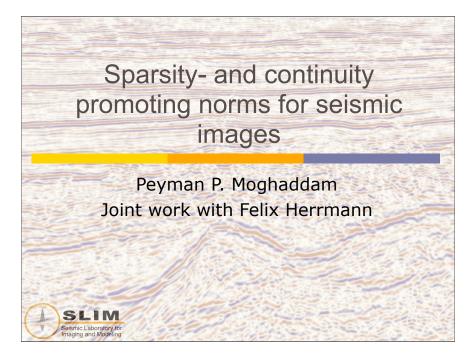
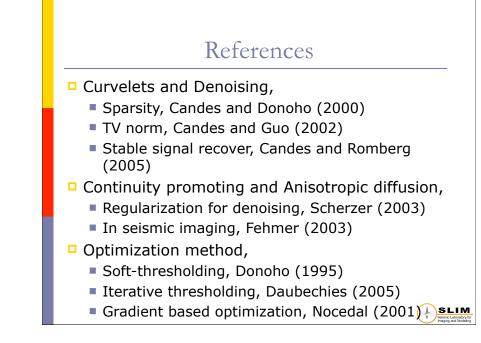
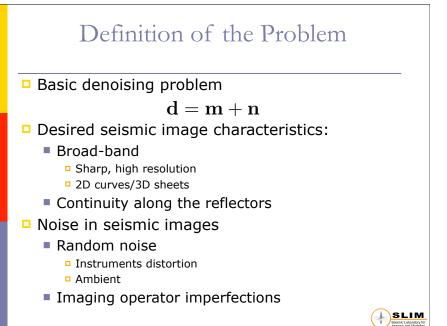
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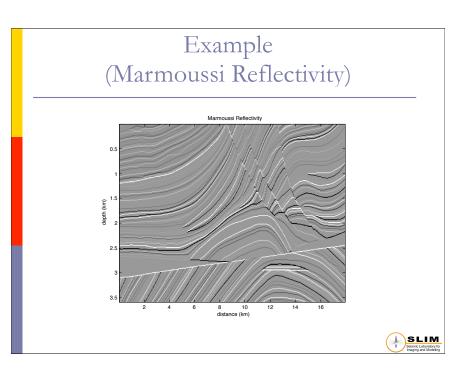


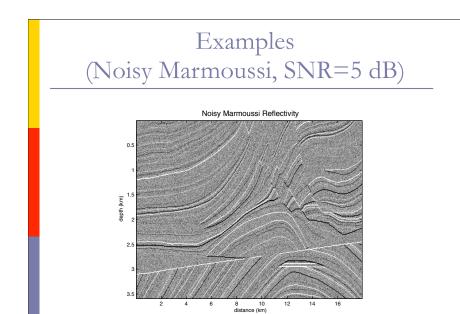
Overview

- Definition of problem
- Denoising as an inversion problem
- Curvelets and their properties
- Curvelets sparsity norm
- Continuity enhancing norm
- Problem reformulation
- Optimization method
- Results
- Conclusion









Denoising as Inversion Problem

- Following inversion problem is introduced
 - $\min_{m} J(\mathbf{m}) \text{ subject to } ||\mathbf{d} \mathbf{m}||_{\ell_2} \leq \epsilon$
 - J(m) is the norm or penalty function

This norm has to

- Explore the continuity along the reflectors
- Explore the sparsity of image in the Curvelet domain
- Reduce the artifacts from image
- Enhance the reflectors
- Remove the noise from seismic image



Curvelets and their properties

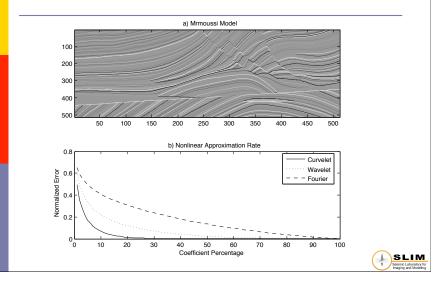
Curvelets:

- are multi-scale and multi-directional
- sparsely present a seismic image
- are invariant under the action of idealize normal operator
- are constructed as tight frames
- transformation is fast
- are reliably used for denoising in image processing applications



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Approximation Rate Comparison



Curvelet Sparsity Norm

Properties

- Theorem states that Curvelet transform of a 2D singularity is sparse (Candes 2001)
- It is Lp norm on the Curvelet coefficients of an image
- Formulation

$$J_c(\mathbf{x}) = ||W\mathbf{x}||_{\ell_1}$$

x is the Curvelet coefficients vector and W is the weighting matrix which controls

- Scaling of the denoised image
- Phase space of the denoised image

Continuity Enhancing Norm

Properties

- Minimize L2 norm on a specific function of the image gradient
- Penalize the amplitude between reflectors and smooth along them
- Enhance the singularities in an image

T ()

Linear and non-linear

$$J_a(m) = |\Lambda[\mathbf{b}] \,{}^2 \, m|_{\ell_2}$$
$$\Lambda[\bar{\mathbf{b}}] = \frac{1}{\|\nabla_d \bar{\mathbf{b}}\|_2^2} \left\{ \begin{pmatrix} D_2 \bar{\mathbf{b}} \\ -D_1 \bar{\mathbf{b}} \end{pmatrix} \begin{pmatrix} D_2 \bar{\mathbf{b}} & -D_1 \bar{\mathbf{b}} \end{pmatrix} \right\}.$$

 $\overline{\mathbf{b}}$ is a smooth or primary estimate of image (+)

Problem Reformulation

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$$\begin{cases} \min_{\mathbf{x}} J(\mathbf{x}) & \text{subject to} \quad \|\mathbf{d} - \mathbf{C}^T \mathbf{x}\|_2 \le \epsilon \\ \mathbf{m} = \mathbf{C}^T \mathbf{x} \\ J(\mathbf{x}) = \sum_{j=1}^N |w_j x_j| + \|\mathbf{\Lambda}^{1/2} \mathbf{C}^T \mathbf{x}\|_2, \end{cases}$$

- This problem solve joint Curvelet sparsity and anisotropic diffusion while preserving the misfit less than the small control parameter
- It is required an optimization method to solve above problem
- A computationally simple method is introduced

