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Extended images in action (efficient AVA via probing)

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Motivation

- prohibitively expensive (storage & computation time)
- Full-subsurface offset volumes allow us to conduct AVA w/ geologic *dip* corrections using information from all offset directions.

• Computation of *full*-subsurface offset volumes is computationally



[Biondo & Symes, '04 ;Sava & Vasconcelos, '11]



horizontal offset horizontal +vertical offset

all offsets



•use all subsurface offsets (5D volume)

2-way wave-equation



but.... we can never hope to compute or store such an extended image volume!

Can we work with the extended volume implicitly ?



Overview

- Anatomy
- Computation
- Dip angle gather
- Application
- Conclusion
- Future work



Anatomy

$$e(\omega, \mathbf{x}, \mathbf{x}') = \sum_{i} u_i(\omega, \mathbf{x})$$

- Organize wavefields in monochromatic data matrices
- Express extended image volume tensor as matrix

$$E = U$$

 $\mathbf{x})v_i(\omega, \mathbf{x'})^*$

 \mathcal{T}^*



Extended images





- Complete image volume too large to form: $(n_x \times n_z)^2$
- instead, probe volume for information via mat-vecs Ew
- w can be interpreted as subsurface (sim.) source function

VAN LEEUWEN 2012



• *mat-vec* with extended image :

$\widetilde{E} = EW = H^{-1}P_s^T Q D^* P_r H^{-1} W$

- $\widetilde{\mathbf{d}} = P_r H^{-1} \mathbf{y}$ (one subsurface source)
- $\widetilde{E} = H^{-1} P_s^T Q \widetilde{\mathbf{w}}$ (one source)

• $\widetilde{\mathbf{w}} = D^* \widetilde{\mathbf{d}}$ (source weight)





Are able to compute full-subsurface offset extended images

- w/o looping over all source
- Probe image space w/ arbitrary test function

 - Gaussian weights (simultaneous source)

- point scatterers (one at location of subsurface point)



computation of an image point gathe

	# of PDE solves	"flops for correlations"
conventional	2Ns	$N_s \times N_h$
mat-vecs	2N _×	$N_s \times N_r$

 N_s - # of sources N_r - # of receivers N_h - # of subsurface offsets N_x - # of sample points



align subsurface offset with local dip







dip can be detected by measuring the stack-power normal to the dip





1000



dip can be detected by measuring the stack-power normal to the dip





• Compute image point gather

• determine dip

$$\tilde{\theta} = \arg \max_{\theta} \sum_{h} \left| \sum_{\omega} e(\omega) \right|_{\theta}$$

• extract offset along dip

$\omega, \mathbf{x}_i, \mathbf{x}(h, \theta + \pi/2))$



[de Bruin et al., 1990]

Dip angle gathers

Radon transform to compute angle gather

$$I(\mathbf{x}_i, p, \theta) = \sum_{\omega} \sum_{h}$$

where

 $p = \frac{k_x}{\omega} = \frac{\sin(\alpha)}{v}$

 $e(\omega, \mathbf{x}_i, \mathbf{x}(h, \theta))e^{\imath \omega p h}$





Applications

- Dip estimation
- AVA



Example









angle gathers for correct velocity, should all be flat







AVA [I-layer model]





- Zoeppritz equation
- Predicted response



AVA [dipping layer model]

velocity [m/s]



density [kg/m³]





AVA [dipping layer model]







AVA [marmousi model]







AVA [4-layer model]





AVA [4-layer model]



• Zoeppritz equation

• Predicted response



[Aki & Richards, 1980; Wijngaarden et al., 1995]

Acoustic impedance inversion [4 layer model]









Conclusion

- Probe image volume with *mat*-vecs
- Full subsurface offset help to estimate dip automatically
- Suitable for AVA at targeted regions



Future Work

• Explore the issues in acoustic impedance inversion

• Incorporate free-surface multiple to perform AVA analysis





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