



Simply denoise: wavefield reconstruction via jittered undersampling

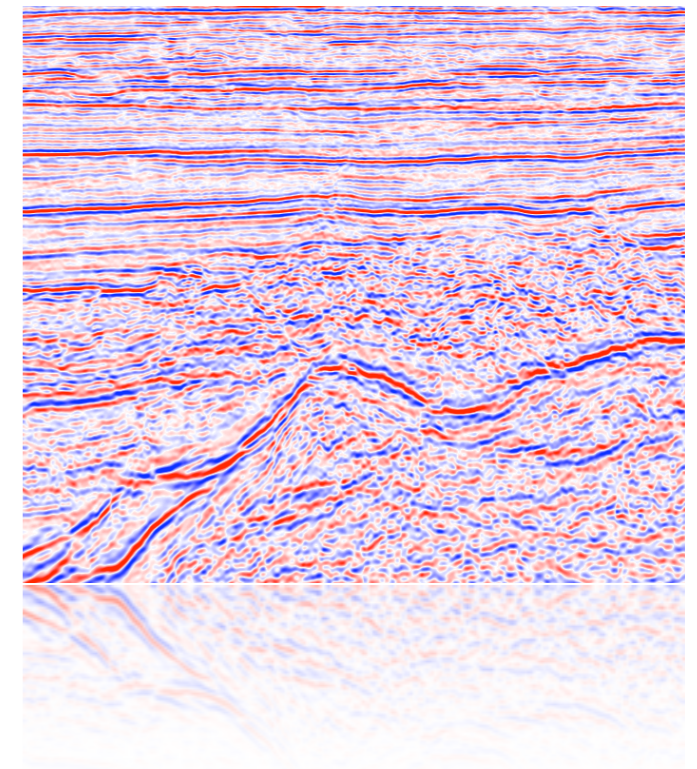
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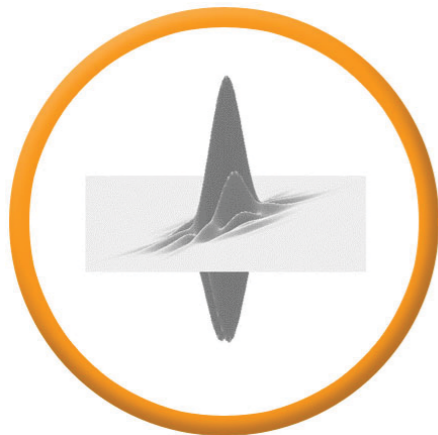
Felix J. Herrmann

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Department of Earth & Ocean Sciences
The University of British Columbia



SLIM consortium meeting
Seismic wavefield reconstruction
Wednesday, February 20th, 2008 - 2:00 PM

[Hennenfent and Herrmann, 2008]



Unleash the power of random sampling...

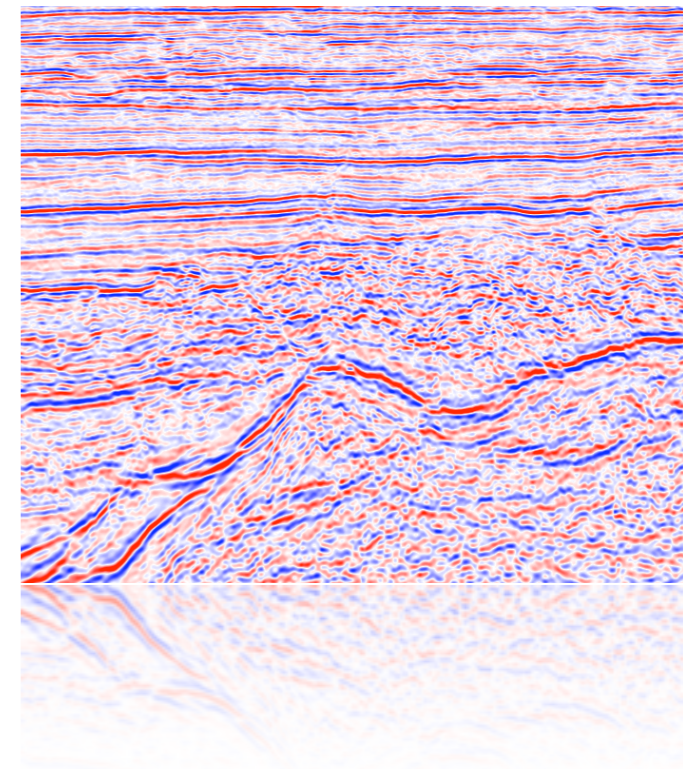
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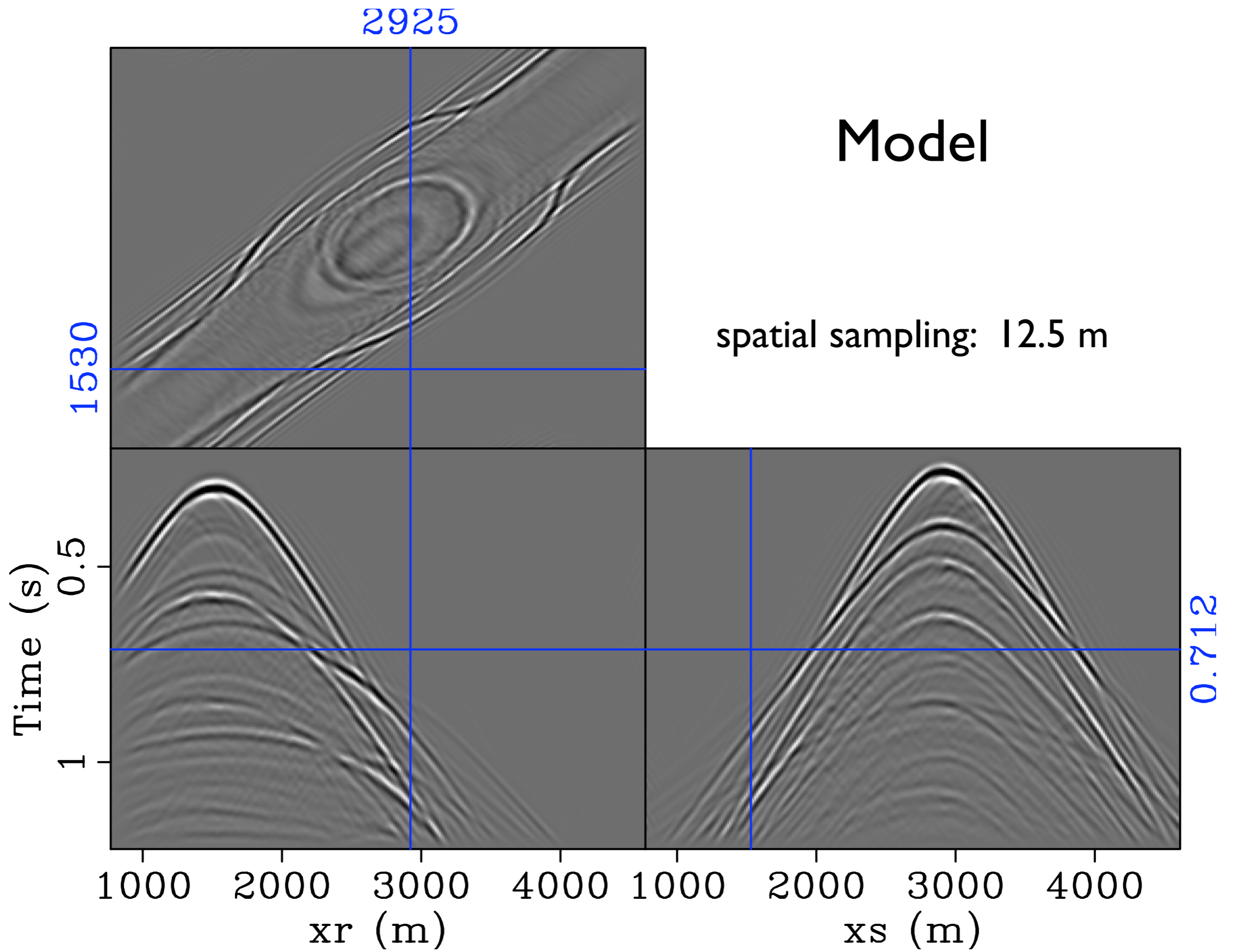
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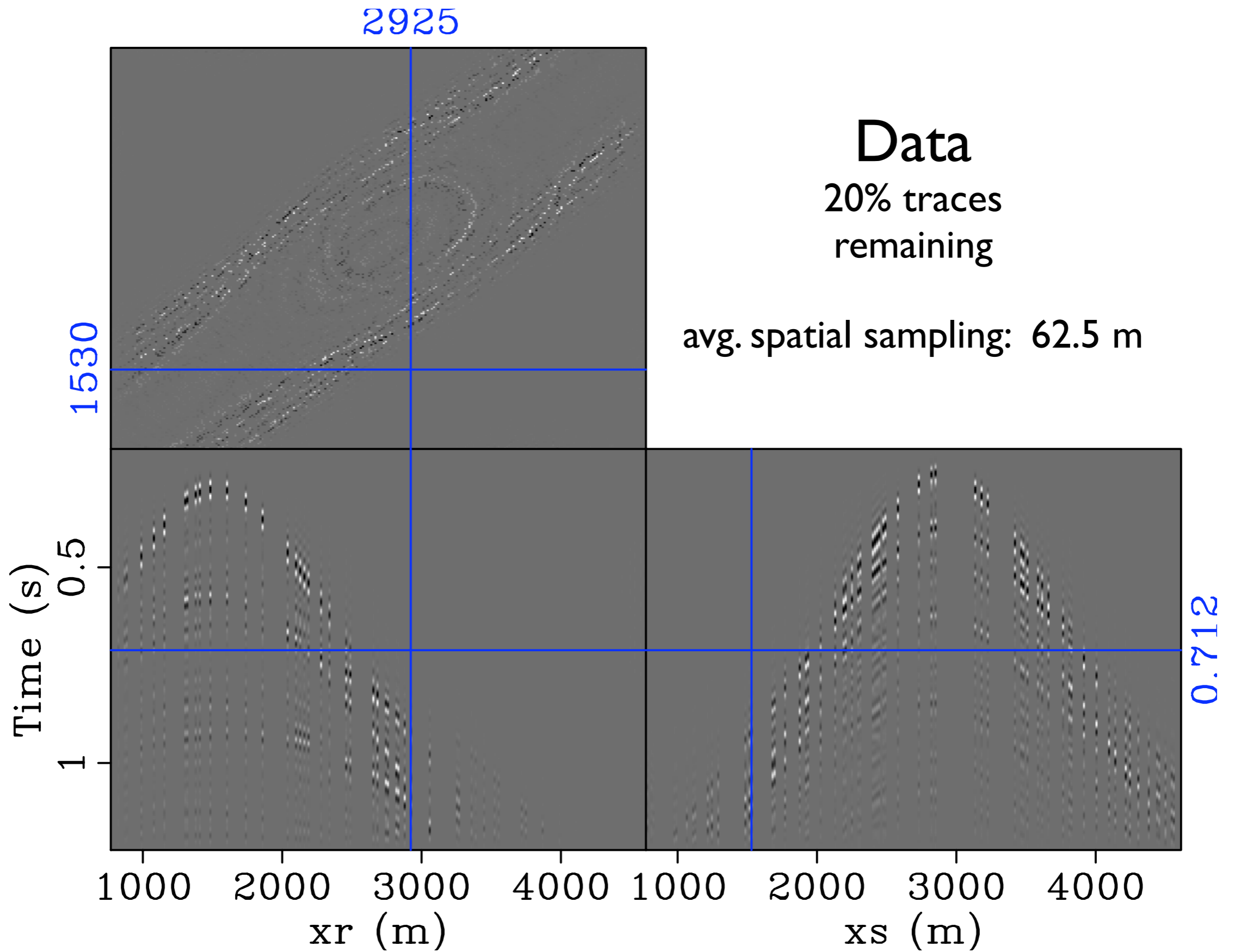
Felix J. Herrmann

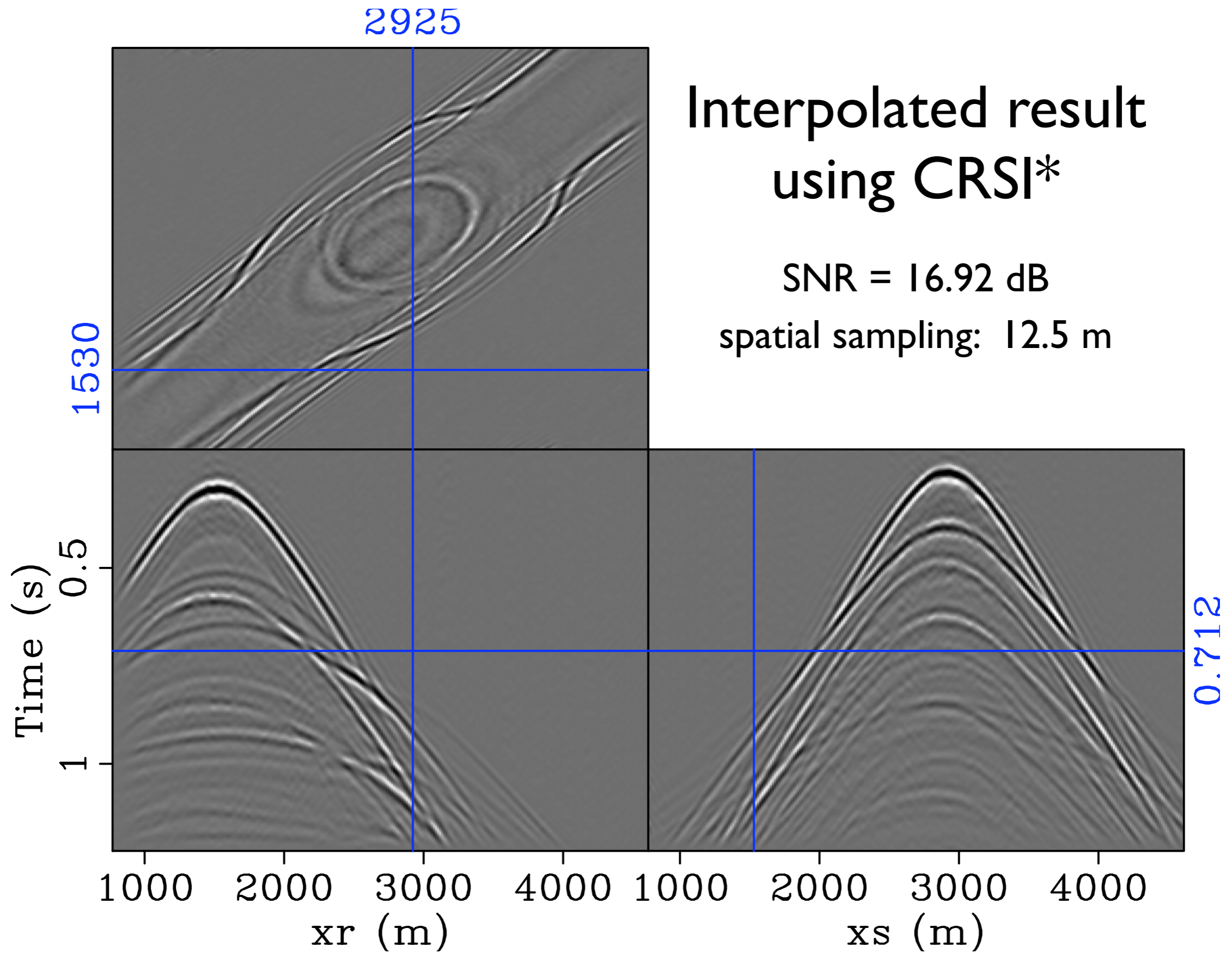
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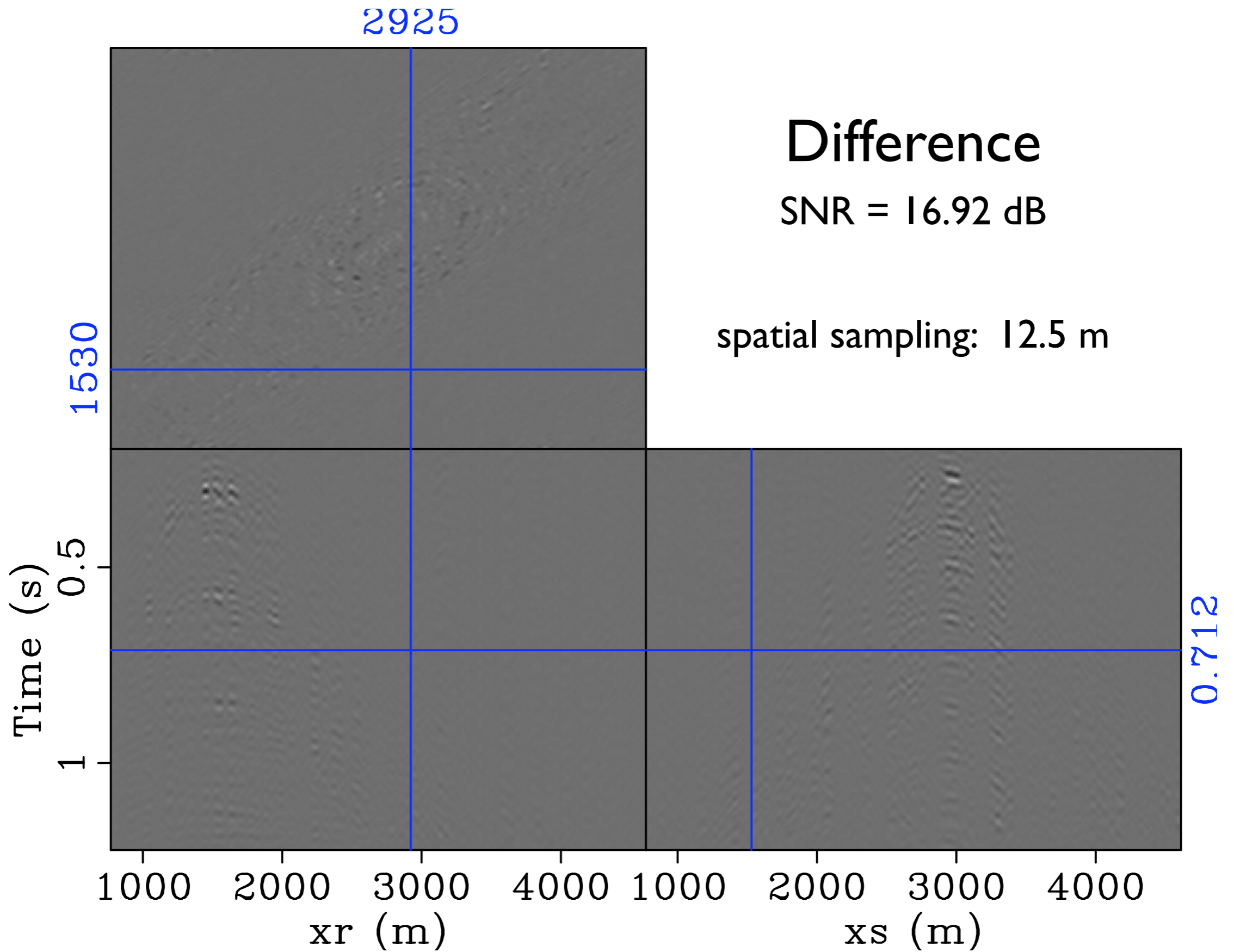


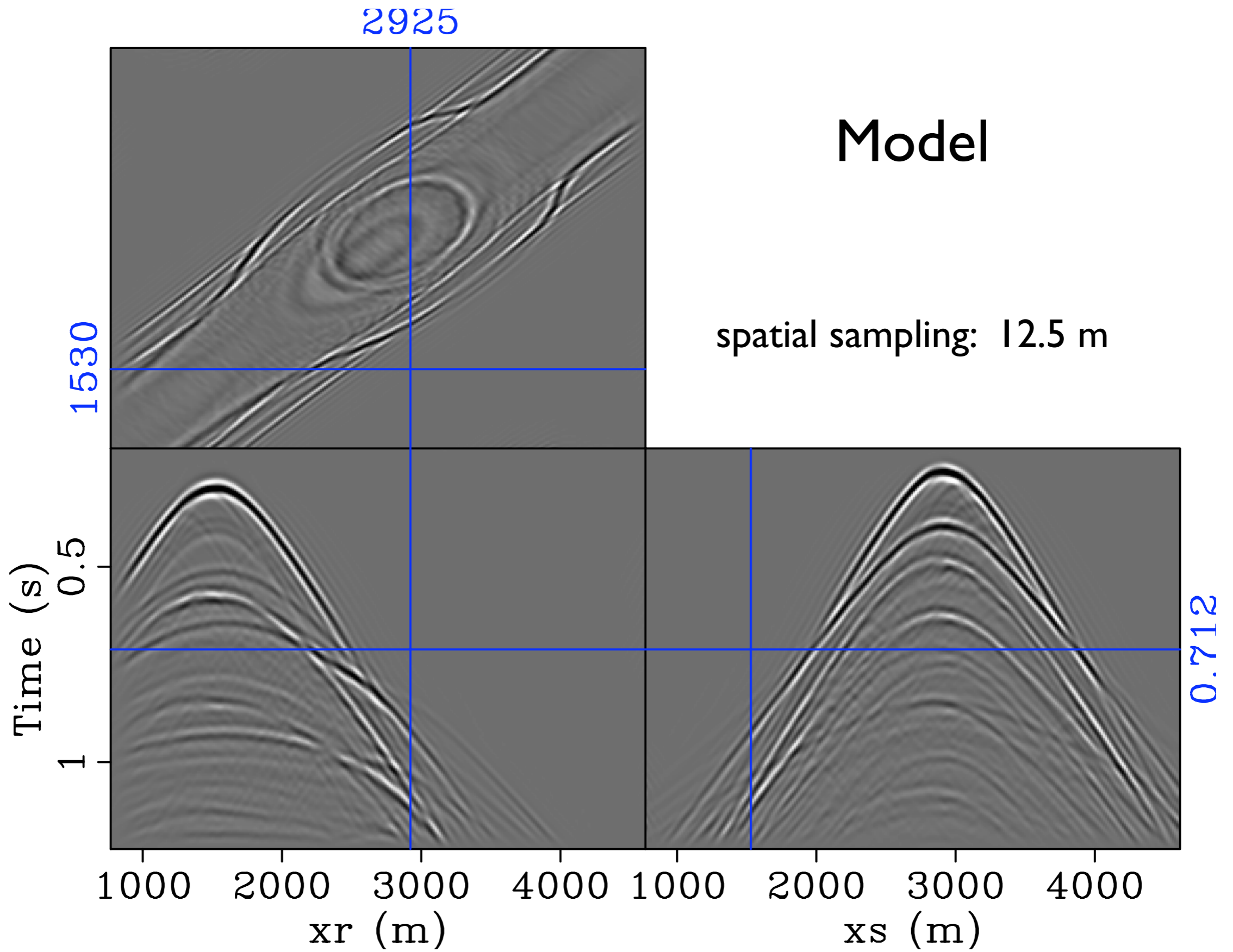
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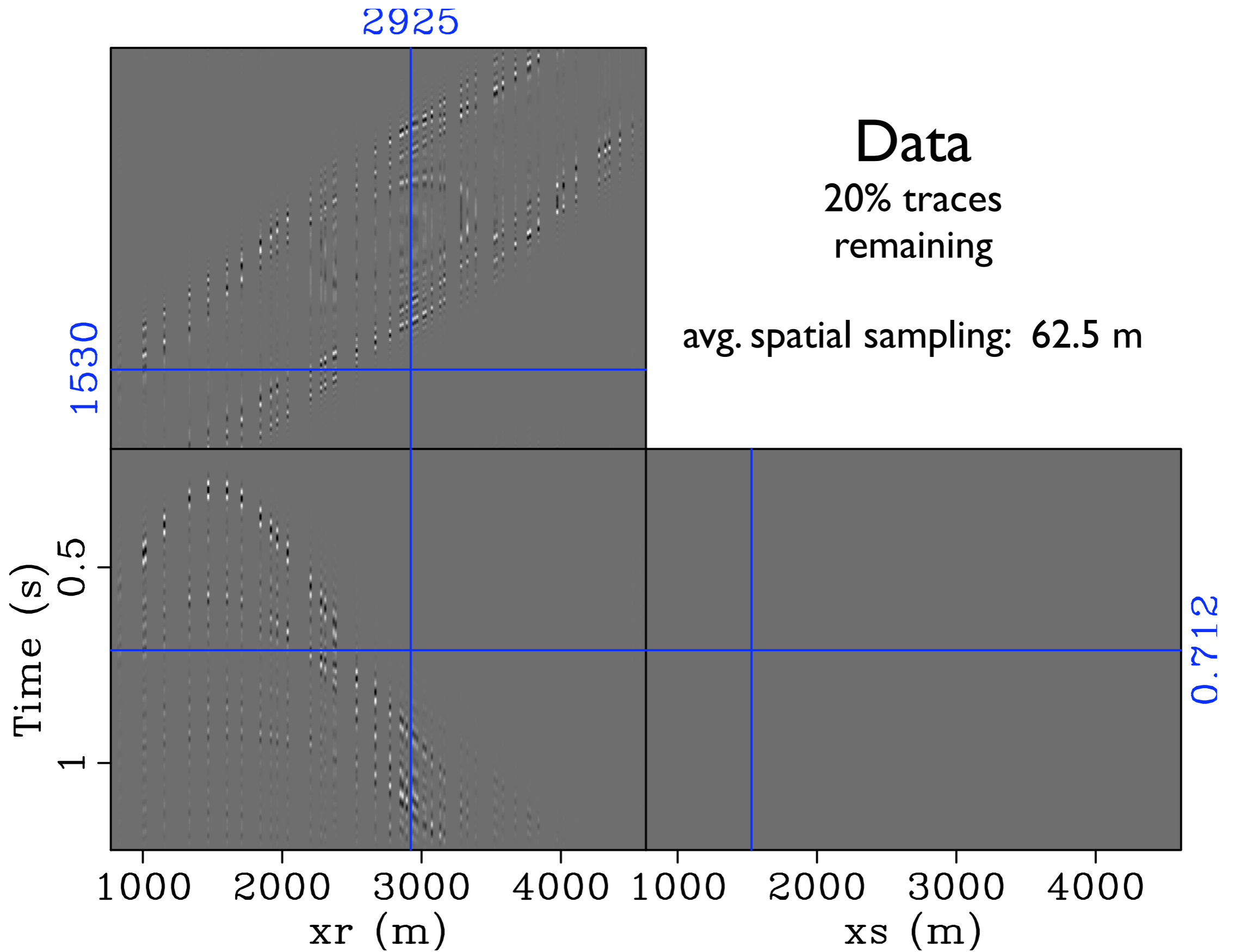












2925

Data

20% traces
remaining

avg. spatial sampling: 62.5 m

1530

0.712

Time (s)

0.5

1

1000

2000

3000

4000

xr (m)

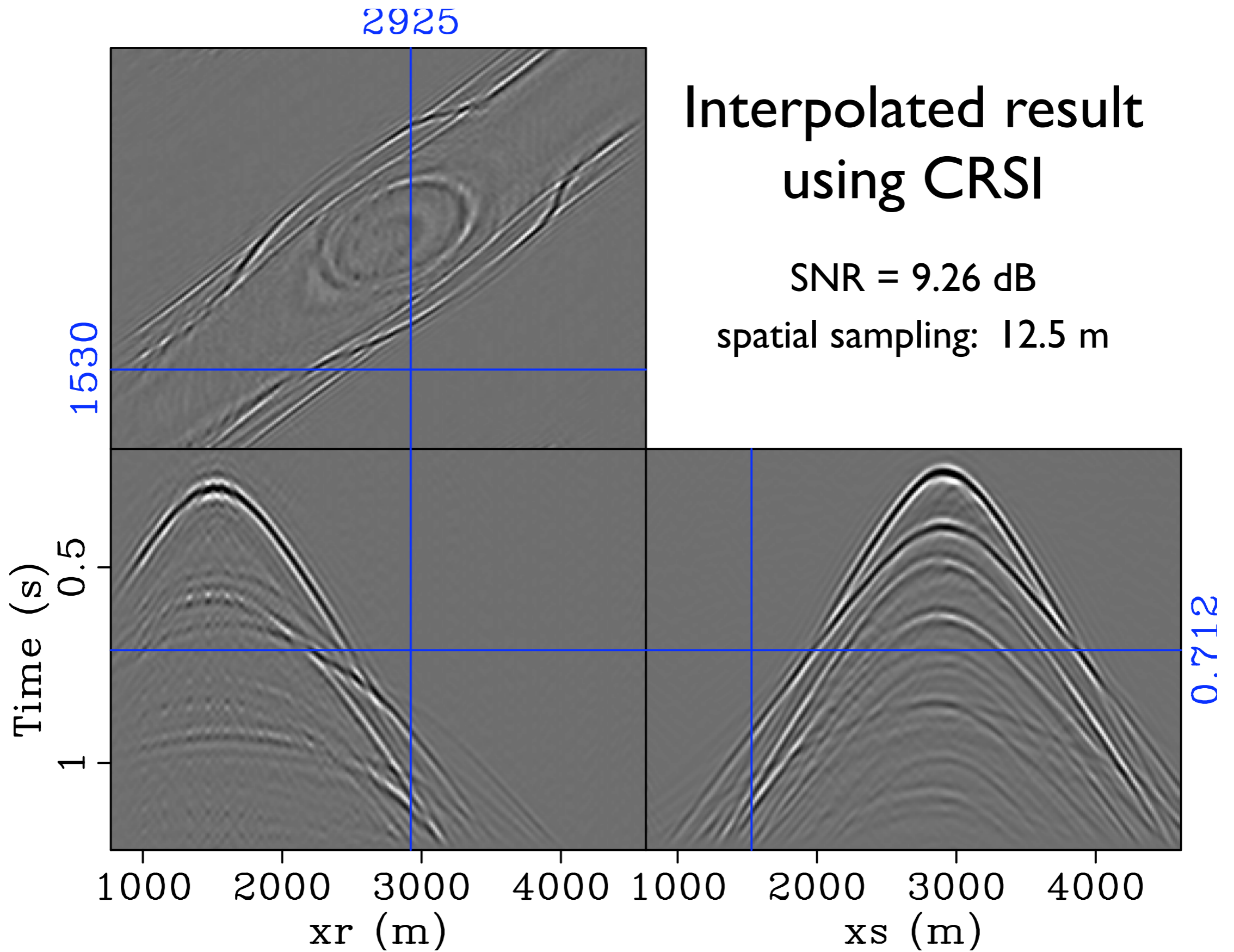
1000

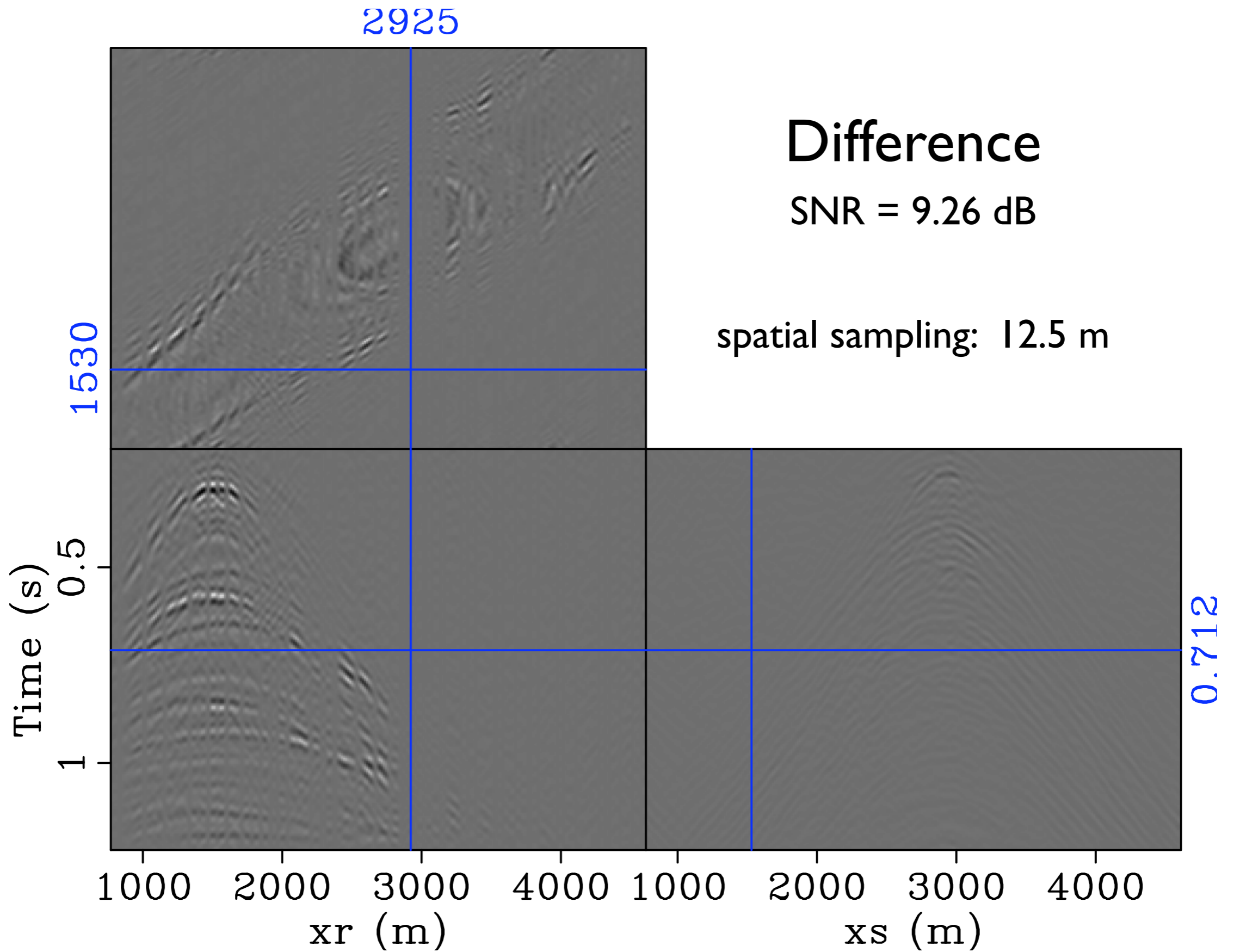
2000

3000

4000

xs (m)





Motivation

- preliminary observations

- 5-fold undersampled data in the time-source-receiver volume
 - missing traces at *irregular source-receiver locations*:
good reconstruction!
 - missing traces at *irregular receiver locations*:
(much) less accurate reconstruction...

- questions

- what makes one case better than the other?
- are acquisition irregularities really harmful to processing and imaging?
- is there something to learn about favorable coarse acquisition geometries?
- can the success of an interpolation method be (accurately) predicted based on the acquisition geometry?

Previous art

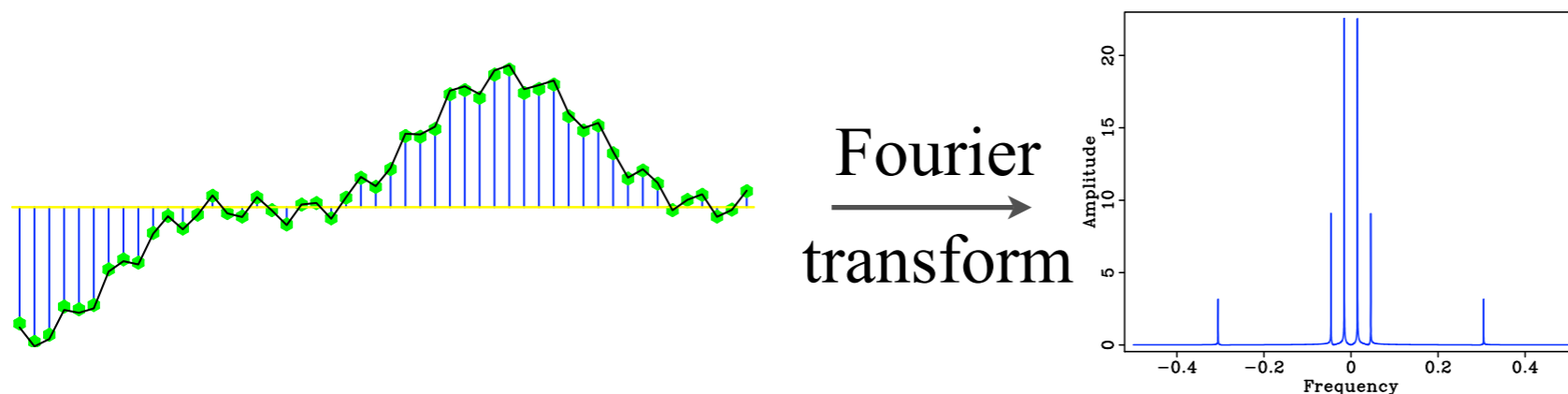
- geophysical literature

- Bednar, J. B., 1996, Coarse is coarse of course unless... The Leading Edge, **15**, 763 - 764.
- Sun, Y., G. T. Schuster, and K. Sikorski, 1997, A quasi-Monte Carlo approach to 3D migration: Theory: Geophysics, **62**, 918 - 928.
- Trad, D. O., and T. J. Ulrych, 1999, Radon transform: beyond aliasing with irregular sampling, 6th International Congress of the Brazilian Geophysical Society.
- Abma, R. and N. Kabir, 2006, 3D interpolation of irregular data with a POCS algorithm: Geophysics, **71**, E91 – E97.
- Zwartjes, P. M. and M. D. Sacchi, 2007, Fourier reconstruction of nonuniformly sampled, aliased data: Geophysics, **72**, V21–V32.

- other fields

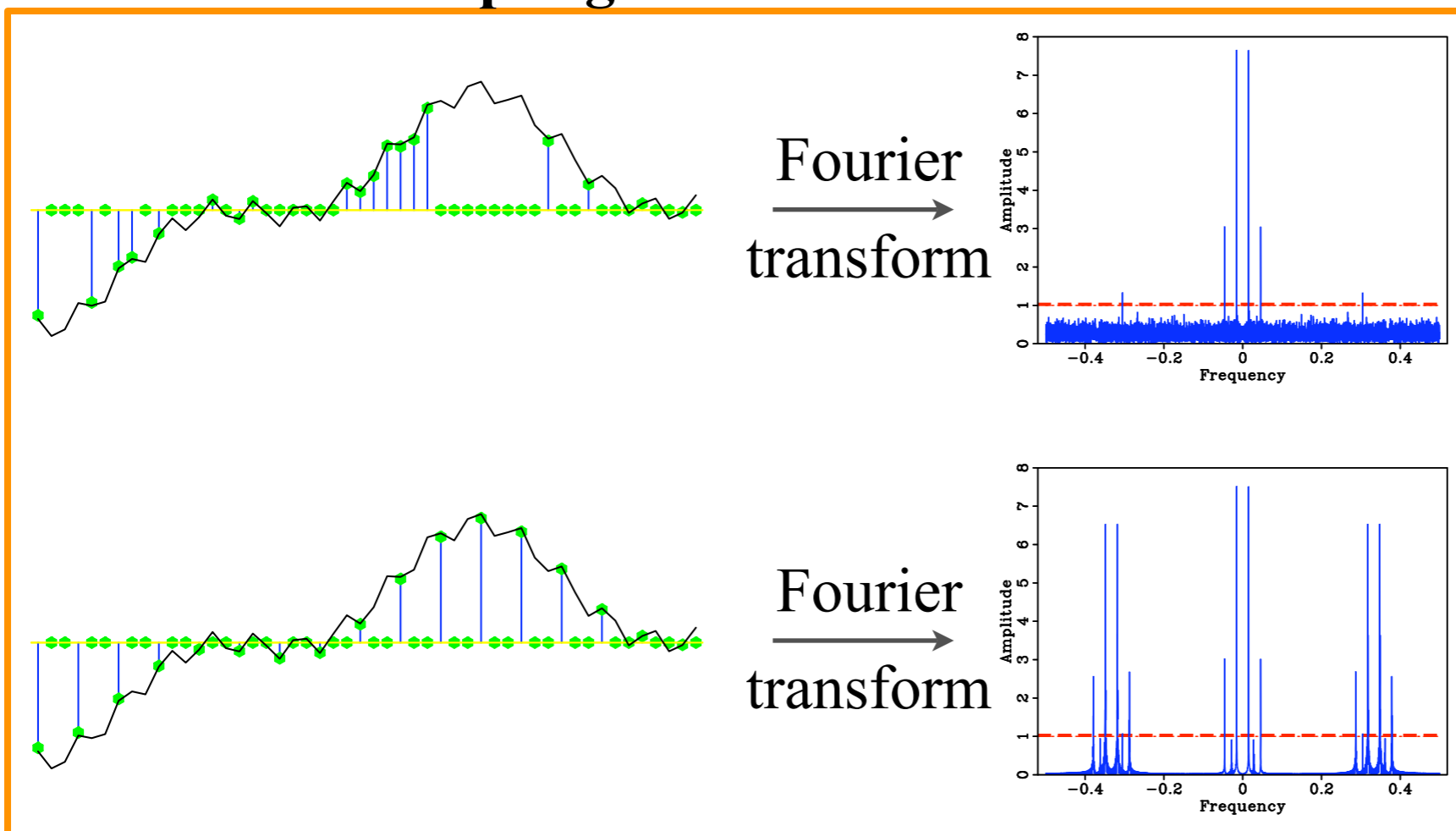
- Donoho, D. L., Y. Tsaig, I. Drori, and J.-L. Starck, 2006, Sparse solution of underdetermined linear equations by stagewise orthogonal matching pursuit: Technical report, Stanford Statistics Department. TR-2006-2.
- Dippe, M. and E. Wold, 1992, Stochastic sampling: theory and application: Progress in computer graphics, **1**, 1 – 54.

Simple example



**few significant
coefficients**

3-fold under-sampling

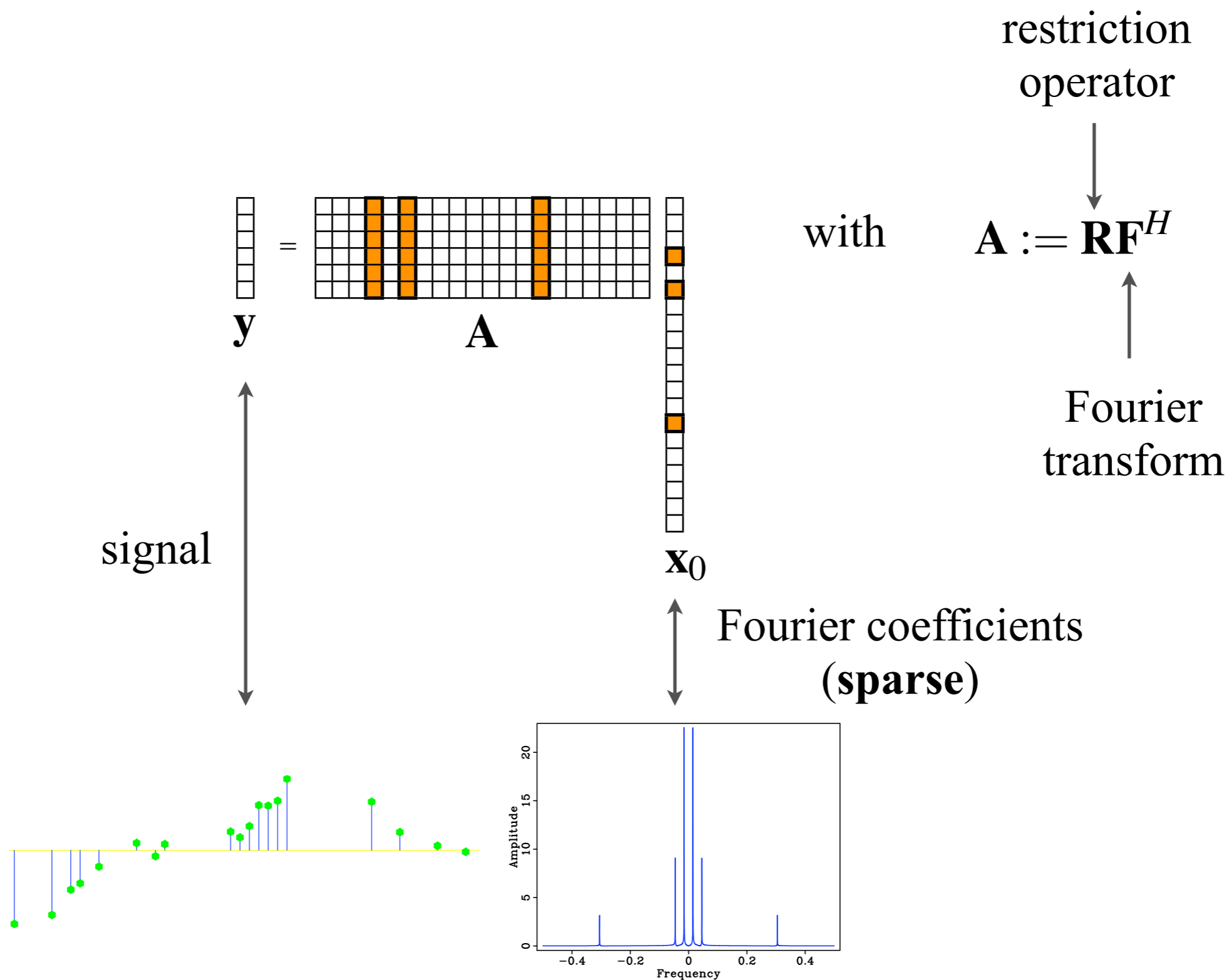


**significant
coefficients detected**

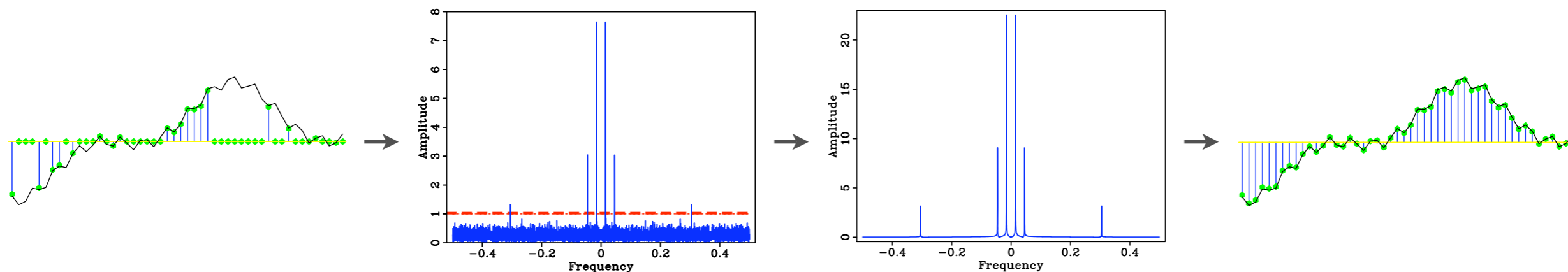


ambiguity

Forward problem



Naive sparsity-promoting recovery

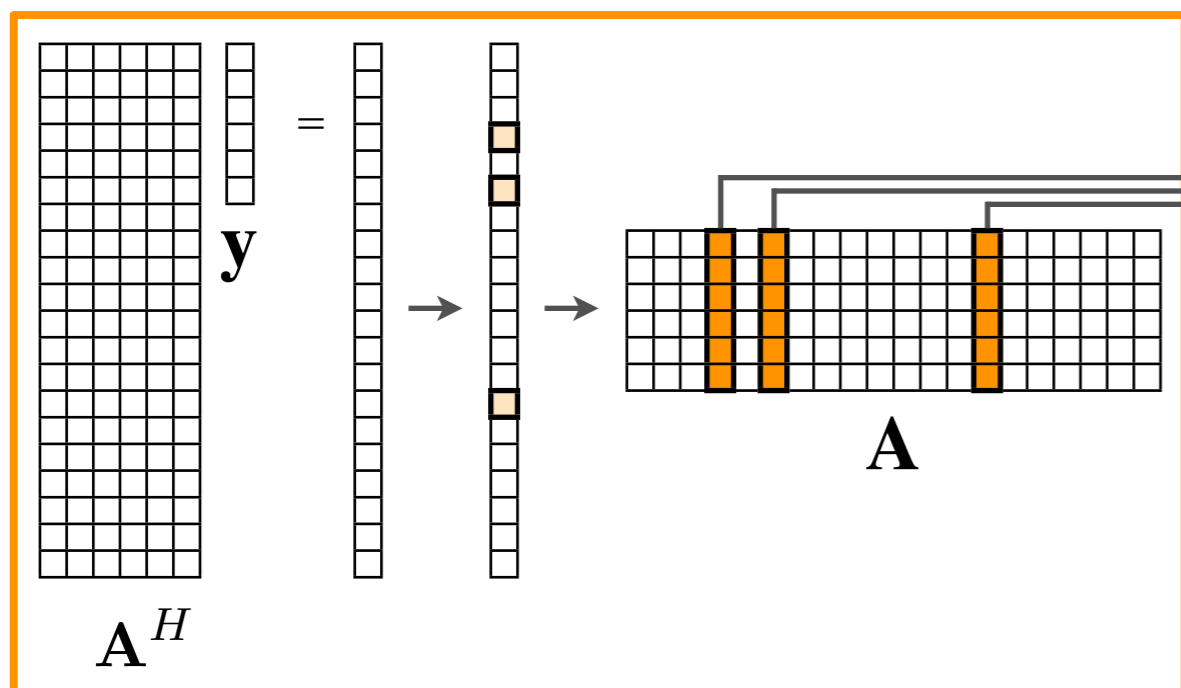


inverse
Fourier
transform

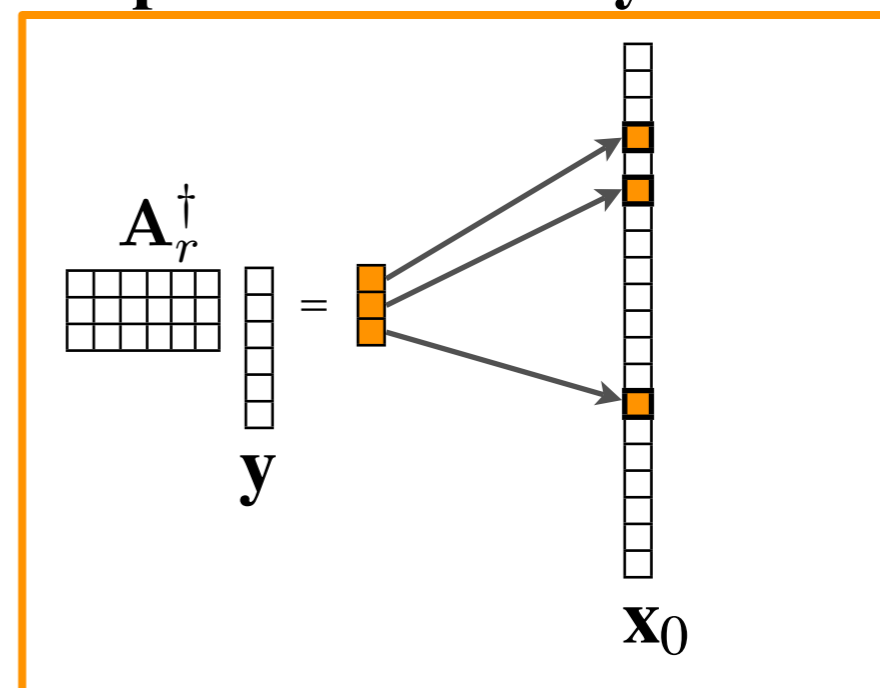
detection +
data-consistent
amplitude recovery

Fourier
transform

detection



**data-consistent
amplitude recovery**



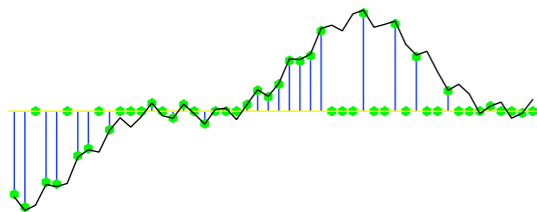
Observations

- 3-fold undersampling
 - random: significant coefficients **detected!**
 - regular: **ambiguity** between significant coefficients and aliases
- random undersampling
 - recovery \approx denoising + amplitudes correction
 - (accurate) recovery of the coefficients above the “noise” level

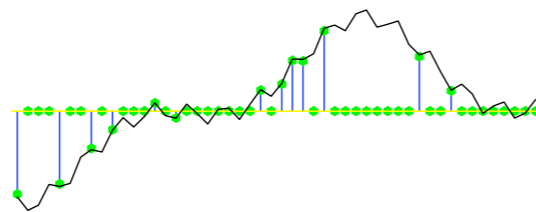
Undersampling “noise”

- “noise”
 - due to $\mathbf{A}^H\mathbf{A} \neq \mathbf{I}$
 - defined by $\mathbf{A}^H\mathbf{A}\mathbf{x}_0 - \mathbf{a}\mathbf{x}_0 = \mathbf{A}^H\mathbf{y} - \mathbf{a}\mathbf{x}_0$

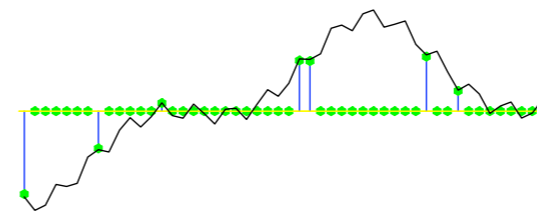
1 out of 2



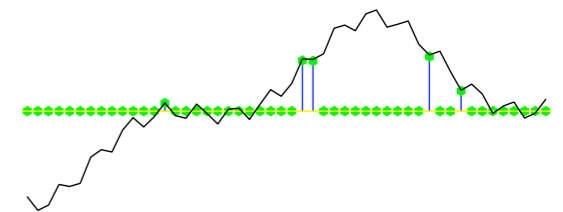
1 out of 4



1 out of 6



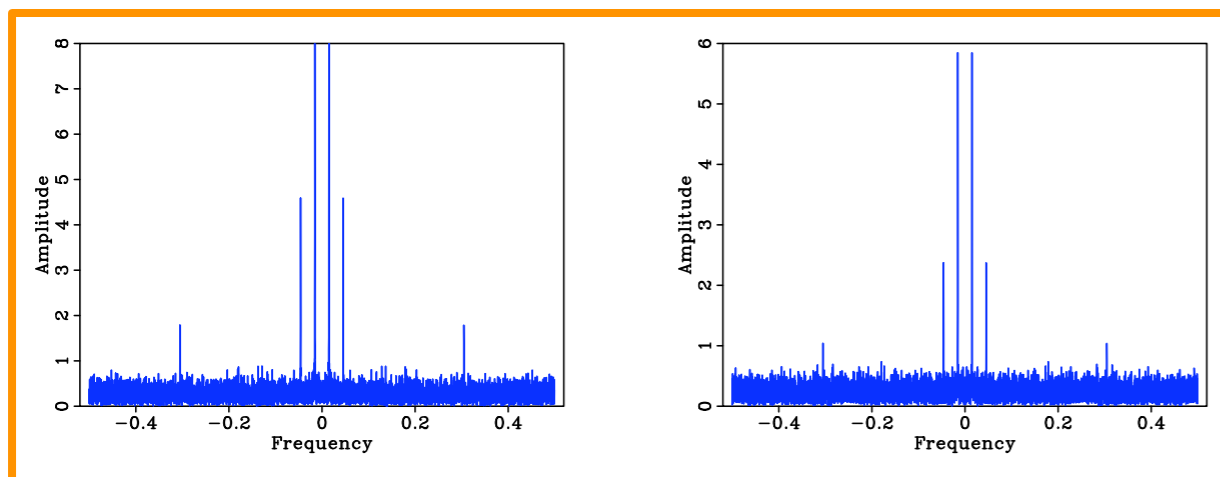
1 out of 8



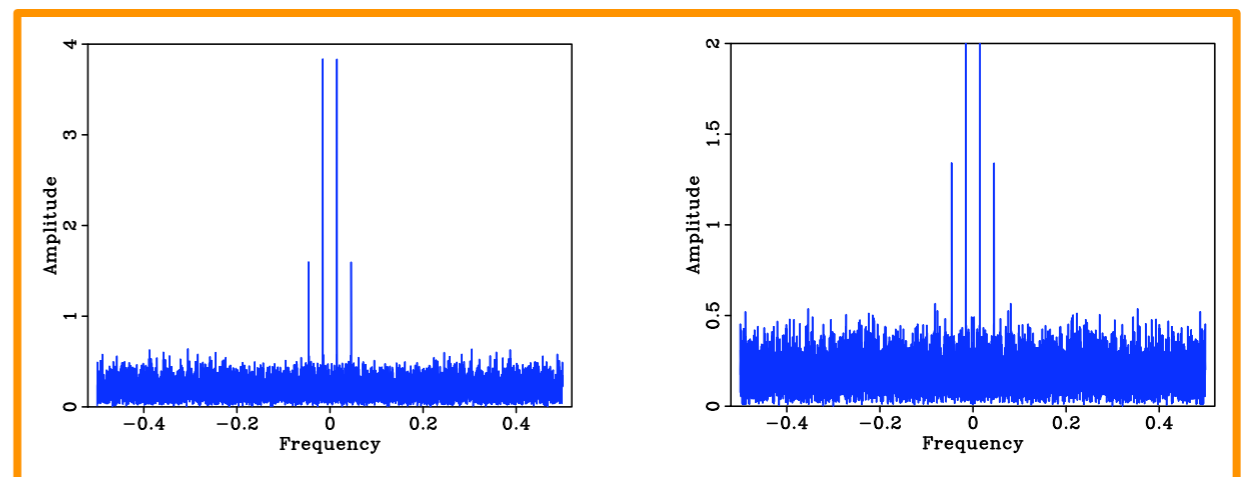
less acquired data



3 detectable Fourier modes



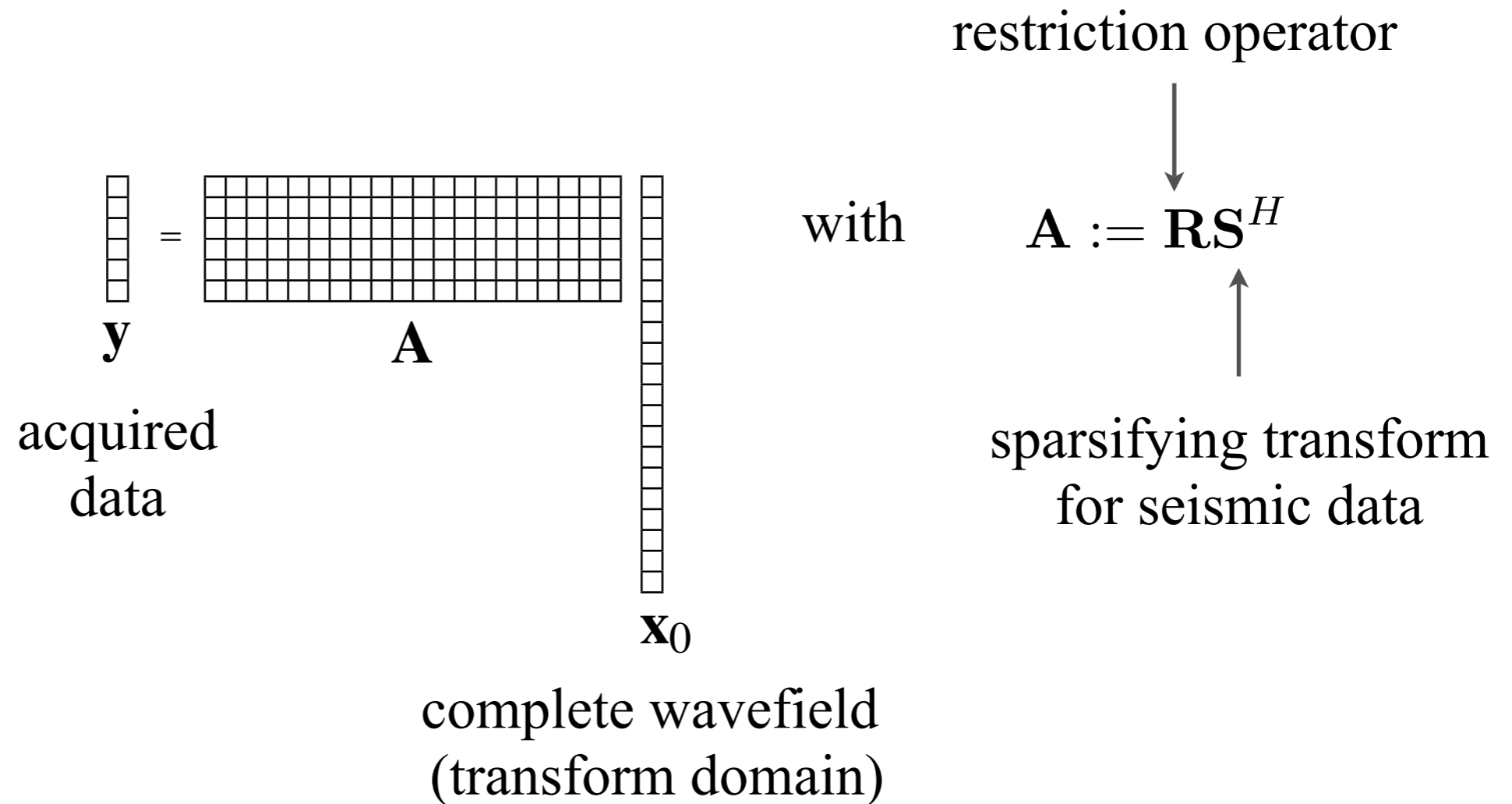
2 detectable Fourier modes



Further observations & comments

- random undersampling
 - size of the undersampling “noise” is a function of the undersampling factor
 - the less data acquired, the higher the “noise” level
 - for increasing undersampling
 - the largest coefficients remain detectable for the longest
 - for given undersampling
 - fixed number of recoverable coefficients
 - the more energy these significant coefficients carry compared to the total energy, the better the recovery ⇒ **need of an efficient representation for seismic data**

Sparsity-promoting wavefield reconstruction



Interpolated data given by $\tilde{\mathbf{f}} = \mathbf{S}^H \tilde{\mathbf{x}}$ with

$$\tilde{\mathbf{x}} = \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = \mathbf{A} \mathbf{x}$$

[Sacchi et al '98]

[Xu et al '05]

[Zwartjes and Sacchi '07]

[Herrmann and Hennenfent '08]

Nonlinear wavefield sampling

- *sparsifying transform*

- typically **localized** in the time-space domain to handle the complexity of seismic data
 - curvelet transform (dyadic-parabolic partition of the f-k domain)
 - [windowed Fourier transform]

- *sampling scheme*

- generates incoherent random undersampling “noise” in the sparsifying domain
- do not create large gaps
 - because of the limited spatiotemporal extend of transform elements used for the reconstruction

- *sparsity-promoting solver*

- requires few matrix-vector multiplications

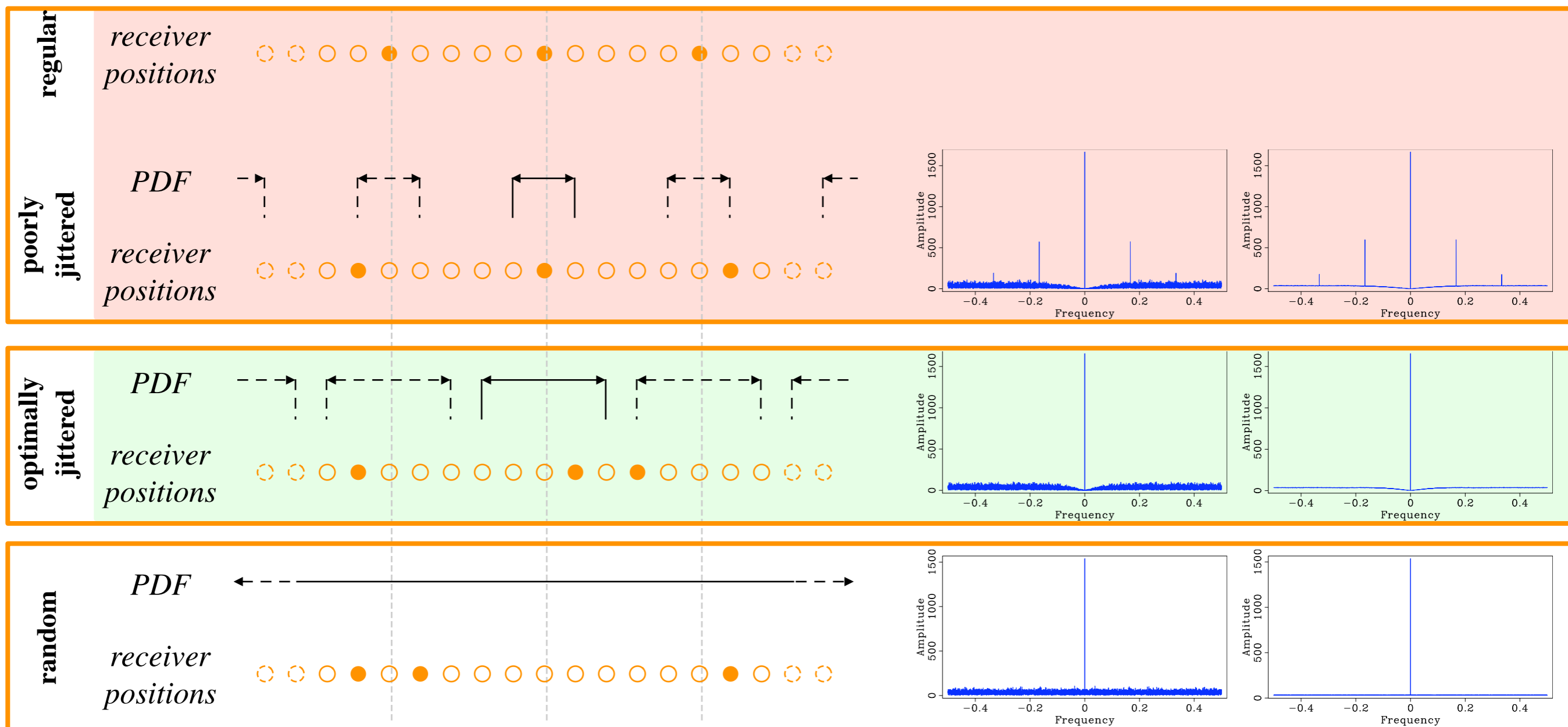
Discrete random jittered undersampling

Type

Sampling scheme

Typical spatial
convolution kernel
(amplitudes)

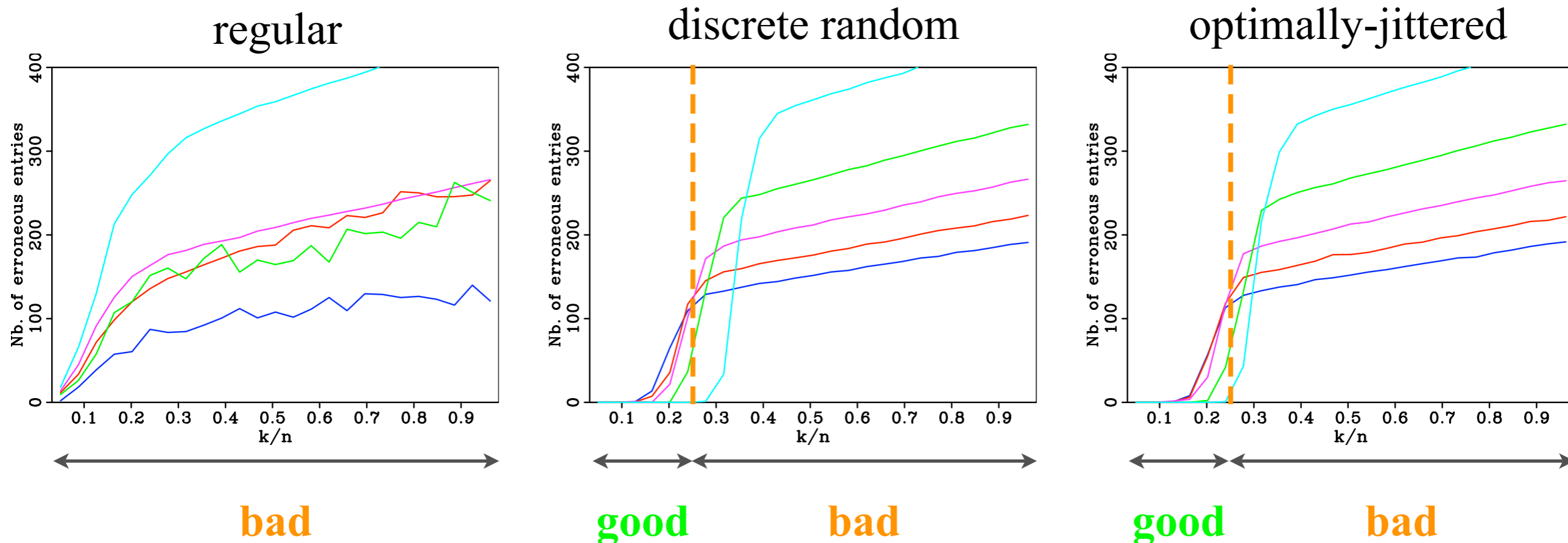
Averaged spatial
convolution kernel
(amplitudes)



Recovery from random vs. opt.-jittered data

- k -sparse signal of length N in the Fourier domain
- n observations in the time domain
 - $n = N/\gamma$ with the undersampling factor γ ranging from 2 to 6

$$\tilde{\mathbf{x}} = \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = \mathbf{A}\mathbf{x}$$



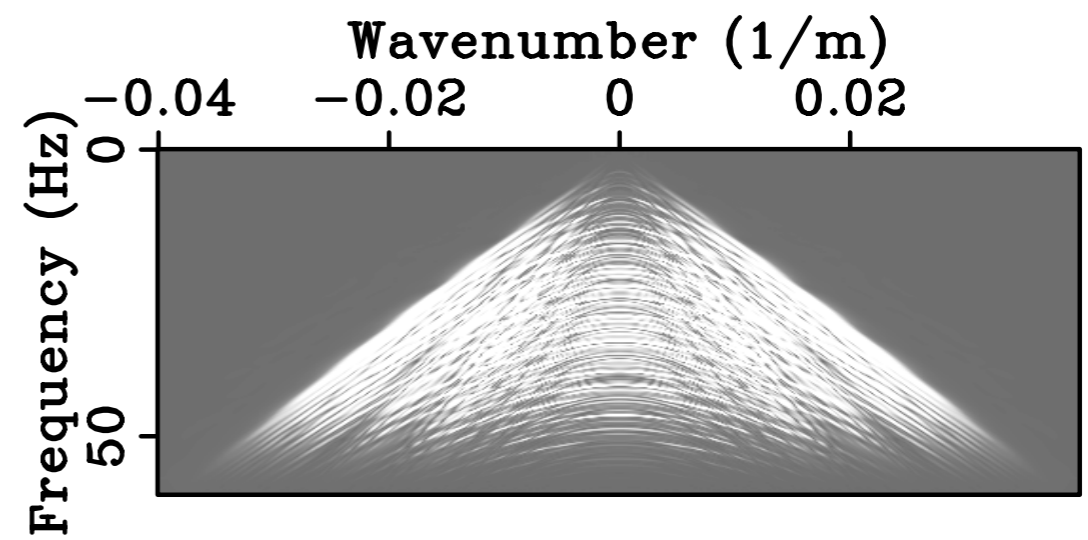
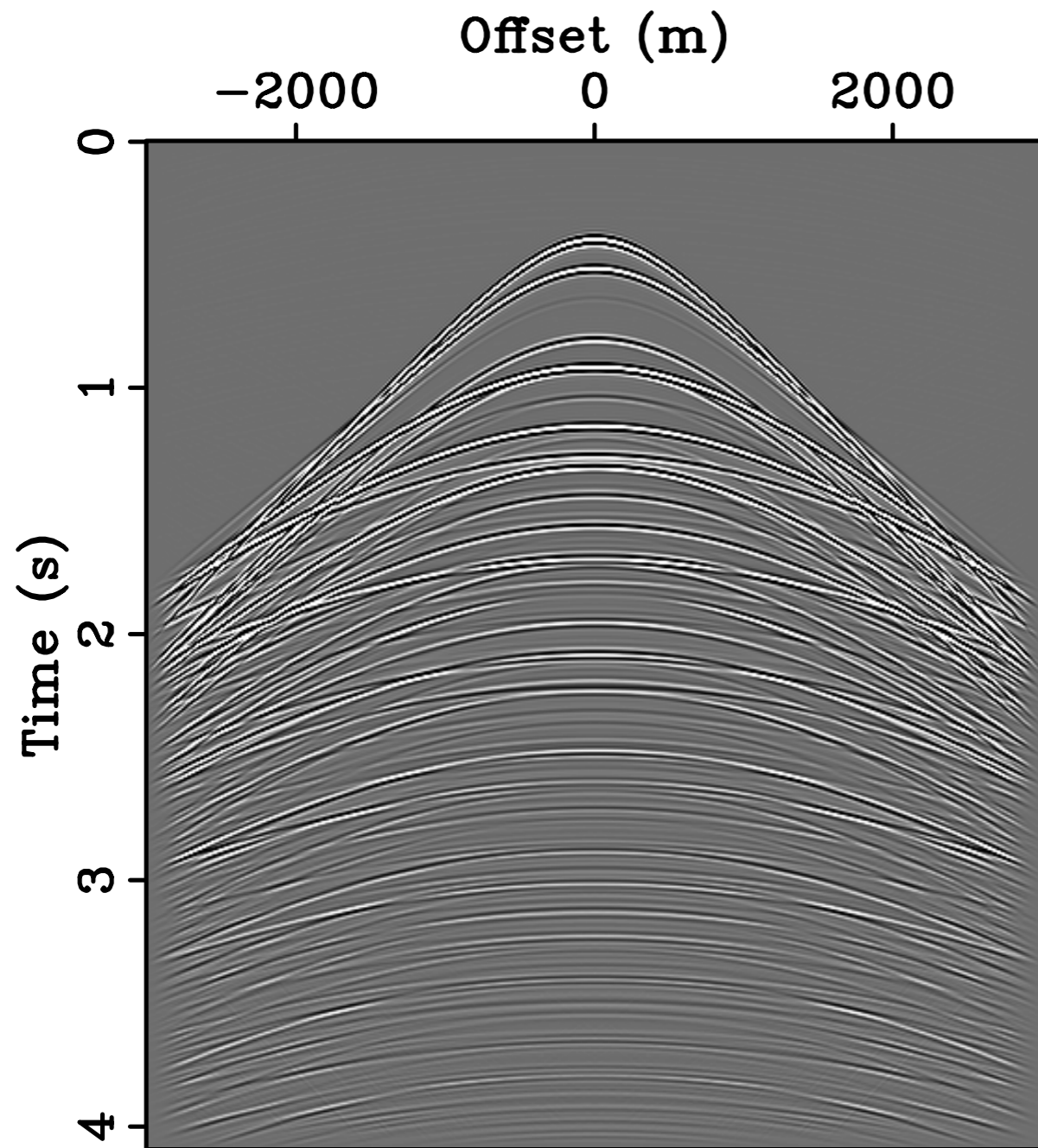
Curvelet Recovery w Sparsity-promoting Inversion

- Interpolated data given by $\tilde{\mathbf{f}} = \mathbf{C}^H \tilde{\mathbf{x}}$ with

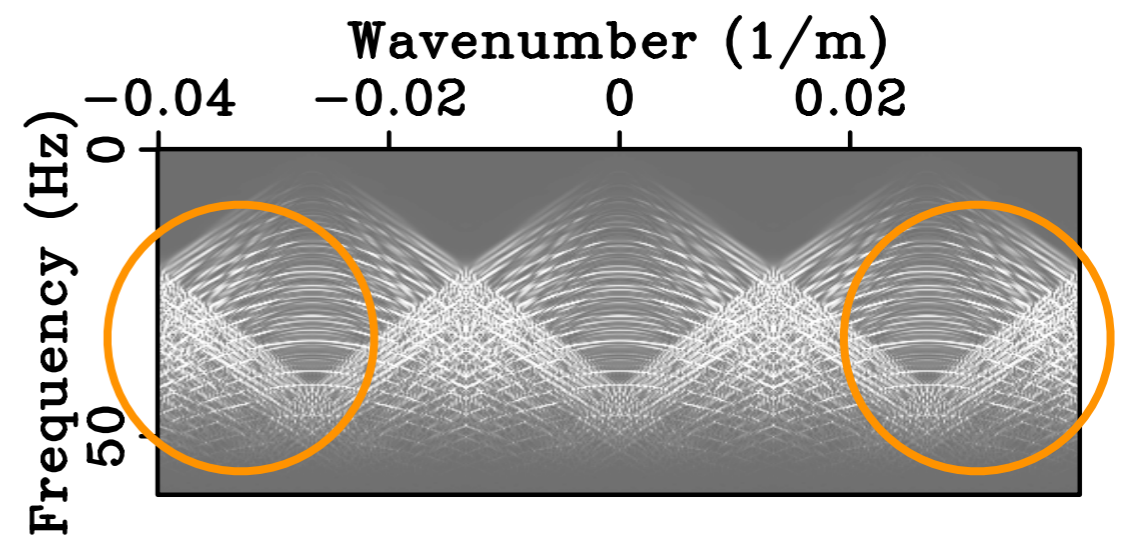
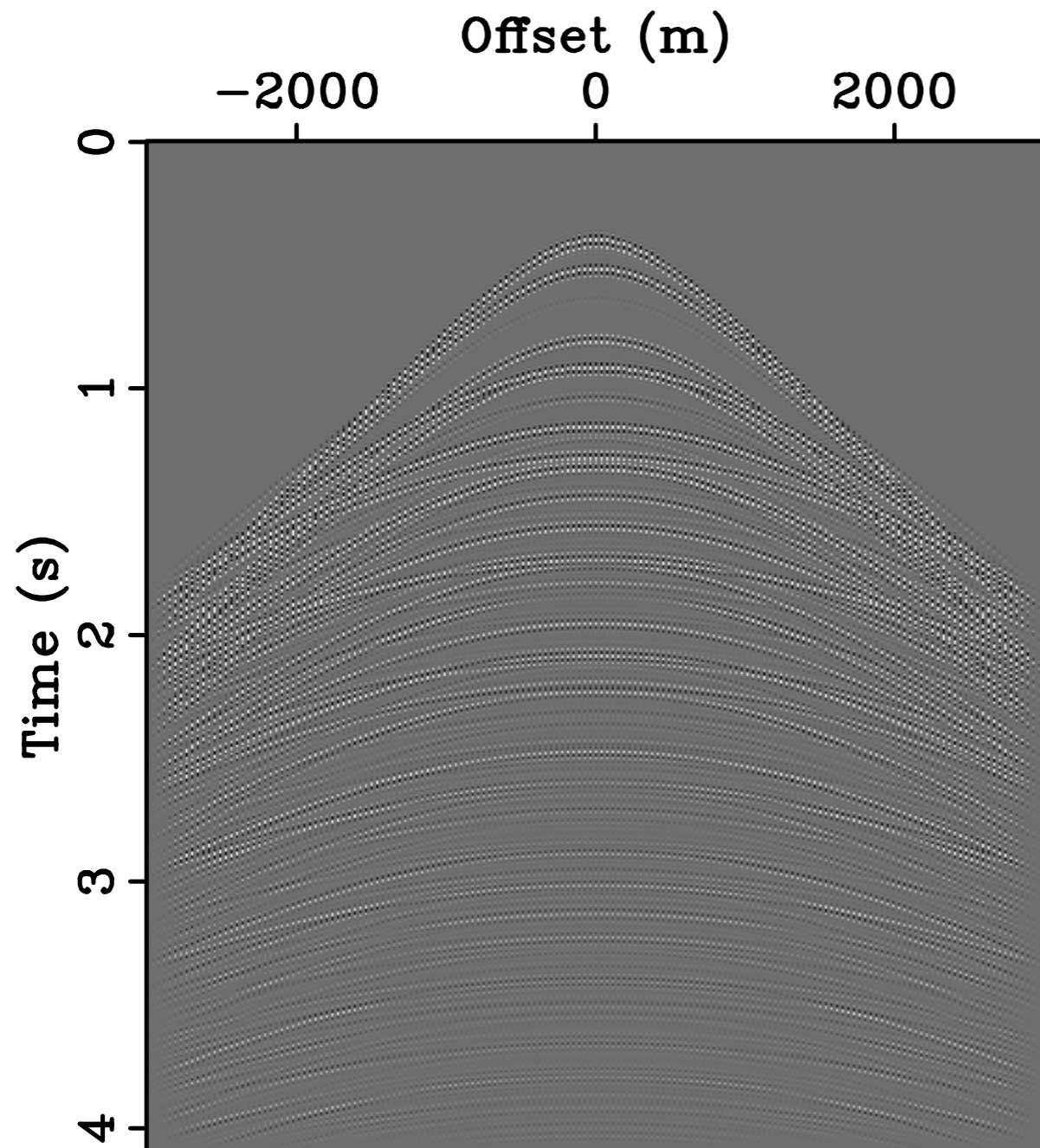
$$\tilde{\mathbf{x}} = \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = \mathbf{RC}^H \mathbf{x}$$

- sparsity-promoting solver
 - Iterative Soft Thresholding with cooling (ISTc)

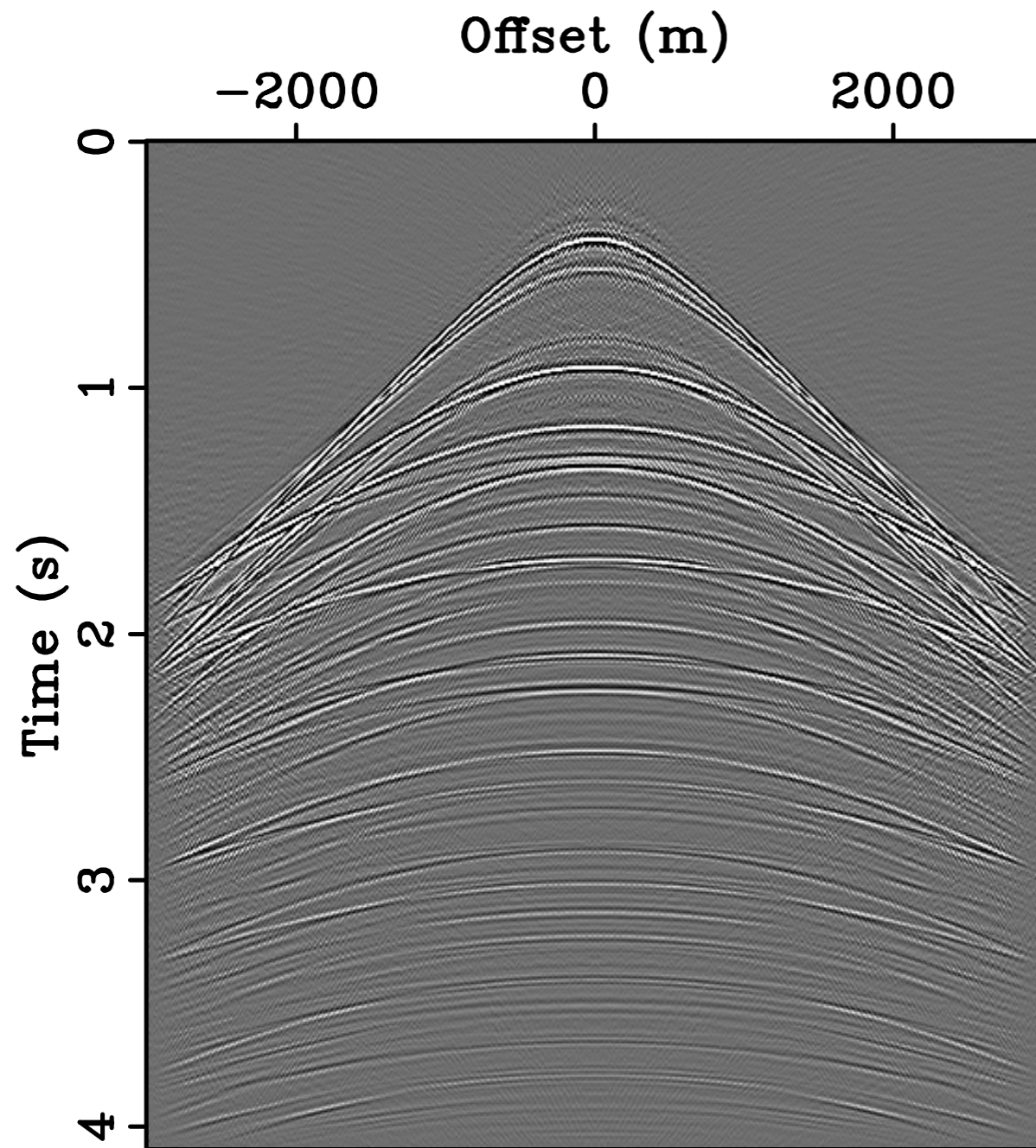
Model



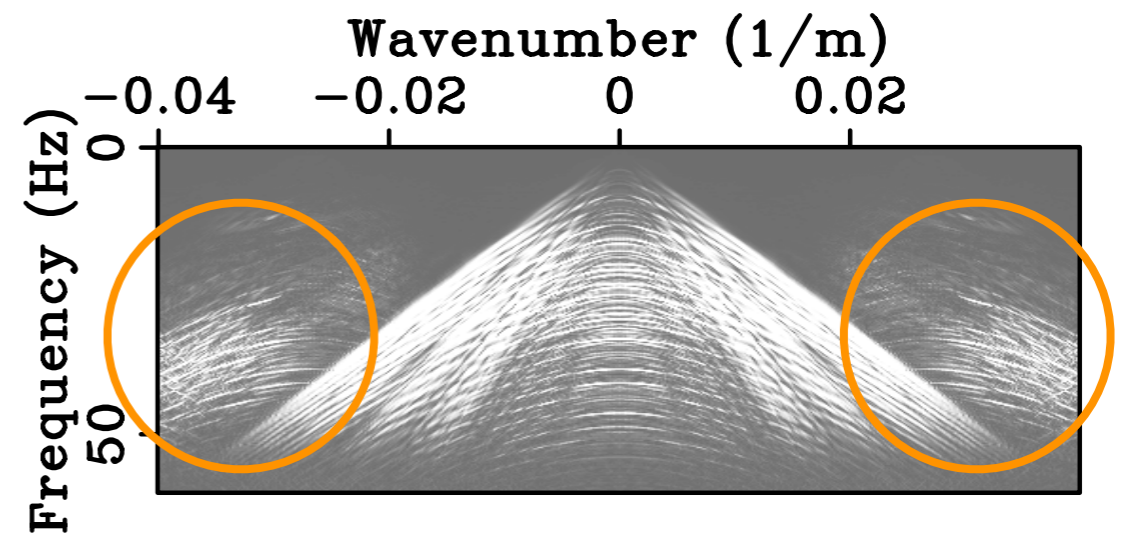
Regular 3-fold undersampling



CRSI from regular 3-fold undersampling

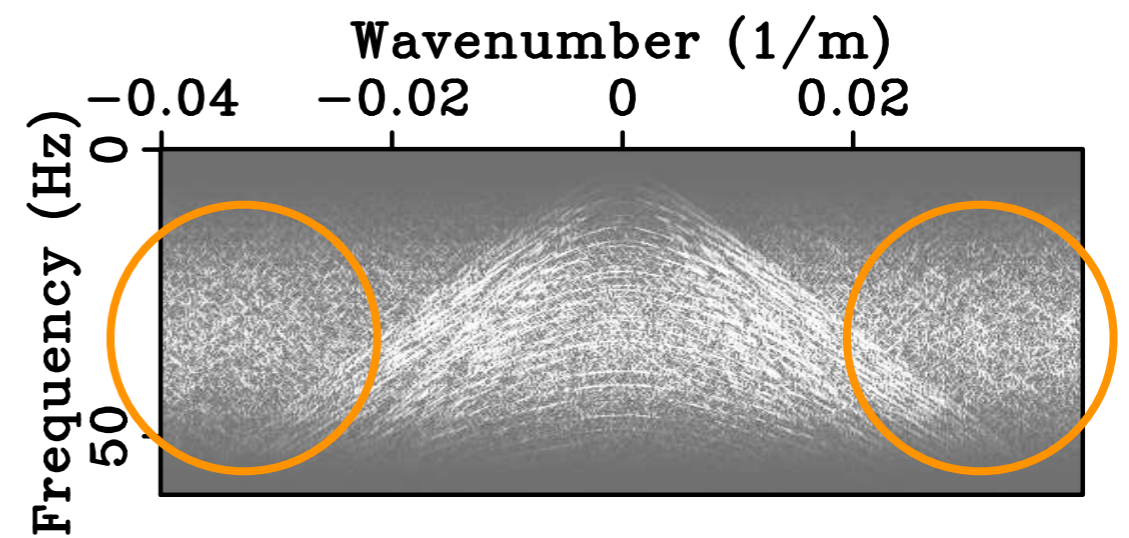
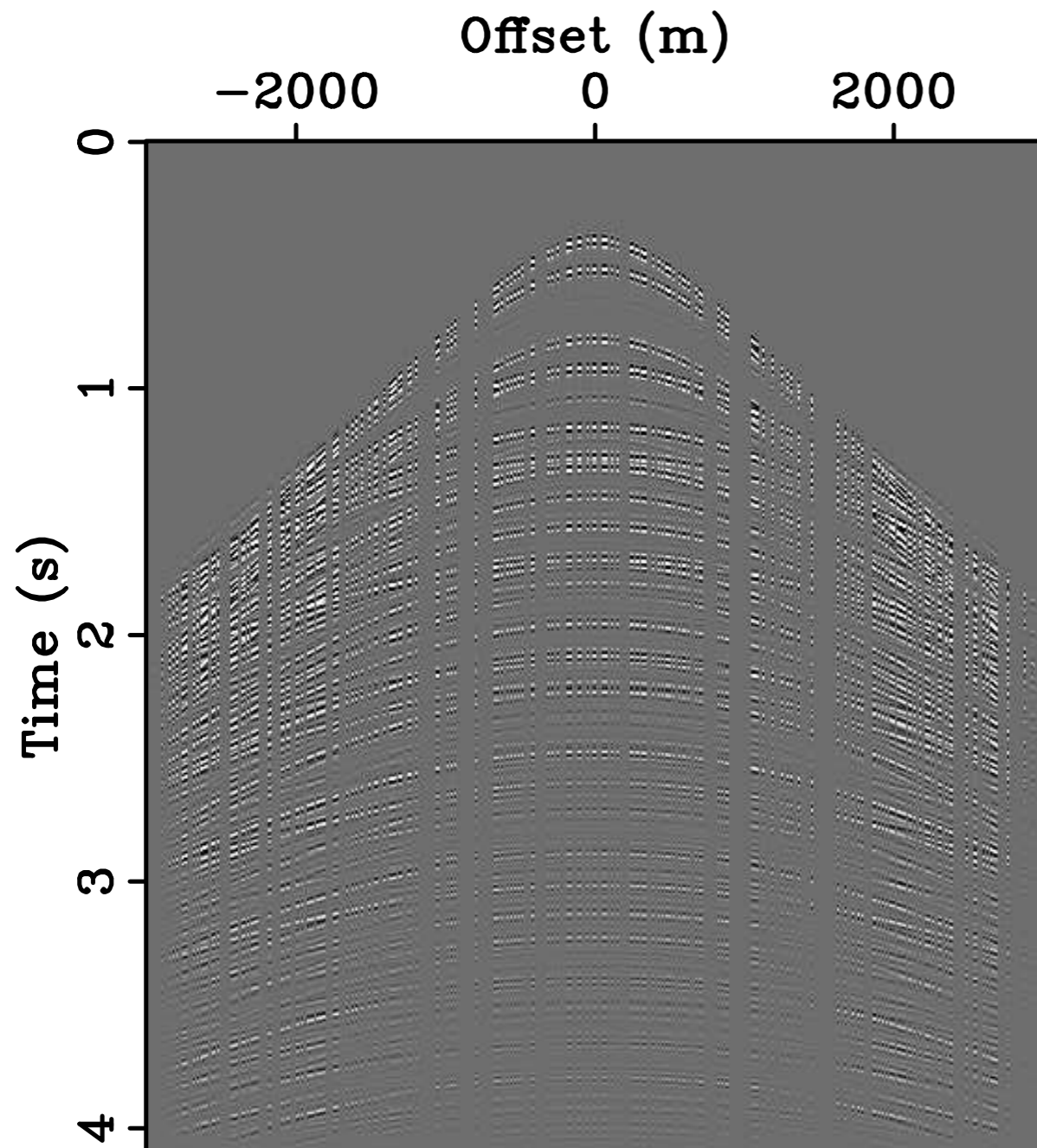


$SNR = 6.92 \text{ dB}$

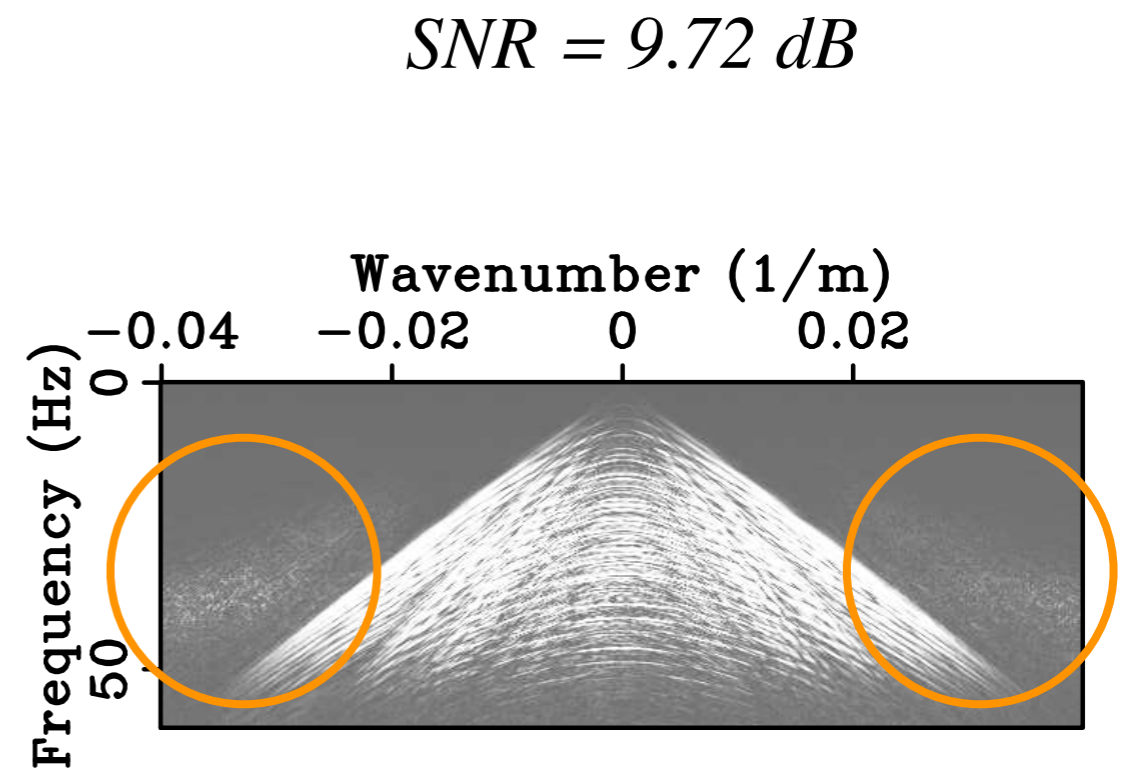
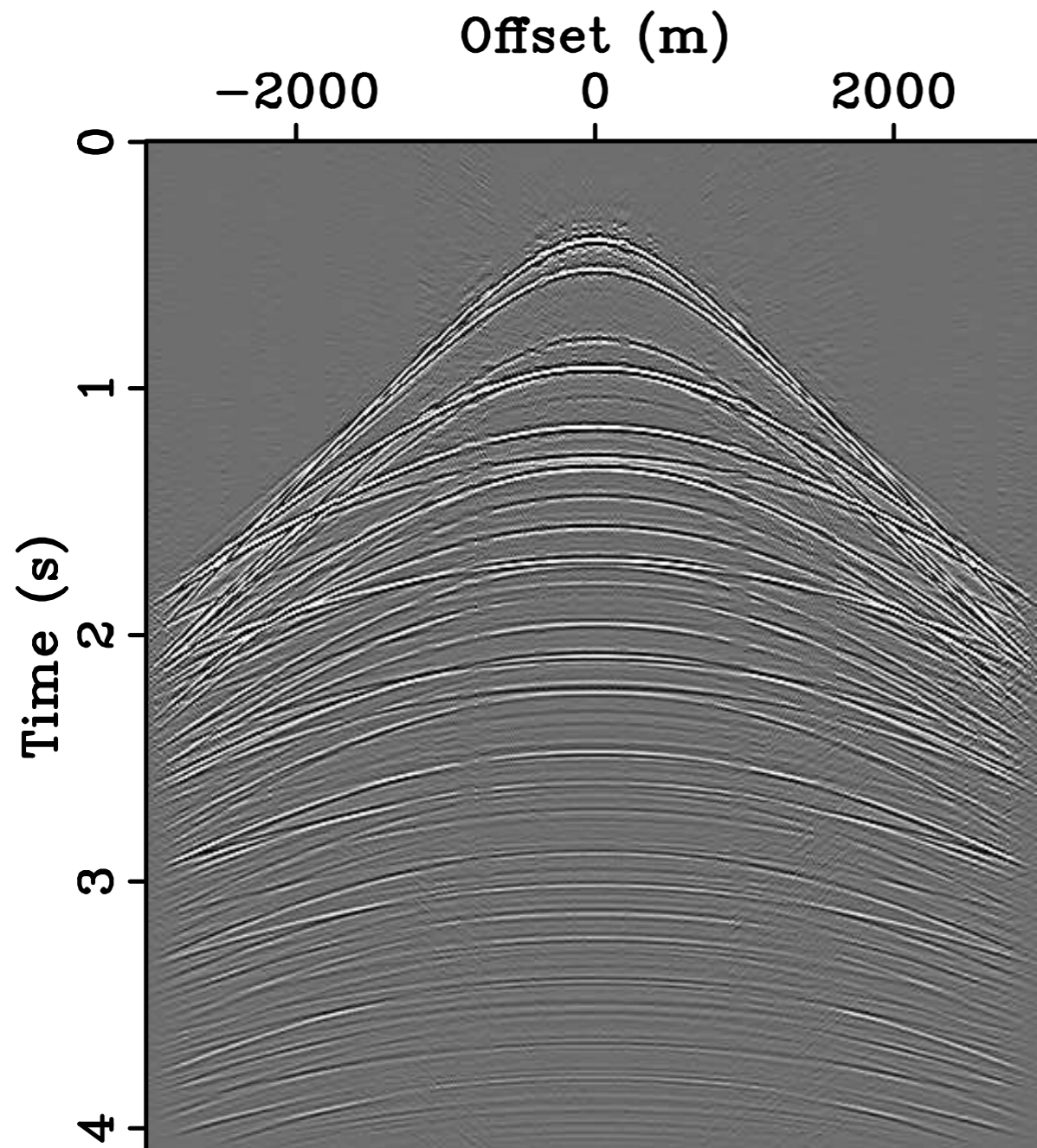


$$SNR = 20 \times \log_{10} \left(\frac{\|\text{model}\|_2}{\|\text{reconstruction error}\|_2} \right)$$

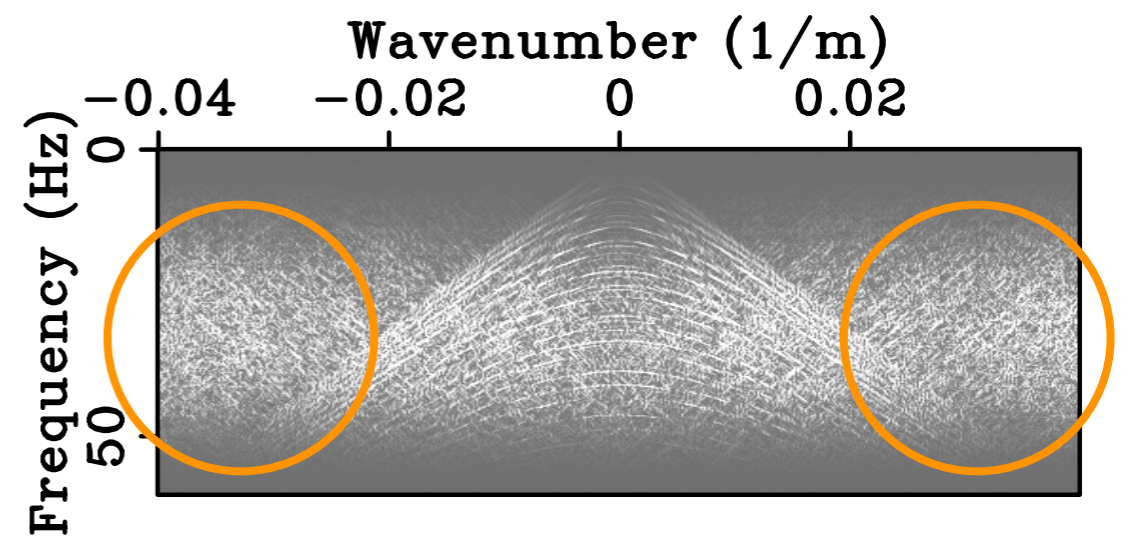
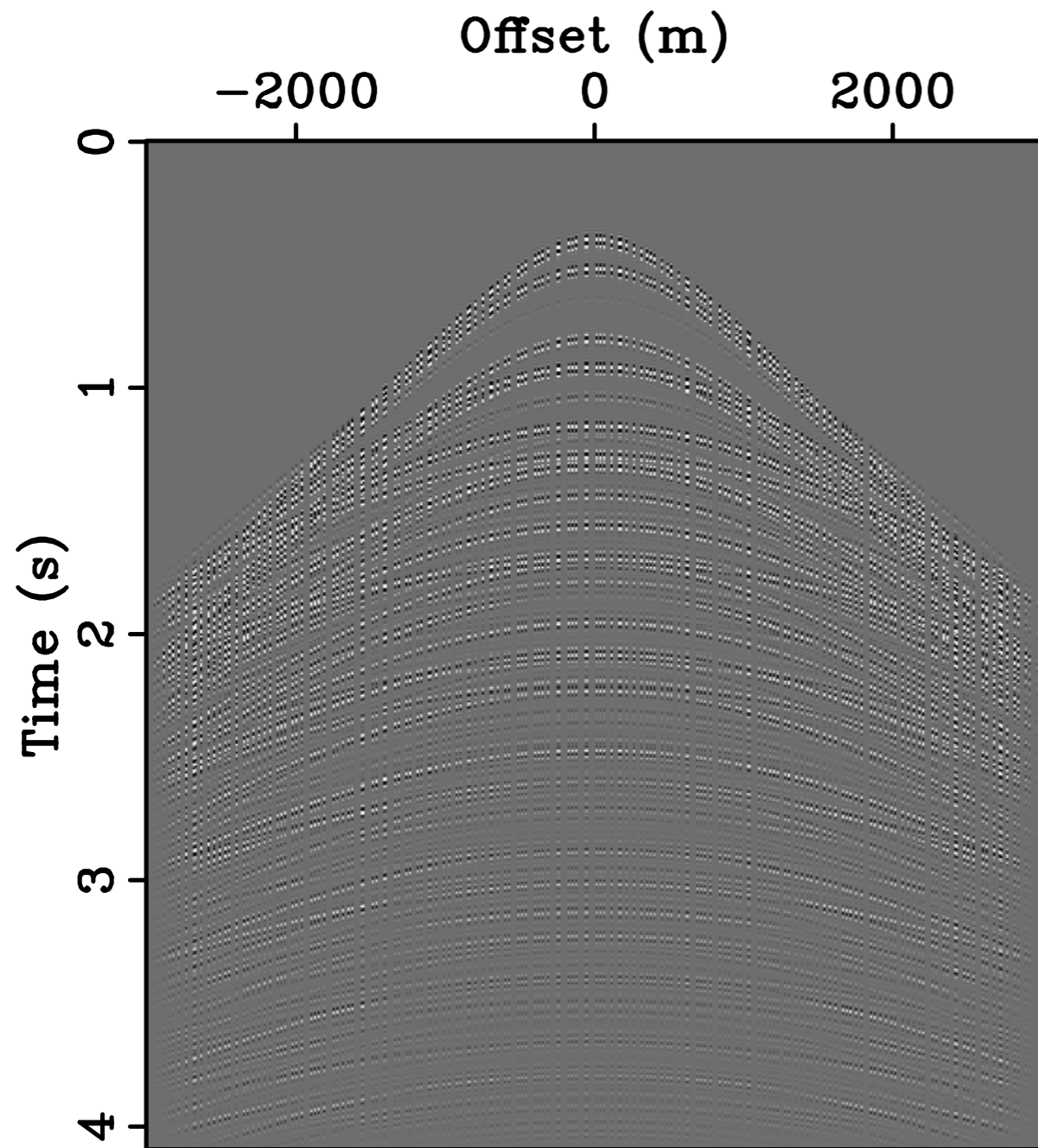
Random 3-fold undersampling



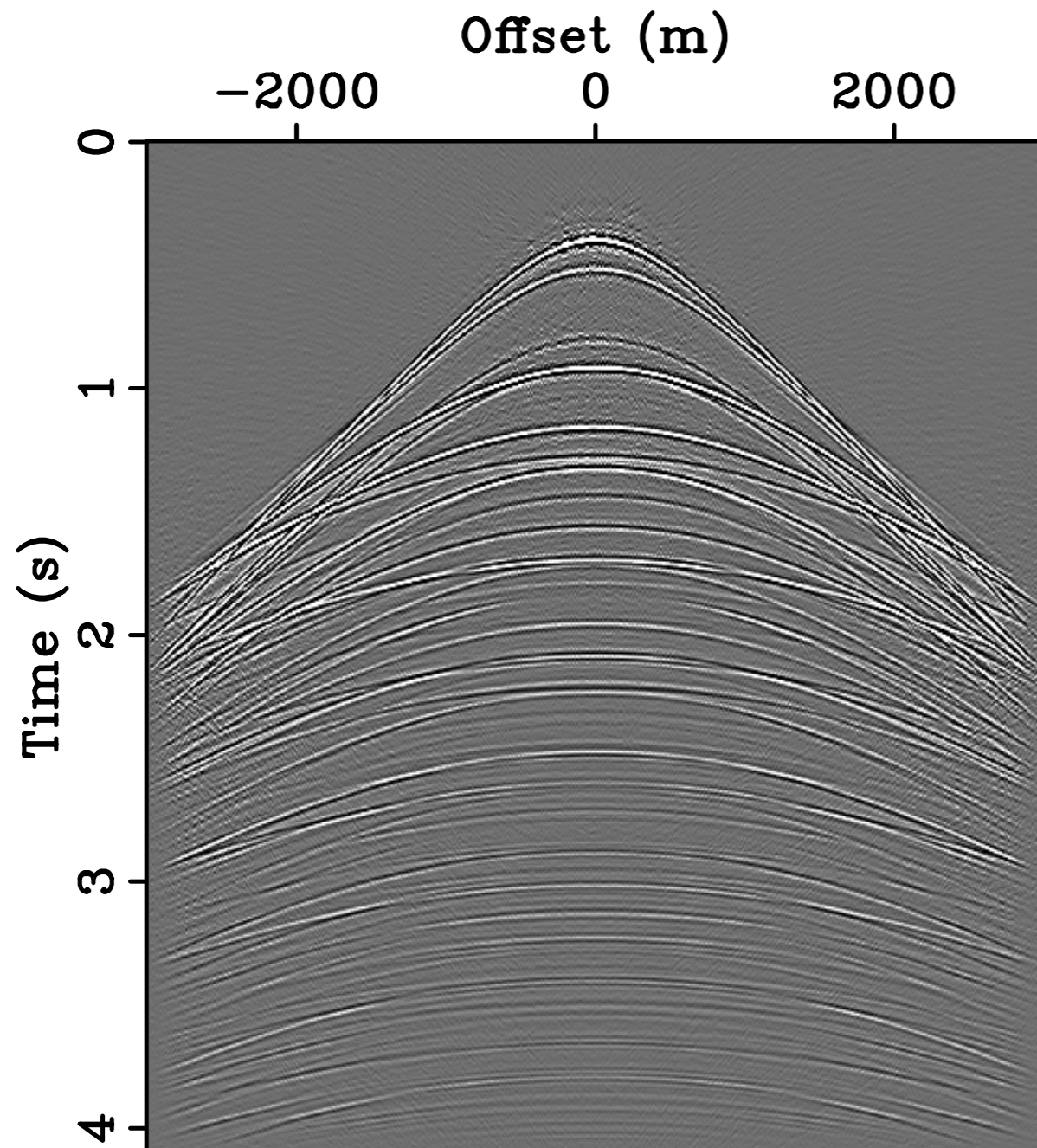
CRSI from random 3-fold undersampling



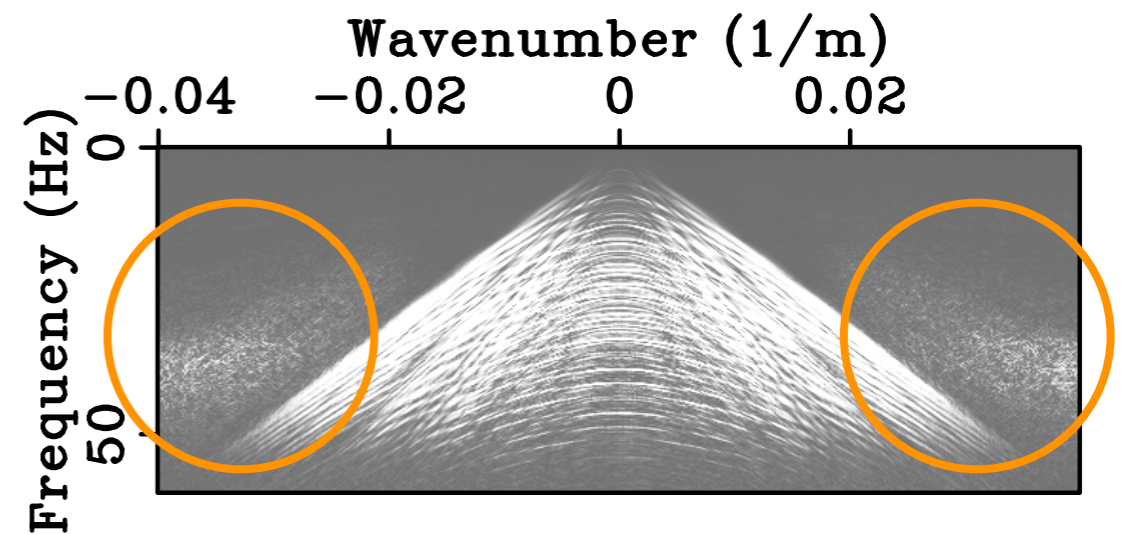
Optimally-jittered 3-fold undersampling



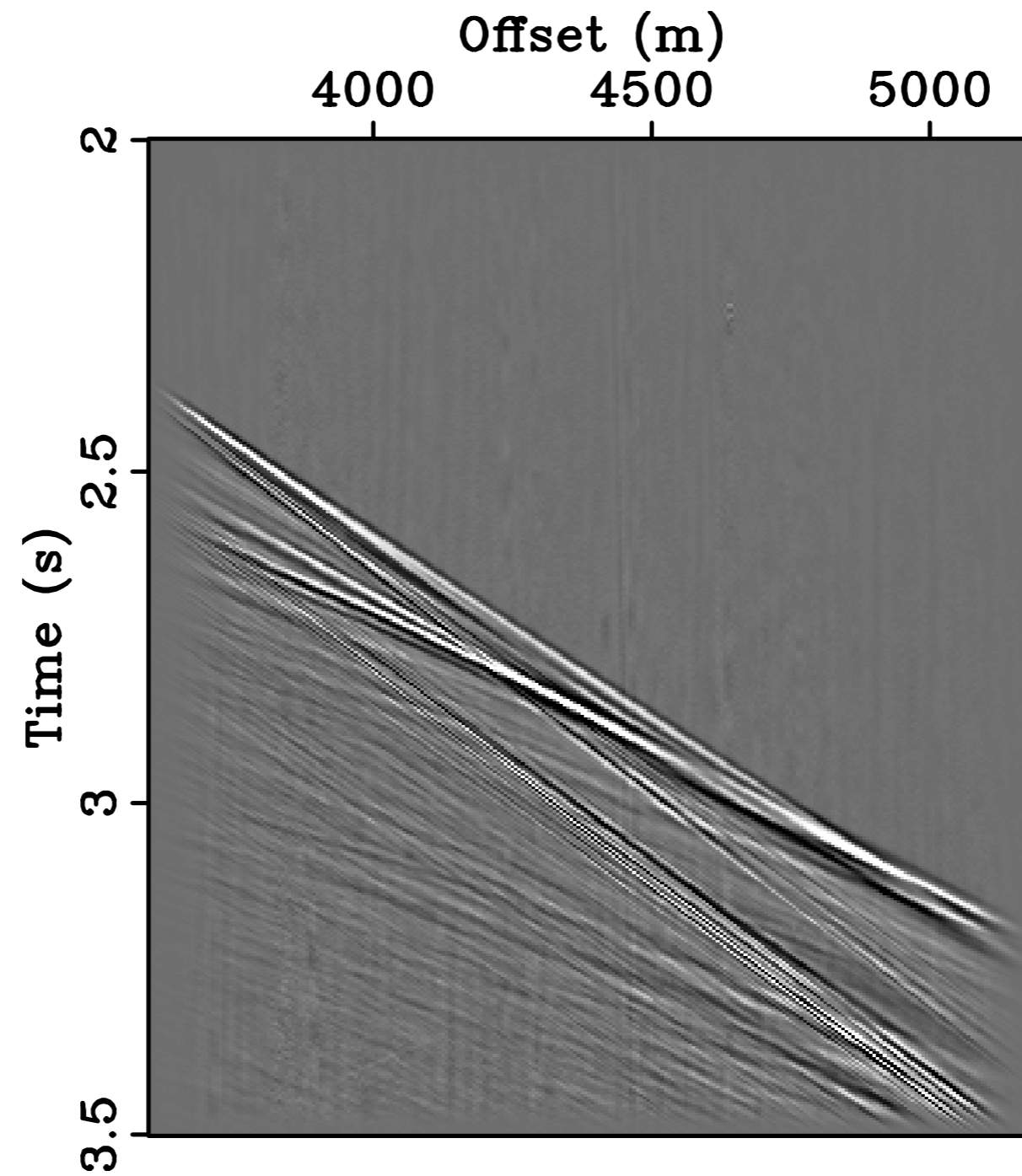
CRSI from opt.-jittered 3-fold undersampling



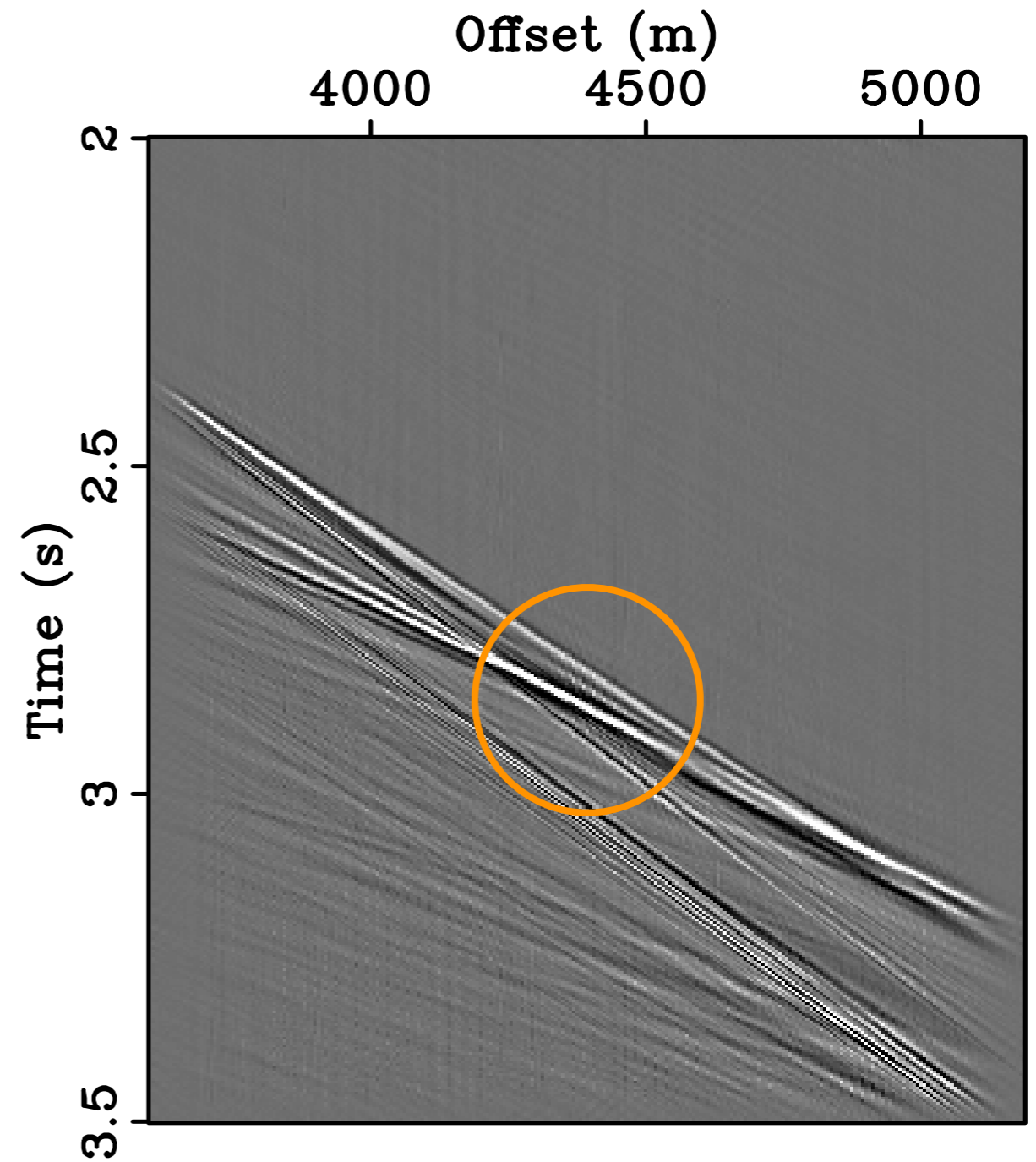
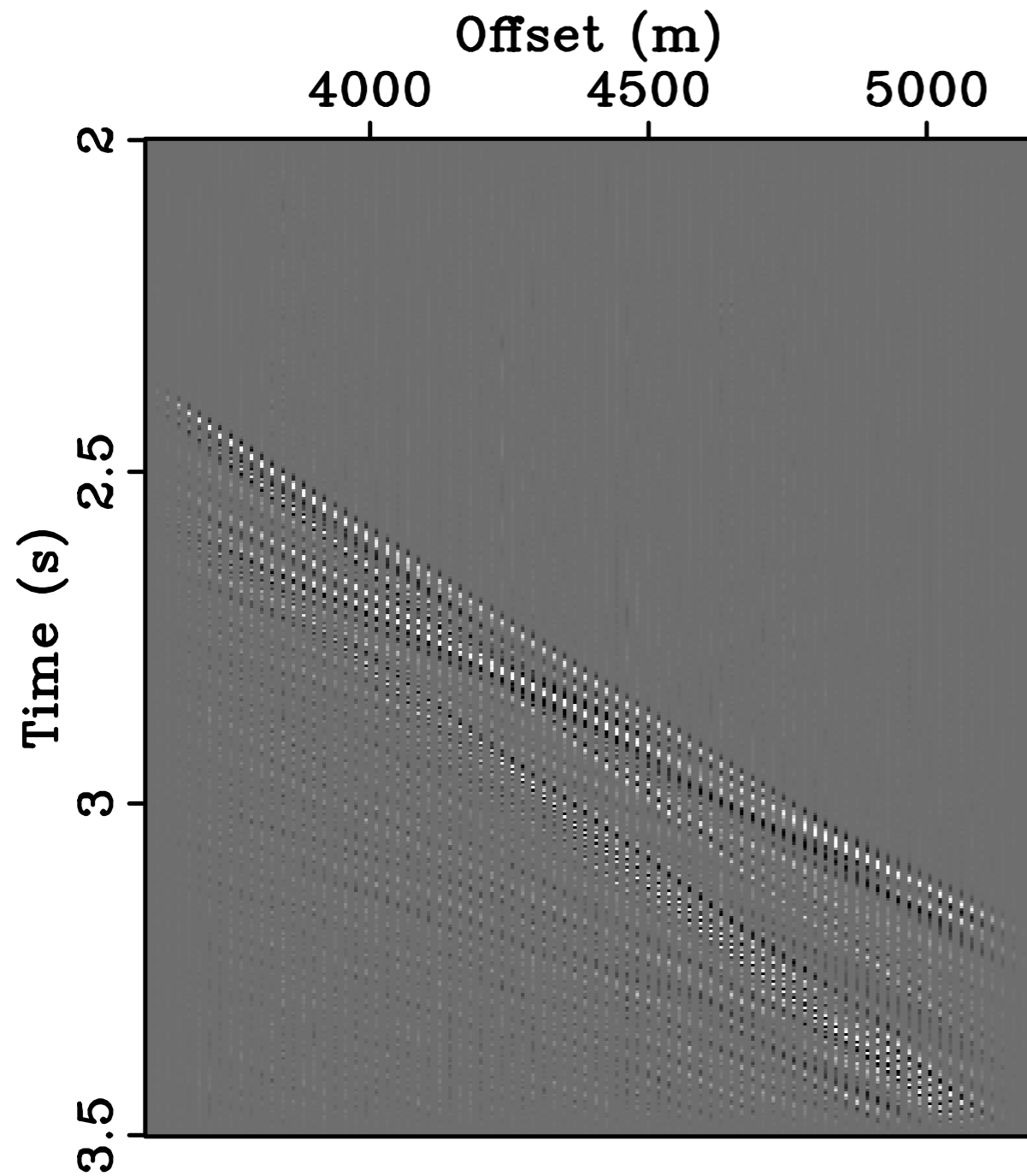
$SNR = 10.42 \text{ dB}$



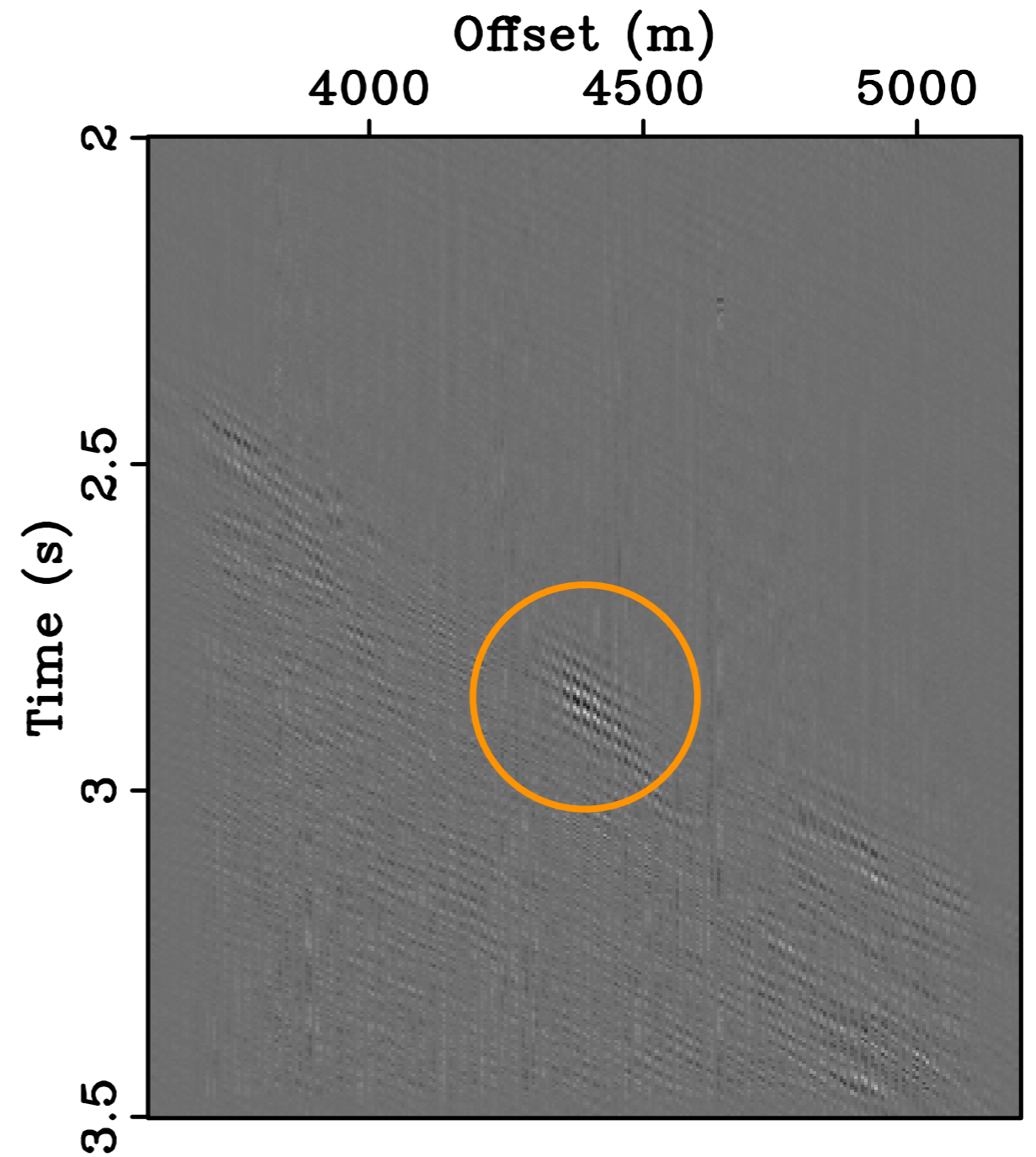
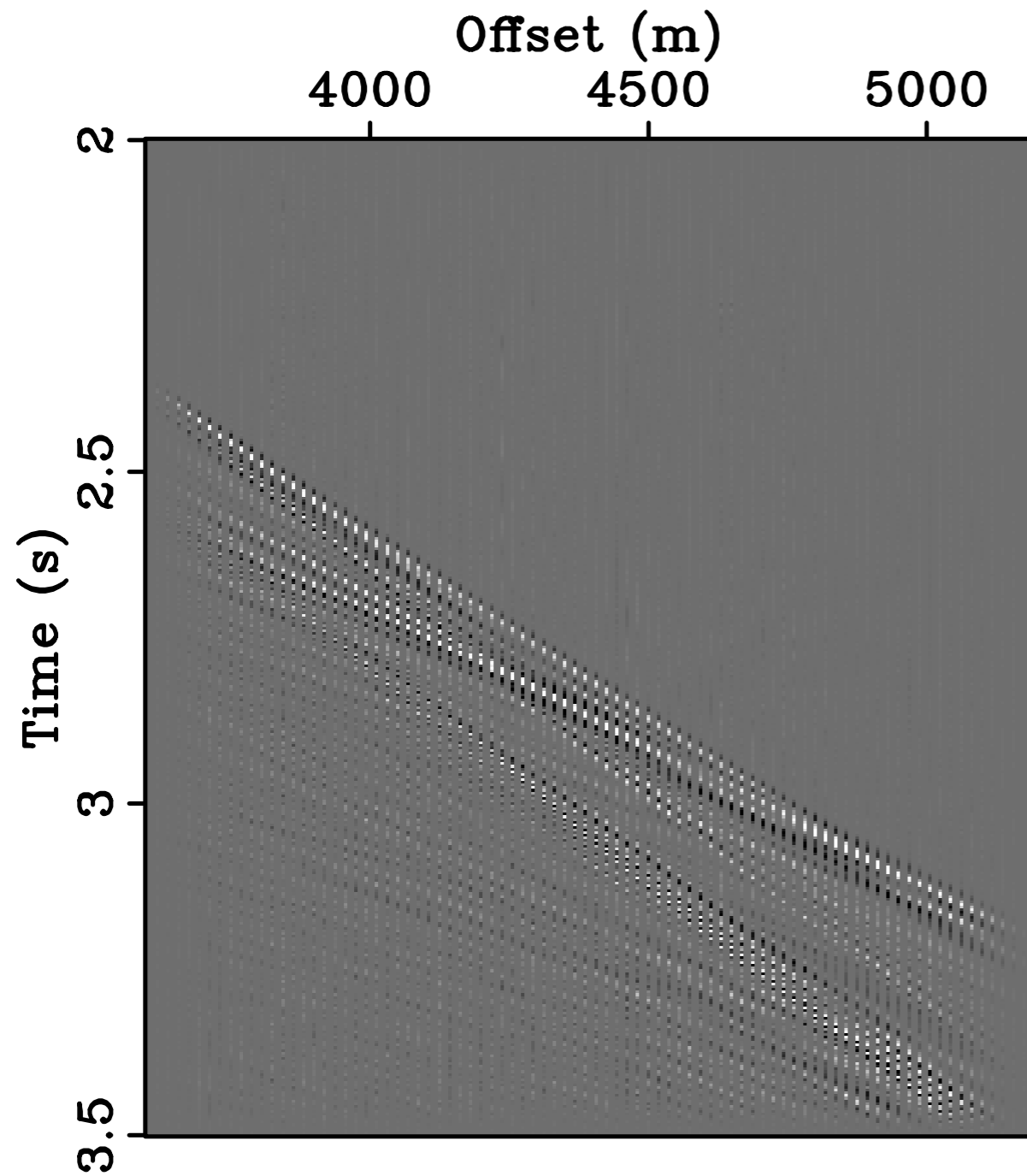
Model



Regular 3-fold undersampling

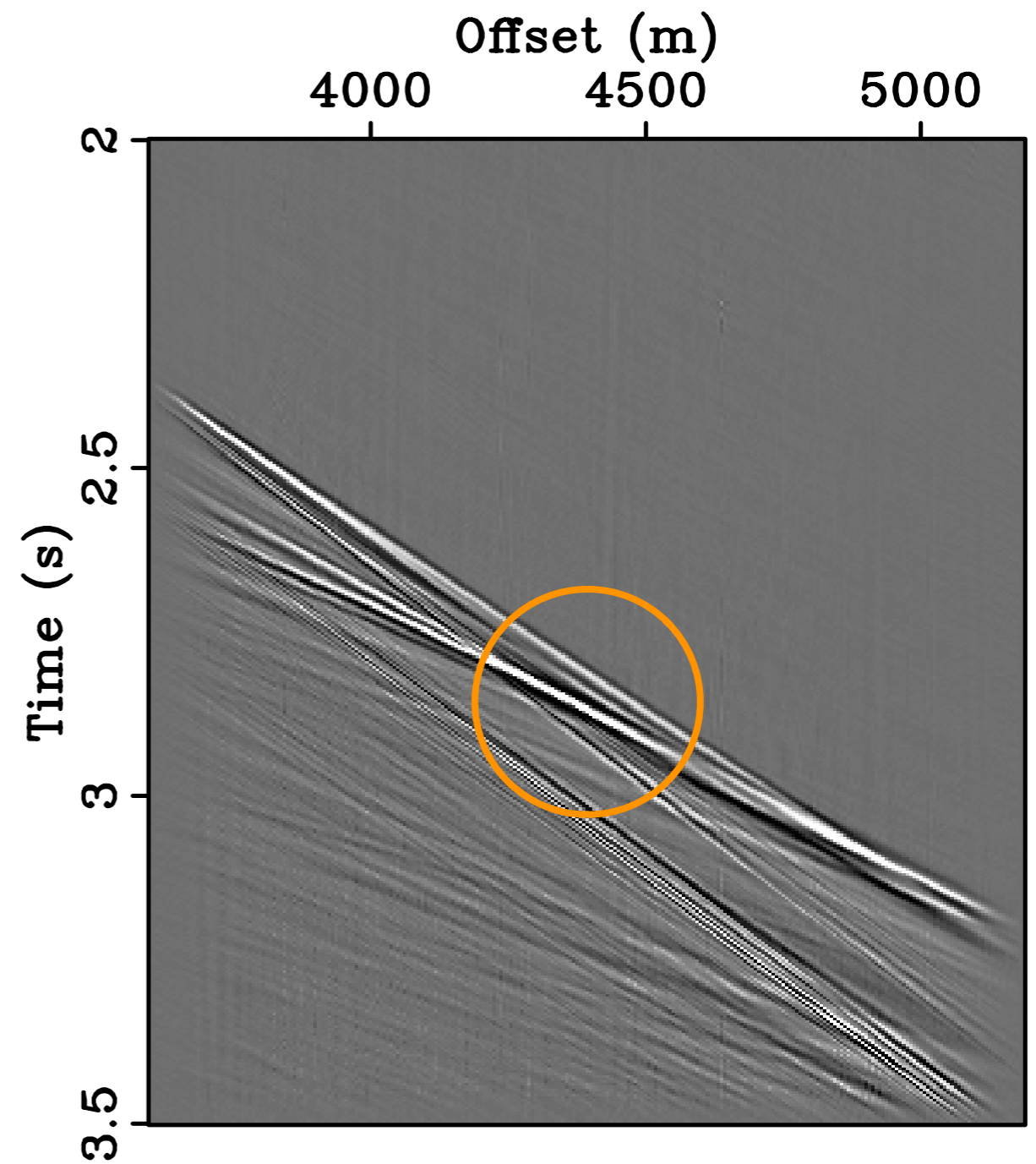
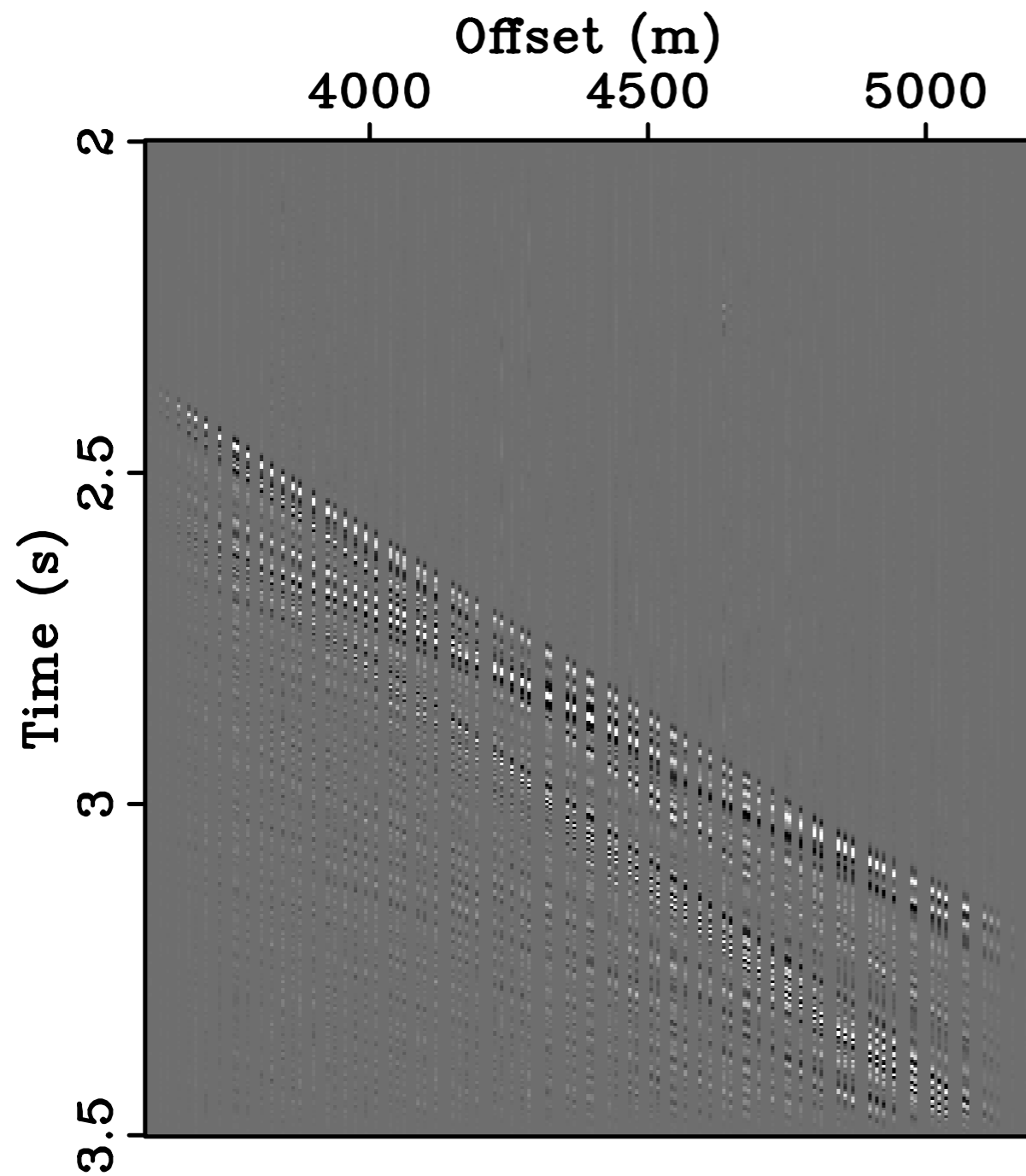


Regular 3-fold undersampling



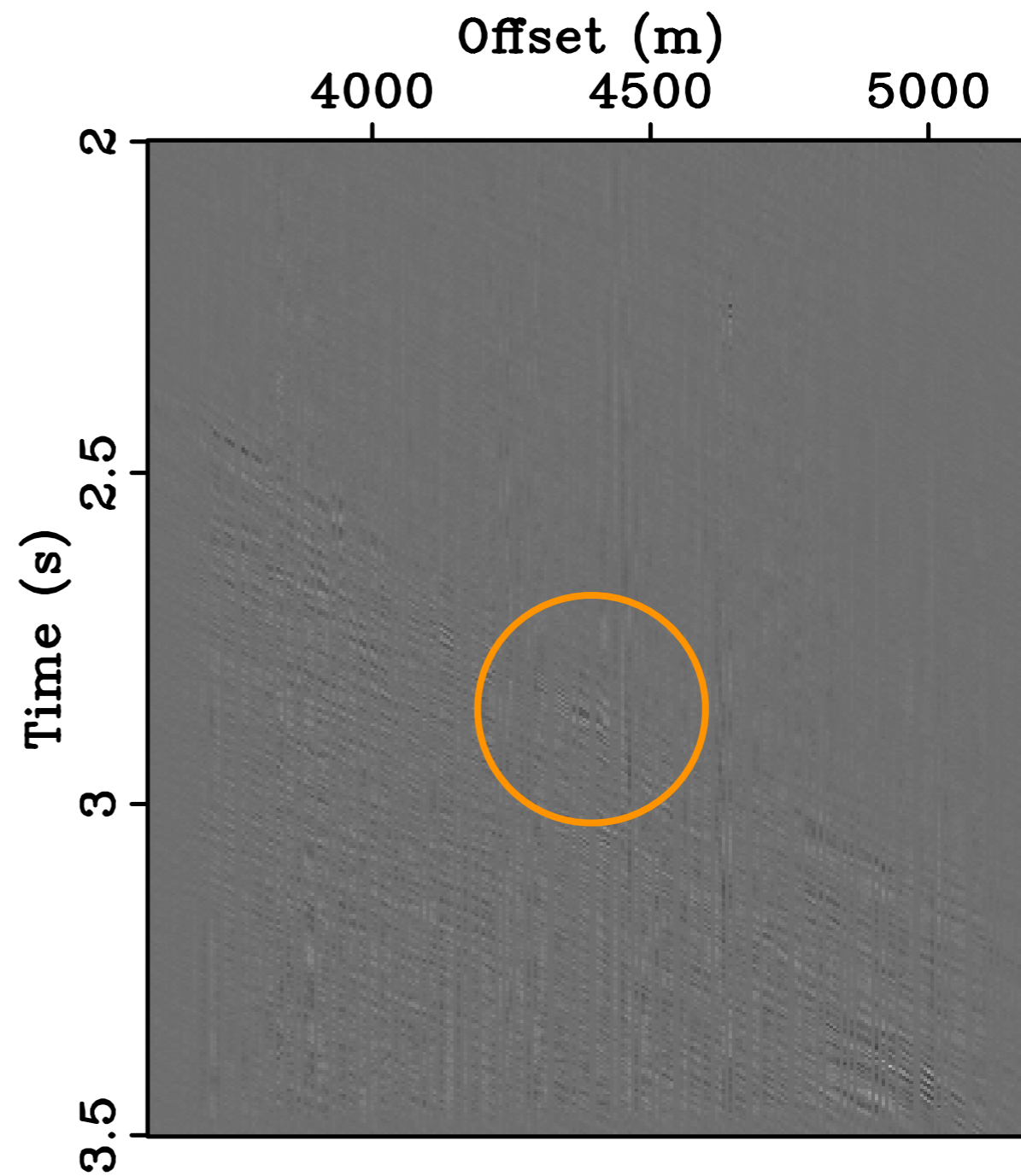
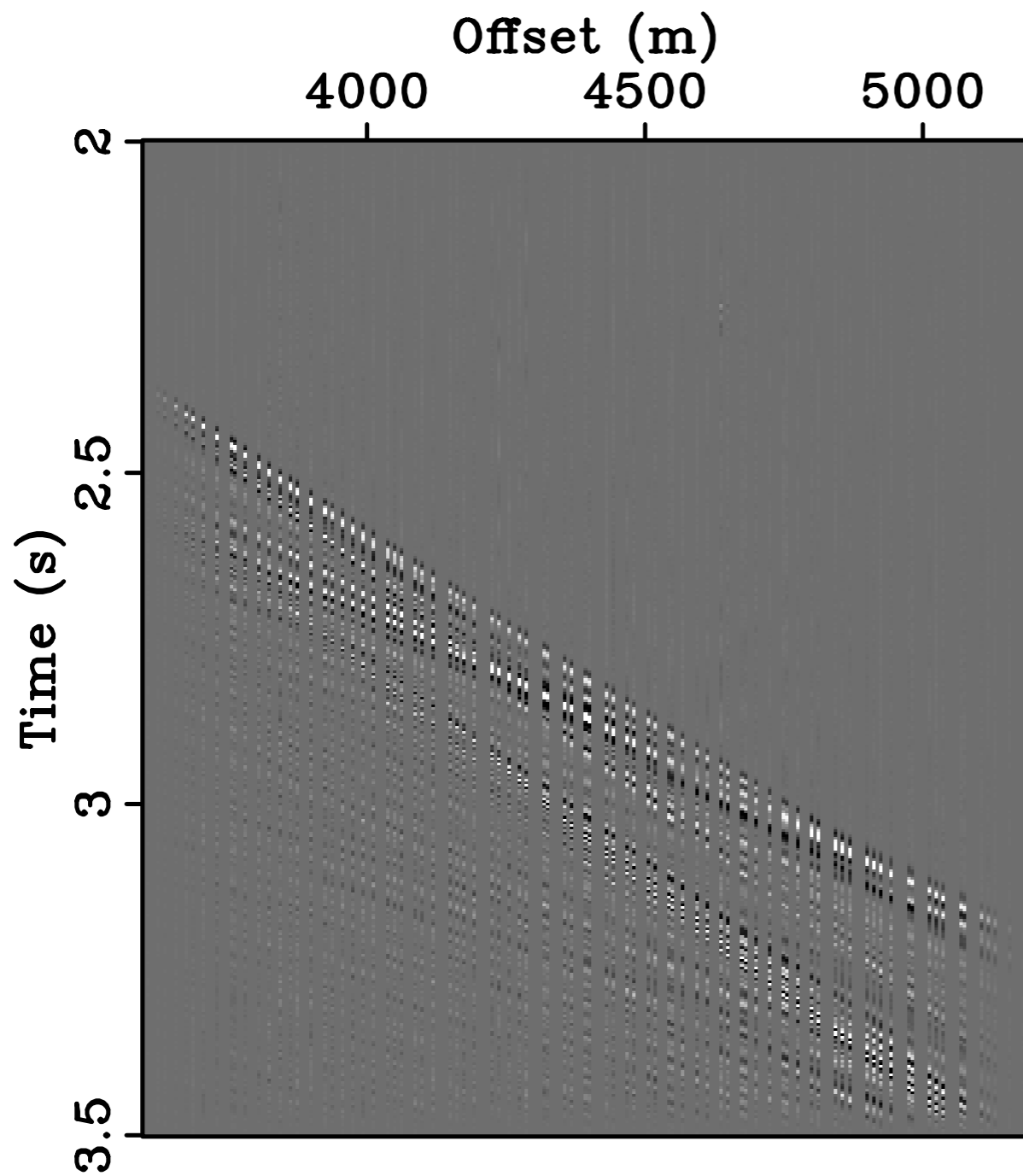
$SNR = 12.98 \text{ dB}$

Optimally-jittered 3-fold undersampling



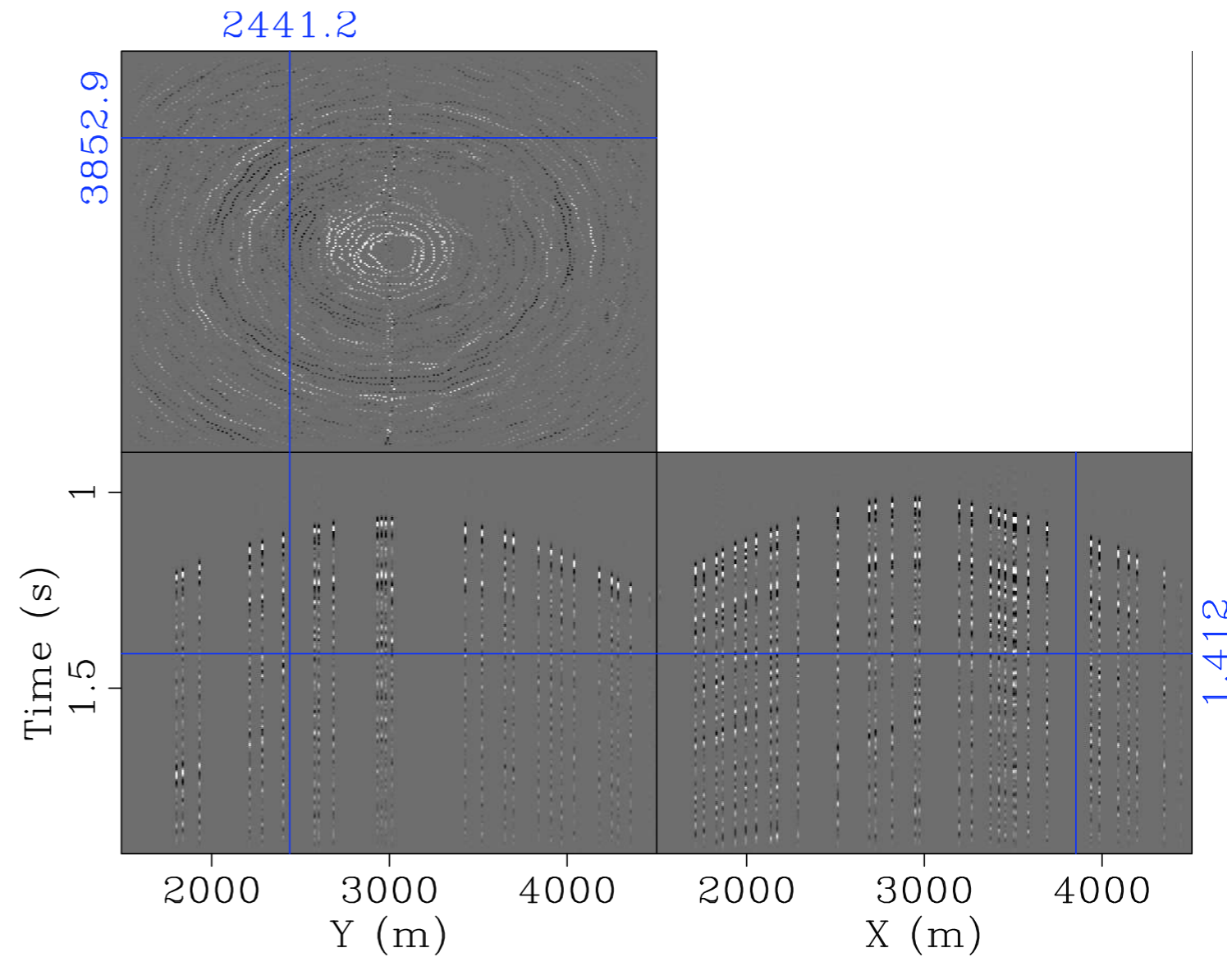
$SNR = 15.22 \text{ dB}$

Optimally-jittered 3-fold undersampling



Is jittered undersampling practical?

- field data
 - typ. irregularly sampled
 - no large gaps when possible

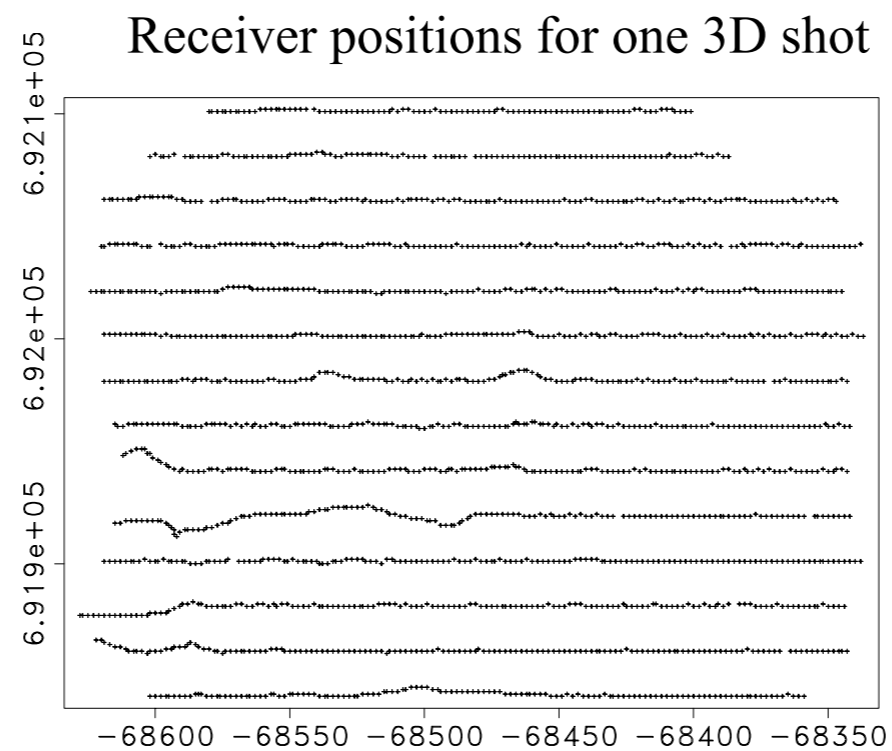


Conclusions

- *sparsity* is a powerful property that offers striking benefits for signal reconstruction BUT it is not enough
- in the sparsifying domain, *interpolation is a denoising problem*
 - regular undersampling:
harmful coherent undersampling “noise”, i.e., aliases
 - random & optimally-jittered undersamplings:
harmless incoherent random undersampling “noise”
- nonlinear wavefield sampling
 - sparsifying transform: **curvelet transform**
 - coarse sampling scheme: **optimally-jittered undersampling**
 - sparsity-promoting solver: **iterative soft thresholding with cooling**

Future work

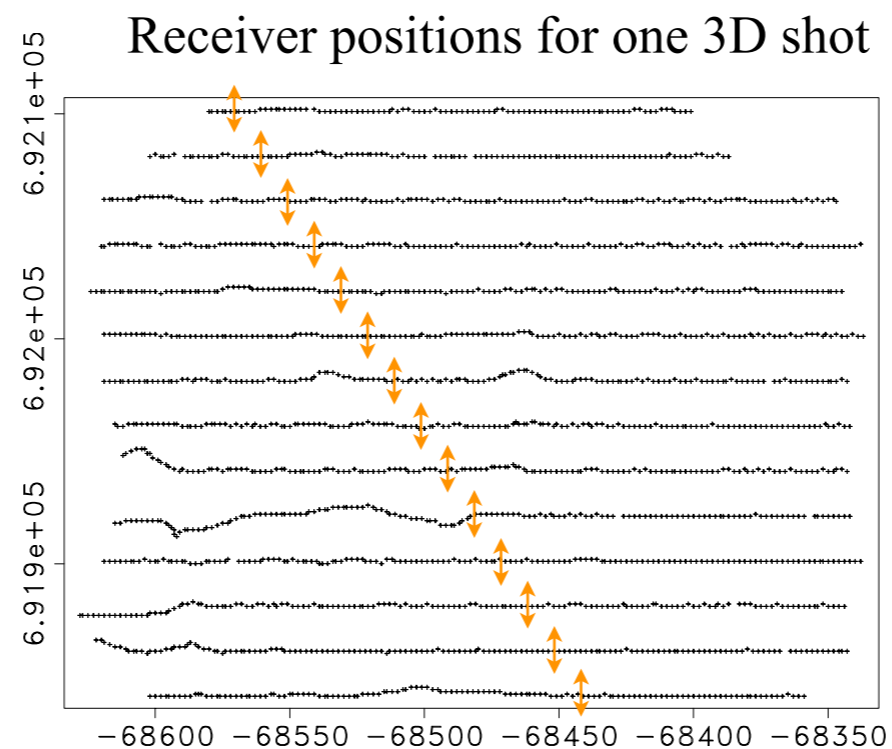
- translate jittered undersampling into **practical** acquisition geometries
 - 2D
 - regular receiver positions, jittered source positions?
 - 3D
 - jittered receiver lines, jittered source positions?



- work on **deterministic AND practical** undersampling schemes

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 - 2D
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 - 3D
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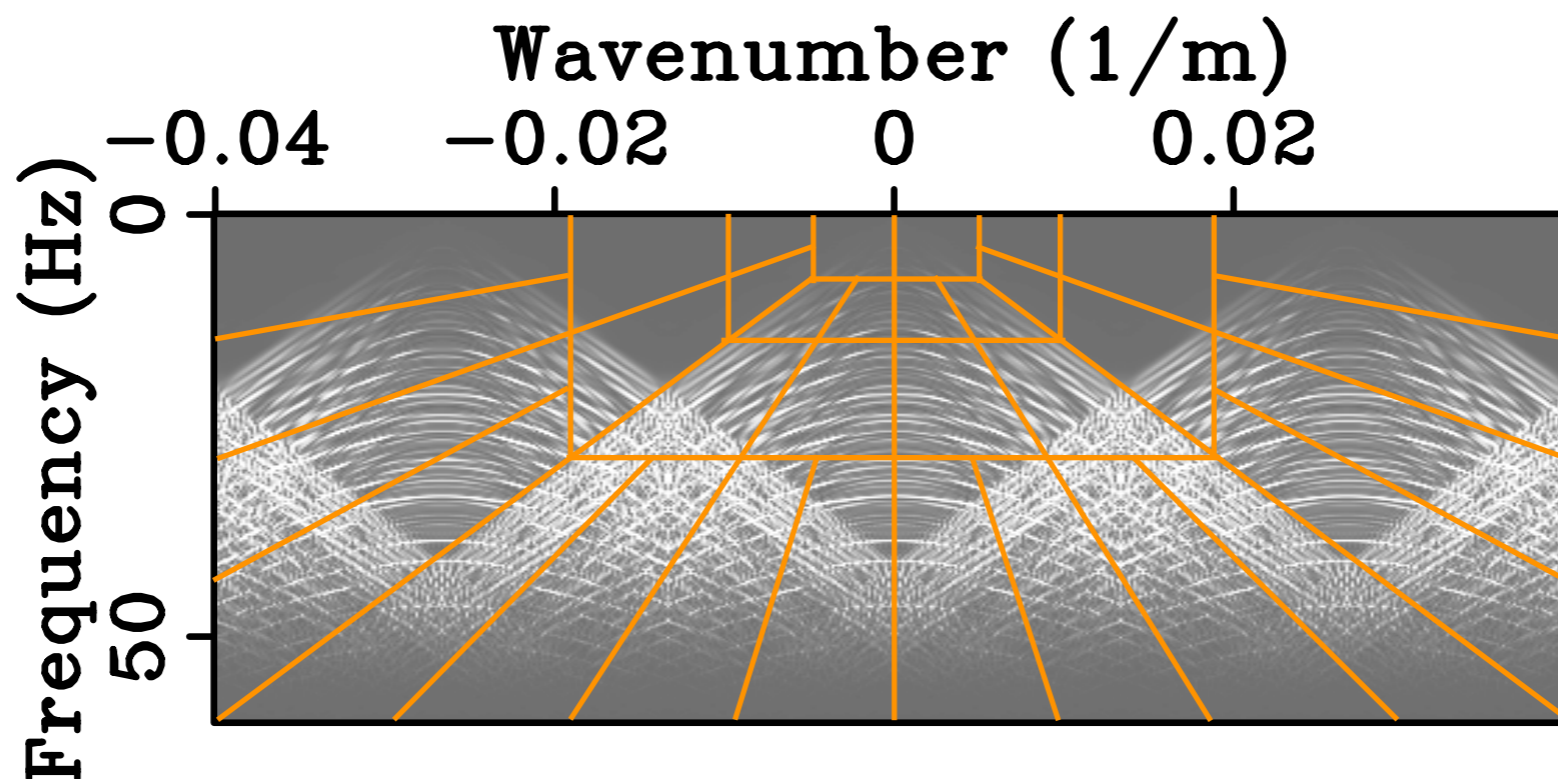


- work on **deterministic AND practical** undersampling schemes

More future work

- CRSI & regular undersampling
 - explore neighbourhood in phase-space to break aliasing

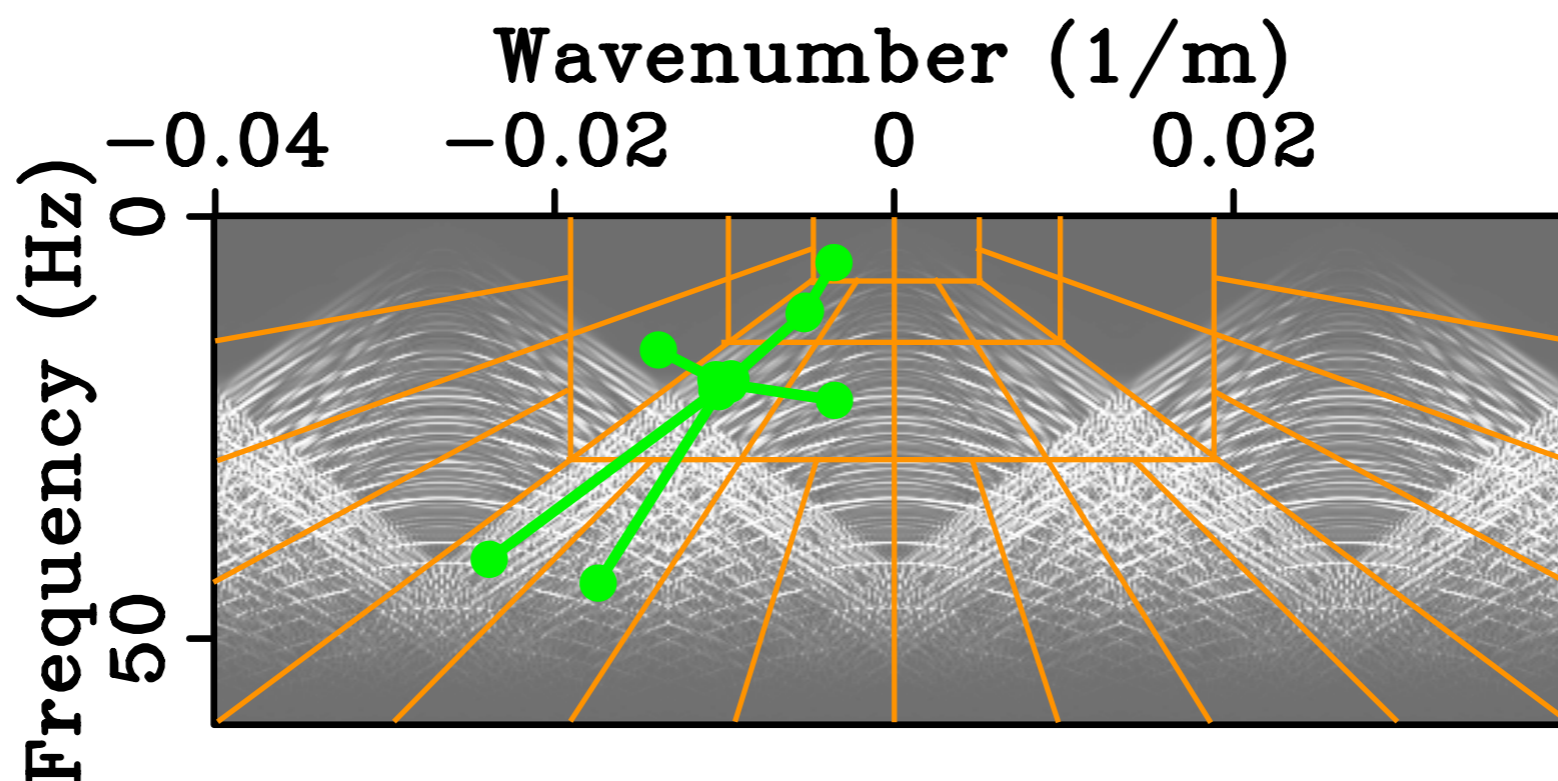
$$\min_{\mathbf{x}} \frac{1}{2} \underbrace{\|\mathbf{y} - \mathbf{RC}^H \mathbf{x}\|_2^2}_{\text{data misfit}} + \lambda_1 \underbrace{\|\mathbf{x}\|_1}_{\text{sparsity}} + \lambda_2 \underbrace{\|\mathbf{Lx}\|_2}_{\text{smooth neighbourhood}}$$



More future work

- CRSI & regular undersampling
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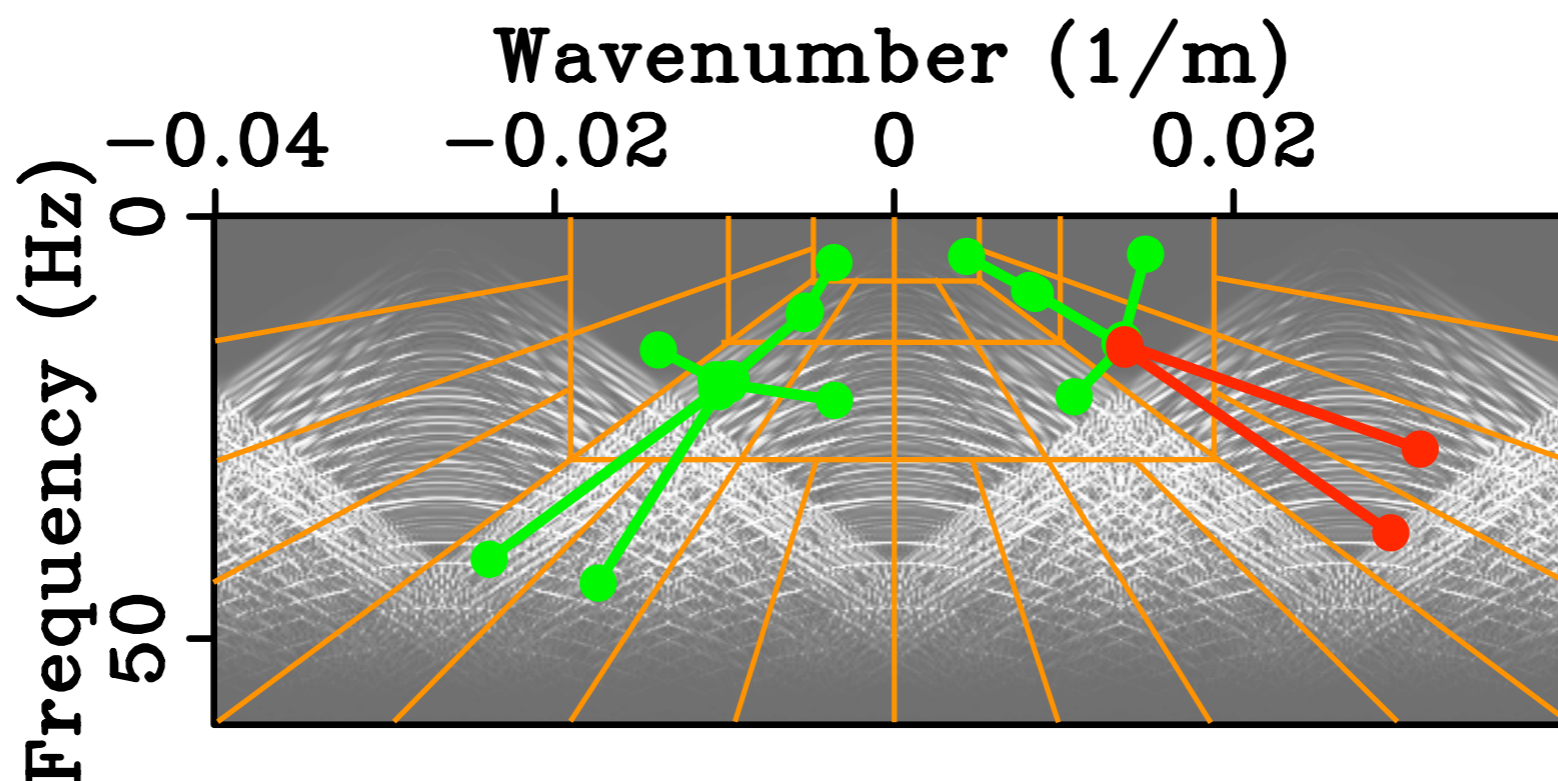
$$\min_{\mathbf{x}} \frac{1}{2} \underbrace{\|\mathbf{y} - \mathbf{RC}^H \mathbf{x}\|_2^2}_{\text{data misfit}} + \lambda_1 \underbrace{\|\mathbf{x}\|_1}_{\text{sparsity}} + \lambda_2 \underbrace{\|\mathbf{Lx}\|_2}_{\text{smooth neighbourhood}}$$



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 - S. Ross Ross, H. Modzelewski, and C. Brown for SLIMpy (slim.eos.ubc.ca/SLIMpy)
- D. J. Verschuur for the synthetic dataset
- Chevron and Norsk Hydro for the real datasets
- E. J. Candès, L. Demanet, D. L. Donoho, and L. Ying for CurveLab (www.curvelet.org)
- S. Fomel, P. Sava, and the other developers of Madagascar (rsf.sourceforge.net)

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