Released to public domain under Creative Commons license type BY (https://creativecommons.org/licenses/by/4.0). Copyright (c) 2018 SINBAD consortium - SLIM group @ The University of British Columbia.

## Quadratic-penalty based full-space methods for waveform inversion

**Bas Peters** SINBAD Fall Consortium meeting, 2014. Whistler, BC.



Tuesday, December 9, 14



## Waveform inversion

### Works well if initial model is good



## Waveform inversion – poor start model



3



### Wavefield reconstruction inversion [T. van Leeuwen & F.J. Herrmann, 2013]

### Less sensitive to

- starting models compared to FWI
- missing low-frequency data

Avoids cycle-skipping problems by virtue of extending the search space.

But, requires reasonable accurate solve of the augmented wave equation...



# Wavefield reconstruction inversion

Can we do better?

Maybe full-space methods?

But, at the gain of no longer insisting on accurate solves...

### Still limitations on quality of start models & missing low-frequencies

• at the "expense" of storing 2 copies of monochromatic wavefields



# Toy problem

- cross-well setting
- 4 frequencies [6-10] Hz
- 5 simultaneous sources
- 5 receivers







Tuesday, December 9, 14

7



## Toy problem

### direct solve, full space, $\lambda$ =1000



### direct solve, reduced space, $\lambda$ =1000

**direct** solution for least-squares problems





9

accurate iterative solution for least-squares problems





inaccurate iterative solution for least-squares problems



## Toy problem

## model errors, direct solver



### model errors





### Tuesday, December 9, 14







# Toy problem

### Inexact iterative linear system solves:

- full-space method not very sensitive
- WRI & FWI quite sensitive

olves: ensitive



# Full-space vs reduced-space methods **Bottom line**

reduced-space: solve for the fields

full-space:

- update the medium parameters
- update fields & medium parameters



# Full-space vs reduced-space methods **Bottom line**

reduced-space: solve for the fields

full-space:

- update the medium parameters
- update fields & medium parameters





# Full-space vs reduced-space methods **Bottom line**

reduced-space: solve for the fields

full-space: update fields & medium parameters ← joint updating





## Full-space vs reduced-space methods

FWI & WRI are in the reduced-space class –i.e., wave-equations are solved Full-space is commonly used in a Lagrangian setting. Because of memory requirements, rarely used in (academic) geophysics. [EM: E. Haber et al., 2004 ; Seismic: M. J. Grothe et al., 2011]



### Problem formulation:

$$\min_{\mathbf{m},\mathbf{u}} \frac{1}{2} \|\mathbf{P}\mathbf{u} - \mathbf{d}\|_2^2 \quad \text{s.t.}$$

### $\mathbf{H}(\mathbf{m})\mathbf{u} = \mathbf{q}$



### Quadratic penalty form (WRI):

# $\phi(\mathbf{m}, \mathbf{u}, \lambda) = \frac{1}{2} \| \mathbf{P} \mathbf{u} \|$

$$-\mathbf{d}\|_{2}^{2} + rac{\lambda^{2}}{2}\|\mathbf{H}(\mathbf{m})\mathbf{u} - \mathbf{q}\|_{2}^{2}$$



### Quadratic penalty form (WRI):









### Newton's method:



# $\begin{pmatrix} \mathbf{P}^*\mathbf{P} + \lambda^2 \mathbf{H}^*\mathbf{H} & \nabla_{\mathbf{h}\mathbf{m}}\phi \\ \nabla_{\mathbf{h}\mathbf{m}}\phi & \lambda^2 \mathbf{G}_{\mathbf{m}}^*\mathbf{G}_{\mathbf{m}} \end{pmatrix} \begin{pmatrix} \delta_{\mathbf{u}} \\ \delta_{\mathbf{m}} \end{pmatrix} = -\begin{pmatrix} \mathbf{P}^*(\mathbf{P}\mathbf{u} - \mathbf{d}) + \lambda^2 \mathbf{H}^*(\mathbf{H}\mathbf{u} - \mathbf{q}) \\ \lambda^2 \mathbf{G}_{\mathbf{m}}^*(\mathbf{H}\mathbf{u} - \mathbf{q}) \end{pmatrix}$



### Approximate Hessian:

# $\begin{pmatrix} \mathbf{P}^*\mathbf{P} + \lambda^2 \mathbf{H}^*\mathbf{H} & 0\\ 0 & \lambda^2 \mathbf{G}_{\mathbf{m}}^*\mathbf{G}_{\mathbf{m}} \end{pmatrix} \begin{pmatrix} \delta_{\mathbf{u}}\\ \delta_{\mathbf{m}} \end{pmatrix} = -\begin{pmatrix} \mathbf{P}^*(\mathbf{P}\mathbf{u} - \mathbf{d}) + \lambda^2 \mathbf{H}^*(\mathbf{H}\mathbf{u} - \mathbf{q})\\ \lambda^2 \mathbf{G}_{\mathbf{m}}^*(\mathbf{H}\mathbf{u} - \mathbf{q}) \end{pmatrix}$



### Approximate Hessian:

# $\begin{pmatrix} \mathbf{P}^*\mathbf{P} + \lambda^2 \mathbf{H}^*\mathbf{H} & 0\\ 0 & \lambda^2 \mathbf{G}_{\mathbf{m}}^*\mathbf{G}_{\mathbf{m}} \end{pmatrix} \begin{pmatrix} \delta_{\mathbf{u}}\\ \delta_{\mathbf{m}} \end{pmatrix} = - \begin{pmatrix} \mathbf{P}^*(\mathbf{P}\mathbf{u} - \mathbf{d}) + \lambda^2 \mathbf{H}^*(\mathbf{H}\mathbf{u} - \mathbf{q})\\ \lambda^2 \mathbf{G}_{\mathbf{m}}^*(\mathbf{H}\mathbf{u} - \mathbf{q}) \end{pmatrix}$

Can be solved inexactly (cheap)!



# Algorithm

- 0. construct initial guess **m** for medium and  $\mathbf{u}_i$  for each field while not converged do
- 1. form Hessian and gradient // form (~free)
- 2. ignore the  $\nabla^2_{\mathbf{u},\mathbf{m}}\phi, \nabla^2_{\mathbf{m},\mathbf{u}}\phi$  blocks // approximate
- 3. find  $\delta \mathbf{m}$  & each  $\delta \mathbf{u}_i$  in parallel // solve
- find steplength  $\alpha$  using linesearch // evaluate (~free) 4.
- 5.  $\mathbf{m} = \mathbf{m} + \alpha \delta \mathbf{m} \& \mathbf{u} = \mathbf{u} + \alpha \delta \mathbf{u}$  // update model and fields end



# Algorithm

- 0. construct initial guess  $\mathbf{m}$  for medium and  $\mathbf{u}_i$  for each field while not converged do
- 1. form Hessian and gradient
- 2. ignore the  $\nabla^2_{\mathbf{u},\mathbf{m}}\phi, \nabla^2_{\mathbf{m},\mathbf{u}}\phi$  blocks //
- 3. find  $\delta \mathbf{m}$  & each  $\delta \mathbf{u}_i$  in parallel
- find steplength  $\alpha$  using linesearch 4.
- 5.  $\mathbf{m} = \mathbf{m} + \alpha \delta \mathbf{m} \& \mathbf{u} = \mathbf{u} + \alpha \delta \mathbf{u}$  // update model and f end

// form (~free)	
// approximate // solve ←	medium and field updated are independent
// undate model and fie	lds



# Algorithm

0. construct initial guess **m** for medium and  $\mathbf{u}_i$  for each field while not converged do 1. form Hessian and gradient // form (~free) 2. ignore the  $\nabla^2_{\mathbf{u},\mathbf{m}}\phi, \nabla^2_{\mathbf{m},\mathbf{u}}\phi$  blocks // approximate 3. find  $\delta \mathbf{m}$  & each  $\delta \mathbf{u}_i$  in parallel // solve find steplength  $\alpha$  using linesearch // evaluate (~free) 4. 5.  $\mathbf{m} = \mathbf{m} + \alpha \delta \mathbf{m} \& \mathbf{u} = \mathbf{u} + \alpha \delta \mathbf{u}$  // update model and fields

end

depend on the updated model and updated fields



## Full-space vs reduced-space methods

	FWI & WRI
Hessian	dense
Hessian	solve "PDE's'
gradient	solve "PDE's'
memory	2 fields per parallel
function evaluation	solve "PDE's'



~free = sparse matrix-vector products







## Inexact full-space vs inexact reduced-space

### FWI & WRI:

- error in objective function value
- error in gradient
- error in Hessian



error in medium parameter update



# Inexact full-space vs inexact reduced-space

### FWI & WRI:

- error in objective function value
- error in gradient
- error in Hessian



### Full-space from WRI:

- objective function value always exact
- gradient always exact  $\longrightarrow$  0 iterations  $\rightarrow$  gradient descent many iterations  $\rightarrow$  Newton's method
- Hessian always exact

rror in medium parameter update



## Toy examples

### Using a direct solver:

- approximation
- need to test on more realistic models.

### • similar reconstruction quality compared to WRI+diagonal Hessian



# Memory requirements

save all fields for all frequencies & sources can be distributed over multiple nodes

### Feasible? Need

- parallel computing
- simultaneous sources
- small frequency batches



# **Computational cost**

Independent update computation No communication between compute nodes to compute updates

1 iteration of WRI  $\approx$  1 iteration of full-space Newton type quadratic penalty



## Conclusions

## Constructed a full-space method which:

- updates fields & medium parameters simultaneously
- computational cost ≈ reduced-space methods
- similar parallelism as in FWI & WRI
- many properties are different from FWI & WRI
- promising results with iterative solvers
- con: need to store all fields

but, less storage needed compared to Lagrangian full-space methods



# Current & future work

Test on more realistic examples. Evaluate reconstruction quality compared to WRI. Maximize benefit from inexact update computation.



## Acknowledgements



This work was in part financially supported by the Natural Sciences and Engineering Research Council of Canada Discovery Grant (22R81254) and the Collaborative Research and Development Grant DNOISE II (375142-08). This research was carried out as part of the SINBAD II project with support from the following organizations: BG Group, BGP, CGG, Chevron, ConocoPhillips, ION, Petrobras, PGS, Statoil, Total SA, Sub Salt Solutions, WesternGeco, and Woodside.

