

CAIMS Annual Meeting

21 May 2007

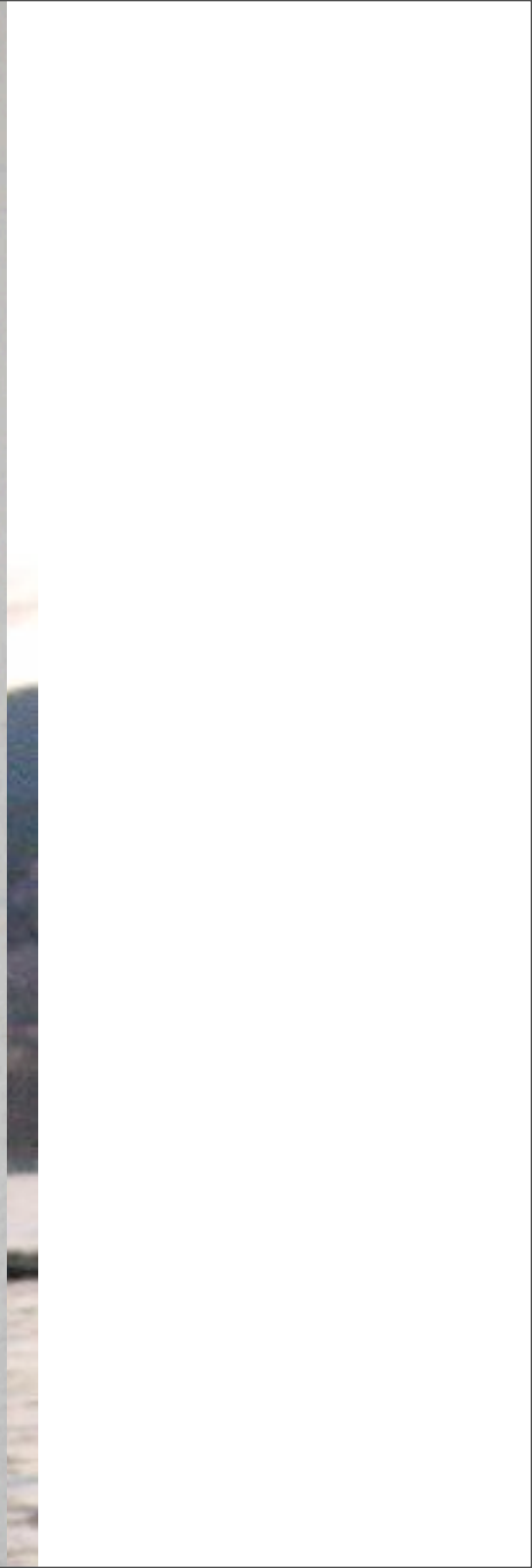
In Pursuit of a Root

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UBC Computer Science

[Felix Herrmann (UBC), Ozgur Yilmaz (UBC), Michael Saunders (Stanford)]

$$\begin{array}{ll} \underset{x}{\text{minimize}} & \|x\|_1 \\ \text{subject to} & \|Ax - b\|_2 \leq \sigma \end{array}$$



Generic Regularization

$$\boxed{A} \quad x \approx b$$

Infinitely many solutions

- Encourage stability of solution
- Choose a solution with favorable properties

eg, **sparsity**

Regularization approaches

1. minimize $\|x\|$ subj to $\|Ax - b\| \leq \sigma$
2. minimize $\|Ax - b\|$ subj to $\|x\| \leq \lambda$
3. minimize $\|Ax - b\| + \tau\|x\|$

Sparse Solutions

$\|x\|_0 := \text{sparsity} := \text{number of nonzeros in } x$

The **sparsest** solution is given by

$$\begin{array}{ll} \underset{x}{\text{minimize}} & \|x\|_0 \\ \text{subject to} & \|Ax - b\|_2 \leq \sigma \end{array}$$

Drawbacks

- Combinatorial problem: NP hard
- Tractable for only trivial problems

Alternative

Replace $\|x\|_0$ with $\|x\|_1$

[Chen et al'98], [Donoho, Elad '03], [Candés et al '04,'05], [Donoho et al, '05],
[Donoho, Tanner, '05], [Fuchs '04,'05] [Tropp '04,'06], [many more!]

Basis Pursuit

Sparse Solutions via $\|x\|_1$

$$\boxed{A} \quad x \approx b$$

Basis pursuit

[Chen, Donoho, Saunders '98]

(BP) minimize $\|x\|_1$ subject to $Ax = b$

Basis pursuit denoise

(BPDN) minimize $\|x\|_1$ subject to $\|Ax - b\|_2 \leq \sigma$

Lasso

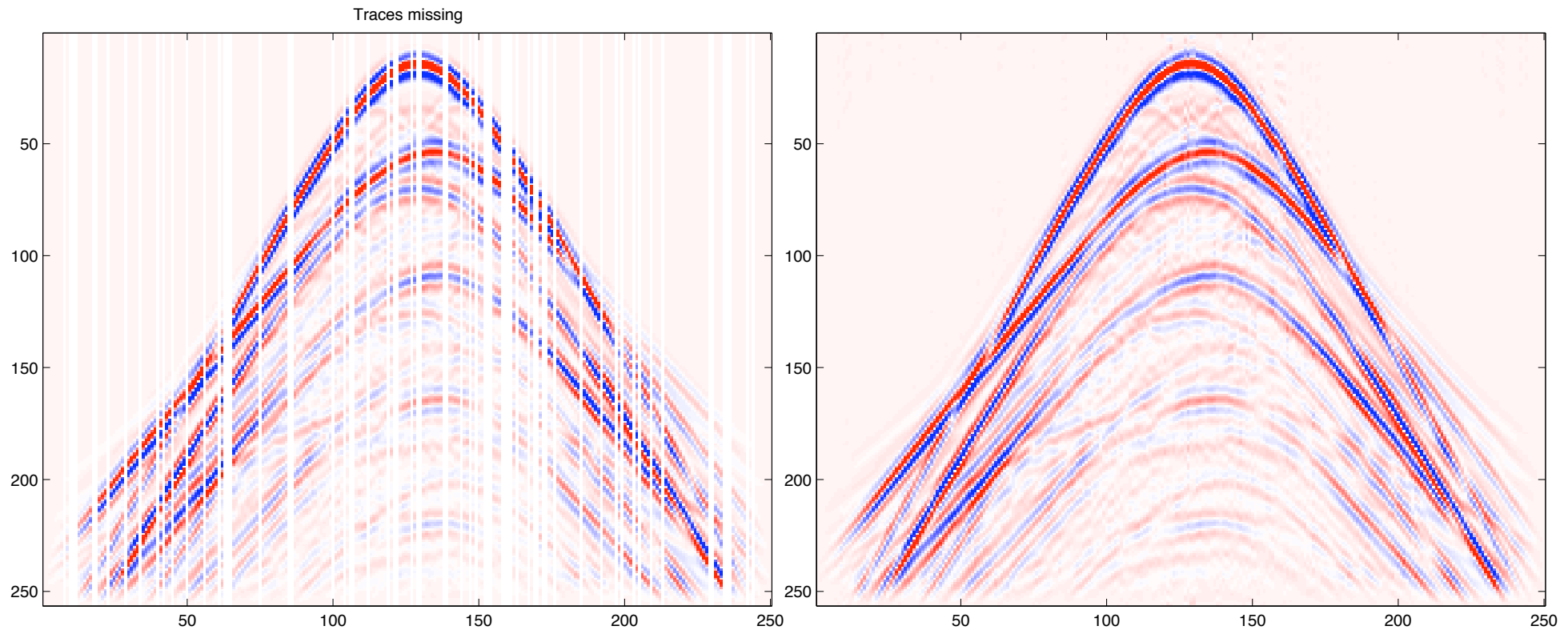
[Tibshirani '96]

(LS $_{\lambda}$) minimize $\|Ax - b\|_2$ subject to $\|x\|_1 \leq \lambda$

GOAL

Seismic Imaging

Felix Herrmann (UBC Earth & Ocean Sciences)



Large-Scale BPDN Solver

$$\underset{x}{\text{minimize}} \quad \|x\|_1 \quad \text{subject to} \quad \|Ax - b\|_2 \leq \sigma$$

Solver requirements

- Use A only as operator
- Frugal with mat-vec projects
- “warm” starts

Ax and $A^T y$
 \sim days CPU time
 take advantage of $x_0 \approx x_\lambda$

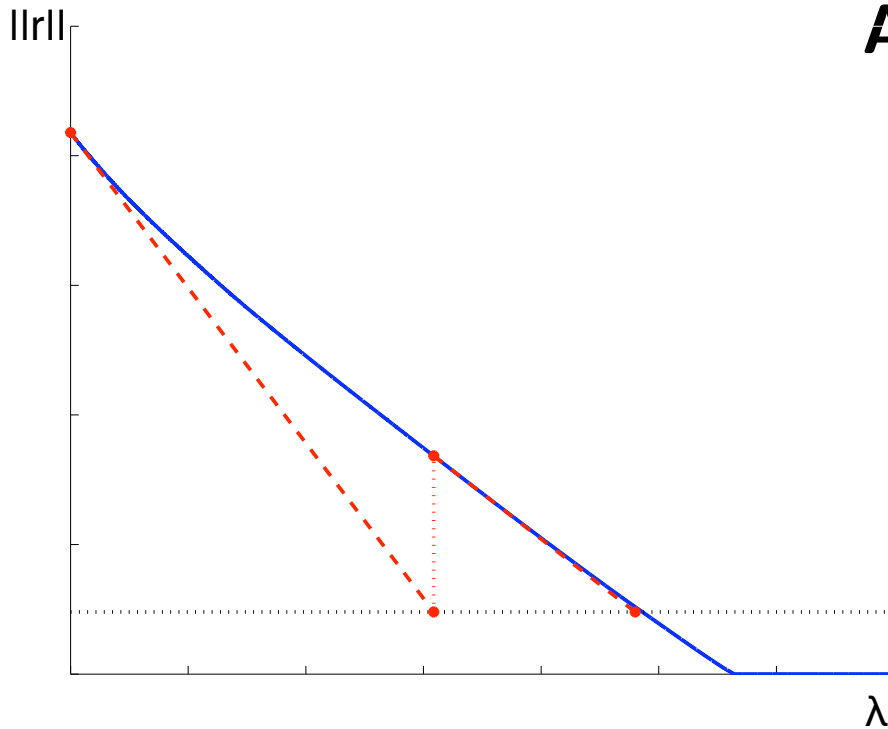
Current approaches

- Log-barrier for SOCP
- QP formulation:

$$\text{minimize} \quad \frac{1}{2} \|Ax - b\|_2^2 + \tau \|x\|_1$$

eg, MOSEK, SeDuMi
 eg, PDCO, GPSR, Homotopy

Approach



$$\begin{aligned}
 (\text{LS}_\lambda) \quad & \underset{x}{\text{minimize}} && \|Ax - b\|_2 \\
 & \text{subject to} && \|x\|_1 \leq \lambda
 \end{aligned}$$

Value function

$$\psi(\lambda) = \|Ax_\lambda - b\|_2$$

Algorithm

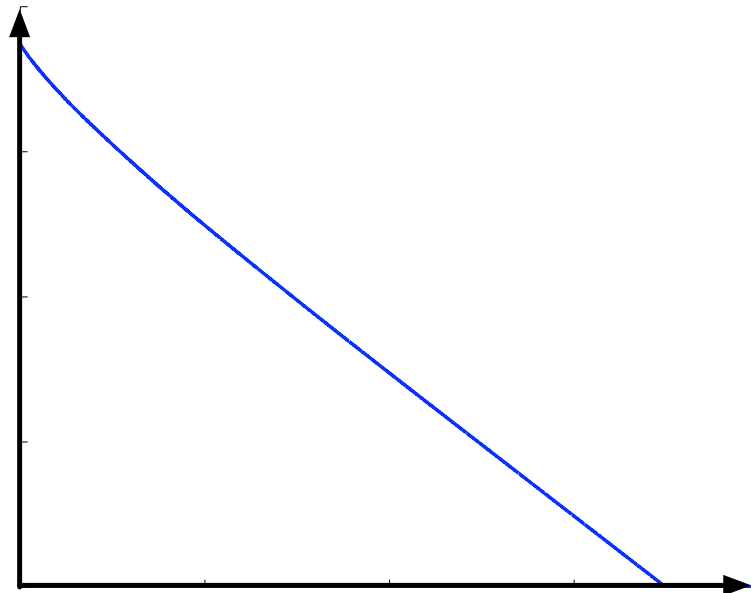
1. Evaluate $\psi(\lambda)$
2. Compute $\psi'(\lambda)$
3. Apply 1-dim Newton's method

gradient projection

duality

$$\lambda_{k+1} \leftarrow \lambda_k - \frac{\psi(\lambda_k) - \sigma}{\psi'(\lambda_k)}$$

Pareto Frontier



Lasso and its Dual

$$\psi(\lambda) := \|Ax_\lambda - b\|_2 = \|r_\lambda\|_2$$

Primal

$$(LS_\lambda) \quad \underset{r, x}{\text{minimize}} \quad \|r\|_2 \quad \text{s.t.} \quad \mathbf{Ax} + \mathbf{r} = \mathbf{b}, \quad \|\mathbf{x}\|_1 \leq \lambda$$

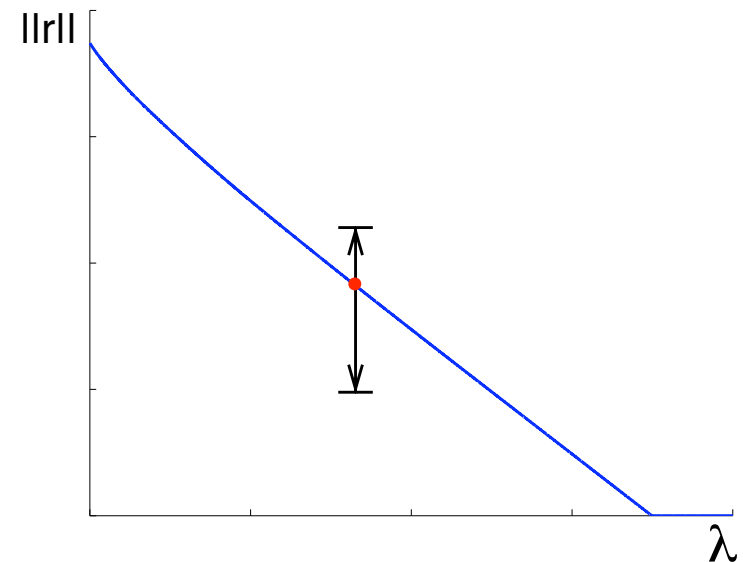
Dual

$$(LS_\lambda^D) \quad \underset{y, \mu}{\text{maximize}} \quad b^T y - \mu \lambda \quad \text{s.t.} \quad \|y\|_2 \leq 1, \quad \|A^T y\|_\infty \leq \mu$$

Solutions for $\lambda \in (0, \lambda_{BP})$

$$\|x_\lambda\|_1 = \lambda \quad y_\lambda = \frac{r_\lambda}{\|r_\lambda\|_2}$$

$$\psi(\lambda) = \|r_\lambda\|_2 \quad \mu_\lambda = \|A^T y_\lambda\|_\infty$$

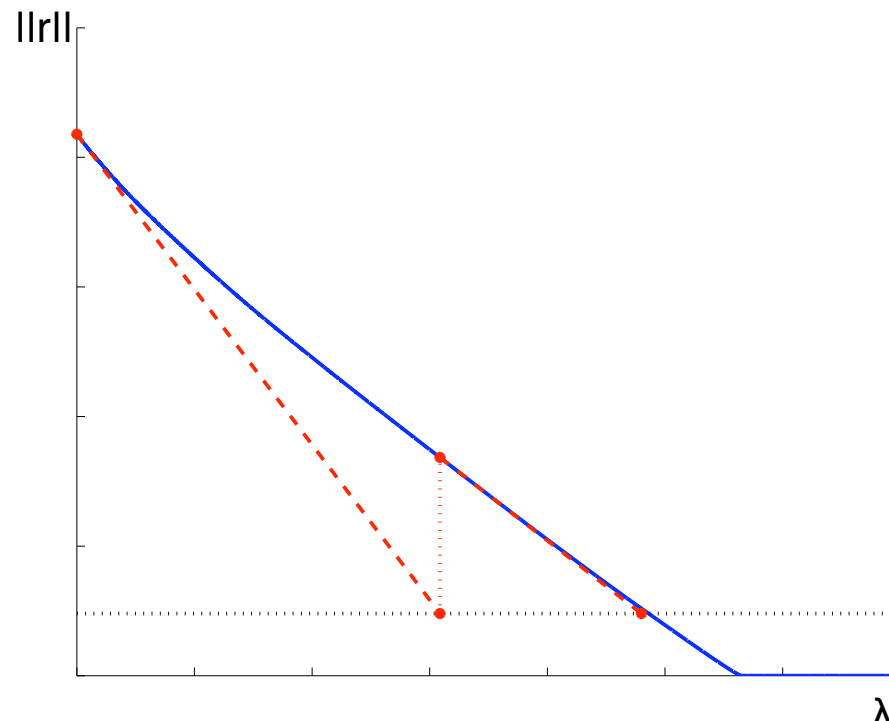


Useful Properties

$$\psi(\lambda) := \text{optimal value of } \underset{x}{\text{minimize}} \|Ax - b\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda$$

Theorem

1. ψ is convex and nonincreasing
2. For all $\lambda \in (0, \lambda_{\text{BP}})$
 - ψ is **continuously differentiable**
 - $\psi'(\lambda) = -\mu_\lambda$ where $\mu_\lambda = \|A^T y_\lambda\|_\infty$, $y_\lambda = r_\lambda / \|r_\lambda\|_2$



Spectral Projected Gradient

Projected Gradient

Evaluate $\psi(\lambda) \implies$ minimize $f(x)$ subject to $x \in \mathcal{C}$

Projected gradient path

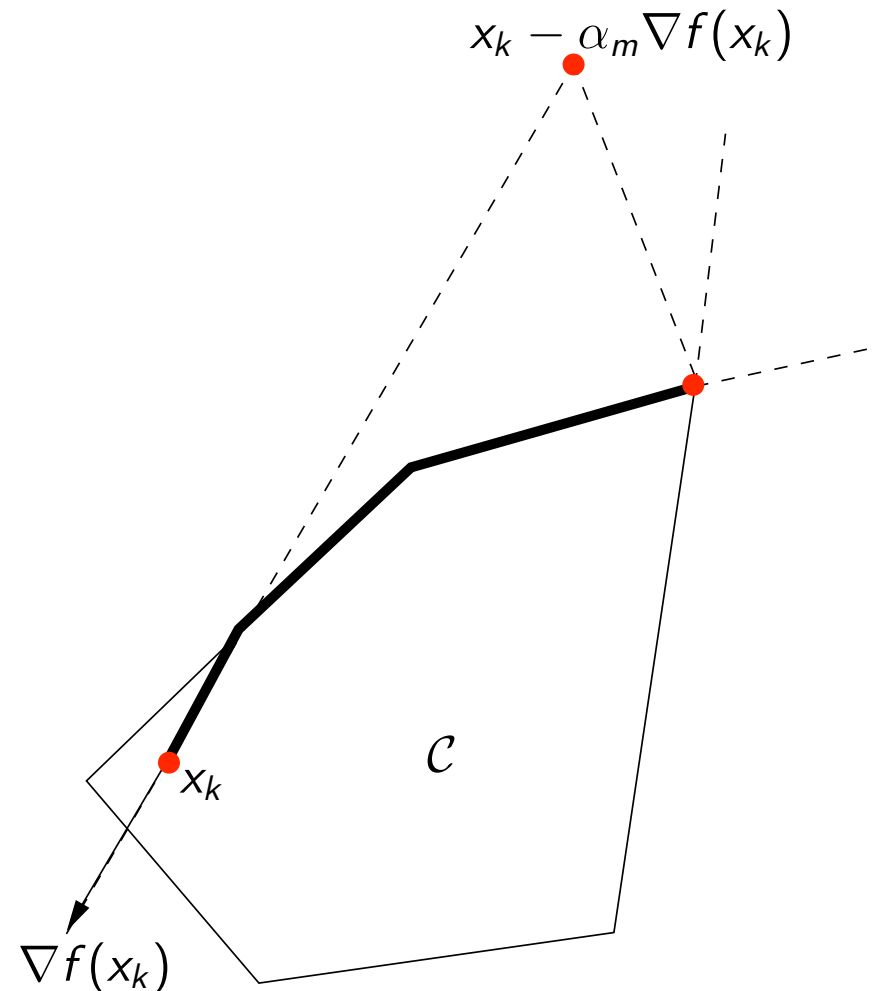
- $x_k(\alpha) = P[x_k + \alpha d]$, $d = -g_k$

Each iteration

- Project steepest descent onto \mathcal{C}
- Minimize along piecewise linear path

Properties

- Large changes to active set possible
- $x_k \rightarrow x^*$, but slow (steepest descent)



Spectral Step Length

Reduce $f(x)$ along $x_k(\alpha) = P[x_k + \alpha d]$

Classical gradient projection

- $d = -g_k$
- Find $\alpha > 0$ to **minimize** along $x_k(\alpha)$ (ie, the Cauchy point)

Spectral step length

- $H_k d = -g_k$ with $H_k := \gamma_k I \approx \nabla^2 f(x)$ (!!)
- Find $\alpha \in (0, 1]$ to sufficiently reduce f along $x_k(\alpha)$
- Secant equation:

$H_{k+1} s_k = y_k$	$s_k := x_{k+1} - x_k$
$\gamma_{k+1} s_k = y_k$	$y_k := g_{k+1} - g_k$
$\gamma_{k+1} := (y_k^T s_k) / (s_k^T s_k)$	

[Barzilai/Borwein '88], [Birgin,... '00], [Dai/Fletcher '05], [Figueiredo,... '07]

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\text{minimize}_x \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\underset{x}{\text{minimize}} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0

28

-4

29

-38

21

120

- $n = 5, \Delta x_i = 20$

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\underset{x}{\text{minimize}} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0	\bar{x}_0
28	8
-4	16
29	9
-38	-18
21	1
120	52

- $n = 5, \Delta x_i = 20$

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\underset{x}{\text{minimize}} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0	\bar{x}_0		x_1
28	8		28
-4	16		
29	9	\Rightarrow	29
-38	-18		-38
21	1		21
120	52		116

- $n = 5, \Delta x_i = 20$
- $n = 4, \Delta x_i = 24$

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\begin{array}{l} \text{minimize} \\ x \end{array} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0	\bar{x}_0		x_1	\bar{x}_1
28	8		28	4
-4	16			
29	9	\Rightarrow	29	5
-38	-18		-38	-14
21	1		21	-3
120	52		116	26

- $n = 5, \Delta x_i = 20$
- $n = 4, \Delta x_i = 24$

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\underset{x}{\text{minimize}} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0	\bar{x}_0		x_1	\bar{x}_1		x_2
28	8		28	4		28
-4	16					
29	9	\Rightarrow	29	5	\Rightarrow	29
-38	-18		-38	-14		-38
21	1		21	-3		
120	52		116	26		95

- $n = 5, \Delta x_i = 20$
- $n = 4, \Delta x_i = 24$
- $n = 3, \Delta x_i = 25$

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\underset{x}{\text{minimize}} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0	\bar{x}_0		x_1	\bar{x}_1		x_2	x^*
28	8		28	4		28	3
-4	16						
29	9	\Rightarrow	29	5	\Rightarrow	29	4
-38	-18		-38	-14		-38	-13
21	1		21	-3			
120	52		116	26		95	20

- $n = 5, \Delta x_i = 20$
- $n = 4, \Delta x_i = 24$
- $n = 3, \Delta x_i = 25$

Orthogonal Projection onto One-Norm Ball

$$P[x_0] \iff \boxed{\underset{x}{\text{minimize}} \|x_0 - x\|_2 \quad \text{s.t.} \quad \|x\|_1 \leq \lambda}$$

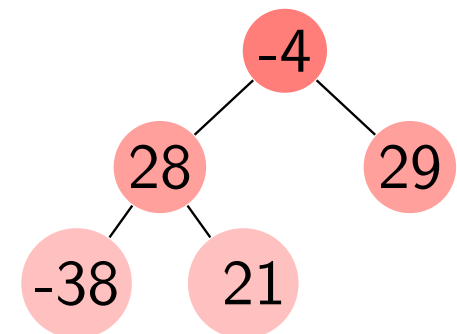
Stages

- Reduce all components x_i equally by $\Delta x := \|x\|_\lambda - \lambda$
- Do not let components x_i change sign

Example: $\lambda = 20$

x_0	\bar{x}_0		x_1	\bar{x}_1		x_2	x^*
28	8		28	4		28	3
-4	16						
29	9	\Rightarrow	29	5	\Rightarrow	29	4
-38	-18		-38	-14		-38	-13
21	1		21	-3			
120	52		116	26		95	20

- $n = 5, \Delta x_i = 20$
- $n = 4, \Delta x_i = 24$
- $n = 3, \Delta x_i = 25$



Algorithm cost

- Maintain elements in min-abs-val heap
- $\mathcal{O}(n \log n)$ iterations

Numerical Experiments

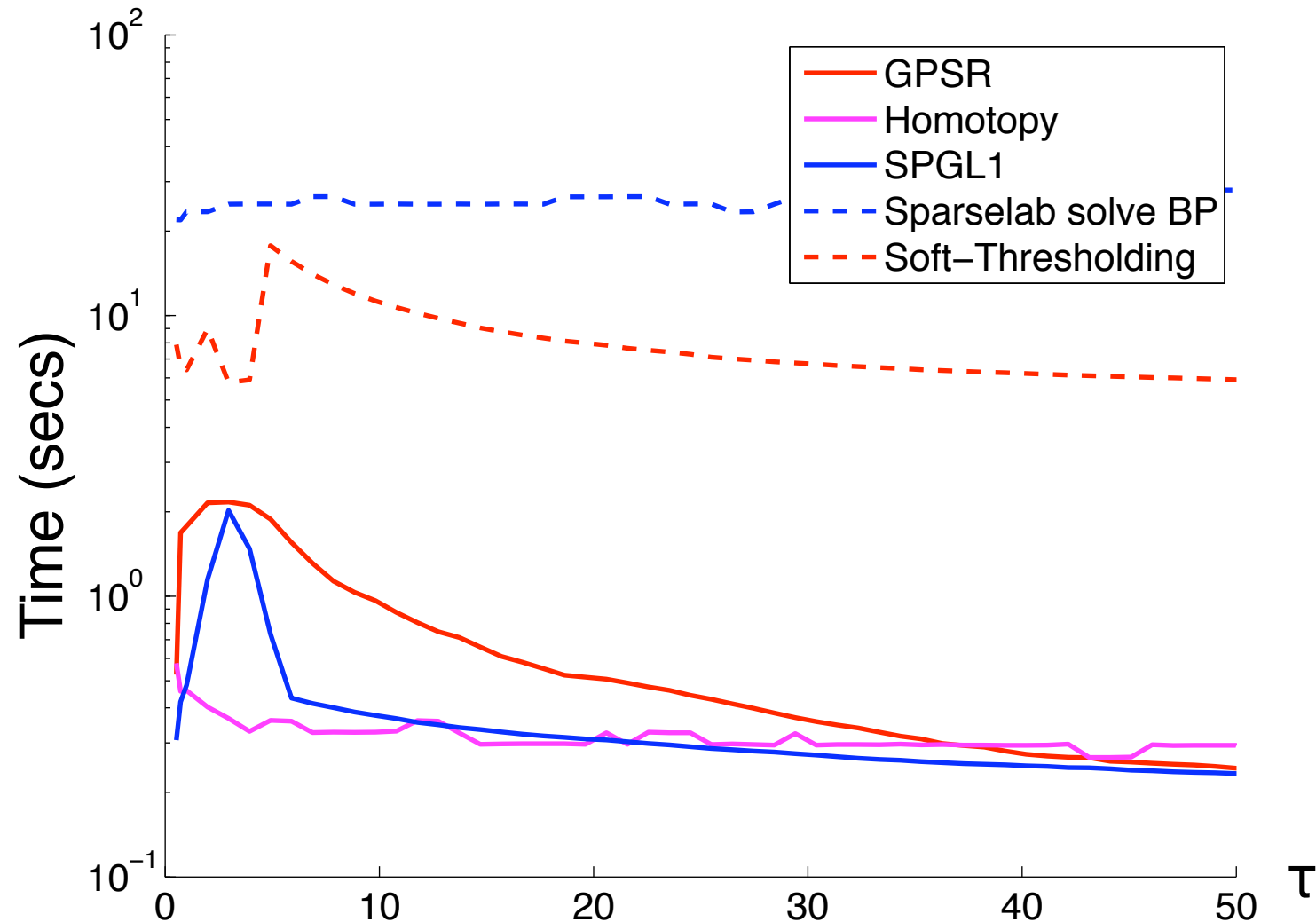
Lasso vs. Weighted Least-Squares

$$\begin{array}{ll} \text{minimize} & \|Ax - b\|_2 \\ \text{subject to} & \|x\|_1 \leq \lambda \end{array}$$

vs.

$$\text{minimize}_x \|Ax - b\|_2 + \tau \|x\|_1$$

A is 512-by-4069



Basis Pursuit De-noise

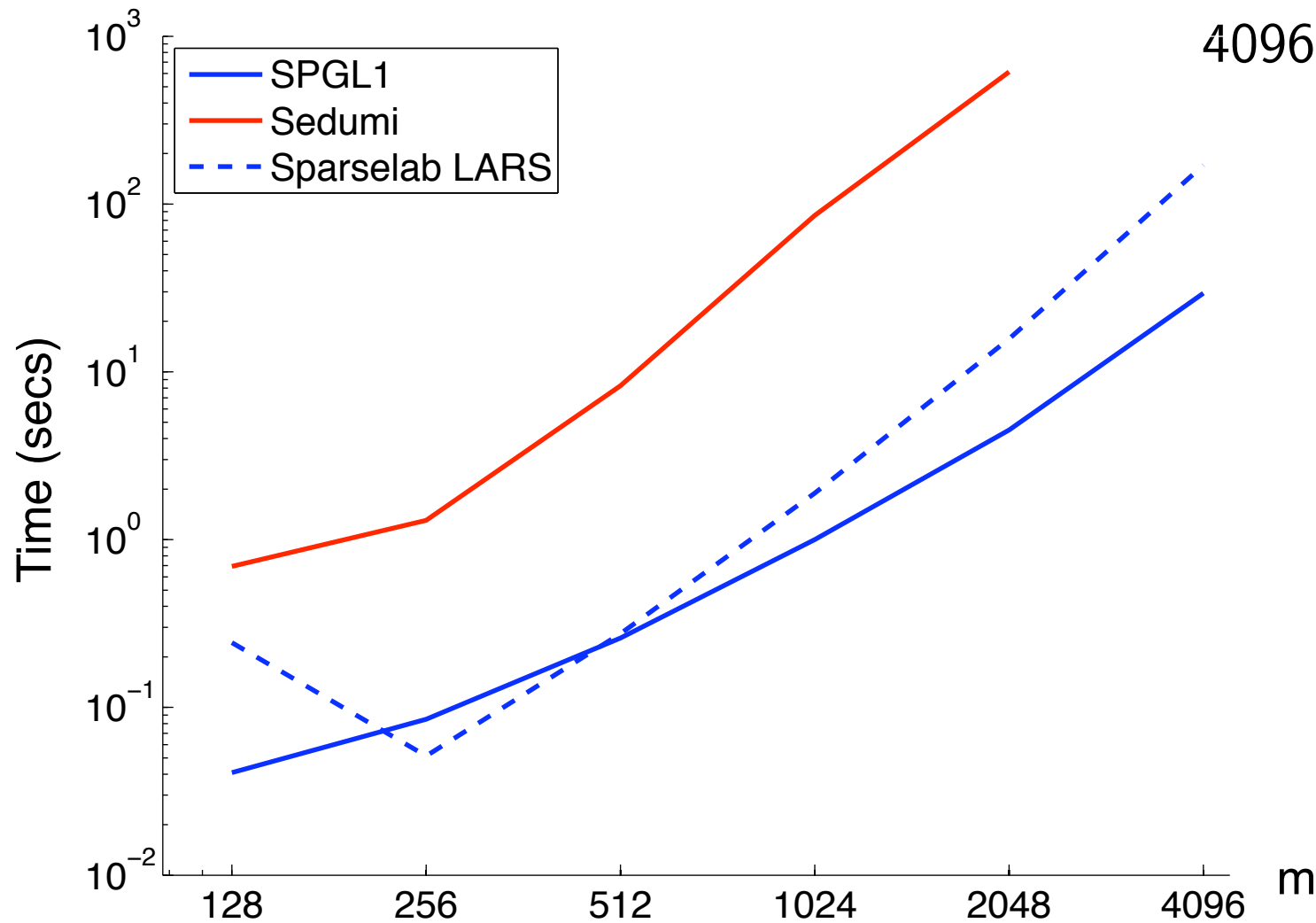
$$\text{minimize } \|x\|_1 \quad \text{s.t.} \quad \|Ax - b\|_2 \leq \sigma$$

Increasing sizes, $n = 4m$:

128-by-512

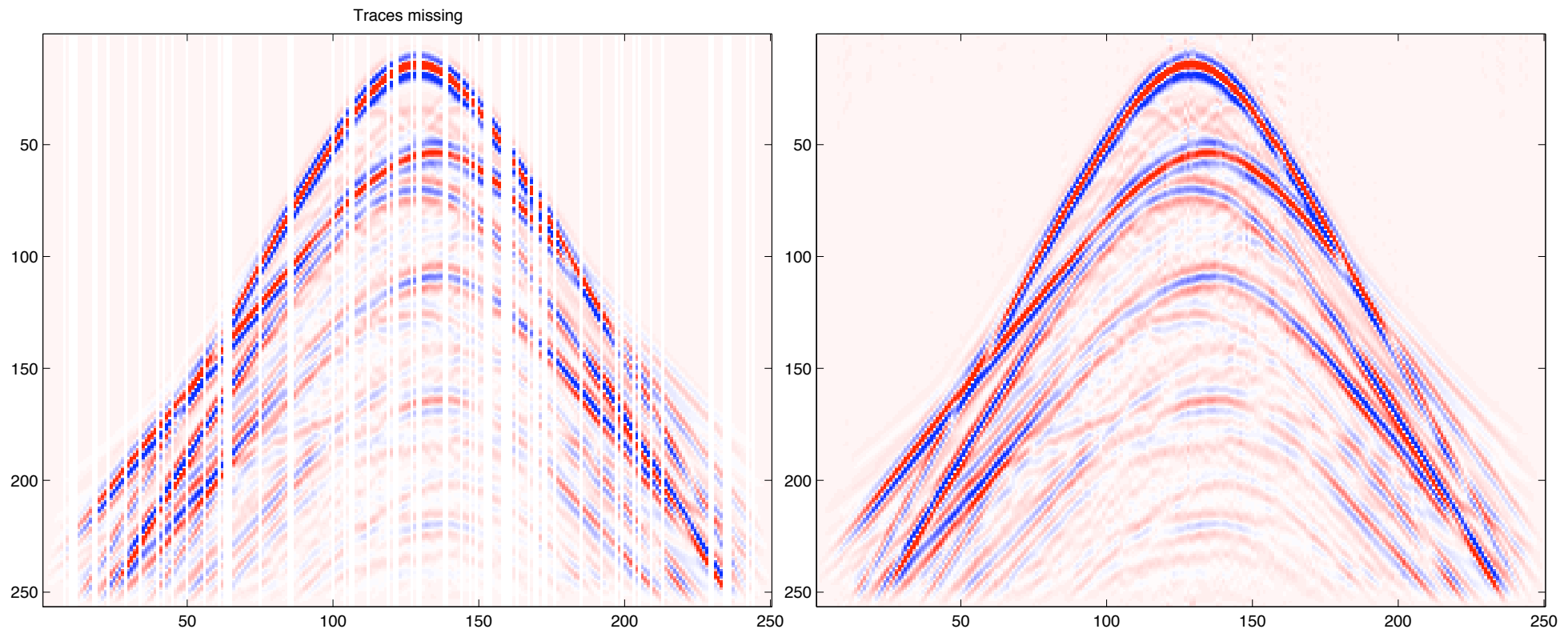
⋮

4096-by-16384



Seismic Imaging

Felix Herrmann (UBC Earth & Ocean Sciences)



- 30% missing traces
- $n = 481K$
- $\text{nnz}(x^*) \approx 70K$ (15%)

- # mat-vec prod's Ax 913
- # mat-vec prod's $A^T y$ 585
- Total time for Ax or $A^T y$ 622 secs
- Total time for $P[\cdot]$ 60 secs

Thanks!

Looking Ahead

Accelerate Lasso subproblem

- Newton-type method for subproblem

$$\begin{array}{ll} (\text{LS}_\lambda) & \underset{x}{\text{minimize}} \quad \|Ax - b\|_2 \\ & \text{subject to} \quad \|x\|_1 \leq \lambda \end{array}$$

Better root-finding

- Reformulation of Pareto curve is piecewise quadratic
- Can we use higher-order Newton approximations?