

Structured tensor missing-trace interpolation in the Hierarchical Tucker format

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Motivation

3D seismic experiments - 5D data

- expensive to acquire, store
- sample at *sub-Nyquist* rates

Data exhibits *low-rank* structure

- exploit structure for interpolation

Fully sampled data

- simultaneous sources in wave-equation based inversion
- mitigating multiples

- [1] Kreimer, N, and Sacchi, M. D. "A tensor higher-order singular value decomposition for prestack seismic data noise reduction and interpolation." (2012)
- [2] Gao, Jianjun, Vicente Oropenza, and Mauricio D. Sacchi. "Evaluation of a fast algorithm for the eigen-decomposition of large block Toeplitz matrices with application to 5D seismic data interpolation." (2011)

Context

Low-rank matrix/tensor completion via *nuclear norm* projection [1]

- Require SVDs on huge data matrices
- Not scalable to large problem sizes

Data completion via Toeplitz embedding [2]

- Problem size - $(\# \text{ data points})^2$

Goals

Generalization of Compressive Sensing to multiple dimensions

- what can we learn from 1D/2D recovery?

Randomized source/receiver acquisition

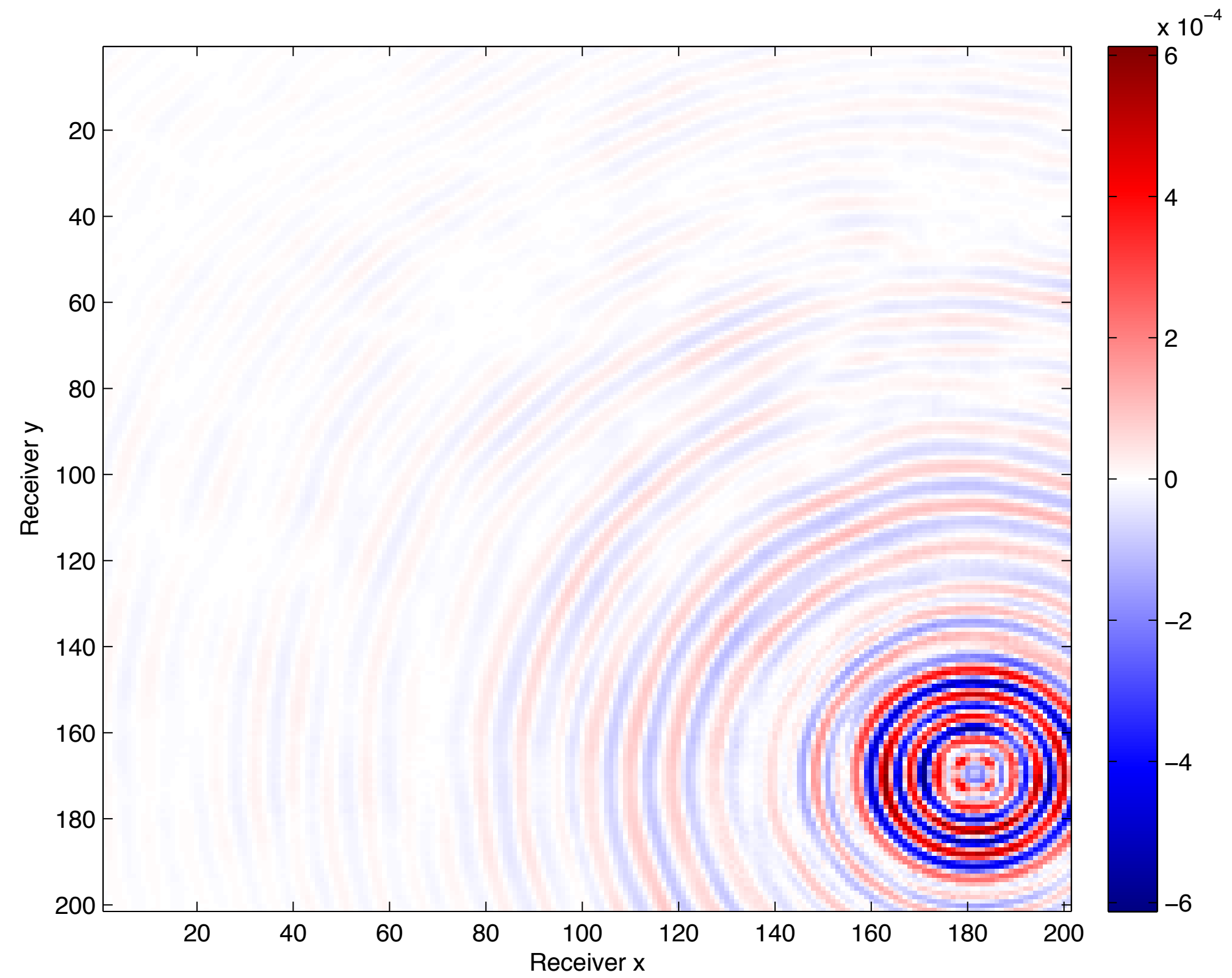
- reduce acquisition financial/time costs

Efficient solver

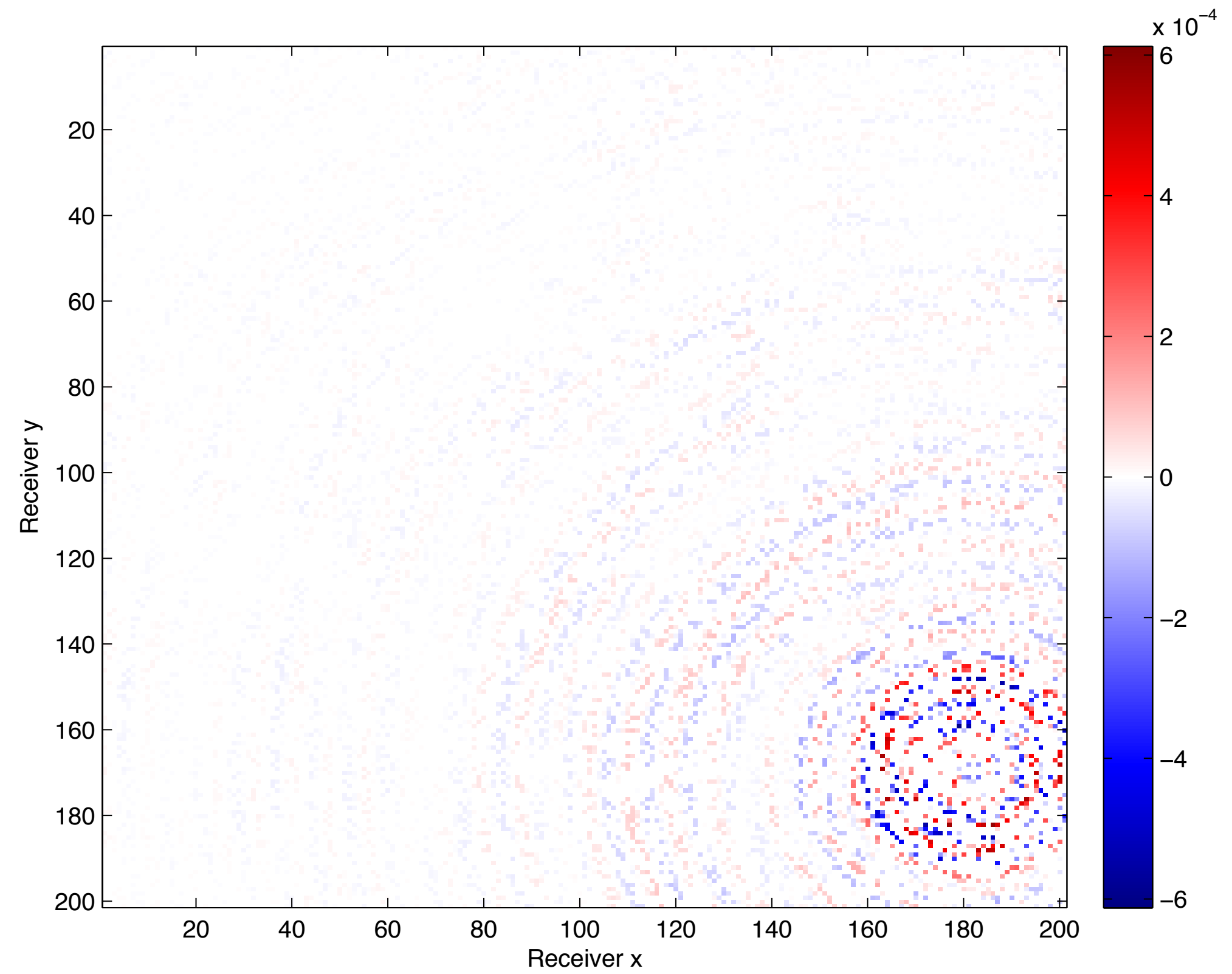
- SVD-free, parallelizable
- # parameters $\ll$ # data points

7.34 Hz - 75% missing receivers

Common source gather



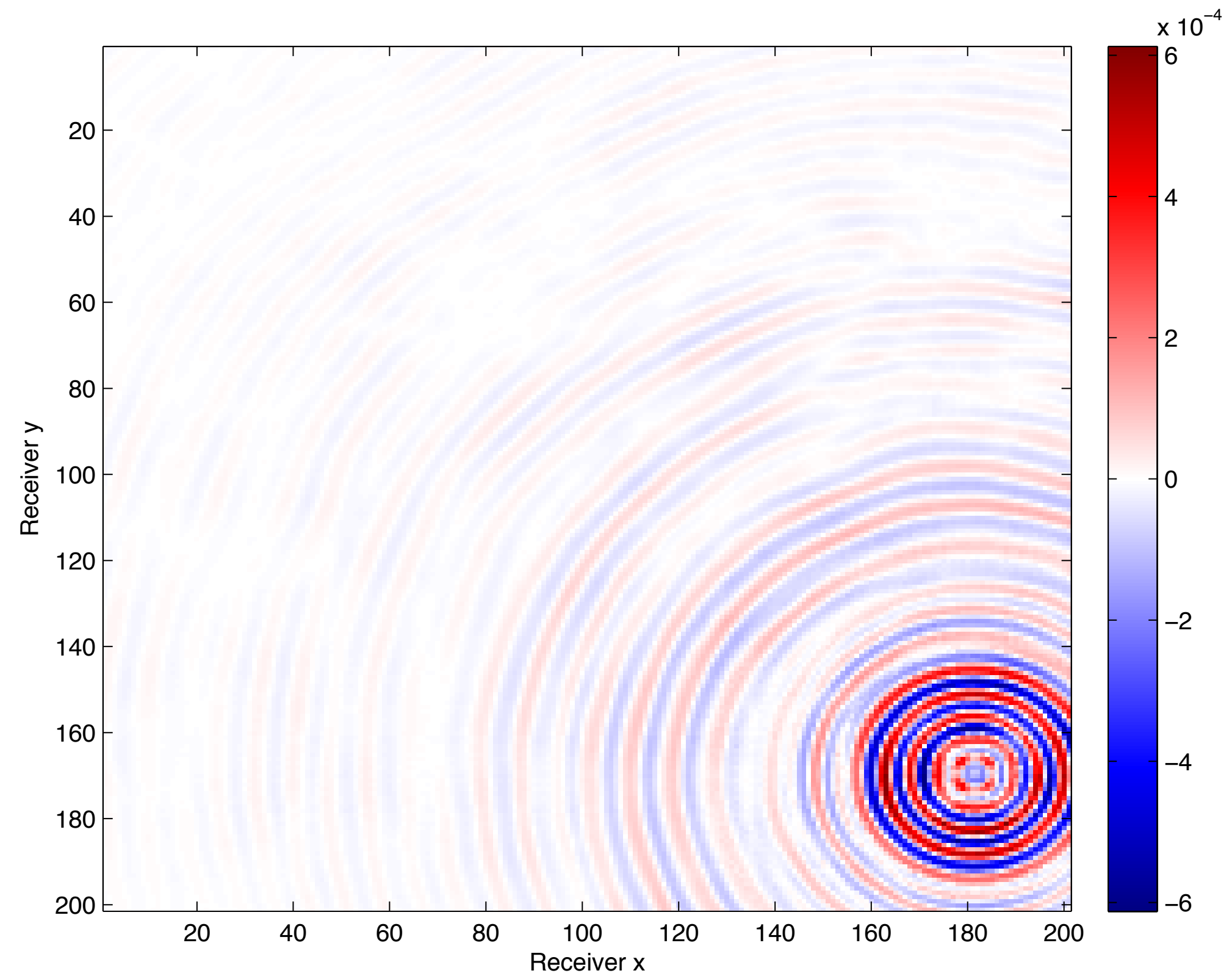
True data



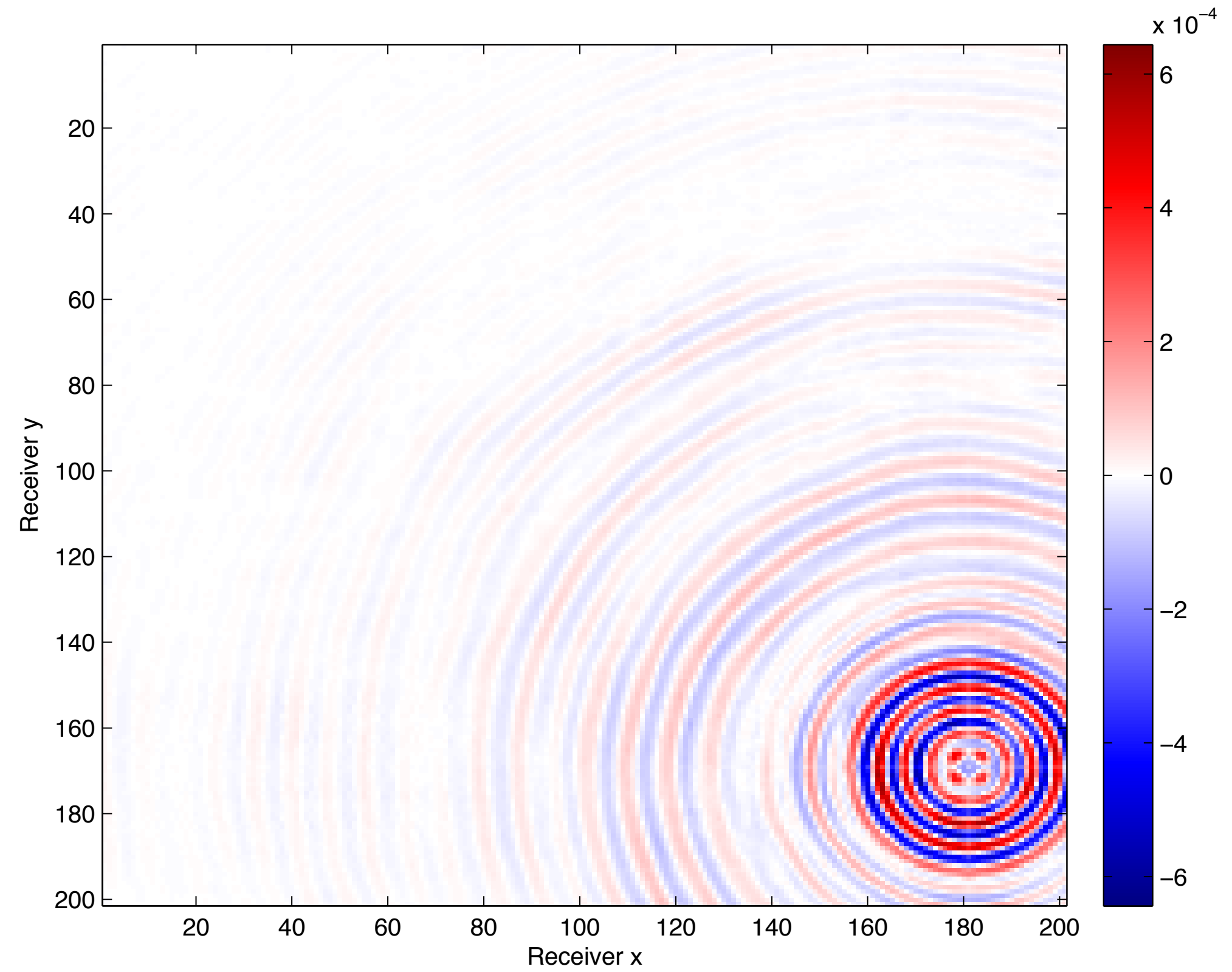
Subsampled data

7.34 Hz - 75% missing receivers

Common source gather



True data



Recovered data - SNR 17.4 dB

Compressive sensing

with sparsity promotion

Successful reconstruction scheme

Signal structure

- sparsity

Sampling

- subsampling decreases sparsity

Optimization

- look for sparsest solution

Multidimensional interpolation

with Hierarchical Tucker

Successful reconstruction scheme

Signal structure

- ***Hierarchical Tucker***

Sampling

- subsampling increases hierarchical rank

Optimization

- fit data in the Hierarchical Tucker format

Matricization

The matricization of a tensor X with dimensions $1, \dots, d$ along the dimensions $t = (t_1, \dots, t_r)$ is the matrix formed by placing the dimensions t along the rows and dimensions t^c along the columns

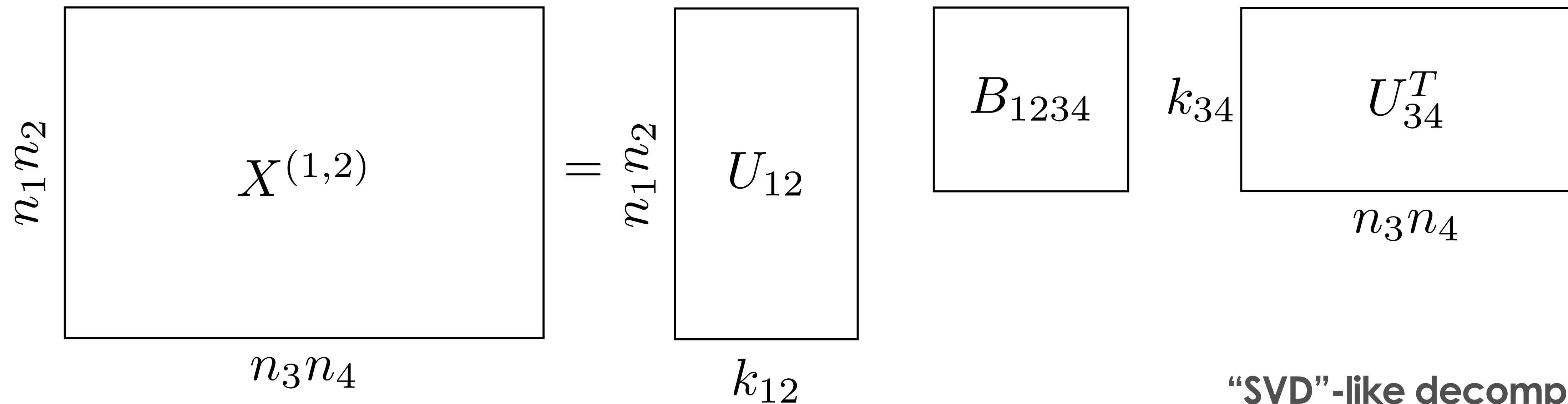
Denoted $X^{(t)}$

Example in Matlab

```
n1 = 20; n2 = 20; n3 = 20; n4 = 20;  
% Tensor  
x = randn(n1,n2,n3,n4);  
  
% Matricization along dimensions 1 and 2  
 $X^{(1,2)}$  x12 = reshape(x,n1 * n2, n3 * n4);  
  
% Matricization along dimensions 3 and 4  
 $X^{(3,4)}$  y34 = permute(x,[3 4 1 2]);  
x34 = reshape(x, n3 * n4, n1 * n2);  
  
% Matricization along dimensions 1 and 3  
 $X^{(1,3)}$  y13 = permute(x,[1 3 2 4]);  
x13 = reshape(x,n1 * n3, n2 * n4);
```

Hierarchical Tucker format

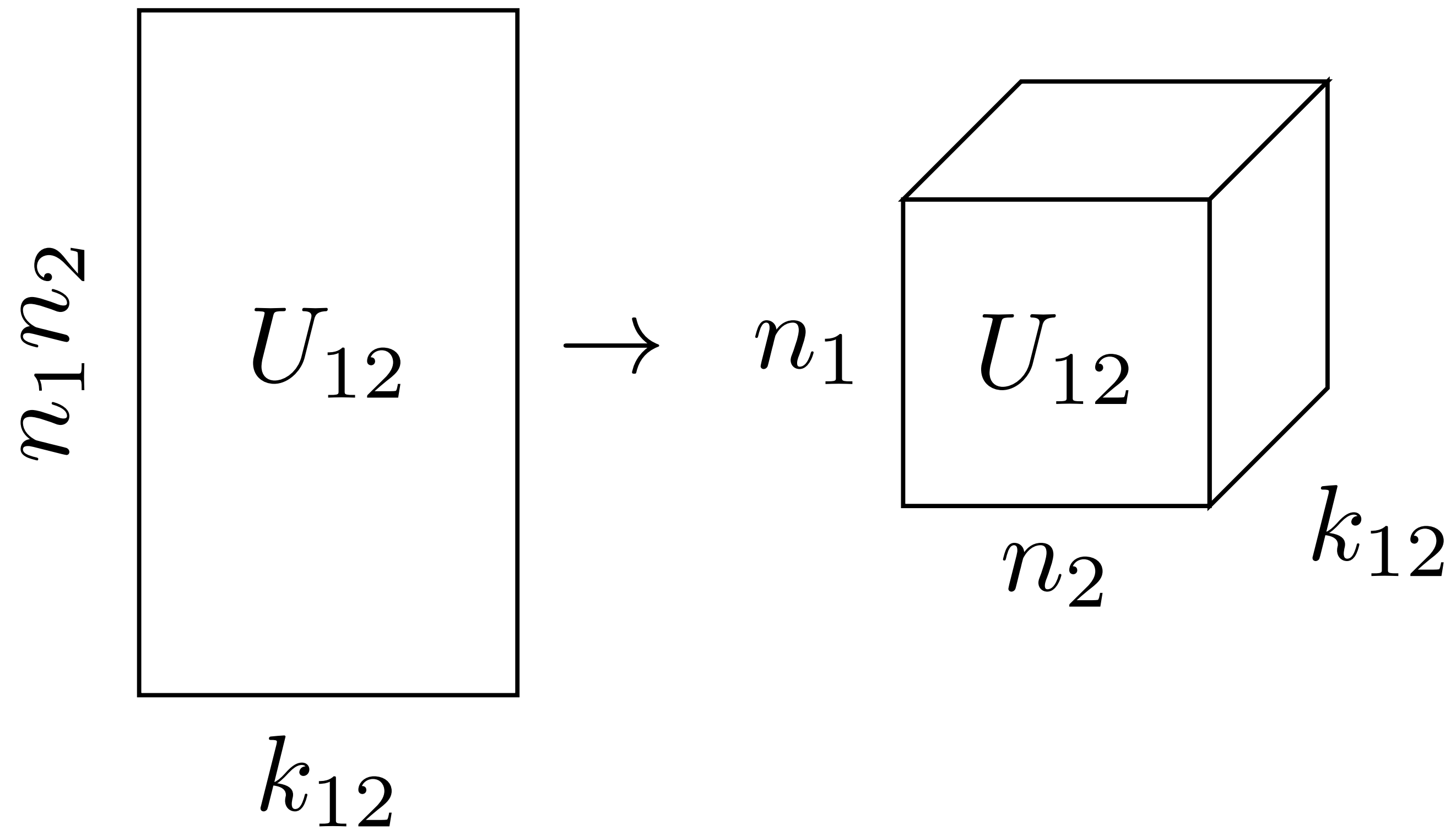
$X - n_1 \times n_2 \times n_3 \times n_4$ tensor



“SVD”-like decomposition

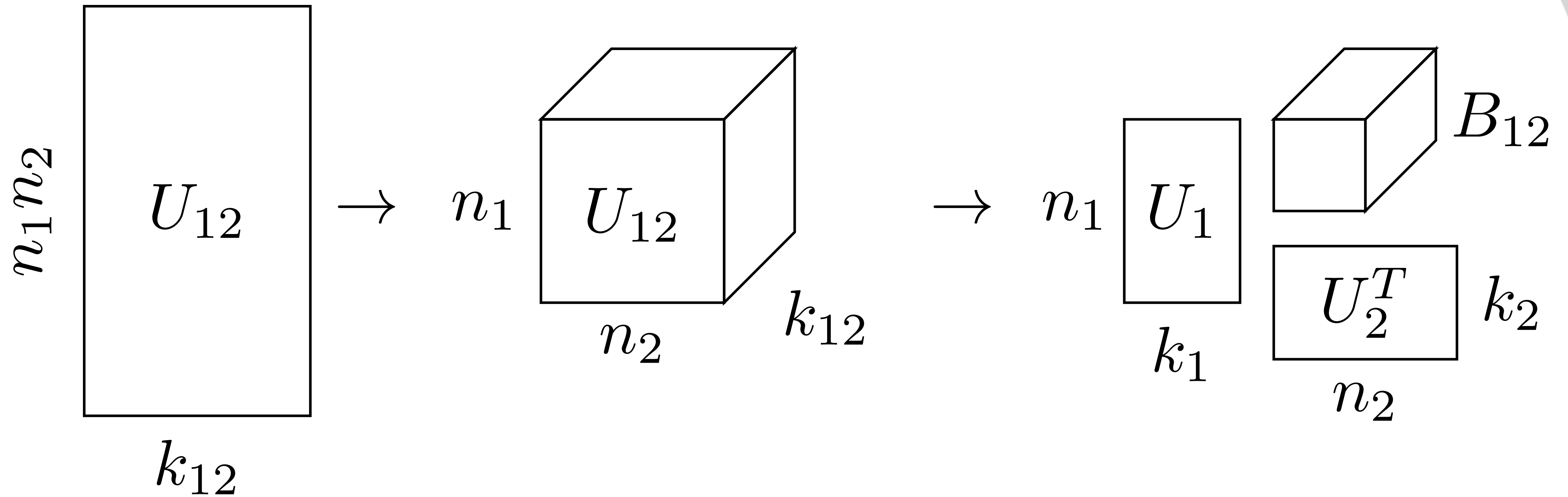
Hierarchical Tucker format

$X - n_1 \times n_2 \times n_3 \times n_4$ tensor



Hierarchical Tucker format

$X - n_1 \times n_2 \times n_3 \times n_4$ tensor



Hierarchical Tucker format

Intermediate matrices don't need to be stored

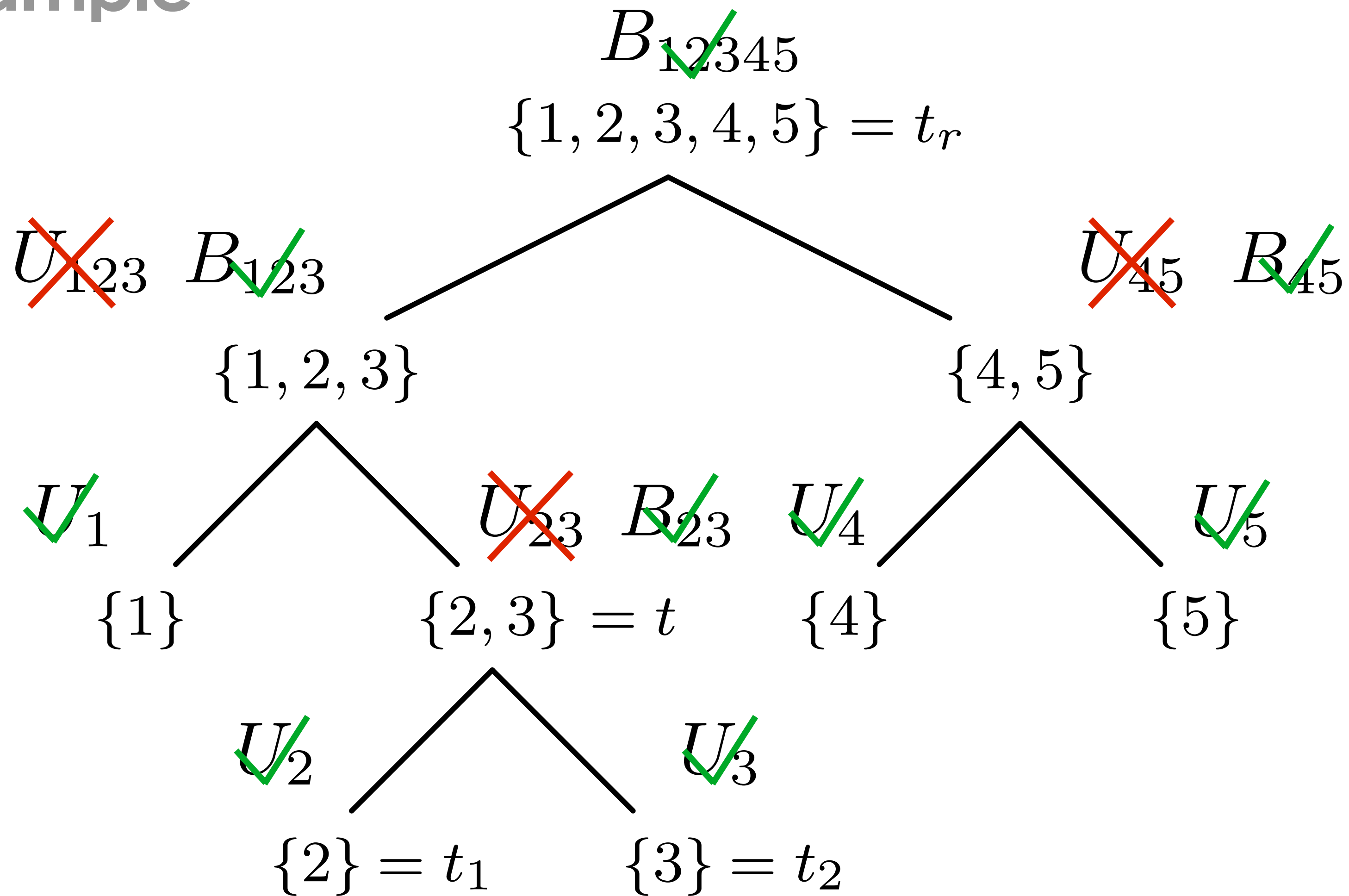
U_t, B_t - small parameter matrices

- specify the tensor completely

Separating groups of dimensions from each other

- dimension tree

Example



Hierarchical Tucker format

$$\text{Storage} \leq dNK + (d-2)K^3 + K^2$$

Compare to N^d storage for the full tensor

Effectively breaking the curse of dimensionality when $K \ll N$ $d \geq 4$

Low frequency data compresses in HT

Hierarchical Tucker example

For a $100 \times 100 \times 100 \times 100$ cube with max rank 20

$$N = 100, d = 4, K = 20$$

Full storage: $N^d = 10^8$ values

HTucker storage: 24400 values

Compression of a factor of **99.97%**

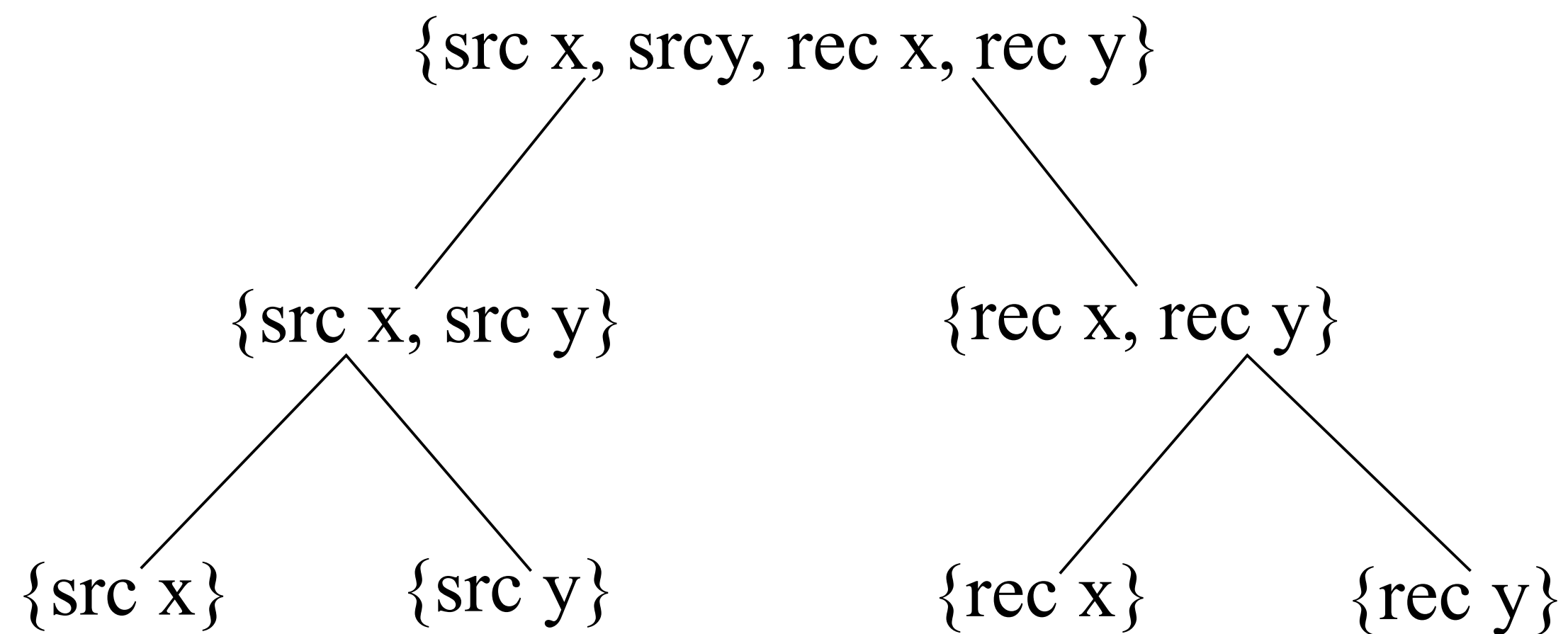
Seismic Hierarchical Tucker

We consider a 3D seismic survey with coordinates
(src x, src y, rec x, rec y, time)

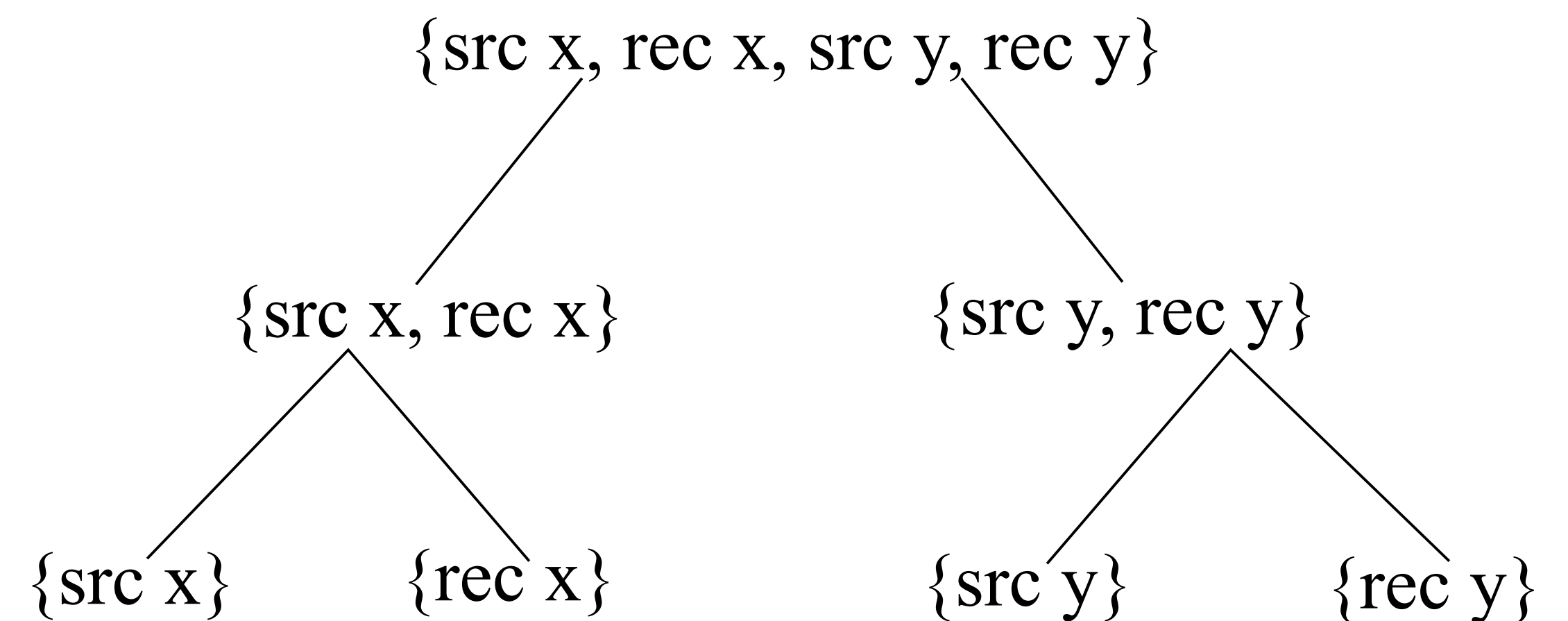
We take a Fourier transform in time and restrict ourselves to a single
frequency slice

Seismic Hierarchical Tucker

For a frequency slice with coordinates (src x, src y, rec x, rec y),
there are essentially two choices of dimension splitting (by reciprocity)

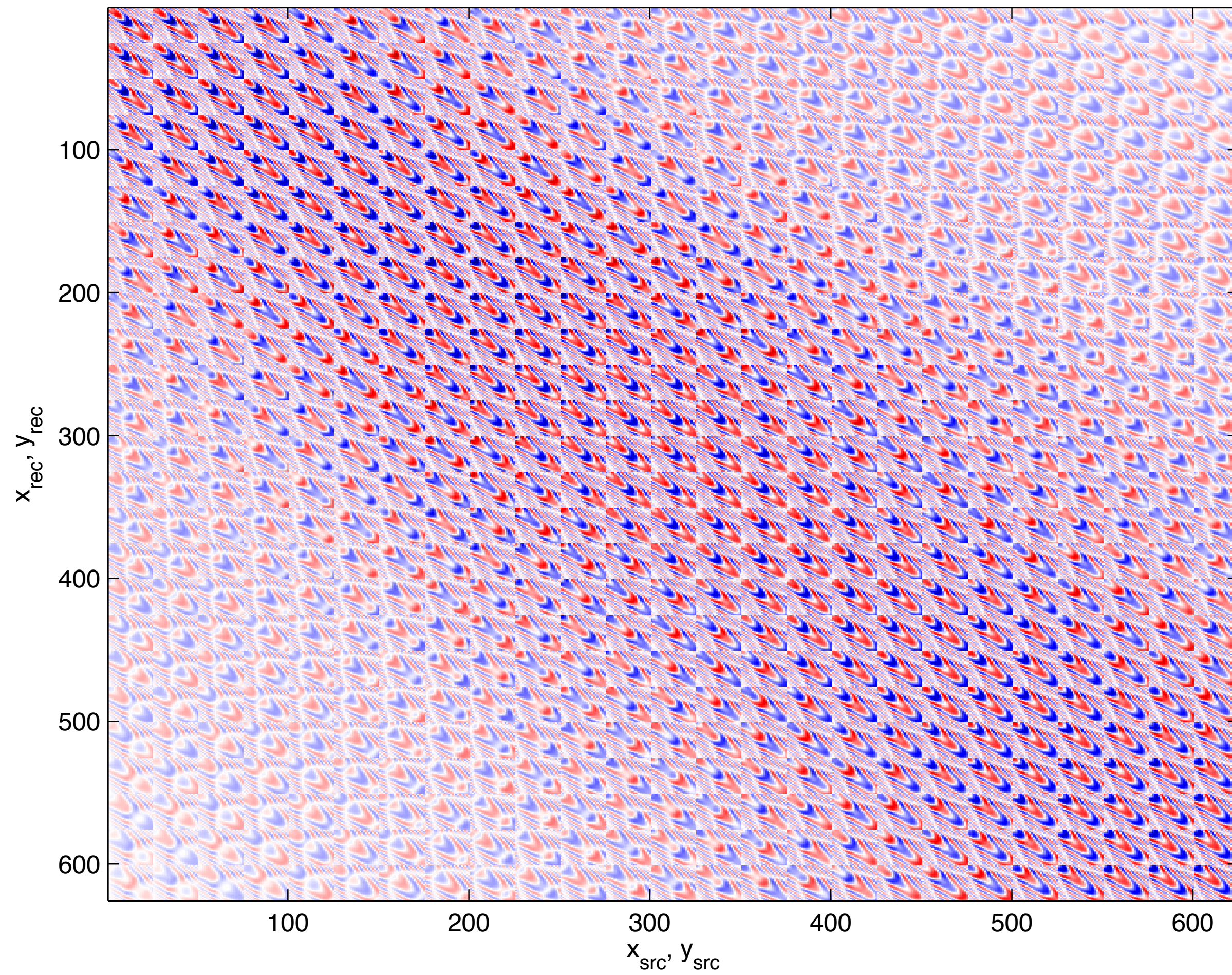


Canonical Decomposition

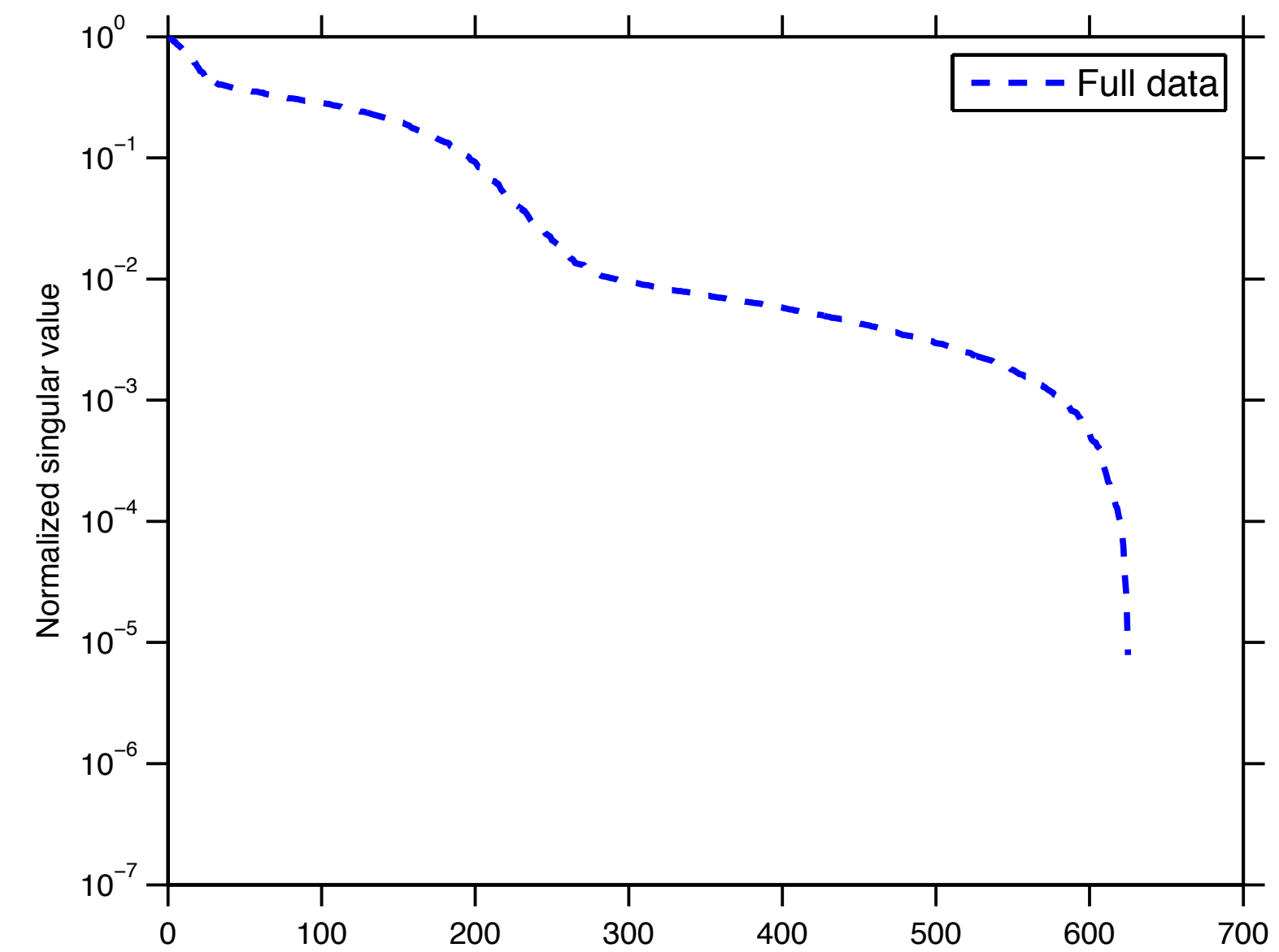
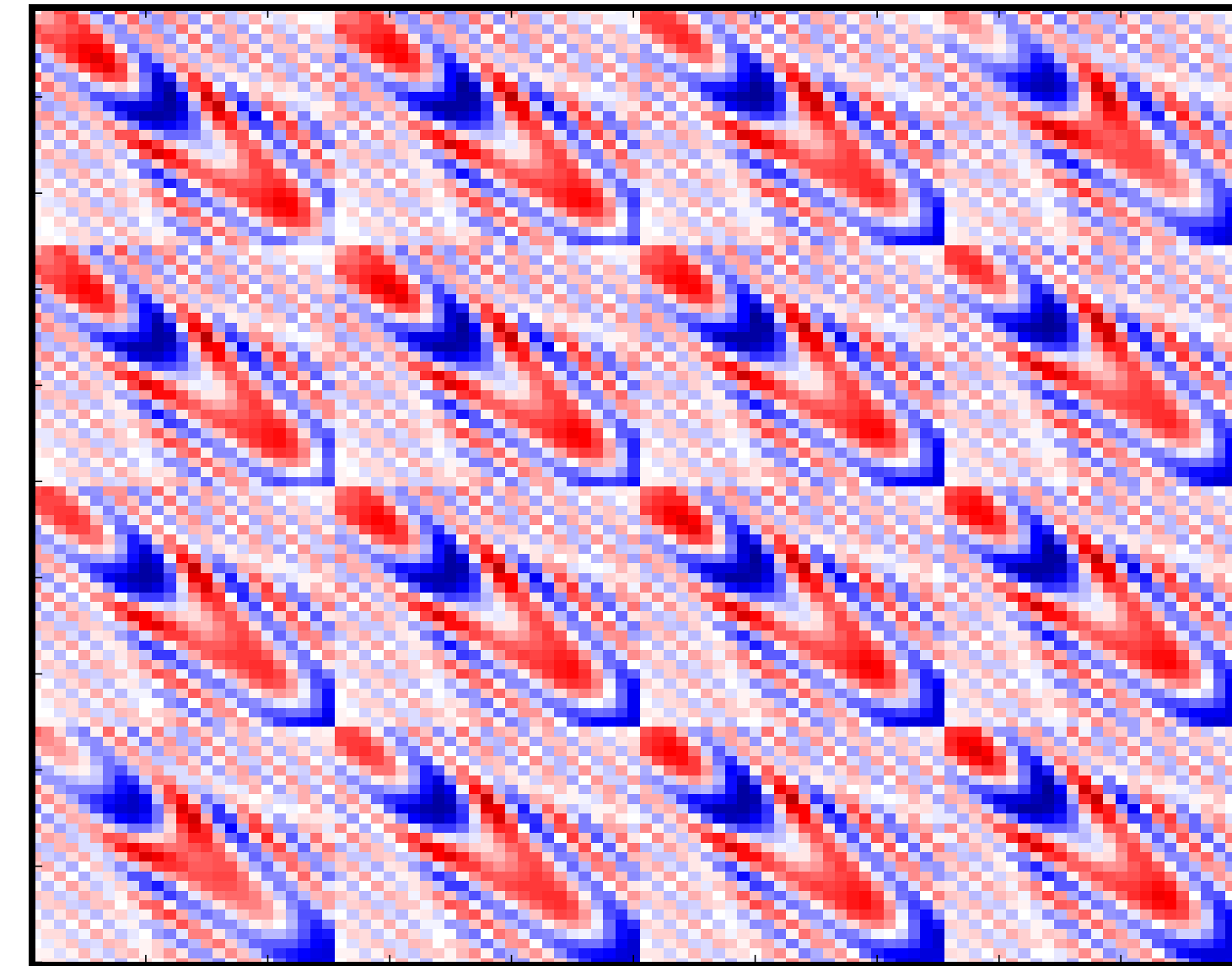


Non-canonical Decomposition

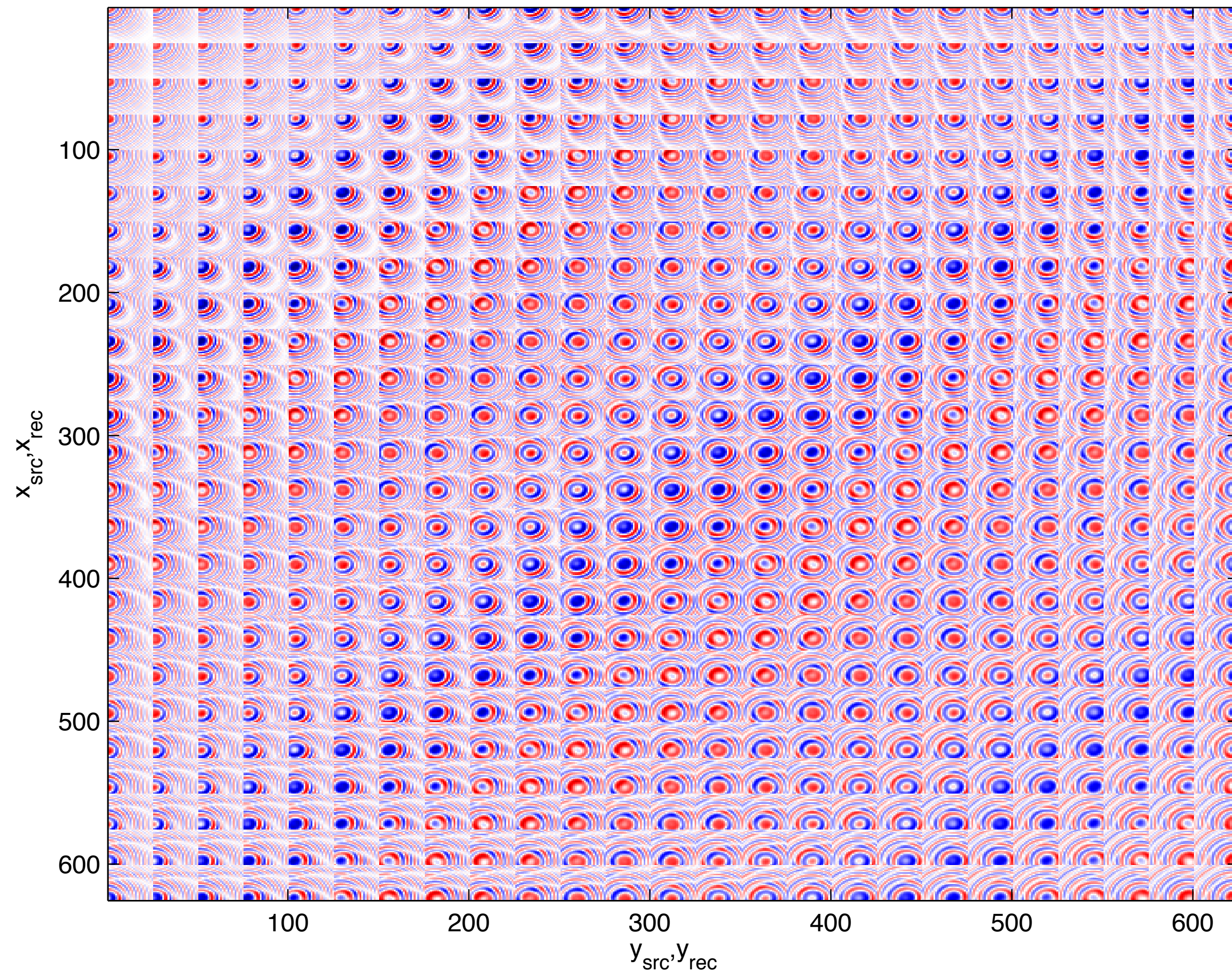
Matricizations



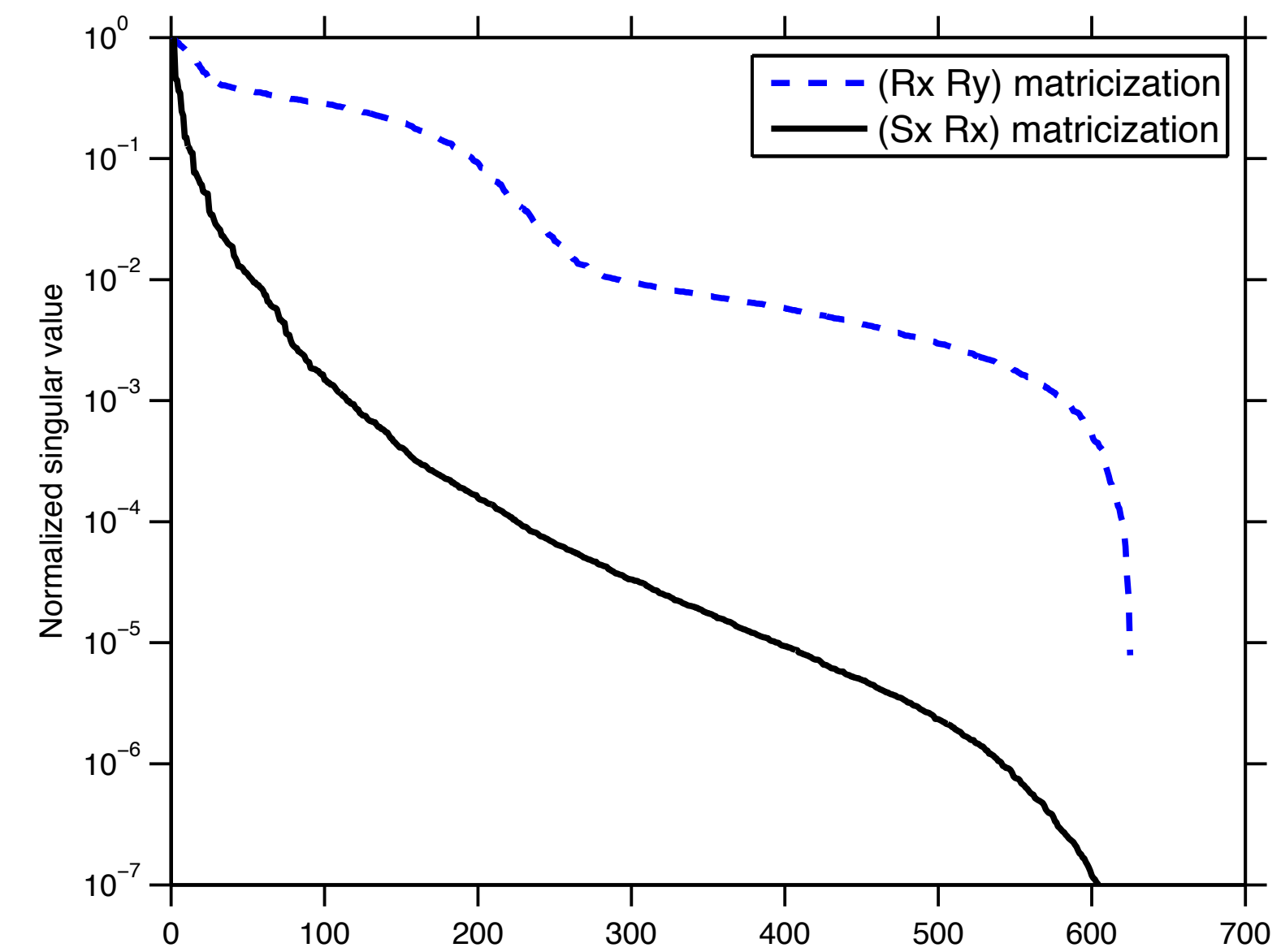
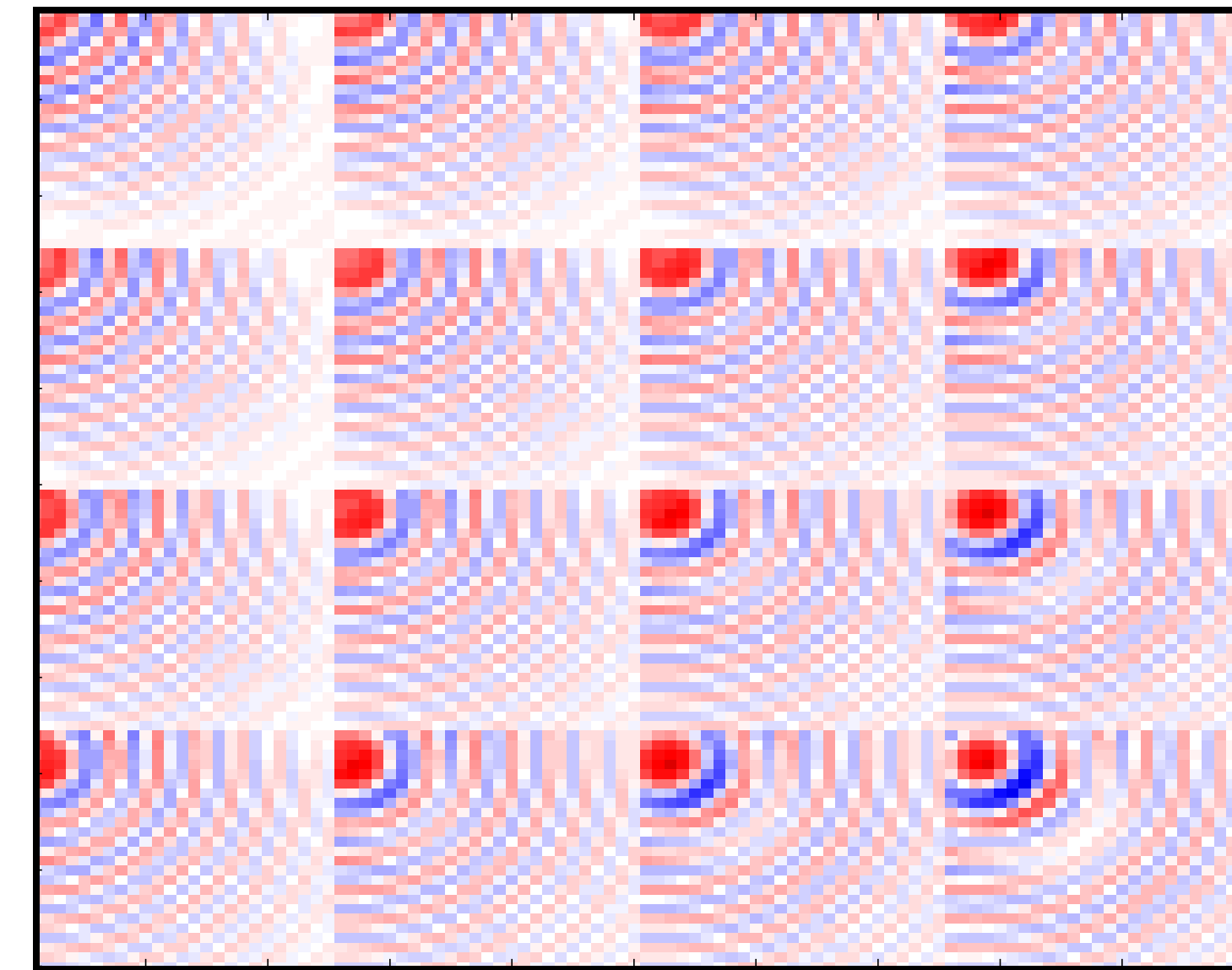
(Rec x, Rec y) matricization - Canonical ordering



Matricizations



(Src x, Rec x) matricization - Noncanonical ordering



Multidimensional interpolation

with Hierarchical Tucker

Successful reconstruction scheme

Signal structure

- Hierarchical Tucker

Sampling

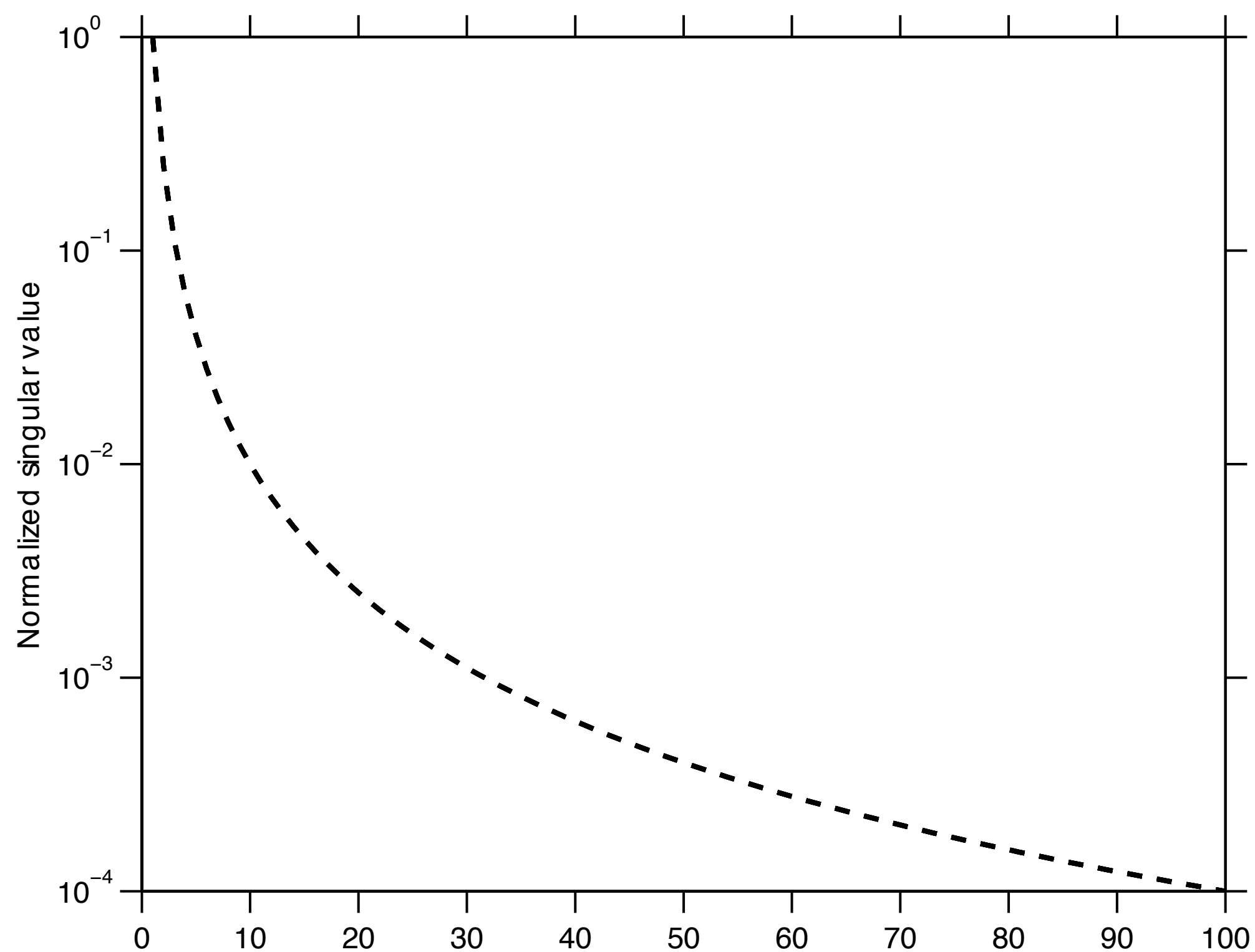
- ***subsampling increases hierarchical rank***

Optimization

- fit data in the Hierarchical Tucker format

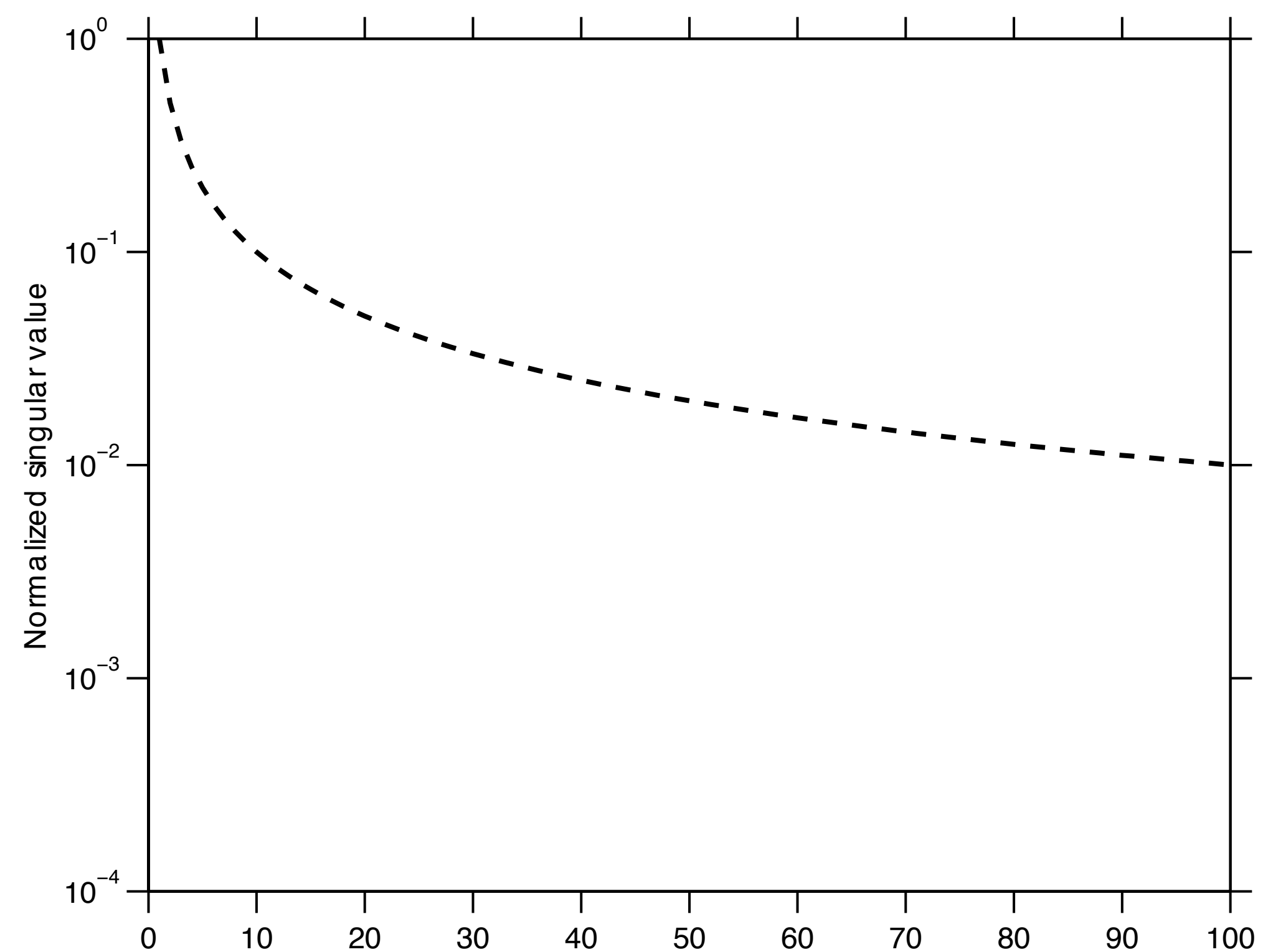
Matrix Completion

X



Matrix Completion

$$\mathcal{A}(\mathbf{X}) = \begin{bmatrix} * & * & * & 0 & * \\ * & 0 & 0 & * & 0 \\ * & * & * & * & * \\ * & * & 0 & * & * \\ 0 & * & * & * & 0 \end{bmatrix}$$



Tensor Completion

Structure - recover a tensor X which has low hierarchical rank

- Well represented in HT

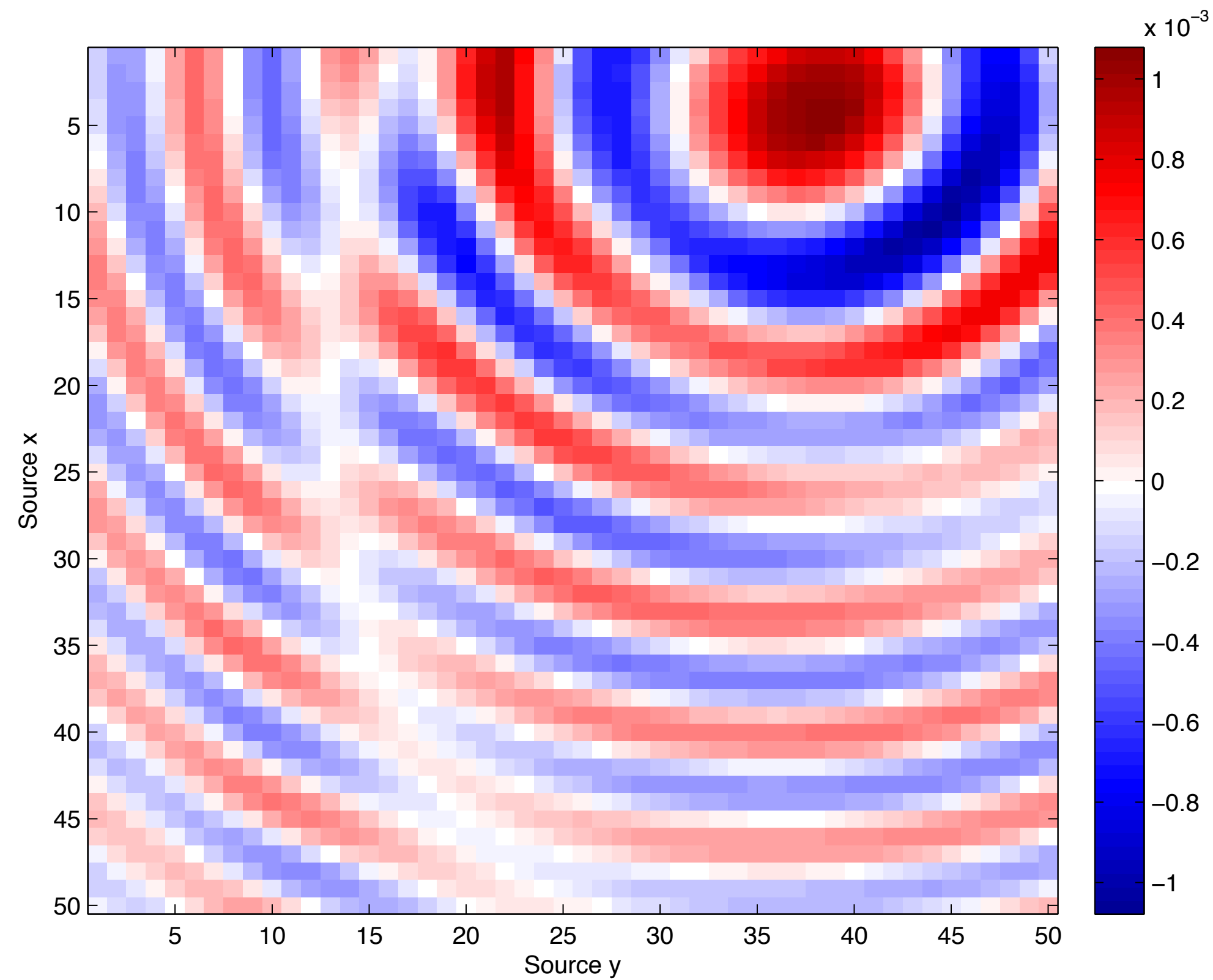
Sampling - random removal of points increases rank

- Poorly represented in HT
- Idealized sampling

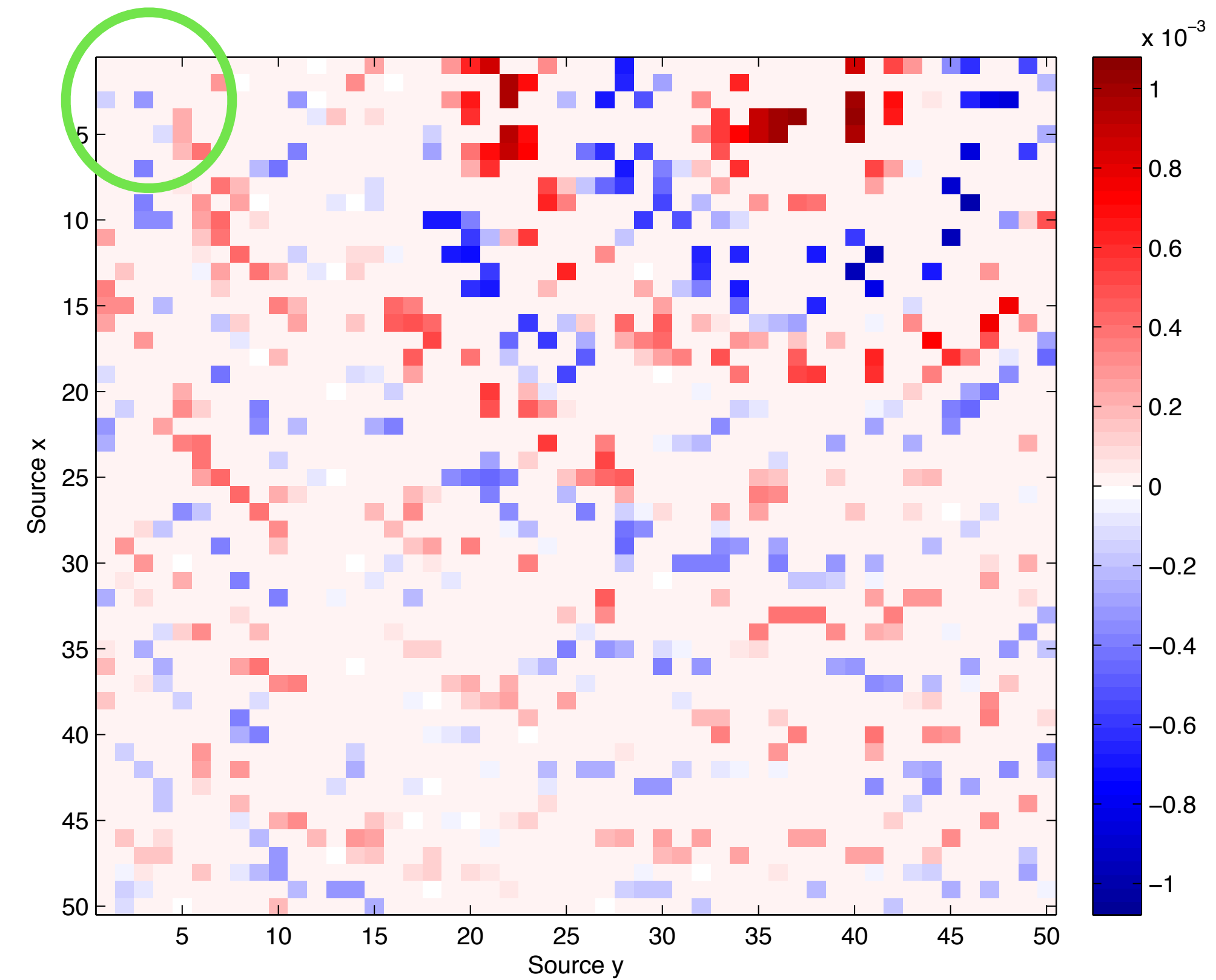
Idealized recovery

75% random entries removed

Common receiver gather



True data

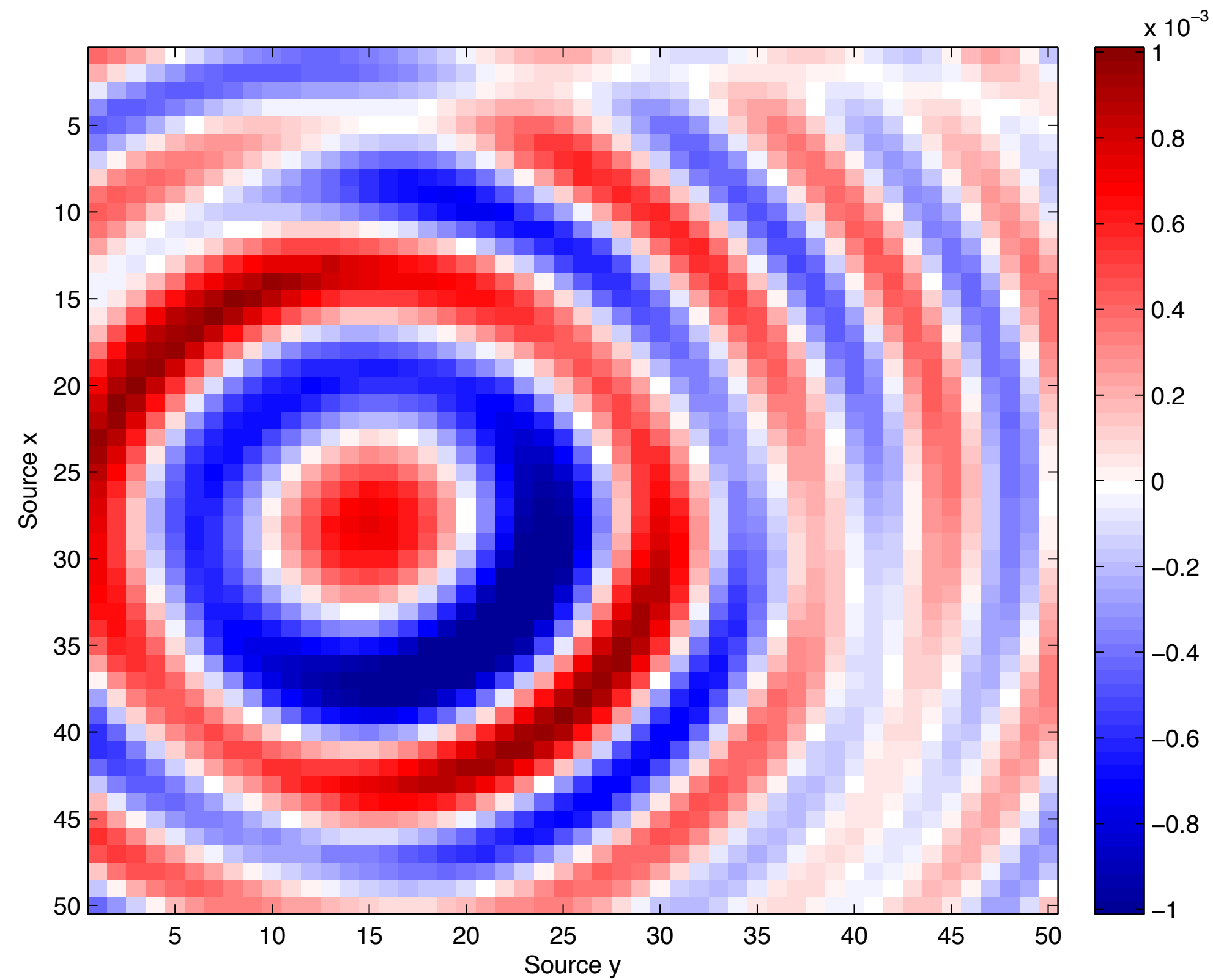


Subsampled data

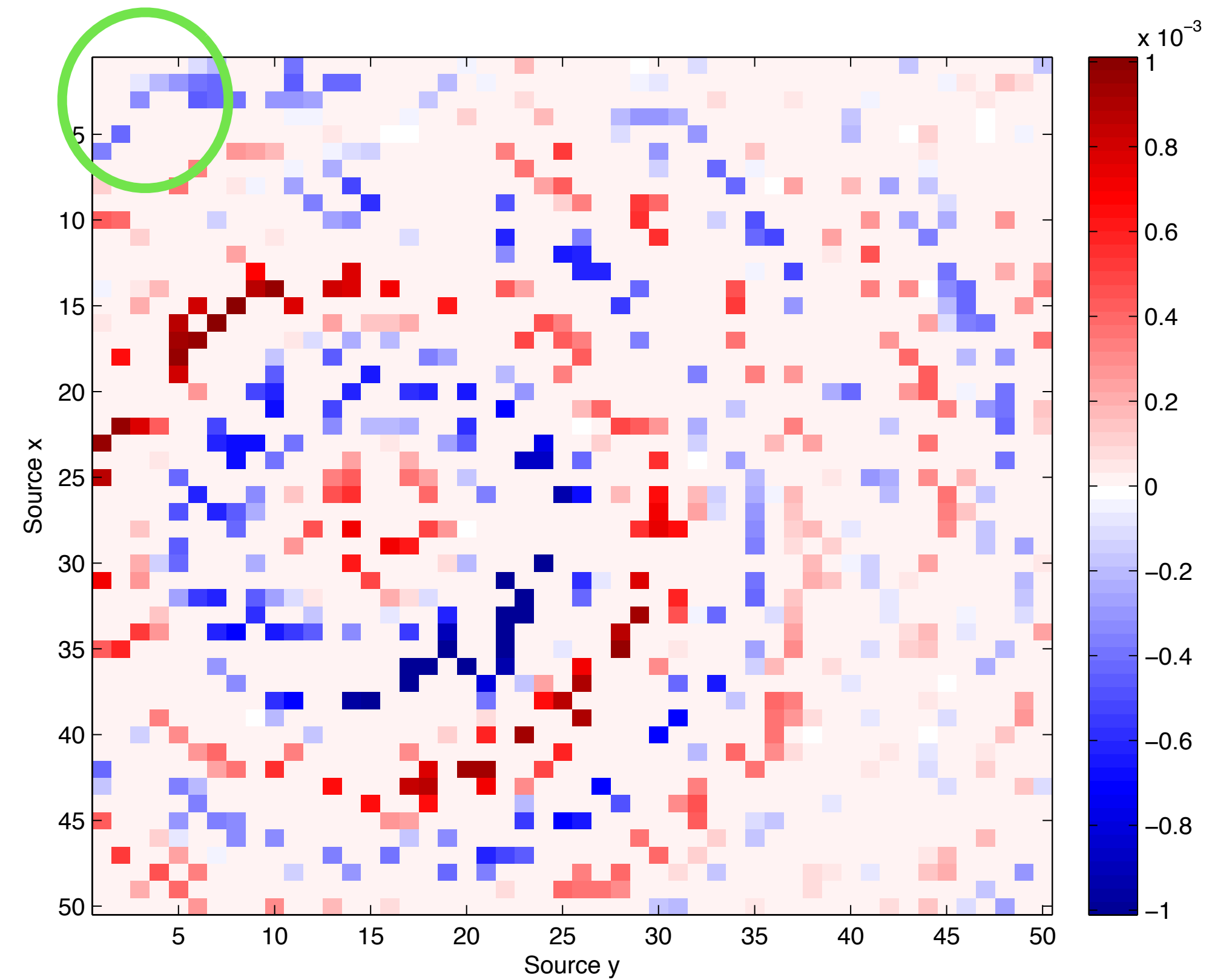
Idealized recovery

75% random entries removed

Common receiver gather



True data

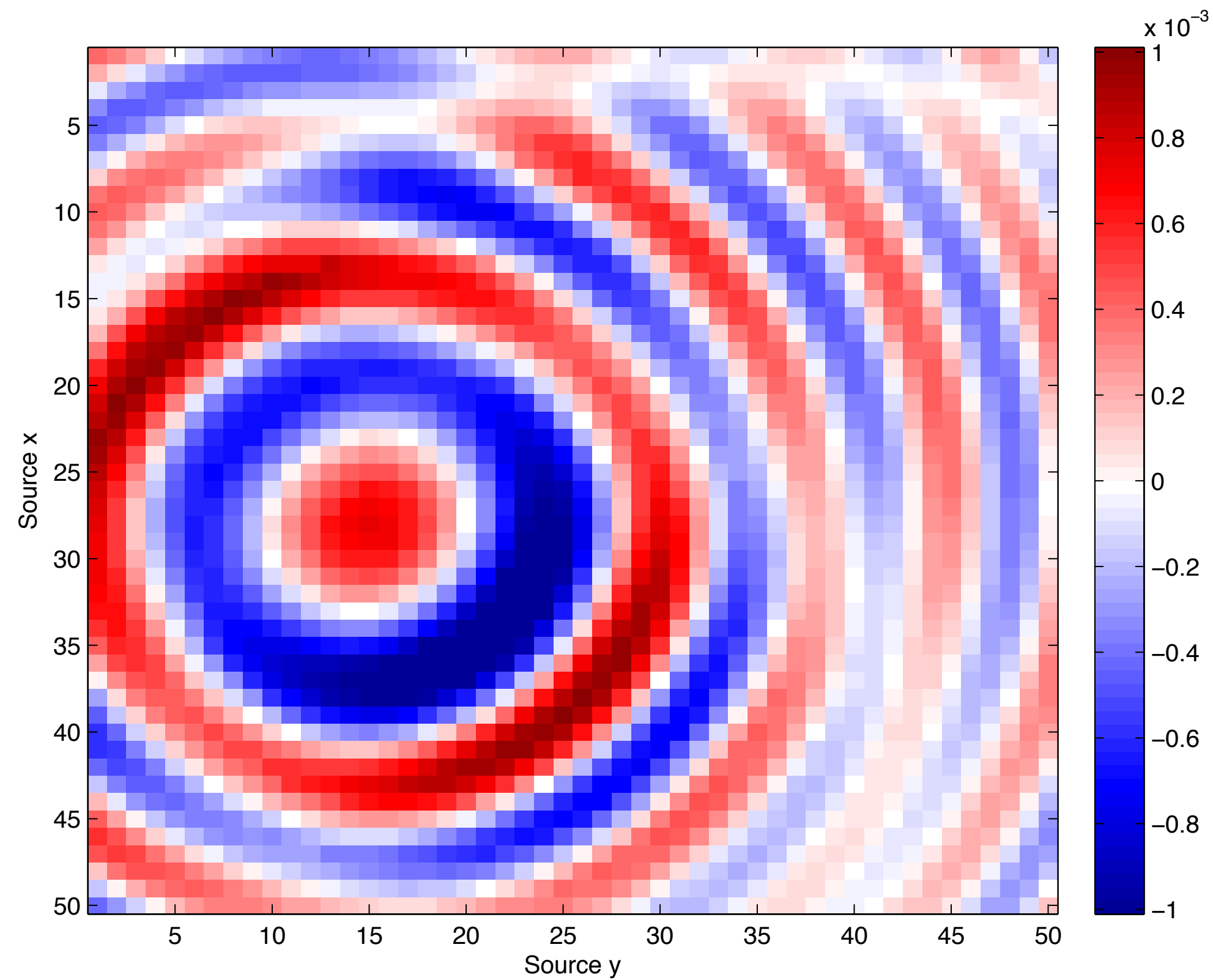


Subsampled data

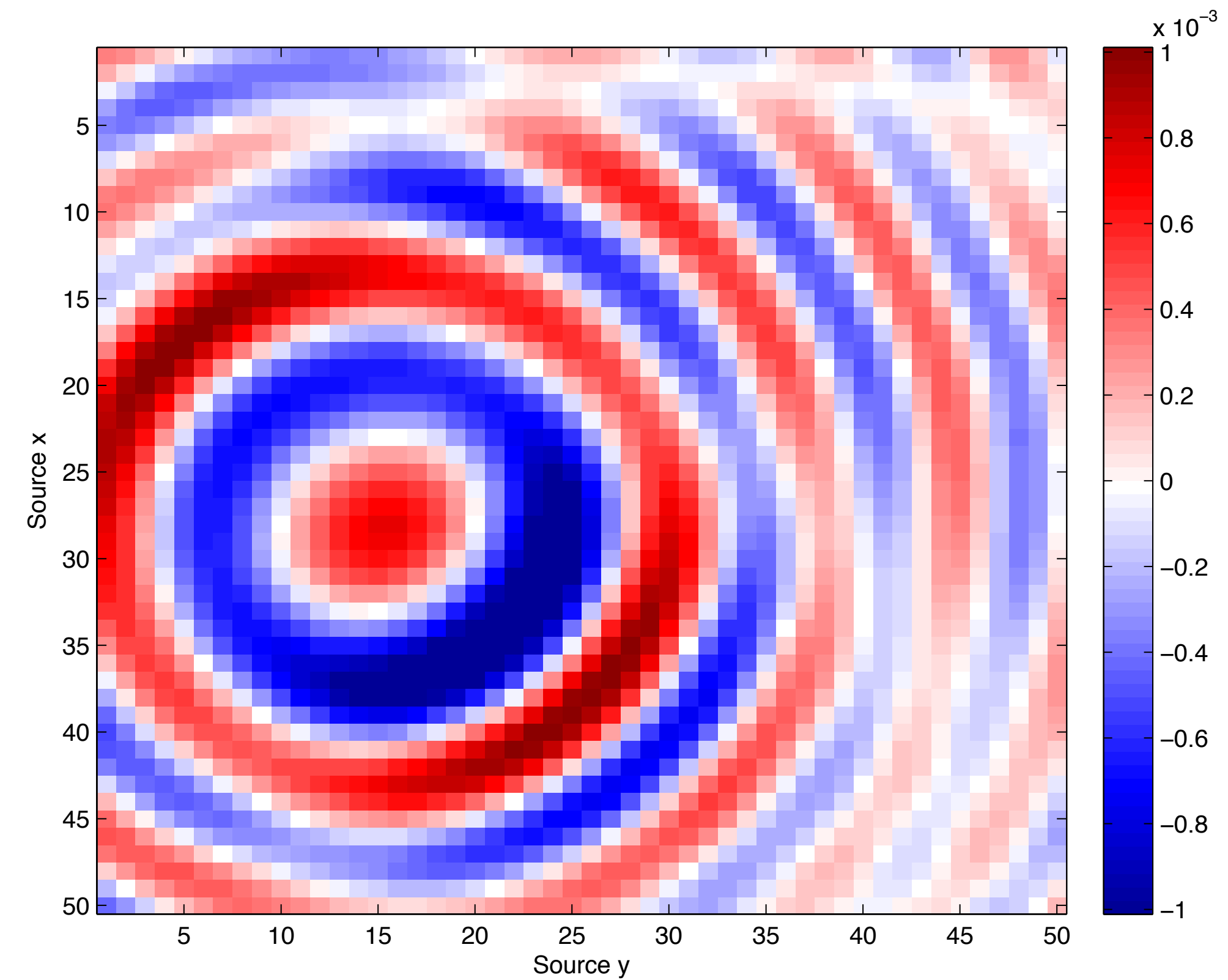
Idealized recovery

75% random entries removed

Common receiver gather



True data



Recovered data - SNR 19.3 dB

Sampling

Sampling $(x_{\text{src}}, y_{\text{src}}, x_{\text{rec}}, y_{\text{rec}})$ points from the data

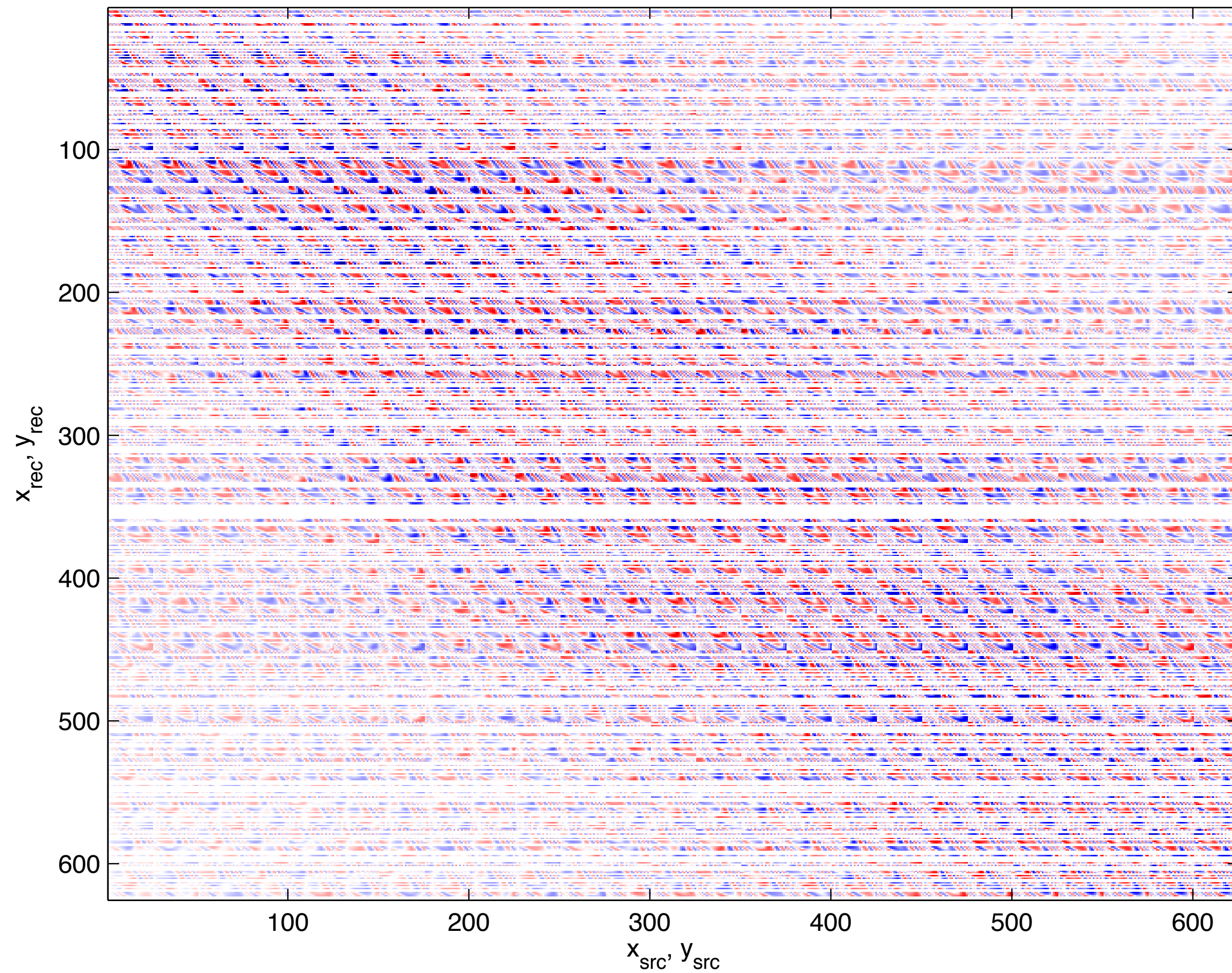
- idealized recovery
- impossible to physically implement

Sampling $(x_{\text{rec}}, y_{\text{rec}})$ points from the data

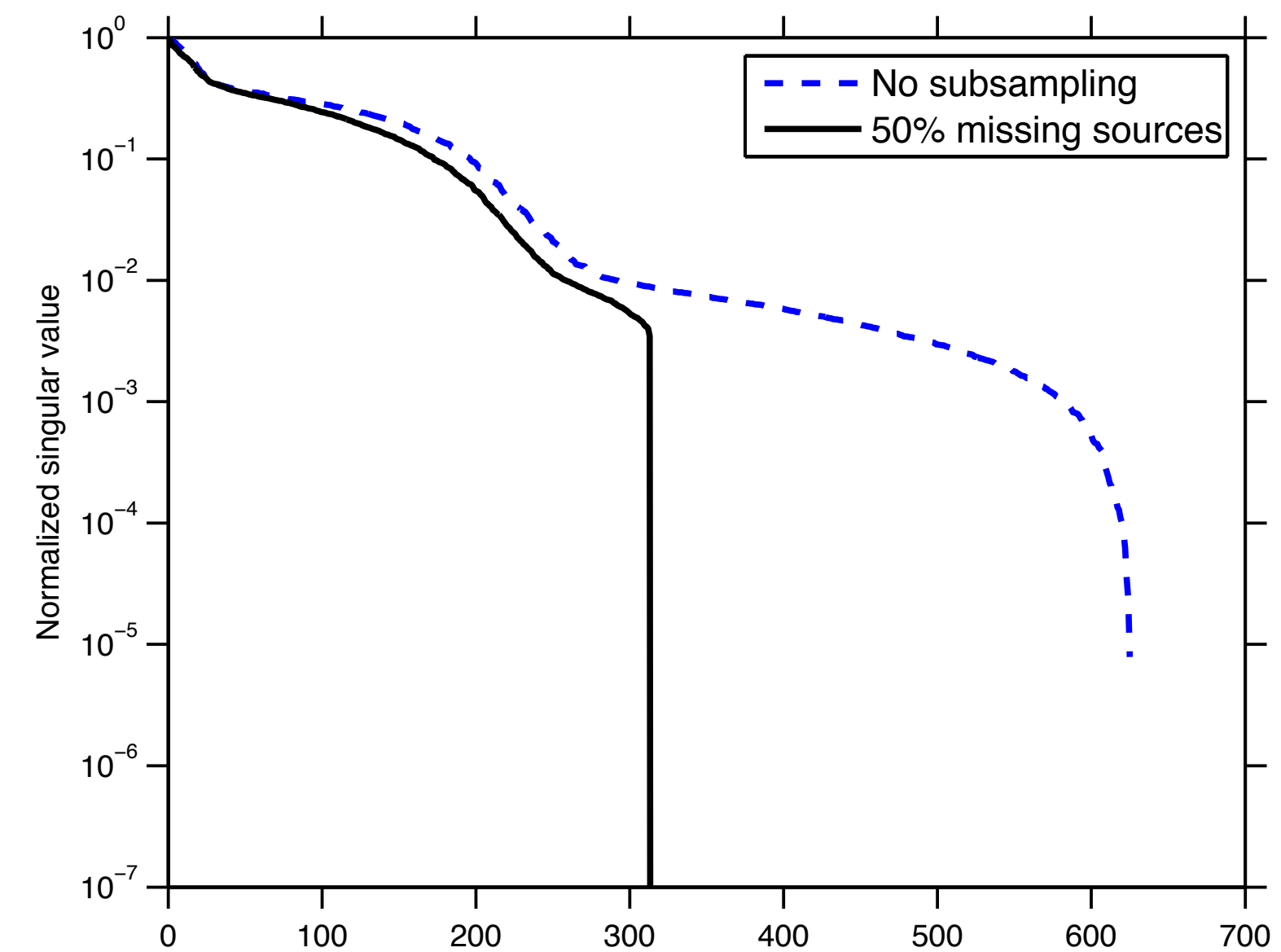
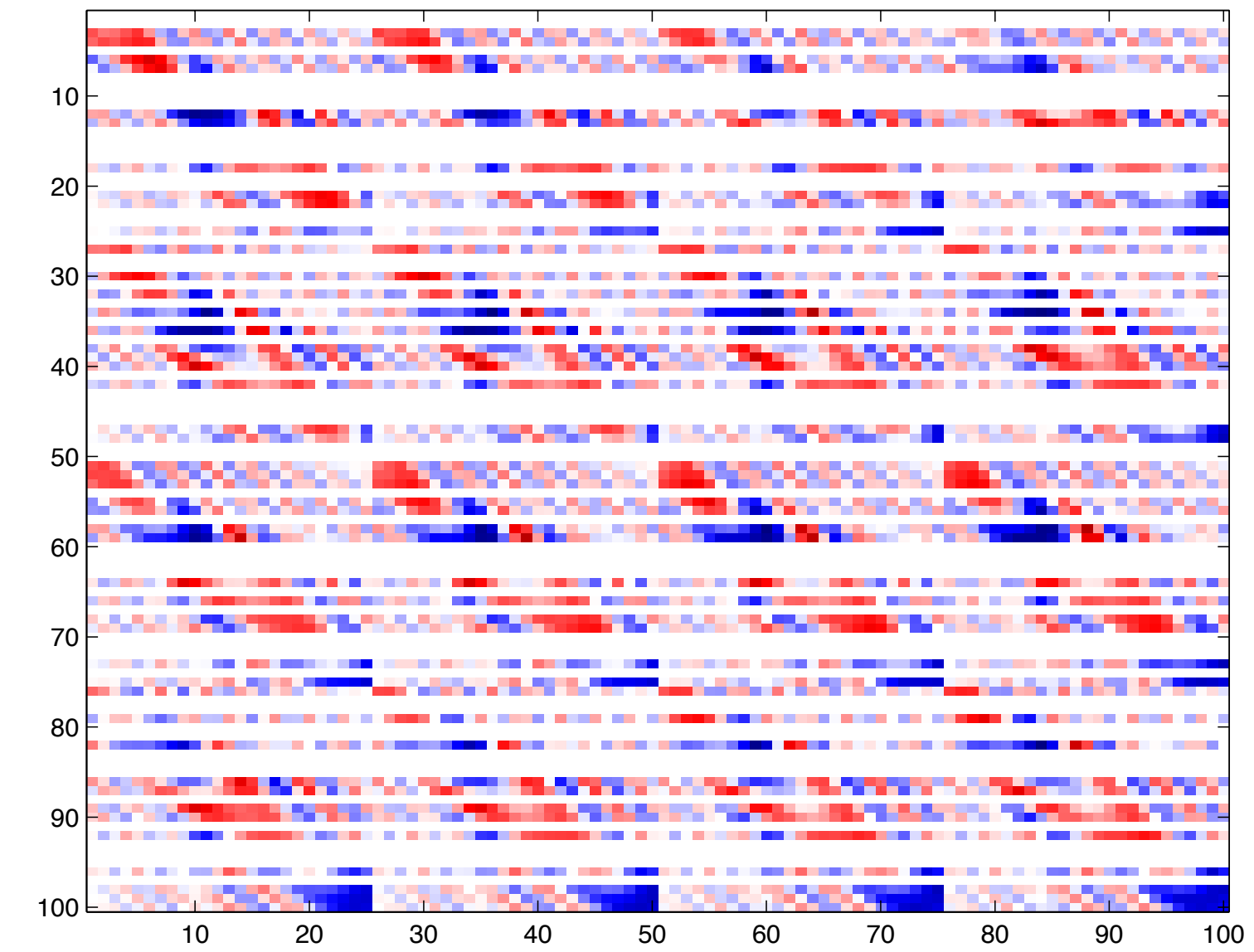
- less idealized
- possible to acquire data - e.g. ocean bottom nodes

Realistic recovery

50% random receivers removed

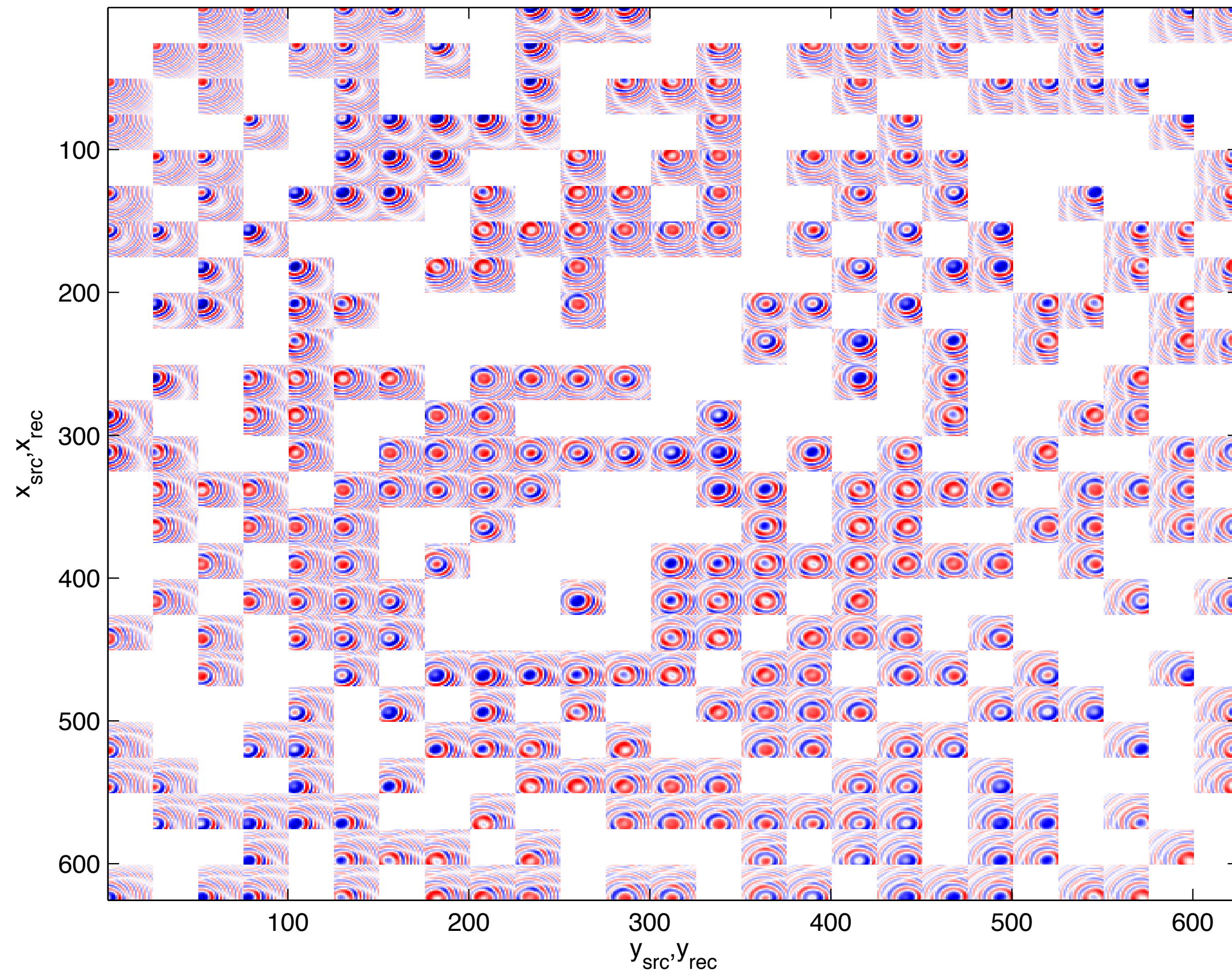


(Rec x, Rec y) matricization - Canonical ordering

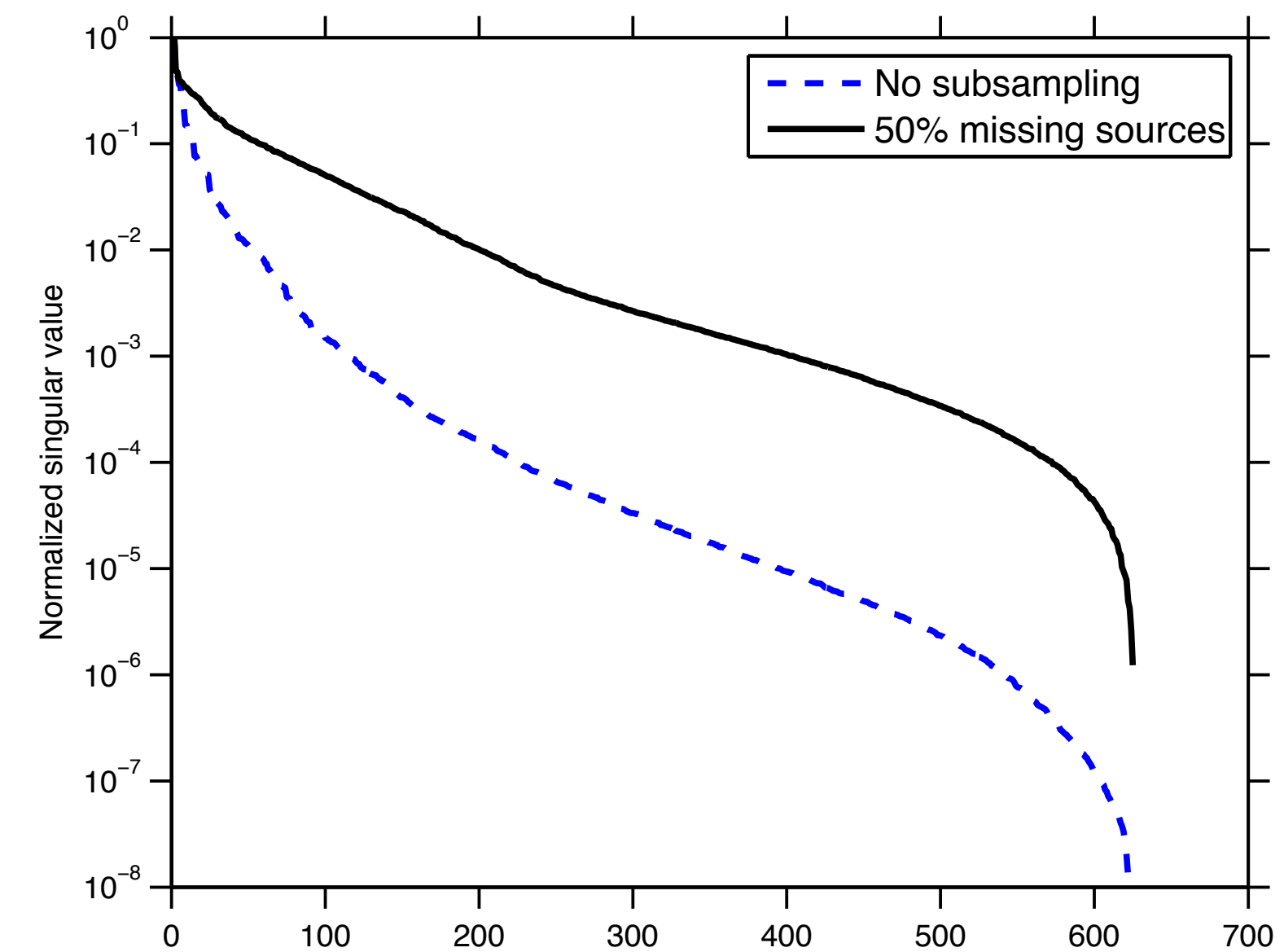
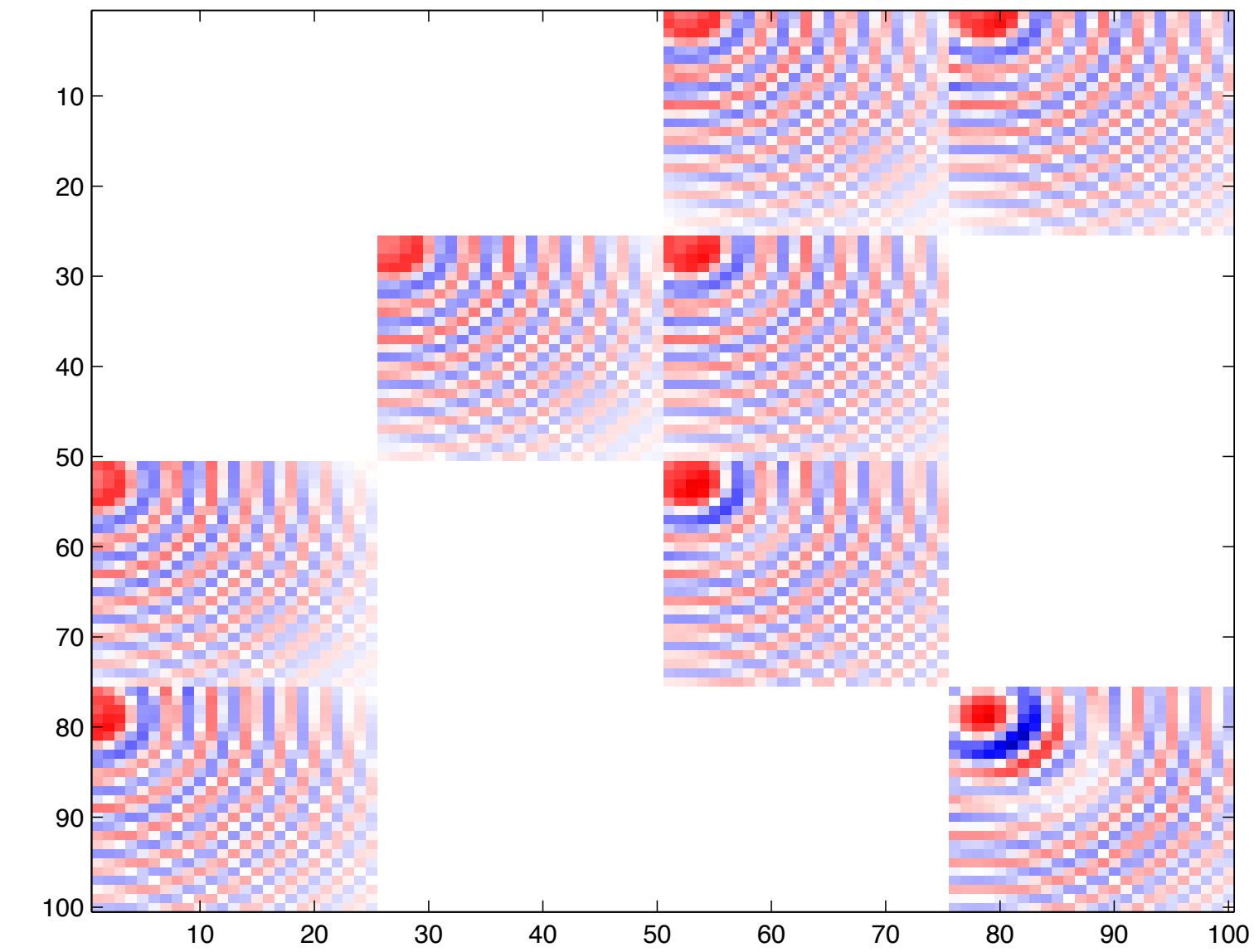


Realistic recovery

50% random receivers removed



(Src x, Rec x) matricization - Noncanonical ordering



Data organization

In summary:

(rec x, rec y) organization

- High rank
- Missing sources operator - removes columns
- Poor recovery scenario

(src x, rec x) organization

- Low rank
- Missing sources operator - removes blocks
- Closer to ideal recovery scenario

Multidimensional interpolation

with Hierarchical Tucker

Successful reconstruction scheme

Signal structure

- Hierarchical Tucker

Sampling

- subsampling increases hierarchical rank

Optimization

- ***fit data in the Hierarchical Tucker format***

Optimization

Given data b with missing sources and/or receivers, subsampling operator A , full tensor expansion operator

$$\phi : (U_t, B_t) \rightarrow \mathbb{C}^{n_1 \times \dots \times n_d}$$

solve

$$\min_{x=(U_t, B_t)} \frac{1}{2} \|A\phi(x) - b\|_2^2$$

A. Uschmajew, B. Vandereycken. *The geometry of algorithms using hierarchical tensors*. Linear algebra and its applications, 2013

C. Da Silva and F. J. Herrmann, *Optimization on the Hierarchical Tucker manifold - applications to tensor completion*, 2013

Differential geometry

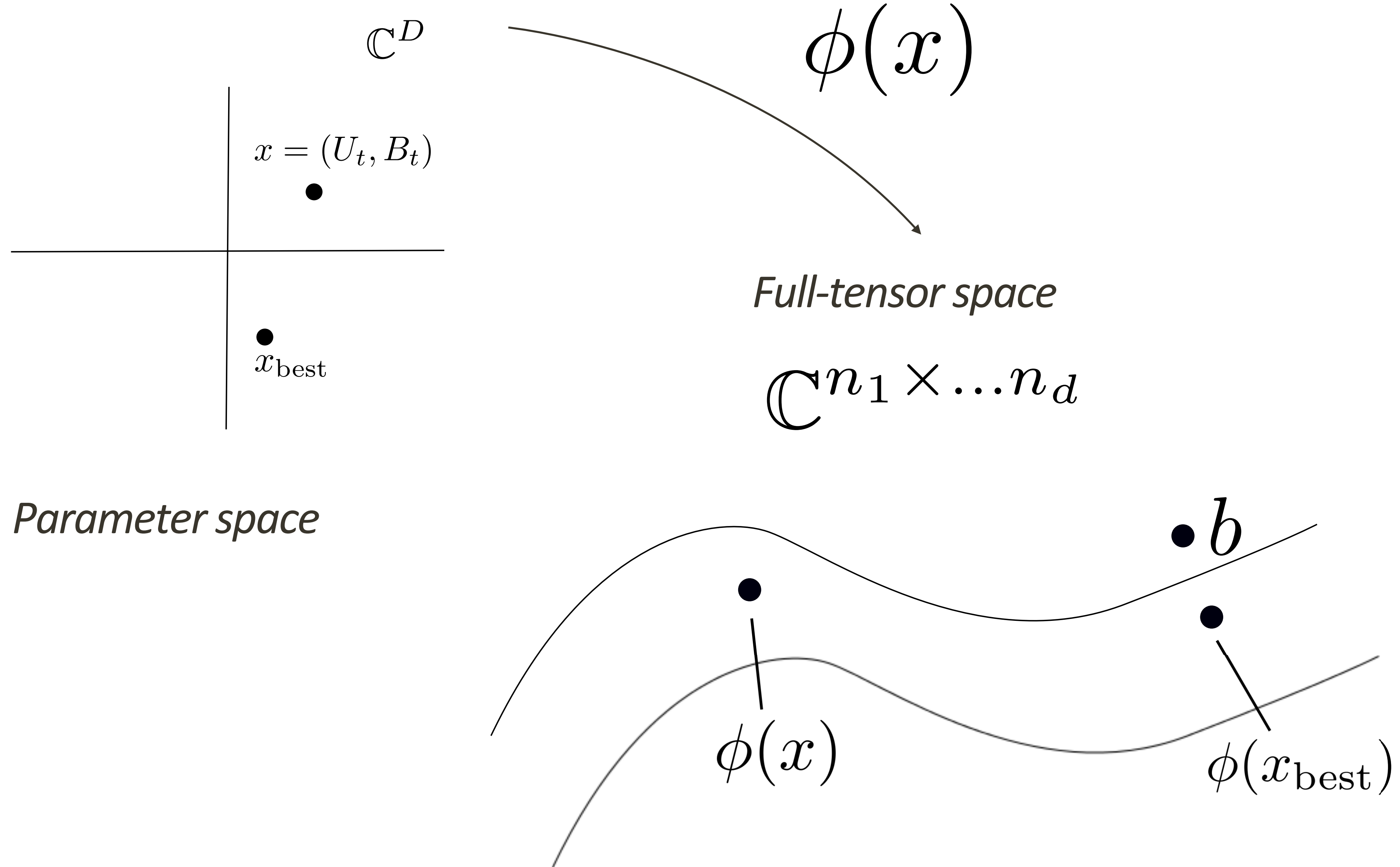
HT tensors parametrize a submanifold of full tensor space $\mathbb{C}^{n_1 \times \dots \times n_d}$

- Nonlinear, nonconvex space
- Generalization of curved surfaces

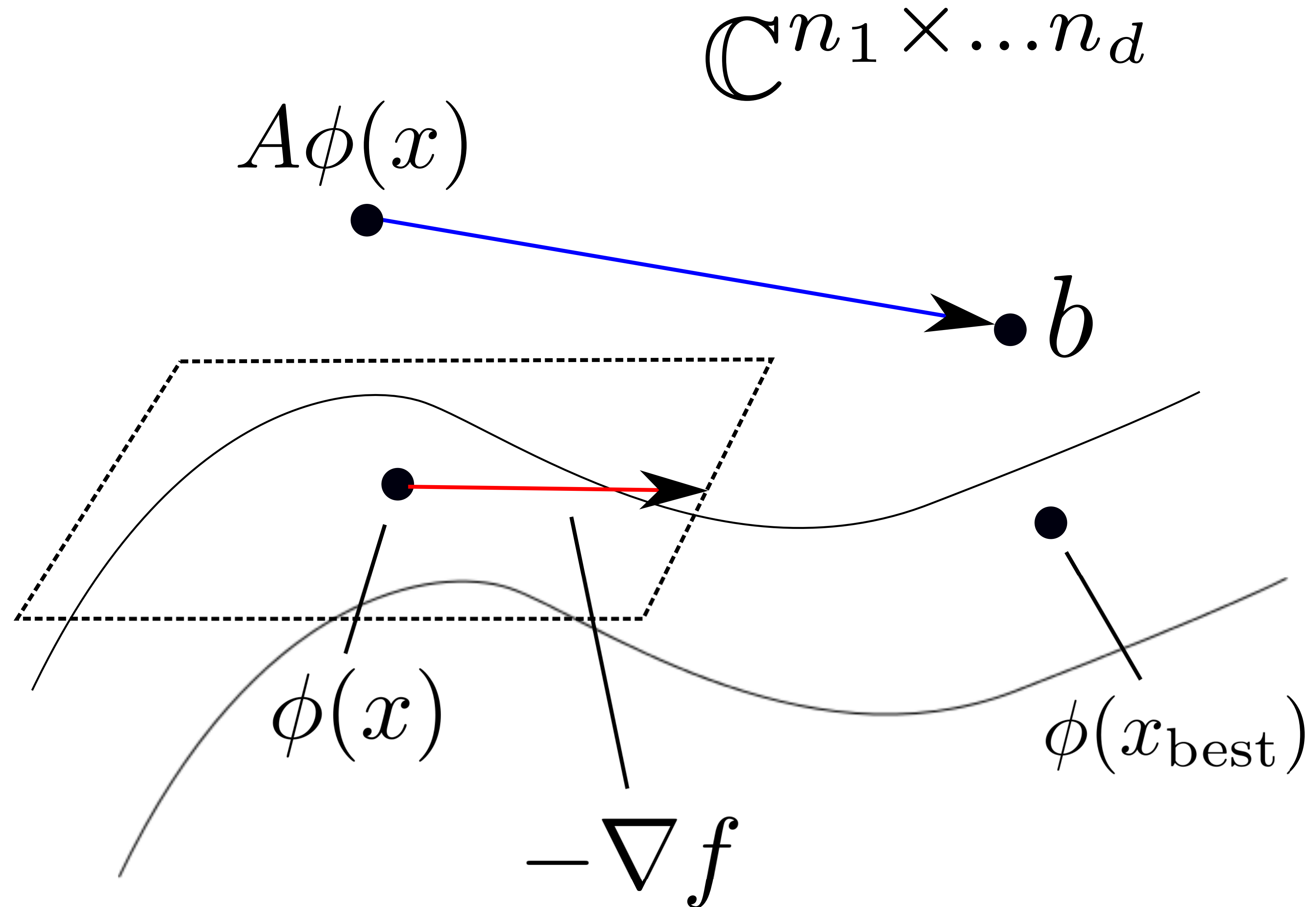
Steepest Descent, Conjugate gradient, Gauss-Newton

- **without** SVDs in the full tensor space

Optimization program



Optimization program



Derivatives

Derivatives of a particular node with respect to its children can be computed efficiently, i.e. via

$$(I - U_{t_l} U_{t_l}^H) \langle U_{t_r}^T \circ_2 Z, B_t \rangle_{(2,3),(2,3)}$$

$$(I - U_{t_r} U_{t_r}^H) \langle U_{t_l}^T \circ_1 Z, B_t \rangle_{(1,3),(1,3)}$$

$$P \circ_i Q \text{ multiplies } Q \text{ by } P \text{ in dimension } i, \langle X, Y \rangle_{(1,3),(1,3)} = \sum_{i_1, i_3} \bar{X}_{i_1, :, i_3} Y_{i_1, :, i_3}$$

The chain rule gives the gradient of the function ϕ

Derivatives

Only involves matrix-matrix multiplications of small matrices compared to the full-tensor space

Parallelizable - multilinear product can be done in parallel

SVD-free - no large-scale SVDs, unlike nuclear norm-based methods

Results

Synthetic BG Group data

Unknown model

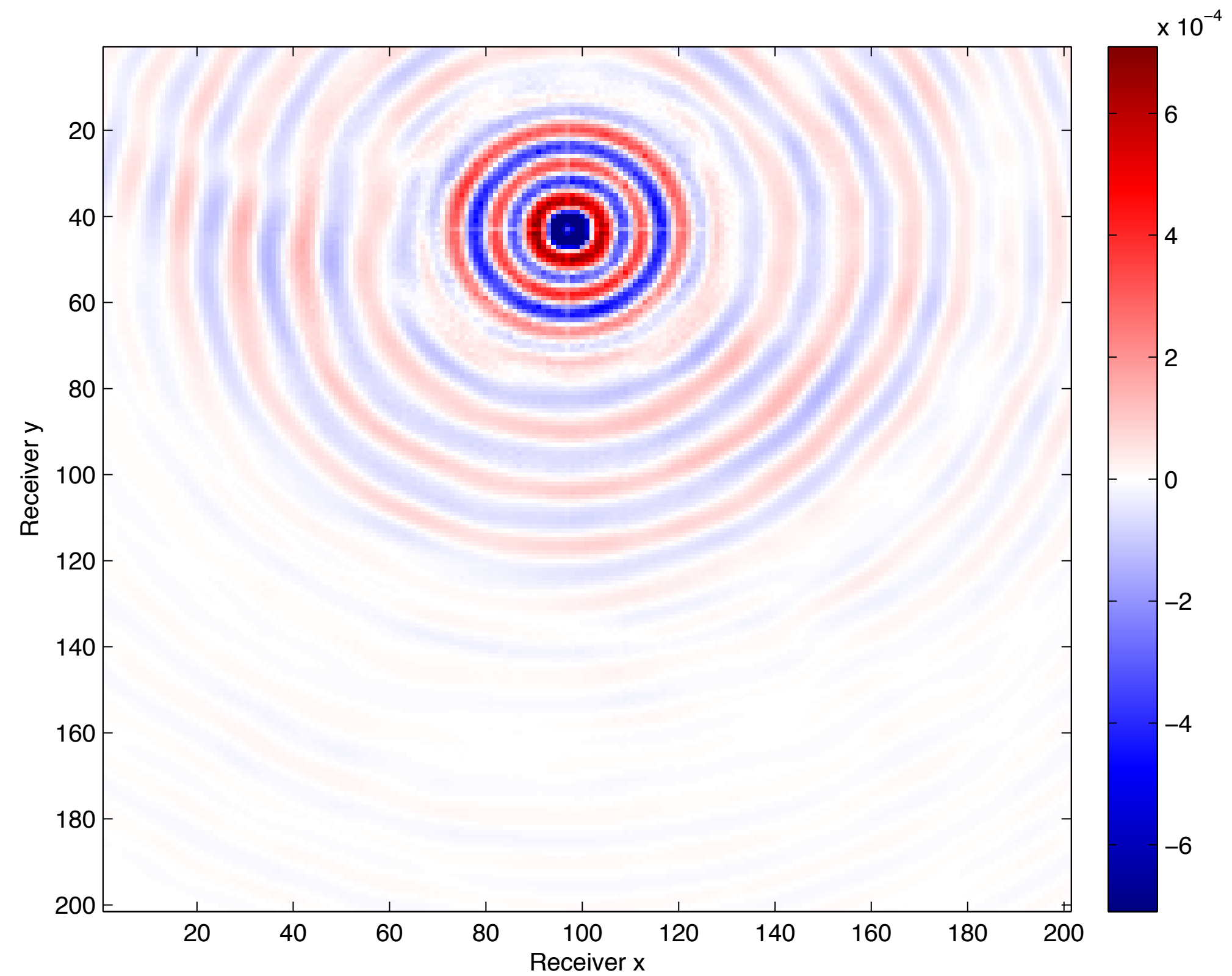
- 68 x 68 sources with 401 x 401 receivers, data at 4.68Hz, 7.34 Hz

Receivers subsampled to 201 x 201

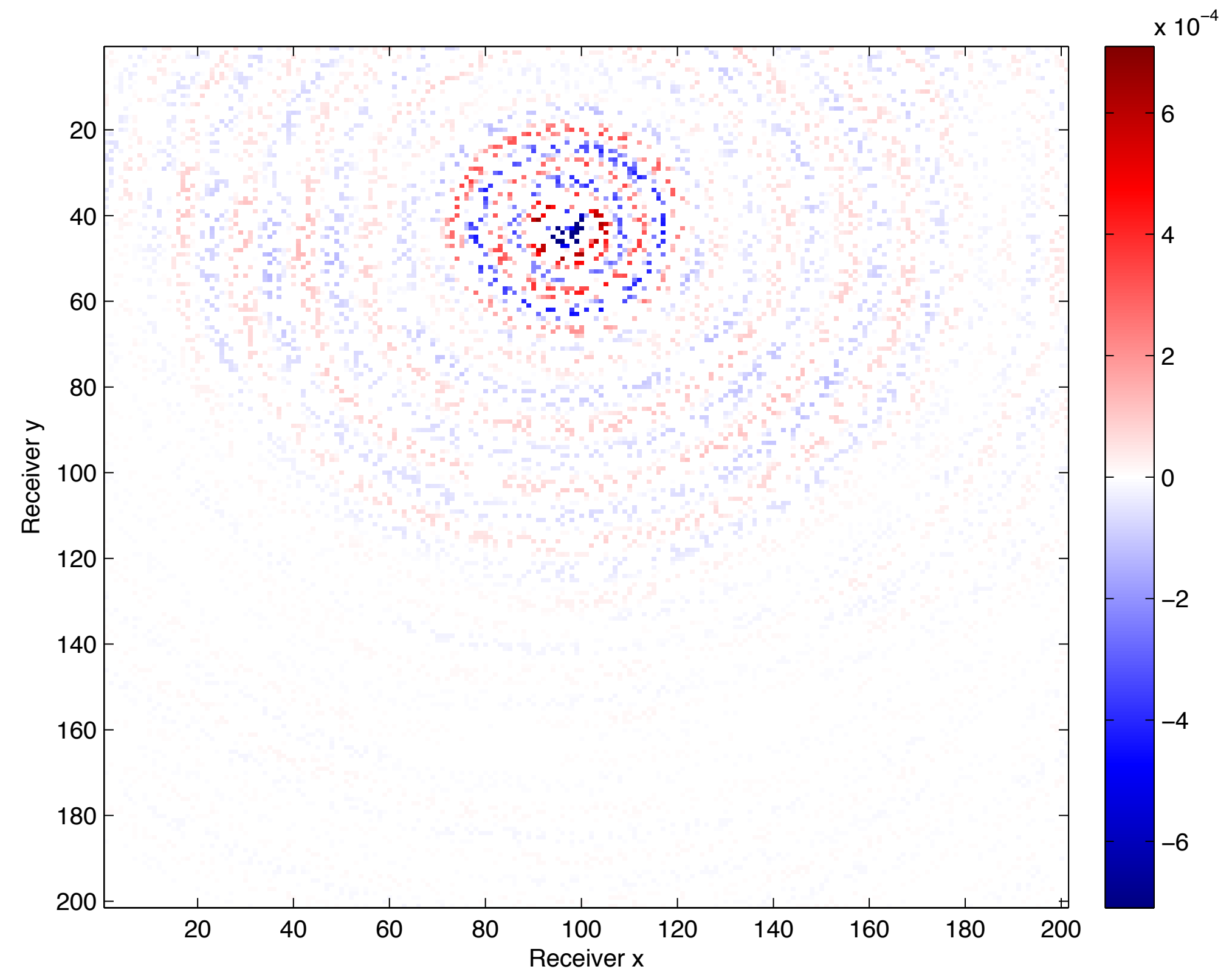
Recovered with Gauss-Newton

4.68 Hz - 75% missing receivers

Common source gather



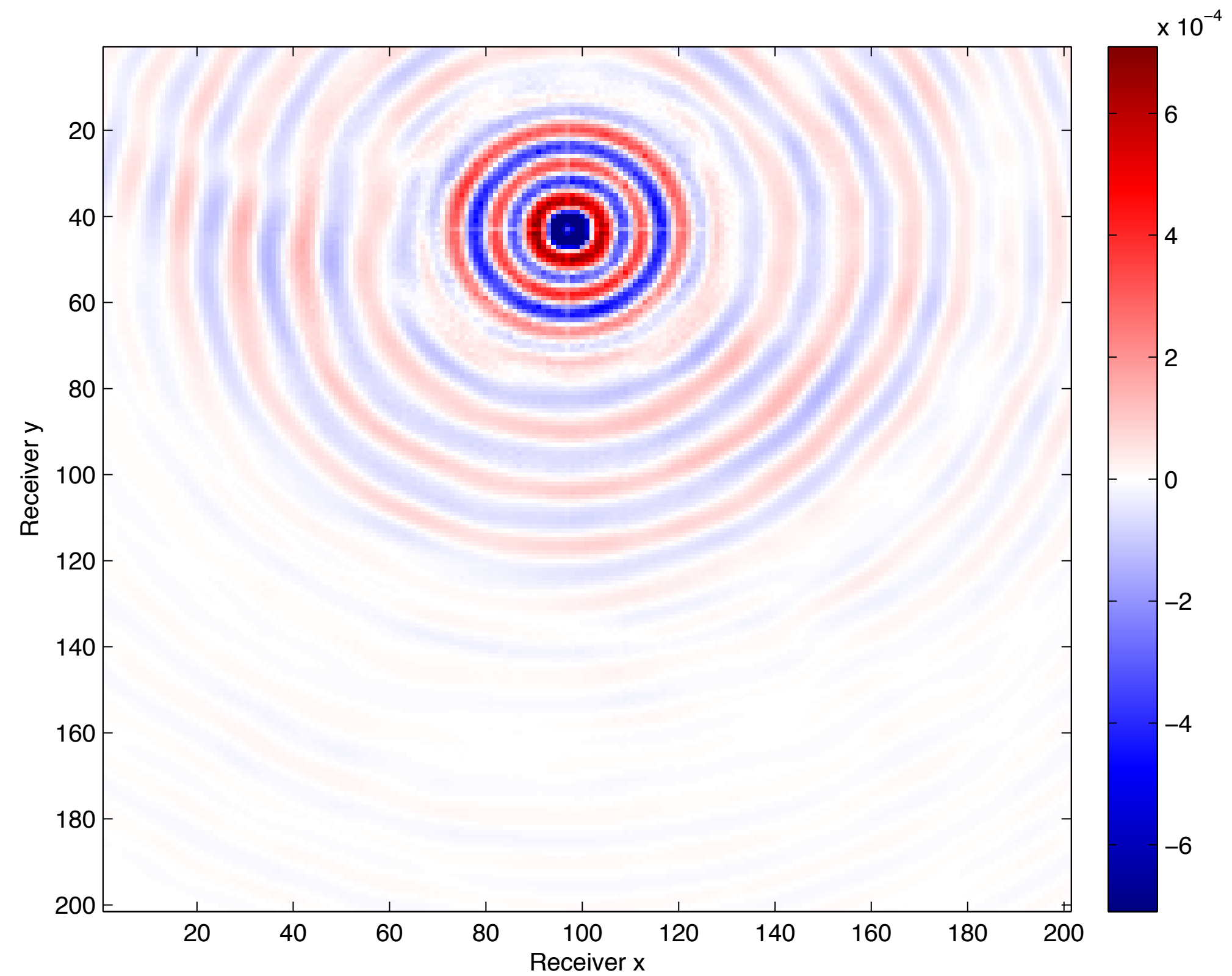
True data



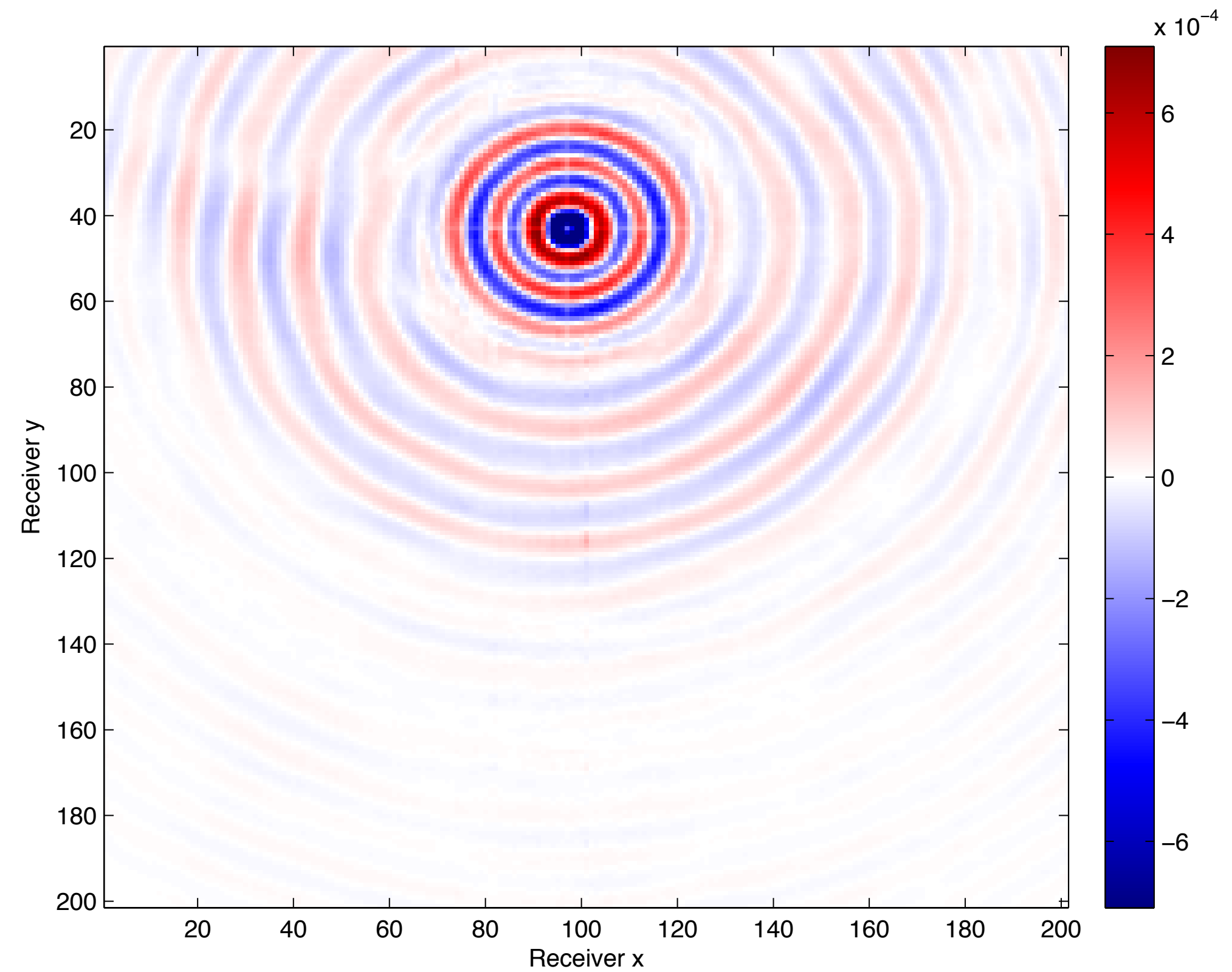
Subsampled data

4.68 Hz - 75% missing receivers

Common source gather



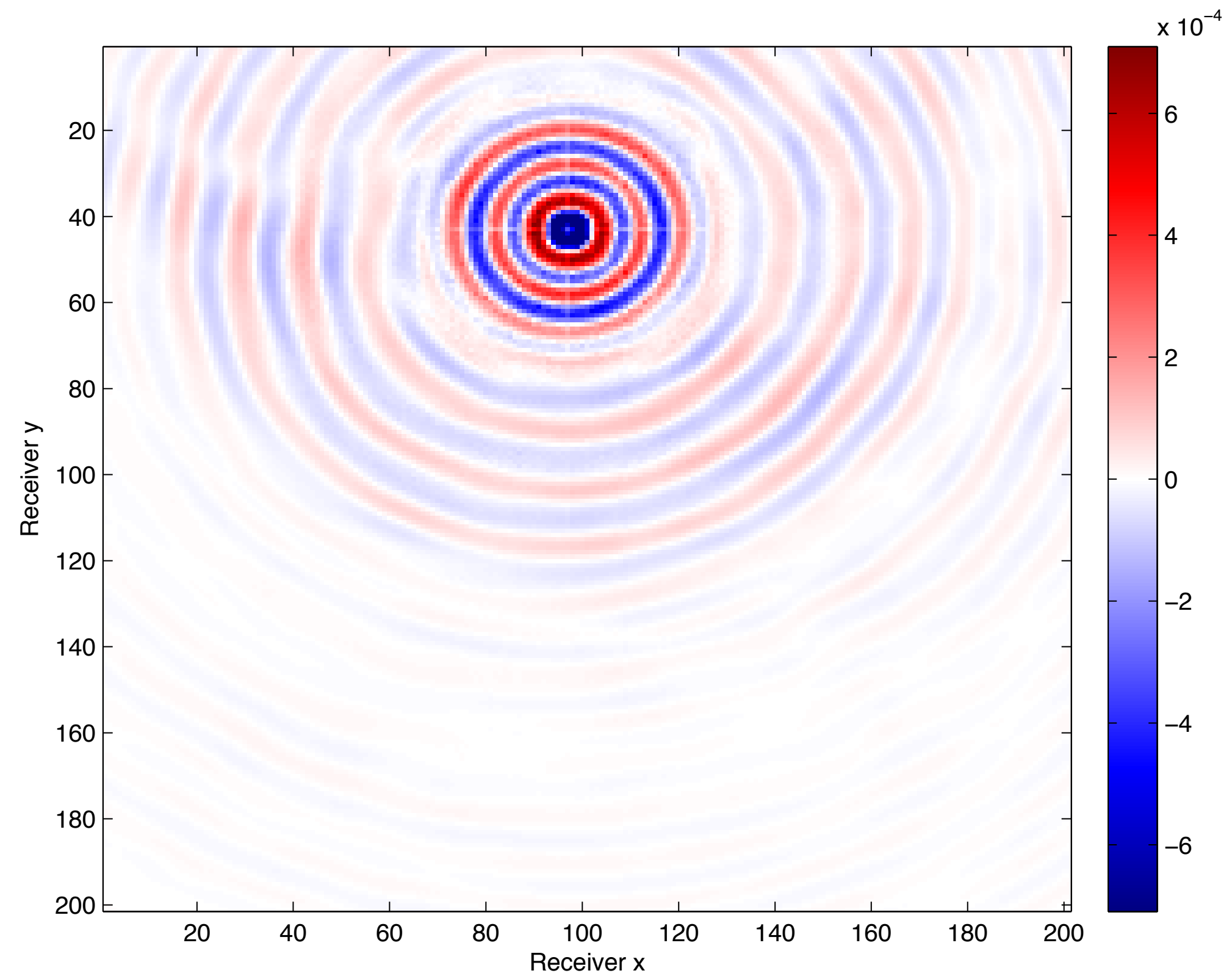
True data



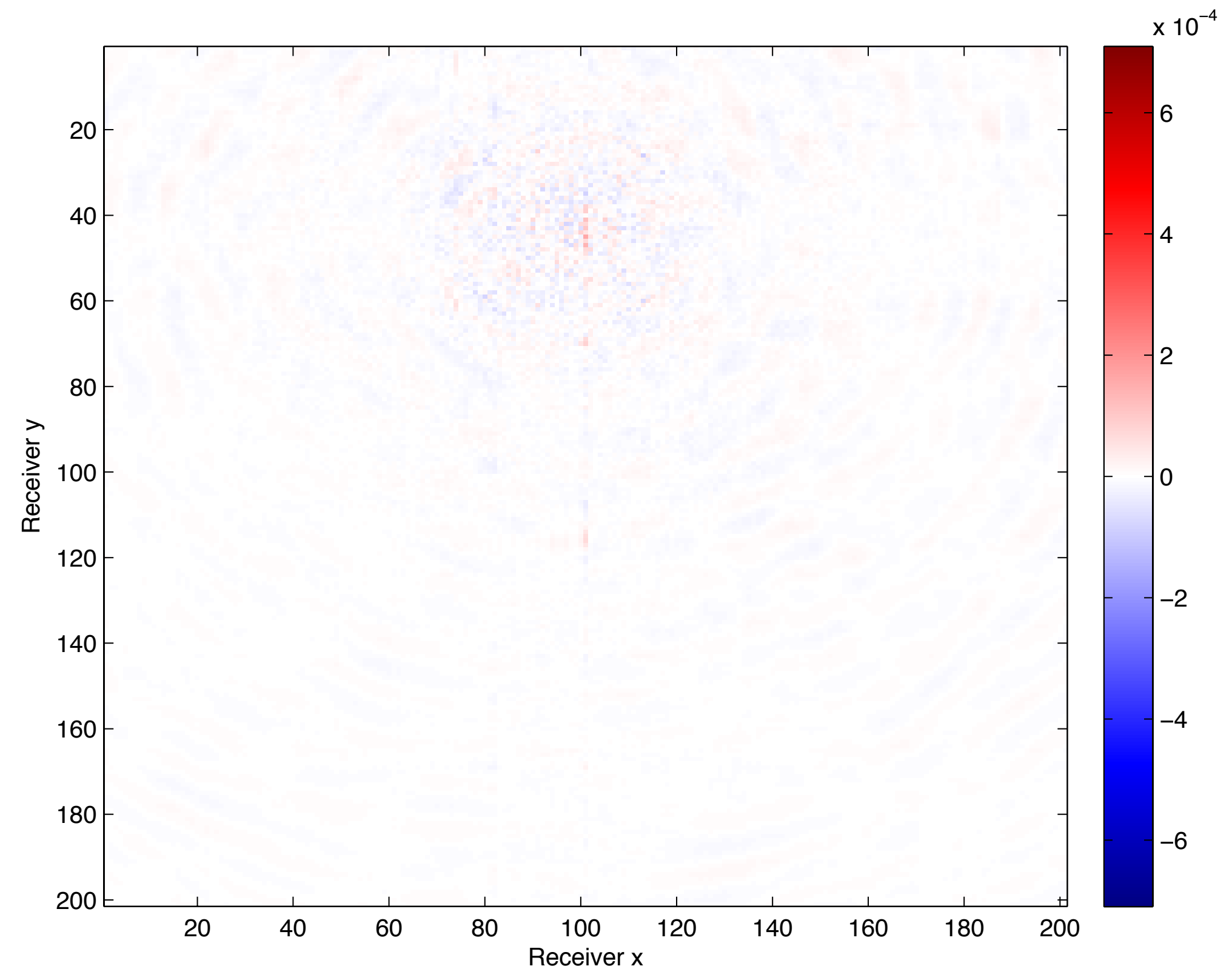
Recovered data - SNR 19.7 dB

4.68 Hz - 75% missing receivers

Common source gather



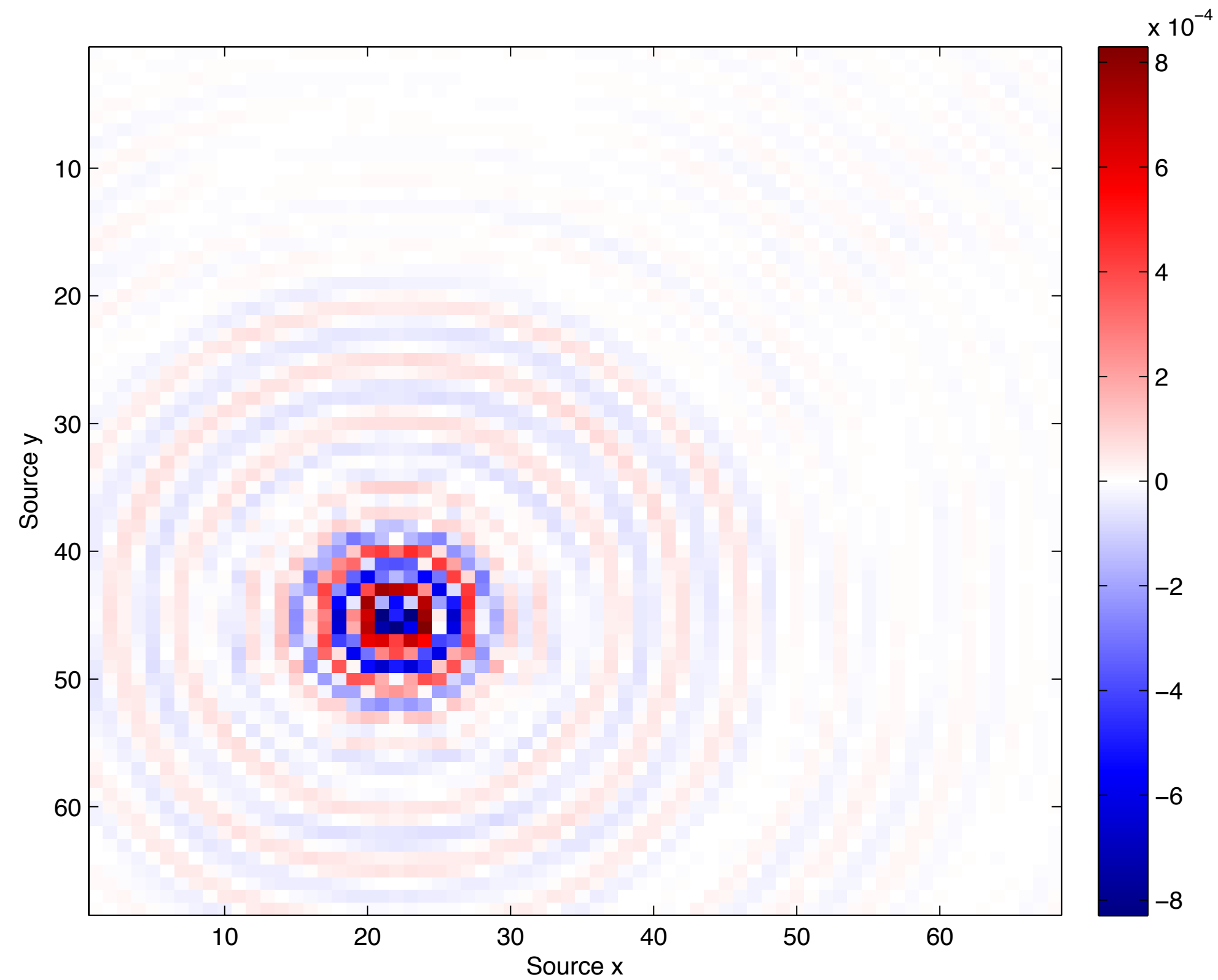
True data



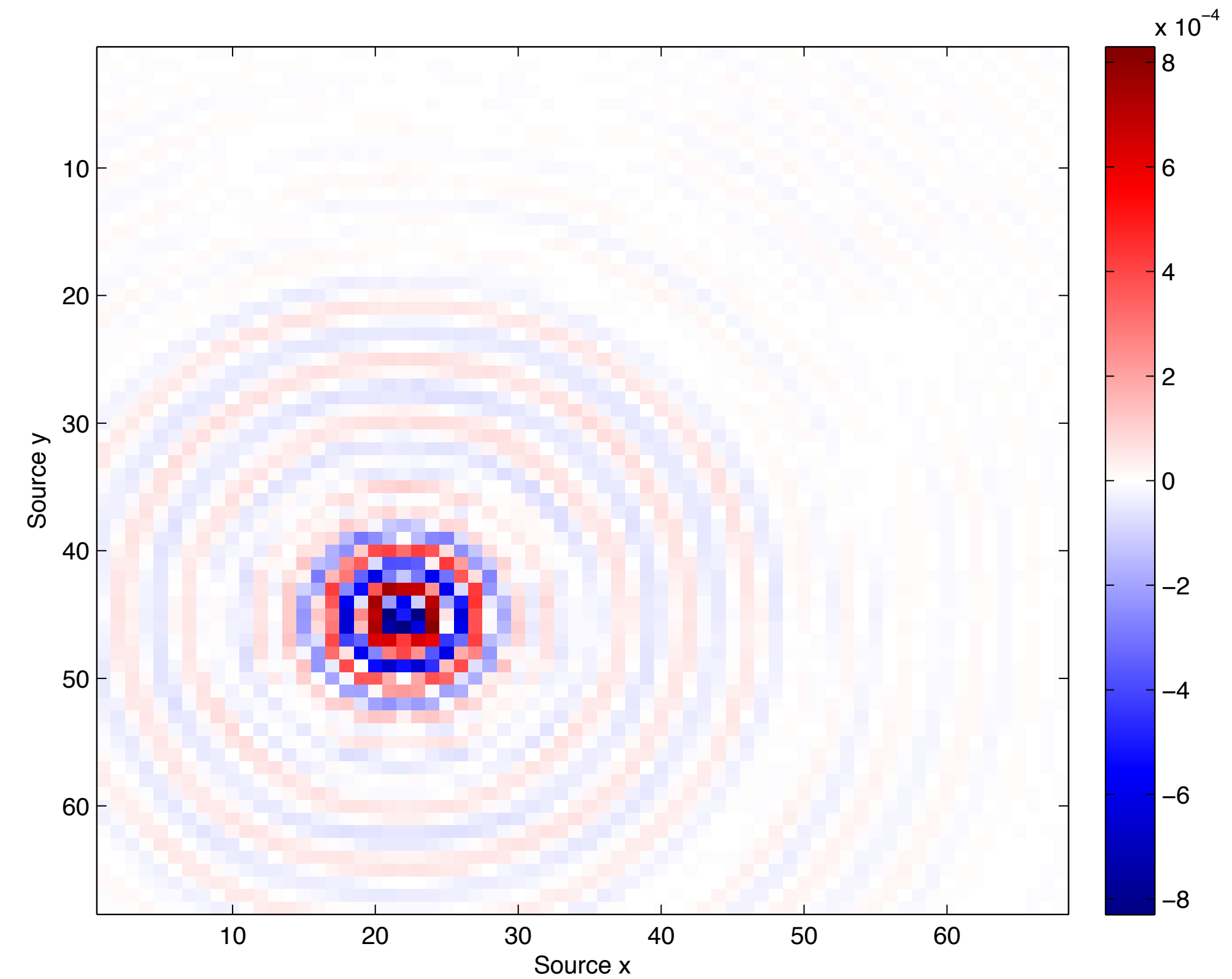
Difference

4.68 Hz - 75% missing receivers

Common receiver gather - no data initially



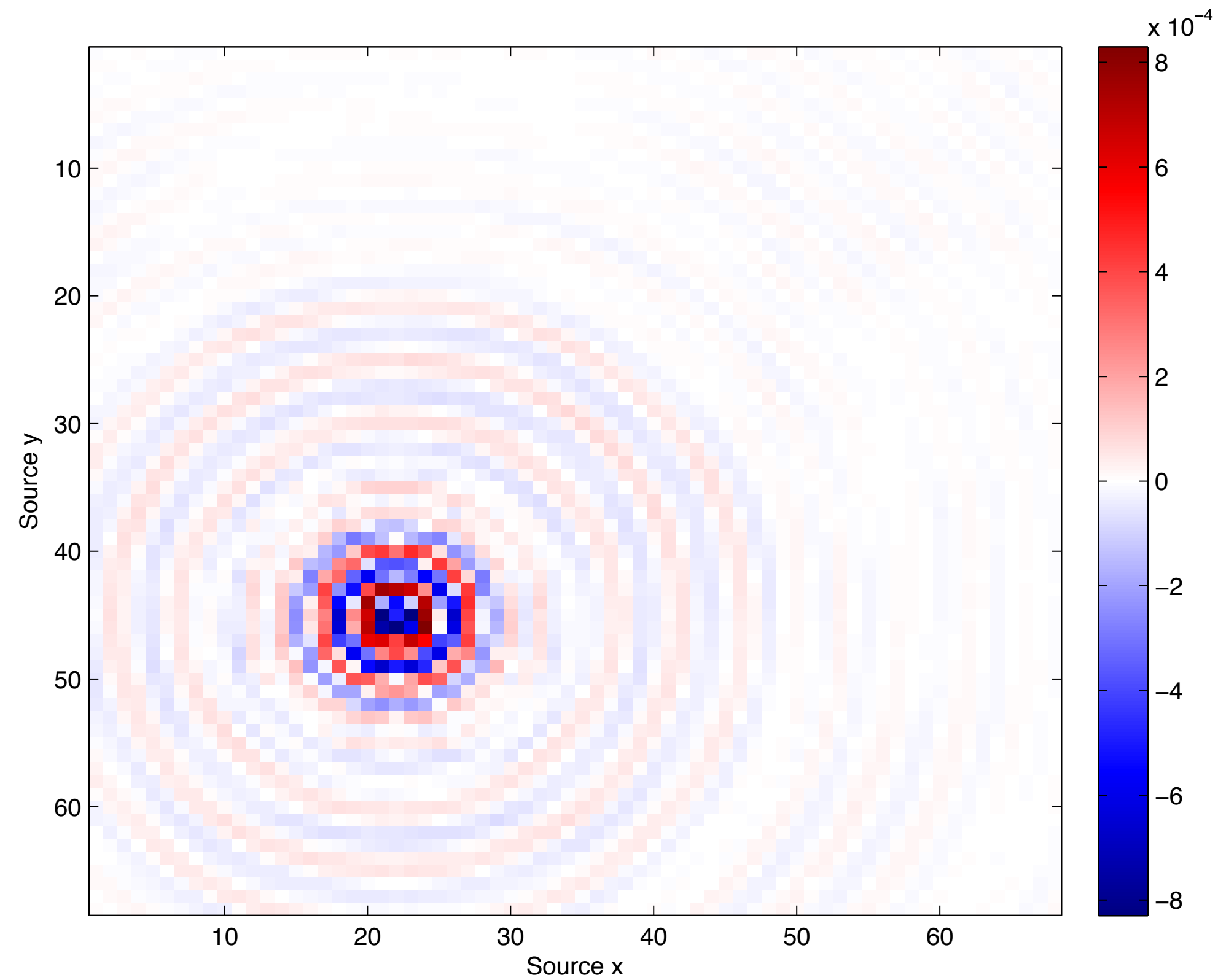
True data



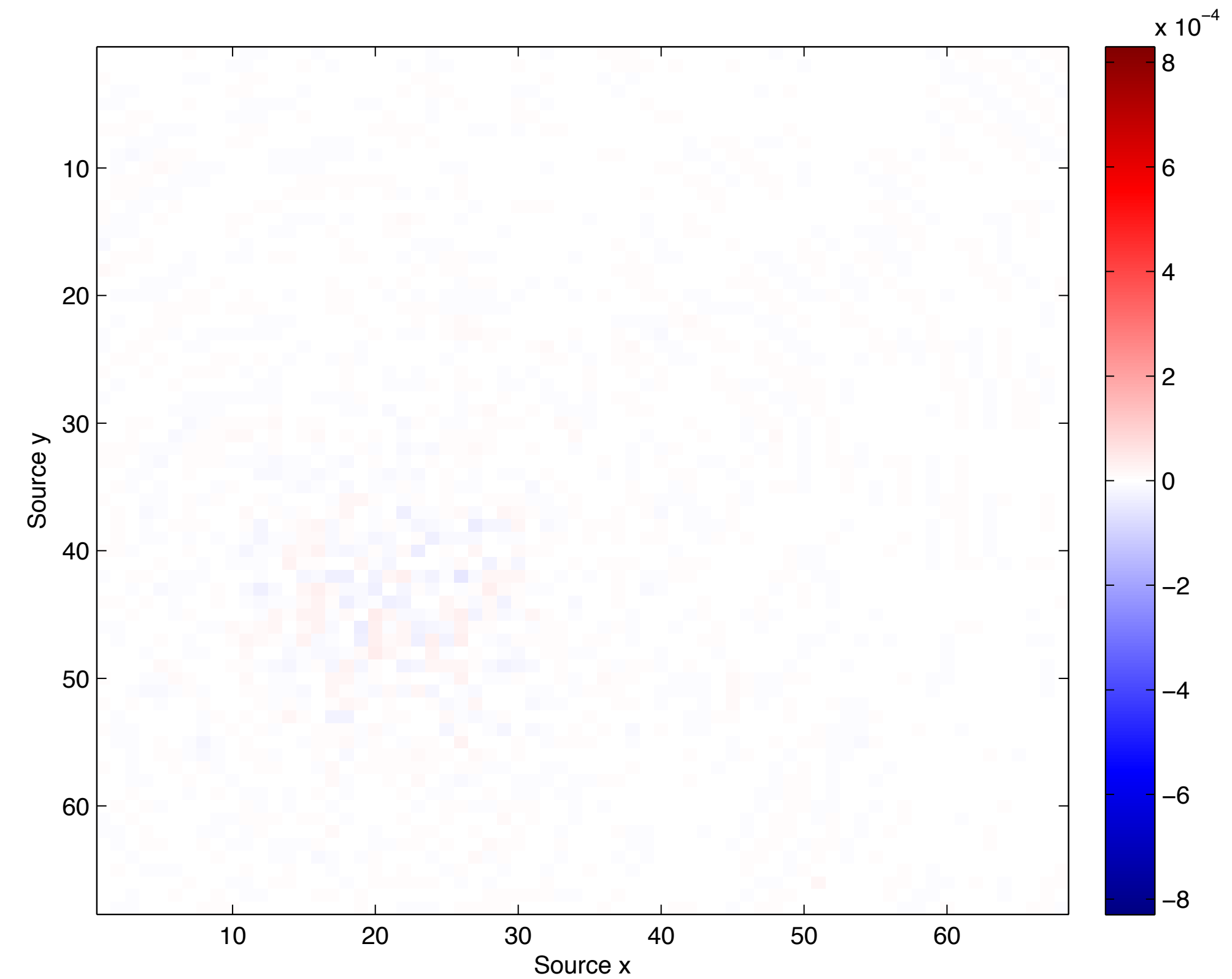
Recovered data - SNR 23 dB

4.68 Hz - 75% missing receivers

Common receiver gather - no data initially



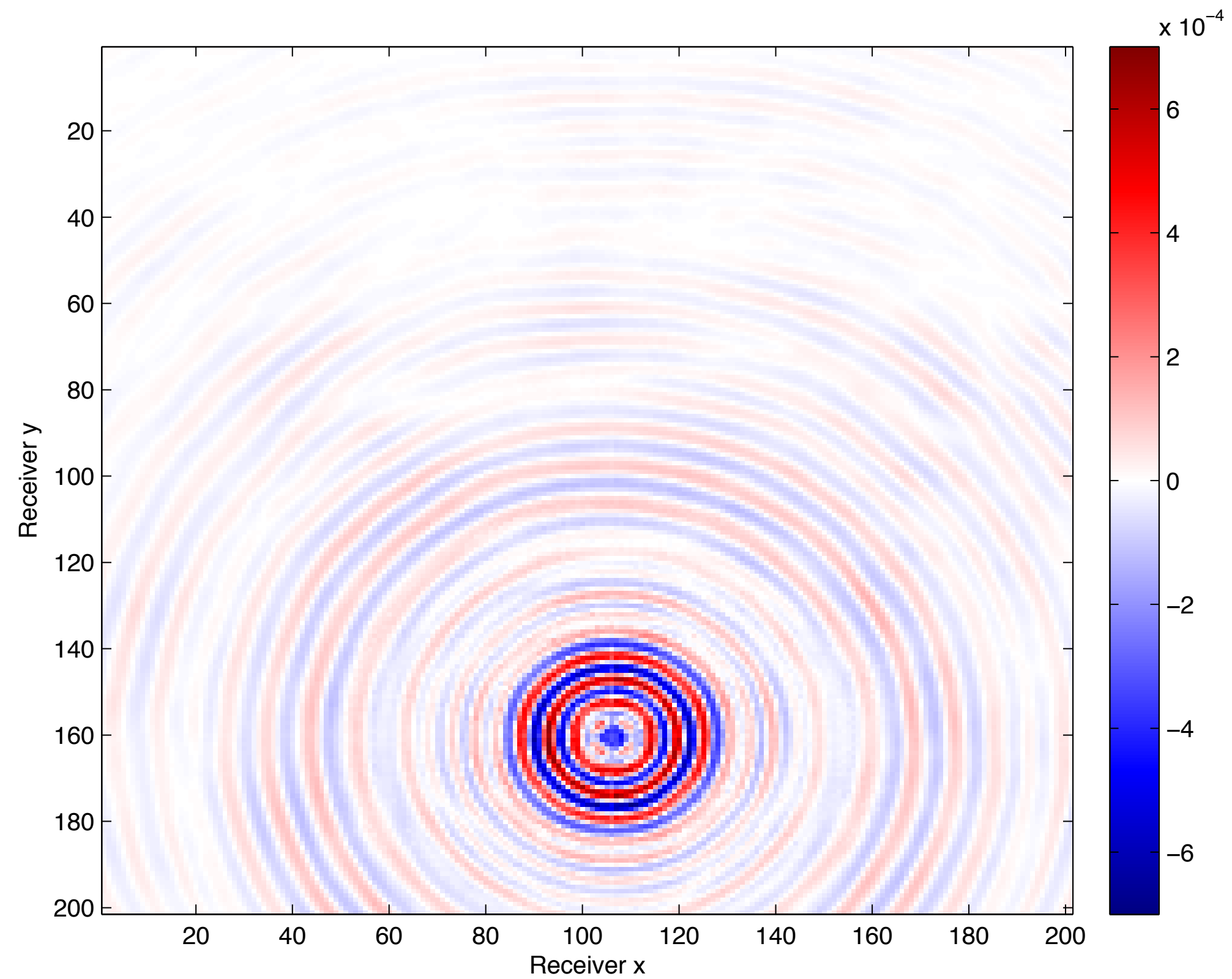
True data



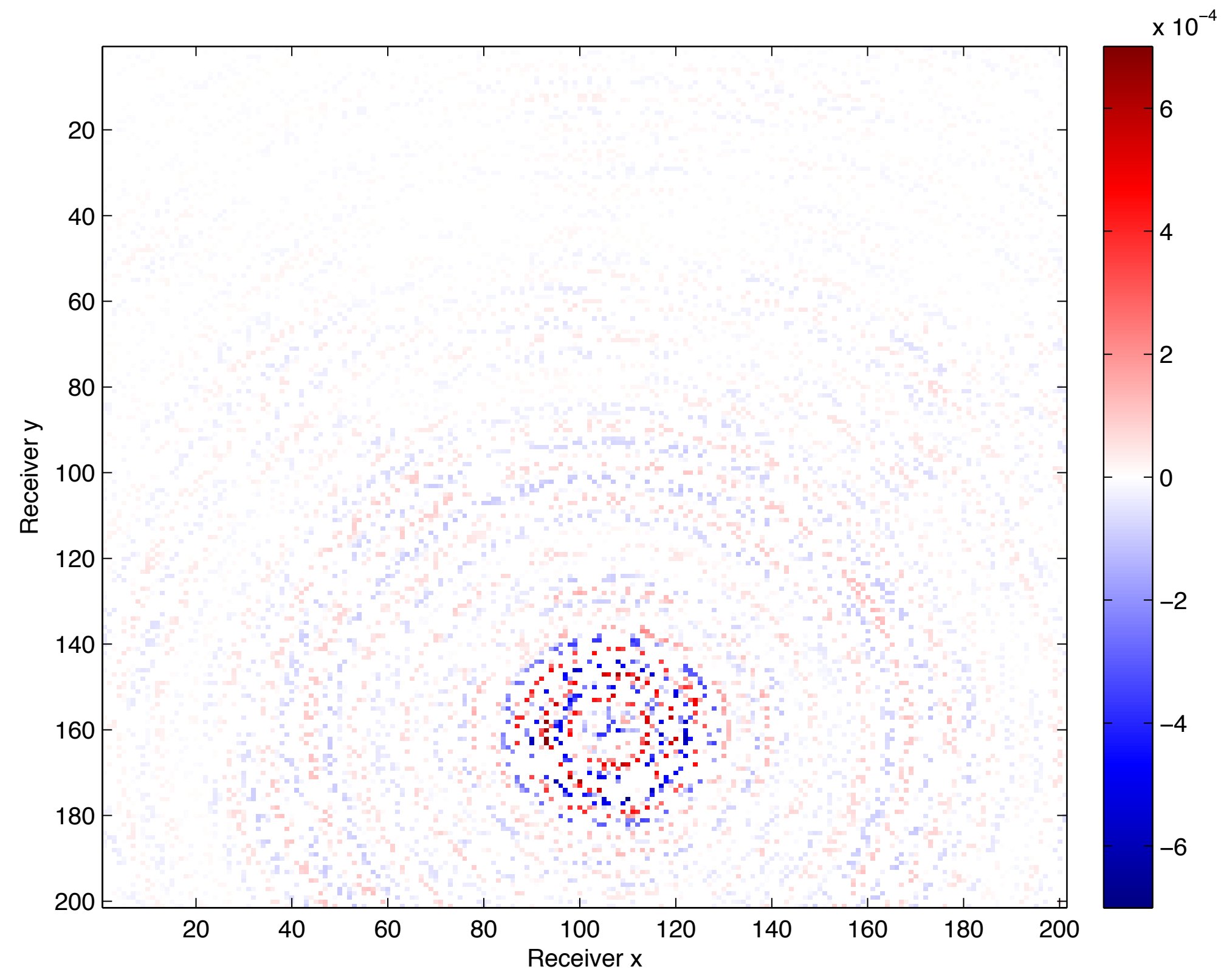
Difference

7.34 Hz - 75% missing receivers

Common source gather



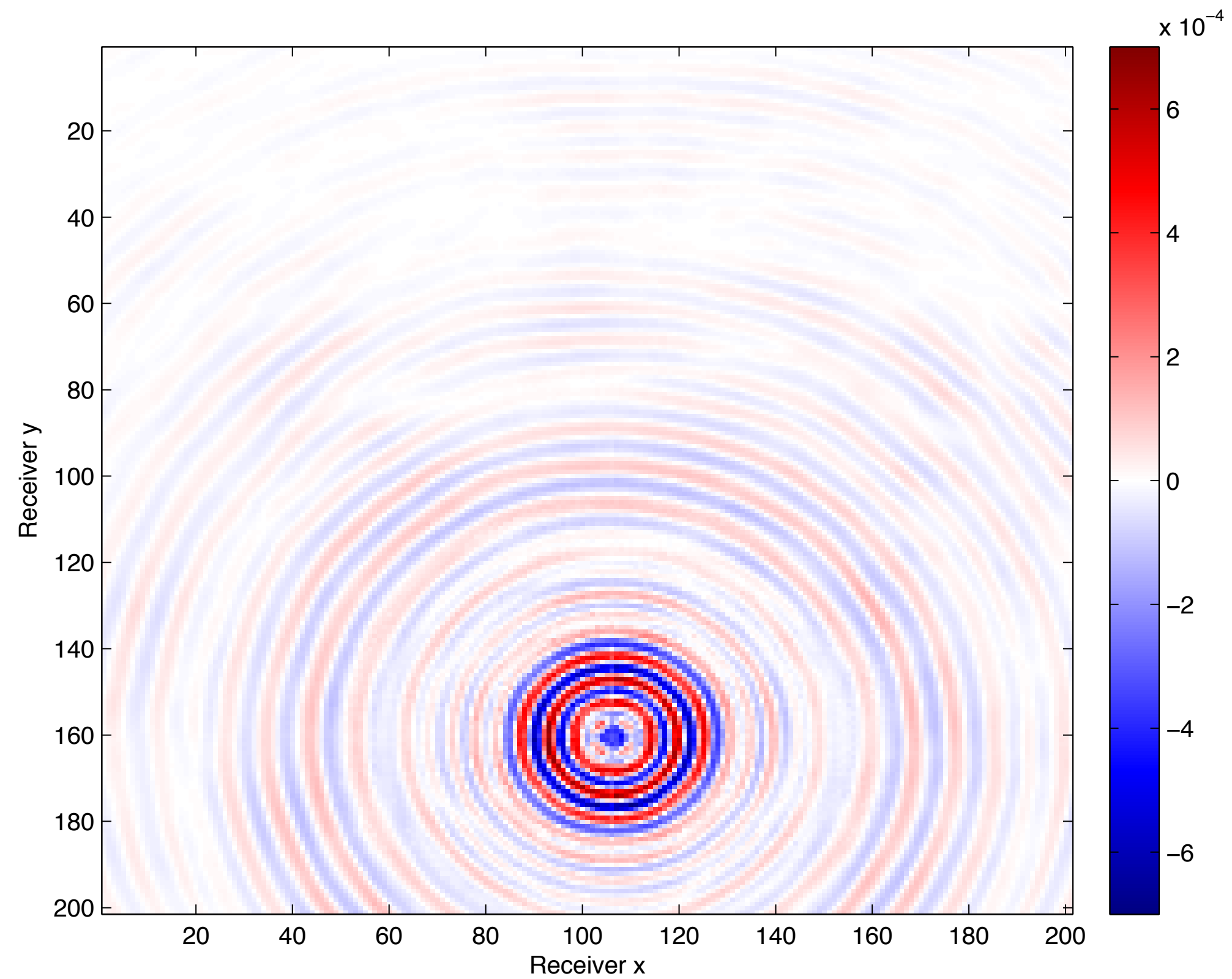
True data



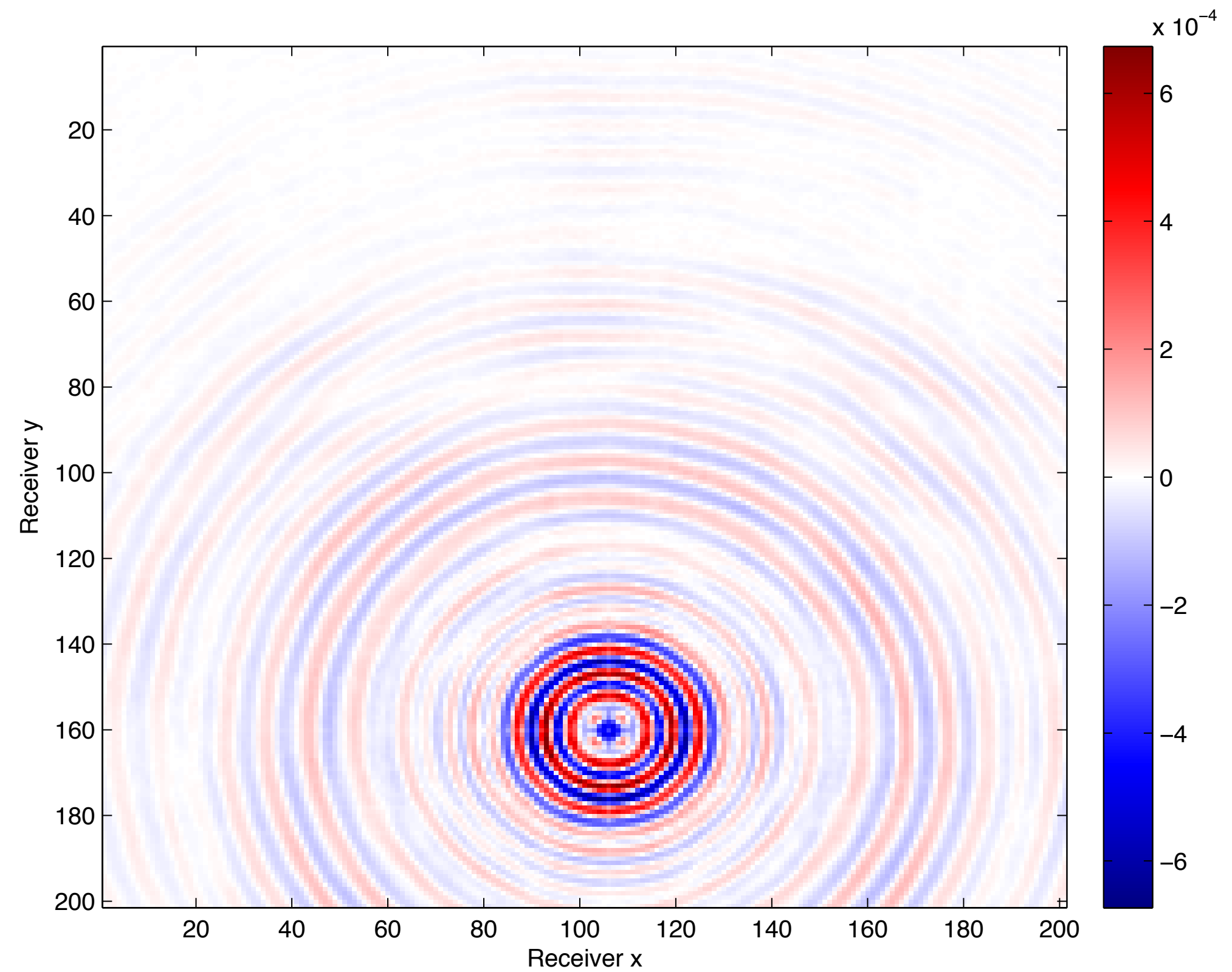
Subsampled data

7.34 Hz - 75% missing receivers

Common source gather



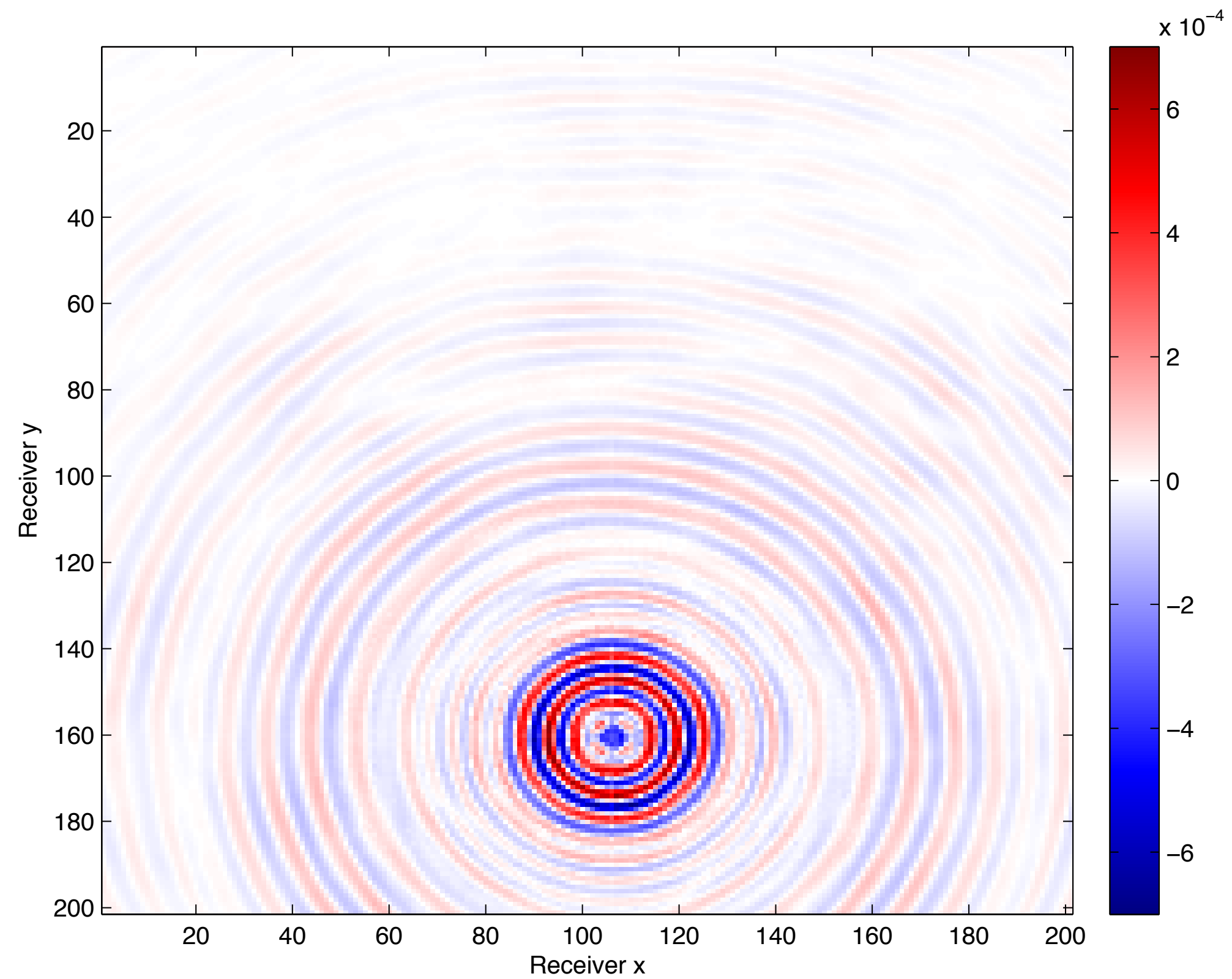
True data



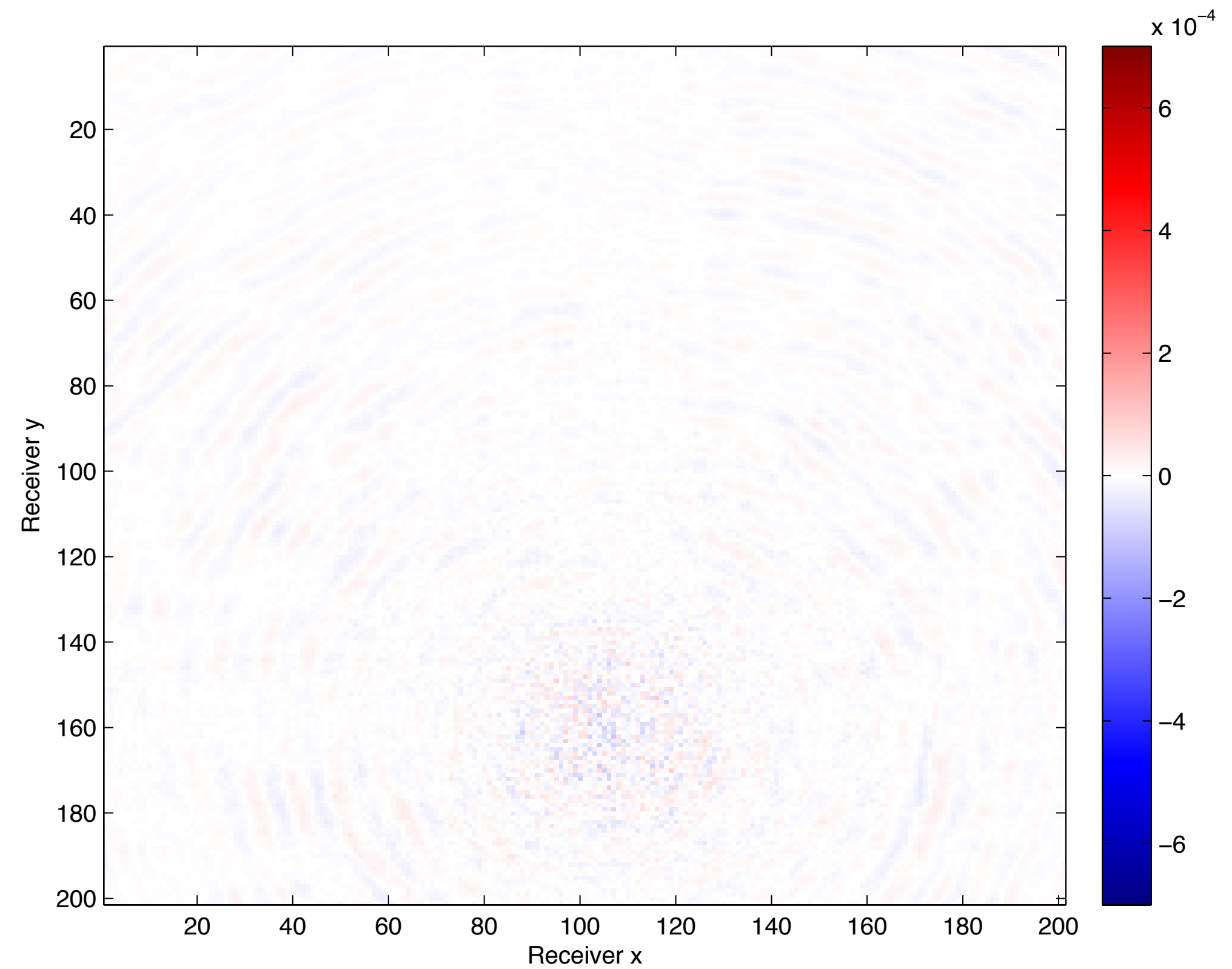
Recovered data - SNR 17.6 dB

7.34 Hz - 75% missing receivers

Common source gather



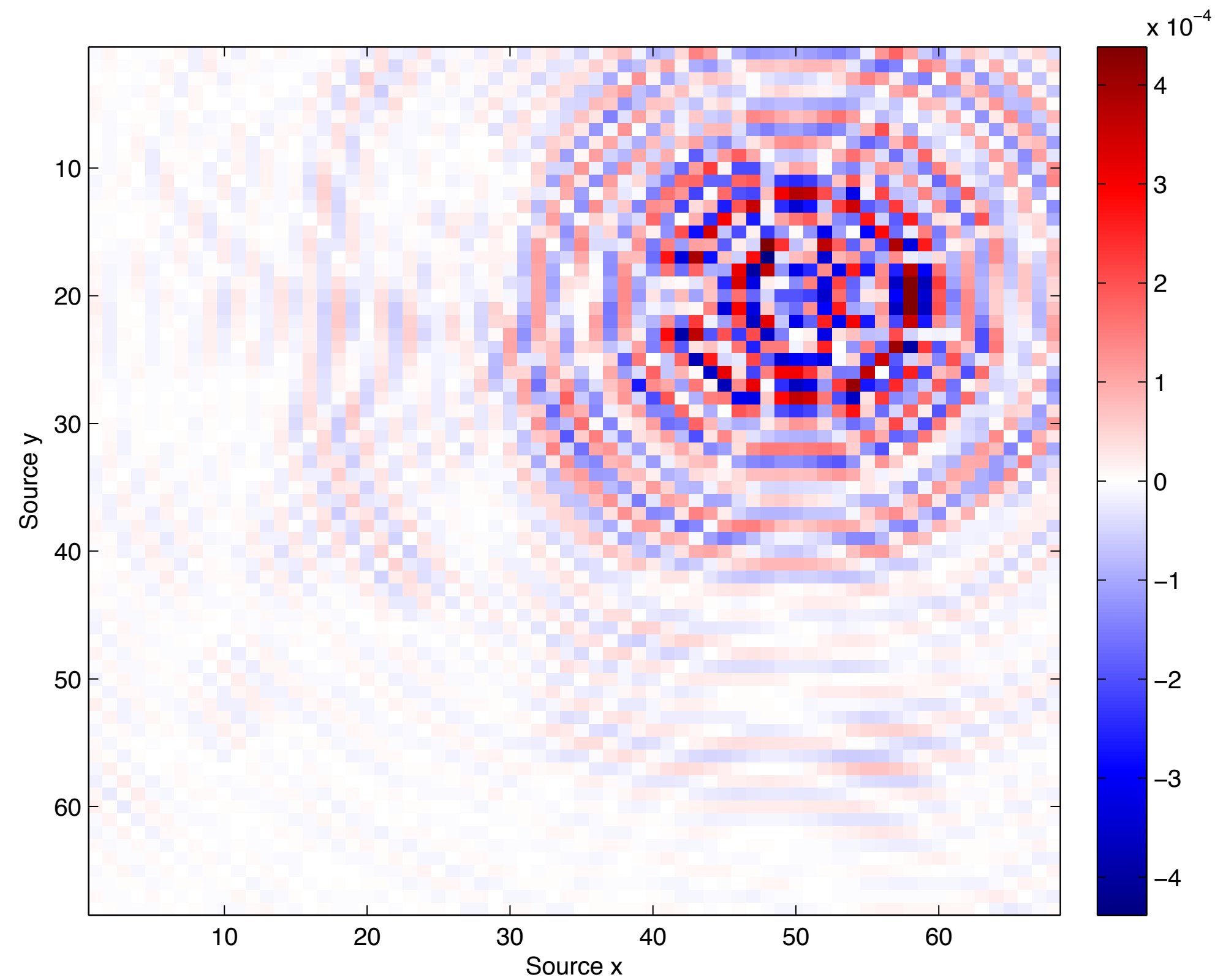
True data



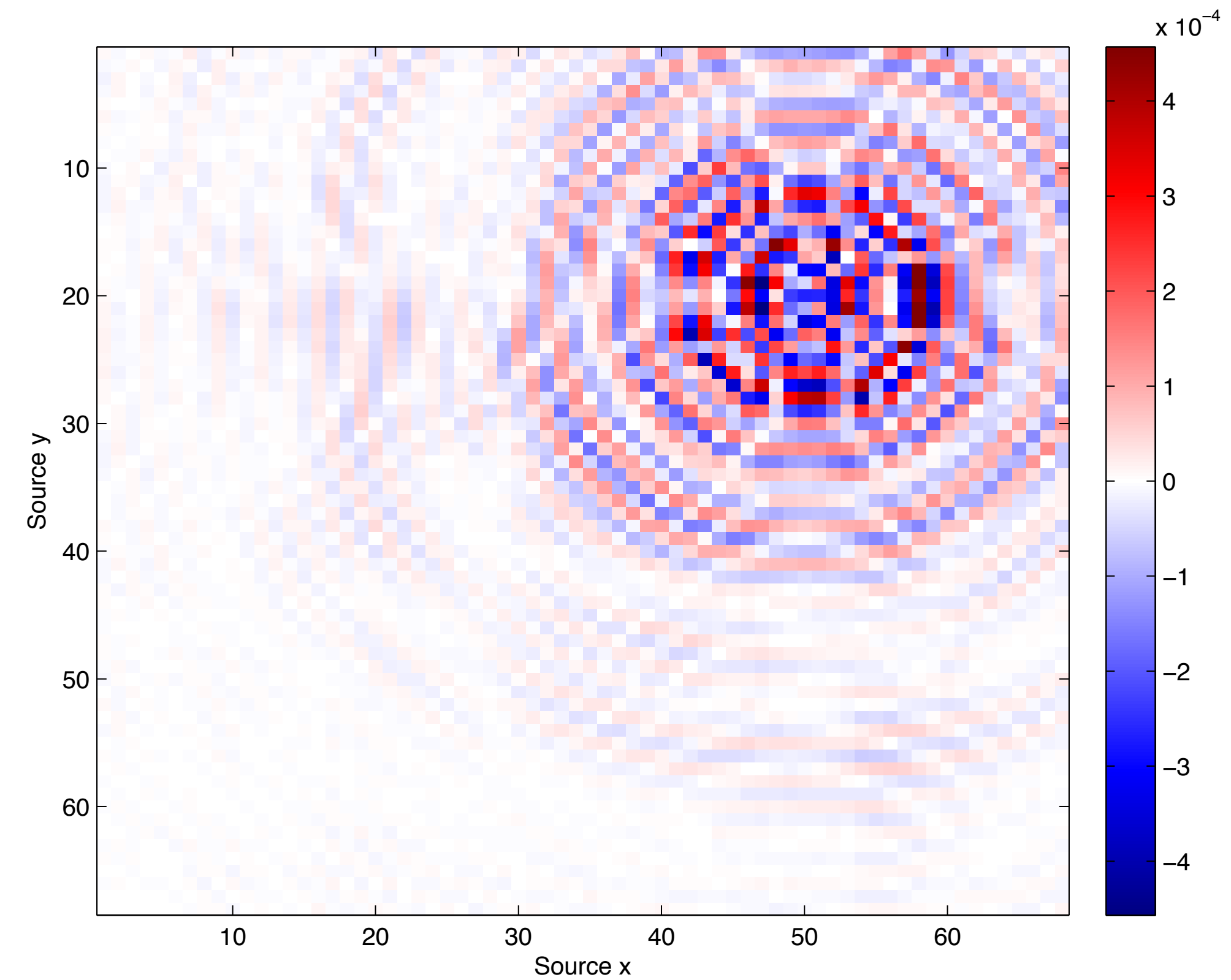
Difference

7.34 Hz - 75% missing receivers

Common receiver gather - no data initially



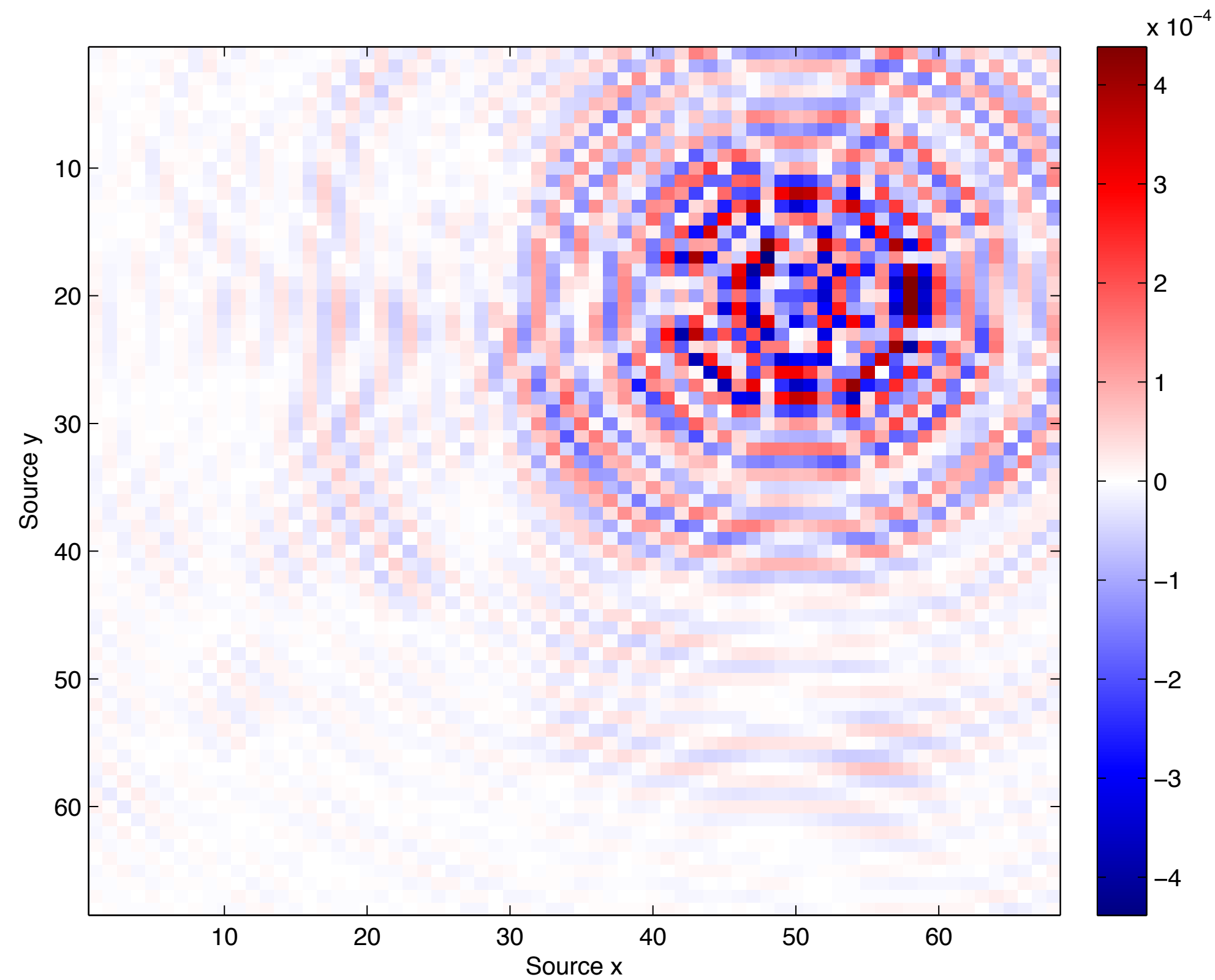
True data



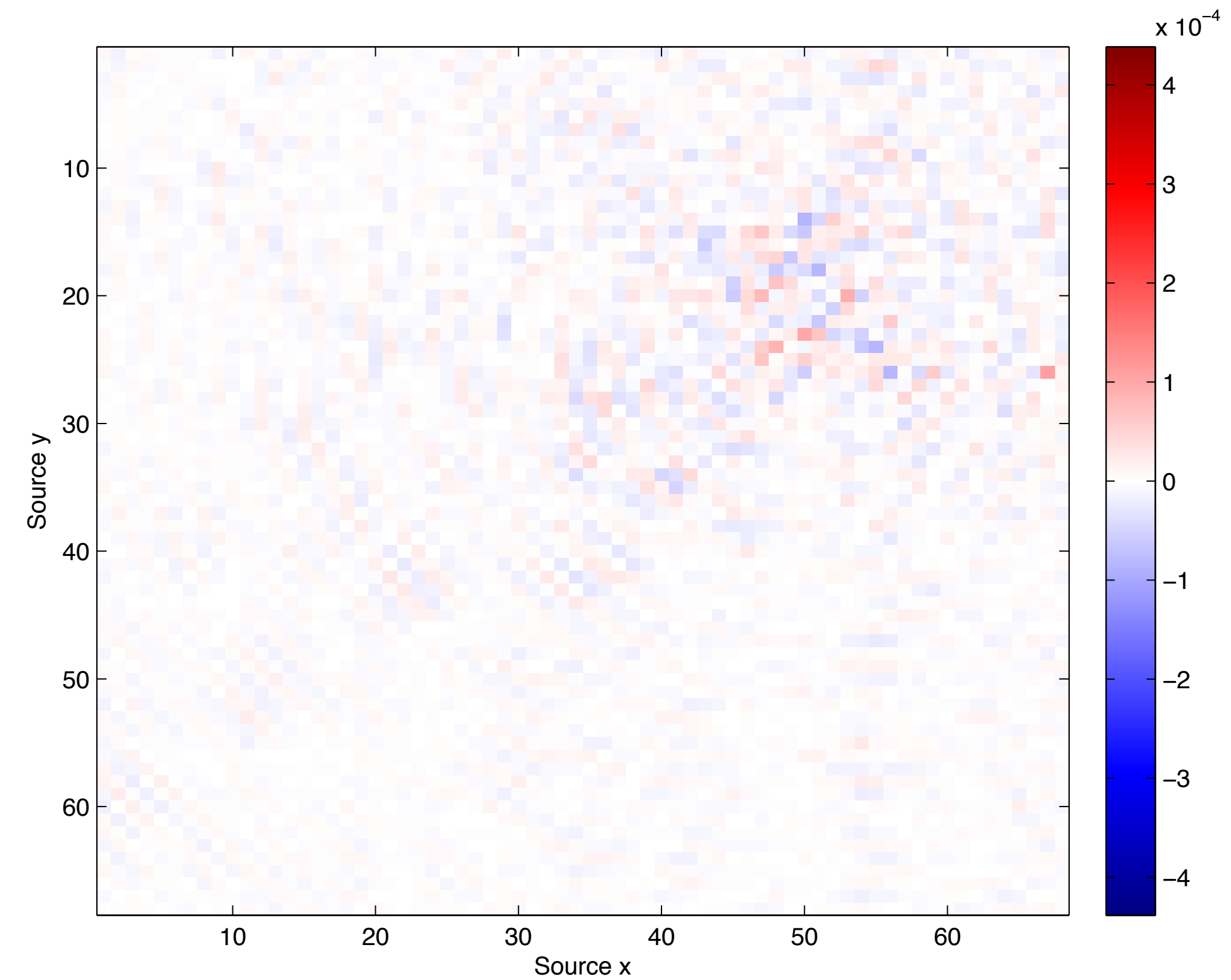
Recovered data - SNR 16.2 dB

7.34 Hz - 75% missing receivers

Common receiver gather - no data initially



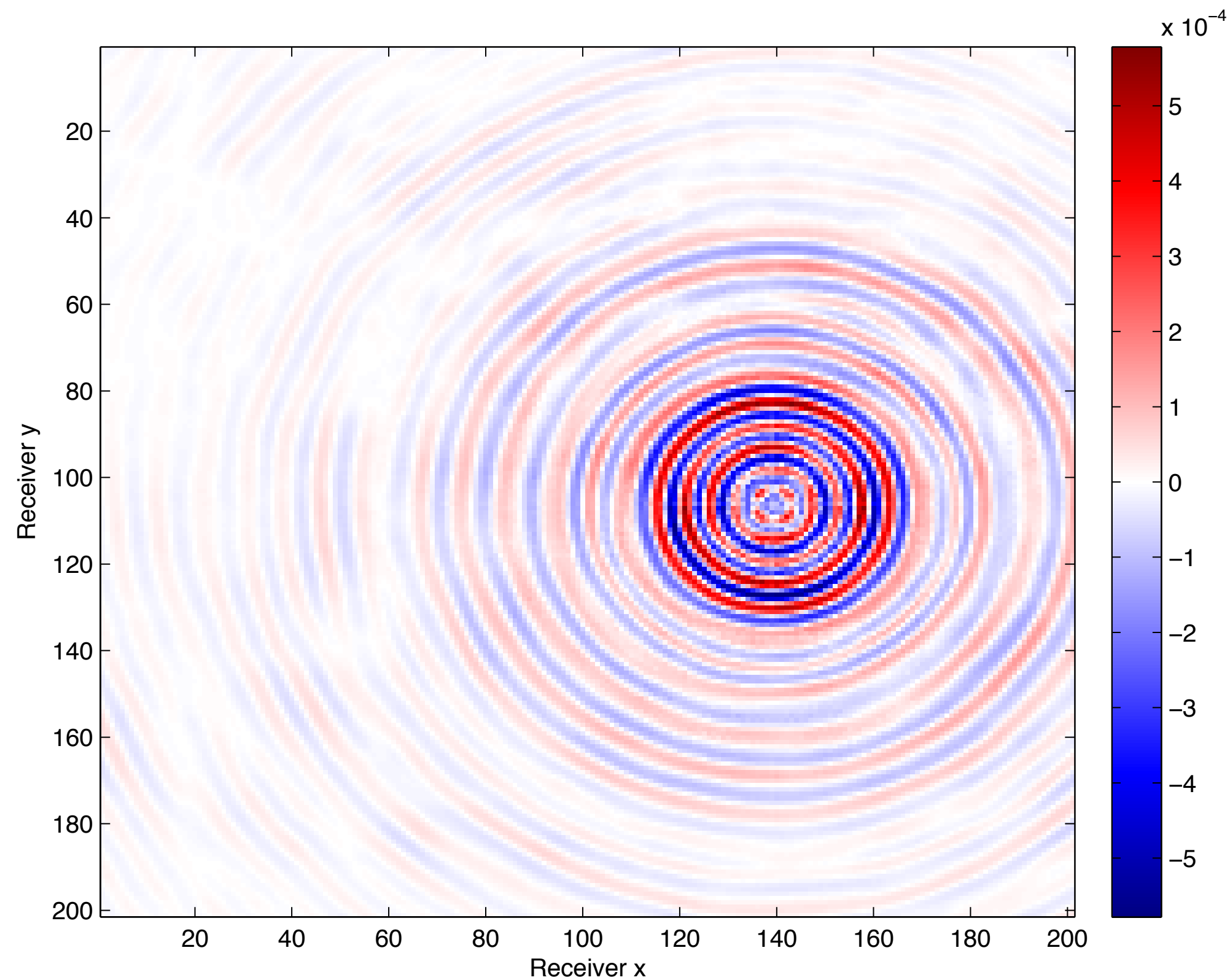
True data



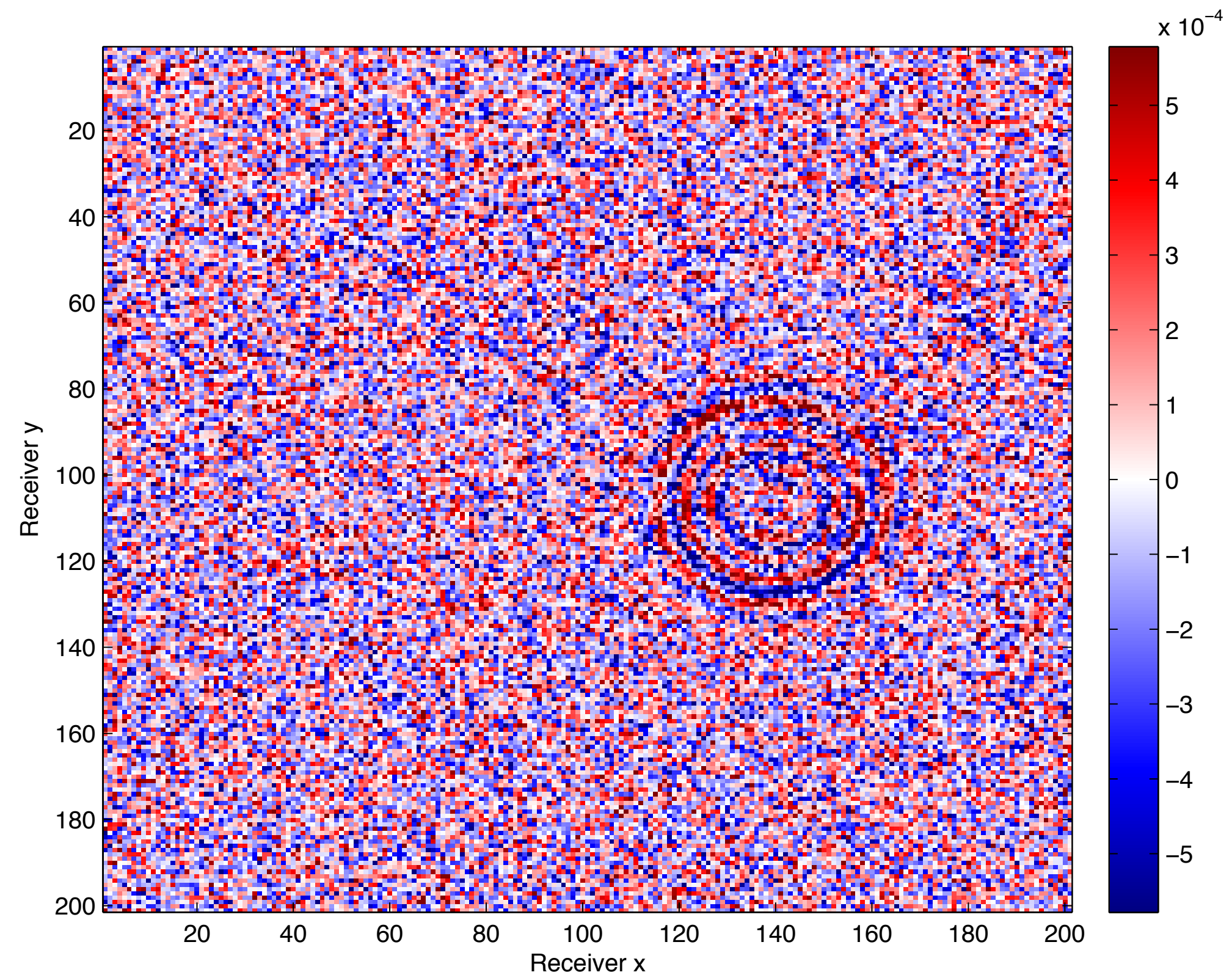
Difference

7.34 Hz - simultaneous receivers - 90% data reduction

Common source gather



True data

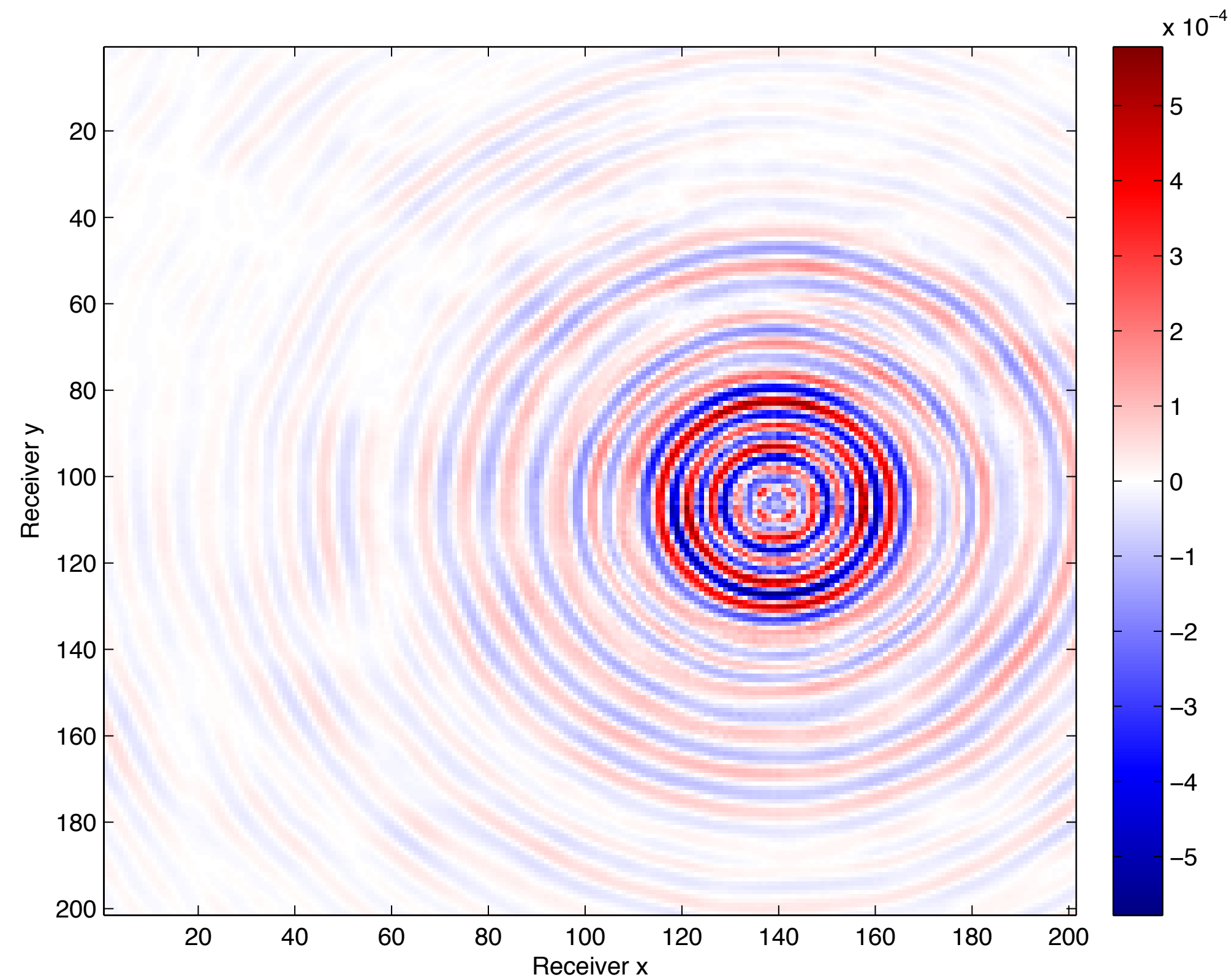


Input data - $A^T A b$

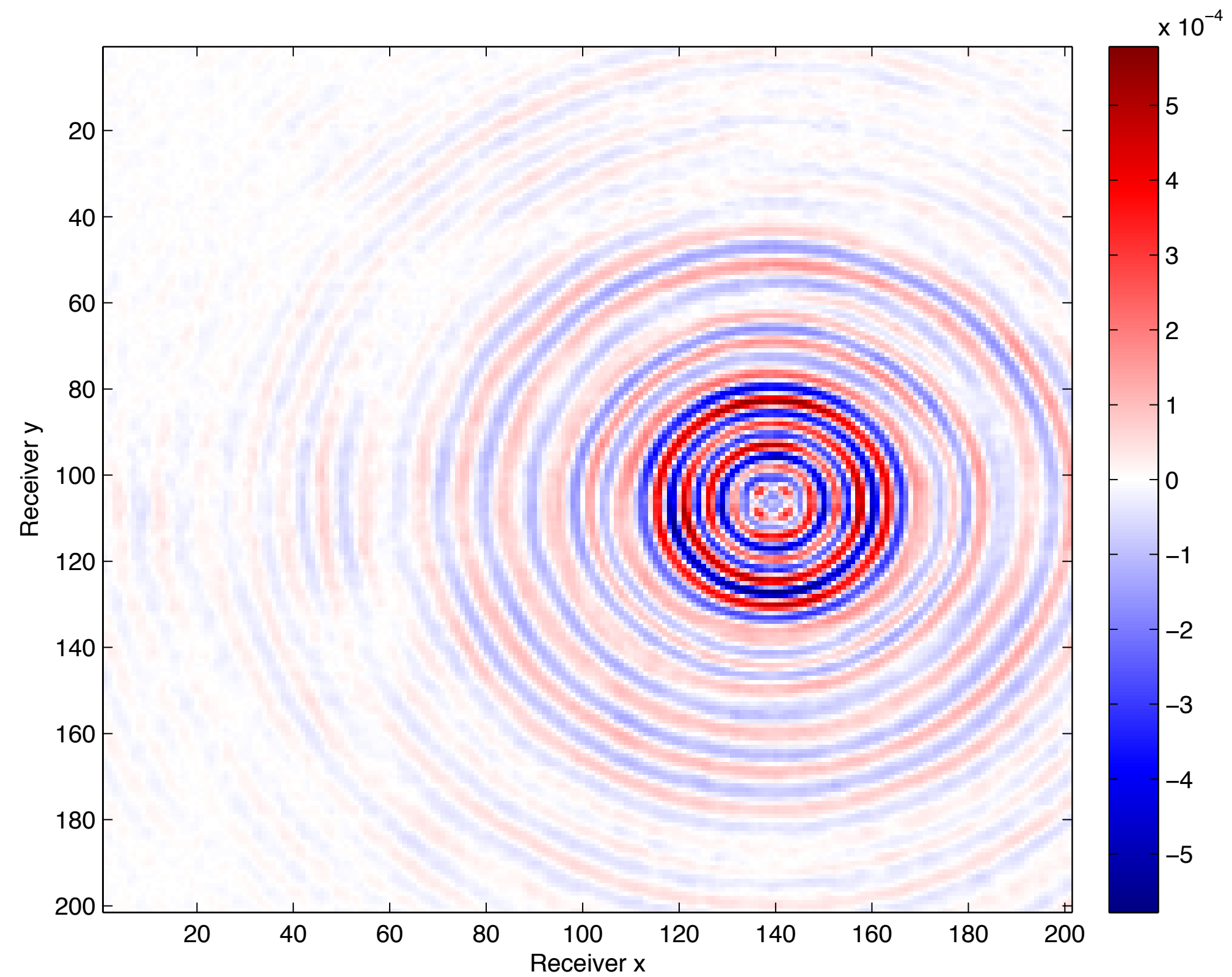
A - subsampling operator b - full data

7.34 Hz - simultaneous receivers - 90% data reduction

Common source gather



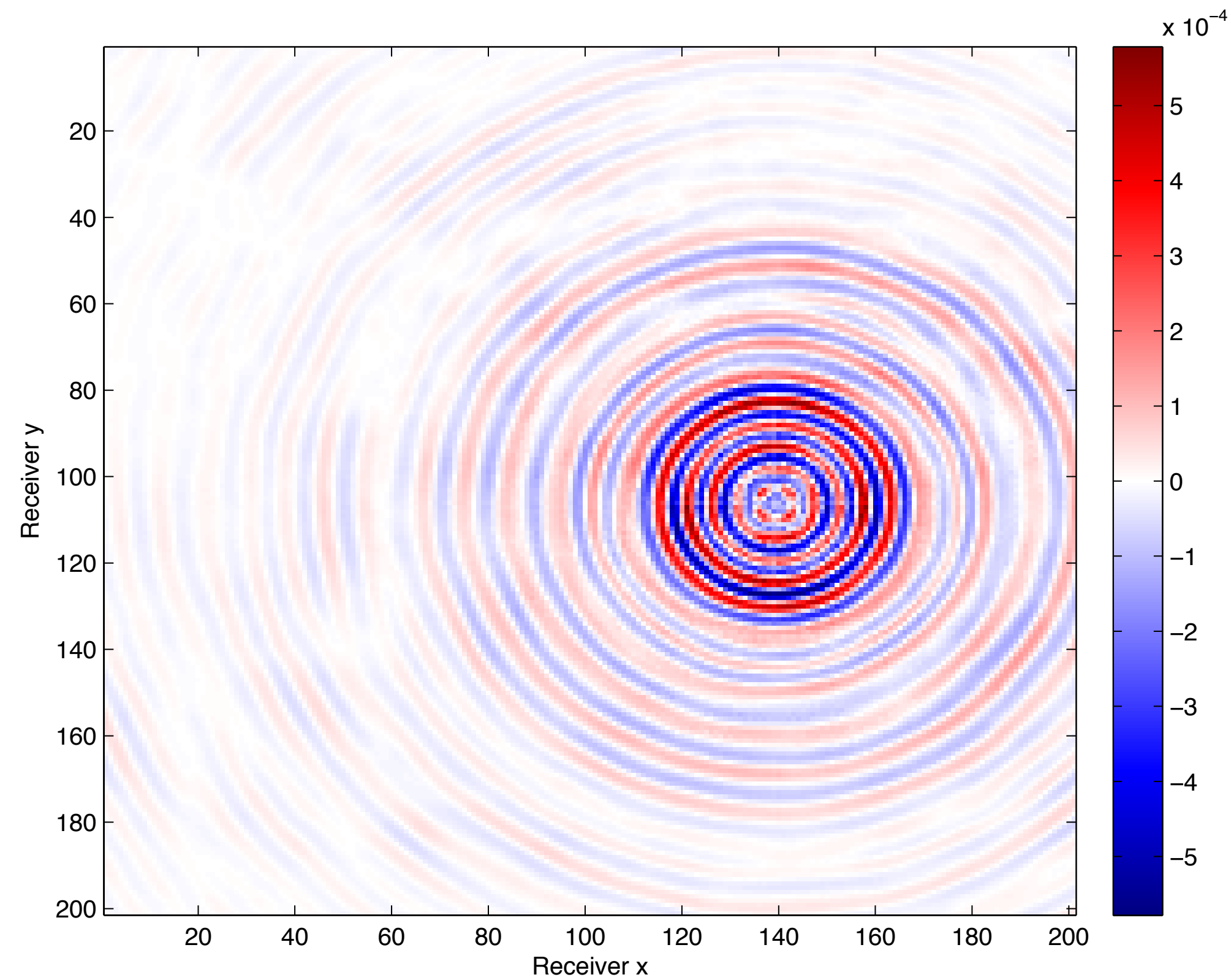
True data



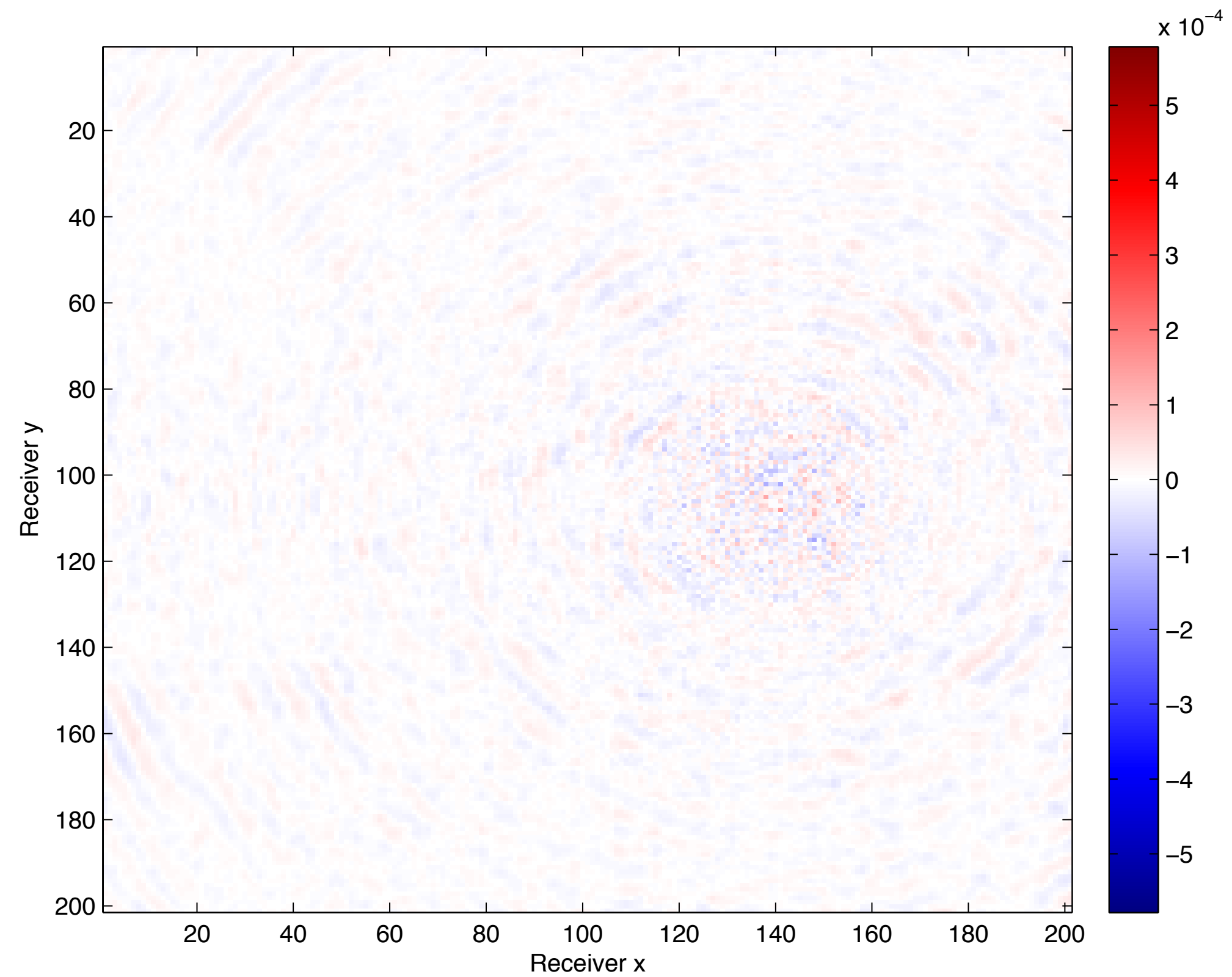
Recovered data - SNR 16.4 dB

7.34 Hz - simultaneous receivers - 90% data reduction

Common source gather



True data



Difference

Conclusion

3D seismic data has an underlying structure that we can exploit for interpolation (Hierarchical Tucker format)

Different schemes for organizing data - important for recovery

Conclusion

We can interpolate HT tensors with missing entries using the Riemannian manifold structure of the HT format

Achieve good results from largely subsampled data (75% missing receivers)

Can use this method to create full volumes from subsampled data

- Migration, multiple removal, etc.

Acknowledgements

Thank you for your attention



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