

Source separation via SVD-free rank-minimization in the hierarchical semi-separable representation

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Conventional marine acquisition

★ source depth = 10 m

regularly sampled spatial grid →

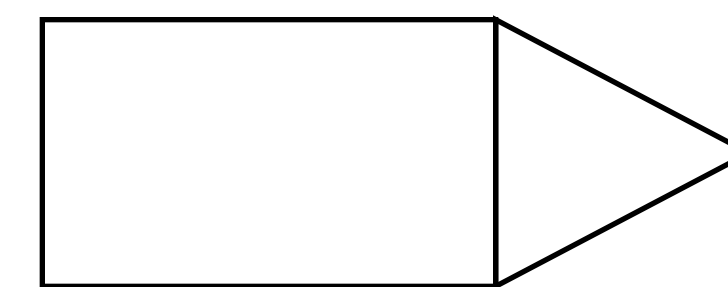
shot 1



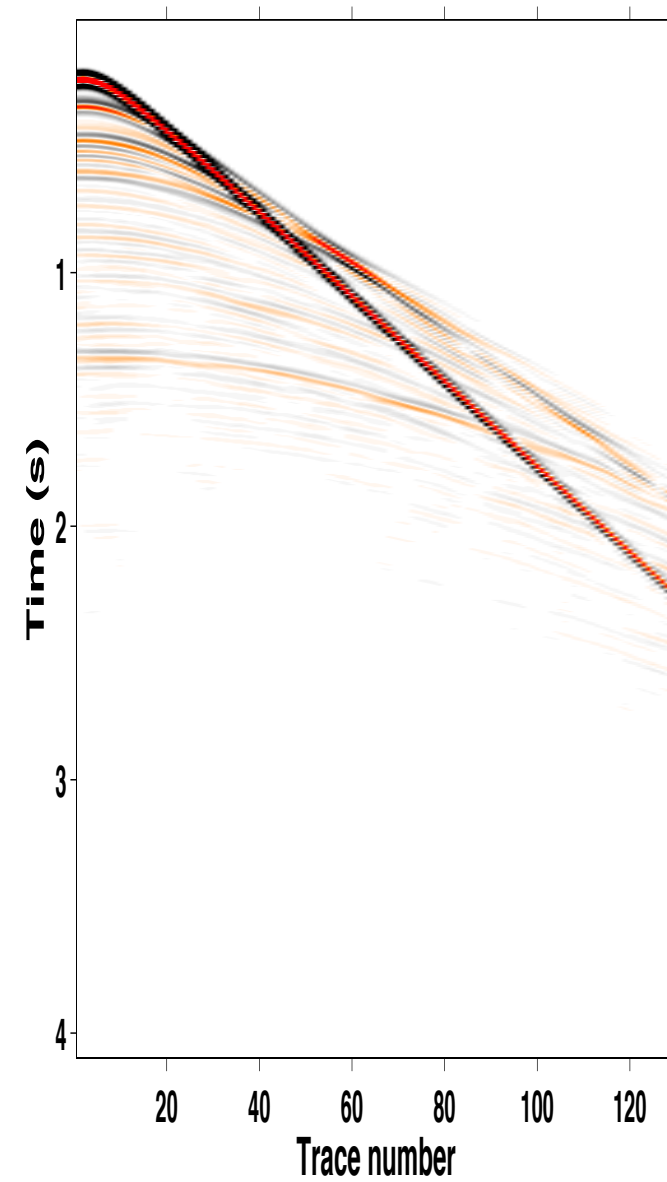
shot 2



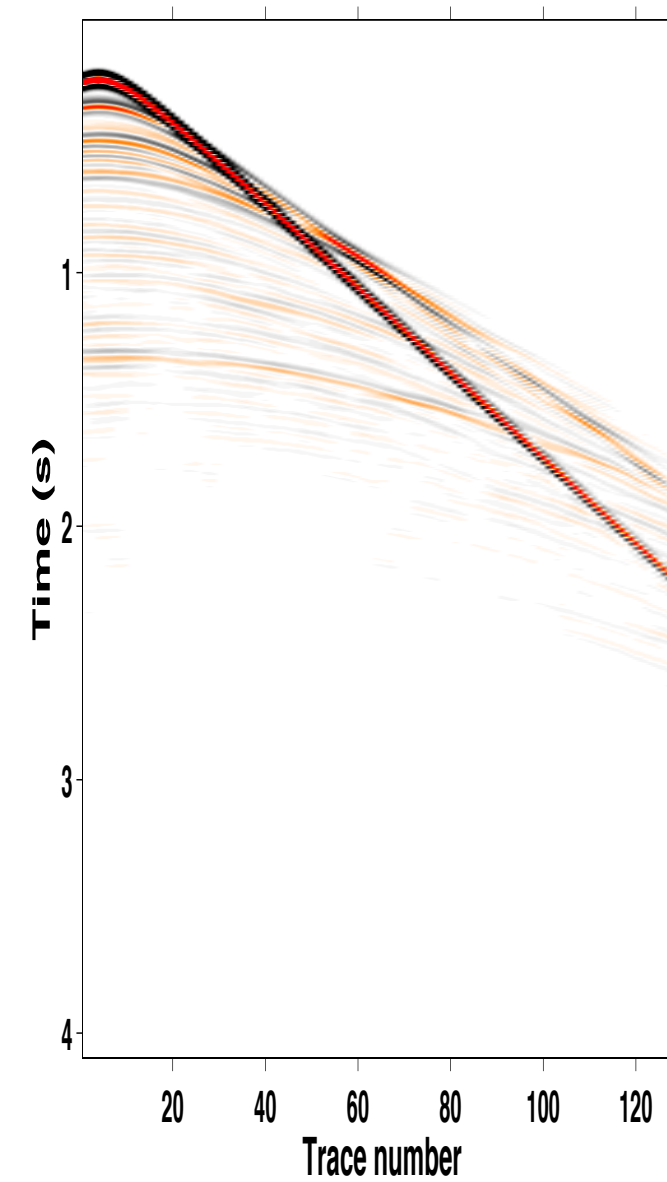
shot 3



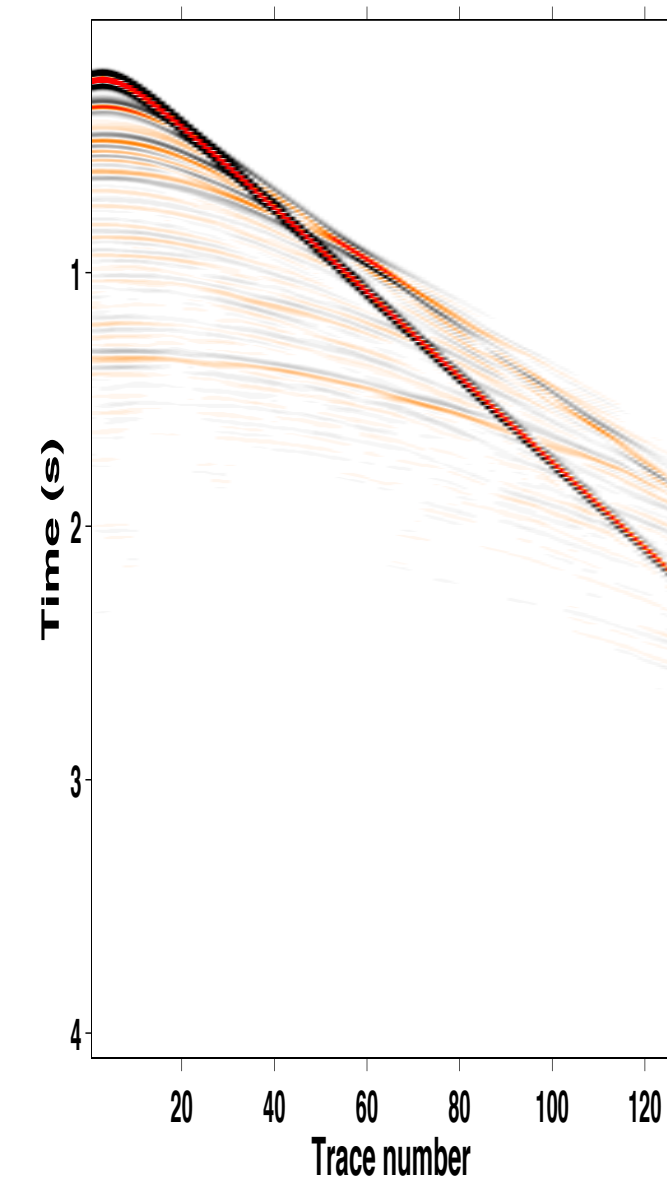
shot 1



shot 2

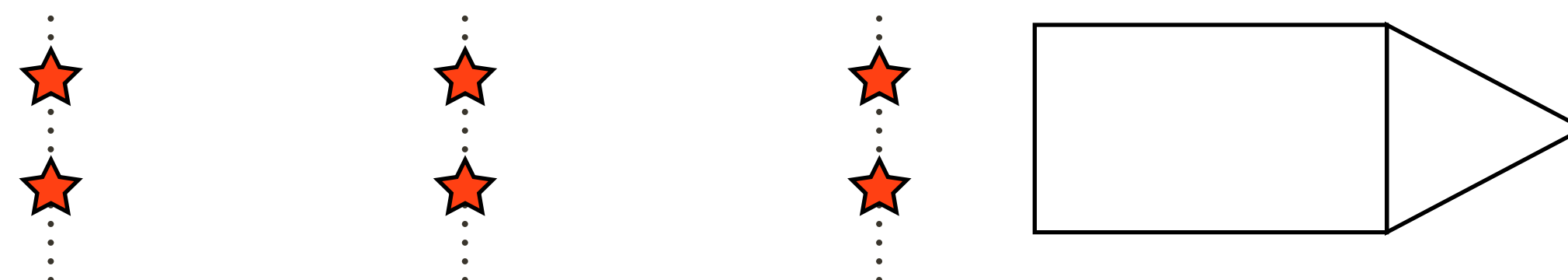


shot 3

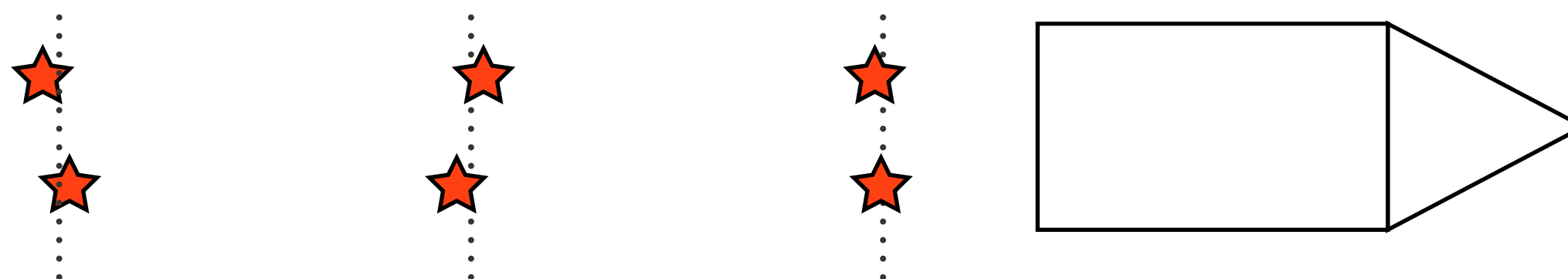


Blended/Simultaneous marine acquisition

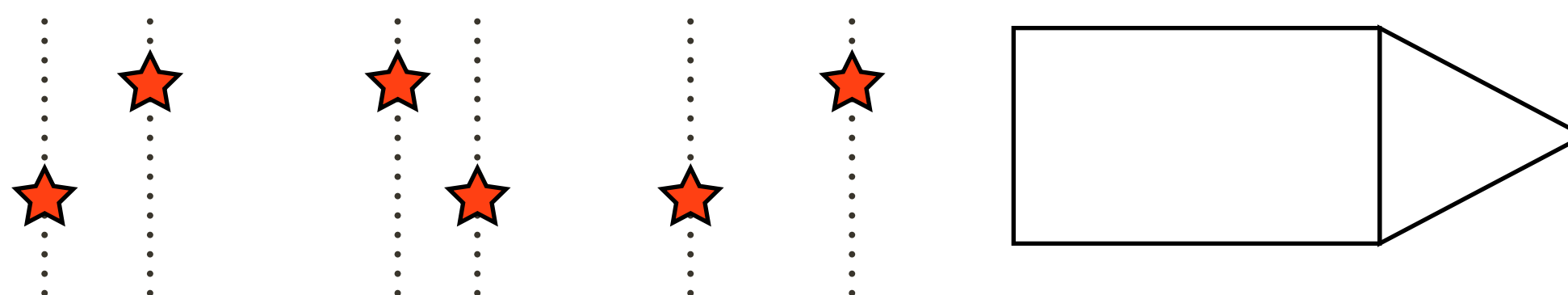
regularly sampled spatial grid



almost regularly sampled spatial grid
(over/under acquisition)



irregularly sampled spatial grid
(SLIM acquisition)



[Mansour et. al., 2012]
[Wason and Herrmann, 2013]

Blended/Simultaneous marine acquisition

[over/under acquisition]

regularly sampled spatial grid
(almost)

shot-time randomness - **LOW**

★ source1 depth = 10 m

★ source2 depth = 15 m

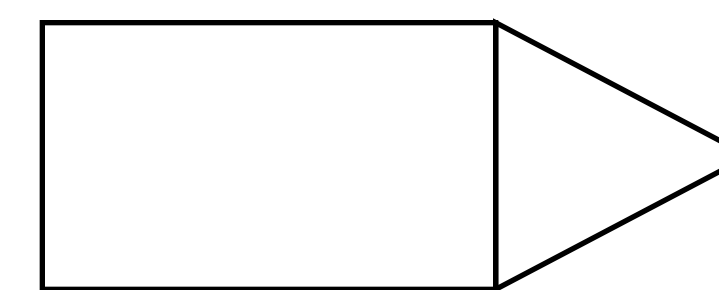
shot 1



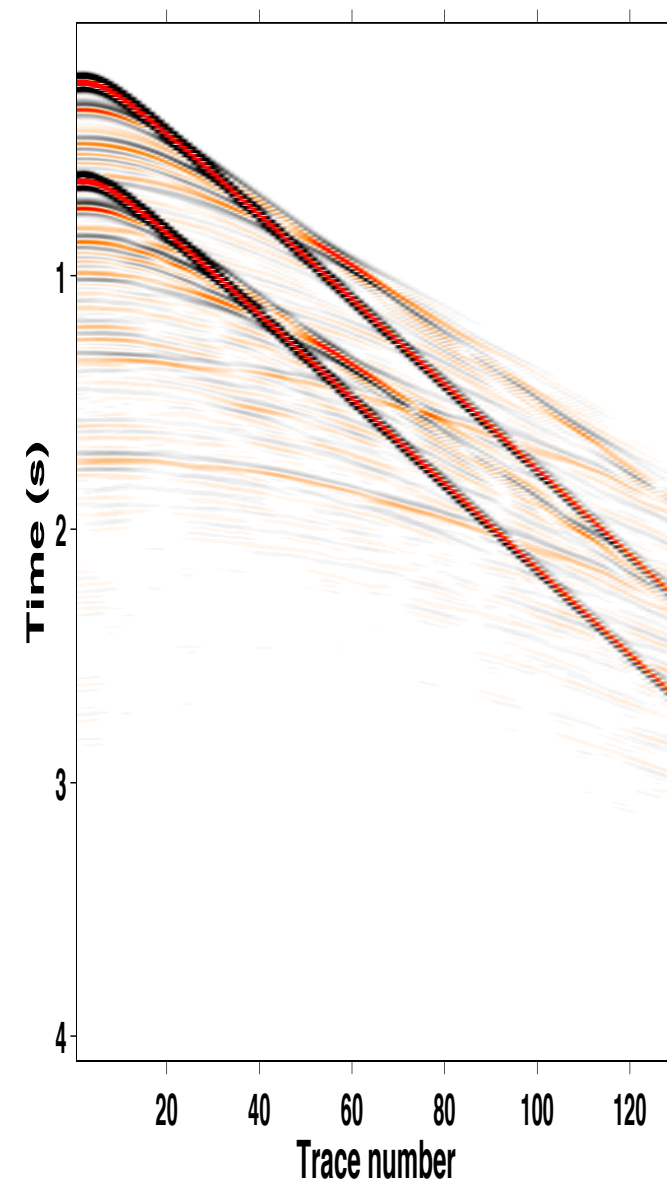
shot 2



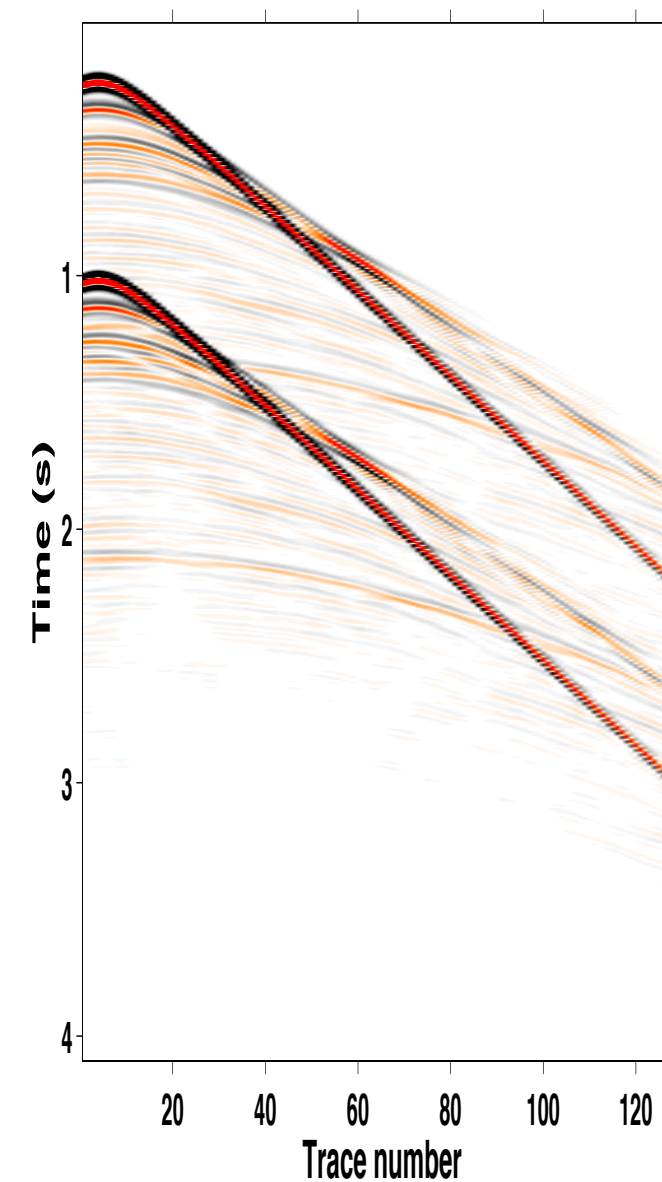
shot 3



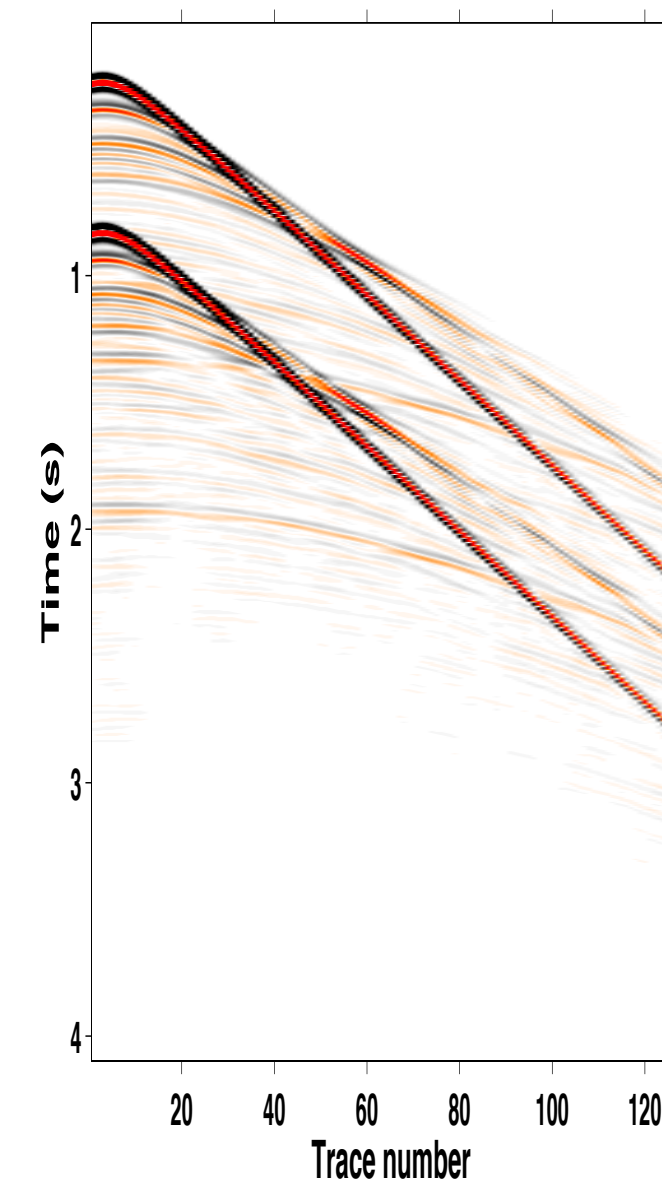
shot 1



shot 2



shot 3



Challenges

- ▶ Source separation (or deblending)
 - recover individual datasets
- ▶ Shot-time randomness
 - low

Compressed sensing

Successful sampling & reconstruction scheme

- ▶ exploit *structure* via *sparsifying* transform
 - *fast decay* of “transform domain” coefficients
- ▶ sampling
 - randomly blended data *decreases* sparsity in “transform domain”
- ▶ optimization
 - via *sparsity-promotion*

Matrix completion

Successful reconstruction scheme

- ▶ exploit *structure*
 - *low-rank / fast decay* of singular values
- ▶ sampling
 - randomly blended data *increases* rank in “transform domain”
- ▶ optimization
 - via *rank-minimization (nuclear norm-minimization)*

Low-rank structure

In which domain?

source-receiver or midpoint-offset

Blended data (w/o delay)

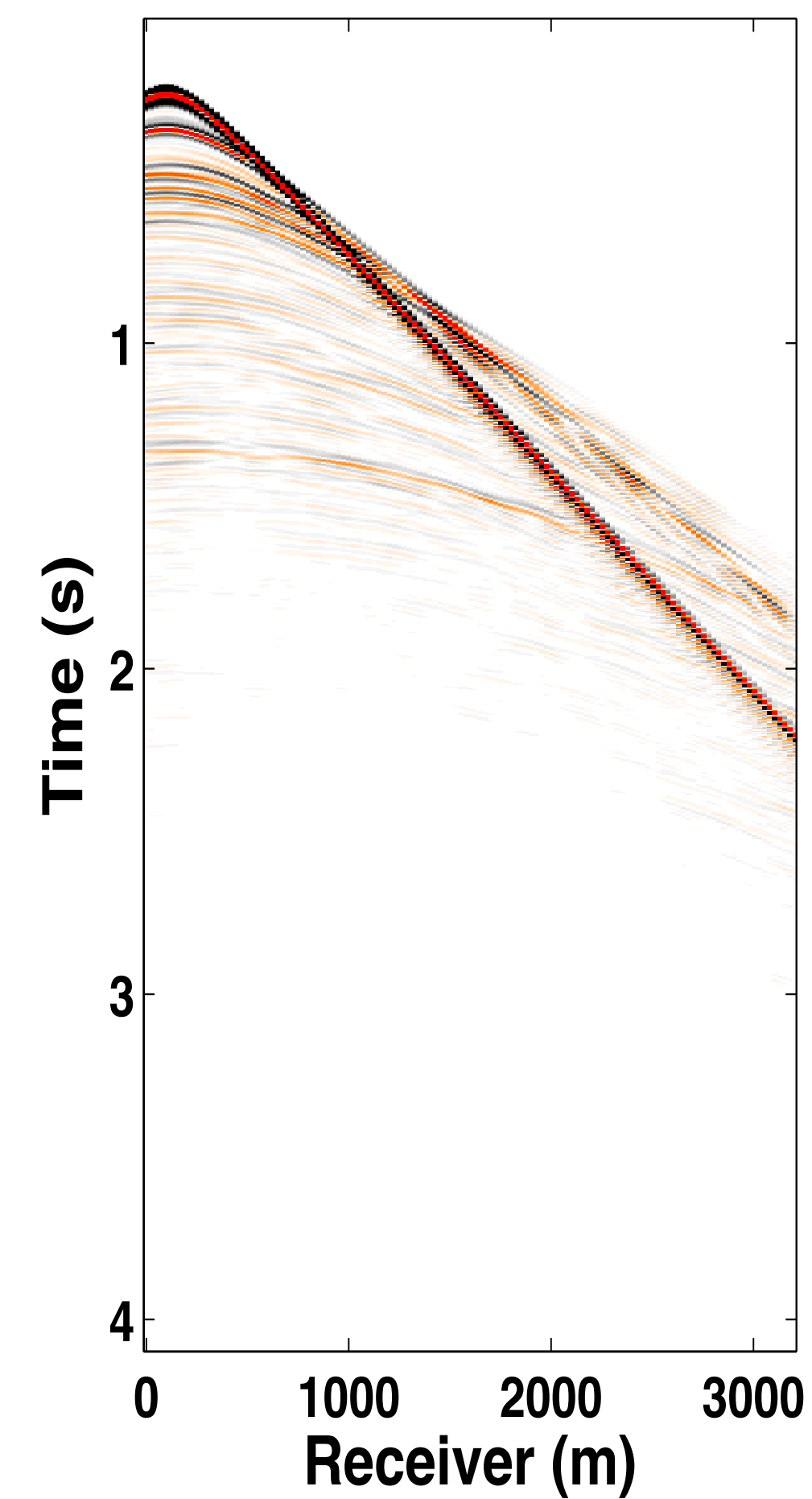
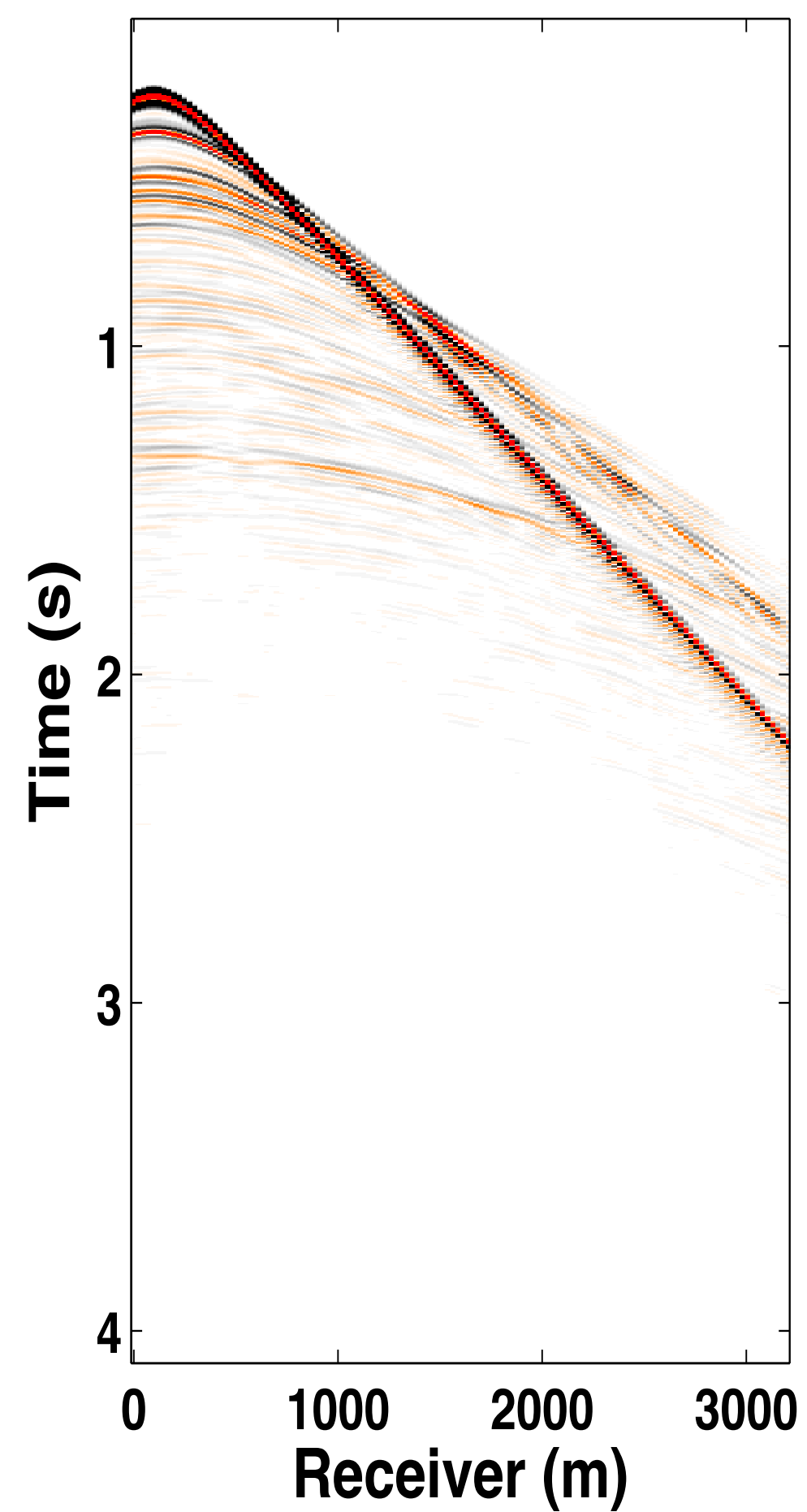
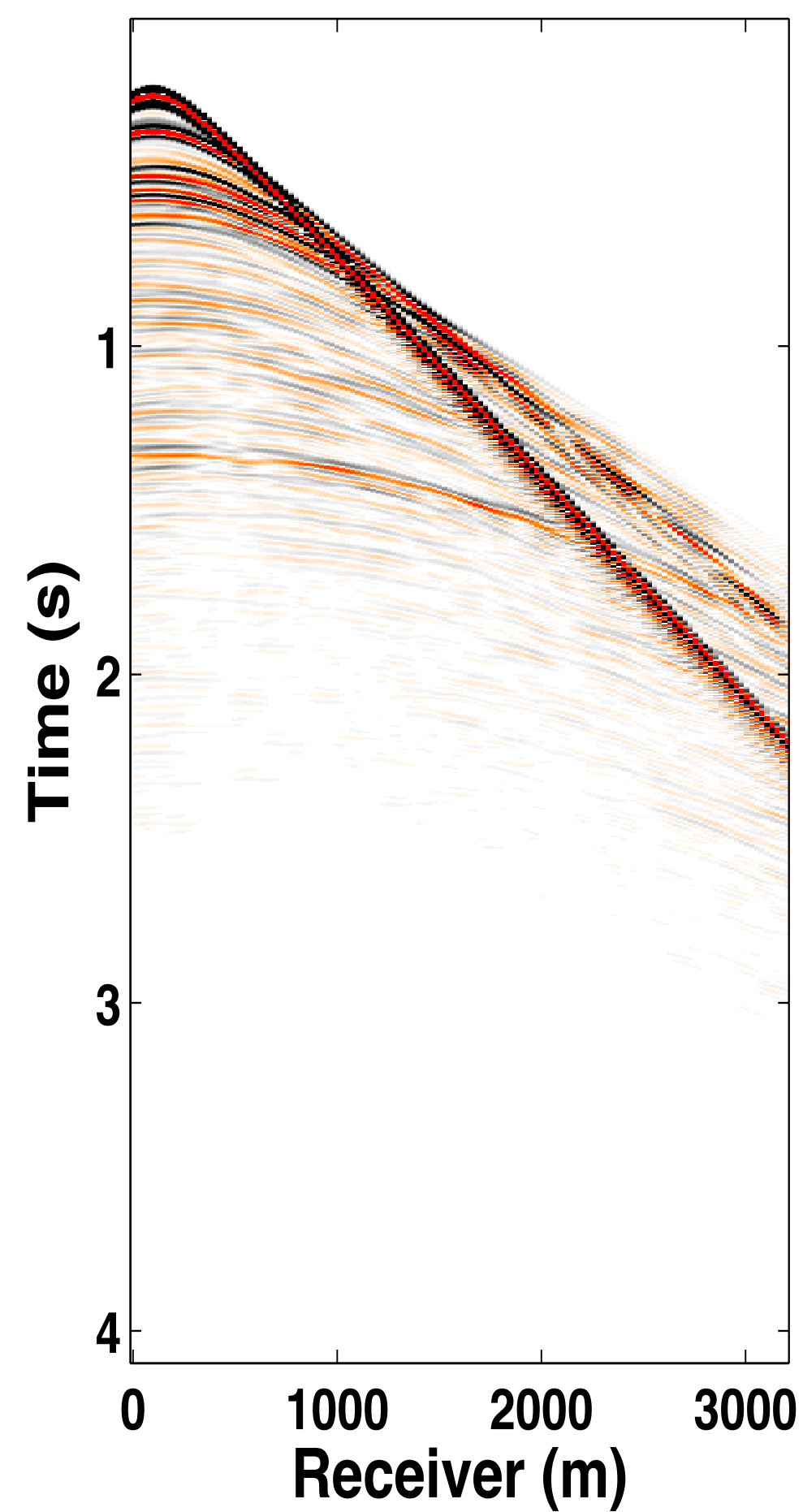
blended shot

=

source 1

+

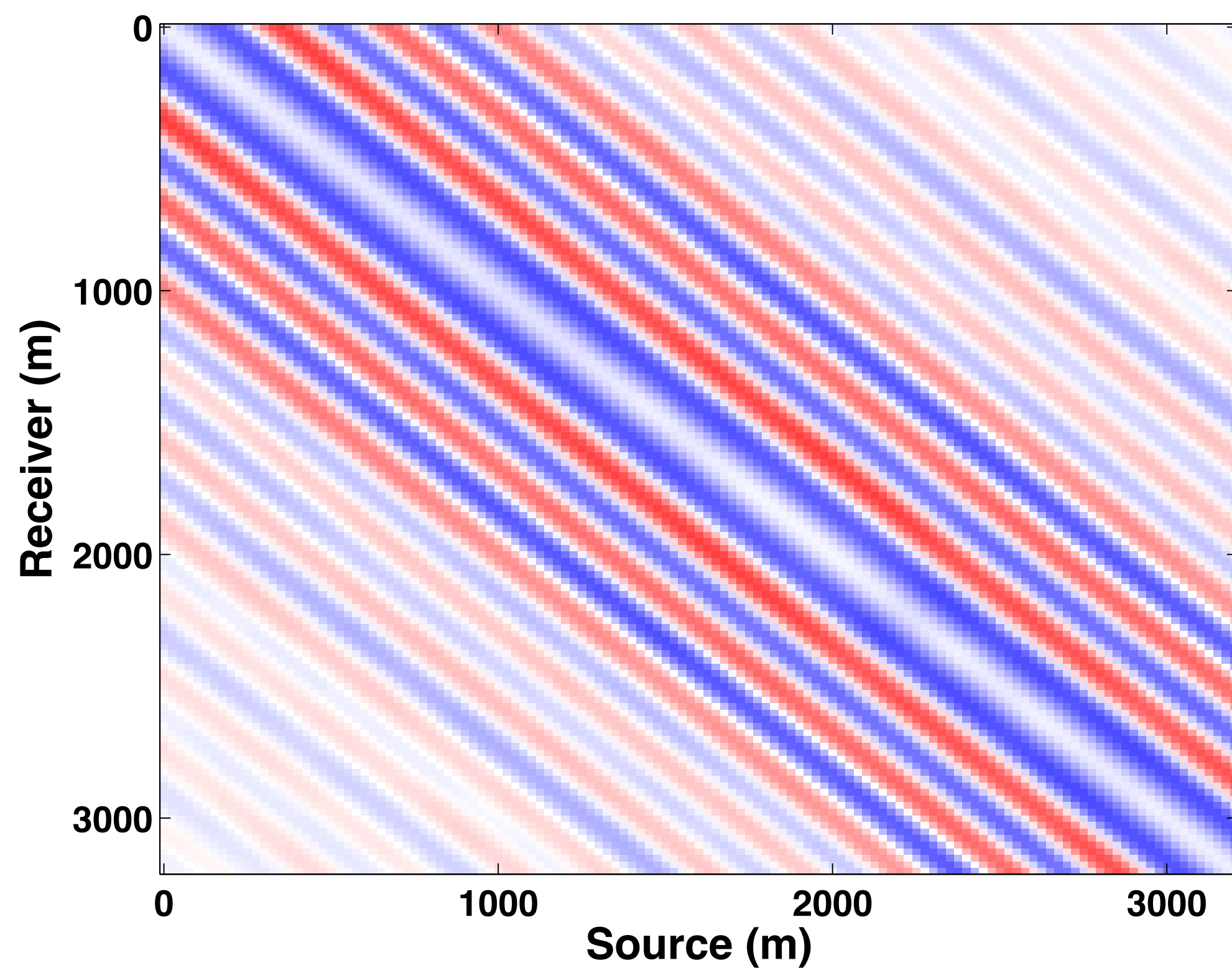
source 2



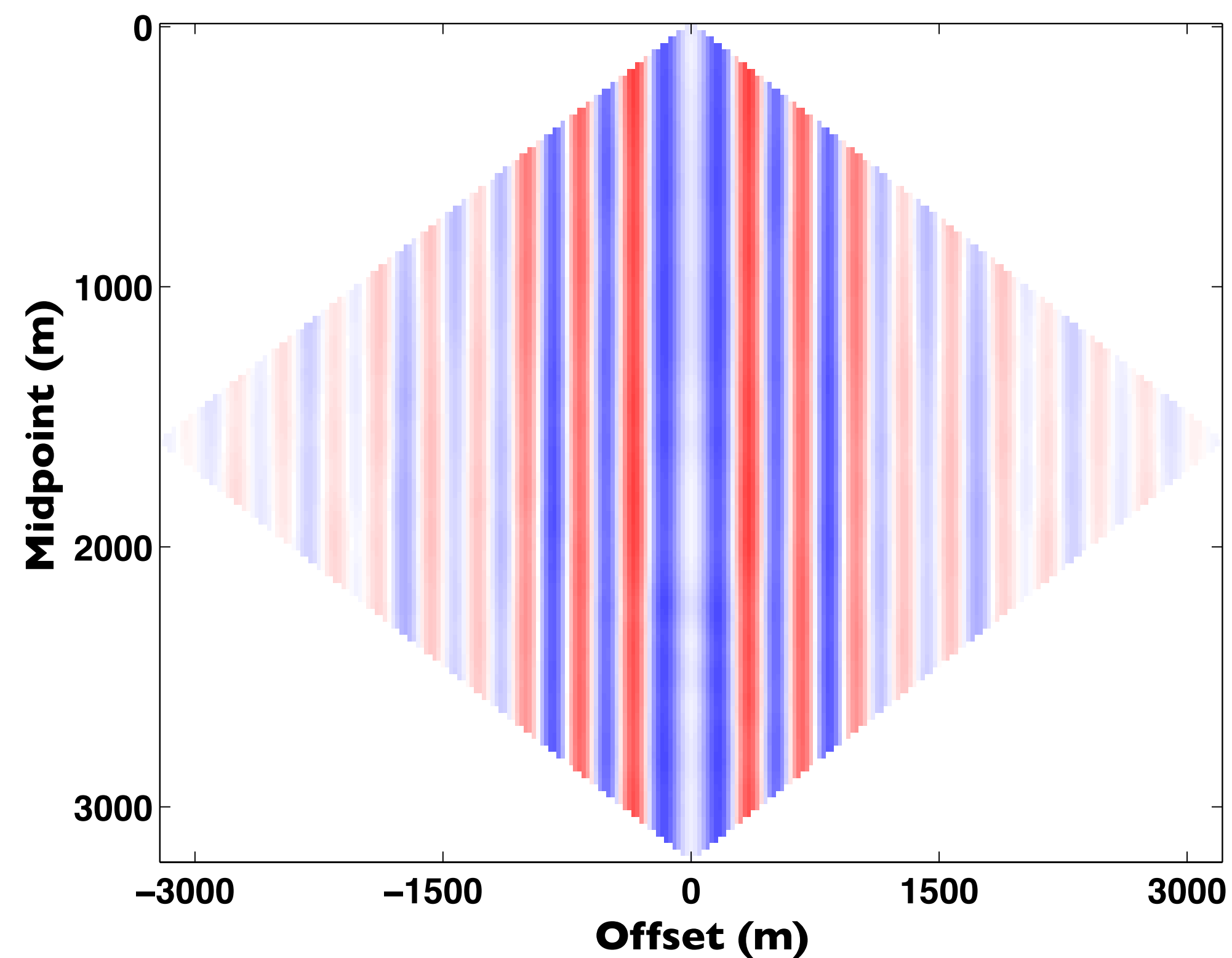
In which domain?

[frequency slice at 5 Hz]

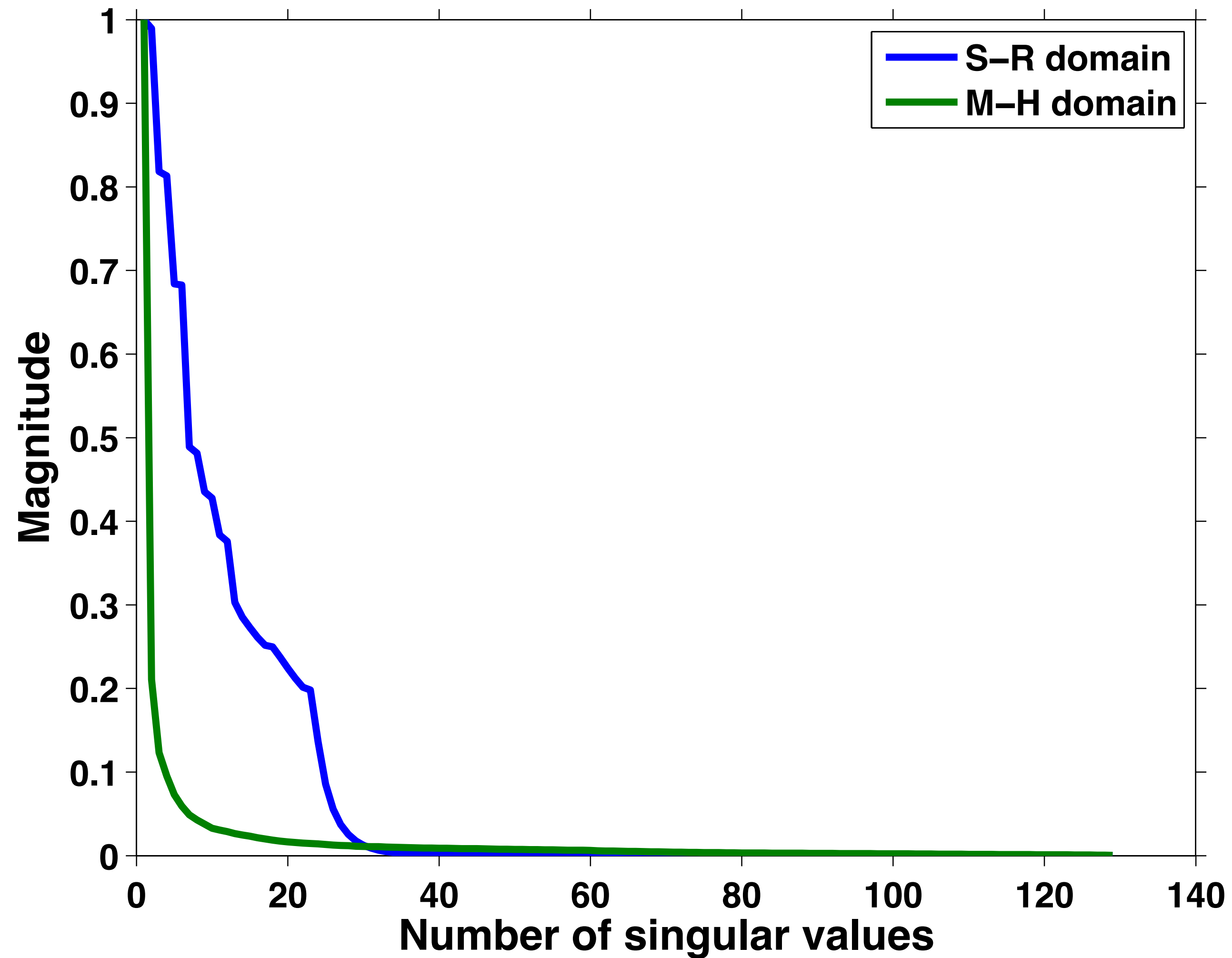
source-receiver domain



midpoint-offset domain



Decay of singular values



**low-rank in
midpoint-offset
domain**

Sampling scheme

sample to *break* the structure

random time delays break the structure

Blended data (w/o delay)

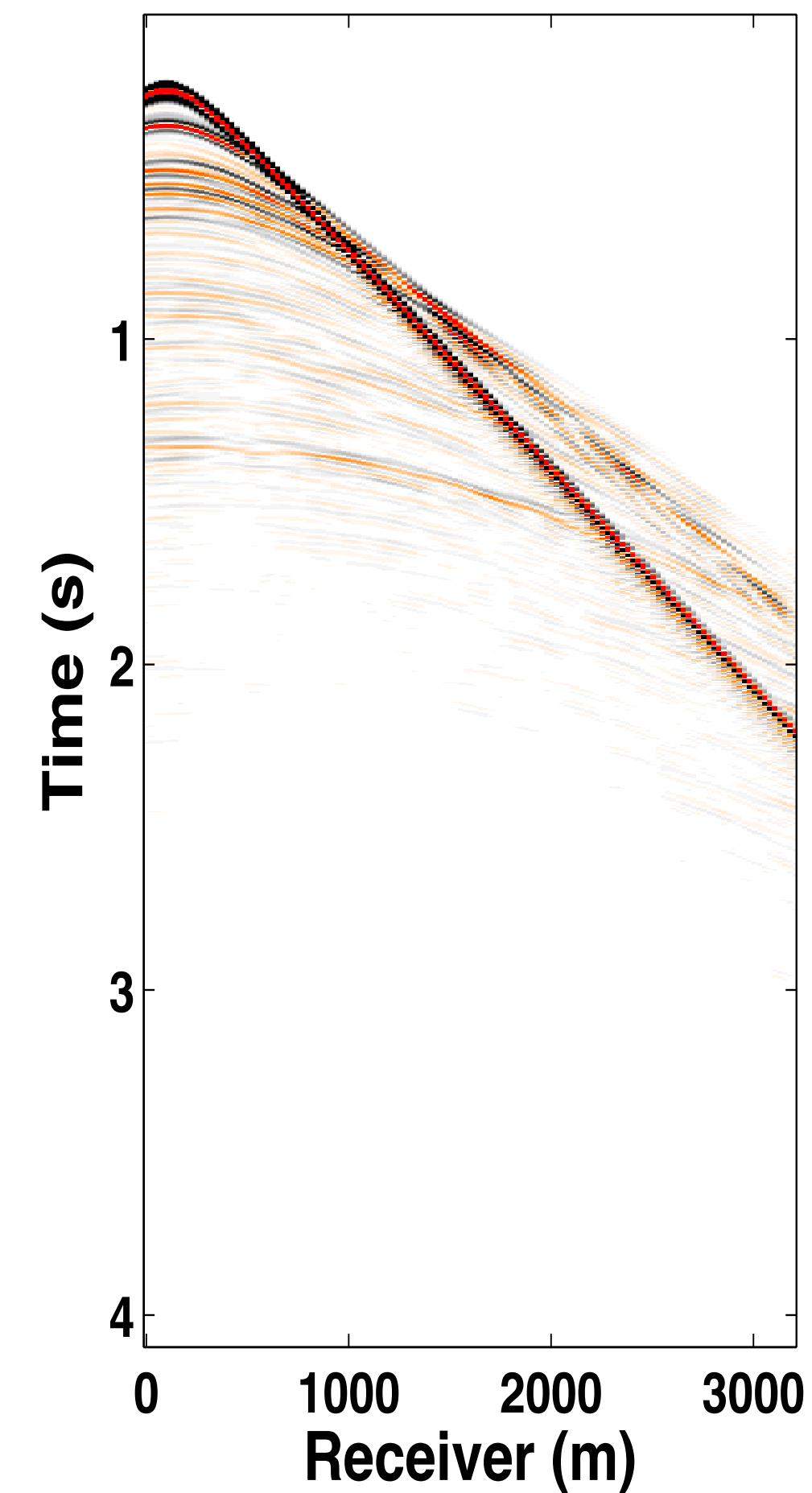
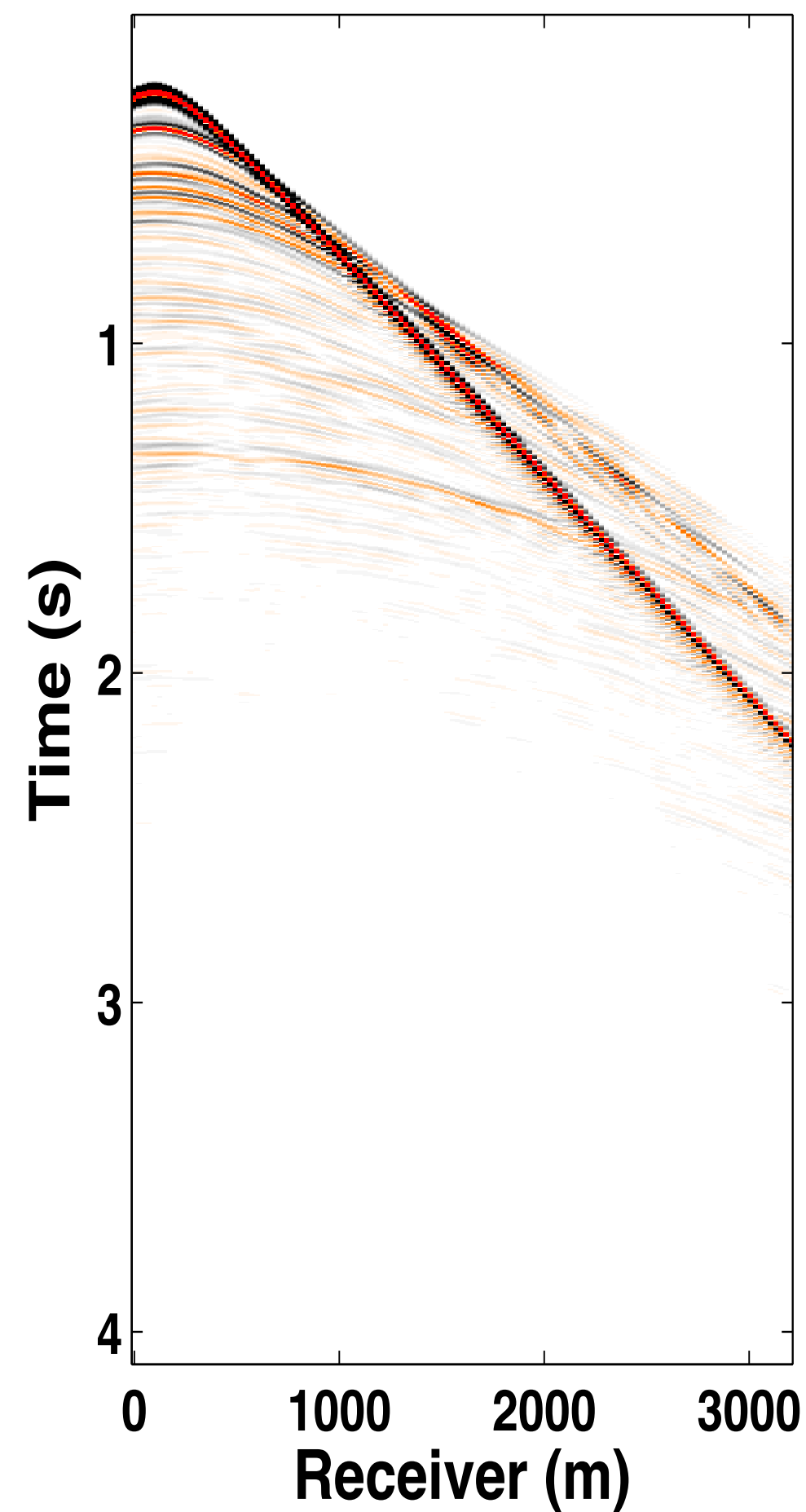
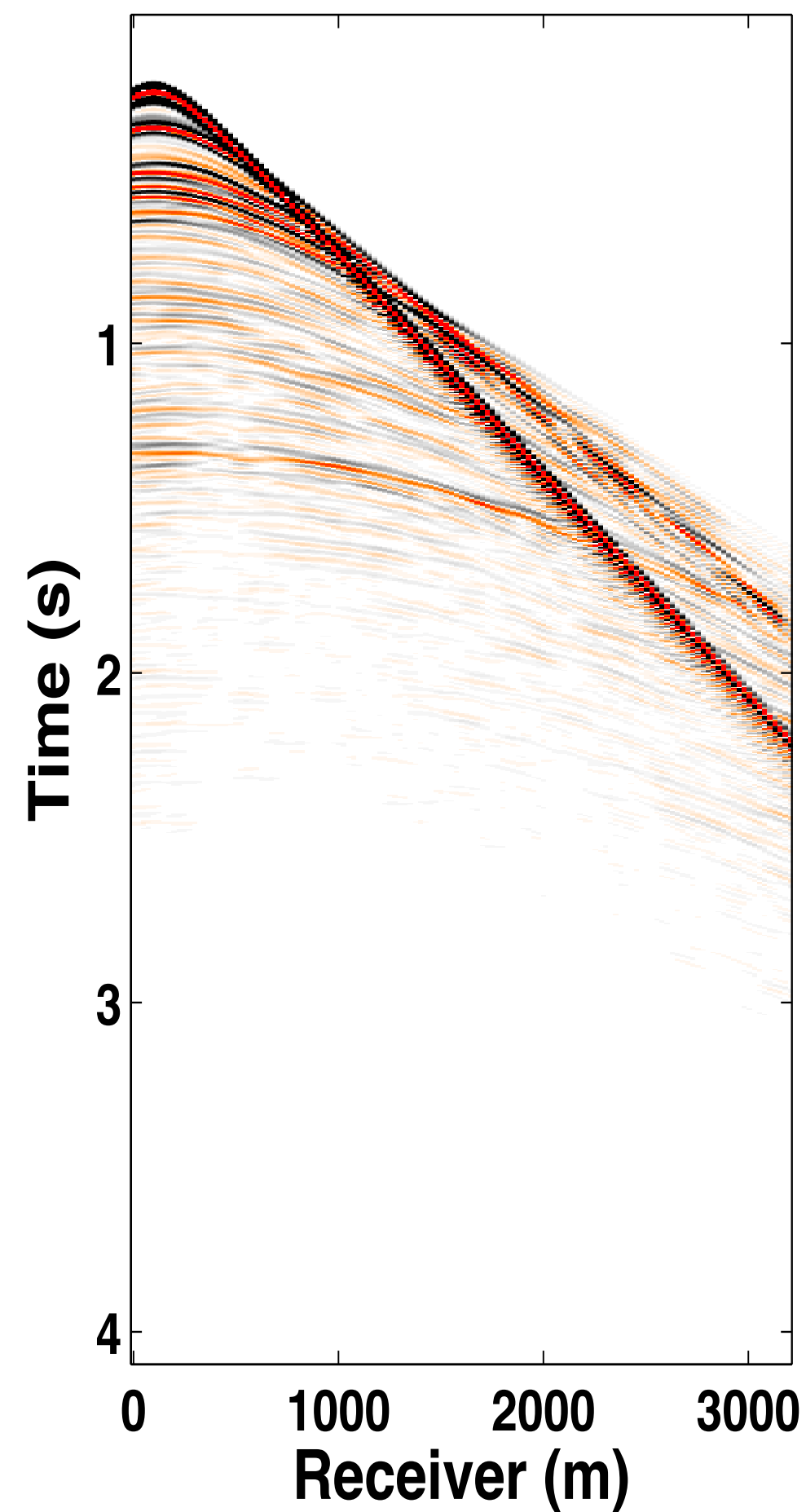
blended shot

=

source 1

+

source 2



Blended data (w/ delay)

[random time delays applied to source 2]

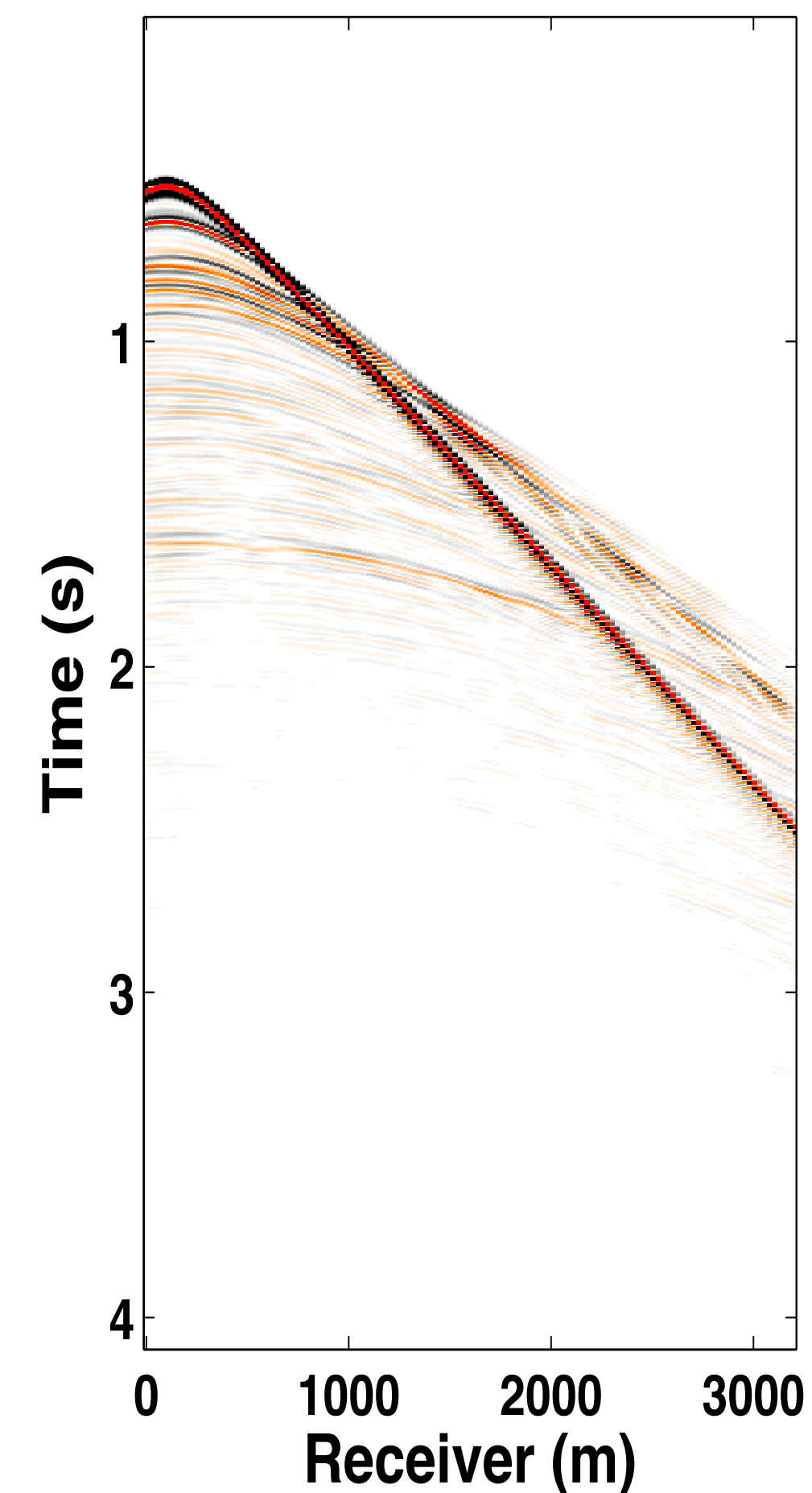
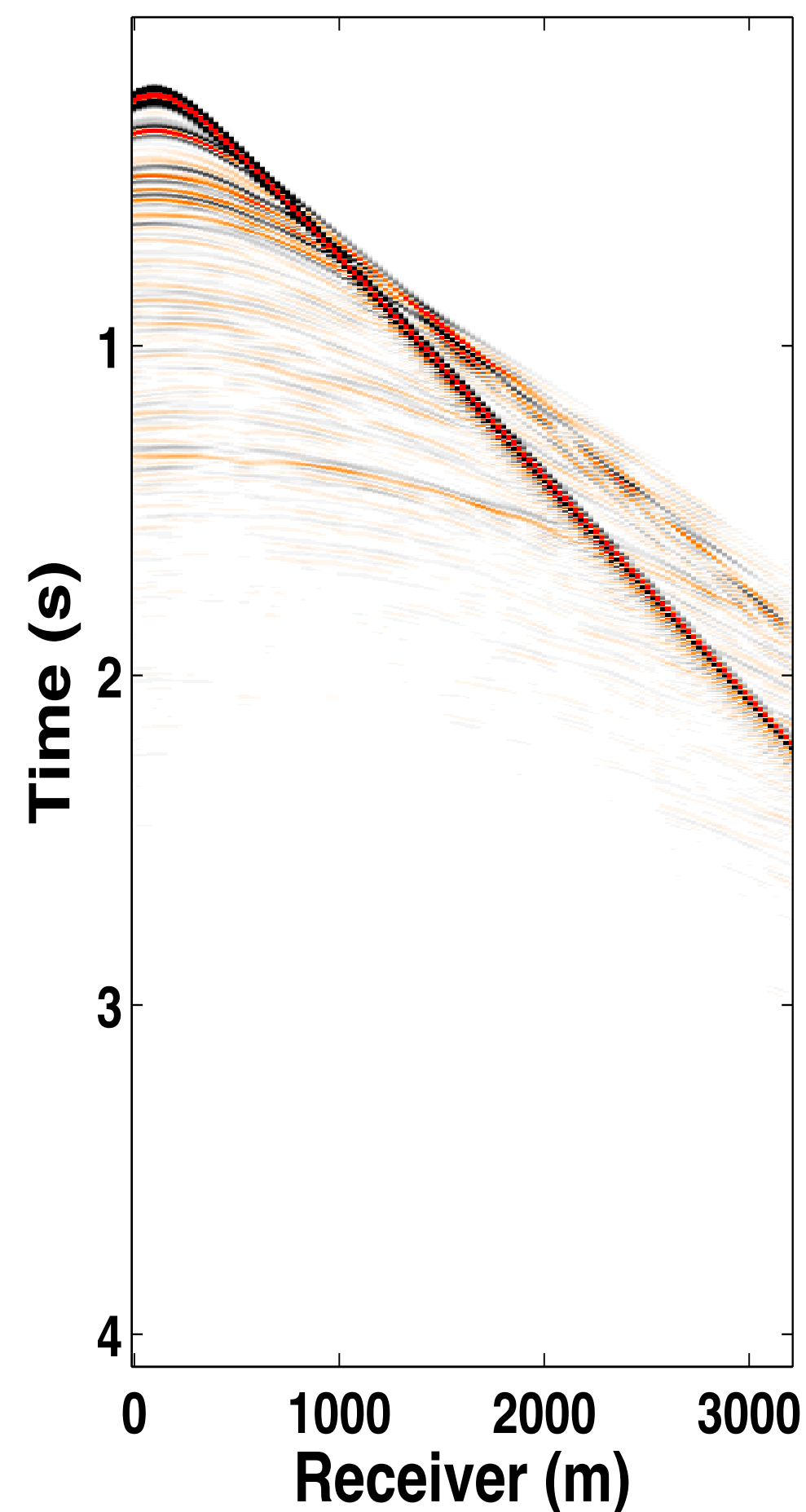
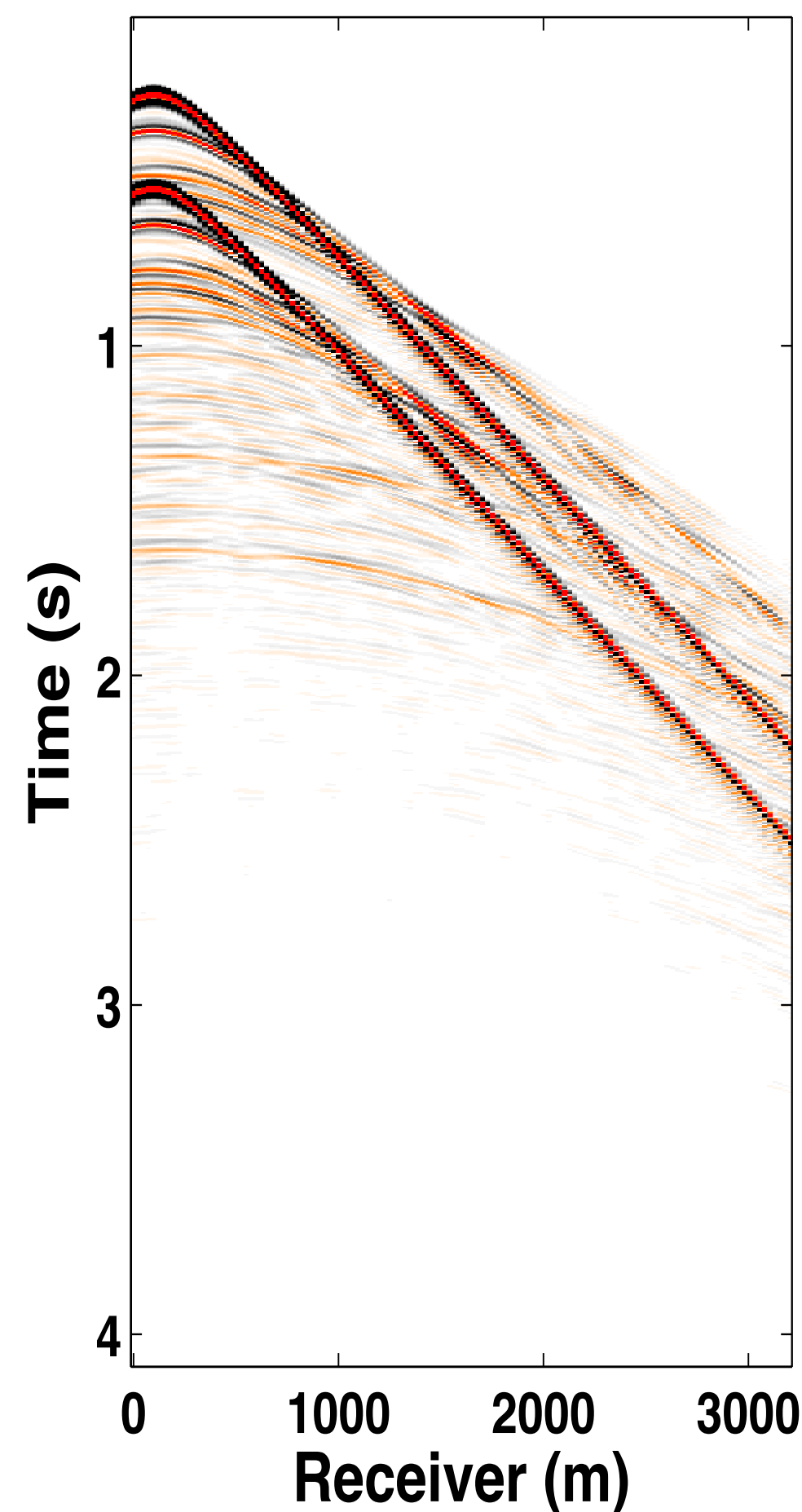
blended shot

=

source 1

+

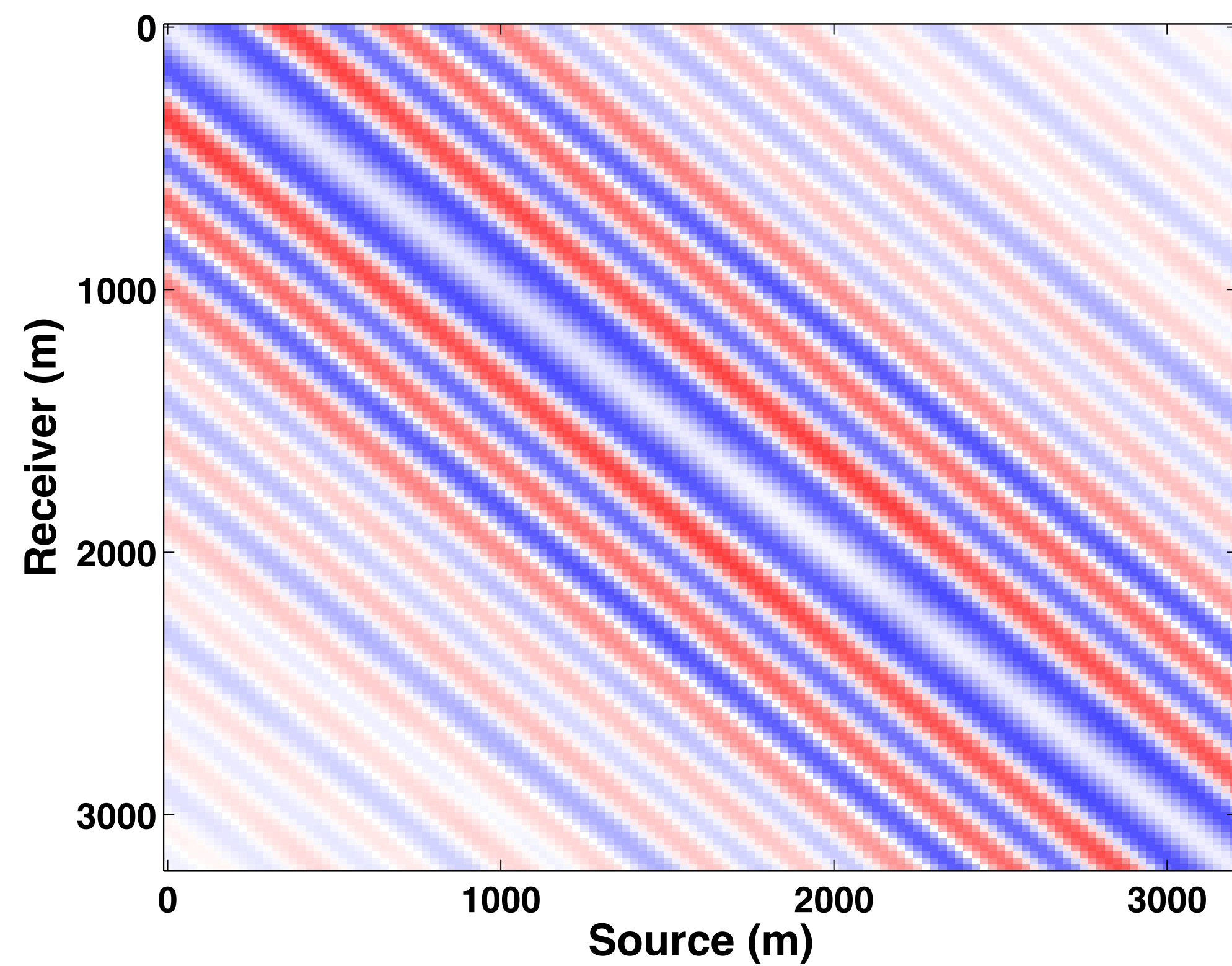
source 2
(time-delayed)



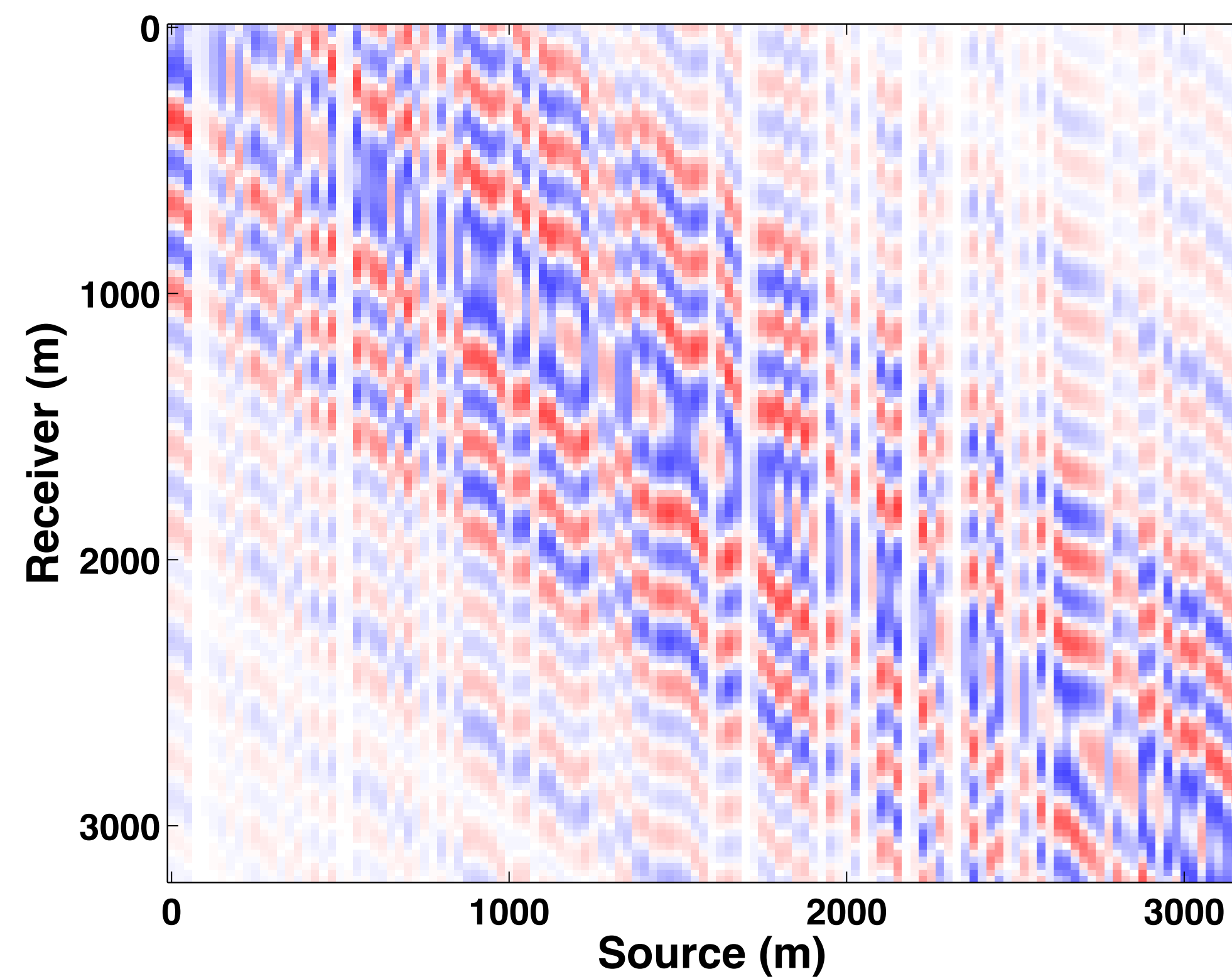
Source-receiver domain

[frequency slice at 5 Hz]

without delay



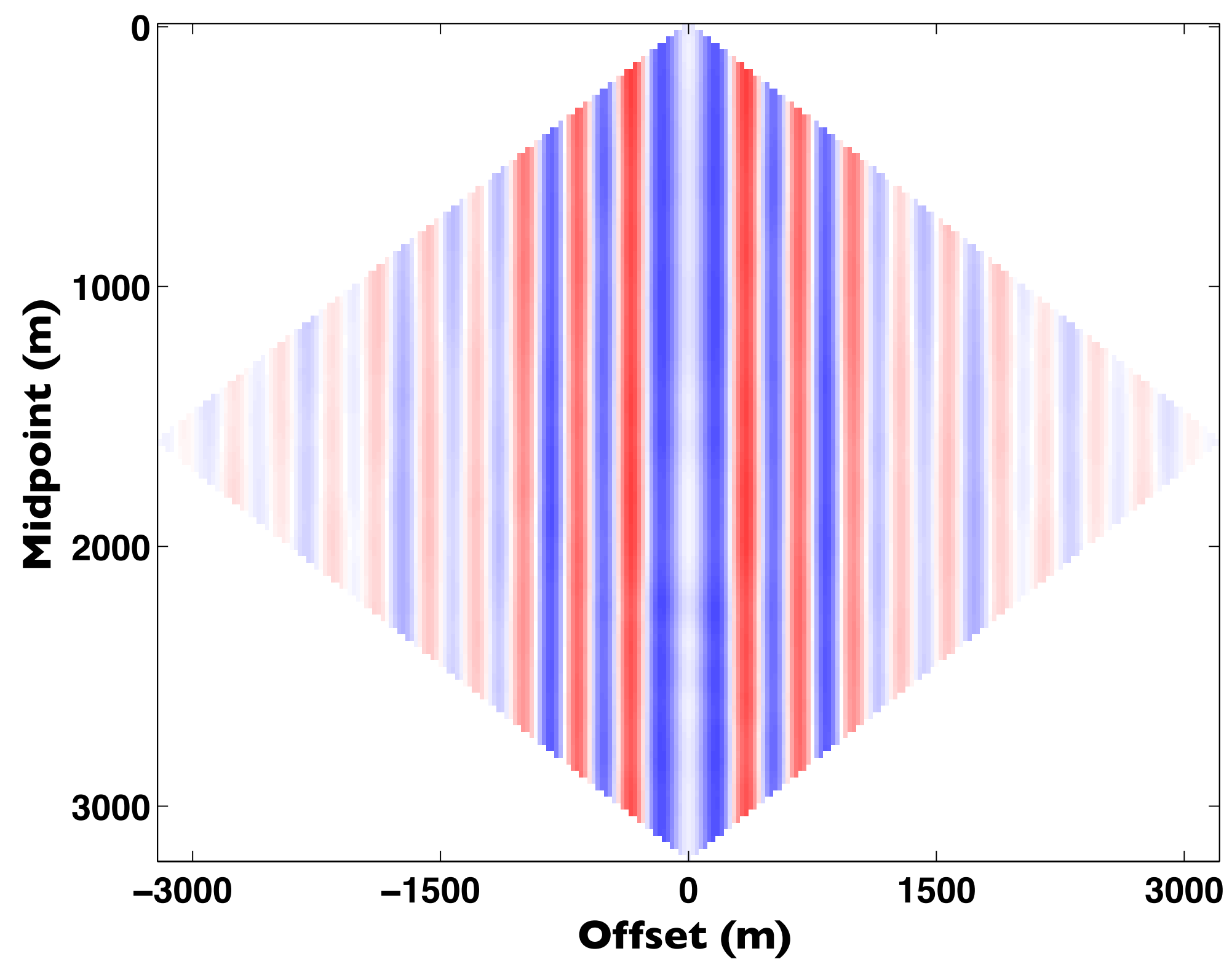
with delay



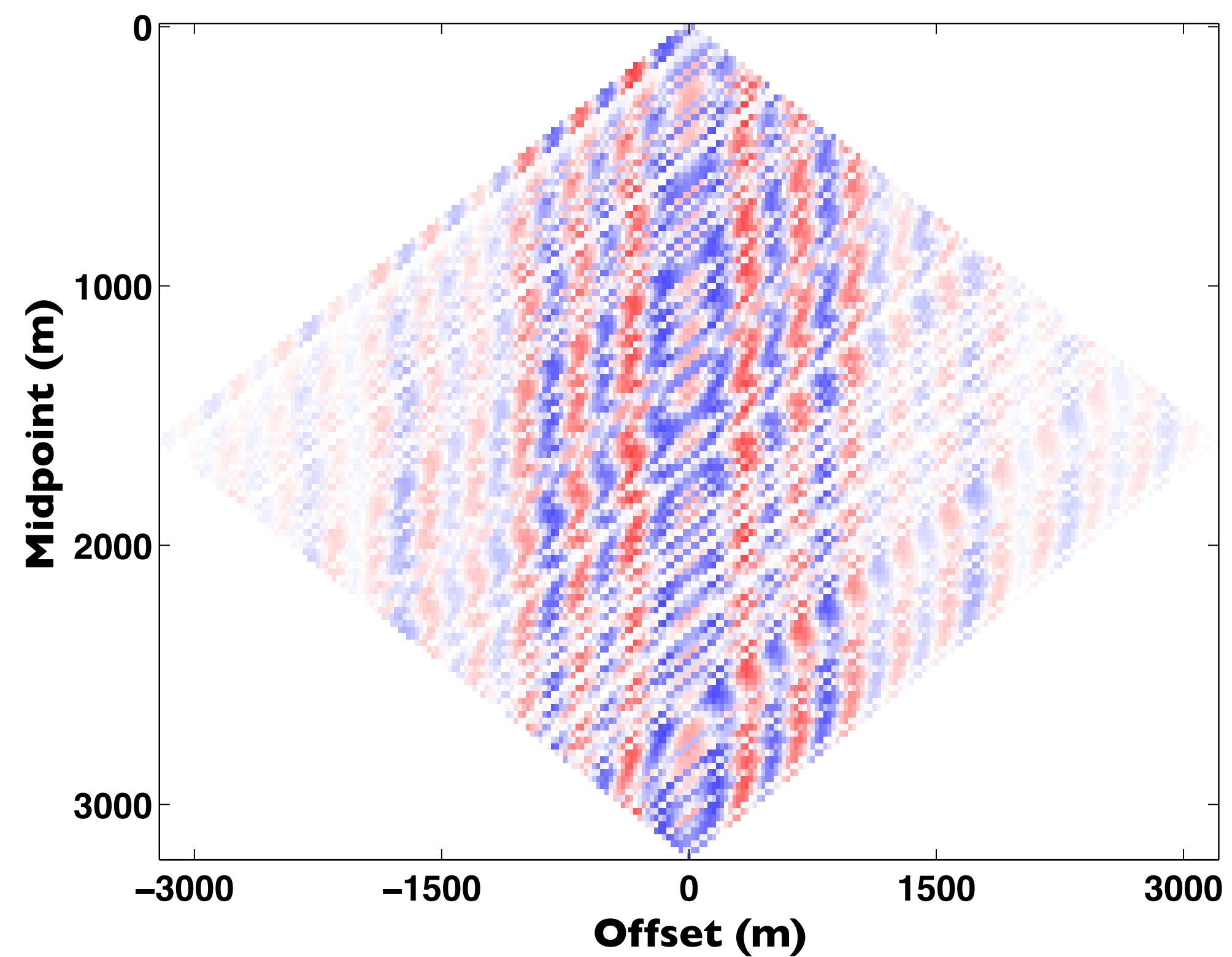
Midpoint-offset domain

[frequency slice at 5 Hz]

without delay

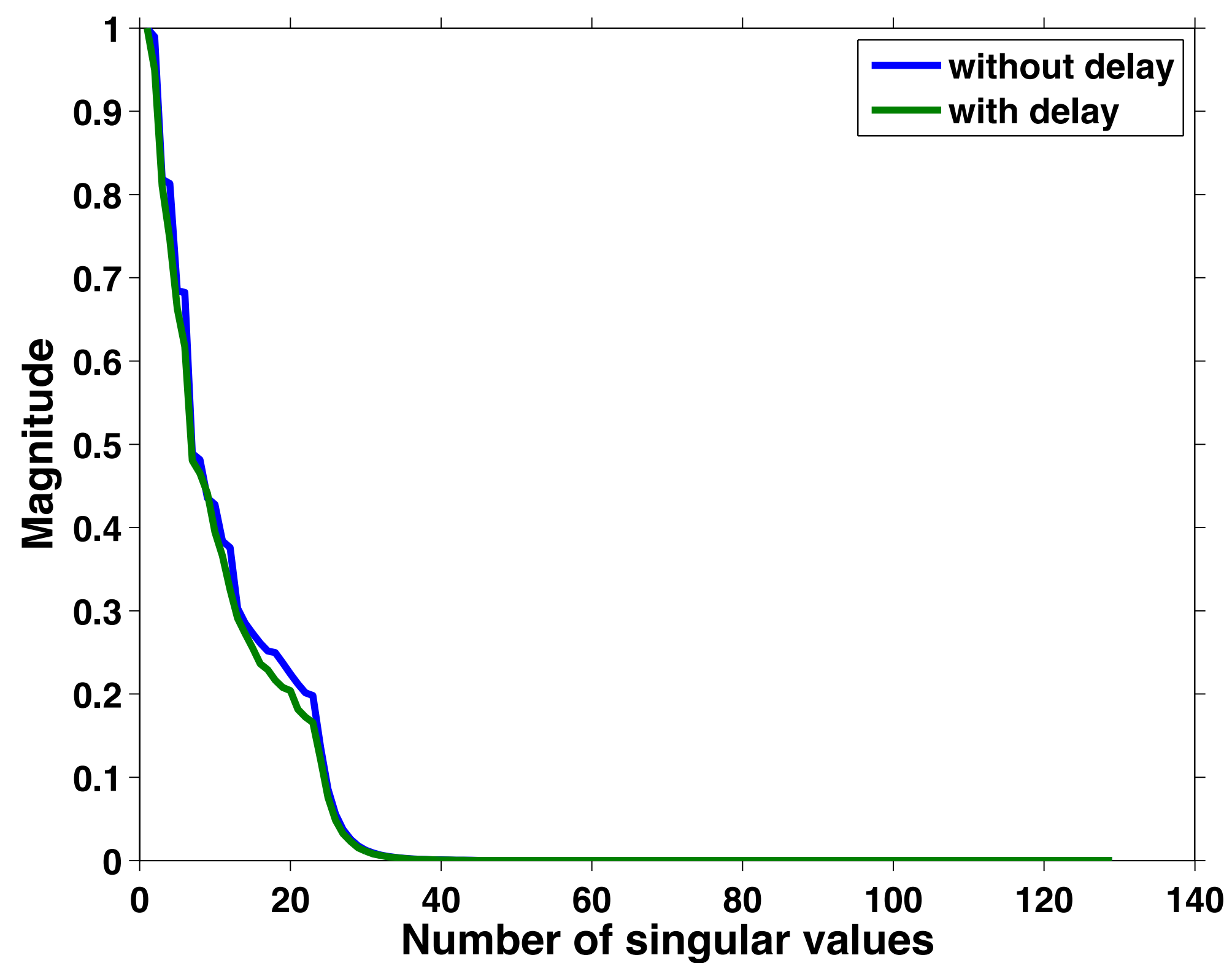


with delay

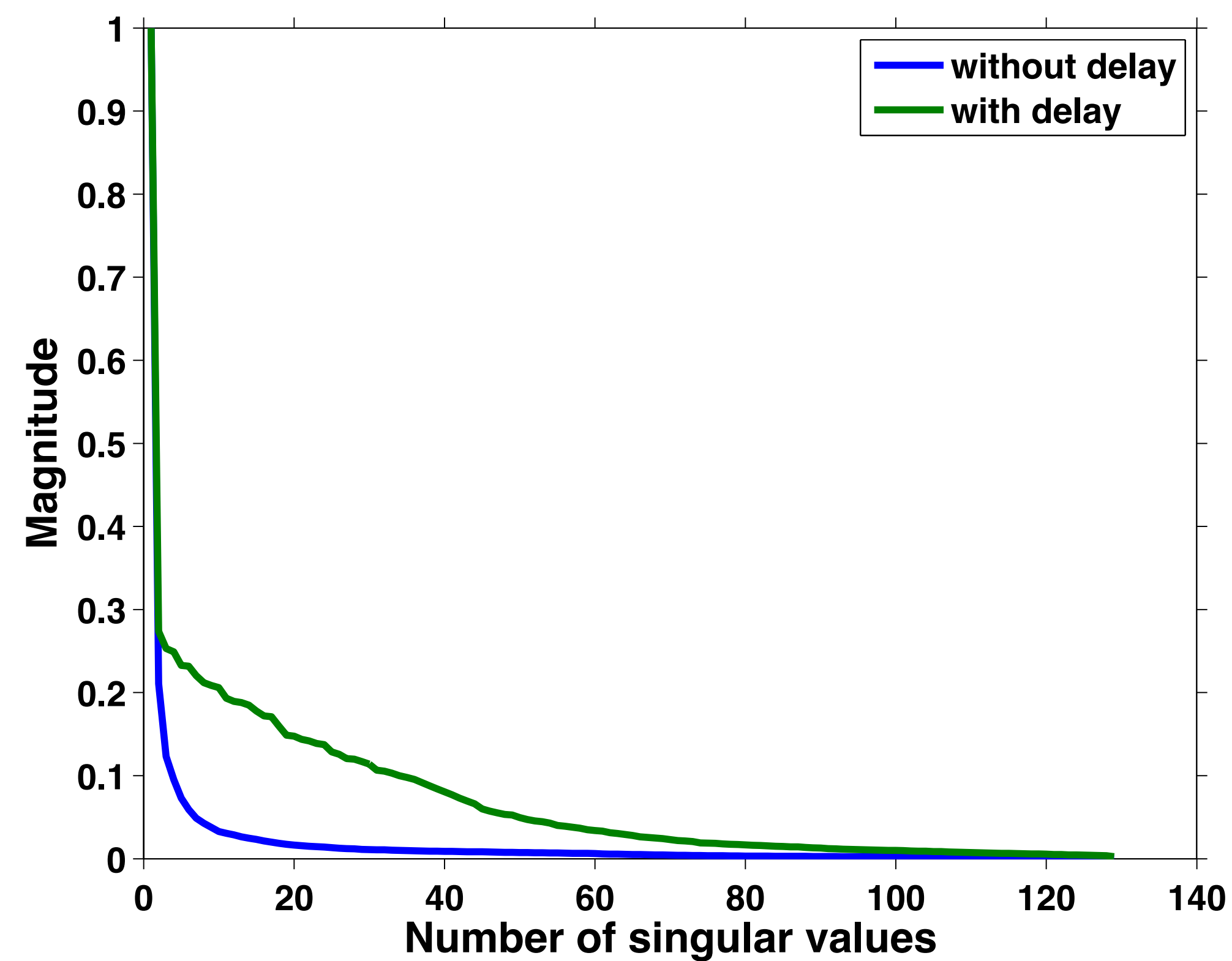


Decay of singular values

source-receiver domain

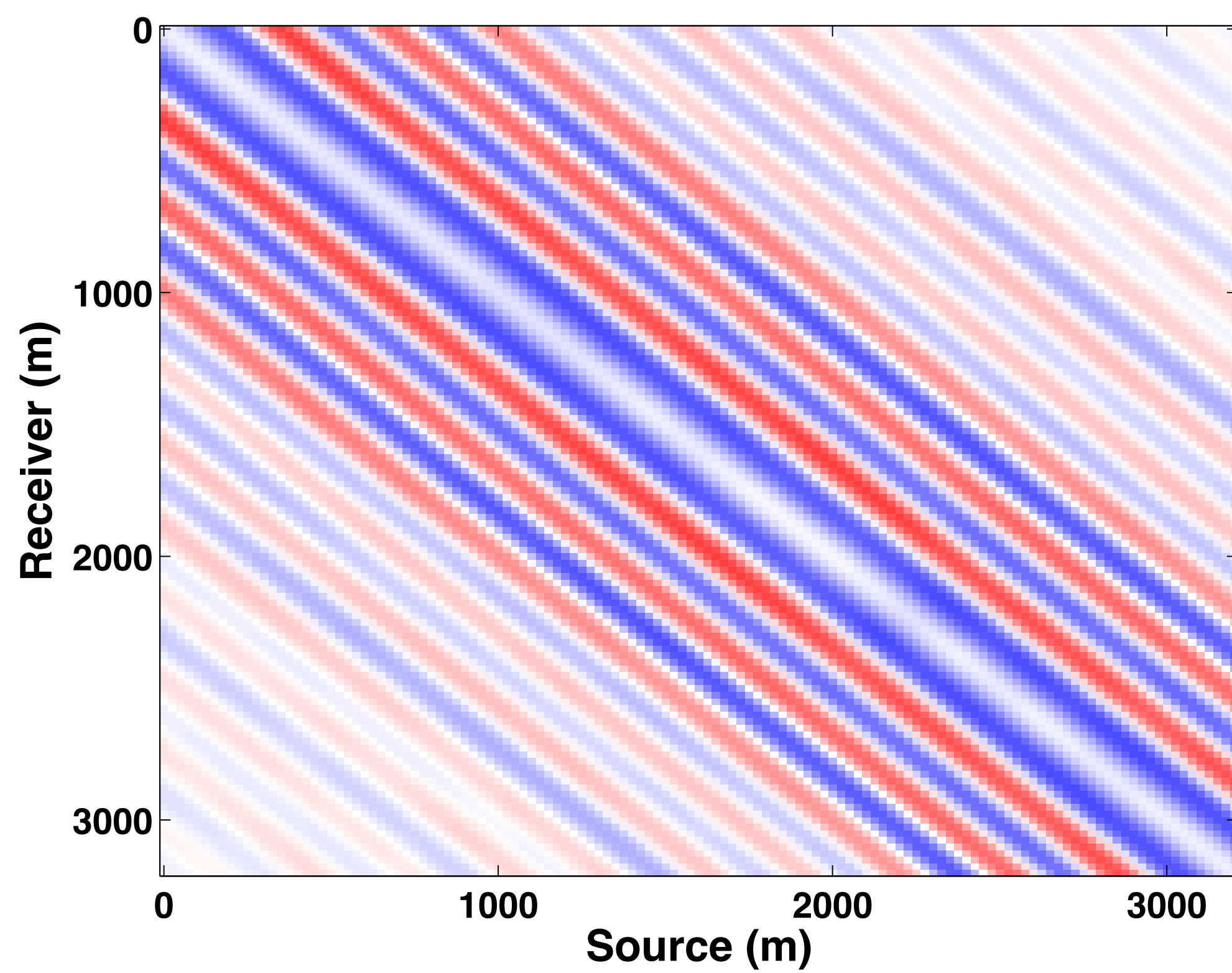


midpoint-offset domain

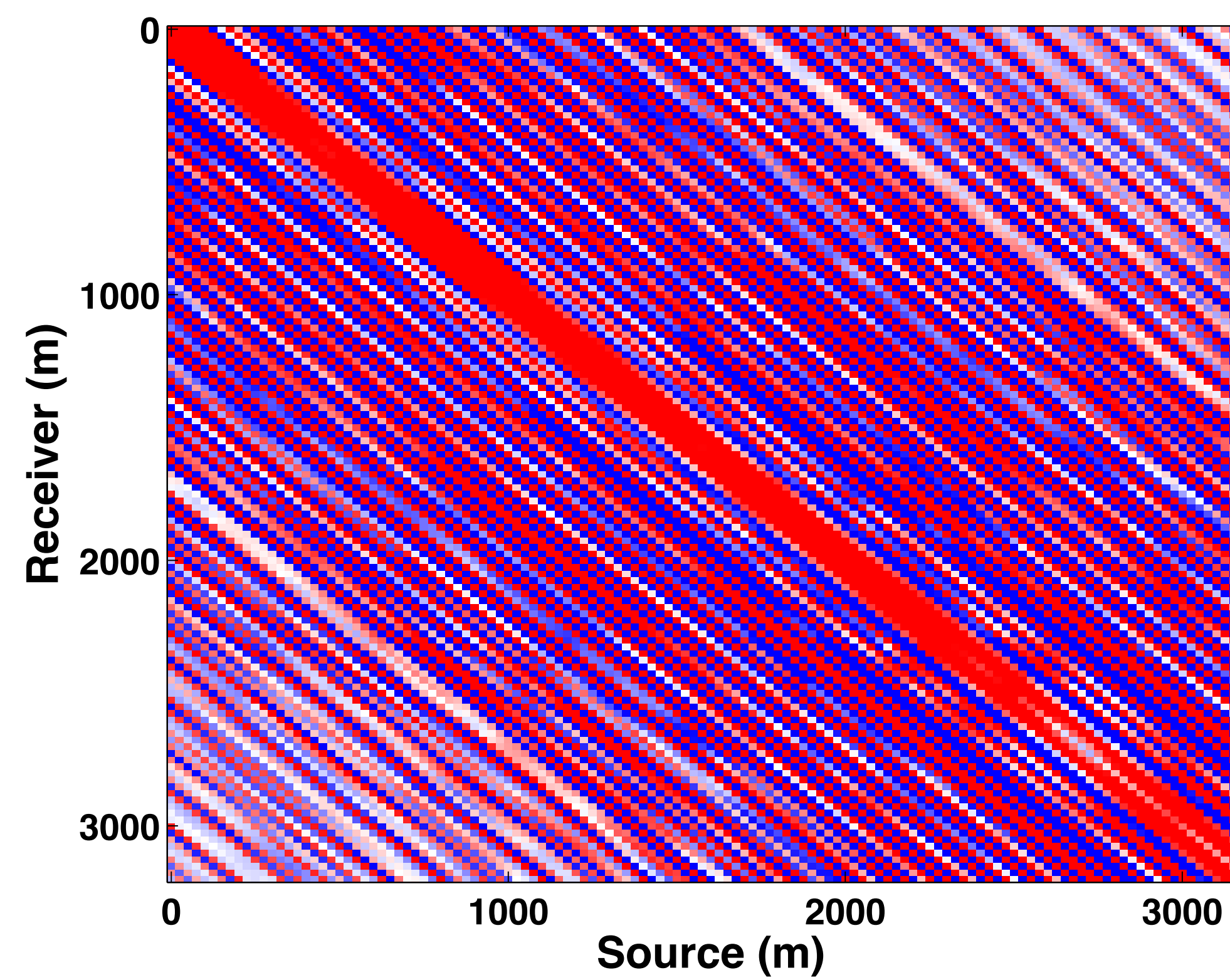


Are high frequencies low-rank?

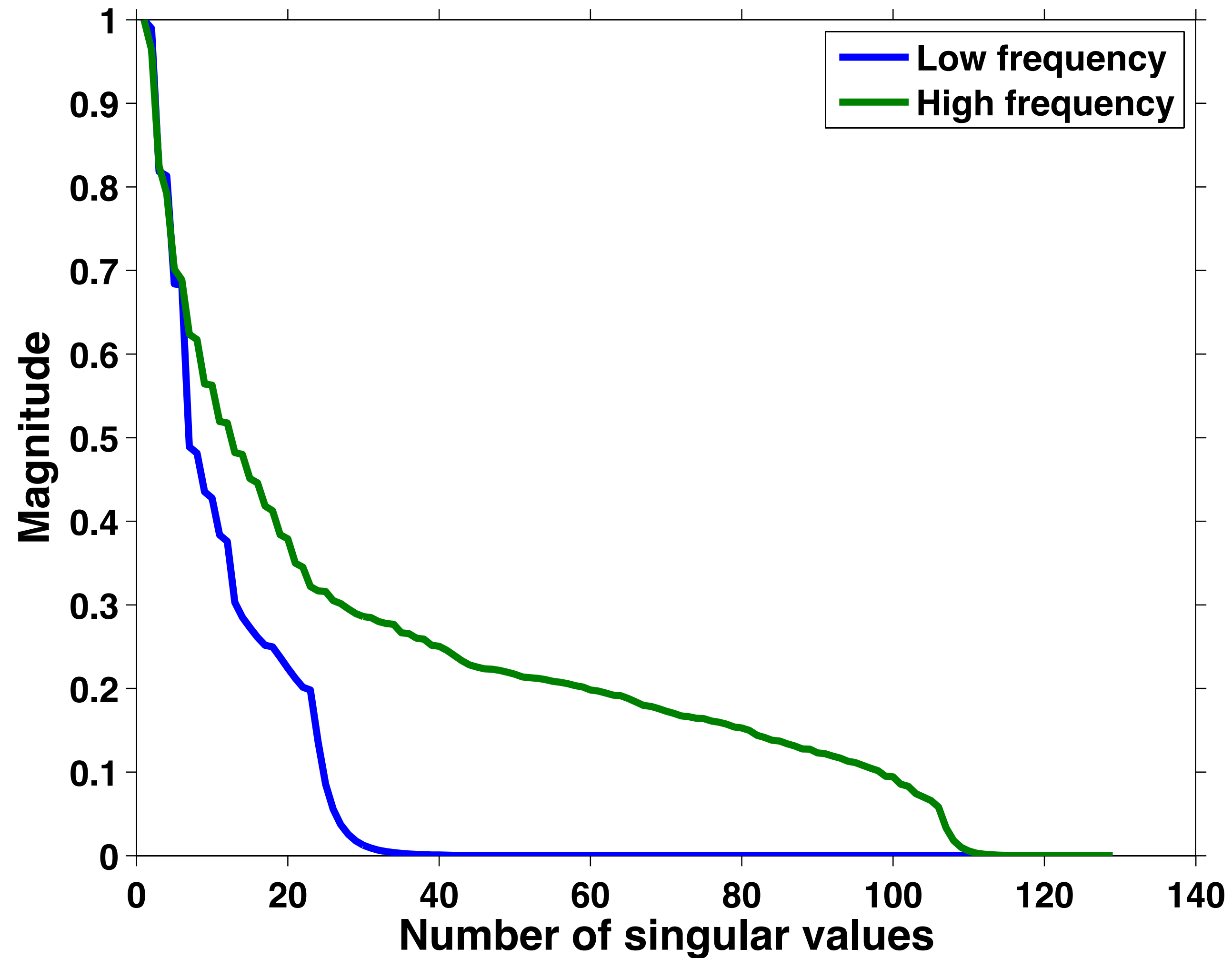
low frequency



high frequency



Decay of singular values



**high frequencies
do NOT have
low-rank structure**

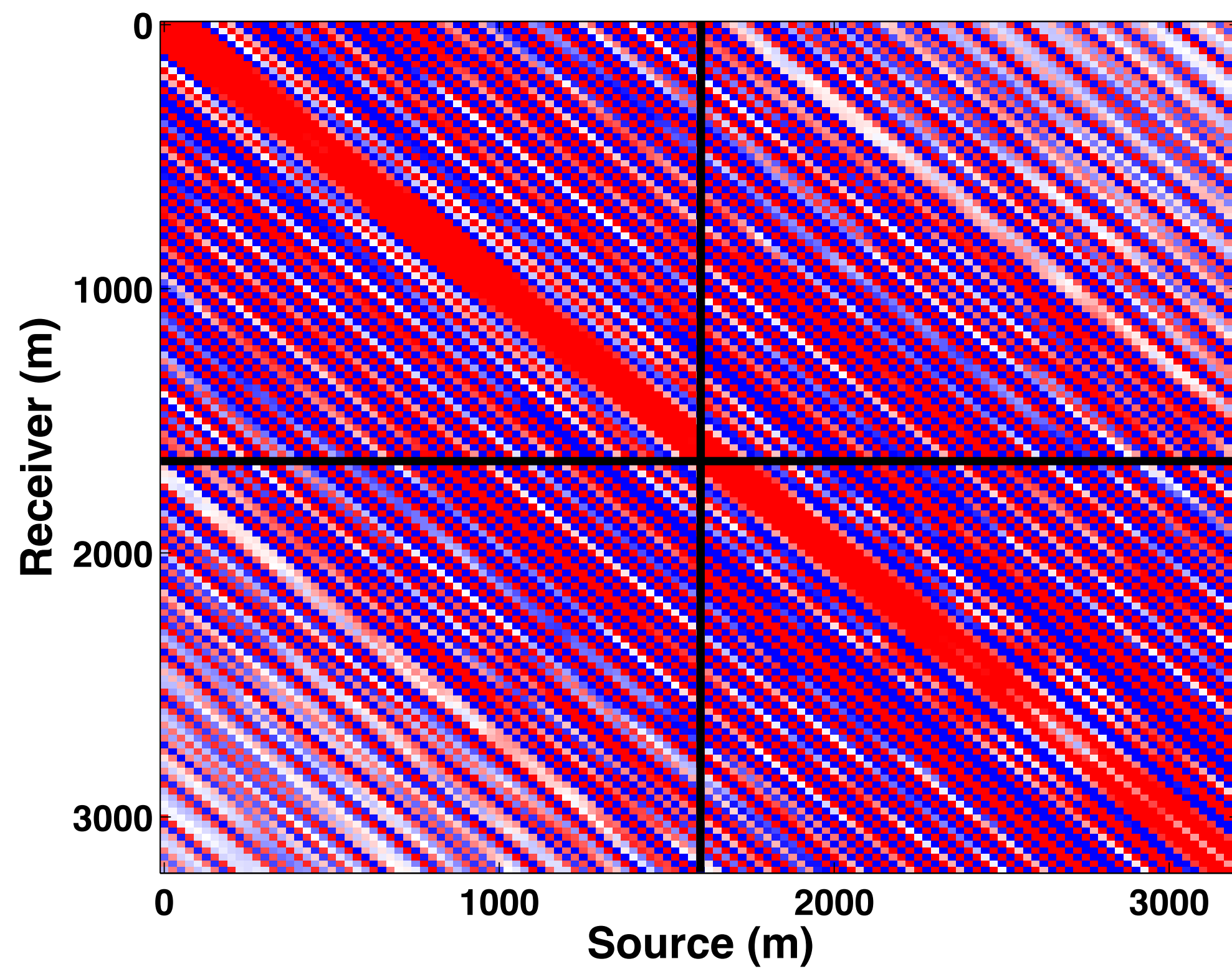
Hierarchical semi-separable (HSS) representation

HSS representation

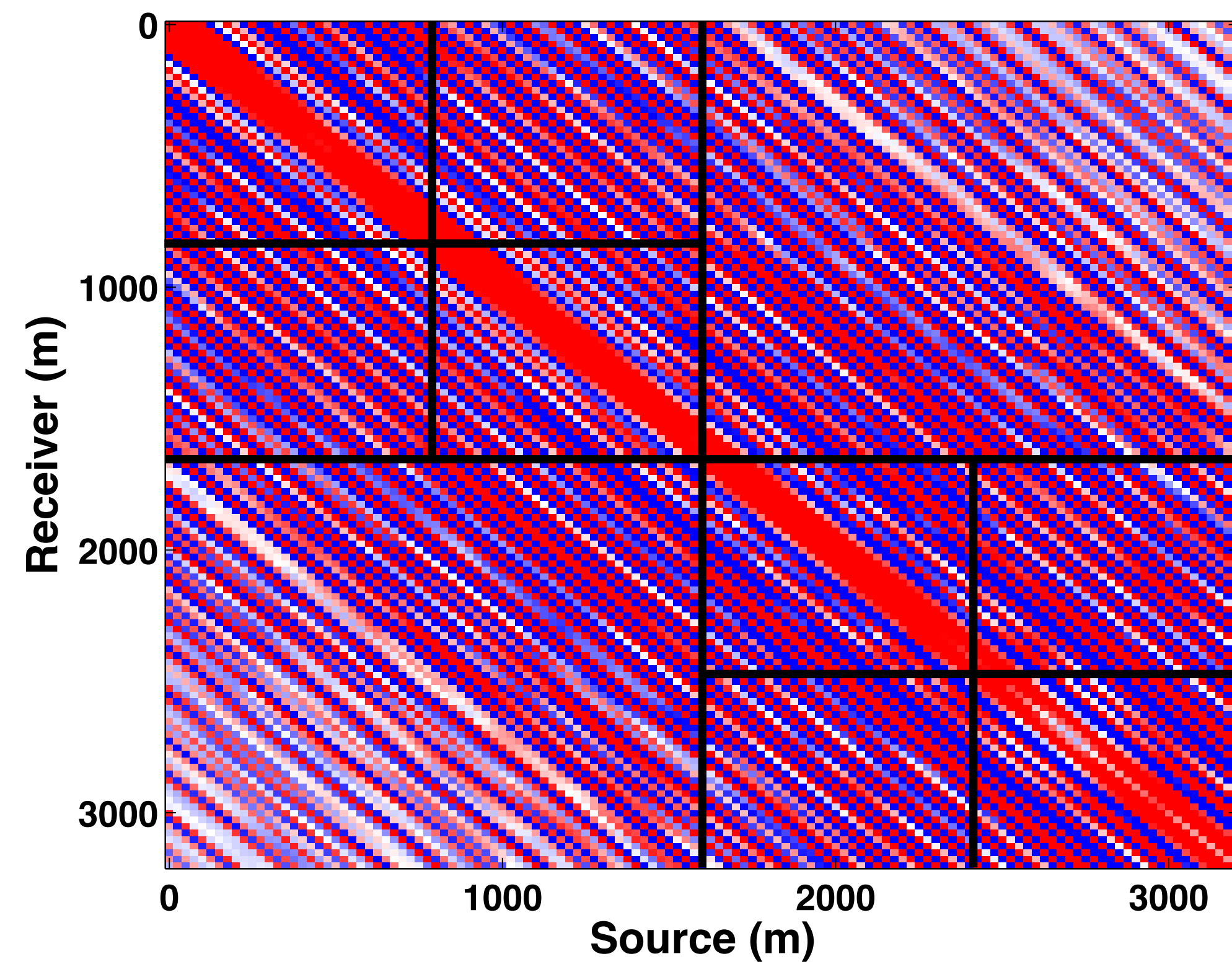
[Chandrasekaran, et. al., 2006]

off-diagonals are low-rank

level - 1



level - 2

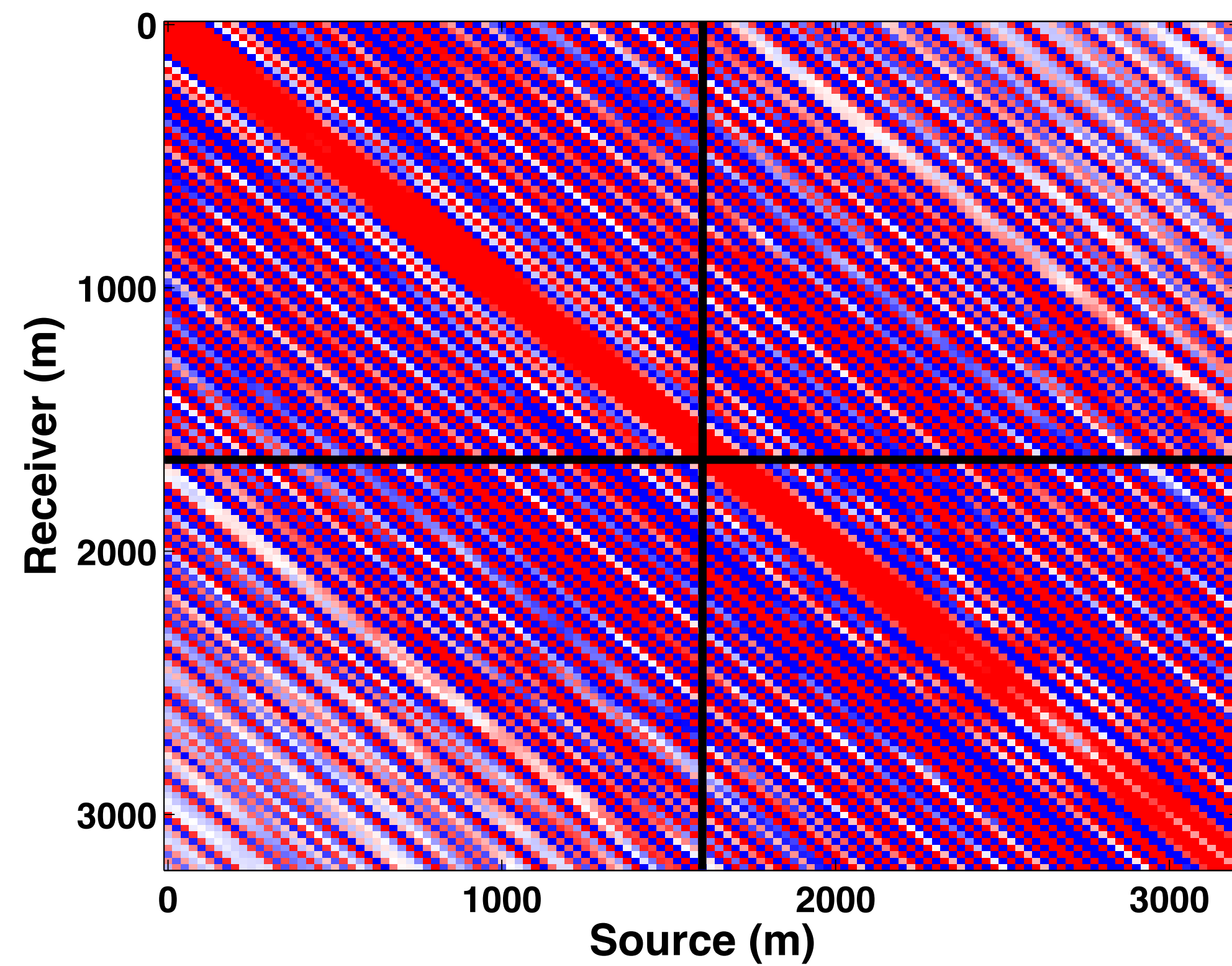


HSS representation

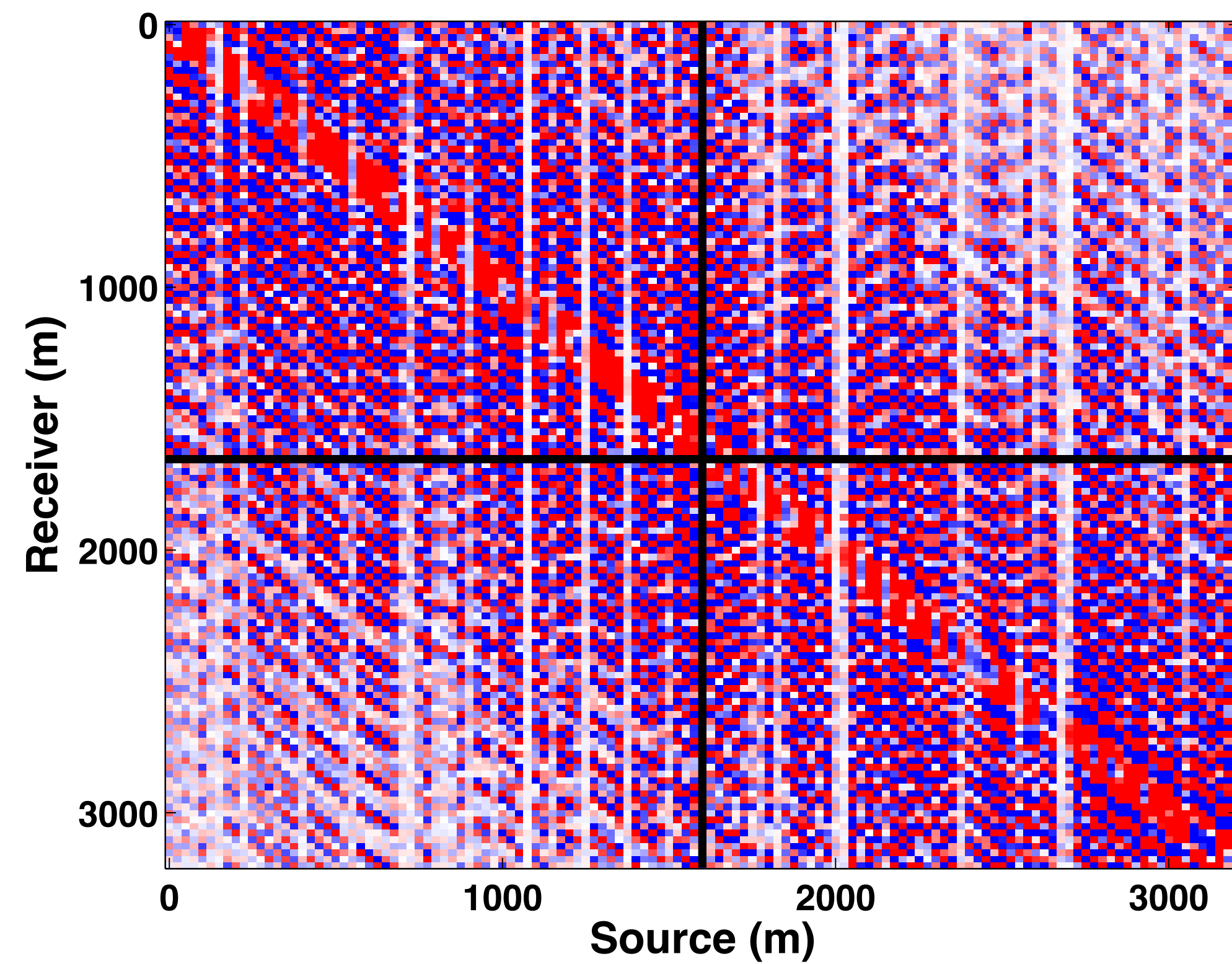
[Chandrasekaran, et. al., 2006]

level - 1 (applied)

without delay



with delay



Rank-minimization

Nuclear norm-minimization

Factorized formulation (“*SVD-free*”)

Rank-minimization

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

Rank-minimization

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

for blended acquisition:

\mathbf{b} : blended data

$$\mathbf{A} := \begin{bmatrix} \mathbf{M}\mathbf{S}^H & \mathbf{M}\mathbf{T}\mathbf{S}^H \end{bmatrix}$$

↑
time delay matrix

unblended data matrix

$$\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} \begin{array}{l} \leftarrow \text{source 1} \\ \leftarrow \text{source 2} \end{array}$$

Rank-minimization

expensive
(search over all possible values of rank)

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

Rank-minimization

expensive
(search over all possible values of rank)

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

Nuclear norm-minimization

convex relaxation of rank-minimization

[Recht, et. al., 2010]

$$\min_{\mathbf{X}} \underbrace{\|\mathbf{X}\|_*}_{\text{sum of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

sum of singular values of \mathbf{X}

Rank-minimization

expensive
(search over all possible values of rank)

$$\min_{\mathbf{X}} \underbrace{\text{rank}(\mathbf{X})}_{\text{number of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

number of singular values of \mathbf{X}

Nuclear norm-minimization

convex relaxation of rank-minimization

[Recht, et. al., 2010]

$$\min_{\mathbf{X}} \underbrace{\|\mathbf{X}\|_*}_{\text{sum of singular values of } \mathbf{X}} \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{X}) - \mathbf{b}\|_2 \leq \epsilon$$

sum of singular values of \mathbf{X}

however ...
requires repeated application of SVD

Factorized formulation (“SVD-free”)

[Rennie and Srebro, 2005; Lee et. al., 2010; Recht and Re, 2011]

$$\boxed{\mathbf{X} \in \mathbb{R}^{n \times m}} = \boxed{\mathbf{L} \in \mathbb{R}^{n \times k}} \boxed{\mathbf{R}^H \in \mathbb{R}^{k \times m}}$$

Upper-bound on nuclear norm:

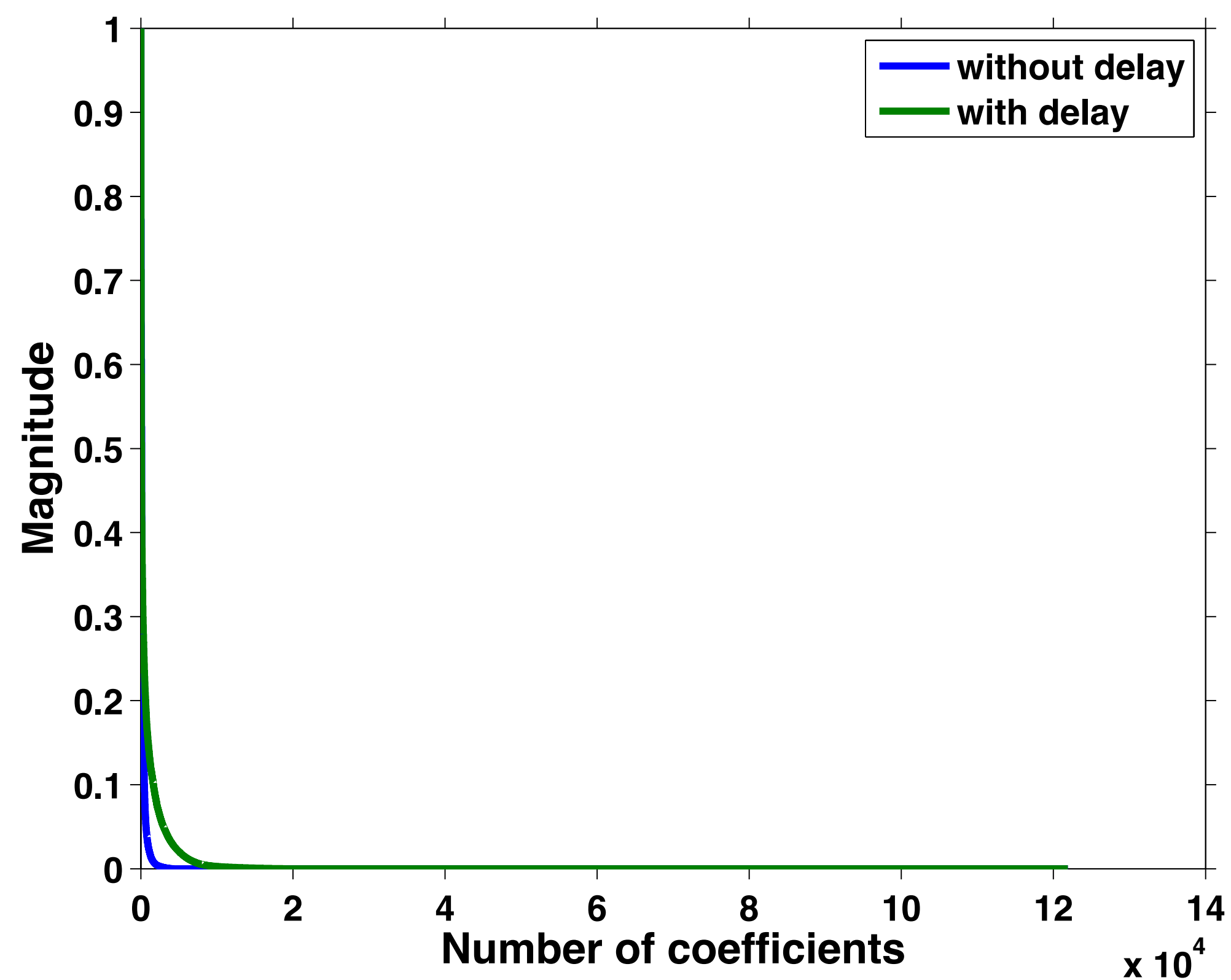
$$\|\mathbf{X}\|_* \leq \frac{1}{2} \left\| \begin{bmatrix} \mathbf{L}_1 \\ \mathbf{R}_1 \end{bmatrix} \right\|_F^2 + \frac{1}{2} \left\| \begin{bmatrix} \mathbf{L}_2 \\ \mathbf{R}_2 \end{bmatrix} \right\|_F^2 =: \Phi(\mathbf{L}_1, \mathbf{R}_1, \mathbf{L}_2, \mathbf{R}_2)$$

Sparsity-promotion

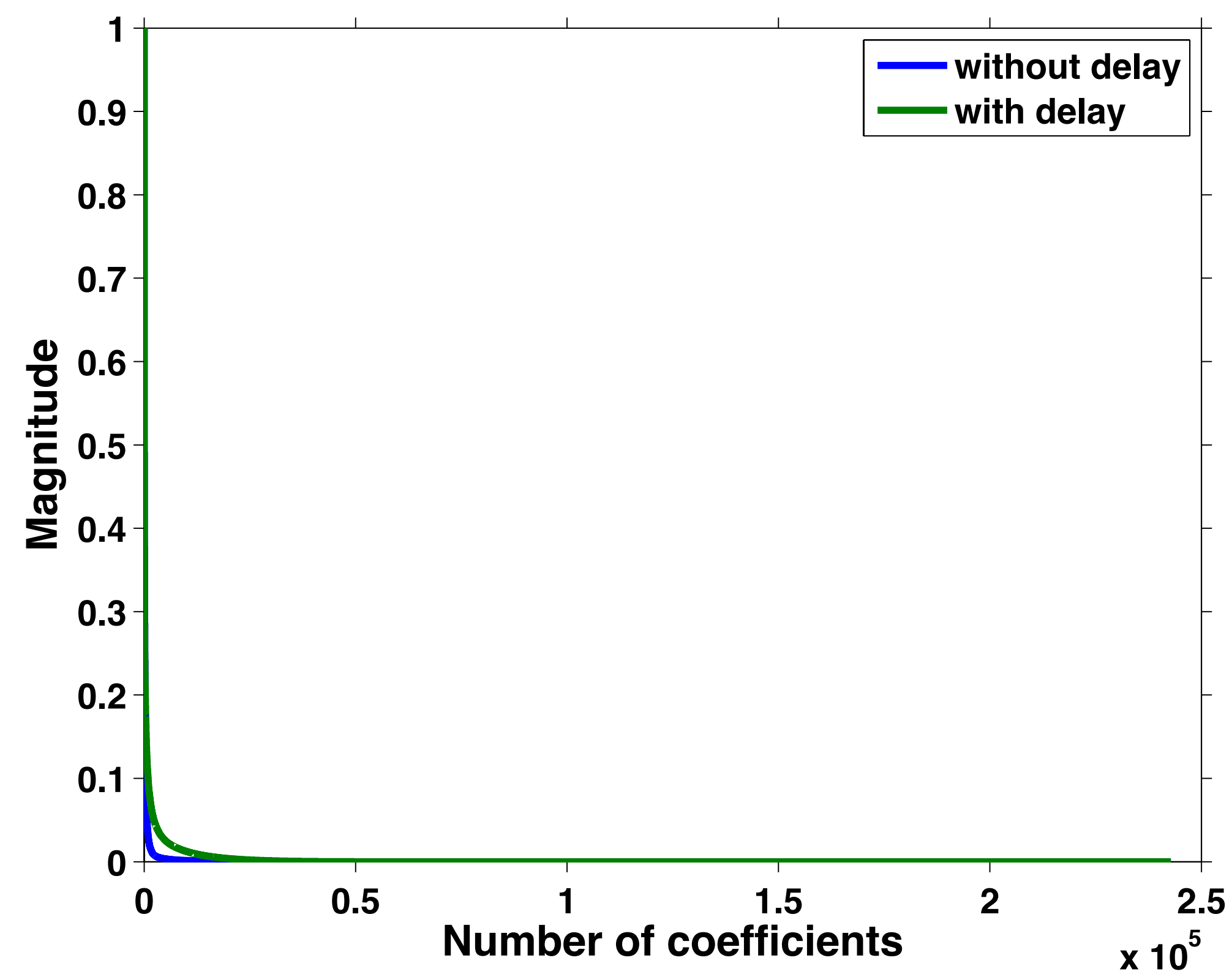
one norm-minimization

Decay of curvelet coefficients

source-receiver domain



midpoint-offset domain

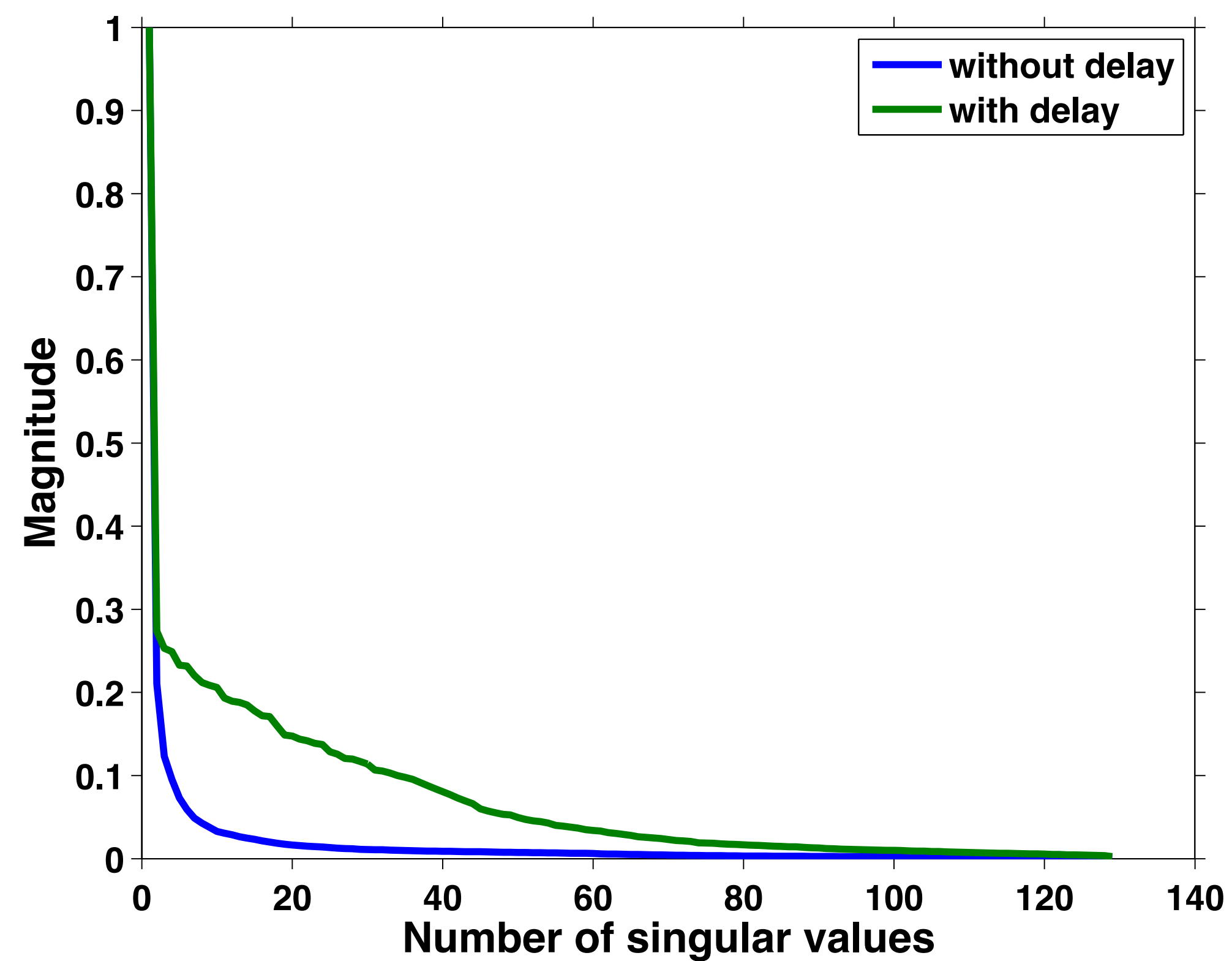


Source separation results

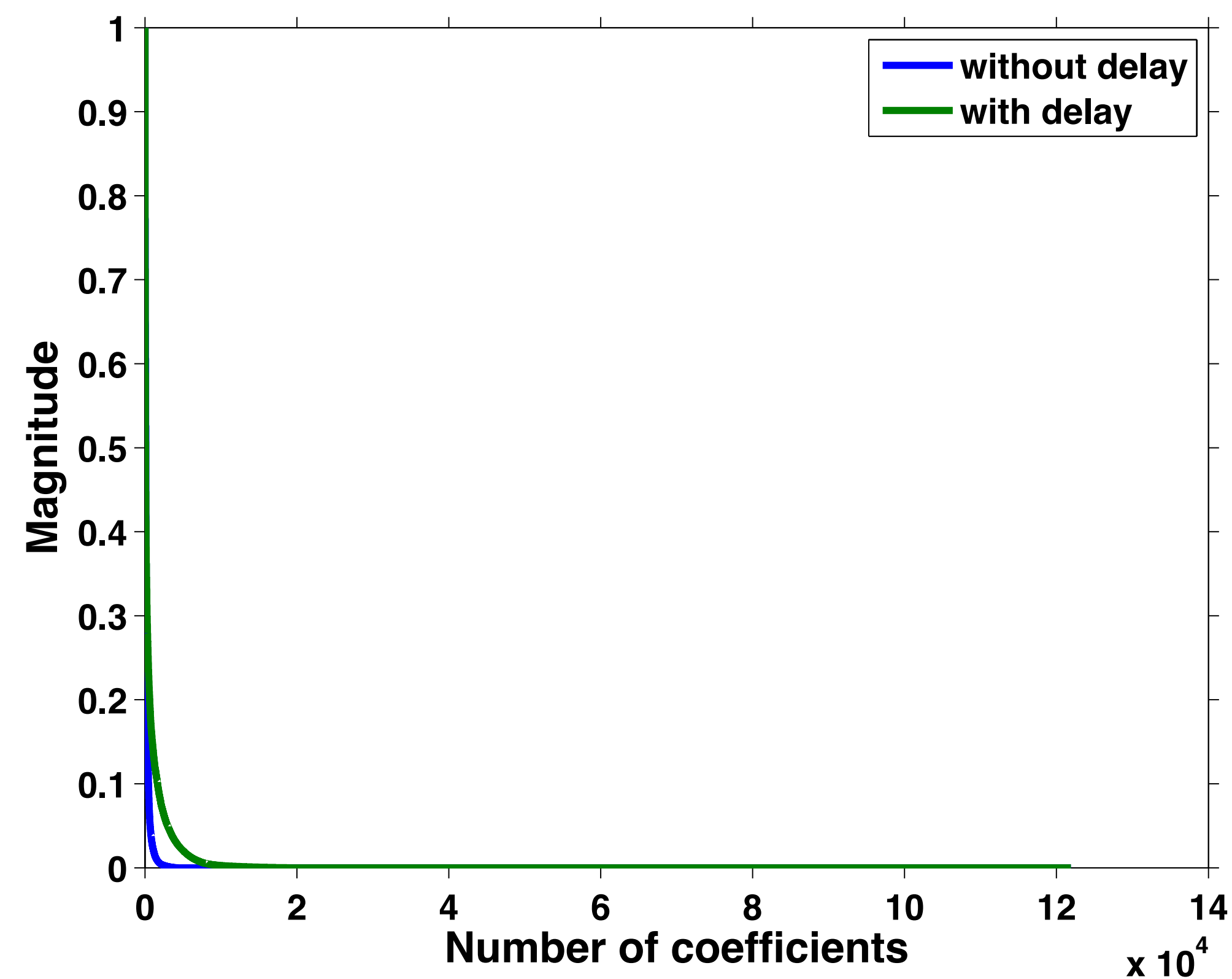
Rank-minimization vs. sparsity-promotion

Rank vs. sparsity

rank-minimization
(midpoint-offset domain)



sparsity-promotion
(source-receiver domain)



Blended data (w/ delay)

[random time delays applied to source 2]

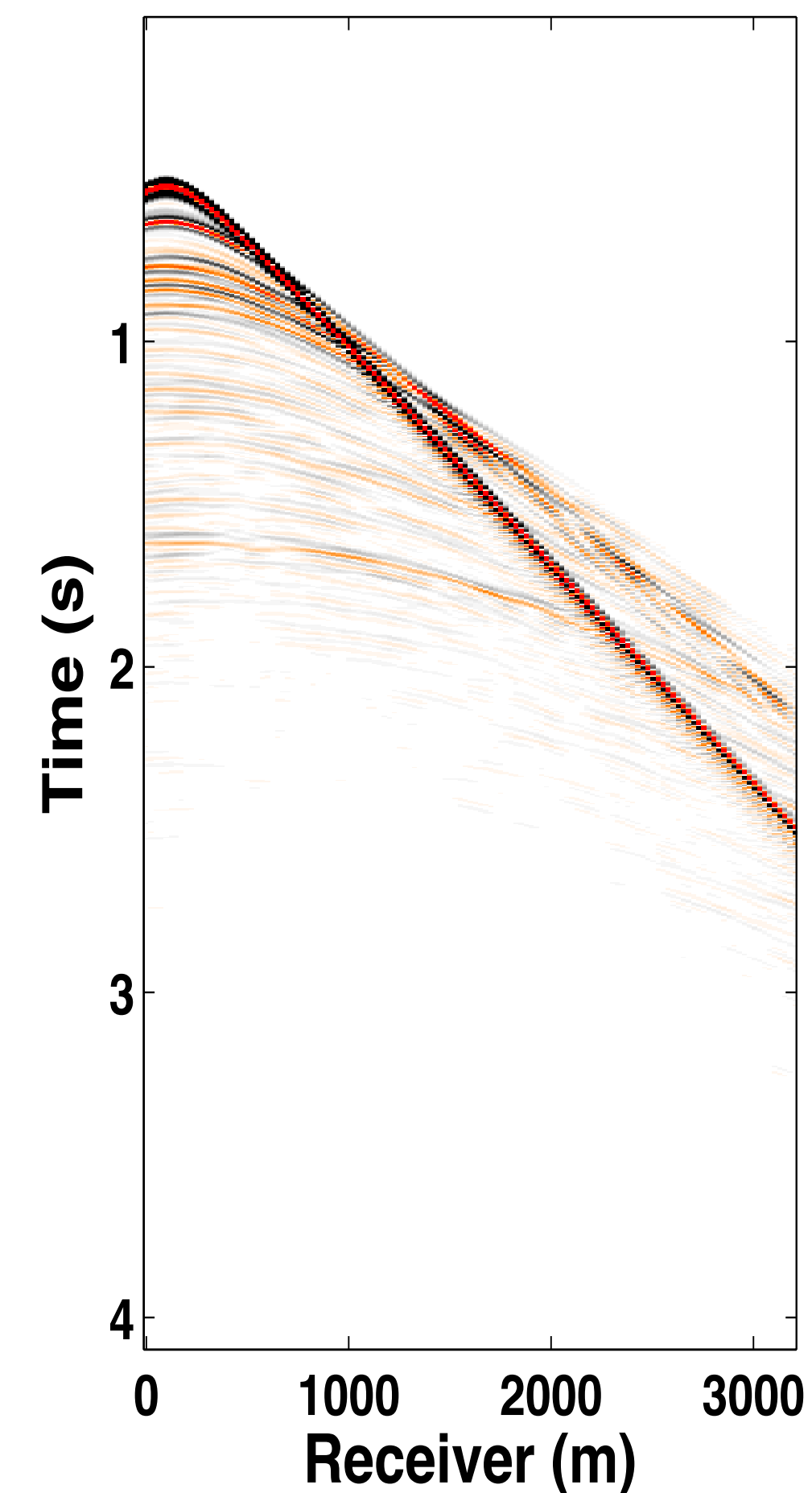
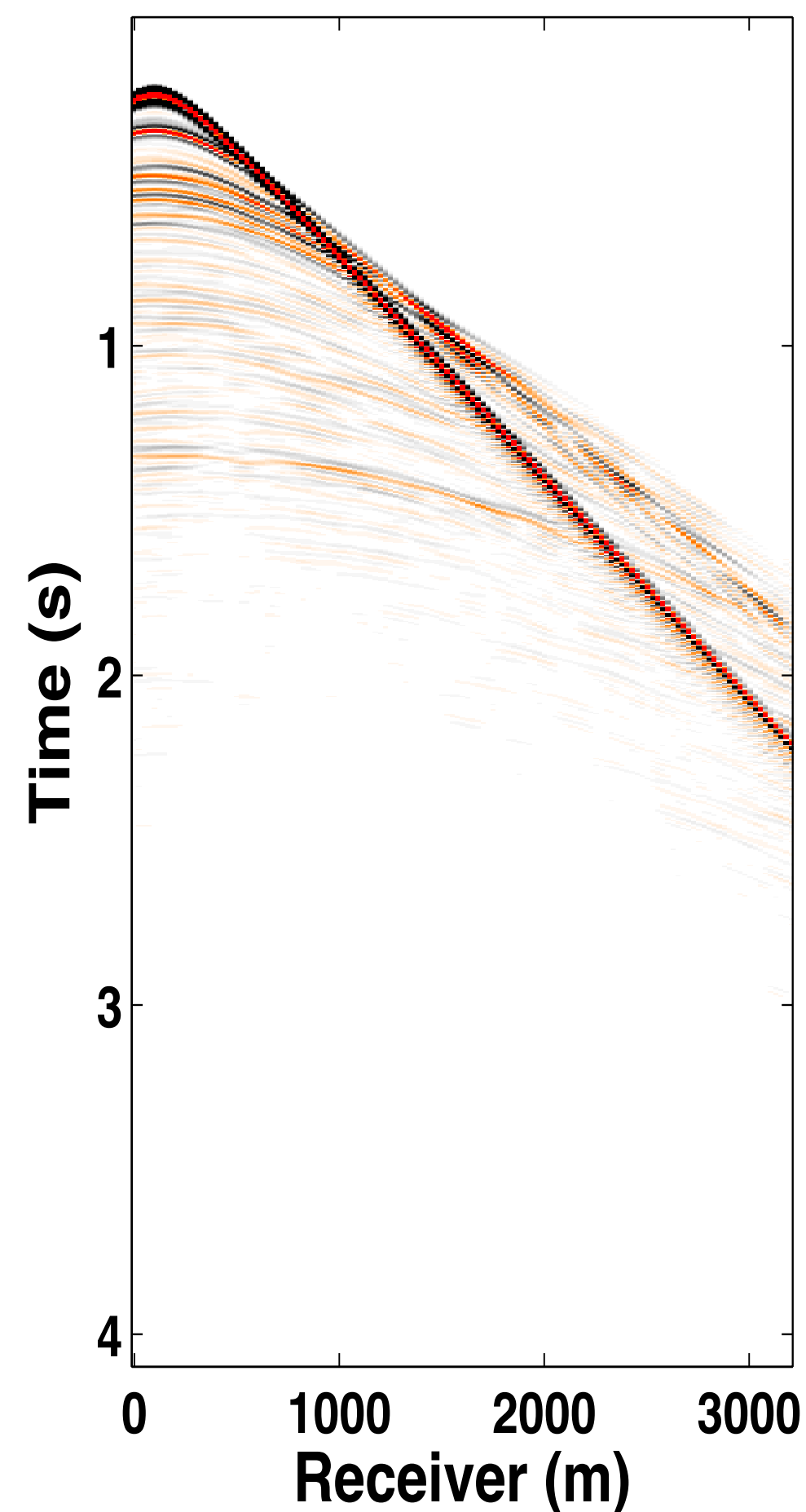
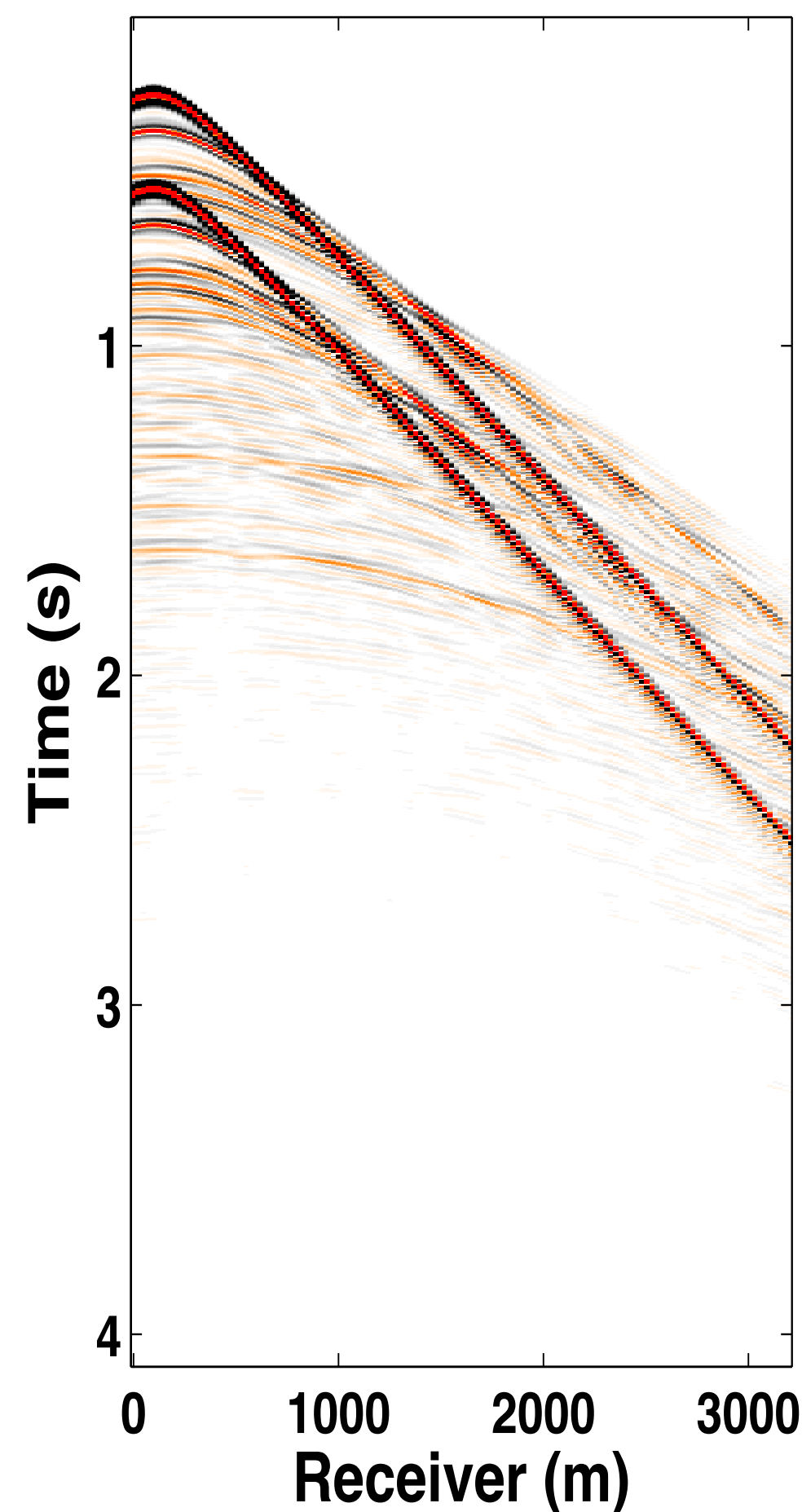
blended shot

=

source 1

+

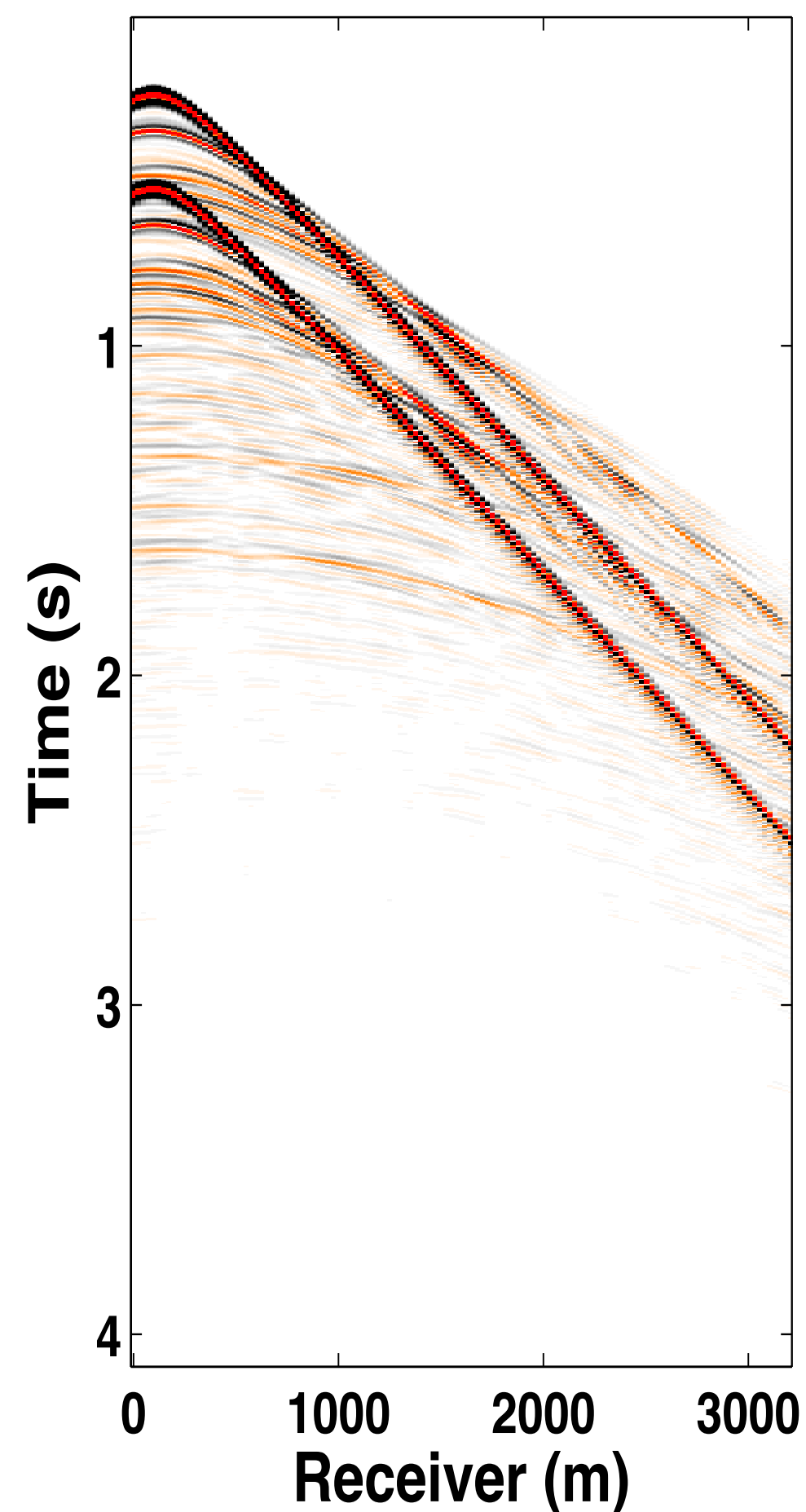
source 2
(time-delayed)



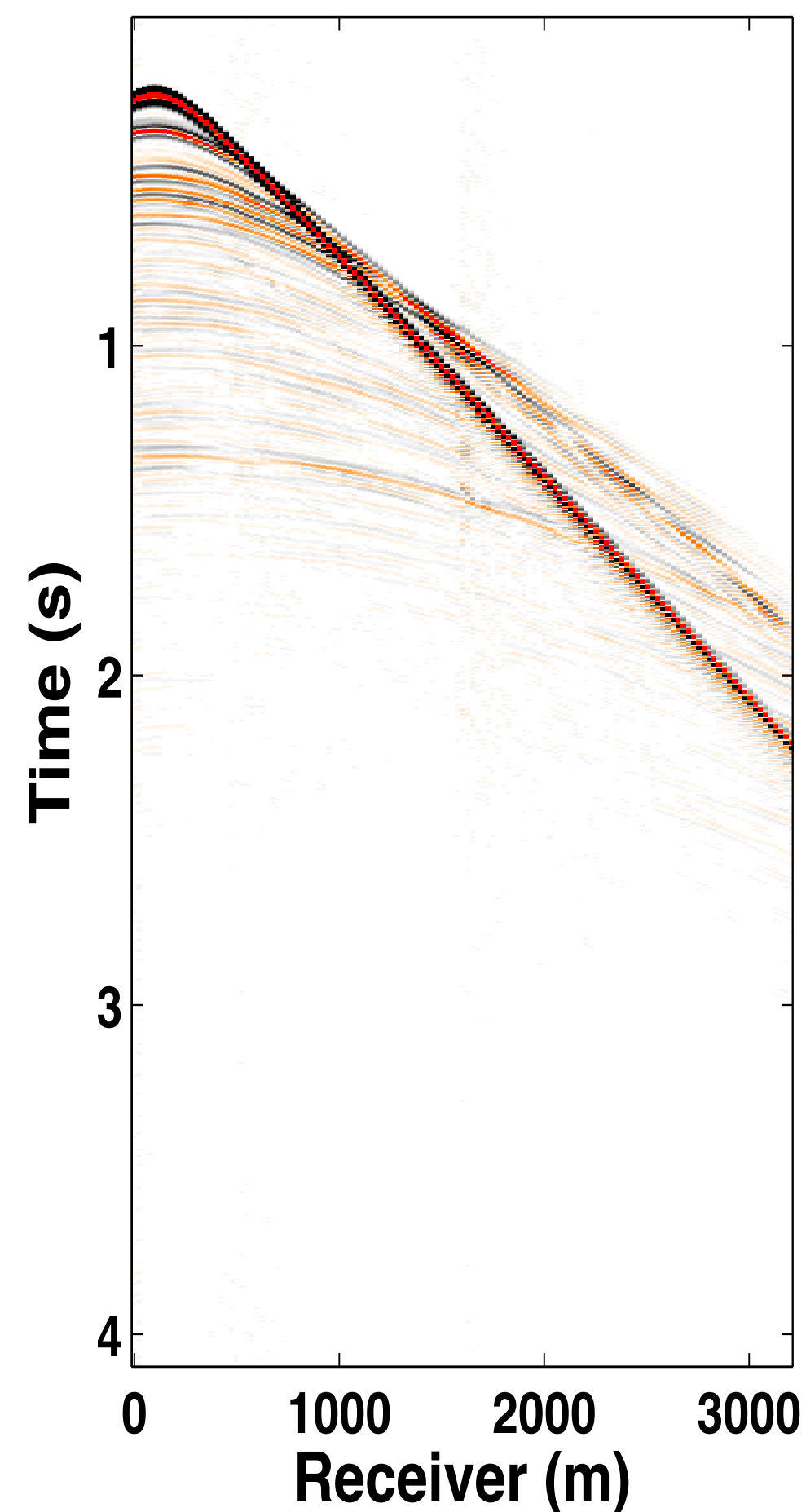
Source separation via *rank*-minimization

[computation time = 4 x 10 hours]

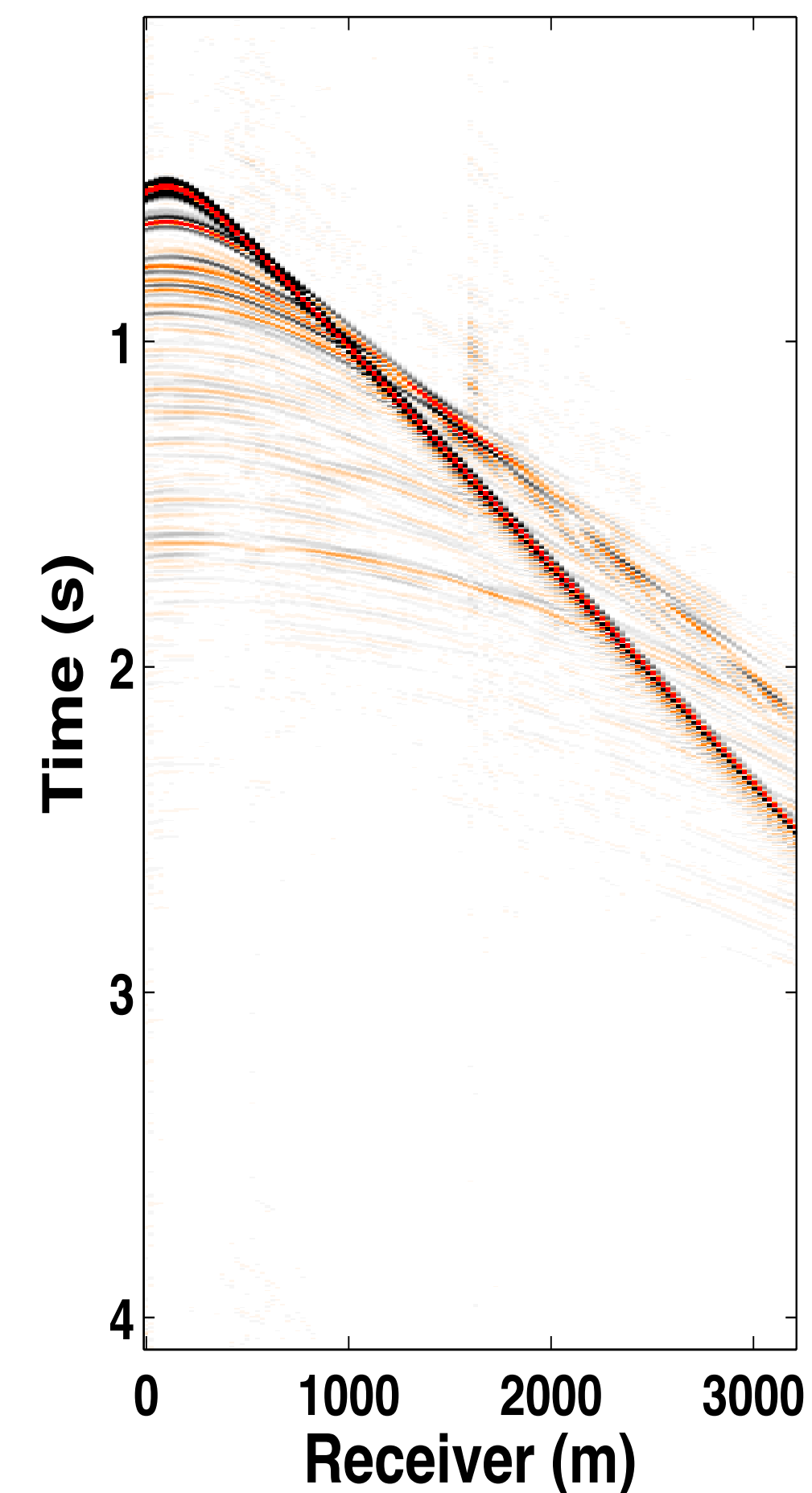
blended shot



source 1



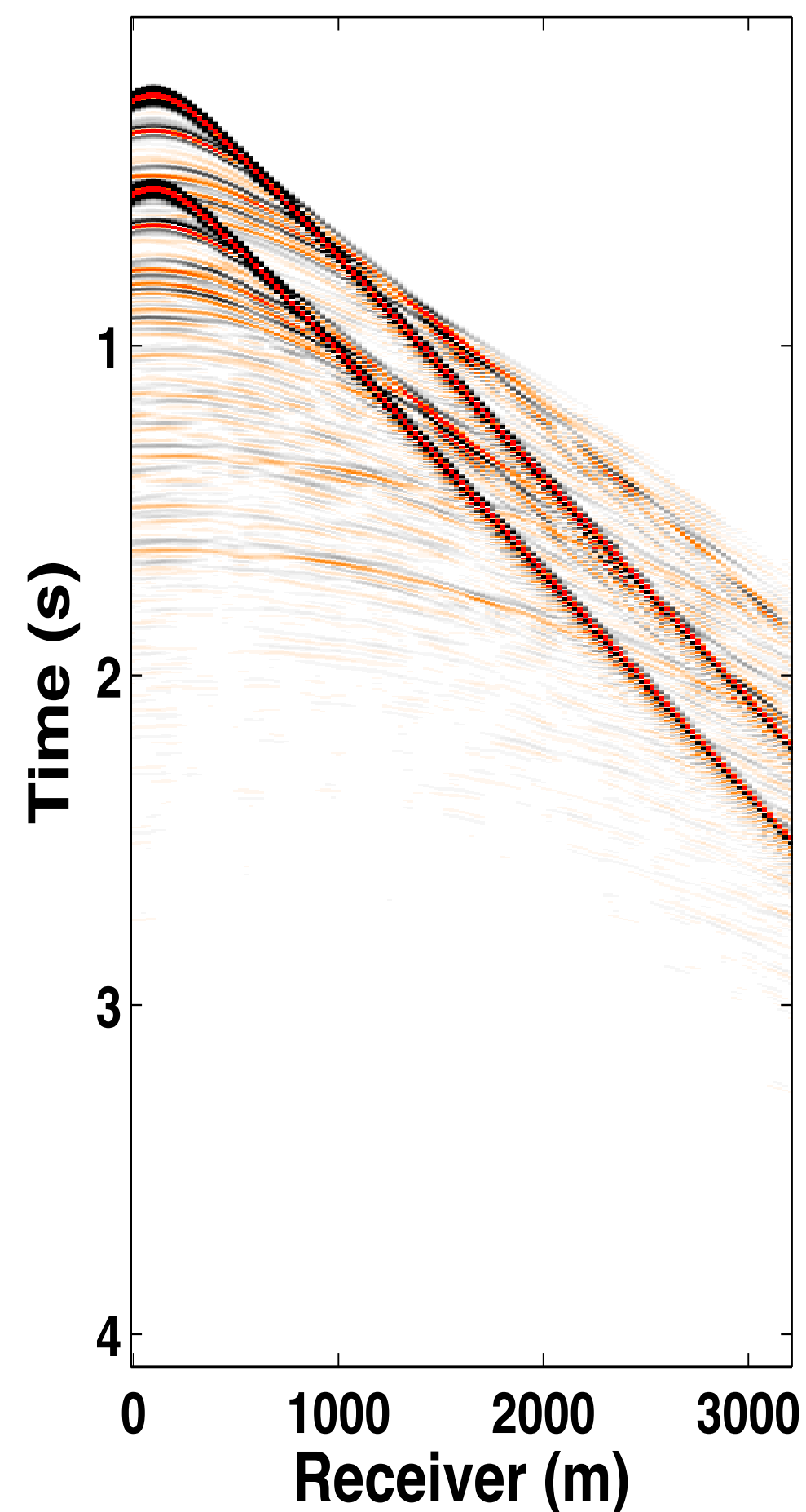
source 2
(time-delayed)



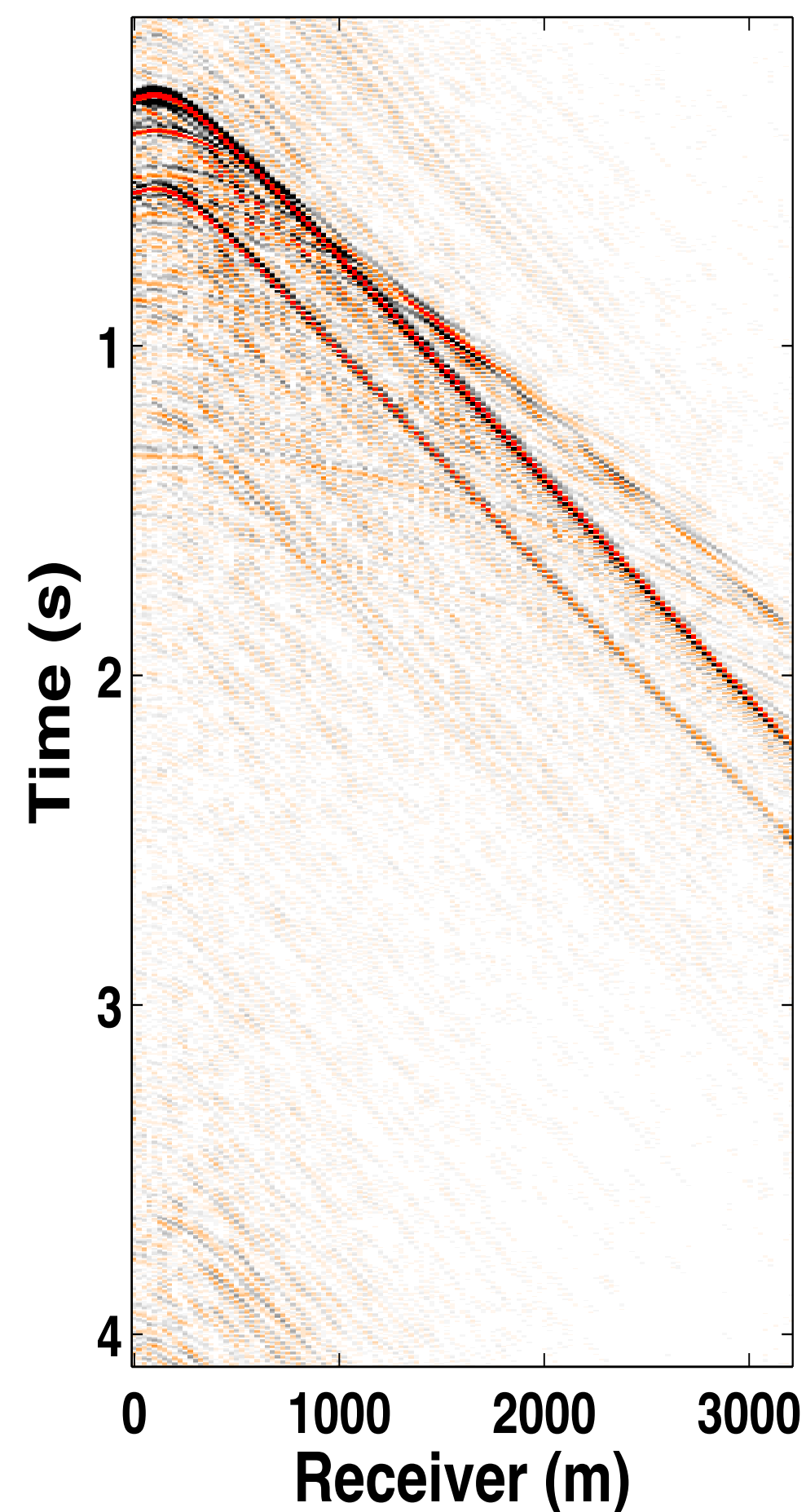
Source separation via *sparsity*-promotion

[computation time = 4 x 25 hours]

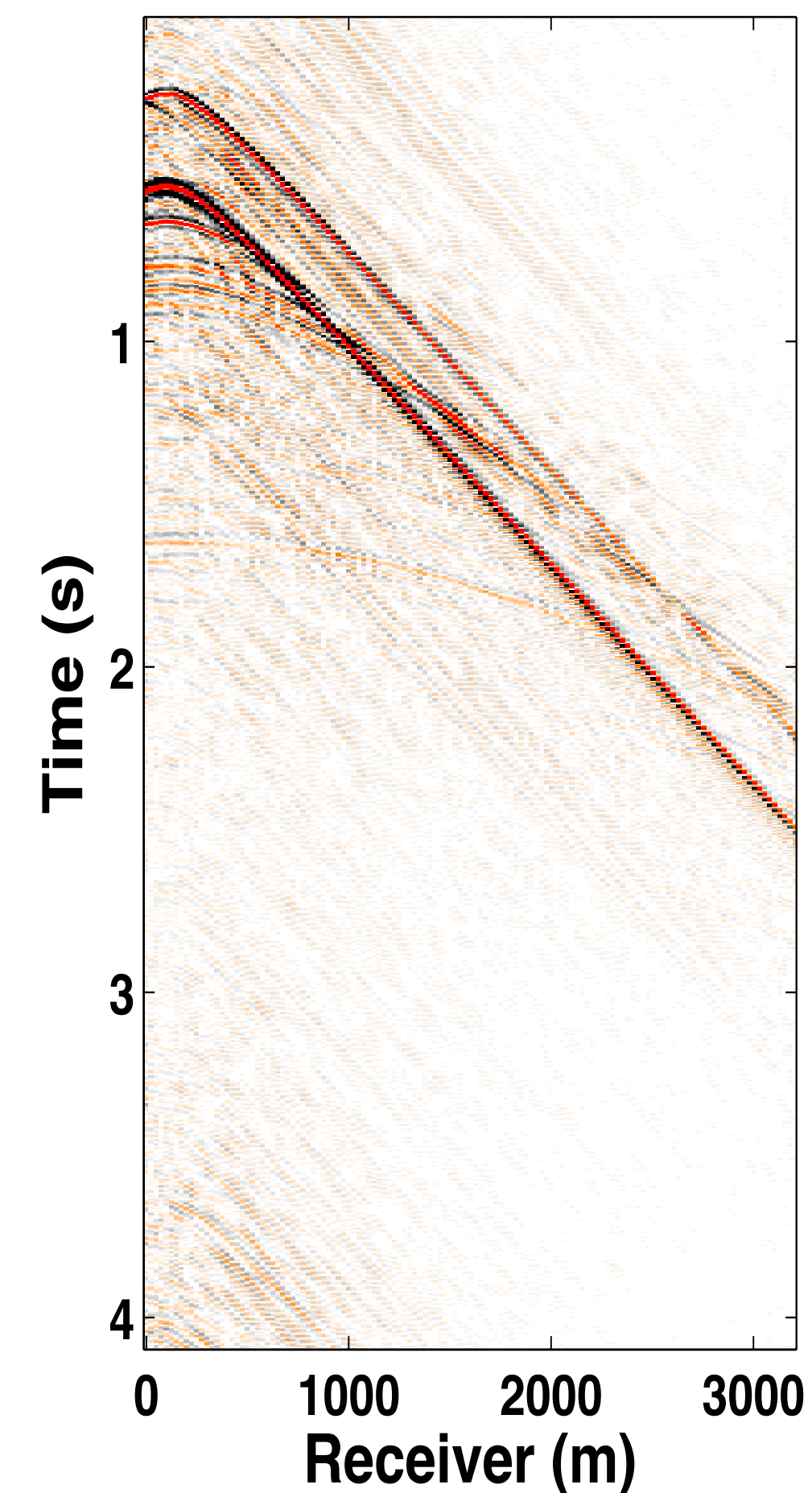
blended shot



source 1



source 2
(time-delayed)



Observations

- ▶ Source separation for *low variability* acquisition scenarios can be treated as a *rank-minimization* problem
 - towed-array (streamer) acquisition
- ▶ Small variability in shot-times does *not* seem *desirable* for source separation via *sparsity-promotion*

References

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Acknowledgements

Thank you for your attention!

SINBAD



This work was in part financially supported by the Natural Sciences and Engineering Research Council of Canada Discovery Grant (22R81254) and the Collaborative Research and Development Grant DNOISE II (375142-08). This research was carried out as part of the SINBAD II project with support from the following organizations: BG Group, BGP, BP, CGG, Chevron, ConocoPhillips, ION, Petrobras, PGS, Statoil, Total SA, Sub Salt Solutions, WesternGeco, and Woodside.