

# Denoising in wave inversion with source blending

Rongrong Wang, Felix Herrmann

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# Outline

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- 1 An alternative solver (DC-WRI) for WRI when  $\lambda$  is small.
- 2 Accelerating and Denoising the (DC)-WRI using principal source encoding.
- 3 Conclusion and future direction.

# Wavefield Reconstruction Inversion

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WRI in matrix form

$$\hat{m} = \arg \min_{m, U} \underbrace{\|P_{\Omega}U - D_{obs}\|_F^2 + \lambda^2 \|A(m)U - Q\|_F^2}_{J(m,U)}.$$

We assume

- $\Omega$ : locations of receivers.
- each source corresponds to the same set of receivers.

# Solving WRI by Alternative Projection

We alternatively update  $m$  and  $U$

$$U_{k+1} = \arg \min_U \underbrace{J(m_k, U)}_{\text{quadratic in } U} = \begin{bmatrix} \lambda A \\ P_\Omega \end{bmatrix}^\dagger \begin{bmatrix} Q \\ D_{obs} \end{bmatrix},$$

$$m_{k+1} = m_k - \gamma \left. \frac{\partial J(m, U_{k+1})}{\partial m} \right|_{m=m_k}.$$

- As  $\lambda \rightarrow \infty$  WRI converge to FWI.
- As  $\lambda \rightarrow 0$ ,  $\begin{bmatrix} \lambda A \\ P_\Omega \end{bmatrix}$  becomes ill conditioned.

# Taking the limit

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Consider the following two penalties

$$\hat{m}_\lambda = \arg \min_{m, U} \|P_\Omega U - D_{obs}\|_F^2 + \lambda^2 \|A(m)U - Q\|_F^2.$$

$$\hat{m}_\alpha = \arg \min_{m, U} \alpha^2 \|P_\Omega U - D_{obs}\|_F^2 + \|A(m)U - Q\|_F^2.$$

We assert

$$\lim_{\lambda \rightarrow 0} \hat{m}_\lambda = \lim_{\alpha \rightarrow \infty} \hat{m}_\alpha.$$

# An Alternative Method

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As  $\alpha \rightarrow \infty$ , WRI reduces to

$$\hat{m} = \arg \min_{m, U} \|A(m)U - Q\|_F \equiv \tilde{J}(m, U)$$
$$s.t. \quad P_{\Omega}U = D_{obs},$$

We expect

$$U_{\lambda} \rightarrow U.$$

$$\hat{m}_{\lambda} \rightarrow \hat{m}.$$

# The Alternative Minimization for the New Formulation

When applying the alternative minimization, we found an explicit form of  $U_{k+1}$  as a minimizer of  $\tilde{J}(m_k, U)$ .

$$U_{k+1} = P_{\Omega^c}^* (A(m_k) P_{\Omega^c}^*)^\dagger (Q - A(m_k) P_{\Omega}^* D_{obs}) + P_{\Omega}^* D_{obs}$$
$$m_{k+1} = m_k - \gamma \frac{\partial \tilde{J}(m, U_{k+1})}{\partial m} \Big|_{m=m_k}.$$

$P_{\Omega^c}$  restricts the wavefield to non-receiver locations.

# DC-WRI

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In WRI we need to invert

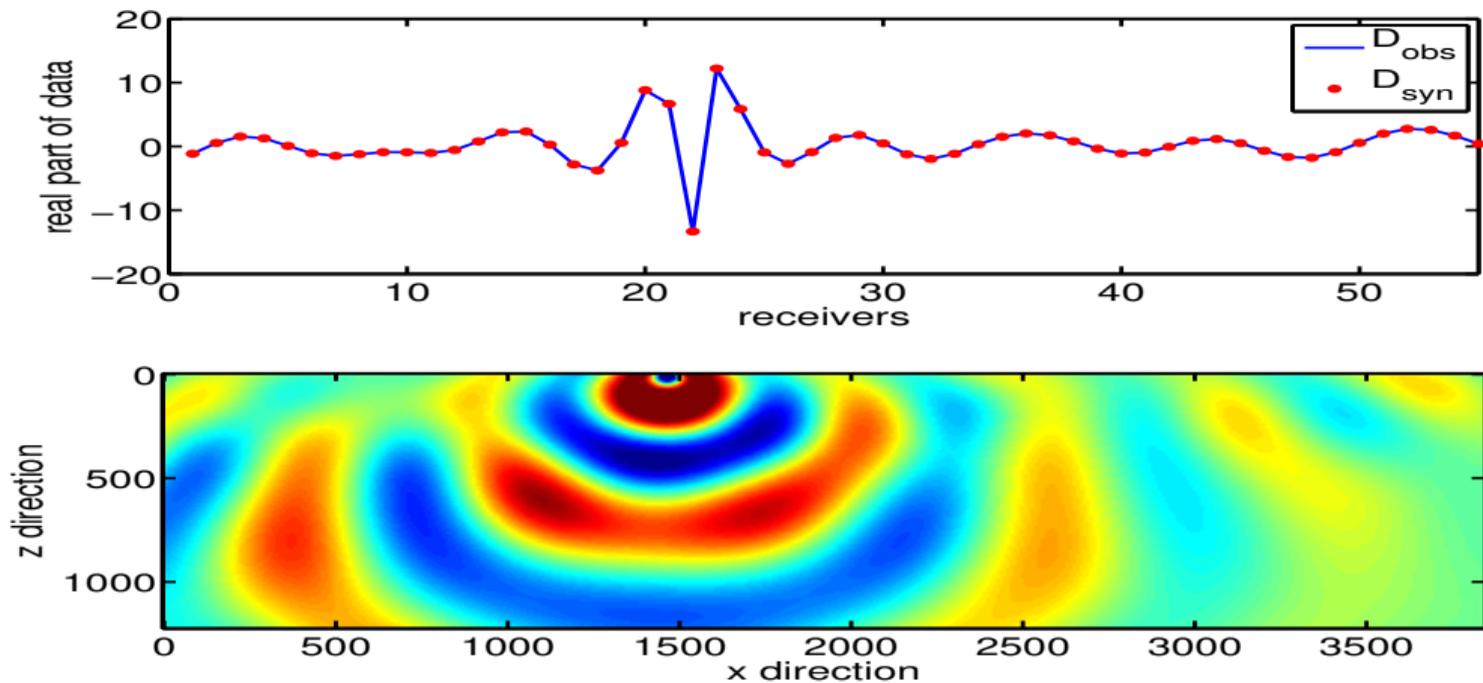
$$\begin{bmatrix} \lambda A \\ P_{\Omega} \end{bmatrix} \leftarrow \text{a data augmented operator}$$

and now we need to invert

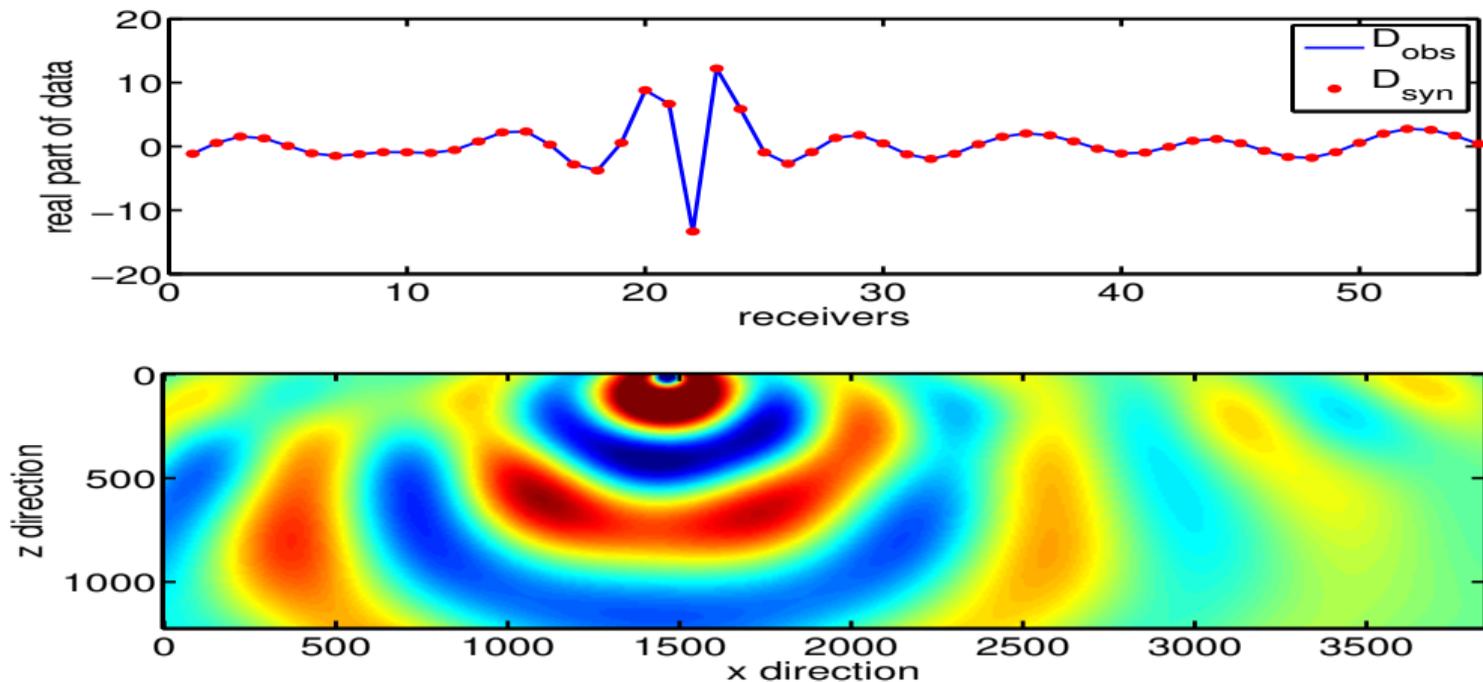
$$A(m_k)P_{\Omega^c}^* \leftarrow \text{a data constrained operator}$$

We call the new method Data-Constrained Wavefield Reconstruction Inversion (DC-WRI).

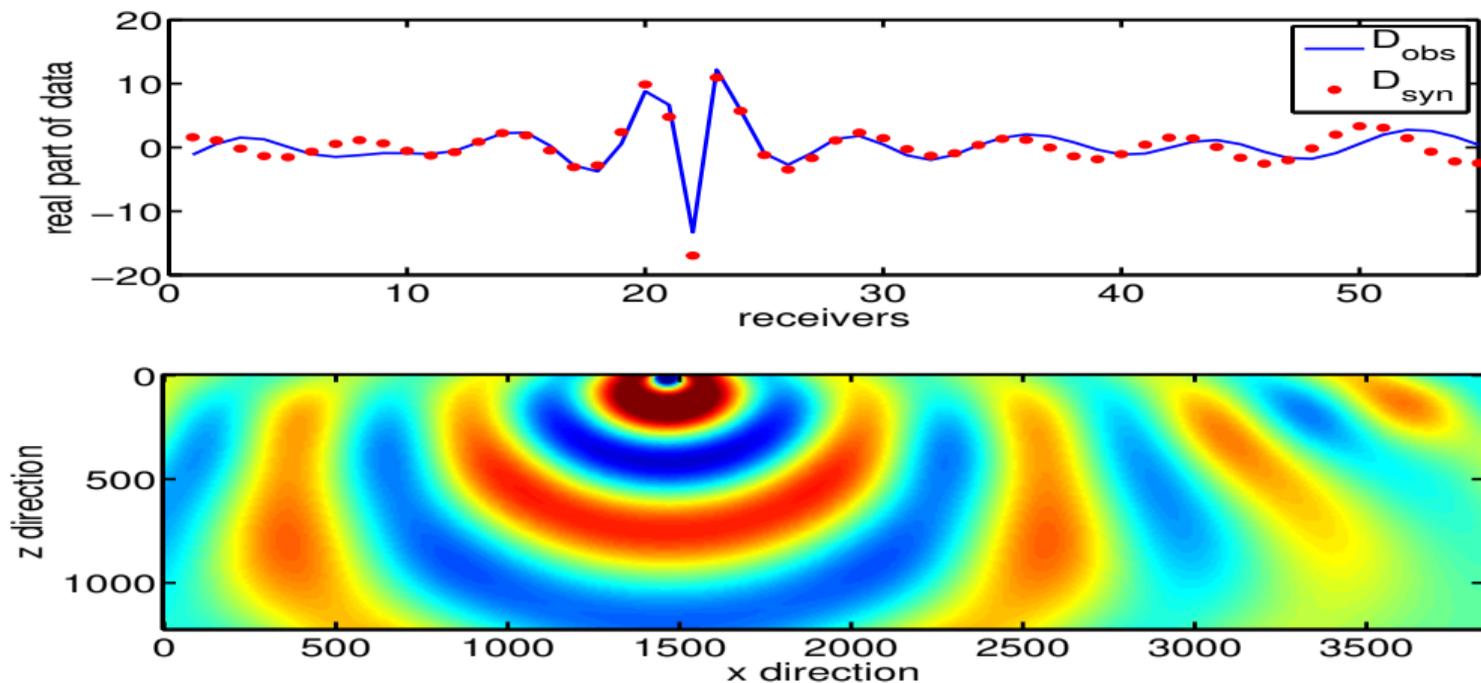
# Wavefield in DC-WRI



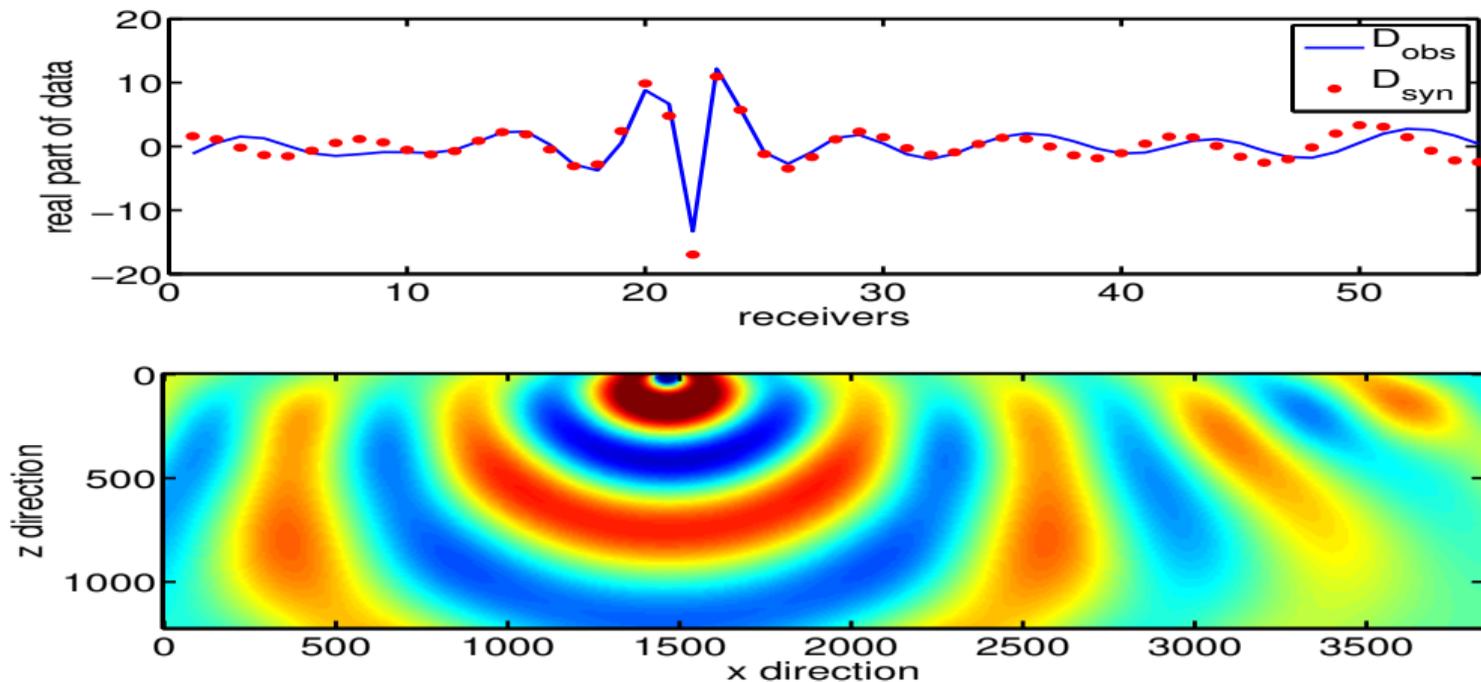
# Wavefield in WRI with $\lambda = 10^{-5}$



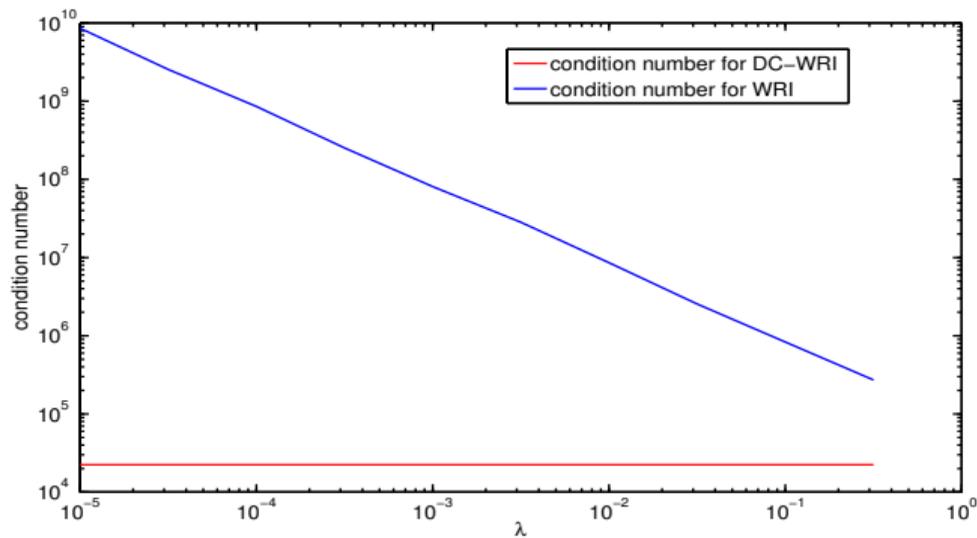
# Wavefield in WRI with $\lambda = 10^5$



# Wavefield in FWI

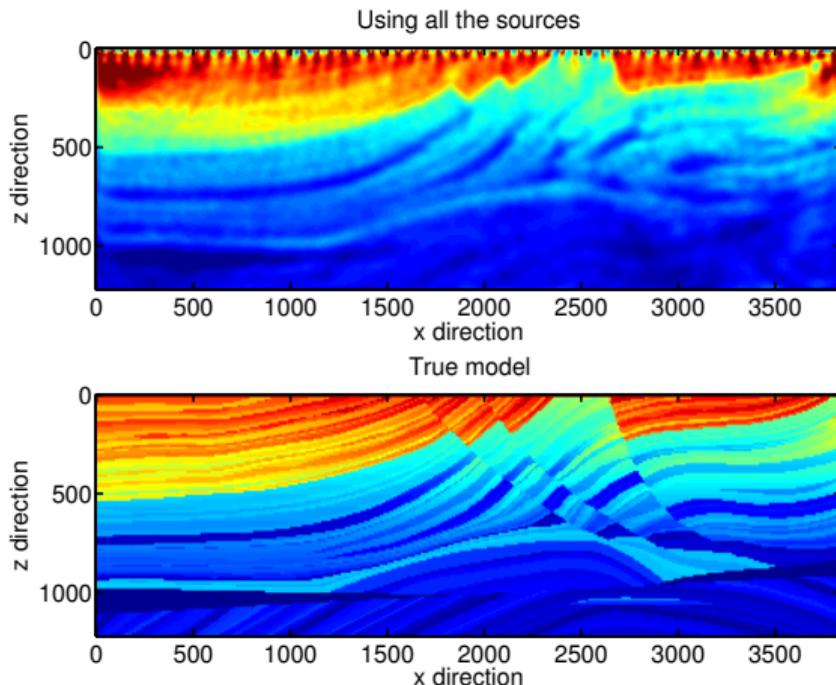


# Comparison of condition numbers



# Noisy data?

Source offset: 20m, Frequency: 5-7Hz: SNR=9.5(dB) 8-20 Hz: SNR=25 dB



# Source encoding

Source encoding techniques:

- randomly picking the sources:  $[(q_{n_1}, \dots, q_{n_k})] \leftarrow \begin{matrix} \text{matrix} \\ \text{with } q \end{matrix} = \tilde{Q}$

- Gaussian encoding:  $QN \leftarrow \begin{matrix} \text{matrix } Q \\ \text{with } N \end{matrix} = \tilde{Q}$

- Encoding using singular vectors  $QV_k \leftarrow \begin{matrix} \text{matrix } Q \\ \text{with } v_k \end{matrix} = \tilde{Q}$

$V_k$  is orthogonal, deterministic, model dependent.

# Source encoding

What is a reasonable  $V_k$ ?

- $\hat{m}$  is closely related to the accuracy of reconstructions of  $U$ ;
- we want to reconstruct the wavefields for only a subset of "sources";
- Low rank approximation (or PCA)

$$U = W\Sigma V^T \approx W_k \Sigma_k V_k^T$$

- $Q \leftrightarrow U, QV_k \leftrightarrow UV_k = W_k \Sigma_k \leftarrow$  the principal component of  $U$ .

# Source encoding

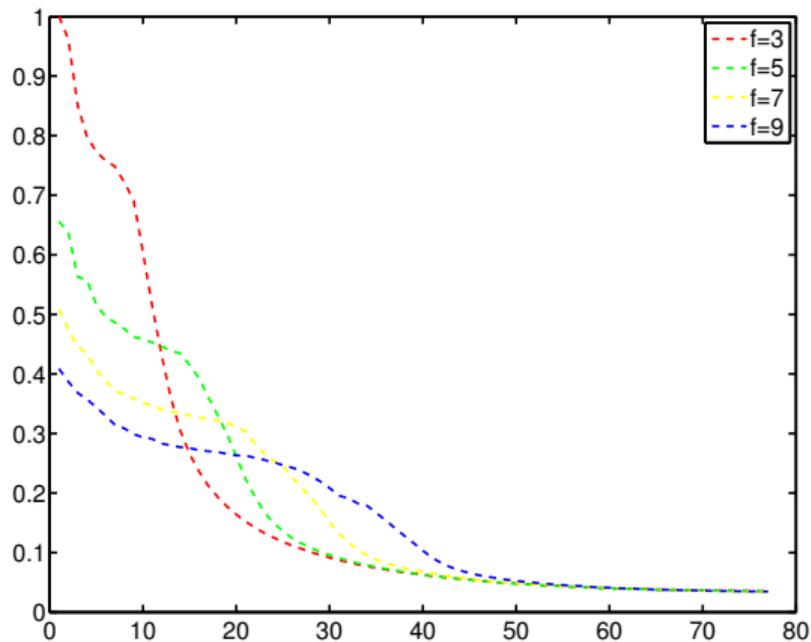
What is a reasonable  $V_k$ ?

- $\hat{m}$  is closely related to the accuracy of reconstructions of  $U$ .
- Reconstruct the wavefields for all the sources vs. those for a subset of sources.
- The best subset? Low rank approximation (or PCA)

$$U = W\Sigma V^T \approx W_k \Sigma_k V_k^T$$

- $Q \leftrightarrow U$ ,  $\underbrace{QV_k}_{\text{encoded source}} \leftrightarrow UV_k = W_k \Sigma_k \leftarrow \boxed{\text{the principal component of } U}$ .

# Normalized singular values of $U$ for $f = 3, 5, 7, 9$

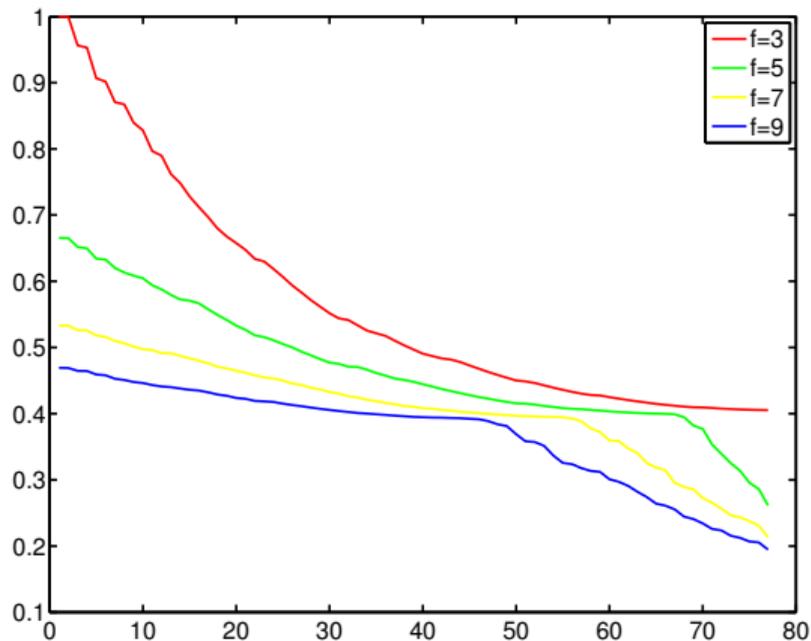


# Source encoding with noise

What if we have noise?

- the principle directions of  $D_{obs}$  have the largest SNR when the noise is i.i.d.
- the principle directions are obtained through  $D_{obs} = \widetilde{W}\widetilde{\Sigma}\widetilde{V}^T \approx \widetilde{W}_k\widetilde{\Sigma}_k\widetilde{V}_k^T$ .
- $Q \leftrightarrow U, QP_{\widetilde{V}_k}V_k \leftrightarrow UP_{\widetilde{V}_k}V_k \leftarrow$  projecting  $V_k$  onto directions with high SNR.

# Normalized singular values of $D_{obs}$ for $f = 3, 5, 7, 9$



# Sketched SVD

Sketched SVD: - [Gilbert, Anna C., Jae Young Park, and Michael B. Wakin].

The right singular vectors of  $X$  is close to those of  $GX$ , where  $G$  is Gaussian with rows much less than columns.

## Theorem 1.

$X$  is an  $n \times d$  matrix with rank  $k$ . Let  $G$  be an a random Gaussian matrix with  $m < n$ . If  $m \geq O(k\epsilon^{-2} \log(1/\epsilon) + \log(1/\delta))$ , then with probably over  $1 - \delta$

$$\|V_X - V_{GX}\|_2 \leq \epsilon \frac{C\|X\|}{d(X)},$$

where  $V_X$  and  $V_{GX}$  are the first  $k$  right singular vectors of  $X$  and  $GX$ ,  $d(X) = \max_{i \neq j} |\sigma_i - \sigma_j|$ .

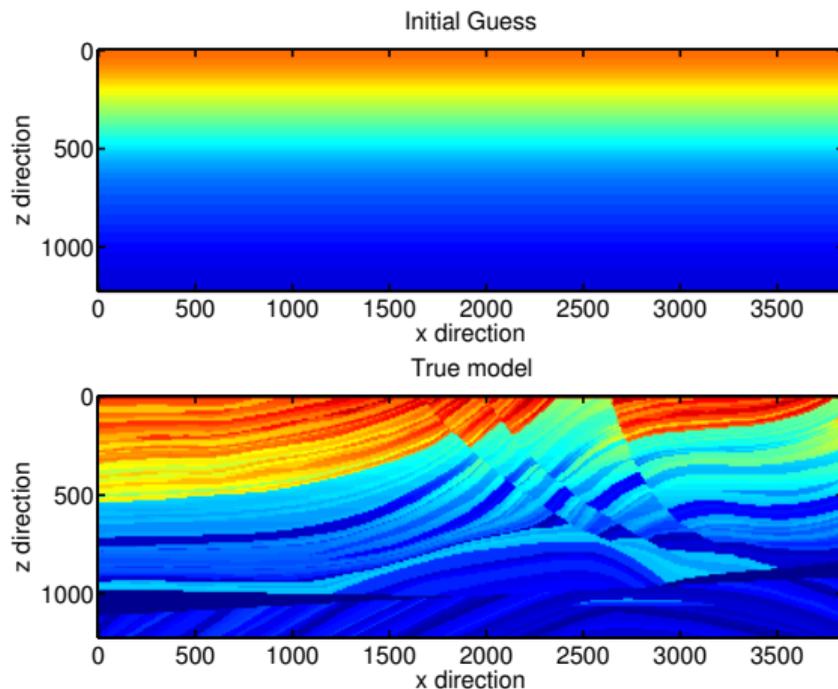
# Summary of the algorithm

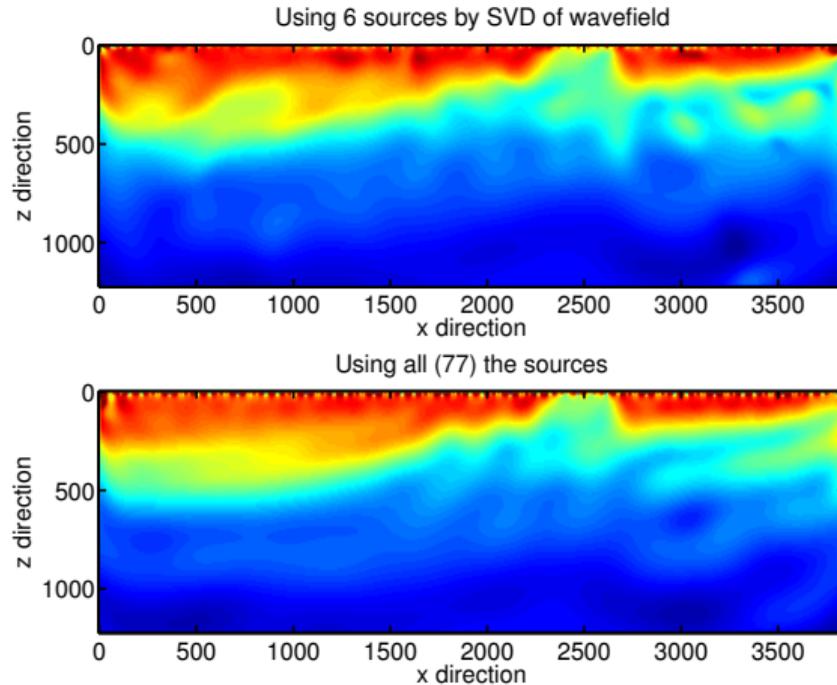
Input:  $D, m_0$ , some  $k_1, k_2 \in \mathbb{Z}$   $k_1 < k_2$  Output:  $\hat{m}$ .

- 1 set  $f = f_{\min}$ ;
- 2 find the SVD of  $D_{obs}$  ( $nr \times ns$ ) and store  $\tilde{V}_{k_2}$ ;
- 3 solve the first iteration of DC-WRI and get  $U$ ;
- 4 apply sketched SVD on  $U$  and obtained  $V_{k_1}$ ;
- 5 construct the mixed sources by  $q \cdot P_{\tilde{V}_{k_2}} V_{k_1}$  ;
- 6 solve DC-WRI using the mixed sources  $q \cdot P_{\tilde{V}_{k_2}} V_{k_1}$  and mixed data  $d \cdot P_{\tilde{V}_{k_2}} V_{k_1}$  for all frequencies.

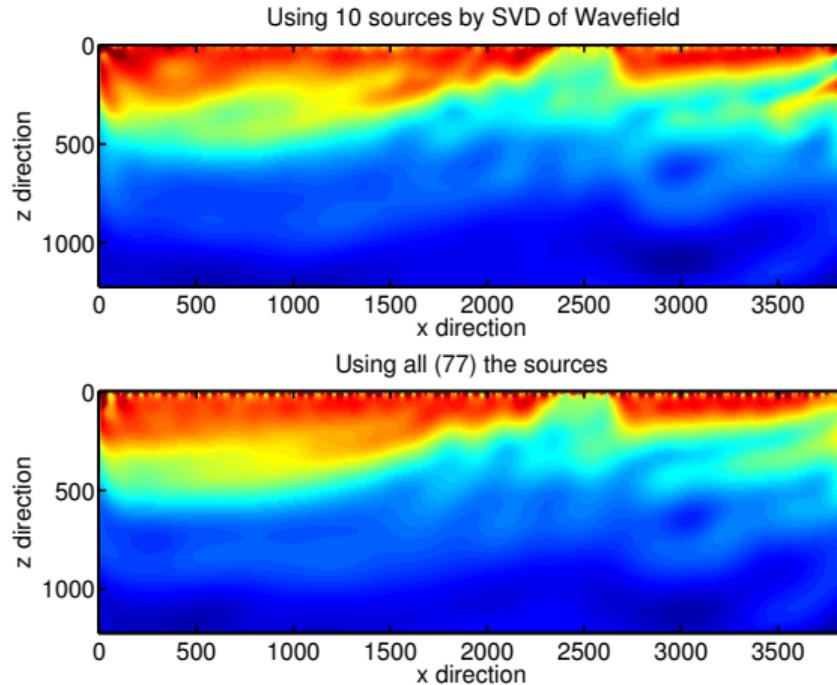
# Examples

Receiver and source offset: 50m Frequency: 4 HZ, no noise

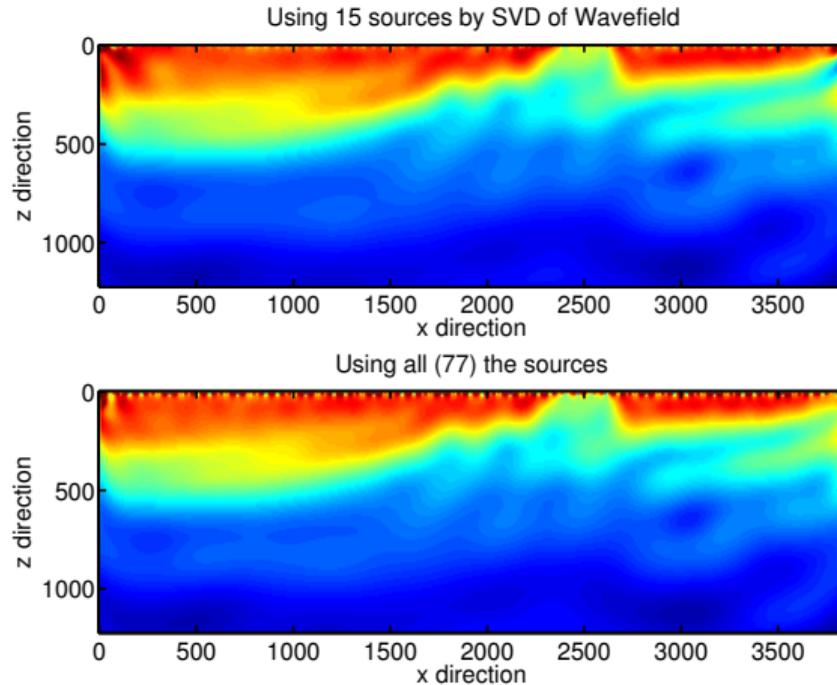




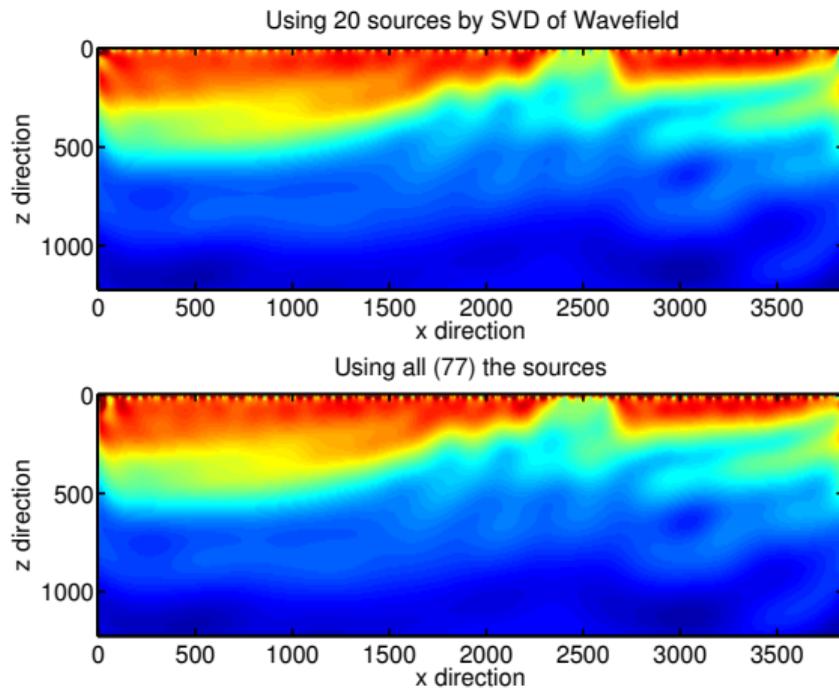
**Figure :** Up: 6 principal sources from wavefield SVD. Down: all (77) sources.



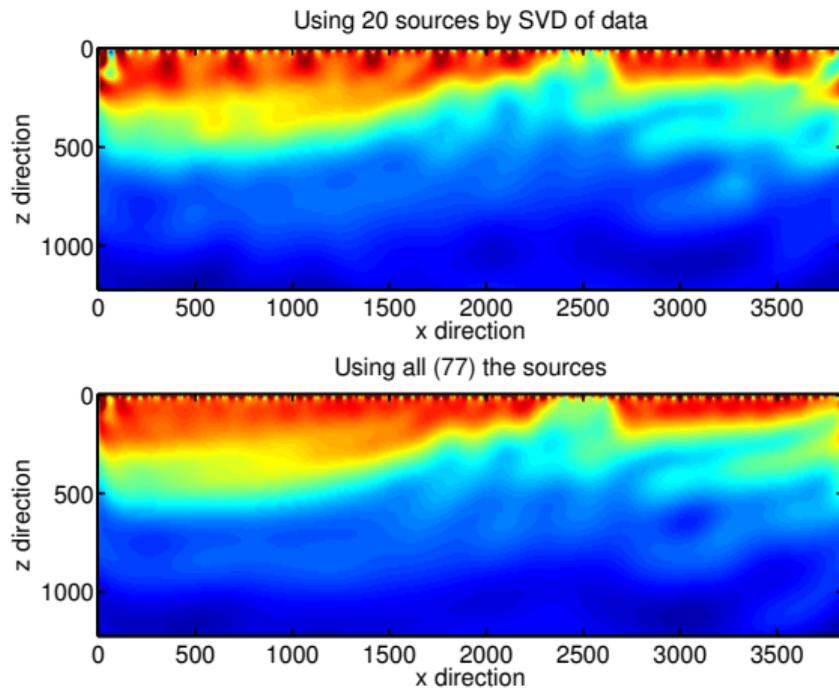
**Figure :** Up 10 principal sources from wavefield SVD. Down: all (77) sources.



**Figure :** Up: 15 principal sources from wavefield SVD. Down: all (77) sources.

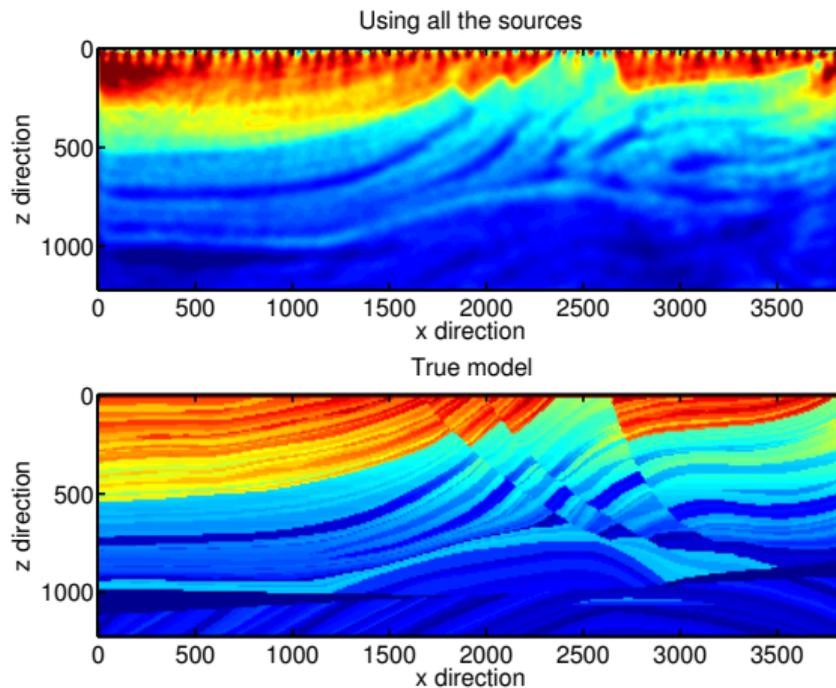


**Figure :** Up: 15 principal sources from wavefield SVD. Down: all (77) sources.

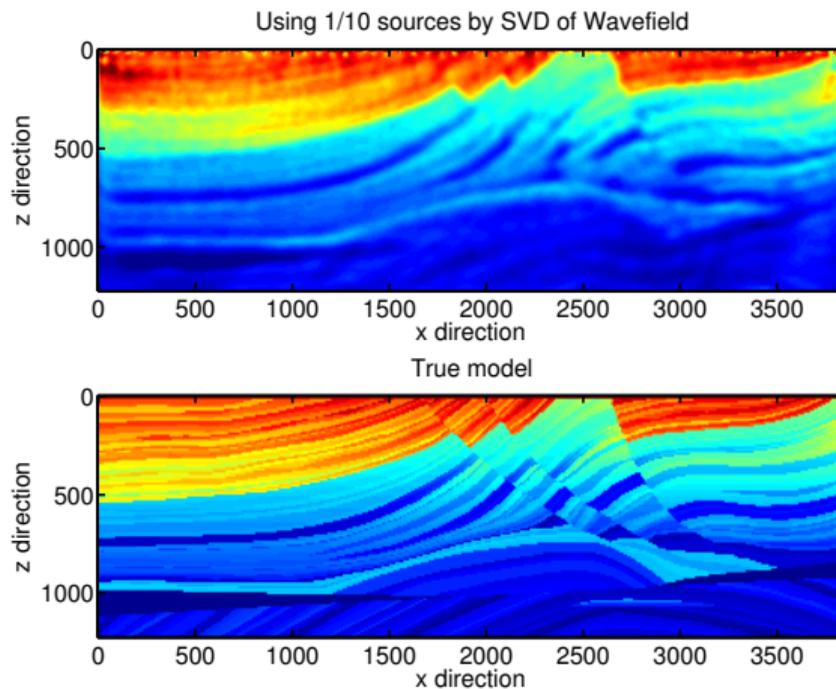


**Figure :** Up: 20 principal sources from SVD on the data. Down: all (77) sources.

Source offset: 20m, Frequency: 5-7Hz: SNR=9.5(dB) 8-20 Hz: SNR=25 dB



Source offset: 20m, Frequency: 5-7Hz: SNR=9.5(dB) 8-20 Hz: SNR=25 dB



# Summary

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We proposed

- a method that overcomes the ill-conditioning problem of small parameter regime of WRI;
- a new source encoding method that could accelerate and stabilize both the new approach and WRI with any  $\lambda$ .

Future direction:

- Testing cases with missing traces, data completion, or other non-OBS scenarios;
- Bringing the technique to time domain.

# Acknowledgement

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# Data Constrained WRI

Misfit:

$$J(m, u) = \|P_{\Omega}U - D_{obs}\|_F^2 + \lambda^2 \|A(m)U - Q\|_F^2$$

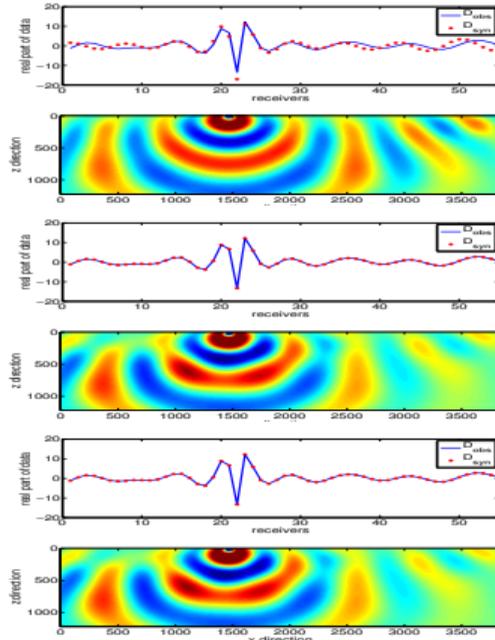
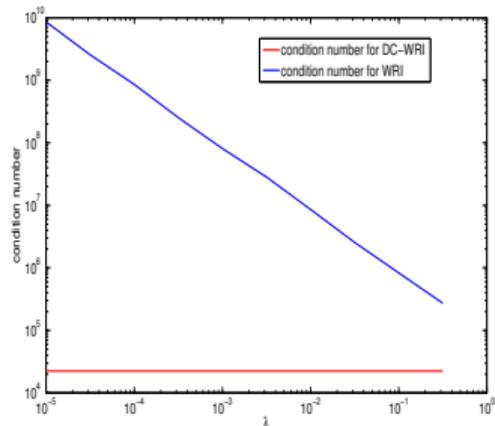
Data Augmented System (WRI)

$$\arg \min_U J(m_k, U) = \begin{bmatrix} \lambda A \\ P_{\Omega} \end{bmatrix}^{\dagger} \begin{bmatrix} Q \\ D_{obs} \end{bmatrix}$$

Data Constrained System (DC-WRI)

$$\arg \min_U J(m_k, U) = (A(m_k)P_{\Omega^c}^*)^{\dagger} \begin{bmatrix} Q \\ D_{obs} \end{bmatrix}$$

## Comparison of condition numbers



Up:  $\lambda = 10^{10}$  Middle:  $\lambda = 10^{-10}$  Down: DC-WRI