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Wavefield reconstruction via randomized sampling



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Outline

- This problem has a lot of room for improvement.
- In this talk we consider of a few simple techniques that can improve the results significantly.

• We do seismic trace interpolation by transforming the data to the curvelet domain.





Monday, December 8, 14





Weighting





- Weighting
- Jittered subsampling





- Weighting
- Jittered subsampling
- Midpoint-offset domain



Outline

• ℓ_1 recovery in curvelet domain

- Weighting
- Jittered subsampling
- Midpoint-offset domain
- 2-stage weighted algorithm



Main result

Improvement on an example with 70% missing receivers.

L1 minimization in SR



2-stage minimization in MH





Main result

Improvement on an example with 70% missing receivers.

L1 error image in SR



2-stage in MH error image





ℓ_1 for randomized acquisition of seismic lines

- Consider a seismic line with 178 sources, 178 receivers with a sample interval of 12.5m. • 512 time samples collected in a 2s temporal window.
- 30% of the receiver spread is randomly subsampled.

Fully Sampled time slice in source–receiver domain





Random subsampling mask



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Subsampled time slice





ℓ_1 for seismic trace interpolation

We want to recover f by interpolating between a smaller number of measurements b = RMf.







ℓ_1 for seismic trace interpolation

Let $S \in \mathbb{C}^{P \times N}$ with P > N be the redundant curvelet transform ($S^H S = \mathbb{I}$).

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Let $S \in \mathbb{C}^{P \times N}$ with P > N be the redundant curvelet transform $(S^H S = \mathbb{I})$. Then $b = RMS^H x$, where x can be recovered by sparse recovery algorithms like ℓ_1 minimization.

- We want to recover f by interpolating between a smaller number of measurements b = RMf.





To recover f from the measurements $b = RMS^H x$, we solve the ℓ_1 minimization problem $x^{\ell_1} := \min_{z \in R^P} ||z||_1$ subject to $||RMS^H z - b||_2 \le \epsilon$, and approximate f by $S^H x^{\ell_1}$. complete S^H incomplete data ℓ_1 minimization complete data Curvelet (frequency#k) (frequency#k)





Recovery results (shotgather # 84)





Recovery results: ℓ_1 minimization (5.3 dB)







Jittered subsampling mask





Jittered subsampling mask

Why does jittering help?

transform domain.

• success of Randomized subsampling depends on destroying the structure of data in some



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Why does jittering help?

- transform domain.
- Uniformly random subsampling might result in large gap in the data.
- Jittering is a safe alternative that doesn't allow large gaps in the data.

success of Randomized subsampling depends on destroying the structure of data in some



New subsampled data

Jittered sampling controls the average amount of information per row in the transform domain.

Subsampled shot gather



Jittered shot gather





Weighted ℓ_1 for seismic trace interpolation







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- 2-D curvelet transform captures the continuity in each slice. However we lose the continuity along frequency slices.
- We utilize the continuity along adjacent frequency slices by weighting.
- If the support estimate is at least 50% accurate, we get better results.

Recovery results: ℓ_1 vs weighted ℓ_1





Jittered weighted L1 (SR)





Recovery error: ℓ_1 vs weighted ℓ_1



Monday, December 8, 14

Jittered weighted L1 error (SR) 0.5 Time(sec) 1.5 500 1500 2000 1000 Distance (m) (n) SNR= 8.8 dB



Shot gathers: ℓ_1 vs weighted ℓ_1





Recovery in the midpoint-offset domain

We transform the seismic line into the frequency-midpoint-offset (MH) domain.

Fully Sampled time slice in midpoint-offset domain





Weighting in MH and SR domain

- Similar to the SR domain we do the recovery by utilizing frequency slices. \bigcirc
- The adjacent frequency slices have overlapping support in both cases.





Why does transforming to MH domain help?





Recovery results: ℓ_1 in SR vs weighted ℓ_1 in MH

L1 minimization in SR 0.5 Time(sec) 1.5 2 500 1000 1500 2000 Distance (m)

(q) SNR=5.4 dB



500 1000 1500 Distance (m) (r) SNR= 12.8 dB



Recovery error: ℓ_1 in SR vs weighted ℓ_1 in MH







Shot gathers results





 For each frequency slice first, use a fast the time domain.

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- the time domain.
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- Use the estimate in curvelet domain to improve the recovery results.

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Approximate message passing (AMP)

• We use AMP in Fourier domain for the first stage.



- We use AMP in Fourier domain for the first stage. • AMP starts from an initial x^0 and iteratively goes by $x^{t+1} = \eta(x^t + A^*z^t; \tau^t)$ $z^t = y - Ax^t + \delta^{-1}z$
- η is the soft thresholding function $[\eta(x;s)]_j = sign(x_j)(|x_j| s_j)$

$$egin{aligned} & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,1), \ & (1,$$

(1)



The 2-stage algorithm WAMP+weighted ℓ_1





Simple example with a 2-sparse signal, iteration t = 1



Iteration t = 2



Iteration t = 3



AMP and WAMP for seismic trace interpolation

- AMP is a delicate algorithm that just works for certain types of measurements.
- We can't use curvelets with AMP.
- Instead we use 2-D DFT matrix in the source-receiver domain.
- Then $b = RMF_s^H F_s f$, where F_s is a 2-D DFT matrix.



Flowchart of the 2-stage algorithm WAMP+weighted ℓ_1





ℓ_1 vs 2-stage WAMP+weighted ℓ_1





2-stage minimization in MH





Results of the 2-stage algorithm







Results of the 2-stage algorithm





Comparison of recovery results





50% undersampling (19.6 dB)

2-stage minimization in MH





2-stage in MH error image





50% undersampling (19.6 dB)







2-stage in MH with 50% undersampling



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- We get better sparse representation once we go from SR domain to MH domain.
- Finding a fast estimation of the data in the curvelet domain improves the results significantly. Especially in high frequencies.

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