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SVD-free matrix completion for seismic data reconstruction

Rajiv Kumar, Oscar Lopez, Ernie Esser and Felix J. Herrmann





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Outline

interpolation

 regularization - is binning the right approach?

- comparison with curvelet-based reconstruction methods



Motivation

- acquisition challenges
 - missing data
 - irregular acquisition grid
- fully sampled data
 - simultaneous shot based FWI & migration
 - estimation of primaries by sparse inversion & SRME
- regularization
 - imaging and inversion algorithm require equi-spaced grid
- exploit low-rank structure of seismic data - SVD-free matrix factorization



Outline

interpolation - comparison with curvelet-based reconstruction methods

regularization - is binning the right approach?



[Candes and Plan 2010, Oropeza and Sacchi 2011]

Matrix completion

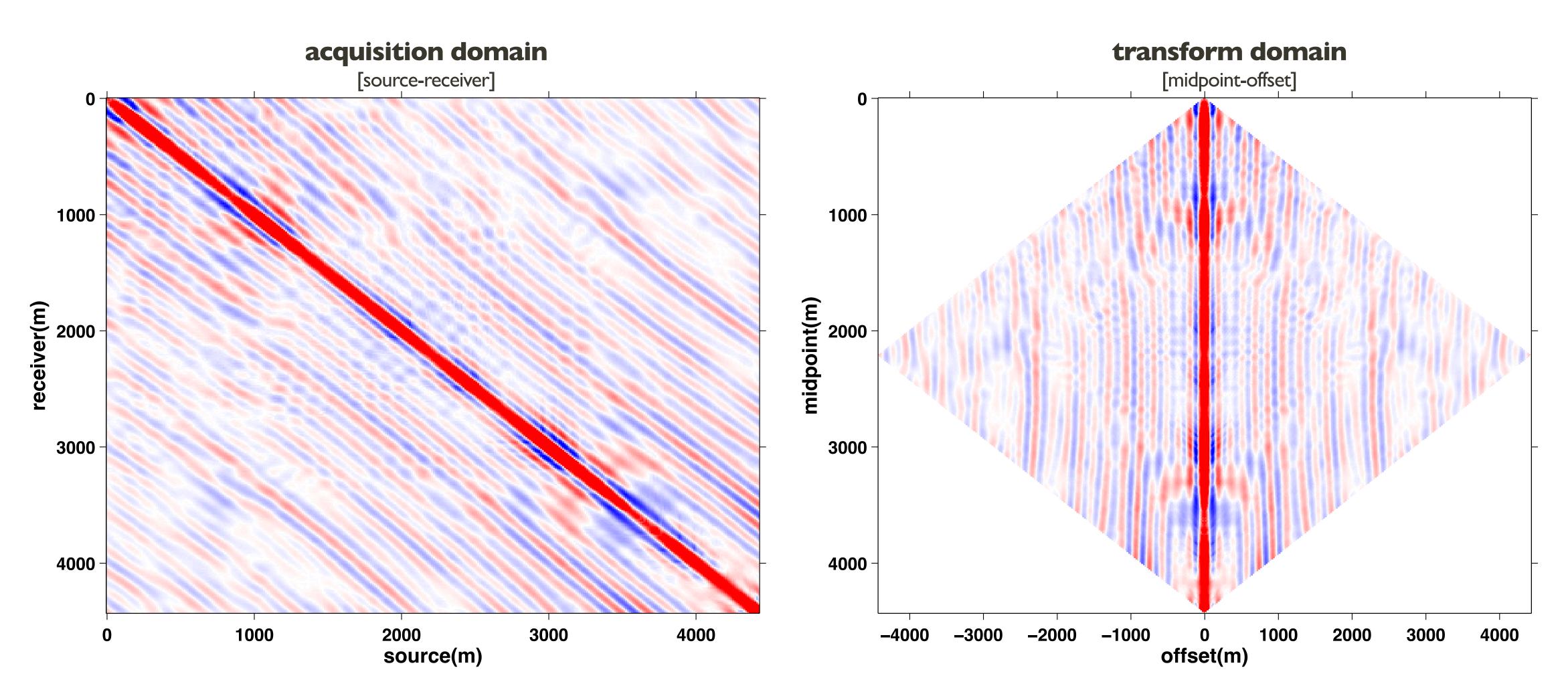
signal structure

- low rank/fast decay of singular values
- sampling scheme
 - missing data increase rank in "transform domain"
- recovery using rank penalization scheme



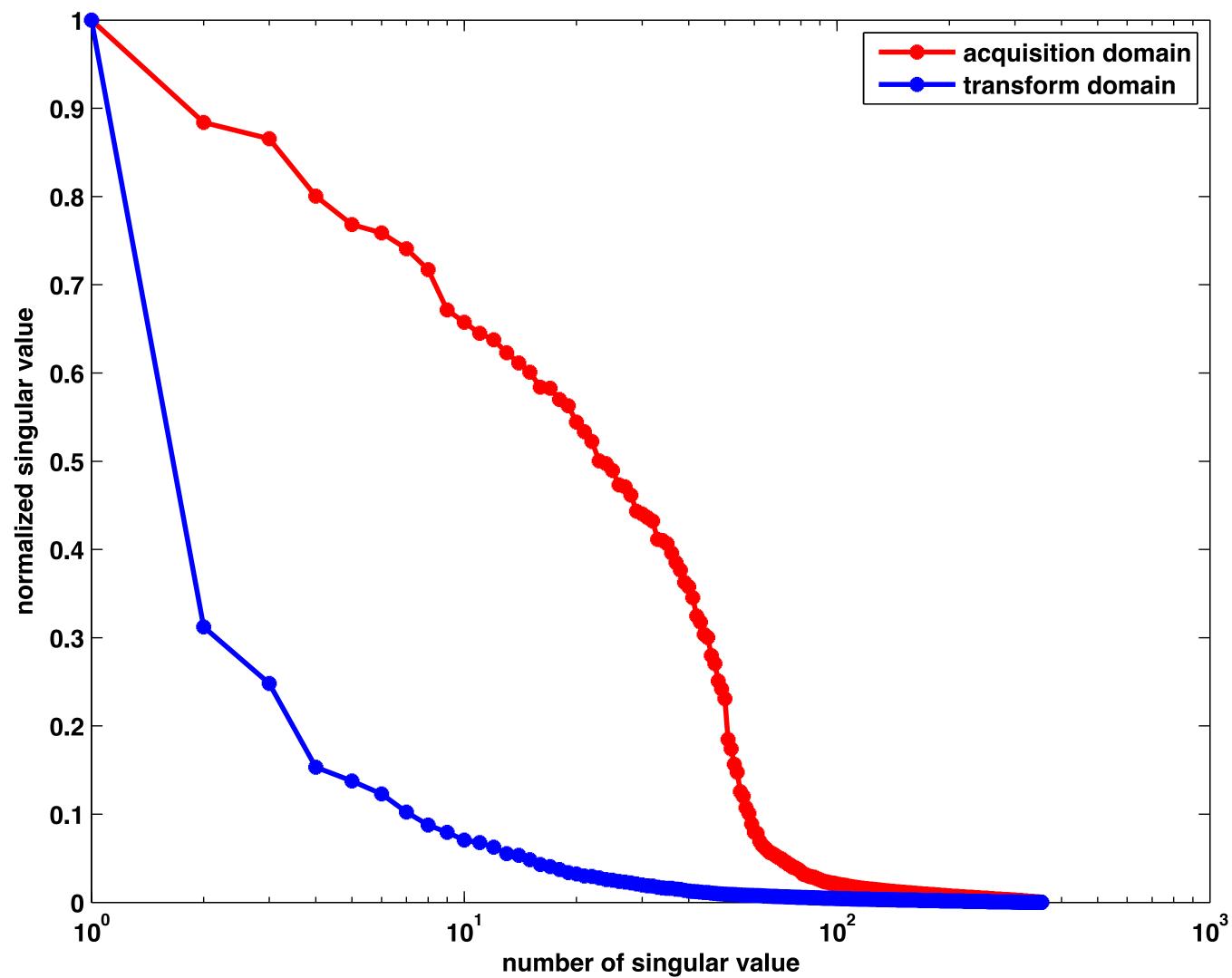


Low-rank structure **2-D** acquisition





Singular value decay 2-D acquisition





Matrix completion

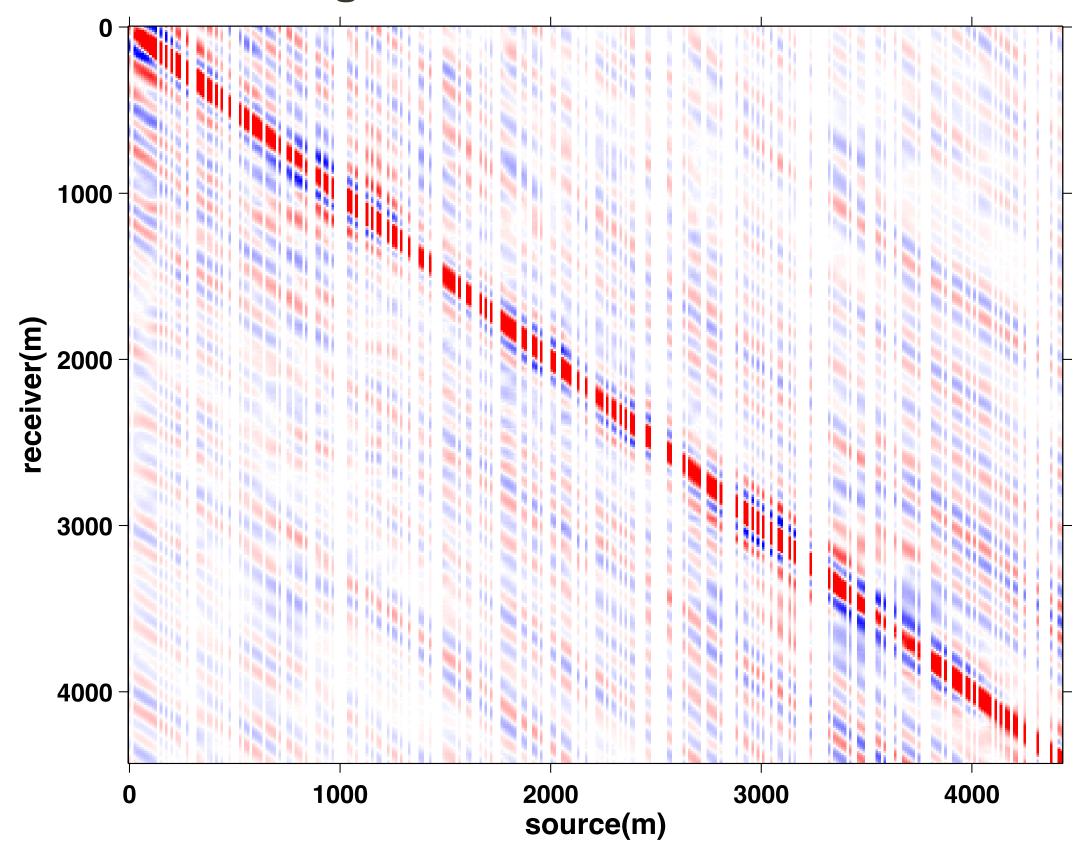
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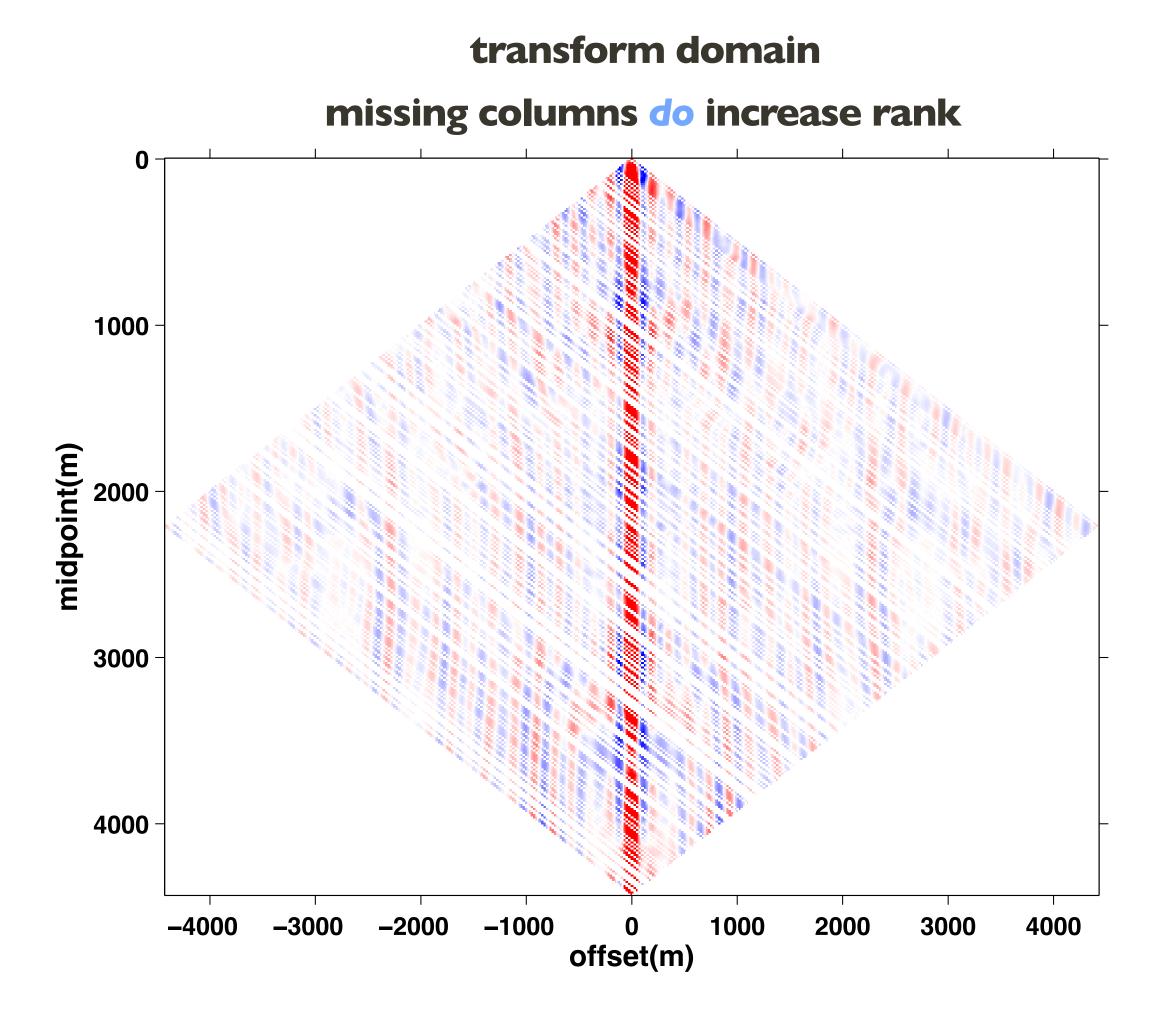


2-D acquisition uniform-random sampling

acquisition domain

missing columns do not increase rank

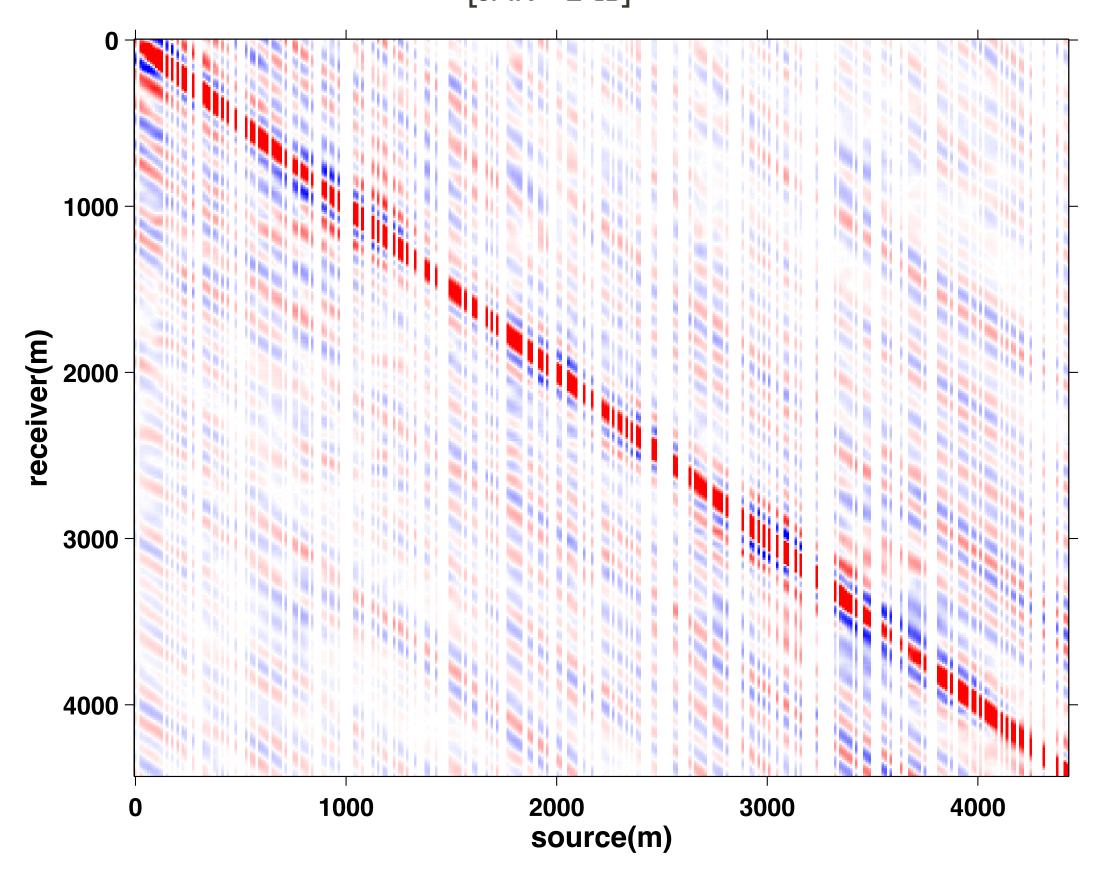


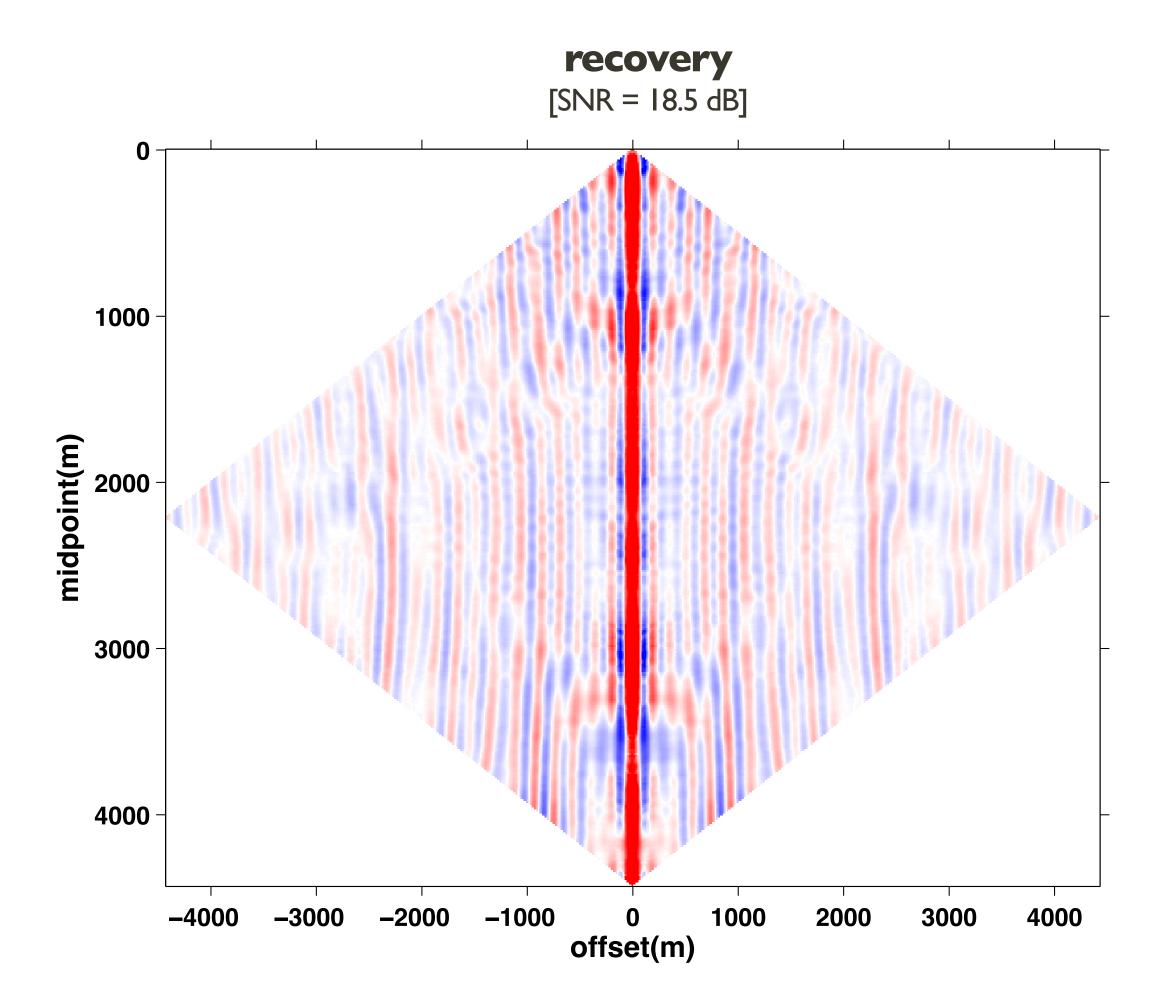




Low-rank interpolation

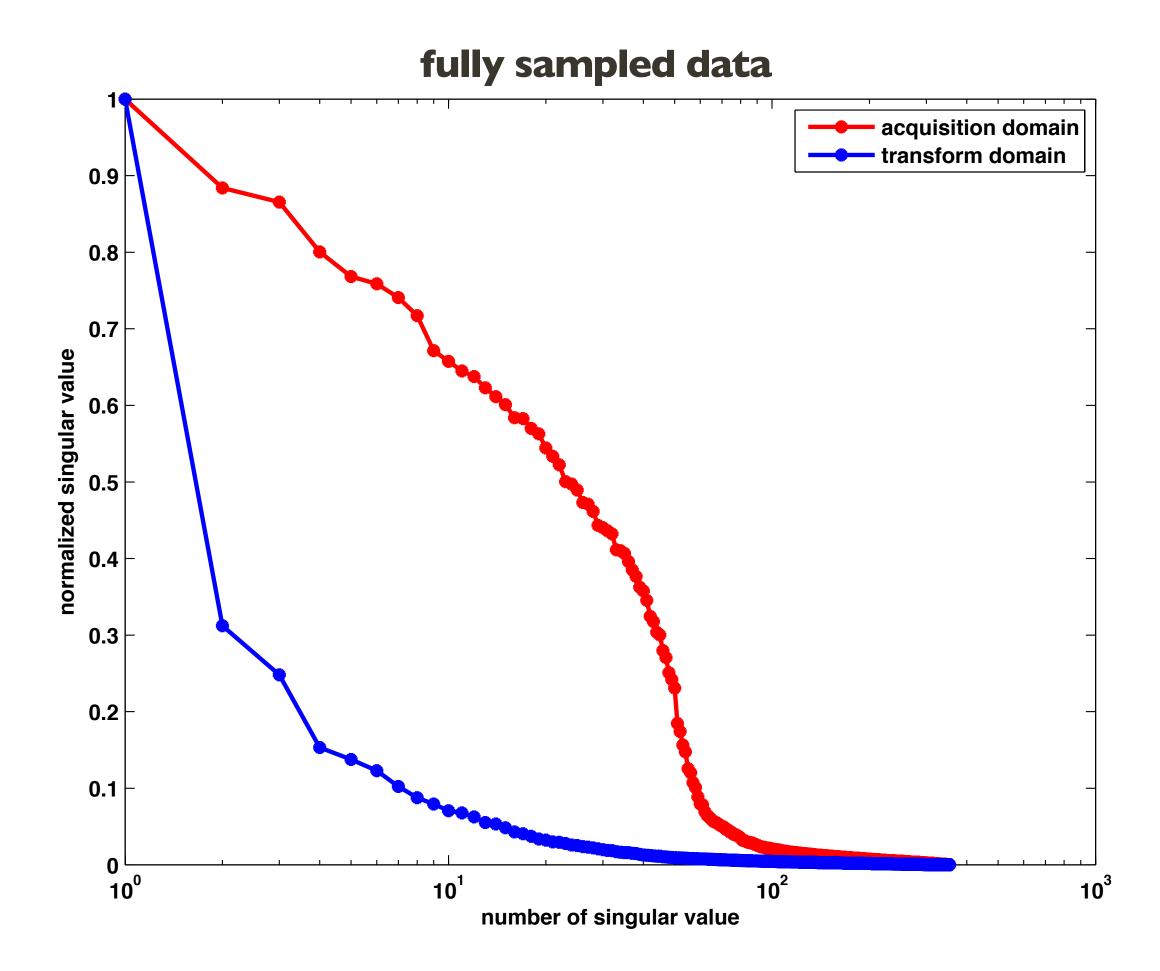
recovery [SNR = 2 dB]

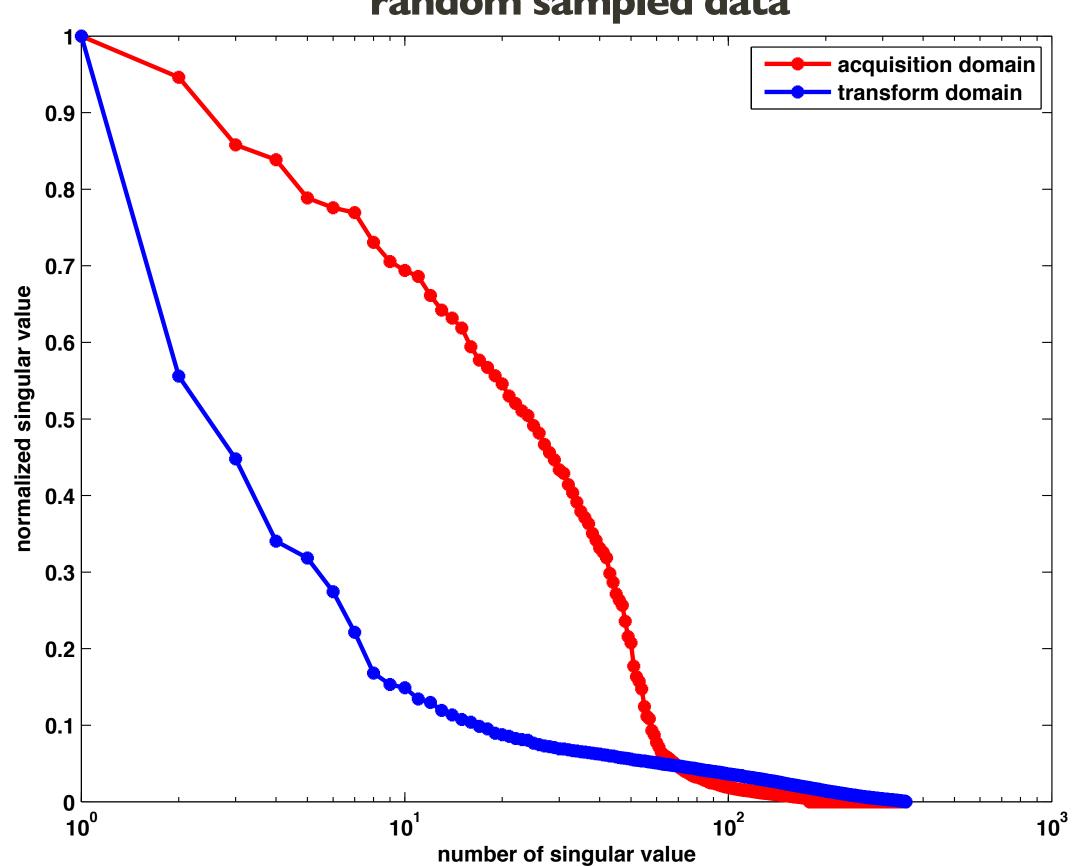






Randomized sampling singular value decay





random sampled data



Observations

- sampling become incoherent in "transform" domain
- slow decay of singular values in "transform" domain



Matrix completion

- signal structure
 - low rank/fast decay of singular values
- sampling scheme
 - missing data increase rank in "transform domain"

recovery using rank penalization scheme



Rank minimization

where

• given a set of measurements b, aim is to solve $\min_{\mathbf{X}} \quad \operatorname{rank}(\mathbf{X}) \quad \text{s.t.} \ ||\mathcal{A}(\mathbf{X}) - \mathbf{b}||_2^2 \leq \sigma$ $(BPDN_{\sigma})$

where $rank(\mathbf{X}) = number of singular values of \mathbf{X}$

• \mathcal{A} is the transform-sampling operator defined as

- $\mathcal{A} = \mathbf{R}\mathbf{M}\mathcal{S}^H$

 - \mathbf{R} : restriction operator M: measurement operator \mathcal{S}^{H} : transform operator



Rank minimization

- prohibitively expensive
 - do not know rank value in advance
 - search over all possible values of rank
- instead solve nuclear-norm minimization
 - convex relaxation of rank-minimization [Recht et. al. 2010]



[Recht et. al. 2010]

Nuclear-norm minimization

we want to solve $\min_{\mathbf{X}} ||\mathbf{X}||_{*} \quad \text{s.t.} \; ||\mathcal{A}(\mathbf{X}) - \mathbf{b}||_{2}^{2} \leq \sigma$ $(BPDN_{\sigma})$ where

 $\|\mathbf{X}\|_* = \sum_{i=1} \lambda_i = \|\lambda\|_1$

where λ_i are the singular values



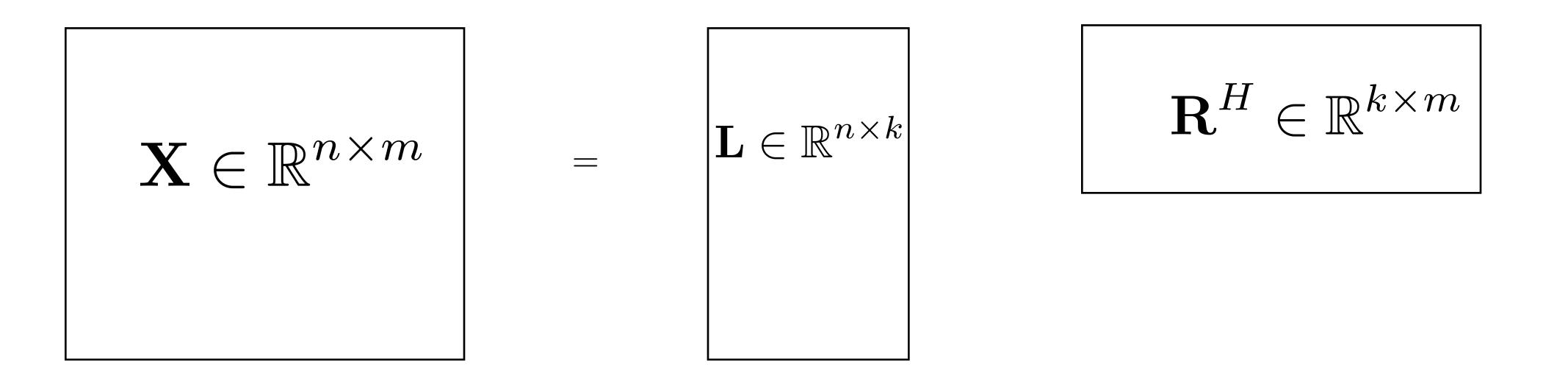
Challenges

- requires repeated application of SVD for projections
- expensive to compute for large system - curse of dimensionality
- can we exploit rank structure "SVD free"



[Rennie and Srebro 2005, Lee et. al. 2010, Recht and Re 2011]

Factorized formulation



1

$\mathbf{X} = \mathbf{L}\mathbf{R}^{H}$



[Berg and Friedlander 2008, Aravkin et al. 2012b] **Factorized formulation**

• reformulate $(BPDN_{\sigma})$ formulation

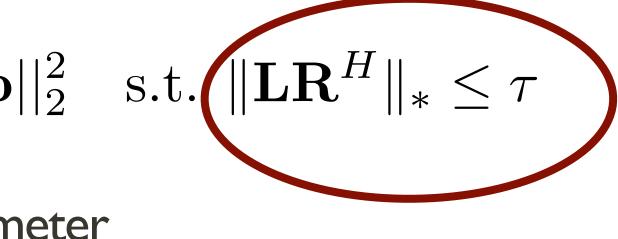
$$\min_{\mathbf{L},\mathbf{R}} ||\mathbf{L}\mathbf{R}^{H}||_{*} \quad \text{s.t.} ||\mathcal{A}|$$

• approximately solve a series of $LASSO_{\tau}$ formulation

$$v(\tau) = \min_{\mathbf{L},\mathbf{R}} ||\mathcal{A}(\mathbf{L}\mathbf{R}^{H}) - \mathbf{b}|$$

where \mathcal{T} is a rank regularization parameter

 $4(\mathbf{LR}^H) - \mathbf{b}||_2^2 \le \sigma$





[Rennie and Srebro 2005]

Factorized formulation

- Upper-bound on nuclear norm is defined as $\|\mathbf{L}\mathbf{R}^{H}\|_{*} \leq \frac{1}{2} \left\| \begin{bmatrix} \mathbf{L} \\ \mathbf{R} \end{bmatrix} \right\|_{F}^{2}$
 - where $\|\cdot\|_F^2$ is sum of squares of all entries
- choose k explicitly & avoid costly SVD's



Computational cost with and without SVD

		50%		75%	
	σ	0.1	0.08	0.1	0.08
Matrix completion w/ SVD	SNR (dB)	17.3	18.3	11.6	11.5
	time (sec)	812	937	790	765
Matrix completion w/o SVD	SNR (dB)	17.6	18.4	12.6	13.3
	time (sec)	8	10	8	7



Upcoming paper Check https://www.slim.eos.ubc.ca soon!

Computational cost matrix completion v/s curvelet-based methods

		50%		75%	
	σ	0.1	0.08	0.1	0.08
Matrix completion w/ SVD	SNR (dB)	17.3	18.3	11.6	11.5
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Matrix completion w/o SVD	SNR (dB)	17.6	18.4	12.6	13.1
	time (sec)	8	10	8	7
Curvelet-based sparsity promotion	SNR (dB)	17.4	18.6	12.5	12.8
	time (sec)	879	989	817	1010



Observation matrix completion v/s curvelet-based methods

Low-rank

computational time

O(*minutes*)

 $k \times (n+m)$ storage

Curvelet

O(hours)

$8 \times nm$



Take-away message

can avoid "SVD"

faster compare to curvelet-based sparsity promotion techniques

memory efficient compare to curvelet-based techniques



Outline

interpolation

 regularization - is binning the right approach?

- comparison with curvelet-based reconstruction methods



Regularization

unstructured acquisition grid

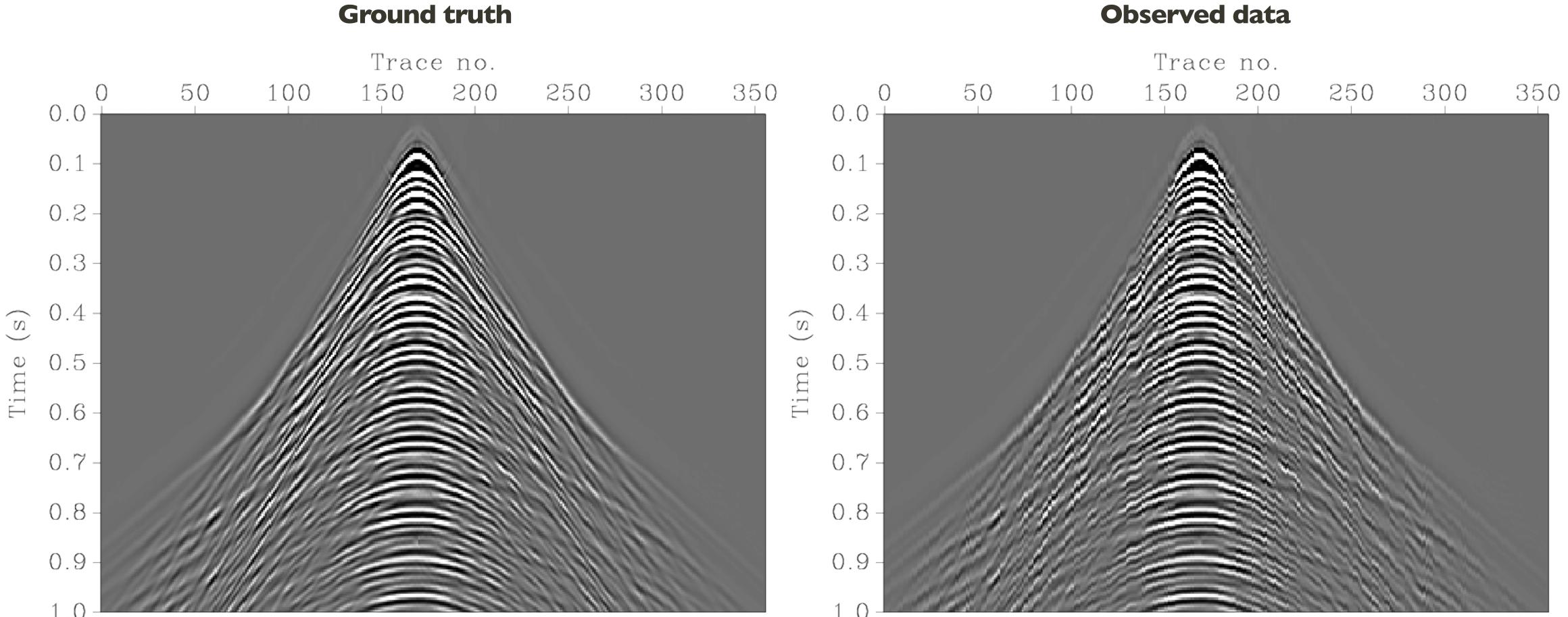
imaging and inversion algorithm
regularly sampled data

binning

- does not preserve the data-structure

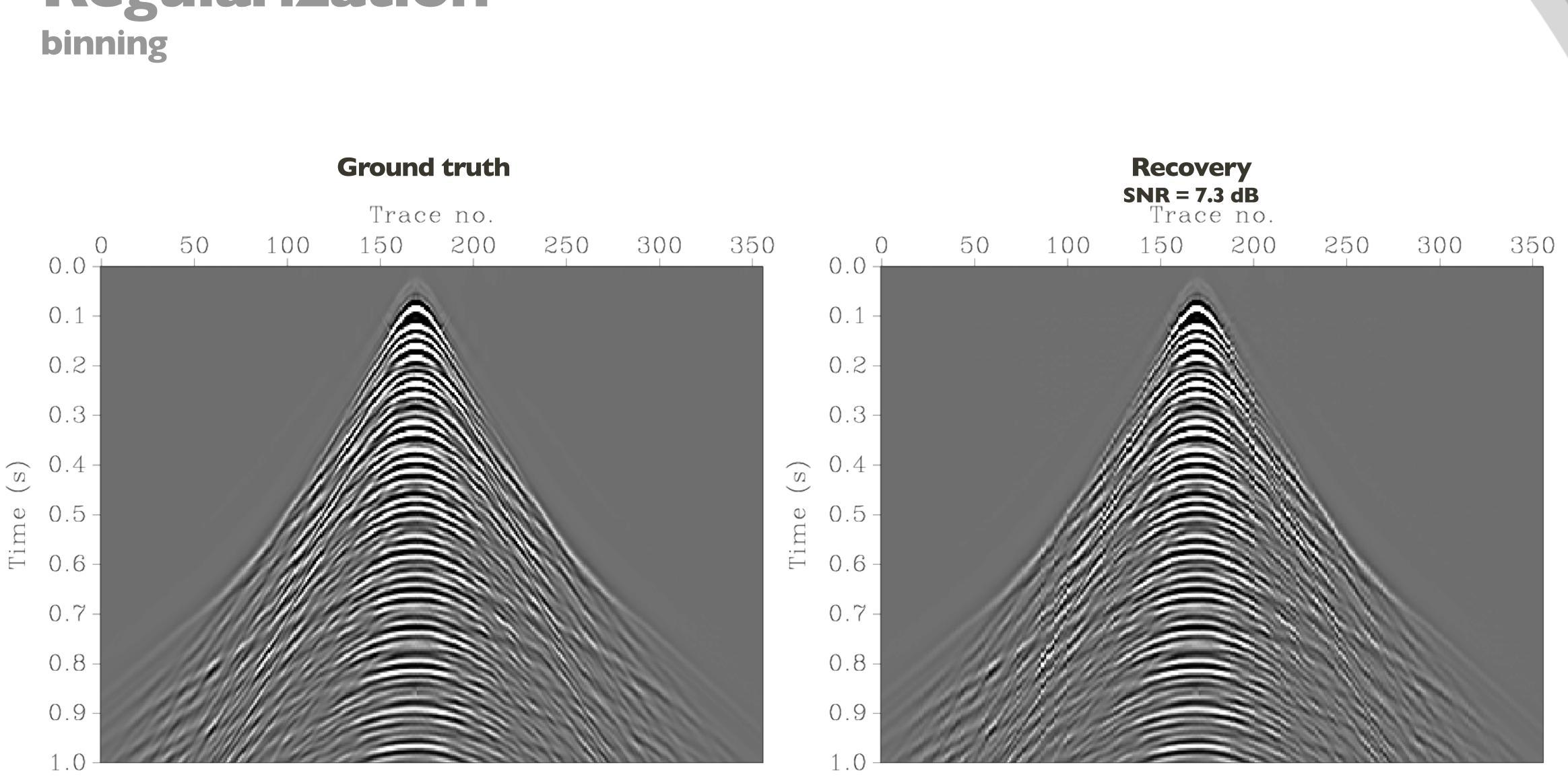


Regularization



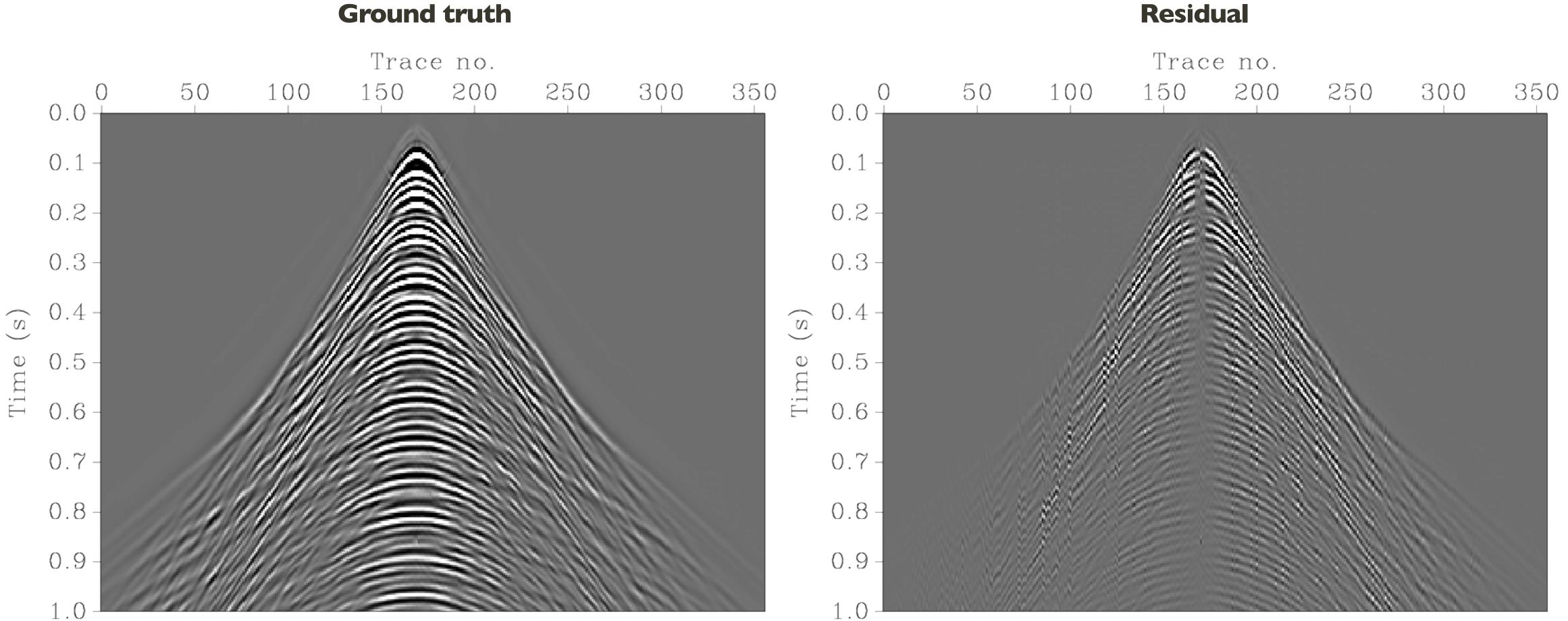


Regularization





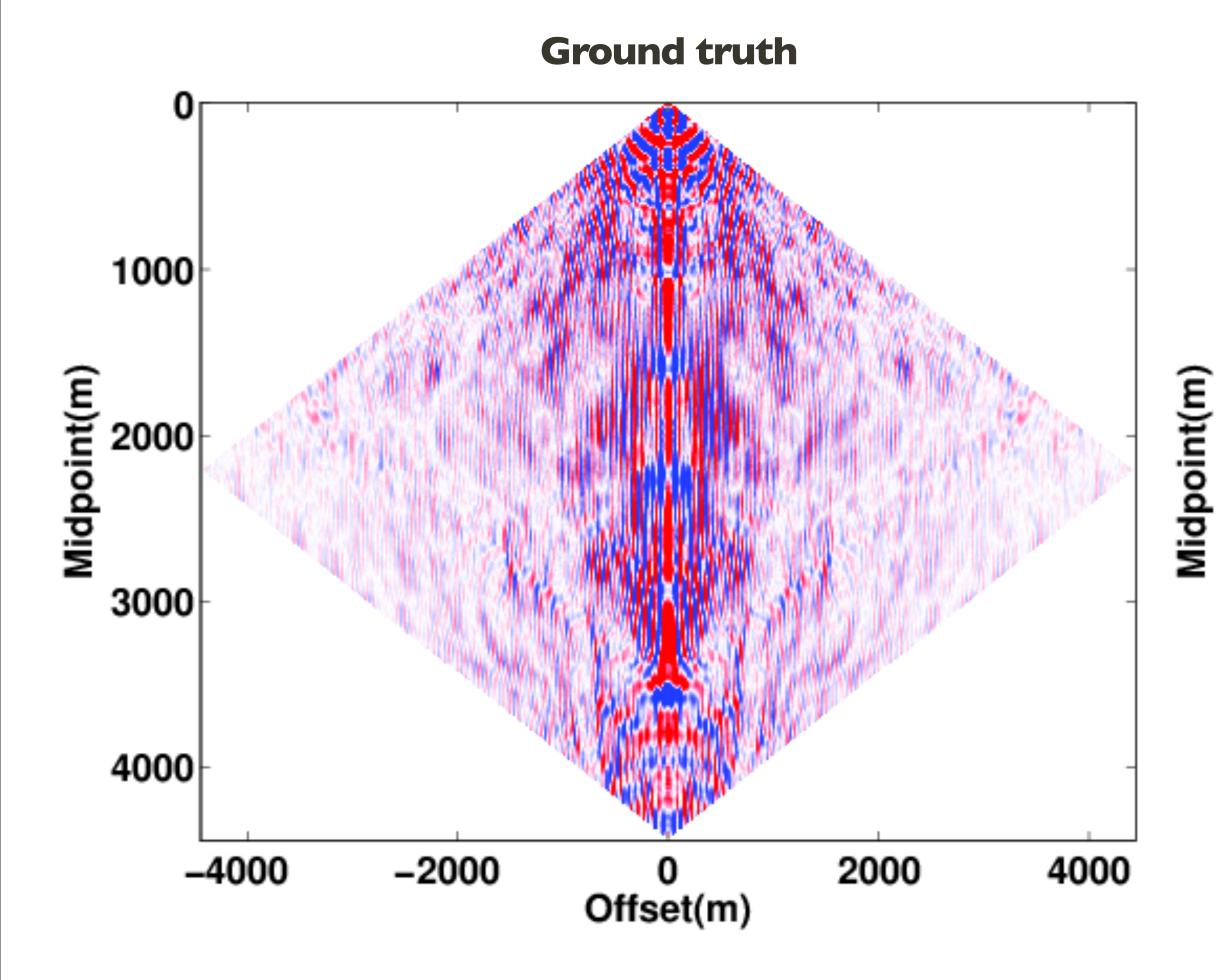
Regularization binning

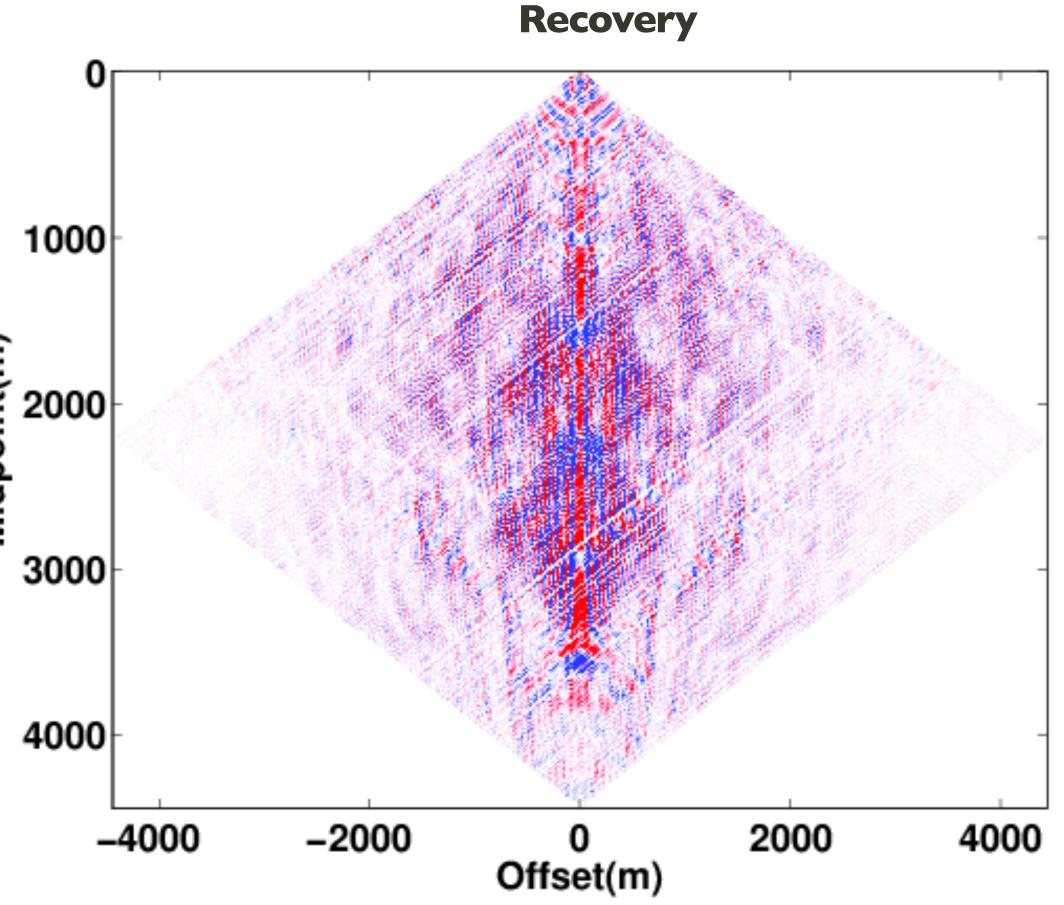


Residual



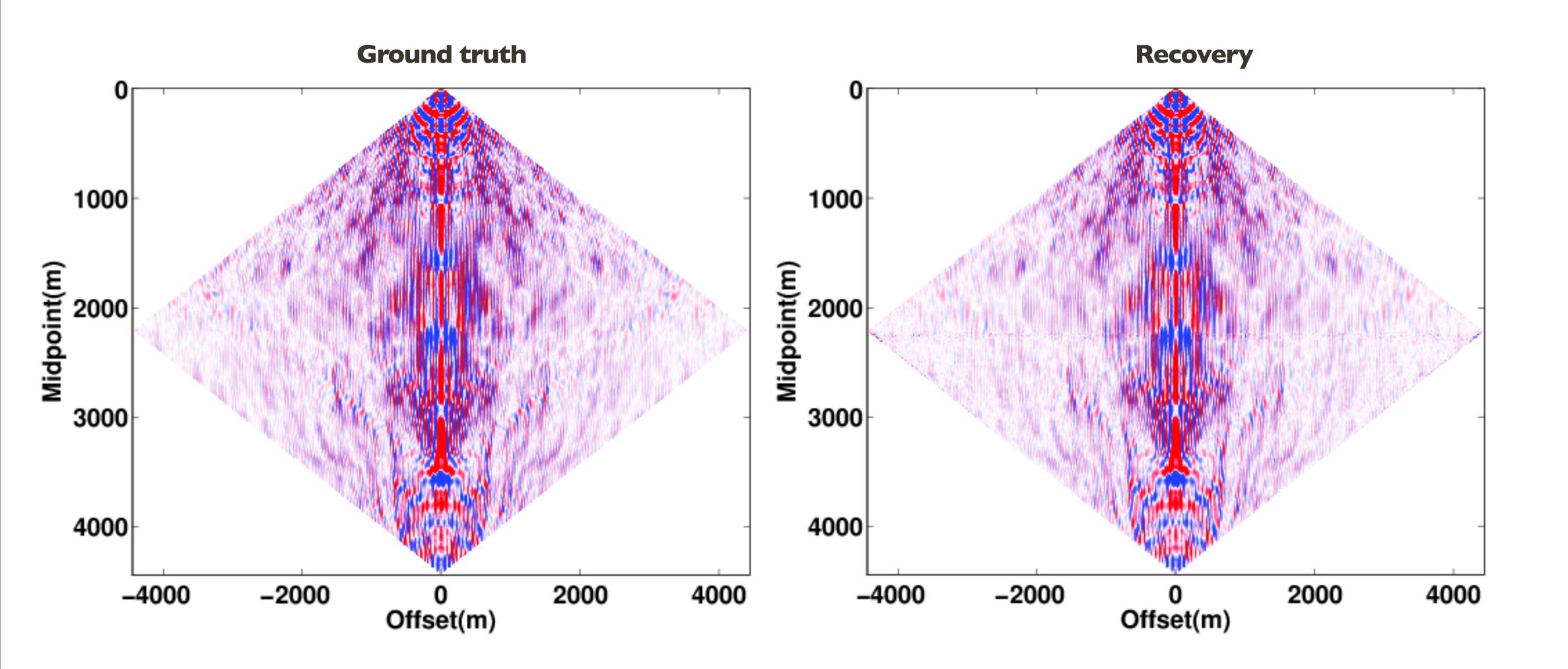
Low-rank structure binning, midpoint-offset domain





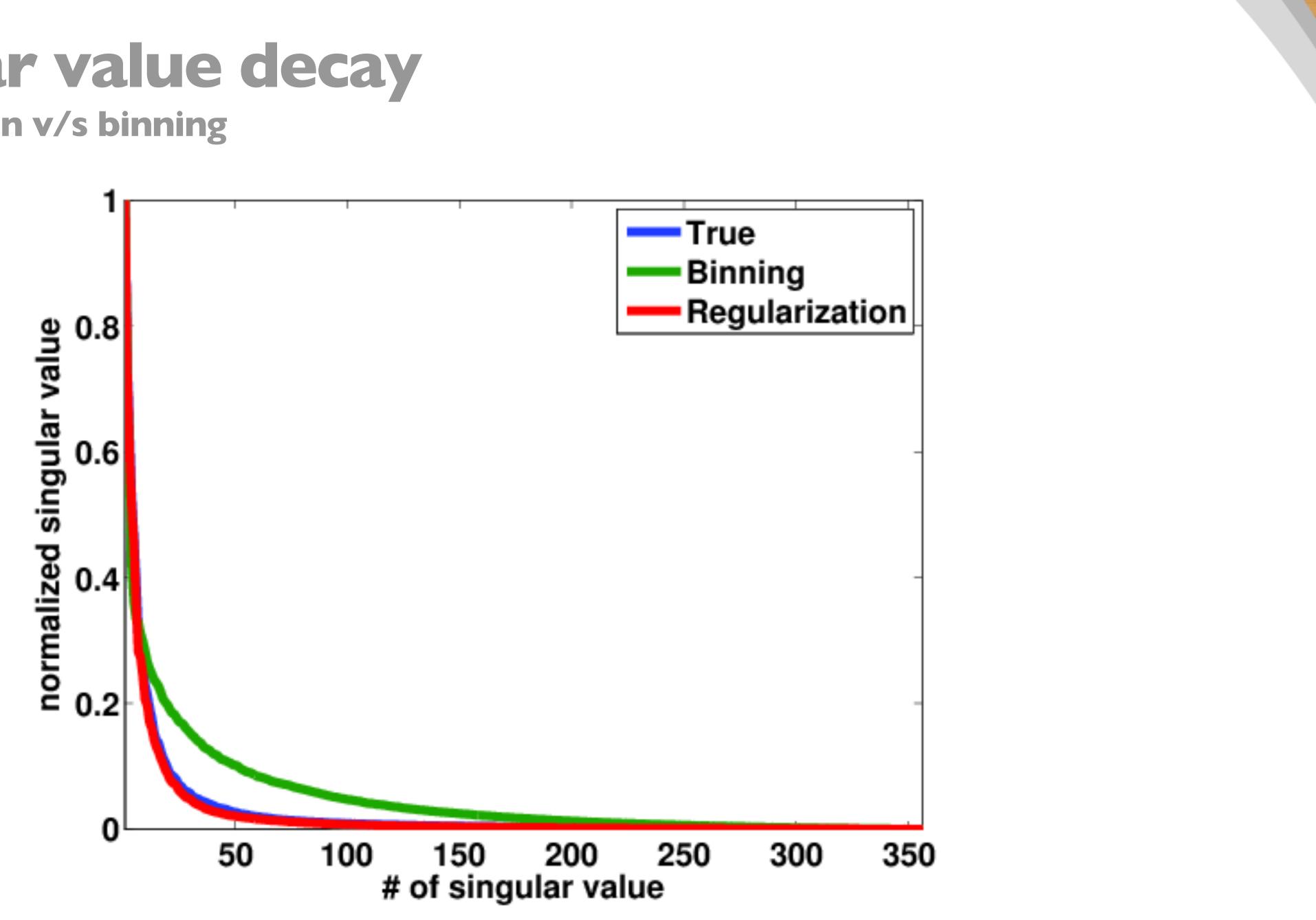


Regularization matrix completion, midpoint-offset domain





Singular value decay regularization v/s binning





Methodology matrix completion

- transform-sampling operator is redefine as

where

- S^H : transform operator

• given a regularization operator $\mathbf{N}: \mathbb{C}^{n \times m} \to \mathbb{C}^{n \times m}$ so that $\mathbf{N}(\mathbf{X}_r) = (\mathbf{X}_{ir})$,

$\mathcal{A} = \mathbf{R}\mathbf{M}\mathbf{N}^H\mathcal{S}^H$

 \mathbf{R} : restriction operator M: measurement operator \mathbf{N}^{H} : regularization operator

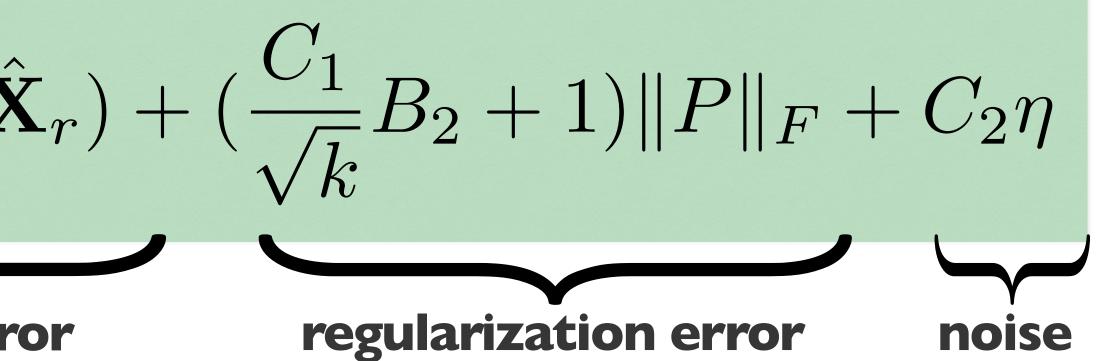


Theorem matrix completion

Let $\mathbf{X}_{\mathbf{r}} \in \mathbb{C}^{n \times m}$, $\hat{\mathbf{X}}_{r} \in \mathcal{S}$ and $\mathbf{b} = \mathbf{RM}(\mathbf{X}_{ir}) + e$ with $\|e\| \leq \eta$. Let $\tilde{\mathbf{X}}$ be the solution of BPDN_{σ}, then

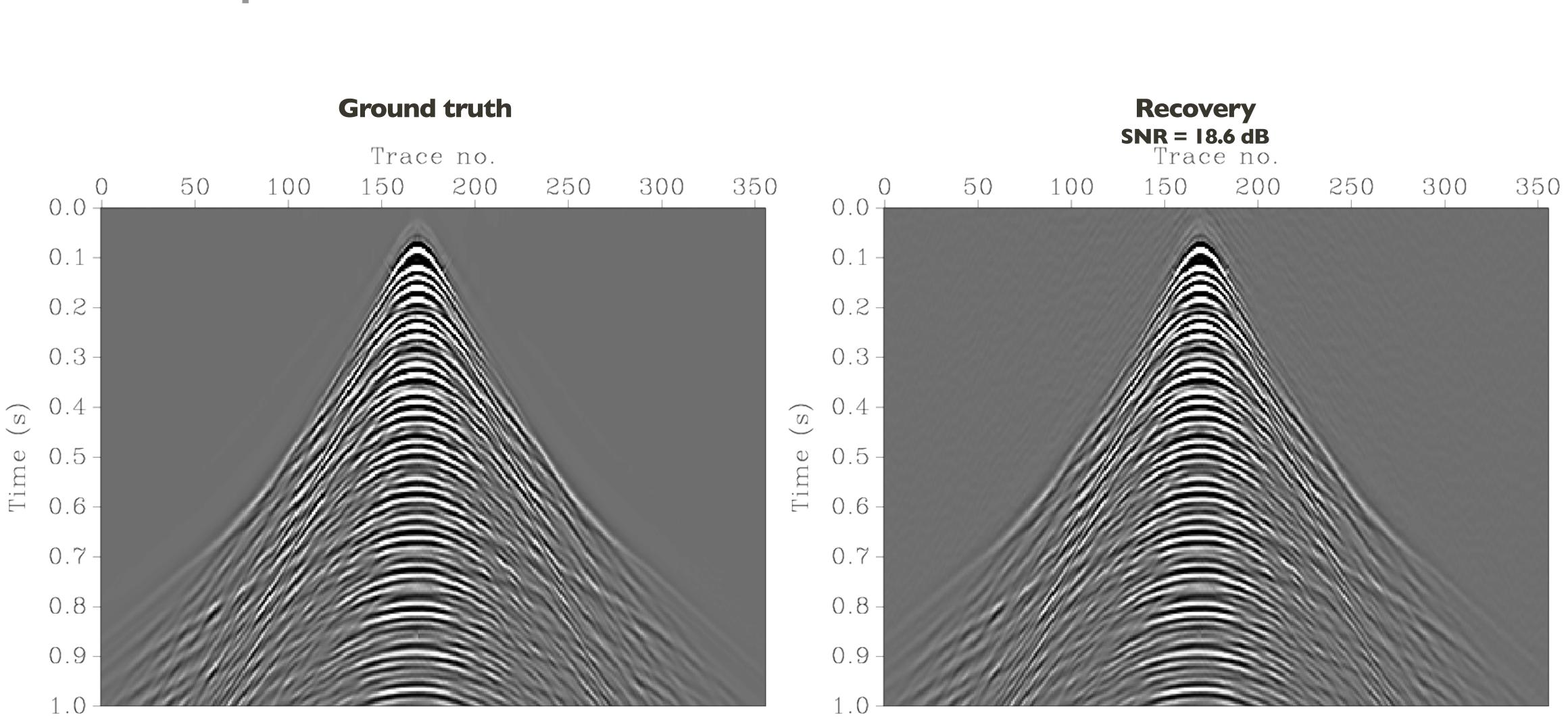
$$\|\mathcal{S}(\mathbf{X}_{r} - \tilde{\mathbf{X}})\| \leq \frac{C_{1}}{\sqrt{k}} \sum_{j=k+1}^{l} \sigma_{j}(\hat{\mathbf{X}}_{r}) + (\mathbf{X}_{r}) + \mathbf{X}_{r}$$

interpolation error
where
$$P = \mathbf{N}^{-1}(\mathbf{X}_{ir}) - \mathbf{X}_{r}$$
$$l = min\{n, m\}$$
$$B_{2} = (1 - \frac{k}{l})\sqrt{l}$$
$$C_{1} \text{ and } C_{2} > 0$$



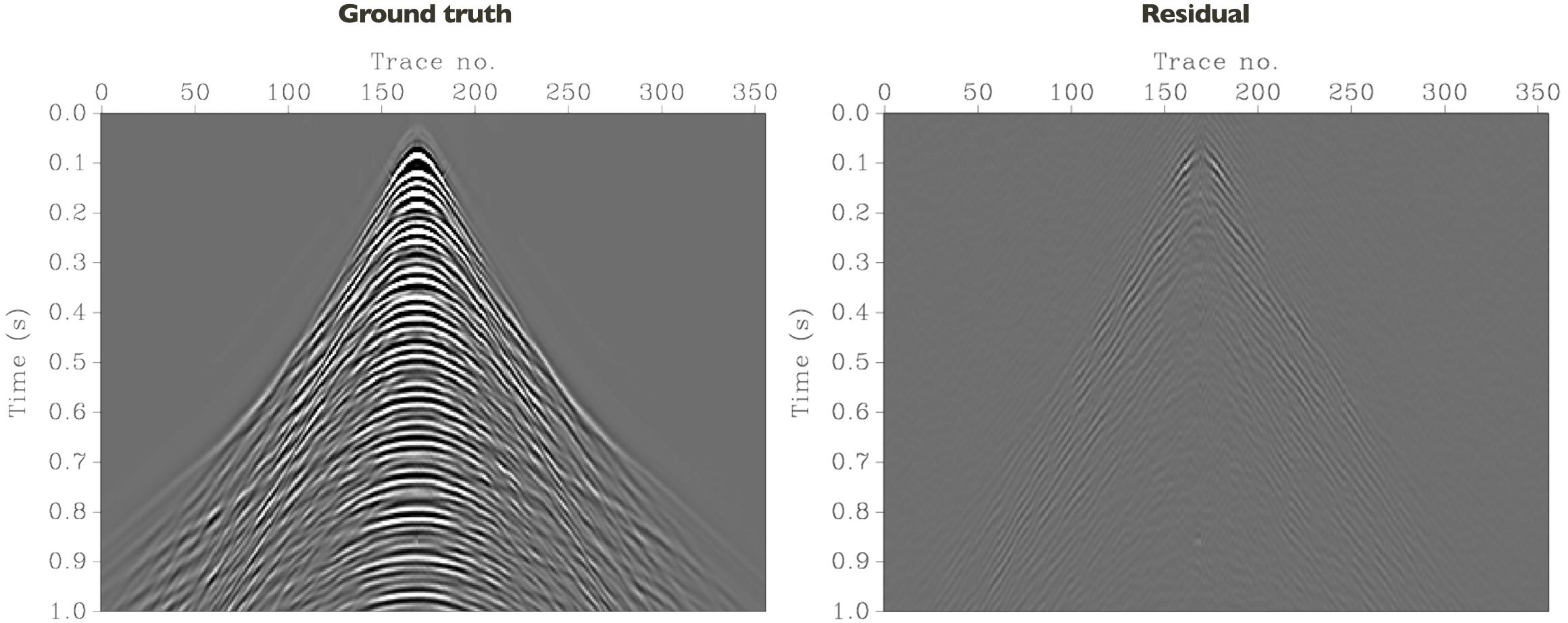


Regularization matrix completion





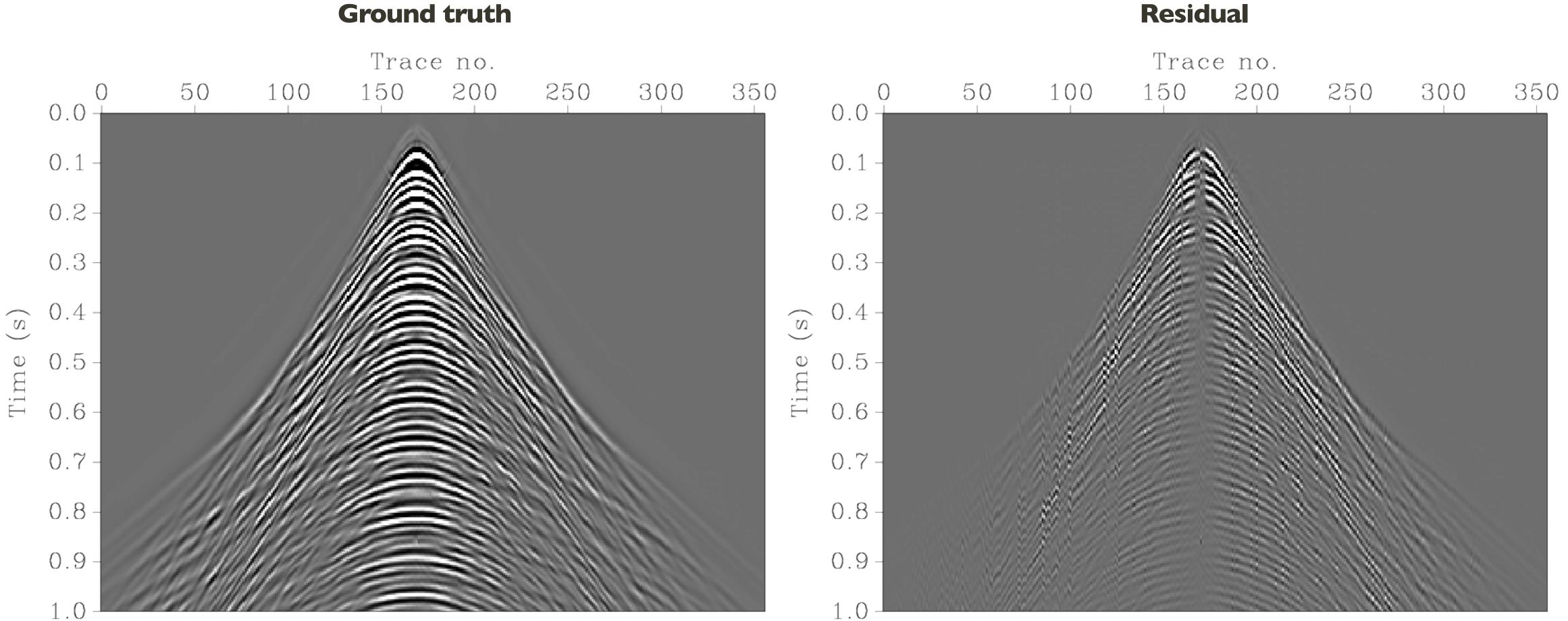
Regularization matrix completion



Residual

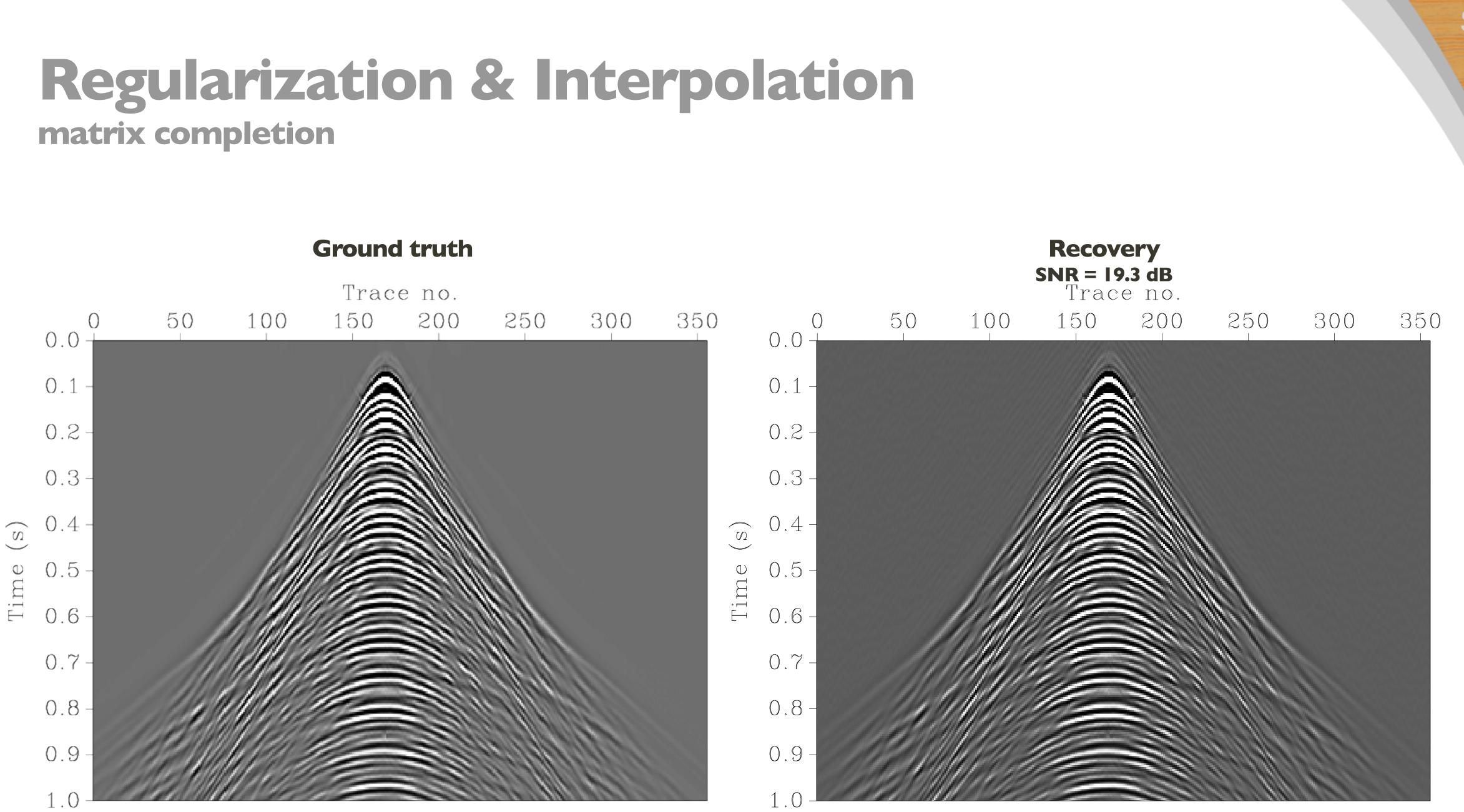


Regularization binning



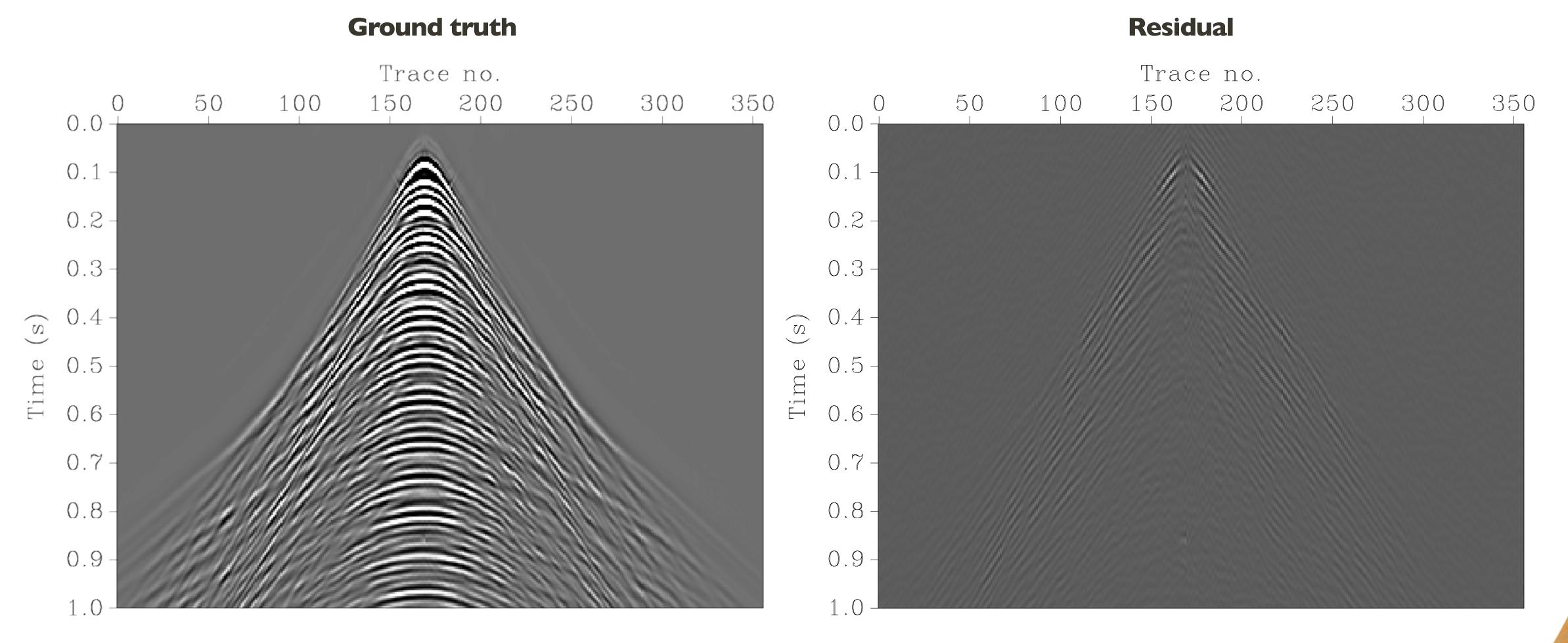
Residual







Regularization & Interpolation matrix completion





Conclusion

- matrix factorization allows SVD-free low-rank methods that work fast on large data
- feasible then curvelet
- matrix-factorization promise more compact representation
- able to handle data at unstructured grids



reconstruction quality is as good as curvelet-based techniques but computationally more



Future work

incorporate irregularity along both sources & receivers coordinates

extension to 5D seismic data volumes

testing of matrix-factorization based methods on real-data

comparison with tensor-based interpolation methods



Acknowledgements We need Real data set

Thank you for your attention ! https://www.slim.eos.ubc.ca/



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