

Matrix and Tensor Completion for Large-Scale Seismic Interpolation: A Comparative Study

Okan Akalin, Curt Da Silva, Rajiv Kumar
Ben Recht, Felix Herrmann



Quick Summary

- Problem: Large Scale Seismic Data Interpolation
- Approach: Matrix completion and tensor completion on different representations of seismic data
- Contribution: Posing the interpolation problem in the compressed sensing framework that allows scalable algorithms
- Outcome: Large scale interpolation problems can be solved efficiently by simple scalable algorithms

Outline

- Introduction
- Approach
- Experiments
- Conclusion & Future Work

Seismic Data Interpolation Problem

- Data is poorly sampled along a subset of modes
- Different from classical interpolation due to the nature of seismic data
 - Incomplete
 - Large volume
 - High dimensional
- Hence we need a space and time efficient algorithm for feasible analysis

Problem Setting

- 5-D data. Modes are time, source and receiver coordinates.
- Fourier transform is taken in time domain and a certain frequency slice is selected.
- 4.68Hz downsampled to 68x68x101x101
- 7.34Hz downsampled to 68x68x101x101
- 12.3Hz downsampled to 68x68x201x201

Structured Signal Recovery

- Fundamentally different from Shannon-Nyquist based approaches:
 - **Shannon-Nyquist based methods:** periodic sampling with costly sampling rate
 - **Structured recovery methods:** impose stronger structural requirements with milder sampling rates

CS-Based Recovery

- Every successful compressed sensing recovery scheme consists of three main components:
 - **Signal structure - sparsity:** a sparse signal in some dictionary
 - *Seismic images tend to be sparse in curvelet domain*
 - **Structure-destroying sampling operator:** a sampling operator that breaks the assumed structure of the signal
 - **Structure-promoting optimization program:** a formulation which favors the sparsest signal that fits our data

Outline

- Introduction
- Approach
 - Matrix Completion
 - Tensor Completion
 - Low Rank Promoting Organization
 - Structure Promoting Optimization Program
- Experiments
- Conclusion & Future Work

Matrix Completion

- Matrix completion is the problem of filling the missing entries based on the observations
- Ill posed unless we assume structure: low-rank!
- The CS framework can be easily extended for the matrix completion problem.

Matrix Completion

- The original matrix completion problem

$$\begin{aligned} &\text{minimize} && \text{rank}(\mathbf{X}) \\ &\text{subject to} && X_{ij} = M_{ij} \quad (i, j) \in \Omega \\ &&& \mathbf{X} \in \mathbb{R}^{n \times n}, \end{aligned}$$

- Its convex relaxation that is tractable

$$\begin{aligned} &\text{minimize} && \|\mathbf{X}\|_* \\ &\text{subject to} && X_{ij} = M_{ij} \quad (i, j) \in \Omega. \end{aligned}$$

$$\|X\|_* = \sum_i \sigma_i(X)$$

Matrix Completion

- Three pillars:
 - **Signal Structure - Low Rank:** For a matrix, a direct analogue of sparsity in the signal domain is sparsity in singular value spectrum
 - **Structure-destroying sampling operator:**
Random sampling of entries!
 - **Structure-promoting optimization program:**

$$\begin{aligned} \min \quad & \|\mathbf{X}\|_* \\ \text{s.t.} \quad & \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2 \leq \sigma \end{aligned}$$

Matrix Completion

- Three different formulations:
- Basis Pursuit Denoising (BPDN) formulation

$$\begin{aligned} \min \quad & \|\mathbf{X}\|_* \\ \text{s.t.} \quad & \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2 \leq \sigma \end{aligned}$$

- Quadratic Programming (QP) Formulation

$$\min_{\mathbf{X}} \frac{1}{2} \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2^2 + \lambda \|\mathbf{X}\|_*$$

- LASSO Formulation

$$\begin{aligned} \min_{\mathbf{X}} \quad & \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2^2 \\ \text{s.t.} \quad & \|\mathbf{X}\|_* \leq \tau \end{aligned}$$

Matrix Completion

- Basis Pursuit Denoising (BPDN) formulation

$$\begin{aligned} \min \quad & \|\mathbf{X}\|_* \\ \text{s.t.} \quad & \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2 \leq \sigma \end{aligned}$$

- The parameter σ can be naturally interpreted as the noise level
- Challenging to solve

Matrix Completion

- (Quadratic Programming) QP Formulation

$$\min_{\mathbf{X}} \frac{1}{2} \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2^2 + \lambda \|\mathbf{X}\|_*$$

- λ parameter does not have a natural interpretation, hard to pick in the noisy case
- Time and space efficient scalable algorithms exist to solve the QP formulation

Matrix Completion

- LASSO Formulation

$$\begin{aligned} \min_{\mathbf{X}} \quad & \|\mathcal{A}(\mathbf{X}) - \mathbf{B}\|_2^2 \\ \text{s.t.} \quad & \|\mathbf{X}\|_* \leq \tau \end{aligned}$$

- Needs an estimate on the rank of the matrix, much harder than the estimation of the noise level
- Can be solved efficiently

Outline

- Introduction
- Approach
 - Matrix Completion
 - Tensor Completion
 - Low Rank Promoting Organization
 - Structure Promoting Optimization Program
- Experiments
- Conclusion & Future Work

Tensor Completion

- The low rank idea can also be applied in the tensor completion setting.
- However the problem is much harder:
 - Even tensor rank is very hard to compute (NP-Complete!)
 - Fixed rank tensors do not form a closed set (a lowest rank approximation may not exist at all!)
 - A lack of theoretical framework for the completion problem

Tensor Completion

- An alternative (and popular) method is penalizing the rank of matricizations of the tensor

$$\begin{aligned} \min_{\mathbf{D}} \quad & \sum_{i=1}^4 \|\mathbf{D}^{(i)}\|_* \\ \text{s.t.} \quad & \|\mathcal{A}(\mathbf{D}) - b\|_2 \leq \sigma \end{aligned}$$

- Since this formulation uses nuclear norm, the problem is tractable
- It is unclear why this combination of nuclear norms is supposed to work

Tensor Completion

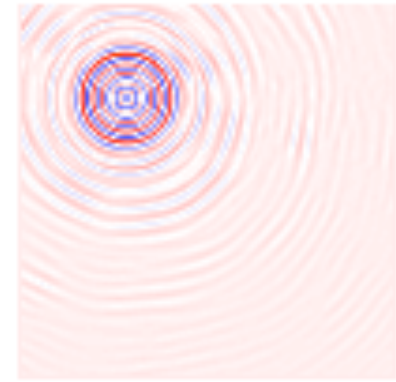
- Actually when the sampling operator is Gaussian, the sample complexity can be bounded below by the greatest sample complexity amongst all matricizations
- It is impossible to outperform the single most successful matricization
- Gaussian sampling does not fit in the tensor completion framework, however empirical evidence suggests a similar argument might still hold.

Outline

- Introduction
- Approach
 - Matrix Completion
 - Tensor Completion
 - Low Rank Promoting Organization
 - Structure Promoting Optimization Program
- Experiments
- Conclusion & Future Work

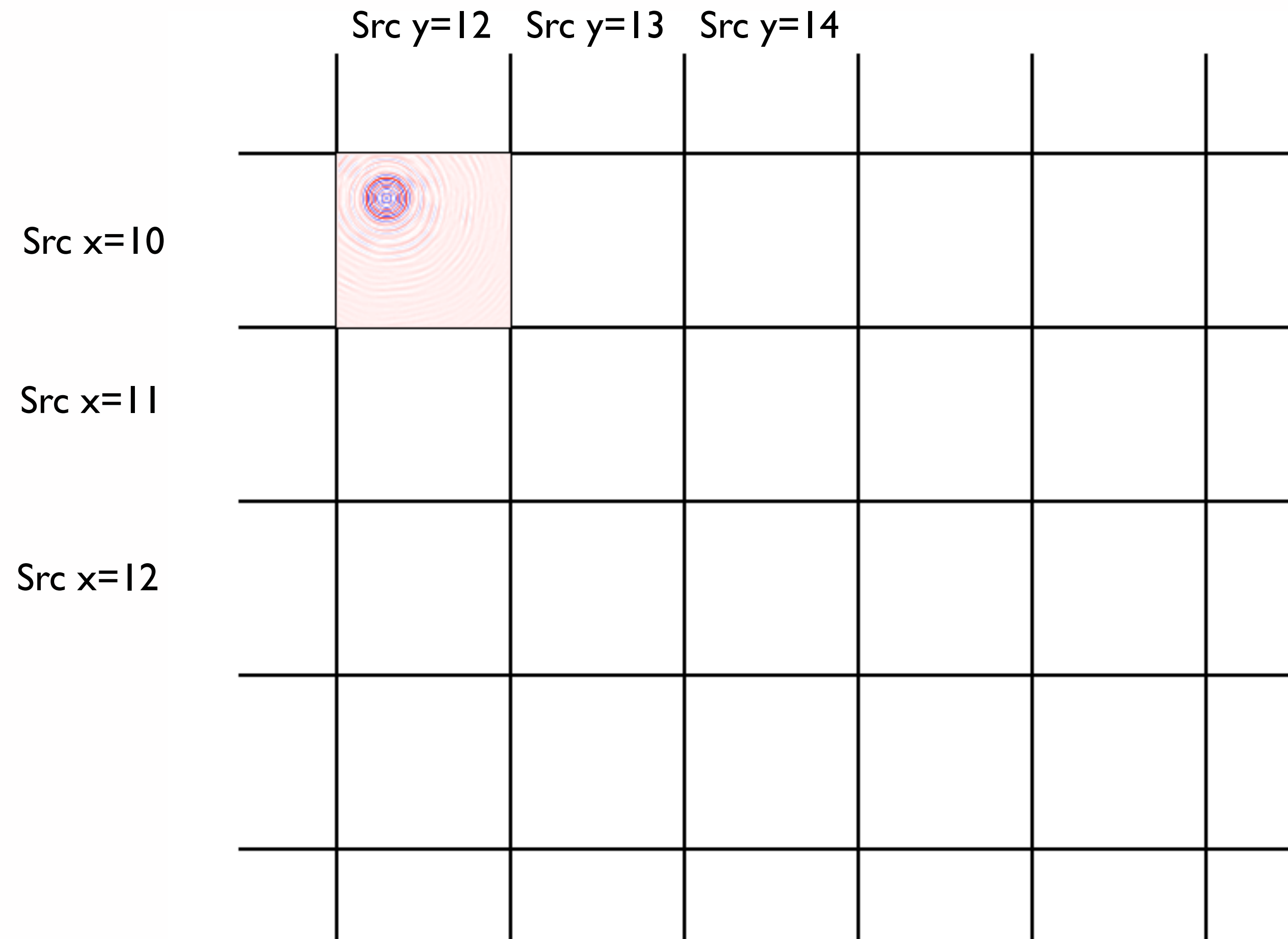
Low Rank Promoting Organization

(src x, src y)=(10,12)

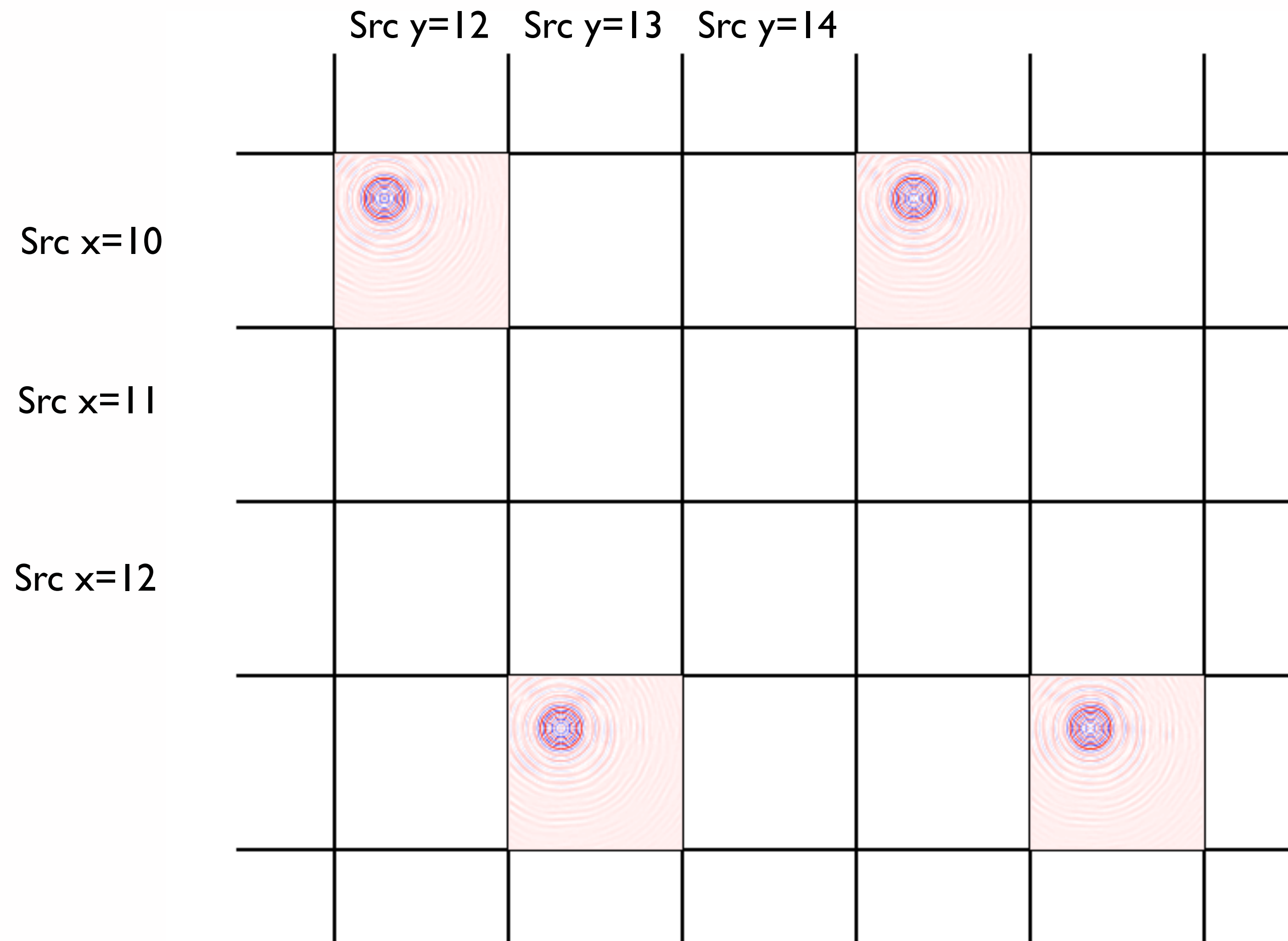


Fixing source coordinates, we obtain a specific shot

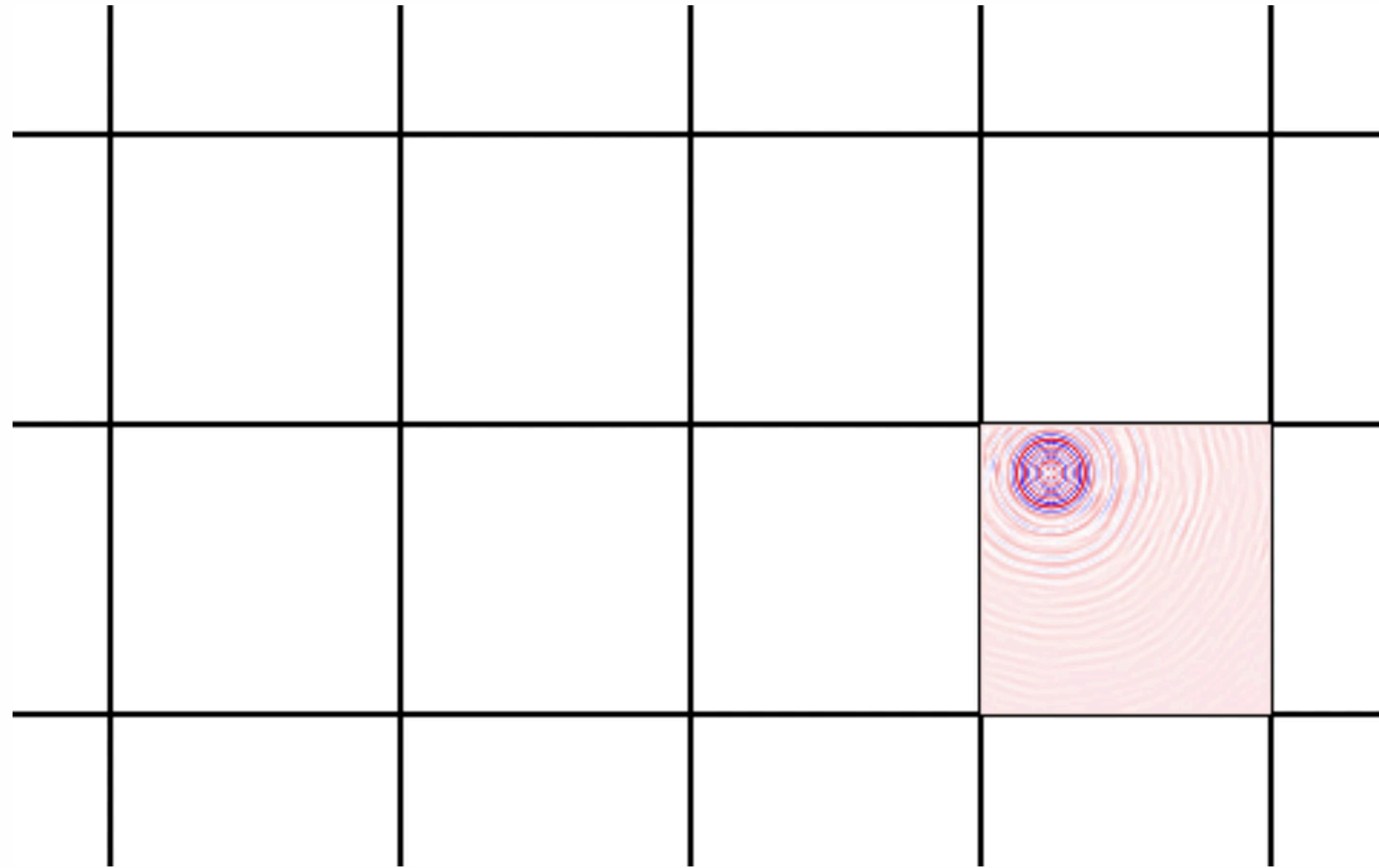
Low Rank Promoting Organization



Low Rank Promoting Organization



Low Rank Promoting Organization



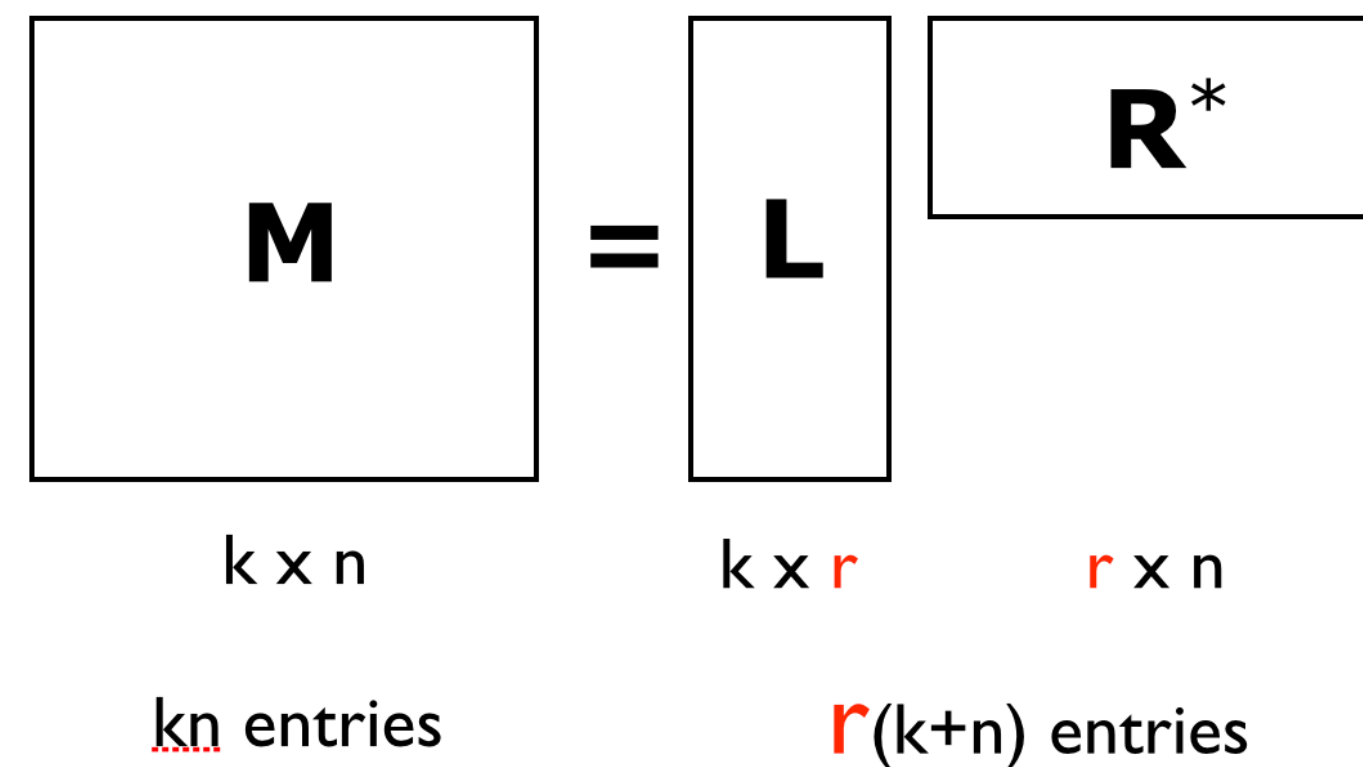
Outline

- Introduction
- Approach
 - Matrix Completion
 - Tensor Completion
 - Low Rank Promoting Organization
 - Structure Promoting Optimization Program
- Experiments
- Conclusion & Future Work

Jellyfish

- Jellyfish solves a relaxation of the QP program which is equivalent to the original program:

$$\text{minimize}_{(\mathbf{L}, \mathbf{R})} \sum_{(u,v) \in E} \{ (\mathbf{L}_u \mathbf{R}_v^T - M_{uv})^2 + \mu_u \|\mathbf{L}_u\|_F^2 + \mu_v \|\mathbf{R}_v\|_F^2 \}$$



Jellyfish

- This formulation allows application of stochastic gradient descent algorithm which can be highly parallelized by proper sampling of data points
- Can scale to GB sized matrices on workstations
- Jellyfish explicitly compresses the matrix by factorizing it

SPGL1

- Successively solves LASSO problems, updating τ at each iteration:

$$\tau^{k+1} = \tau^k - \frac{v(\tau) - \eta}{v'(\tau)}$$

- where

$$v(\tau) = \min_x \rho(\mathcal{A}(x) - b) \quad \text{s.t.} \quad \|x\| \leq \tau$$

Tensor Completion

- For tensor completion, the objective function is:

$$J(\mathcal{D}, \mathcal{Y}_i, \mathcal{W}_i) = \frac{\lambda}{2} \|\mathcal{T}\mathcal{D} - \mathbf{d}^{obs}\|_F^2 + \sum_{i=1}^4 \left(\|\mathbf{Y}_i^{(i)}\|_* - \langle \mathcal{W}_i, \mathcal{D} - \mathcal{Y}_i \rangle + \frac{\beta}{2} \|\mathcal{D} - \mathcal{Y}_i\|_F^2 \right)$$

- This is the ADMM reformulation of the original problem.

Gandy, S., Recht, B., & Yamada, I. (2011). Tensor completion and low-n-rank tensor recovery via convex optimization. *Inverse Problems*, 27(2), 025010.

Kreimer, N. , Stanton, A., Sacchi, M. (2013). Tensor completion based on nuclear norm minimization for 5D seismic data reconstruction

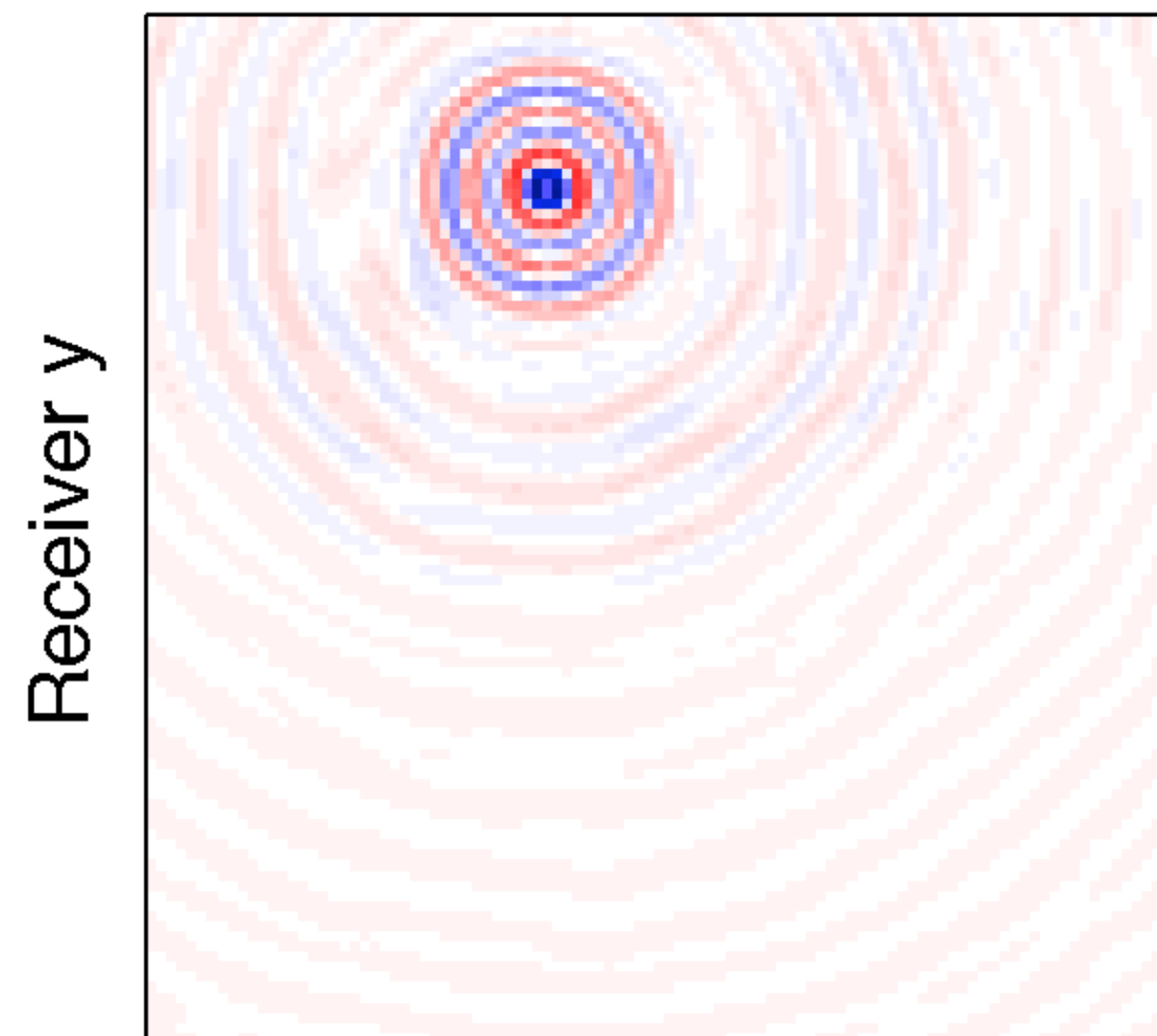
Outline

- Introduction
- Approach
- Experiments
- Conclusion & Future Work

Matrix Completion Results

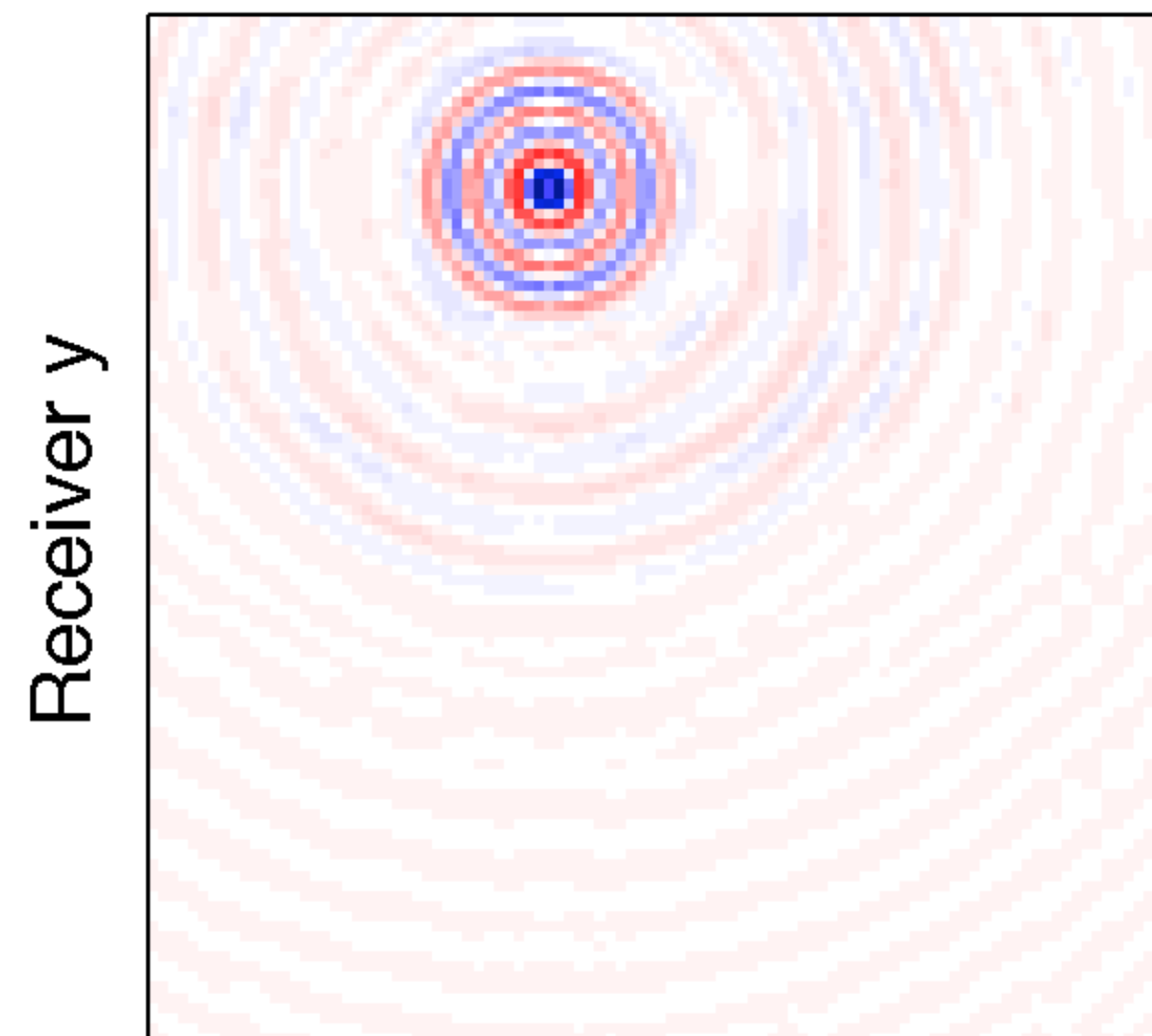
Freq 4.68Hz (Source x, Source y)=(12, 27) Sampling Ratio: 0.25

Ground Truth



Receiver x

Jellyfish estimation, SNR: 14.009181



Receiver x

Residual

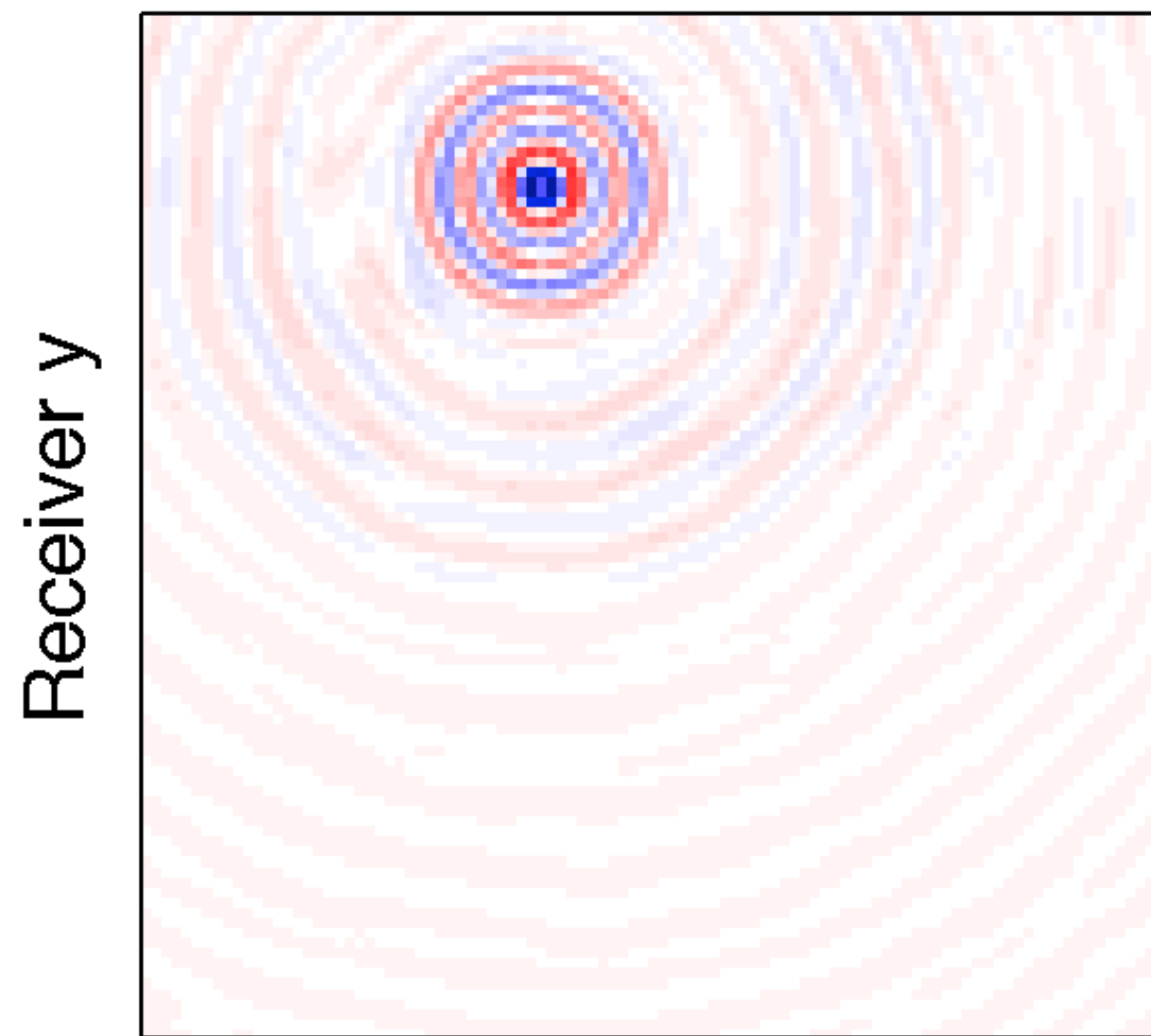


Receiver x

Matrix Completion Results

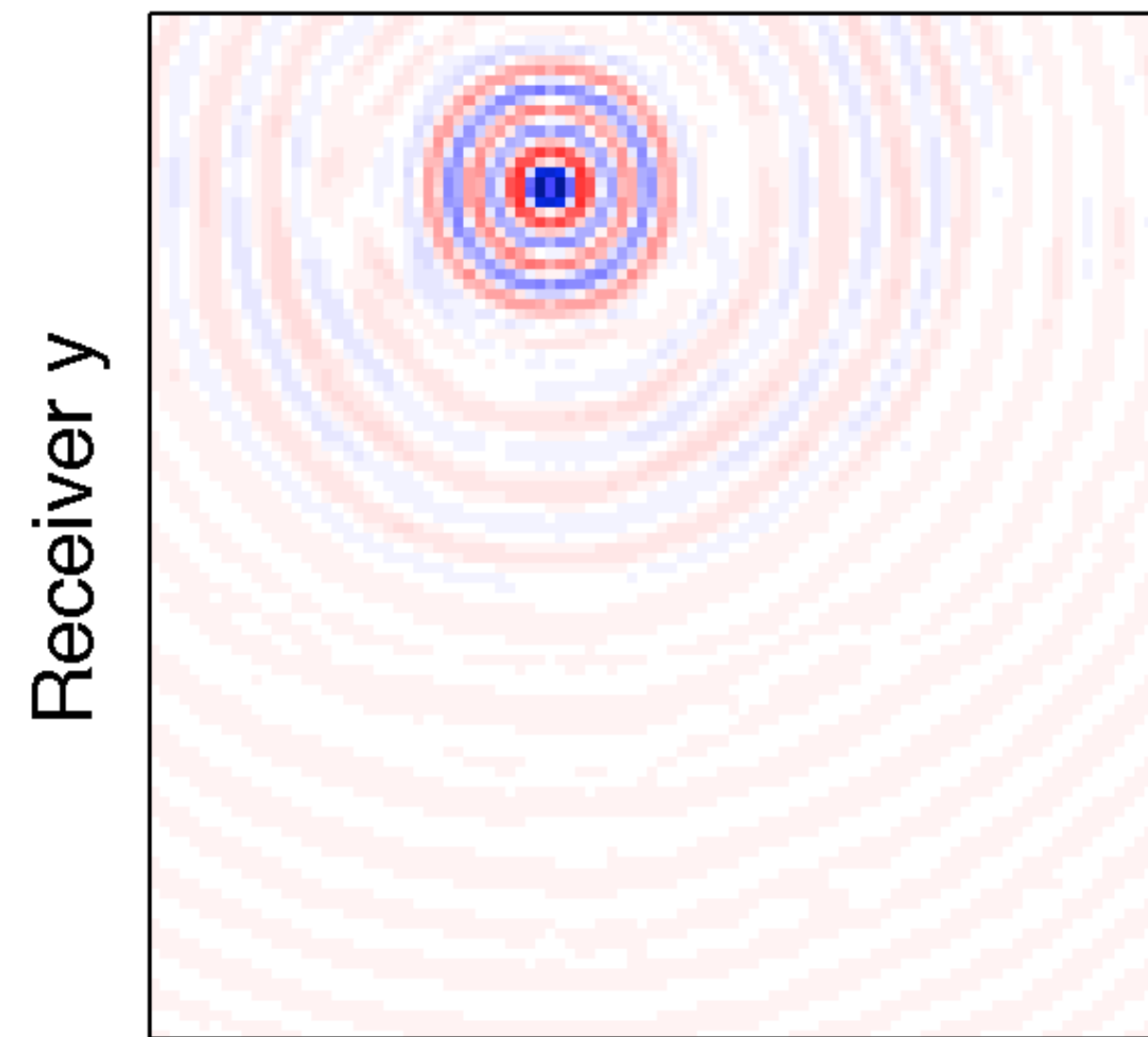
Freq 4.68Hz (Source x, Source y)=(12, 27) Sampling Ratio: 0.75

Ground Truth



Receiver x

Jellyfish estimation, SNR: 20.231058



Receiver x

Residual

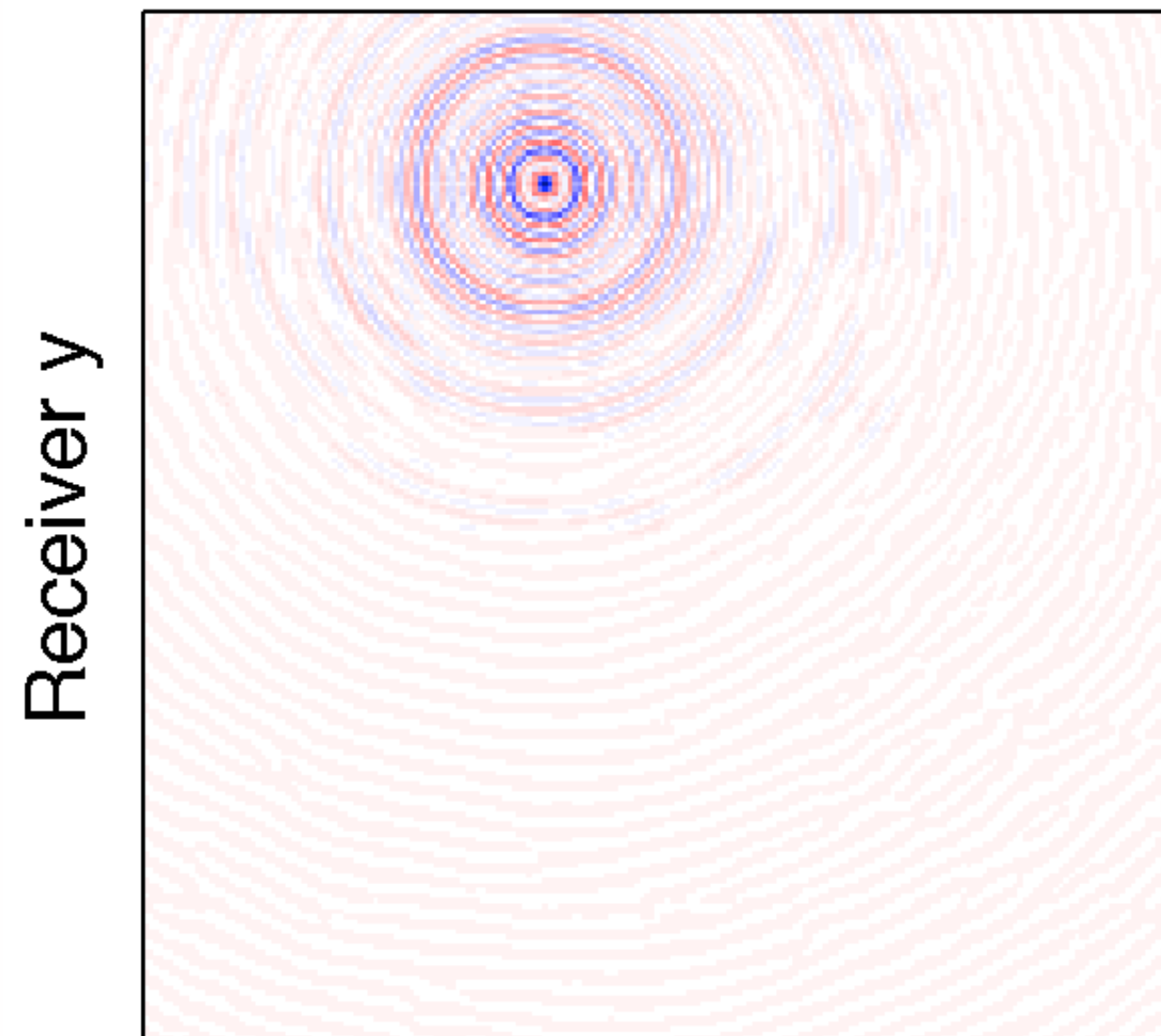


Receiver x

Matrix Completion Results

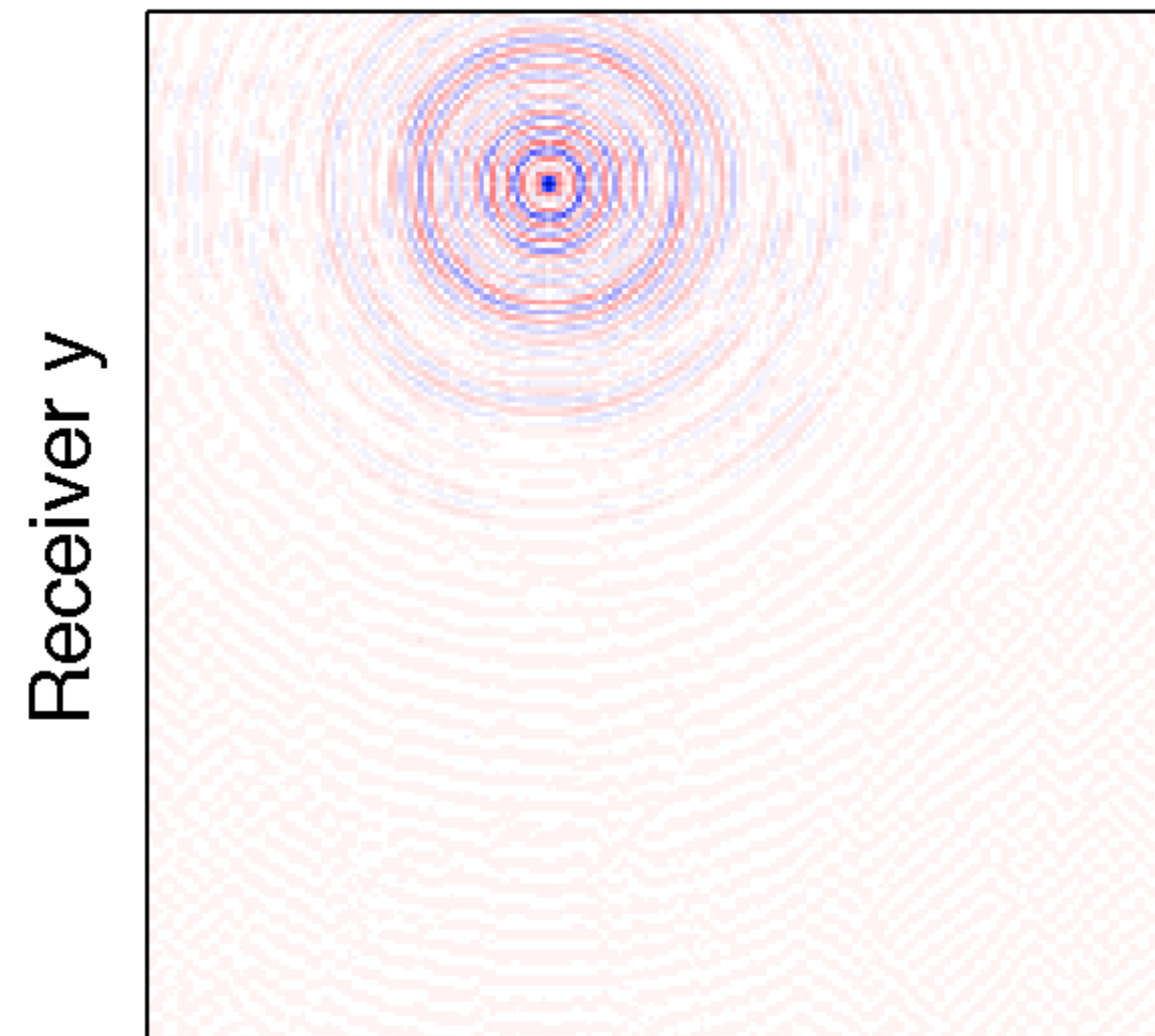
Freq 12.30Hz (Source x, Source y)=(12, 27) Sampling Ratio: 0.25

Ground Truth



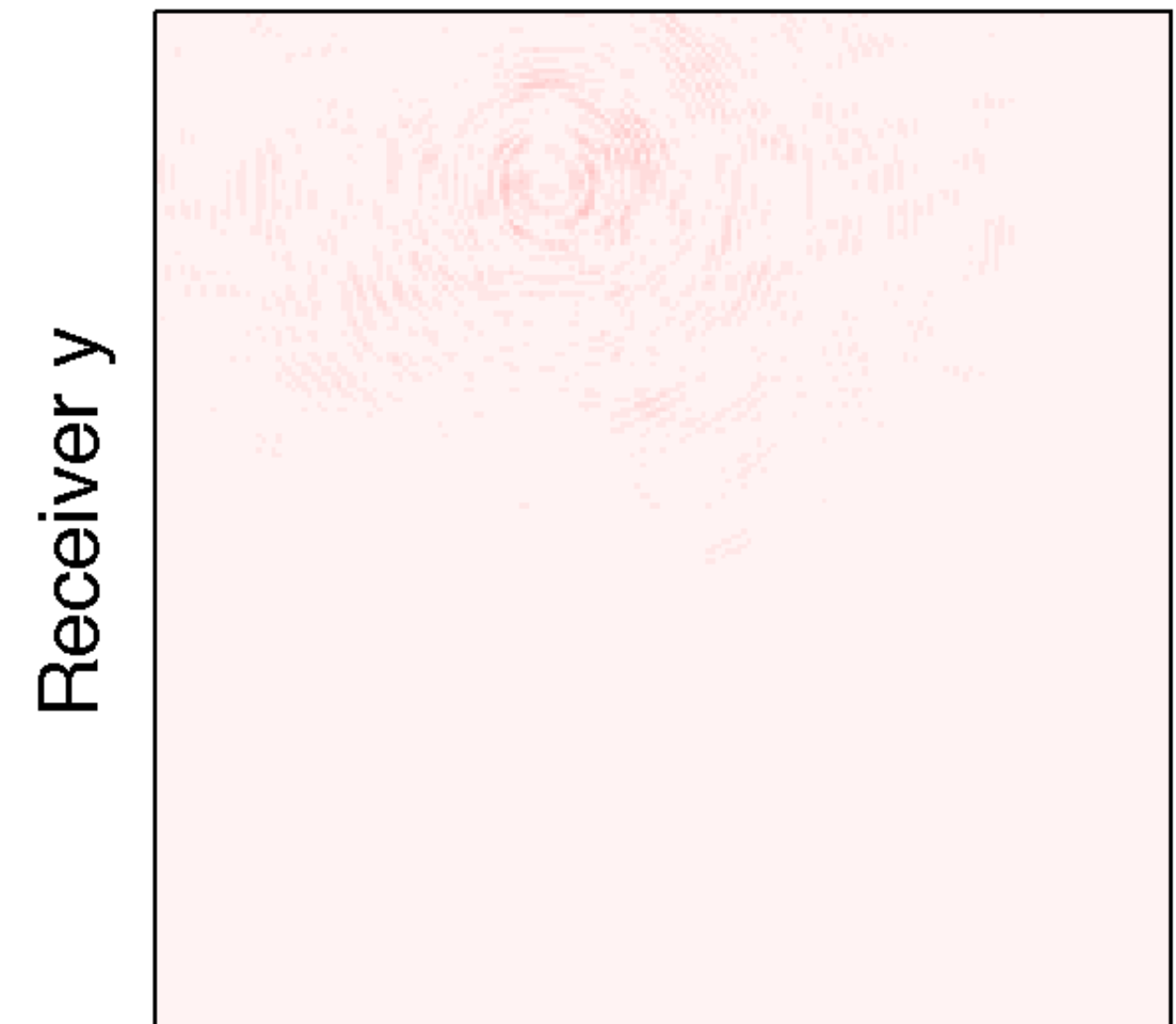
Receiver x

Jellyfish estimation, SNR: 8.662400



Receiver x

Residual

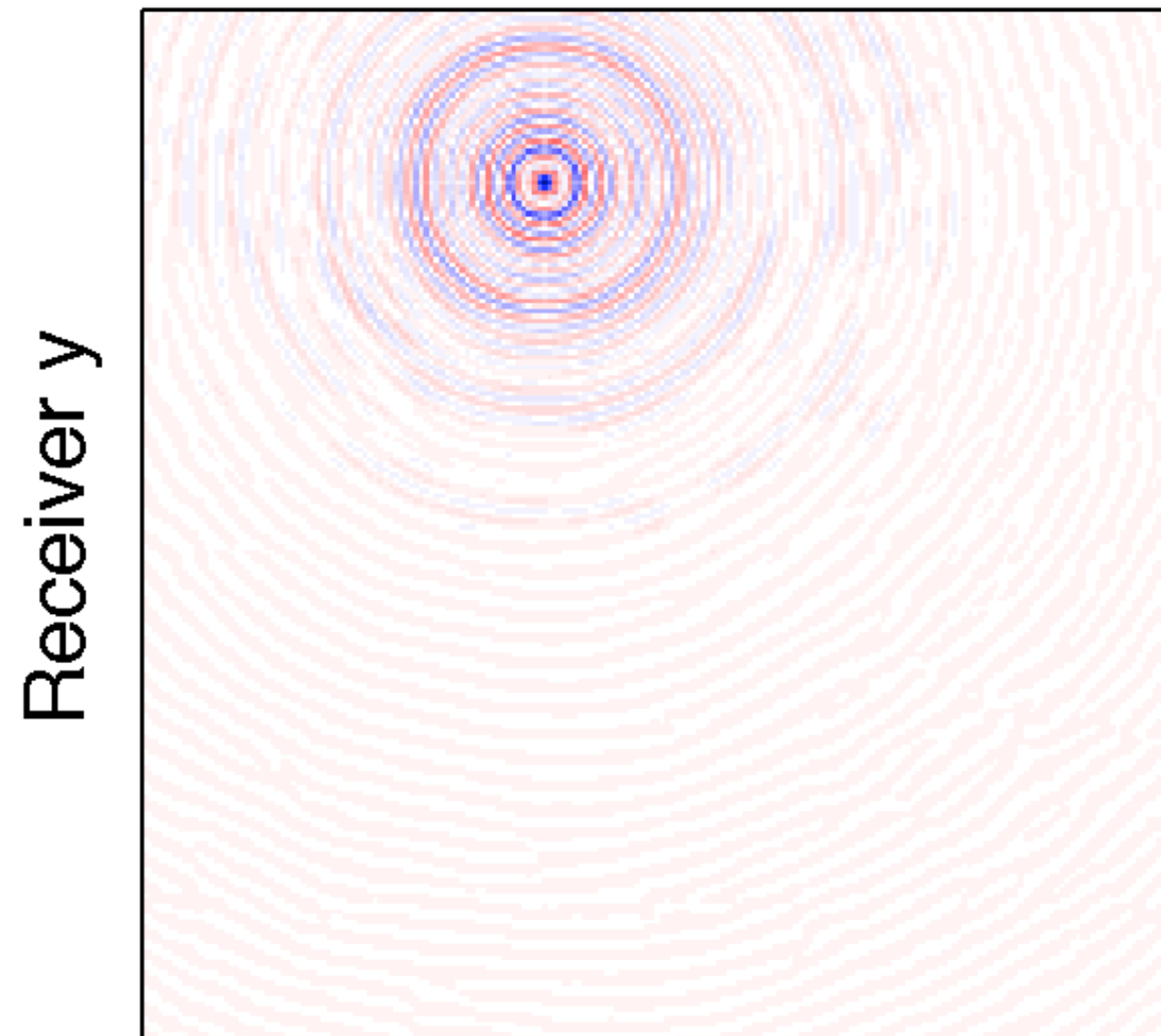


Receiver x

Matrix Completion Results

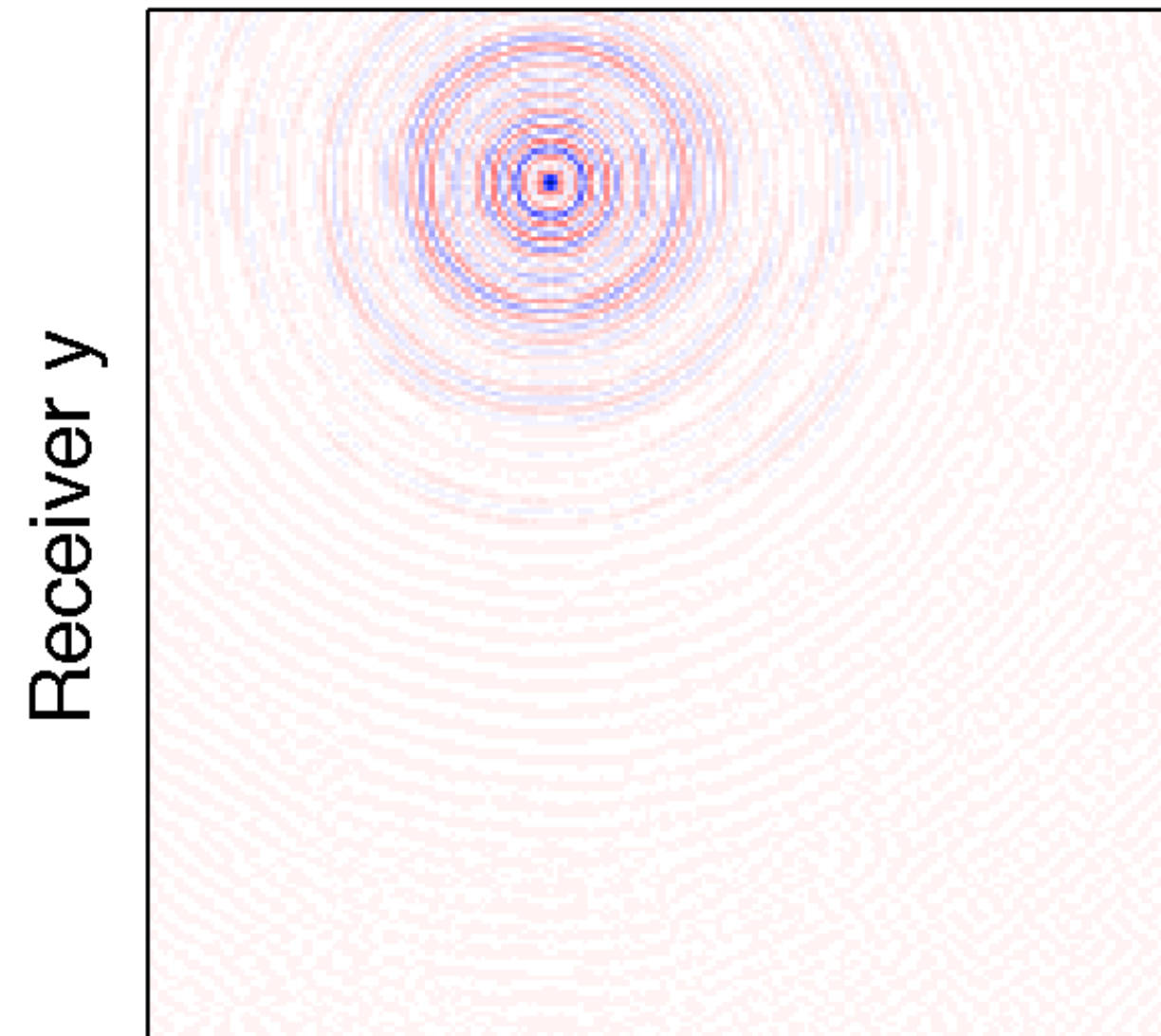
Freq 12.30Hz (Source x, Source y)=(12, 27) Sampling Ratio: 0.75

Ground Truth



Receiver x

Jellyfish estimation, SNR: 11.950294



Receiver x

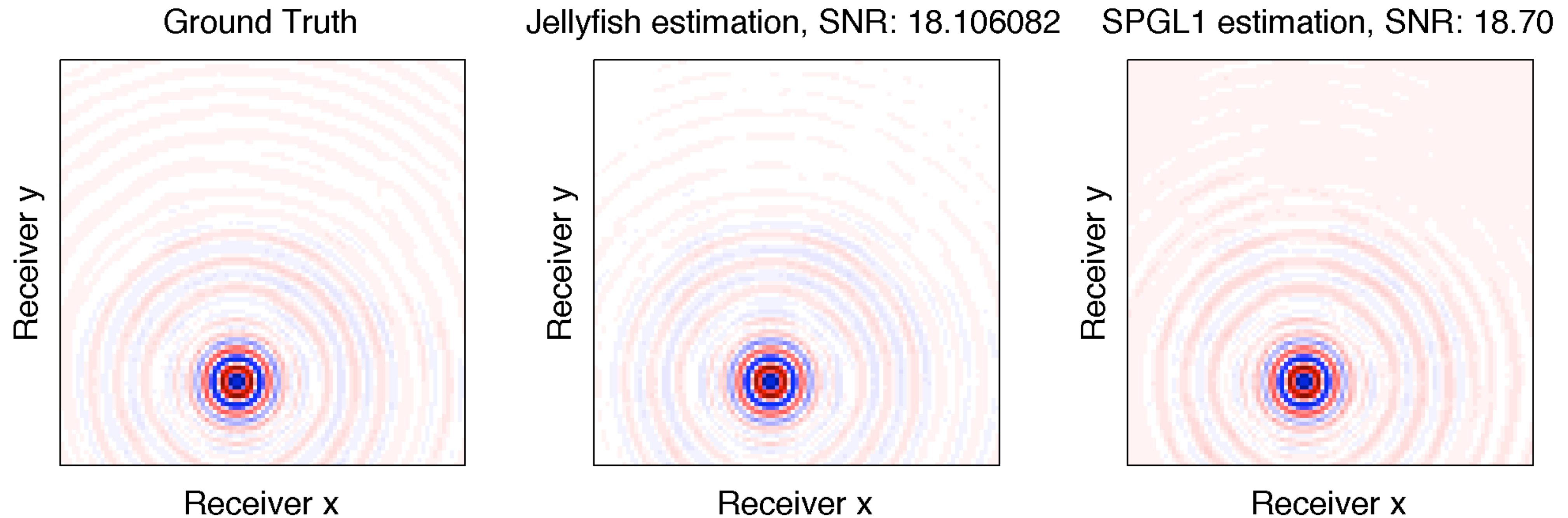
Residual



Receiver x

Jellyfish vs. SGPL1

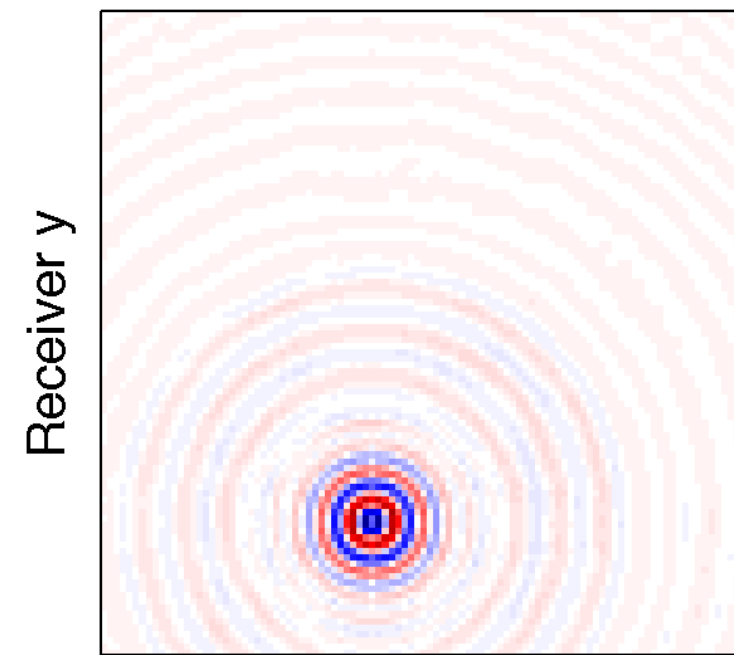
Freq 4.68Hz (Source x, Source y)=(54, 30) Sampling Ratio: 0.25



Windowing Results

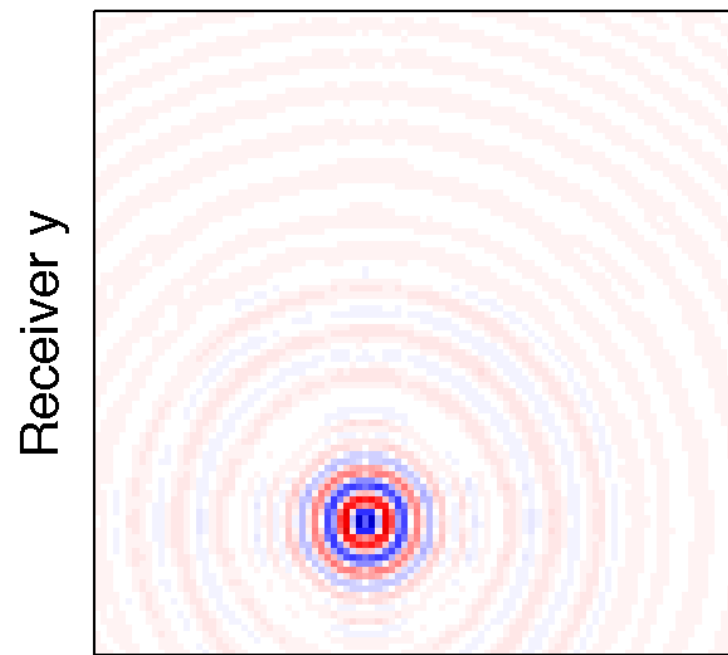
Freq: 4.68Hz (Source x, Source y)=(54, 29) Sampling Ratio: 0.25

of Windows = 1, SNR: 18.50



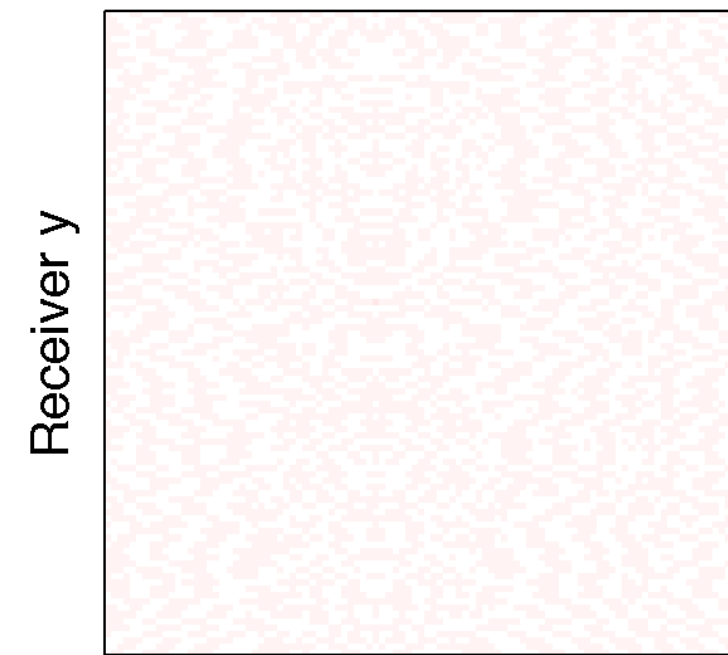
Receiver x

of Windows = 4x4, SNR: 12.52



Receiver x

of Windows = 17x17, SNR: -0.03



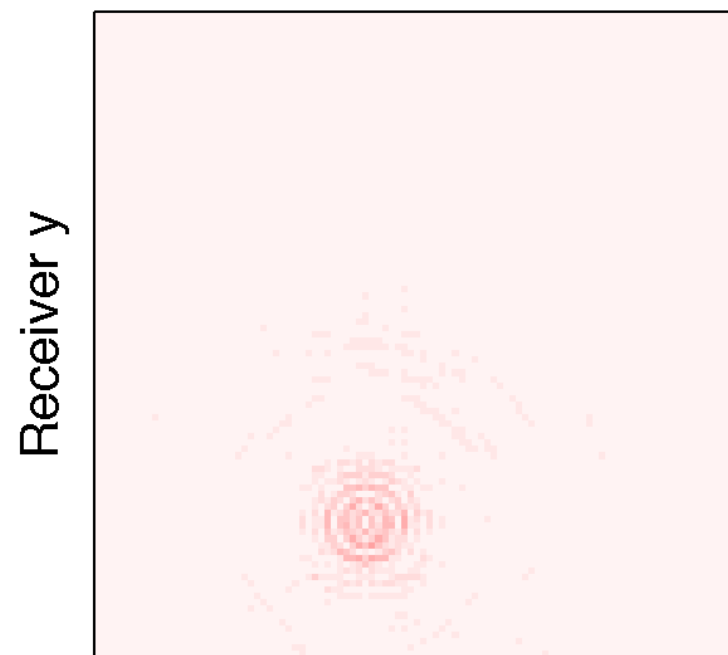
Receiver x

Residual, # of Windows = 1



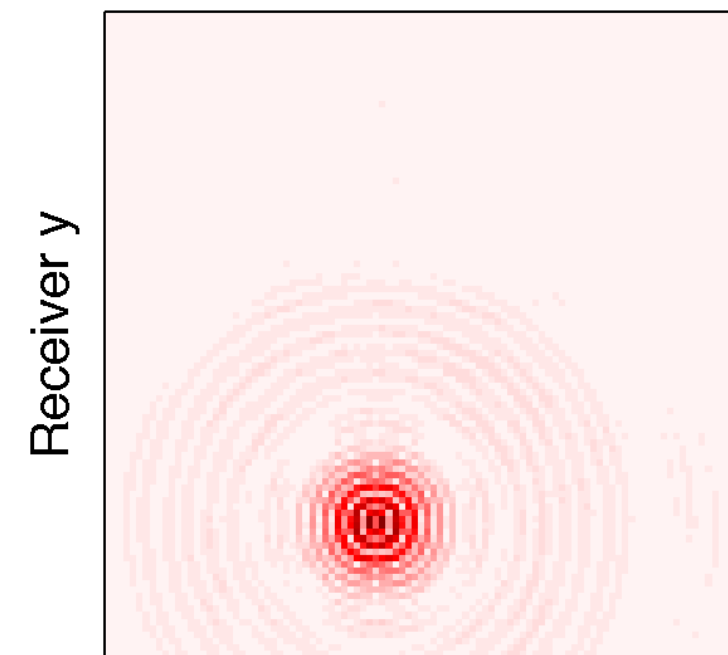
Receiver x

Residual, # of Windows = 4x4



Receiver x

Residual, # of Windows = 17x17

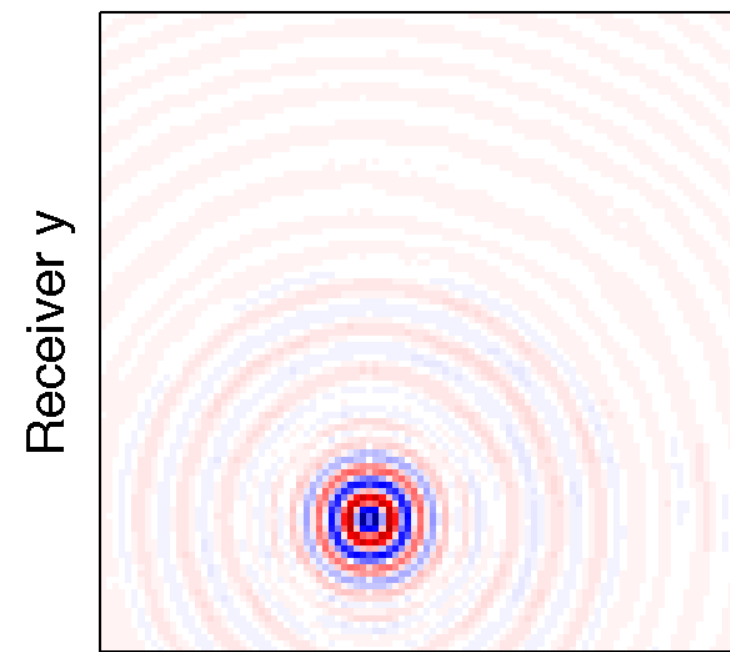


Receiver x

Windowing Results

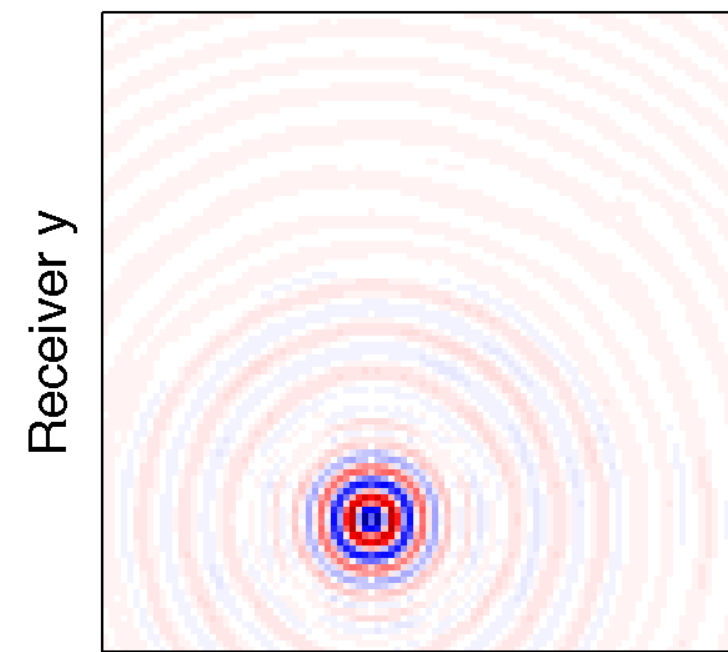
Freq: 4.68Hz (Source x, Source y)=(54, 29) Sampling Ratio: 0.75

of Windows = 1, SNR: 23.31



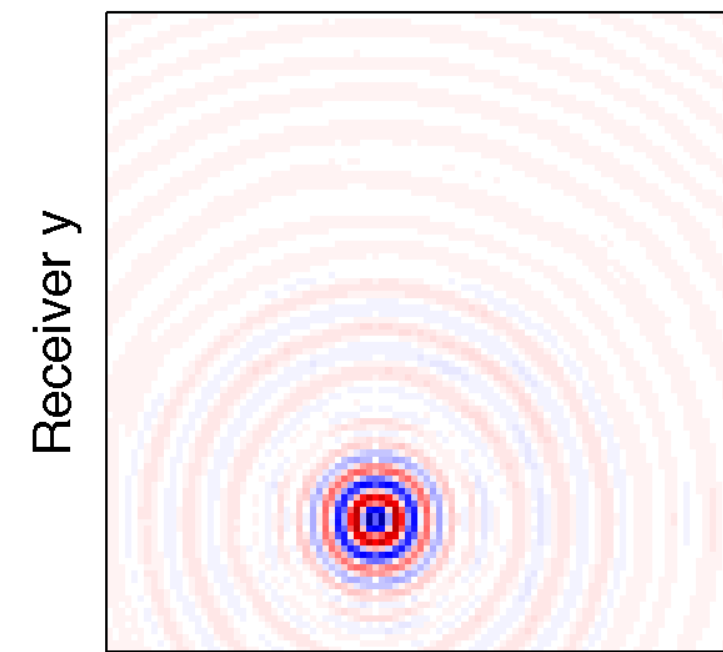
Receiver x

of Windows = 4x4, SNR: 25.83



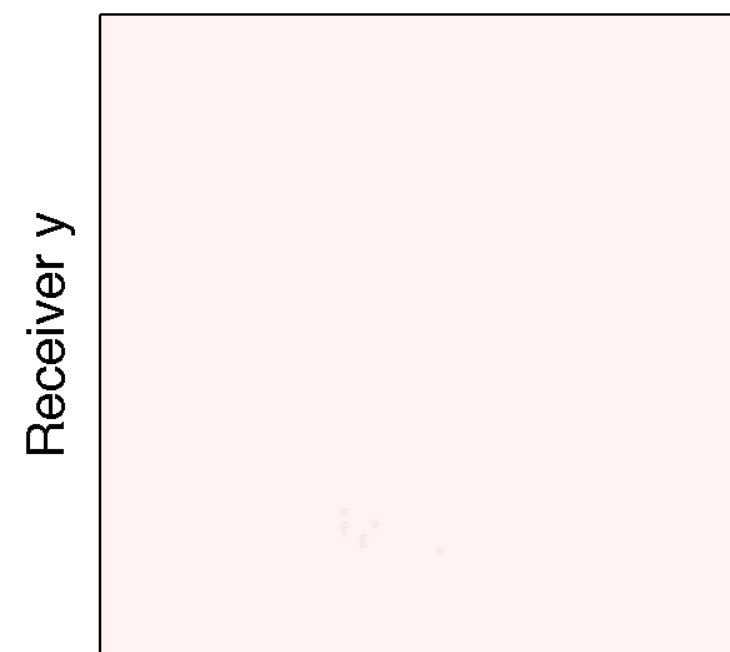
Receiver x

of Windows = 17x17, SNR: 23.06



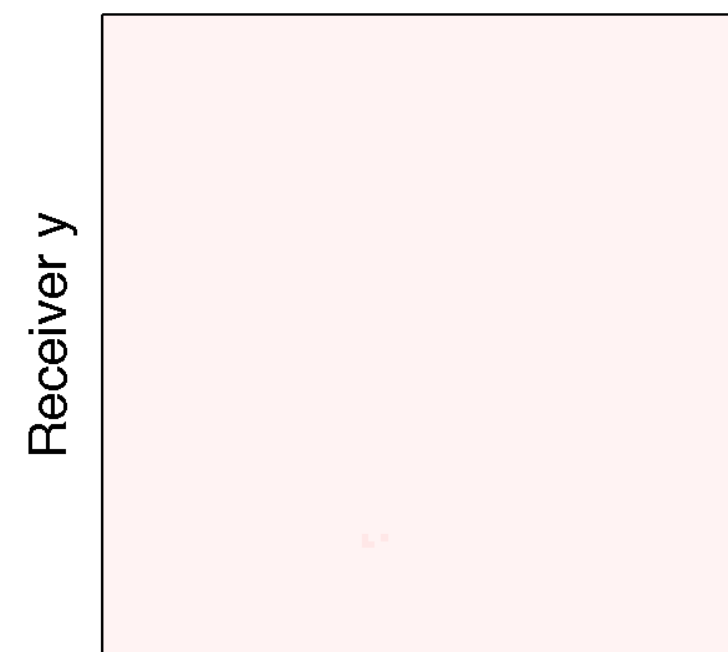
Receiver x

Residual, # of Windows = 1



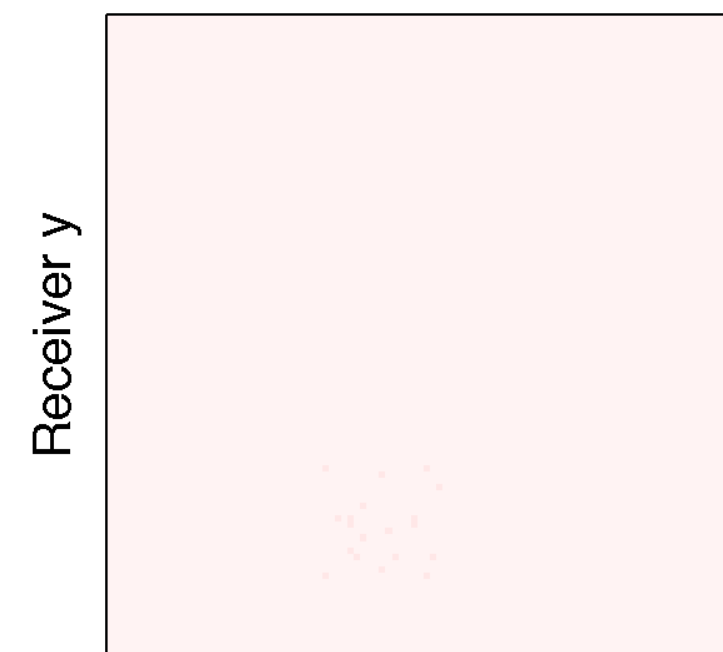
Receiver x

Residual, # of Windows = 4x4



Receiver x

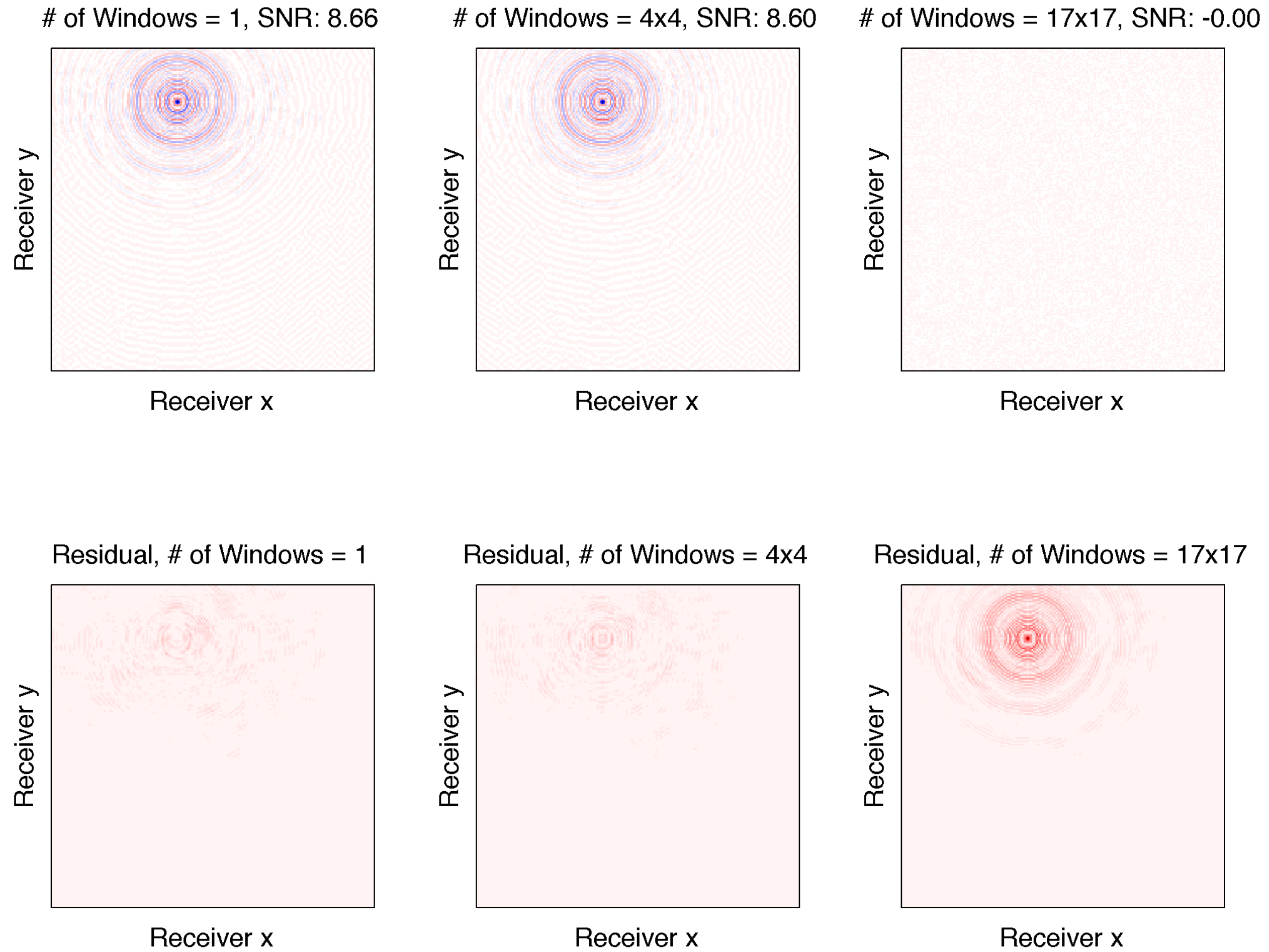
Residual, # of Windows = 17x17



Receiver x

Windowing Results

Freq: 12.30Hz (Source x, Source y)=(12, 27) Sampling Ratio: 0.25

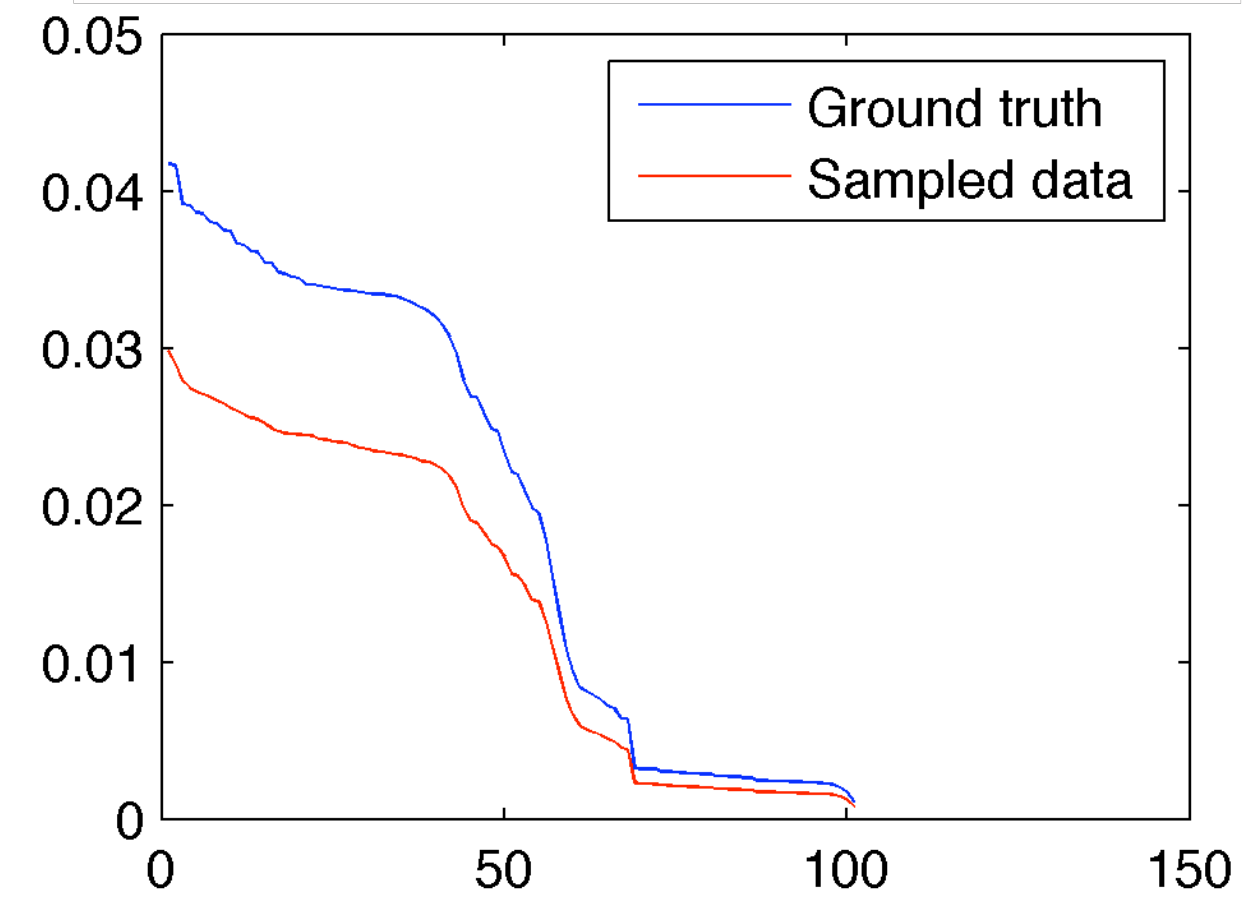
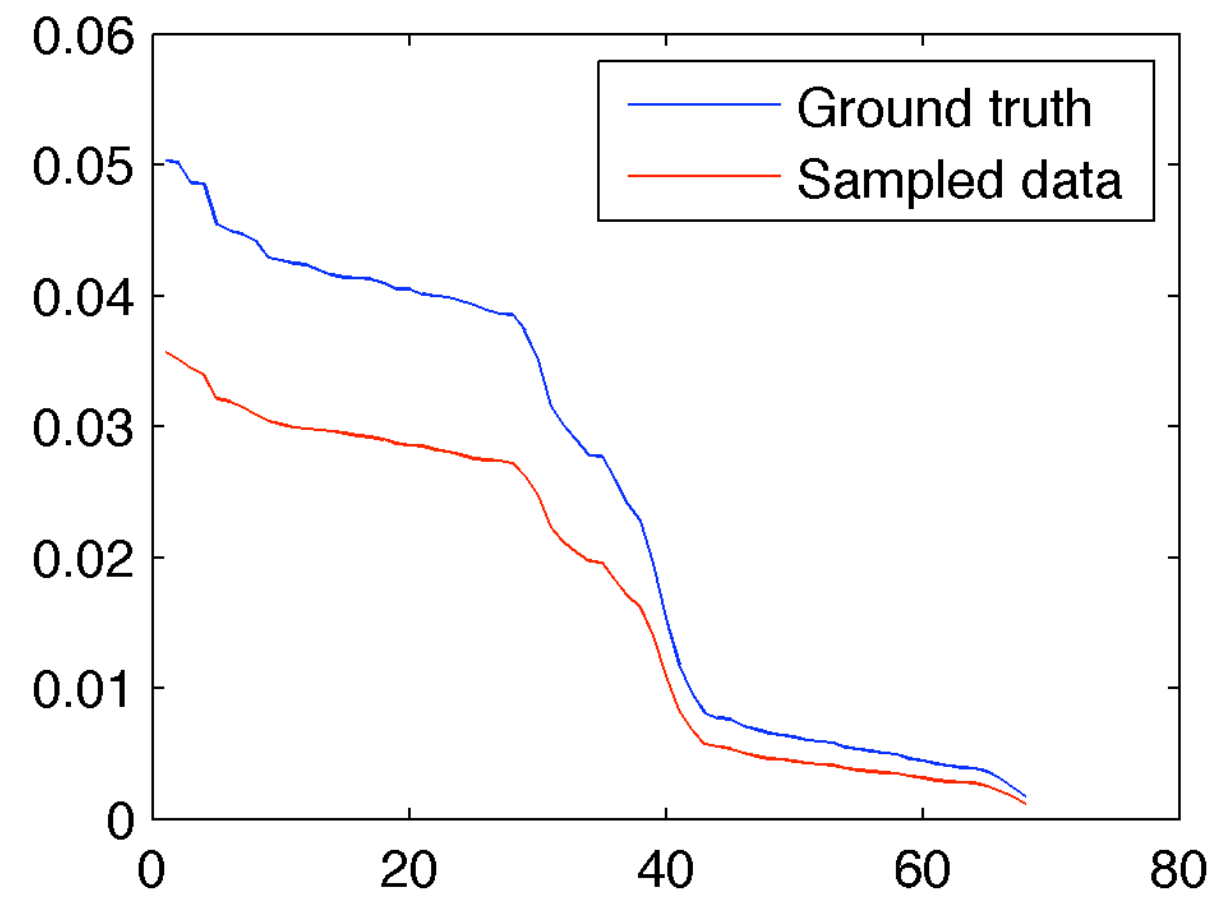
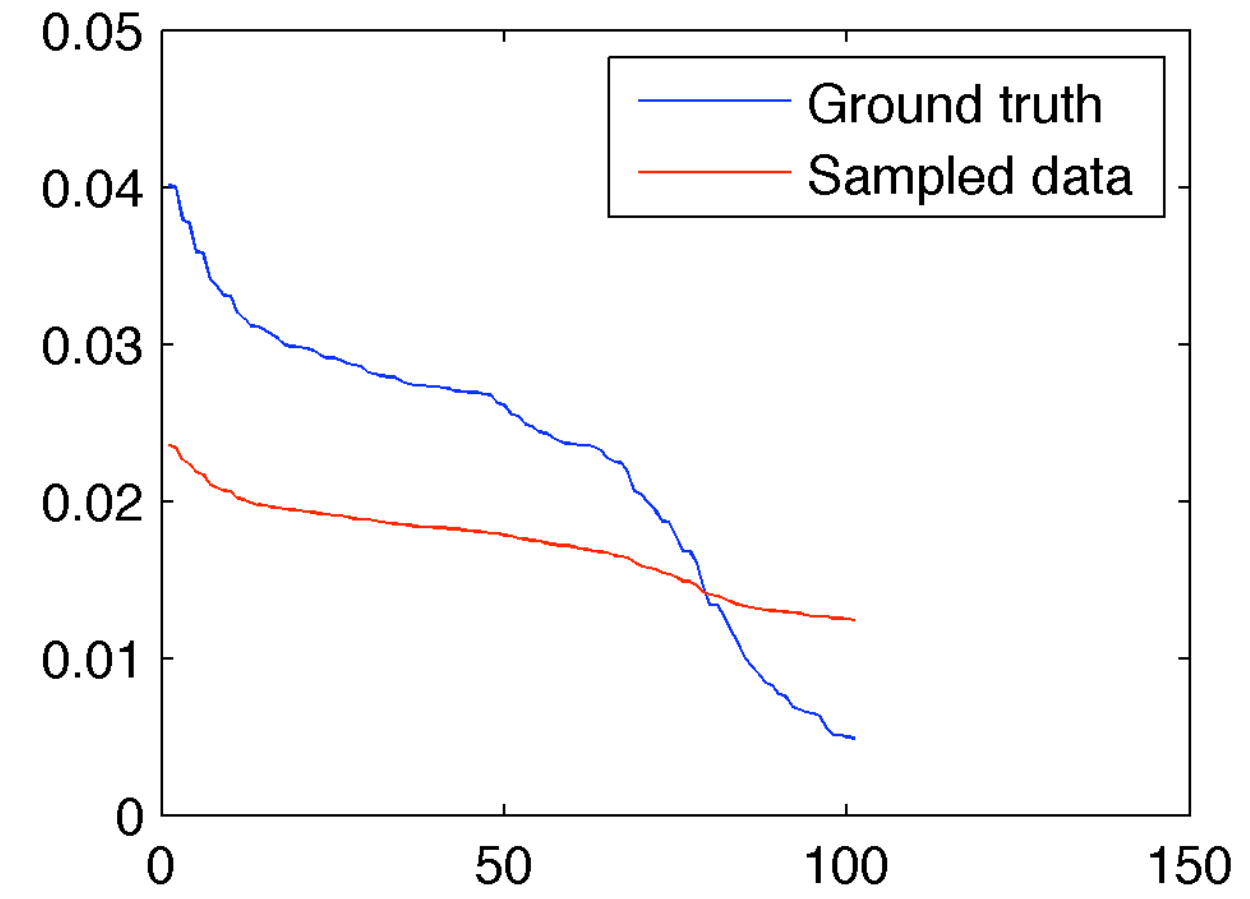
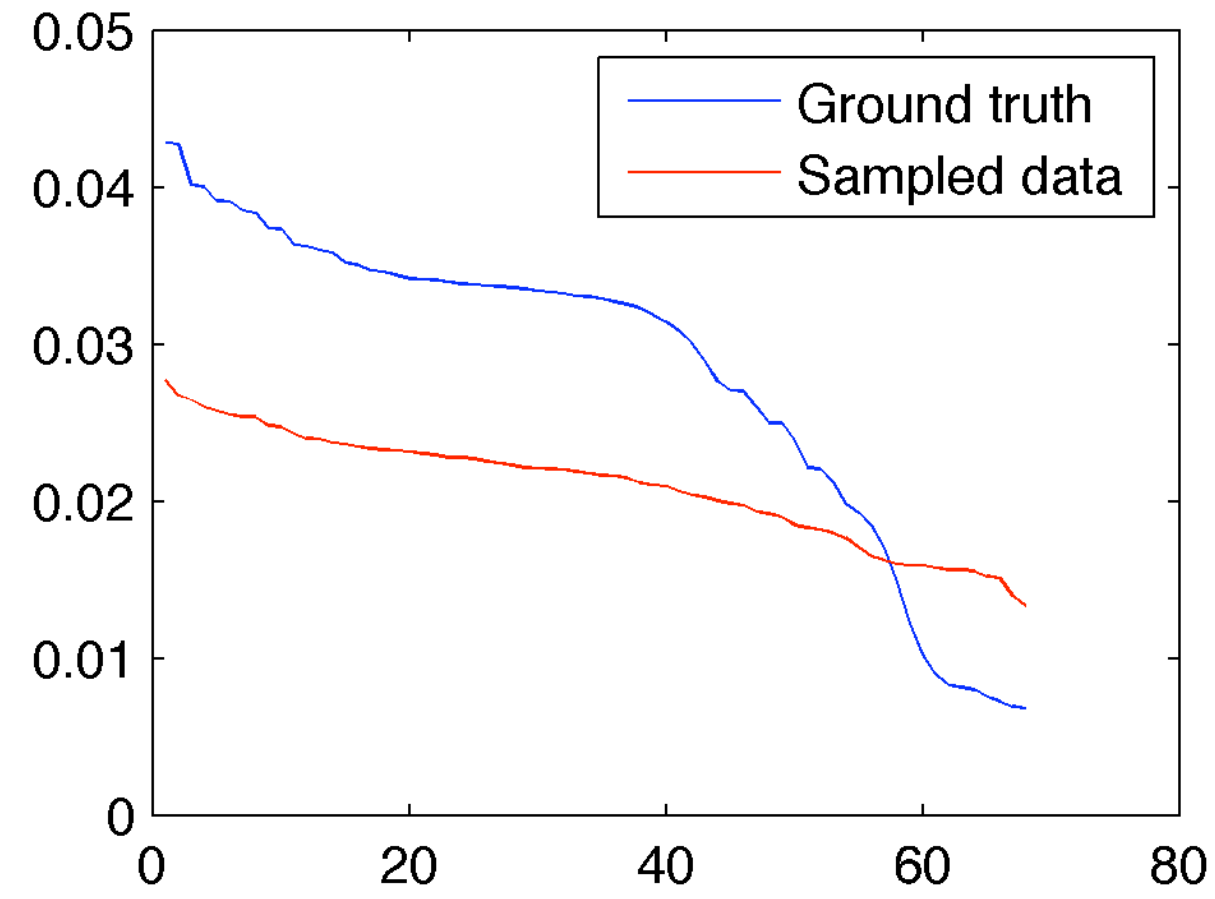


Comparison of Methods

Frequency	% sources	SPGL ₁	SPGL ₁ time	Jellyfish	Jellyfish time	ADMM	ADMM time
4.68 Hz	25%	15.9	5040	16.34	2160	-80.96	127346
	50%	20.75	5760	19.81	4899	-82.03	132987
	75%	21.47	6840	19.64	7434	-82.25	130309
7.34 Hz	25%	11.2	5040	11.99	3126	-81.12	126984
	50%	15.2	7560	15.05	8767	-82.85	128921
	75%	16.3	8280	15.31	11710	-81.12	133567
12.3 Hz	25%	7.3	19440	9.34	13387	-80.14	174296
	50%	12.6	26280	12.12	42330	-81.19	177145
	75%	14.02	27000	12.90	77670	-81.53	175340

Tensor Completion Results

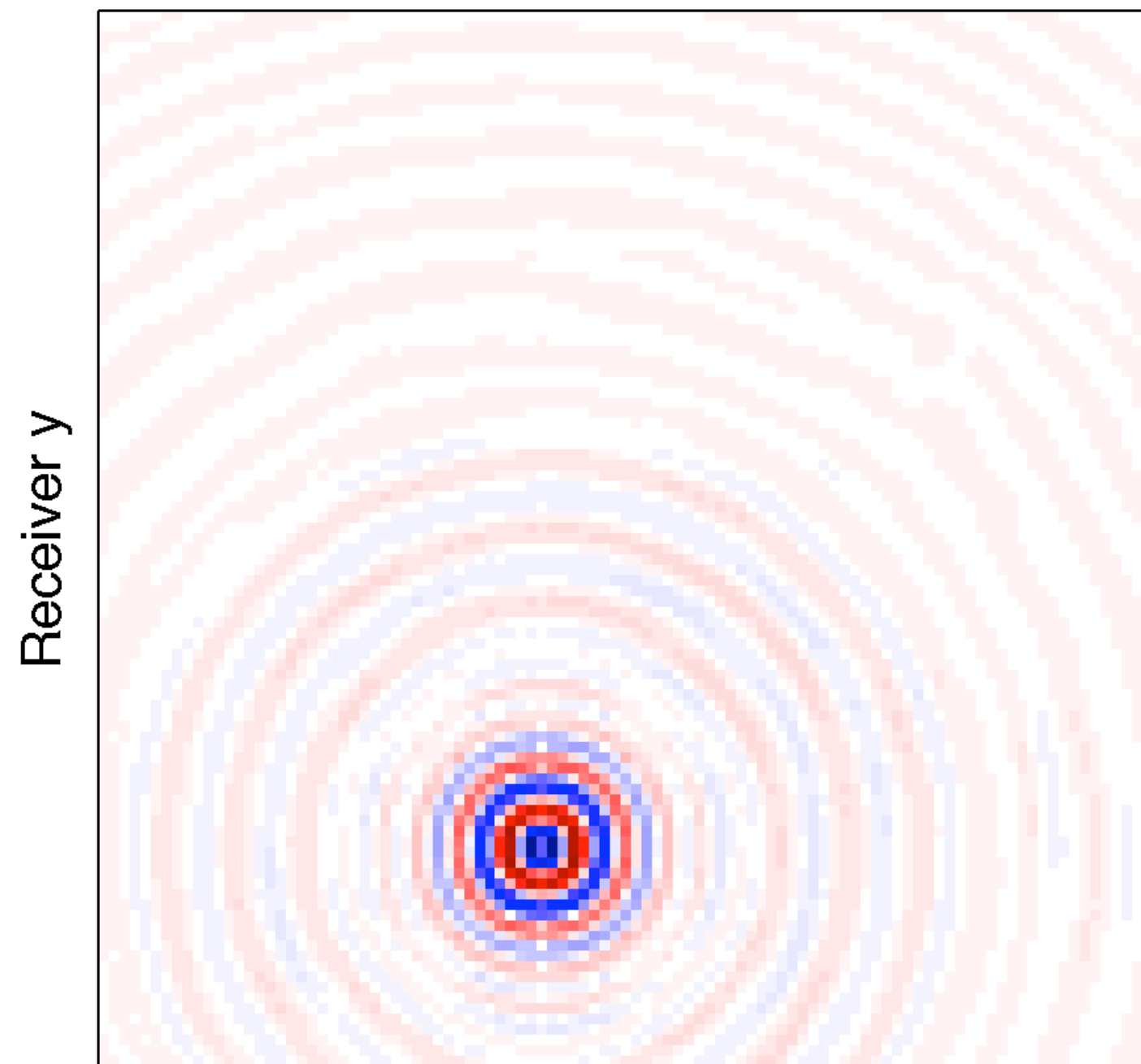
Singular value spectrums of matricizations



Tensor Completion Results

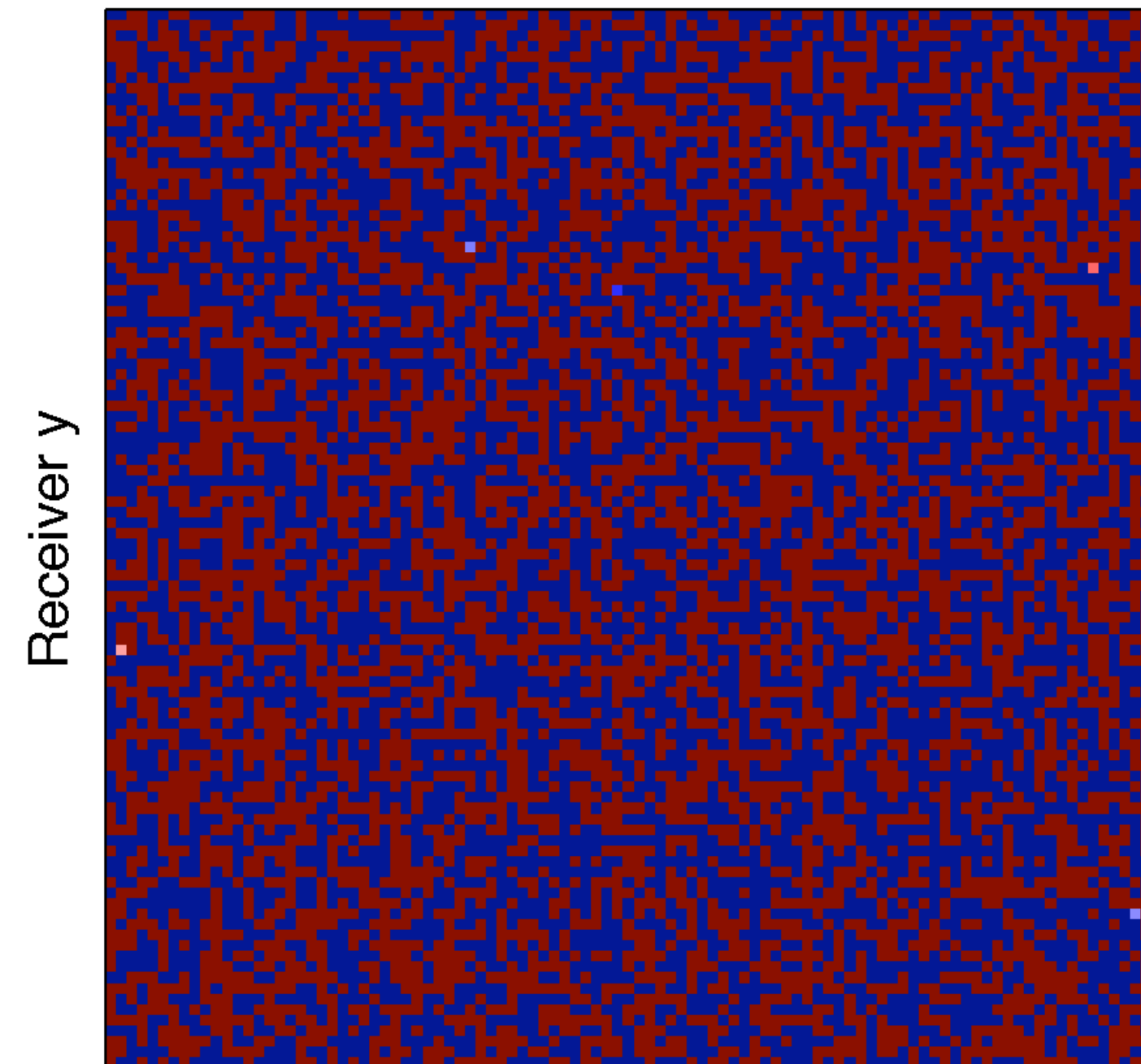
(Source x, Source y)=(54, 29) Sampling Ratio: 0.50

Ground Truth

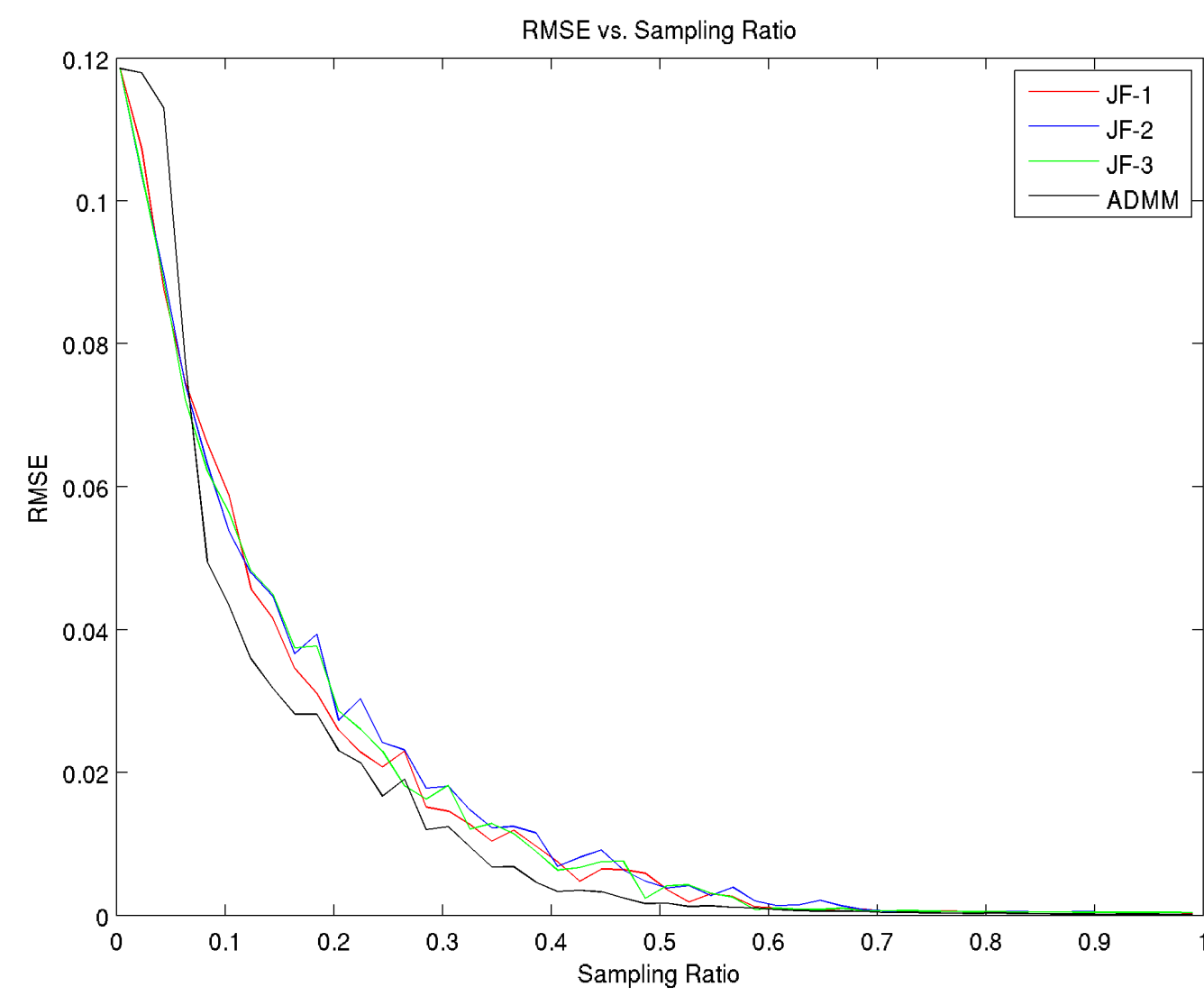


Receiver x

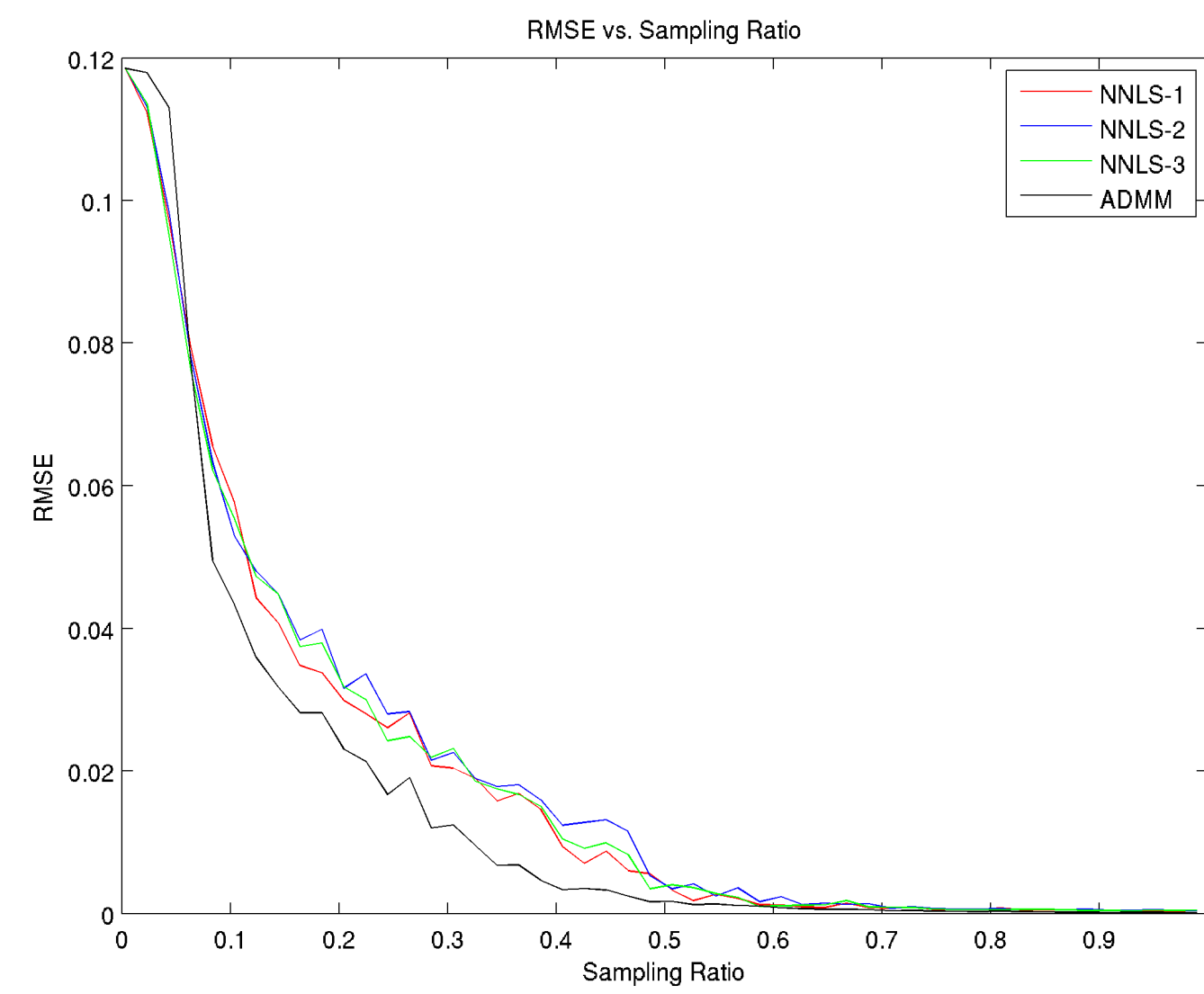
Tensor Completion Result



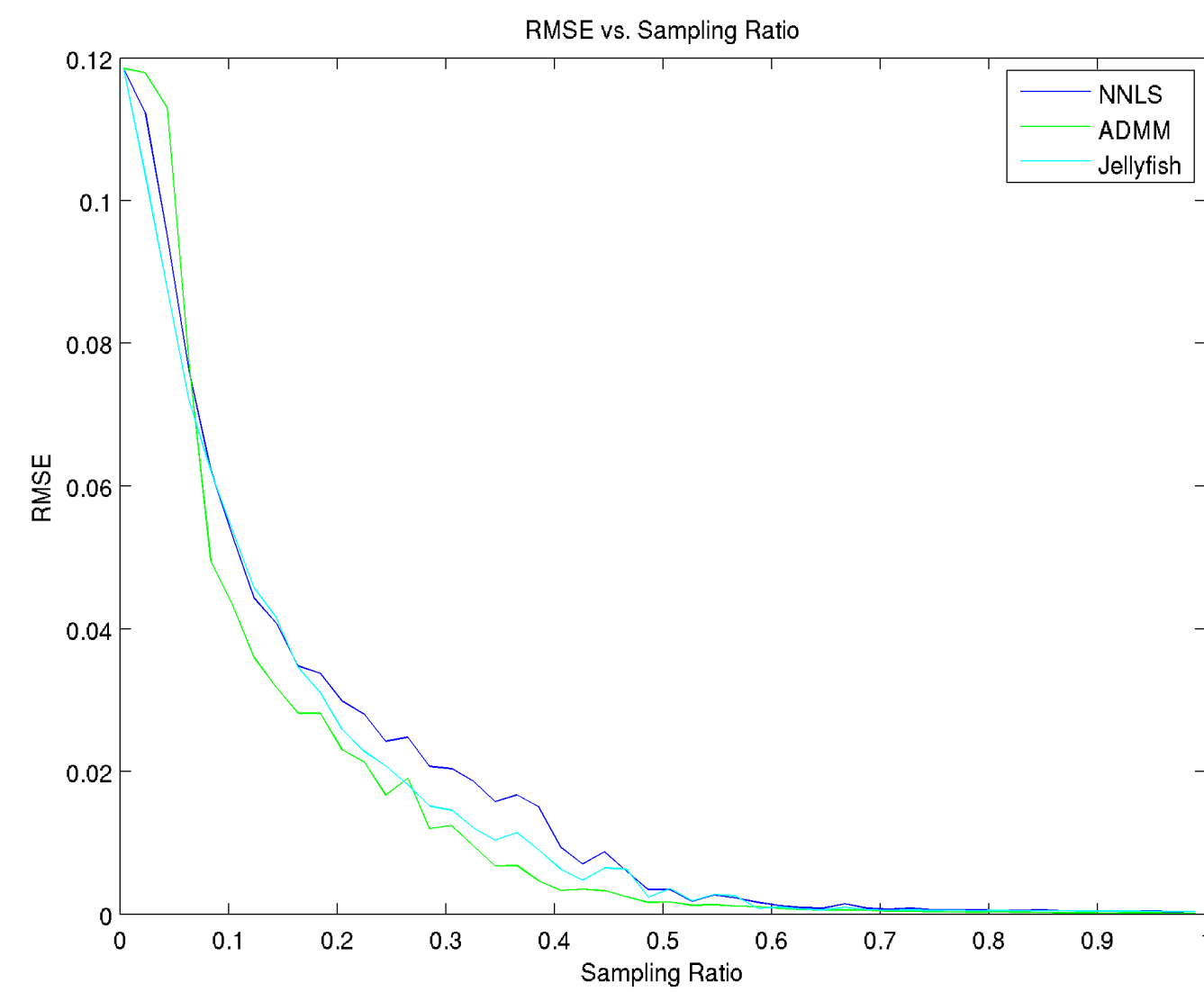
Receiver x



(a) Jellyfish Results

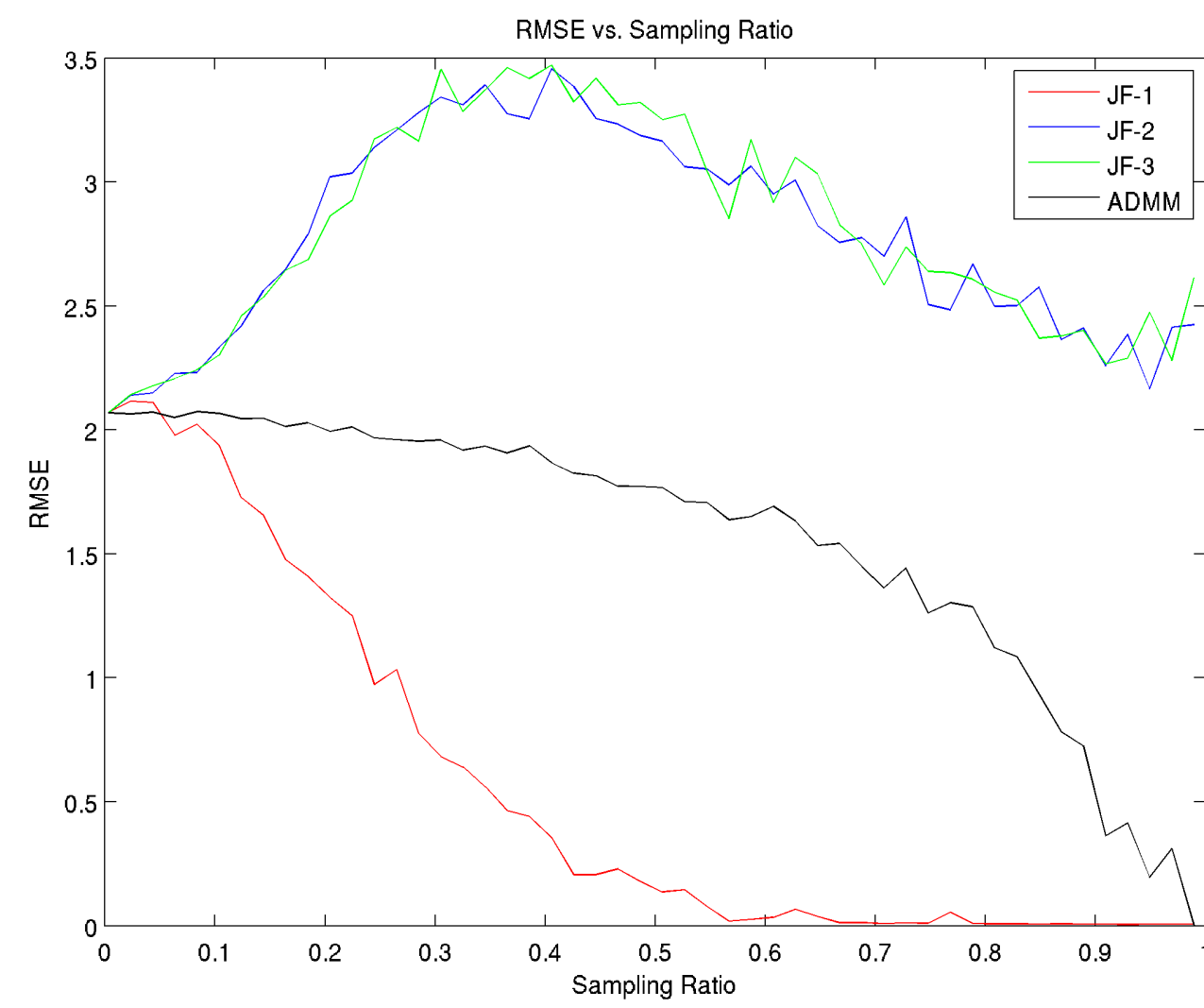


(b) NNLS Results

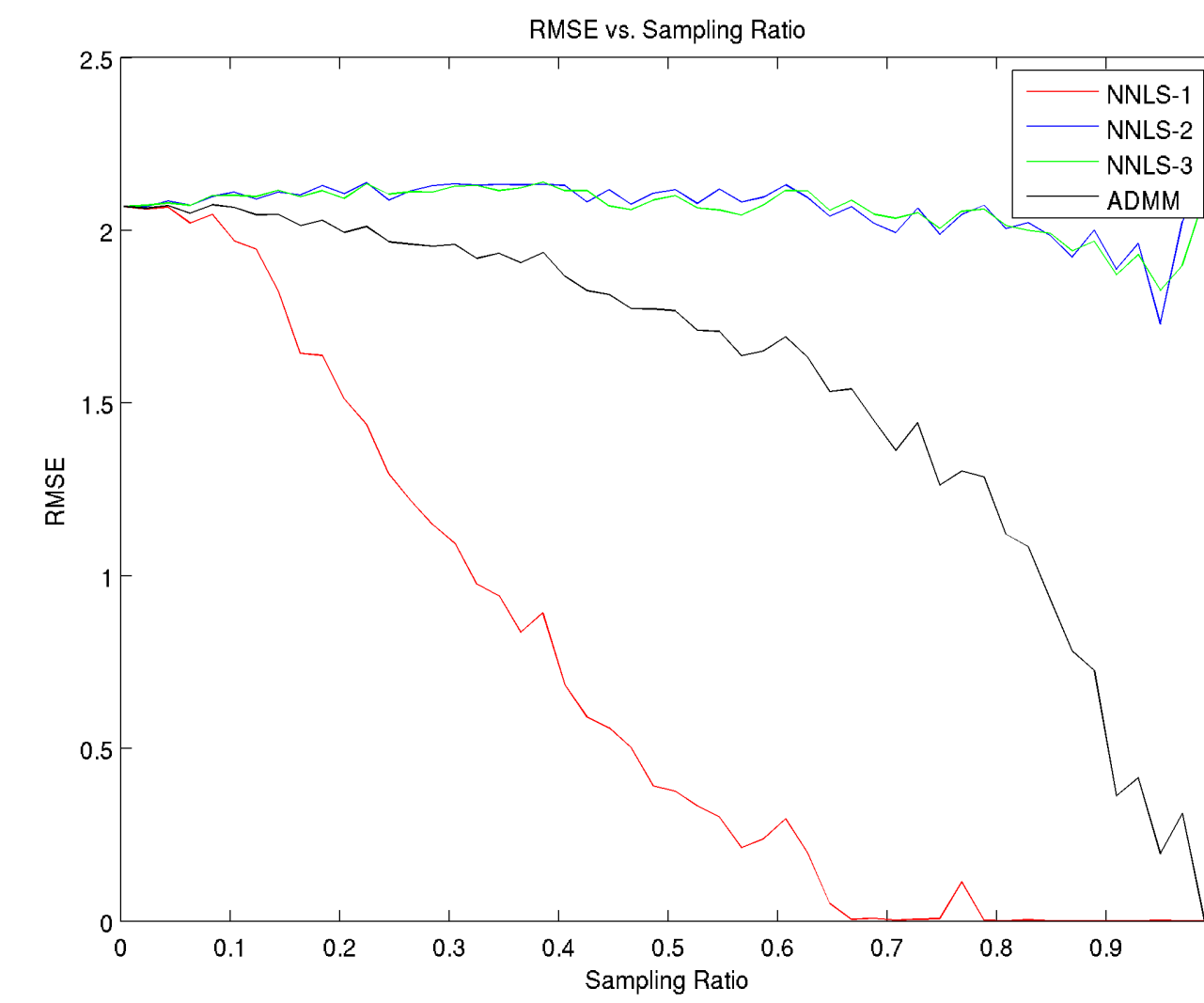


(c) Comparative Results

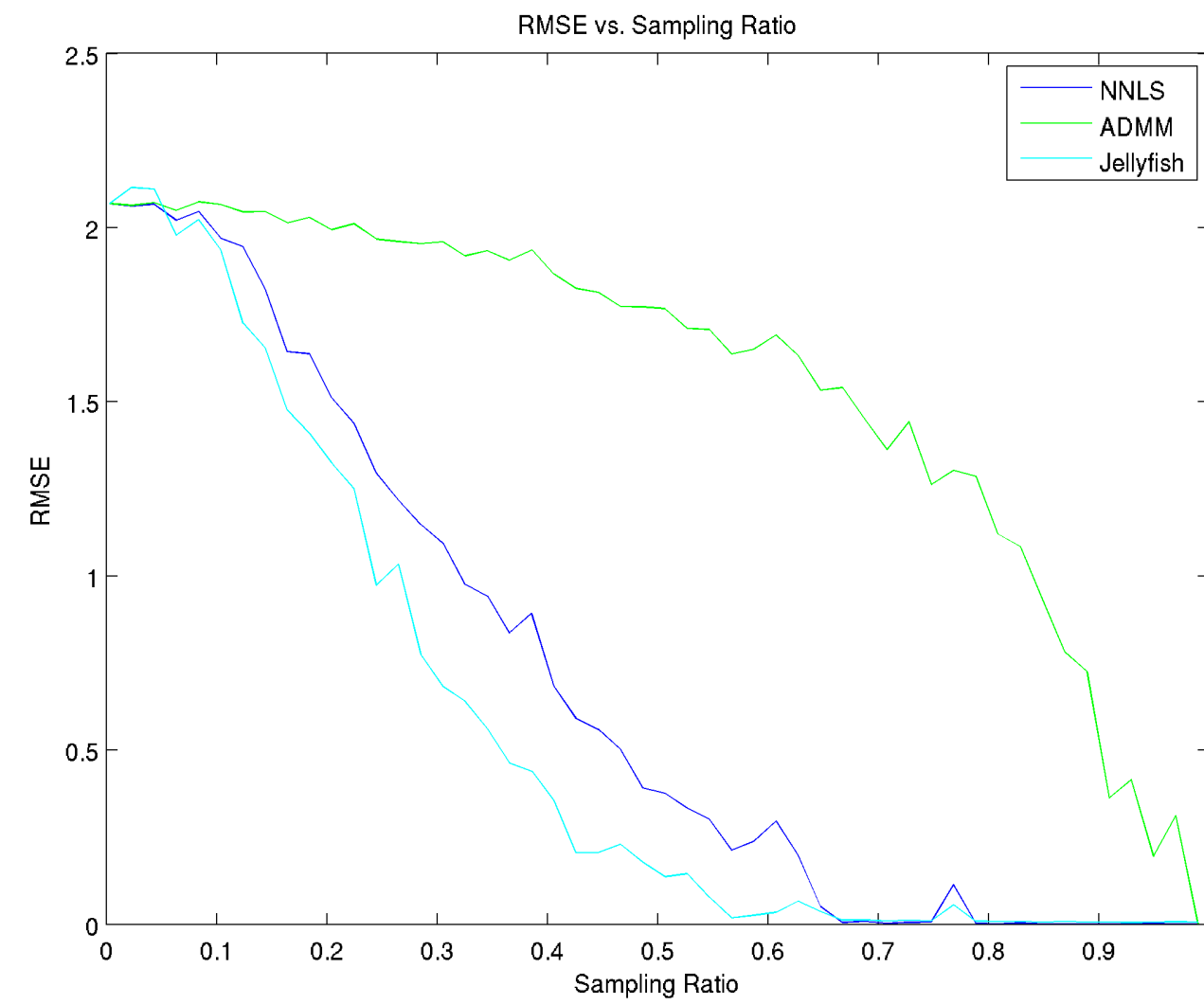
Figure 1: Sample complexity results for a rank 5 tensor of size $20 \times 20 \times 20$.



(a) Jellyfish Results



(b) NNLS Results



(c) Comparative Results

Figure 2: Sample complexity results for tensor of size $20 \times 20 \times 20$ with exactly one low rank unfolding (rank 5).

Recap

- Jellyfish and SPGL1 yield very similar results as expected.
- Matrix completion performs fairly well
- Windowing yields very good results, making it possible to scale to very large data sets
- Tensor completion with nuclear norm averaging does not work
- Parameter selection still takes considerable time, however good parameter combinations work across different problems

Outline

- Introduction
- Approach
- Experiments
- Conclusion & Future Work

Conclusion

- Compressed sensing provides a framework that allows scalable algorithms for the large scale seismic data interpolation problem
- The runtime efficiency can be increased by windowing
- In order to do successful tensor completion, we need a model that agrees with the structure of seismic data
- Hierarchical Tucker Decomposition yields comparable results

Future Work

- Finding different low rank representations of seismic data
- Sample complexity comparison between tensor completion (Hierarchical Tucker Decomposition) and matrix completion methods
- Using windowing to interpolate high frequencies
- Using windowing for fast parameter selection

Thank you!

- Any questions?