

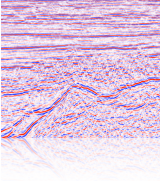
## A primer on stable signal recovery

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## Problem statement

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consider the following (severely) underdetermined system of linear equations

$$\begin{matrix} \text{data} \\ \text{(measurements/} \\ \text{observations)} \end{matrix} \rightarrow \mathbf{y} = \mathbf{A} \begin{matrix} \mathbf{x}_0 \\ \text{unknown} \end{matrix} + \mathbf{n} \leftarrow \text{error term}$$

is it possible to recover  $\mathbf{x}_0$  accurately from  $\mathbf{y}$ ?

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- general answer is NO...
  - infinitely many solutions

$$\begin{bmatrix} 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 3 \\ 0 \\ 0 \end{bmatrix} \quad \text{but} \quad \begin{bmatrix} 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 50 \\ 47 \\ 0 \end{bmatrix}$$

desired solution  other possible solution

- least squares solution

$$\mathbf{x}_{LS} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{y} \quad \mathbf{x}_{LS} = \begin{bmatrix} 0 \\ 1.5 \\ -1.5 \\ 0 \end{bmatrix}$$

- BUT, under some specific conditions on the matrix  $\mathbf{A}$  and the solution  $\mathbf{x}_0$ , the answer is YES!

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## References

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- E. Candès, J. Romberg, "Practical signal recovery from random projections", IEEE Trans. Signal Processing, 2005.
- E. Candès, J. Romberg, T. Tao, "Stable signal recovery from incomplete and inaccurate measurements", Comm. on Pure and Applied Math, 2005.
- J. Romberg, "Sparse signal recovery via  $l_1$  minimization", 2006.
- E. Candès, T. Tao, "Decoding by linear programming", IEEE Transactions on information theory, vol. 51, no. 12, December 2005, pp. 4203-4215.
- D. L. Donoho, "Compressed sensing", IEEE transactions on information theory, vol. 52, no. 4, April 2006, pp. 1289-1306.
- Y. Tsaig, D. L. Donoho, "Extensions of compressed sensing". Signal processing 86:33, 549-571, Elsevier Science, 2006.

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## Applications in geophysics

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- manifold, e.g.
  - data sampling & regularization
    - Recovery of seismic data: practical considerations (today 11:15 am)
  - signal separation
    - Stable recovery and separation of seismic data (next talk)
    - Primary-multiple separation by curvelet frames (today 2:30 pm)
  - imaging
    - Compressed imaging (tomorrow 11:15 am)
- appealing
  - Stable Signal Recovery (SSR) theory provides **explicit recovery condition**.

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## Agenda

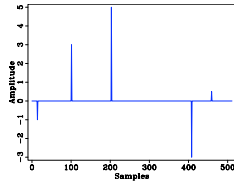
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- sparsity, compressibility & representations
- uncertainty principles and recovery
- stability

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## Sparsity

- what is sparsity?
  - the sparsity of a vector is defined as the number of its 0 entries
    - sparse vector  $\mathbf{x}$  (e.g. sparse spike train)
  - sparseness corresponds to small  $l_0$  quasi-norm
    - $\|\mathbf{x}\|_0 := \#$  of nonzero entries



- why using sparsity?
  - powerful property (i.e. extra piece of information about the signal) that offers striking benefits

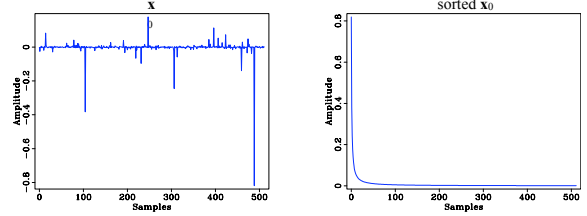
note: The idea of promoting sparsity for geophysical problems is commonly attributed to Claerbout and Muir in 1973. This was further developed e.g. by Oldenburg who proposed to deconvolve seismic traces for reflectivity as sparse spike trains. Although applications are successful in both cases, no explicit recovery condition is given.

## Compressibility

- what is compressibility?
  - $\mathbf{x}_0$  is compressible if its entries obey a power law

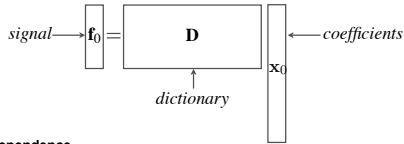
$$|\mathbf{x}_0|_{(k)} \leq C_r \cdot k^{-r}$$

where  $|\mathbf{x}_0|_{(k)}$  is the  $k$ -th largest value of  $\mathbf{x}_0$  (e.g. wavelet coefficients of a piecewise smooth signal),  $C_r$  a constant, and  $r \geq 1$ .



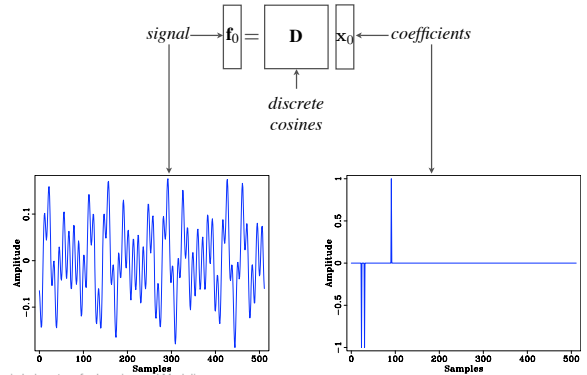
## Sparse & compressible representations

- seek
  - **simplicity** (already forgot "Make it as simple as possible, but not simpler" by A. Einstein????)
    - signal  $\mathbf{f}_0$  is built as a linear combination of **few atoms** from dictionary  $\mathbf{D}$

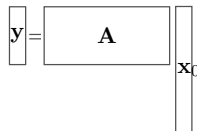


- **independence**
  - atoms used to construct  $\mathbf{f}_0$  do not contain redundant information
- **expressiveness**
  - each selected atom significantly contributes to the construction of  $\mathbf{f}_0$  (i.e. energy of the signal  $\mathbf{f}_0$  is concentrated in **few significant coefficients**)

## Example: sparse DCT representation



## Perfect recovery



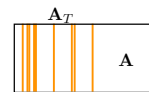
- conditions
  - $\mathbf{A}$  obeys a type of **uncertainty principle**
  - $\mathbf{x}_0$  is **sufficiently sparse**

- procedure

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{subject to} \quad \mathbf{Ax} = \mathbf{y}$$

## Closer look at the conditions

- uncertainty principles
  - Uniform Uncertainty Principle (UUP) is the most powerful
    - all subsets of  $4S$  or less columns of  $\mathbf{A}$  behave like an **orthonormal basis**



- sparsity
  - $\mathbf{x}_0$  is an  $S$ -sparse vector (i.e.  $\mathbf{x}_0$  has at most  $S$  nonzero entries)

insight: suppose

- $\mathbf{x}_0$  is an  $S$ -sparse vector
- $\mathbf{A}$  obeys the UUP for sets of size  $2S$

compute  $\mathbf{y} = \mathbf{Ax}_0$ . Is  $\mathbf{x}_0$  the sparsest solution that explains  $\mathbf{y}$ ?

Consider another  $S$ -sparse vector  $\mathbf{x}'_0$ , then  $\mathbf{h} = \mathbf{x}'_0 - \mathbf{x}_0$  has at most  $2S$  nonzeros and  $\mathbf{Ah} = \mathbf{A}(\mathbf{x}'_0 - \mathbf{x}_0) = 0$ . Since  $\mathbf{A}$  obeys the UUP for sets of size  $2S$ ,  $\mathbf{A}_{[1:2S]}$  has no null space thus  $\mathbf{x}'_0 = \mathbf{x}_0$ .

## Closer look at the recovery procedure

- severely underdetermined system of linear equations
  - infinitely many solutions
  - want the **sparsest** that explains the data ← **RECOVERY PROCEDURE**

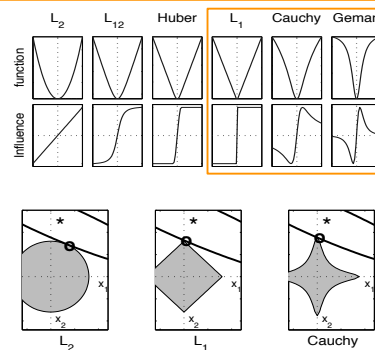
$$\min_x \underbrace{\|x\|_1}_{\text{sparsity}} \quad \text{s.t.} \quad \underbrace{Ax = y}_{\text{perfect reconstruction}}$$

- performance
  - $S$ -sparse vectors recovered from roughly on the order of  $S$  measurements (to within constant and log factors)

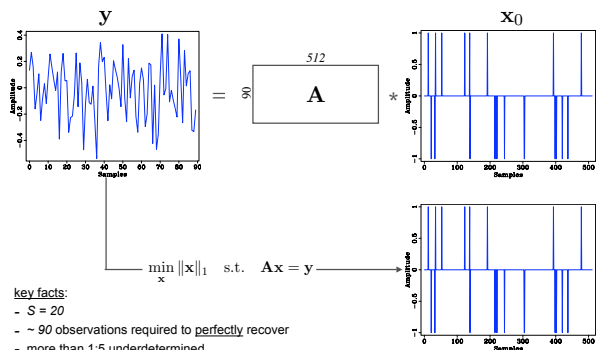
**Note:**

- sparsity measured using  $l_0$  quasi-norm however recovery procedure is combinatorial (intractable!!)
- $l_1$  norm
  - is a convex sparsity-enhancing norm
  - is, under some circumstances, equivalent to  $l_0$  quasi-norm for our recovery procedure
  - makes the recovery procedure stable

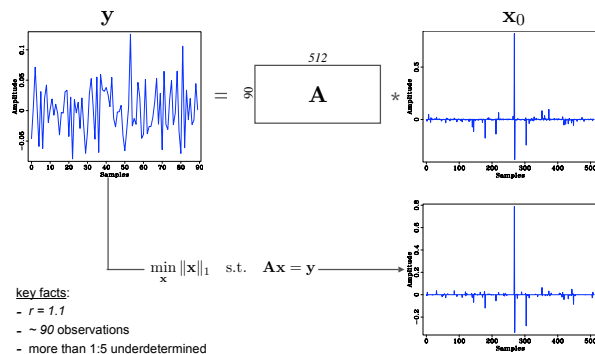
## Sparsity-enhancing norms



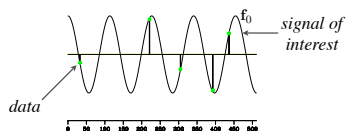
## Example: perfect recovery



## Example: recovery of comp. signals



## General setting



- $f_0$  is not sparse/compressible but  $f_0$  has a sparse/compressible representation, i.e.  $f_0 = S^H x_0$ .

$$y = Ax_0 \quad \text{with} \quad A := RMS^H$$

restriction      measurement      sparsity

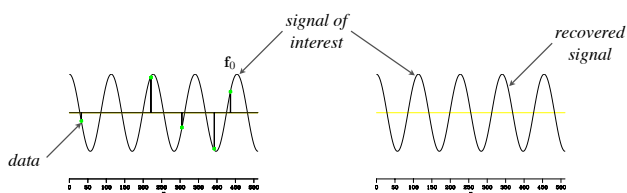
## General recovery condition

- performance
    - $(\# \text{ observations}) \propto \mu^2 \cdot (\# \text{ nnz entries of } x_0)$
- with  $\mu$  the mutual coherence between  $M$  and  $S$ .

**Note:**

- mutual coherency measures the similarity of the columns of  $M$  and  $S$ .
- general recovery key factors:
  - mutual coherency
  - sparsity/compressibility of  $x_0$

## Example: general perfect recovery



### key facts:

- $S = 1$
- ~5 observations required to **perfectly** recover
- more than 1:100 underdetermined

## Stability

$$\mathbf{y} = \mathbf{A} \mathbf{x}_0 + \mathbf{n} \leftarrow \text{error term}$$

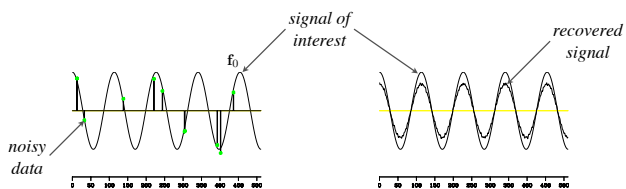
- recovery conditions
  - $\mathbf{x}_0$  is an  $S$ -sparse vector
  - $\mathbf{A}$  obeys the UUP for sets of size  $4S$

- procedure

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_2 \leq \epsilon$$

- performance
  - similar to noise-free but recovery error is on the order of the noise

## Example: recovery from noisy data



### key facts:

- $S = 1$
- ~10 observations (SNR=8.3 dB)
- more than 1:50 underdetermined

## Conclusions

- **sparsity & compressibility** are powerful properties (i.e. extra piece of information about the signal) that offer striking benefits
- stable signal recovery theory provides
  - **robust sampling criteria** as a function of
    - sparsity/compressibility
    - mutual coherence
  - a **stable & tractable recovery procedure** via  $l_1$  minimization

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- E. Candès and J. Romberg for  $l_1$ -magic
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