Released to public domain under Creative Commons license type BY (https://creativecommons.org/licenses/by/4.0).
Copyright (c) 2018 SINBAD consortium - SLIM group @ The University of British Columbia.
Tim Tai-Yi Lin
in collaboration with Felix Herrmann
Joris Grimbergen, Frank Dessing, E. Candes et. al.
with special thanks to authors of StOMP
D. L. Donoho et. al.
SLIM
Seissic. Laboratory for
Imaging and Modeling
August 29, 2006

## Problem Description

$\square$ Very large-scale imaging problems
$\square$ Usage of wave propagator that is desirable but expensive to compute
$\square$ Imaging is necessarily a recovery problem due to diminished evanescent waves

## Project Goals

$\square$ Employ ideas of compressed sensing
$\square$ Deliberately limit signal sampling to reduce computational cost
$\square$ L1-minimization recovery reduces blurring due to missing evanescent modes


propagated signal in spatial domain


Stable Wave Propagator


## Stable Wave Propagator

$\square$ Property of $\mathrm{W}^{ \pm}$is crucial for computation

$$
\begin{aligned}
& \mathbf{p}^{\mathbf{p}}=\int_{x_{3}>0} \mathbf{W} \mathbf{R}^{+} \mathbf{W}^{+} \mathbf{s}^{+} \mathrm{d} x_{3} \\
& \mathbf{p}=\sum_{x_{3}>0} \mathbf{W}^{-} \mathbf{R}^{+} \mathbf{W}^{+} \mathbf{s}^{+} \Delta x_{3}
\end{aligned}
$$

## Stable Wave Propagator

## $\square$ No Dip Limitation

$\square$ Handles Lateral Variations

- Unconditional Stability
- Low Computational Cost

$\square$ Physical behavior of wavefield modeled by coupled differential equation of depth
(Claerbout, 1971; Wapenaar and Berkhout, 1989)

$$
\partial_{3} \mathcal{Q}+j \mathcal{A} \mathcal{Q}=\mathcal{D}
$$

$\sqrt{4}$

## One-Way Wave Operator

wave vector
source vector
$\square$ Solution for $\mathcal{Q}$ at any depth

$$
\mathcal{Q}\left(x_{3}\right)=\exp \left(-j \mathcal{A} x_{3}\right) \mathcal{Q}_{0}
$$

$\square$ Unfortunately this expression is meaningless!

## One-Way Wave Operator

$\square$ Decomposition of $\mathcal{A}$ proposed to rectify its usefulness in computation
(Claerbout, 1971; Wapenaar and Berkhout, 1989; de Hoop, 1992)

$$
\begin{aligned}
& \mathcal{A}=\mathcal{H} \mathcal{C} \\
& \mathcal{H}=\left(\begin{array}{cc}
\mathcal{H}_{1} & 0 \\
0 & -\mathcal{H}_{1}
\end{array}\right) \\
& \mathcal{H}_{2}=\mathcal{H}_{1} \mathcal{H}_{1}
\end{aligned}
$$

## One-Way Wave Operator

- Substitution of $\mathcal{A}$ by its decomposition is performed, and its composition operators is allowed to act on the signal vectors

$$
\partial_{3} \mathcal{Q}+j \mathcal{A} \mathcal{Q}=\mathcal{D}
$$

$$
\mathcal{A}=\mathcal{L H} \mathcal{L}^{-1}
$$

$$
\partial_{3} \boldsymbol{P}+j \mathcal{H} \boldsymbol{P}=\boldsymbol{S}+\boldsymbol{\Theta} \boldsymbol{P}
$$

One-way Wave Equation

## Modal Decomposition

$\square$ We still need to compute the actual $\mathrm{W}^{ \pm}$Operator

- this requires structure of $\mathcal{H}_{1}$

$$
\mathcal{H}_{2}=\mathcal{H}_{1} \mathcal{H}_{1}
$$

- with $\mathcal{H}_{2}$ defined as

$$
\mathcal{H}_{2}=k^{2}(\boldsymbol{x})+\partial_{\mu} \partial_{\mu}
$$

- or, written as a numerical linear operator

$$
{\underset{\sim}{\mathbf{H}}}_{2}=\underset{\sim}{\mathbf{C}}+{\underset{\sim}{\mathbf{D}}}_{2} .
$$

## Modal Decomposition

$$
\begin{aligned}
& \mathbf{H}_{2}=\underset{\sim}{\mathbf{C}}+\underset{\sim}{\mathbf{D}_{2}} . \quad \quad \mathbf{C}=\left(\begin{array}{cccc}
\left(\frac{\omega}{c_{1}^{\prime}}\right)^{2} & 0 & \cdots & 0 \\
0 & \left(\frac{\omega}{c^{\prime}}\right)^{2} & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & \left(\frac{\omega}{c_{M}^{\prime}}\right)^{2}
\end{array}\right), \text { Hermitrian } \\
& \text { Self-adjoint }
\end{aligned}
$$

$$
\mathbf{D}_{2}=\frac{1}{\Delta x_{1}^{2}}=\left(\begin{array}{cccccc}
-2 & 1 & 0 & \cdots & 0 & 0 \\
1 & -2 & 1 & \cdots & 0 & 0 \\
0 & 1 & -2 & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & -2 & 1 \\
0 & 0 & 0 & \cdots & 1 & -2
\end{array}\right)
$$

The new definition is consistent with the standard "migration" model

$$
\mathrm{P}^{-}=\sum_{x_{3}>0} \mathrm{~W}^{-} \mathrm{R}^{+} \mathrm{W}^{+} \mathrm{s}^{+} \Delta x_{3}
$$

Solution to one-way wave equation now has the one-way wave operator defined as

$$
\mathcal{W}^{ \pm}\left(x_{3} ; x_{3}^{\prime}\right)=\exp \left(\mp j\left(x_{3}-x_{3}^{\prime}\right) \mathcal{H}_{1}\right)
$$

## Modal Decomposition

$\square$ Guaranteed existence of similarity transform decomposition


## Modal Decomposition

## Implicit Wavefield Propagation Algorithm

- bring signal into frequency domain
- for each frequency \& layer:
- construct ${\underset{\sim}{\mathbf{H}}}_{2}$ operator matrix
- obtain eigenvalue decomposition of ${\underset{\sim}{\mathbf{H}}}_{2}$
- transform monochromatic signal to eigenvector basis
- apply phase rotation $\exp \left\{\mp j\left(x_{3}-x_{3}^{\prime}\right) \simeq^{\frac{1}{2}}\right\}$
- backward transform signal to space basis
- combine monochromatic signal \& transform back to time domain


## Modal Decomposition

$\square$ From the structure of $\mathbf{H}_{2}$ it is simple to deduce that it's "square root" can be computed as

$$
{\underset{\sim}{\mathbf{H}}}_{1}=\underset{\sim}{\mathbf{L}}{\underset{\sim}{\mid}}^{\frac{1}{2}}{\underset{\sim}{\mathbf{L}}}^{-1}=\underset{\sim}{\mathbf{L}}{\underset{\sim}{\boldsymbol{\sim}}}^{\frac{1}{2}}{\underset{\sim}{\mathbf{L}}}^{H}
$$

$\square$ Linear algebra thus allows the propagator to be written in the form:
${\underset{\sim}{\mathbf{W}}}^{ \pm}\left(x_{3}, x_{3}^{\prime}\right)=\underset{\sim}{\mathbf{L}}\left(x_{3}^{\prime}\right) \exp \left\{\mp j\left(x_{3}-x_{3}^{\prime}\right){\underset{\sim}{\boldsymbol{\Lambda}}}^{\frac{1}{2}}\right\}{\underset{\sim}{\mathbf{L}}}^{H}\left(x_{3}^{\prime}\right)$

## Modal Decomposition

$\square$ For propagation examples, refer to Grimbergen et. al. 1998

- Shown to effortlessly handle lateral medium
 variations without tweaking



## Modal Decomposition

$\square$ simple 1-D space/time propagation example


propagated 1.5 km down

## Motivation: Ideal Propagator?

$\checkmark$ No Dip Limitation
$\checkmark$ Handles Lateral Variations
$\checkmark$ Unconditional Stability
$\square$ Computational Speed

## Motivation: Ideal Propagator?

$\square$ spectrum of $\underset{\sim}{\boldsymbol{\Lambda}}$ dictates existence of evanescent wave modes $\tilde{b}$ elonging to imaginary eigenvalues



Amplitude of these wave modes decay exponentially as a result

## Motivation: Ideal Propagator?

- Our W operator will inevitably be "pseudorestricted" with a part of the operator having diminished amplitude



## Motivation: Ideal Propagator?

$\square$ This causes problems with inverse propagation, defined as Hermitian adjoint $W^{T} W x$

- Evanescent wave modes are not accounted
- Results in frequency-limited artifact


Inverse propagated wave signal (should resemble source's perfect spike shape)

Motivation: Ideal Propagator?


## SLIM

## Motivation: Ideal Propagator?

$\square$ Inverse propagation can instead be treated as a least squares problem to reduce artifact

$$
\hat{x}=\left(A^{T} A+\epsilon I\right)^{-1} A^{T} y
$$

$\square$ However this must be solved iteratively since the Hessian $\left(A^{T} A\right)$ is ill-conditioned
$\square$ This adds a factor of $\mathbf{1 0 x} \mathbf{\sim} \mathbf{2 0 x}$ to the computing cost of each propagation

## Motivation: Ideal Propagator?

$\square$ However, least-squares do not completely solve the problem of inverse propagation


## Motivation: Ideal Propagator?

$\square$ Furthermore, the modal decomposition method is inherently costly

## - synthesis cost:

requires solving a full eigenvalue problem with the H 2 matrix, which could be $\mathbf{O}\left(\mathbf{n}^{3}\right)$ with n being the number of detectors

- operation cost:
requires a FFT in addition to vector-matrix multiplications which is $\mathbf{O}\left(\mathbf{n}^{2}\right)$, with Isqr contributing a factor of $10 \sim 20$ to this cost


## Inspiration: Wave Modes of H2

- The wave modes of ${\underset{\sim}{\mathbf{H}}}_{2}$ very much resembles a Fourier transform operator's wave modes!
(Grimbergin et. al., 1998)

```
Wave modes for invariant medium is identical to that of a cosine
transform
```






Sram mocems

## Propagation via L1-recovery

$\square$ We can actually directly ignore evanescent wave modes and call it "conveniently restricted out"
$\square$ Result is clean spikes without artifacts caused by "incomplete" propagation


From UUP we know that it takes only ~5 Fourier wave modes to recover one point spike (disregarding log-like factors)
Fourier basis is known to be a good measurement basis for sparse recovery due to strong incoherence with Dirac basis
(E. Candes, D.L. Donoho)


## Propagation via L1-recovery


$\qquad$
$\qquad$

## Propagation via L1-recovery

## Restricted Wave Propagation Algorithm

- Decompose signal into freq \& H2 wave mode
- Delete (restrict) most of the signal, for practical cases usually ~90\%
- Construct a much smaller Implicit Wavefield Propagation Algorithm and apply it to restricted signal
- Use a fast L1-solver to recover the full propagated signal in space/time domain


## Restricted Wave Propagation Algorithm



Restricted Wave Propagation Algorithm
estricted signal in H2 domain

## Propagation via L1-recovery

$\square$ Restriction index keeps track of restricted signal


## Computational Savings

## What about the L1-recovery?

$\square$ Reduction in synthesis cost

- a fully restricted frequency eliminates one full eigenvalue problem
- partially restricted frequencies gain a reduction in the size of the eigenvalue ( $10 \%$ of original size)
$\square$ Reduction in computation cost
- Applying the operator now is only $O(n)$, with a factor that is proportional to the fraction of signal surviving restriction
$\square$ L1-recovery isn't free, which is why we need a fast solver
$\square$ StOMP can be utilized as a fast approximate L1 solver
$\square$ But in reality, any L1 solver can be used as long as it is fast


## Experimental Results

$\square$ StOMP is approximately equal to $2 \sim 5 x$ of an iterative Isqr problem. But:


- i.e., Operating on a signal $10 \%$ of the original size will take about $10 \%$ of the time taken by a full operator
$\square$ StOMP will usually be faster than Isqr provided that we restrict more than $80 \%$ of the signal


## Recoverability Phase Diagrams

$\square$ Invariant Medium, 1 km down


## Hard Problems

$\square$ What do we expect when we inverse-propagate in a "hard" medium?

$\square$ Guided wave modes will probably affect recoverability, but hard to predict
$\square$ See separate effects of frequency vs. H2 wave mode restriction

## Recoverability Phase Diagrams

- Rapidly Varying Medium, 1 km down, freq restriction



## Choosing Restrictions

$\square$ Choice of restrictions in frequency and H 2 modes


## Recoverability Phase Diagrams

$\square$ Rapidly Varying Medium, 1km down, H2 restriction

## Savings on Eigenvalue Problem

$\square$ We additionally save time by computing only a small percentage of eigenvalues


## Future Directions

$\square$ Optimal Restriction
$\square$ Multi-layer Propagation
$\square$ Working in curvelet sparsity

## Optimal Restriction

$\square$ Restricting whole frequencies eliminate entire eigenvalue problems, but give less predictable results
$\square$ Pure random restriction gives predictable results but still require solving eigenvalues

[^0]
## Multi-Layer Propagation

$\square$ Multi-Layer propagation is the only way to deal with vertical velocity variations
$\square$ Decaying evanescent waves make deep propagations through many layers difficult

## Curvelet Sparsity

$\square$ Stop working in broadband and start working in Curvelet sparsity
$\square$ Utilizing Curvelet sparsity is possible by incorporating FDCT into the operator

Maintain signal sparsity with new sparsity basis

Possible non-linear inv. propagation using L1 Solvers

## Conclusions

Thanks for your time!
$\square$ Reformat inverse propagation and therefore imaging as a sparse recovery problem

- Remove problem with evanescent wave modes
$\square$ Faster (or at least as fast) to compute as Isqr
$\square$ Loosened memory requirements
$\square$ Improves with future fast L1 solver


[^0]:    An optimal restriction scheme is proposed to exist

