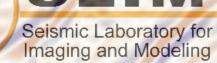
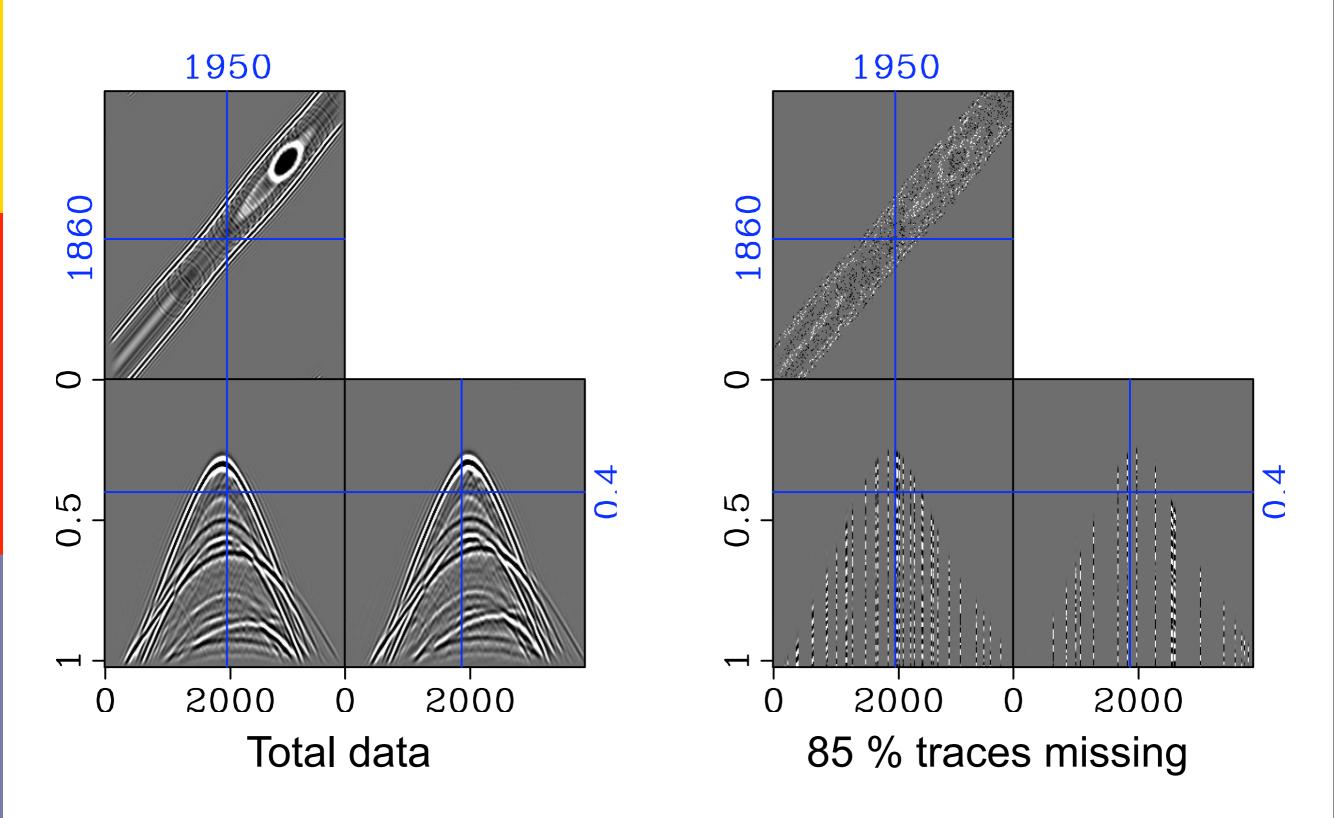
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(De)Focused wavefield reconstructions

Felix J. Herrmann joint work with Deli Wang and Gilles Hennenfent slim.eos.ubc.ca Vancouver, February 20-21

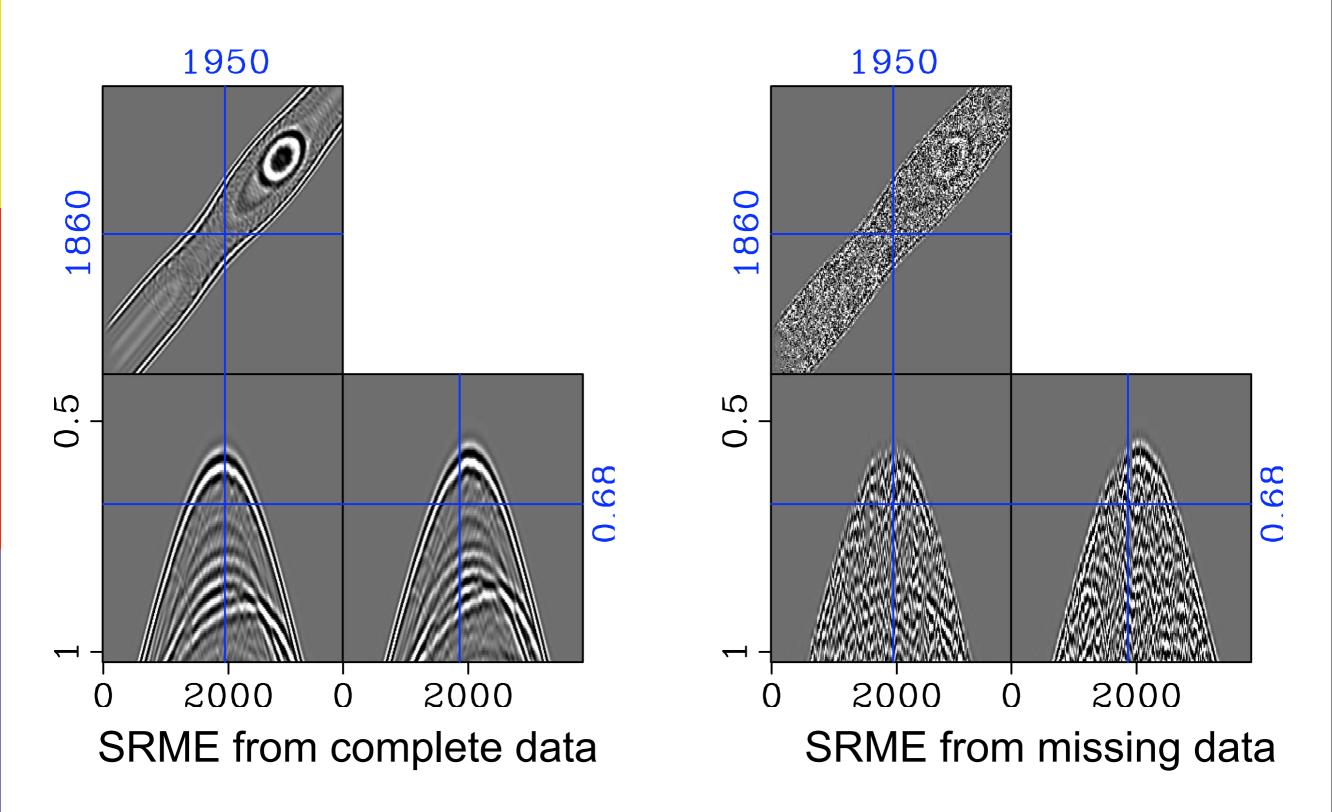


The problem



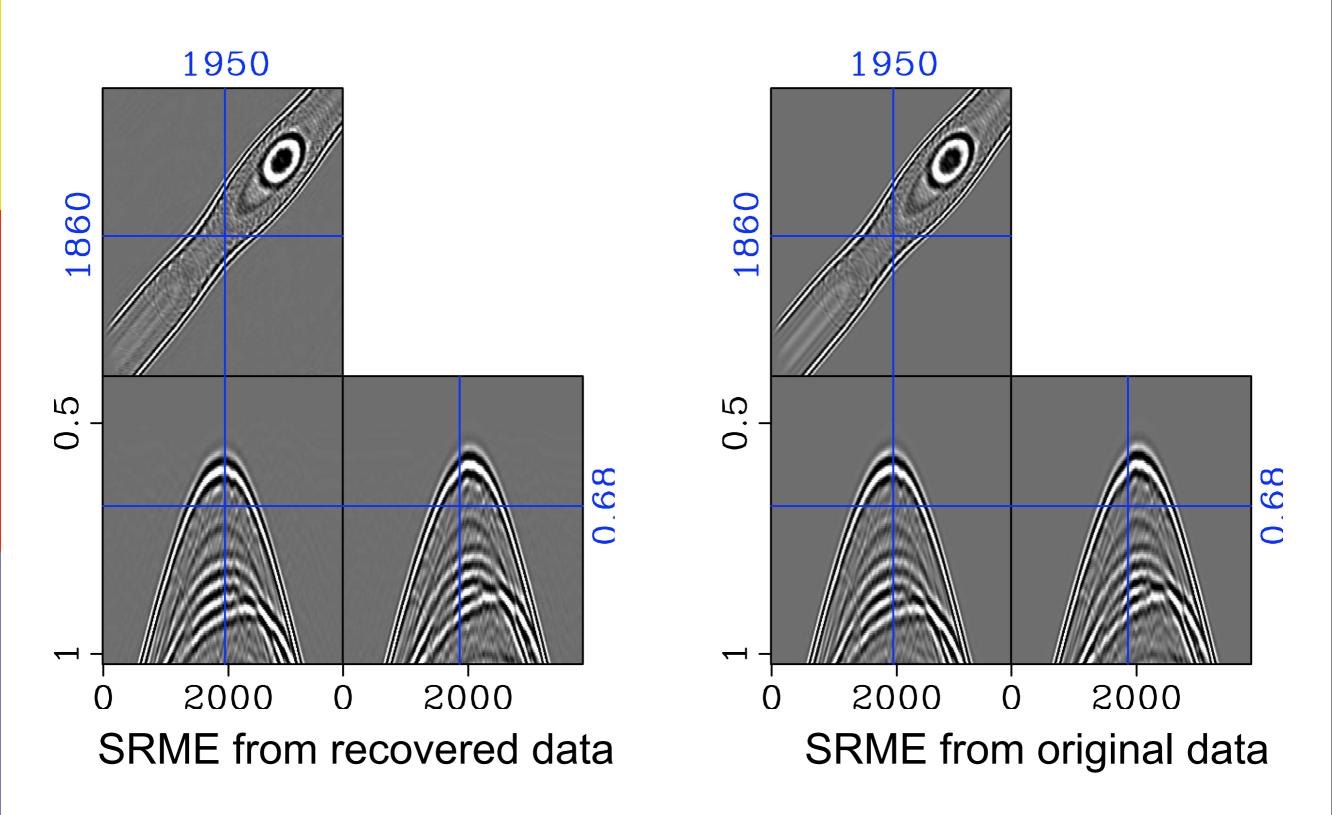


The problem cont'd





Our solution





Motivation

Data-driven (SRME) multiple prediction requires *fully* sampled data.

The Focal transform (Berkhout & Verschuur '06) allows for

- mapping of multiples => primaries
- incorporation of *prior* information in the recovery

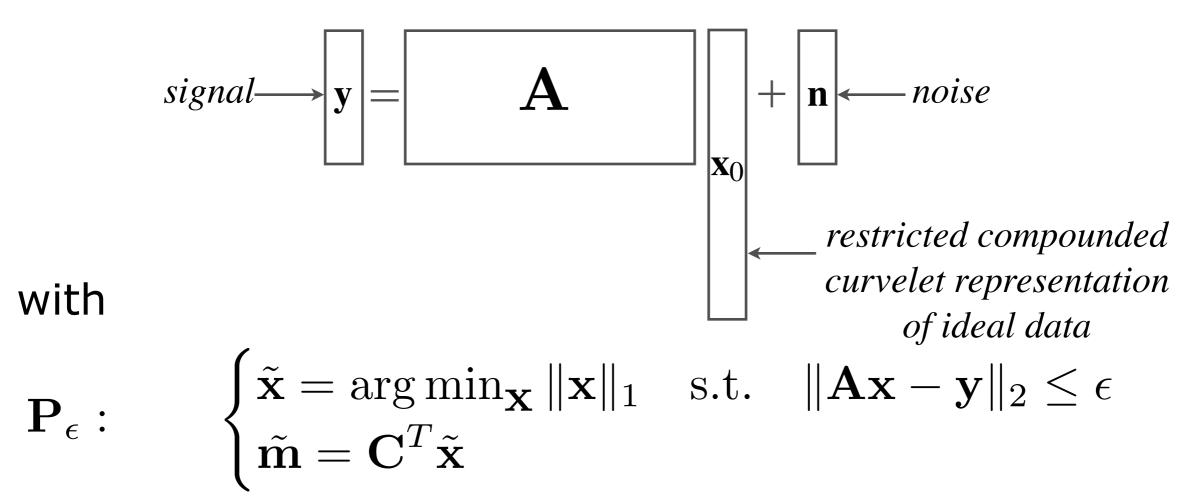
Present a curvelet-based scheme for sparsitypromoting

- recovery of missing data
- prediction of primaries from multiples
- data inverse ... and more ...



Sparsity-promoting program

Solve for x₀



- exploit sparsity in the curvelet domain as a prior.
- find the sparsest set of curvelet coefficients that match the data.
- invert an underdetermined system.



Focal transform with curvelets

Focused recovery

Non-data-adaptive Curvelet Reconstruction with Sparsity-promoting Inversion (CRSI) derives from **curvelet-sparsity** of seismic data.

Berkhout and Verschuur's *data-adaptive* Focal transform derives from *focusing* of seismic data by the *major* primaries.

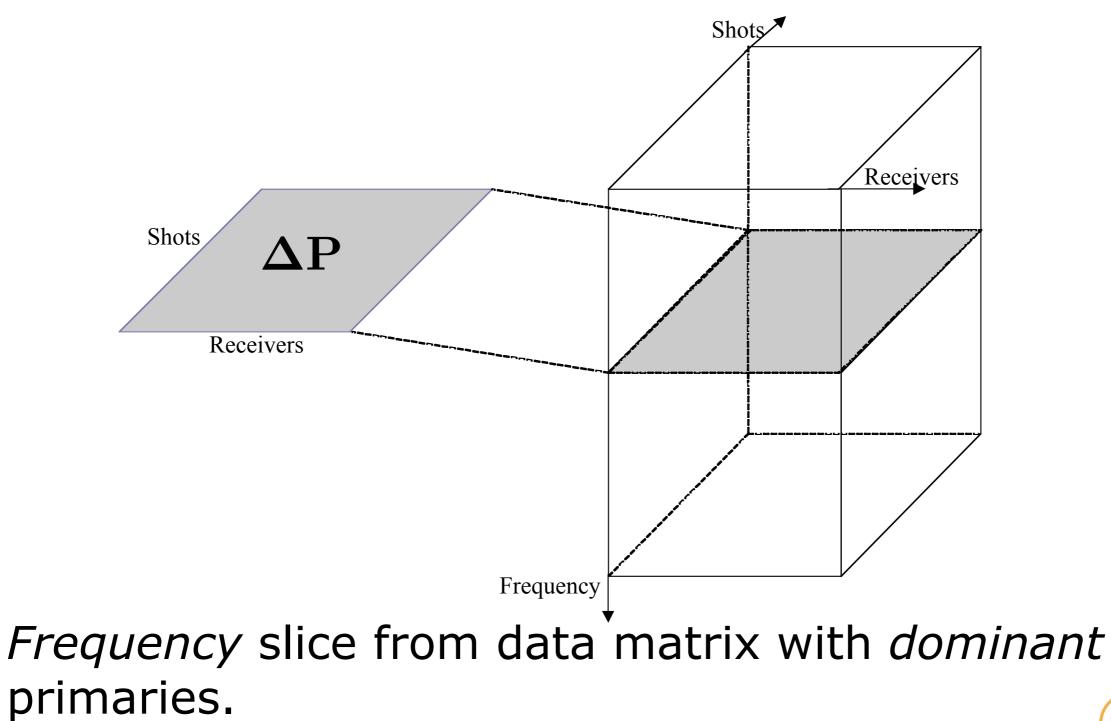
Both approaches entail the *inversion* of a linear operator.

Combination of the two yields

- improved focusing => more sparsity
- curvelet sparsity => better focusing

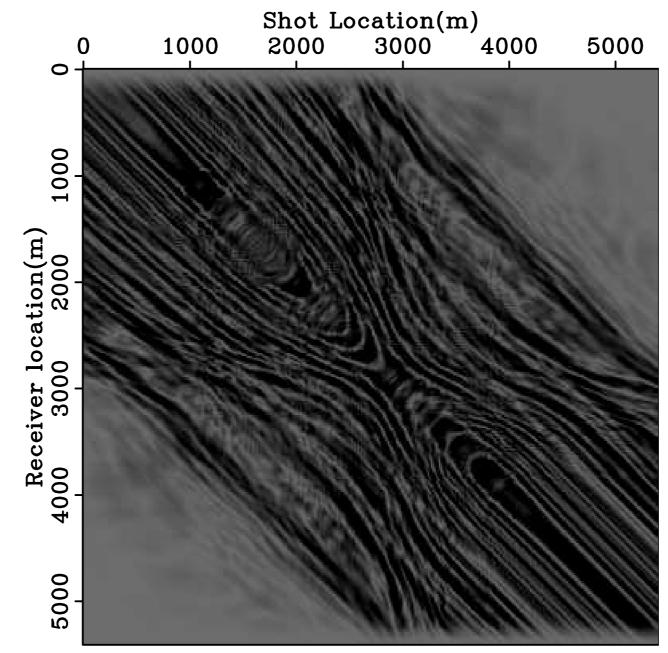


Primary operator





Primary operator



Frequency Slice (30Hz)



Primary operator

Primaries to first-order multiples:

$$\mathbf{\Delta p}\mapsto \mathbf{m}^1=\mathbf{\Delta P}\mathcal{A}\mathbf{\Delta p}$$

First-order multiples into primaries:

$$\mathbf{m}^1 \mapsto \mathbf{\Delta} \mathbf{p} \approx \mathbf{\Delta} \mathbf{P}^T \mathbf{A} \mathbf{\Delta} \mathbf{p}$$

with the acquisition matrix

$$oldsymbol{\mathcal{A}} = \left(oldsymbol{\mathcal{S}}^\dagger \mathbf{R} oldsymbol{\mathcal{D}}^\dagger
ight)$$

"inverting" for source and receiver wavelet wavelets geometry and surface reflectivity.



Focussed curvelet transform

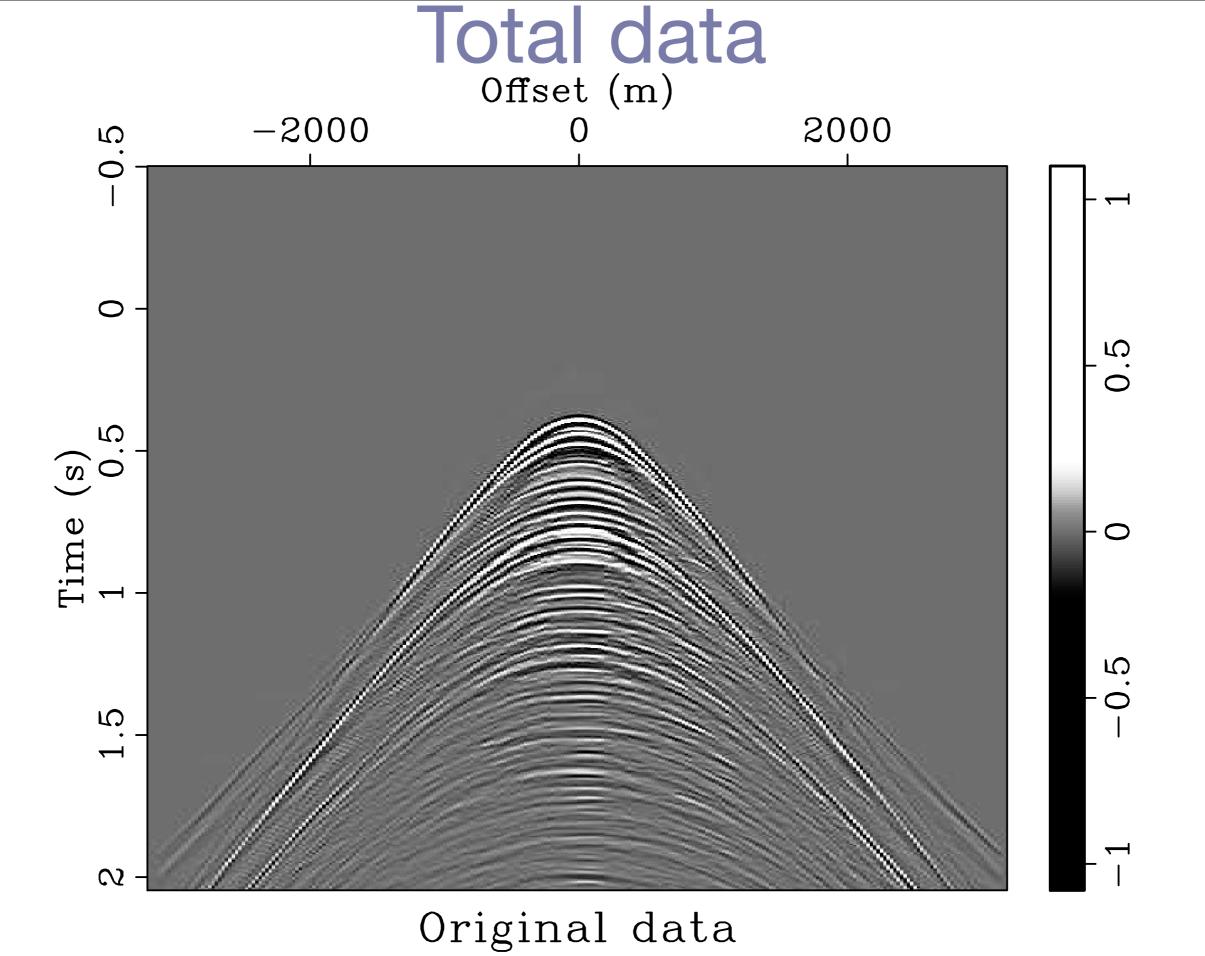
Solve with 3-D curvelet transform

$$\mathbf{P}_{\epsilon}: \qquad \begin{cases} \widetilde{\mathbf{x}} = \arg\min_{\mathbf{x}} \|\mathbf{x}\|_{1} \quad \text{s.t.} \quad \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_{2} \leq \epsilon \\ \widetilde{\mathbf{f}} = \mathbf{S}^{T} \widetilde{\mathbf{x}} \end{cases}$$

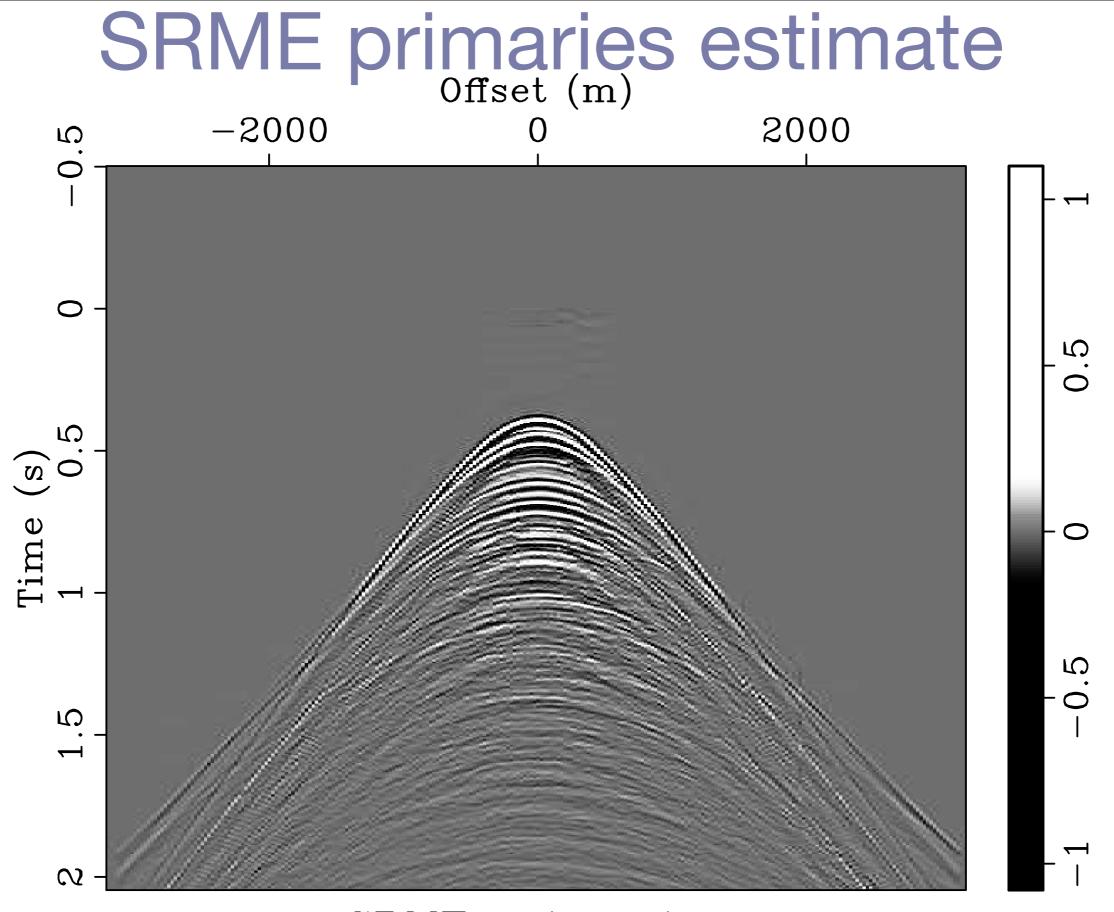
with

- $\mathbf{A} := \mathbf{\Delta} \mathbf{P} \mathbf{C}^T \quad \text{and } \mathbf{\Delta} \mathbf{P} := \mathbf{F}^H \text{block diag}\{\hat{\mathbf{\Delta} \mathbf{p}}\} \mathbf{F}$ $\mathbf{S} := \mathbf{C}$
- $\mathbf{y} = \mathbf{p}$
- \mathbf{p} = total data
- $\hat{\Delta p} = F \Delta p$
- Δp = estimate for the primaries.



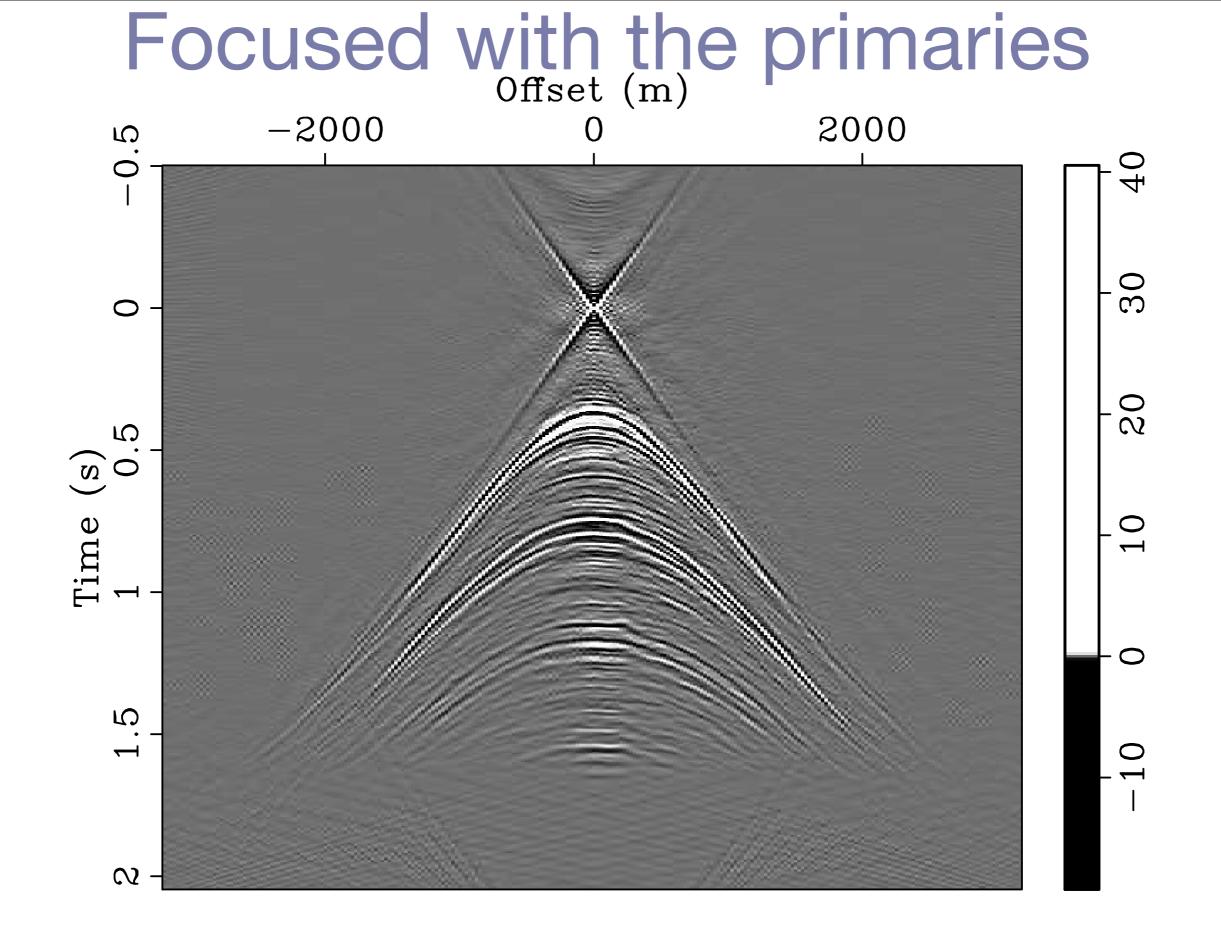






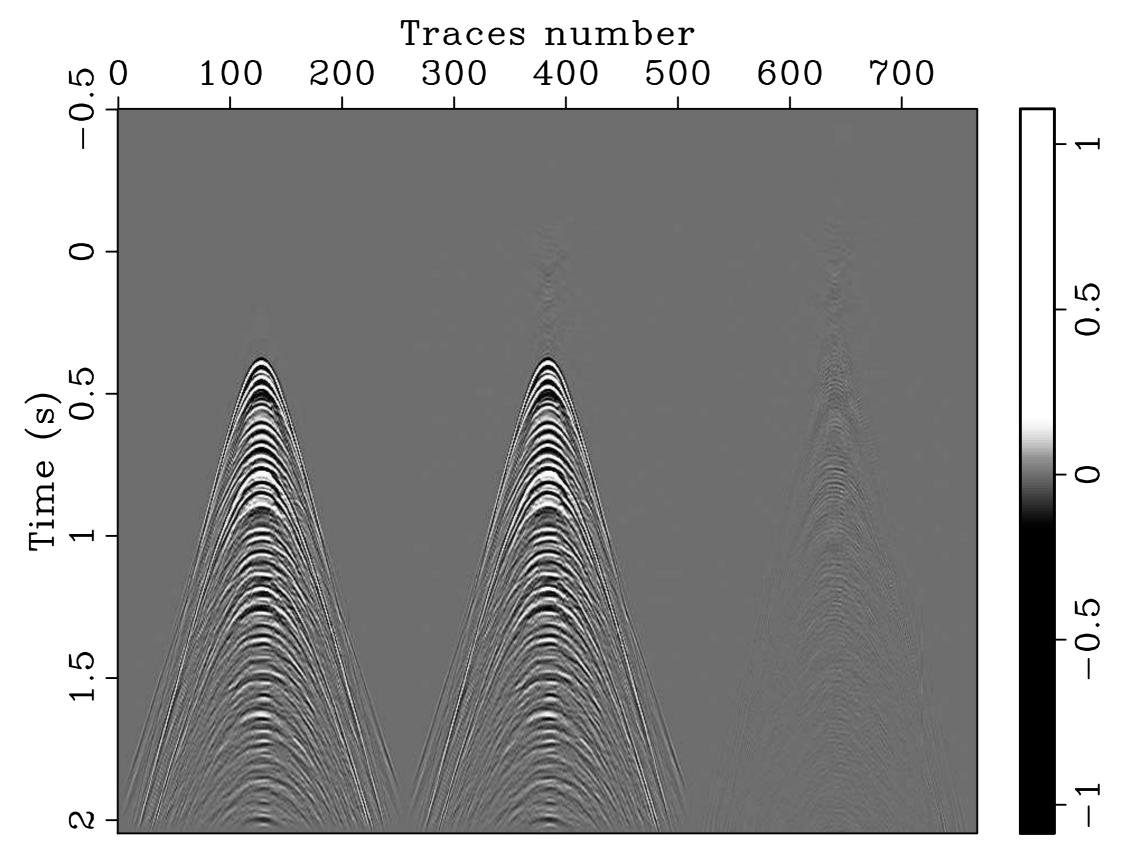
SRME primaries







Difference





Focused wavefield reconstruction with curvelets

Recovery with focussing

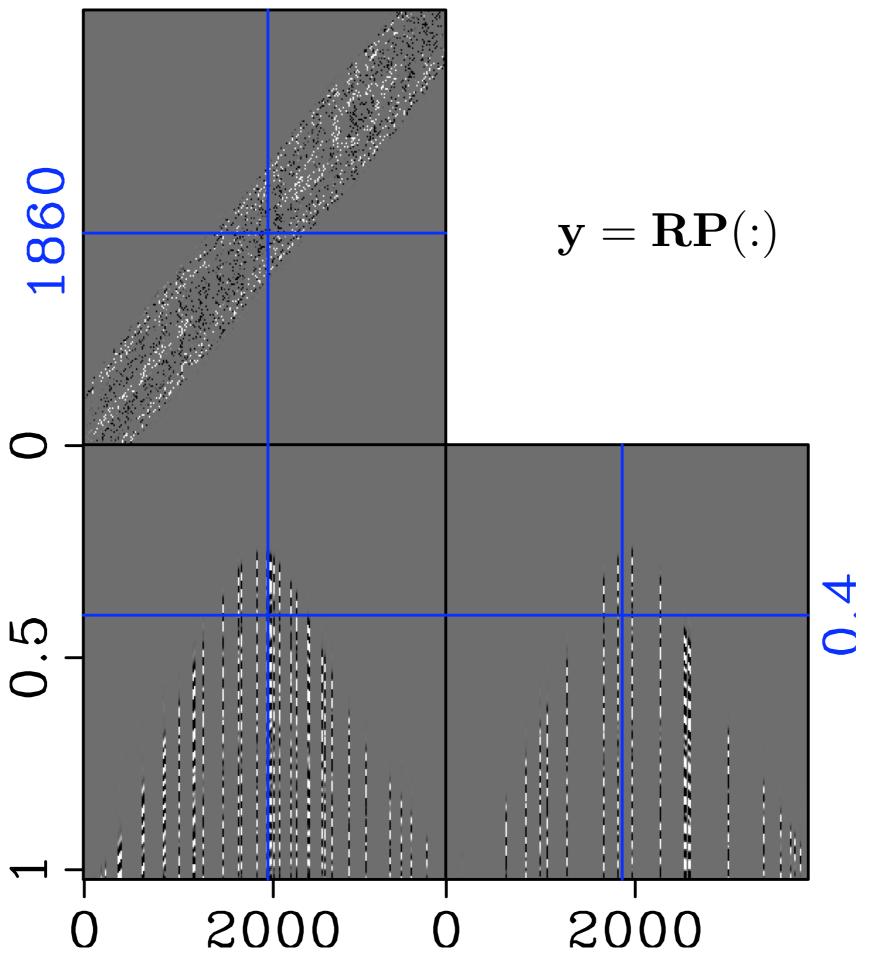
Solve

$$\mathbf{P}_{\epsilon}: \qquad \begin{cases} \widetilde{\mathbf{x}} = \arg\min_{\mathbf{x}} \|\mathbf{x}\|_{1} & \text{s.t.} & \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_{2} \leq \epsilon \\ \widetilde{\mathbf{f}} = \mathbf{S}^{T} \widetilde{\mathbf{x}} \end{cases}$$

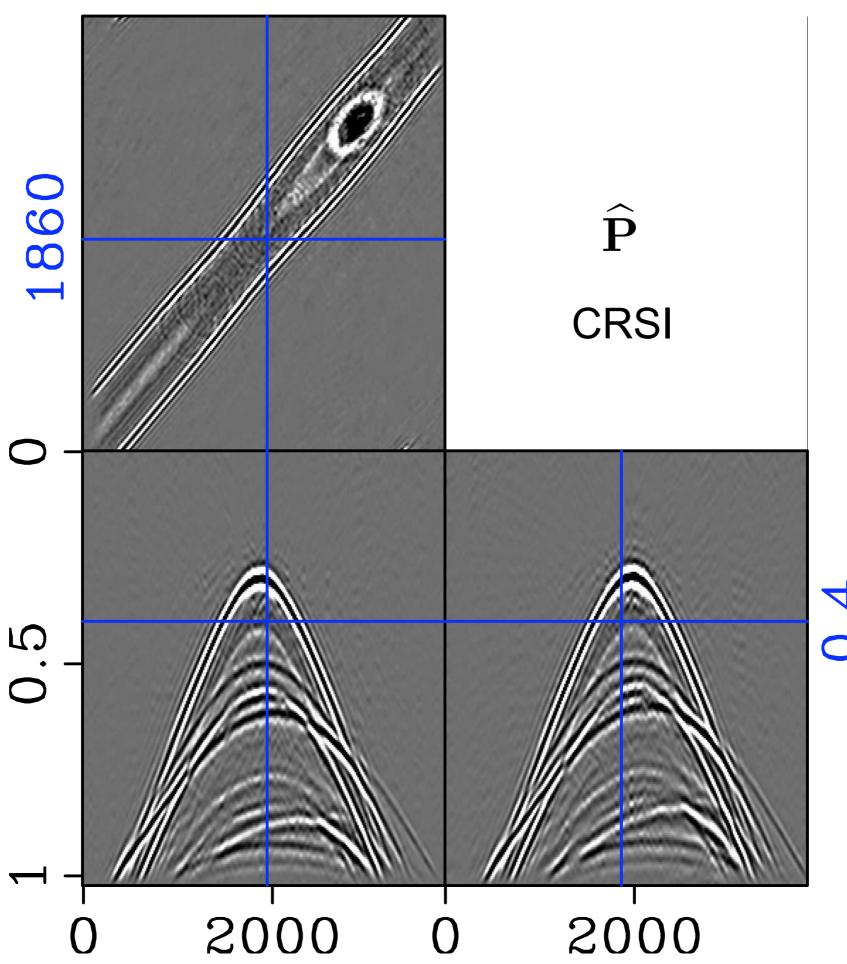
with

- $\mathbf{A} := \mathbf{R} \mathbf{\Delta} \mathbf{P} \mathbf{C}^T$
- \mathbf{S}^T := $\mathbf{\Delta} \mathbf{P} \mathbf{C}^T$
 - $\mathbf{y} = \mathbf{R}\mathbf{p}$
 - \mathbf{R} = picking operator.



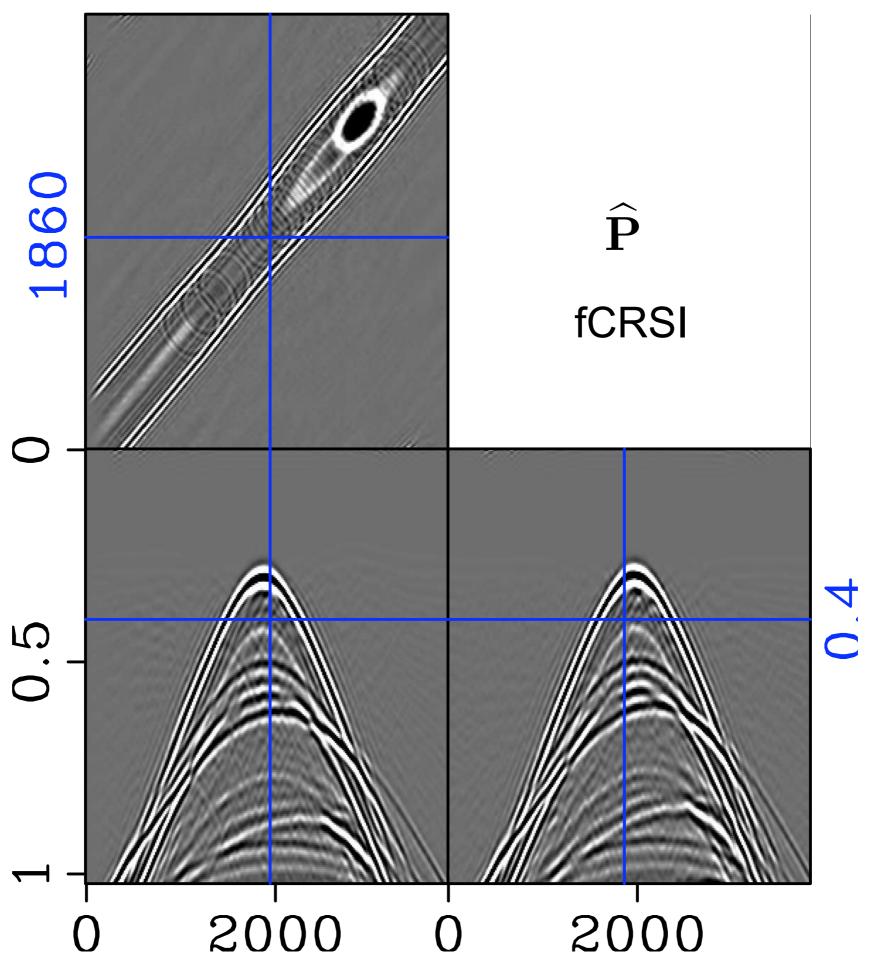




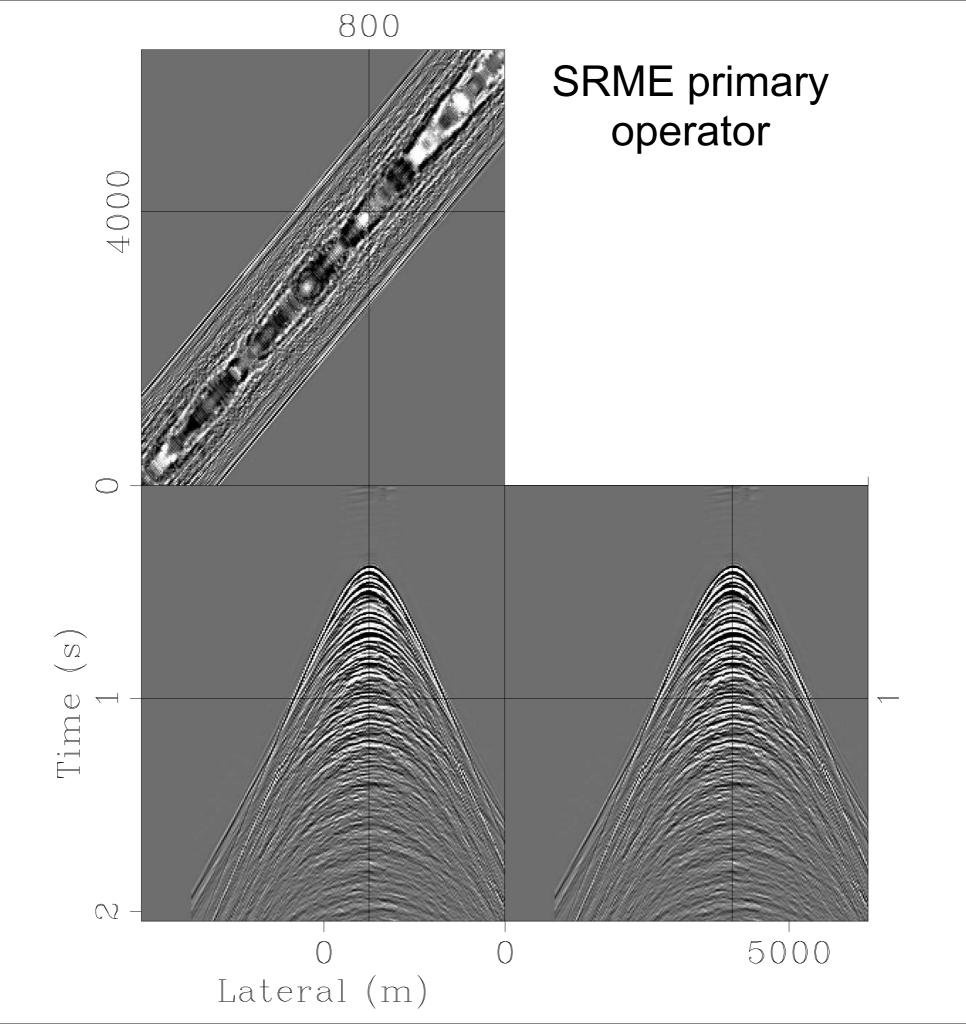




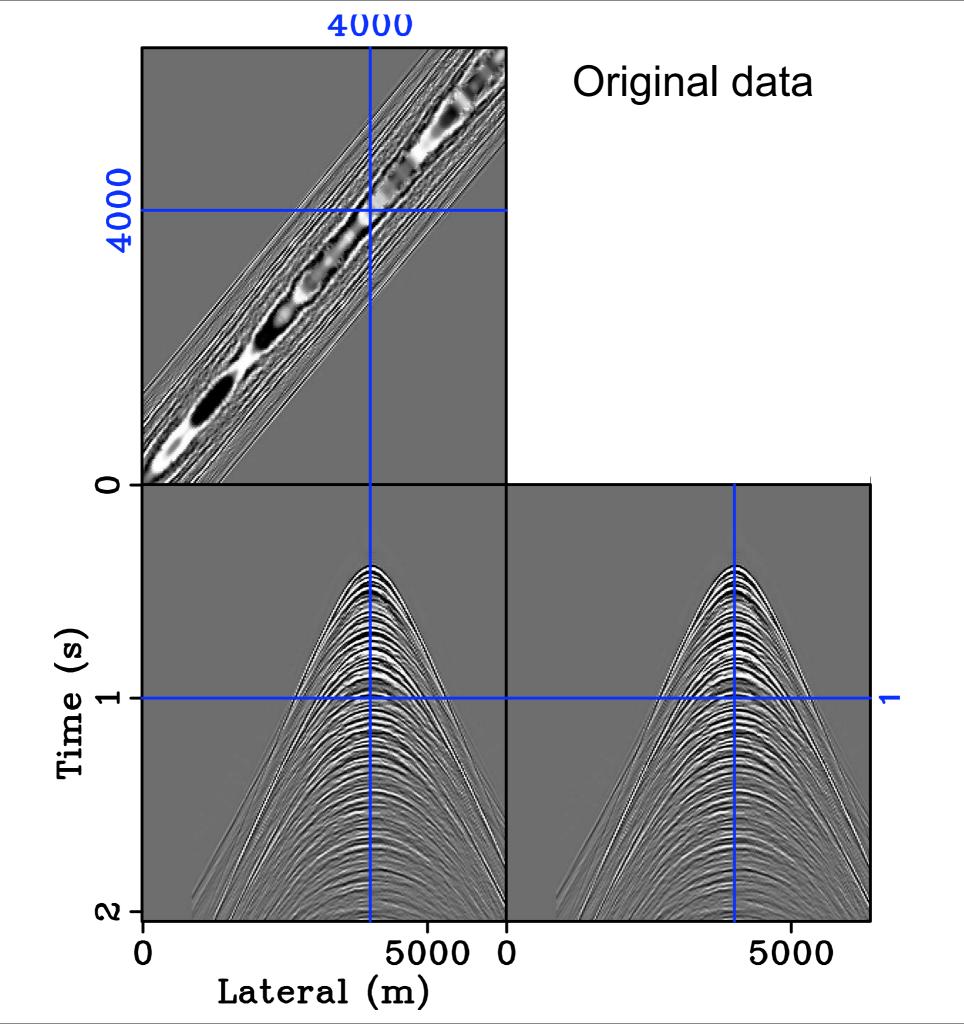




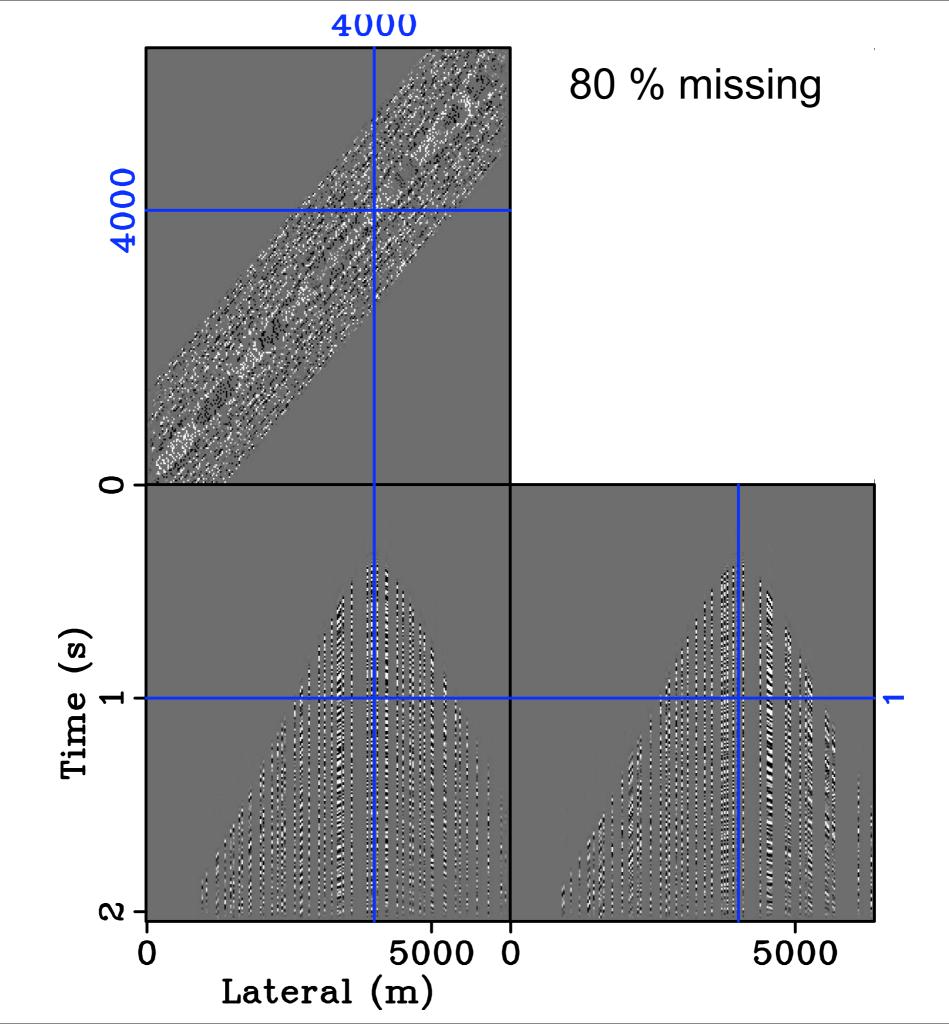




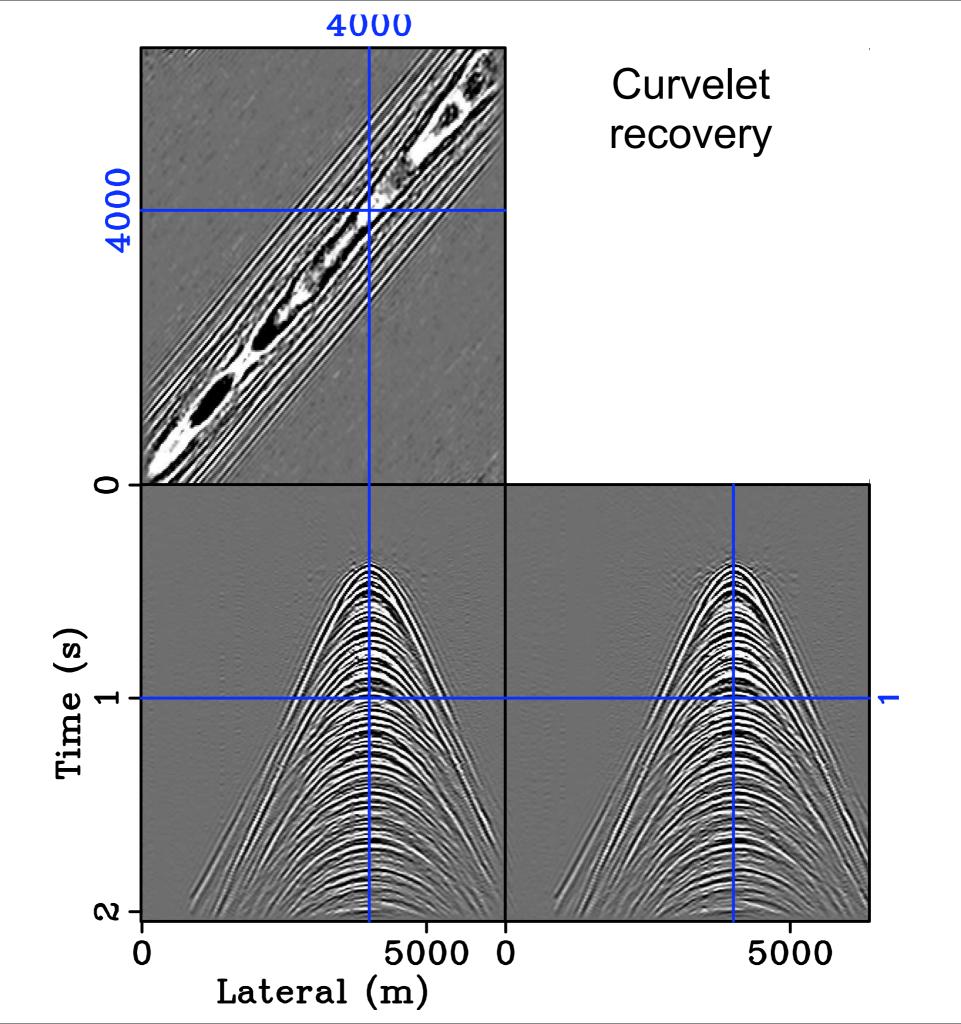




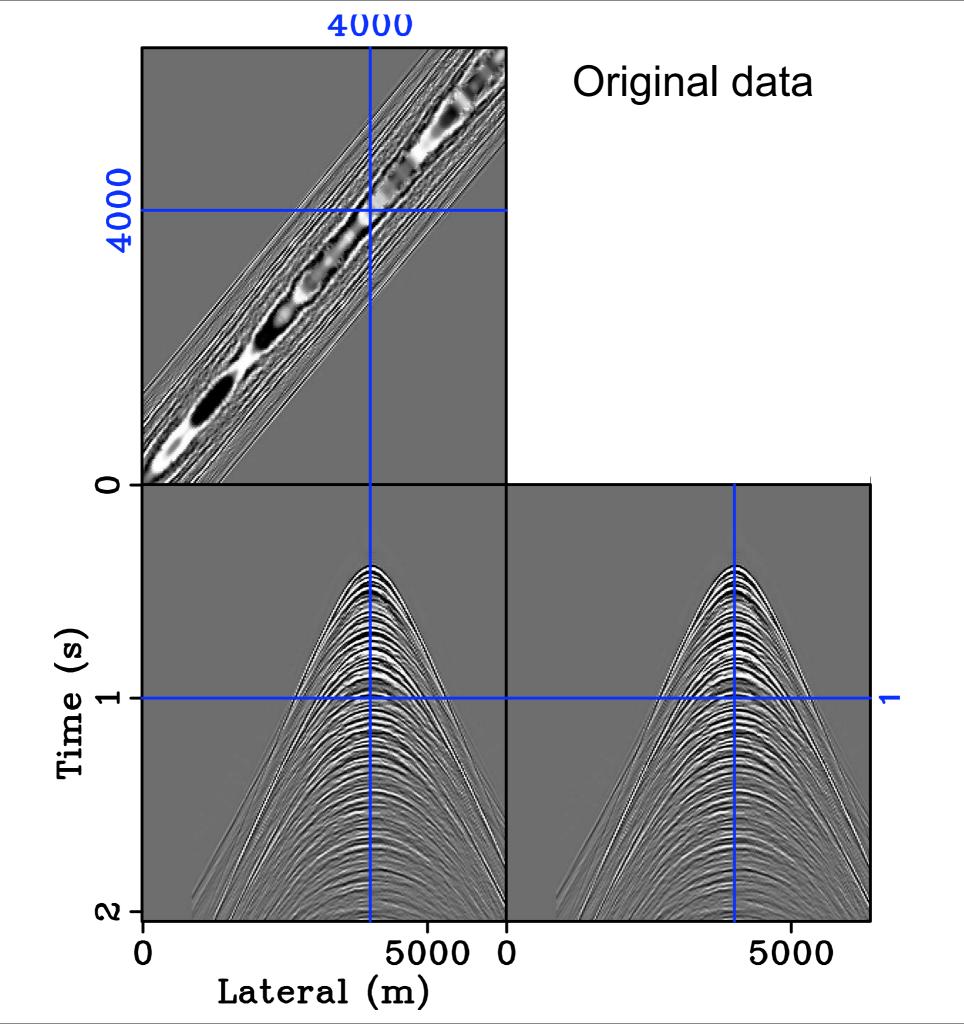




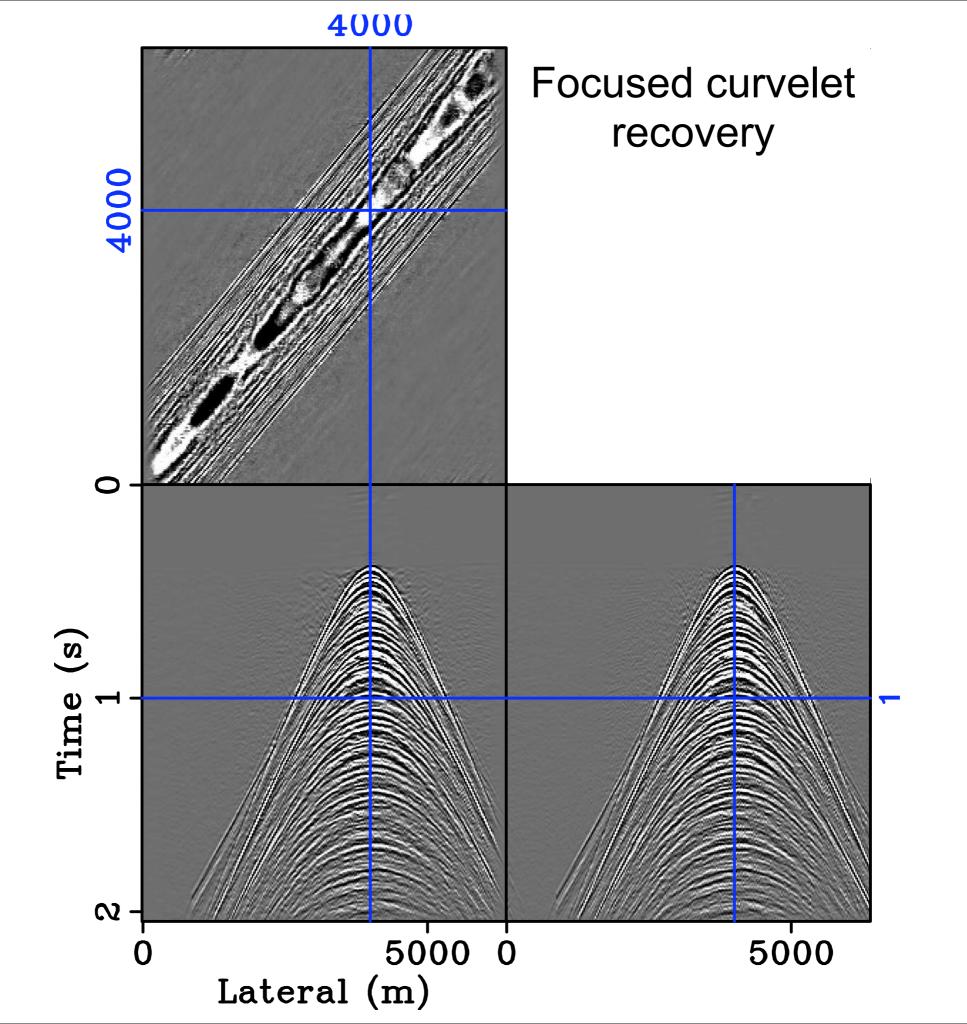




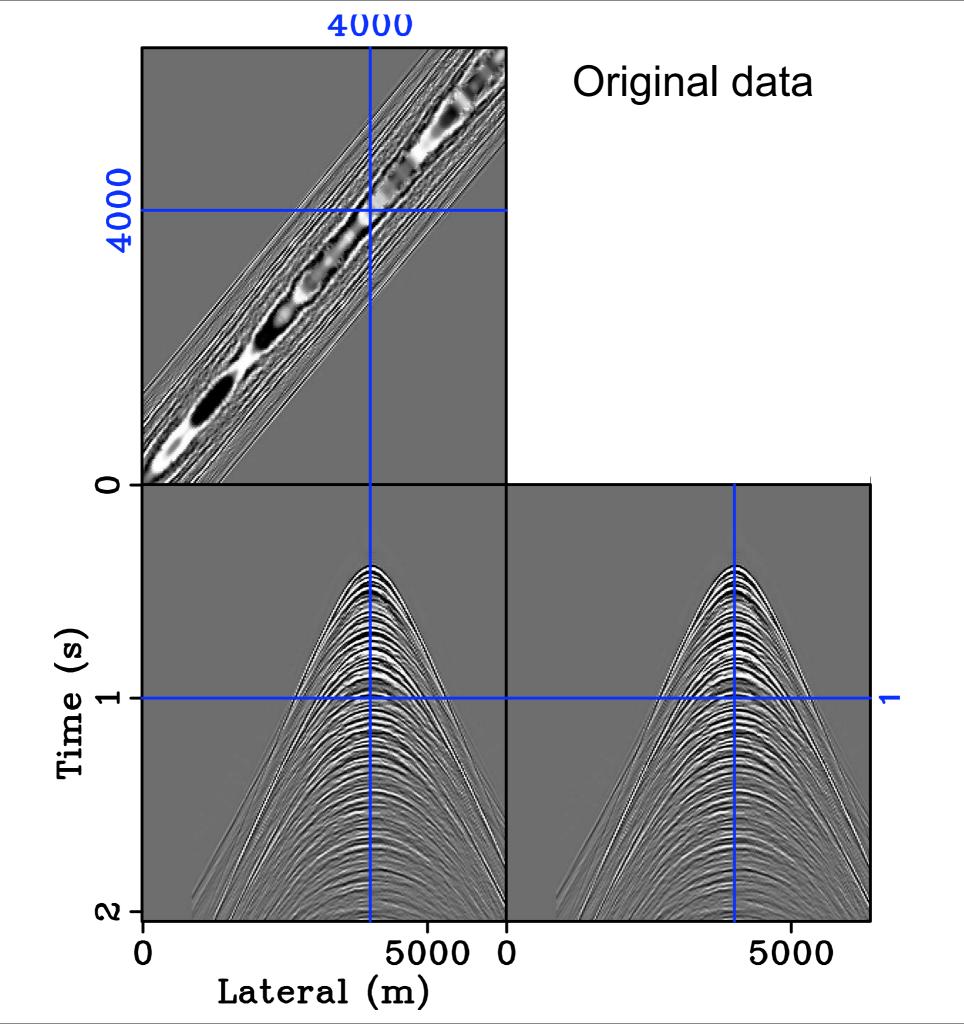








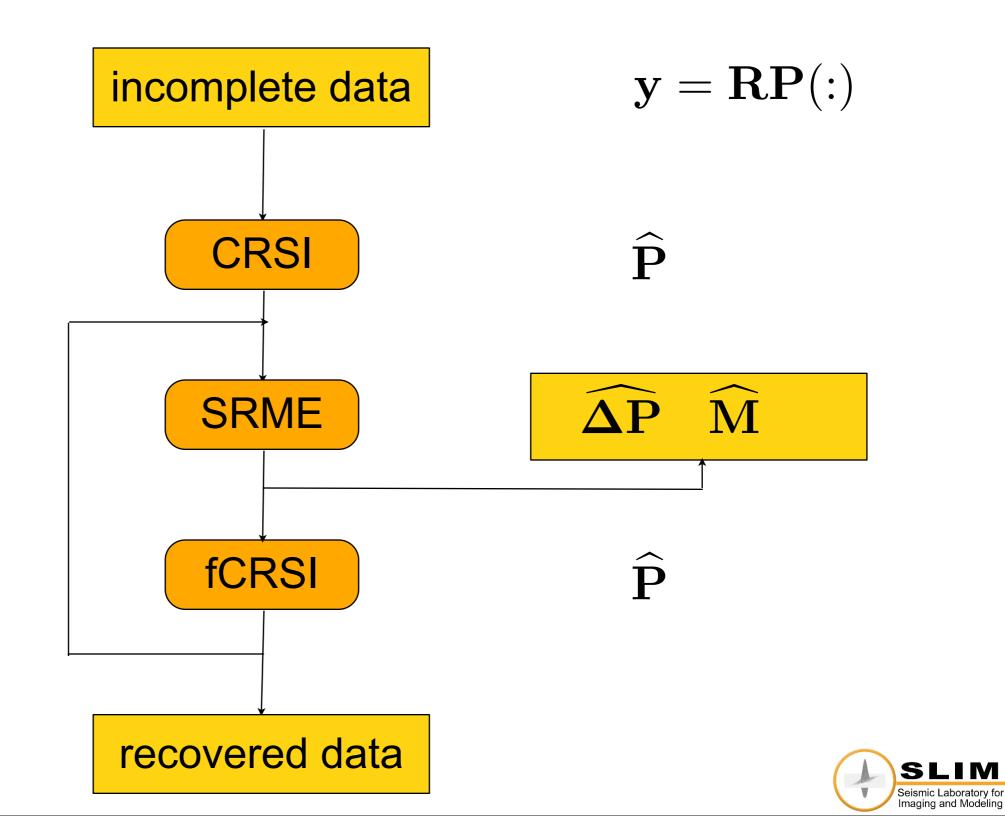






Multiple prediction with fCRSI

Multiple prediction with fCRSI



Multiple recovery with fCRSI

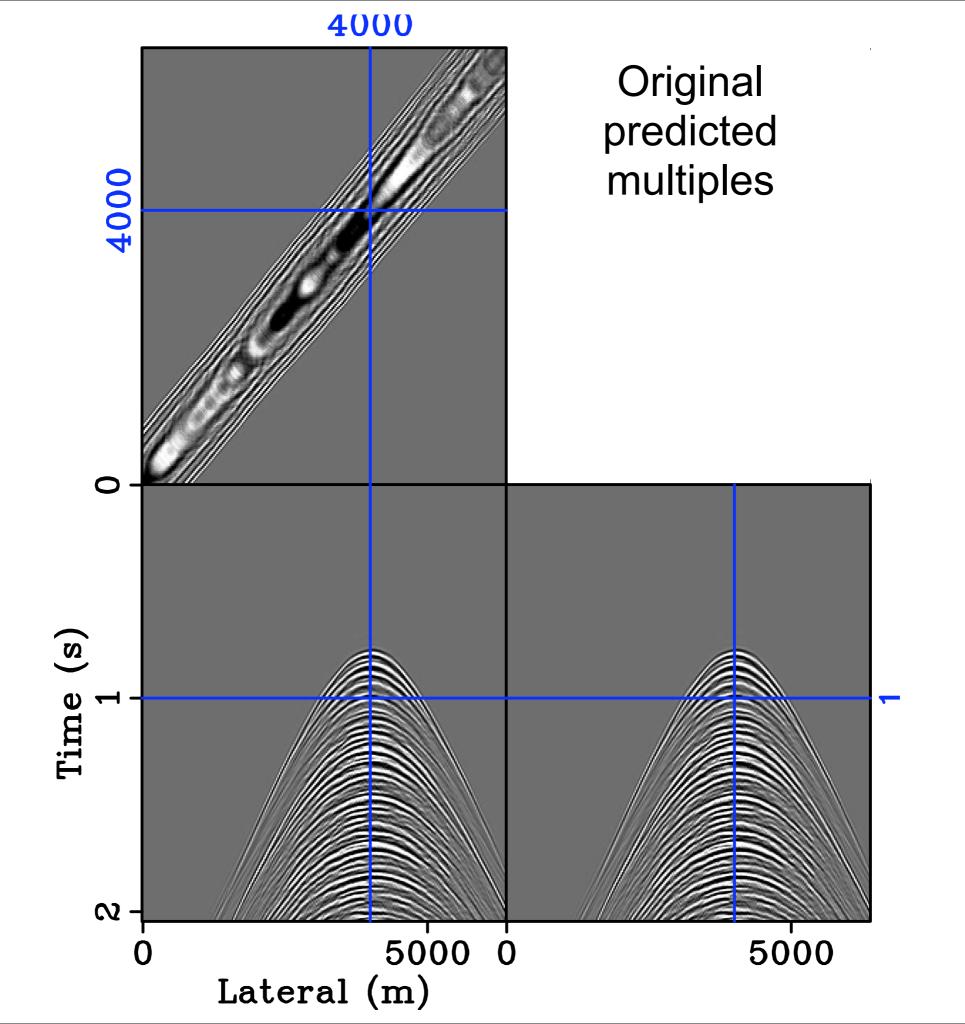
Solve

$$\mathbf{P}_{\epsilon}: \qquad \begin{cases} \tilde{\mathbf{x}} = \arg\min_{\mathbf{X}} \|\mathbf{x}\|_{1} & \text{s.t.} & \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_{2} \le \epsilon \\ \tilde{\mathbf{p}} = \mathbf{\Delta} \mathbf{P} \mathbf{C}^{T} \tilde{\mathbf{x}} \\ \tilde{\mathbf{m}} = \tilde{\mathbf{P}} \tilde{\mathbf{p}} \end{cases}$$

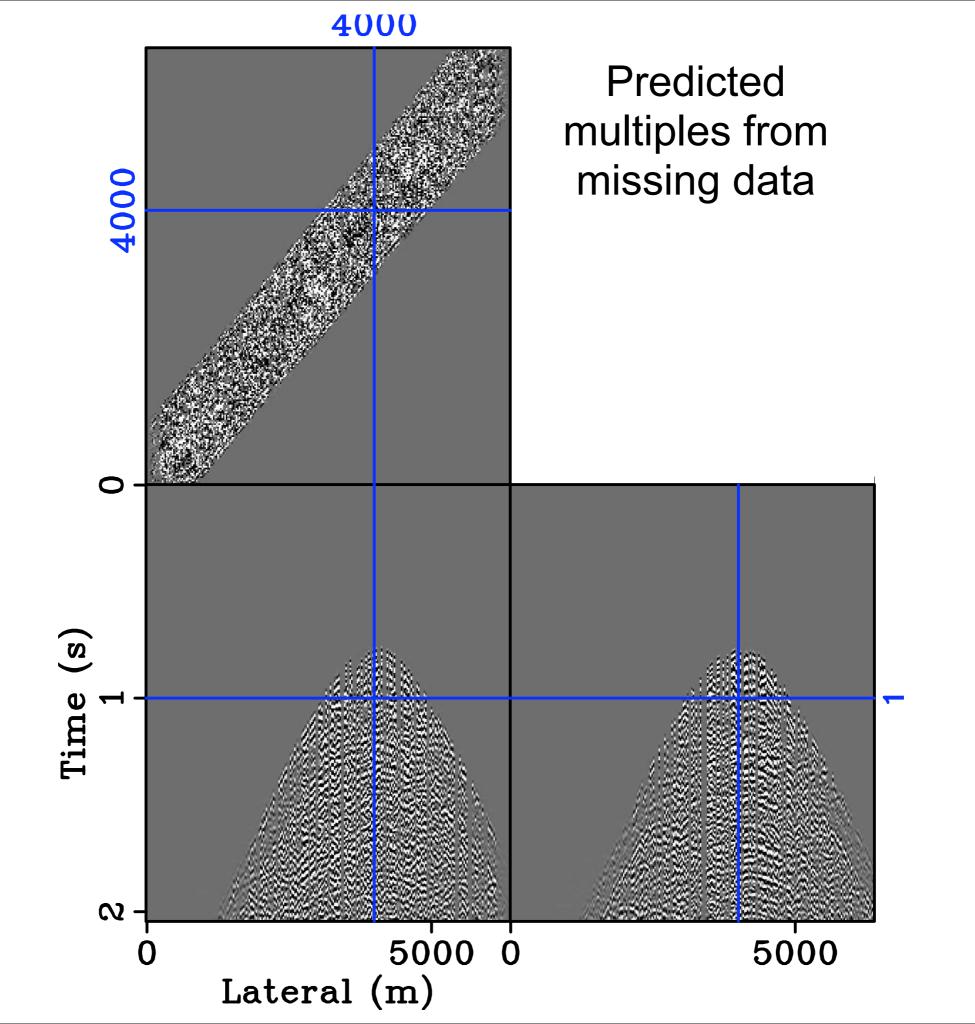
with

- \mathbf{R} = picking operator
- $\mathbf{A} = \mathbf{R} \mathbf{\Delta} \mathbf{P} \mathbf{C}^T$
- $\mathbf{S}^T = \mathbf{\Delta} \mathbf{P} \mathbf{C}^T$
 - $\mathbf{y} = \mathbf{R}\mathbf{p}$
 - $\tilde{\mathbf{p}}$ = recovered data
 - $\tilde{\mathbf{m}}$ = recovered multiples.

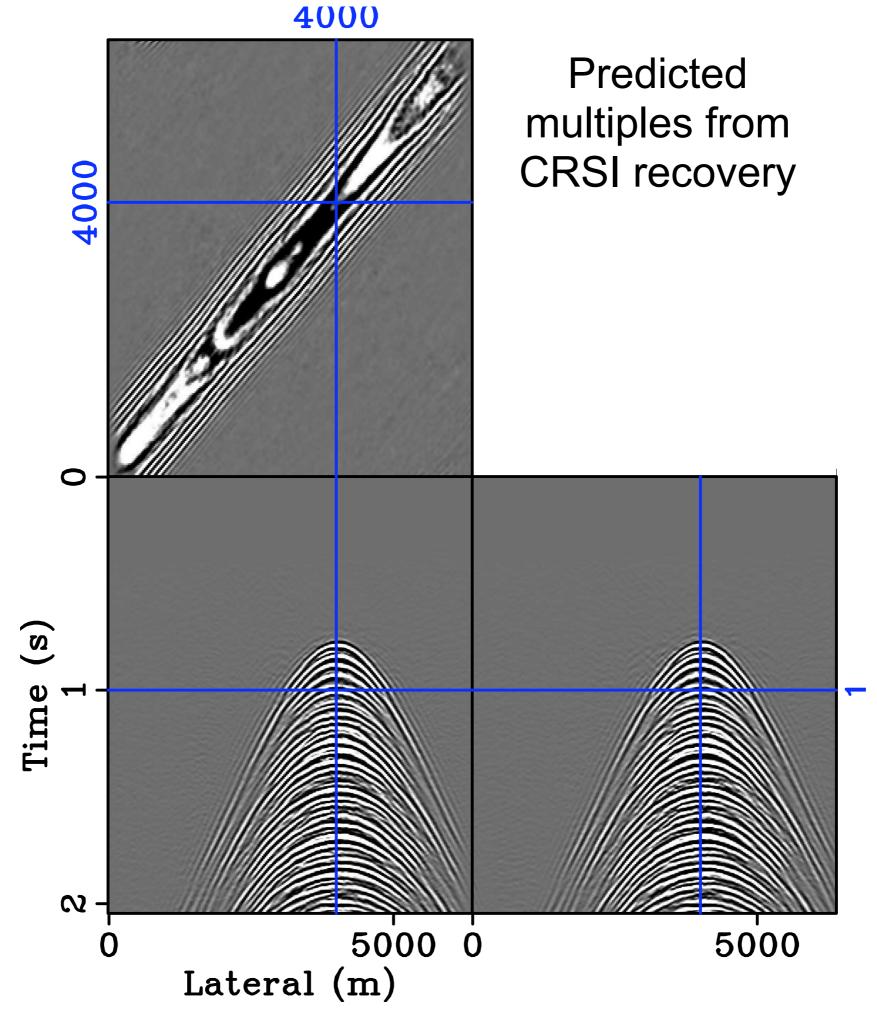




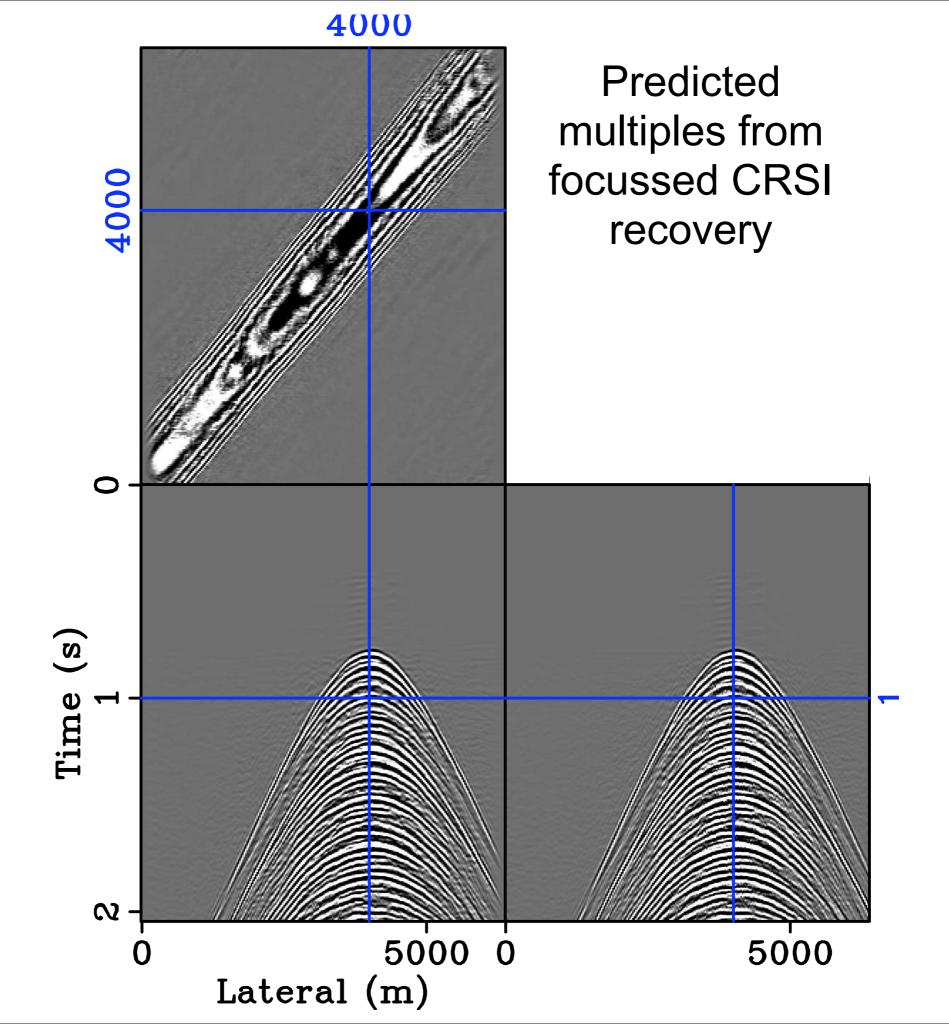




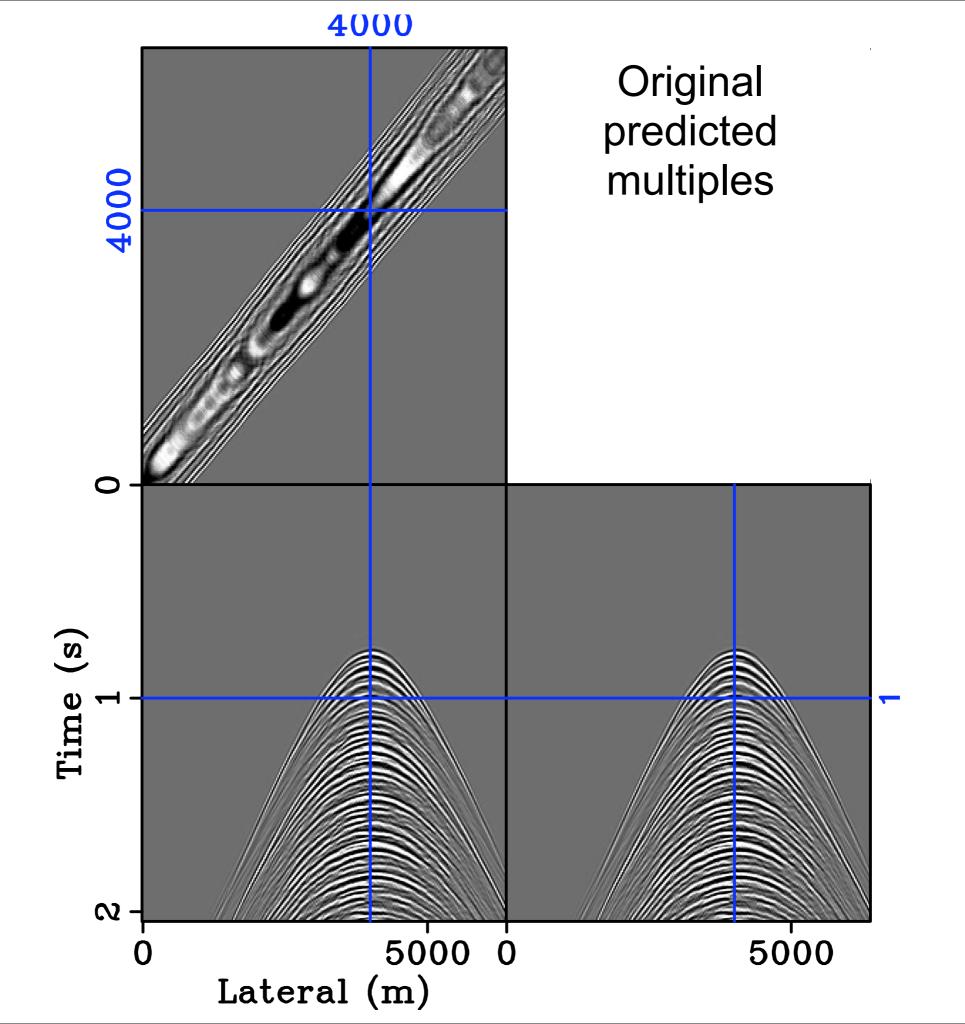






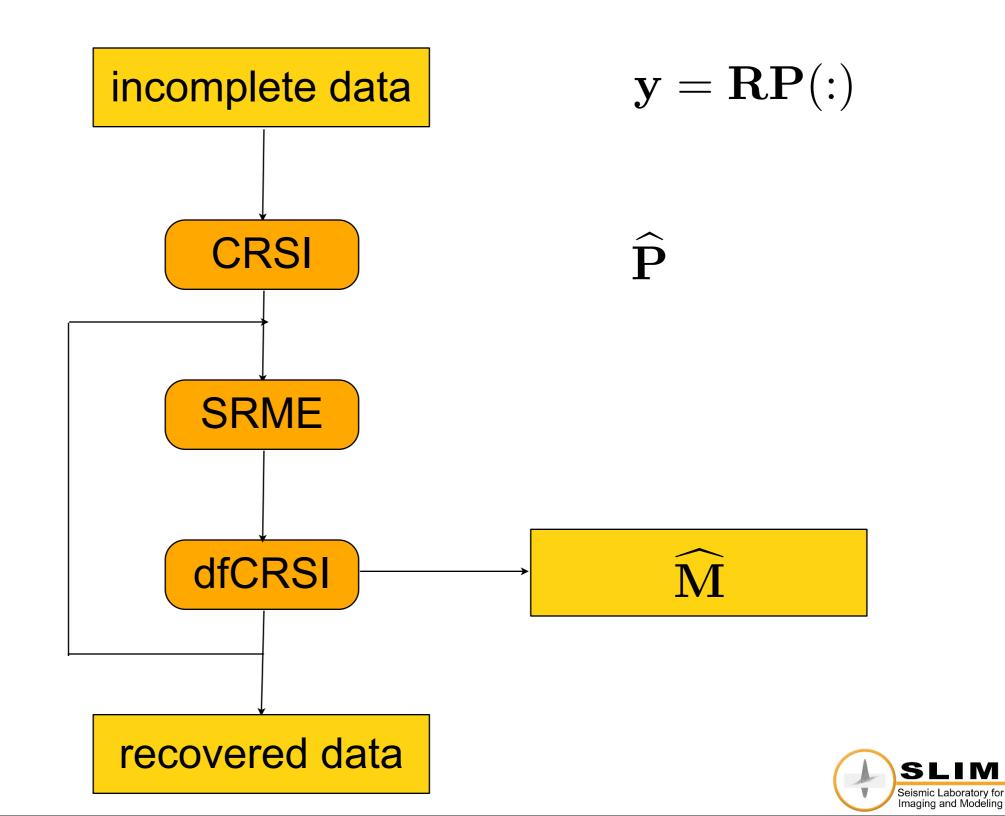








Multiple prediction with dfCRSI



Multiple prediction with dfCRSI

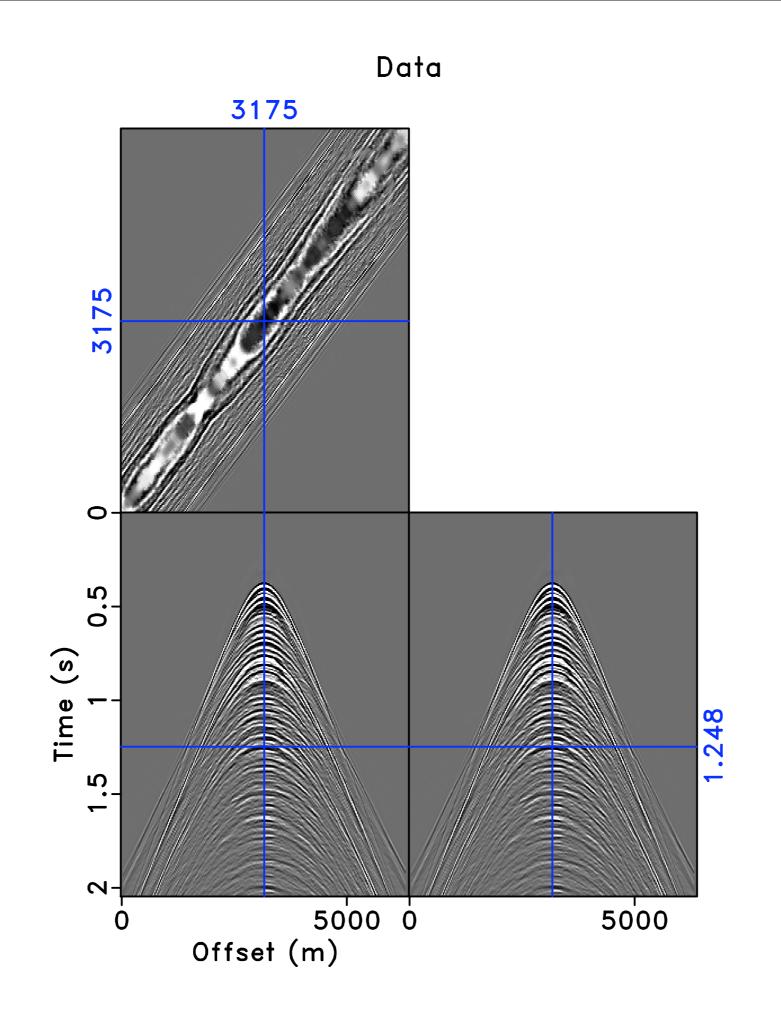
Solve

$$\mathbf{P}_{\epsilon}: \qquad \begin{cases} \tilde{\mathbf{x}} = \arg\min_{\mathbf{X}} \|\mathbf{x}\|_{1} & \text{s.t.} & \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_{2} \le \epsilon \\ \tilde{\mathbf{m}} = \mathbf{C}^{H} \tilde{\mathbf{x}} \end{cases}$$

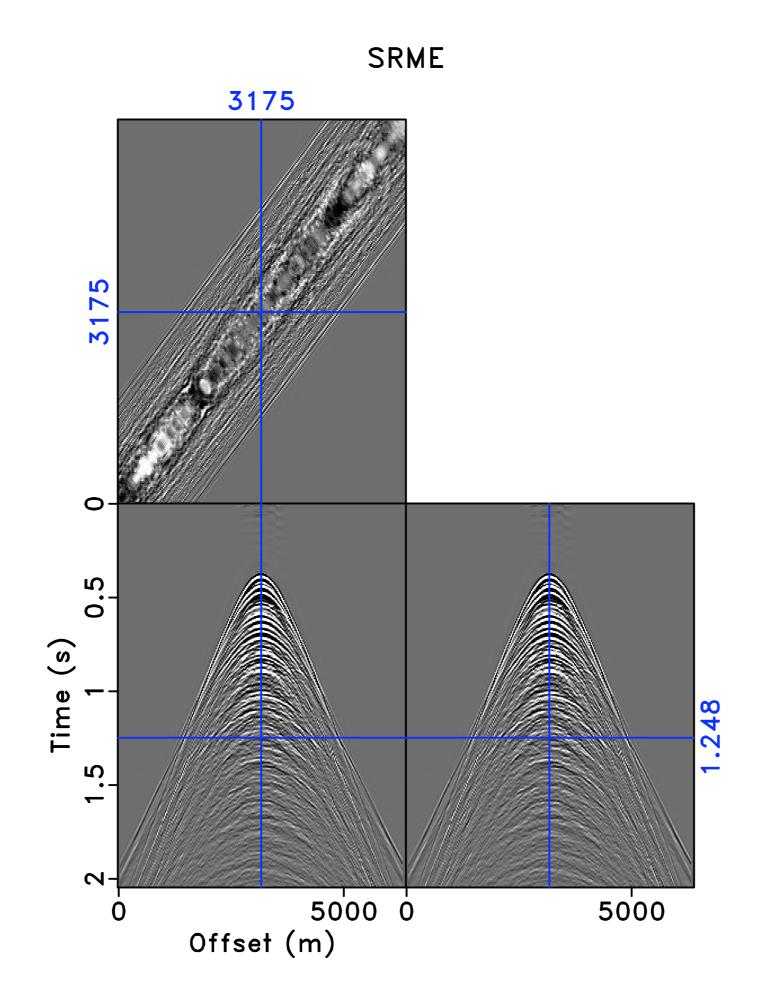
with

- $\mathbf{A} = \mathbf{\Delta} \mathbf{P}^H \mathbf{C}^T$
- $\mathbf{y} = \tilde{\mathbf{p}}$
- $\tilde{\mathbf{m}}$ = predicted multiples.

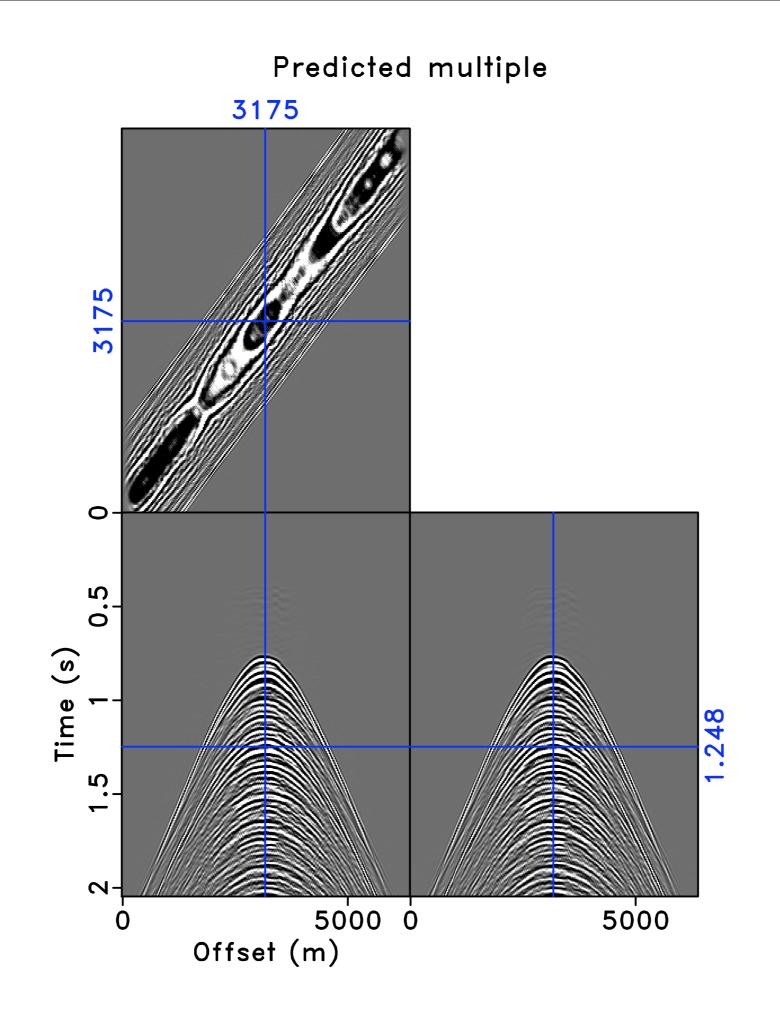




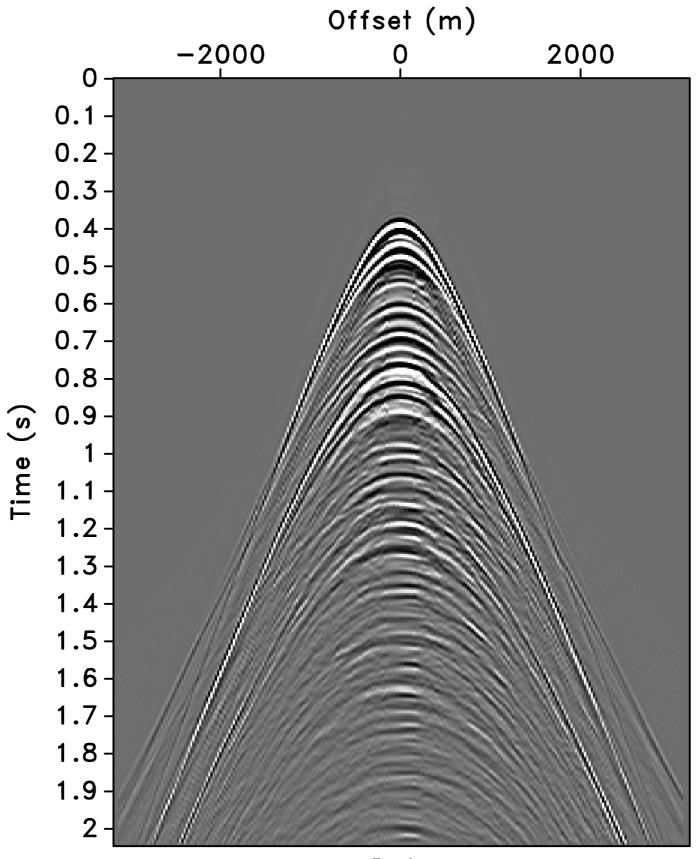






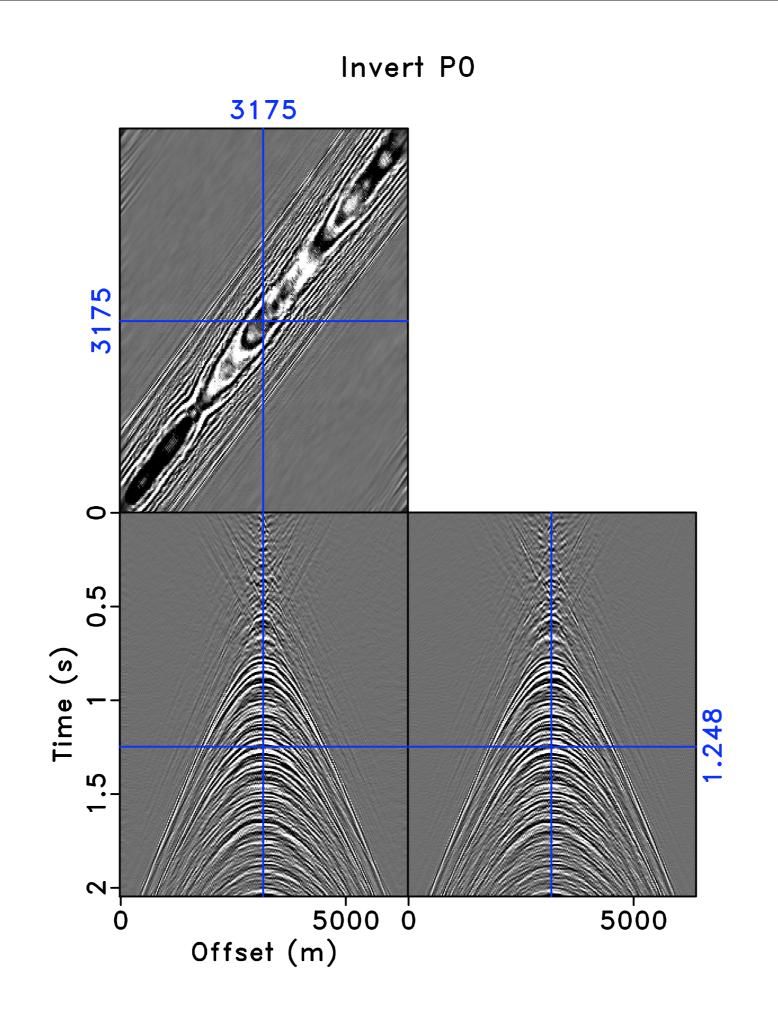




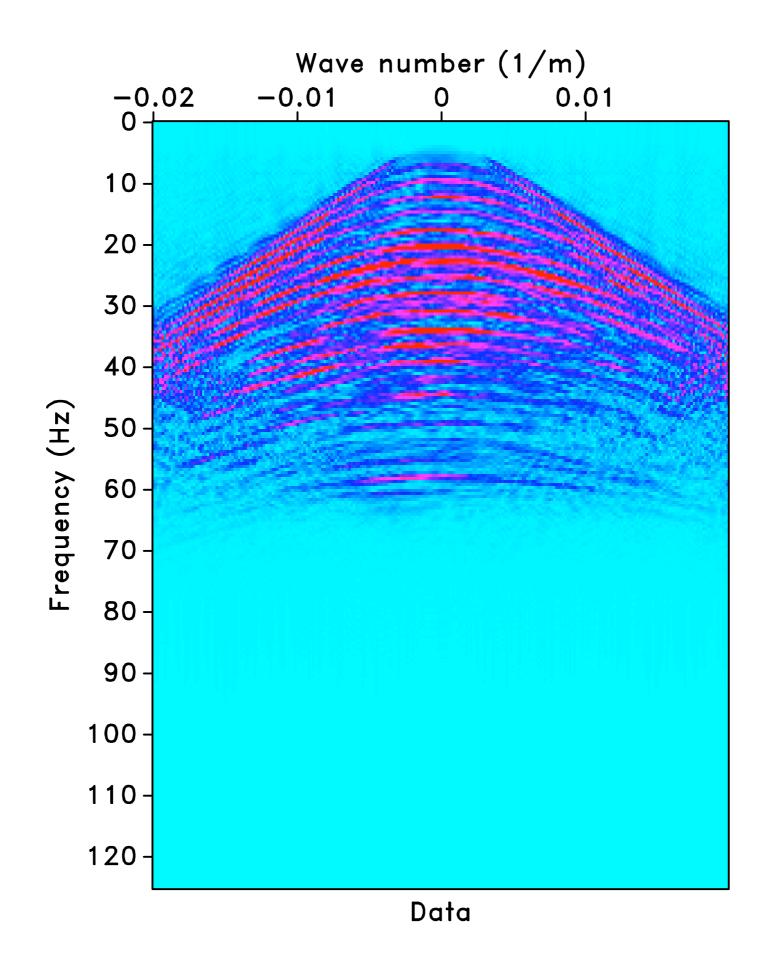




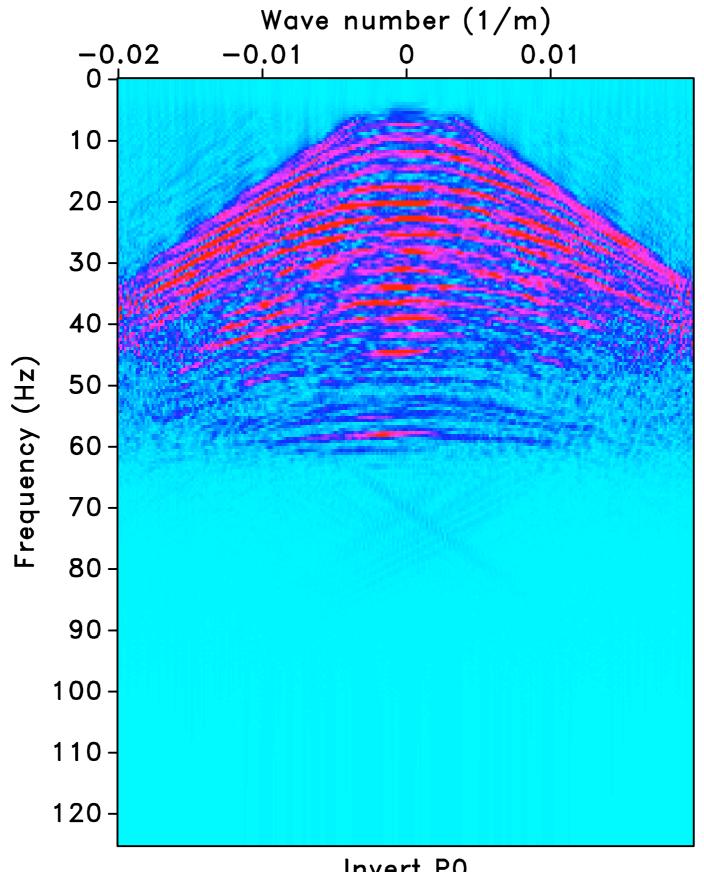






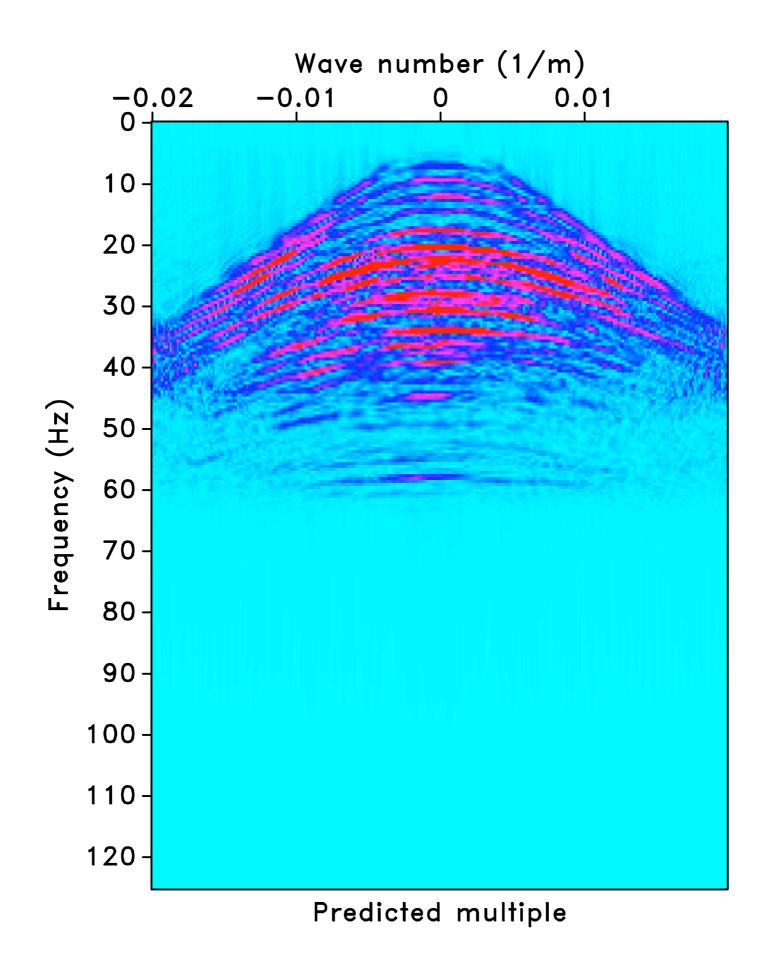




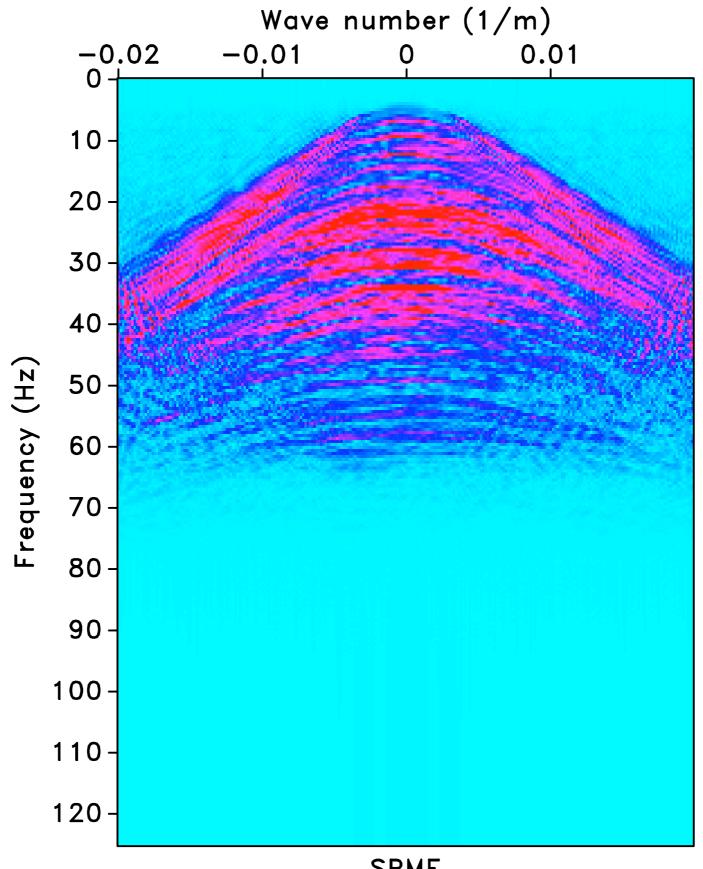




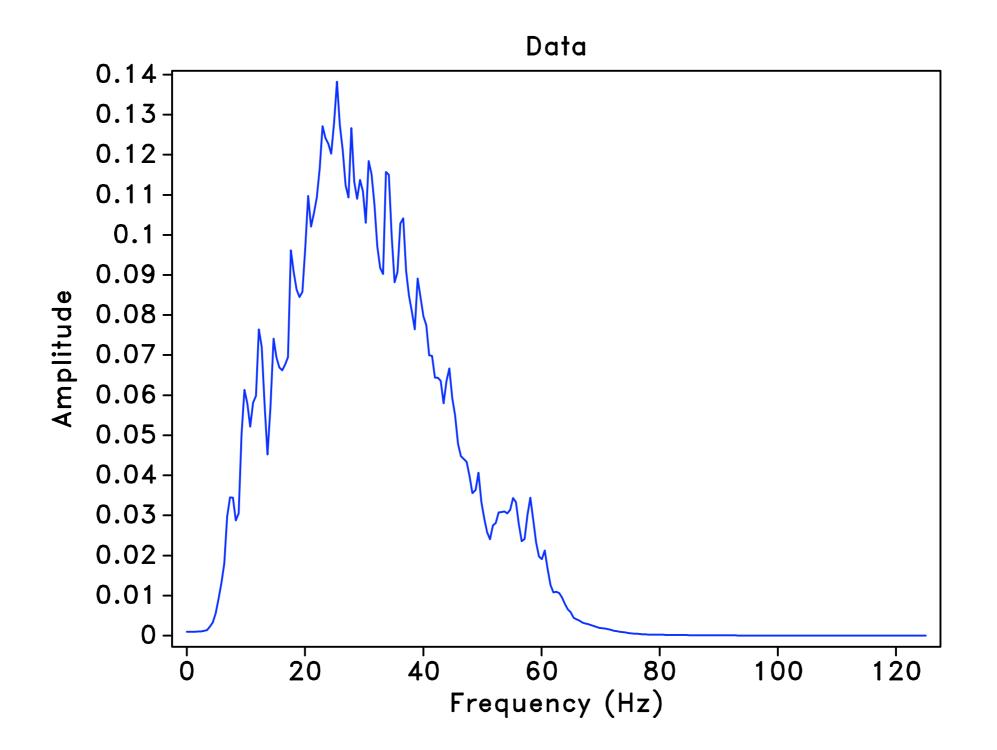
Invert P0



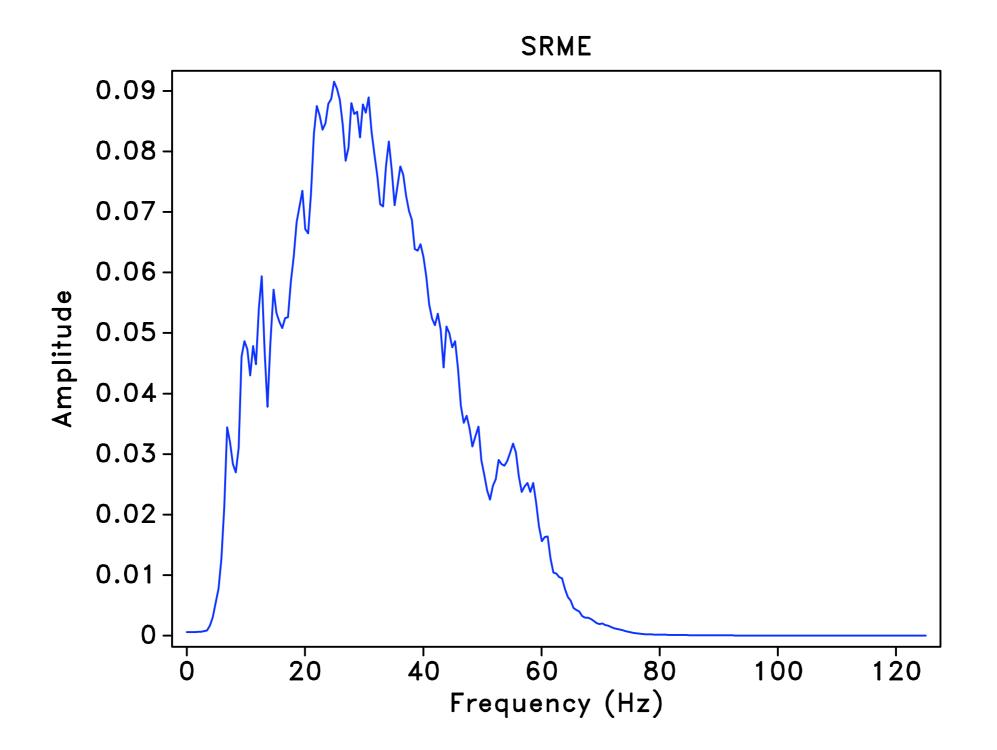




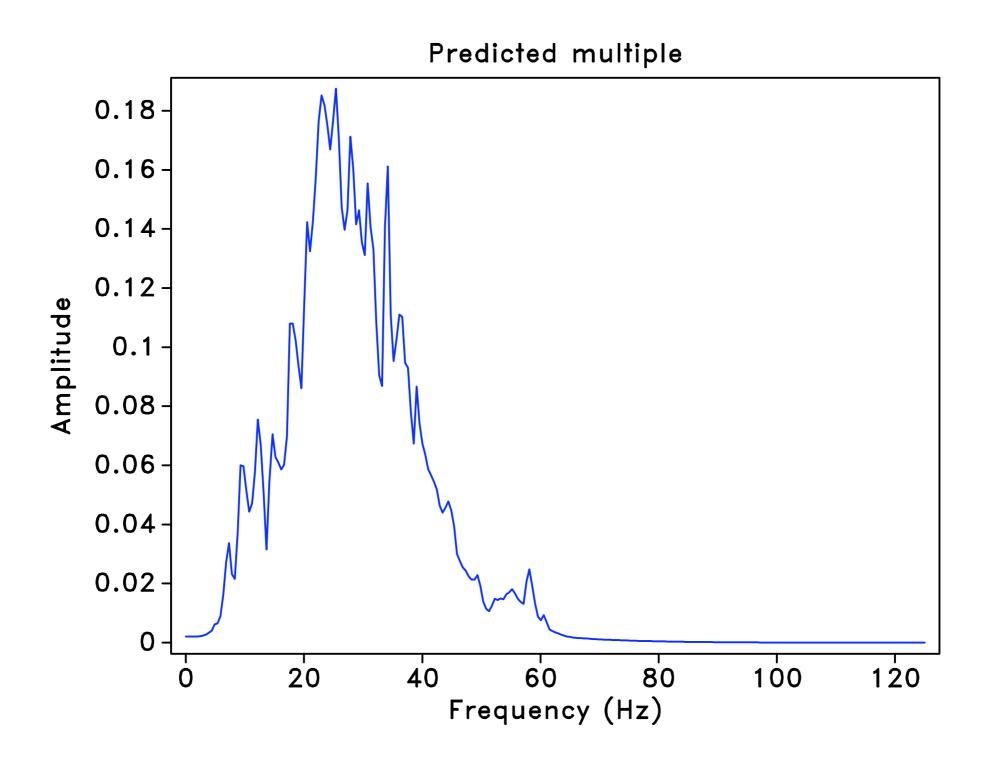




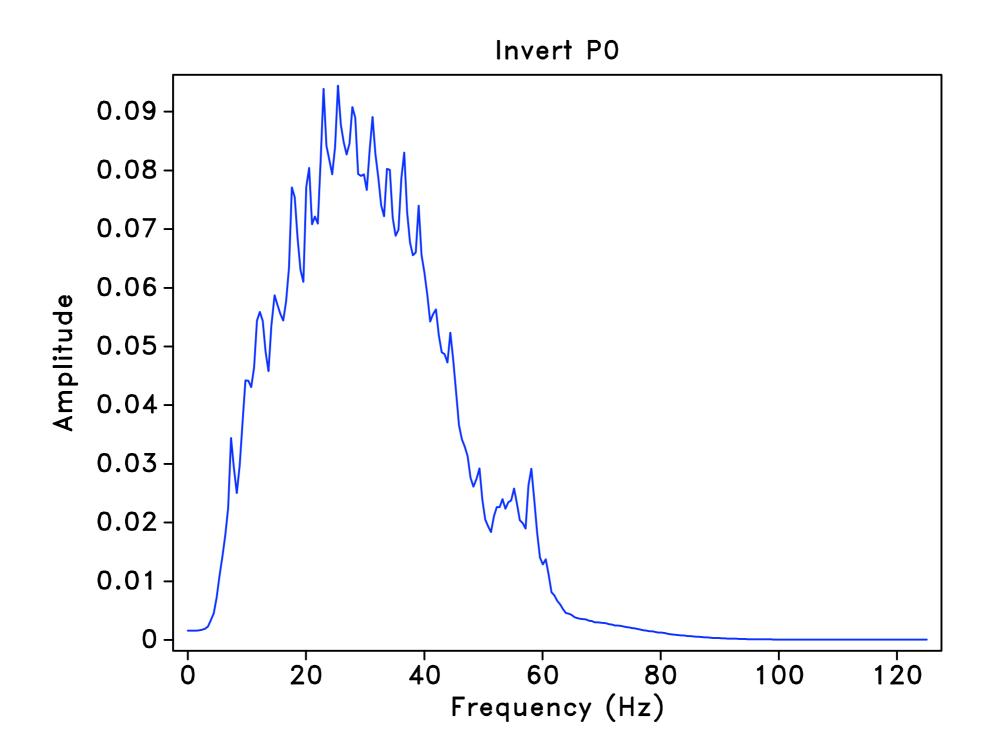




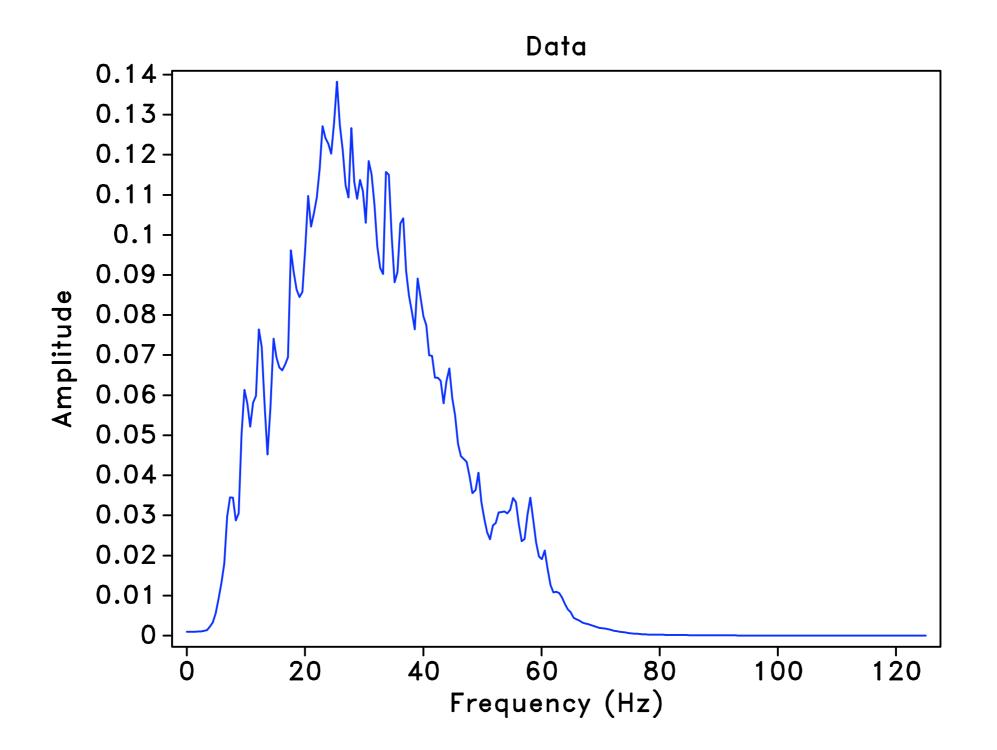




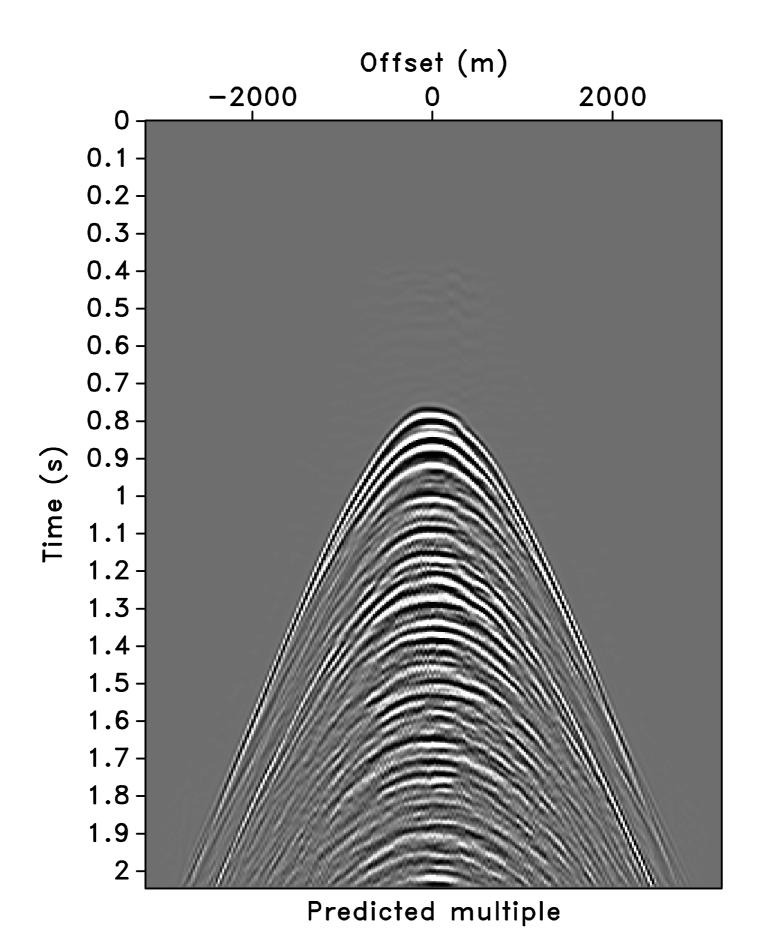




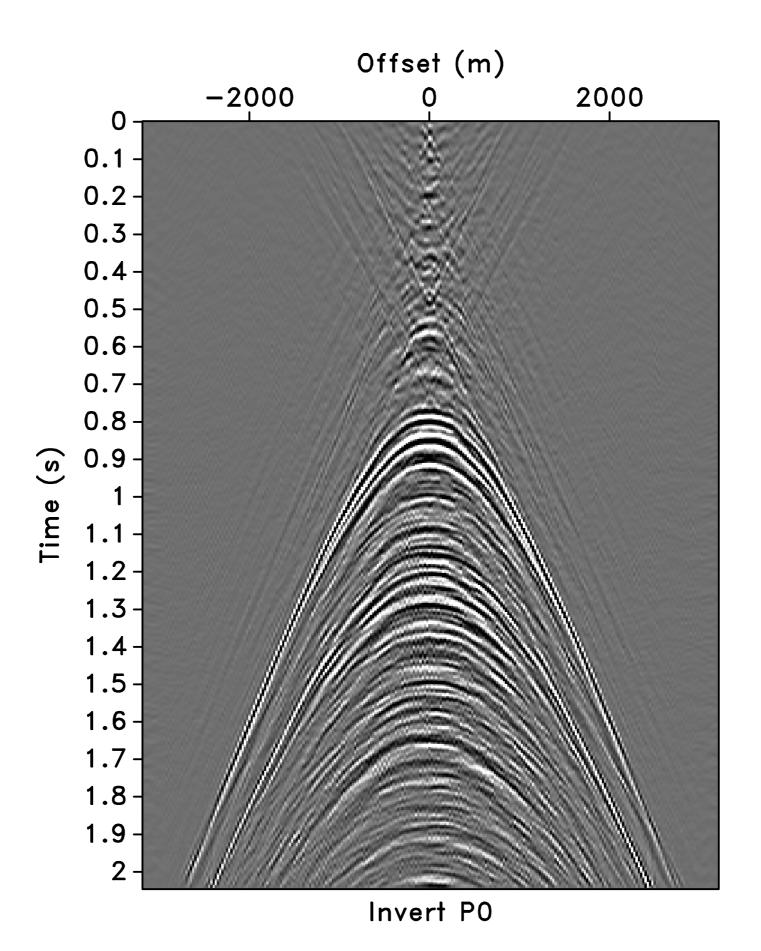








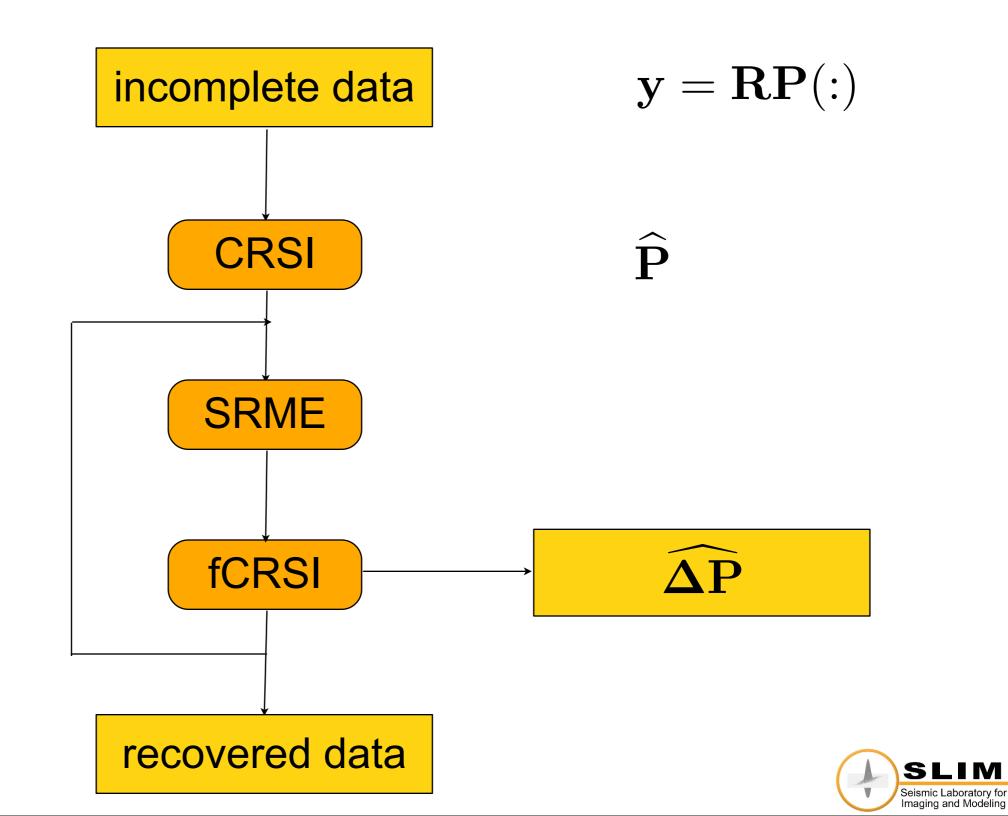






Primary prediction with fCRSI

Primary prediction with fCRSI



Curvelet-based Focal transform

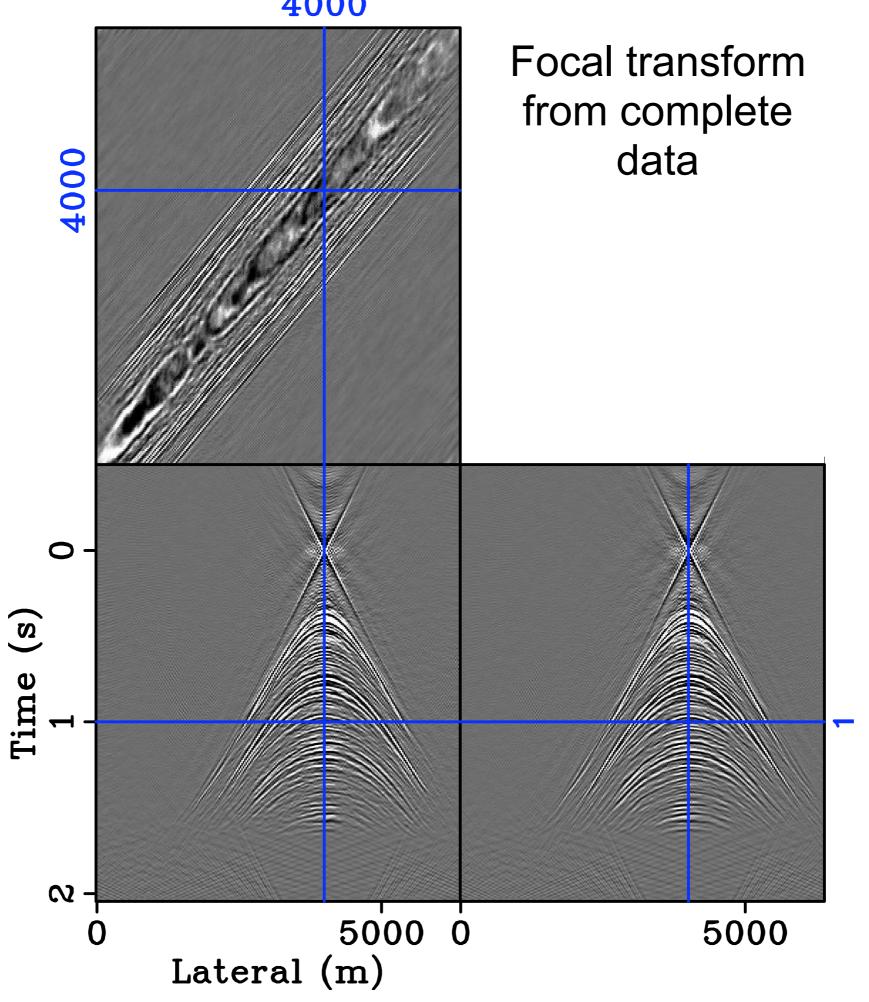
Solve

$$\mathbf{P}_{\epsilon}: \qquad \begin{cases} \widetilde{\mathbf{x}} = \arg\min_{\mathbf{x}} \|\mathbf{x}\|_{1} & \text{s.t.} & \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_{2} \leq \epsilon \\ \widetilde{\mathbf{f}} = \mathbf{S}^{T} \widetilde{\mathbf{x}} \end{cases}$$

with

- $\mathbf{A} := \mathbf{\Delta} \mathbf{P} \mathbf{C}^T$
- $\mathbf{S} := \mathbf{C}$
- $\mathbf{y} = \mathbf{P}(:)$
- \mathbf{P} = total data
- $\tilde{\mathbf{f}}$ = focused data.

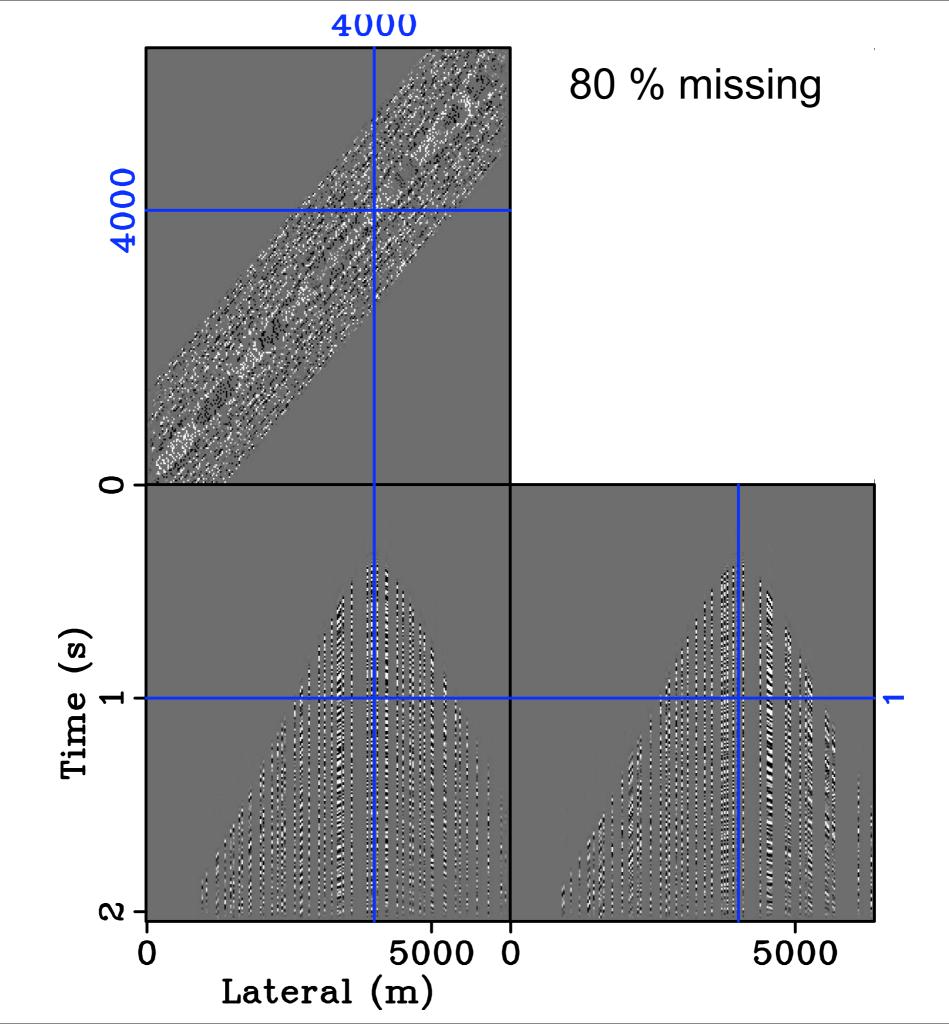




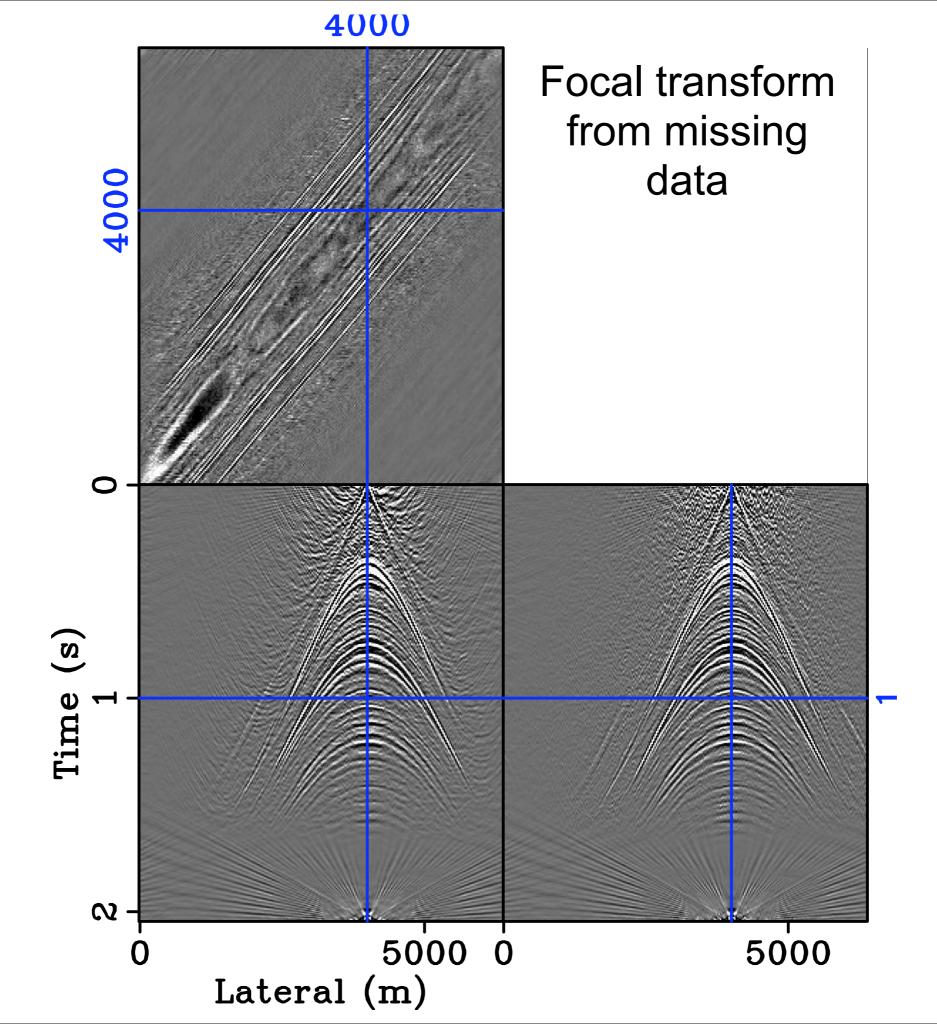
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4000









An encore ... preliminary results for the data inverse

$$\mathbf{P}_{\epsilon}$$
 :

$$\begin{cases} \tilde{\mathbf{x}} = \arg\min_{\mathbf{x}} \|\mathbf{x}\|_{1} & \text{s.t.} & \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_{2} \le \epsilon \\ \tilde{\mathbf{p}}^{-1} = \mathbf{S}^{T} \tilde{\mathbf{x}} \end{cases}$$

with

$$\mathbf{A} := \mathbf{P}\mathbf{C}^T$$

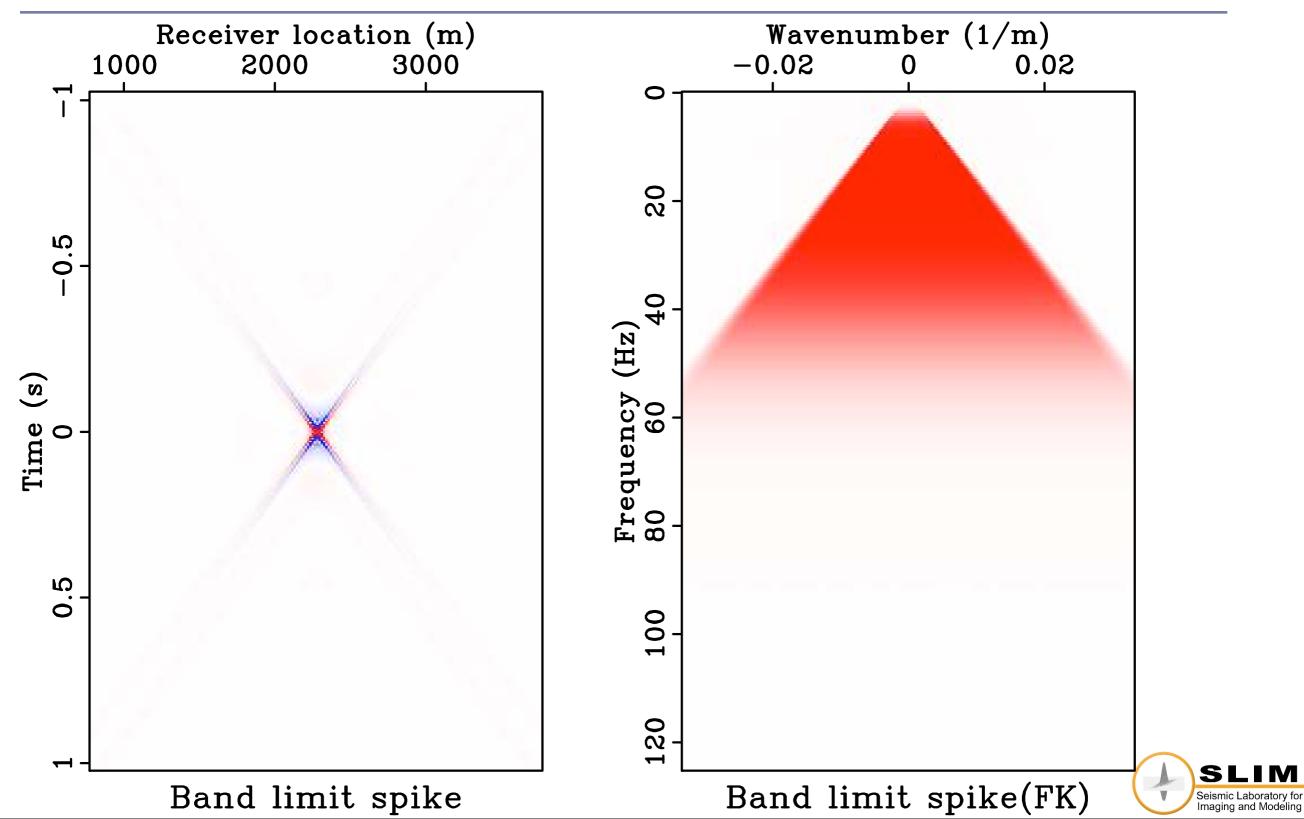
$$\mathbf{S}^T := \mathbf{C}^T$$

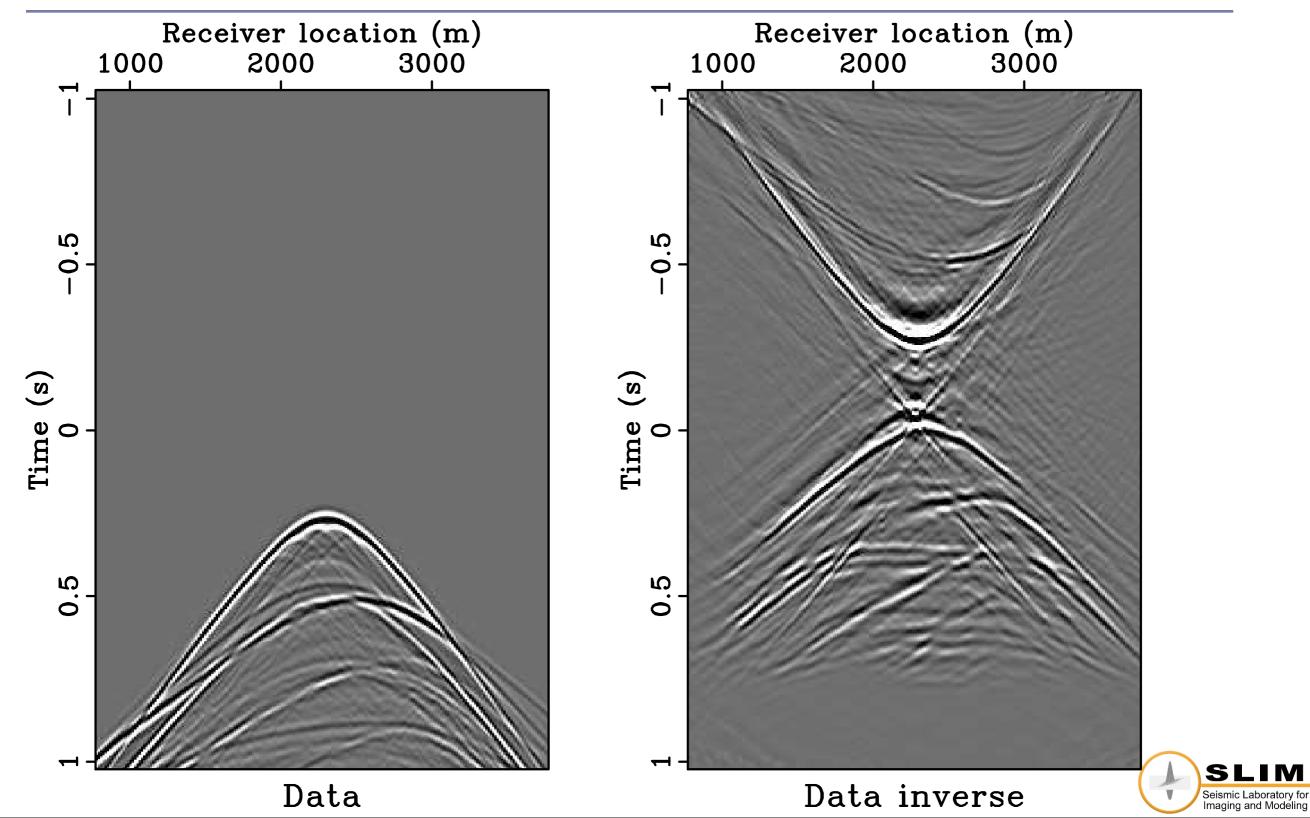
 $\mathbf{y} = \hat{\mathbf{I}}$

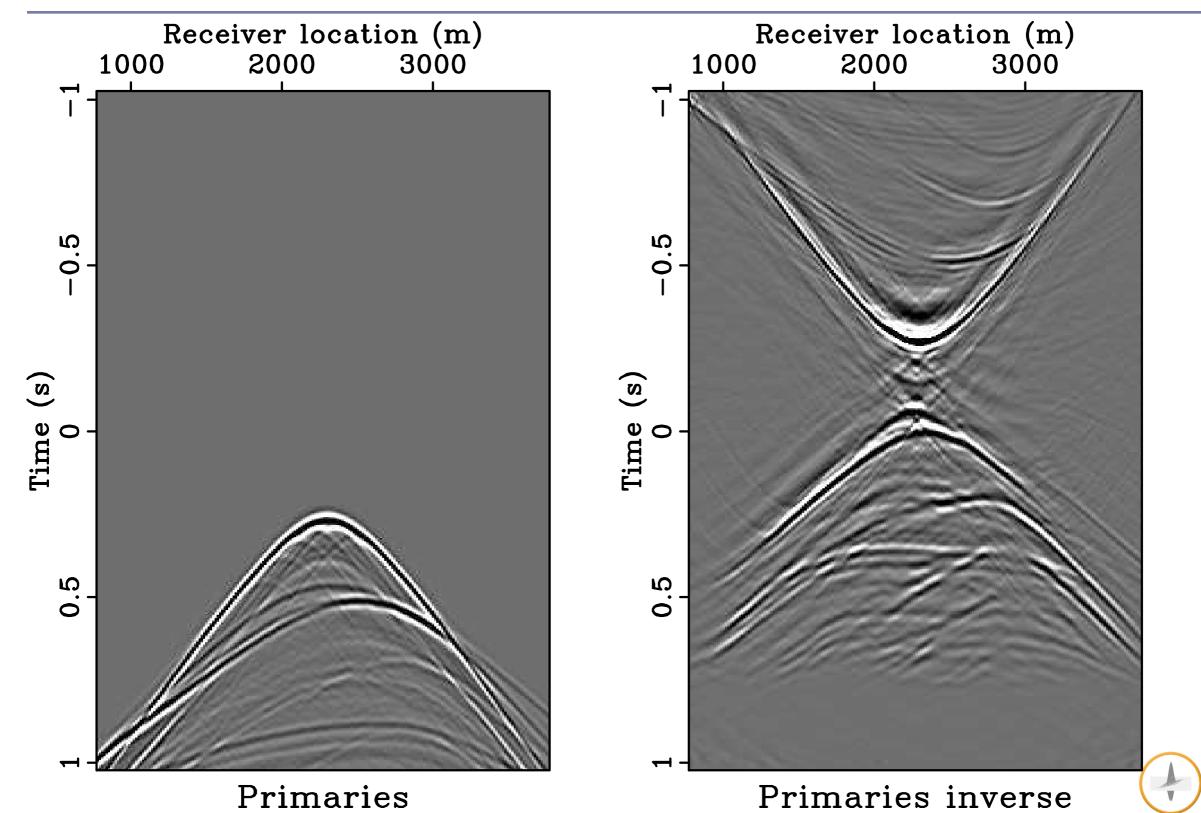
p is the data to be inverted

Curvelet-sparsity regularized *data inverse* computed for the *whole* data volume









SL

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Observations

Focal transform

- allows for incorporation of a priori information
- is reminiscent of an imaging operator
- works because of addition compression and incoherence
- leads to an improved recovery

Outlook

- Restriction corresponds to a compression of the operator
- Opens the way to migration-based recovery
- or a more "blue sky" approach to compressive wavefield extrapolation & imaging



Conclusions

CRSI

- recovers data by curvelet sparsity promotion
- uses sparsity as a prior

Focused CRSI

- incorporates additional prior information
- strips interaction with the surface <=> more sparsity
- improves the recovery and hence predicted multiples
- precursor of migration-based CRSI

Results of curvelet-based computation of the data inverse are encouraging.



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E. J. Candès, L. Demanet, D. L. Donoho, and L. Ying for
CurveLab

S.Fomel, P.Sava, and other developers of Madagascar

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