

Imaging Operator Approximation Using Curvelets

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Overview

- Definition of problem
- Normal operator and its properties
- Curvelets and their invariance under the normal operator
- Invariance bound
- Idealizing the normal operator
- Examples
- Direct approximation method of diagonal
- Curvelets factorization of the normal operator
- Results
- Further extension
- Conclusion



Definition of the Problem

- Linear map between image and data defined as

$$\mathbf{d} = \mathbf{K}\mathbf{m}$$

- Classical linear algebra inversion
 - Conjugate gradient based inversion
 - Approximation based inversion

$$\hat{\mathbf{m}} = (\mathbf{K}^* \mathbf{K})^{-1} \mathbf{K}^* \mathbf{d}$$

- Normal Operator

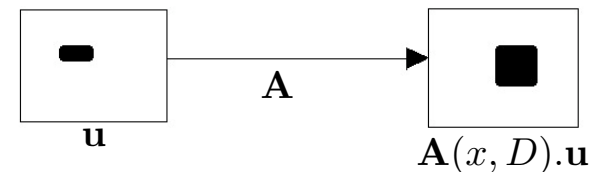
$$\Psi = (\mathbf{K}^* \mathbf{K})$$

- In this talk, an approximation for this operator using Curvelets is discussed.



Normal Operator

- Normal operator is ideally a Pseudo-differential operator



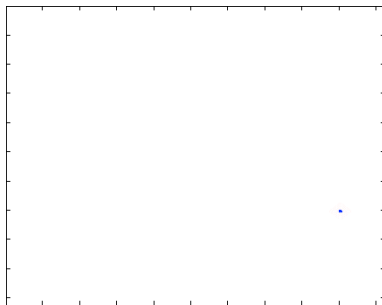
$$\mathbf{A}(x, D) \cdot \mathbf{u} = (2\pi)^{-n} \int e^{i\xi \cdot x} a(x, \xi) U(\xi) d\xi$$

- $a(.,.)$ is smooth for smooth background velocity

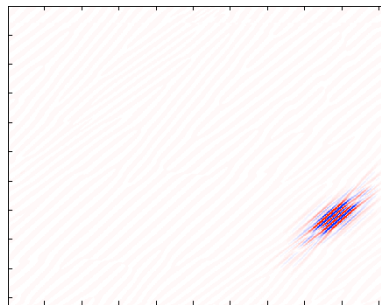


Invariance of Curvelets

impulse response

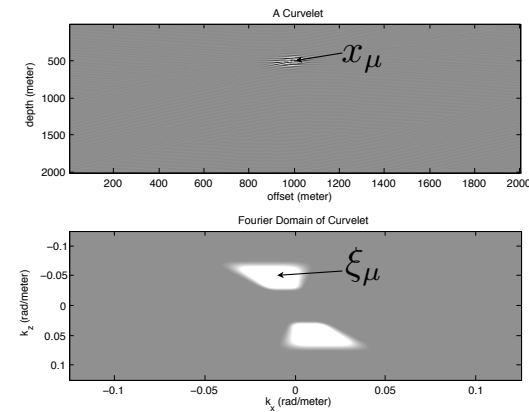


Curvelet response



Normal Operator Approximation

This bound proved to exist
 $\|(A(x, D) - a(x_\mu, \xi_\mu))\phi_\mu\|_{\ell_2} \leq M2^{|\mu|/2}$



Normal Operator Approximation

- The result of theorem

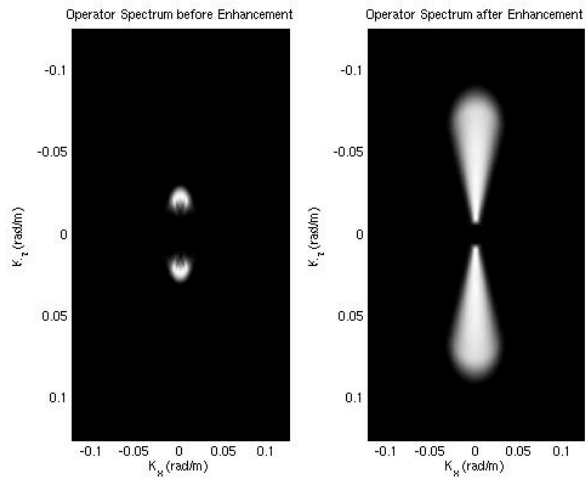
$$\|(A(x, D) - C^T D_A C)\phi_\mu\|_{L^2} \leq K2^{-|\mu|/2}$$

- The above bound holds for an ideal normal operator with
 - Constant background velocity
 - Infinite Aperture
 - Sufficiently smooth operator spectrum
 - Broad-band operator spectrum

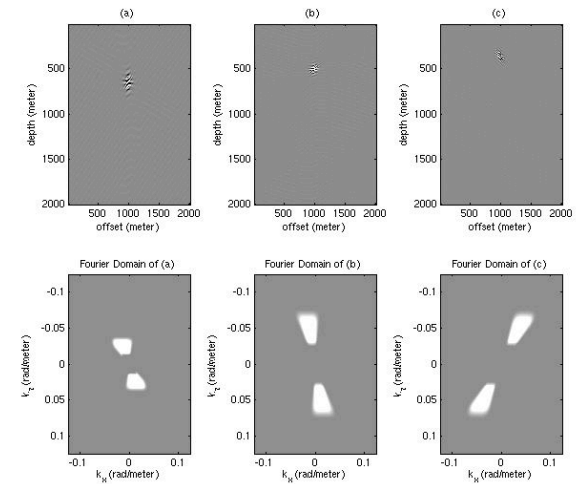
Enhancing the Operator

- Necessary steps to make the normal operator ideal for decomposition
 - Tapering: to flatten the operator spectrum
 - Multiple-source: to widen the operator aperture
 - Broad-band Sources: to widening the operator support
 - Moving boundaries: to eliminating the effect of free surface
 - Depth correction: to eliminating the effect of depth attenuation

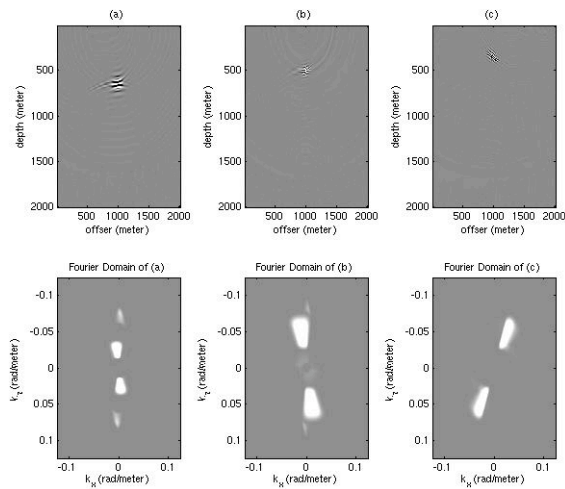
Comparisons



Examples (Three Curvelets)



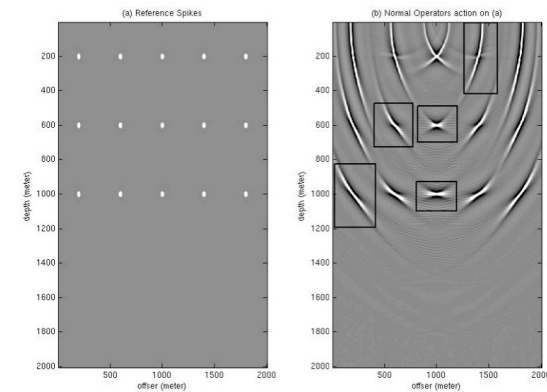
Examples (Normal Operator on three Curvelets)



Direct Approximation

- ❖ Approximation with interpolation

$$a(x_\mu, \xi) = e^{i\xi x_\mu} \mathbf{F}(\mathbf{A}(x, D) \cdot \delta(x - x_\mu))$$



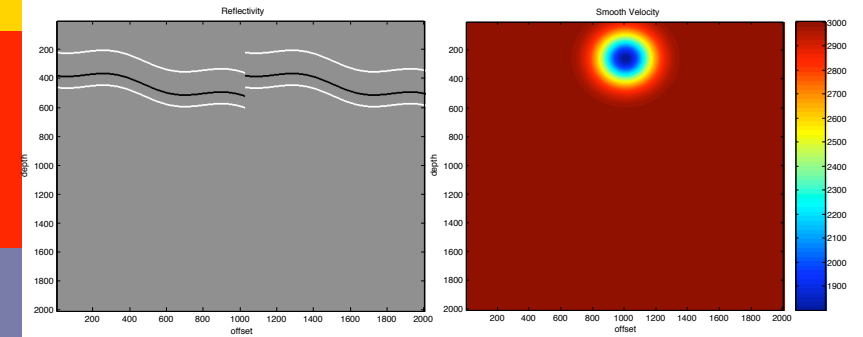
Diagonal Approximation

- ❖ Approximation with Curvelet Regularization

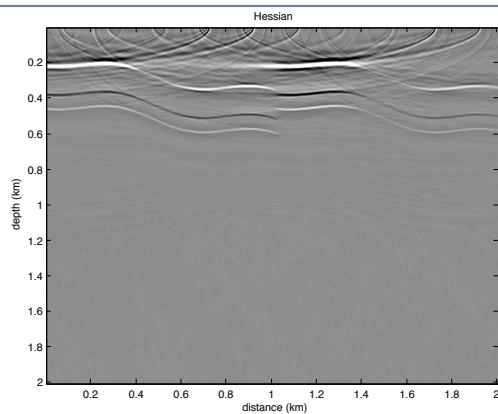
$$C^*DCr \approx K^*Kr$$
$$\begin{pmatrix} C^T \text{diag}(u) \\ \lambda Q \end{pmatrix} d = \begin{pmatrix} K^*Kr \\ \mathbf{Z} \end{pmatrix}$$

- Solve using LSQR method
- Explore smoothness along Curvelet's symbols
- Computationally cheap, Required only "one" evaluation of normal operator

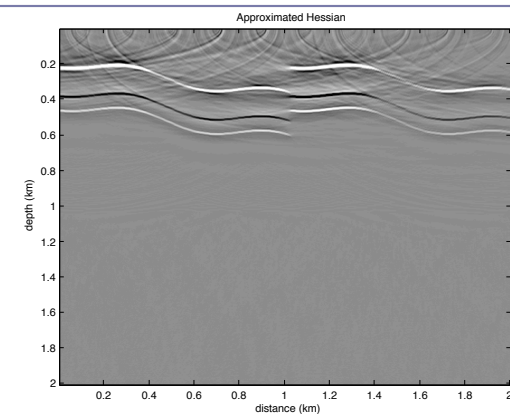
Evaluation Model



Result



Results



Further Extension

- Multiple Reference Vectors

$$\begin{pmatrix} C^T \text{diag}(u_1) \\ C^T \text{diag}(u_2) \\ \dots \\ C^T \text{diag}(u_N) \\ \mathbf{Q} \end{pmatrix} d = \begin{pmatrix} K^* K r_1 \\ K^* K r_2 \\ \cdot \\ K^* K r_N \\ \mathbf{Z} \end{pmatrix}$$

- Aperture limitation correction

Conclusion

We introduce a novel approach

- Employs Curvelets as essential elements in both approximation and estimation
- Employs an accurate decomposition of expensive operator
- Employs smoothness in Curvelets symbols
- Its Application to synthetic data generates promising results
- Further extension of this method is under development
- A python interface for this method is under investigation