

Source separation for simultaneous towed-streamer acquisition via compressed sensing

Haneet Wason

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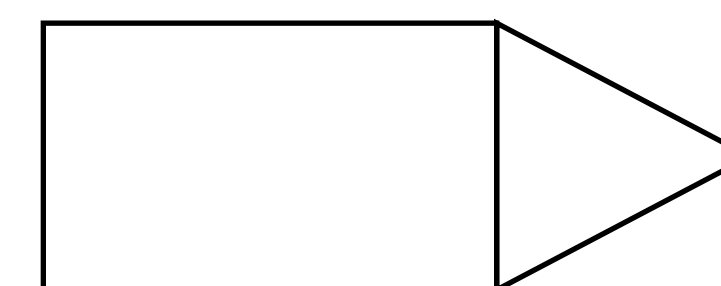
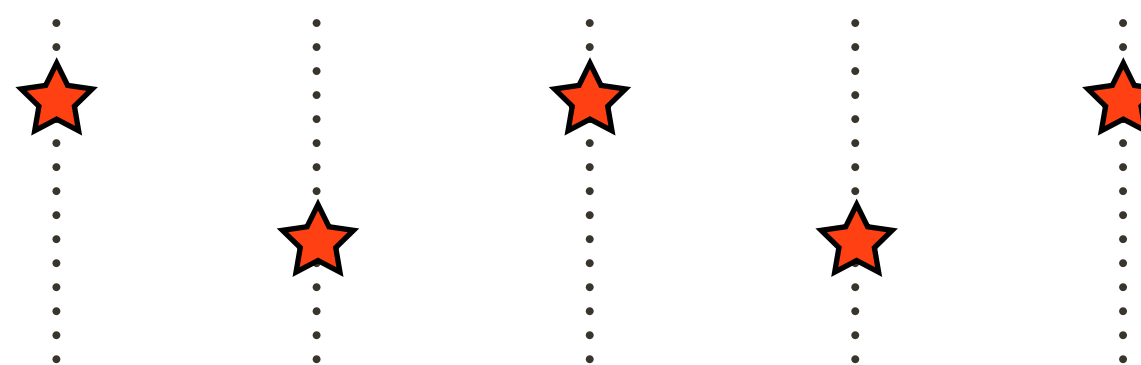


SLIM 
University of British Columbia

Periodic vs. jittered marine acquisition

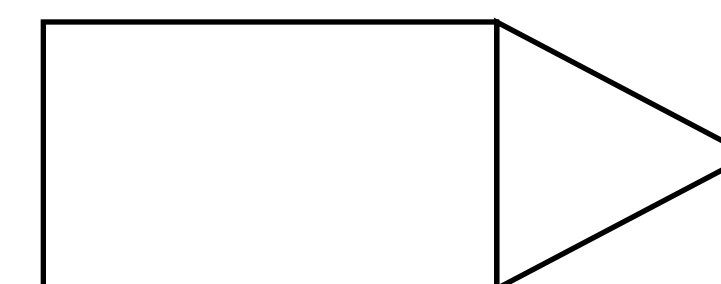
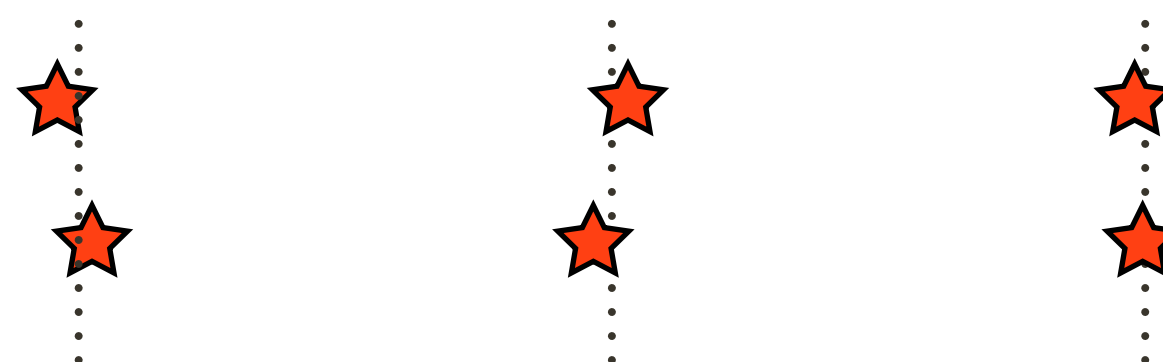
shot-time
randomness

periodically sampled spatial grid



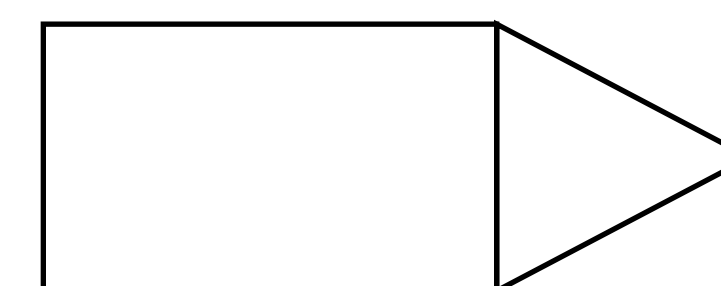
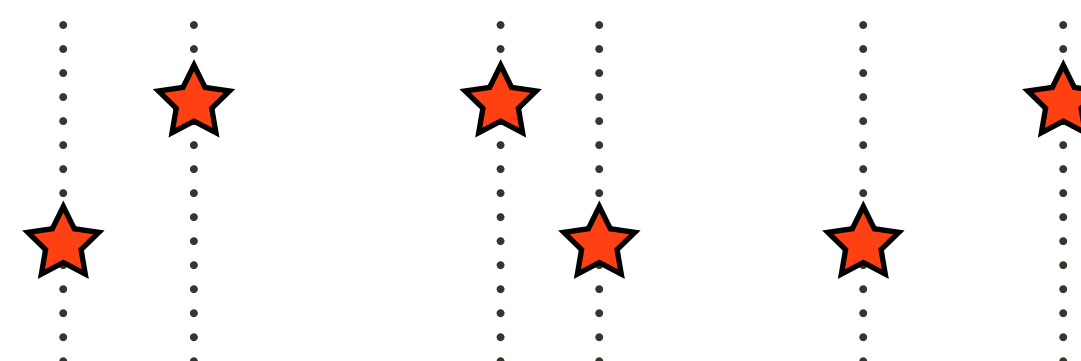
NONE

almost periodically sampled spatial grid
(over/under acquisition, towed arrays)



LOW

randomly jittered sampled spatial grid
(Time-jittered acquisition, OBC/OBN)



HIGH

[Wason and Herrmann, 2013]

[Mansour et. al., 2012]

Conventional marine acquisition

periodically sampled spatial grid

shot 1



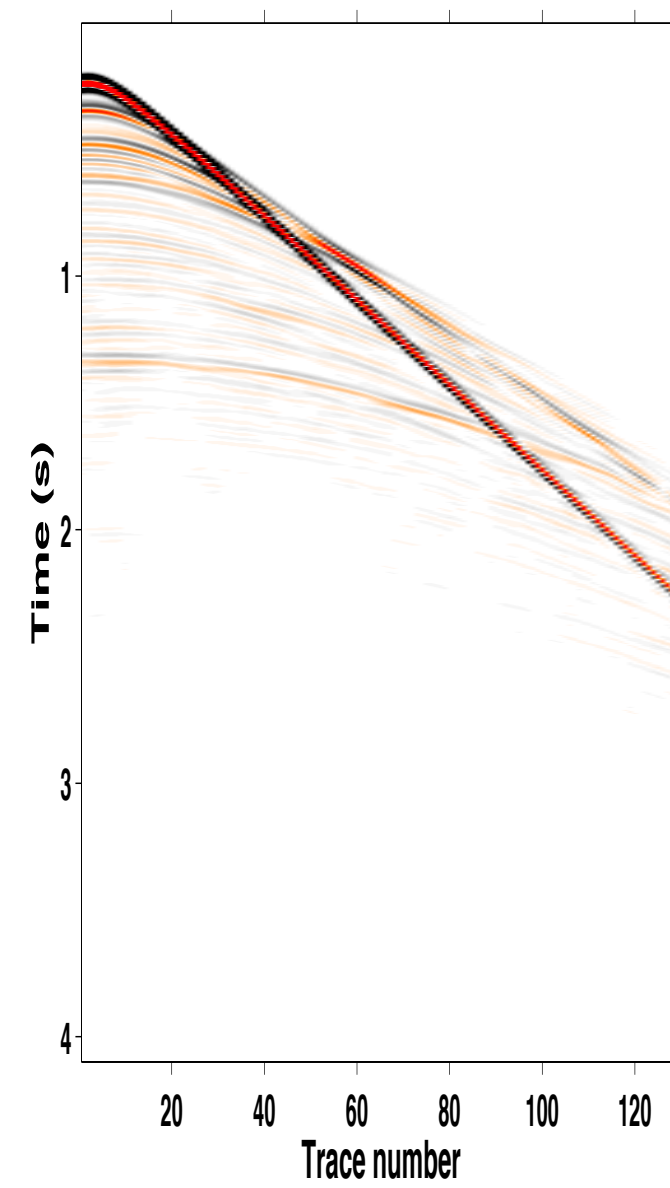
shot 2



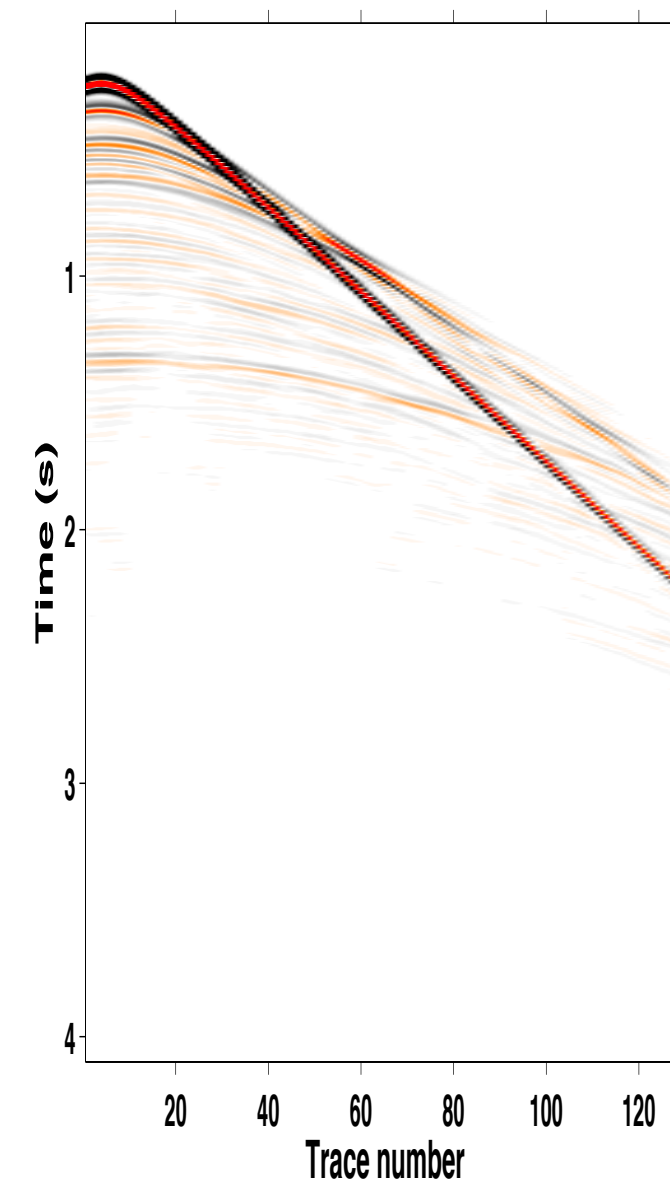
shot 3



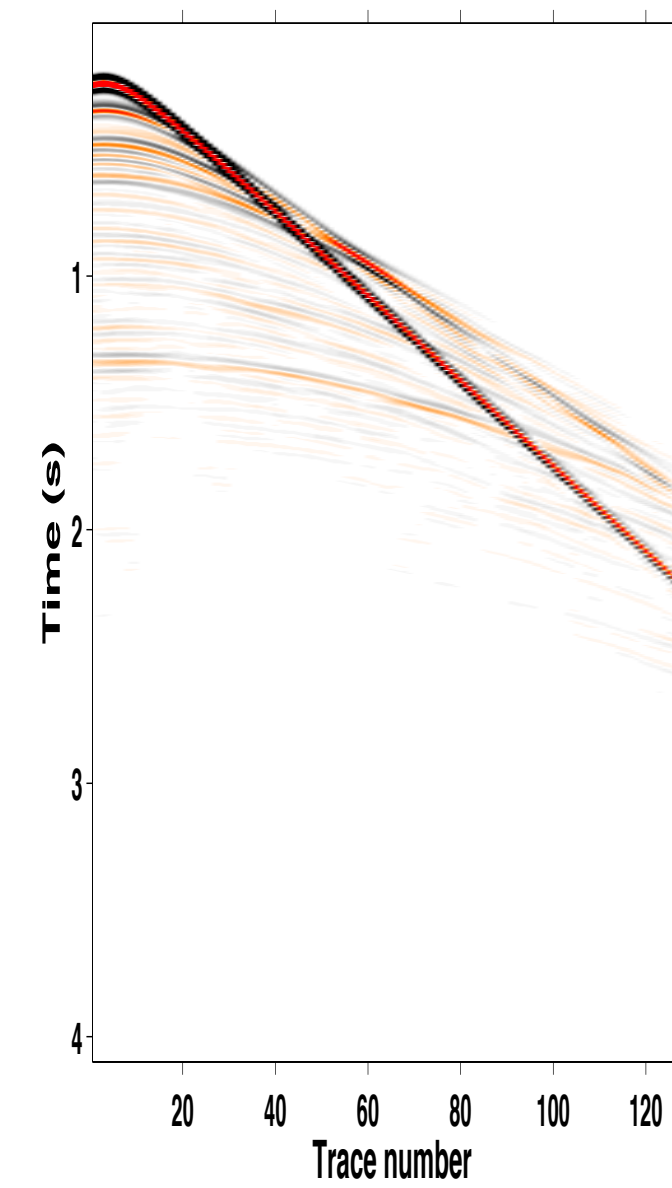
shot 1



shot 2



shot 3



Simultaneous marine acquisition

[over/under acquisition, towed arrays]

★ source depth 1

★ source depth 2

almost periodically sampled spatial grid

shot-time randomness - **LOW**

shot 1



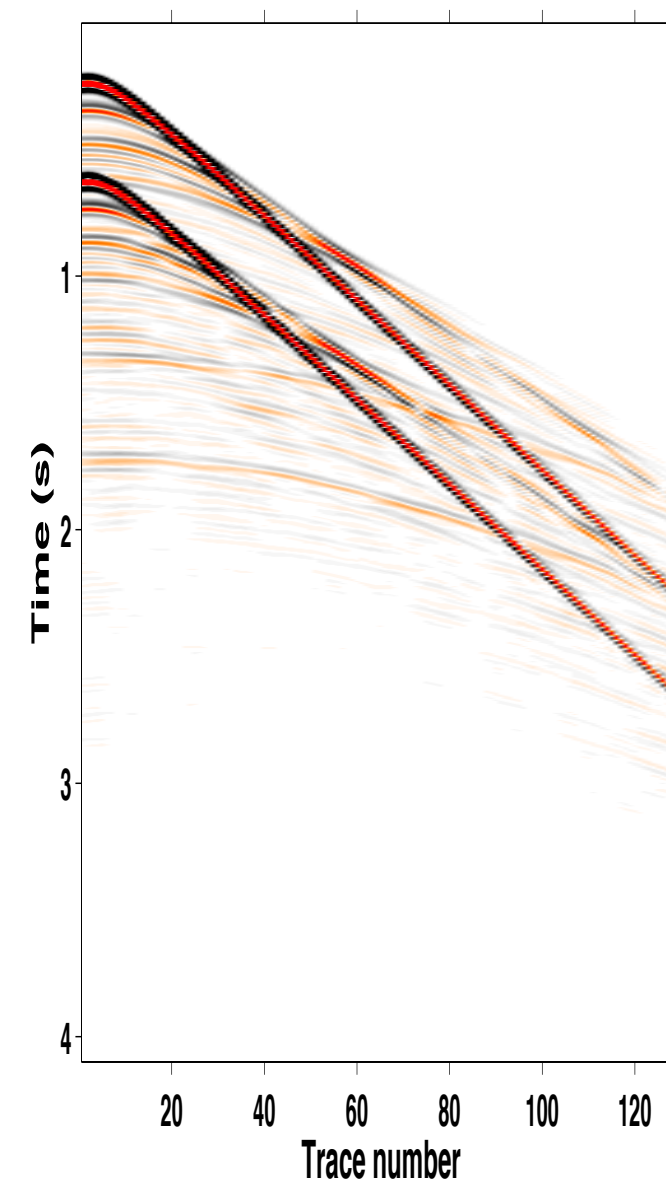
shot 2



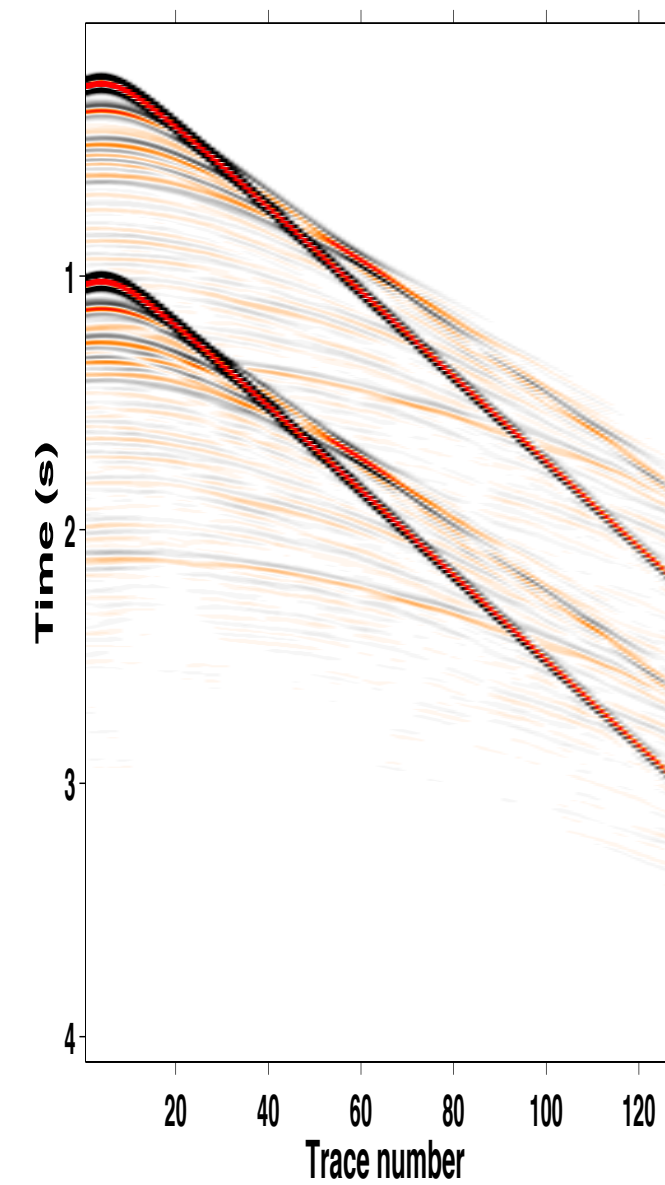
shot 3



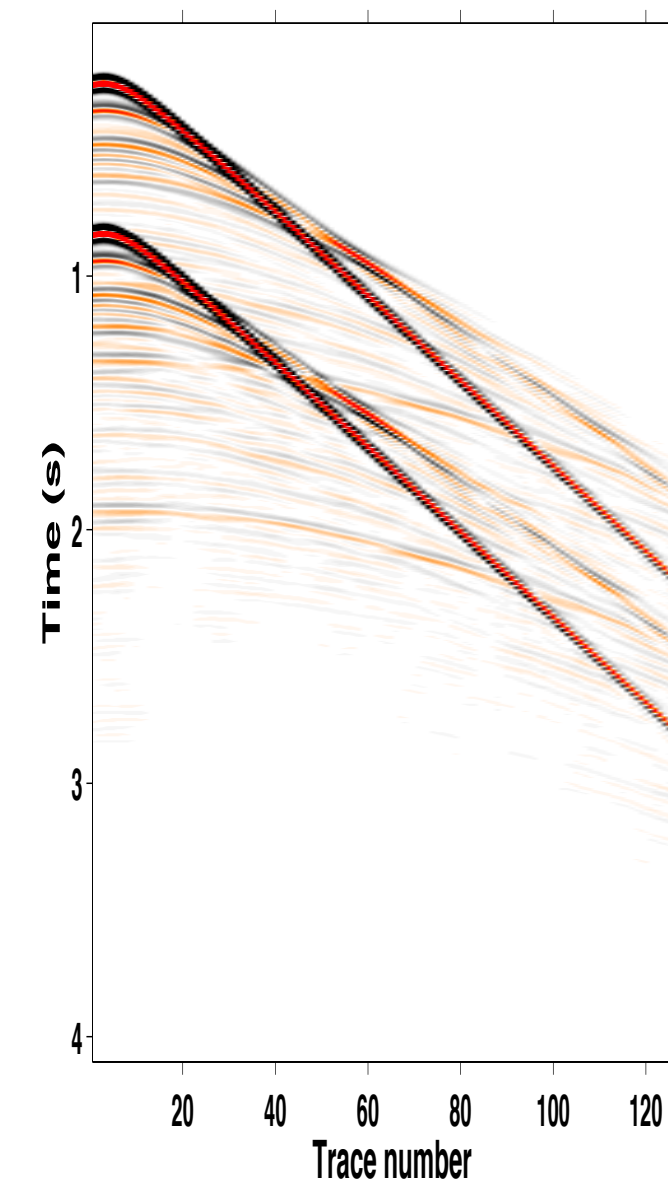
shot 1



shot 2



shot 3



Challenges

Source separation (or *deblending*)

- recover individual datasets

Shot-time randomness

- low

Compressed sensing

Successful sampling & reconstruction scheme

- ▶ exploit *structure* via *sparsifying* transform
 - *fast decay* of “transform domain” coefficients
- ▶ sampling
 - randomly blended data *decreases* sparsity in “transform domain”
- ▶ optimization
 - via *sparsity-promotion*

Matrix completion

Successful reconstruction scheme

- ▶ exploit *structure*
 - *low-rank / fast decay* of singular values
- ▶ sampling
 - randomly blended data *increases* rank in “transform domain”
- ▶ optimization
 - via *rank-minimization (nuclear norm-minimization)*

Low-rank structure

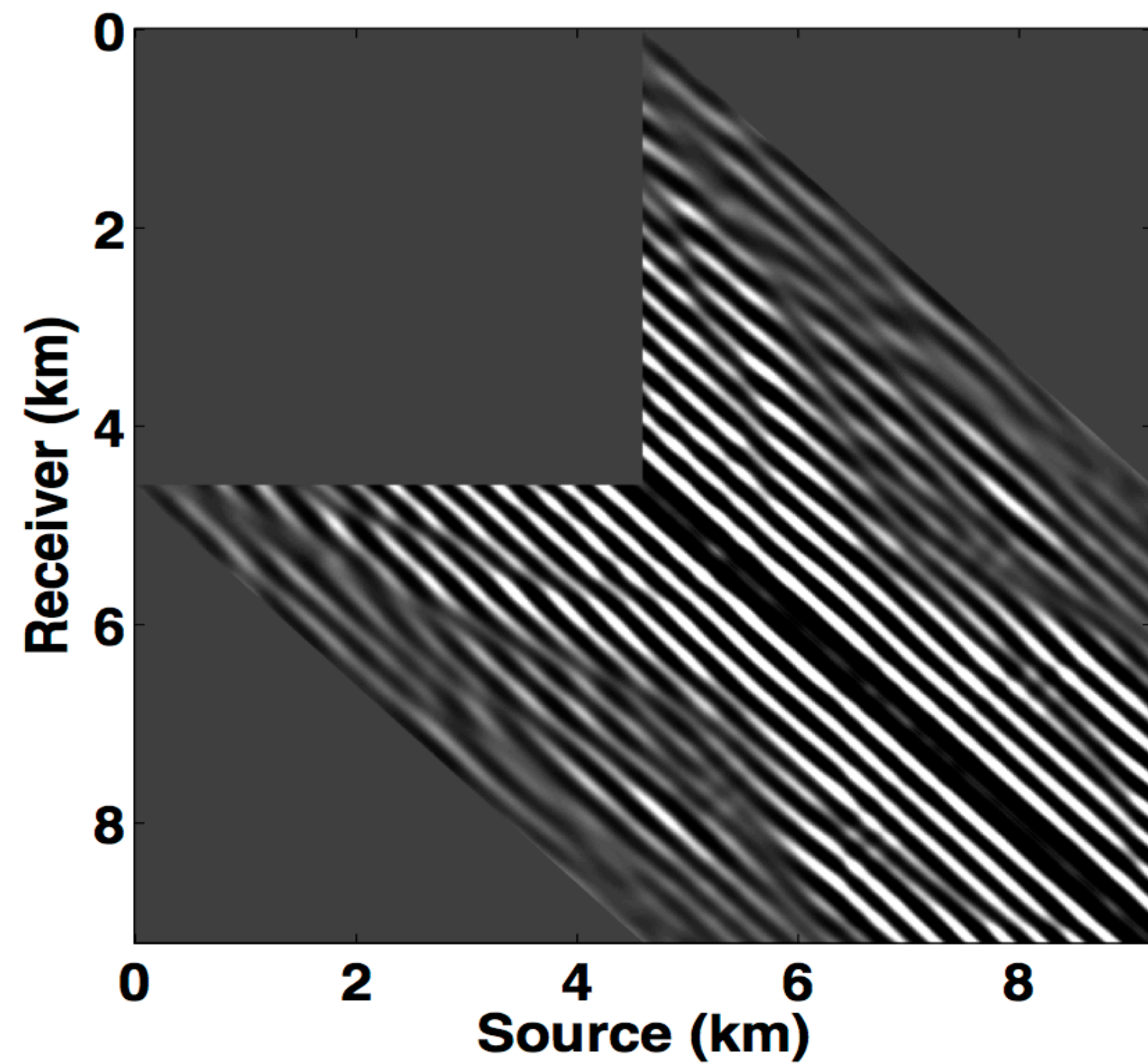
In which domain?

source-receiver or *midpoint-offset*

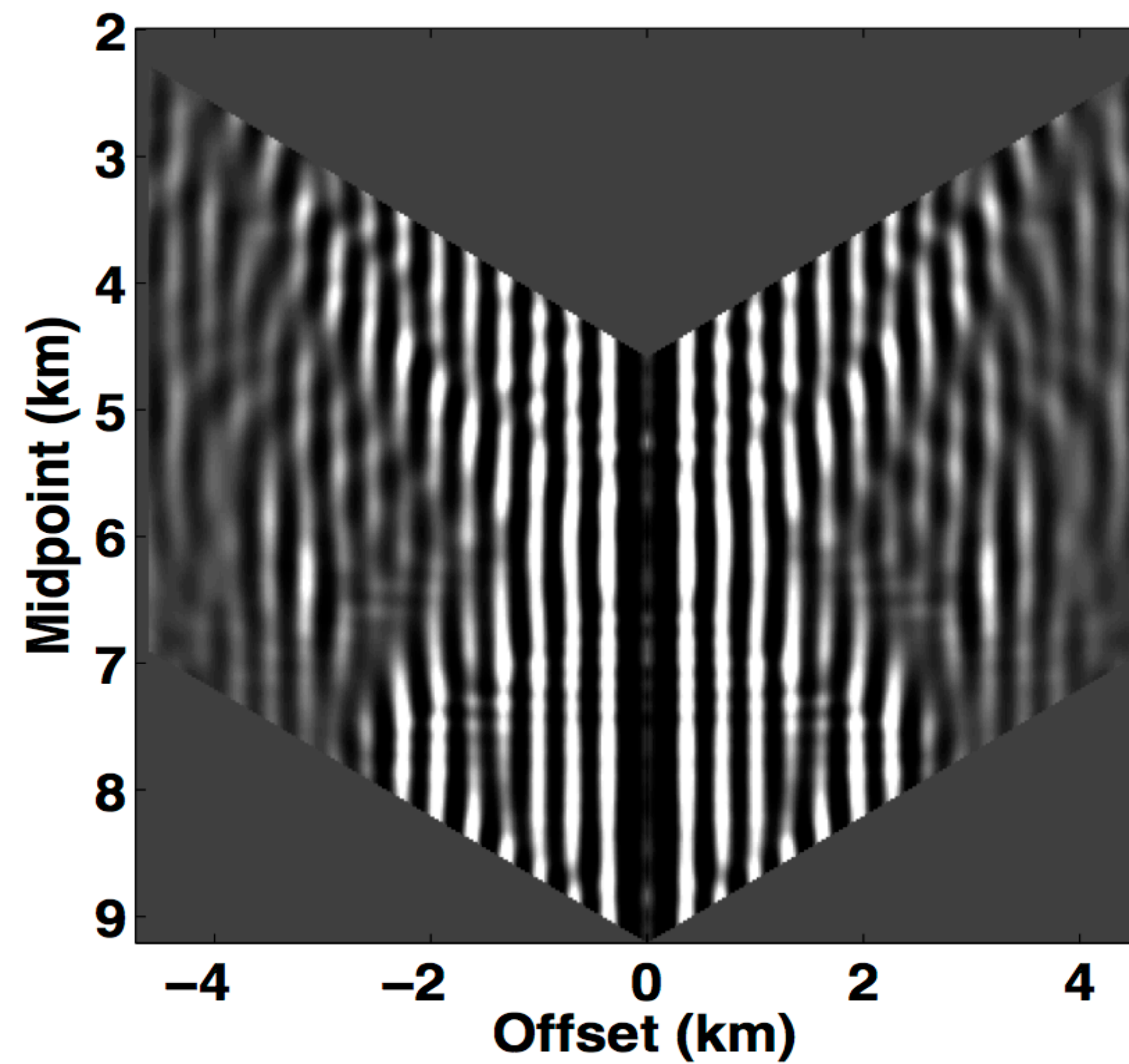
In which domain?

[frequency slice at 5 Hz]

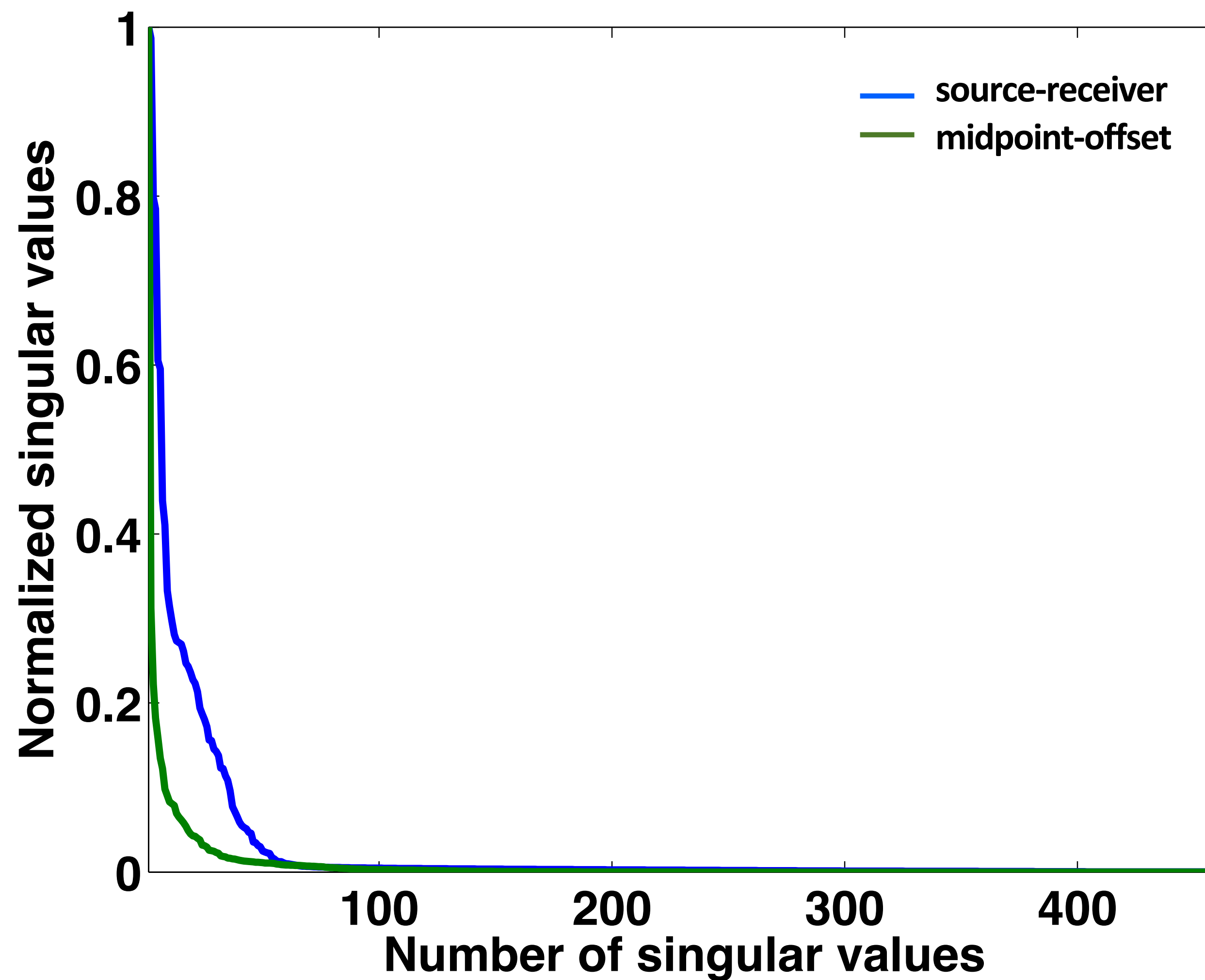
source-receiver domain
(with reciprocity)



midpoint-offset domain
(with reciprocity)



Decay of singular values



**low-rank in
midpoint-offset
domain**

Sampling scheme

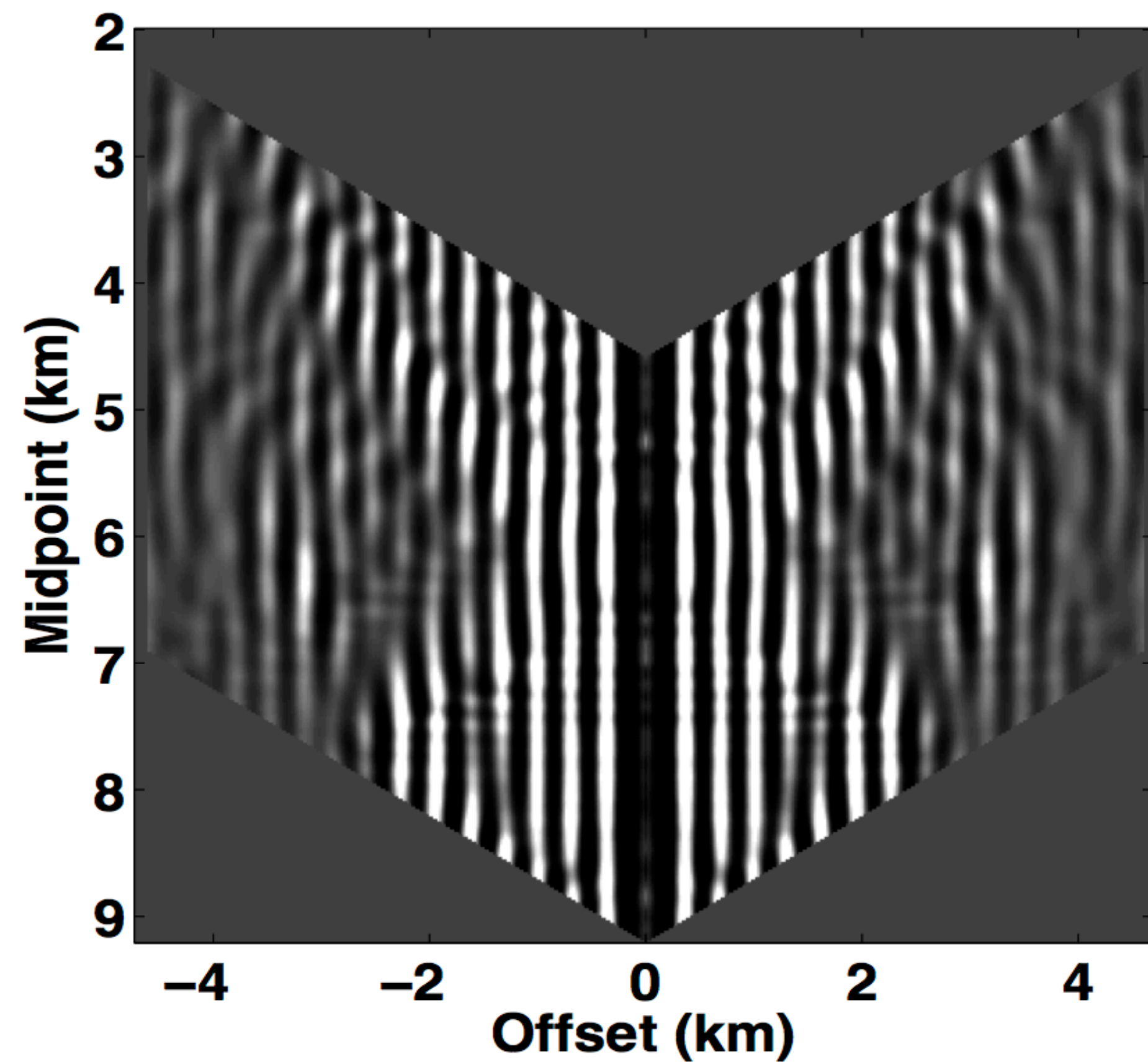
sample to *break* the structure

random time delays break the structure

How to destroy the structure?

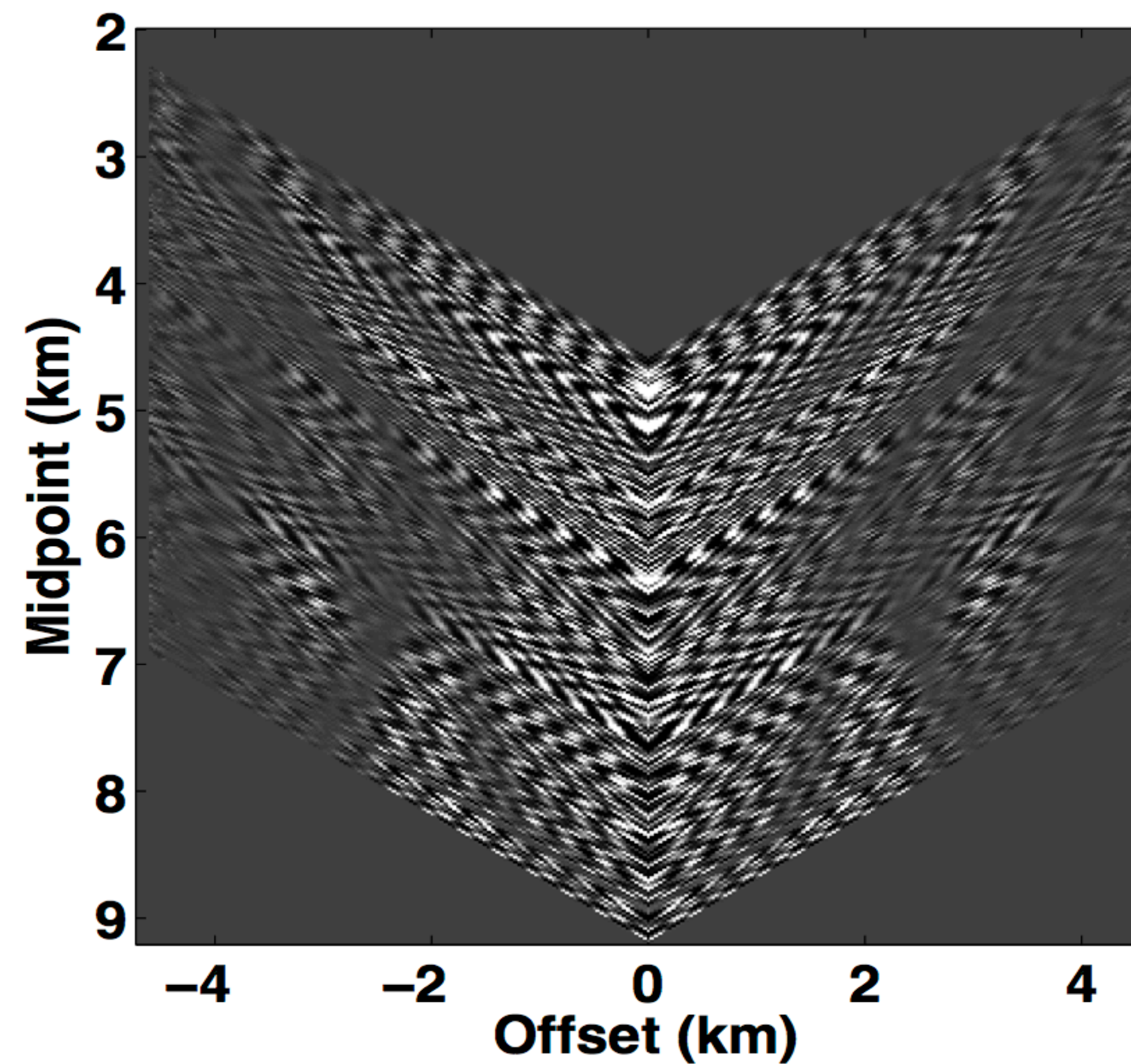
- add random time delays

without delays



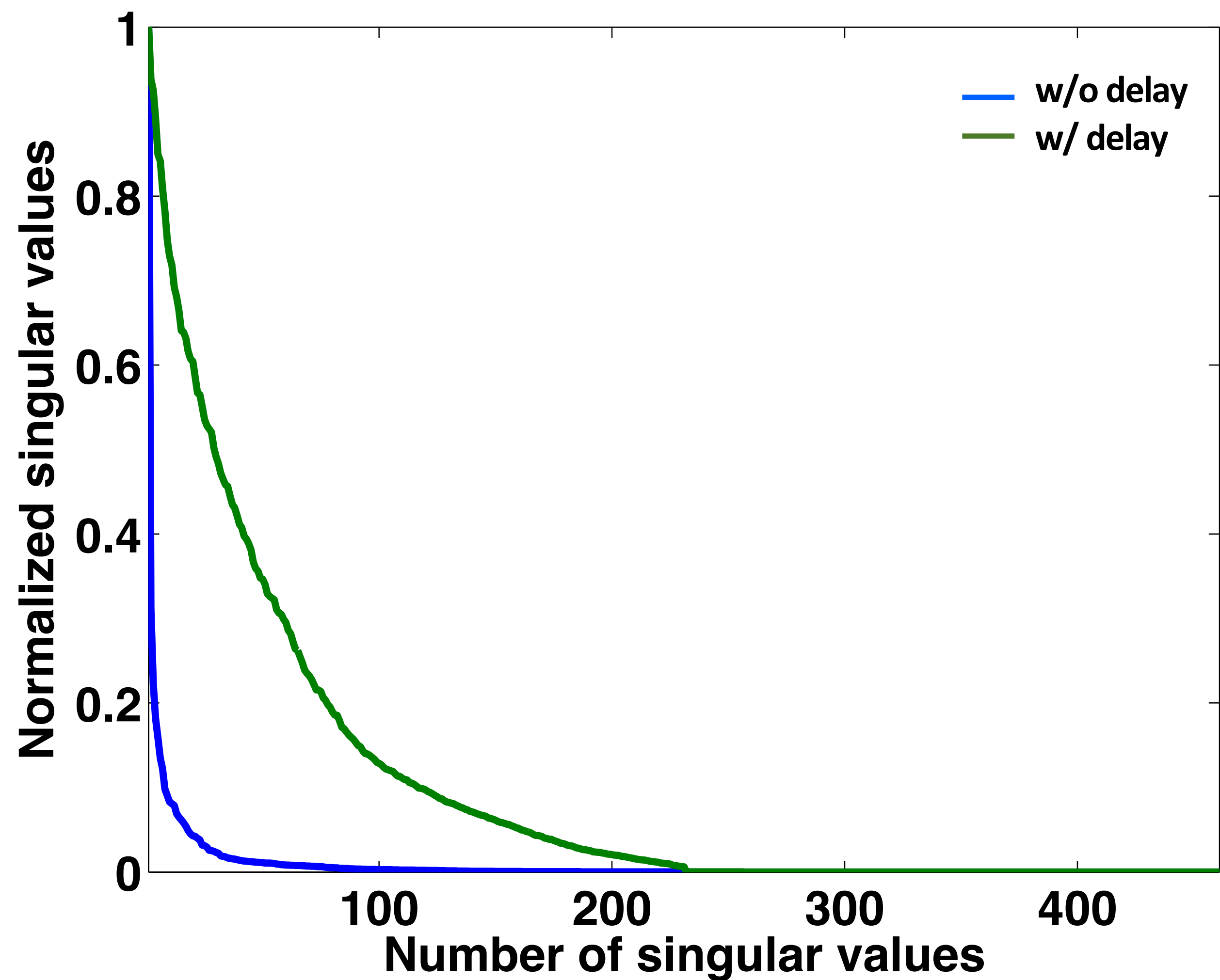
no missing traces!

with random delays (< 1s)



Decay of singular values

[midpoint-offset domain]



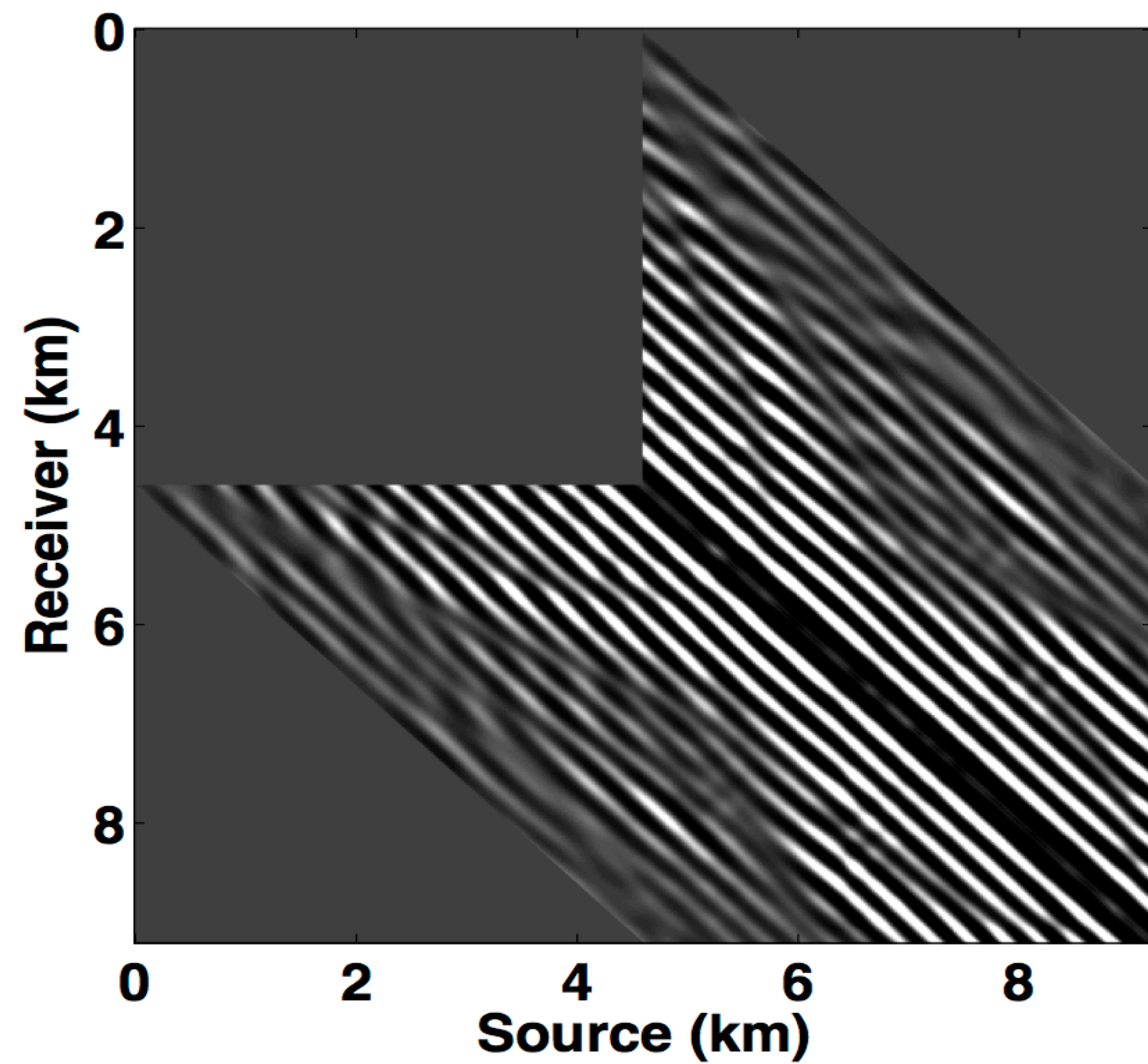
**random time delays
increase the rank**

Do high frequencies have low-rank structure?

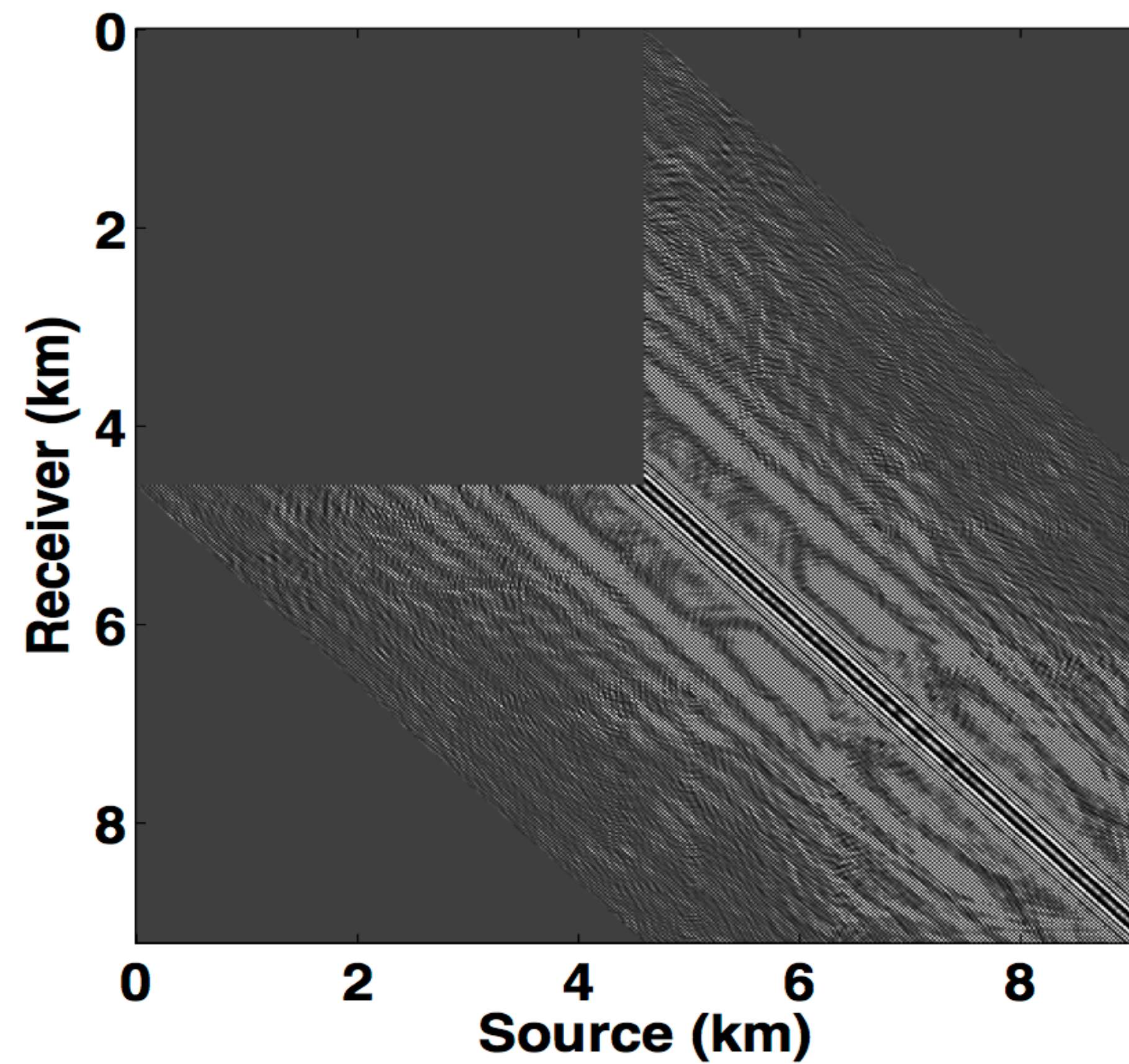
Low vs. high frequency

[source-receiver domain]

low frequency



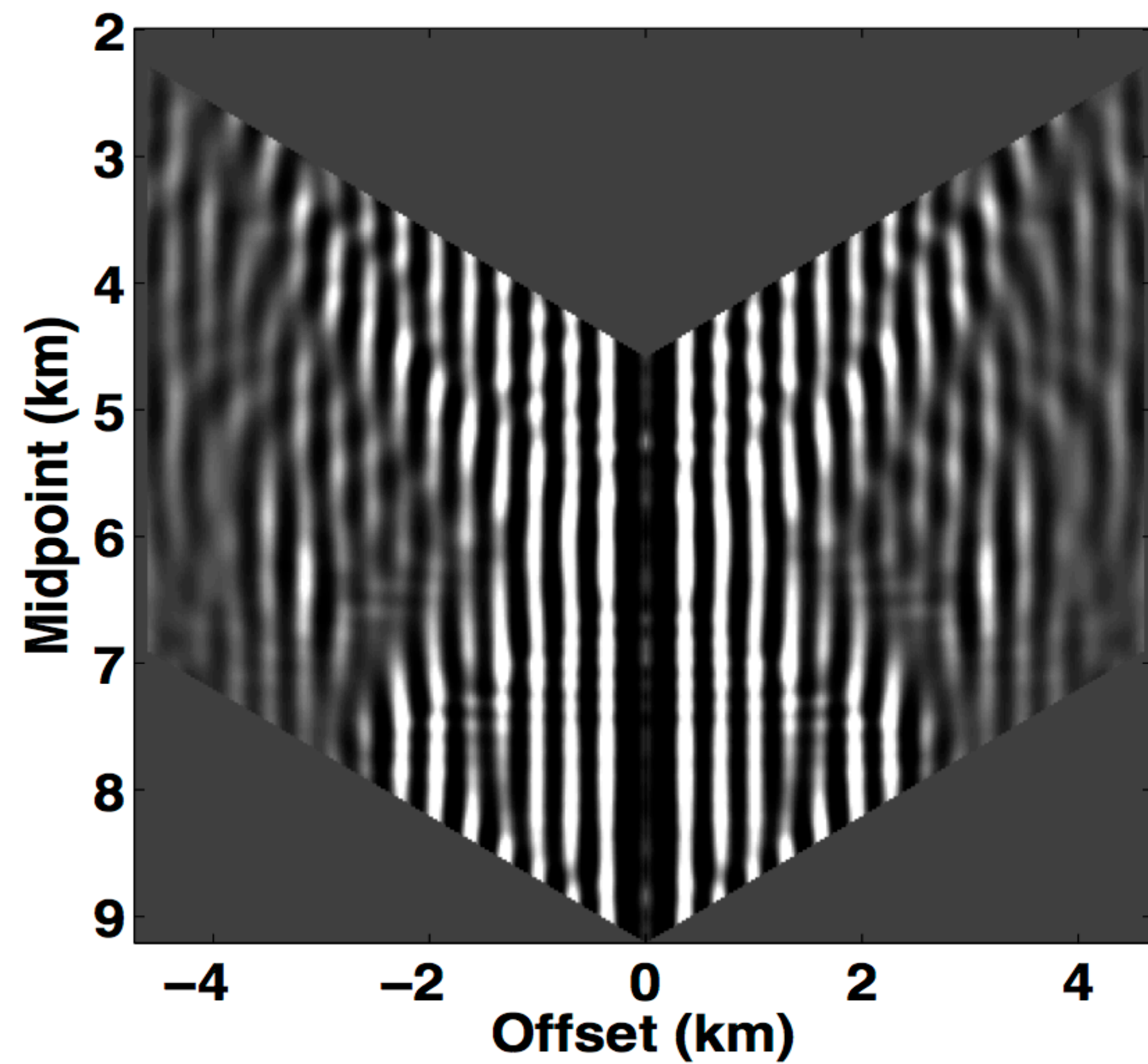
high frequency



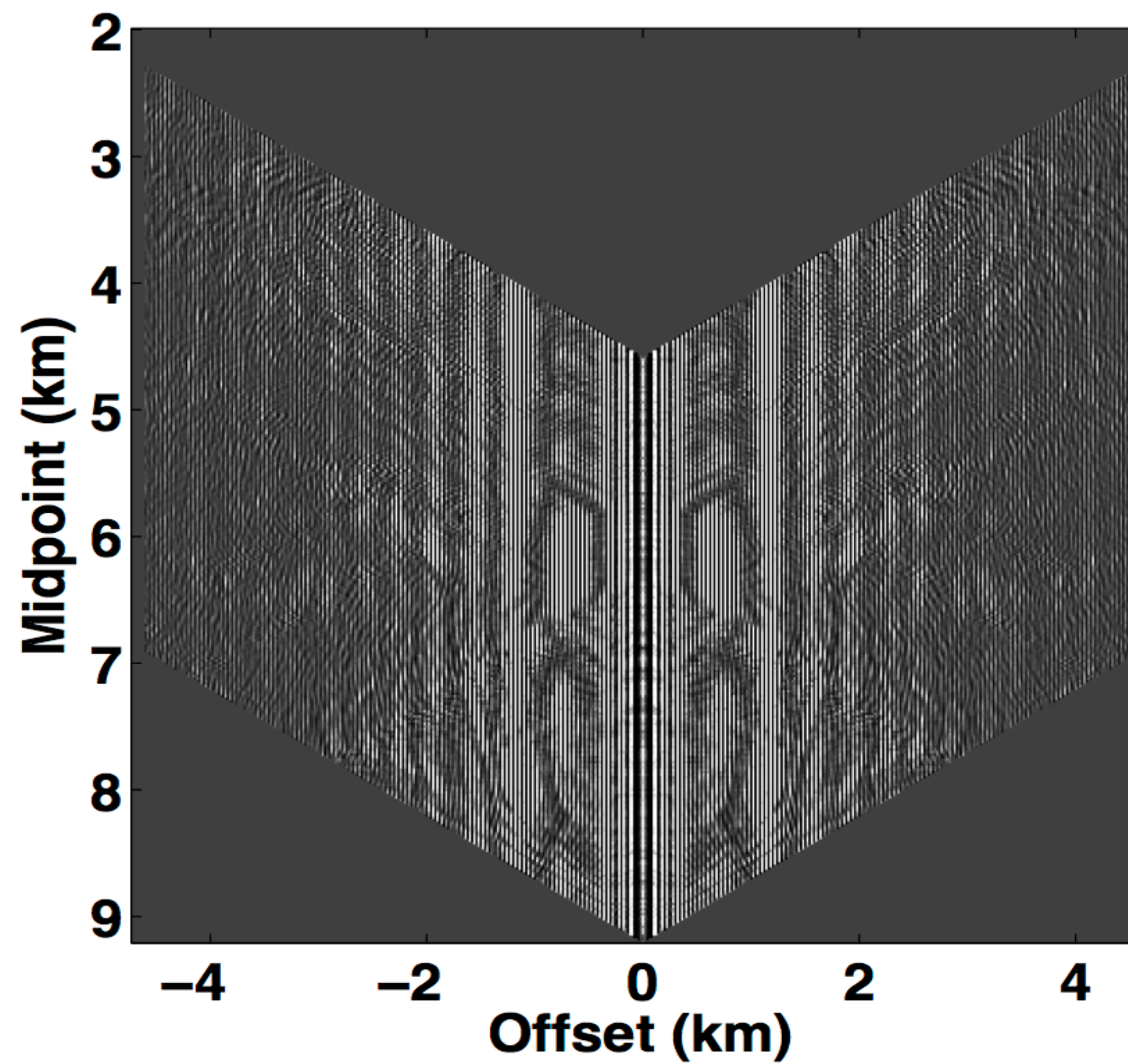
Low vs. high frequency

[midpoint-offset domain]

low frequency

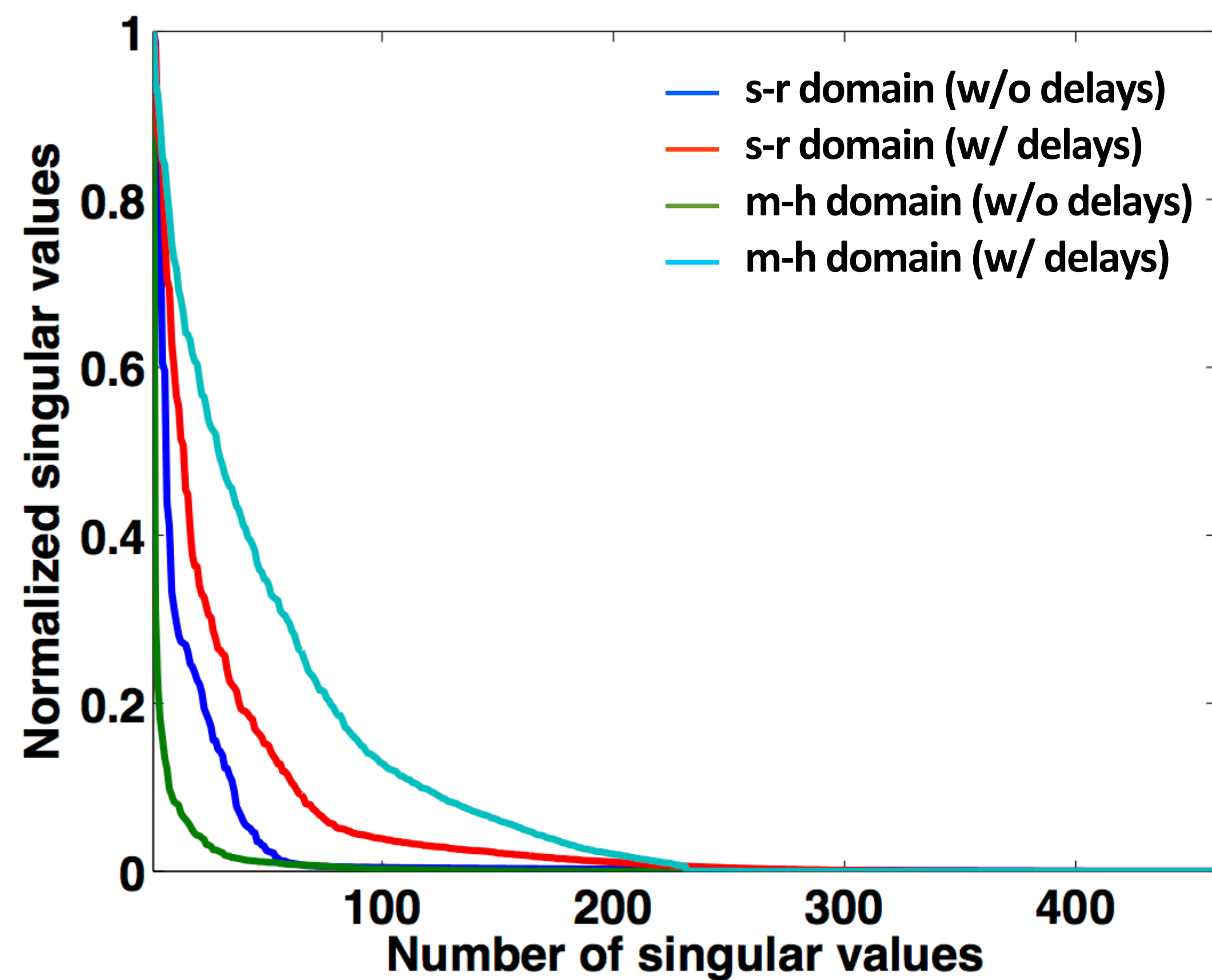


high frequency

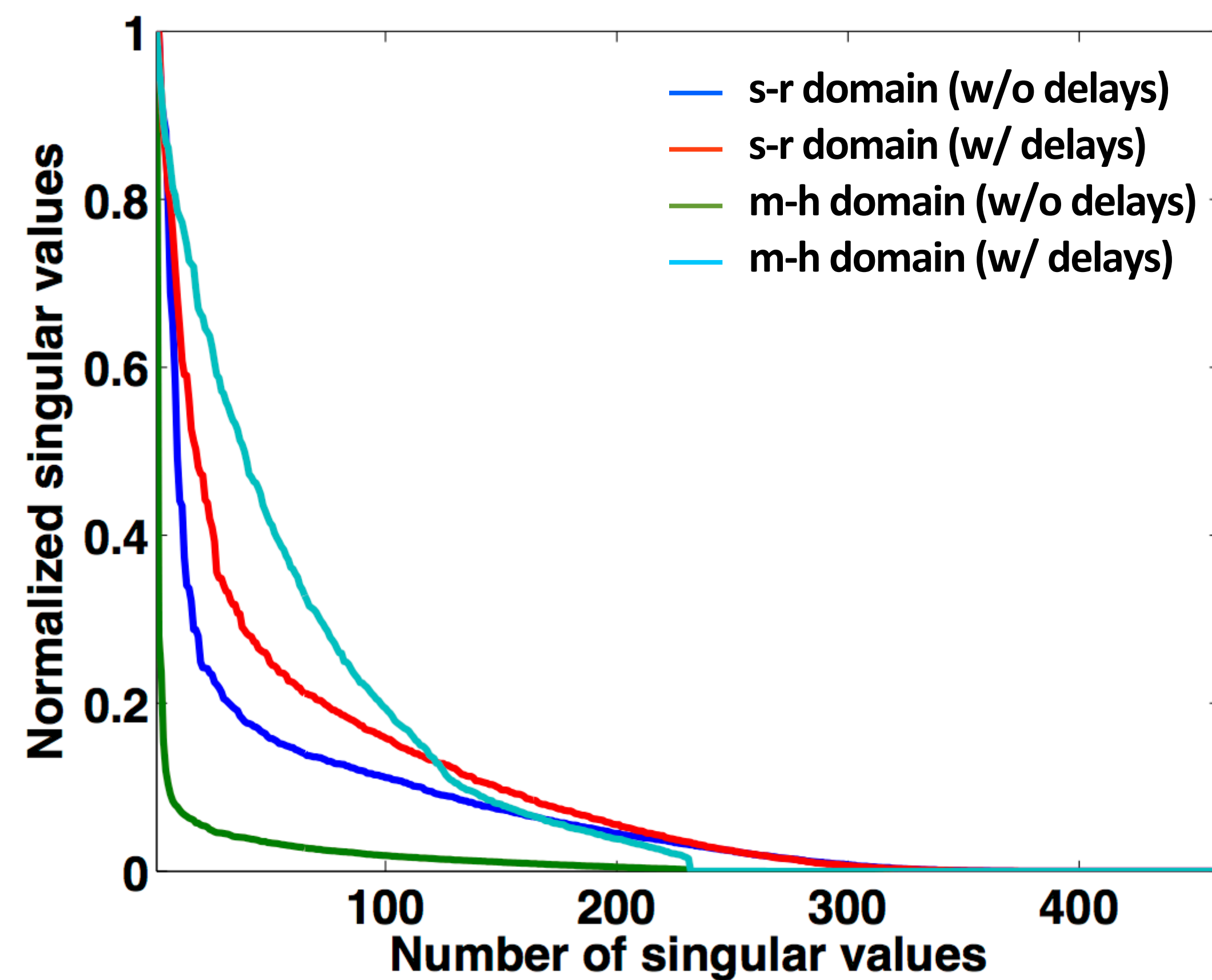


Decay of singular values

low frequency



high frequency

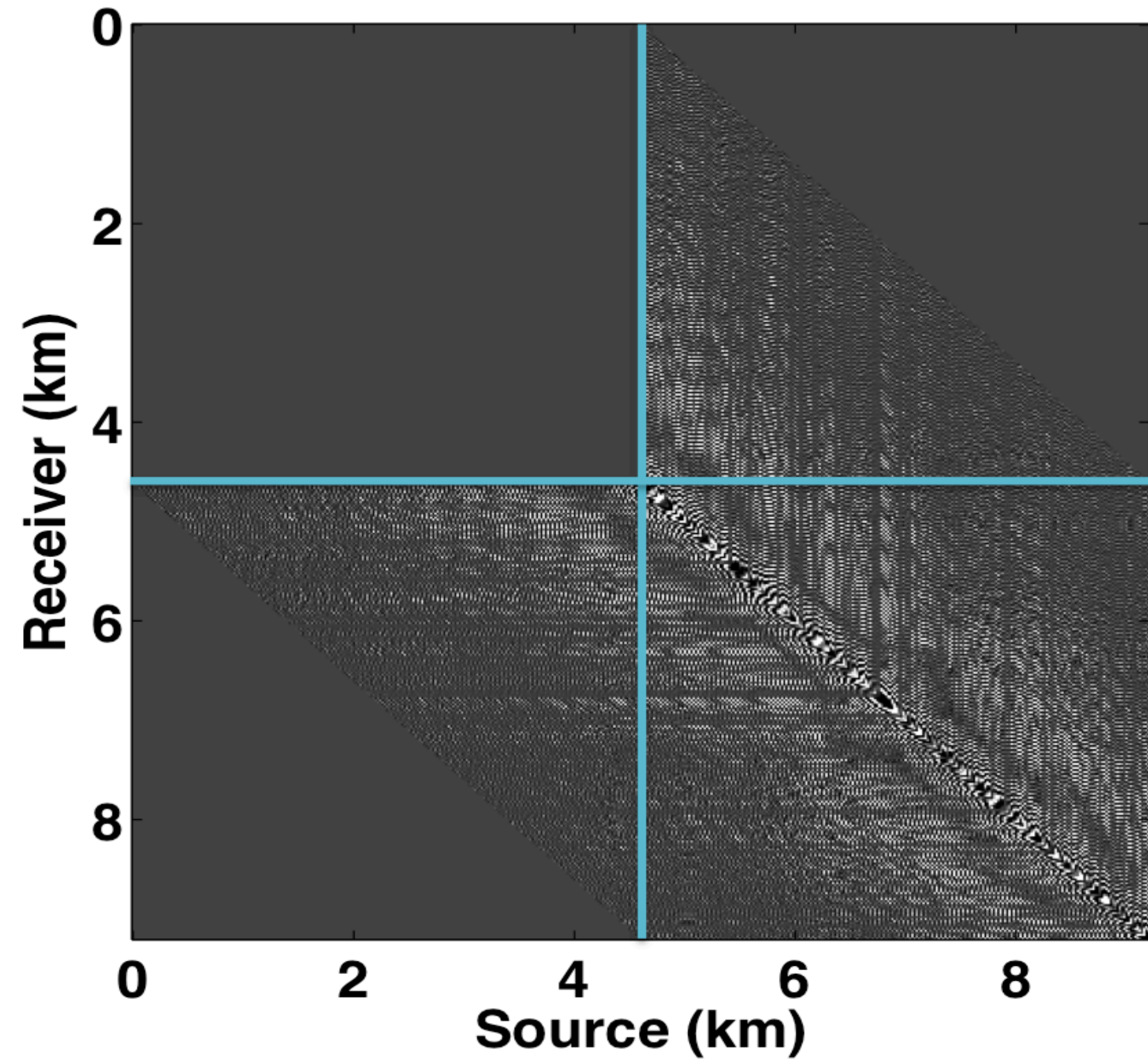


Hierarchical semi-separable (HSS) representation

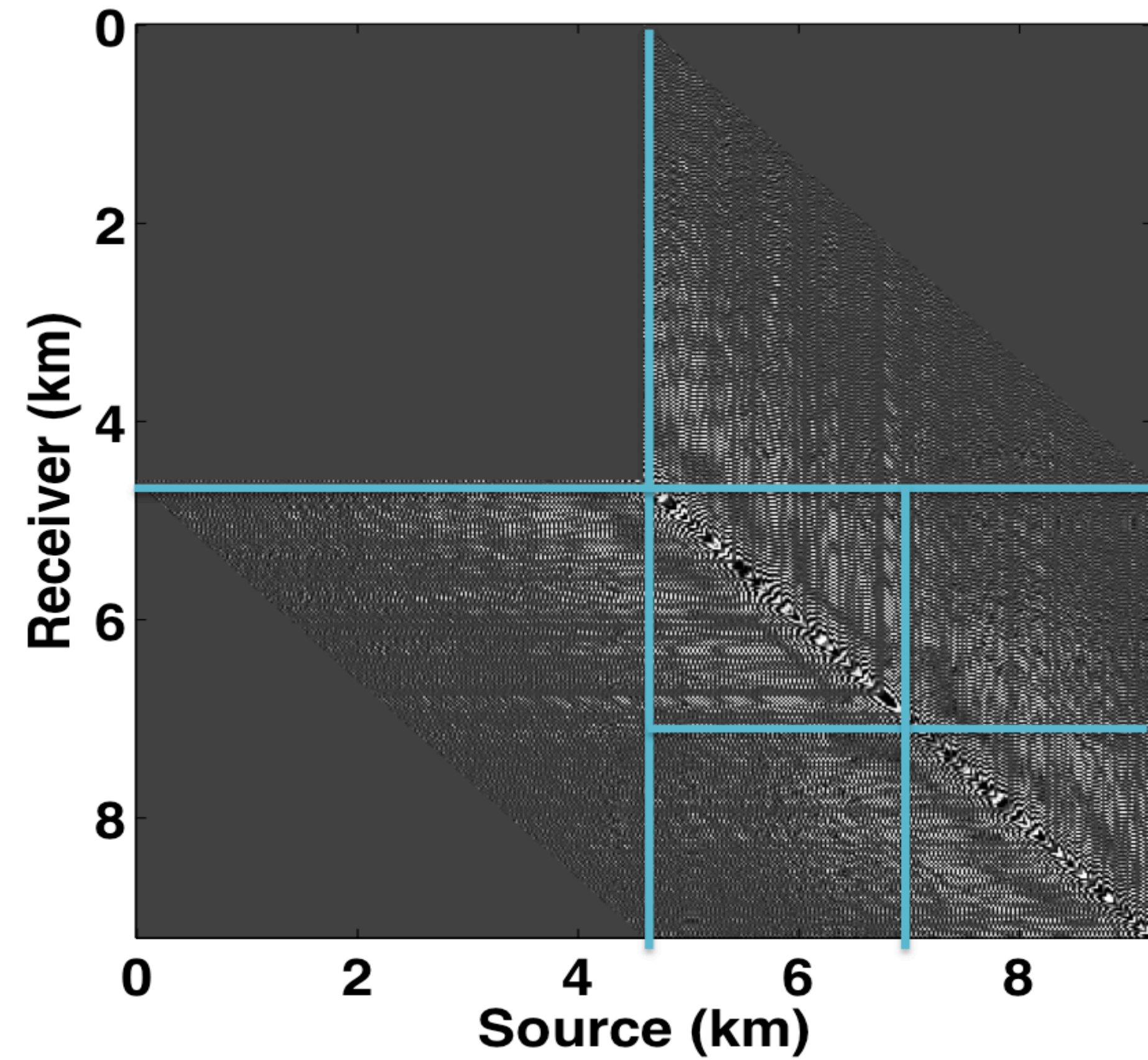
HSS representation

[Chandrasekaran et. al., 2006]

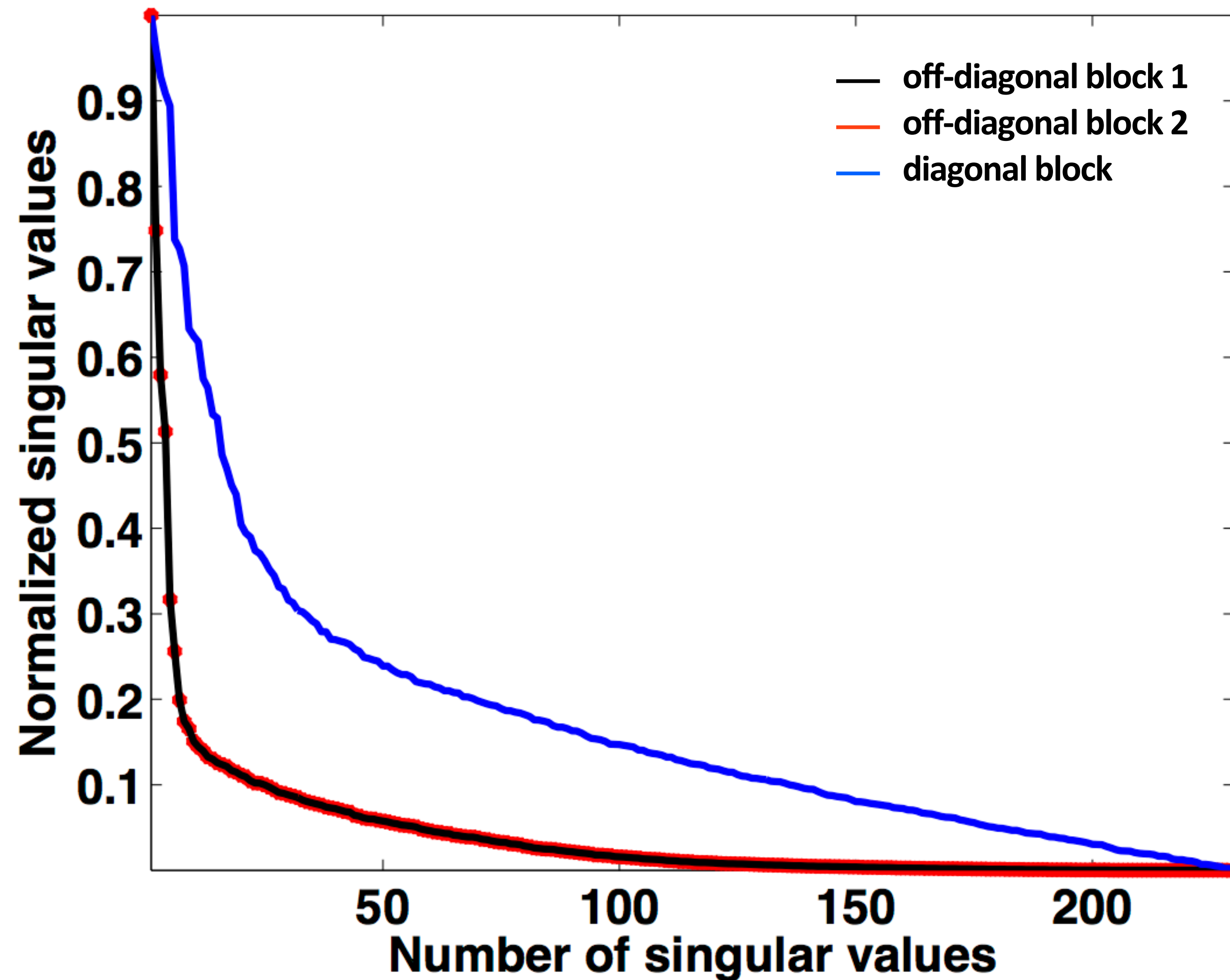
level - 1



level - 2



Decay of singular values of HSS sub-blocks



**off-diagonal blocks
have low-rank structure**

Rank minimization

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

for blended acquisition:

\mathbf{b} : blended data

unblended data matrix

$$\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} \begin{array}{l} \leftarrow \text{source 1} \\ \leftarrow \text{source 2} \end{array}$$

$$\mathcal{A} := \begin{bmatrix} \mathbf{M}\mathbf{T}_1\mathbf{S}^H & \mathbf{M}\mathbf{T}_2\mathbf{S}^H \end{bmatrix}$$

\uparrow \uparrow
time delay matrices

Rank minimization

expensive
(search over all possible values of rank)

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

Rank minimization

expensive
(search over all possible values of rank)

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

Nuclear-norm minimization

convex relaxation of rank-minimization

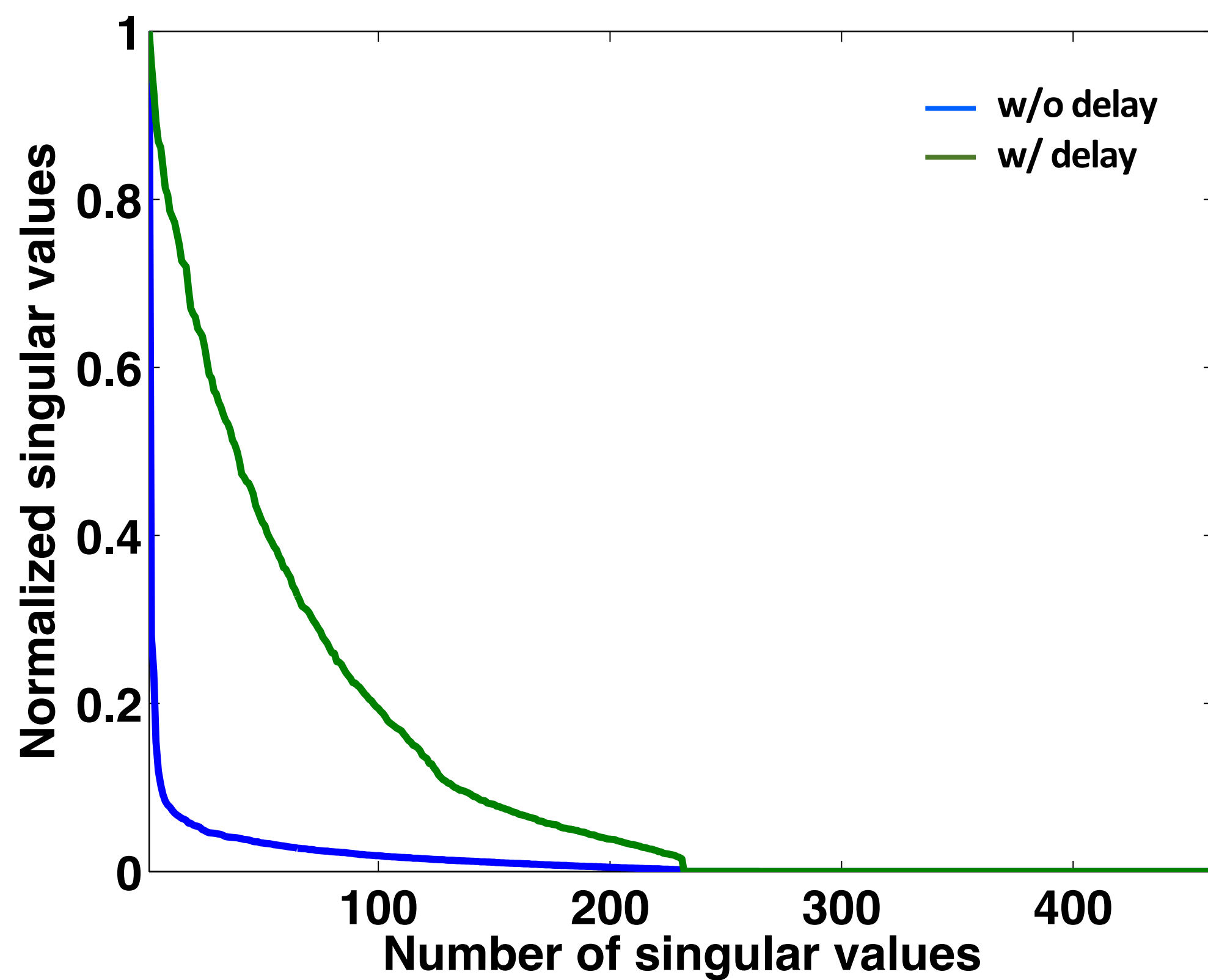
[Recht et. al., 2010]

$$\min_{\mathbf{X}} \underbrace{\|\mathbf{X}\|_*}_{\text{sum of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

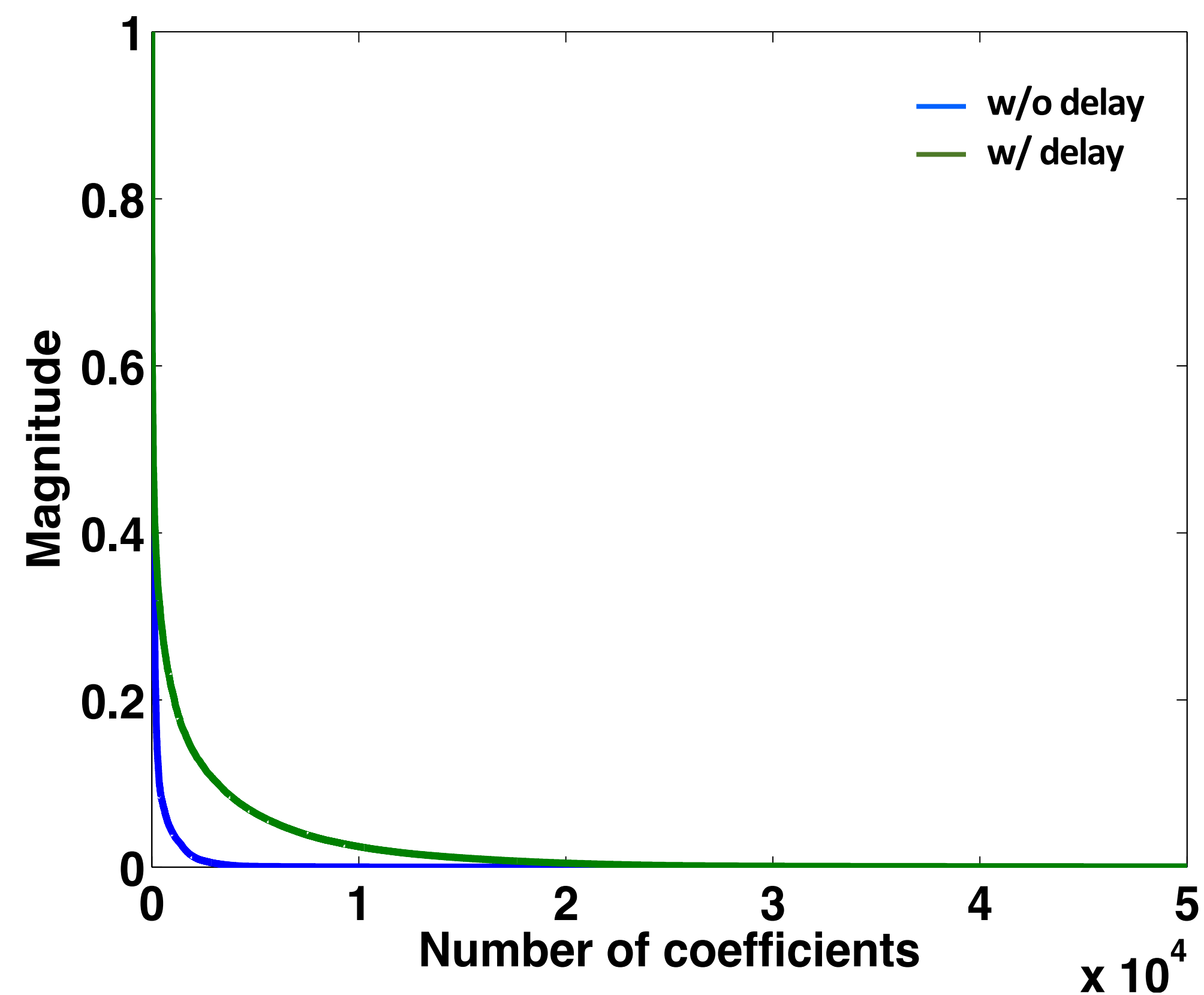
sum of singular values of \mathbf{X}

Rank vs. Sparsity

rank-minimization
(midpoint-offset domain)



sparsity-promotion
(source-receiver domain)



Source separation results

Rank minimization vs. sparsity promotion

Blended data (w/ delay)

- random time delays (< 1 sec) applied to both sources

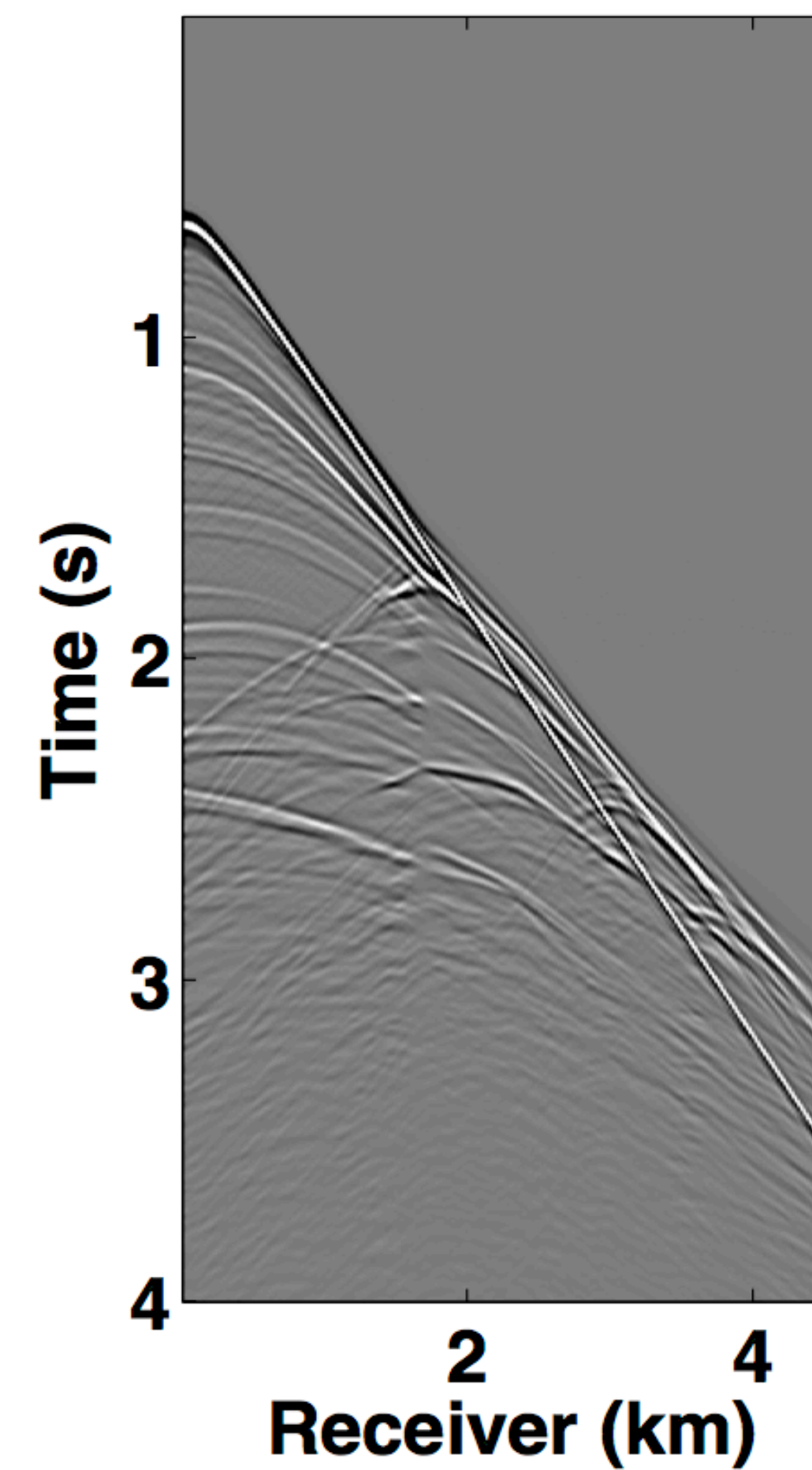
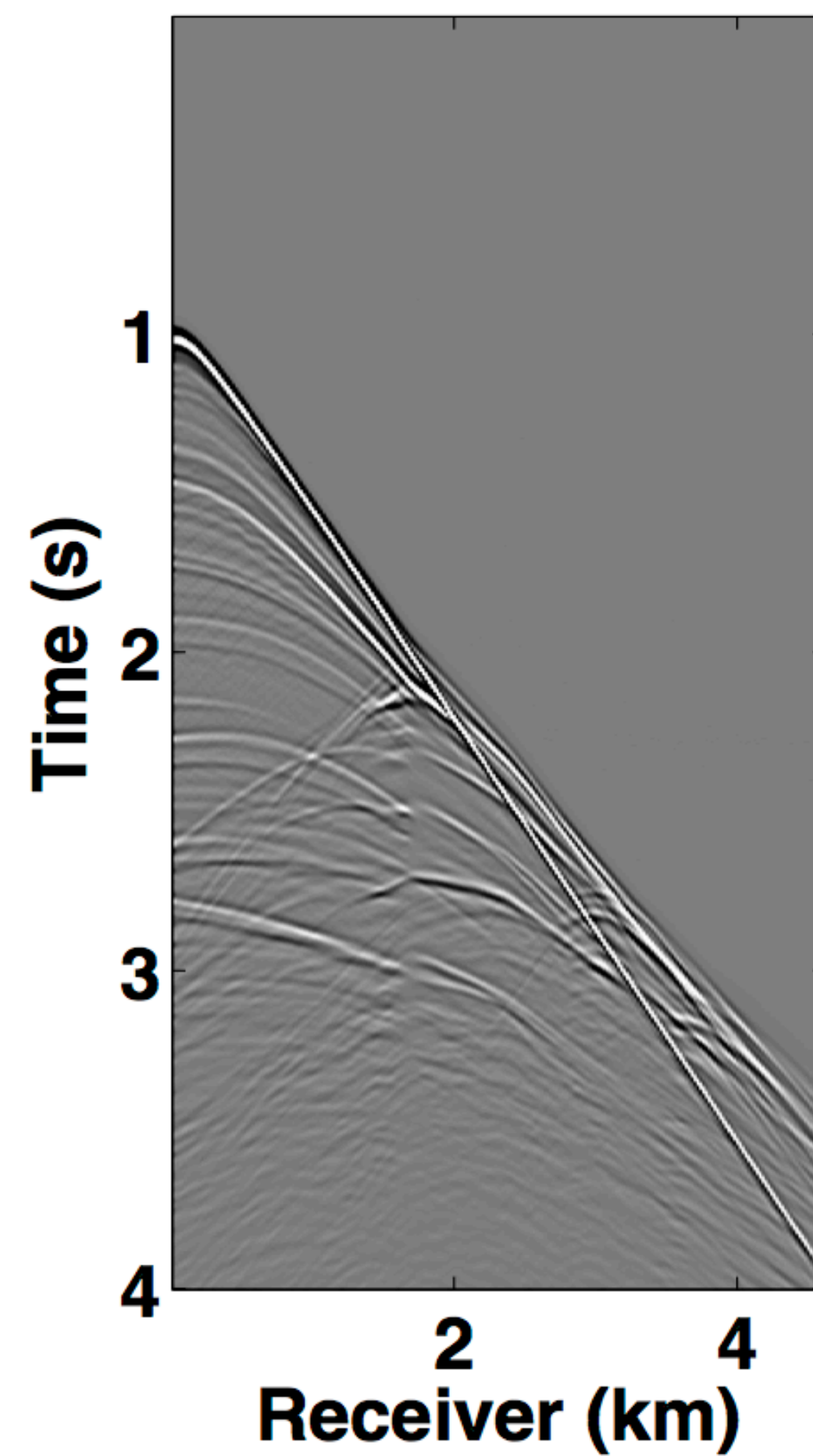
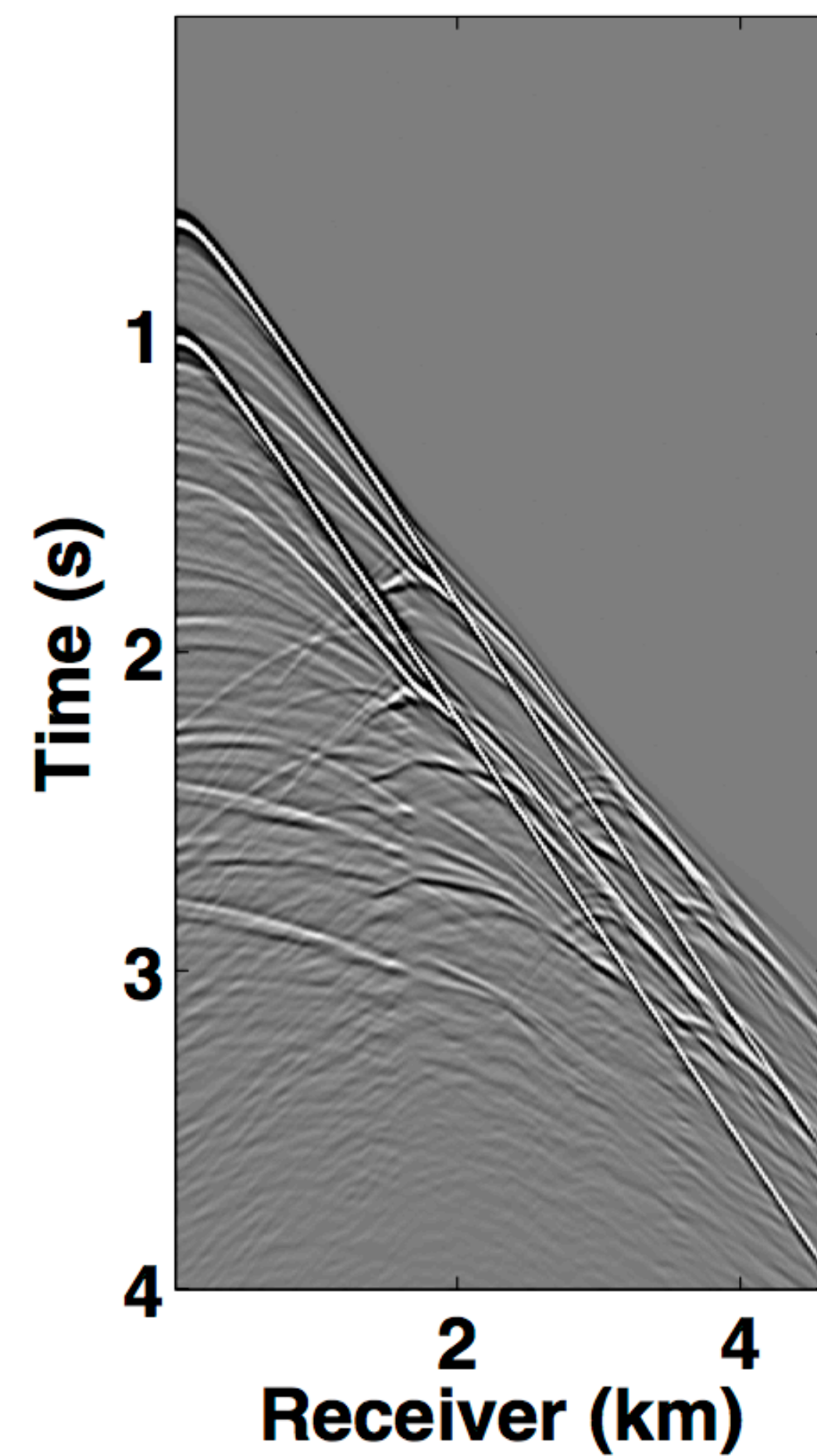
blended shot

=

source 1

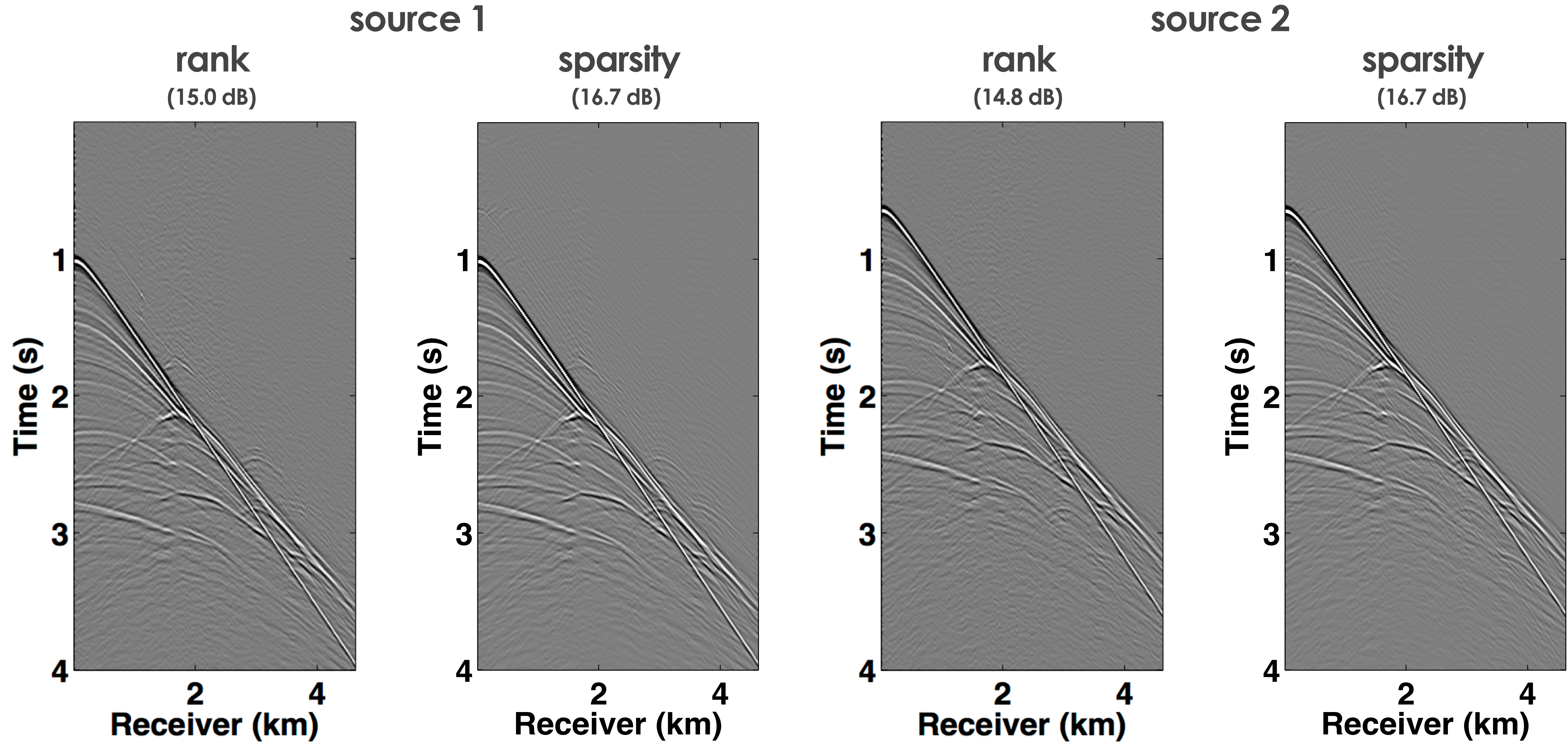
+

source 2



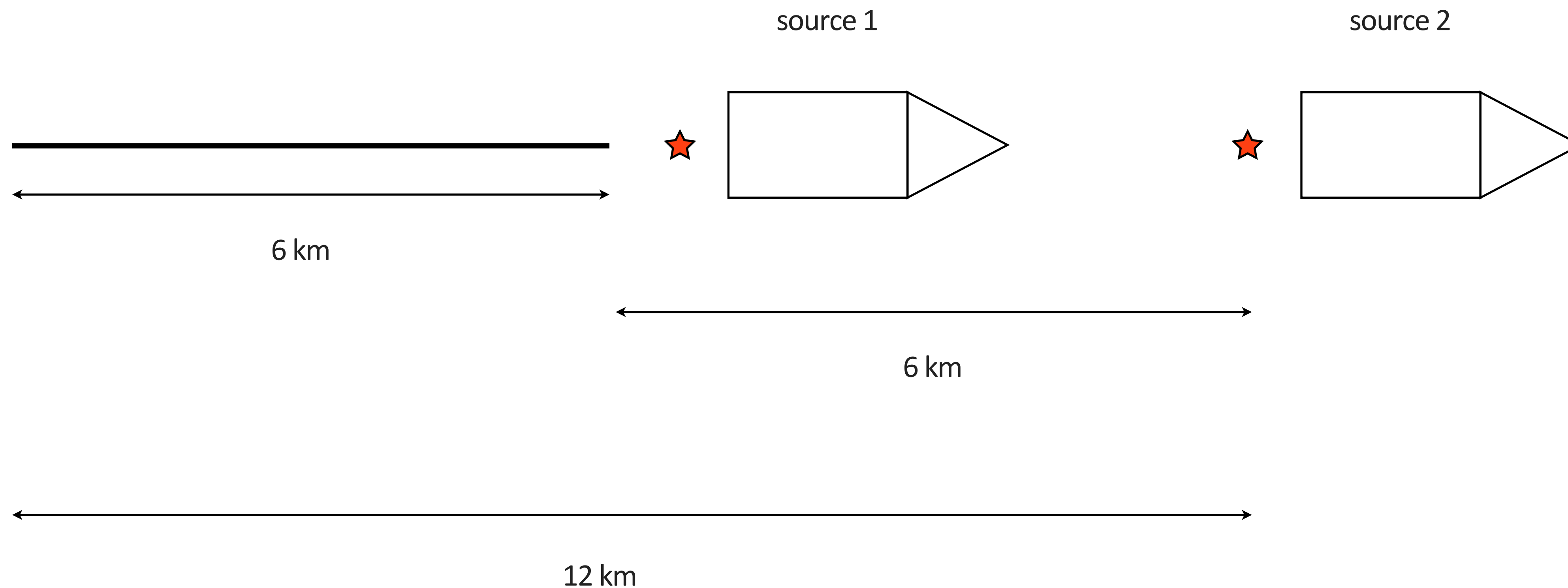
Source separation - rank vs. sparsity

computation time (all data) = 5 vs. 62 hours; memory usage = 2.8 vs. 7.0 GB



Simultaneous long offset acquisition

[adapted from Long et. al., 2013]



A. S. Long et. al., "[Simultaneous long offset \(SLO\) towed streamer seismic acquisition](#)", presented at the *75th EAGE Conference and Exhibition*, June 2013.

Blended data (w/ delay)

- random time delays (< 1 sec) applied to both sources

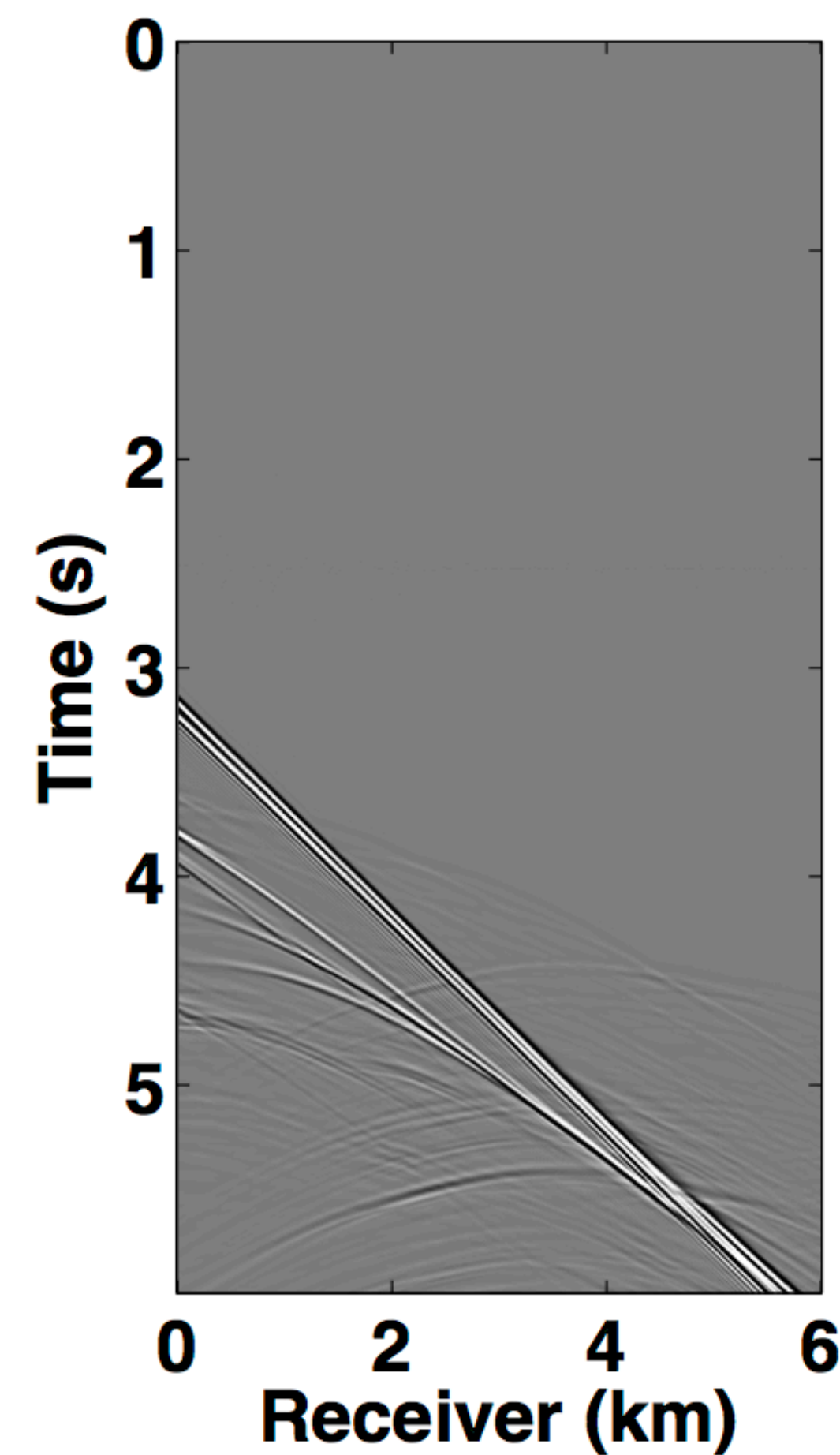
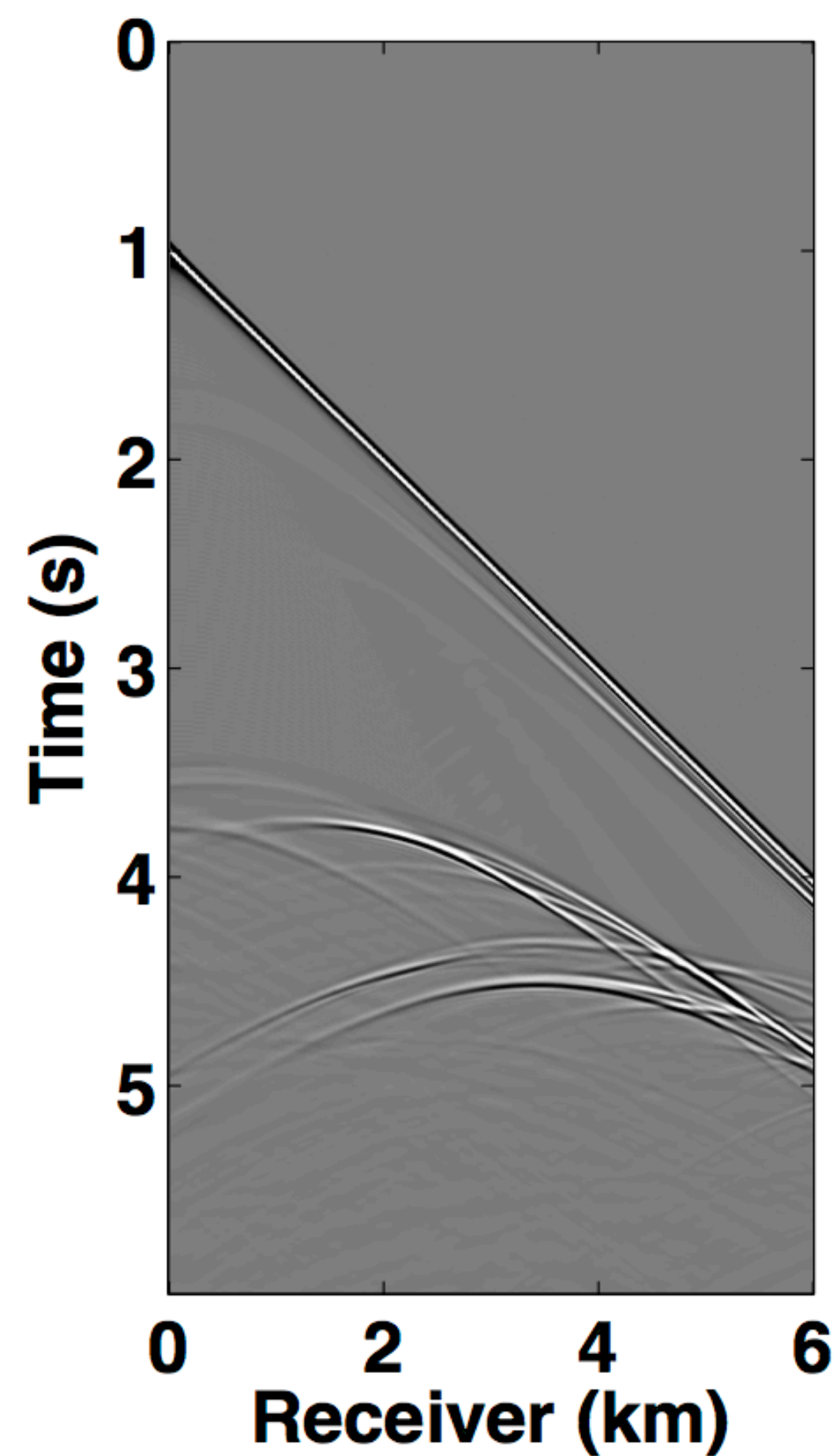
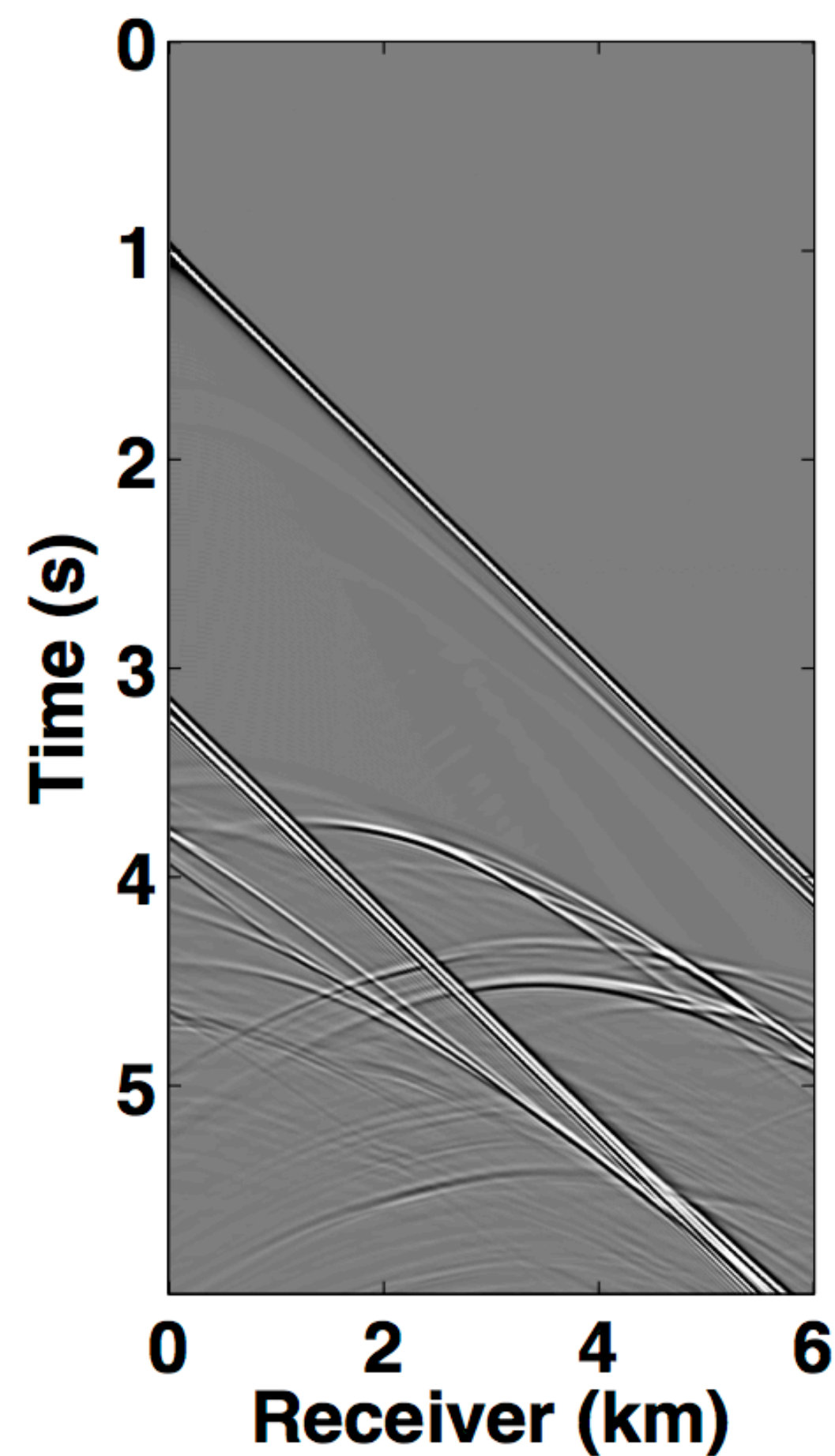
blended shot

=

source 1

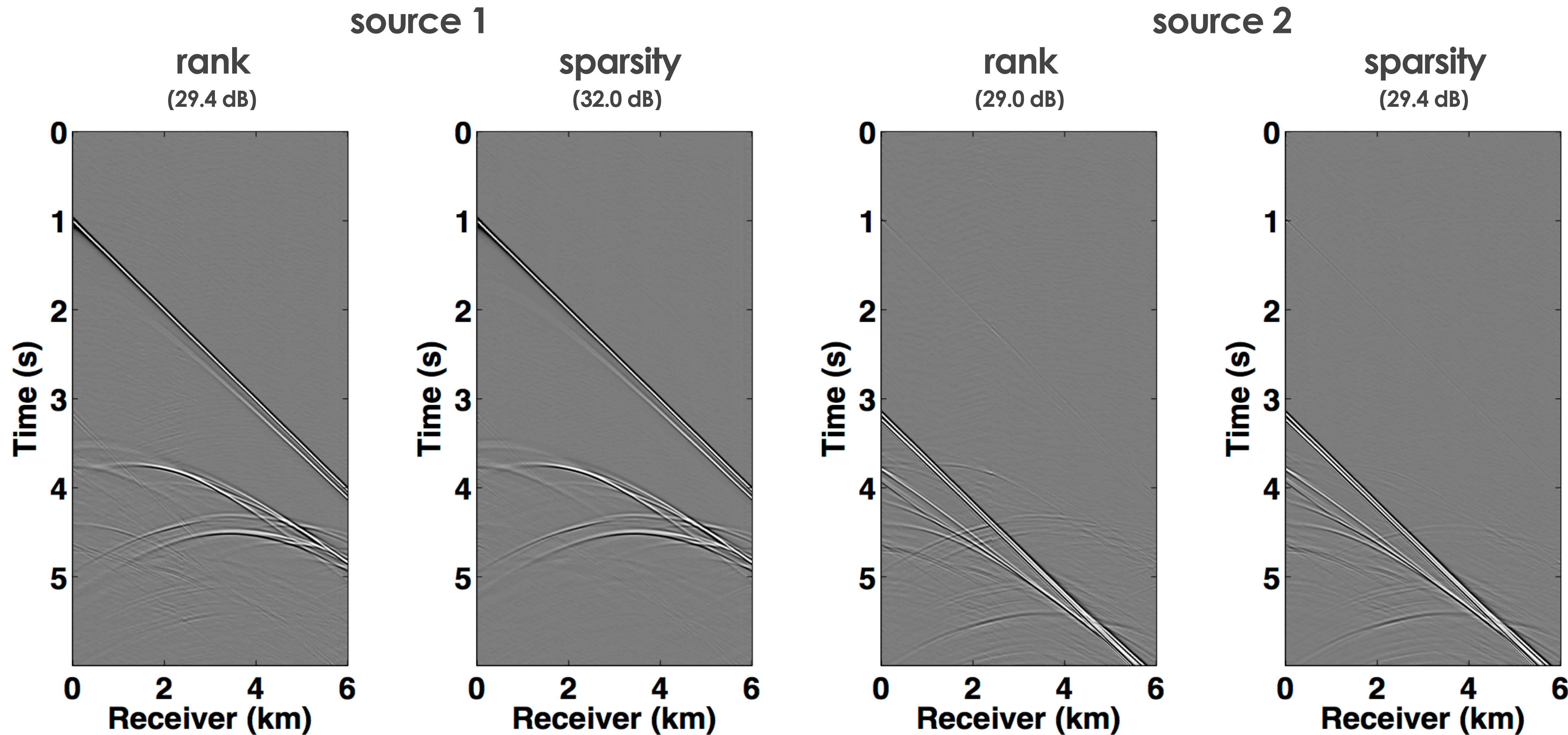
+

source 2



Source separation - rank vs. sparsity

computation time (all data) = 19 vs. 183 hours; memory usage = 6 vs. 12 GB



Experiment summary

– time (in hours), memory (in GB), average SNR (in dB)

	Over/under acquisition			Simultaneous long offset acquisition		
	time	memory	SNR*	time	memory	SNR*
sparsity	62	7.0	16.7	183	12.0	32.0, 29.4
rank	5	2.8	15.0, 14.8	19	6.0	29.4, 29.0

* average SNR for source 1, source 2

Summary

Source separation for low variability acquisition scenarios can be treated both as a sparsity-promoting & rank-minimization problem

Get comparable results for both separation techniques, however, the rank-minimization technique is computationally faster

Future work

Spectral gap analysis

- data with time delays
- data with time delays + missing traces

Source separation + trace interpolation for 3D seismic data

References

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