

# Compressed sensing, random Fourier matrix and jittered sampling

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(Joint work with Hassan Mansour, Rayan Saab and Ozgur Yilmaz)

# Introduction

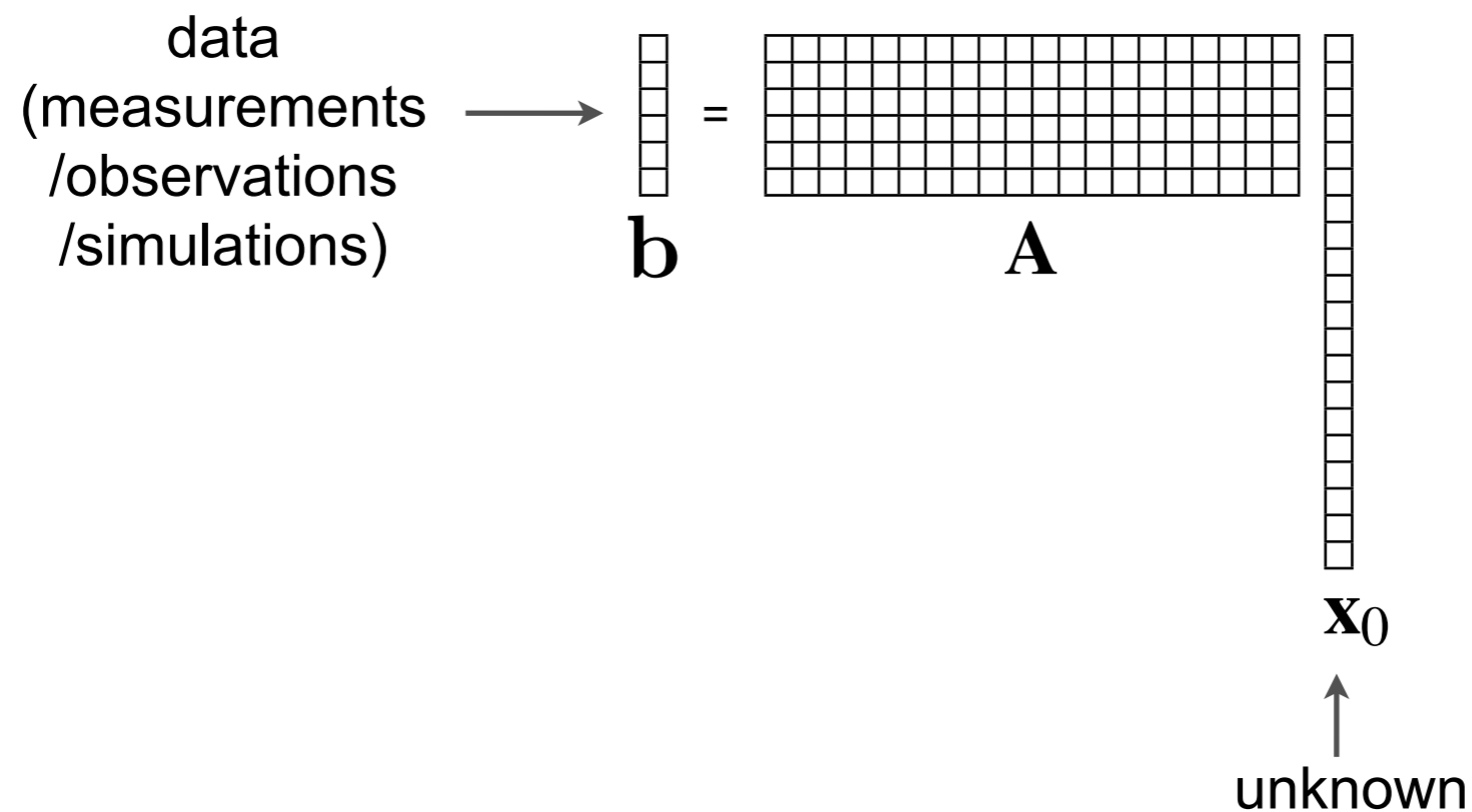
Compressed sensing is a powerful technique to reconstruct sparse data.

- What is the main advantage of jittered sampling?
- What do we mean by better results?



# Compressed sensing

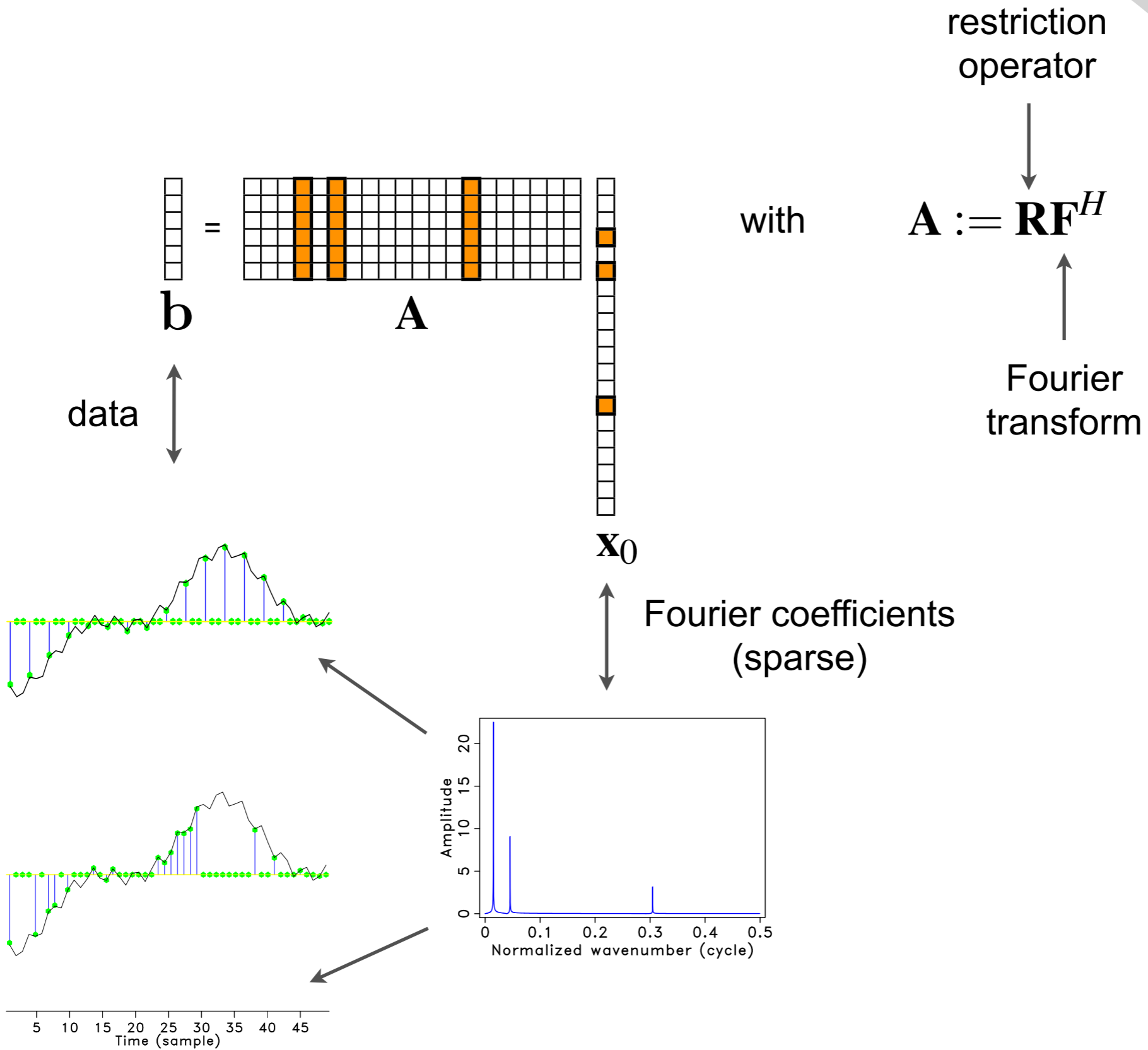
Consider the following (severely) *underdetermined* system of *linear* equations:



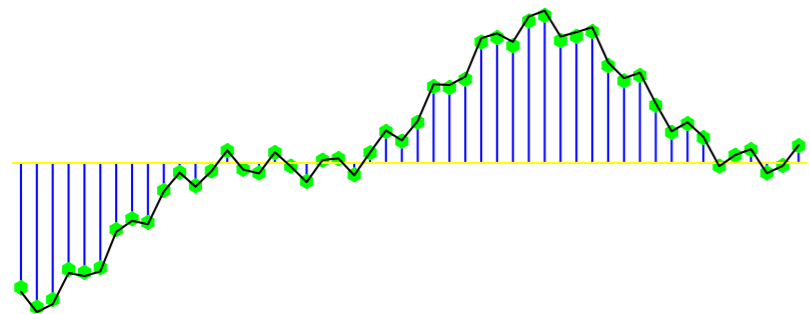
Is it possible to recover  $\mathbf{x}_0$  accurately from  $\mathbf{b}$ ?

*Compressed Sensing* attempts to answer this questions rigorously.

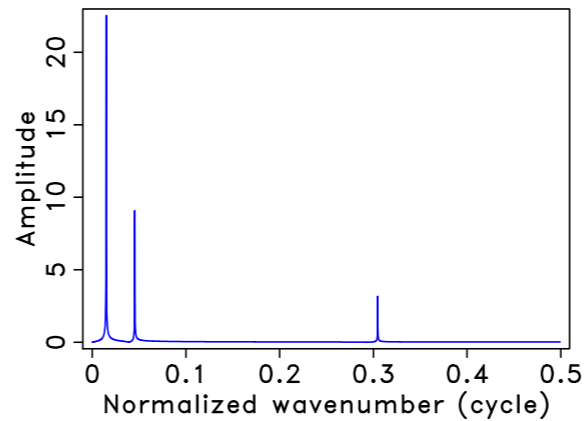
# Sparse recovery



# Coarse sampling schemes

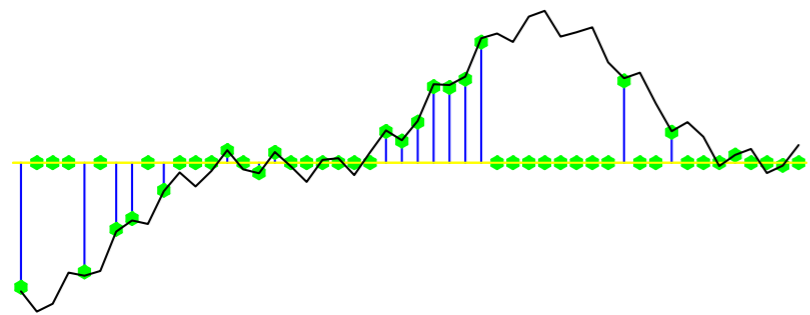


Fourier  
→  
transform

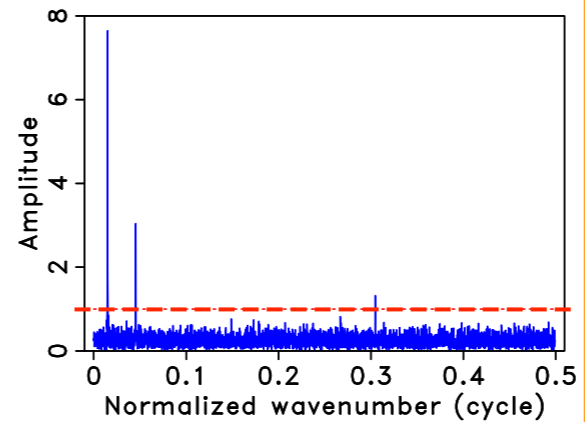


few significant coefficients

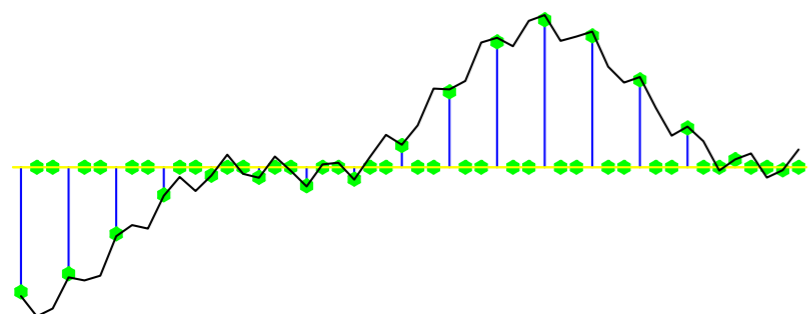
## 3-fold under-sampling



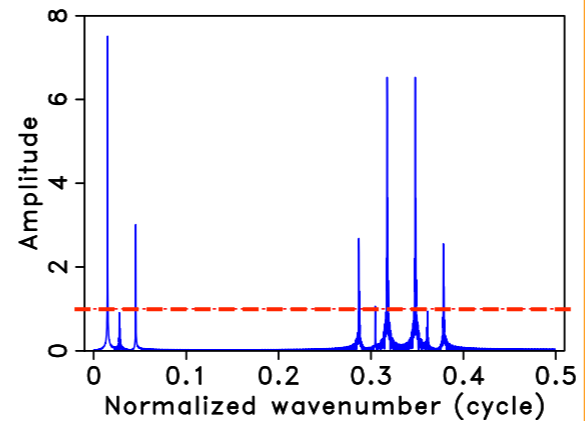
Fourier  
→  
transform



significant coefficients detected



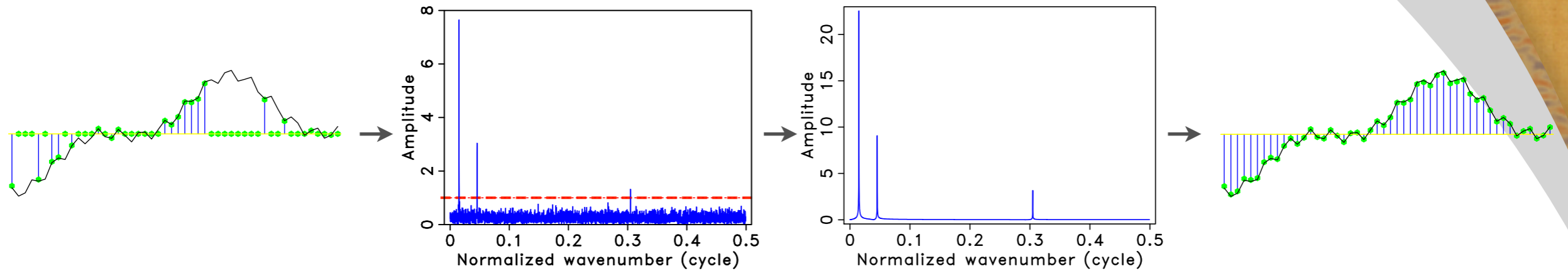
Fourier  
→  
transform



ambiguity

[Hennenfent & Herrmann, '08]

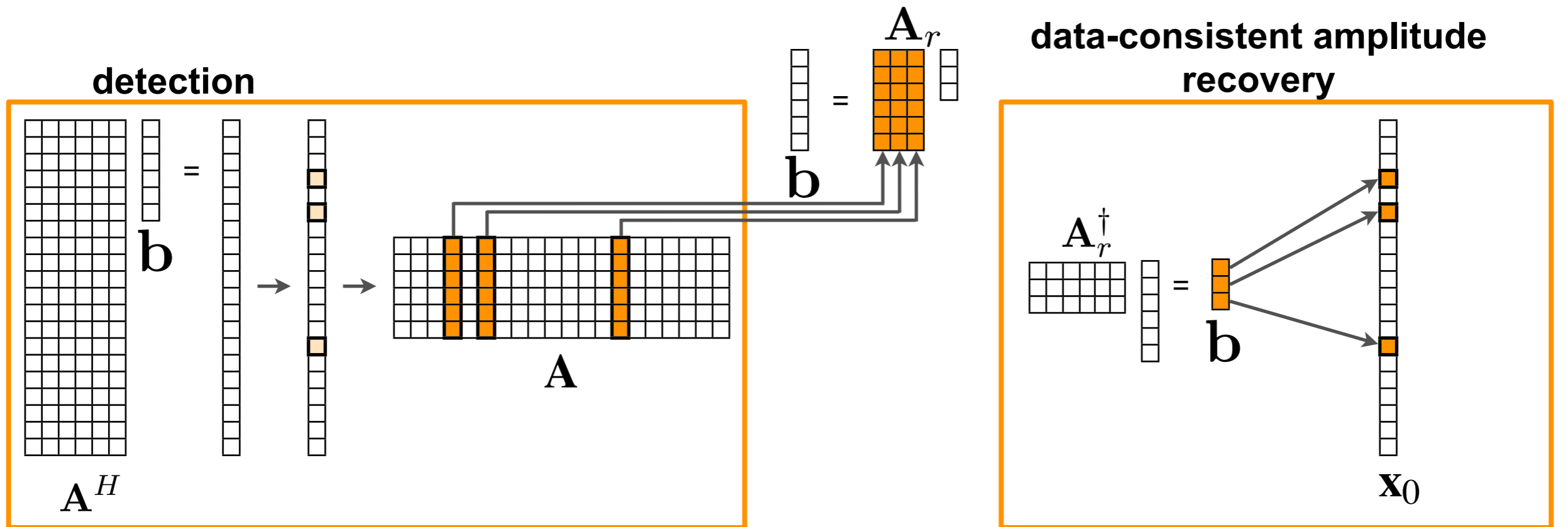
# NAIVE sparsity-promoting recovery



inverse  
Fourier  
transform

detection +  
data-consistent  
amplitude recovery

Fourier  
transform



# Sampling schemes

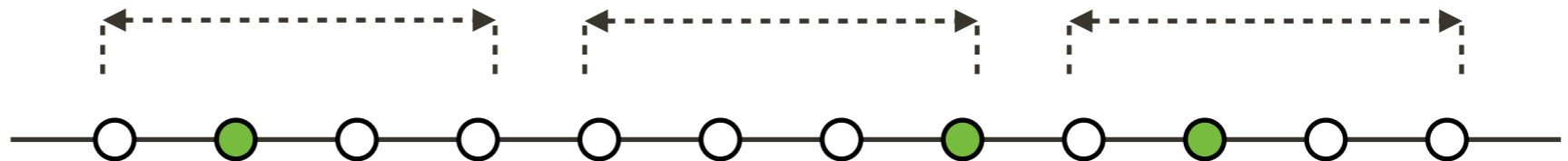
**FULL  
SAMPLING**



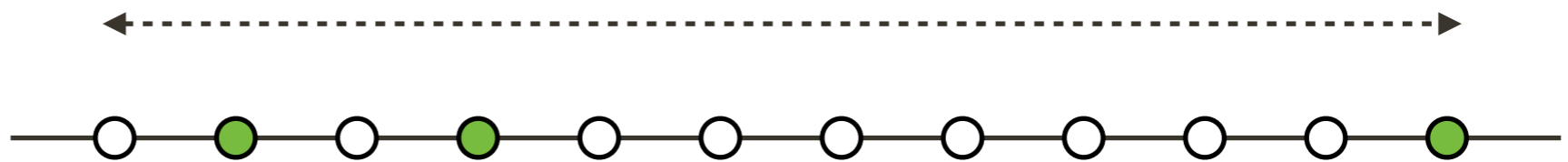
**REGULAR  
UNDERSAMPLING**  
( $\eta = 4$ )



**JITTERED  
UNDERSAMPLING**  
( $\eta = 4$ )

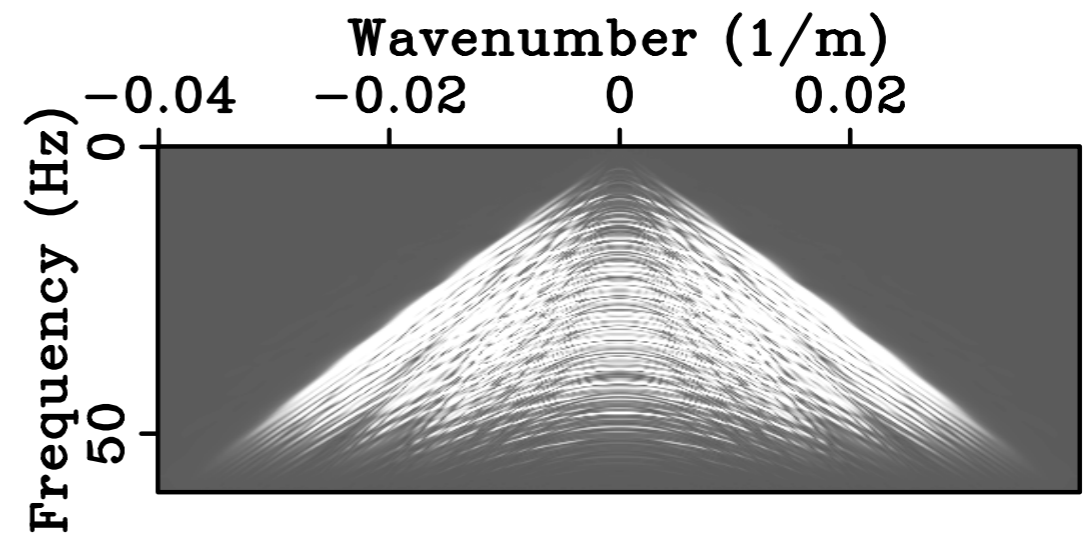
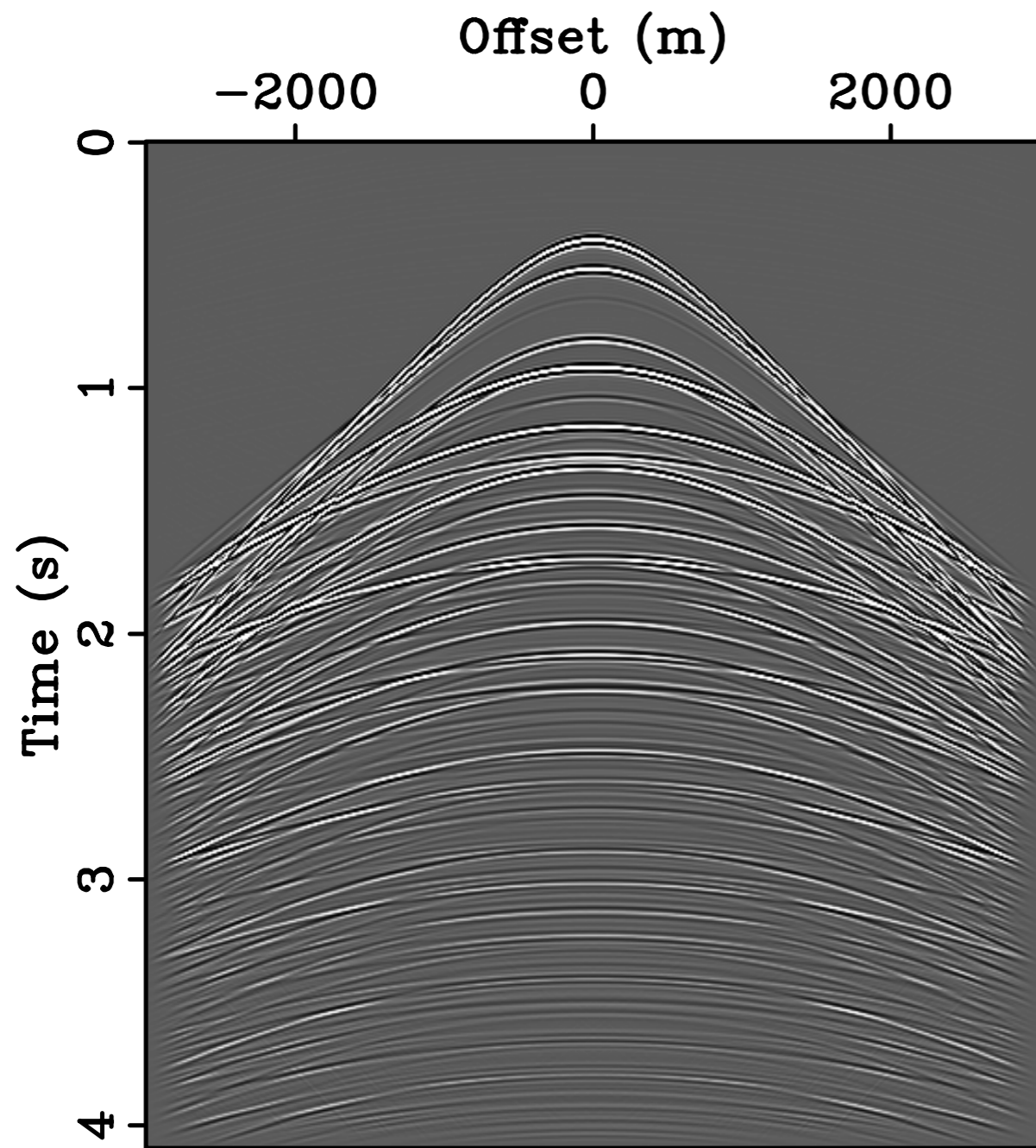


**RANDOM  
UNDERSAMPLING**  
( $\eta = 4$ )



# Model

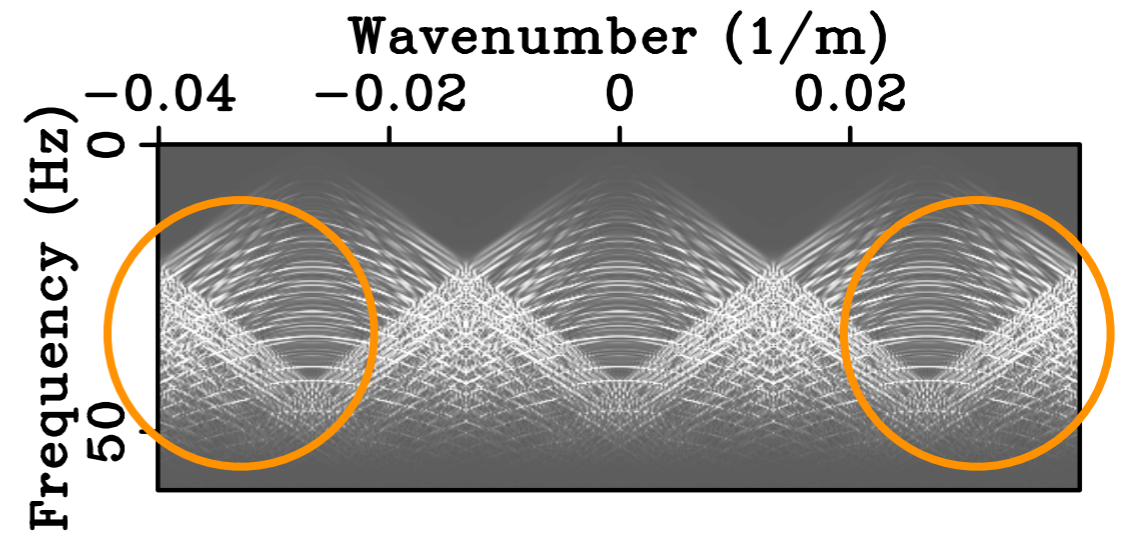
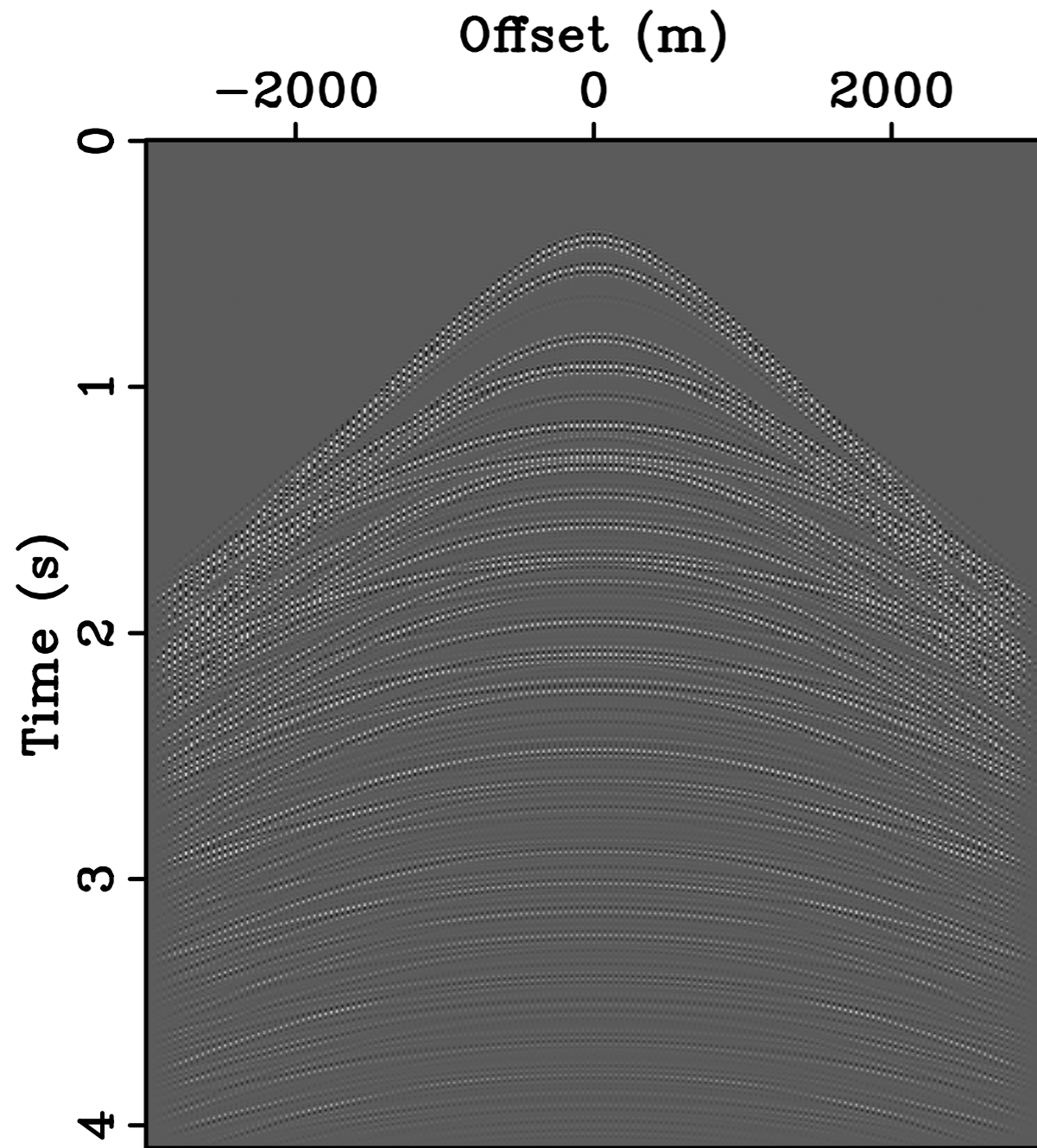
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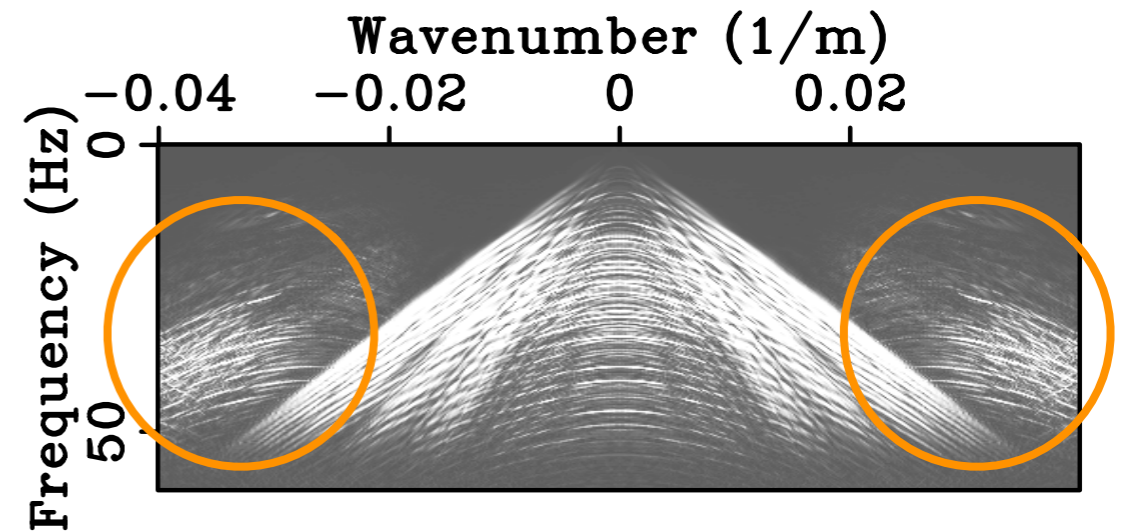
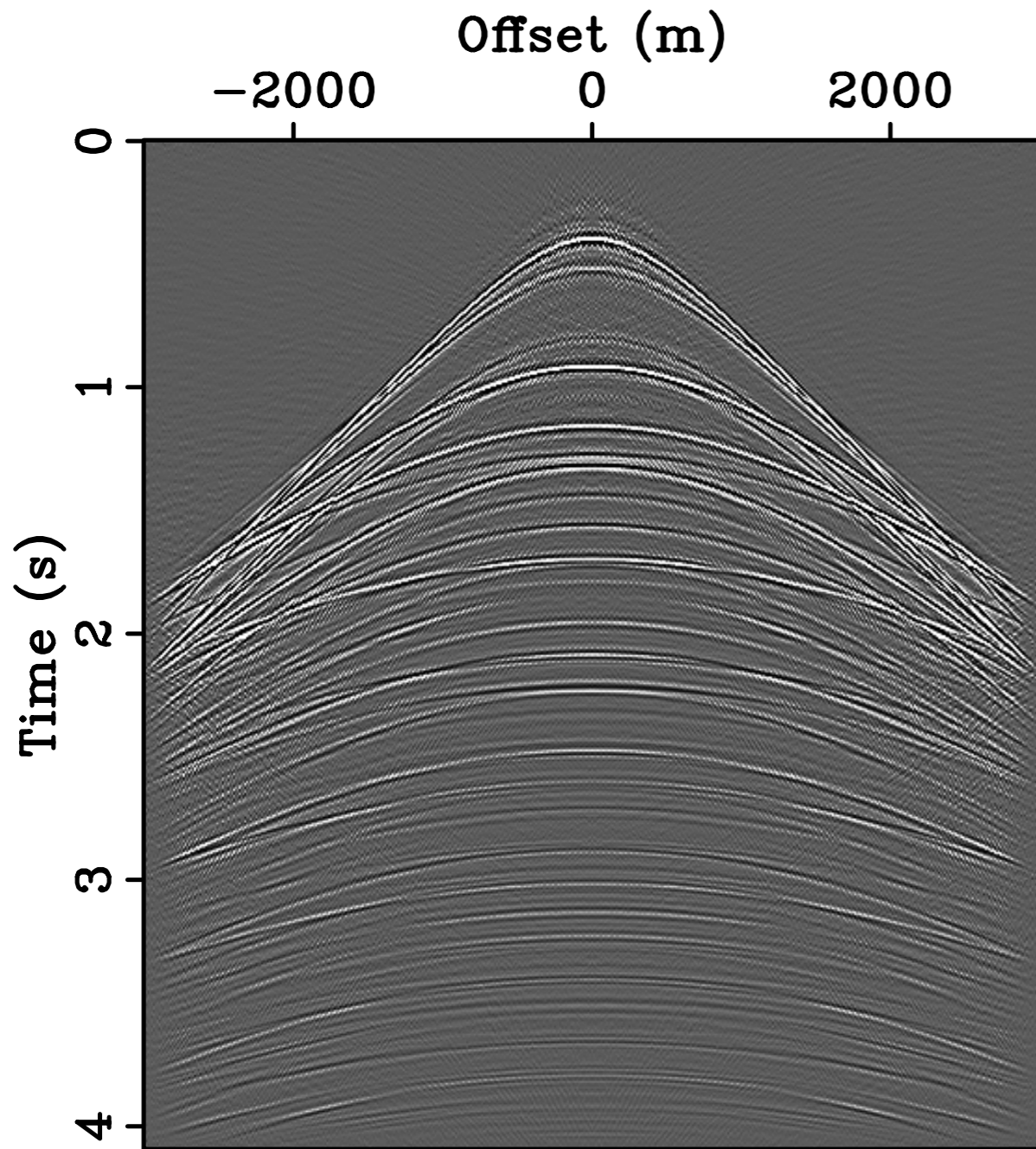


# Regular 3-fold undersampling

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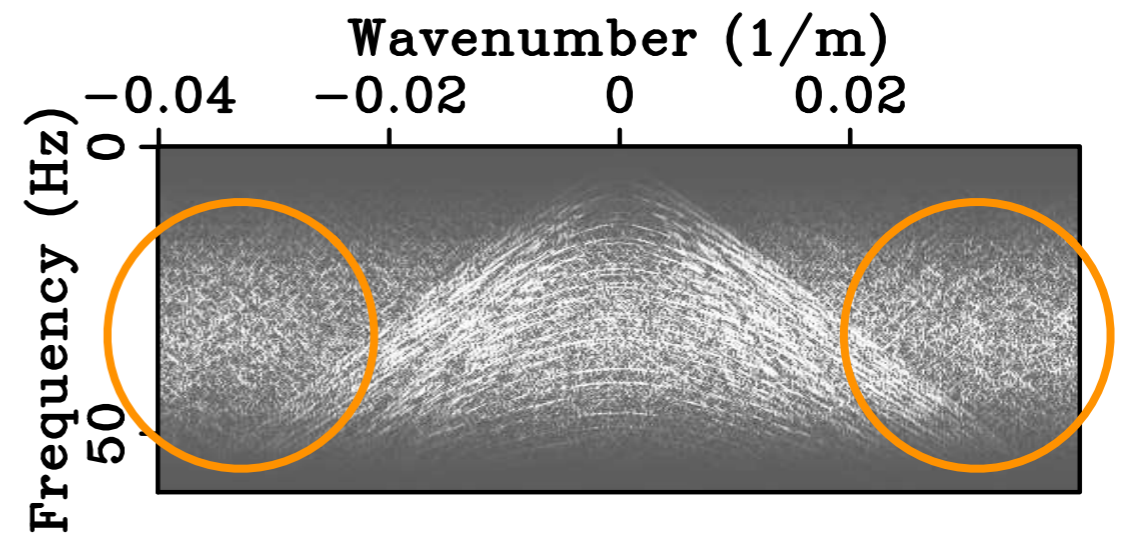
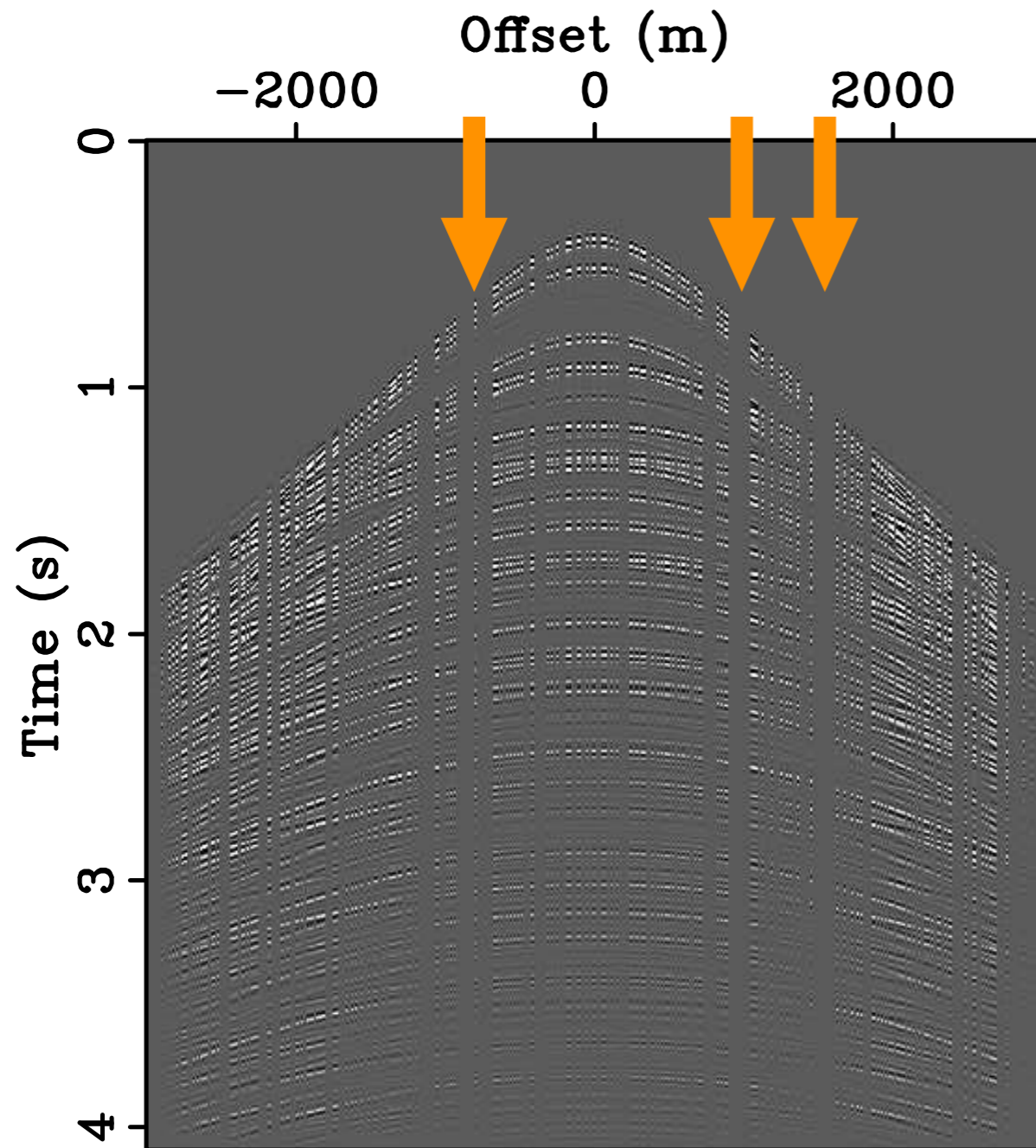
# CRSI from regular 3-fold undersampling



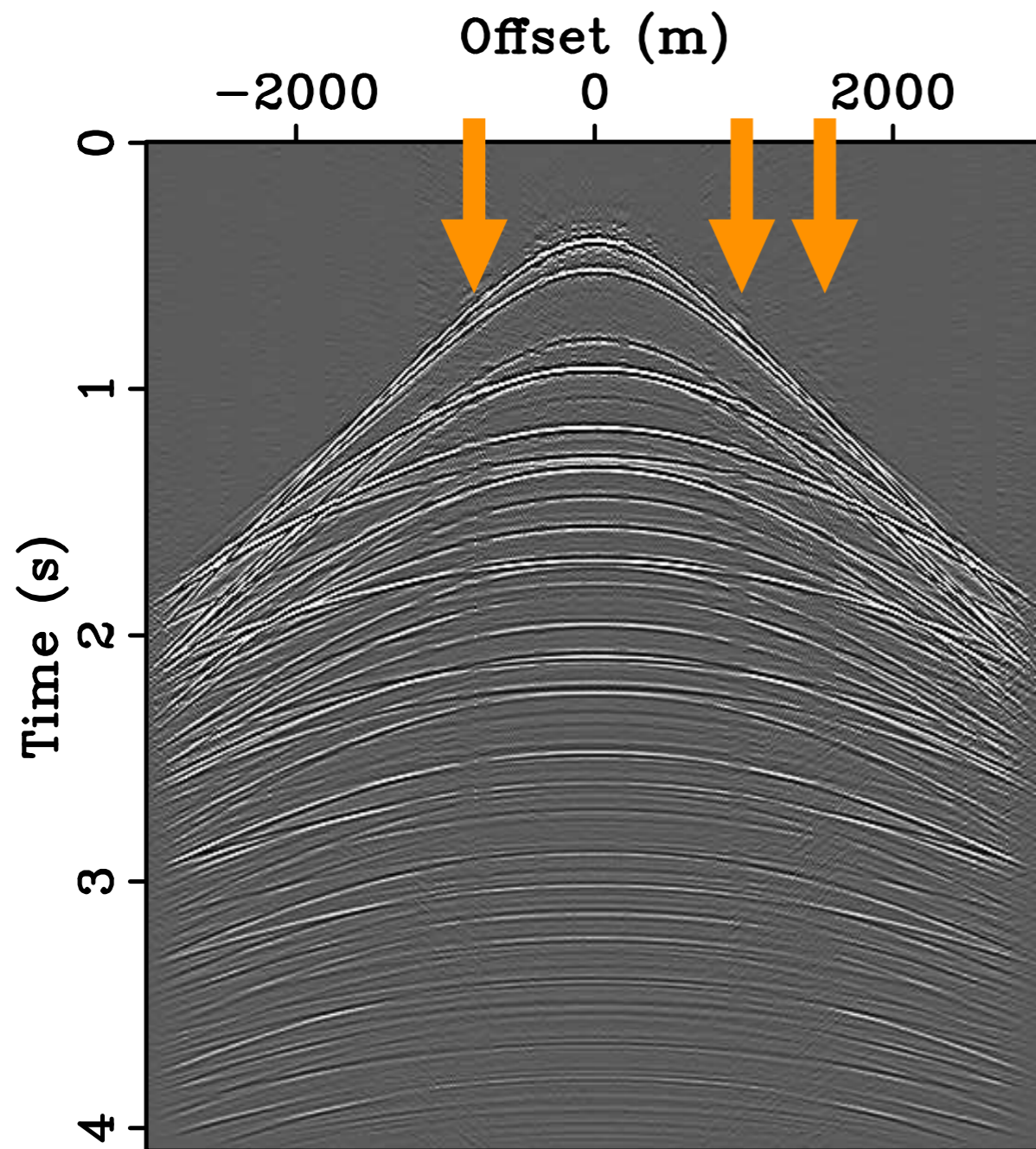
$$\text{SNR} = 20 \times \log_{10} \left( \frac{\|\text{model}\|_2}{\|\text{reconstruction error}\|_2} \right)$$



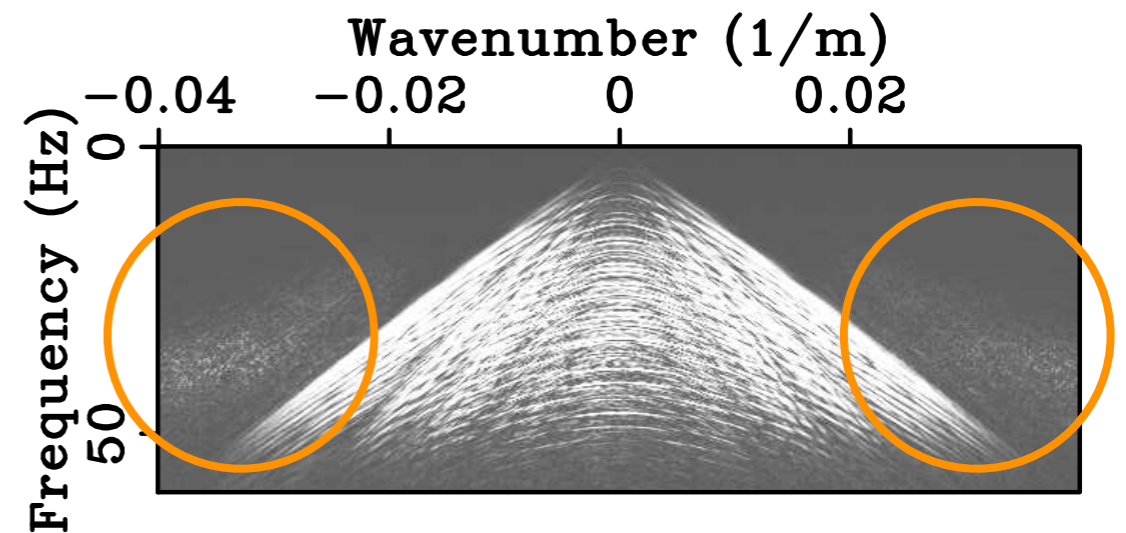
# Random 3-fold undersampling



# CRSI from random 3-fold undersampling



SNR = 9.72 dB

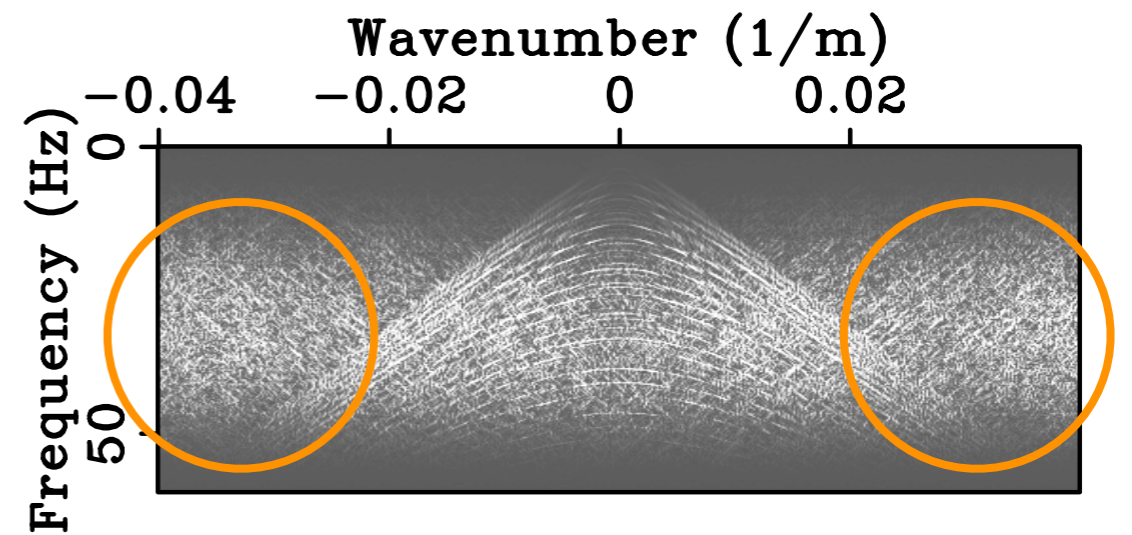
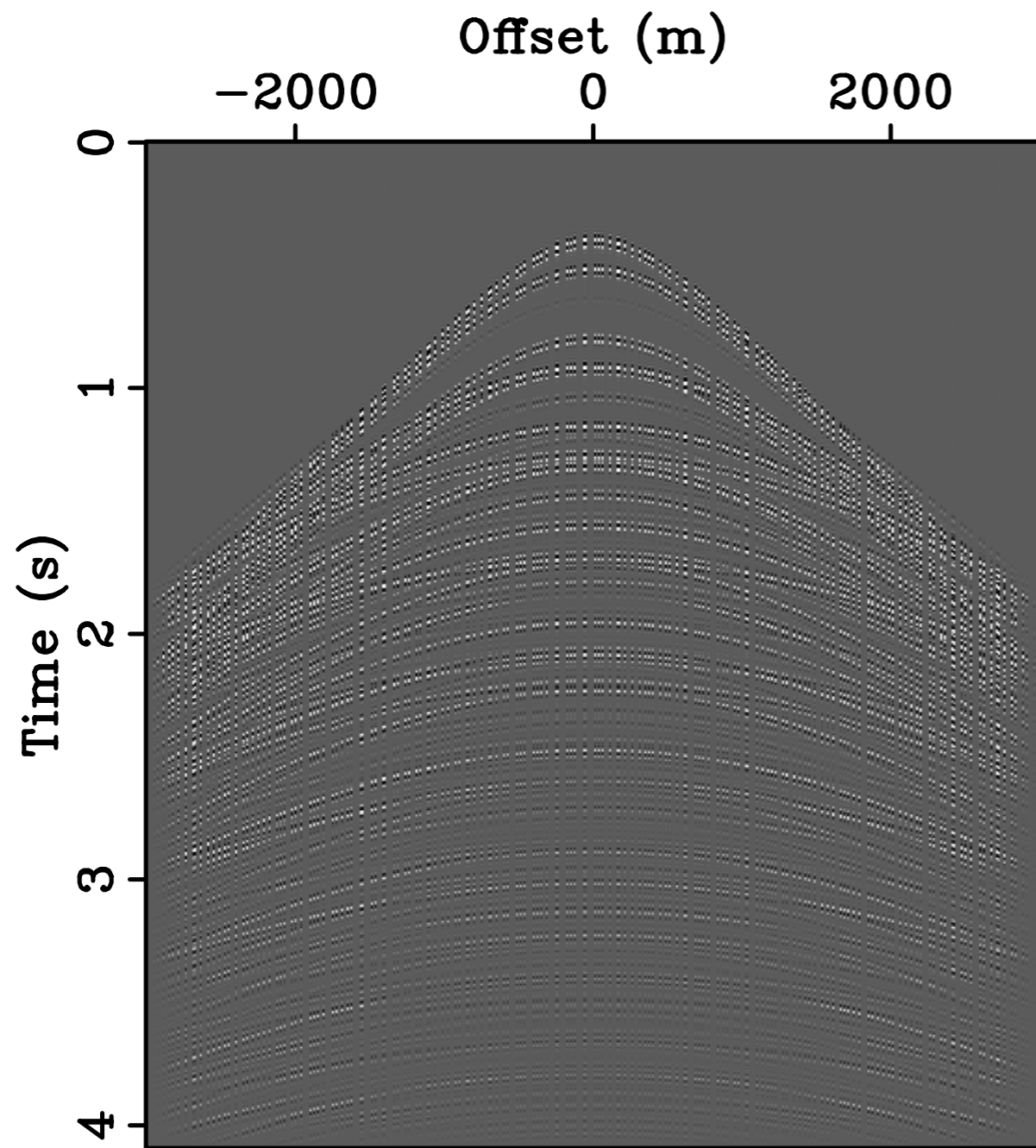


$$\text{SNR} = 20 \times \log_{10} \left( \frac{\|\text{model}\|_2}{\|\text{reconstruction error}\|_2} \right)$$

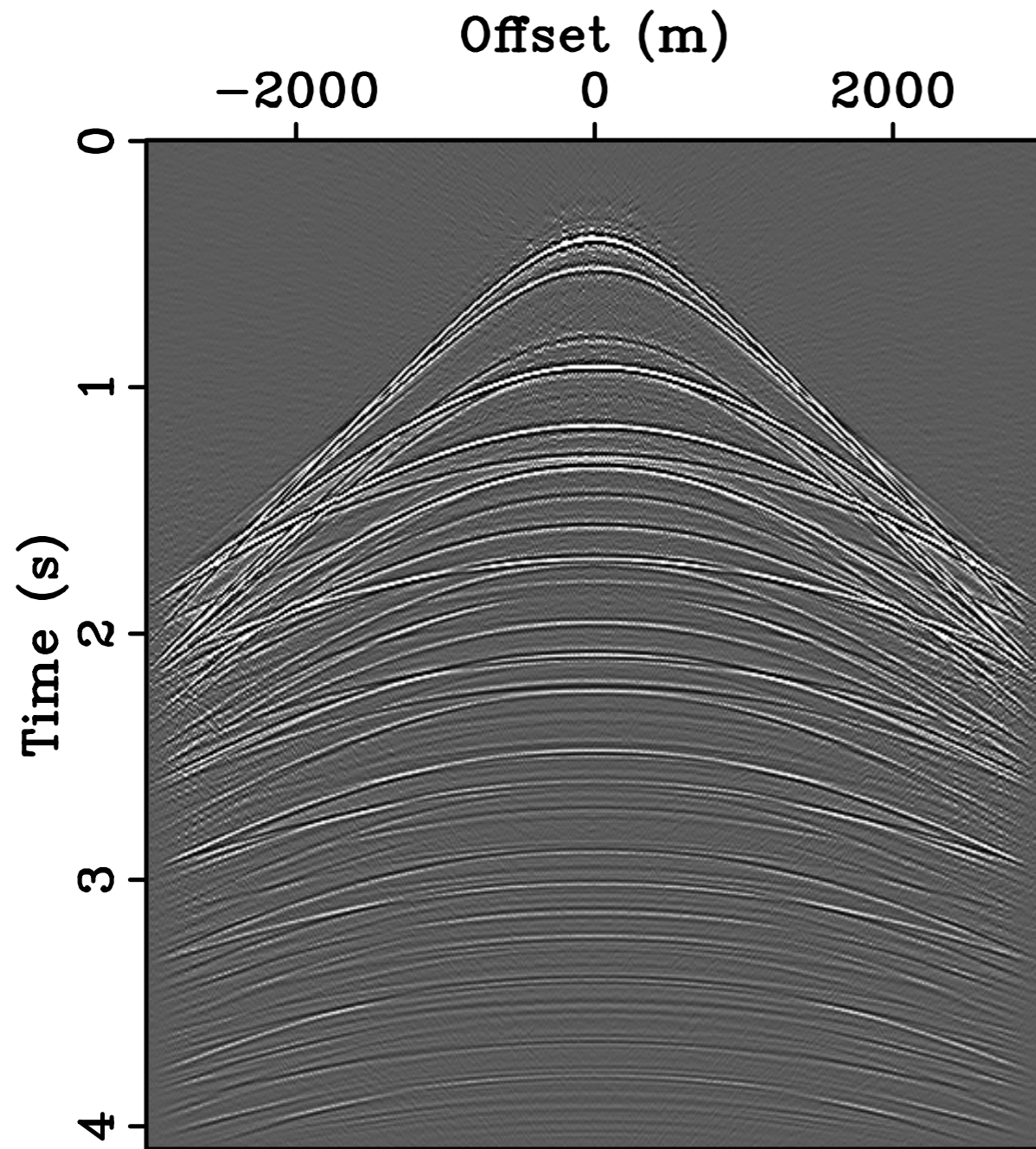


# Jittered 3-fold undersampling

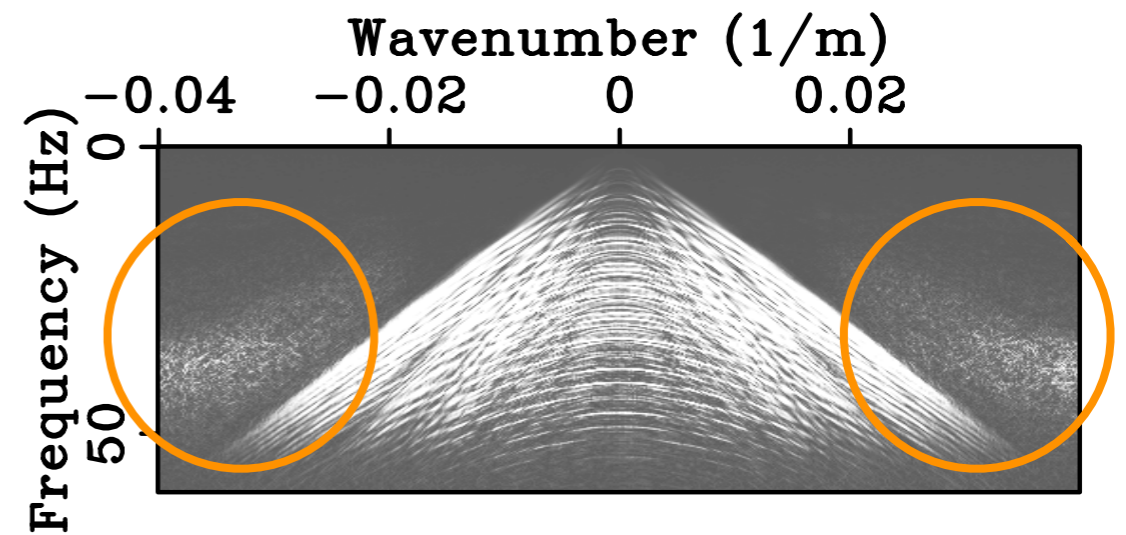
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# CRSI from jittered 3-fold undersampling



SNR = 10.42 dB



# Compressed sensing

How many measurements do we need to make?  
Far less than what Shannon tells us.

$$y = Ax$$

$x$  is a vector in  $\mathbb{R}^N$

$y$  is a vector in  $\mathbb{R}^n$

$y$  is observation

$A$  is a measurement matrix

$A$  has  $n$  rows and  $N$  columns, where  $n \ll M$ .



# Measurement matrix

$$y = Ax \quad A \text{ is a matrix}$$

The matrix satisfies the RIP property:  
nearly preserve length of sparse vectors.

Fourier matrix is more practical.

Gaussian matrix is easier to analyze .



# Random Fourier matrix

- Start with a DFT matrix ( $N$  by  $N$ )
- Pick  $n$  rows at random
- Column entries are not independent
- How to pick the  $n$  rows?

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Regular sampling:

row 10, 20, 30, 40, 50, 60, ..., 990, 1000

Jittered sampling:

7, 16, 22, 36, 44, 53, 67, ..., 994

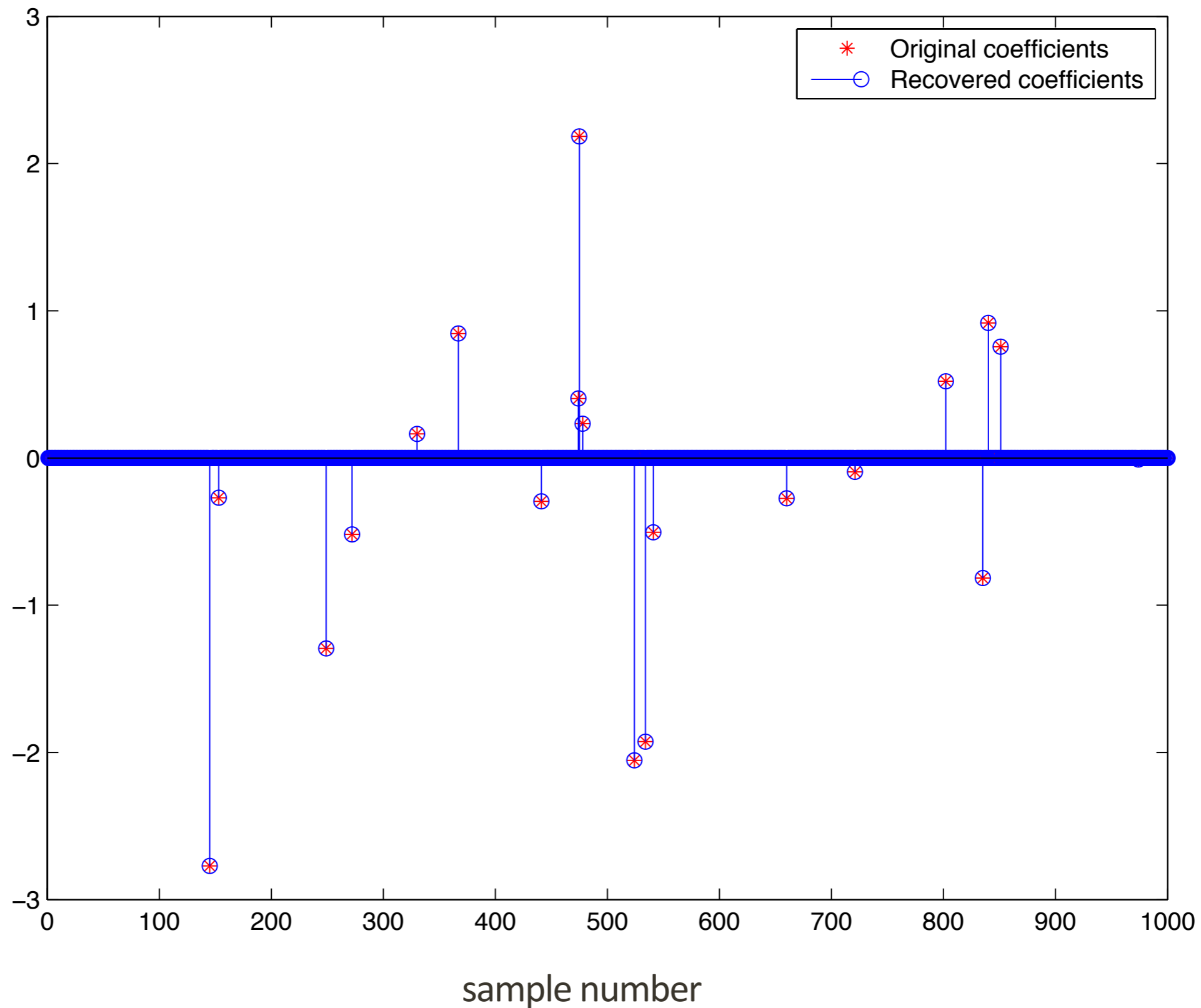
from row 1 to row 10, pick one row

from row 11 to row 20, pick the second row

from row 21 to row 30, pick the third row

# Recovery of sparse signal

$N = 1000$   
 $n = 200$   
k-sparse  
 $k = 20$



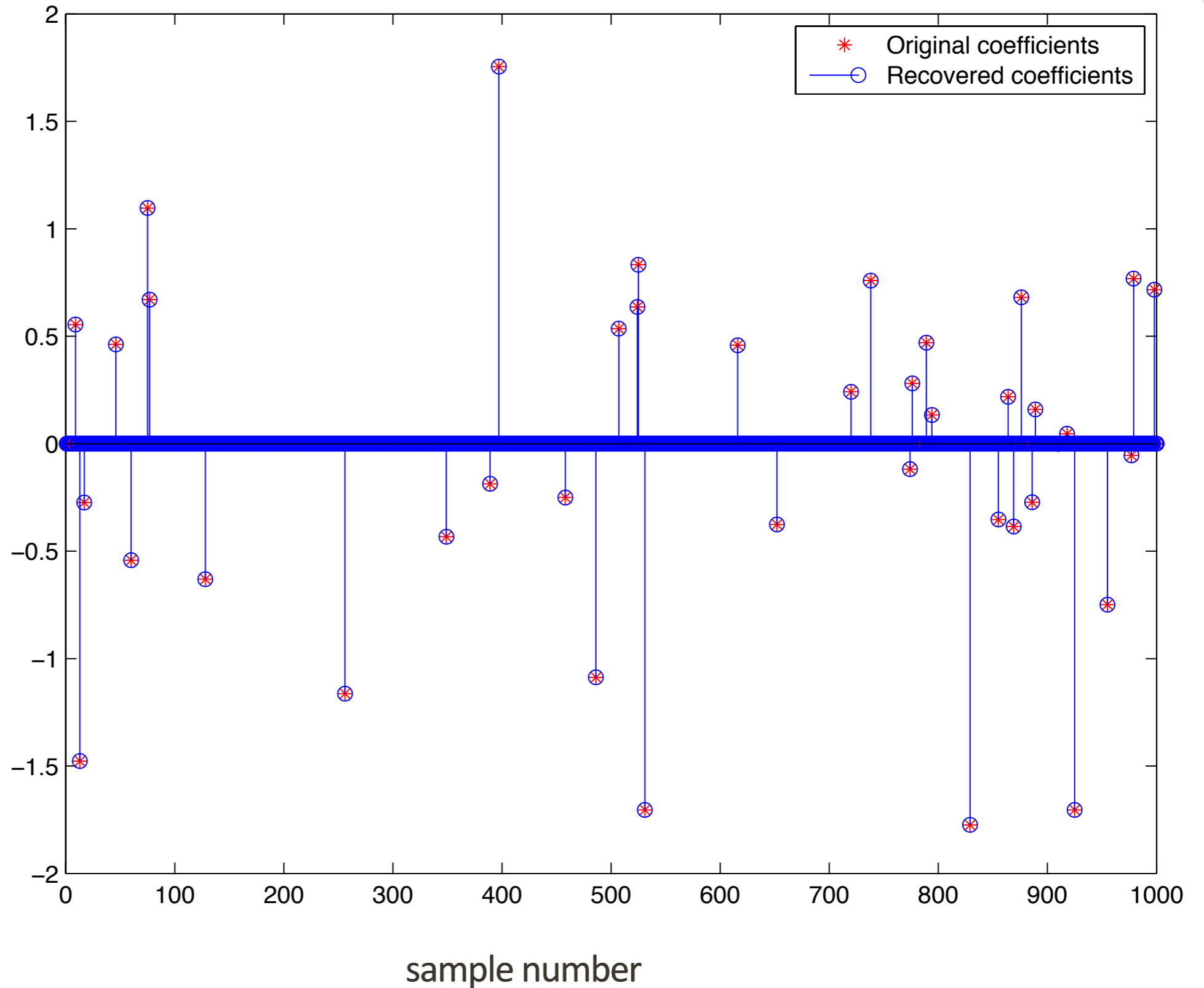
# Sparsity

- Compressed sensing can be applied when a signal is sparse.
- What if your signal is not sparse enough?



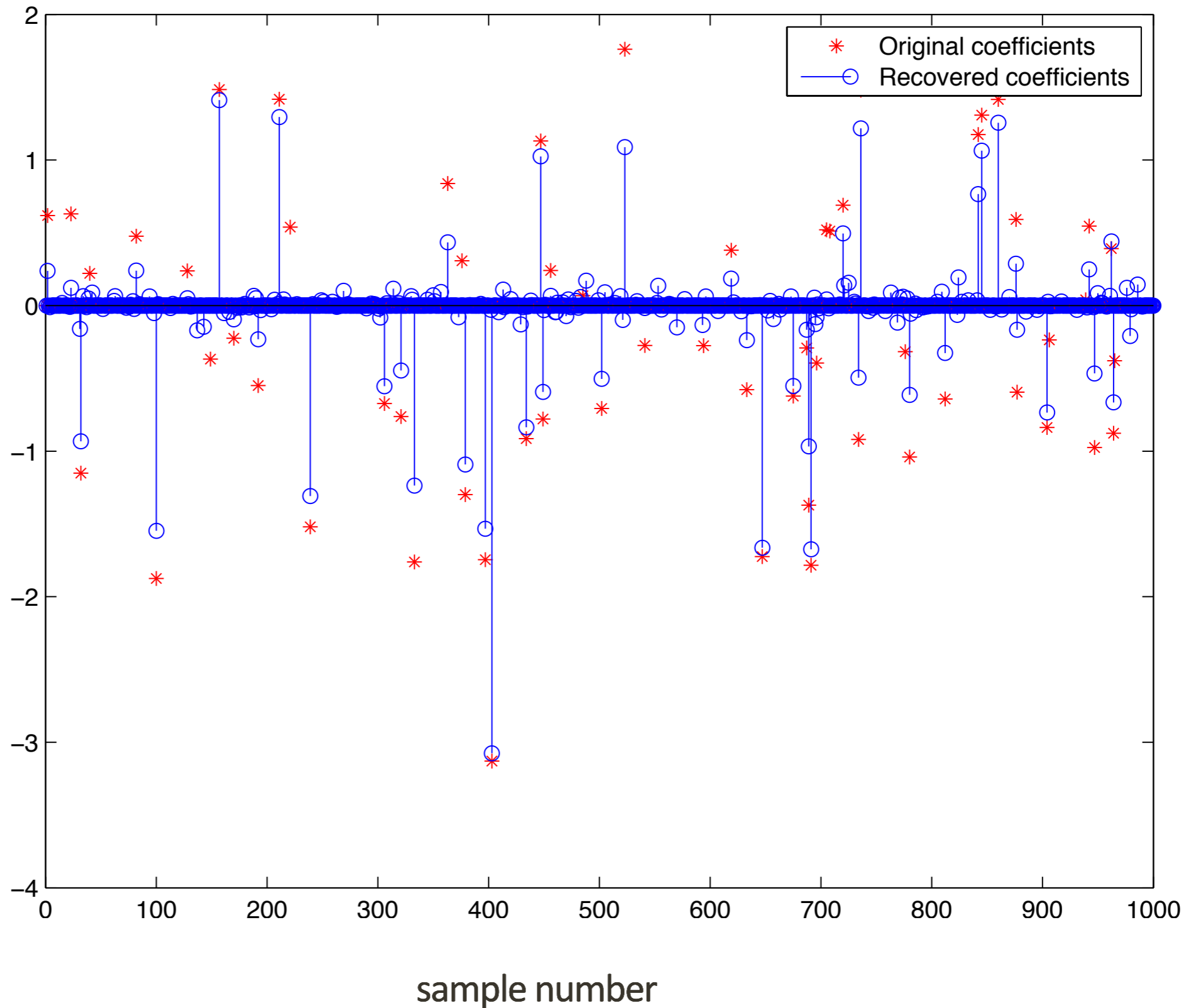
# Recovery of sparse signal

$N = 1000$   
 $n = 200$   
 $k$ -sparse  
 $k = 40$



# Partial recovery

$N = 1000$   
 $n = 200$   
k-sparse  
 $k = 60$



When signal is not sparse enough, there can be reconstruction error.

But if most non-zero entries are in the low pass region of the signal, can we recover the signal?



# What if most non-zero entries are in low-pass?

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Signal in 1000 dimensions is 60-sparse, with 50 entries in the low pass and 10 entries in the high pass.

Suppose we make 200 measurements.

Goal: Compare the reconstruction error in Uniform sampling versus Jittered sampling.

Reconstruction error

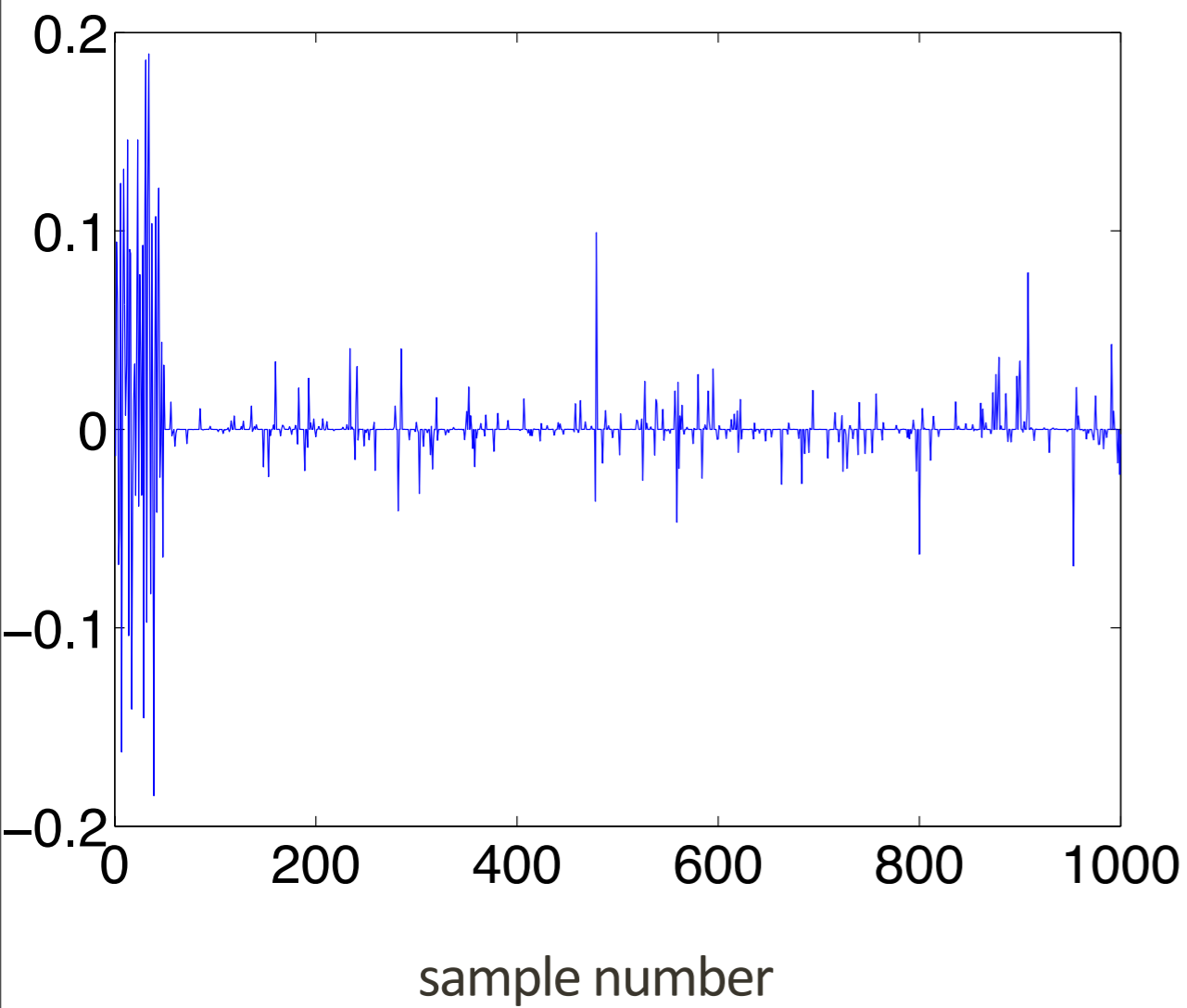
= Difference between actual and reconstructed signal



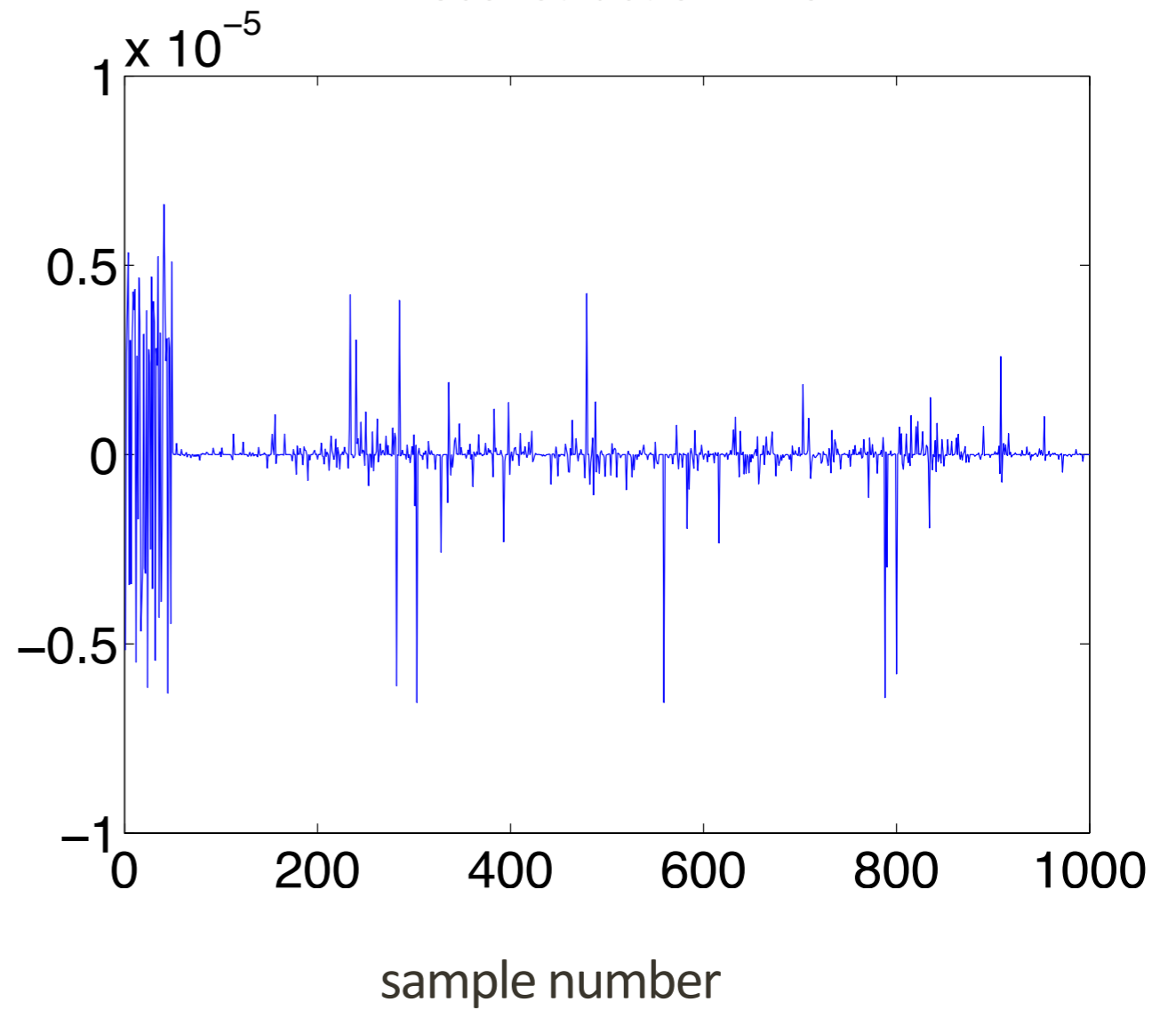
# Uniform

# Jittered

Reconstruction Error



Reconstruction Error



# Better recovery on lowpass

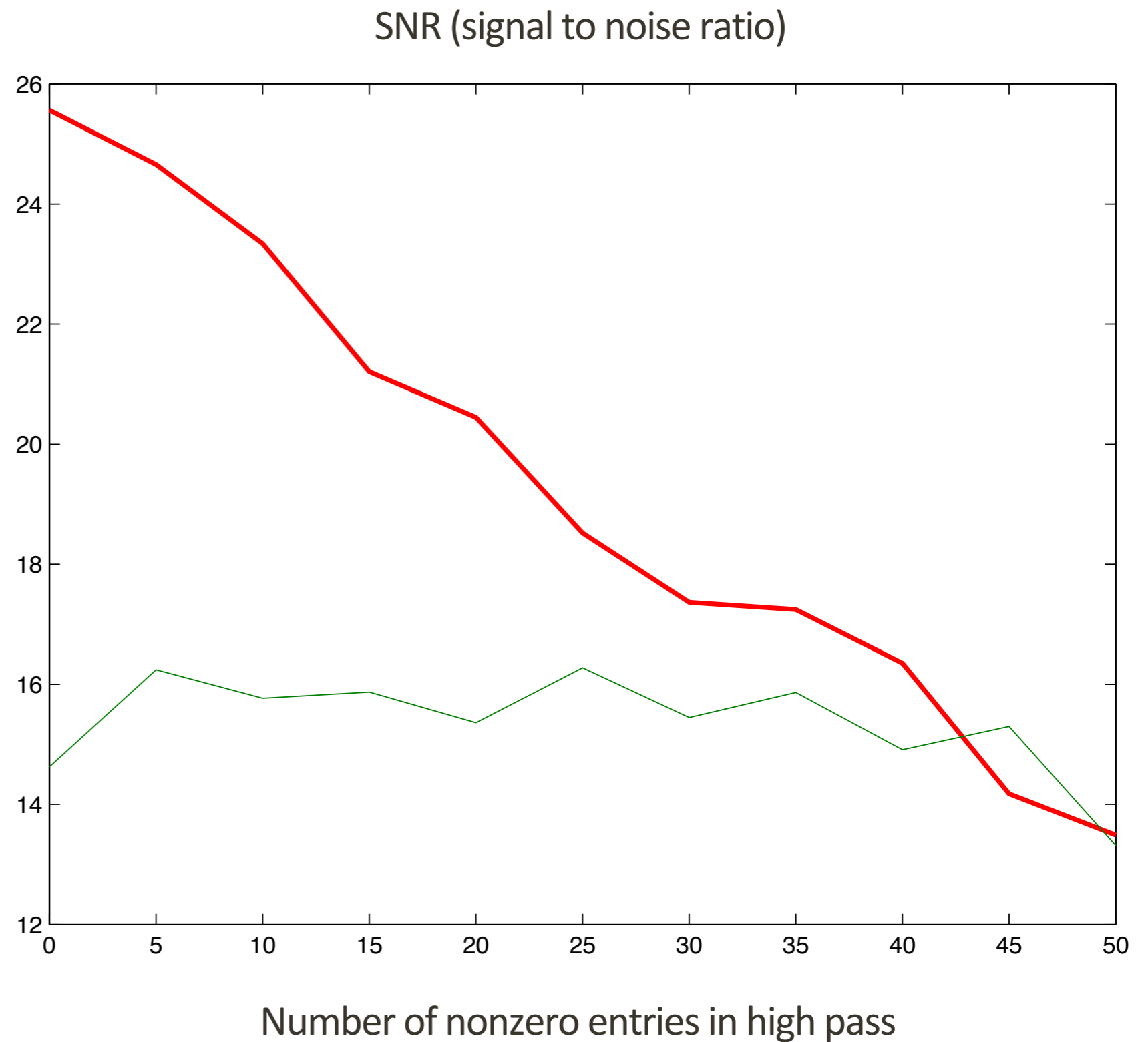
Jittered and  
Uniform  
sampling

$N = 1000$

$n = 200$

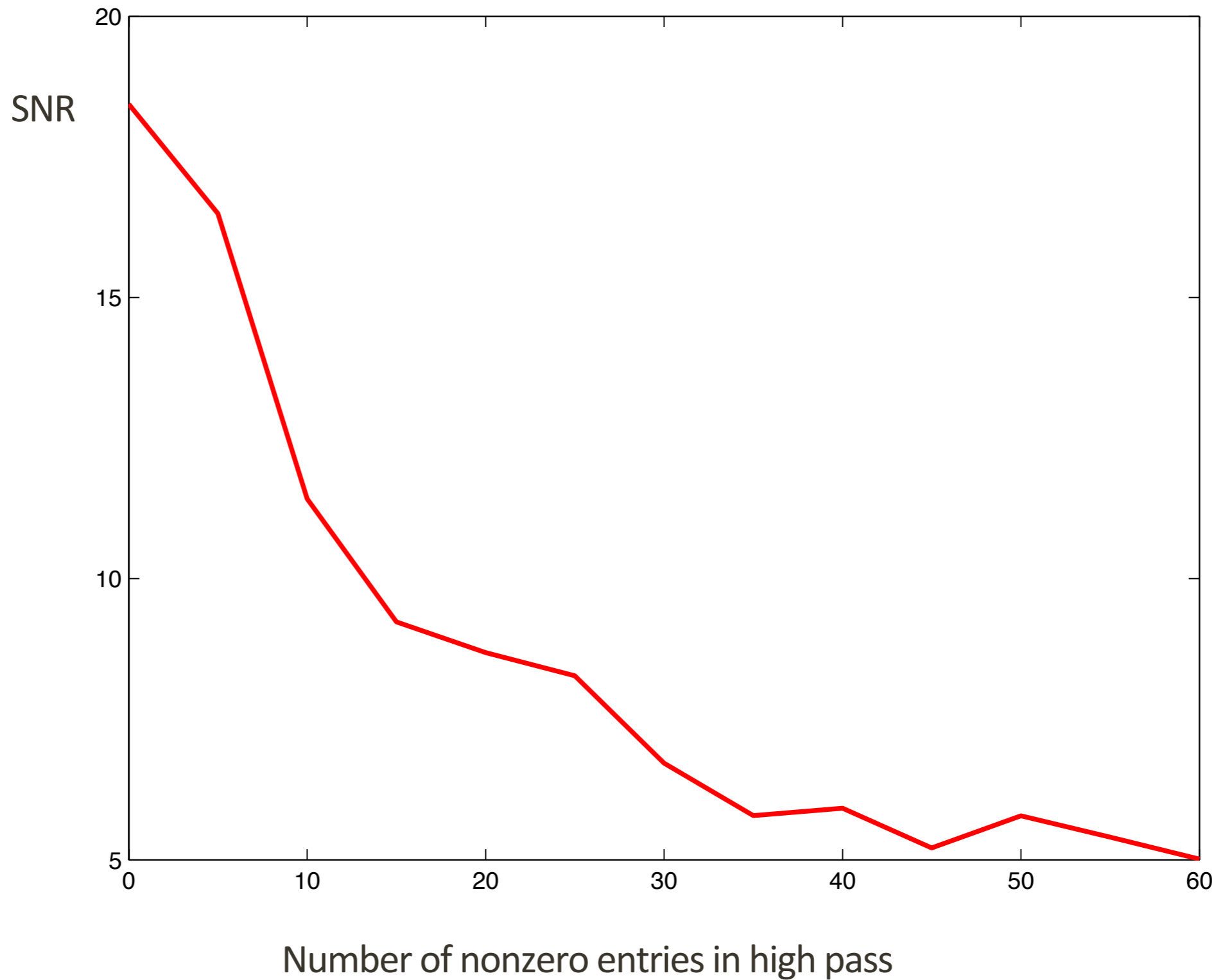
k-sparse

$k = 60$



# SNR decreases as frequency increases

$N = 1000$   
 $n = 200$   
k-sparse,  
 $k = 70$



# What do you gain?

Uniform: flat error as function of frequency

Jittered: SNR increases as frequency decreases



# Moral of the story

What is one main advantage of jittered sampling?

Better reconstruction on low pass and without doing worse on high pass.

# Potential improvement

- Jittered sampling is better than uniform sampling
- Understand why
- Do educated jittered sampling instead of random jitter

# Exploit sparsity structure

Data = sum of wave atoms

Each wave atom has the same shape.

$$X = c_1\psi_1 + c_2\psi_2 + \dots + c_N\psi_N$$

Suppose coefficients are organized in a tree structure.

# Better reconstruction

- What does it mean to reconstruct a signal with high probability?
- Uniform recovery implies non-uniform recovery, but converse is not true



## Uniform recovery

Uniform recovery means that once the random matrix is chosen, then with high probability, **all**  $k$ -sparse signals can be recovered.

Non-uniform recovery states only that **each**  $k$ -sparse signal can be recovered with high probability using a random draw of the DFT matrix.

# Theory behind the scene

$$B = \{x \in \mathbb{R}^N : \|x\|_2 = 1\}$$

**Theorem:** Let  $x, y$  be any two vectors in  $B$ .

Let  $A$  be a random projection into  $k$ -dimensional subspace.

Then the following holds.

$$\Pr \left( \left| \|Ax\|_2 - \|Ay\|_2 \right| > u \sqrt{\frac{k}{n}} \|x - y\|_2 \right) \leq \exp(-cu^2 k)$$

# Dimensional reduction

What does the theorem say in plain English?

$$N = 1000 \quad k = 60 \quad \mathbb{R}^N \rightarrow \mathbb{R}^k$$

Points in very high dimension that were near to each other, when you project them to lower dimension, (most likely) there will not be too much distortion.

---

Theorem (on Dimensional reduction) applies to **every** random projection. It is stronger than the following theorem:

Given any two nearby points  $x$  and  $y$ , there **exists a** random projection matrix  $A$  such that  $Ax$  and  $Ay$  will not be distorted too much.



---

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Given any two nearby points  $x$  and  $y$ , there **exists a** random projection matrix  $A$  such that  $Ax$  and  $Ay$  will not be distorted too much.

This  $A$  can be taken to be a Gaussian matrix.

[Concentration of Measure argument does not apply to random Fourier matrix.]

# Conclusion

Jittered sampling leads to better reconstruction on low pass, without doing worse on high pass.

Thank You!

# Acknowledgement

- Ozgur Yilmaz
- Felix Herrmann
- Haneet Wason, Hassan Mansour
- All siblings from the SLIM family

This work was in part financially supported by a PIMS fellowship from the Pacific Institute for Mathematical Sciences and by a NSERC Accelerator Discovery award (Yilmaz - AID 411944-2011). This research was carried out as part of the SINBAD II project with support from the following organizations: BG Group, BGP, Chevron, ConocoPhillips, Petrobras, PGS, Total SA, and WesternGeco.