

Rank Minimization via Alternating Optimization

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Motivation

Acquisition challenges

- highly subsampled data

Data exhibits *low-rank* structure

- SVD-free matrix completion

Benefits of **Alternating Optimization** procedures

- problems become tractable

Outline

Alternating Optimization

Nuclear Norm Minimization

- factorized formulation
- can we benefit from alternating optimization?

Motivation: Variable Decomposition

$$\boxed{x} = \boxed{x_1} \cdot \boxed{x_2} \cdot \dots \cdot \boxed{x_s}$$

Benefits:

- memory efficiency
- computational efficiency

Motivation: Variable Decomposition

$$\boxed{x} = \boxed{x_1} \cdot \boxed{x_2} \cdot \dots \cdot \boxed{x_s}$$

Benefits:

- memory efficiency
- computational efficiency
- flexibility

Xu, Yin. “A Block Coordinate Descent Method for Regularized Multiconvex Optimization with Applications to Nonnegative Tensor Factorization and Completion”. SIAM 2013

Alternating Optimization

Want to solve:

$$\min_{x \in \mathcal{X}} f(x_1, x_2, \dots, x_s) + \sum_{i=1}^s r_i(x_i)$$

f is multi-convex

each r_i is convex

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Alternating Optimization

Algorithm :

1. Initialization: choose initial point $(x_1^0, x_2^0, \dots, x_s^0)$

2. for $k = 1, 2, \dots, T$ do

3. for $i = 1, 2, \dots, s$ do

4. $x_i^k \leftarrow \arg \min_{x_i \in \mathcal{X}_i^k} f_i^k(x_i) + r_i(x_i)$

5. end for

6. end for

Output: $(x_1^T, x_2^T, \dots, x_s^T)$

Alternate optimization
between factors

Conclusion of Alternating Minimization

Problem becomes tractable

- solve main problem via simpler subproblems

Computationally efficient

- “shown to be superior than other procedures in both speed and quality” - [Xu, Yin](#)

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Matrix Factorization

$$\boxed{\mathbf{X} \in \mathbb{R}^{n \times m}} = \begin{array}{c} \boxed{\phantom{\mathbf{L}}} \\ \mathbf{L} \in \mathbb{R}^{n \times r} \\ \boxed{\phantom{\mathbf{L}}} \end{array} \times \boxed{\mathbf{R}^H \in \mathbb{R}^{r \times m}}$$

$$\mathbf{X} = \mathbf{L}\mathbf{R}^H$$

Matrix Factorization

$$\mathbf{X} \in \mathbb{R}^{n \times m}$$

$$= \begin{matrix} \boxed{\phantom{\mathbf{L}}} \\ \mathbf{L} \in \mathbb{R}^{n \times r} \\ \boxed{\phantom{\mathbf{L}}} \end{matrix} \times \begin{matrix} \boxed{\phantom{\mathbf{R}^H}} \\ \mathbf{R}^H \in \mathbb{R}^{r \times m} \\ \boxed{\phantom{\mathbf{R}^H}} \end{matrix}$$

Choose factorization parameter $r \ll \min(n, m)$

$$\mathbf{X} = \mathbf{L}\mathbf{R}^H$$

[Rennie and Srebro 2005]

Nuclear Norm Minimization- Factorized Form

$$\mathbf{X} = \mathbf{L}\mathbf{R}^H$$

- ▶ Nuclear norm is bounded by

$$\|\mathbf{X}\|_* \leq \frac{1}{2} (\|\mathbf{L}\|_F^2 + \|\mathbf{R}\|_F^2)$$

where $\|\cdot\|_F^2$ is sum of squares of all entries

- ▶ choose r explicitly & avoid costly SVD's

Nuclear Norm Minimization- Factorized Form

We want to solve

$$\min_{\mathbf{L} \in \mathbb{R}^{n \times r}, \mathbf{R} \in \mathbb{R}^{m \times r}} \frac{1}{2} (\|\mathbf{L}\|_F^2 + \|\mathbf{R}\|_F^2) \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{L}\mathbf{R}^H) - \mathbf{b}\|_F^2 \leq \sigma$$

Nuclear Norm Minimization- Factorized Form

We want to solve

$$\min_{\mathbf{L} \in \mathbb{R}^{n \times r}, \mathbf{R} \in \mathbb{R}^{m \times r}} \frac{1}{2} \left(\underbrace{\|\mathbf{L}\|_F^2}_{r_1} + \underbrace{\|\mathbf{R}\|_F^2}_{r_2} \right) \quad \text{s.t.} \quad \underbrace{\|\mathcal{A}(\mathbf{L}\mathbf{R}^H) - \mathbf{b}\|_F^2}_f \leq \sigma$$

convex functions multi-convex function

Nuclear Norm Minimization- Factorized Form

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convex functions multi-convex function

Let's Alternate!

Alternating Nuclear Norm Minimization

1. Input: \mathcal{A}, \mathbf{b}
2. Initialize: \mathbf{L}^0 to be the top- r left singular vectors of \mathbf{b}
3. for $t = 0, \dots, T - 1$ do
4.
$$\mathbf{R}^{t+1} = \min_{\mathbf{R} \in \mathbb{R}^{m \times r}} \frac{1}{2} \|\mathbf{R}\|_F^2 \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{L}^t \mathbf{R}^H) - \mathbf{b}\|_F^2 \leq \sigma_t$$
5.
$$\mathbf{L}^{t+1} = \min_{\mathbf{L} \in \mathbb{R}^{n \times r}} \frac{1}{2} \|\mathbf{L}\|_F^2 \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{L}(\mathbf{R}^{t+1})^H) - \mathbf{b}\|_F^2 \leq \sigma_t$$
6. end for
7. Return $\tilde{\mathbf{X}} = \mathbf{L}^T (\mathbf{R}^T)^H$

Implementation

$$\min_{\mathbf{R} \in \mathbb{R}^{m \times r}} \frac{1}{2} \|\mathbf{R}\|_F^2 \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{L}^t \mathbf{R}^H) - \mathbf{b}\|_F^2 \leq \sigma_t$$

▶ approximately solve a series of $LASSO_\tau$ formulation

$$v(\tau) = \min_{\mathbf{R}} \|\mathcal{A}(\mathbf{L}^t \mathbf{R}^H) - \mathbf{b}\|_F^2 \quad \text{s.t.} \quad \frac{1}{2} \|\mathbf{R}\|_F^2 \leq \tau$$

where τ is the regularization parameter

Experiments: Nelson 2-D seismic line

1024 x 401 x 401 matrix

- 80% missing traces
- Factorization parameter adjusted from low to high frequency
- Jittered subsampling
- solve with SPGL1

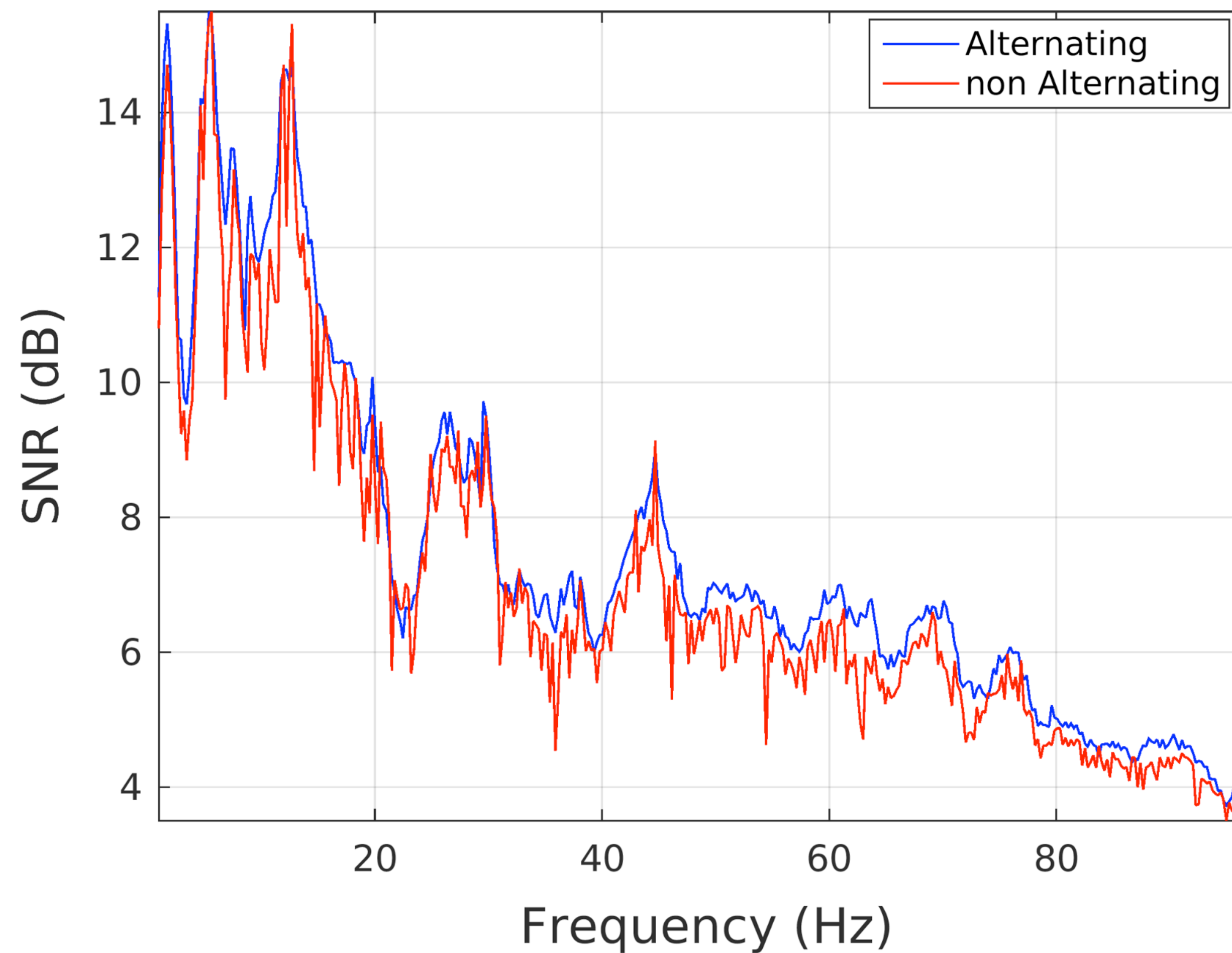
Compare: **Alternating vs Non Alternating**

- 6 alternations, 15 iterations per alternation
- 180 iterations total for both

Experiments

Average Improvement
.5 dB

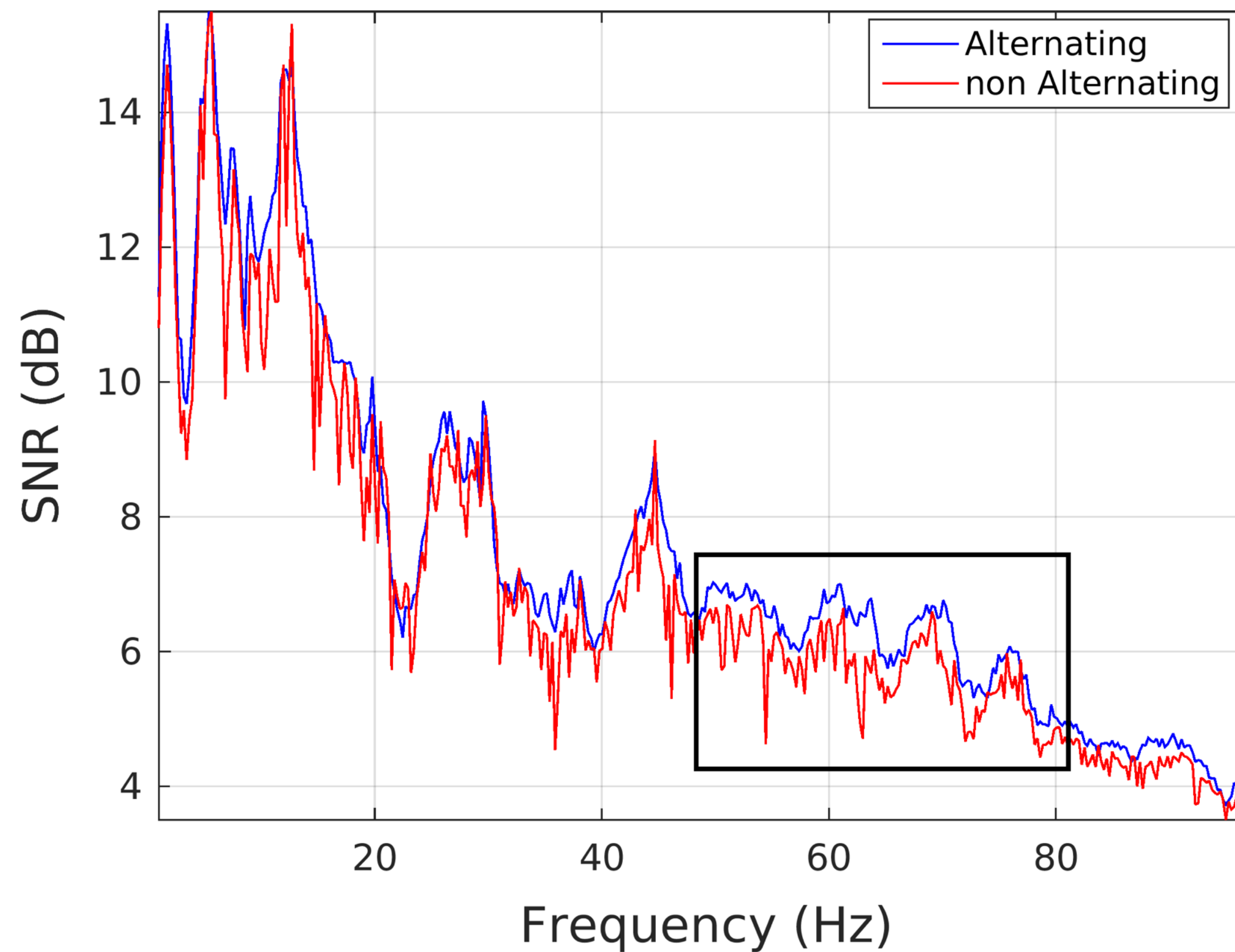
Nelson Data Set (80% Missing Traces)



Experiments

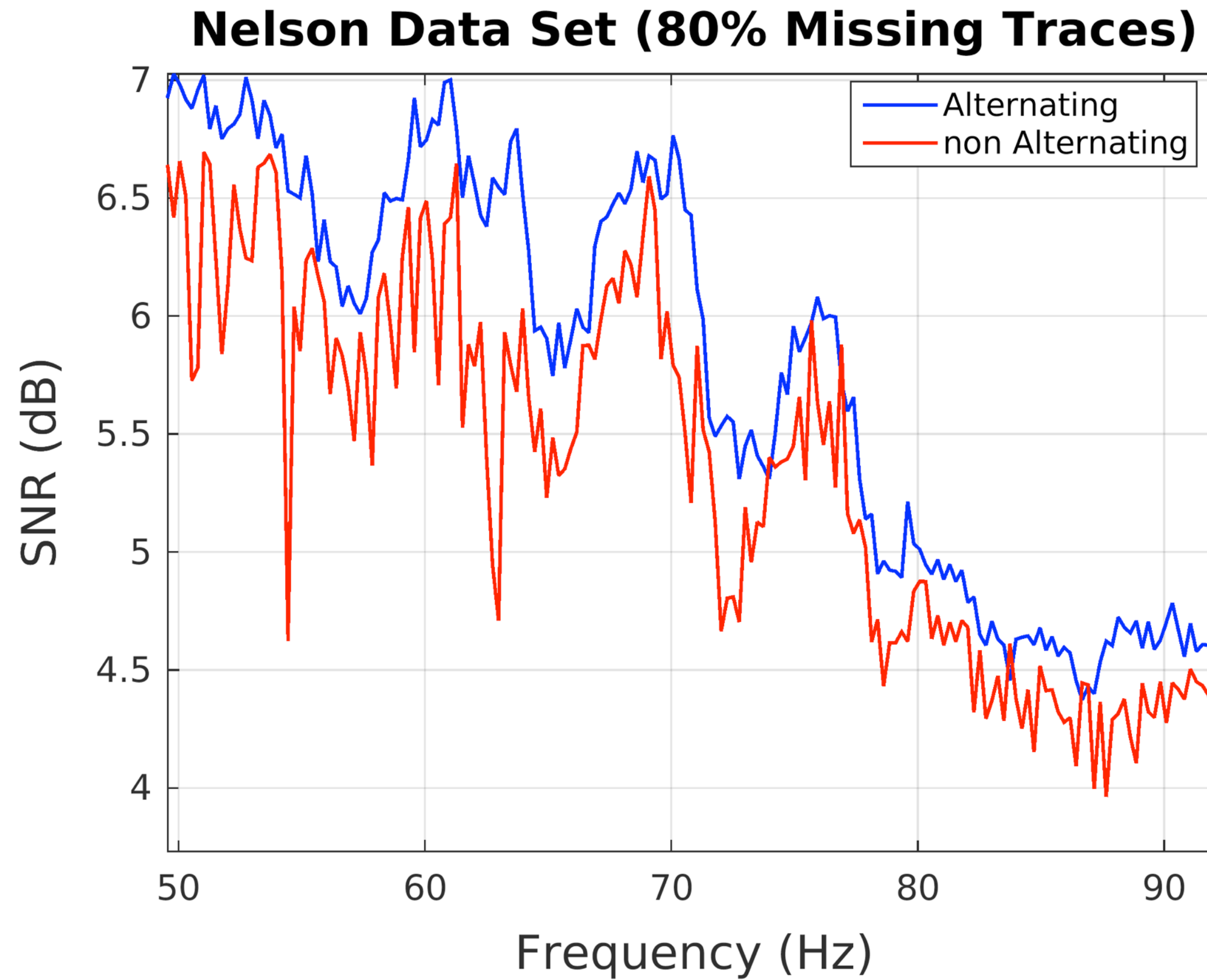
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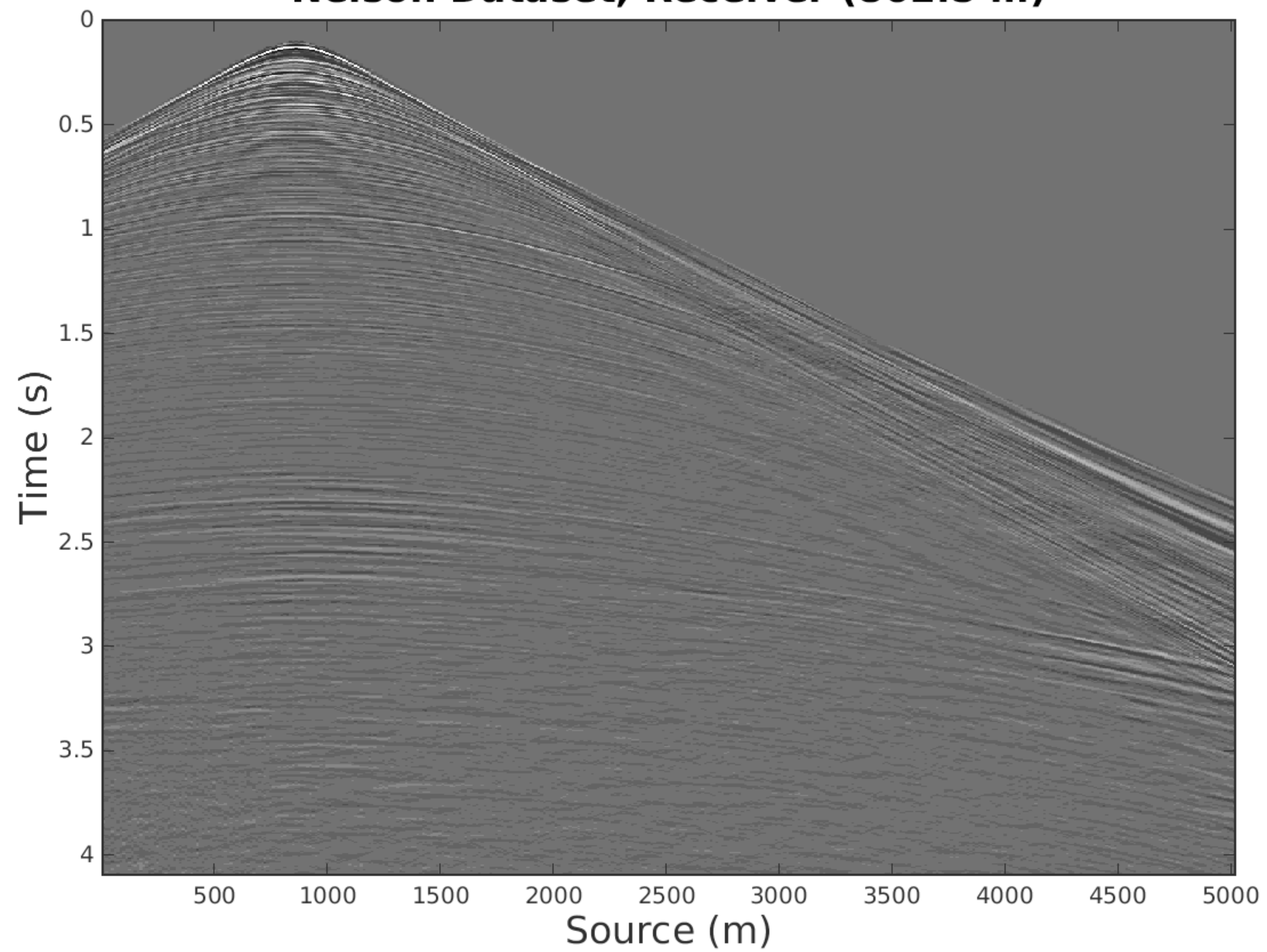


Experiments

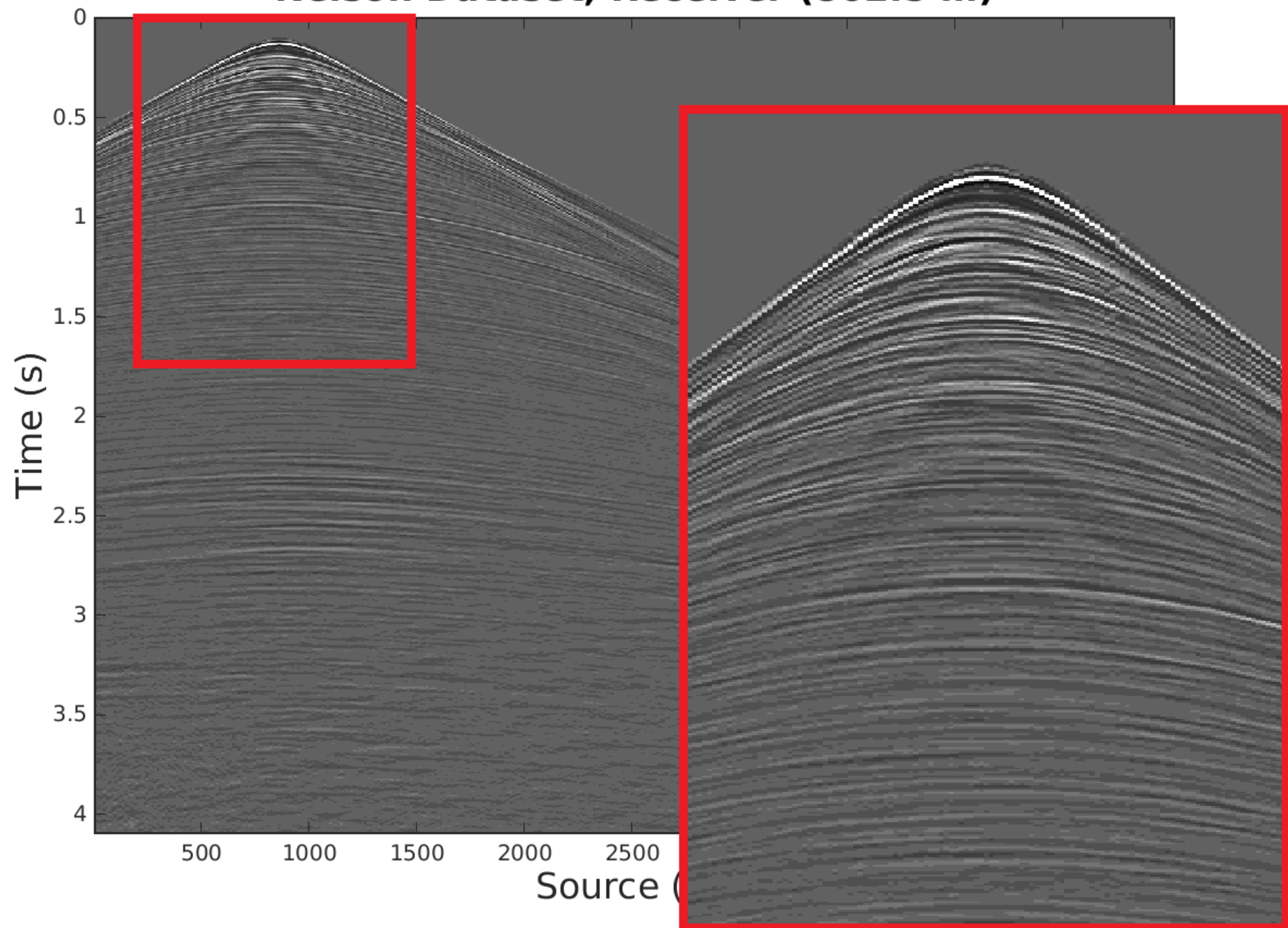
Average Improvement
.5 dB



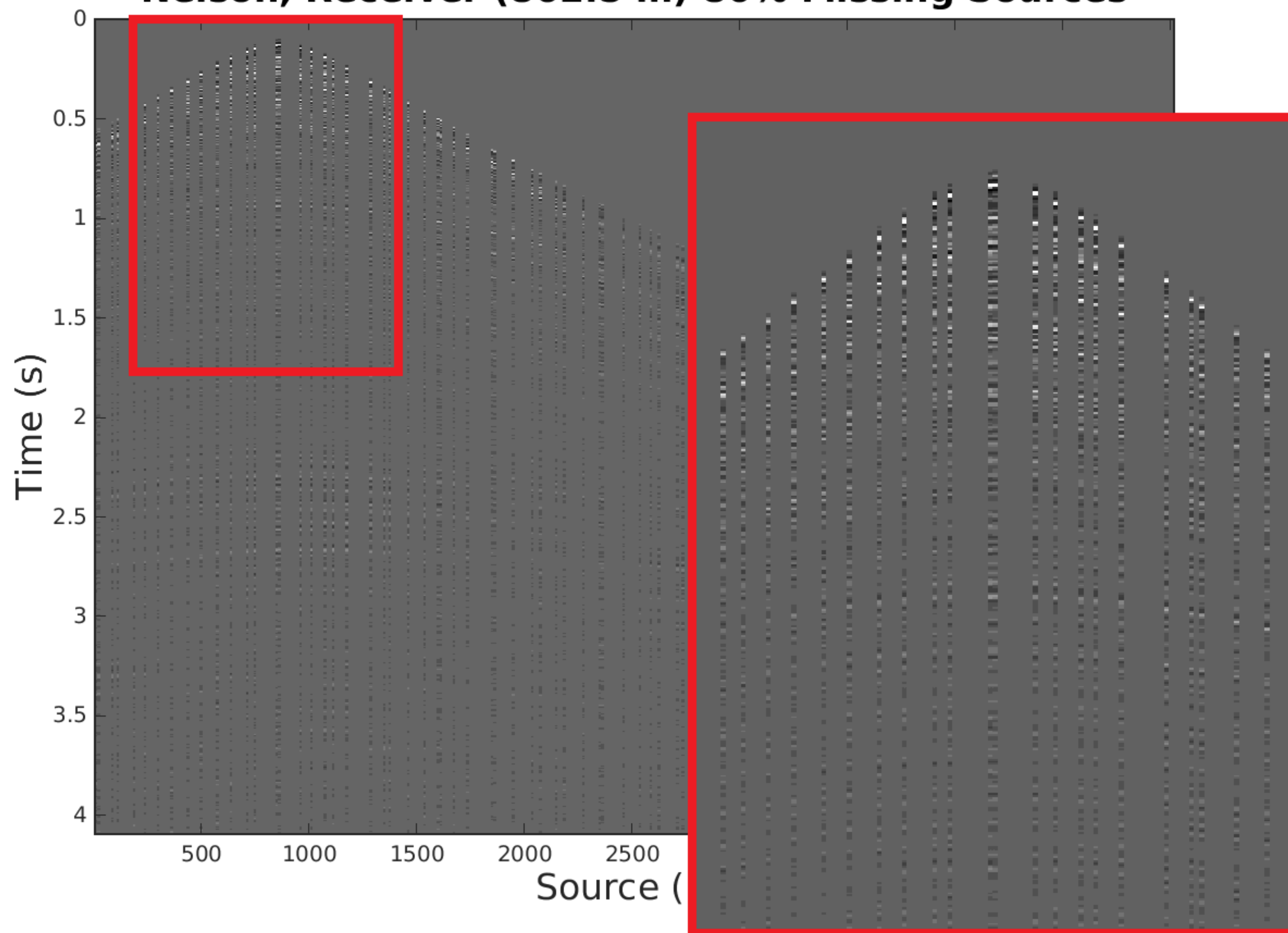
Nelson Dataset, Receiver (862.5 m)



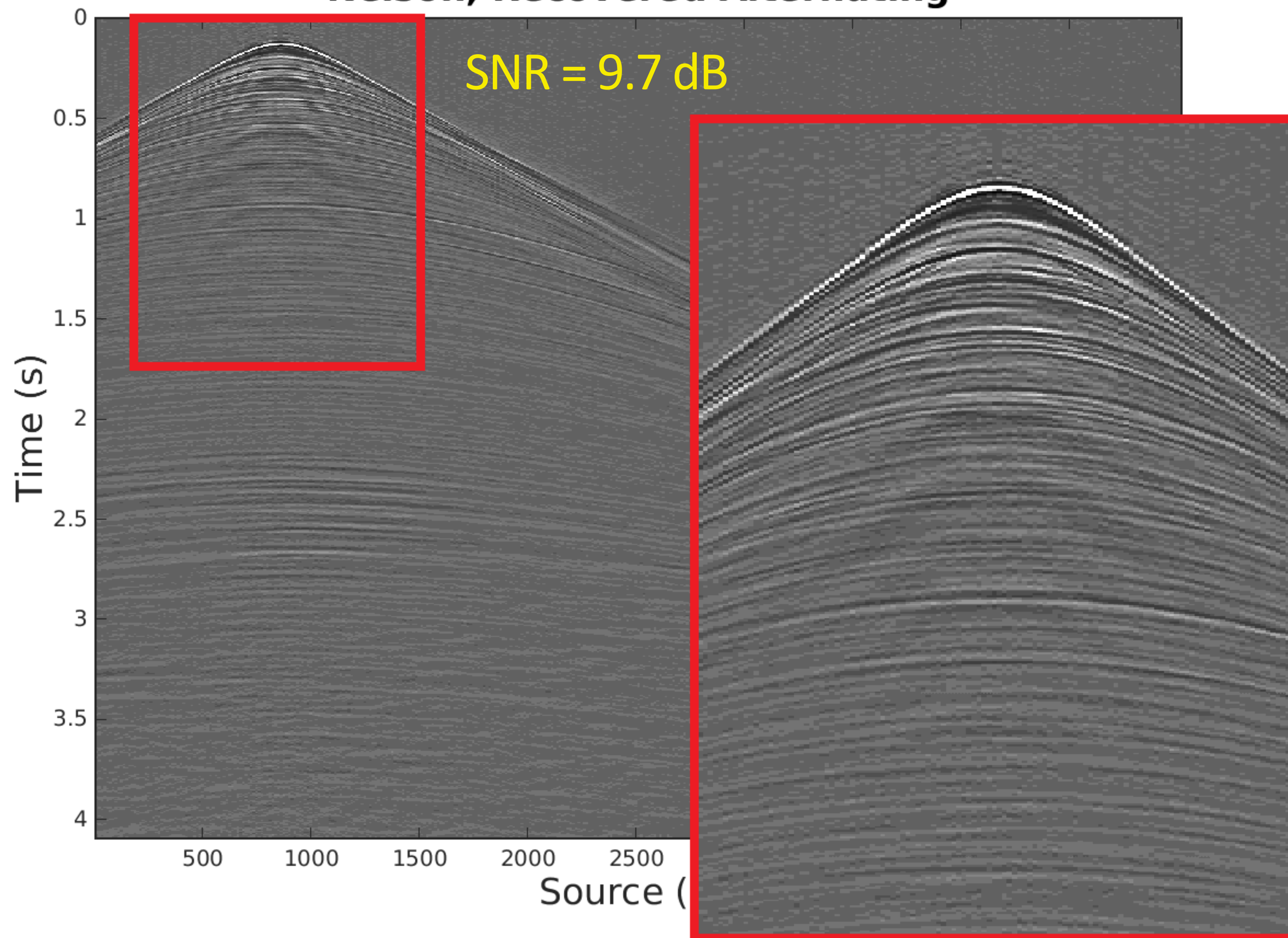
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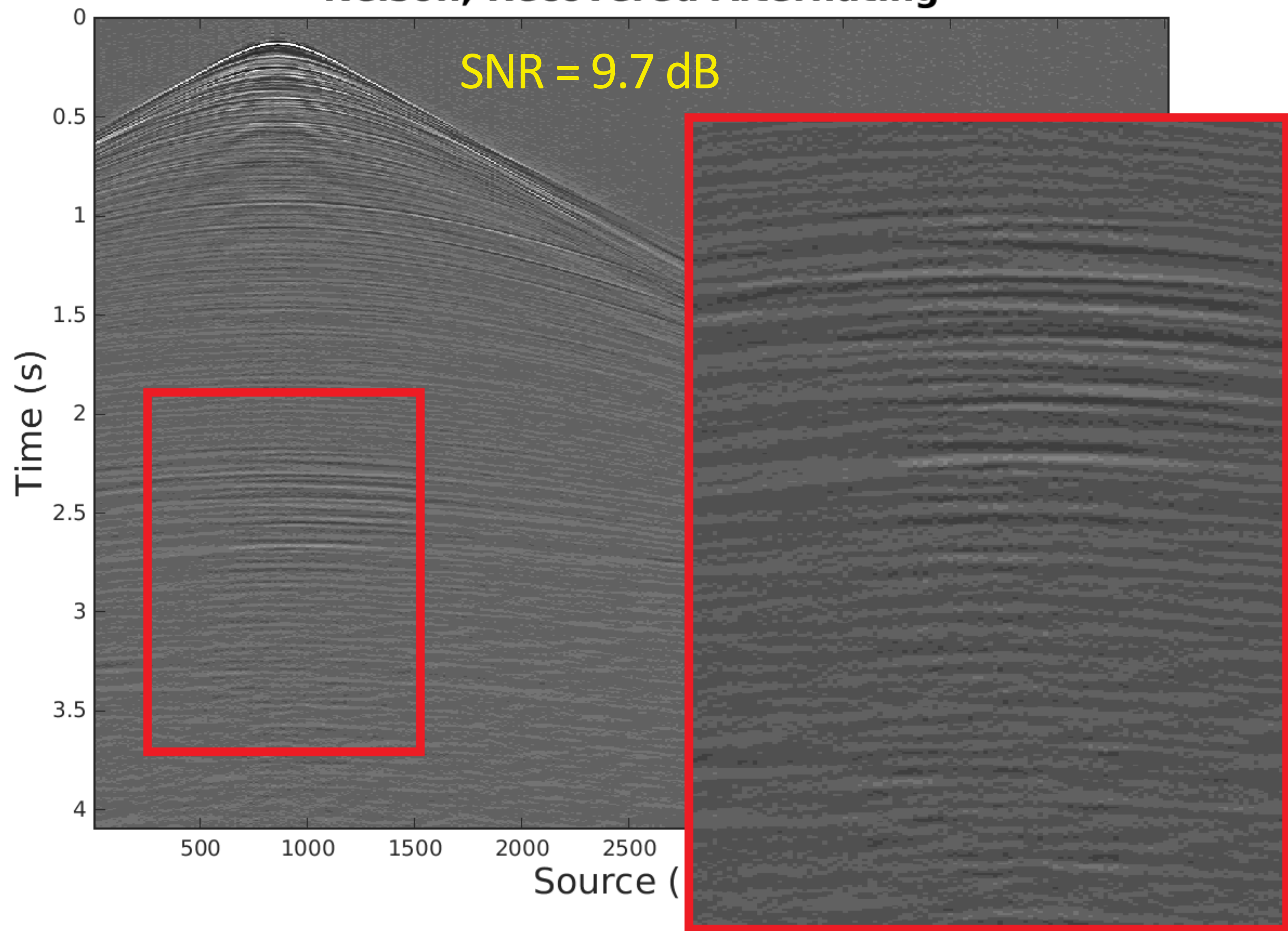
Nelson, Receiver (862.5 m) 80% Missing Sources

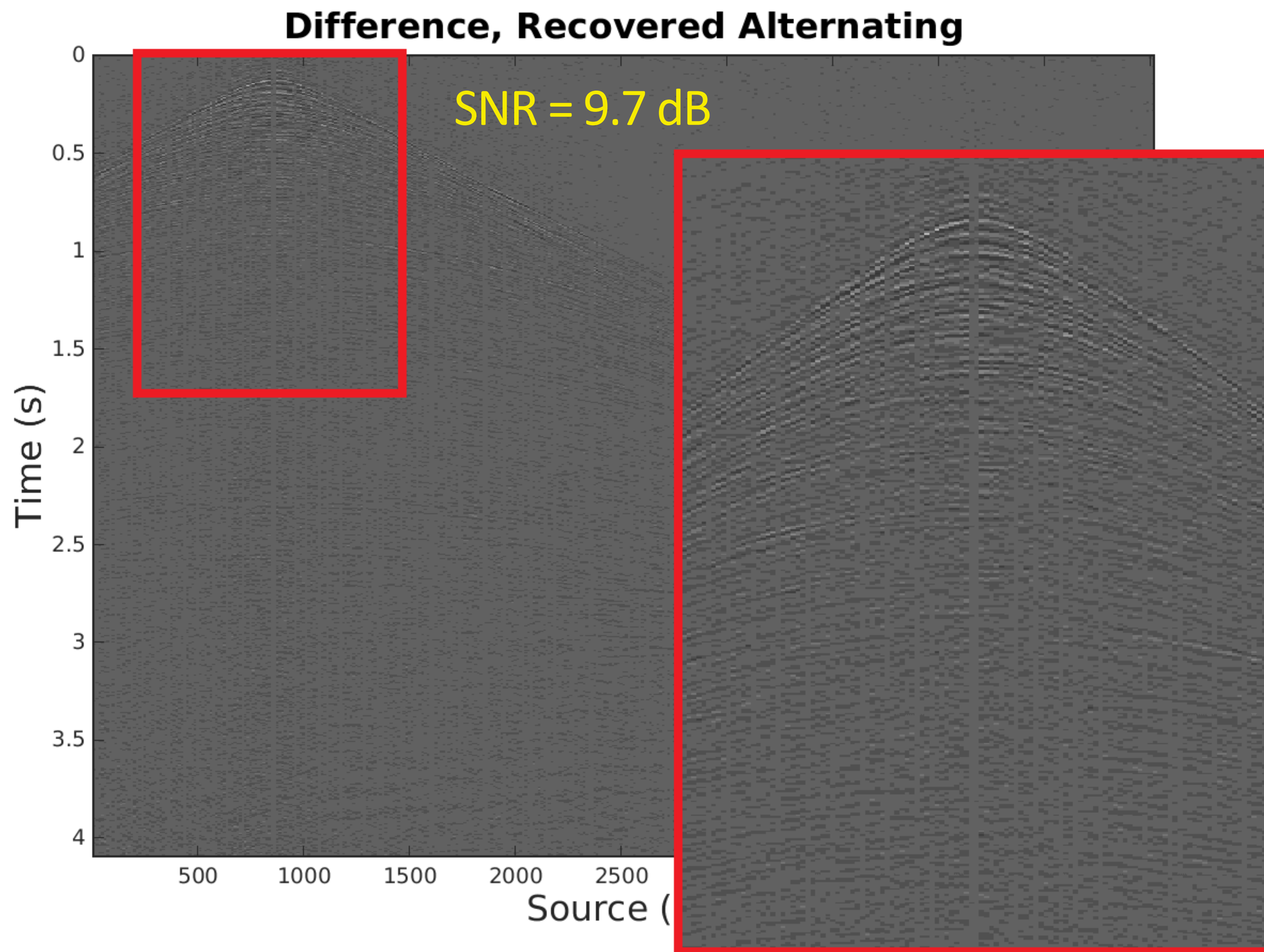


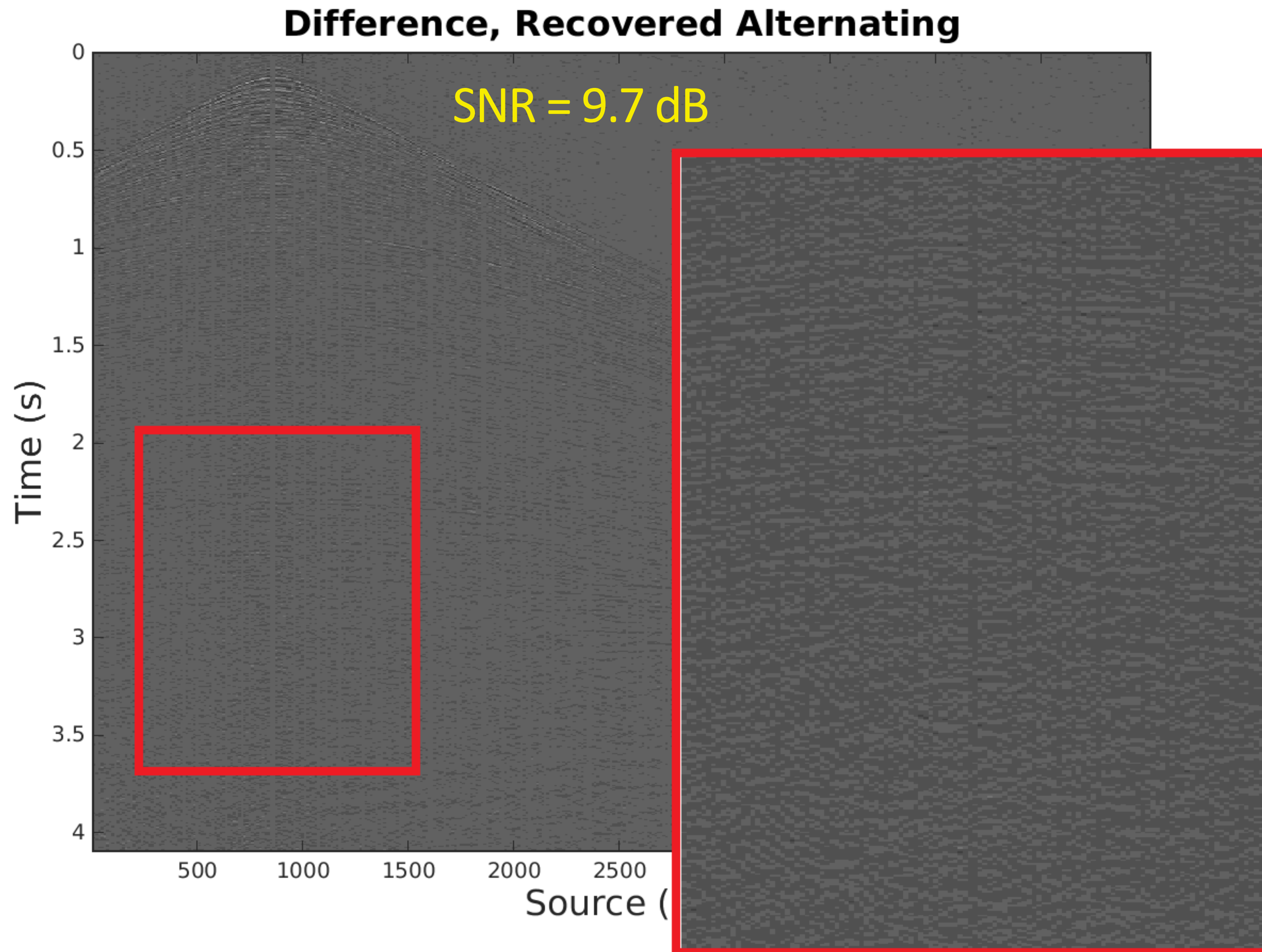
Nelson, Recovered Alternating



Nelson, Recovered Alternating







Experiments: Gulf Of Mexico 7Hz Slice

4001 x 4001 matrix (factorization parameter = 80)

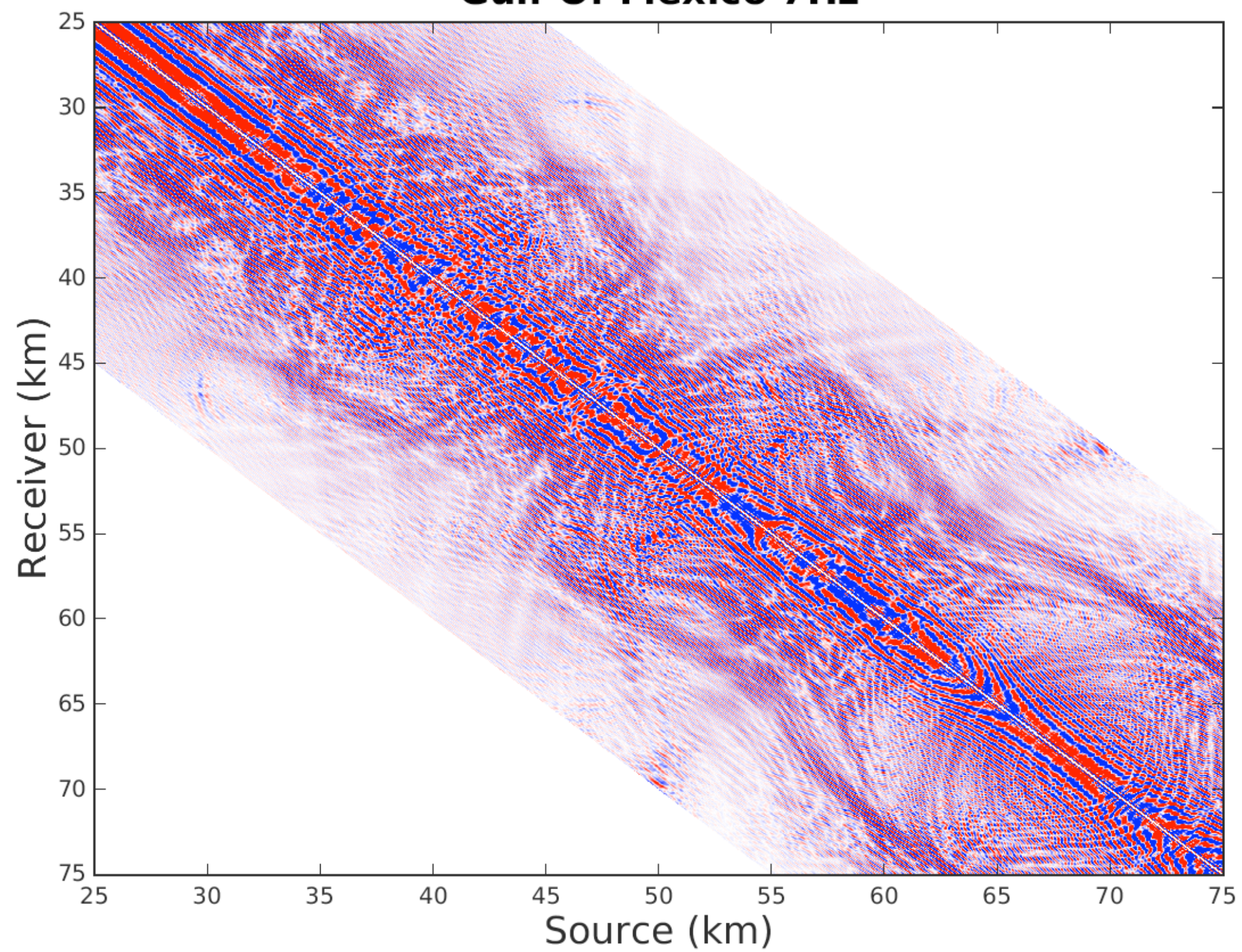
- 90% missing traces
- Jittered subsampling
- solve with SPGL1

Compare: **Alternating vs Non Alternating**

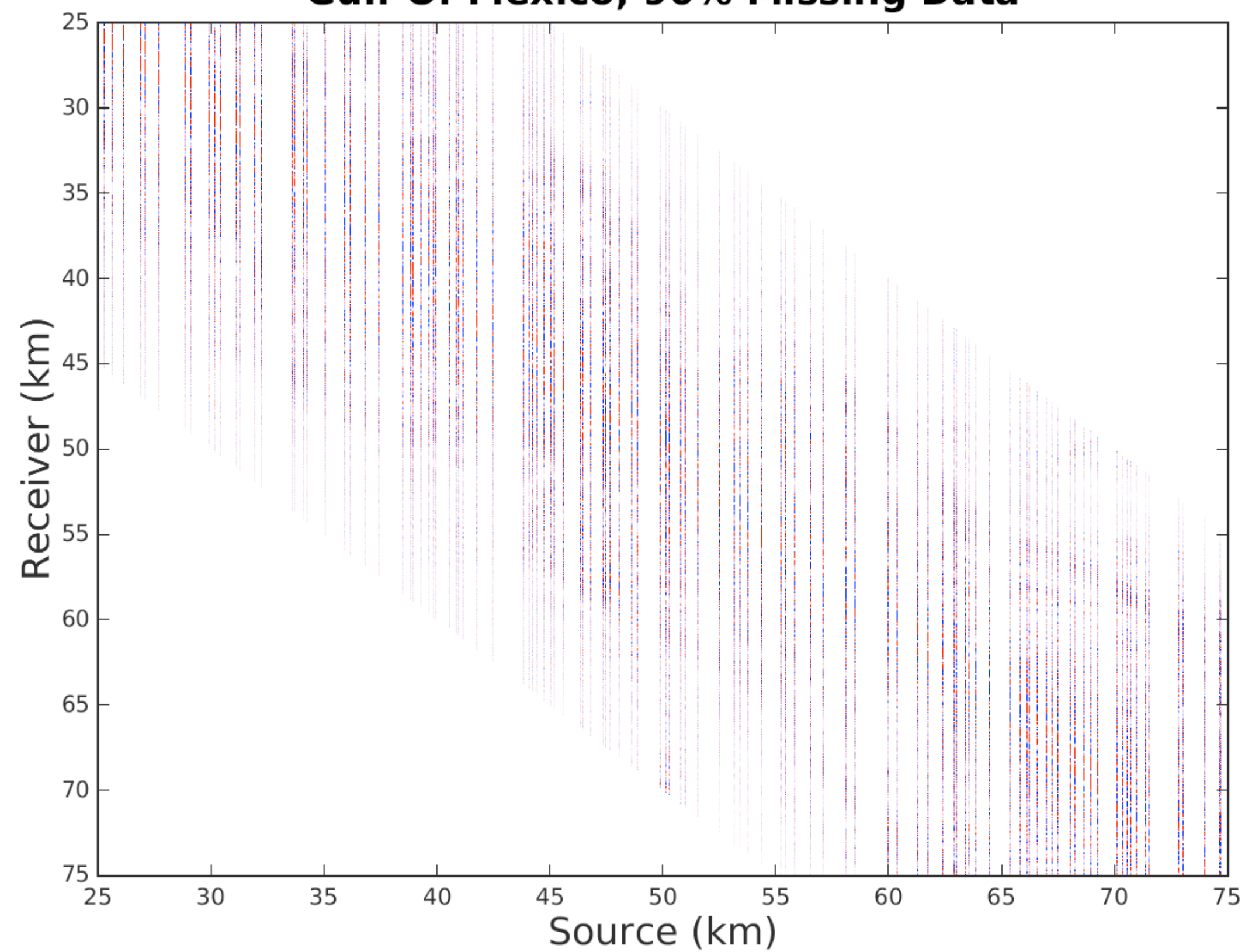
- 10 alternations, 15 iterations per alternation
- 300 iterations total for both

Experiments: Gulf Of Mexico 7Hz (90% missing)

Gulf Of Mexico 7Hz



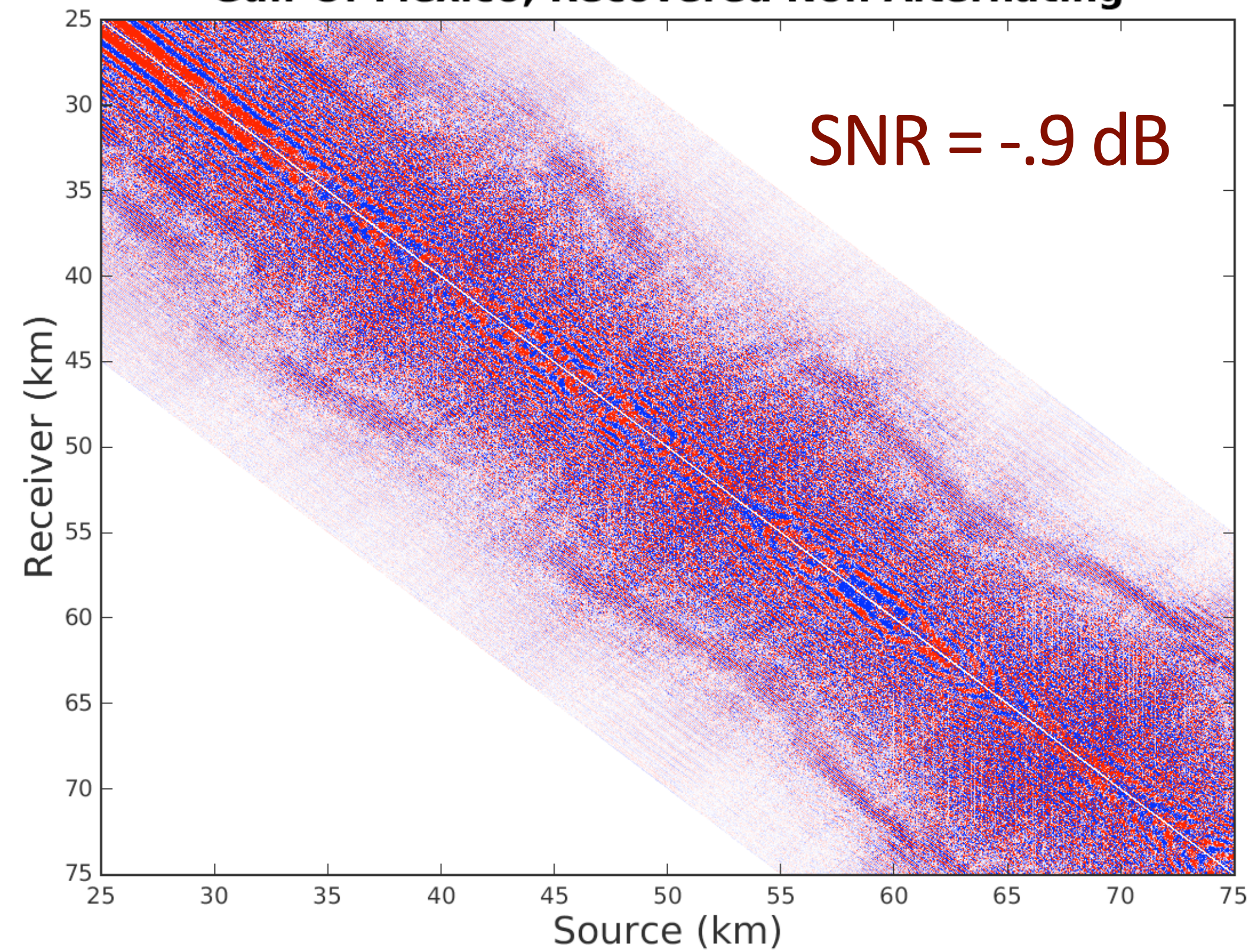
Gulf Of Mexico, 90% Missing Data



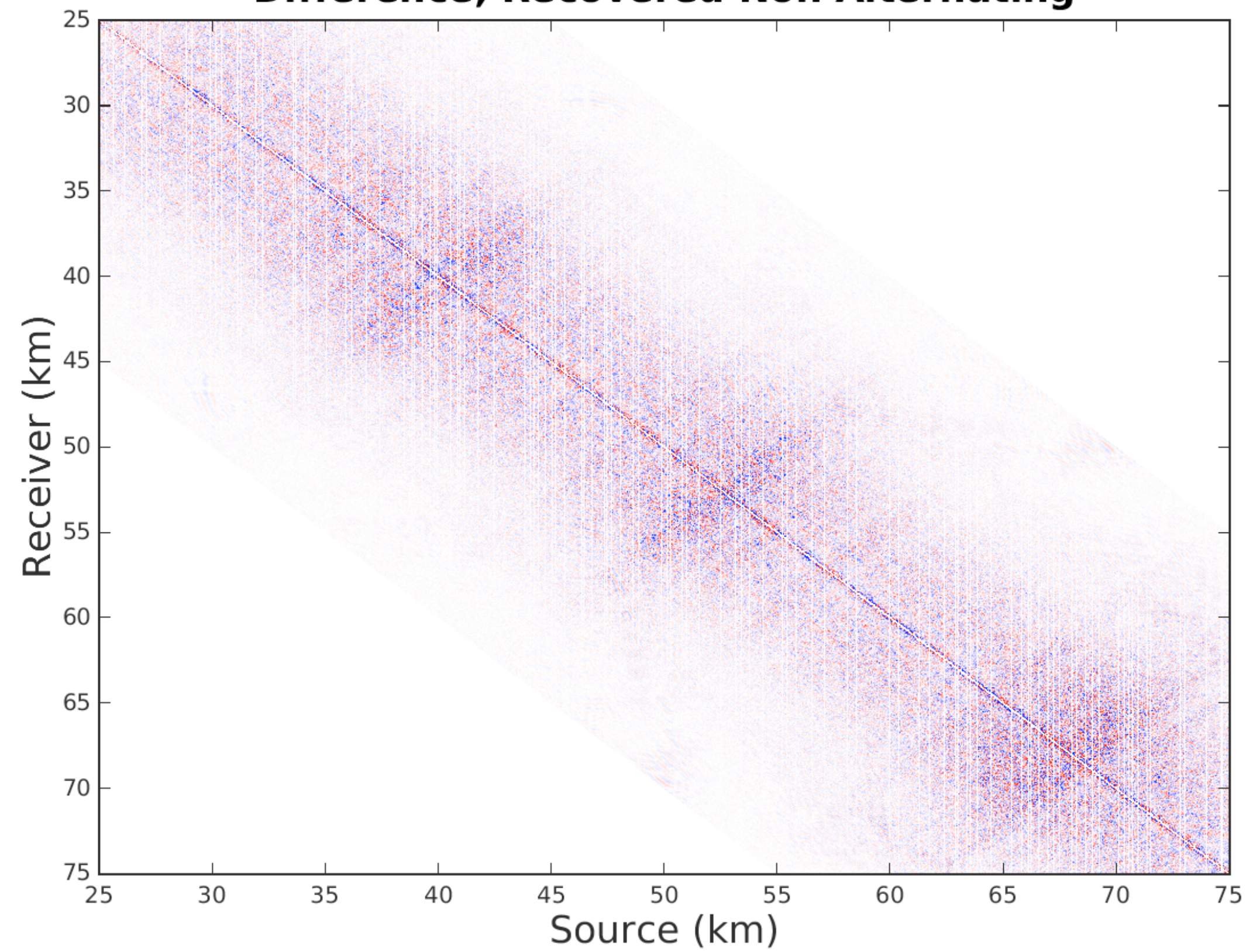
Experiments: Recovered Non Alternating

Gulf Of Mexico, Recovered Non Alternating

SNR = -0.9 dB



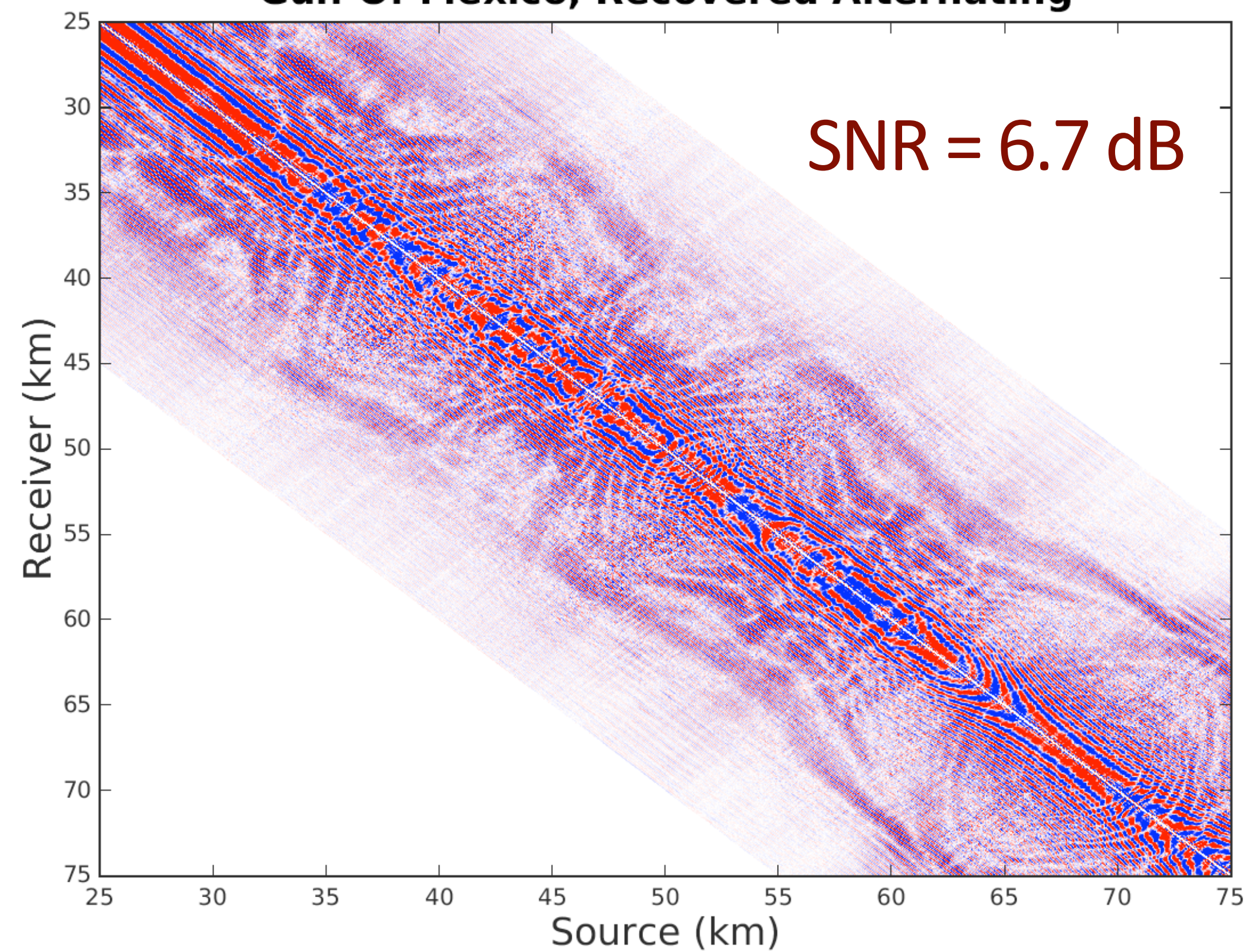
Difference, Recovered Non Alternating



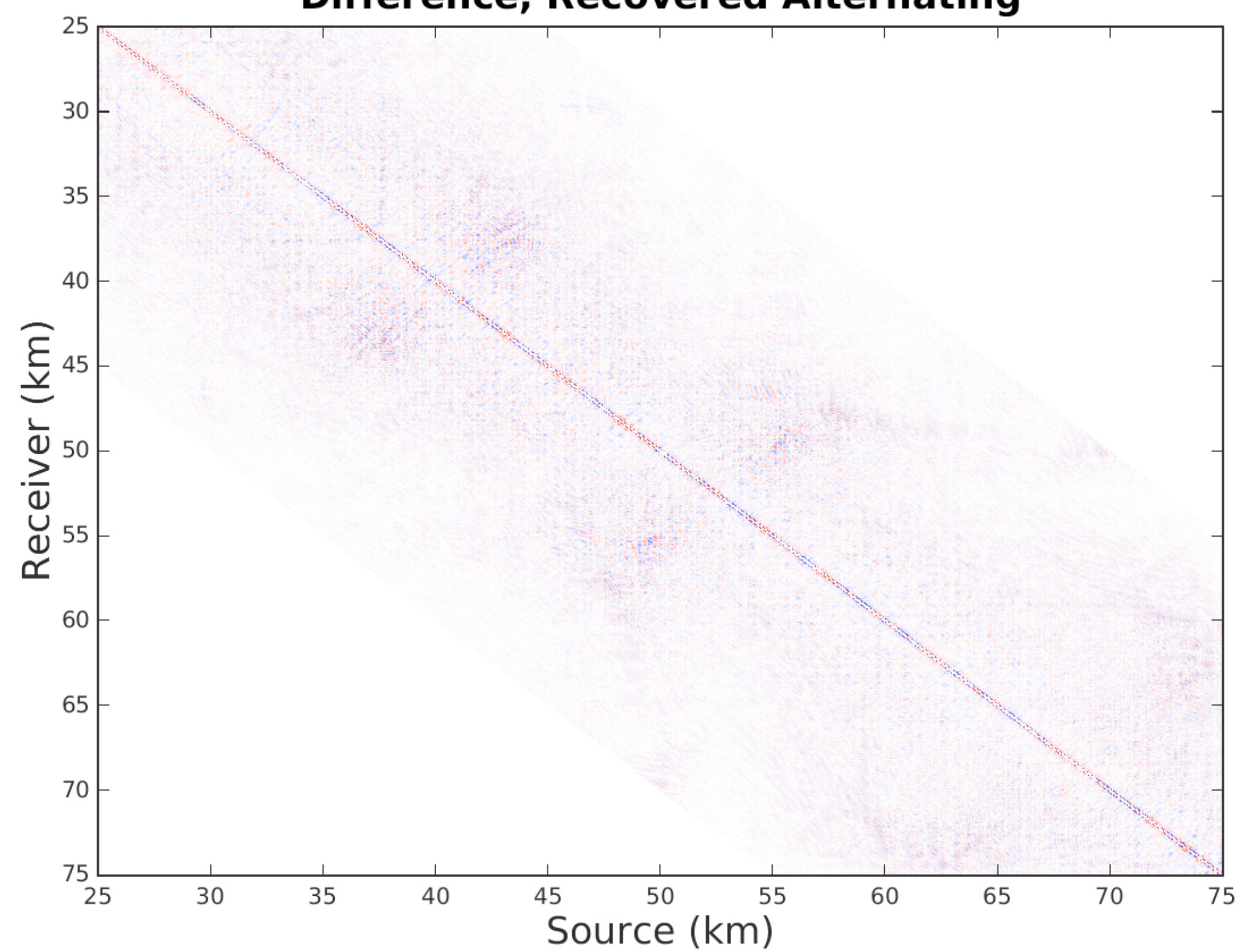
Experiments: Recovered Alternating

Gulf Of Mexico, Recovered Alternating

SNR = 6.7 dB

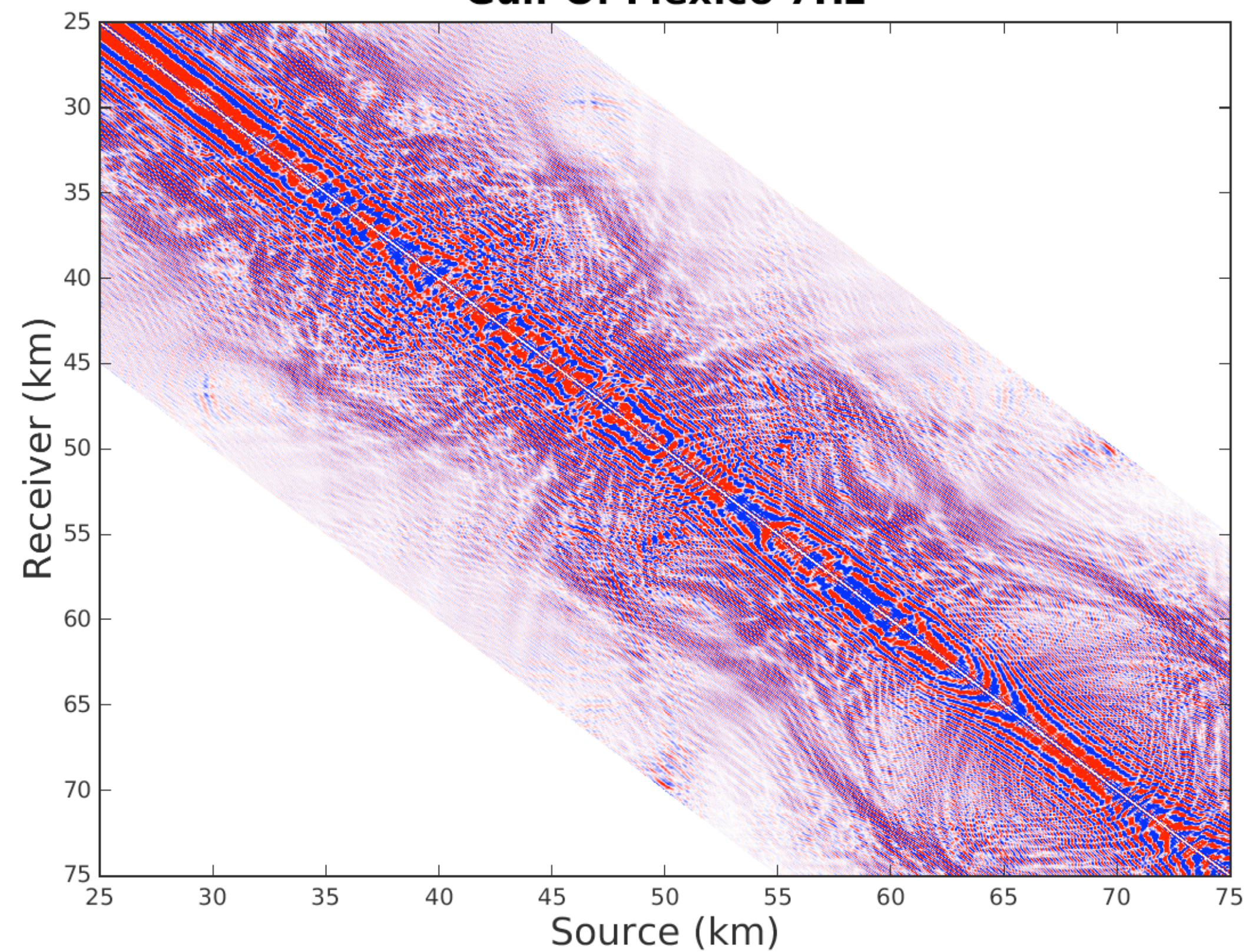


Difference, Recovered Alternating

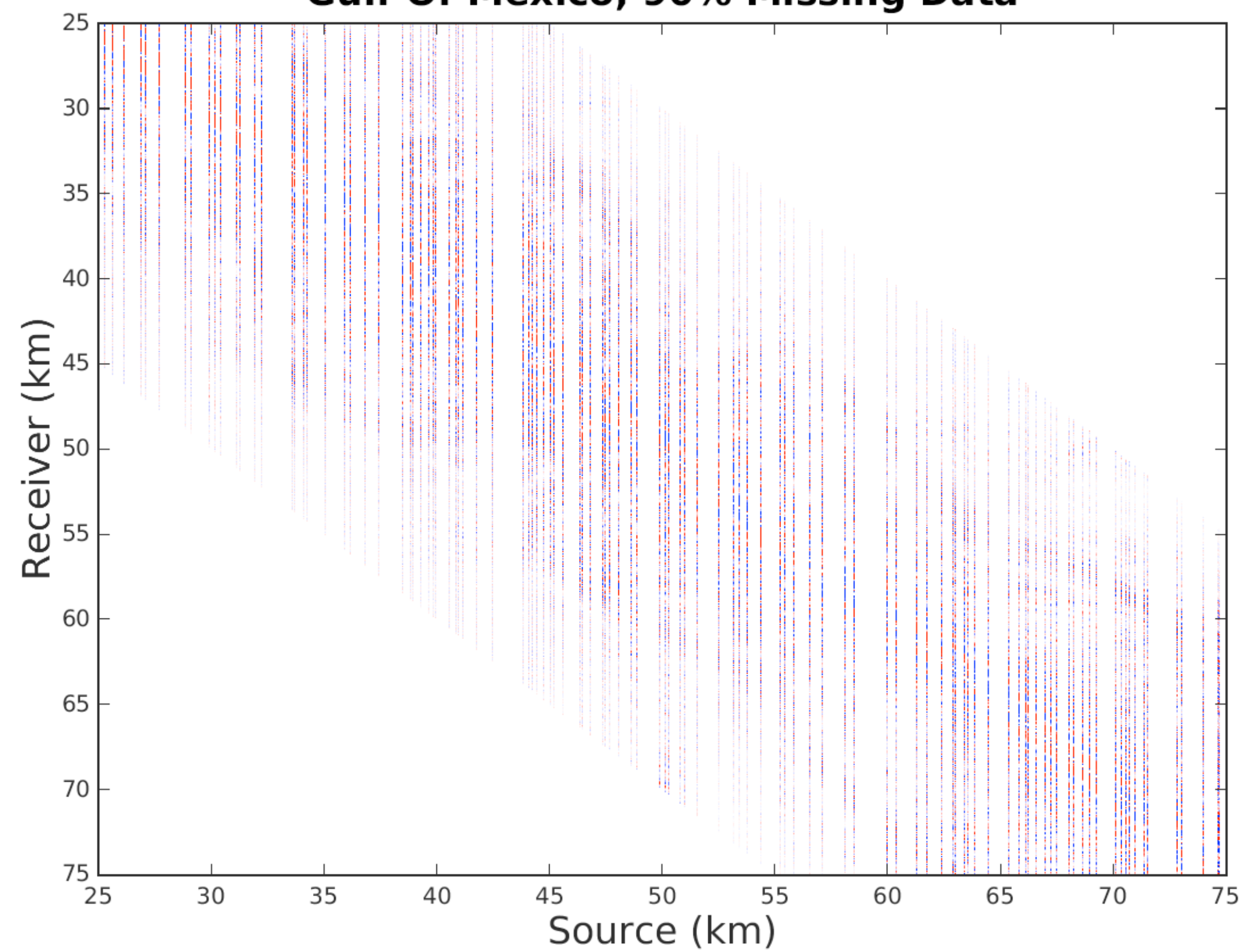


Experiments: Gulf Of Mexico 7Hz (90% missing)

Gulf Of Mexico 7Hz



Gulf Of Mexico, 90% Missing Data



Experiments: Regularization + Interpolation

Gulf Of Suez 10 hz slice - 354 x 354 matrix

- irregular data
- varying % missing sources
- Jittered subsampling

Compare: **Alternating vs Non Alternating**

- 6 alternations, 15 iterations per alternation
- 180 iterations total for both

Experiments: Regularization + Interpolation

solve:

$$\min_{\mathbf{L} \in \mathbb{R}^{n \times r}, \mathbf{R} \in \mathbb{R}^{m \times r}} \frac{1}{2} (\|\mathbf{L}\|_F^2 + \|\mathbf{R}\|_F^2) \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{L}\mathbf{R}^H) - b\|_F^2 \leq \sigma$$

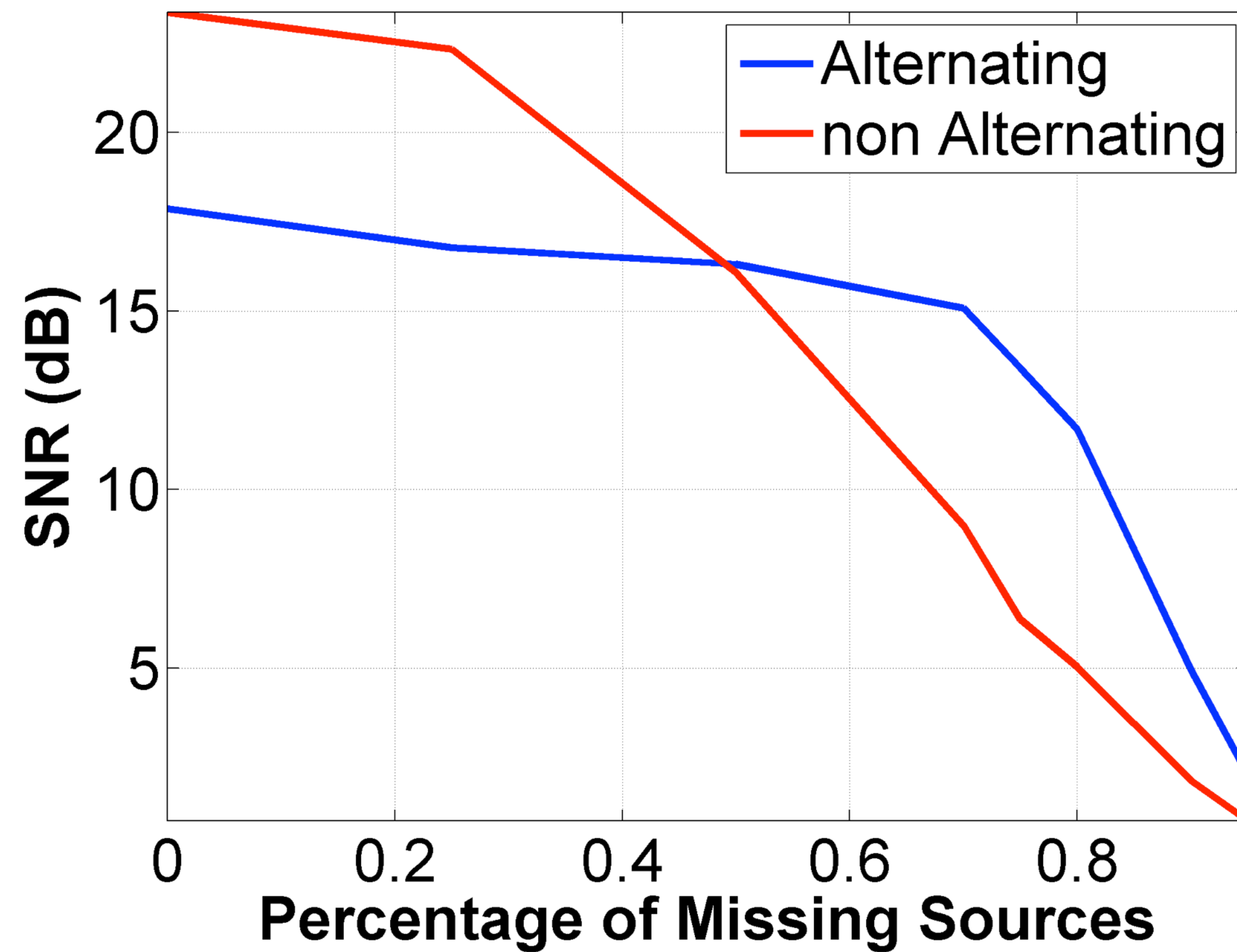
$$\mathcal{A} = \mathbf{R}\mathbf{M}\mathbf{N}\mathcal{S}^H$$

where

- \mathbf{R} : restriction operator
- \mathbf{M} : measurement operator
- \mathbf{N} : regularization operator
- \mathcal{S}^H : transform operator

Experiments: Regularization + Interpolation

Data Regularization + Interpolation



Computational Cost

with and without SVD

Percentage missing sources		50.0%		75.0%	
		σ	0.1	0.1	0.1
Matrix completion w/ SVD	SNR (dB)	17.3	18.3	11.6	11.5
	time (sec)	812	937	790	765
Matrix completion w/o SVD	SNR (dB)	17.6	18.4	12.6	13.3
	time (sec)	8	10	8	7

Computational Cost

Matrix Completion vs Curvelet-based methods

Percentage missing sources		50.0%		75.0%	
		σ	0.1	0.1	0.1
Matrix completion w/ SVD	SNR (dB)	17.3	18.3	11.6	11.5
	time (sec)	812.0	937.0	790.0	765.0
Matrix completion w/o SVD	SNR (dB)	17.6	18.4	12.6	13.1
	time (sec)	8	10	8	7
Curvelet-based sparsity promotion	SNR (dB)	17.4	18.6	12.5	12.8
	time (sec)	879	989	817	1010

Conclusions

- ▶ Alternating Optimization can better handle complicated cases
 - Highly sub sampled data (missing > 80%)
 - Complex data (high frequencies)

- ▶ Alternating Optimization does not increase time complexity

Future Work

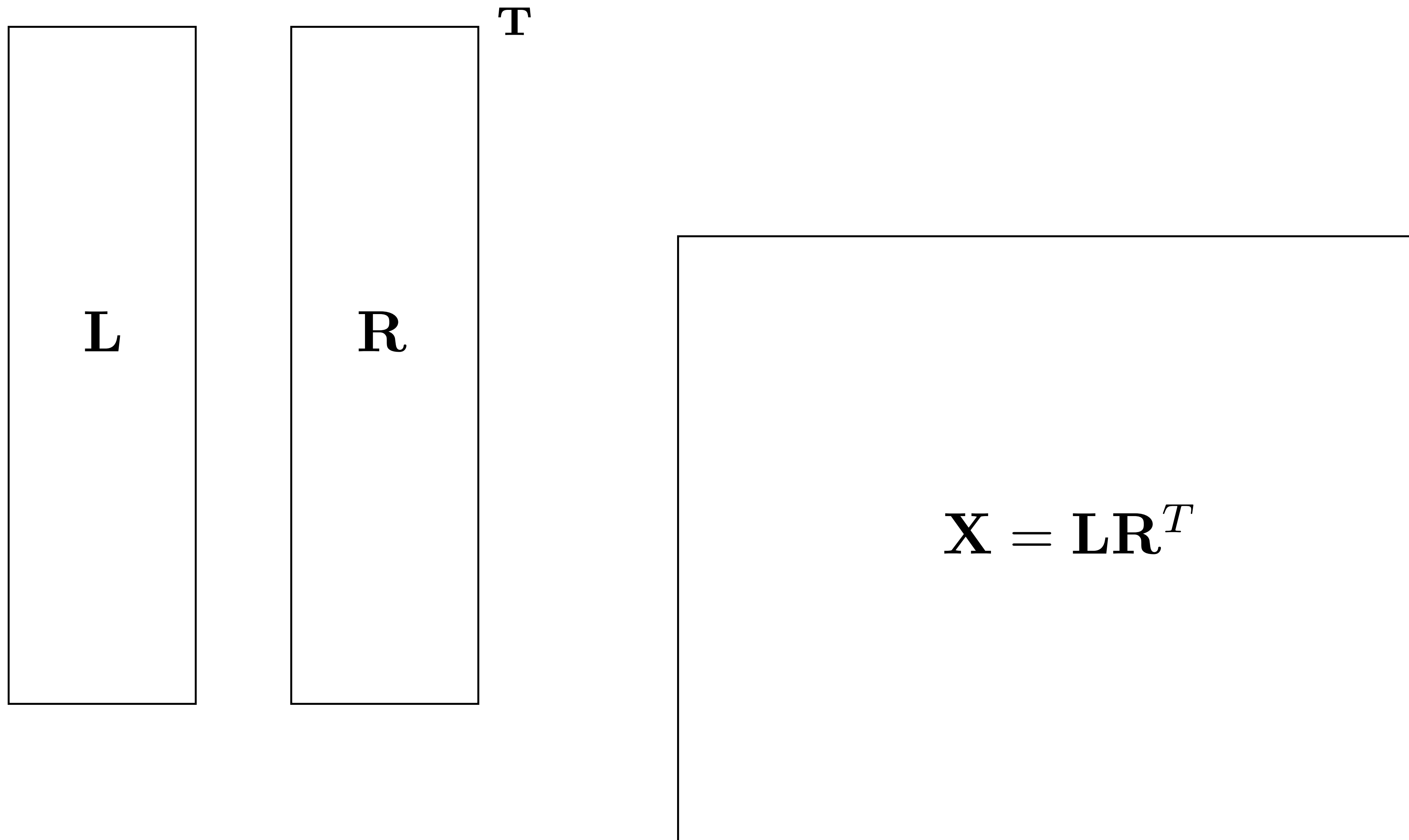
- ▶ Analysis of method
 - How many alternations are needed?

- ▶ Consider method for other applications
 - Tensor Completion
 - Source Separation
 - Parallel Matrix Completion

Future Work

- ▶ Analysis of method
 - How many alternations are needed?
- ▶ Consider method for other applications
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LR parallel matrix multiplication



LR parallel matrix multiplication

Worker 1	L_1		R_1	T
Worker 2	L_2		R_2	
Worker 3	L_3		R_3	
Worker 4	L_4		R_4	
Worker 5	L_5		R_5	

$L_1 R_1^T$	$L_1 R_2^T$	$L_1 R_3^T$	$L_1 R_4^T$	$L_1 R_5^T$
$L_2 R_1^T$	$L_2 R_2^T$	$L_2 R_3^T$	$L_2 R_4^T$	$L_2 R_5^T$
$L_3 R_1^T$	$L_3 R_2^T$	$L_3 R_3^T$	$L_3 R_4^T$	$L_3 R_5^T$
$L_4 R_1^T$	$L_4 R_2^T$	$L_4 R_3^T$	$L_4 R_4^T$	$L_4 R_5^T$
$L_5 R_1^T$	$L_5 R_2^T$	$L_5 R_3^T$	$L_5 R_4^T$	$L_5 R_5^T$

Acknowledgements

Software Release Coming Soon

Thank you for your attention



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