

FWI from Vancouver: lessons learned from “Gulf of Mexico Imaging Challenge Part II: FWI, WEMVA, Workflows &...

Dream team



University of British Columbia



Dream team



Felix J. Herrmann



Andrew J. Calvert



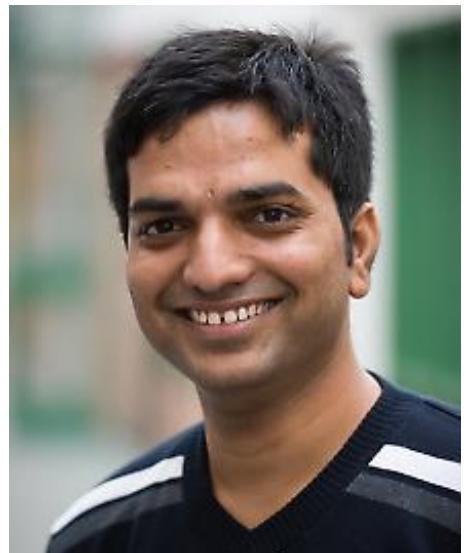
Ian Hanlon



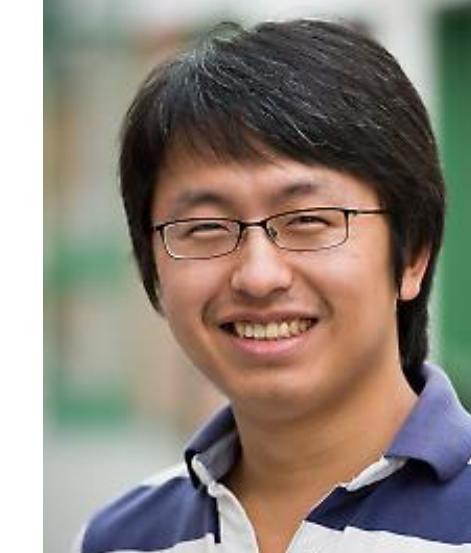
Brendan Smithyman



Tristan van Leeuwen



Rajiv Kumar



Xiang Li



Haneet Wason

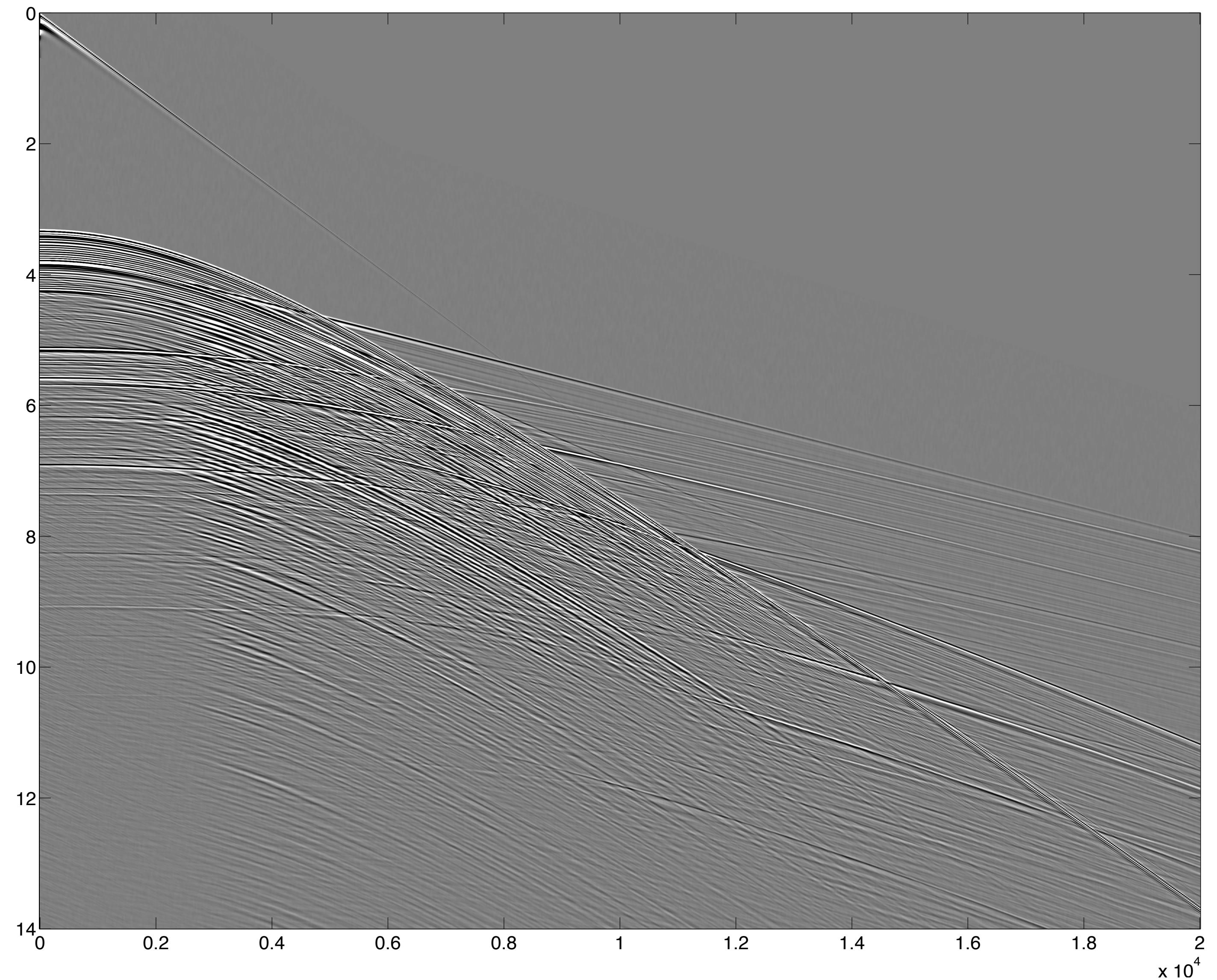


Mostafa Javanmehri

GOM data set (released in 2012)

- 3201 shots with interval 25 m
- 801 receivers with interval 25 m, yielding 20km offset
- record time 14s, sample rate 4ms
- no surface related multiple, but free surface ghost
- isotropic elastic

One shot record



Preprocessing

Travel-time *tomography* based on hand-picked *first* breaks



initial velocity model

Curvelet-denoising at selected *low-frequencies*



improve SNR for FWI

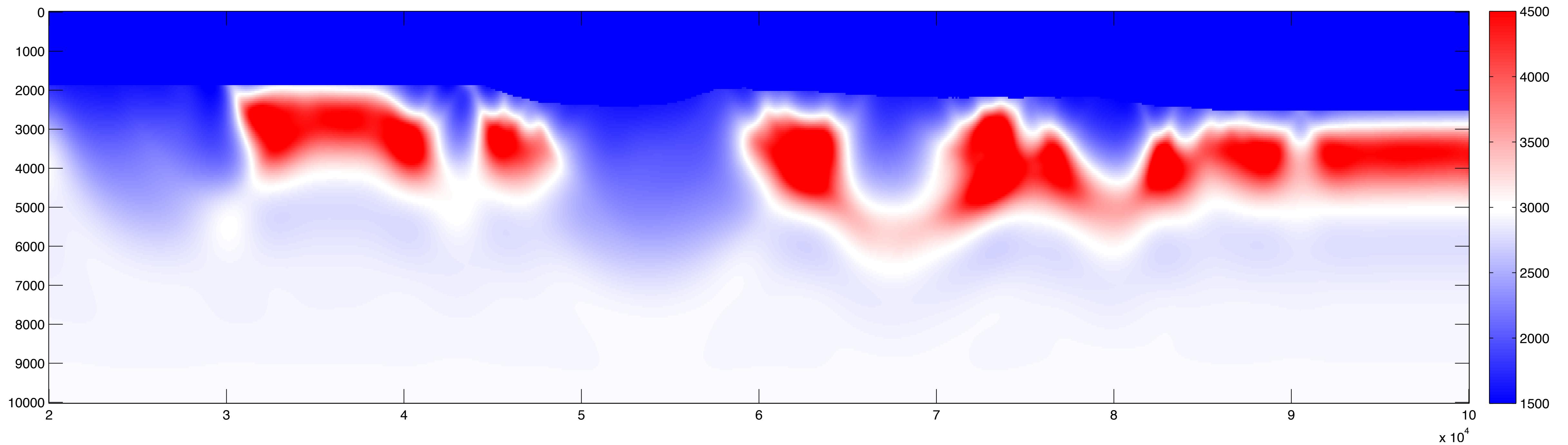


SLIM

Initial model

ray based tomography from *first* breaks

Andrew J. Calvert



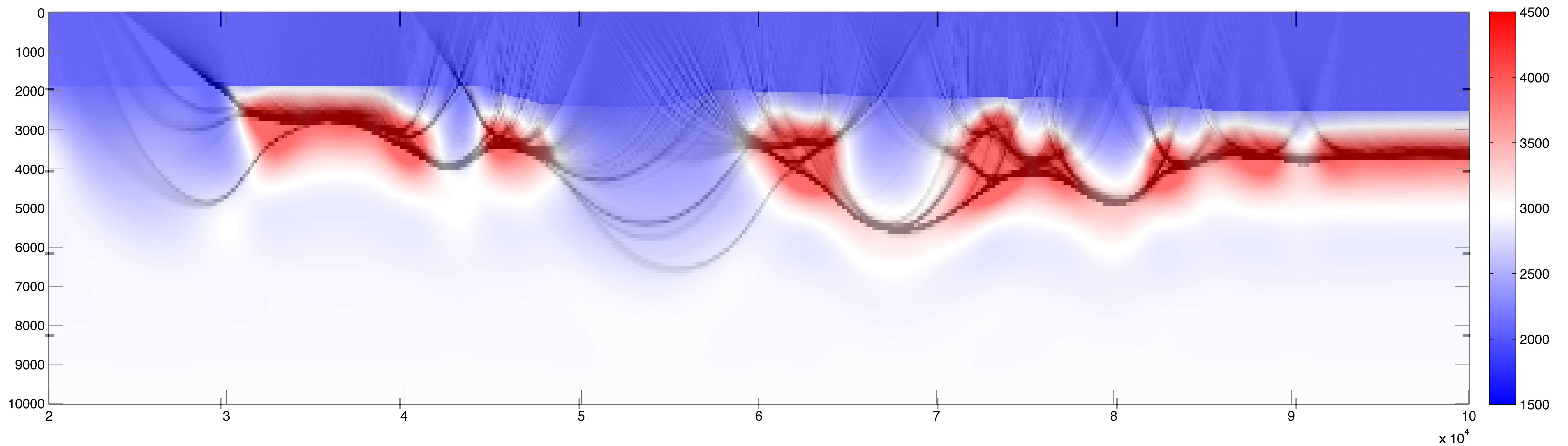


SLIM

Ray paths

[RMS traveltime misfit 11ms]

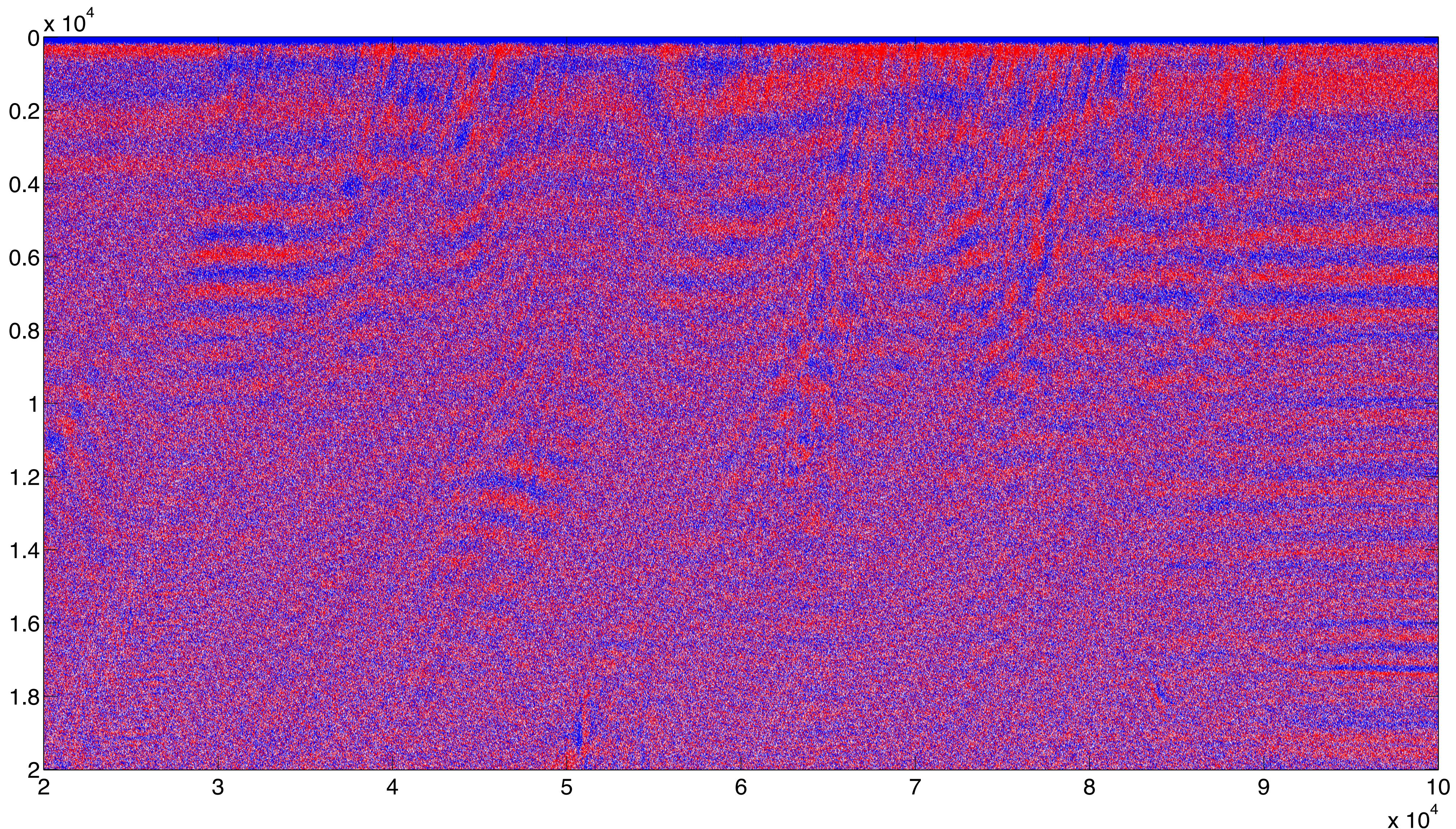
ray based tomography from *first* break



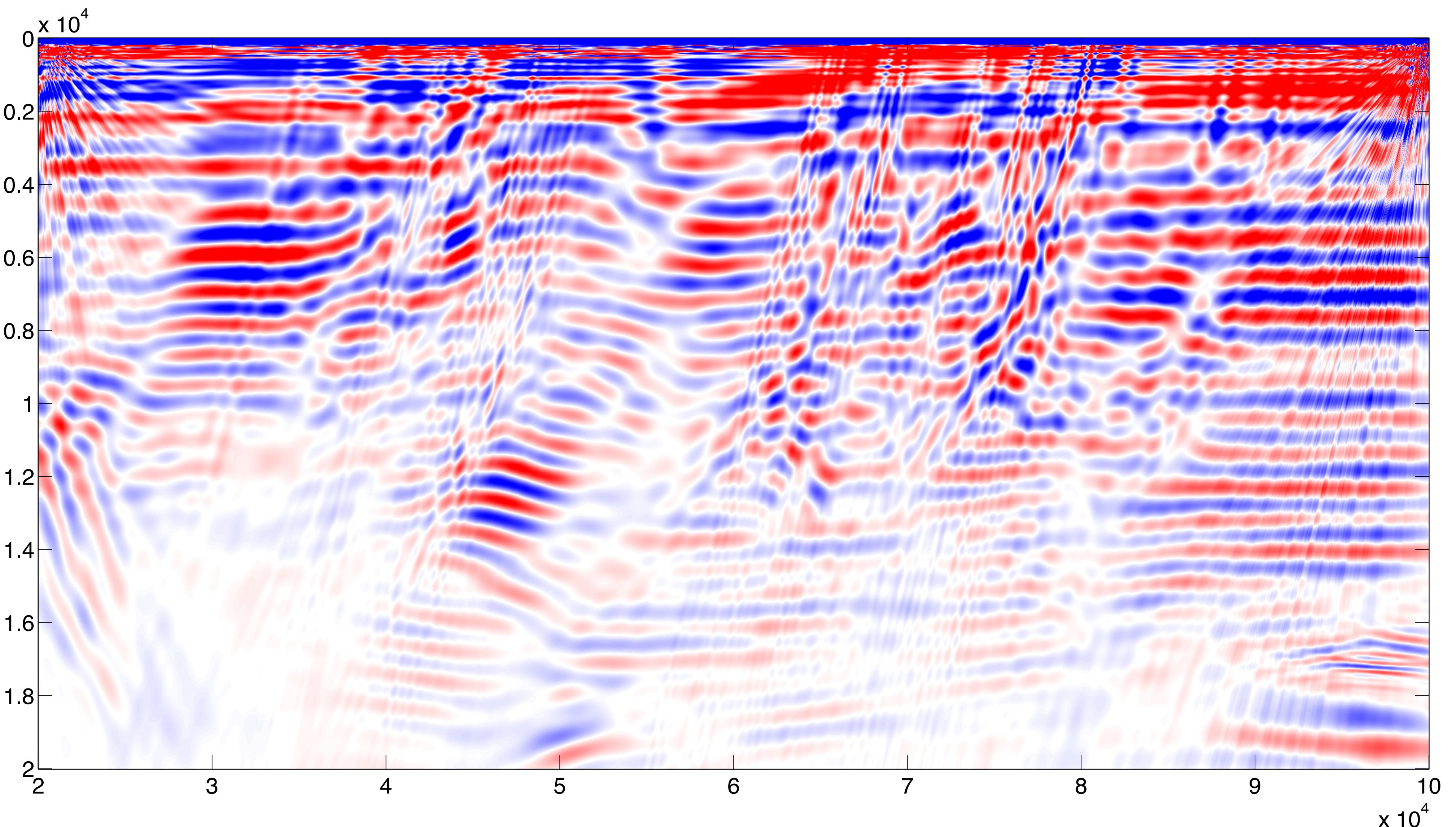
Curvelet denoise

- Work on “frequency slices” in the source/offset plane
- Find support by hand-selected thresholding of synthesis curvelet coefficients
- Followed by debiasing to restore amplitudes...

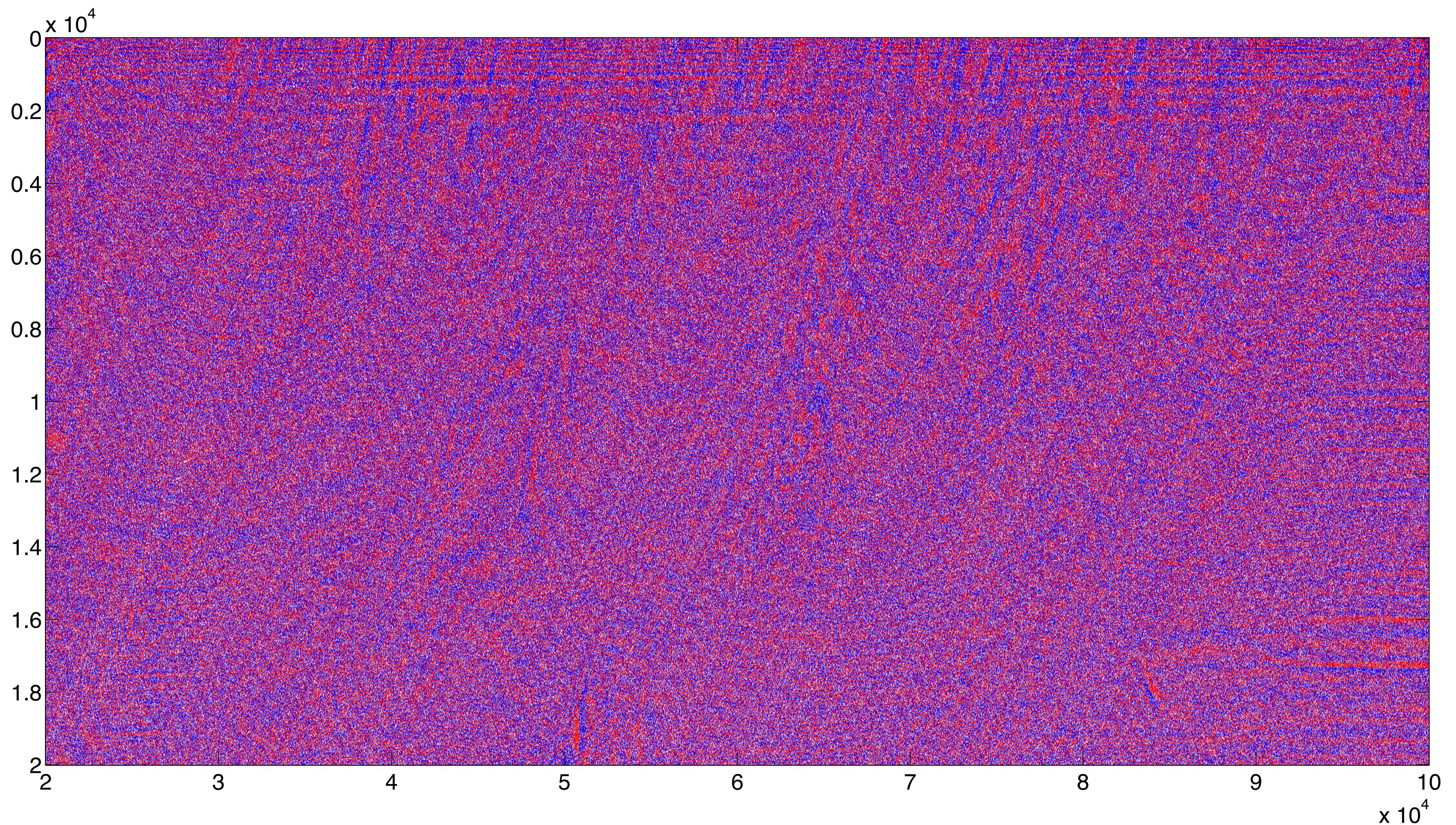
Before denoising [real part 2Hz]



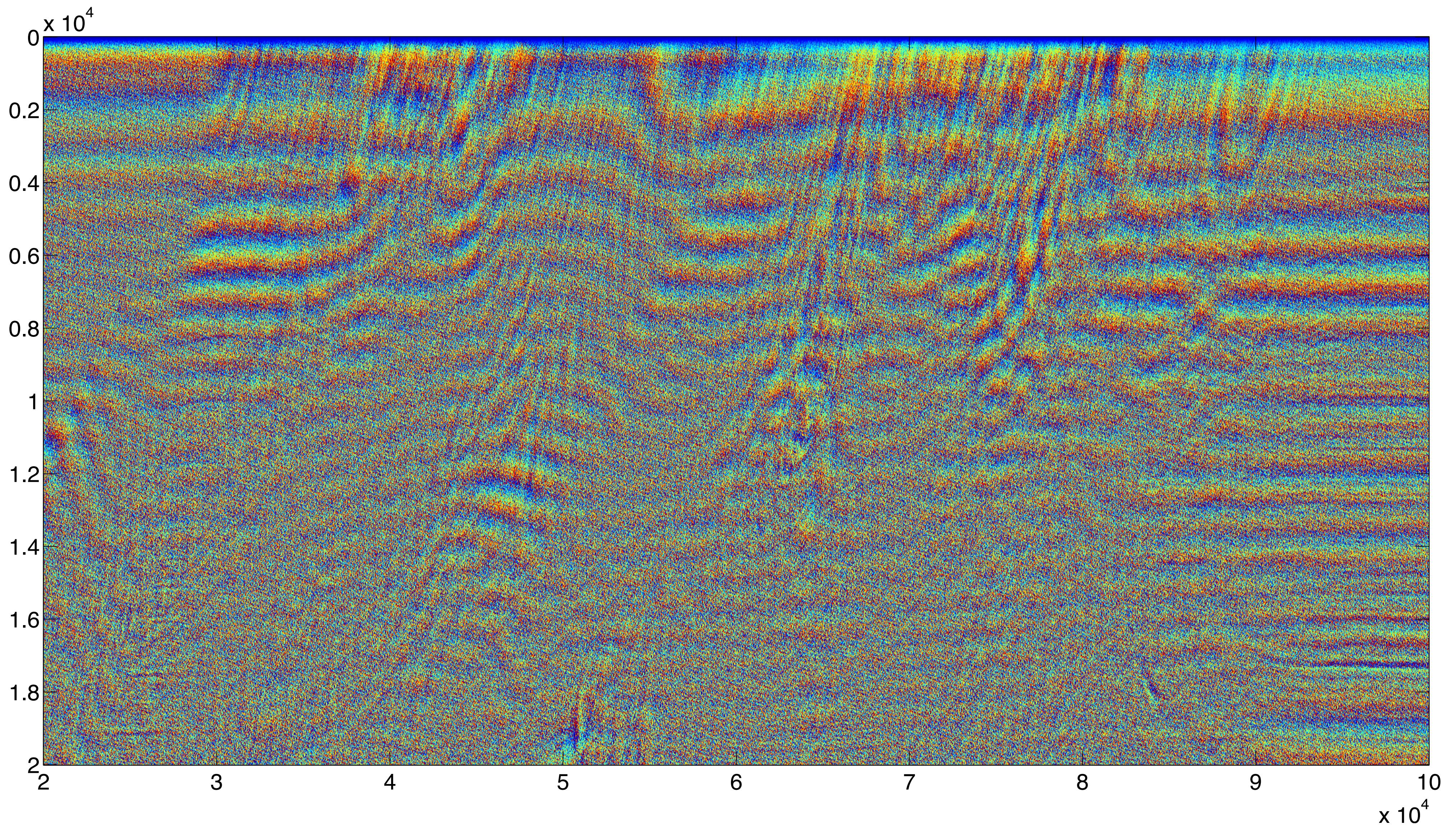
After denoising [real part 2Hz]



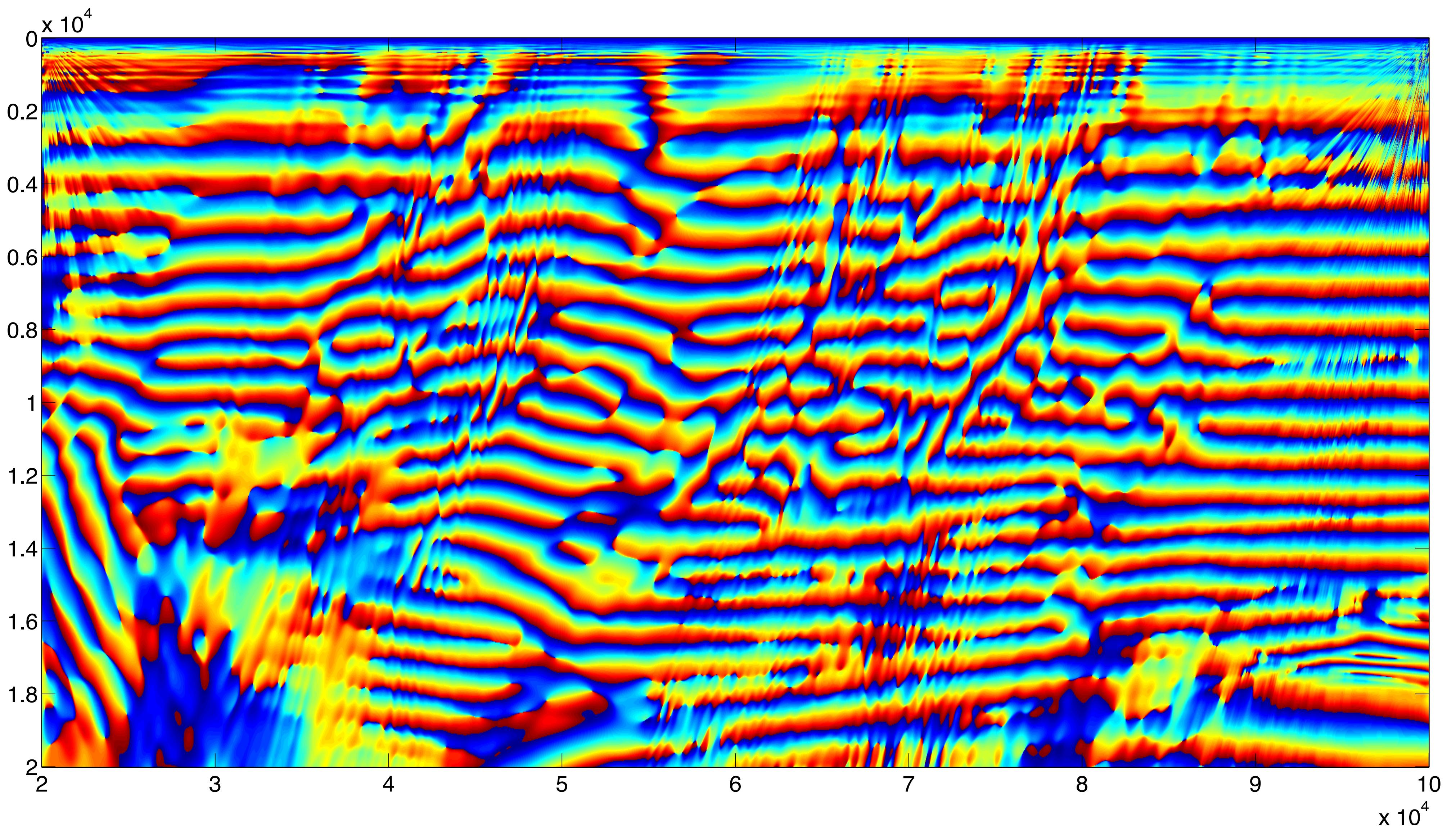
Difference



Before denoising [phase 2Hz]



After denoising [phase 2Hz]





Modified Gauss-Newton

F.J. Herrmann, X. Li, A.Y. Aravkin, and T. van Leeuwen, “A modified, sparsity promoting, Gauss-Newton algorithm for seismic waveform inversion”, in Proc. SPIE, 2011, vol. 2011.

X. Li, F.J. Herrmann, A.Y. Aravkin and T. van Leeuwen - Fast randomized full waveform inversion with compressed sensing. Geophysics 77 (A13), 2012.

F.J. Herrmann, X. Li, A.Y. Aravkin, and T. van Leeuwen - A modified, sparsity-promoting, Gauss-Newton algorithm for seismic waveform inversion. Proc. SPIE 8138, 81380V, 2011

Inversion setting

Modified Gauss-Newton:

- ▶ frequency continuation (10 bands, each band has 3 freqs, 2-5Hz)
- ▶ rerandomized subsets of shot, using *only* 600 at a time
- ▶ 6 GN *iterations* per frequency *band*
- ▶ *preconditioning of Jacobian by depth weighting*
- ▶ *projection of water layer*

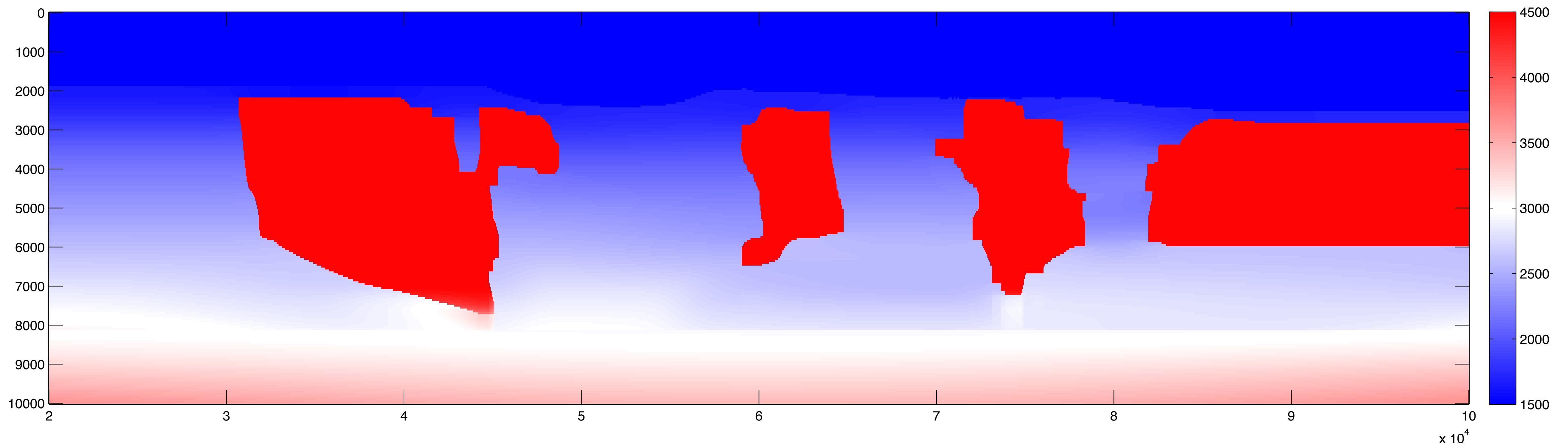
One-norm curvelet *regularized gradients...*



SLIM

Initial model

released by Chevron (2013)

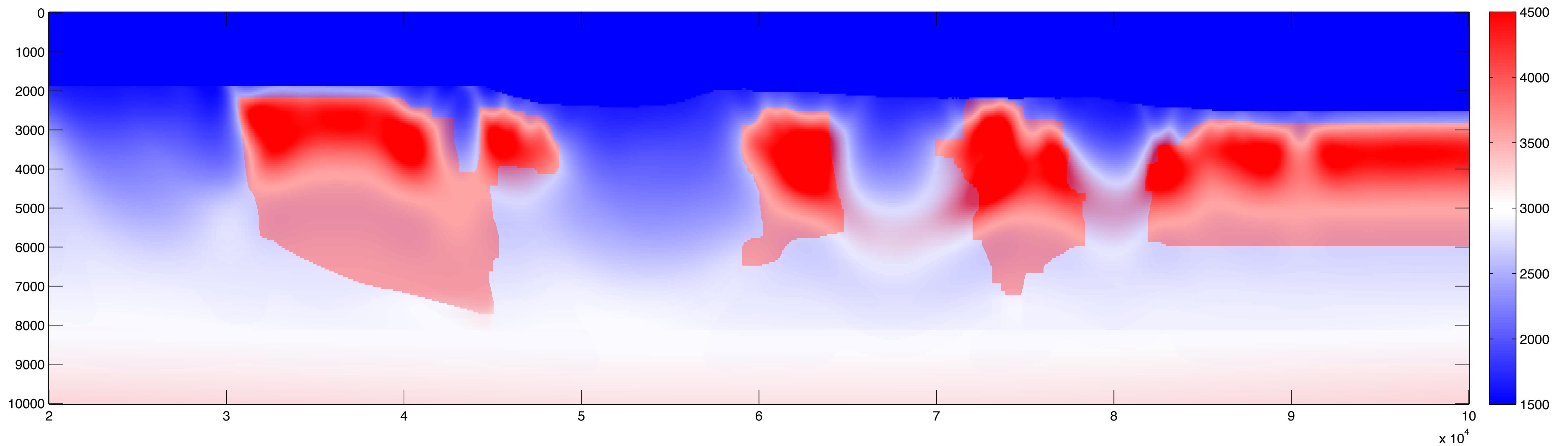




SLIM

Model comparison

overlay with ray based tomography initial model

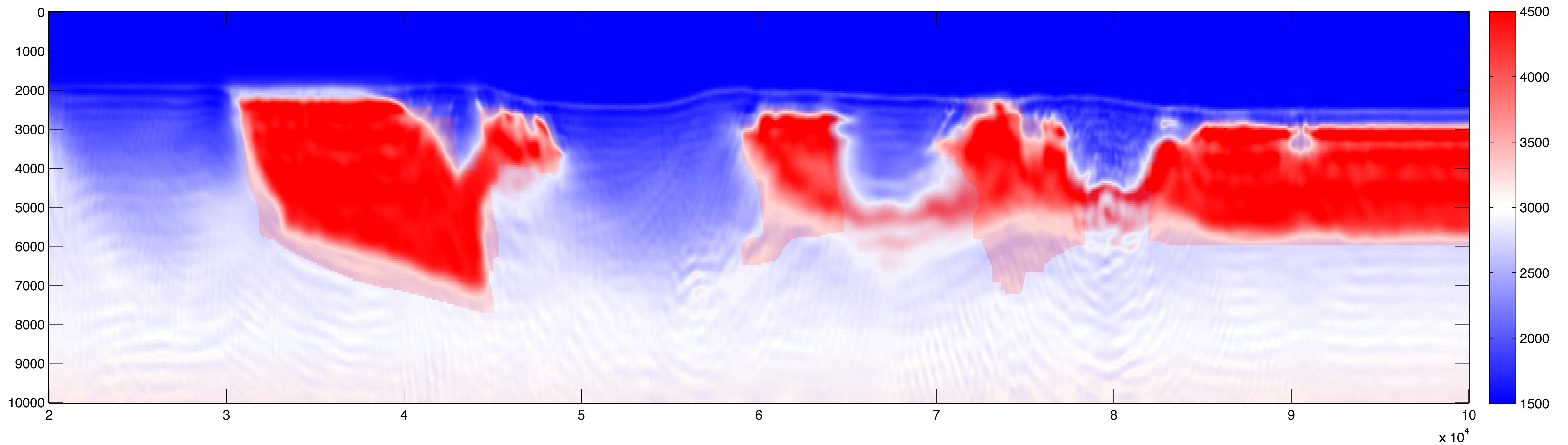




SLIM

Model comparison

overlay with FWI result

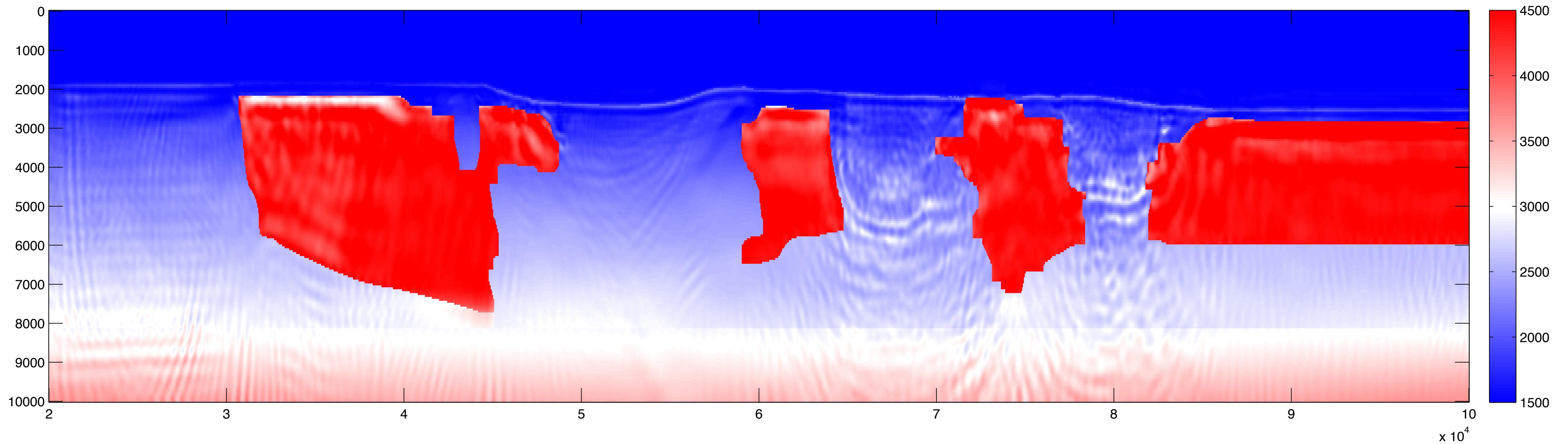




SLIM

FWI result

with new released model & 2012 data set

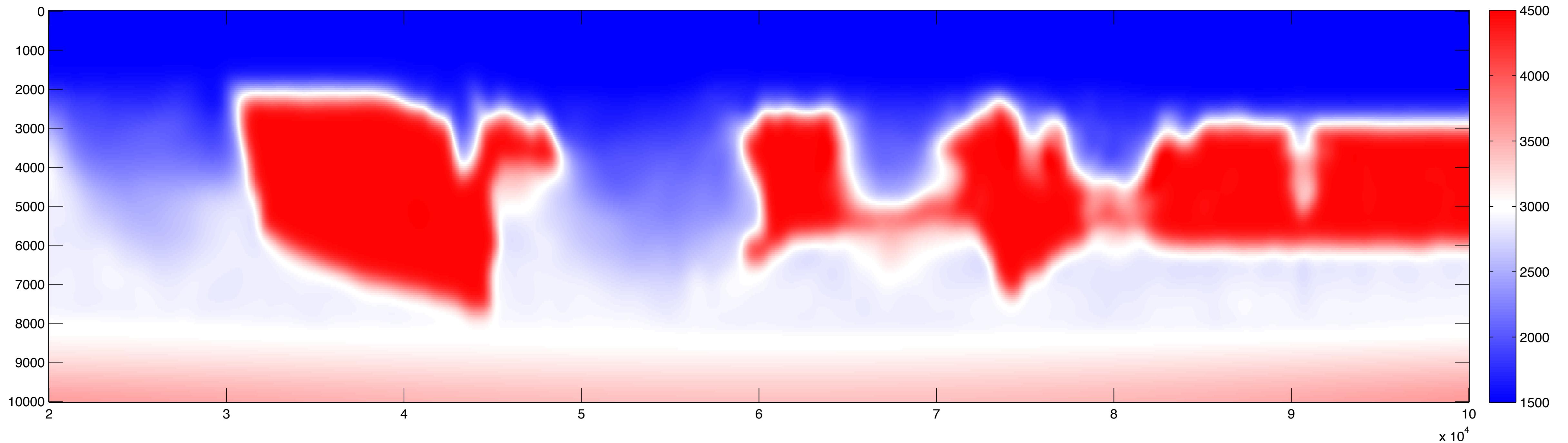




SLIM

Initial model

combination of TOMO initial model and new released model

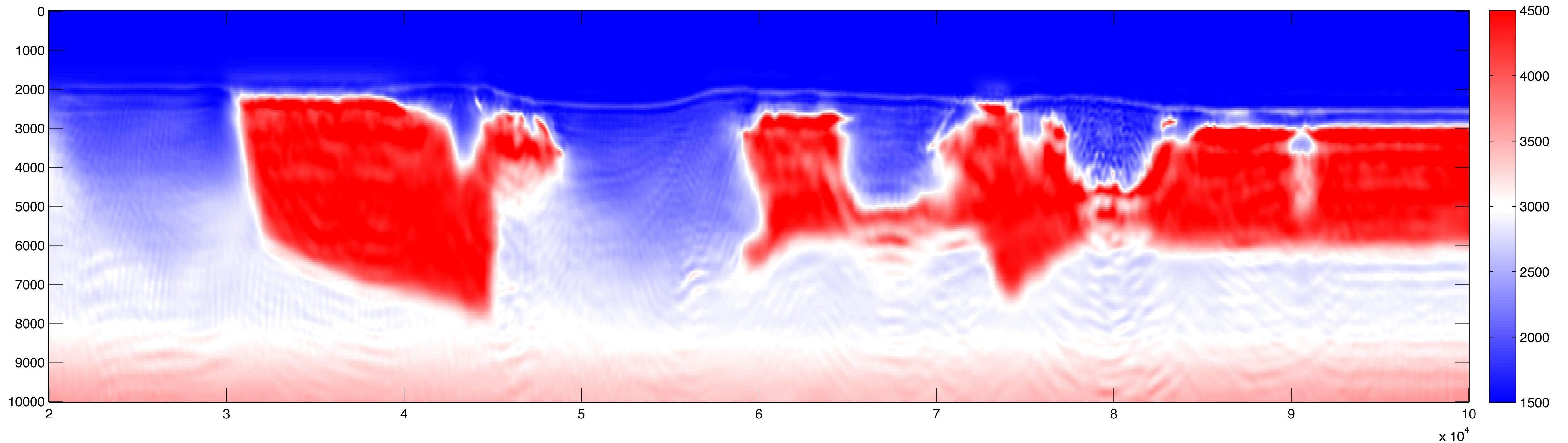




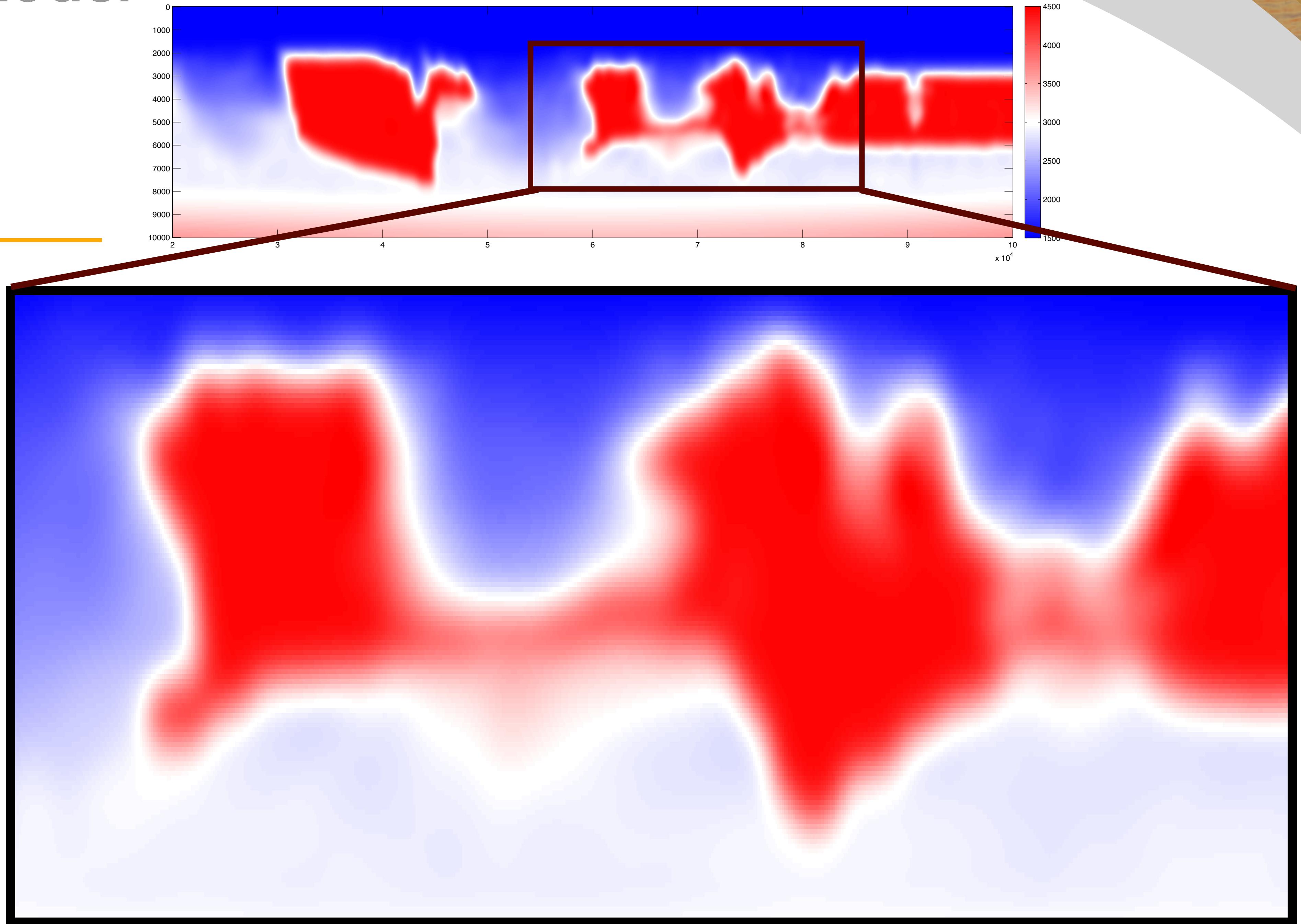
SLIM

FWI result

with combined model and 2012 data set



Initial model

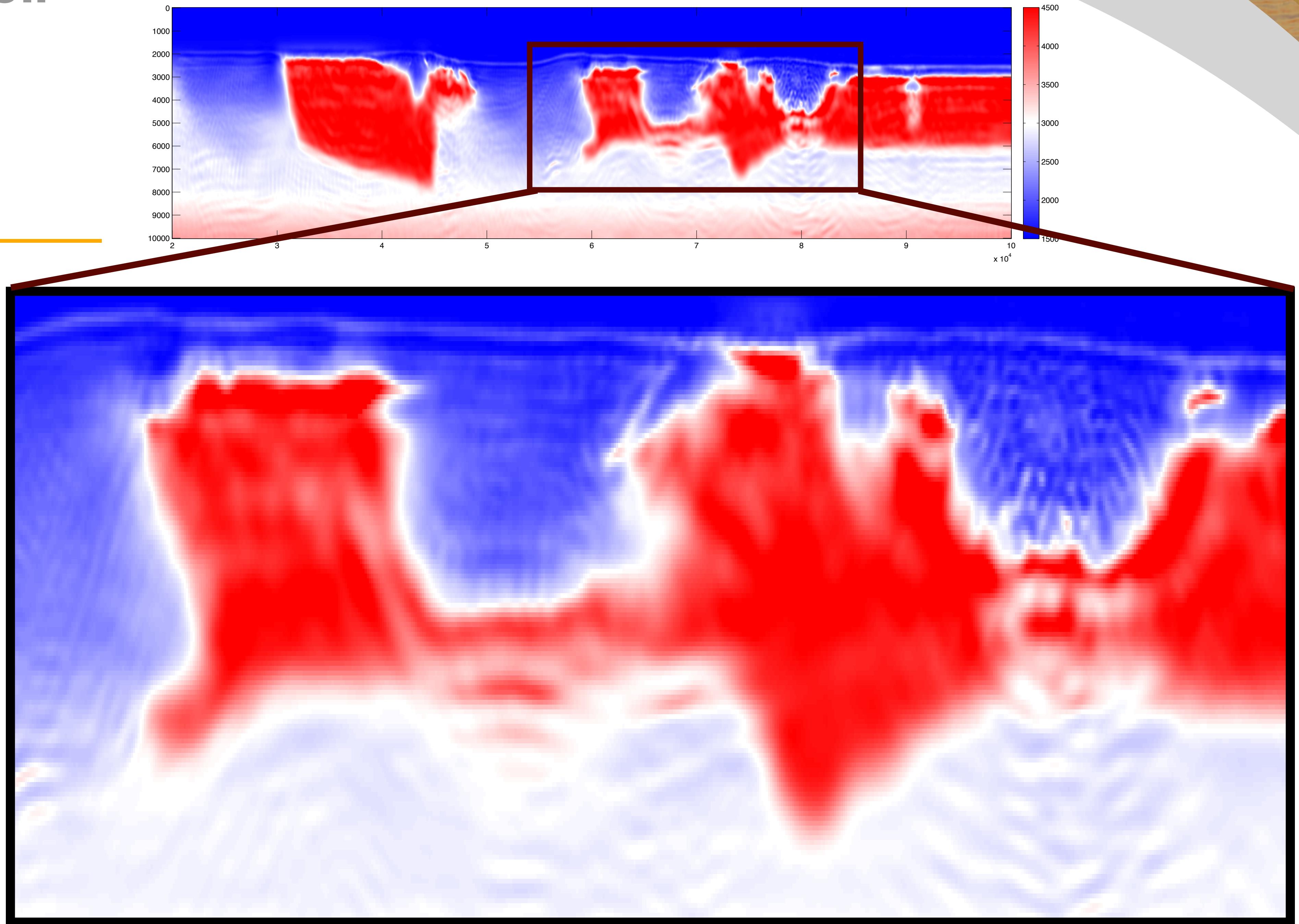


SLIM

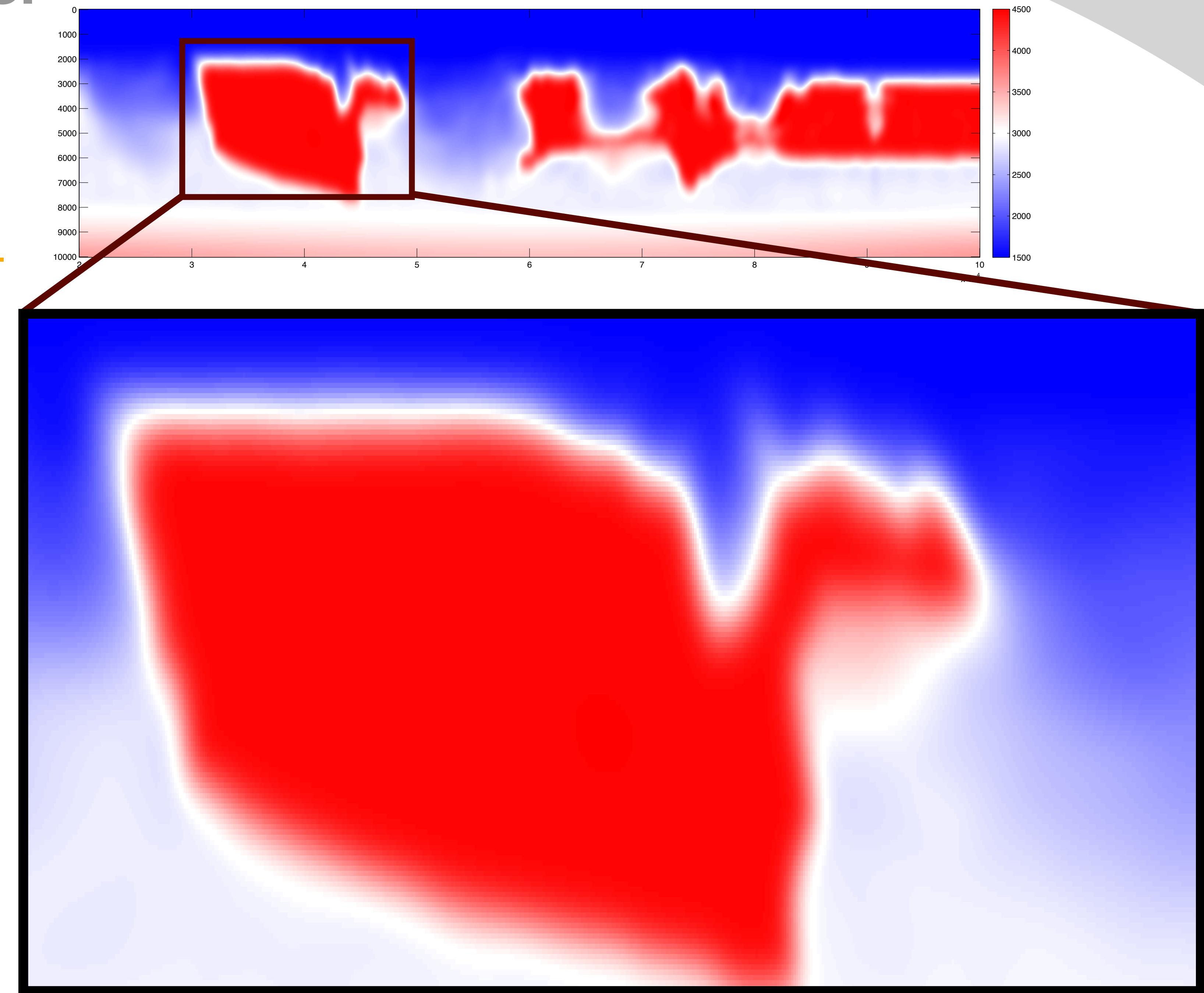
FWI result



SLIM

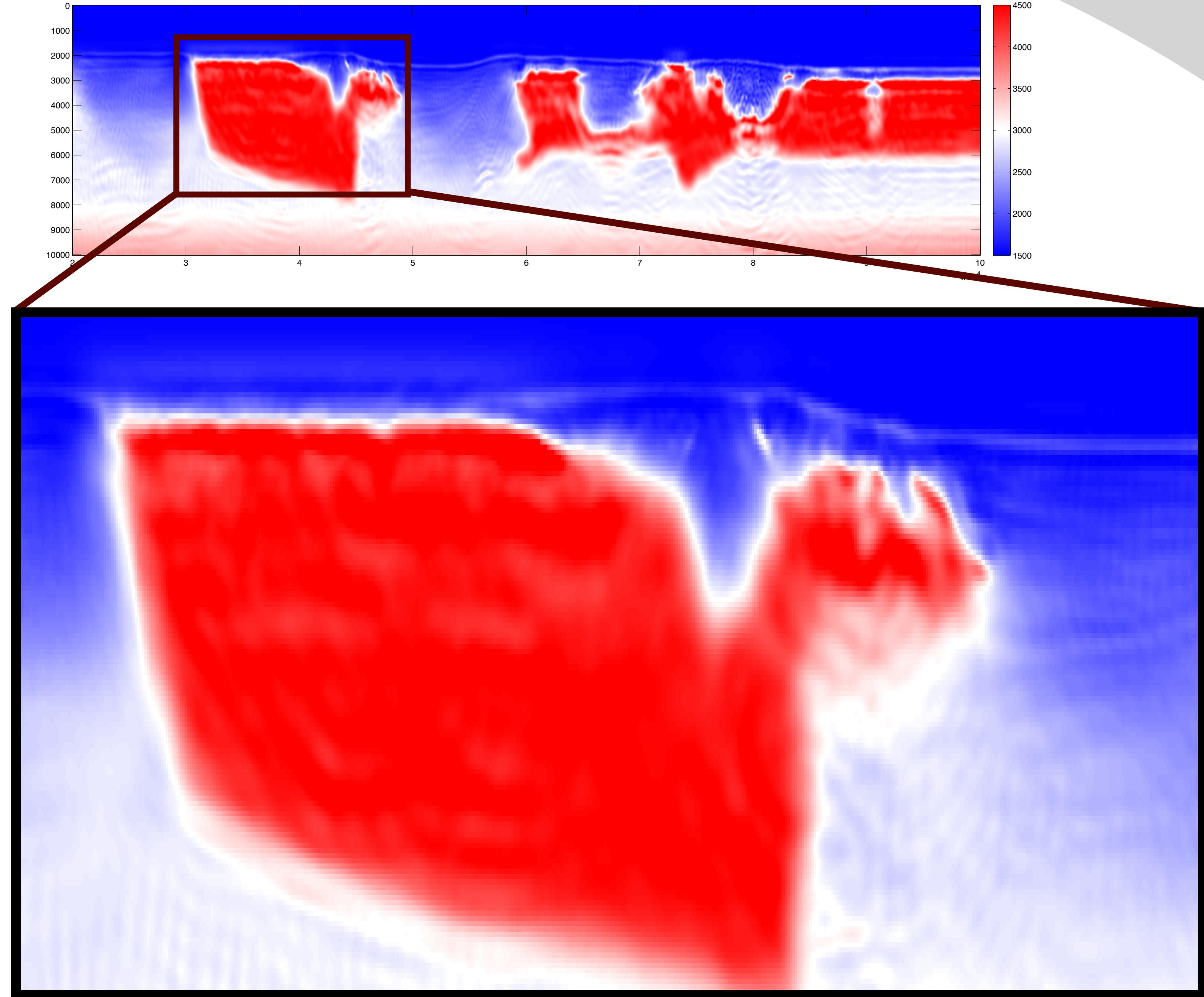


Initial model



SLIM

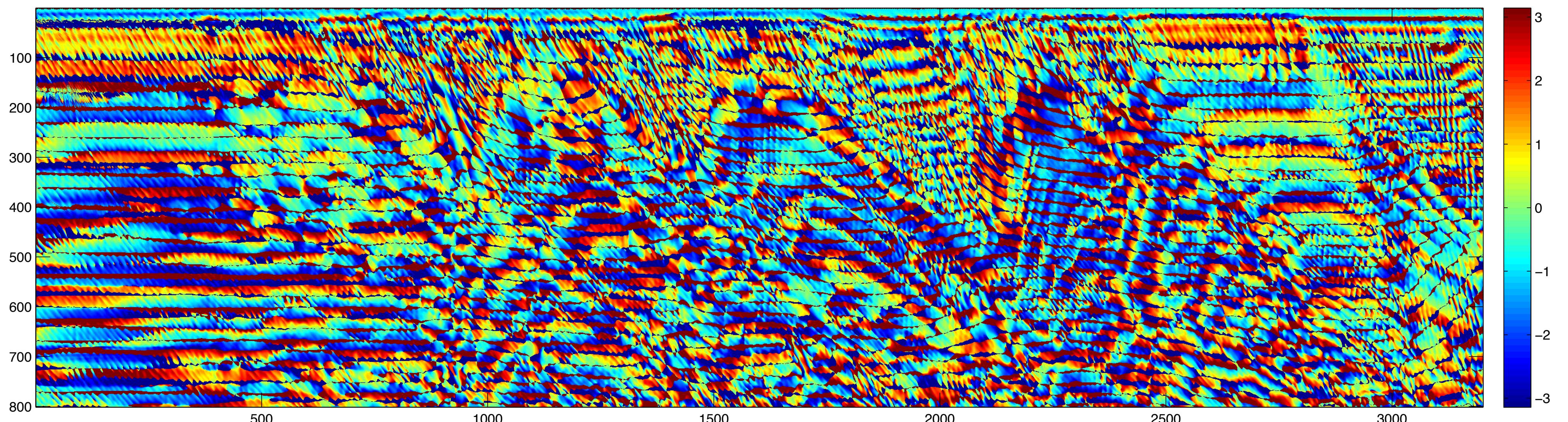
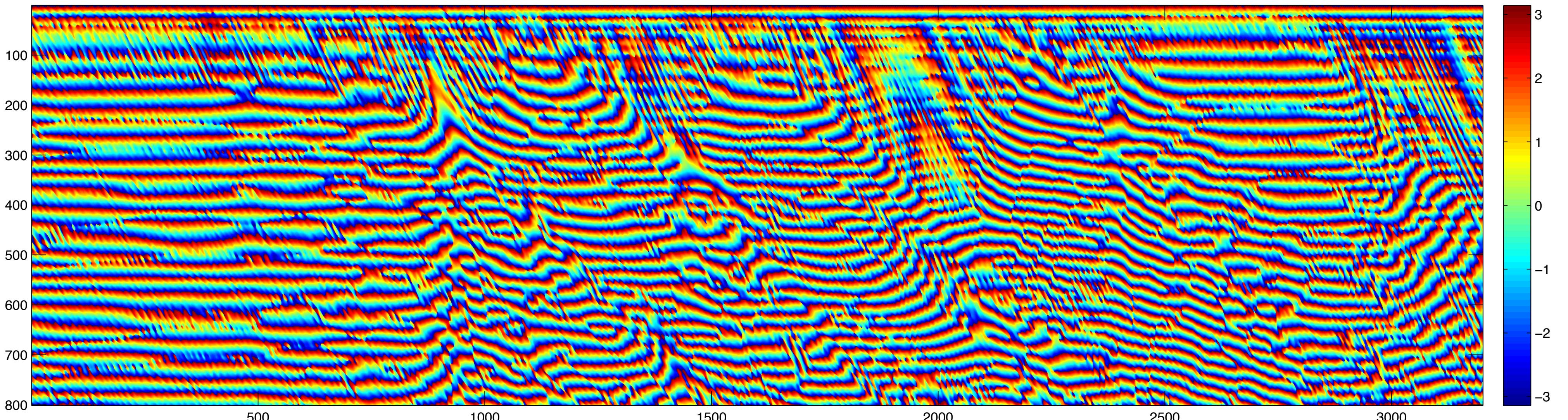
FWI result



SLIM

Data fitting in frequency domain

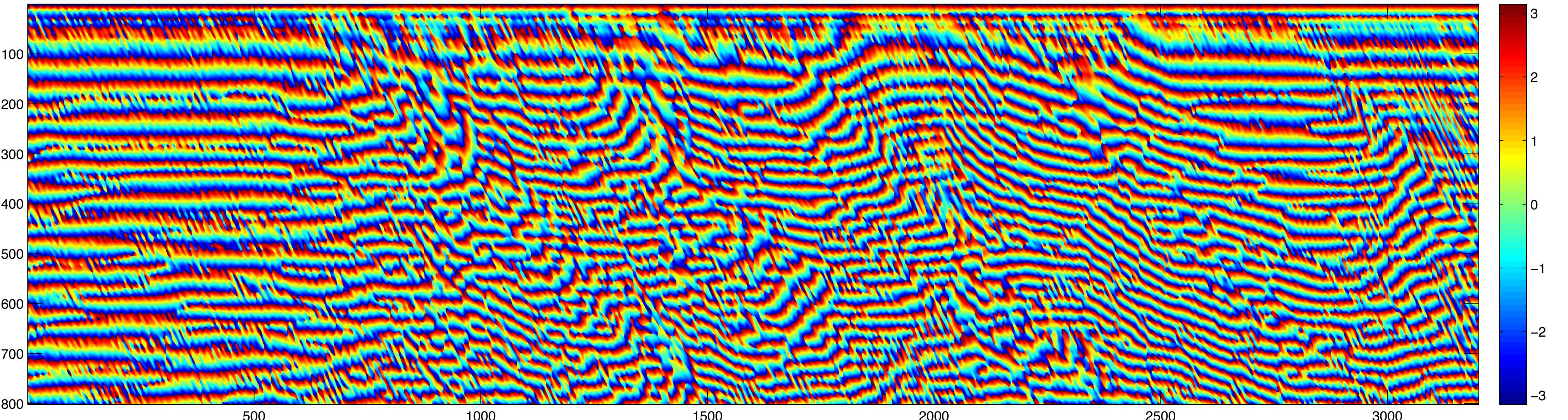
frequency slide from initial model at 3Hz



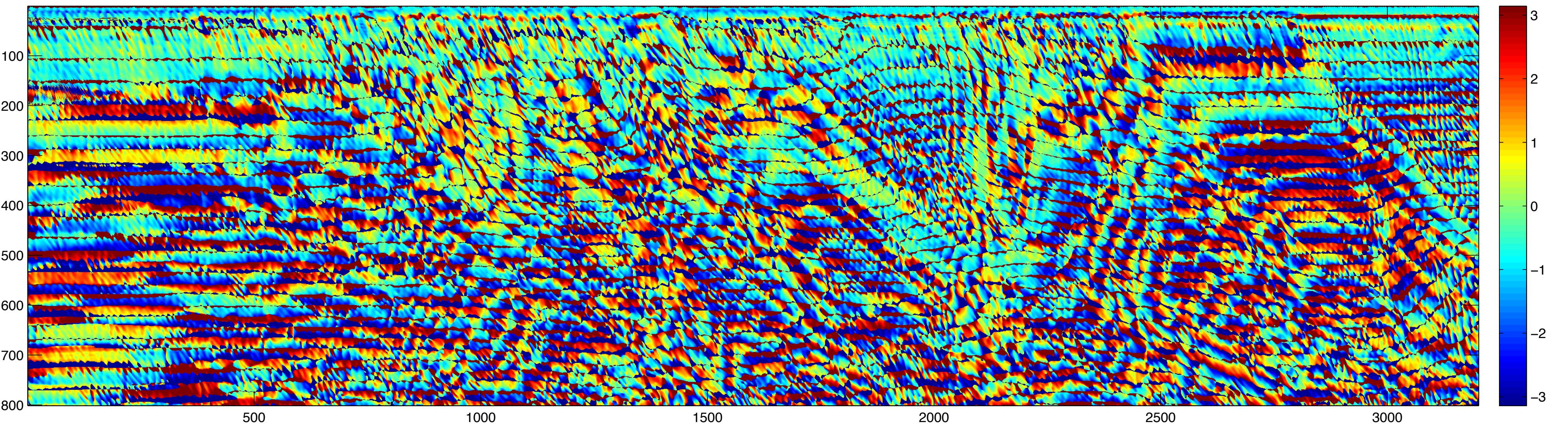
difference

Data fitting in frequency domain

frequency slide from FWI result at 3Hz

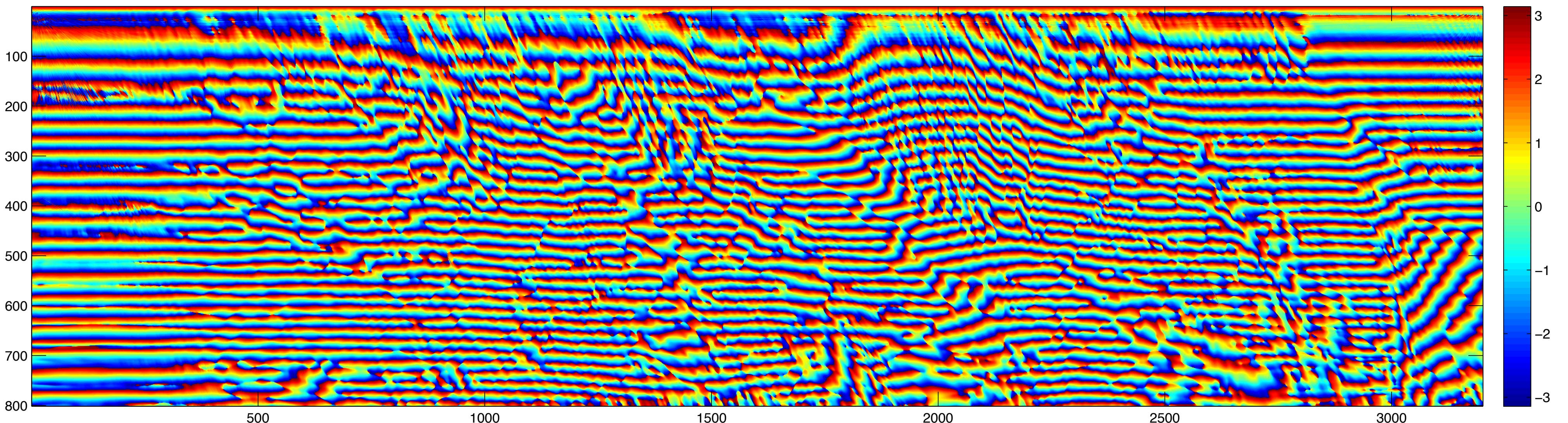


difference

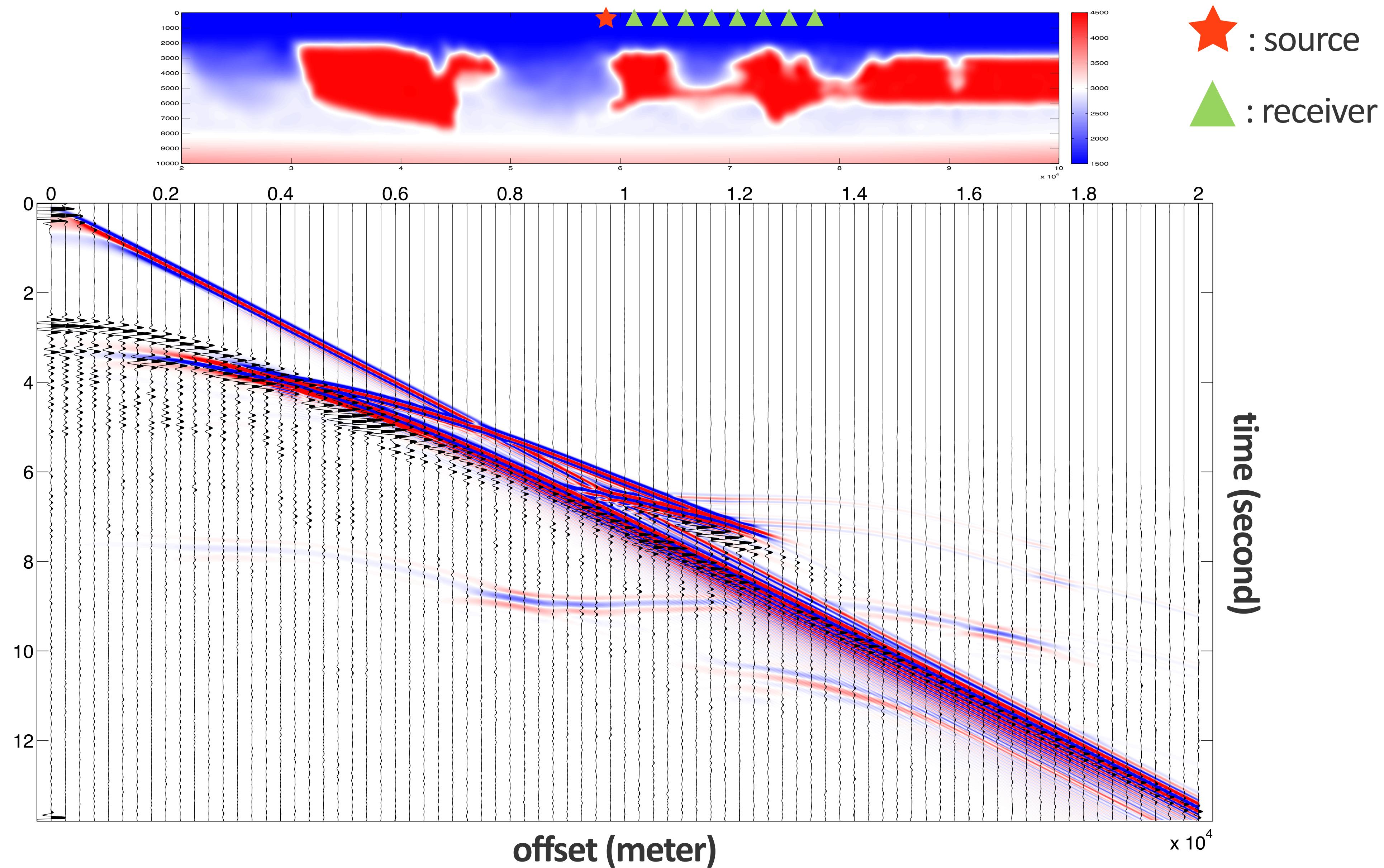


Data fitting in frequency domain

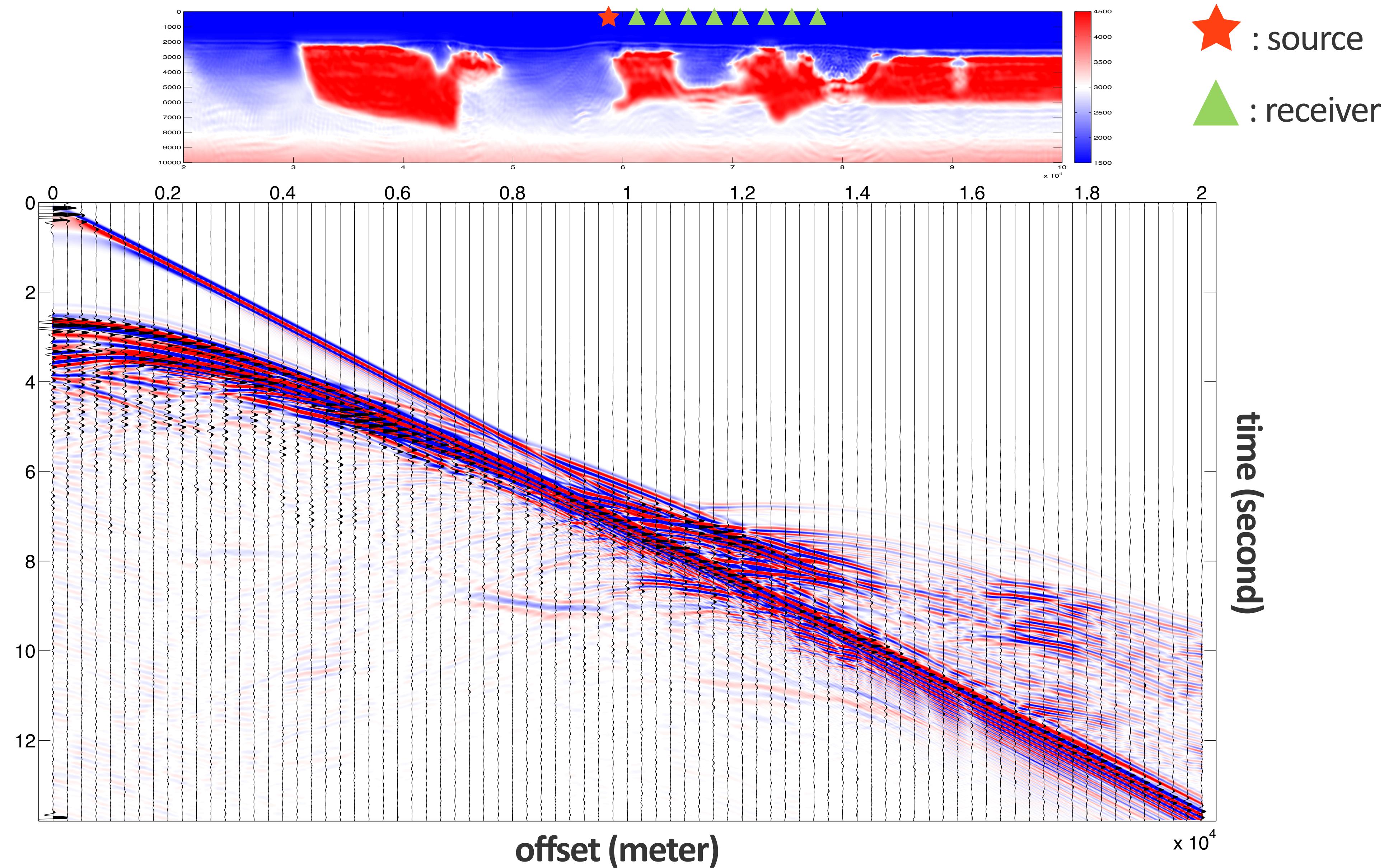
frequency slide from true data at 3Hz



Data fitting in time domain



Data fitting in time domain

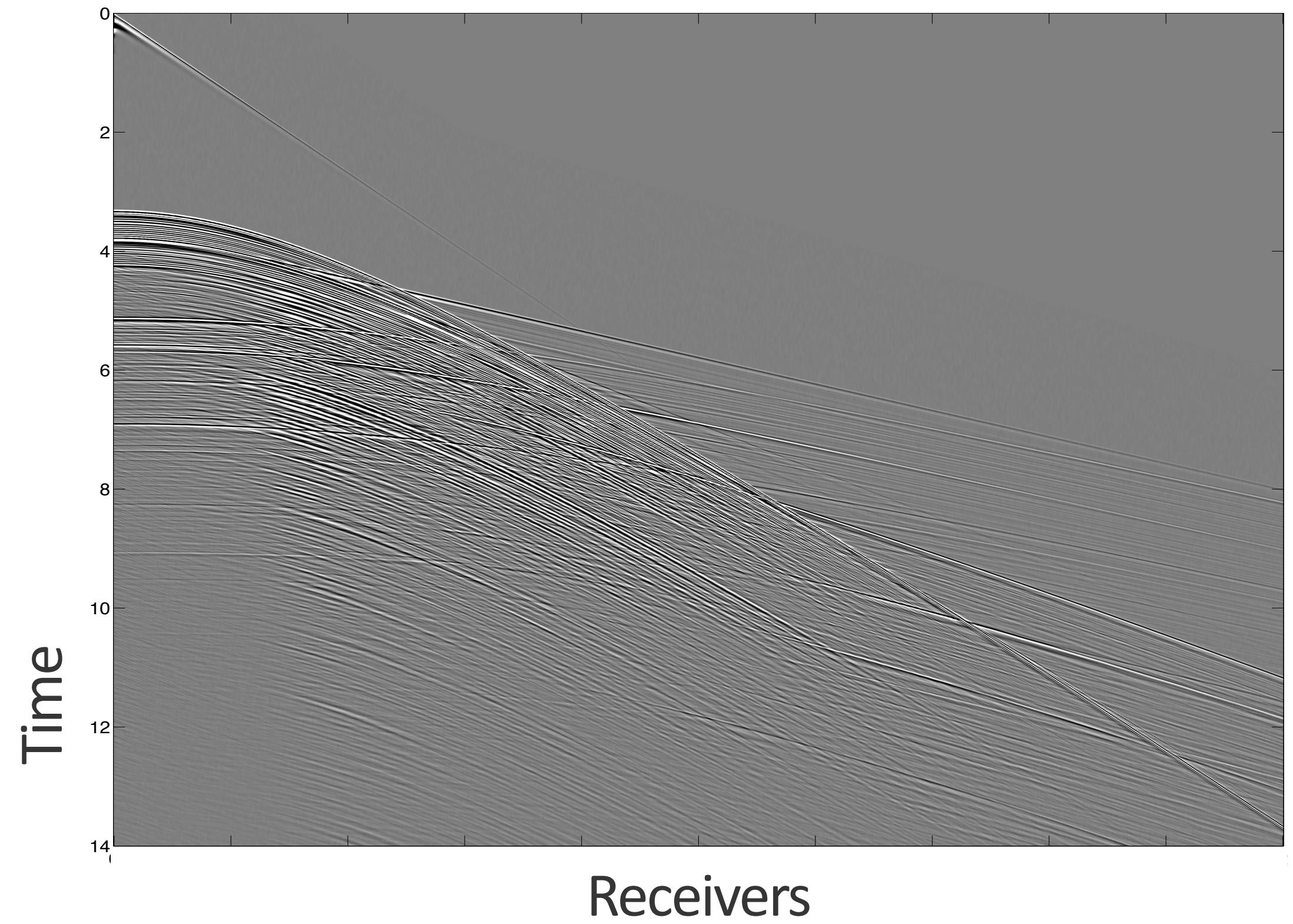


GOM data set (released in 2013)

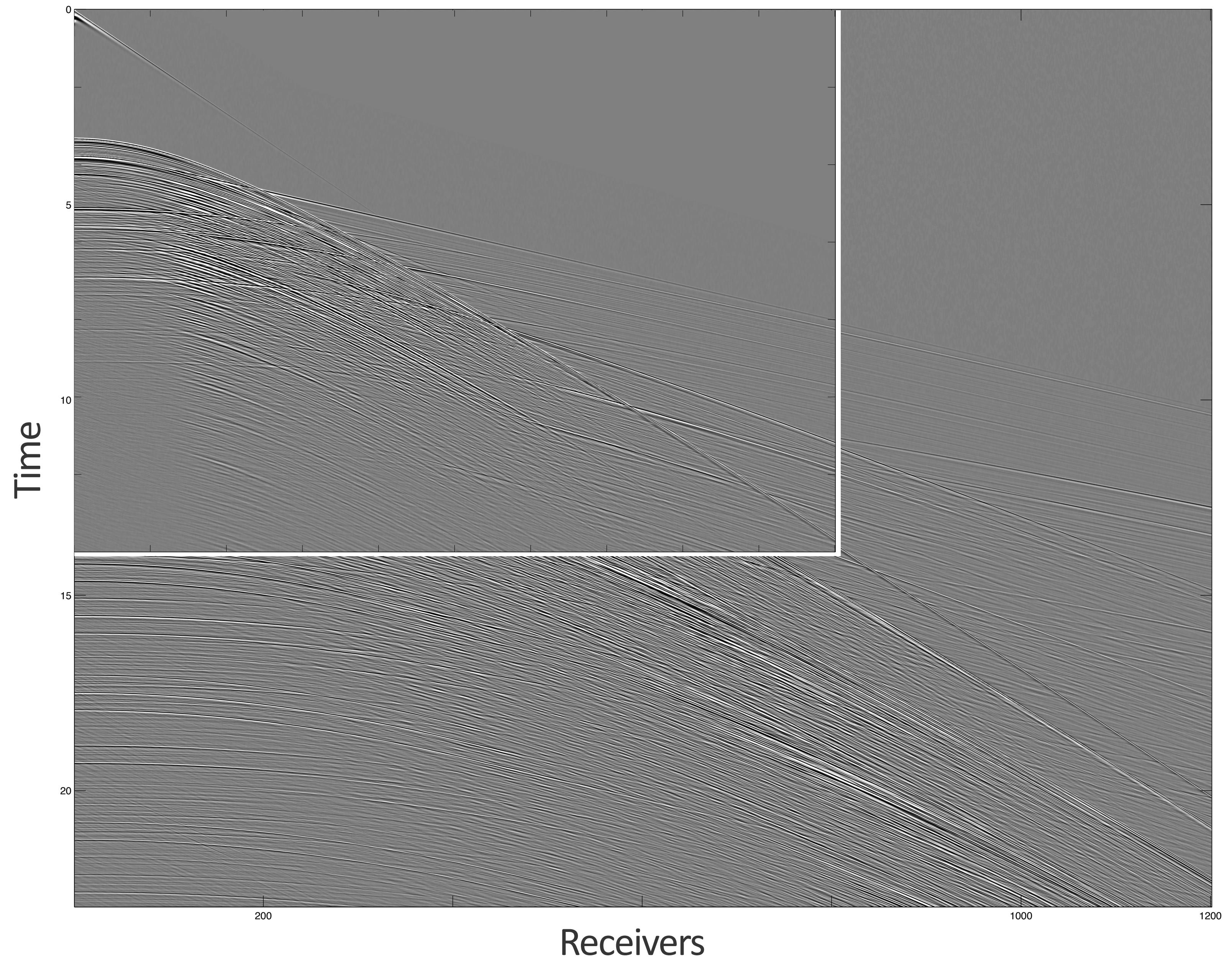
- 3201 shots with interval 25 m
- 1201(801) receivers with interval 25 m, yielding 30km(20km) offset
- record time 22s(14s), sample rate 4ms
- free surface
- isotropic elastic

value in brackets are from the original 2012 data set

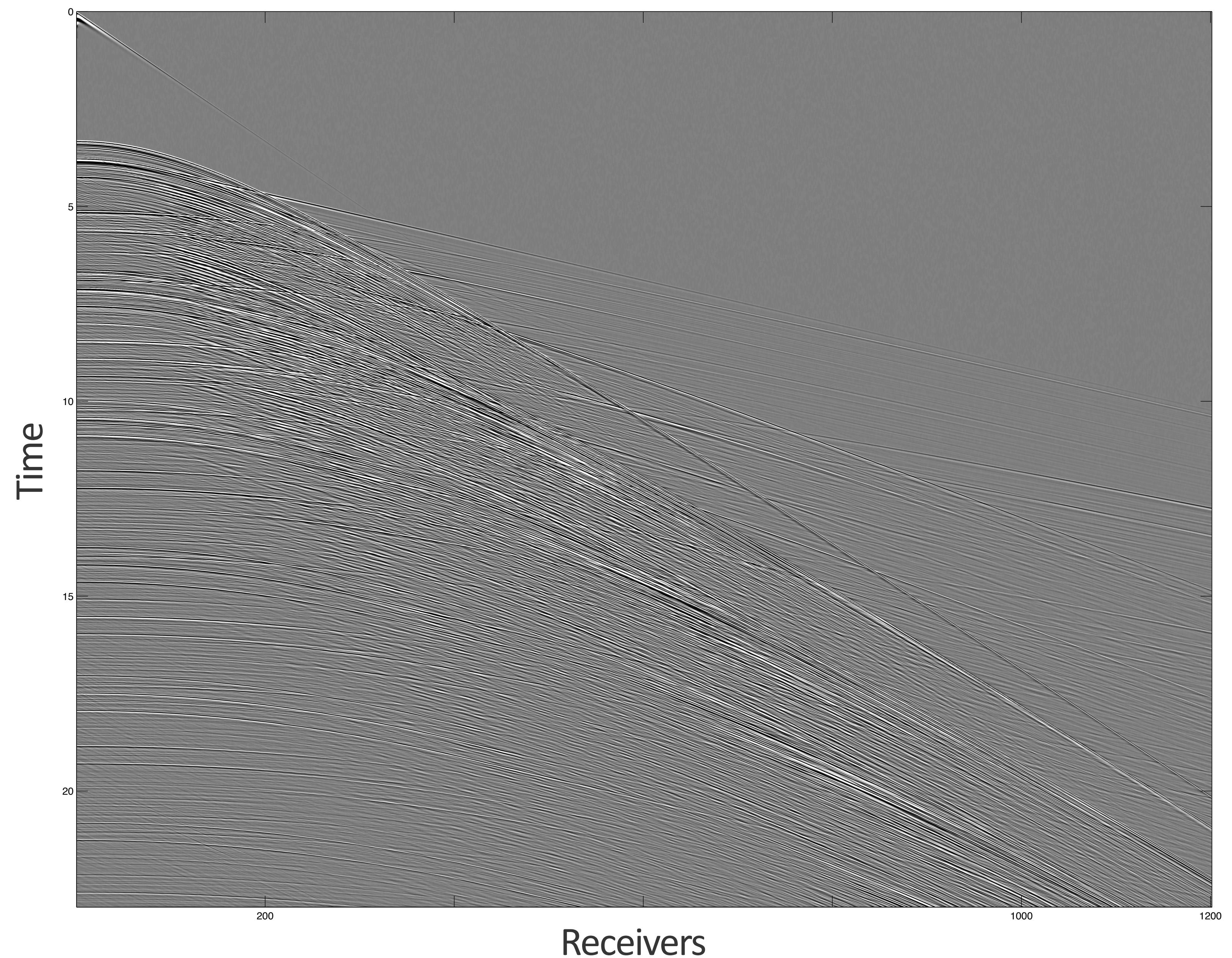
One shot record (2012)



One shot record

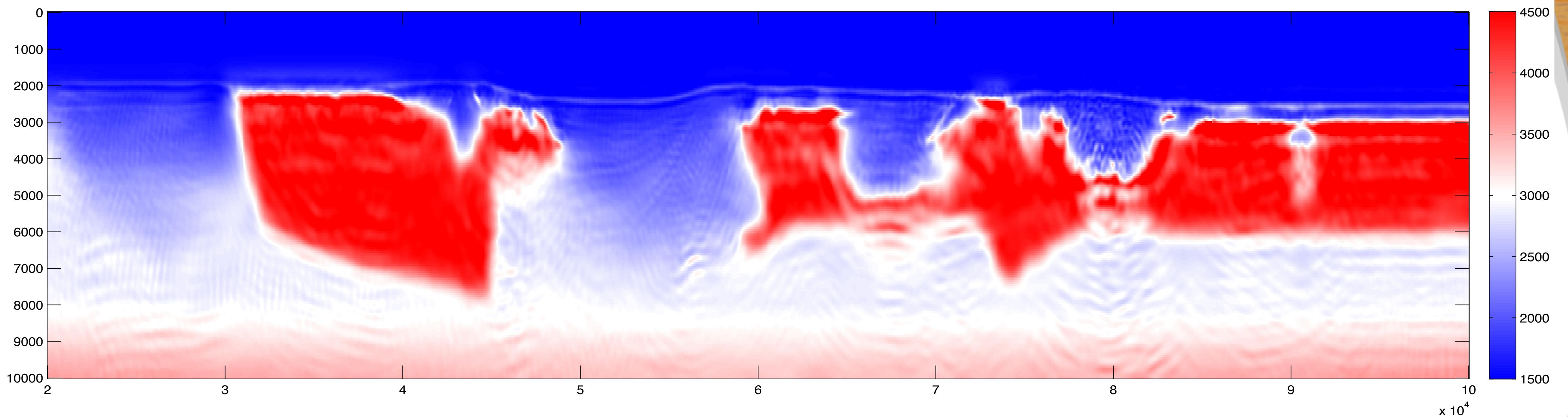


One shot record (2013)



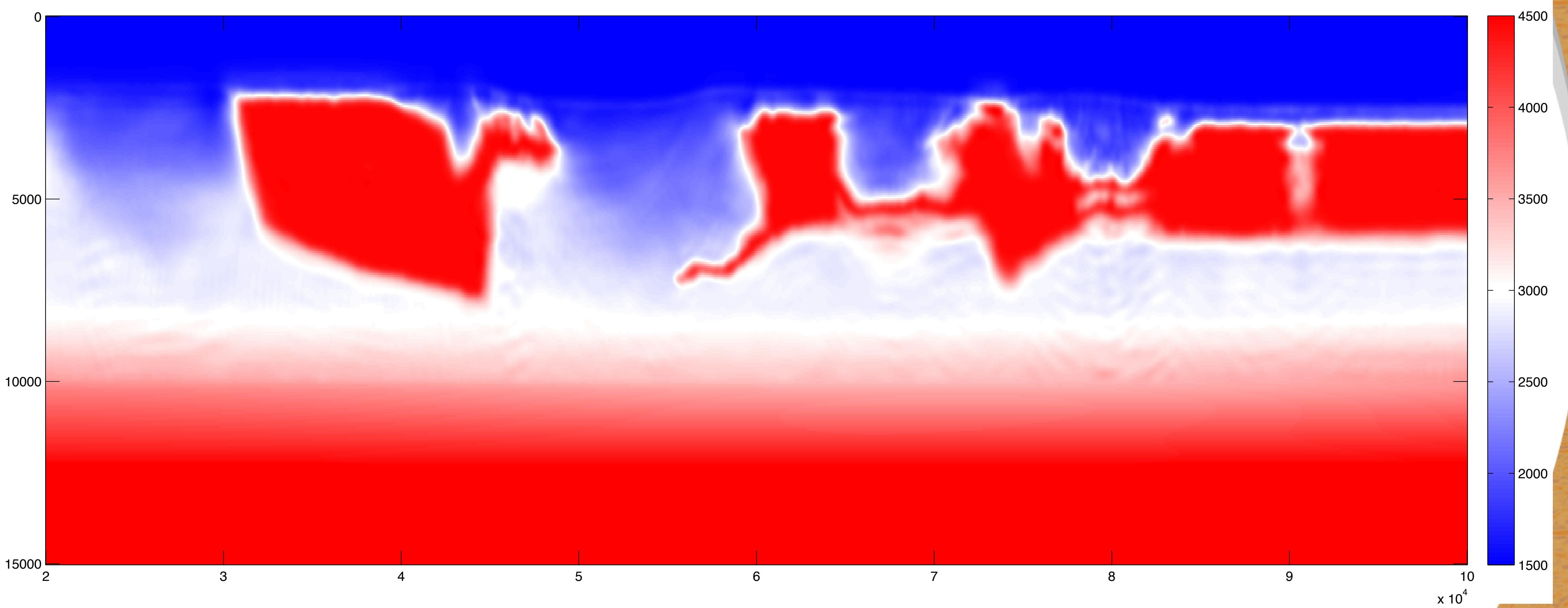
FWI result

with combined model and 2012 data set



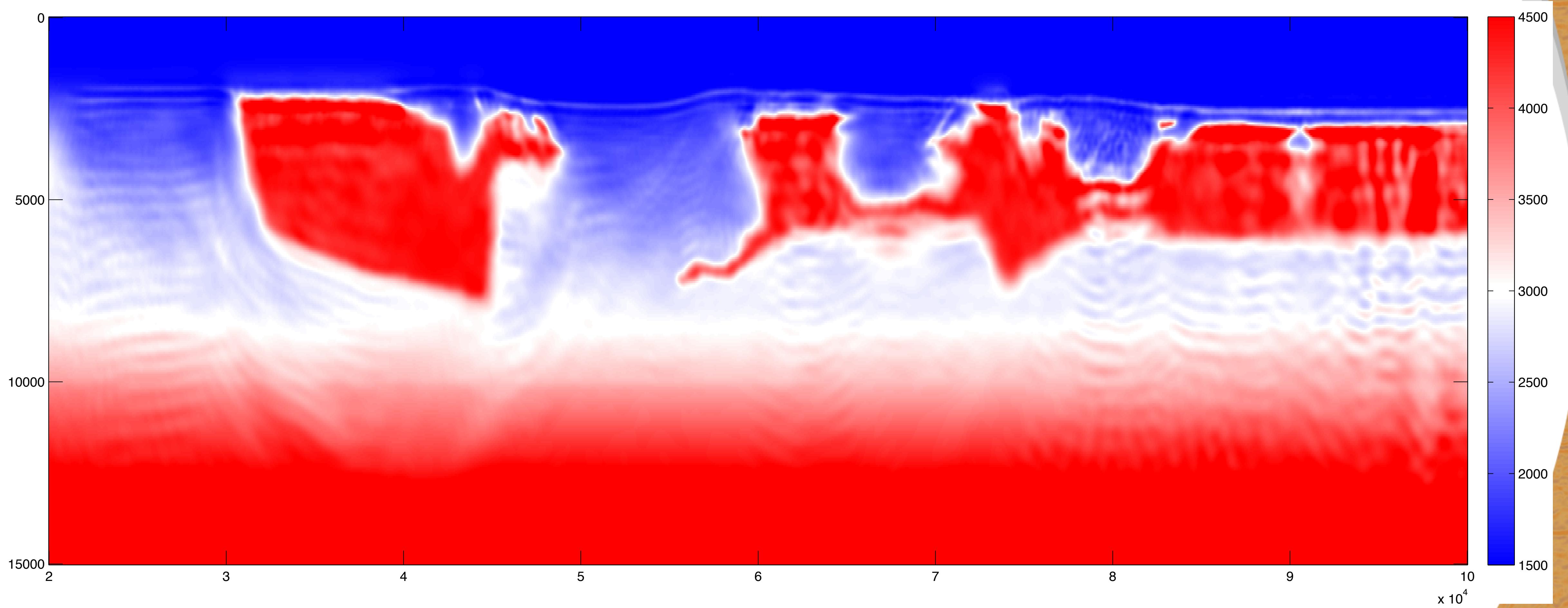
Initial model

salt correction & smoothing



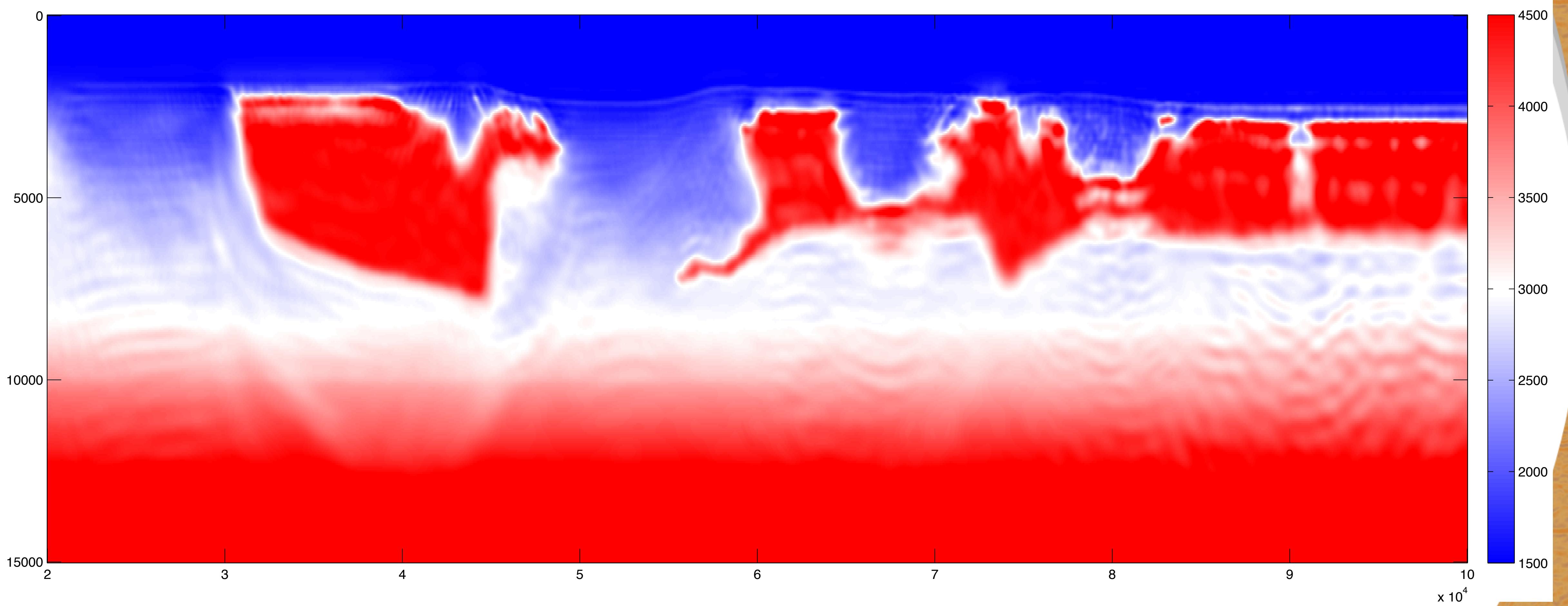
FWI result

inversion without free surface

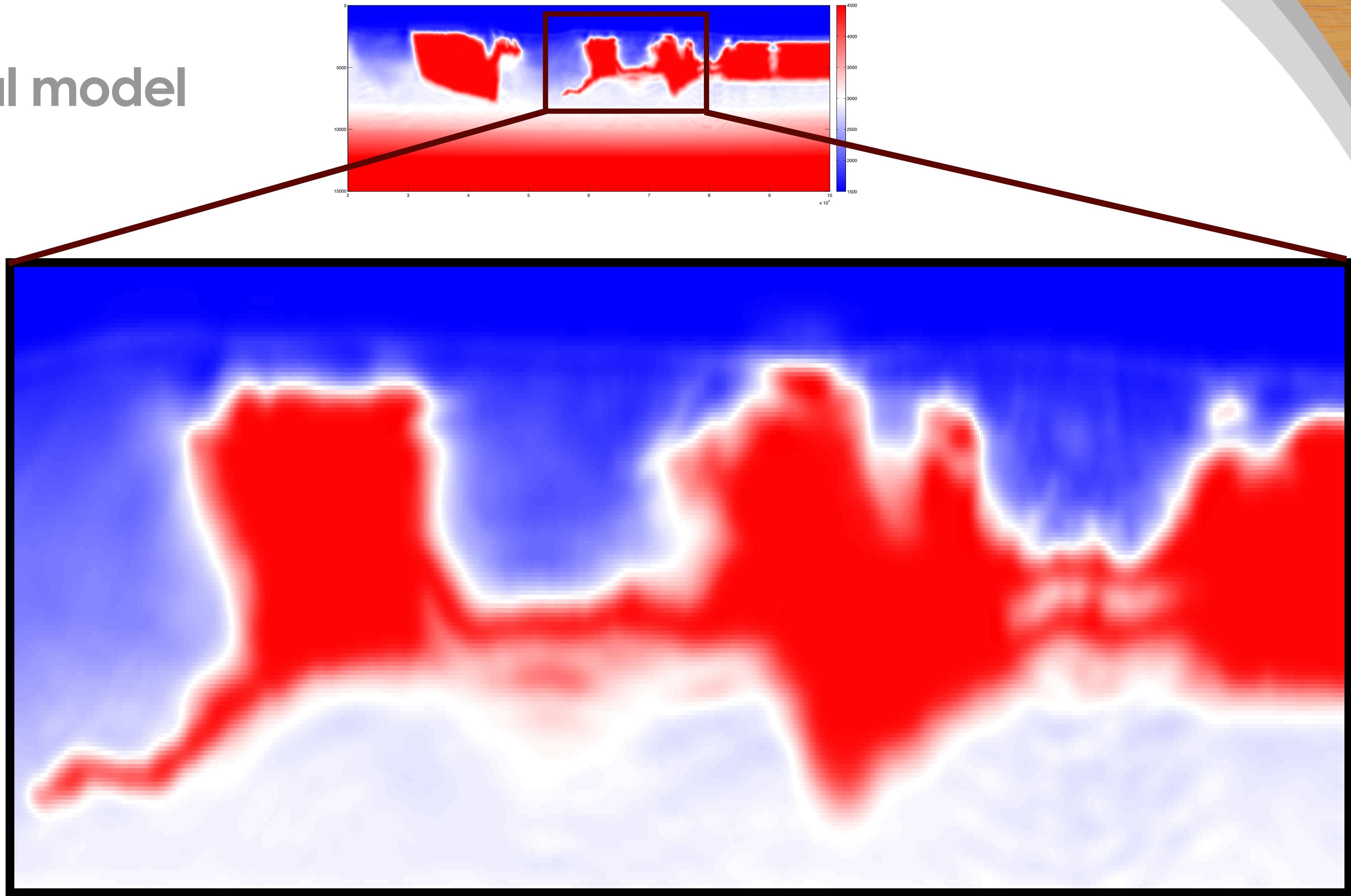


FWI result

inversion with free surface

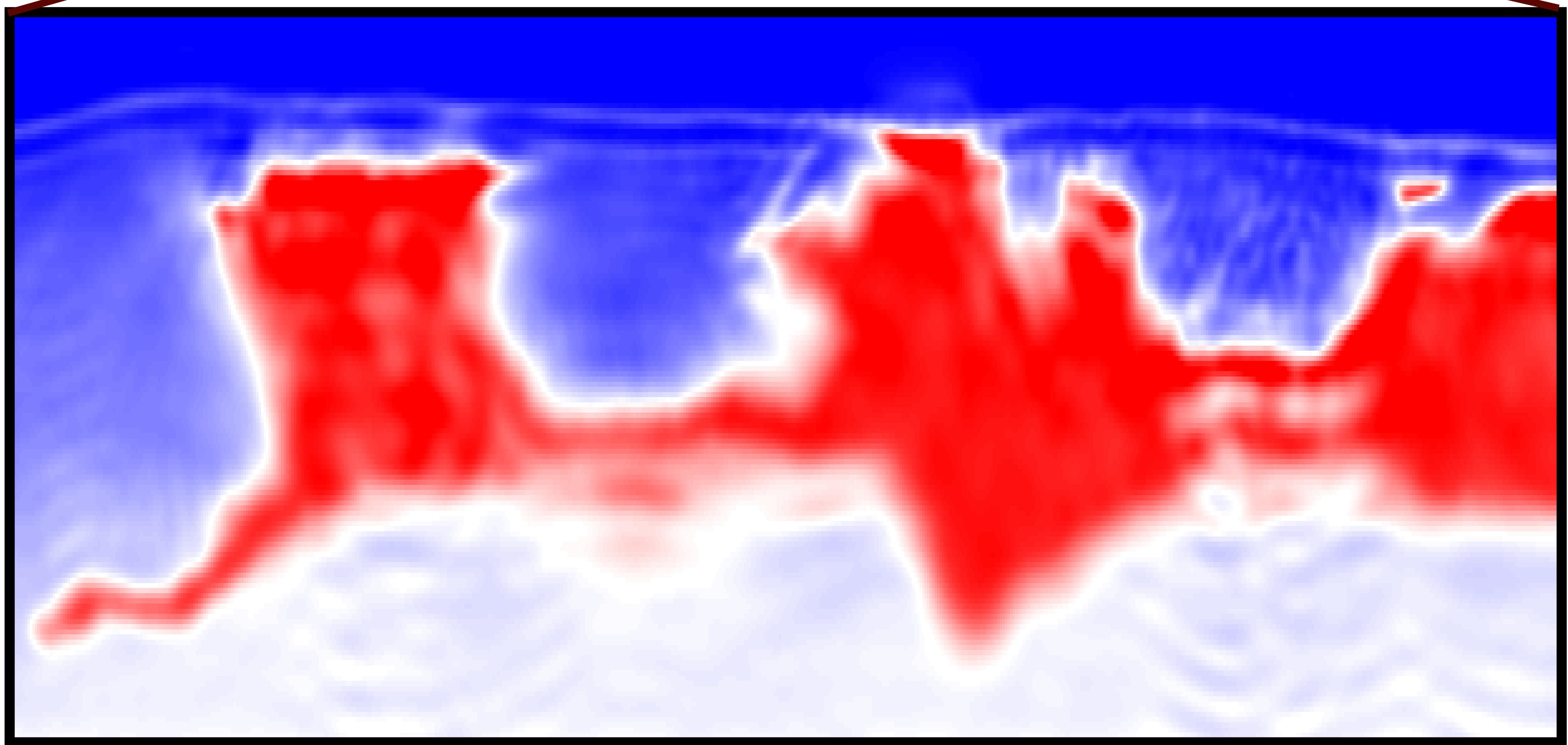


Initial model



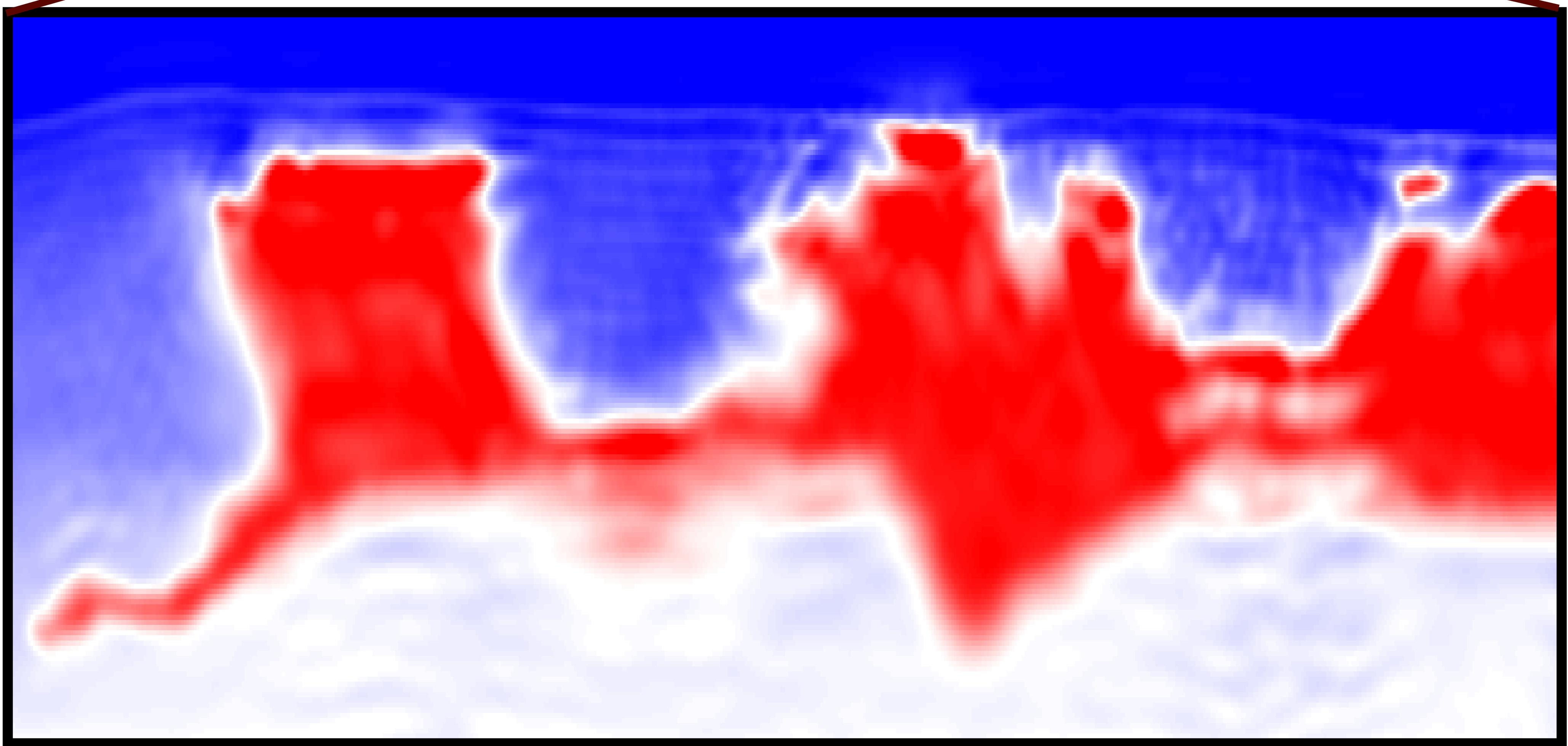
FWI result

w\o free surface

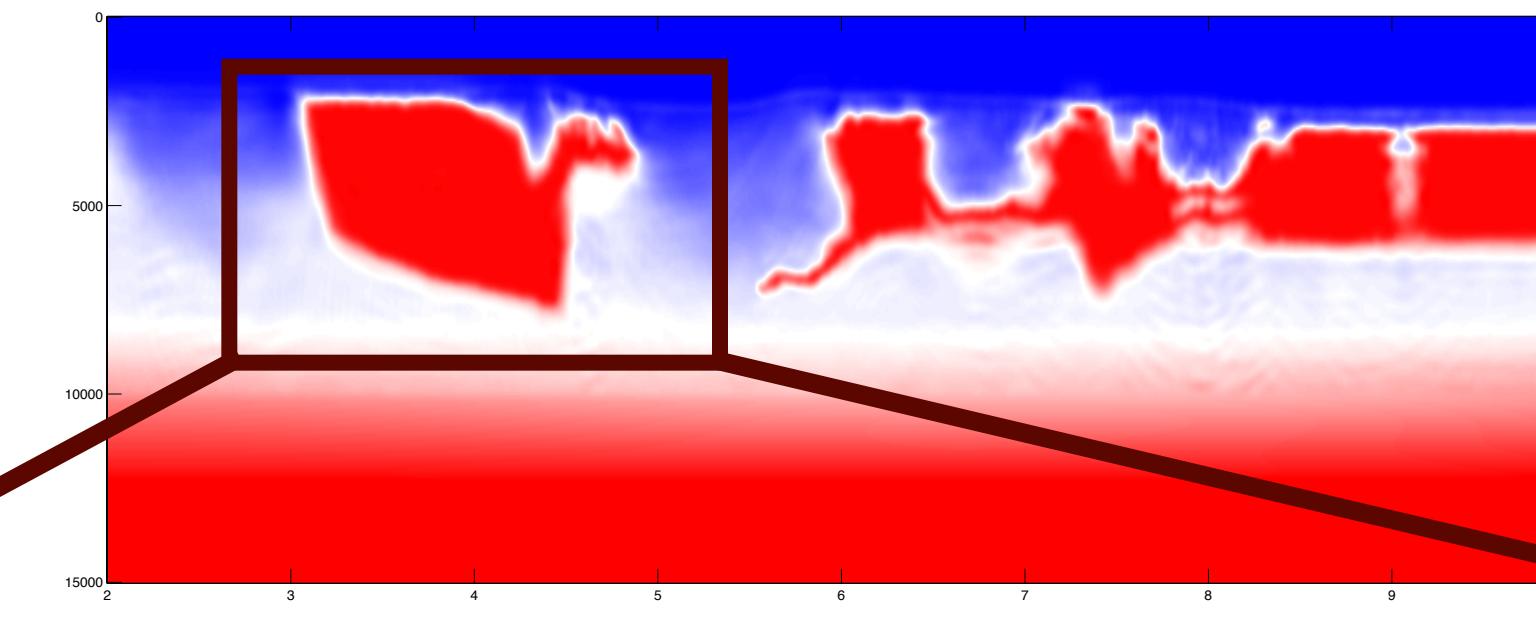
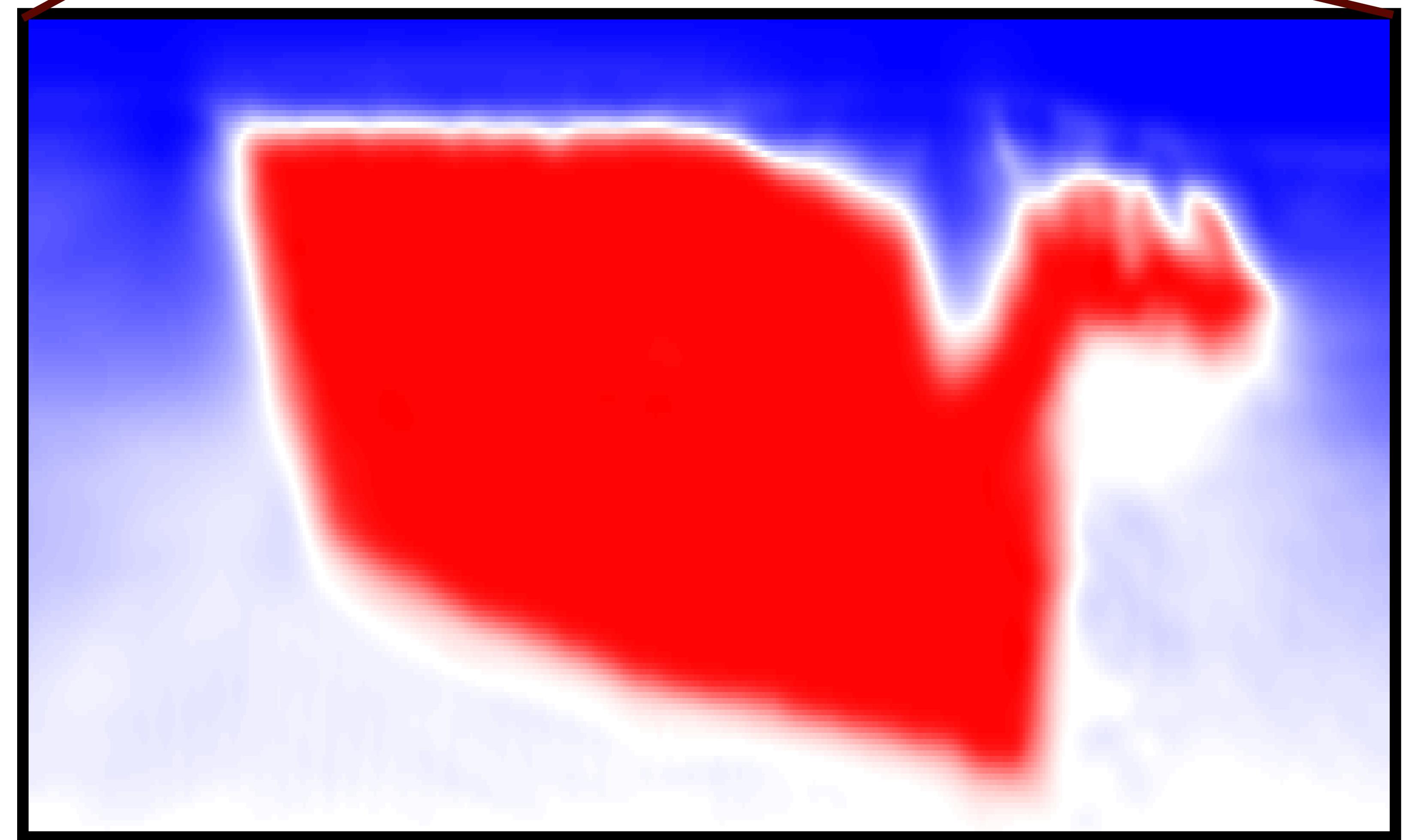


FWI result

w\ free surface

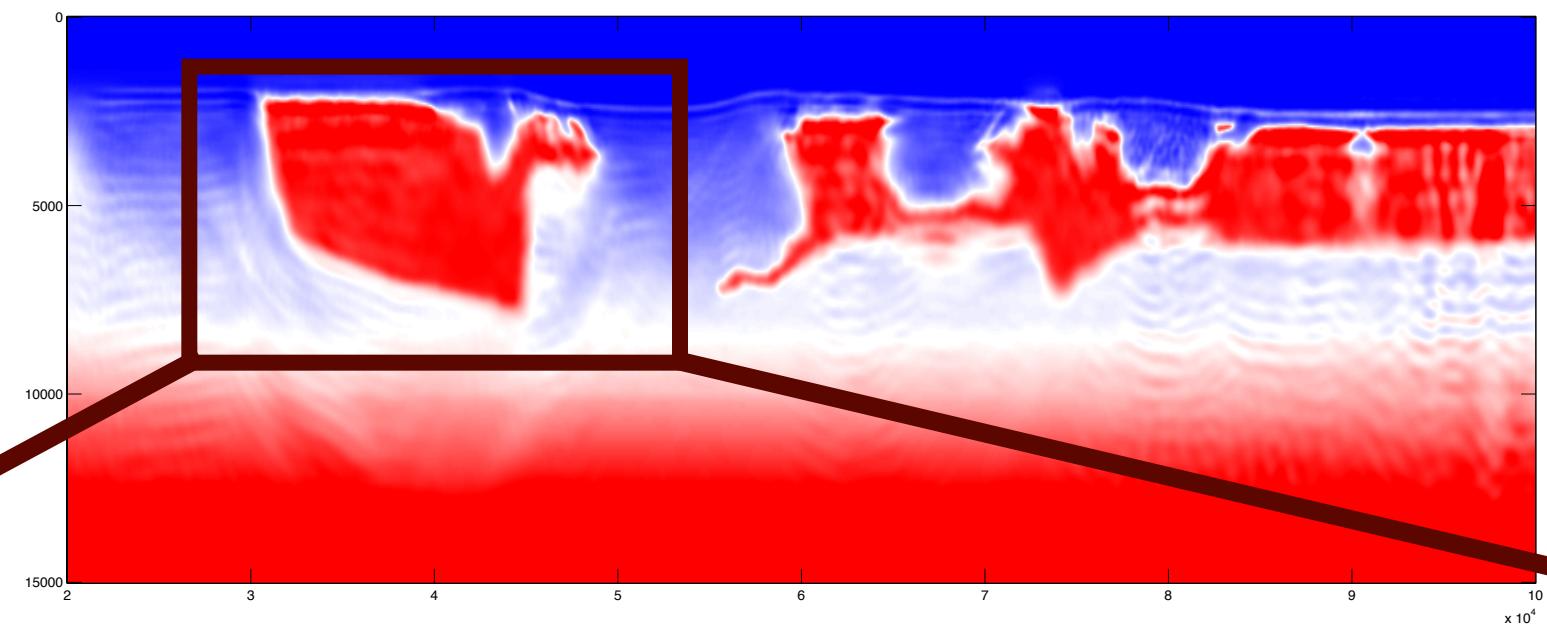
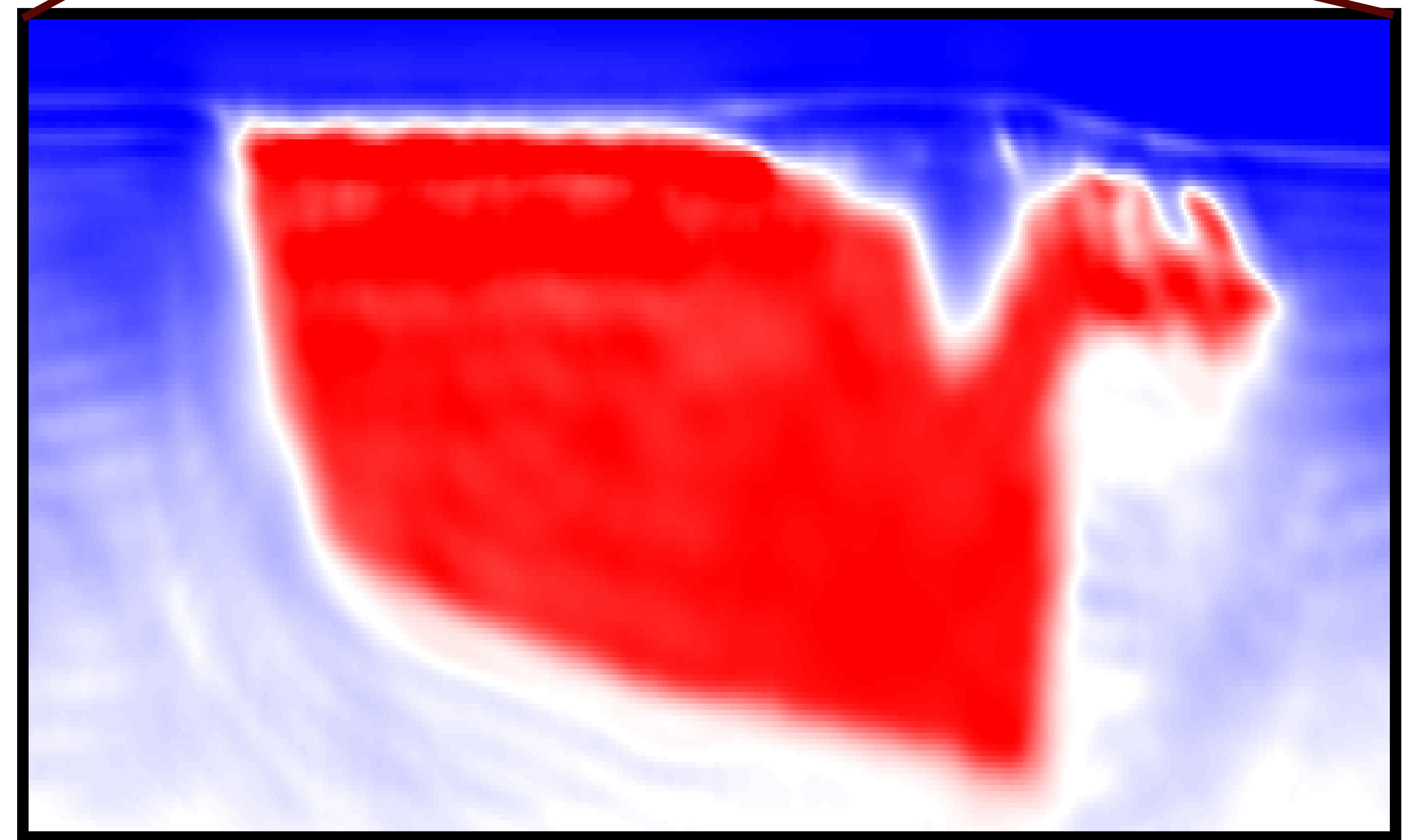


Initial model



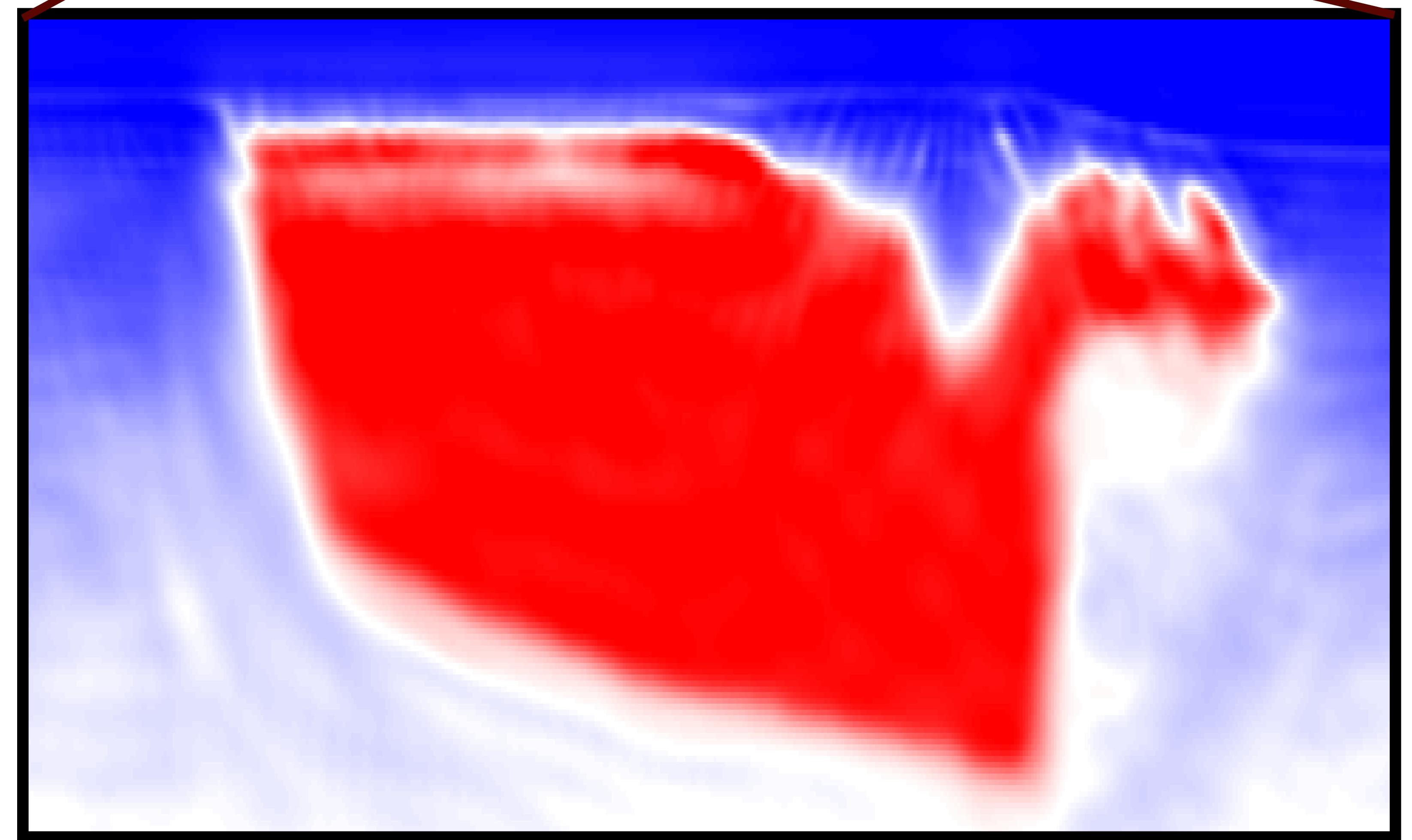
FWI result

w\o free surface



FWI result

w\ free surface





Observations

- Our FWI benefits from *initial model* and *curvelet denoising*
- *Curvelet* transform is efficient in representing *model updates* and “frequency slides”
- *Sparsity regularization* in Curvelet domain of *model updates* can significantly suppress model space artifacts
- “Salt flooding” is a way to help inversion get out of local minima

Acknowledgements

Thank you for your attention !

<https://www.slim.eos.ubc.ca/>



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