

Transfer learning in large-scale ocean bottom seismic wavefield reconstruction

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SLIM 



Problem setup

Ocean bottom node (OBN) geometry:

- ▶ desirable source sampling
- ▶ on the grid sparse receivers on Ocean bottom

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Objective:

- ▶ Recover missing receivers from severe subsampling
- ▶ Improve the reconstruction quality & computational efficiency

Previous works

Deep-learning-based wavefield reconstruction:

- ▶ training only relies on acquired data
- ▶ implicit deep “factorization” via a **nonlinear** neural net
- ▶ recover **randomly** or **periodically** from missing receivers
- ▶ **high** missing rates (~90%)

Main contribution

Transfer learning to accelerate the wavefield reconstruction.

Silva, C. D., and F. J. Herrmann, 2013, Hierarchical Tucker tensor optimization - applications to tensor completion: Presented at the Sampling Theory and Applications conference.

Siahkoohi, A., R. Kumar, and F. J. Herrmann, 2019, Deep-learning based ocean bottom seismic wave field recovery: SEG Technical Program Expanded Abstracts 2019.

Seismic data in a 3D survey

Seismic data is 5D:

$(t, \text{Src } x, \text{Src } y, \text{Rec } x, \text{Rec } y)$

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Taking Fourier transfer w.r.t. time:

$(\omega, \text{Src } x, \text{Src } y, \text{Rec } x, \text{Rec } y)$

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Monochromatic seismic data is 4D:

$(\text{Src } x, \text{Src } y, \text{Rec } x, \text{Rec } y)$

Demanet, L., 2006, *Curvelets, wave atoms, and wave equations: PhD thesis, California Institute of Technology.*

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Matricization of monochromatic seismic data

Our framework operates on *monochromatic* frequency slices

(Src x , Src y , Rec x , Rec y)

Demanez, L., 2006, *Curvelets, wave atoms, and wave equations: PhD thesis, California Institute of Technology.*

Silva, C. D., and F. J. Herrmann, 2013, *Hierarchical Tucker tensor optimization - applications to tensor completion: Presented at the Sampling Theory and Applications conference.*

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Matricization of monochromatic seismic data

Our framework operates on *monochromatic* frequency slices

$(\text{Src } x, \text{Src } y, \text{Rec } x, \text{Rec } y)$

Two choices for matricization:

- ▶ $(\text{Rec } x, \text{Rec } y) \times (\text{Src } x, \text{Src } y)$ domain (canonical)
- ▶ $(\text{Rec } y, \text{Src } y) \times (\text{Rec } x, \text{Src } x)$ domain (non-canonical)

Demanet, L., 2006, *Curvelets, wave atoms, and wave equations: PhD thesis, California Institute of Technology.*

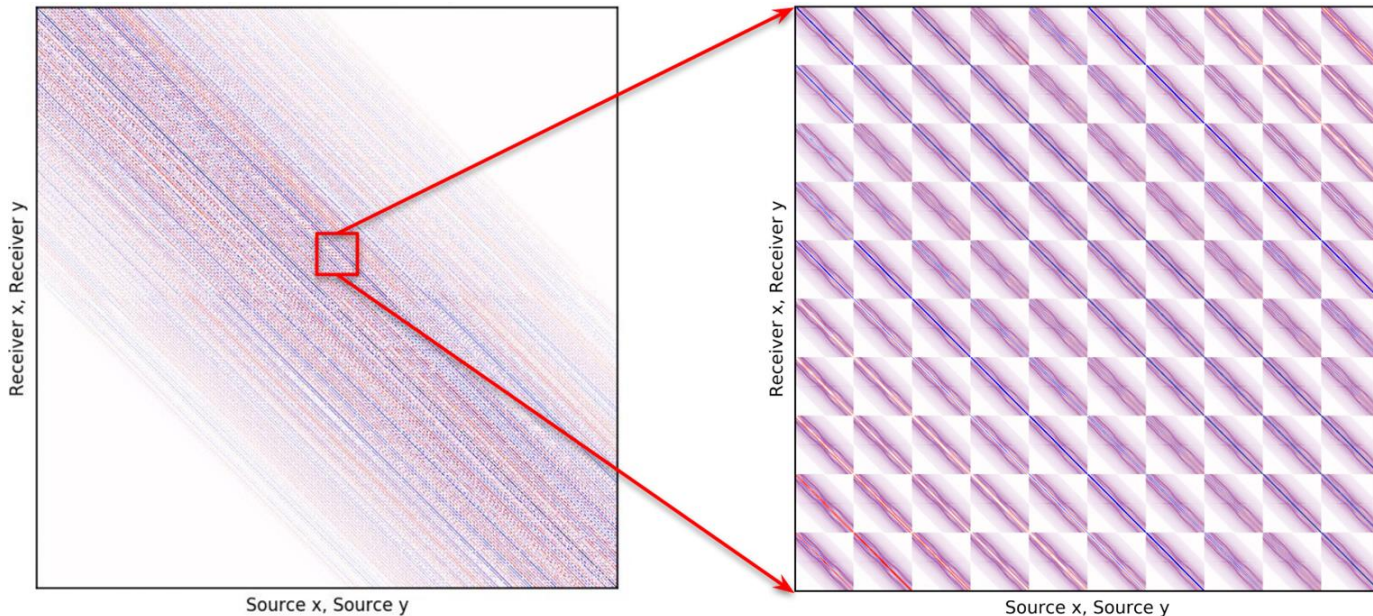
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fully-sampled data



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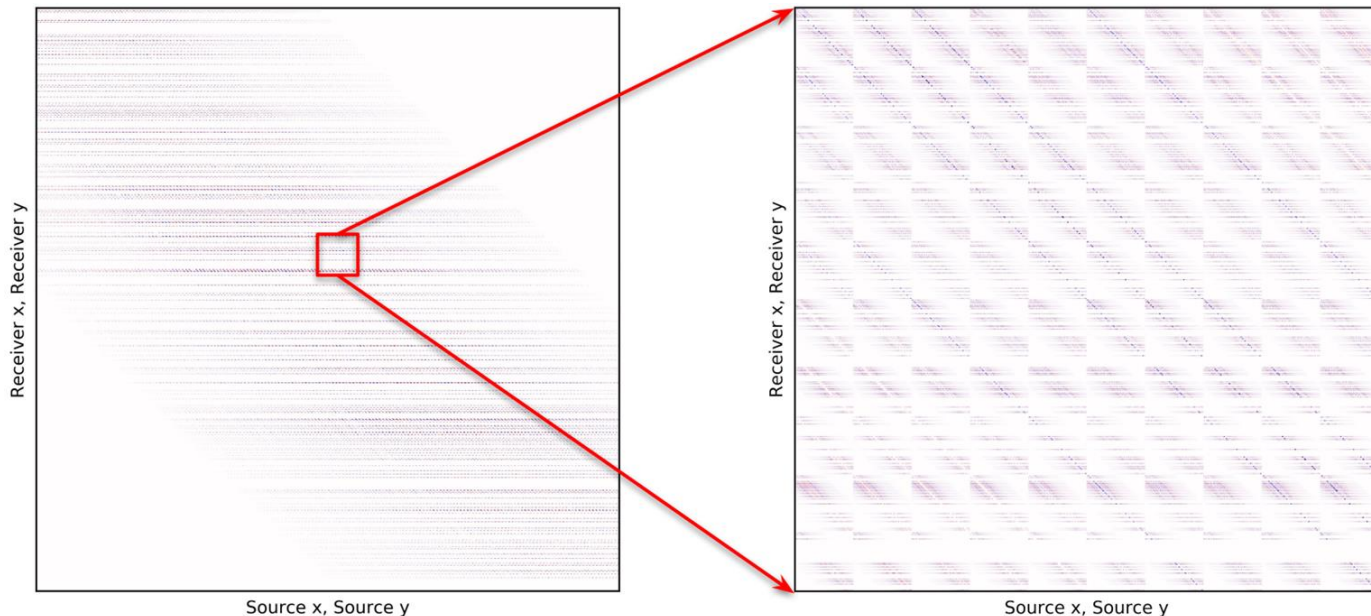
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observed data – sampling rate 10%



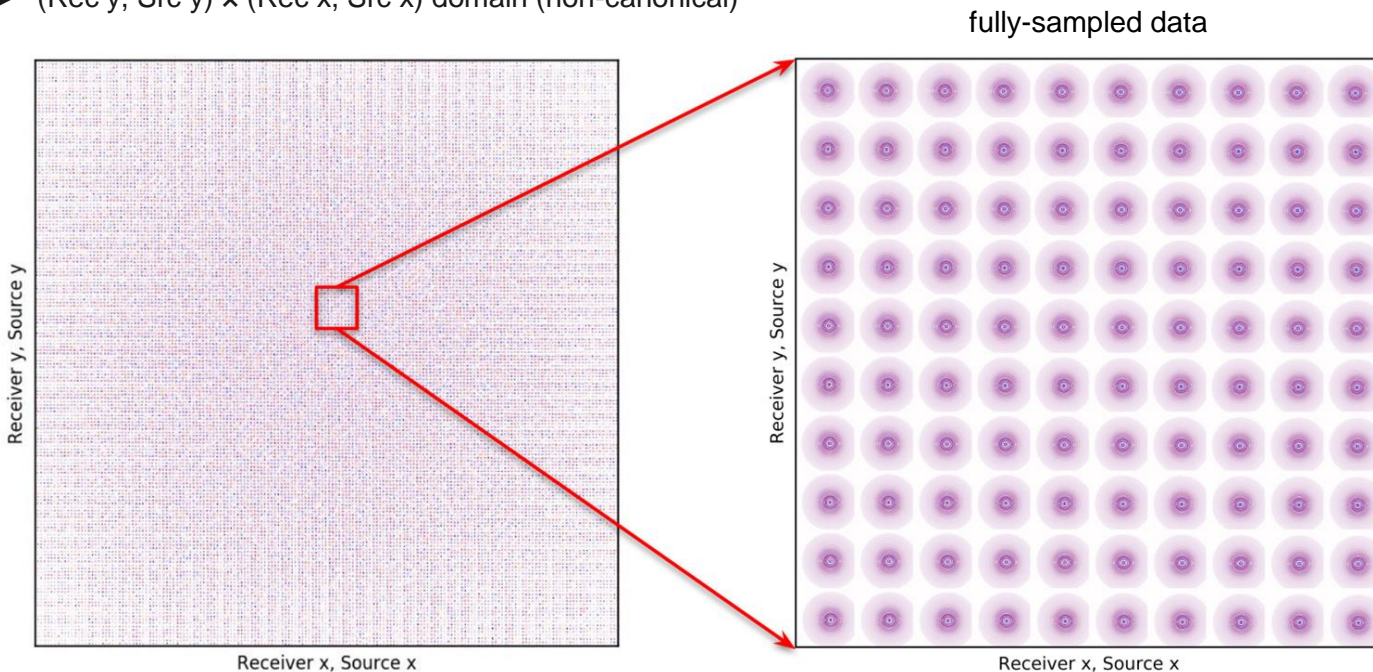
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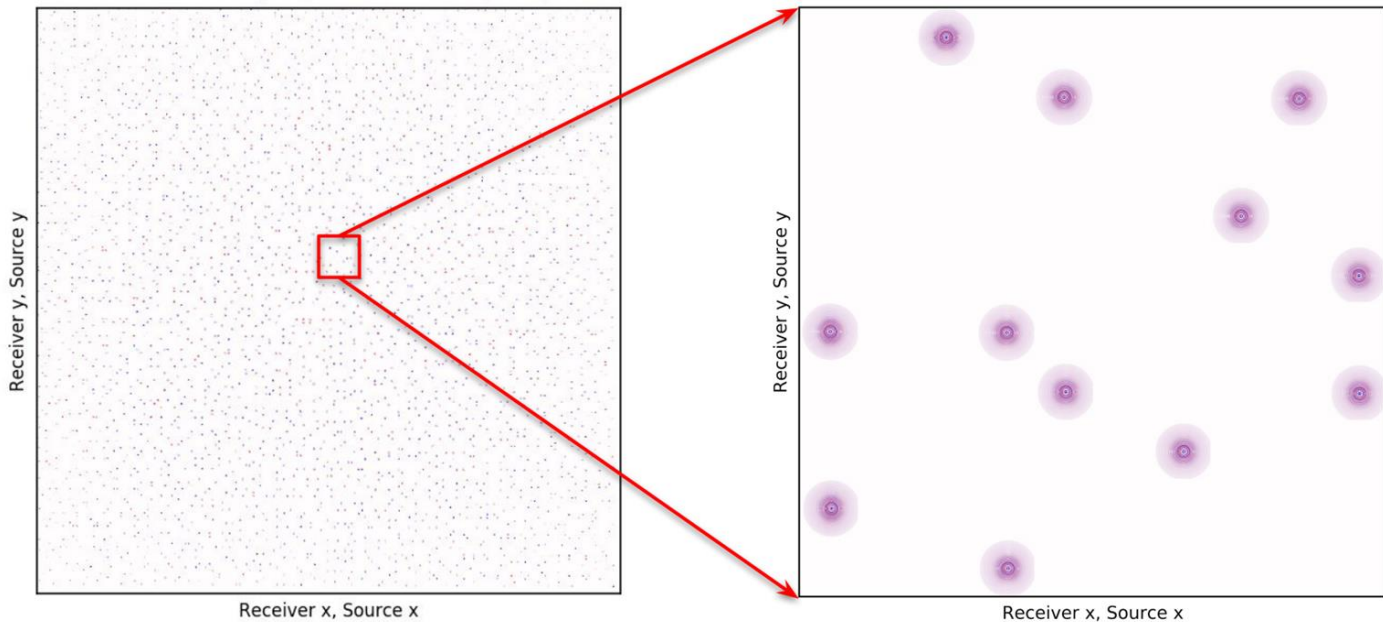
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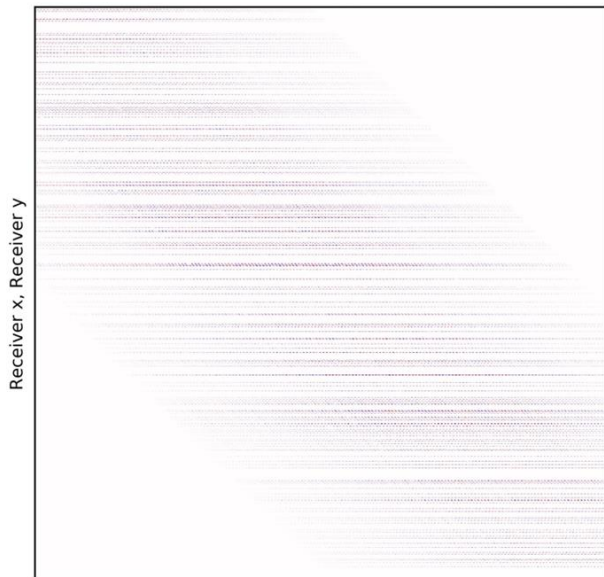
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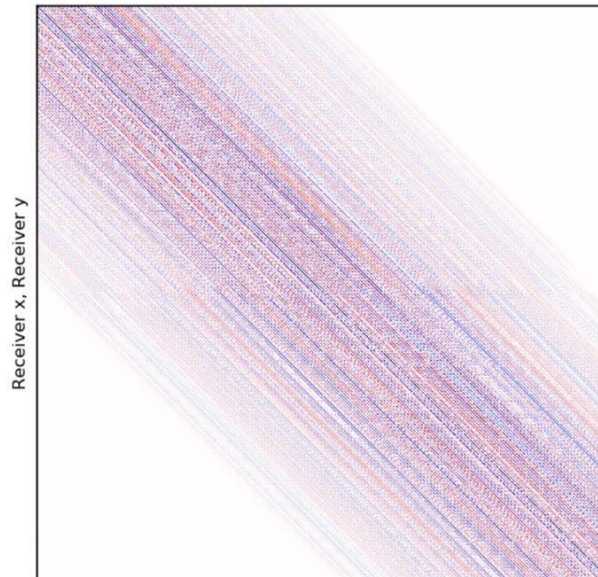
Siahkoohi, A., R. Kumar, and F. J. Herrmann, 2019, *Deep-learning based ocean bottom seismic wave field recovery: SEG Technical Program Expanded Abstracts 2019.*

Objective 1: Recover missing receivers

observed monochromatic data



desired monochromatic seismic data



Source x, Source y

Source x, Source y

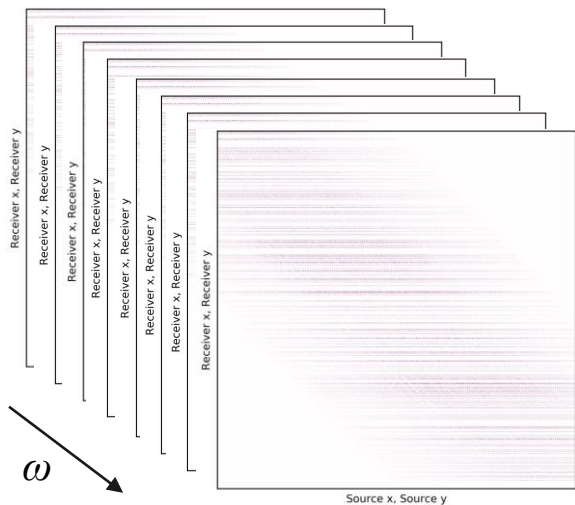
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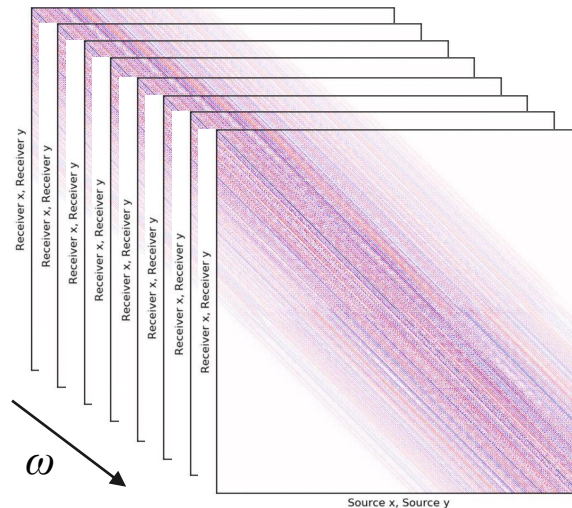
Siahkoohi, A., R. Kumar, and F. J. Herrmann, 2019, *Deep-learning based ocean bottom seismic wave field recovery: SEG Technical Program Expanded Abstracts 2019.*

Objective 2: Speed up the reconstruction

observed all frequency slices



desired all frequency slices



Mao X, Li Q, Xie H, Lau RY, Wang Z, Paul Smolley S. Least squares generative adversarial networks. In Proceedings of the IEEE International Conference on Computer Vision 2017, pages 2794-2802.

Phillip Isola, Jun-Yan Zhu, Tinghui Zhou, and Alexei A. Efros. Image-to-Image Translation with Conditional Adversarial Networks. In The IEEE Conference on Computer Vision and Pattern Recognition (CVPR), pages 5967-5976, July 2017.

Siahkoobi, A., R. Kumar, and F. J. Herrmann, 2019, Deep-learning based ocean bottom seismic wave field recovery: SEG Technical Program Expanded Abstracts 2019.

Training framework: Generative Adversarial Network (GAN)

$$\min_{\theta} \mathbb{E}_{\mathbf{X} \sim p(\mathbf{X})} \left[(1 - \mathcal{D}_{\phi}(\mathcal{G}_{\theta}(\mathbf{M} \odot \mathbf{X})))^2 + \lambda \|\mathcal{G}_{\theta}(\mathbf{M} \odot \mathbf{X}) - \mathbf{X}\|_1 \right],$$

$$\min_{\phi} \mathbb{E}_{\mathbf{X} \sim p(\mathbf{X})} \left[(\mathcal{D}_{\phi}(\mathcal{G}_{\theta}(\mathbf{M} \odot \mathbf{X})))^2 + (1 - \mathcal{D}_{\phi}(\mathbf{X}))^2 \right],$$

\mathbf{X} : input ground truth drawn from the probability distributions $p(\mathbf{X})$

\mathcal{G}_{θ} : generator \mathcal{D}_{ϕ} : discriminator \mathbf{M} : training mask

λ : ensures that each realization of discriminator maps to a particular input, i.e., rather than solely fooling the discriminator.

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Training pair: $(\mathbf{M} \odot \mathbf{X}, \mathbf{X})$

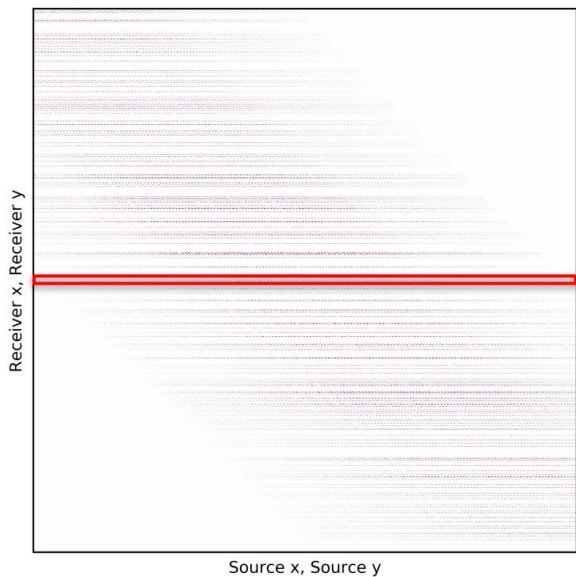
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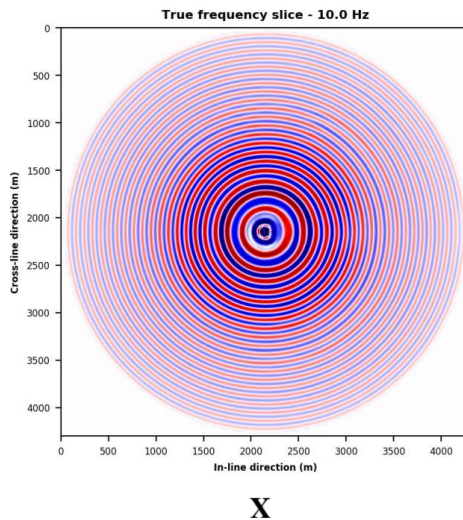
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Extract training pairs for training

- ▶ (Rec x, Rec y) × (Src x, Src y) domain

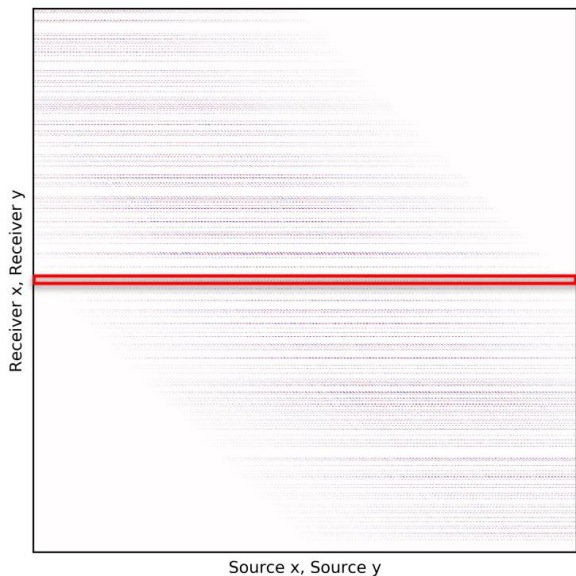


reshape 

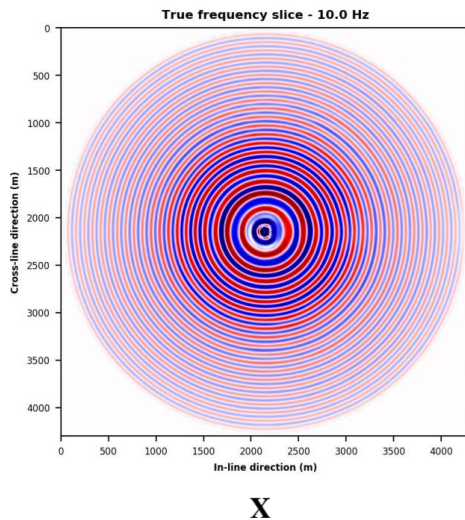


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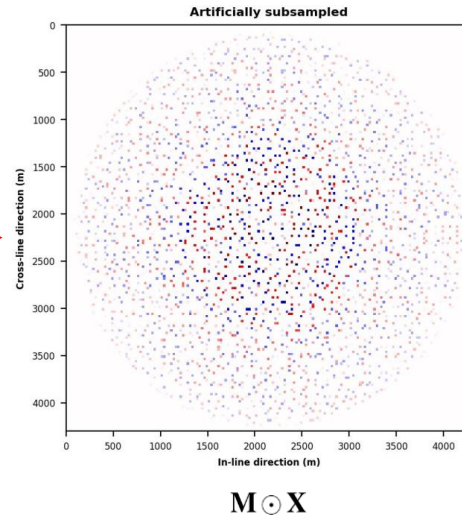
- (Rec x, Rec y) × (Src x, Src y) domain



reshape 

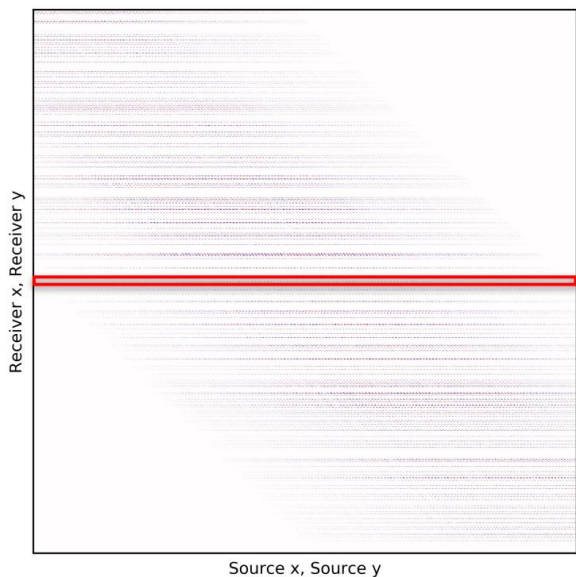


M 

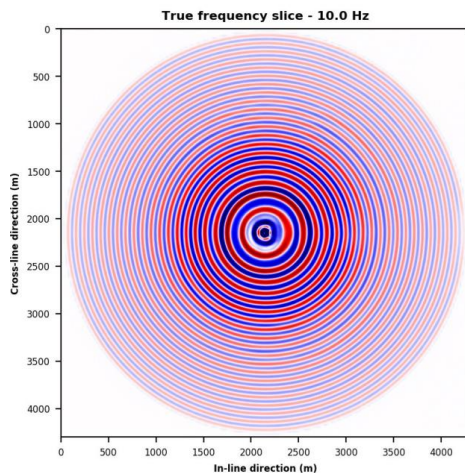


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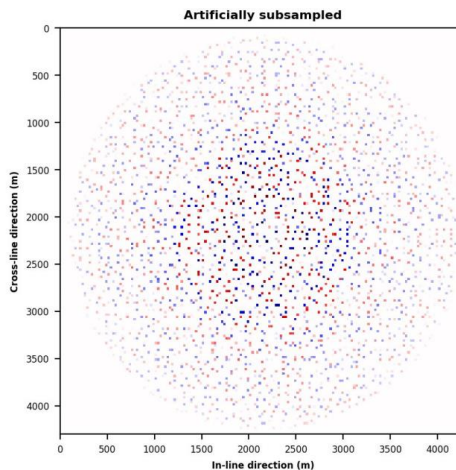


reshape



\mathbf{X}

\mathbf{M}



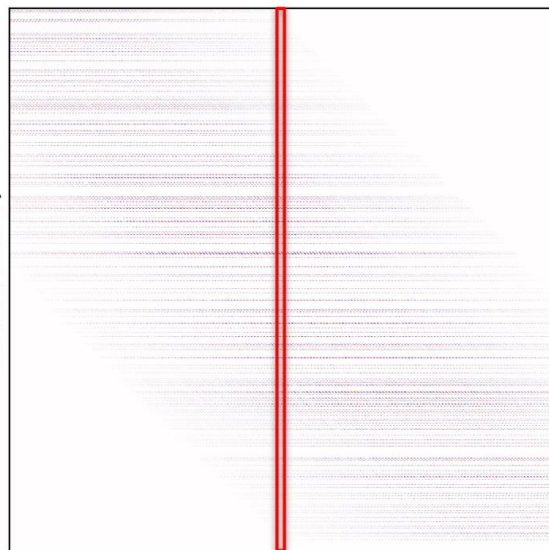
$\mathbf{M} \odot \mathbf{X}$

Training pair: $(\mathbf{M} \odot \mathbf{X}, \mathbf{X}) \longrightarrow \mathcal{G}_\theta \checkmark$

Testing Stage: reconstruction

G_{θ} ✓

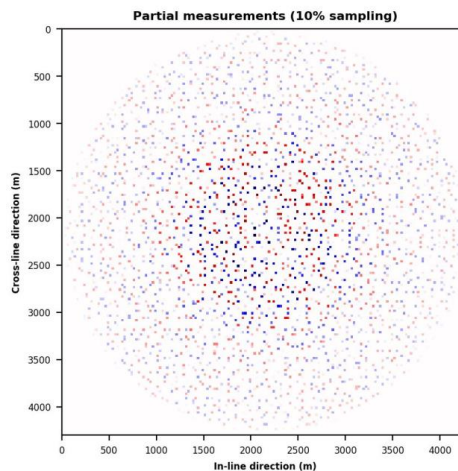
► (Rec x, Rec y) × (Src x, Src y) domain



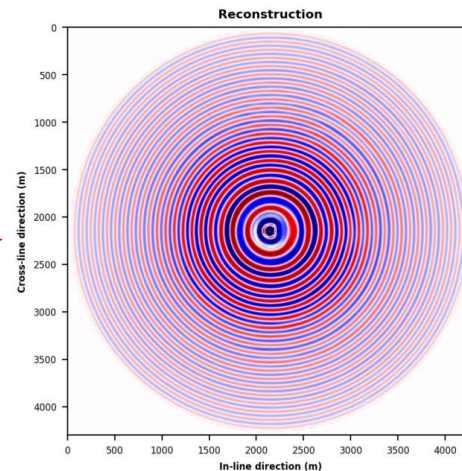
Source x, Source y

reshape →

source-receiver reciprocity



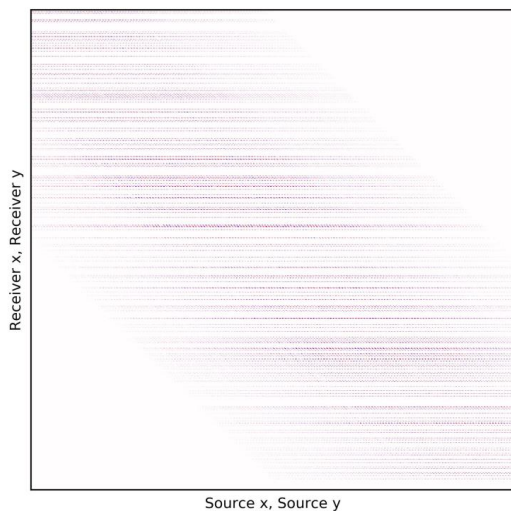
G_{θ} →



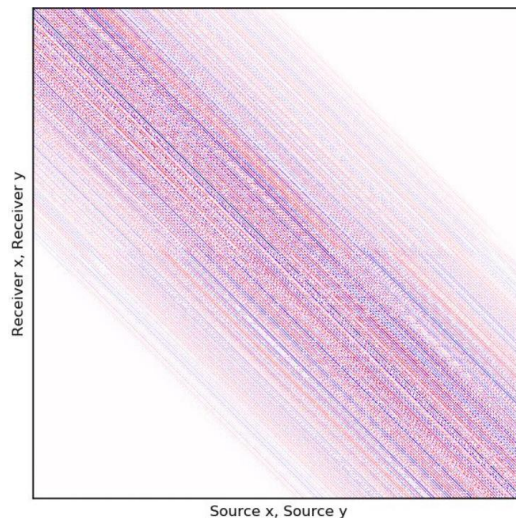
apply the trained neural network to all columns

The problem of the deep-learning-based method

- ▶ $(\text{Rec } x, \text{Rec } y) \times (\text{Src } x, \text{Src } y)$ domain



train from scratch




Problem: each frequency slice is treated independently



high training costs

Transfer learning to speed up the reconstruction


Problem: each frequency slice is treated independently  high training costs

Solution: train from scratch



exploit frequency-to-frequency similarities

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train from transferred weights from neighboring frequencies
(do recursively for all frequencies from low to high)

Transfer learning to speed up the reconstruction

Problem: each frequency slice is treated independently \longrightarrow high training costs

Solution: train from scratch



exploit frequency-to-frequency similarities



train from transferred weights from neighboring frequencies \longrightarrow lower training costs
(do recursively for all frequencies from low to high)

Numerical experiments

Numerically simulated data on 3D BG Compass model

- ▶ 172×172 2D periodic source grid
- ▶ 172×172 2D periodic receiver grid
- ▶ spatial subsampling in both horizontal directions
- ▶ complex velocity model w/ strong vertical & lateral variations

Numerical experiments

We know the missing pattern of receivers

Training mask:

- ▶ **previous:** training mask equal to the missing receiver sampling mask

Numerical experiments

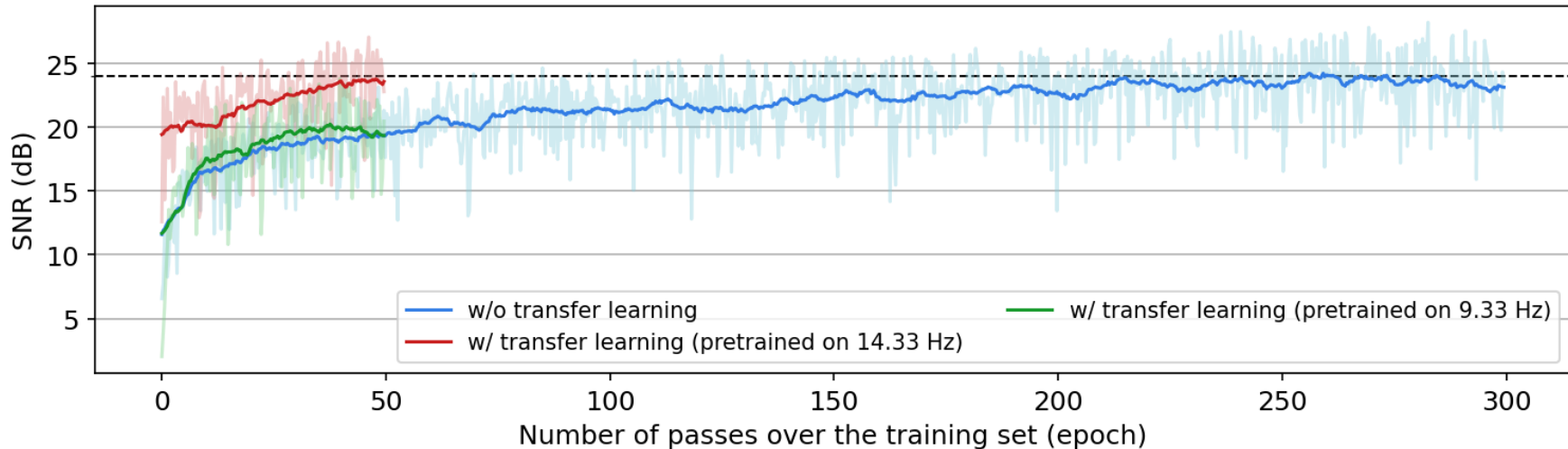
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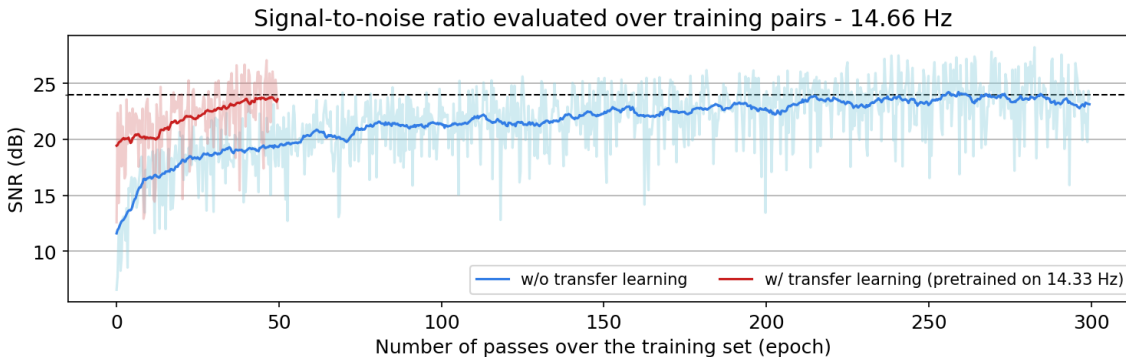
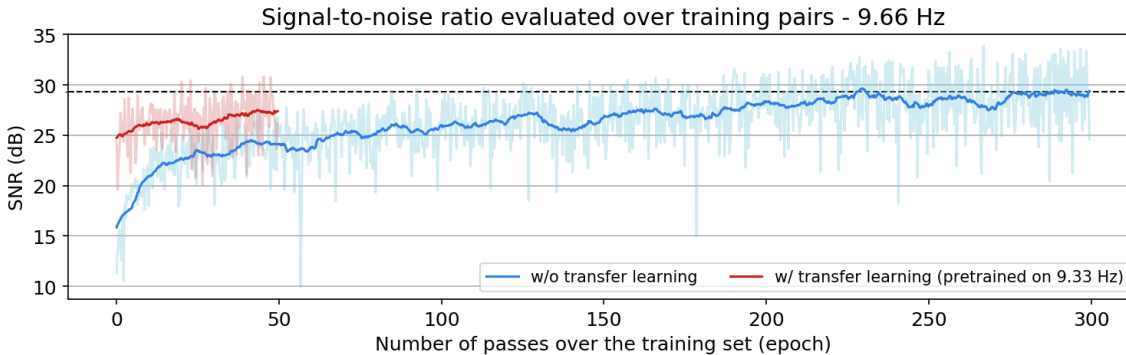
- ▶ **previous:** training mask equal to the missing receiver sampling mask
- ▶ **now:** change the training mask (with a same missing rate) at every epoch

Similarity: neighboring frequency slices > non-neighboring frequency slices
(14.33 Hz -> 14.66 Hz) (9.33 Hz -> 14.66 Hz)

Signal-to-noise ratio evaluated over training pairs - 14.66 Hz



Similarity: (14.33 Hz -> 14.66 Hz) > (9.33 Hz -> 9.66 Hz)

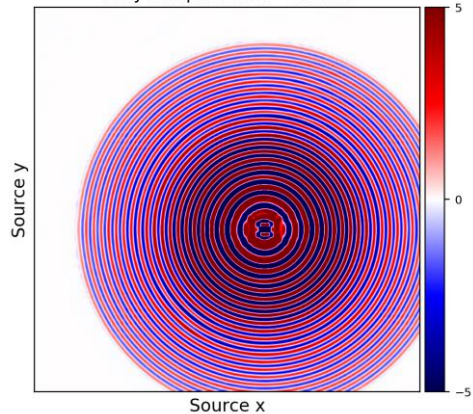


~ six fold speedup

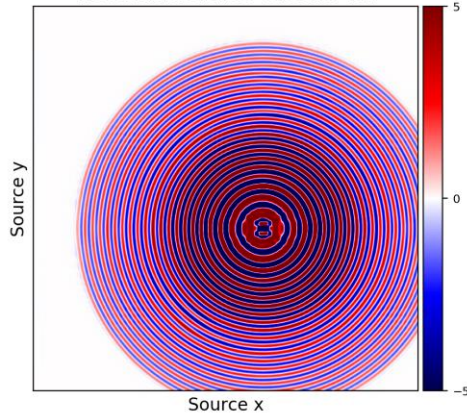
Reconstruction performance

Frequency: 9.66 Hz
Neighboring: 9.33 Hz

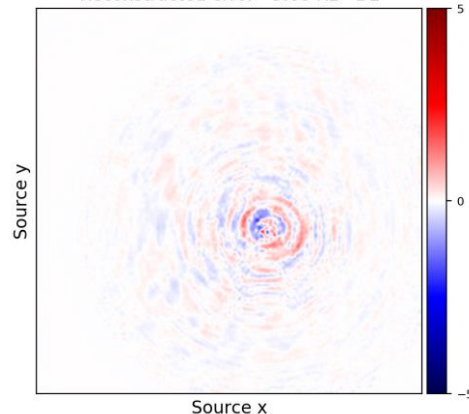
Fully sampled data - 9.66 Hz



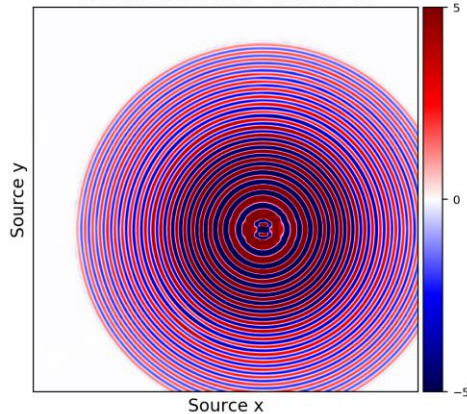
Reconstructed data - 9.66 Hz - DL



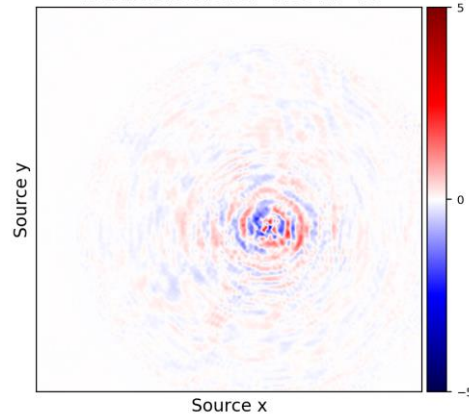
Reconstructed error - 9.66 Hz - DL



Reconstructed data - 9.66 Hz - TL



Reconstructed error - 9.66 Hz - TL



Training from scratch:
300 epochs

Transfer learning from
9.33 Hz: **50 epochs**

Reconstruction performance

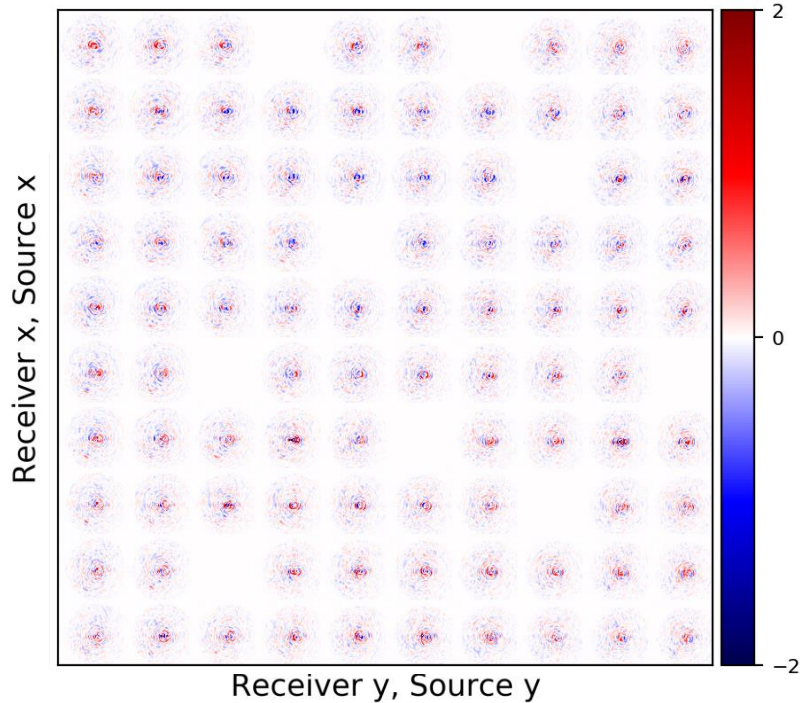
► (Rec y, Src y) × (Rec x, Src x) domain (non-canonical)

Training from scratch: **300 epochs**

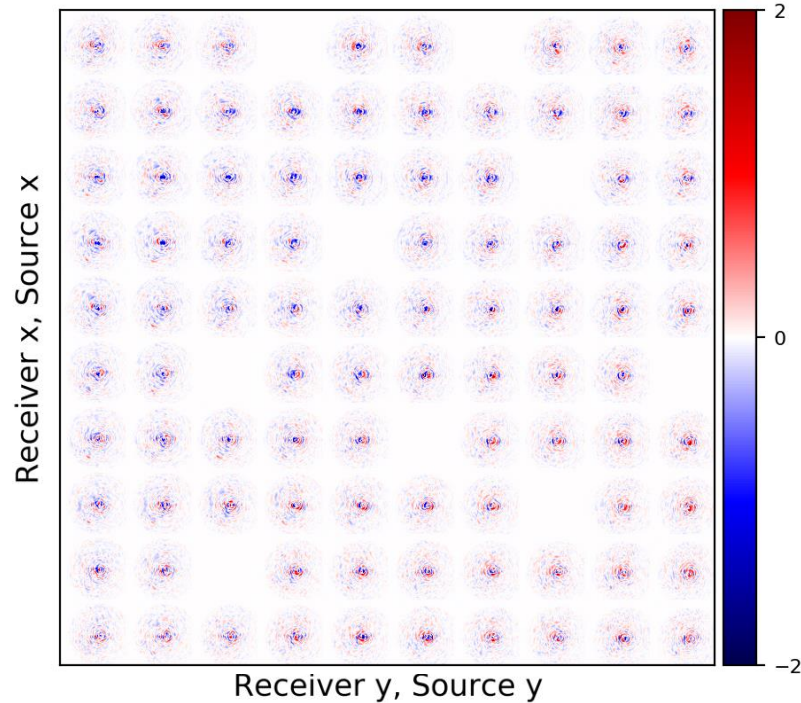


Transfer learning from 9.33 Hz: **50 epochs**

Reconstructed error - 9.66 Hz - DL



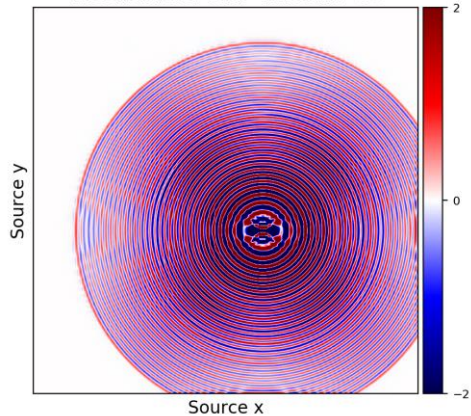
Reconstructed error - 9.66 Hz - TL



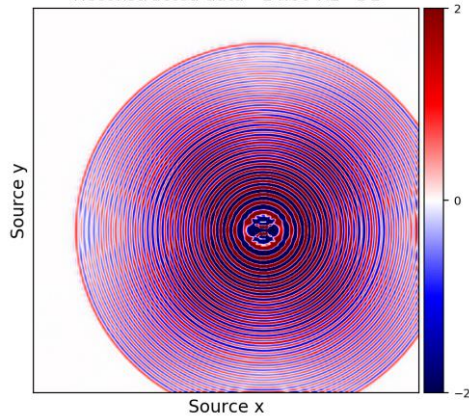
Reconstruction performance

Frequency: 14.66 Hz
Neighboring: 14.33 Hz

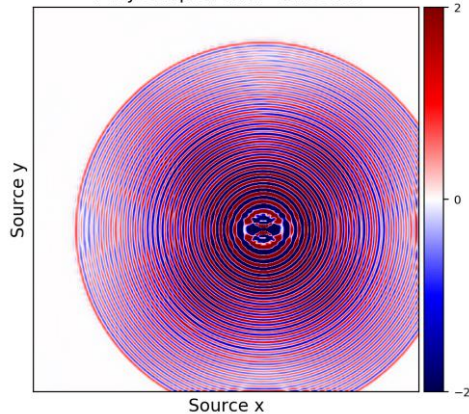
Reconstructed data - 14.66 Hz - TL



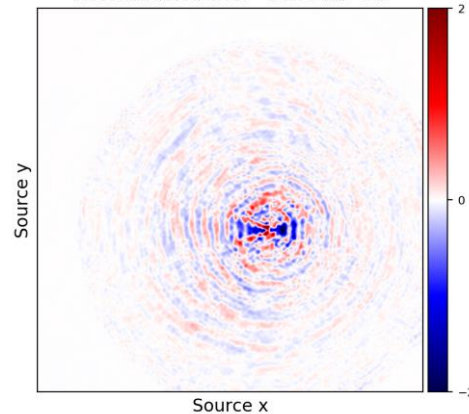
Reconstructed data - 14.66 Hz - DL



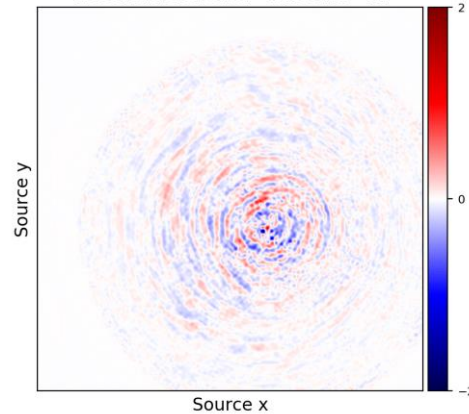
Fully sampled data - 14.66 Hz



Reconstructed error - 14.66 Hz - DL



Reconstructed error - 14.66 Hz - TL



Training from scratch:
300 epochs

SNR: 17.18 dB

Transfer learning from
14.33 Hz: **50 epochs**

SNR: 18.09 dB



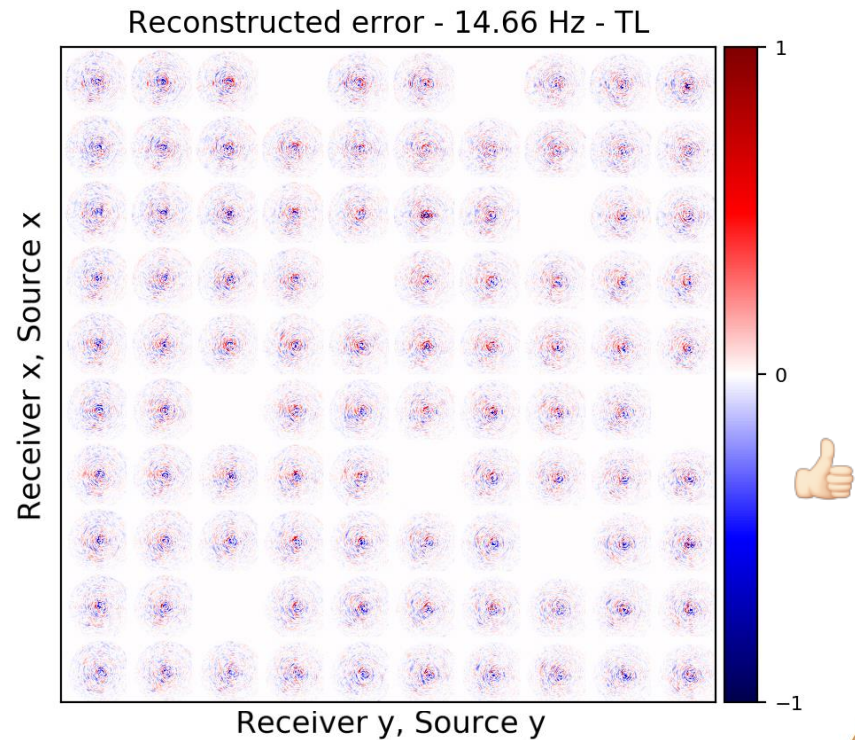
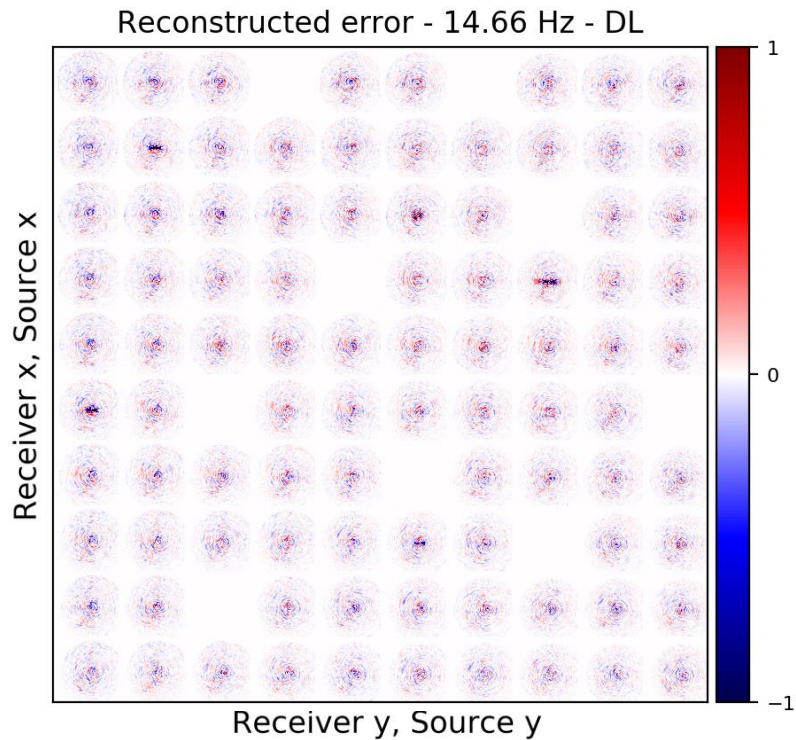
Reconstruction performance

► (Rec y, Src y) × (Rec x, Src x) domain (non-canonical)

Training from scratch: **300 epochs**



Transfer learning from 14.33 Hz: **50 epochs**



Conclusions

The method does not need any external training data, assuming:

- ▶ desirable source sampling
- ▶ source-receiver reciprocity

Transfer learning (recursively for all frequencies) can significantly **speed up** in the training, specially at consecutive frequency slices with relatively **high correlation**.

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Future work: improve the reconstruction accuracy of high-frequency slices

Thank you for your attention!



<https://github.com/slimgroup/Software.SEG2020>