

Analysis vs synthesis in weighted sparse recovery

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Overview

- When using a redundant transform, such as curvelets, there is choice in how to solve the sparse recovery problem, namely synthesis and analysis formulations which I'll introduce shortly.
- Support information can be incorporated in both formulations and a novel weighting scheme is introduced
- Analysis is a viable candidate and can outperform synthesis (but there is no free lunch, yet)

Examples of redundant transforms

- Curvelet frames (Primary transform of interest for us)
- Gabor frames
- Harmonic frames
- Wavelet frames
- Concatenation of bases/frames

Synthesis formulation

Assume our signal f admits a sparse representation with respect to S^H where S is a redundant transform

$$f = S^H x, \quad x \text{ is sparse}$$

Major issue: S redundant \implies Uniqueness of above equation lost.
Possibly many sparse solutions.

$$\hat{x} = \arg \min_x \|x\|_1 \quad \text{s.t.} \quad b = \underbrace{RS^H}_{\leftarrow} x$$

Compressive sensing
Rauhut et al 2008,
Randall 2009

Error and reconstruction

$$\|\hat{x} - x\|_2 \leq C_1 \frac{\|x - x_s\|_1}{\sqrt{s}}$$

x_s : Best s-term approximation of x

$$\hat{f} = S^H \hat{x}$$

$$\implies \|\hat{f} - f\|_2 \leq C_1 \frac{\|x - x_s\|_1}{\sqrt{s}}$$

C_1 : Constant

Remark:

RS^H will rarely satisfy the theoretical conditions required for these bounds to hold when S^H is redundant, however these conditions are only sufficient.

Synthesis weighting

$$\hat{x} = \arg \min_x \|x\|_1 \quad \text{s.t.} \quad b = RS^H x$$

We solve instead,

$$\hat{x} = \arg \min_x \|Wx\|_1 \quad \text{s.t.} \quad b = RS^H x \quad (\text{Hassan's talk})$$

W is a diagonal matrix, whose entries selectively penalize different coefficients in the solution:

$$W_{i,i} = \begin{cases} \omega & i \in \text{estimated support of } x \\ 1, & i \notin \text{estimated support of } x \end{cases}$$

Analysis formulation

$$\hat{f} = \arg \min_f \|(S^H)^\dagger f\|_1 \quad \text{s.t.} \quad b = Rf$$

Let S be the curvelet transform, then $S^H S = I$ because curvelets are tight frames:

$$\hat{f} = \arg \min_f \|Sf\|_1 \quad \text{s.t.} \quad b = Rf$$

S is called the analysis operator, equivalently the forward transform

Error (Candès, Eldar, Needell, Randall 2010 and Shidong Li 2012):

$$\|\hat{f} - f\|_2 \leq C \frac{\|Sf - (Sf)_s\|_1}{\sqrt{s}}, \quad (Sf)_s : \text{Best } s\text{-term approximation of } Sf$$

C : Constant

Weighting: Strategy 1

$$\hat{f} = \arg \min_f \|W(Sf)\|_1 \quad \text{s.t.} \quad b = Rf$$

$$W_{i,i} = \begin{cases} \omega & i \in \text{estimated support of } x \\ 1, & i \notin \text{estimated support of } x \end{cases}$$

This weighting is interpreted the exact same way as in synthesis

See: Candès, Walkin, Boyd 2008 and Candès, Needell 2010

Weighting: Strategy 2

Recall that non-simplified version:

$$\hat{f} = \arg \min_f \|(S^H)^{\dagger} f\|_1 \quad \text{s.t.} \quad b = Rf$$

New weighting strategy (Hargreaves-Yilmaz, November 2012):

$$\hat{f} = \arg \min_f \|(S^H \tilde{W})^{\dagger} f\|_1 \quad \text{s.t.} \quad b = Rf$$

$$\tilde{W}_{i,i} = \begin{cases} 1 & i \in \text{estimated support of } x \\ \omega, & i \notin \text{estimated support of } x \end{cases}$$

Possible interpretation: \tilde{W} acting on the columns of S^T influences the subspace in which our solution vector lives (Cosparsity? See Tim Lin's talk.)

Why are the weights inverted?

A simple motivation:

Suppose B is an orthonormal basis, and x sparse

$$f = Bx$$

If we have a perfect estimate, our weight matrix preserves this:

$$f = BWx$$

So in the imperfect setting, we attempt the same:

$$f = BWx \implies x = (BW)^{-1}f = W^{-1}B^{-1}f$$

On support: small

Off support: big



$\implies W$ should be the opposite

Review: Analysis vs synthesis

Assumption:

x is sparse

Sf is sparse

Problem:

$$\min_x ||x||_1$$

$$\min_f ||Sf||_1$$

Constraint:

$$y = RS^H x$$

$$y = Rf$$

$||\hat{f} - f||_2 :$

$$C_1 \frac{||x - x_s||_1}{\sqrt{s}}$$

$$C \frac{||Sf - (Sf)_s||_1}{\sqrt{s}}$$

Review: Analysis vs synthesis

- Analysis optimizes over signal space, synthesis optimizes over coefficient space
- Not equivalent when S is not a basis and there is an observed performance gap (Elad et al, Nam et al)
- Academic community has not agreed on whether one is better than the other, unless referring to a specific application(Our study: seismic trace interpolation)

Seismic Results

Disclaimer: New weighting strategy is brand new (Nov 2012)

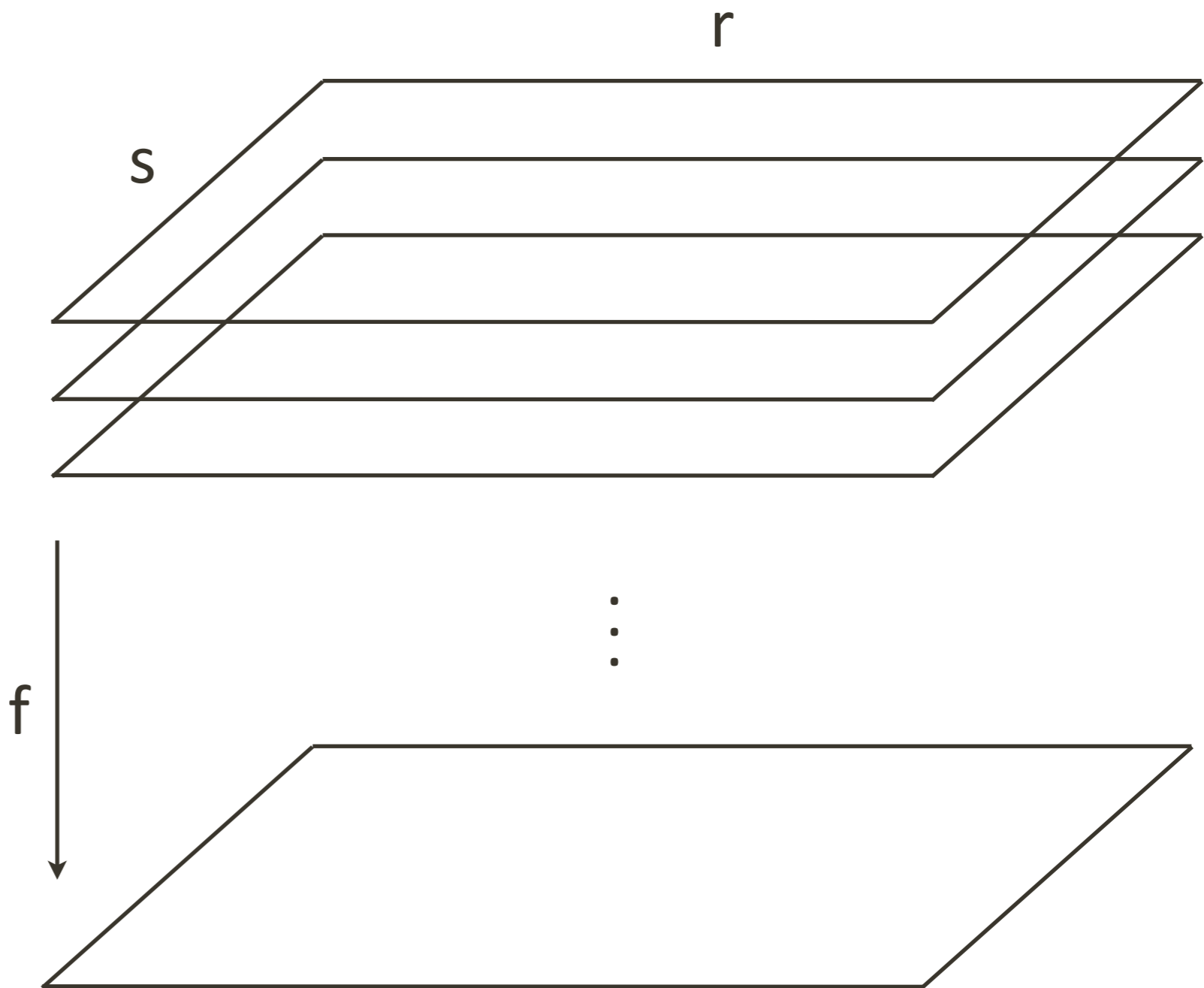
- Gulf of Suez data set: $D = 1024 \times 256 \times 256$
 - $D = (1:2:300, 1:2:100, 1:2:100)$
 - But we believe we will be able to scale this up
- NESTA: A Fast and Accurate First-order Method for Sparse Recovery (Bobin, Becker, Candès, 2011)
 - One of few publicly available solvers that can solve both analysis and synthesis
 - Mainly driven by a single smoothing parameter, which dictates the tradeoff between speed and accuracy

Frequency content as a support estimate

Recover first frequency slice
↳ Estimate support

Recover second frequency slice
using previous support estimate
as a weight

⋮



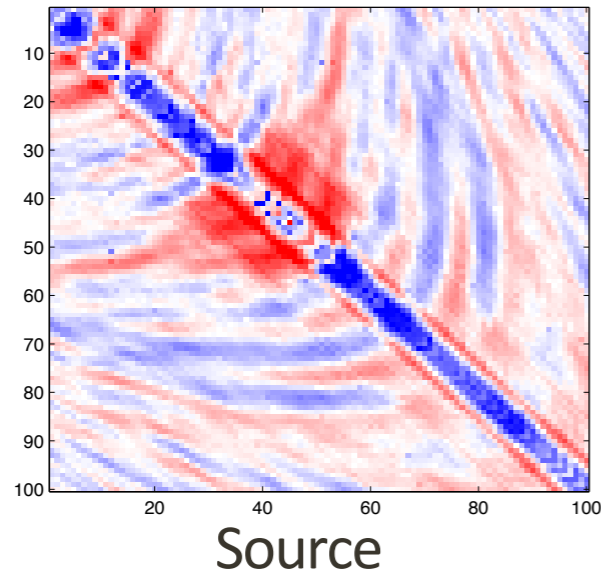
Frequency slice recovery

100 receivers, 100 sources, 2nd frequency slice

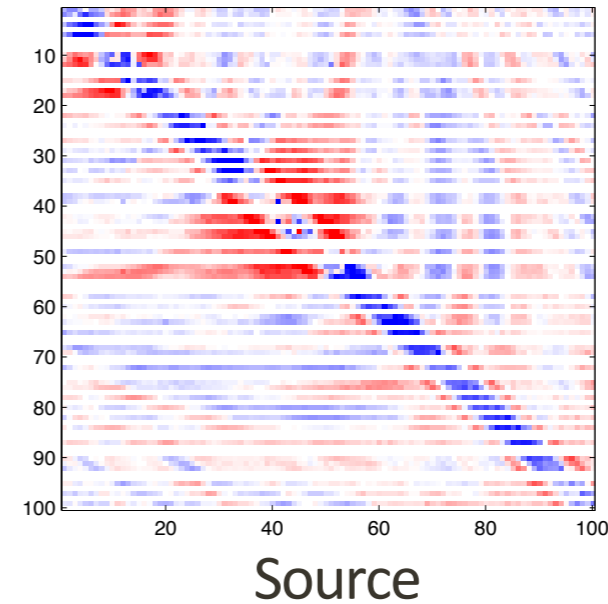
Actual

Masked(50%)

Receiver



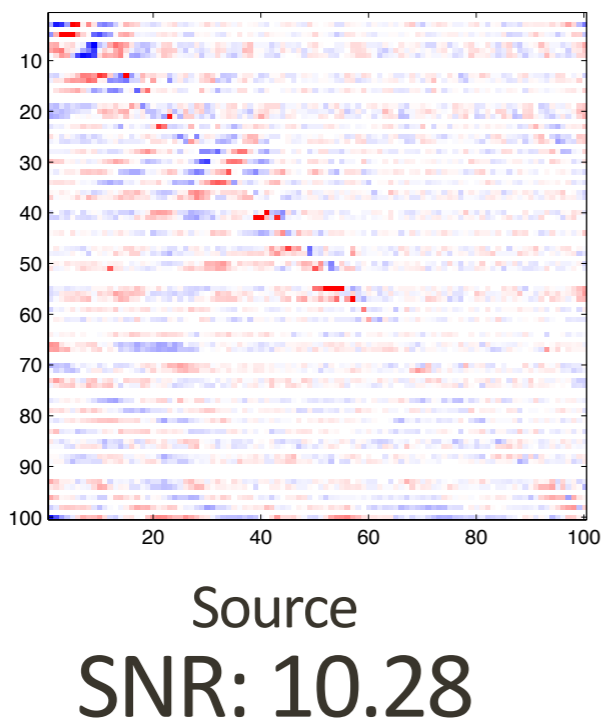
Receiver



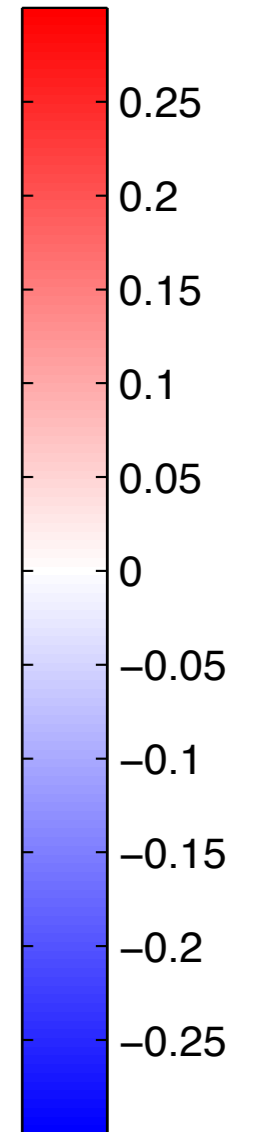
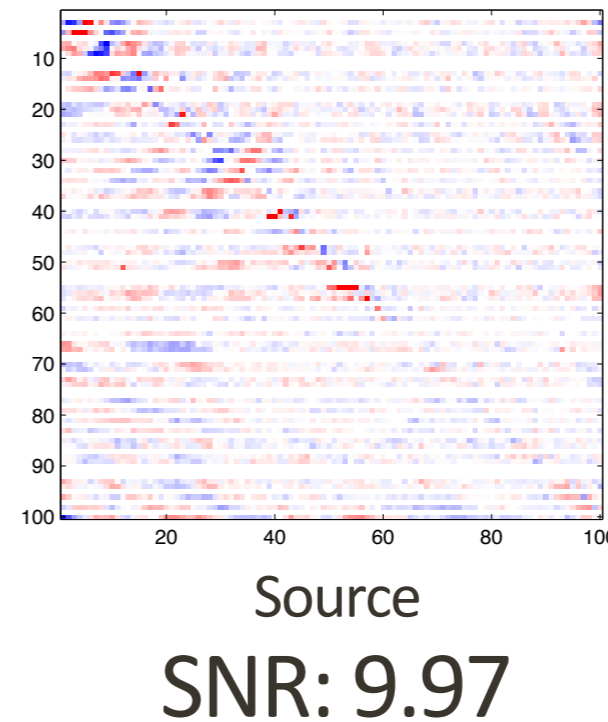
Difference: Weighted Analysis

Difference: Weighted Synthesis

Receiver



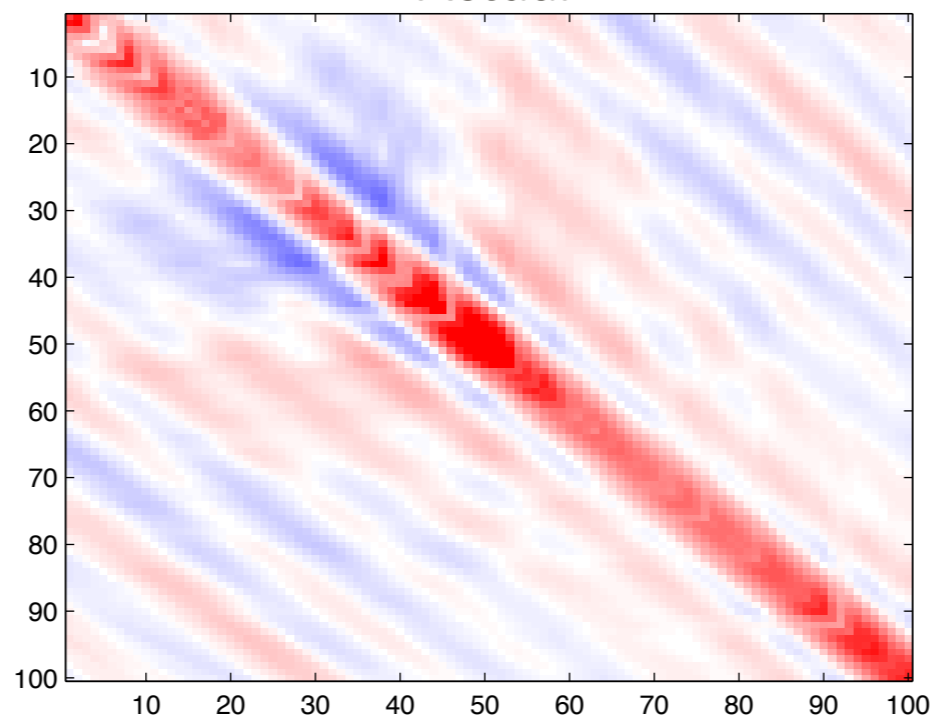
Receiver



15th Frequency slice

Actual

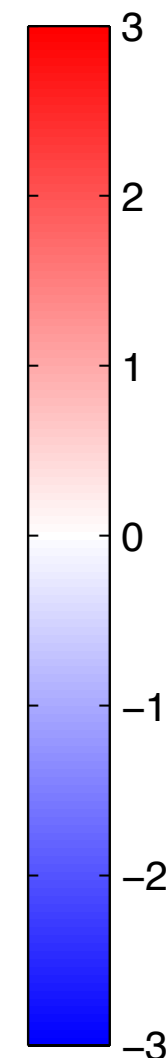
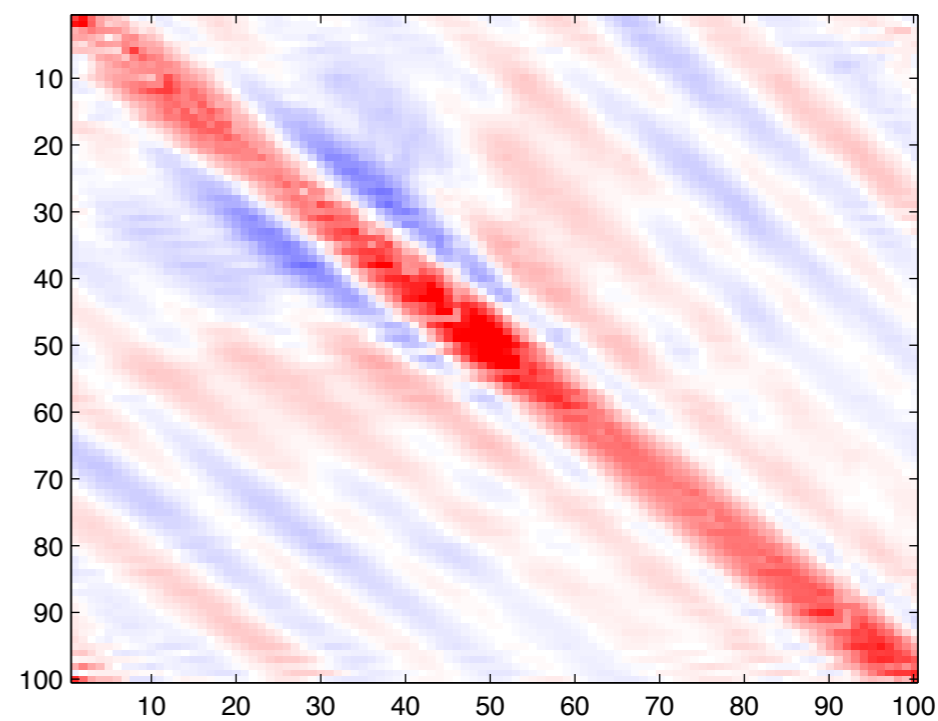
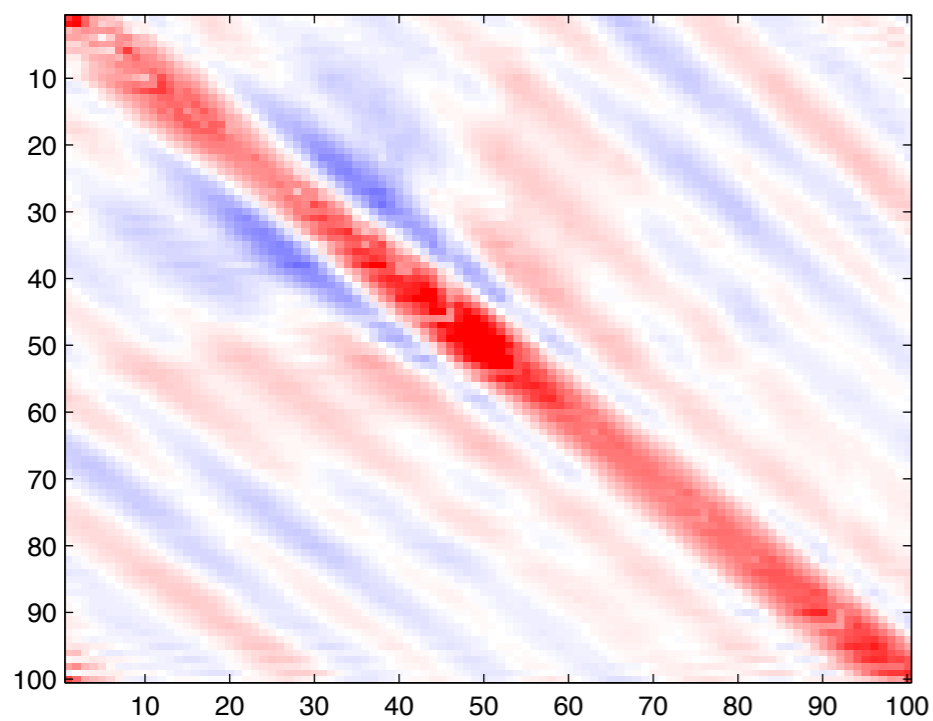
Receiver



Weighted Analysis

Source

Weighted Synthesis

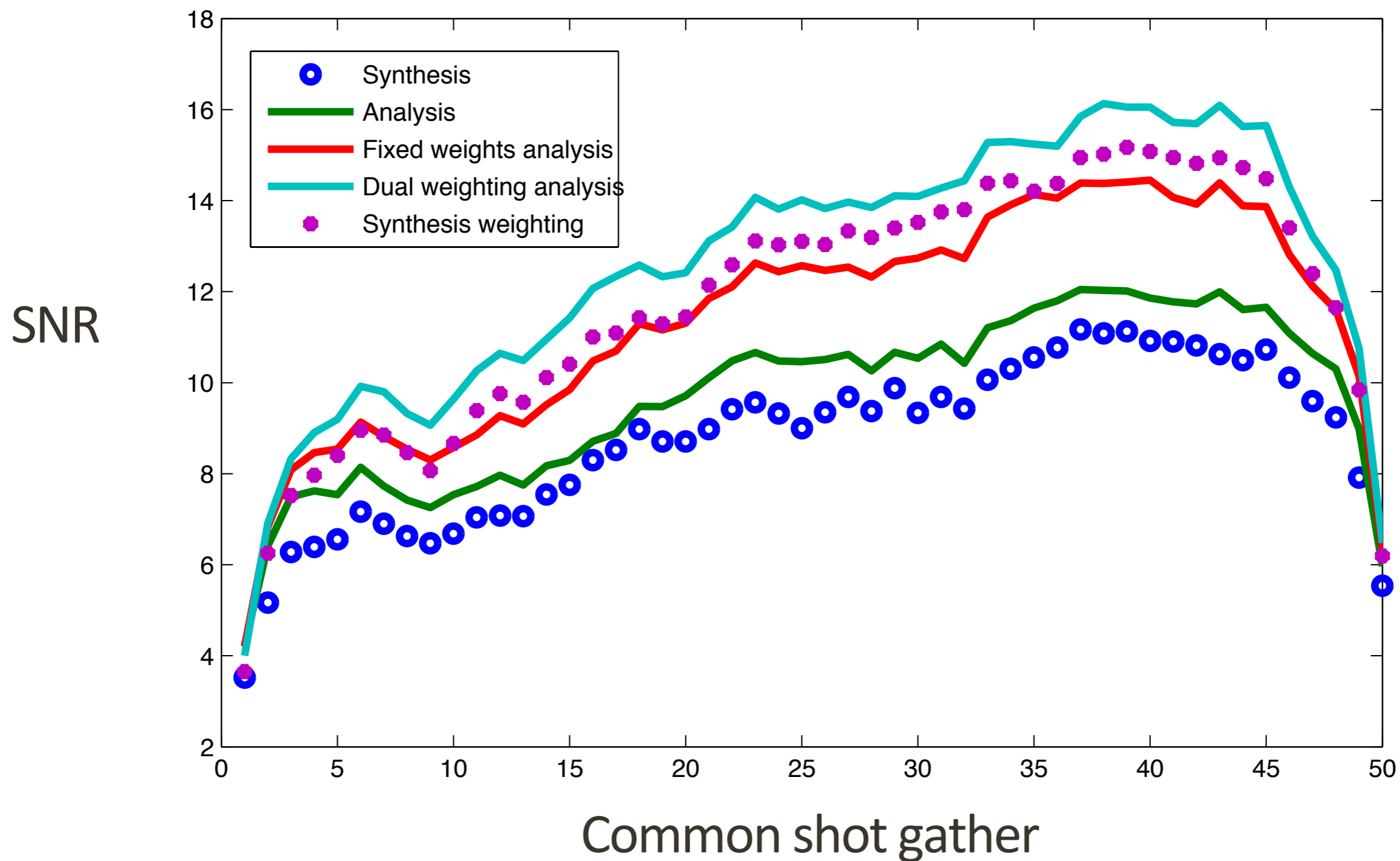


SNR: 20.66

SNR: 19.16

Comparison of algorithms

Recovery in source-receiver domain(50 sources, 50 receivers)



But the story isn't over: Choice of dual and optimality

There are infinitely many choices of the analysis operator, why do we choose the canonical one? Optimize over all possible duals as well:

$$\min_{f, \tilde{D}^* D=I} \|\tilde{D}^* f\|_1 \quad \text{s.t.} \quad y = Af$$

Paper: Compressed sensing with general frames via Optimal-Dual-Based l_1 analysis

Authors: Liu, Mi, Li

Remark: We can also incorporate our weighting strategy here

Remarks and conclusion

- In the new weighting scheme anytime we need to see how the pseudoinverse acts on a vector we need to call LSQR. This is the main bottleneck.
- Conclusion:
 - ***When using NESTA with same parameters:***
The novel weighting technique introduced performs the best with the assumption that the pseudoinverse is approximated well enough

Future work

- Improve computation time so we can handle large problem sizes and test in various domains such as midpoint-offset
- Weighted analysis with ℓ_p , $p < 1$ (Ghadermarzy's talk)
- Analysis operator learning? (M. Elad et al 2012/2013)
- Weighted version of optimal analysis on seismic
- Prove theoretical results

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