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Randomized full-waveform inversion with compressive sensing

Xiang Li and Felix J. Herrmann



Full-waveform inversion

objective function:

$$\min_{\mathbf{m}} \Phi(\mathbf{m}) := \left\{ \frac{1}{2K} \sum_{i=1}^{K} \|\mathbf{d}_i - \mathcal{F}_i[\mathbf{m}]\mathbf{q}_i\|_2^2 = \frac{1}{2} \|\mathbf{D} - \mathcal{F}[\mathbf{m}]\mathbf{Q}\|_F^2 \right\}$$

 \mathbf{d}_i = monochromatic shot records

 \mathbf{q}_i = monochromatic sources

 $\mathcal{F}_i[\mathbf{m}, \mathbf{q}_i] = \text{monochromatic nonlinear forward operators}$



Dimensionality
reduction
$$\min_{\mathbf{m}} \underline{\Phi}(\mathbf{m}) := \left\{ \frac{1}{2K'} \sum_{i=1}^{K'} \|\mathbf{D}\mathbf{w}_i - \mathcal{F}_i[\mathbf{m}]\mathbf{w}_i\|_2^2 = \frac{1}{2} \|\underline{\mathbf{D}} - \mathcal{F}[\mathbf{m};\underline{\mathbf{Q}}]\|_F^2 \right\}$$



GN subproblem:

$$\min_{\mathbf{m}} \quad \underline{\Phi}(\mathbf{m}) := \frac{1}{2} \| \underline{\mathbf{D}} - \mathcal{F}[\mathbf{m}; \underline{\mathbf{Q}}] - \nabla \mathcal{F}[\mathbf{m}; \underline{\mathbf{Q}}] \delta \mathbf{m} \|_{F}^{2}.$$



 $ns' \times nf' \times nr$

 $nx \times nz$





Pareto curve

Compute T using Pareto curve [van den Berg & Friendlander, '08]





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Modified Gauss Newton

Instead of solving the *full* GN subproblem, we solve a series of *dimensionality*-reduced LASSO problems.

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For each LASSO subproblem, we redraw a new random subset of (simultaneous) source experiments.

LASSO problem solved by Spectral Projected Gradient.

Jacobian & Hessian are never formed explicitly.

We use curvelets to sparsely represent geophysical model updates.

Modified Gauss-Newton

Algorithm 1: Dimensionality-reduced Gauss Newton with sparsity

FWI results

Time-harmonic Helmholtz:

- 205 X 701 with mesh size of 10m
- 9 point stencil [C. Jo et. al., '96]
- absorbing boundary condition with damping layer with thickness proportional to wavelength
- solve wavefields on the fly with direct solver

FWI results

Split-spread surface-free 'land' acquisition:

- 350 sources with sampling interval 20m
- 701 receivers with sampling interval 10m
- maximal offset 7km (3.5 X depth of model)
- Ricker wavelet with central frequency of I2Hz

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• recording time for each shot is 3.6s

FWI results

FWI:

- I0 overlapping frequency bands with I0 frequencies (2.9Hz-25Hz)
- I0 Gauss-Newton steps for each frequency band (solved with max 20 spectral-projected gradient iterations)



4000

3000 Velocity (m/s)

2000

Results

True model



4000

3000 Velocity (m/s)

2000

Results

Initial model



Modified GN 7 sim. shots without renewals

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4000

3000 Velocity (m/s)

2000



25 times speedup compared to full GN

Modified GN 7 sim. shots with renewals

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4000

3000 Velocity (m/s)

2000



25 times speedup compared to full GN



Modified GN I sim. shots with renewals

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4000

3000 Velocity (m/s)

2000



175 times speedup compared to full GN

Modified GN I sim. shots without renewals

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4000

3000 Velocity (m/s)

2000



175 times speedup compared to full GN



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Modified GN 7 seq. shots without renewals

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4000

3000 Velocity (m/s)

2000



25 times speedup compared to full GN

Modified GN 7 seq. shots with renewals

SLIM 🛃

4000

3000 Velocity (m/s)

2000



25 times speedup compared to full GN

Modified GN 7 sim. shots with renewals

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4000

3000 Velocity (m/s)

2000



25 times speedup compared to full GN



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Modified GN 7 seq. shots without renewals

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4000

3000 Velocity (m/s)

2000



marine acquisition: min offset 100m; max offset 3km

Modified GN 7 seq. shots with renewals

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4000

3000 Velocity (m/s)

2000



marine acquisition: min offset 100m; max offset 3km



Modified GN 7 seq. shots with renewals

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4000

3000 Velocity (m/s)

2000



Batching LBFGS seq. shots [vanLeeuwen '11]

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4000

3000 Velocity (m/s)

2000



Conclusions

Computational cost can be reduced significantly by using randomized dimensionality reduction.

High-resolution *images* can be attainable by using sparsity promotion.

LASSO problems maintain fast decrease in residual while preserving sparsity of the solution.

Simultaneous shots produce less source cross-talk artifacts.

Renewals lead to significant improvements-especially for random subsets of sequential shots.

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Thank you

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Further reading

Compressive sensing

- Robust uncertainty principles: Exact signal reconstruction from highly incomplete frequency information by Candes, 06.
- Compressed Sensing by D. Donoho, '06
- Curvelets and Wave Atoms for Mirror-Extended Images by L. Demanet, L. Ying, 07.

Simultaneous acquisition

- A new look at simultaneous sources by Beasley et. al., '98.
- Changing the mindset in seismic data acquisition by Berkhout '08.

Simultaneous simulations, imaging, and full-wave inversion:

- Faster shot-record depth migrations using phase encoding by Morton & Ober, '98.
- Phase encoding of shot records in prestack migration by Romero et. al., '00.
- Efficient Seismic Forward Modeling using Simultaneous Random Sources and Sparsity by N. Neelamani et. al., '08.
- Compressive simultaneous full-waveform simulation by FJH et. al., '09.
- Fast full-wavefield seismic inversion using encoded sources by Krebs et. al., '09
- Randomized dimensionality reduction for full-waveform inversion by FJH & X. Li, '10

Stochastic optimization and machine learning:

- A Stochastic Approximation Method by Robbins and Monro, 1951
- Neuro-Dynamic Programming by Bertsekas, '96
- Robust stochastic approximation approach to stochastic programming by Nemirovski et. al., '09
- Stochastic Approximation and Recursive Algorithms and Applications by Kushner and Lin
- Stochastic Approximation approach to Stochastic Programming by Nemirovski
- An effective method for parameter estimation with PDE constraints with multiple right hand sides. by Eldad Haber, Matthias Chung, and Felix J. Herrmann. '10