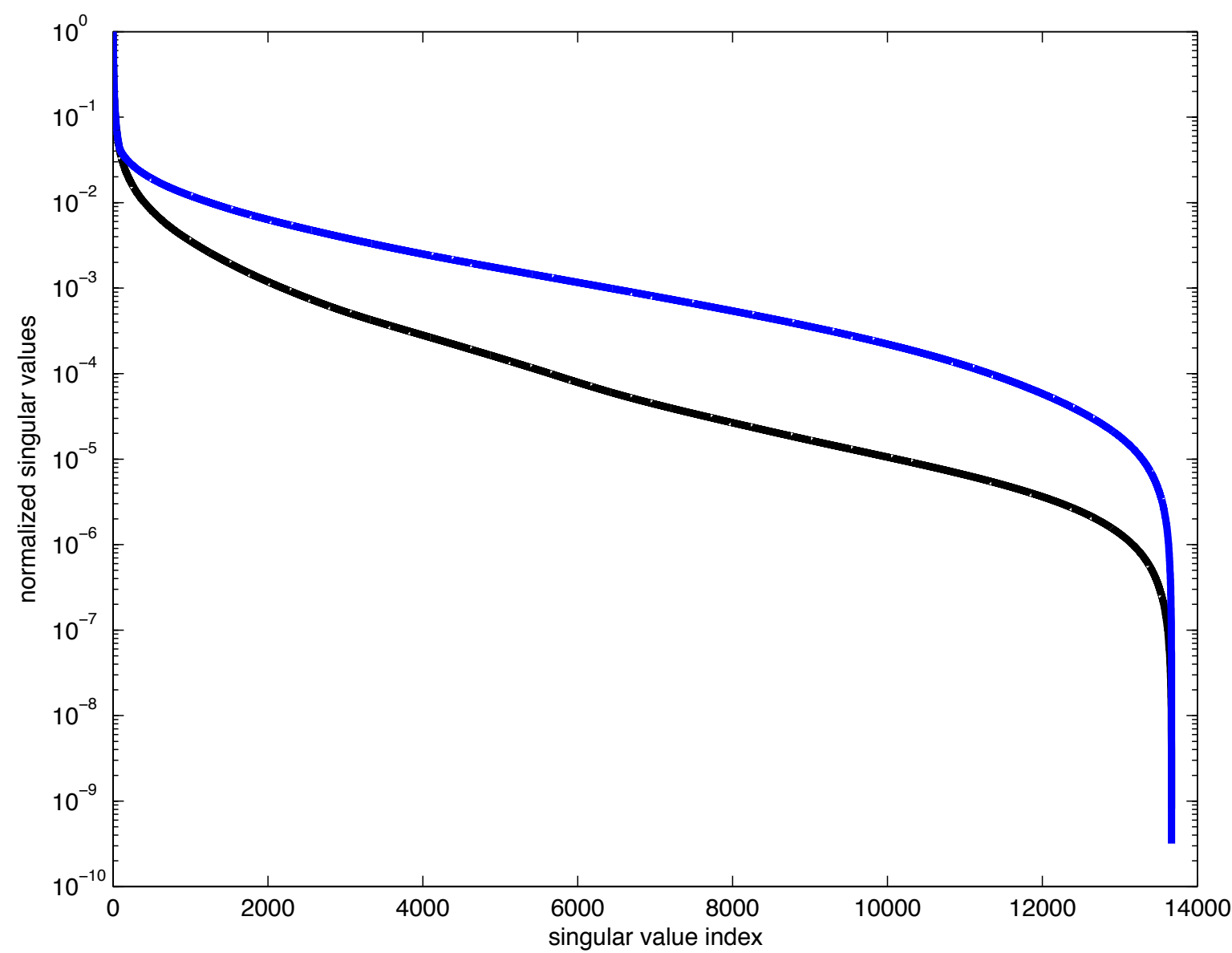


# Unstructured grid

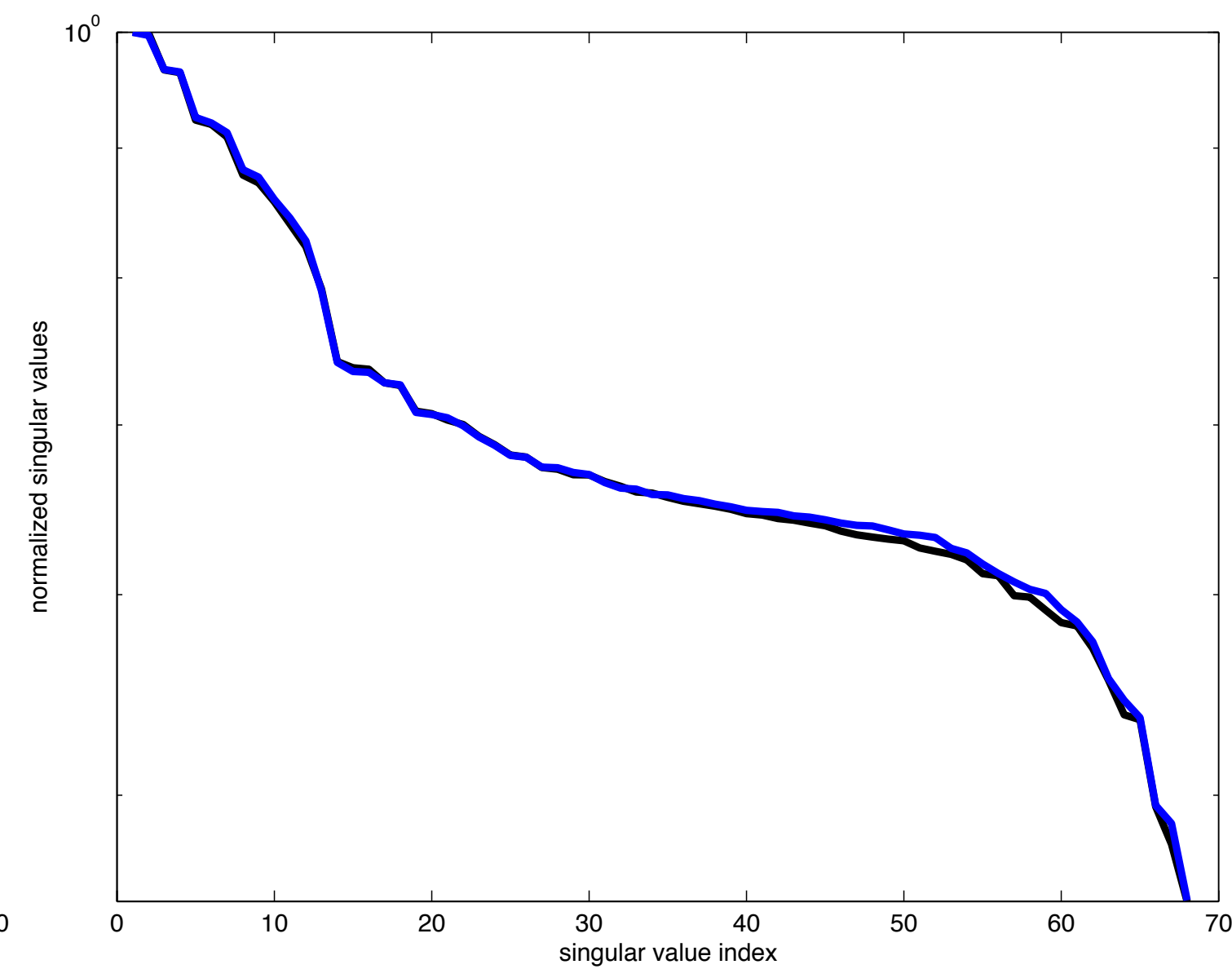


# Regular vs irregular grid - singular values

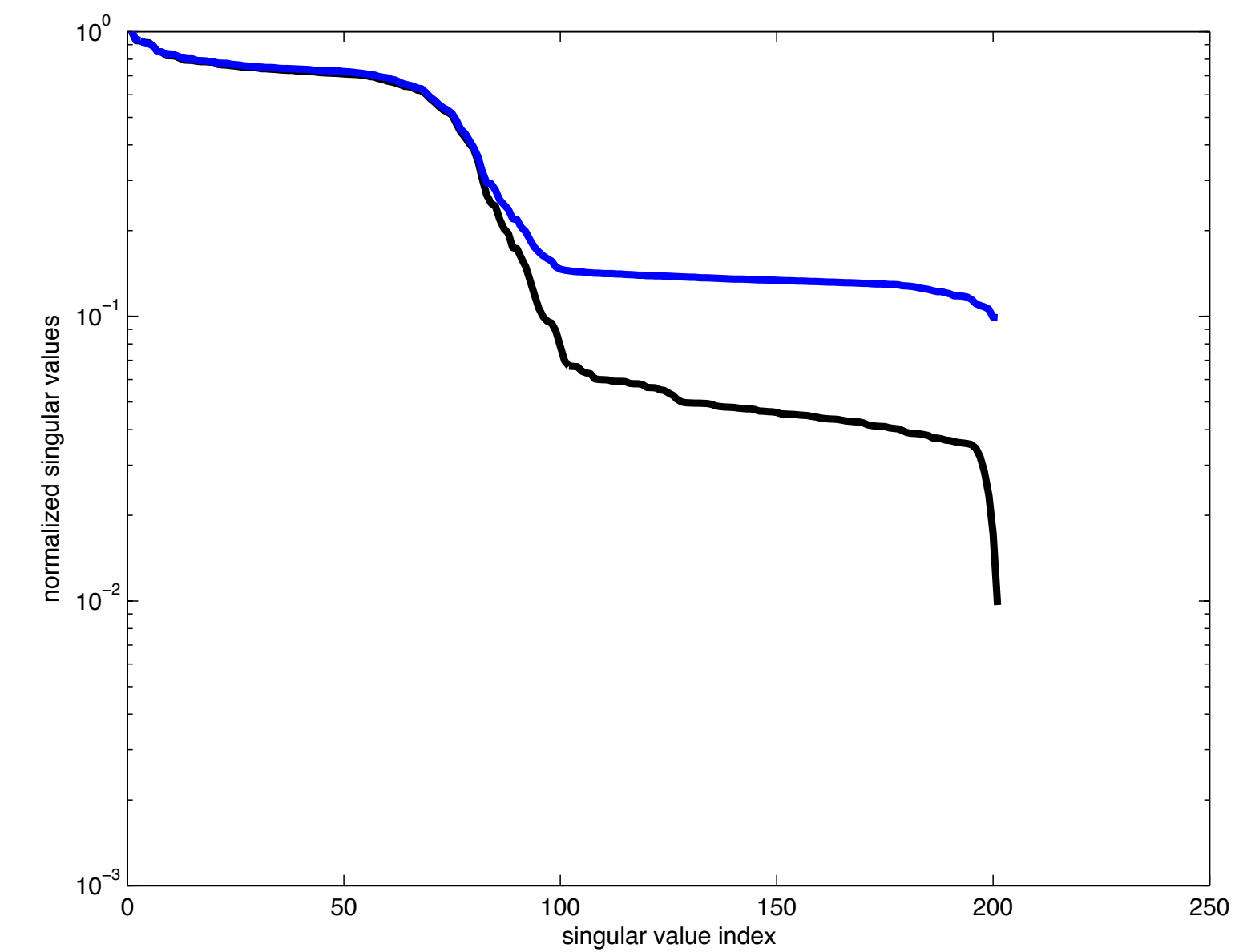
Black - regular grid  
Blue - irregular grid



source x, receiver x



source x



receiver x

## Off the grid tensor interpolation

The data volume is **no longer** low rank when irregularly sampled

- standard tensor completion framework won't work well

### Solution

- construct a domain where the data **is** low rank
- choose an appropriate transform : low rank domain -> sampling domain
- incorporate transform in to the optimization problem

# Multidimensional interpolation

*with Hierarchical Tucker*

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*Successful reconstruction scheme*

Signal structure

- Hierarchical Tucker

Sampling

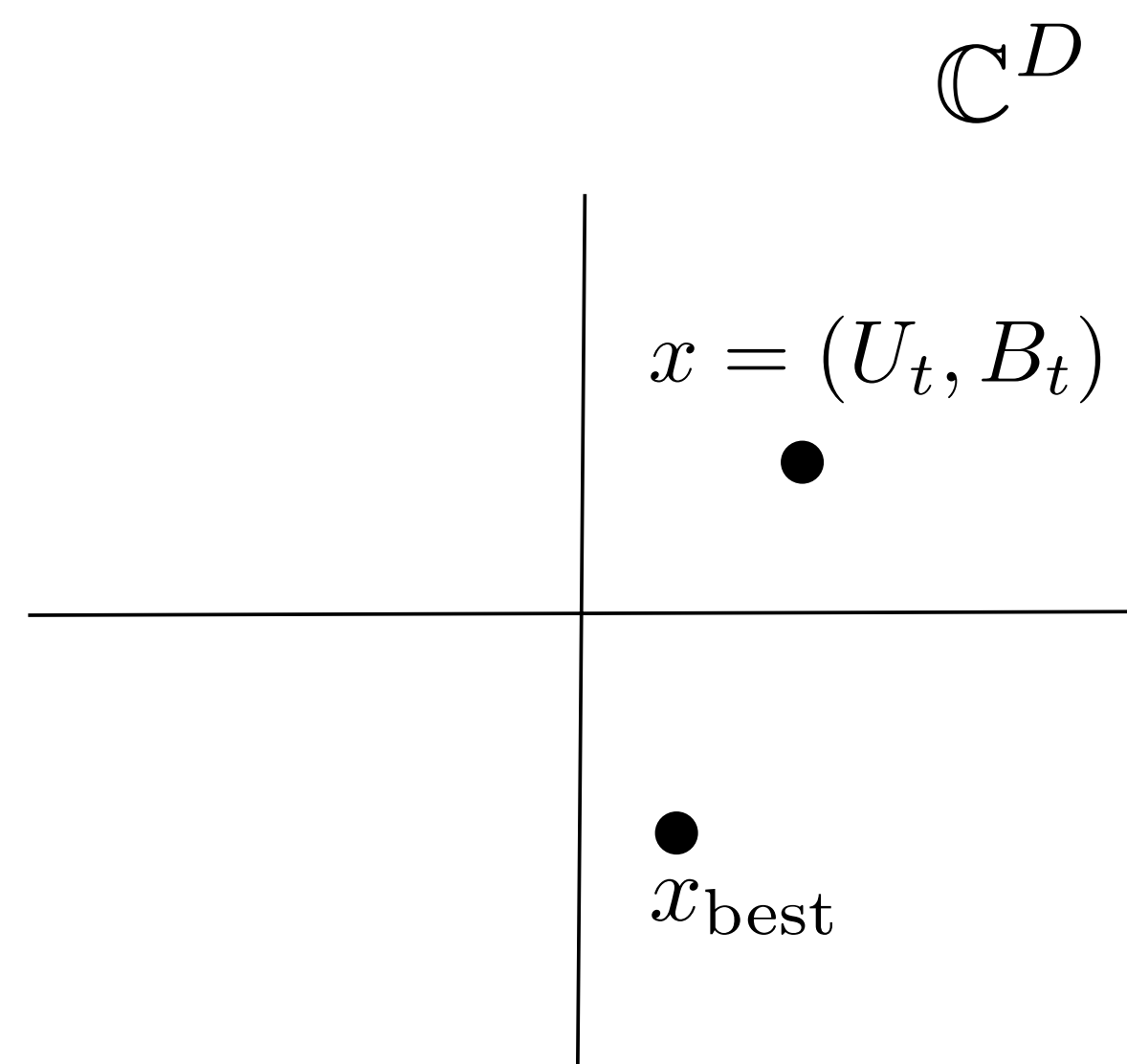
- subsampling, noise increases hierarchical rank

***Optimization***

- ***fit data in the Hierarchical Tucker format***



# Optimization program

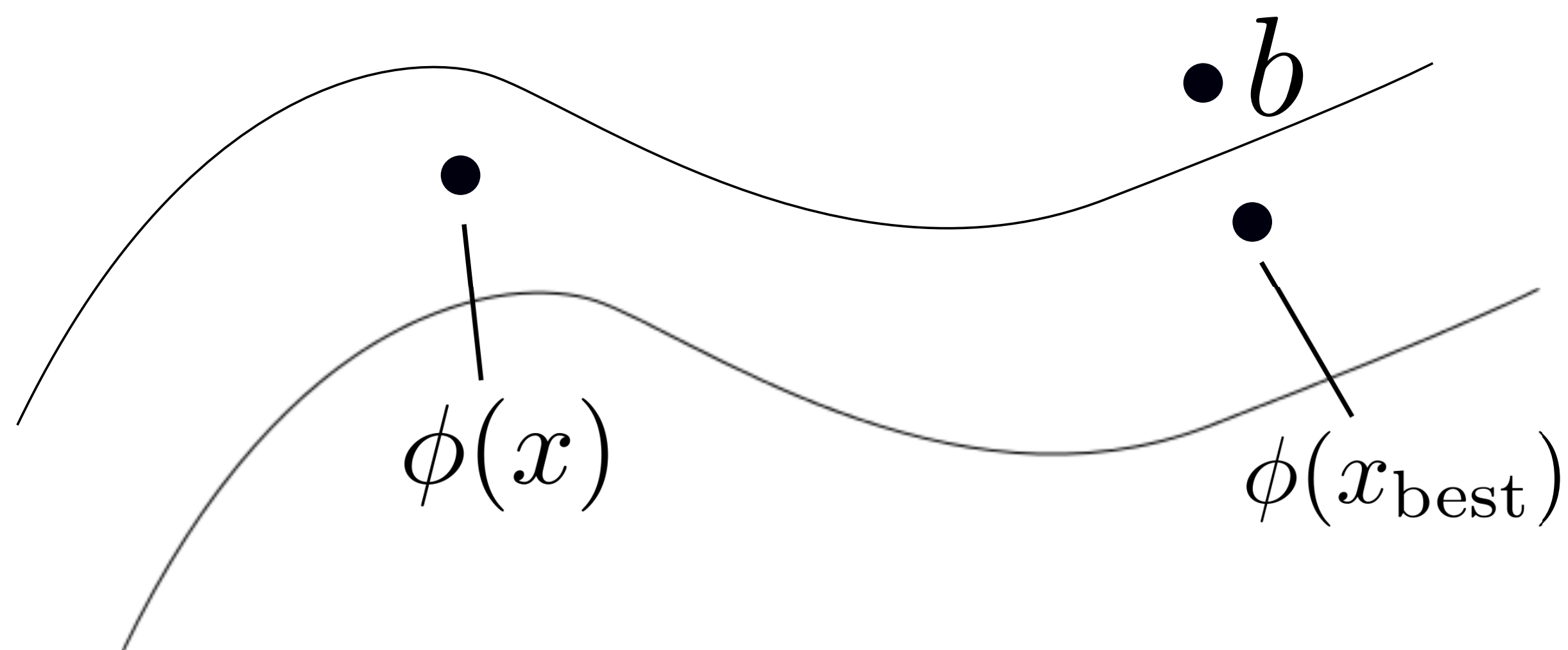


*Parameter space*

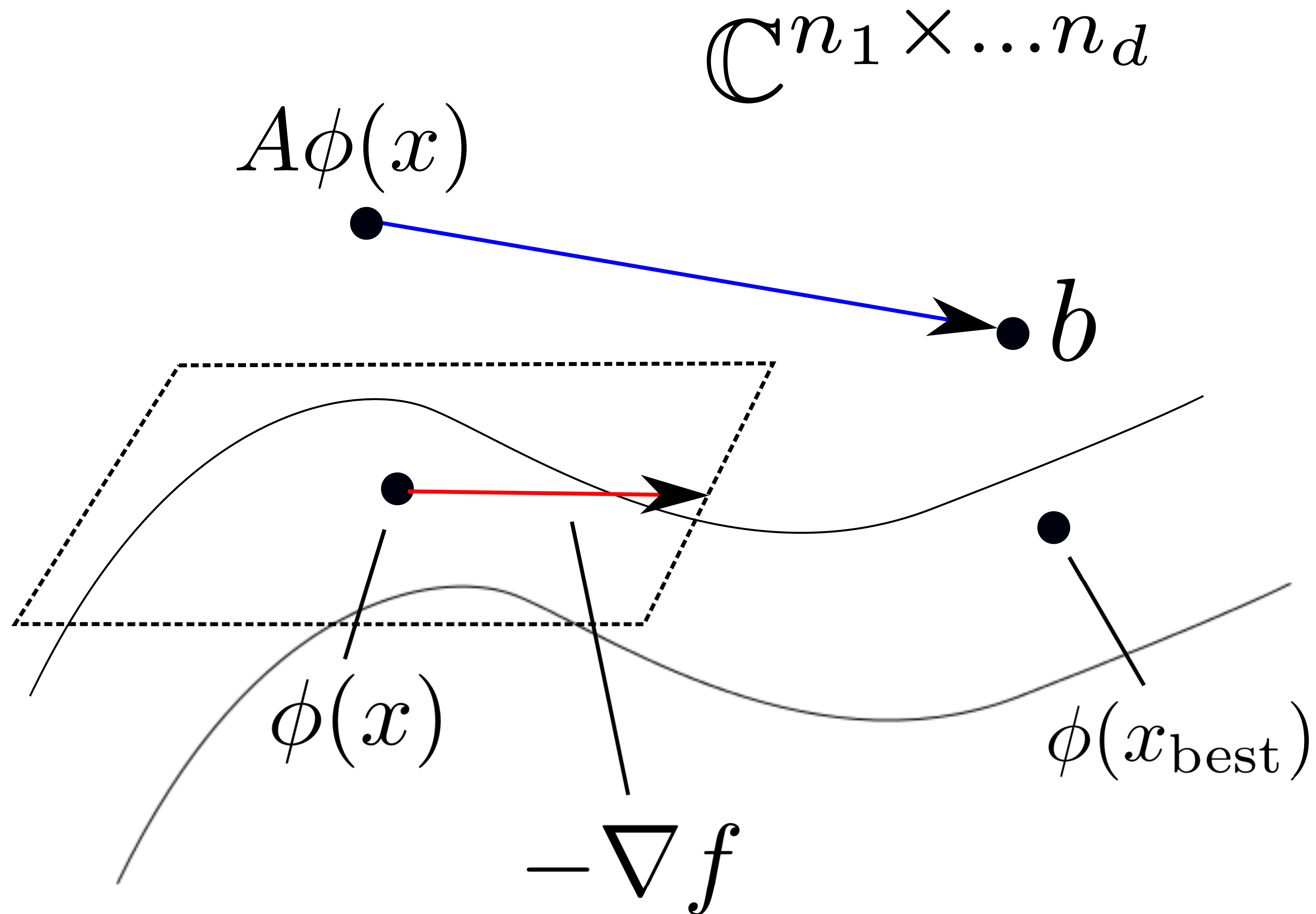
$$\phi(x)$$

*Full-tensor space*

$$\mathbb{C}^{n_1 \times \dots \times n_d}$$



# Optimization program



## Optimization problem

The standard problem we solve is

$$\min_x \|\mathcal{A}\phi(x) - b\|_2^2$$

Our sampling operator is typically

$$\mathcal{A} = \mathcal{R}\mathcal{P}$$

where

$\mathcal{R}$  : regular full grid  $\rightarrow$  subsampled grid

$\mathcal{P}$  : (src x, rec x, src y, rec y)  $\rightarrow$  (src x, src y, rec x, rec y)

## Optimization problem

In the irregular grid case, the subsampling operator is in fact

$$\mathcal{R} : \text{irregular full grid} \rightarrow \text{subsampled grid}$$

In order to take this discrepancy in to account, we introduce an operator

$$\mathcal{F} : \text{regular full grid} \rightarrow \text{irregular full grid}$$

This is an extension of [1] to the tensor case

- [1] C. Da Silva and F. J. Herrmann. Optimization on the hierarchical tucker manifold – applications to tensor completion. Linear Algebra and its Applications
- [2] L Greengard and J.Y. Lee. Accelerating the nonuniform fast fourier transform. SIAM Review.

## Optimization problem

The sequence of operators is then

$\mathcal{R}$  : irregular full grid  $\rightarrow$  subsampled grid

$\mathcal{F}$  : regular full grid  $\rightarrow$  irregular full grid

$\mathcal{P}$  : (src x, rec x, src y, rec y)  $\rightarrow$  (src x, src y, rec x, rec y)

We set  $\mathcal{A} = \mathcal{R}\mathcal{F}\mathcal{P}$  and use the same optimization code as previously in [1]

In our examples, we use the non-uniform Fourier transform [2]

# Optimization problem

## Main computational costs

- Gauss-Newton method -> convergence in ~15 iterations
  - ~ 4 objective evaluations per iteration
- ~60 applications of the interpolation operator
  - main source of computational costs

# Results

## Synthetic BG Group data

### Unknown model

- 68 x 68 sources with 401 x 401 receivers, data at 7.34 Hz, 12.3 Hz

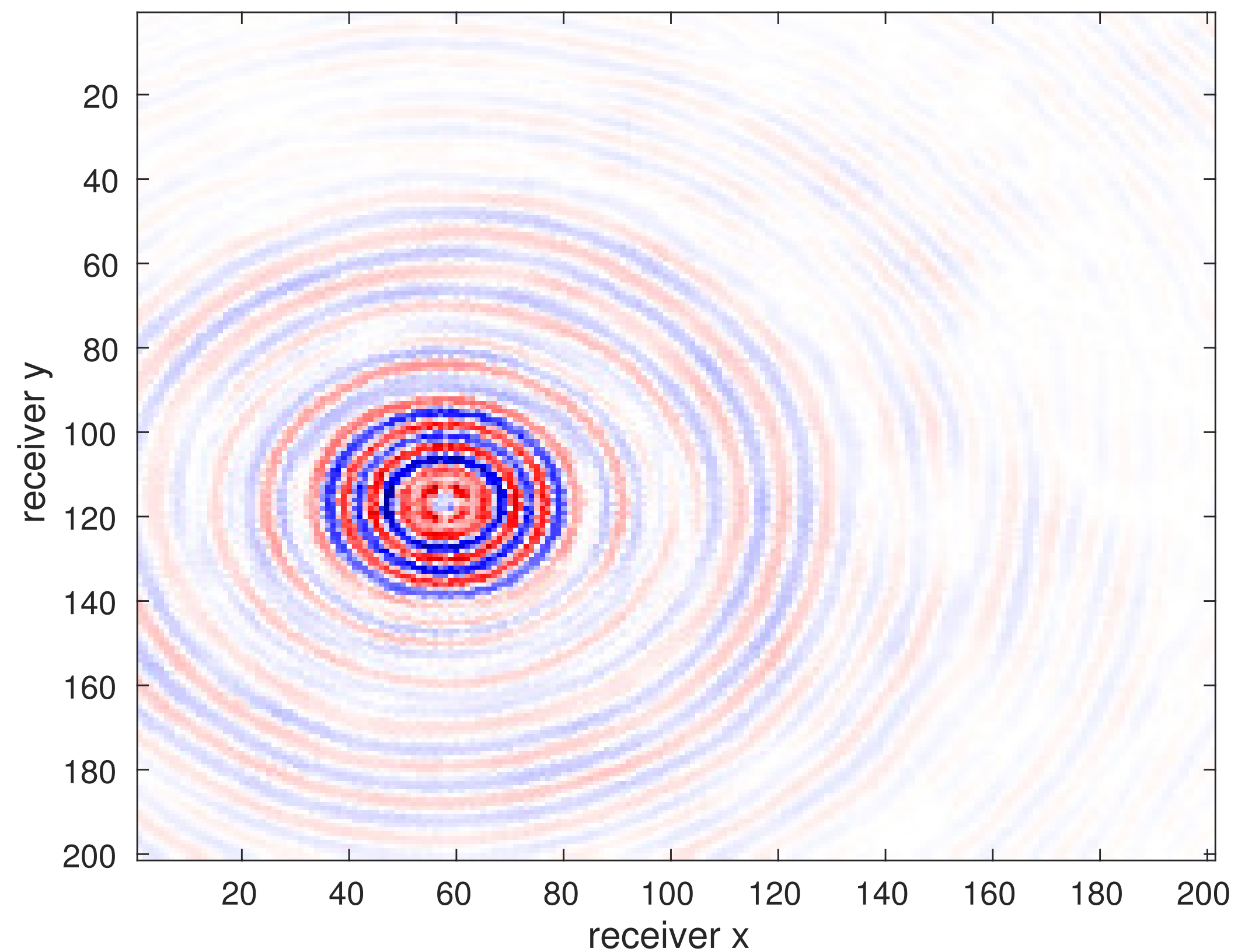
Receivers sampled on a randomly perturbed 201 x 201 grid

We compare to 'vanilla' tensor completion, where we just bin the data to a regular grid

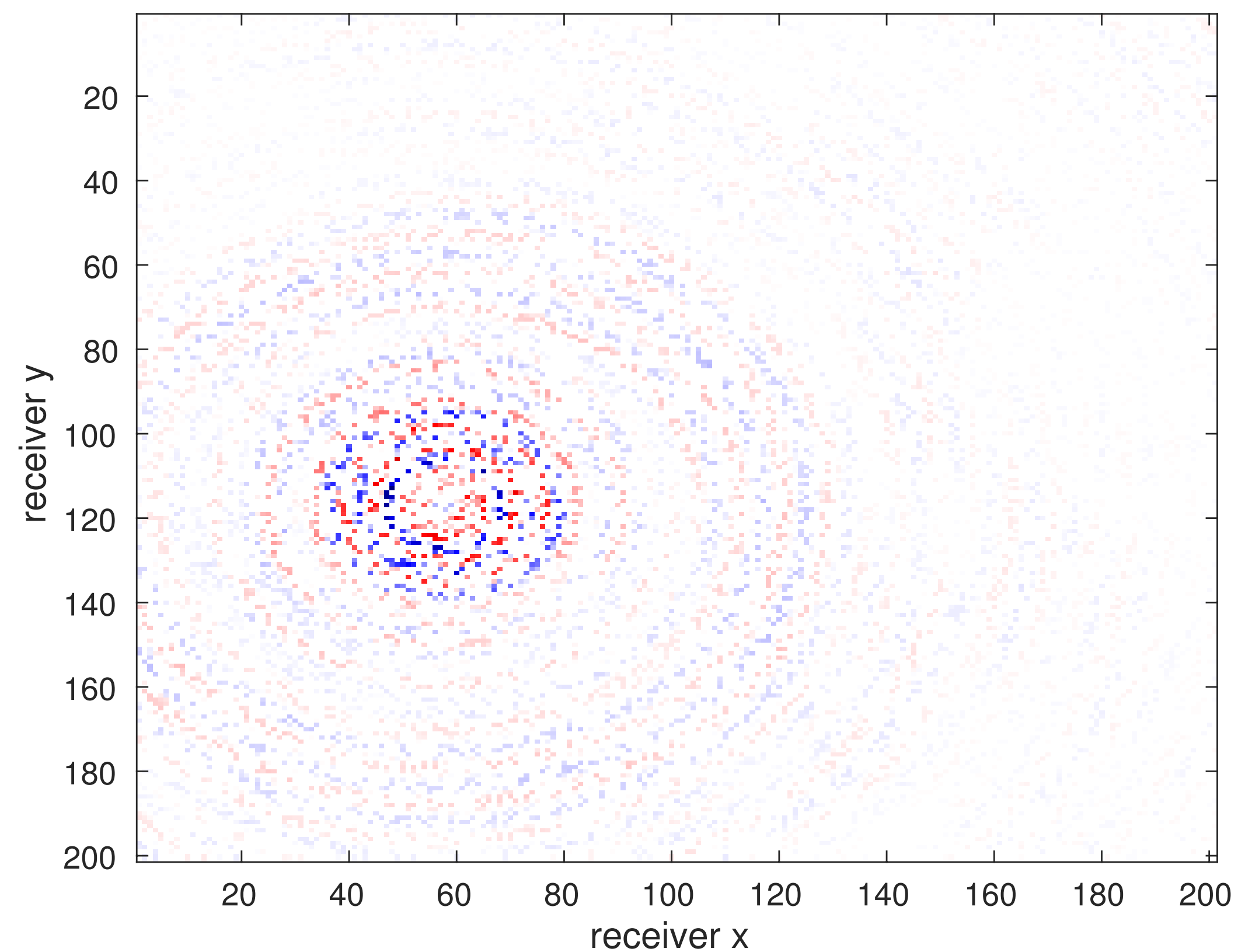


# 7.34 Hz - 75% missing receivers

*Common source gather*



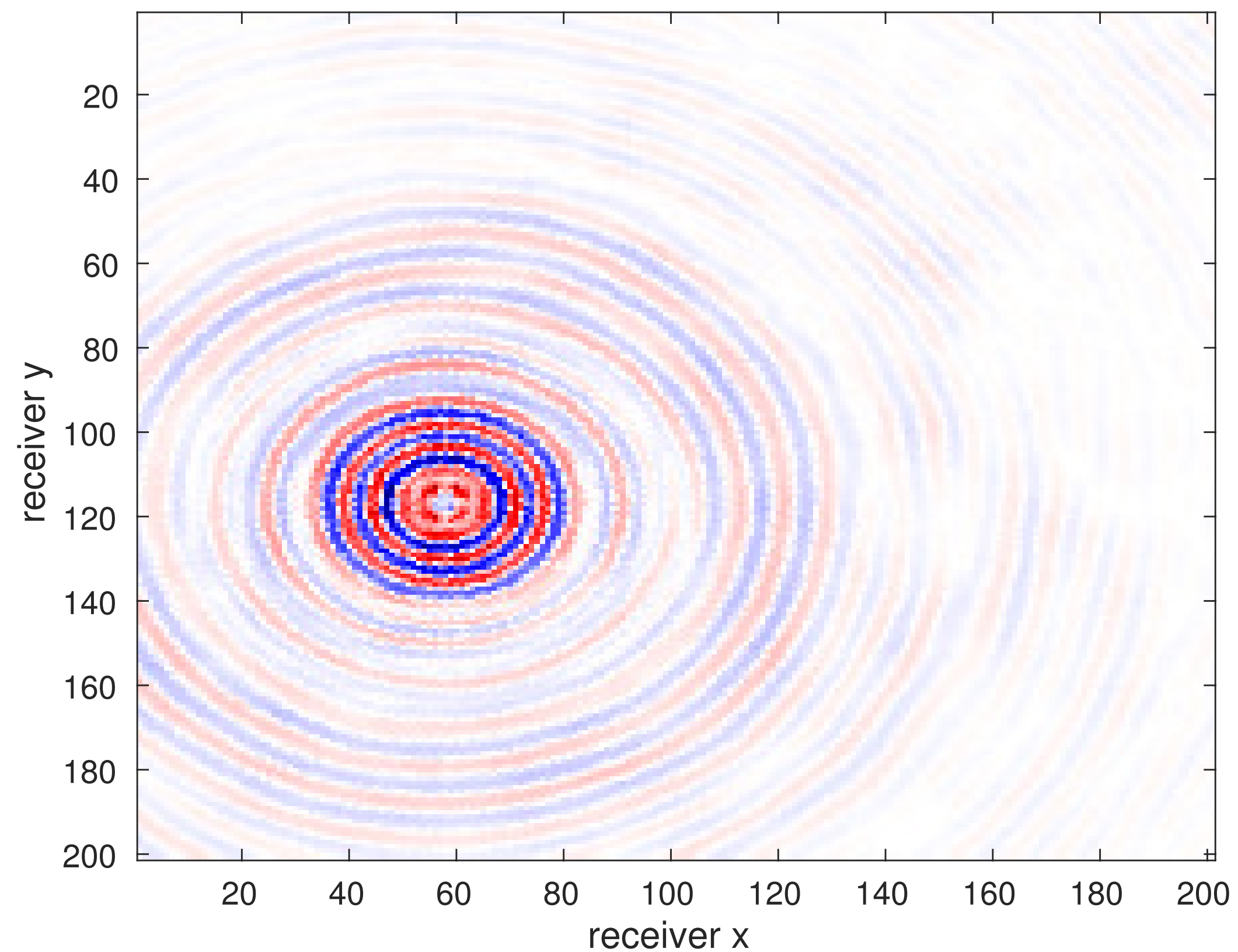
True data



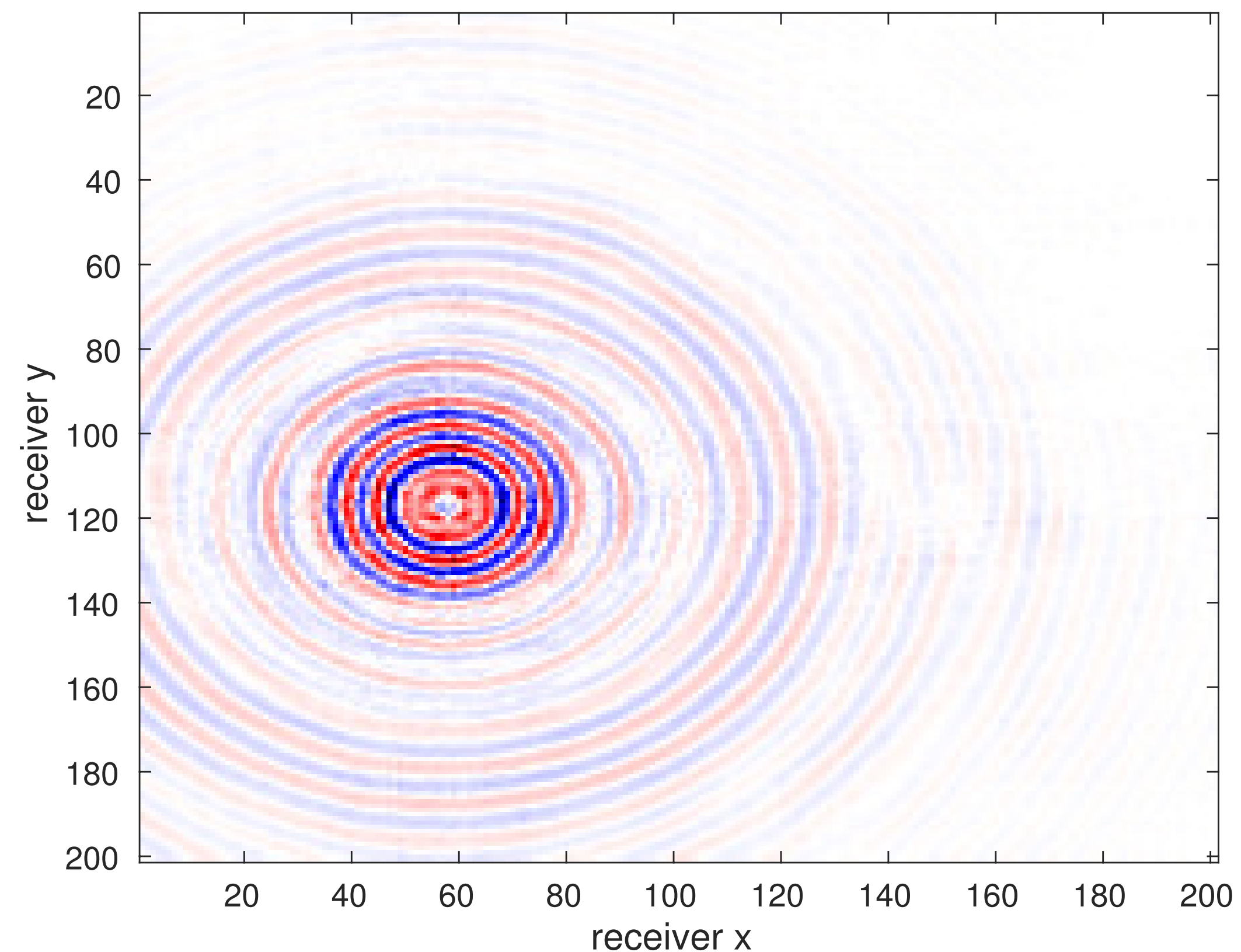
Subsampled data

# 7.34 Hz - 75% missing receivers

*Common source gather*



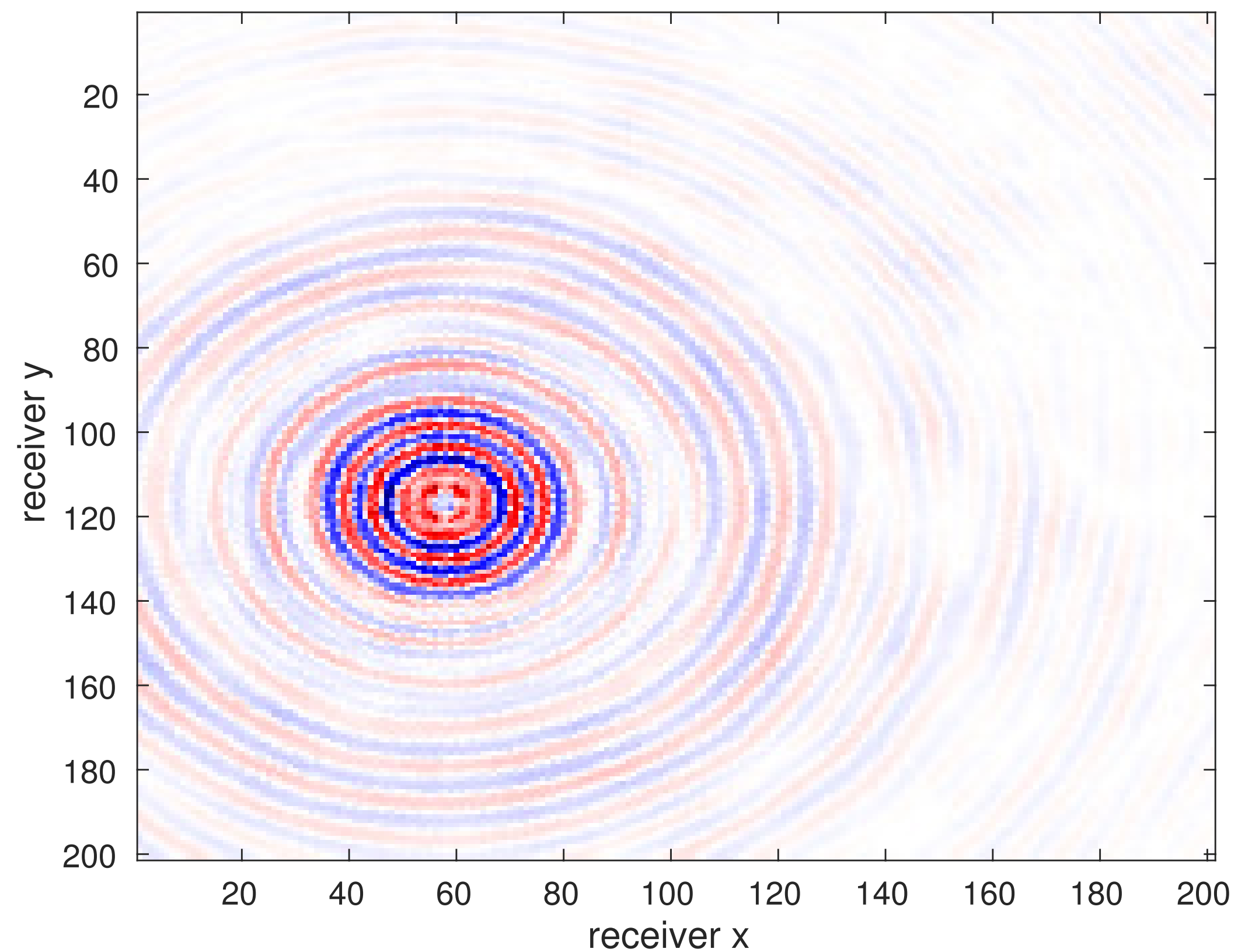
True data



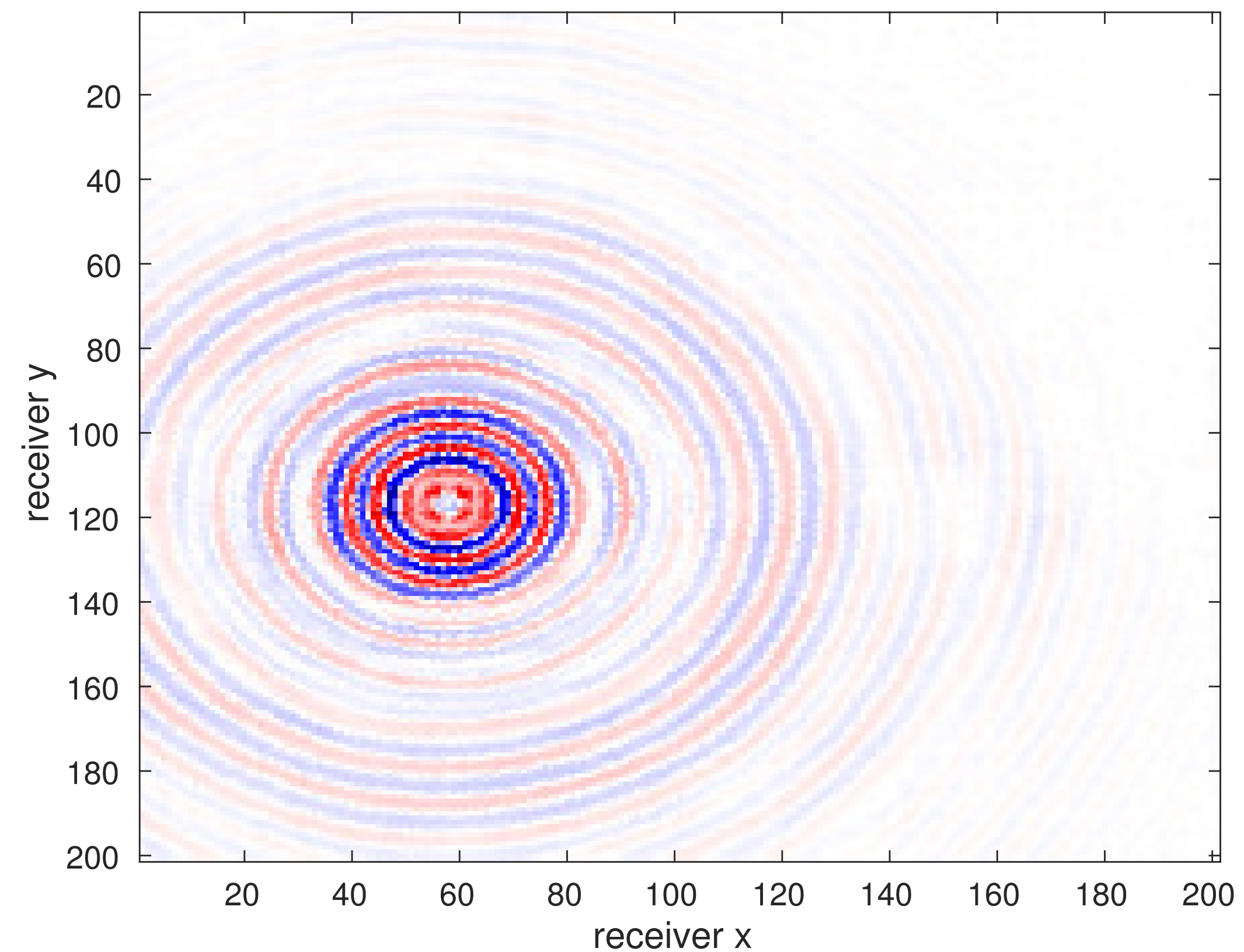
Vanilla tensor completion  
SNR 9.46 dB

# 7.34 Hz - 75% missing receivers

*Common source gather*



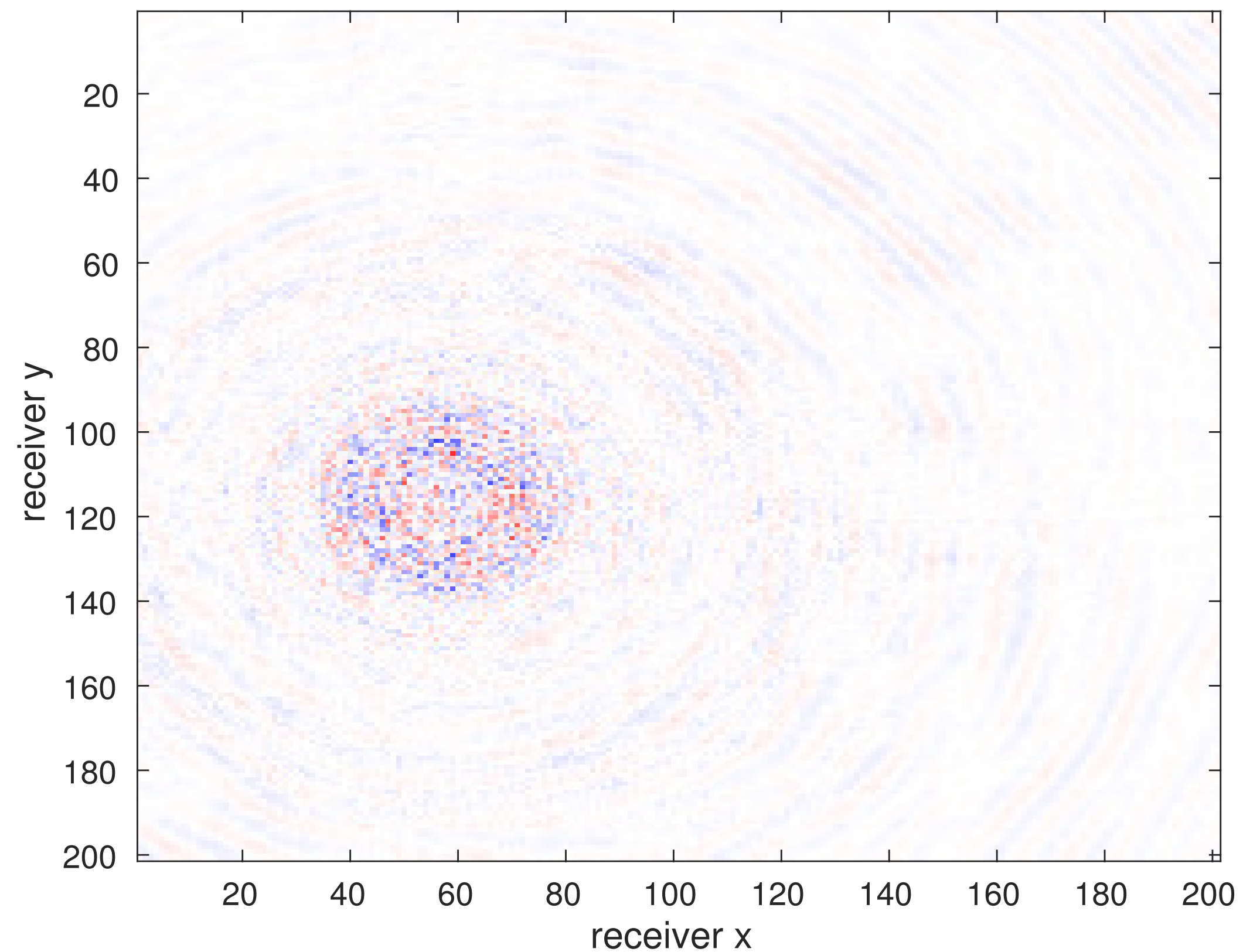
True data



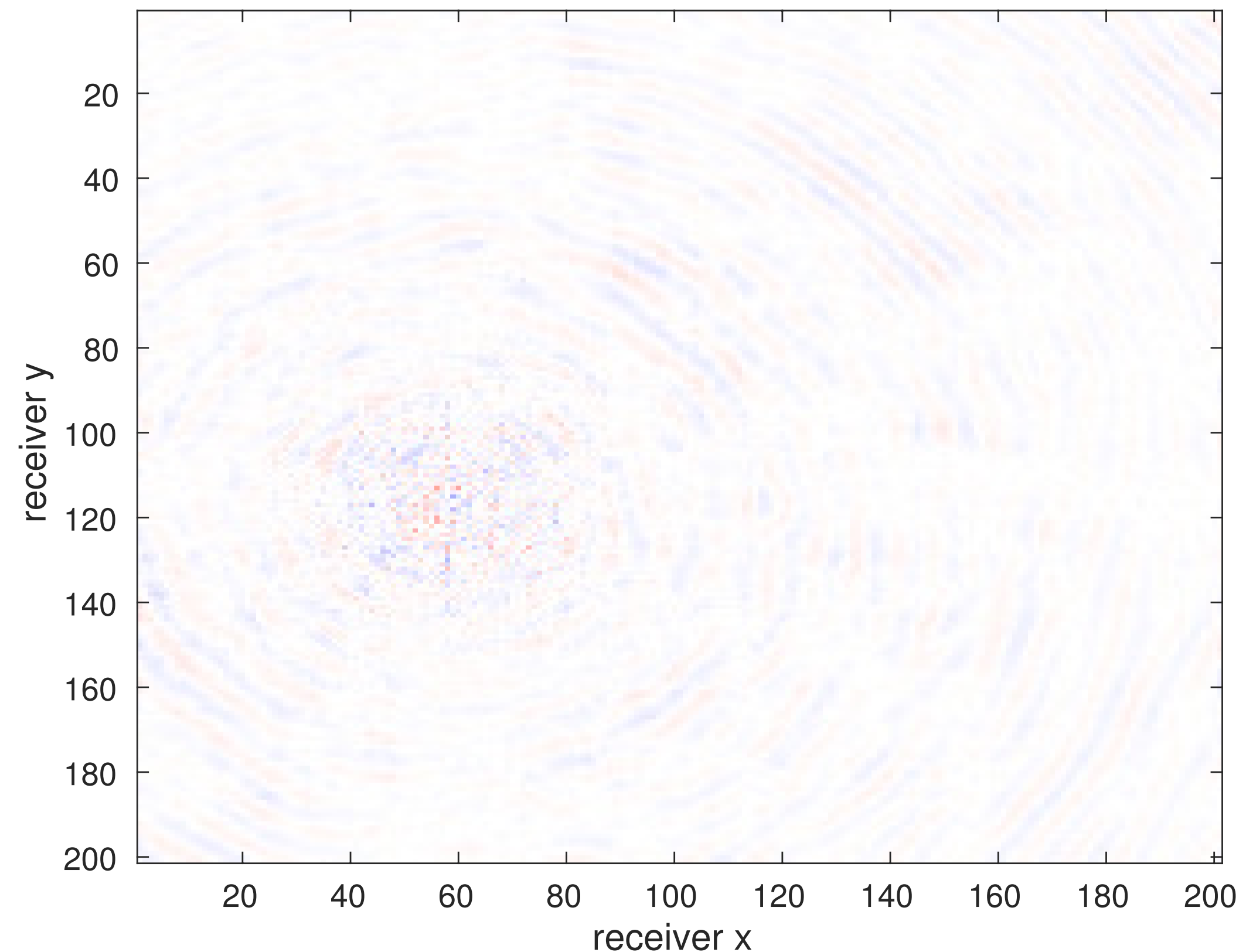
Regularized tensor completion  
SNR 15.7 dB

# 7.34 Hz - 75% missing receivers

*Common source gather*



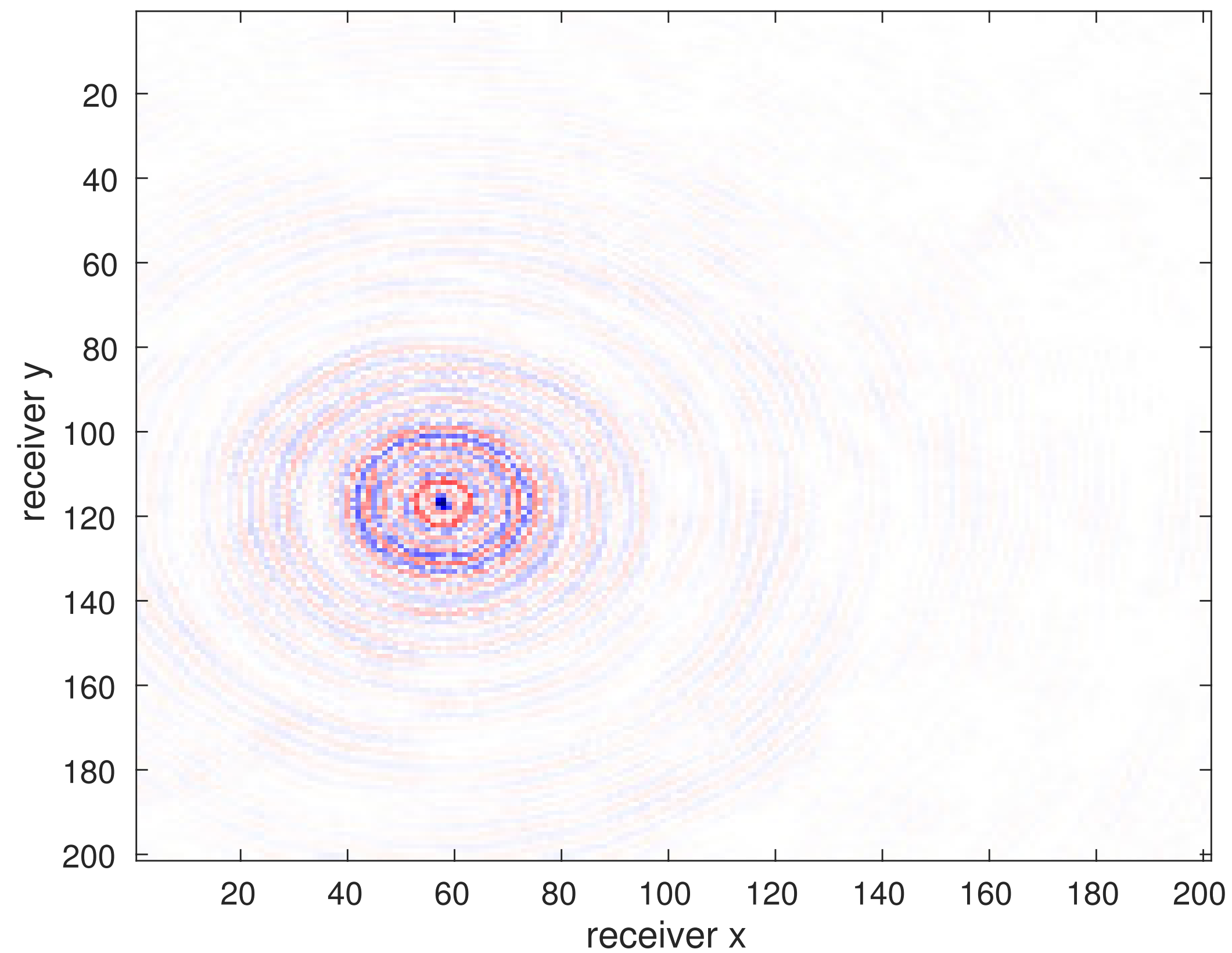
Vanilla tensor completion  
difference



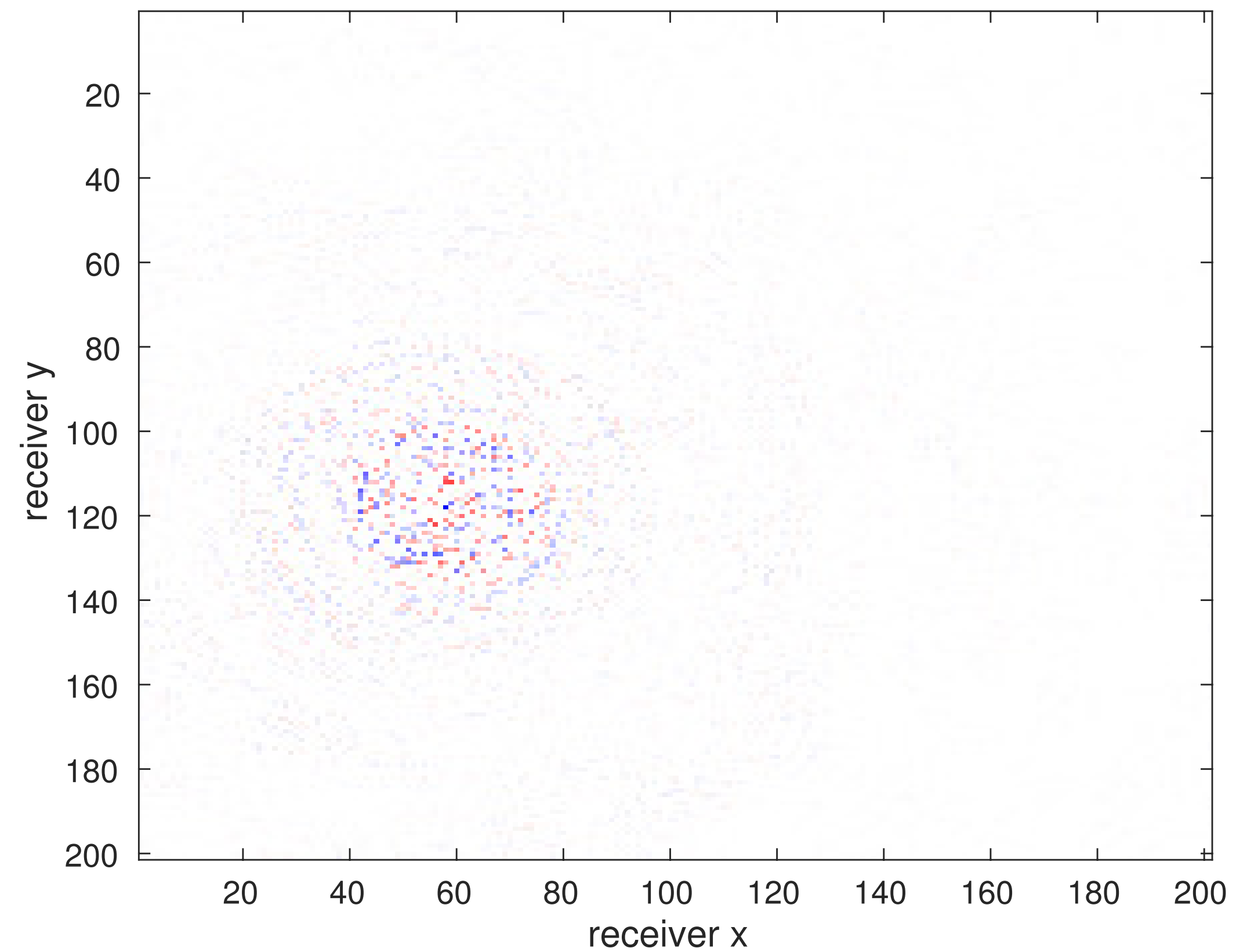
Regularized tensor completion  
difference

# 12.3 Hz - 75% missing receivers

*Common source gather*



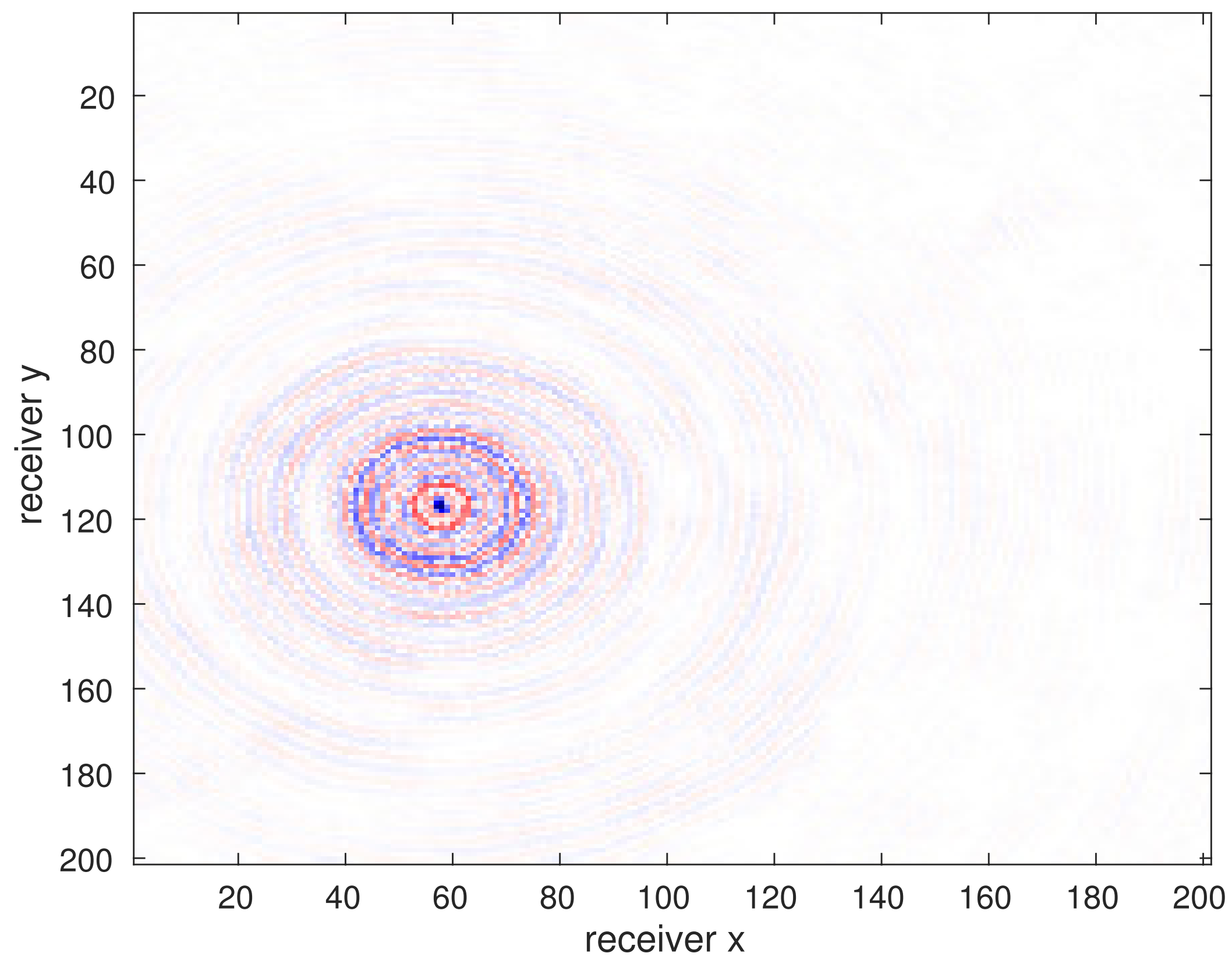
True data



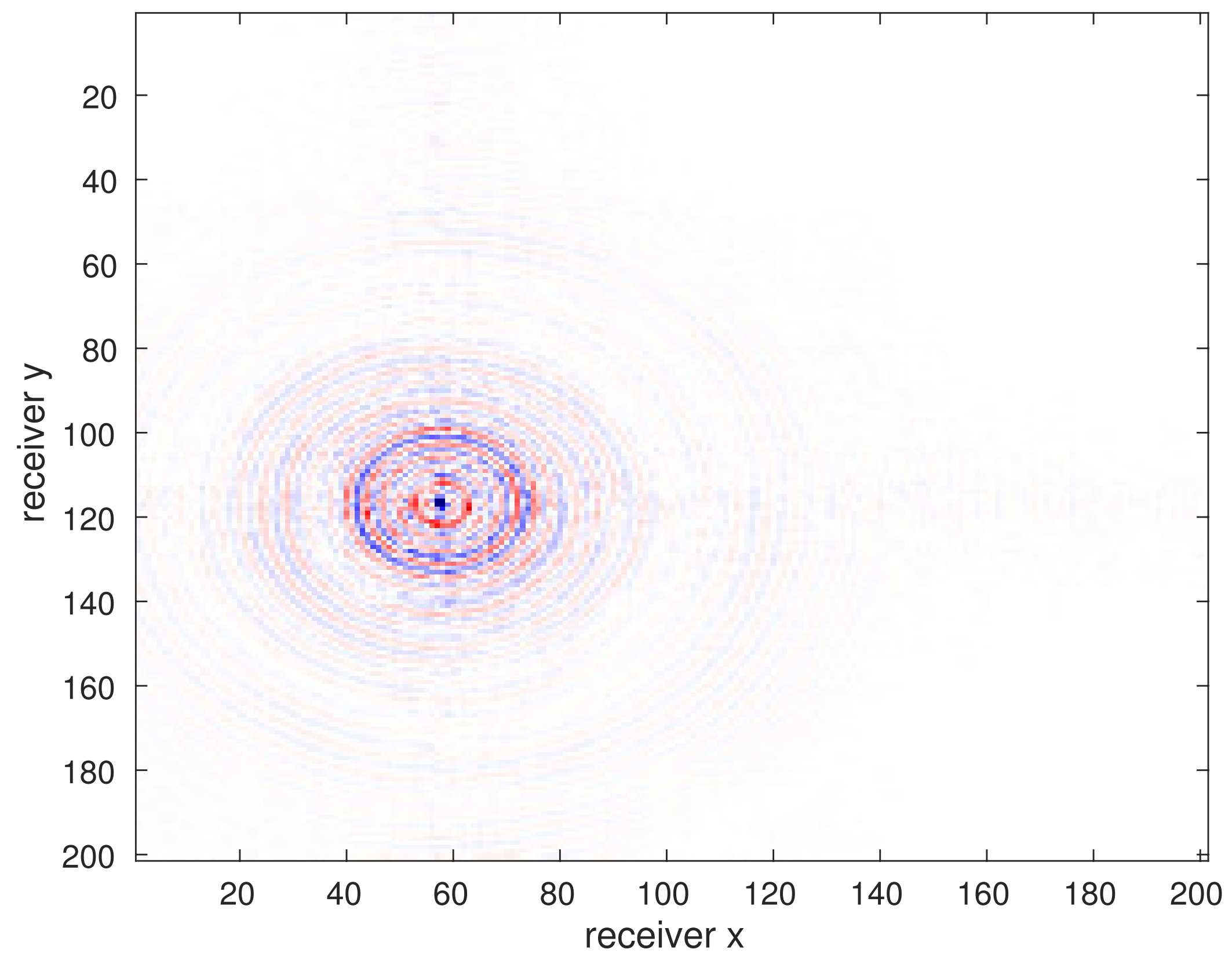
Subsampled data

# 12.3 Hz - 75% missing receivers

*Common source gather*



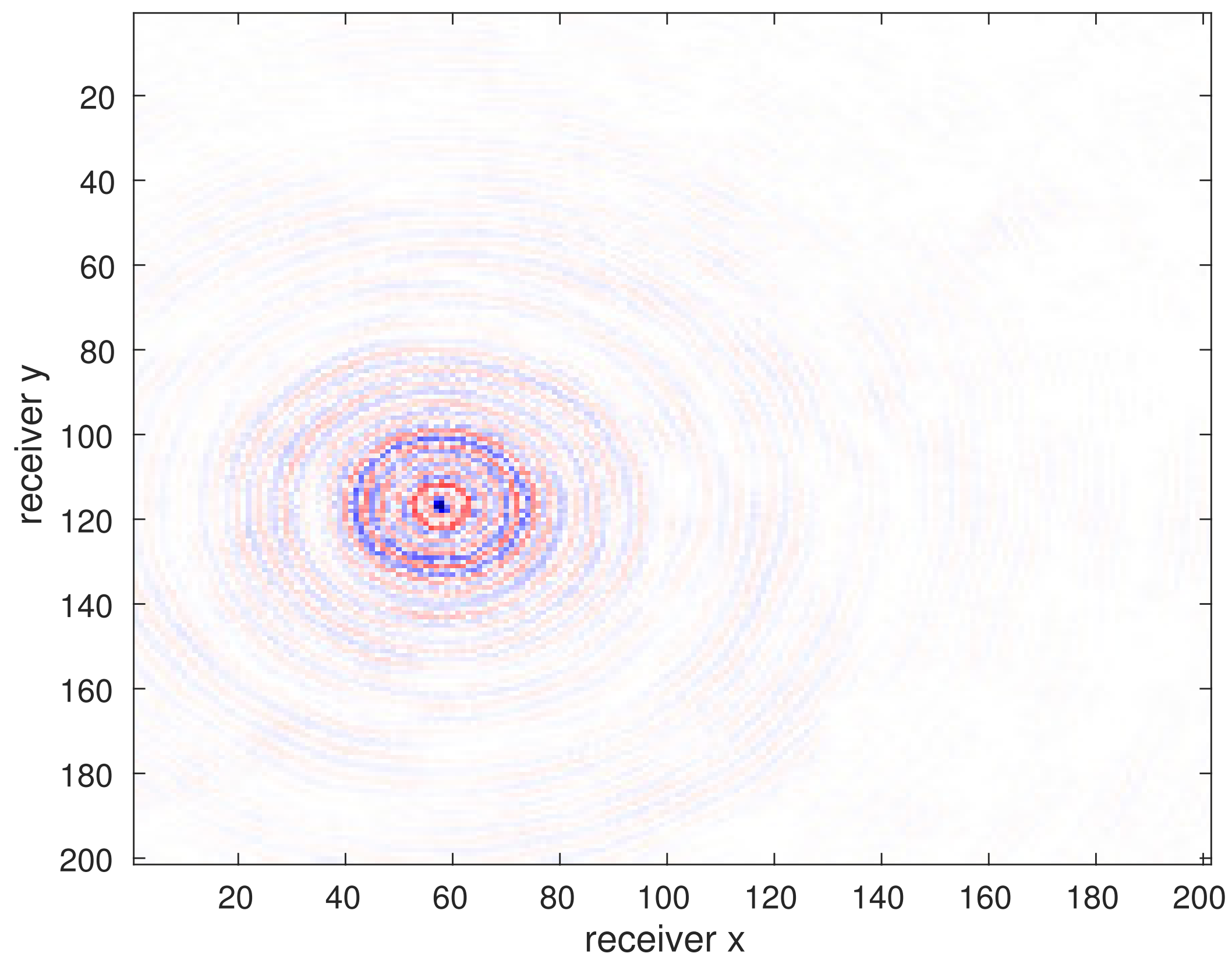
True data



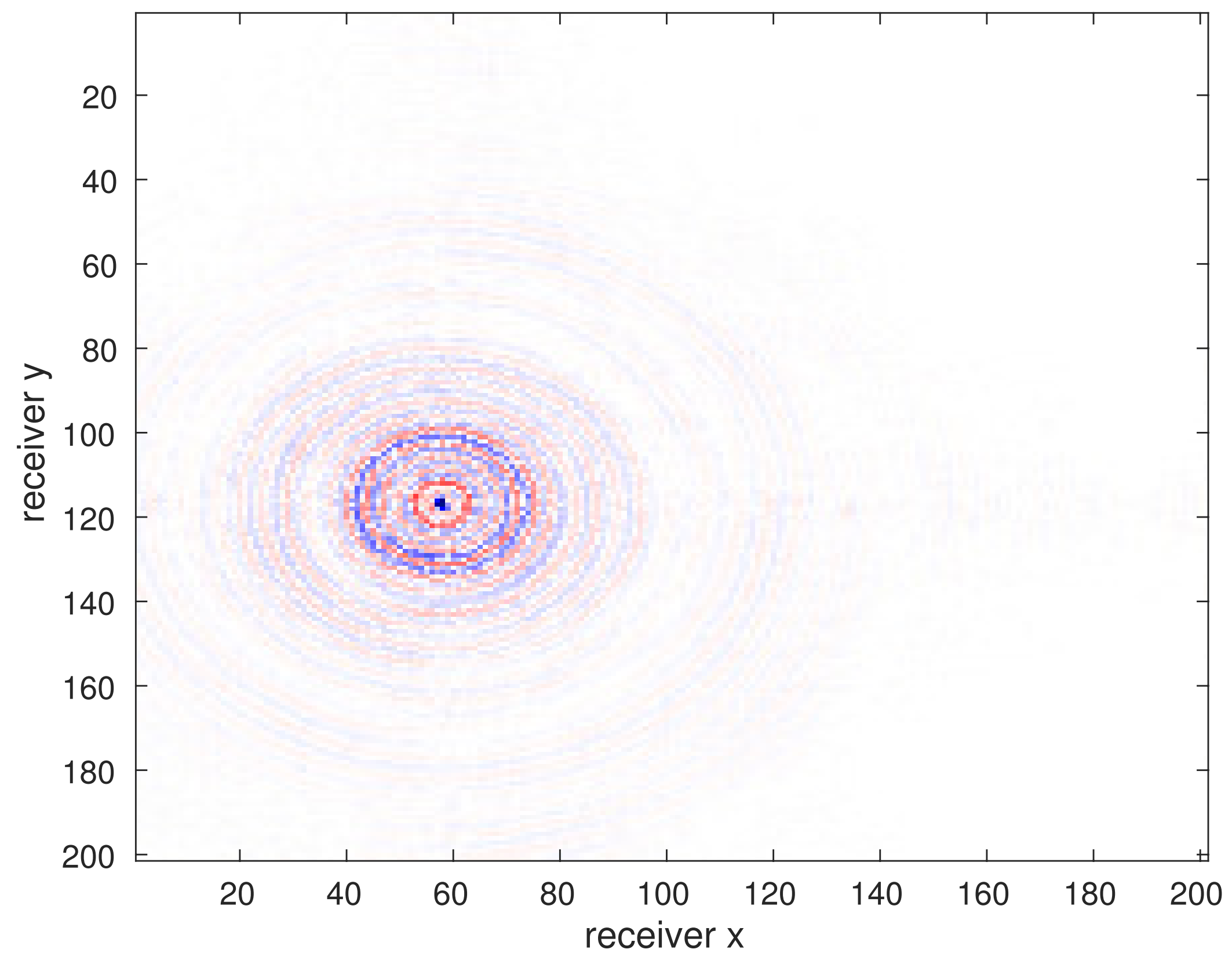
Vanilla tensor completion  
SNR 4.45 dB

# 12.3 Hz - 75% missing receivers

*Common source gather*



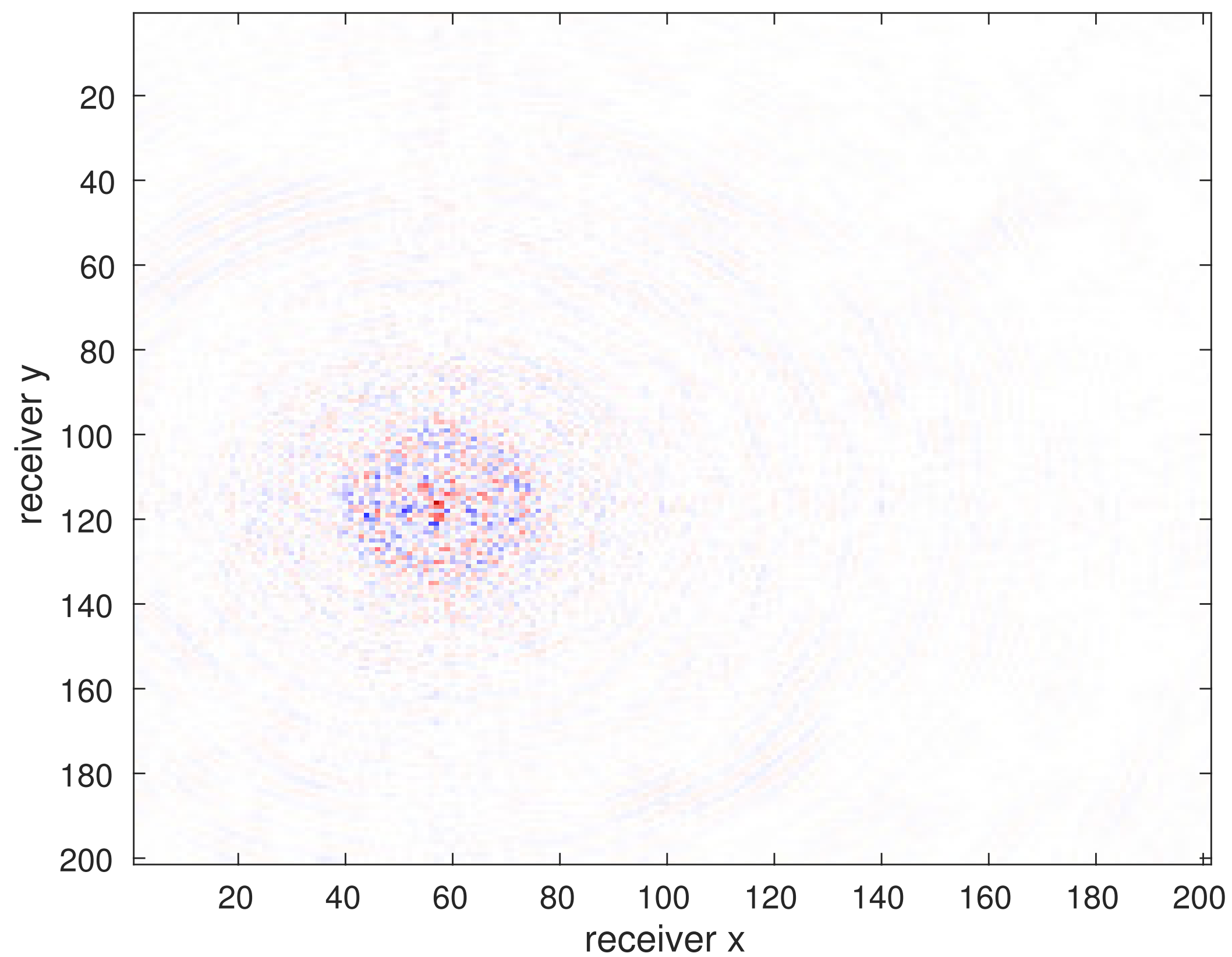
True data



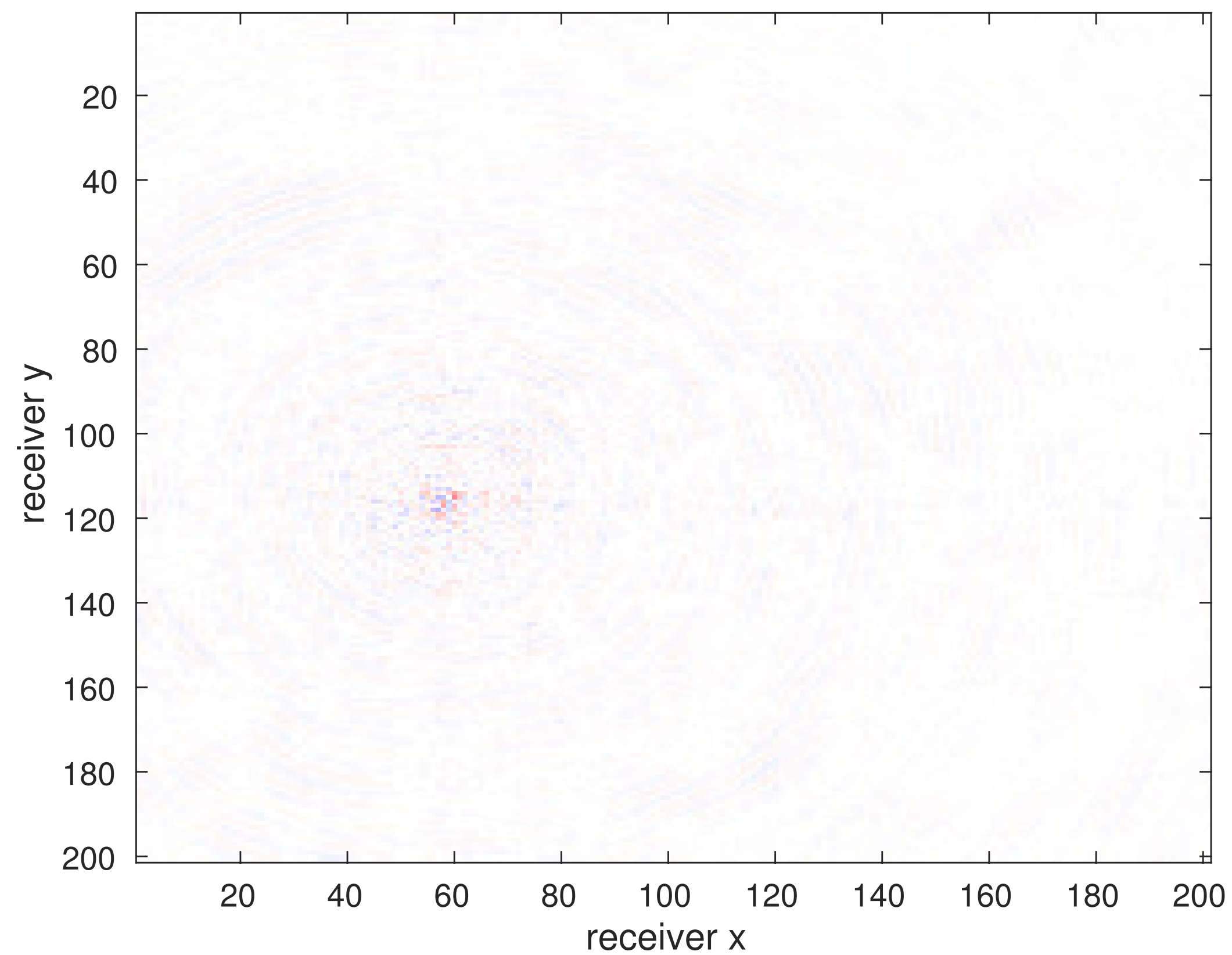
Regularized tensor completion  
SNR 11.4 dB

# 12.3 Hz - 75% missing receivers

*Common source gather*



Vanilla tensor completion  
difference

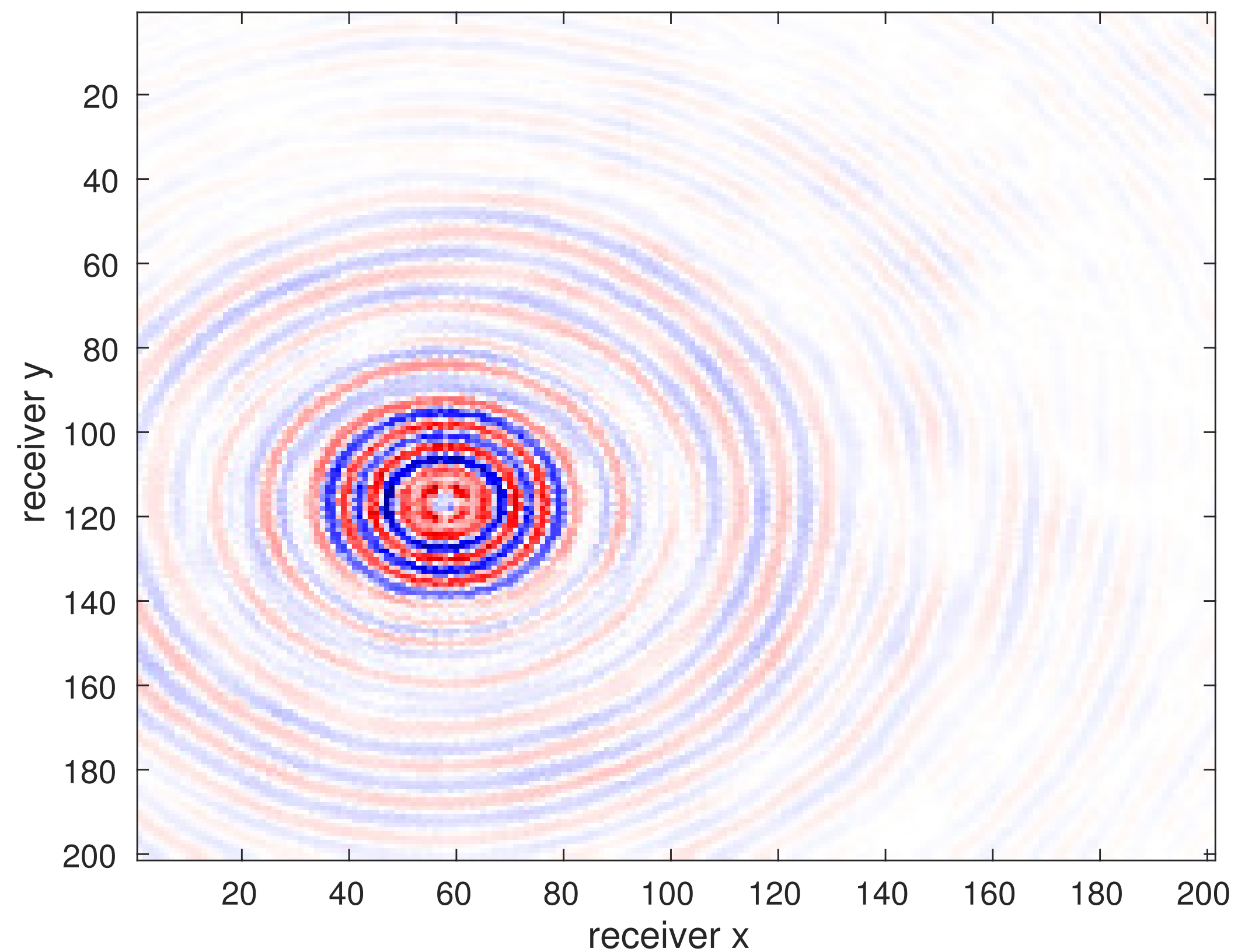


Regularized tensor completion  
difference

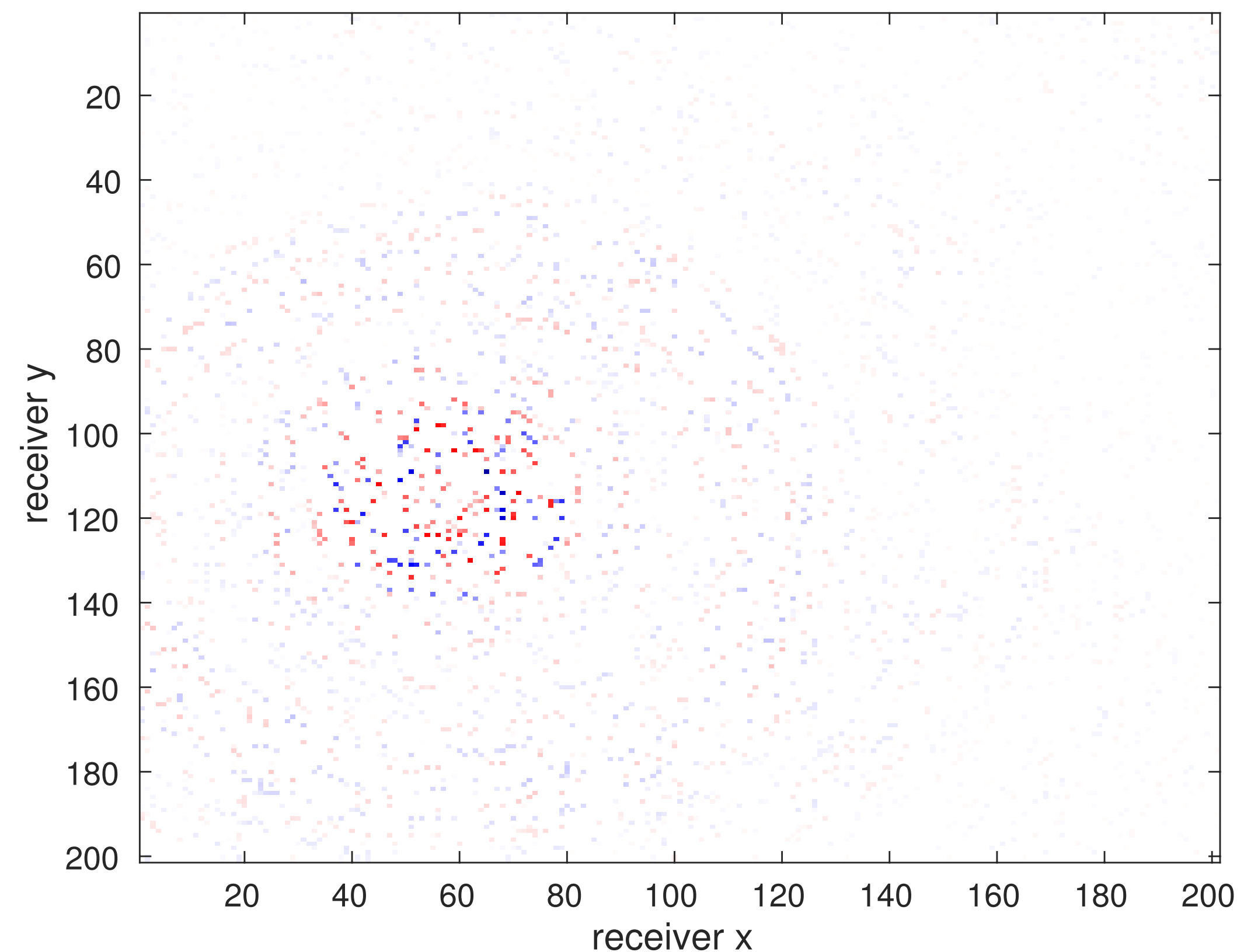


# 7.34 Hz - 90% missing receivers

*Common source gather*



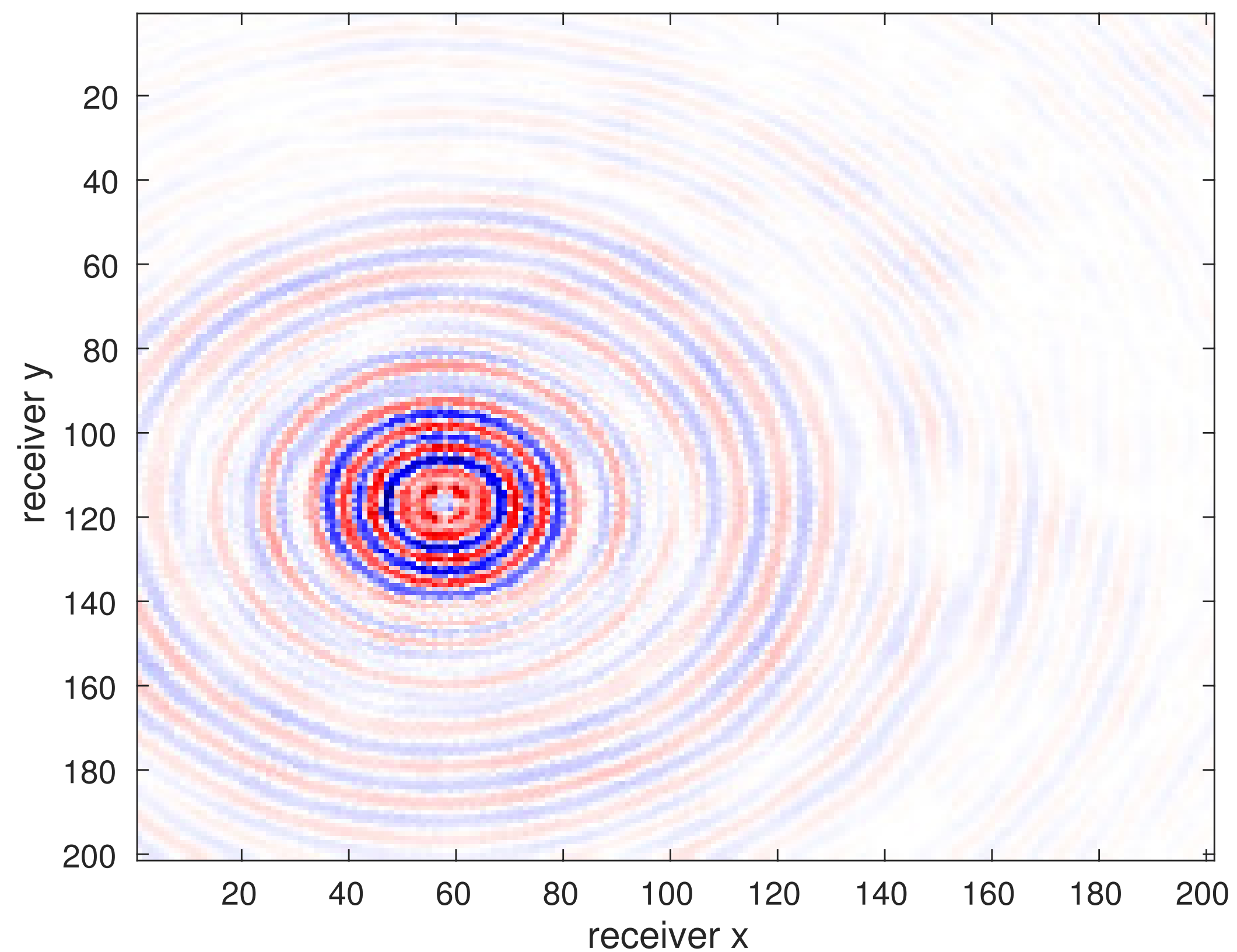
True data



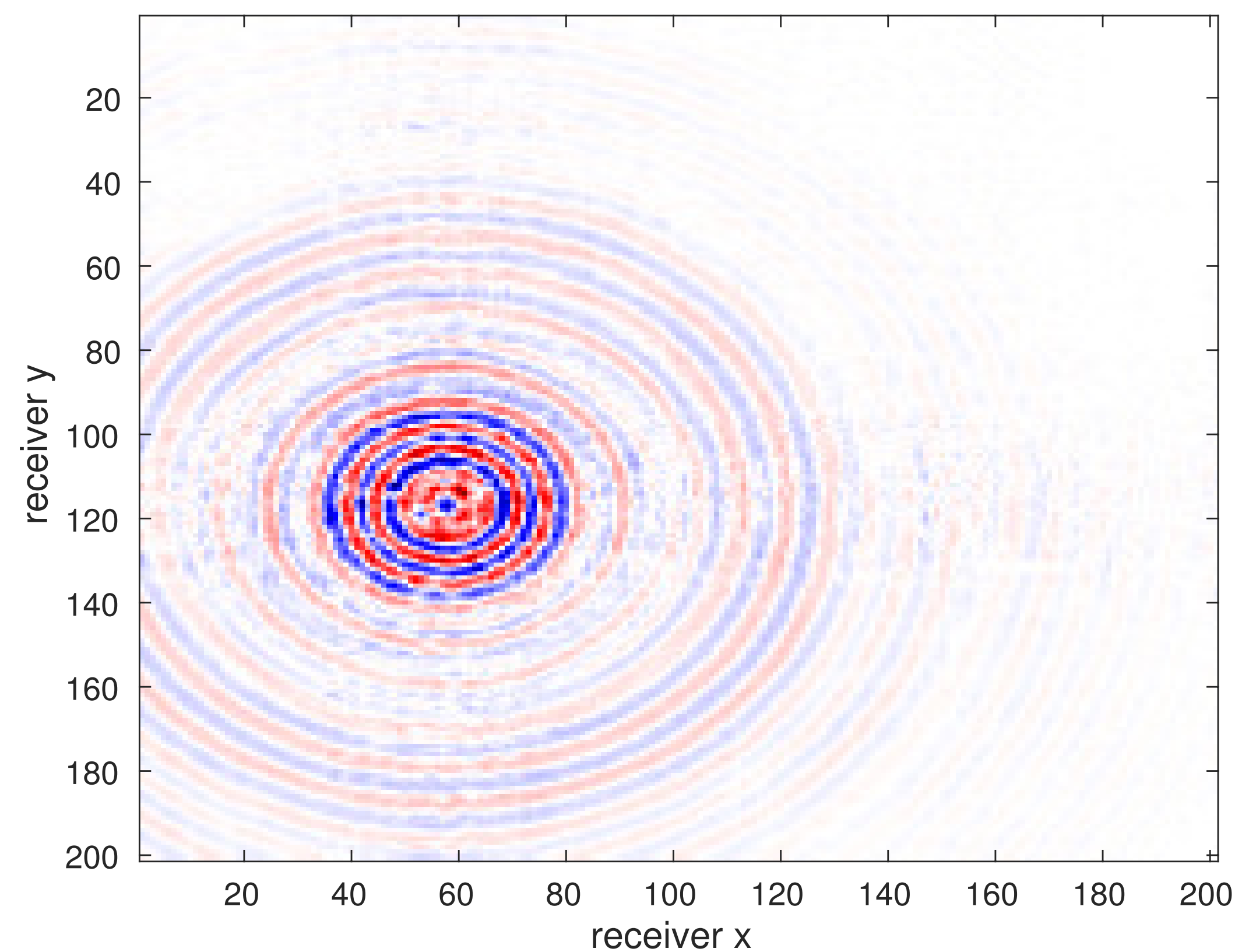
Subsampled data

# 7.34 Hz - 90% missing receivers

*Common source gather*



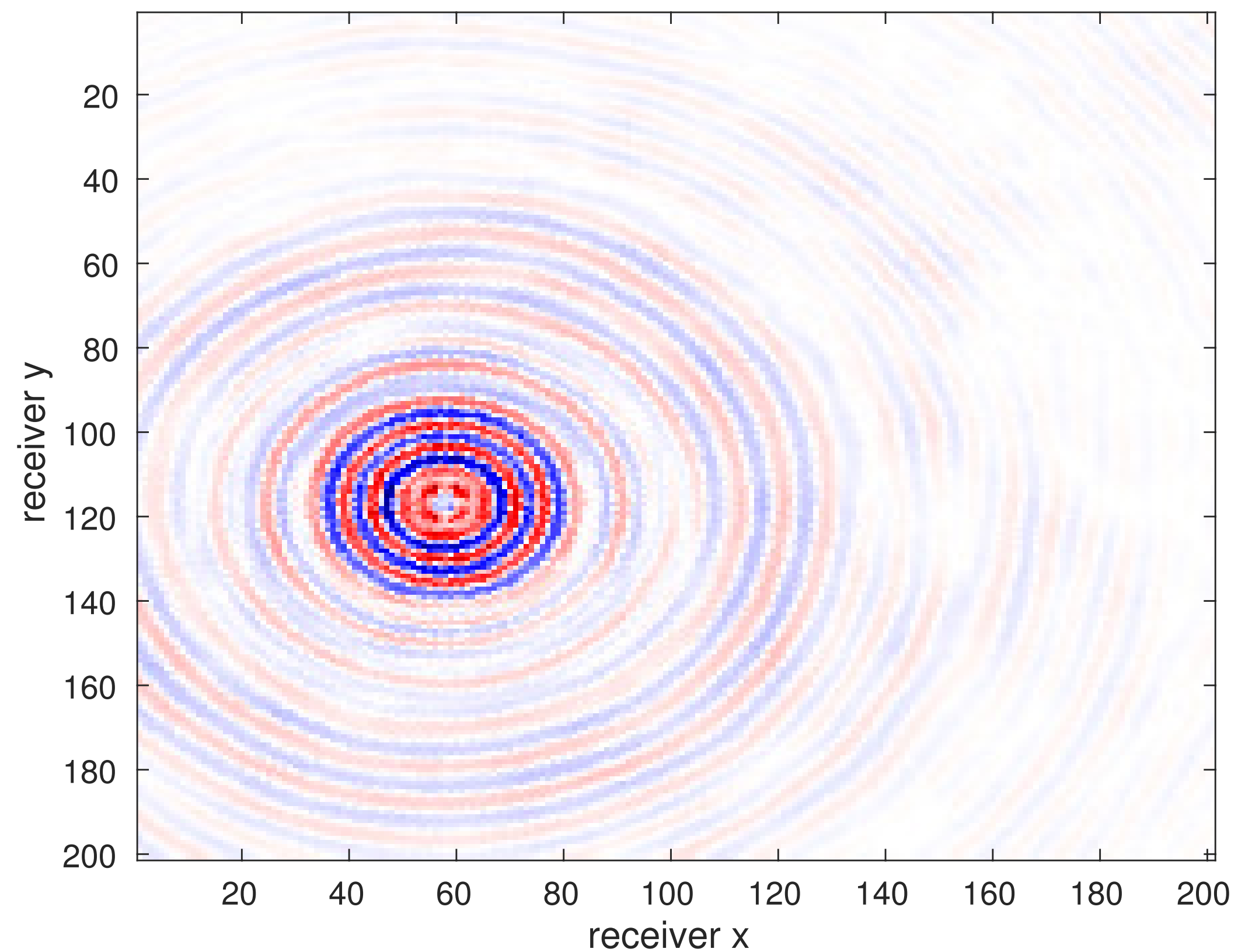
True data



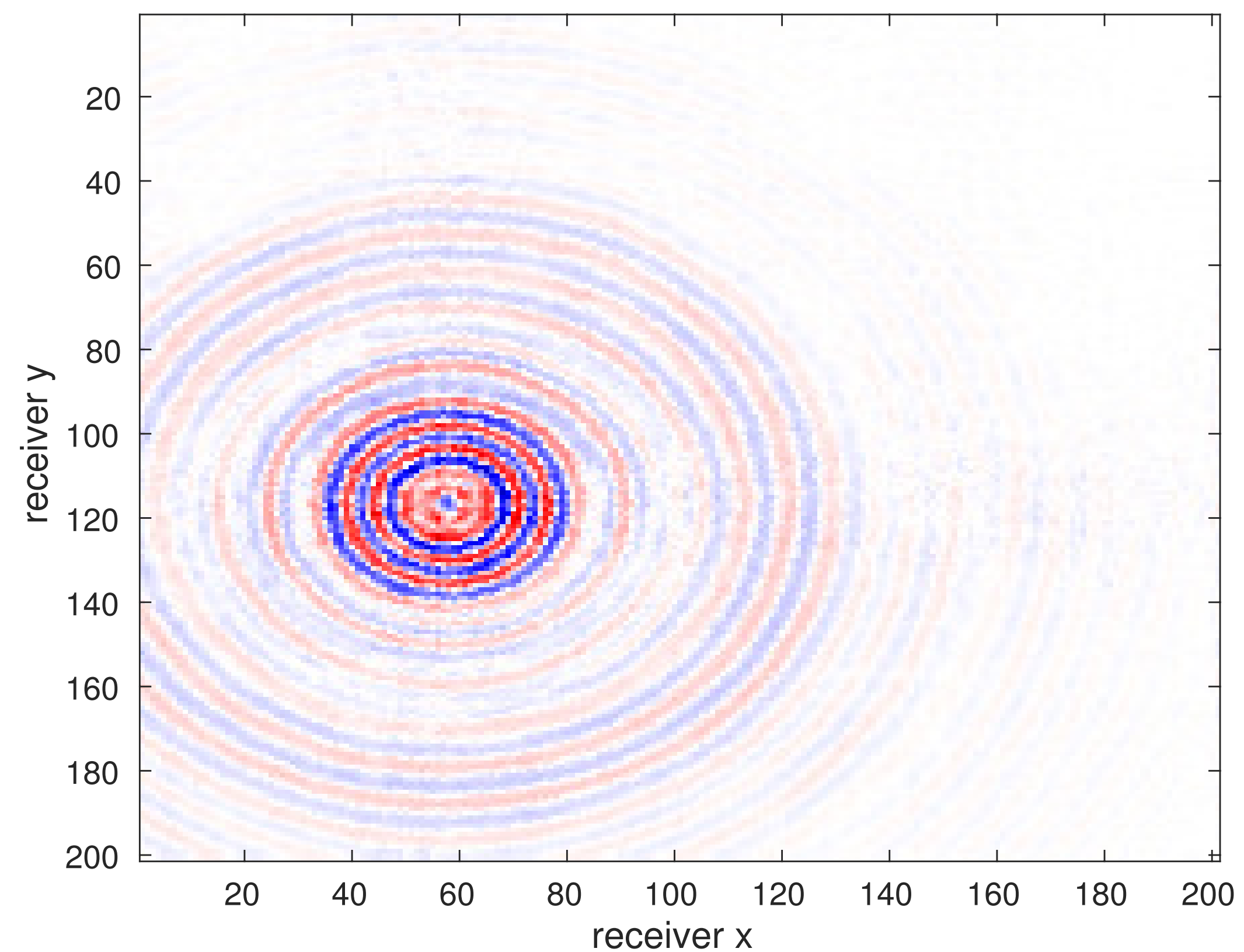
Vanilla tensor completion  
SNR 6.95 dB

# 7.34 Hz - 90% missing receivers

*Common source gather*



True data



Regularized tensor completion  
SNR 11 dB

## Conclusion

3D seismic data has an underlying structure that we can exploit for interpolation (Hierarchical Tucker format)

Different schemes for organizing data - important for recovery

## Conclusion

We can interpolate HT tensors with missing entries using the Riemannian manifold structure of the HT format

It is important and worthwhile to account for the off-grid nature of sampling when interpolating data

- binning just doesn't cut it

# Acknowledgements

Thank you for your attention



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