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Robust FWI Using Student's t-distribution

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Full Waveform Inversion

- The Full Waveform Inversion (FWI) problem is to find solutions to the Helmholtz PDE that match data from source experiments on the surface
- Problems are typically very large: billions of variables and terabytes of data.
- Typically formulated as a Nonlinear Least Squares (NLLS) problem:

$$\min_{\mathbf{m}} \{f(\mathbf{m}) := \|\mathbf{D} - \mathcal{F}[\mathbf{m}; \mathbf{Q}]\|_F^2 \}$$

- \mathbf{D} := data
- \mathbf{m} := model parameters (speed or slowness squared)
- \mathbf{Q} := multiple source experiments
- \mathcal{F} := solution operator of Helmholtz eqn. with absorbing boundary

Statistical Implications

• The NLLS formulation is equivalent to the following statistical model:

$$\mathbf{D} = \mathcal{F}[\mathbf{m};\mathbf{Q}] + \boldsymbol{\epsilon}$$

 $\epsilon \sim \mathbf{N}(0, I)$

 Equivalence follows from maximum likelihood estimate for model parameters:

$$\mathcal{L}(\mathbf{m}) \propto \exp\left(-rac{1}{2}\left\|\mathbf{D}-\mathcal{F}[\mathbf{m};\mathbf{Q}]\right\|_{F}^{2}
ight)$$

• Minimizing the negative log likelihood is exactly the FWI problem.

• Q: So what?



• Large deviations from the mean are VERY unlikely in the Gaussian model:

	Gaussian	
$p(x - \mu > 4\sigma)$	6.3×10^{-5}	
$p(x-\mu > 8\sigma)$	1.3×10^{-15}	

- Observations more than 4 standard deviations away from the mean occur less than .006 percent of the time.
- As we get further away, the likelihood shrinks astronomically.
- Low likelihood values correspond to HIGH penalties for outliers.

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'Outliers' in FWI??

- Mathematical model cannot distinguish 'artifacts' from 'outliers'. Any unexplained events in the residual will have a strong effect on the final image.
- Examples:

 Modeling Inelastic/Anisotropic data with Acoustic PDE
 Ignoring Acquisition Models
- Key point: models are improving all the time, but are never perfect. It is worthwhile to have methods that still perform well when models are wrong.
- Q: How do we design such methods?

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Statistical Modeling

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• We can tweak the assumptions on the NOISE in the model:

$$\mathsf{D} ~=~ \mathcal{F}[\mathbf{m};\mathbf{Q}]+oldsymbol{\epsilon}$$

$$\epsilon \sim$$
 Heavy Tailed Distribution

• The parametric form of the distribution then determines the optimization formulation:

$$\min_{m} -\log(\mathcal{L}(\mathbf{m})) := -\log\left(f\left(\mathbf{D} - \mathcal{F}[\mathbf{m}; \mathbf{Q}]\right)\right)$$

• Q: Which distribution do we choose, and how do we solve the problem?



• We present a comparison with two other distributions:

	Gaussian	$L(\lambda = 1)$	T(df = 3)
$p(x - \mu > 4\sigma)$	6.3×10^{-5}	1.8×10^{-2}	0.6×10^{-2}
$p(x - \mu > 8\sigma)$	1.3×10^{-15}	3.3×10^{-4}	8.1×10^{-4}

- The Laplace distribution corresponds to the L1 penalty on the misfit: $\|\mathbf{D}-\boldsymbol{\mathcal{F}}[\mathbf{m};\mathbf{Q}]\|_1$
- In the class of CONVEX negative log likelihoods, it has the heaviest tail (as does the distribution corresponding to the Huber misfit).
- But the full problem is non-convex anyway, so let's consider Student's t!

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Densities, Penalties, and Gradients







Student's t-Distribution

• Student's t-density

$$\mathbf{p}(\epsilon|\mu, M) = \frac{\Gamma(\frac{s+l}{2})}{\Gamma(\frac{s}{2}) \det[\pi s M]^{1/2}} \left(1 + \frac{\|\epsilon - \mu\|_{M^{-1}}^2}{s}\right)^{\frac{-(s+l)}{2}}$$

• Student's t-objective for Seismic case (negative log likelihood)

$$\min_{m} \phi_{T}(m) := \sum_{i} \frac{s+l}{2} \log \left(s + \left(D - PH[m]^{-1}Q \right)_{i}^{2} \right)$$

• Student's t-gradient

$$\nabla_m \phi_T(m) = \sum_i \frac{s+l}{2} \frac{\nabla_m F[m;Q]_i^T (F[m;Q] - D)_i}{s + (D - F[m;Q])_i^2}$$

Gradient Comparison:

$$\sum_{i} \frac{1}{2} \nabla_m F[m;Q]_i^T (F[m;Q] - D)_i$$

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NLLS

$$\sum_{i} \frac{s+l}{2} \frac{\nabla_{m} F[m;Q]_{i}^{T} (F[m;Q] - D)_{i}}{s + (D - F[m;Q])_{i}^{2}}$$

Marmoussi Example

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- We consider a subset of the Marmoussi model
- 151 shots, 301 receivers
- 9 pt. discretization of Helmholtz operator with absorbing boundary; 10 m. spacing on grid
- Sample of Frequencies [5.0, 6.0, 11.5, 14.0, 15.5, 17.5, 23.5] Hz



300

20

40

TRUE REFLECTIVITY

2.5

3

2

1.5 x [km]

15 HZ DATA SLICE WITH SPIKY NOISE

60 80 100 source position [km]

120

140

2

0.5

2.5

3 0

0.5



2⊾ 0

0.5







Results I



NLLS

HUBER

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0.5

0.5











Results II



NLLS

HUBER

STUDENT

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Conclusions

- Robust formulations allow good recovery even with
 poor modeling
- 'Mistakes' are typically thought of as 'outliers' in the data, but can also be events unexplained (or ignored) by the modeling
- Since the FWI problem is non-convex, we can feel free to exploit distributions with non-convex negative log likelihoods
- Future direction: combining robust and sparse recovery.

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