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Multilevel Acceleration Strategy for the Robust Estimation of Primaries by Sparse Inversion

Tim T.Y. Lin and Felix J. Herrmann Amsterdam, *EAGE 2014*





Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

true primary wavefield

SRME-produced primary

$$\mathbf{P_o} = \mathbf{P} - A(f)\mathbf{P_o}\mathbf{P}$$

P total up-going wavefield

 $\mathbf{P_o}$ primary wavefield

4(f) "matching" operator



Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

true primary wavefield

SRME-produced primary

$$\mathbf{P_o} \approx \mathbf{P} - A(f)\mathbf{PP}$$

SRMP

P total up-going wavefield

 $\mathbf{P}_{\mathbf{O}}$ primary wavefield

4(f) "matching" operator



Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

adaptive
$$\min_{A} \sum_{f} \|\mathbf{P} - A(f)\mathbf{PP}\|$$
 subtraction

P total up-going wavefield

Po primary wavefield

A(f) "matching" operator



Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

true primary wavefield

SRME-produced primary

$$\mathbf{P_o} = \mathbf{P} - A(f)\mathbf{P_o}\mathbf{P}$$

P total up-going wavefield

 $\mathbf{P_o}$ primary wavefield

4(f) "matching" operator



Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

recorded data predicted data from SRME

$$\mathbf{P} = \mathbf{P_o} + A(f)\mathbf{P_o}\mathbf{P}$$

P total up-going wavefield

Po primary wavefield

4(f) "matching" operator

Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

recorded data predicted data from SRME

$$\mathbf{P} = \mathbf{P_o} + A(f)\mathbf{P_o}\mathbf{P}$$

$$\mathbf{P_o} = \mathbf{QG}$$
$$A(f) = -\mathbf{Q}^{-1}$$

- P total up-going wavefield
- down-going source signature
- primary impulse response



Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

recorded data predicted data from SRME

$$P = QG - GP$$

- P total up-going wavefield
- O down-going source signature
- primary impulse response

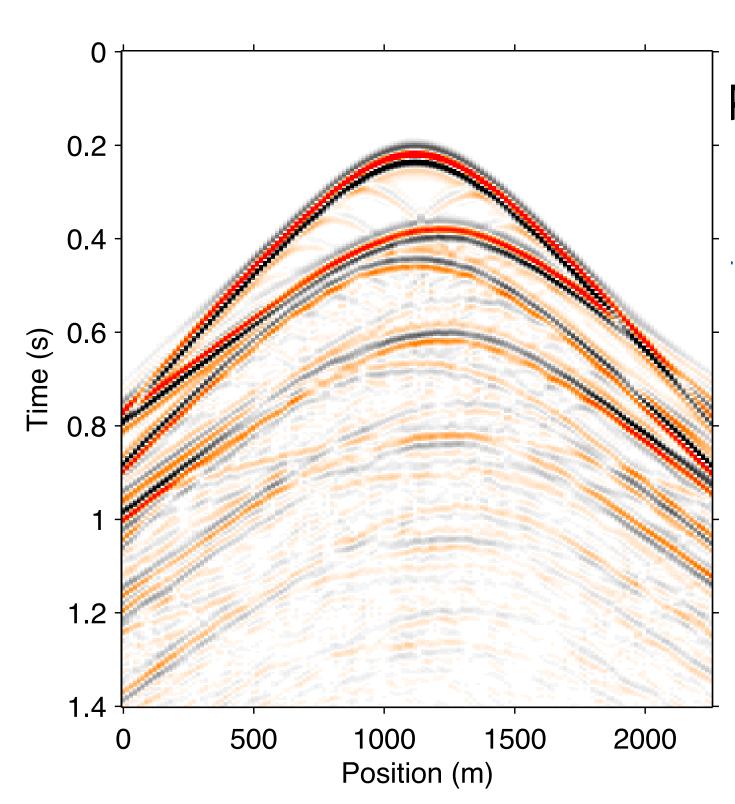
Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

recorded data predicted data from SRME

$$P = QG - GP$$

$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} ||\mathbf{P} - (\mathbf{QG} - \mathbf{GP})||_2^2$$





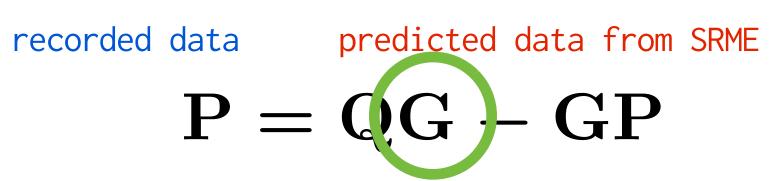
Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

ed data predicted data from SRME
$$\mathbf{P} = \mathbf{QG} - \mathbf{GP}$$

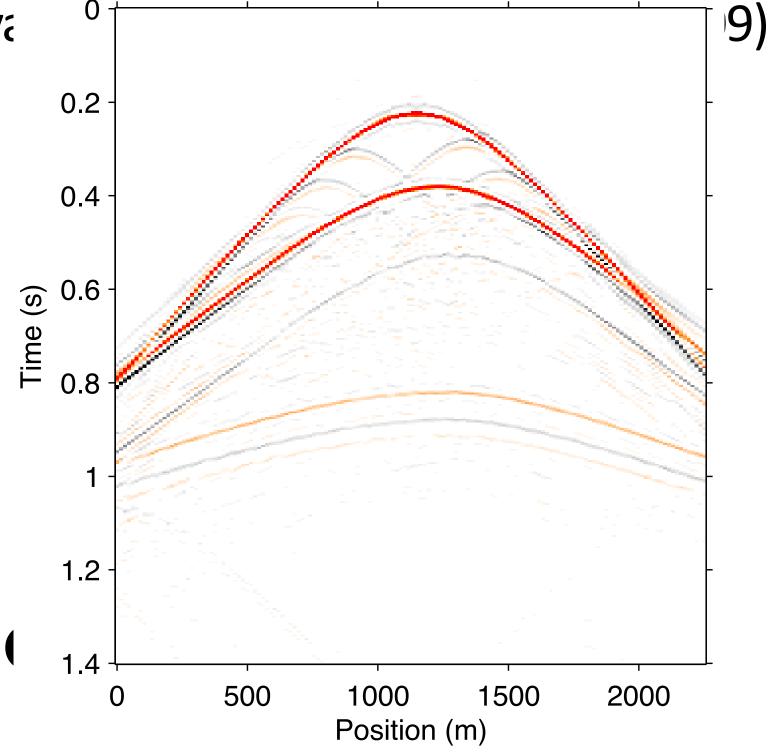
$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} ||\mathbf{P} - (\mathbf{QG} - \mathbf{GP})||_2^2$$



Based on Estimation of Primaries by Sparse Inversion (va

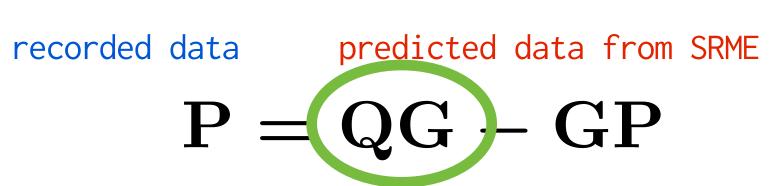


$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} || \mathbf{P} - (\mathbf{Q})||$$

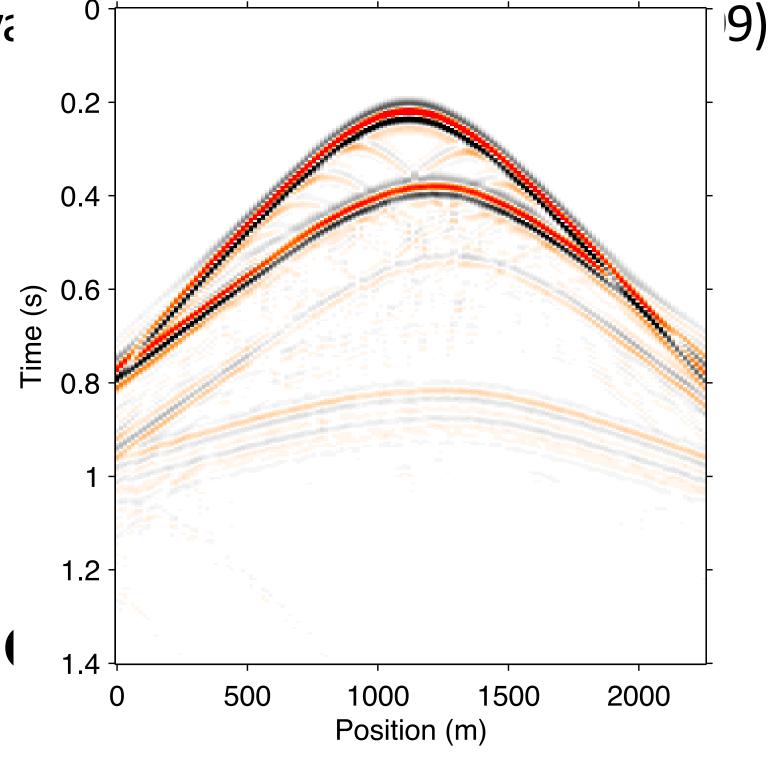




Based on Estimation of Primaries by Sparse Inversion (va

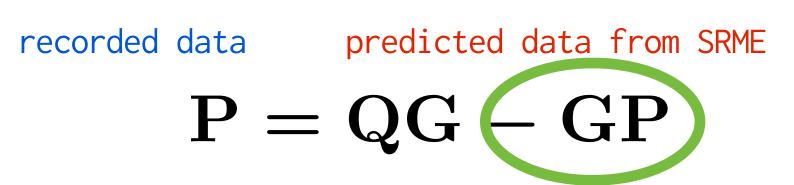


$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} || \mathbf{P} - (\mathbf{Q})||$$

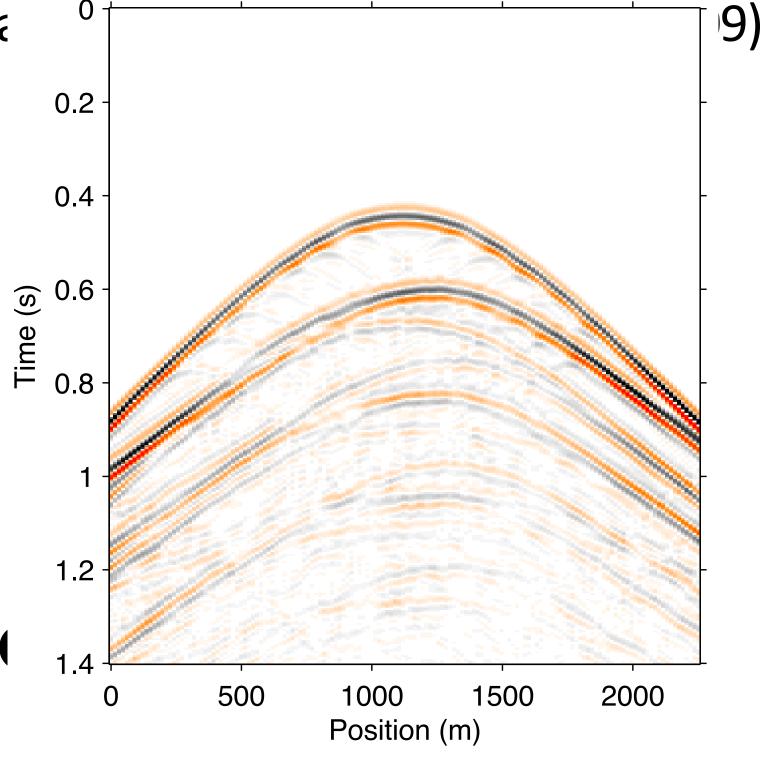




Based on Estimation of Primaries by Sparse Inversion (va



$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} || \mathbf{P} - (\mathbf{Q})||$$

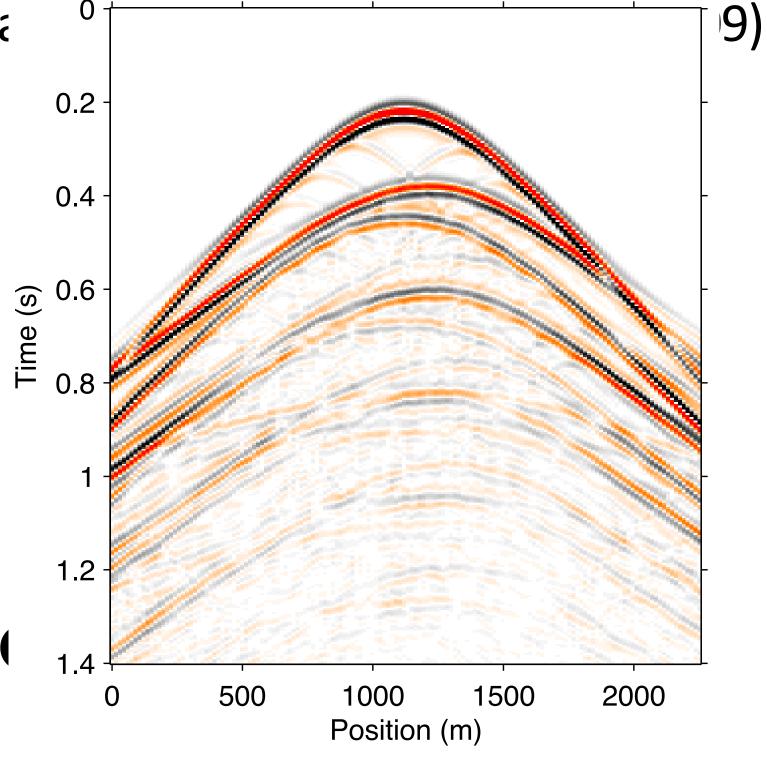




Based on Estimation of Primaries by Sparse Inversion (va



$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} || \mathbf{P} - (\mathbf{Q})||$$



Two ways to obtain the final primary wavefield

"Direct" Primary "Conservative" Primary
$$\mathbf{QG} = \mathbf{P} + \mathbf{GP}$$

$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} ||\mathbf{P} - (\mathbf{QG} - \mathbf{GP})||_2^2$$

In time domain (lower-case: whole dataset in time domain)

recorded data predicted data from SRME

$$\mathbf{p} = \mathcal{M}(\mathbf{g}, \mathbf{q})$$

$$\mathcal{M}(\mathbf{g}, \mathbf{q}) := \mathcal{F}_{\mathrm{t}}^{\dagger} \mathrm{BlockDiag}_{\omega_{1} \cdots \omega_{nf}} [(q(\omega)\mathbf{I} - \mathbf{P})^{\dagger} \otimes \mathbf{I}] \mathcal{F}_{\mathrm{t}} \mathbf{g}$$

$$f(\mathbf{g}, \mathbf{q}) = \frac{1}{2} \|\mathbf{p} - \mathcal{M}(\mathbf{g}, \mathbf{q})\|_2^2$$

Based on Estimation of Primaries by Sparse Inversion (van Groenestijn and Verschuur, 2009)

recorded data predicted data from SRME

$$P = QG - GP$$

$$f(\mathbf{G}, \mathbf{Q}) = \frac{1}{2} ||\mathbf{P} - (\mathbf{QG} - \mathbf{GP})||_2^2$$

Robust EPSI

L1-minimization approach to the EPSI problem

[Lin and Herrmann, 2013 *Geophysics*]

While
$$\|\mathbf{p} - \mathcal{M}(\mathbf{g}_k, \mathbf{q}_k)\|_2 > \sigma$$

determine new τ_k from the Pareto curve

$$\mathbf{g}_{k+1} = \underset{\mathbf{g}}{\operatorname{arg\,min}} \|\mathbf{p} - \mathbf{M}_{q_k} \mathbf{g}\|_2 \text{ s.t. } \|\mathbf{g}\|_1 \le \tau_k$$

$$\mathbf{q}_{k+1} = \underset{\mathbf{q}}{\operatorname{arg\,min}} \|\mathbf{p} - \mathbf{M}_{g_{k+1}}\mathbf{q}\|_{2}$$

Solving the EPSI problem

Linearizations

$$\mathbf{p} = \mathcal{M}(\mathbf{g}, \mathbf{q})$$

$$\mathbf{M}_{ ilde{q}} = \left(rac{\partial \mathcal{M}}{\partial \mathbf{g}}
ight)_{ ilde{q}}$$

$$\mathbf{M}_{ ilde{g}} = \left(rac{\partial \mathcal{M}}{\partial \mathbf{q}}
ight)_{ ilde{g}}$$

In fact it is bilinear:

$$\mathbf{M}_{ ilde{q}}\mathbf{g} = \mathcal{M}(\mathbf{g}, \tilde{\mathbf{q}}) \qquad \mathbf{M}_{ ilde{g}}\mathbf{q} = \mathcal{M}(\mathbf{q}, \tilde{\mathbf{g}})$$

Robust EPSI

L1-minimization approach to the EPSI problem

[Lin and Herrmann, 2013 *Geophysics*]

While
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$$\mathbf{q}_{k+1} = \underset{\mathbf{q}}{\operatorname{arg\,min}} \|\mathbf{p} - \mathbf{M}_{g_{k+1}}\mathbf{q}\|_{2}$$

Robust EPSI

L1-minimization approach to the EPSI problem

[Lin and Herrmann, 2013 *Geophysics*]

While
$$\|\mathbf{p} - \mathcal{M}(\mathbf{g}_k, \mathbf{q}_k)\|_2 > \sigma$$

determine new τ_k from the Pareto curve

Emits sparse, or "deconvolved" solution

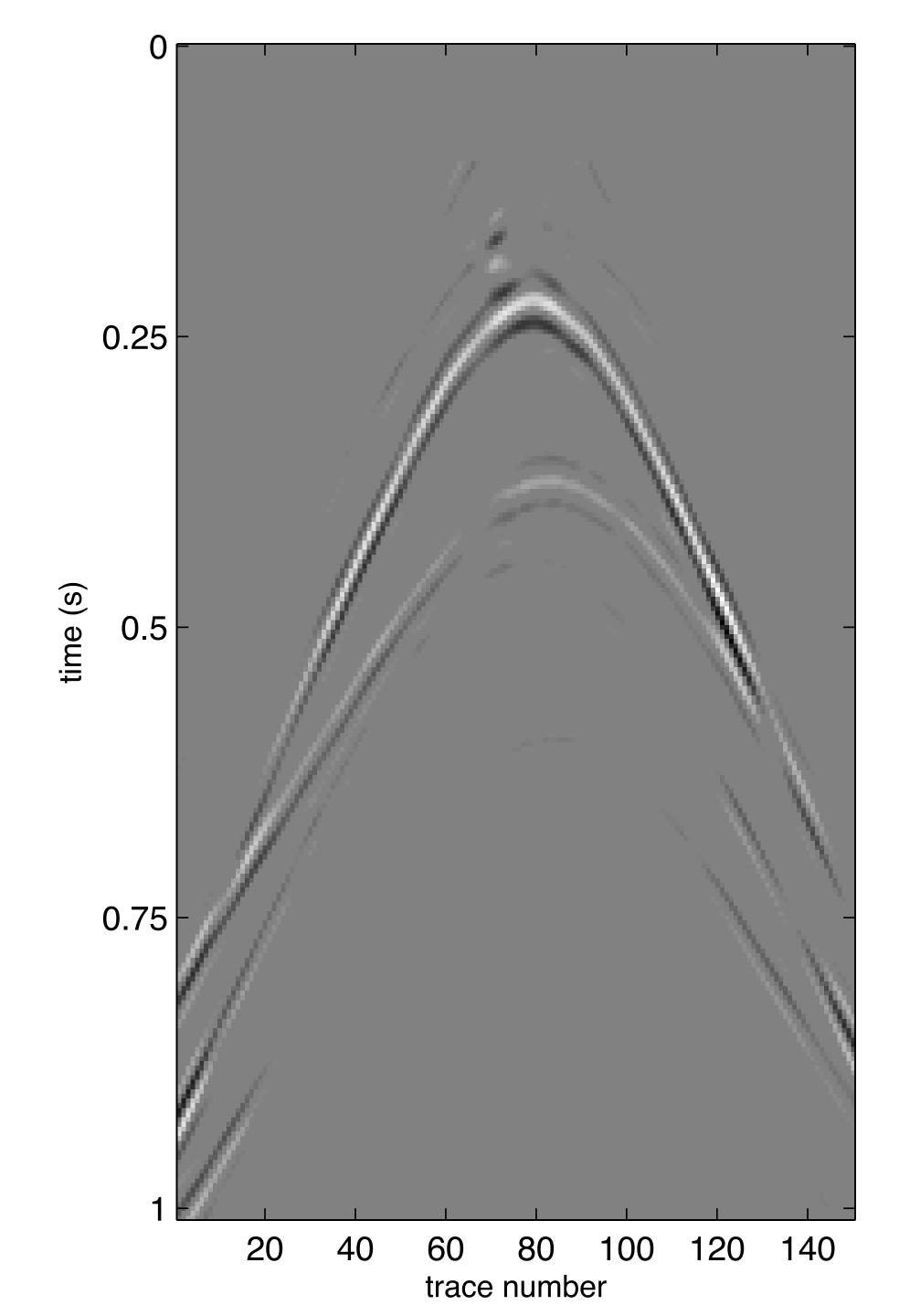
$$\mathbf{g}_{k+1} = \underset{\mathbf{g}}{\operatorname{arg\,min}} \|\mathbf{p} - \mathbf{M}_{q_k} \mathbf{g}\|_2 \text{ s.t. } \|\mathbf{g}\|_1 \le \tau_k$$

$$\mathbf{q}_{k+1} = \underset{\mathbf{q}}{\operatorname{arg\,min}} \|\mathbf{p} - \mathbf{M}_{g_{k+1}} \mathbf{q}\|_2$$

L1 projection and sparsity

variable g at beginning of LASSO

$$\mathbf{g}_{k+1} = rg \min_{\mathbf{g}} \|\mathbf{p} - \mathbf{M}_{q_k} \mathbf{g}\|_2 \text{ s.t. } \|\mathbf{g}\|_1 \le \tau_k$$

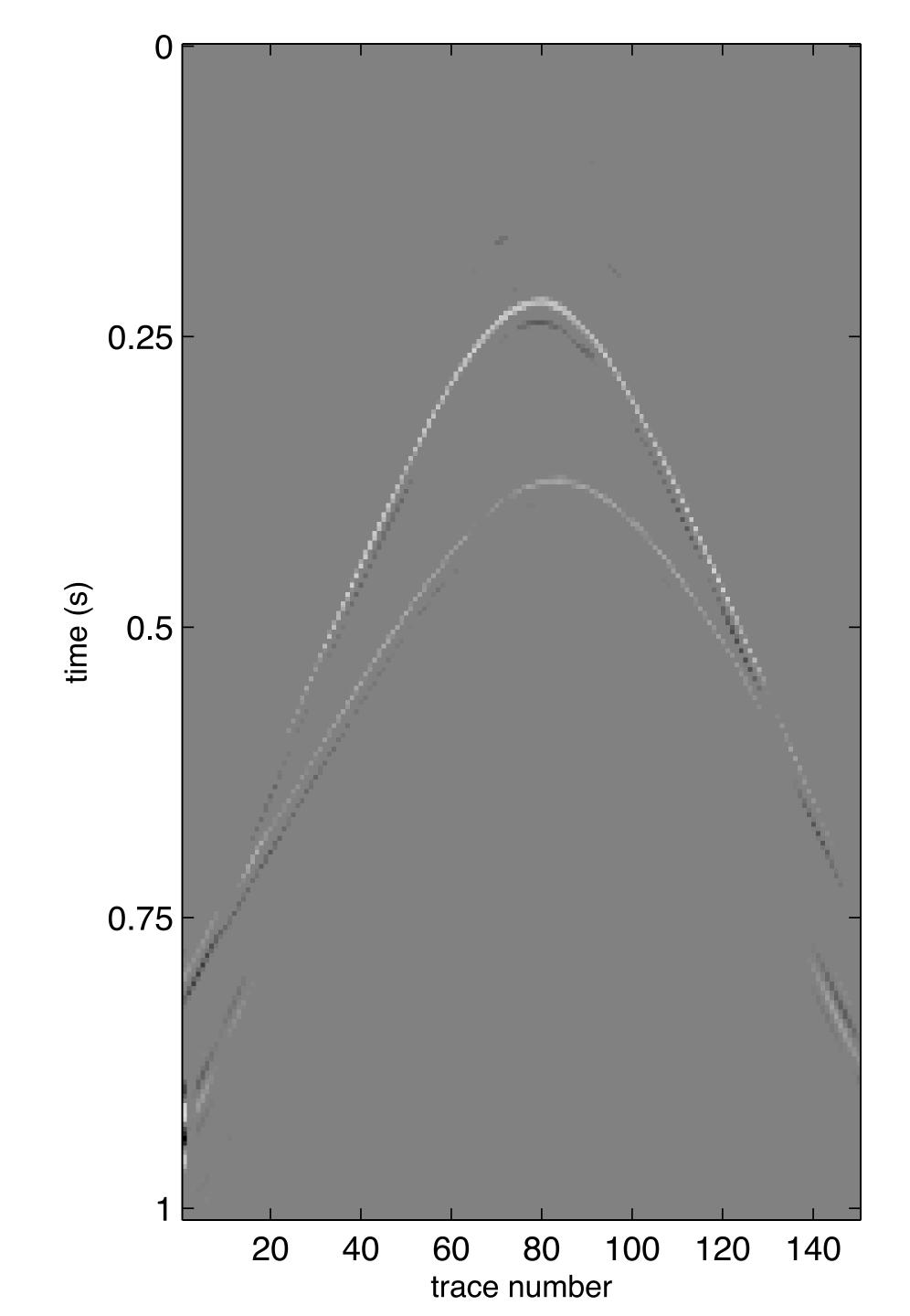


L1 projection and sparsity

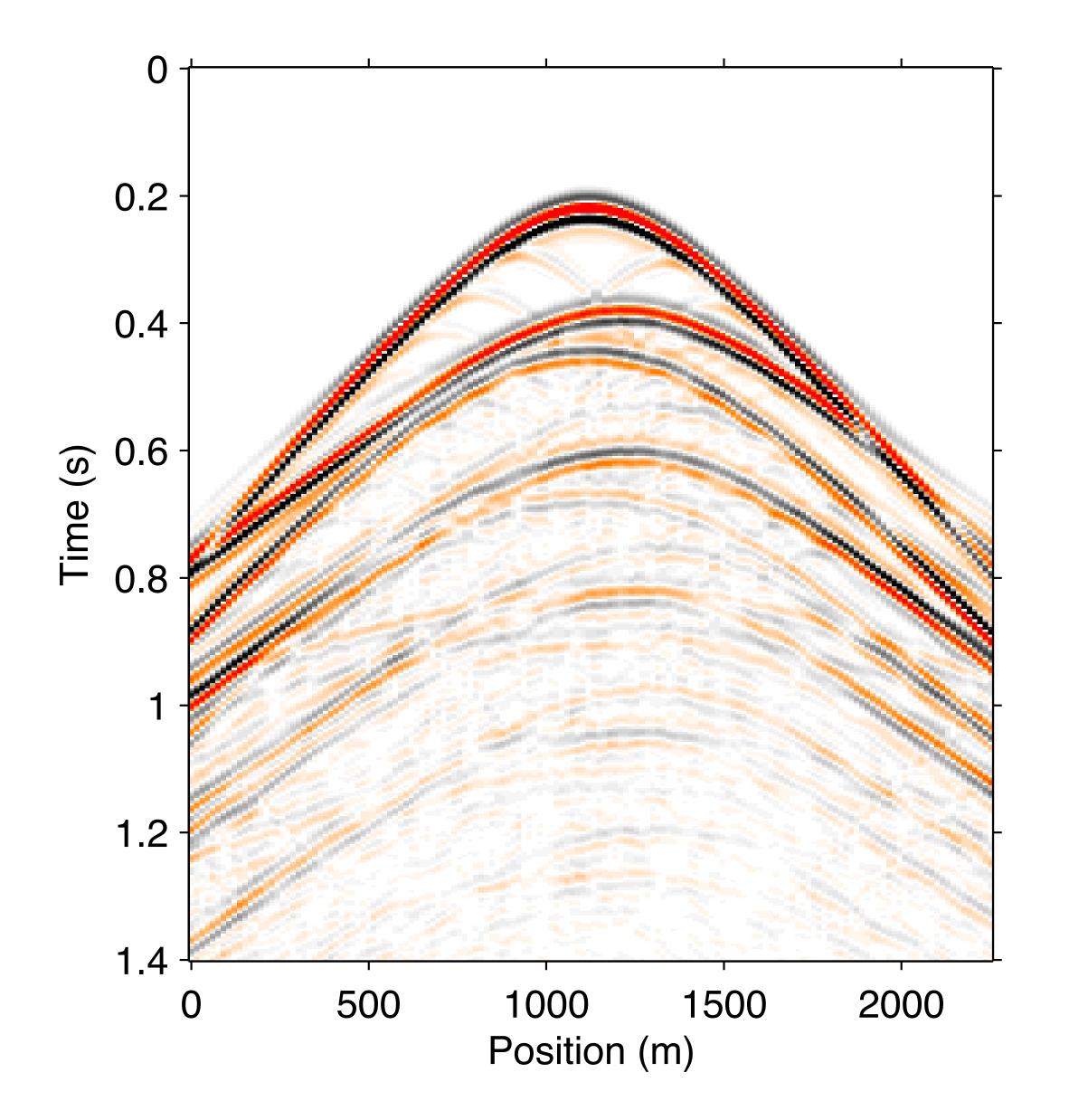
variable g at end of LASSO

$$\mathbf{g}_{k+1} = rg \min_{\mathbf{g}} \|\mathbf{p} - \mathbf{M}_{q_k} \mathbf{g}\|_2 \text{ s.t. } \|\mathbf{g}\|_1 \le \tau_k$$

Emits "deconvolved" solution



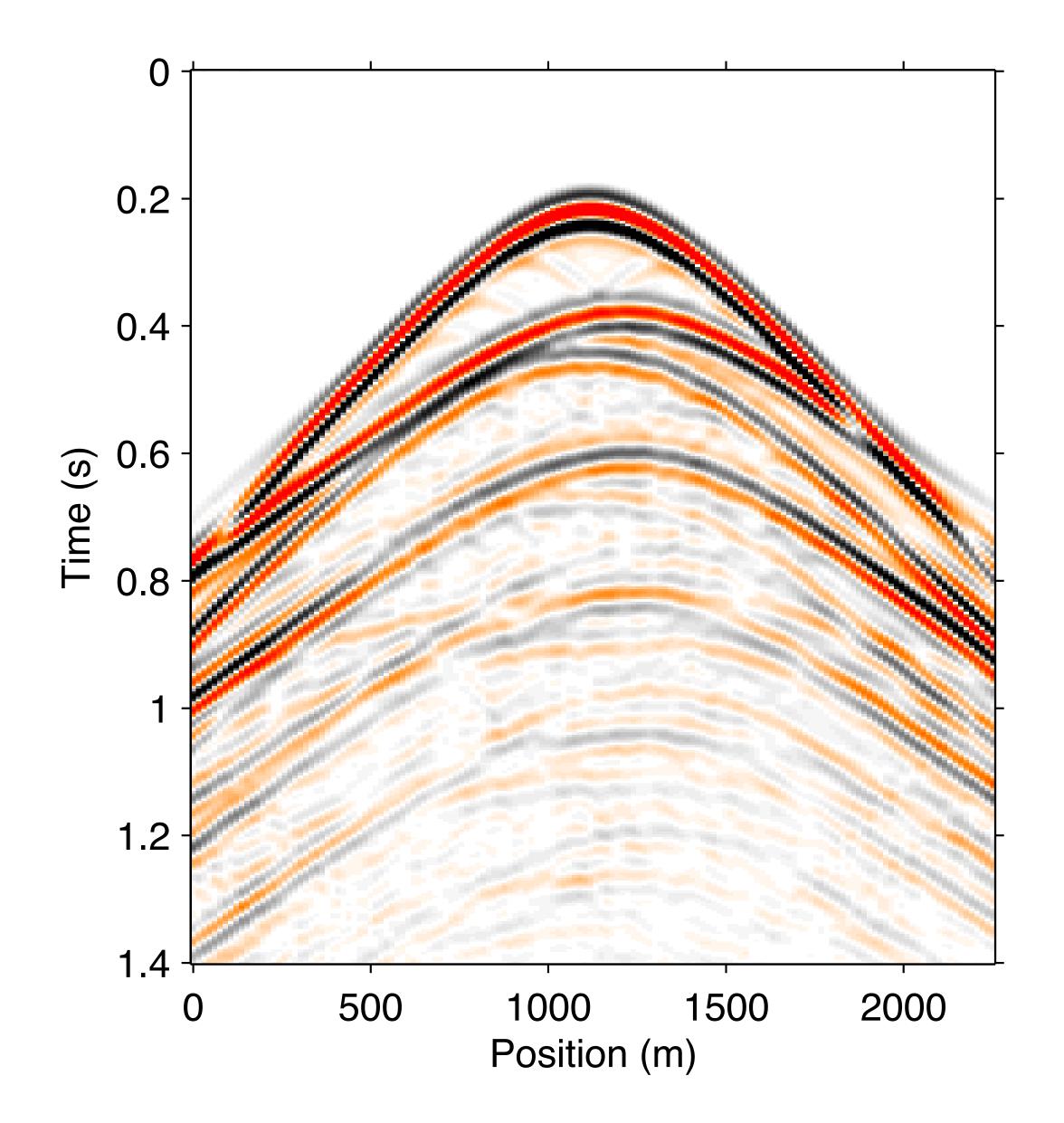




Data

modeled with Ricker 30Hz

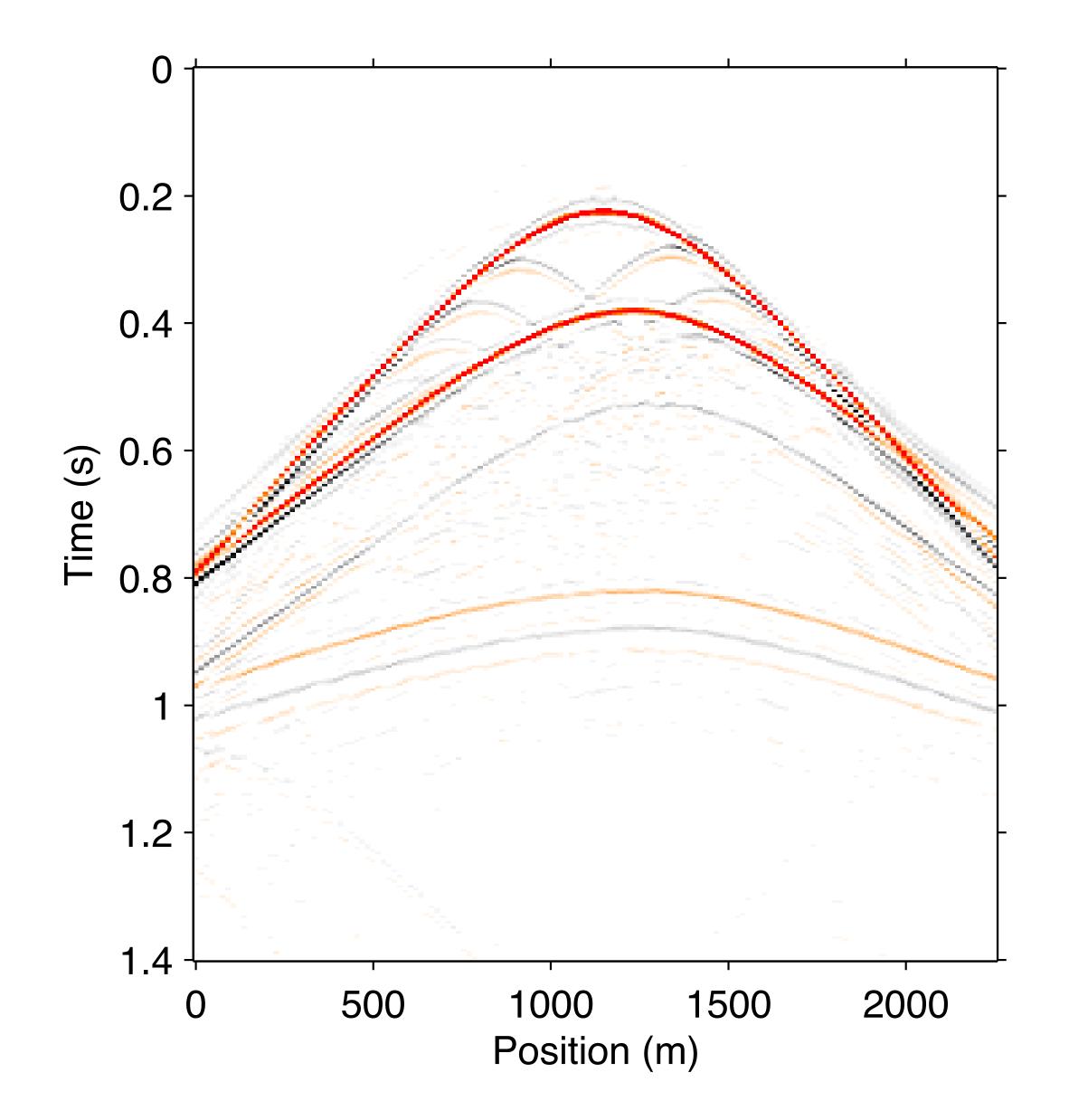




Lowpassed Data

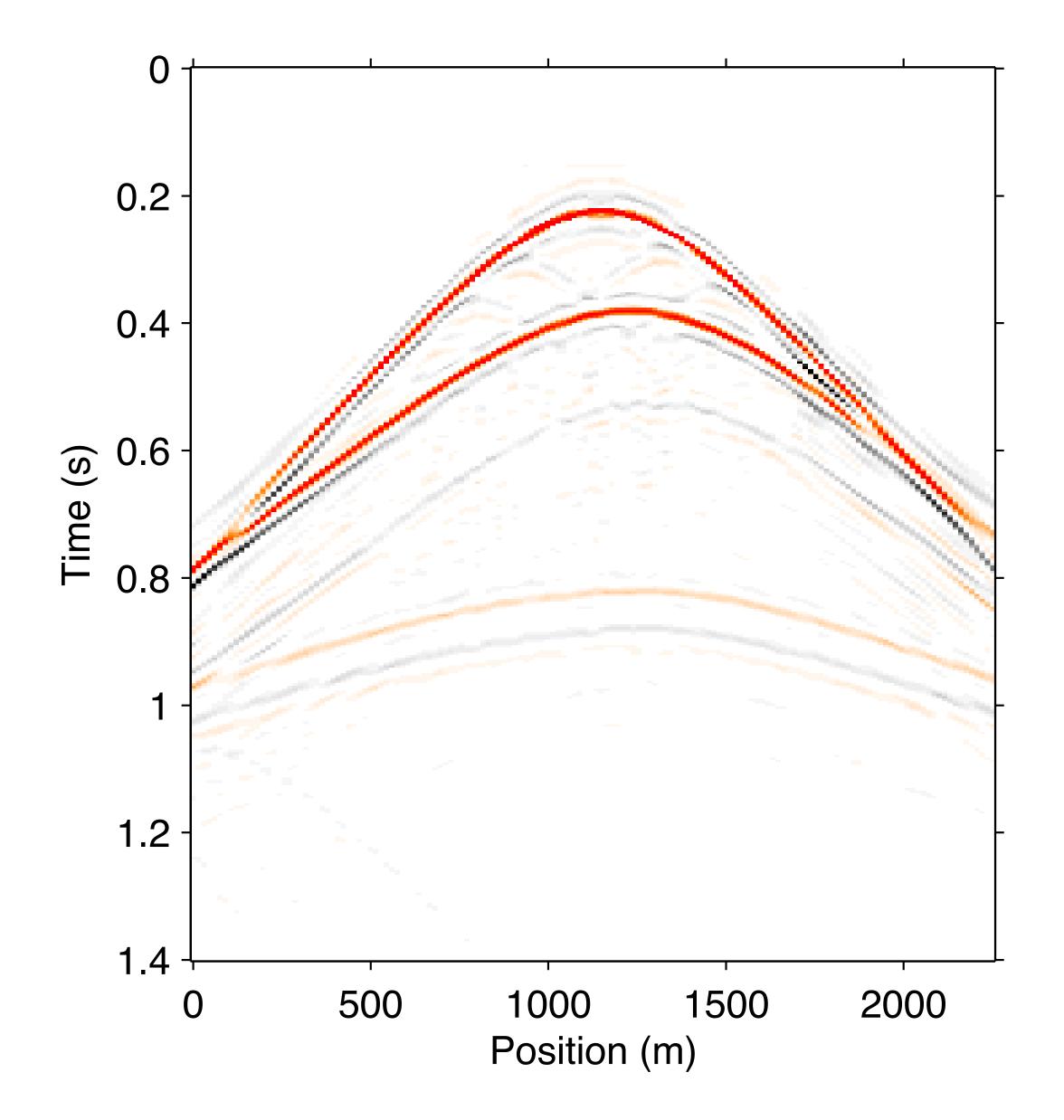
modeled with Ricker 30Hz lowpass at 40Hz (25-order, zero-phase, Hann window)





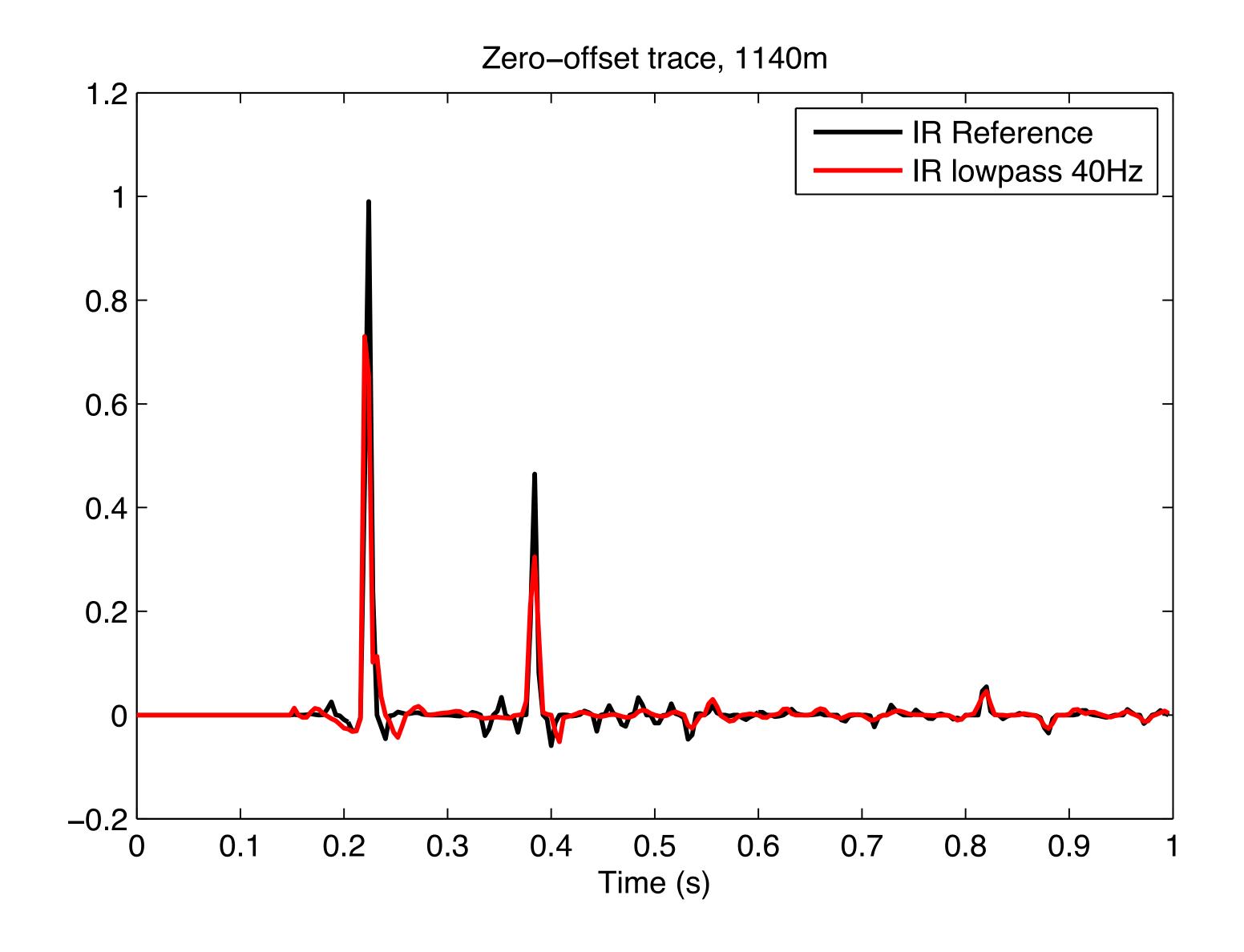
Reference REPSI primary IR from original data



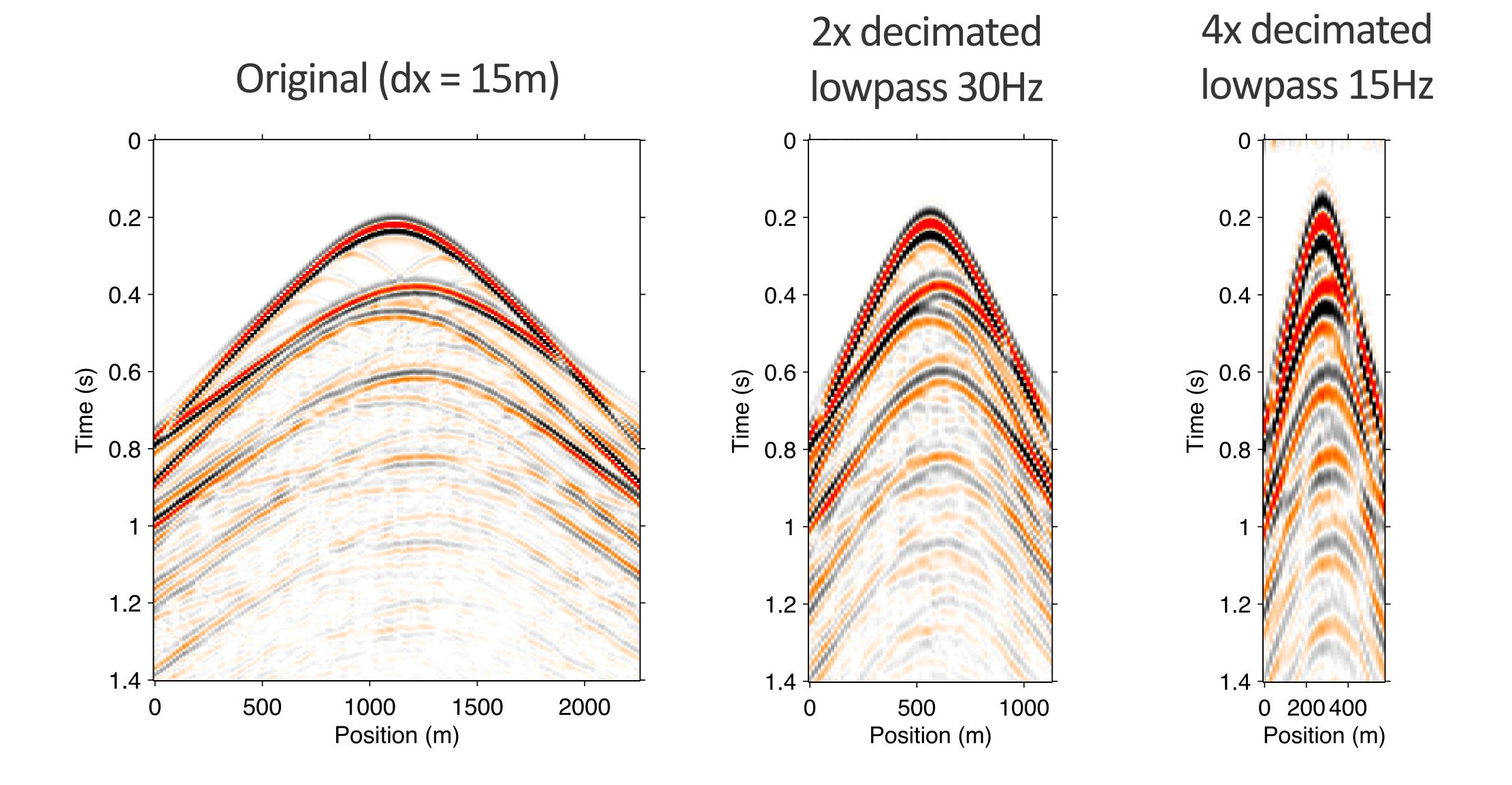


REPSI primary IR

from low-passed data @ 40Hz

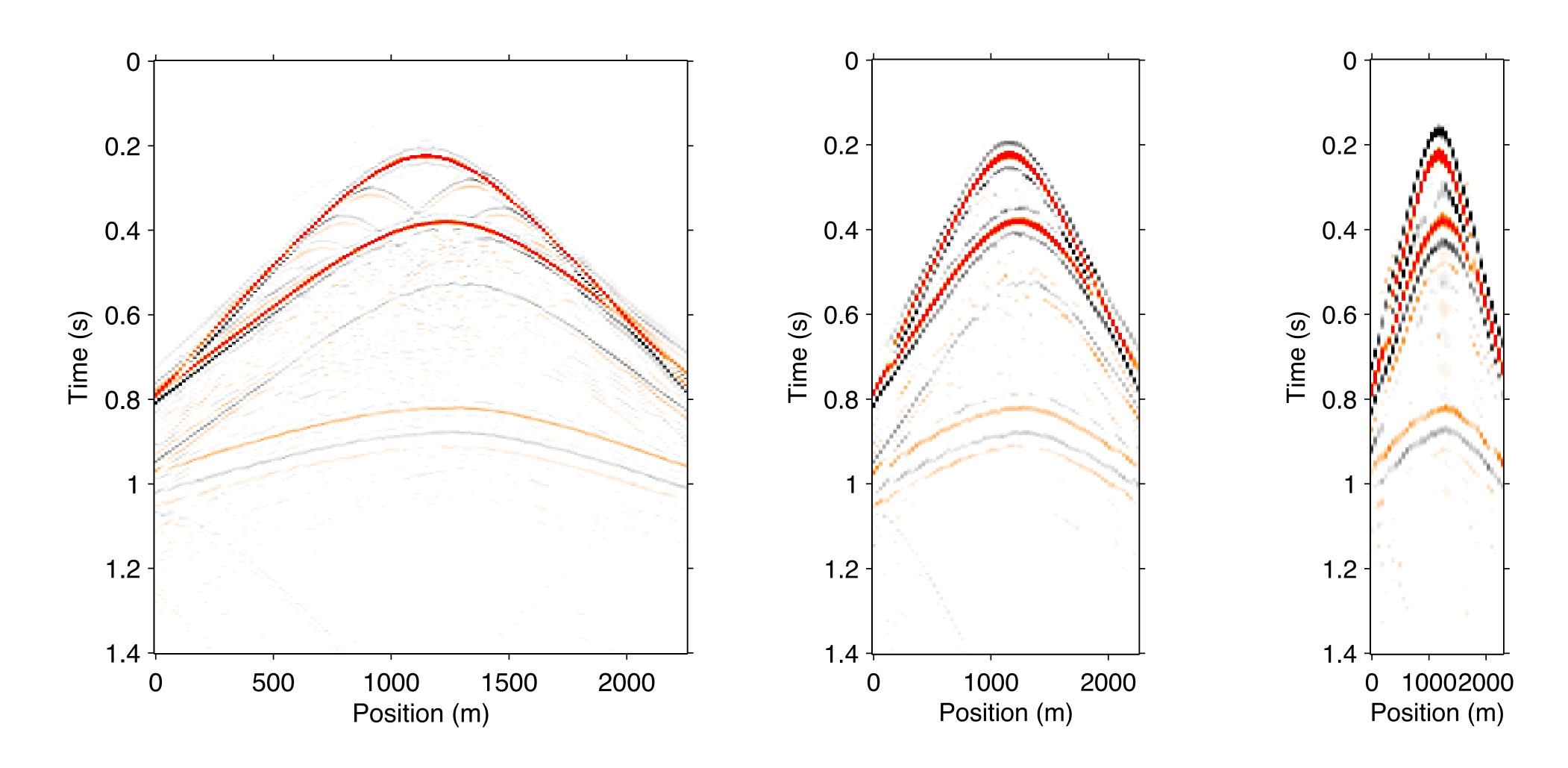


Lowpass data permits coarser sampling w/o aliasing

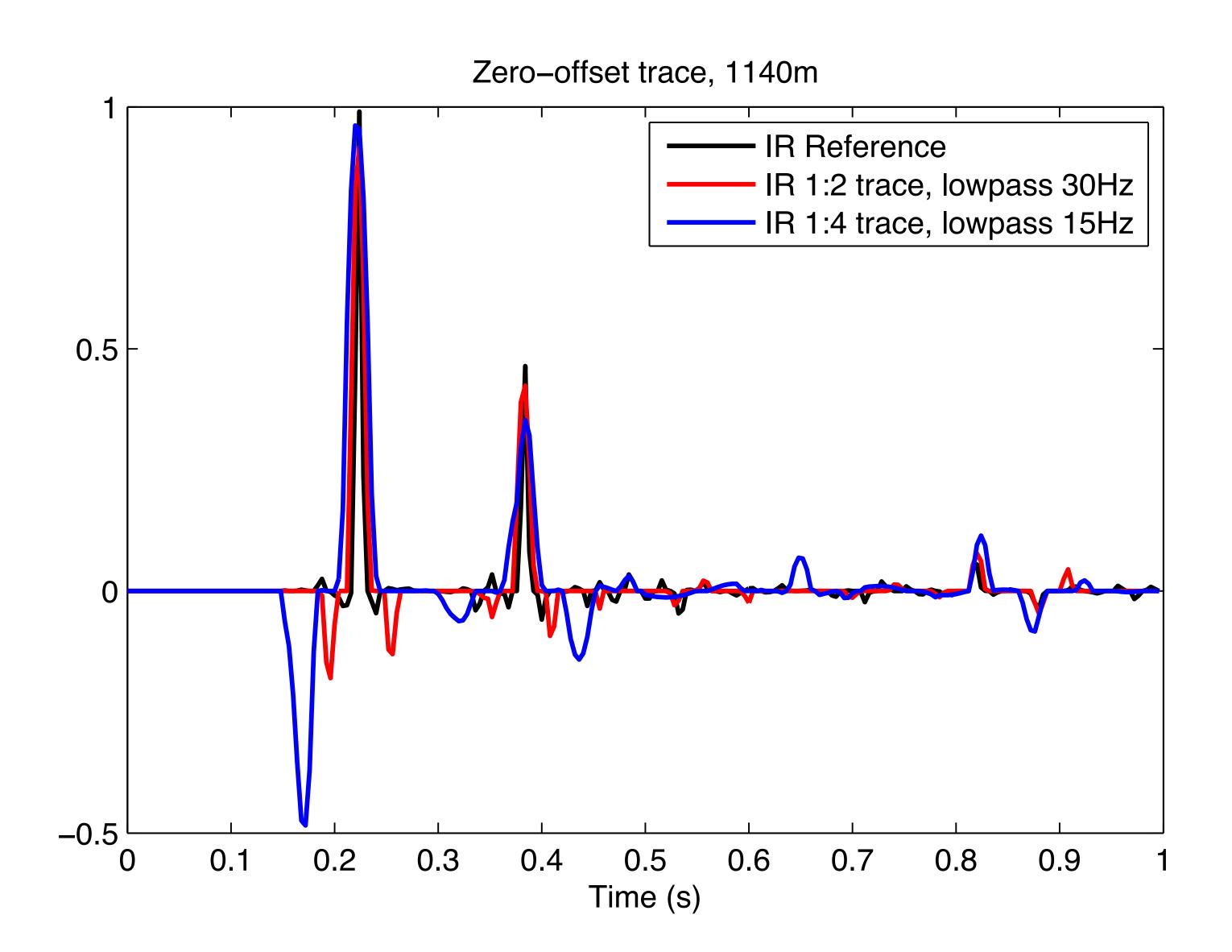


Lowpass data permits coarser sampling w/o aliasing

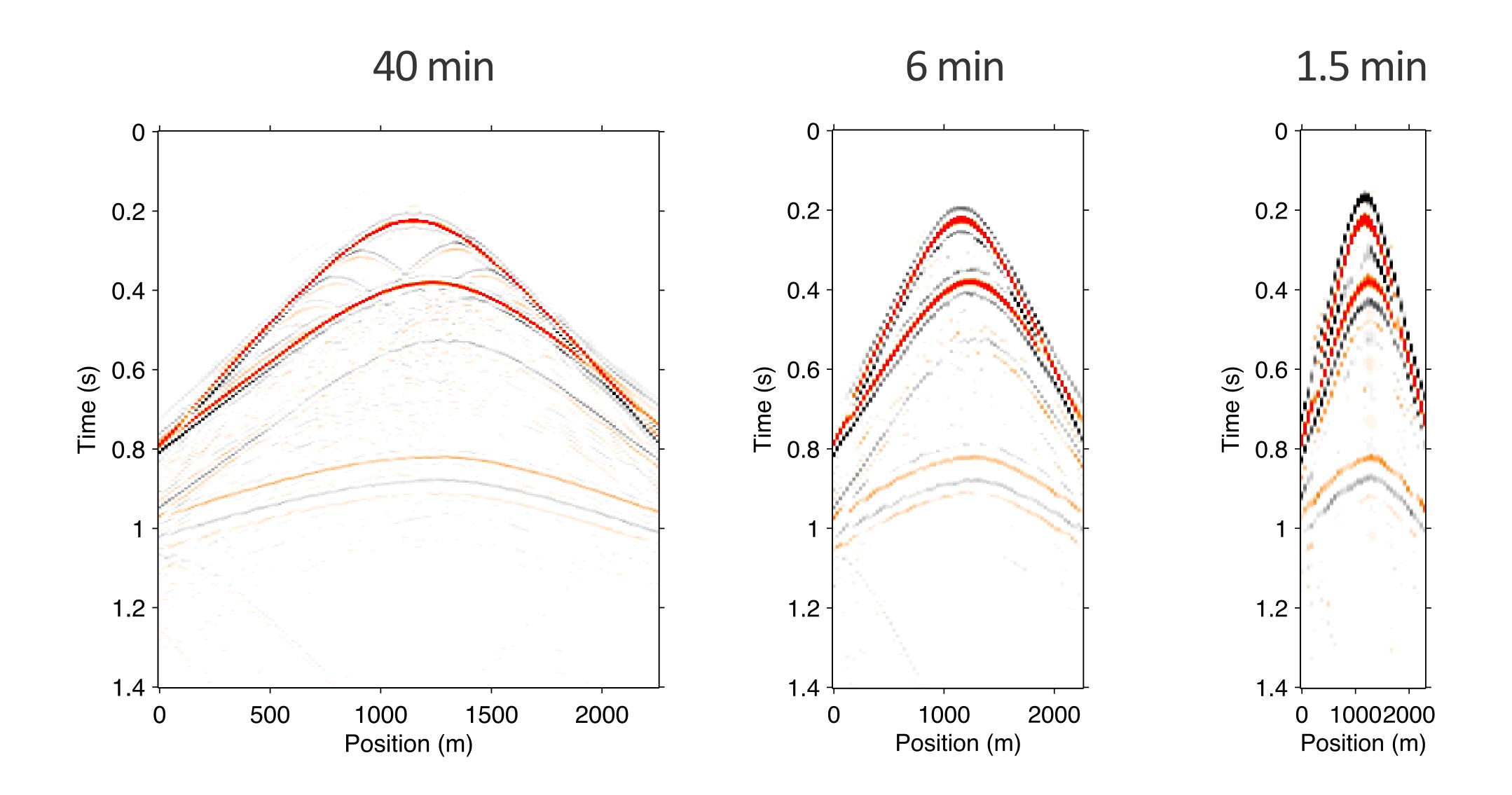
Impulse response solutions



Lowpass data permits coarser sampling w/o aliasing



Lowpass data permits coarser sampling w/o aliasing (much faster!)





Multilevel strategy for EPSI

warm-start fine-scale problem with coarse-scale solutions



Idea: Warm-start with coarse-scale solutions

EPSI takes **70-100 iterations** to converge (each iteration is doing 2 SRME multiple prediction), can we make it **FASTER**?

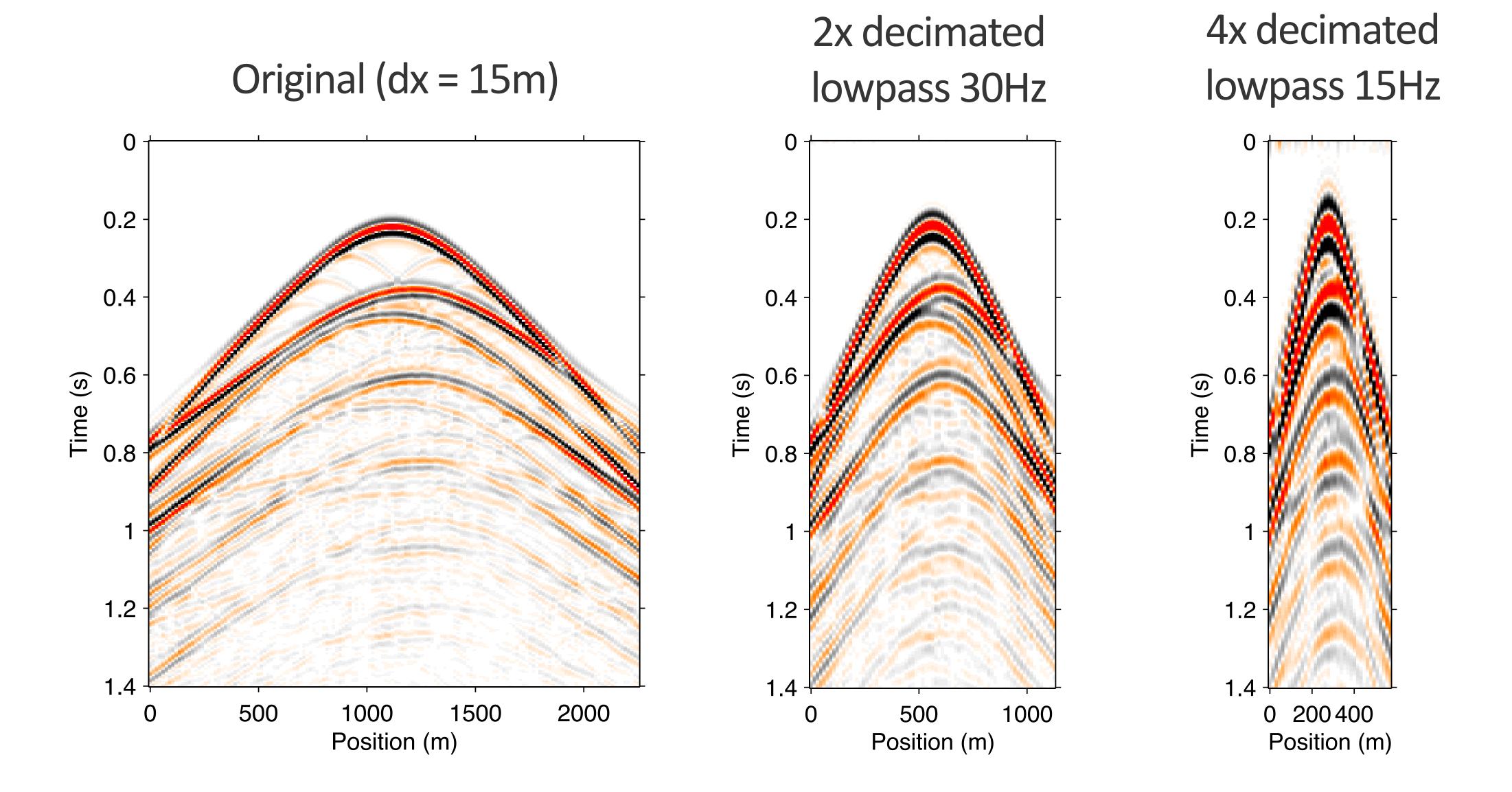
Since decimated datasets solve much faster, we interpolate its (slightly inaccurate) G for the initial estimate to full problem

Previous Q is discarded

Interpolation method of G not important, just can't alias. Simple constant NMO (i.e., at water velocity) + linear interpolation works fine

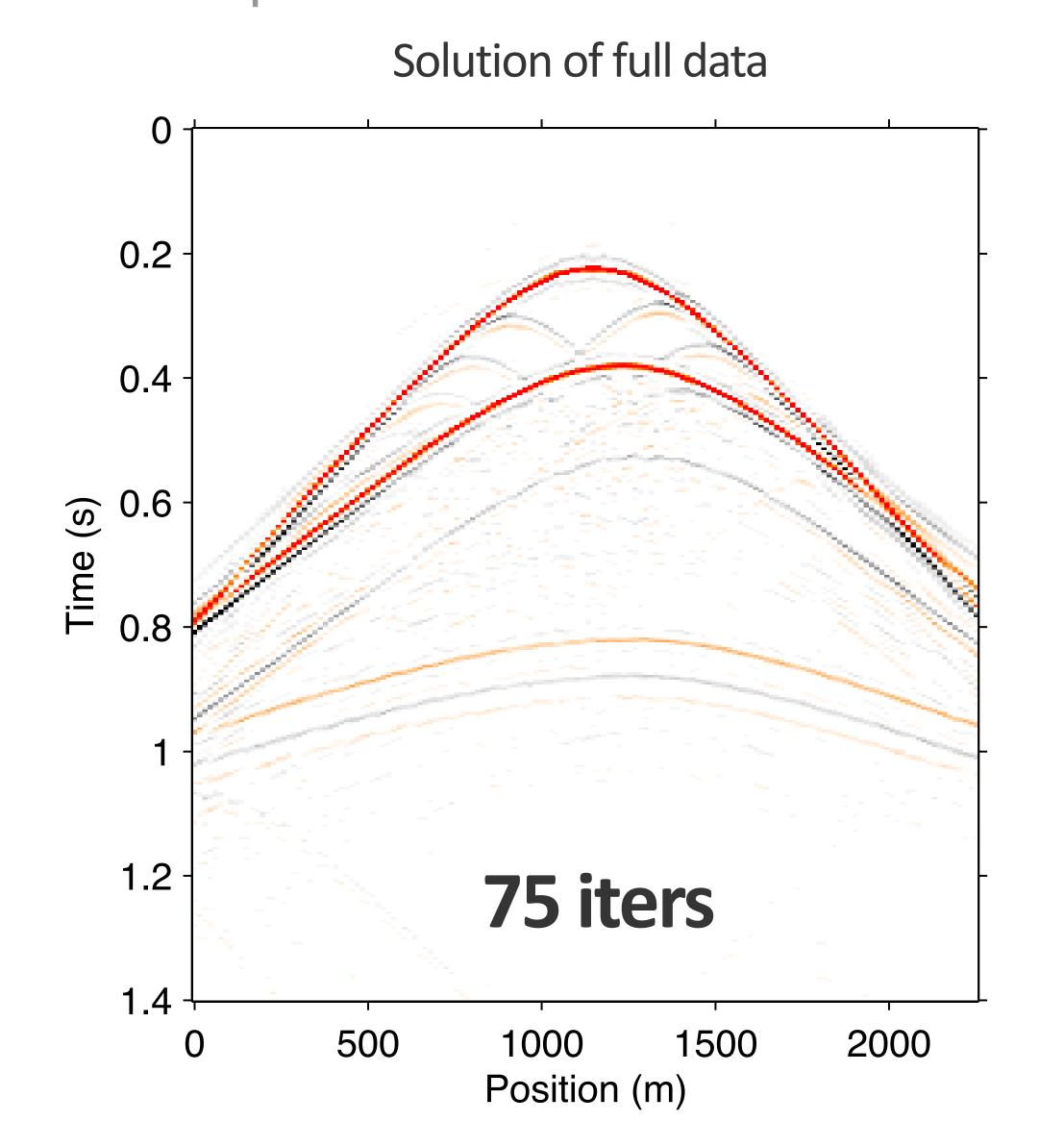


Warm-starting/continuation from coarse solution Example

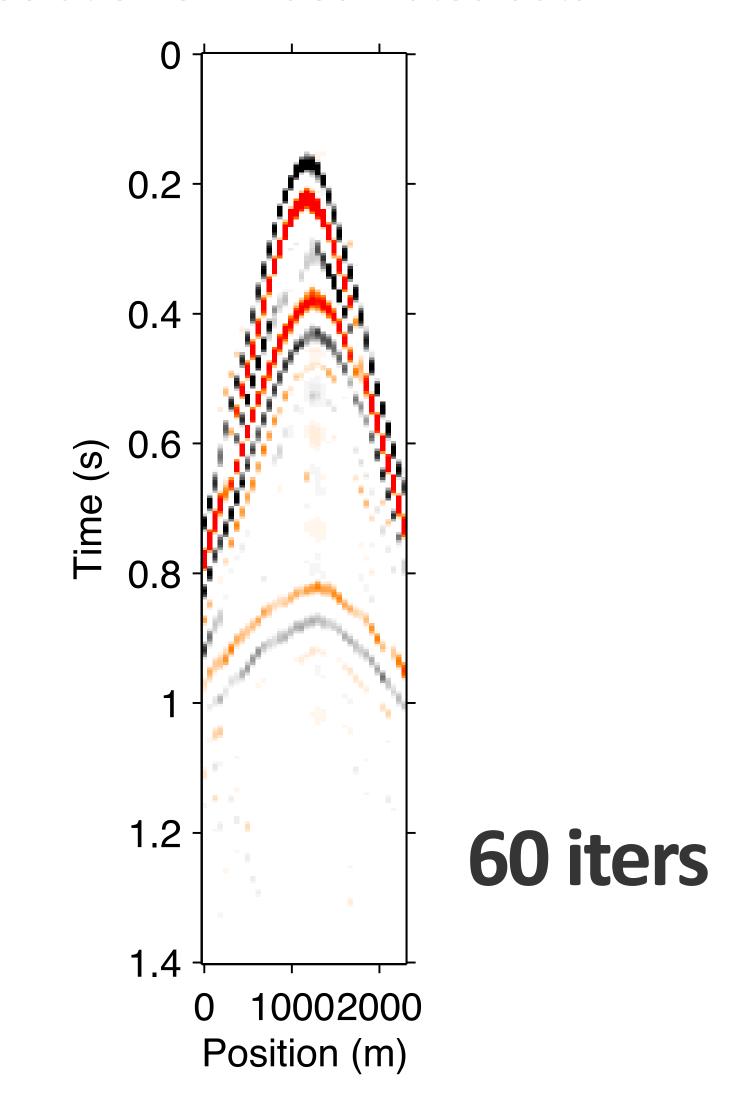




Warm-starting/continuation from coarse solution Example

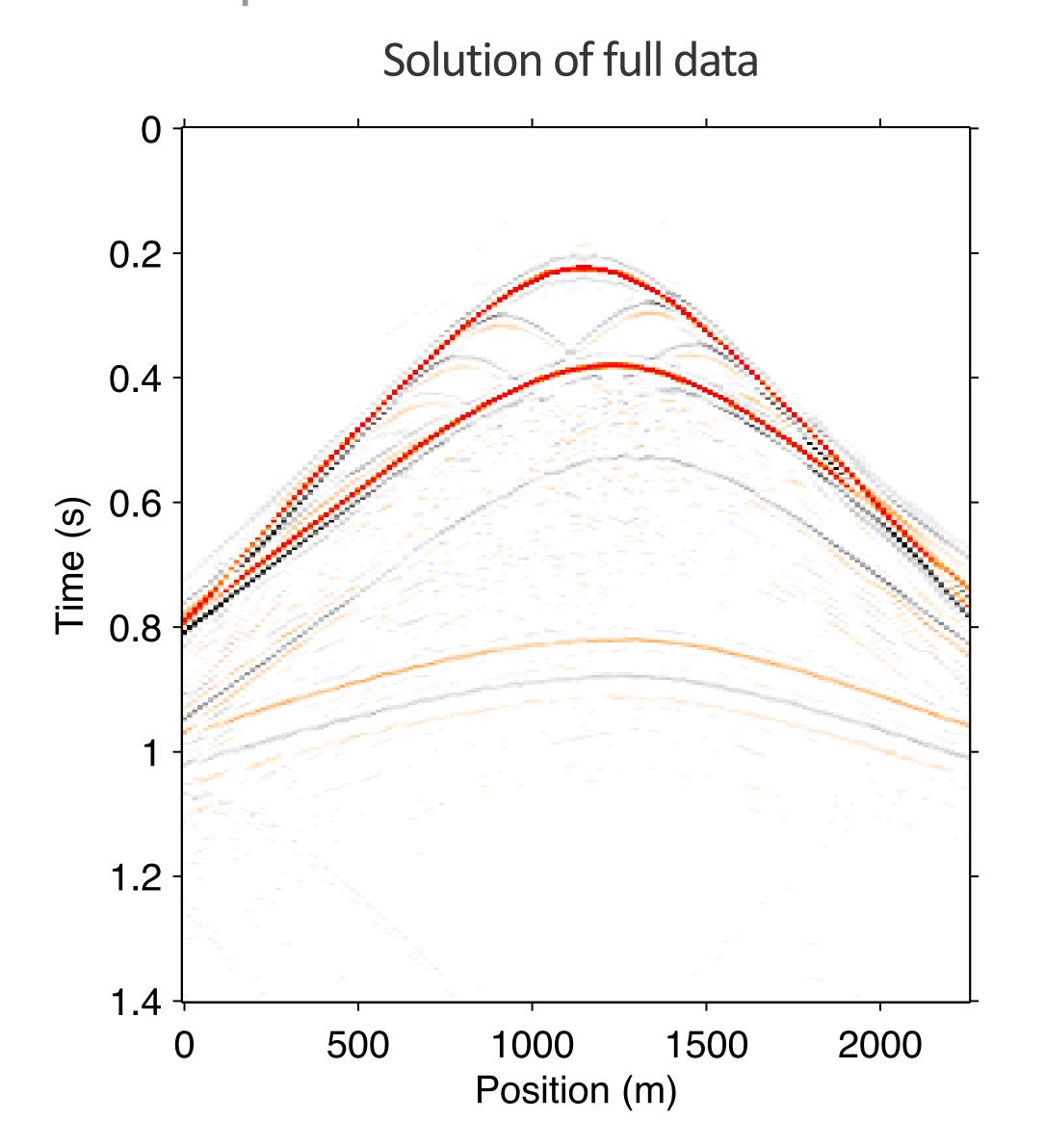




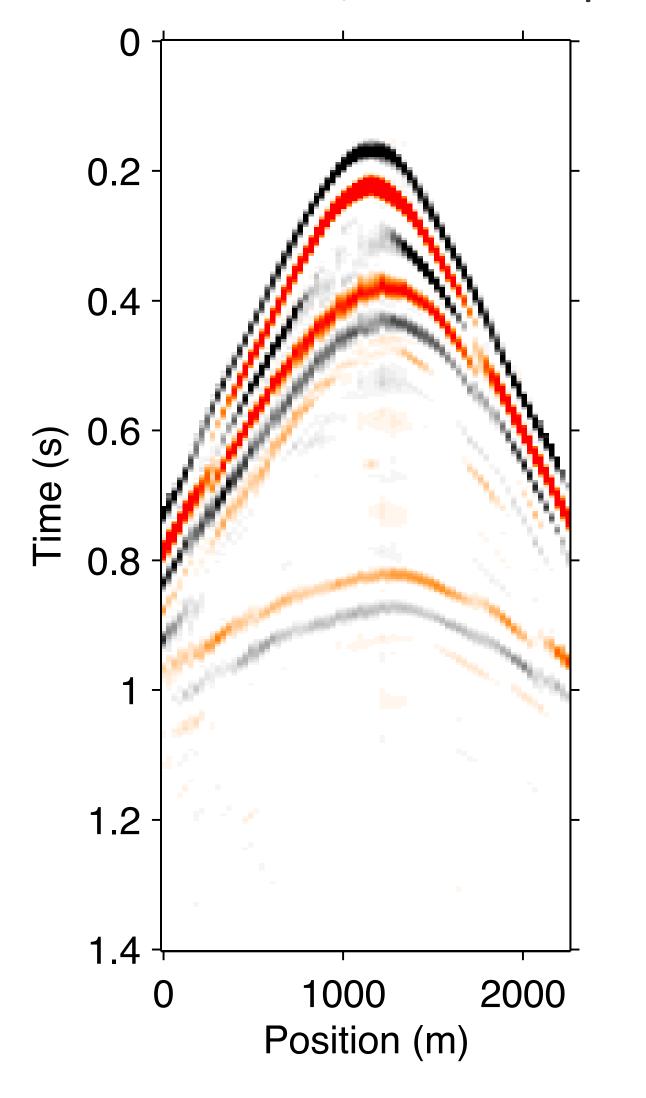




Example

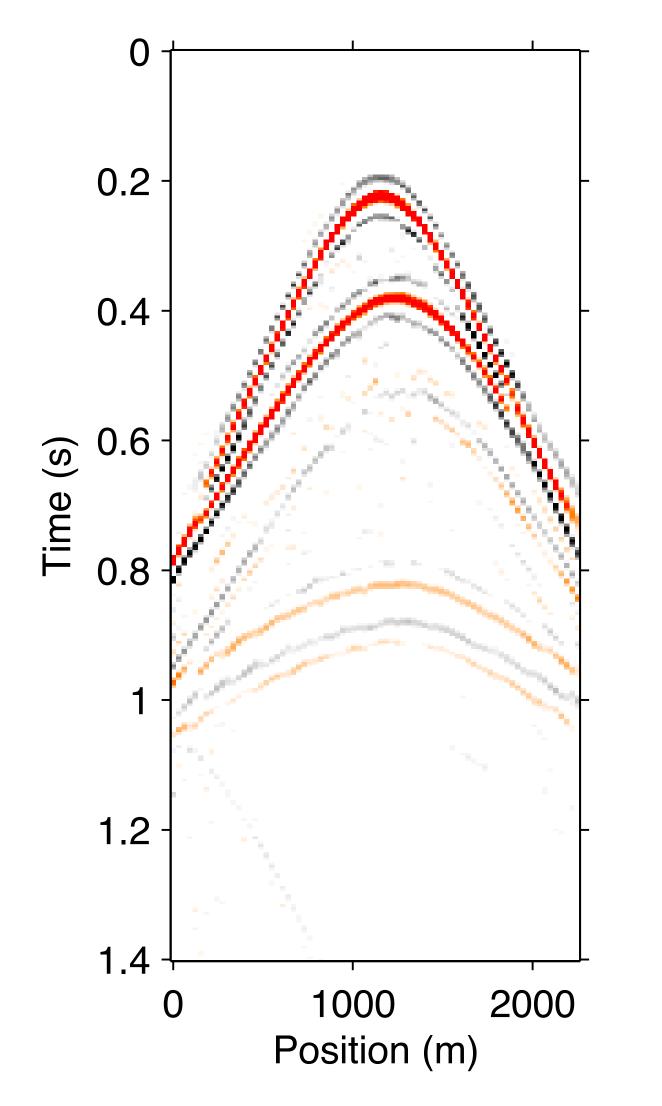


Solution of 4x decimated data 1600m/s NMO, linear interp 2x

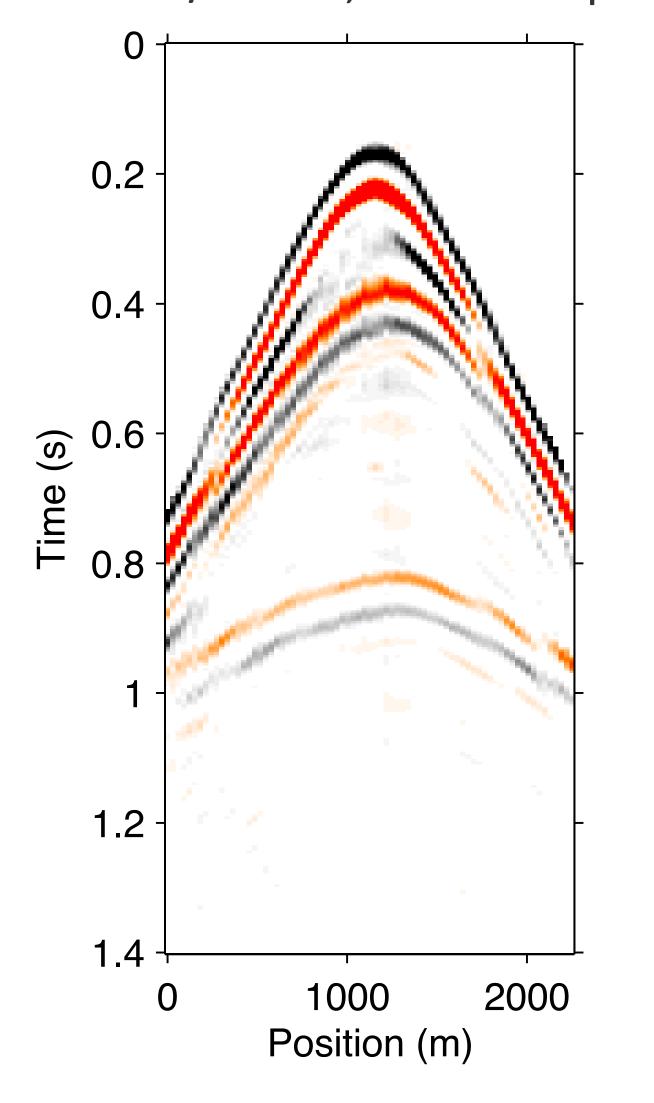




Solution of 2x decimated data

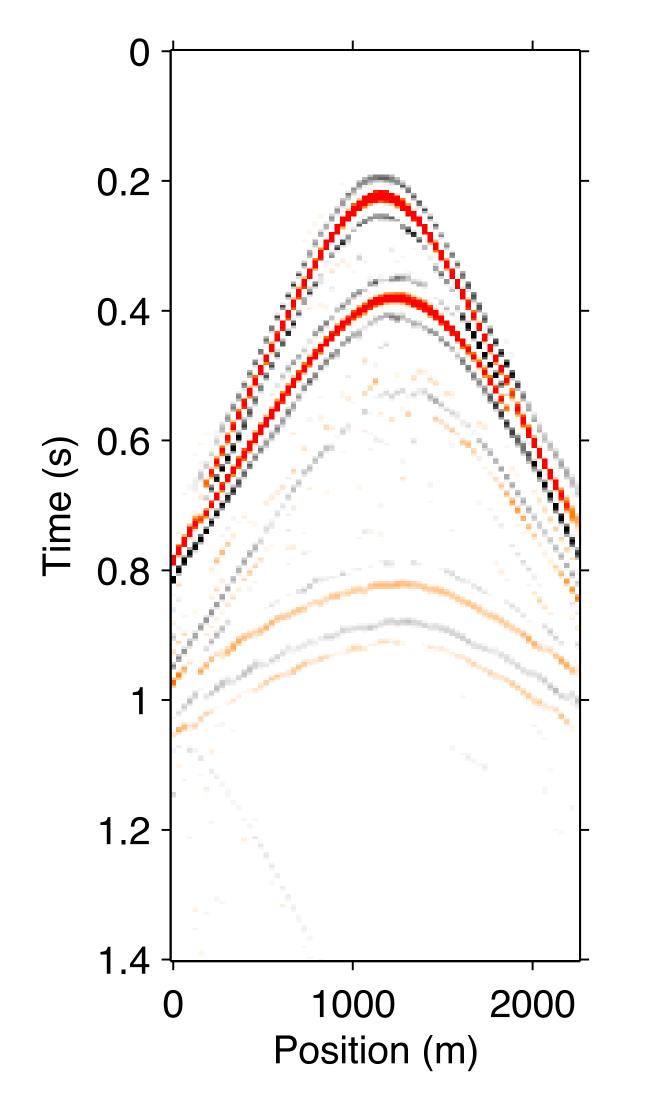


Solution of 4x decimated data 1600m/s NMO, linear interp 2x

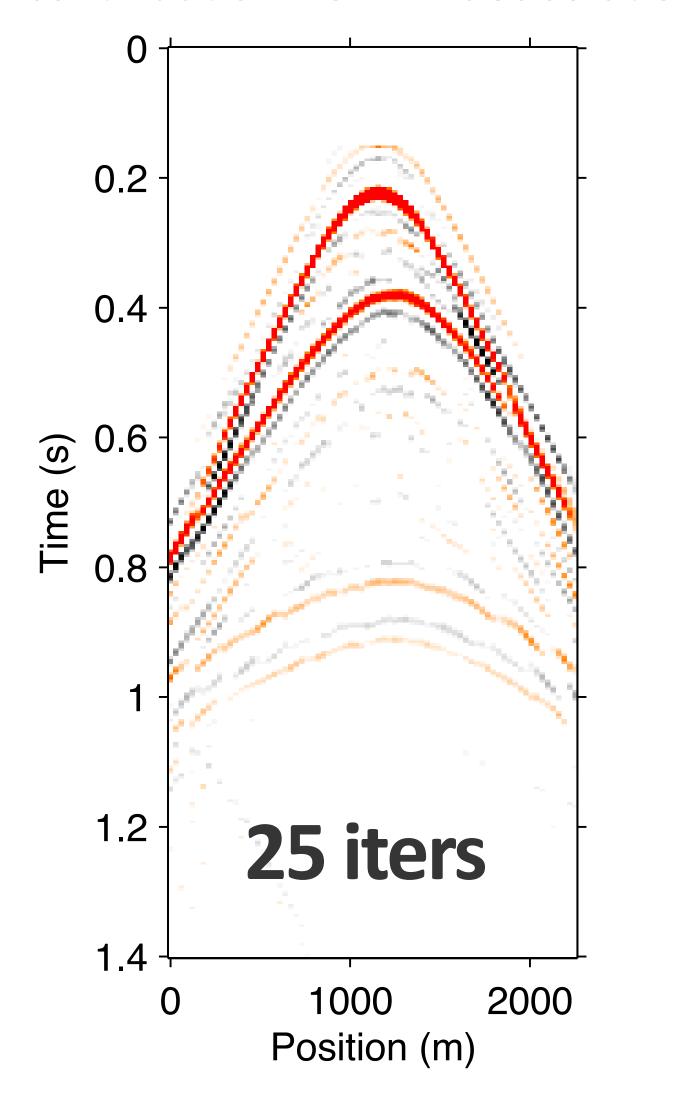




Solution of 2x decimated data

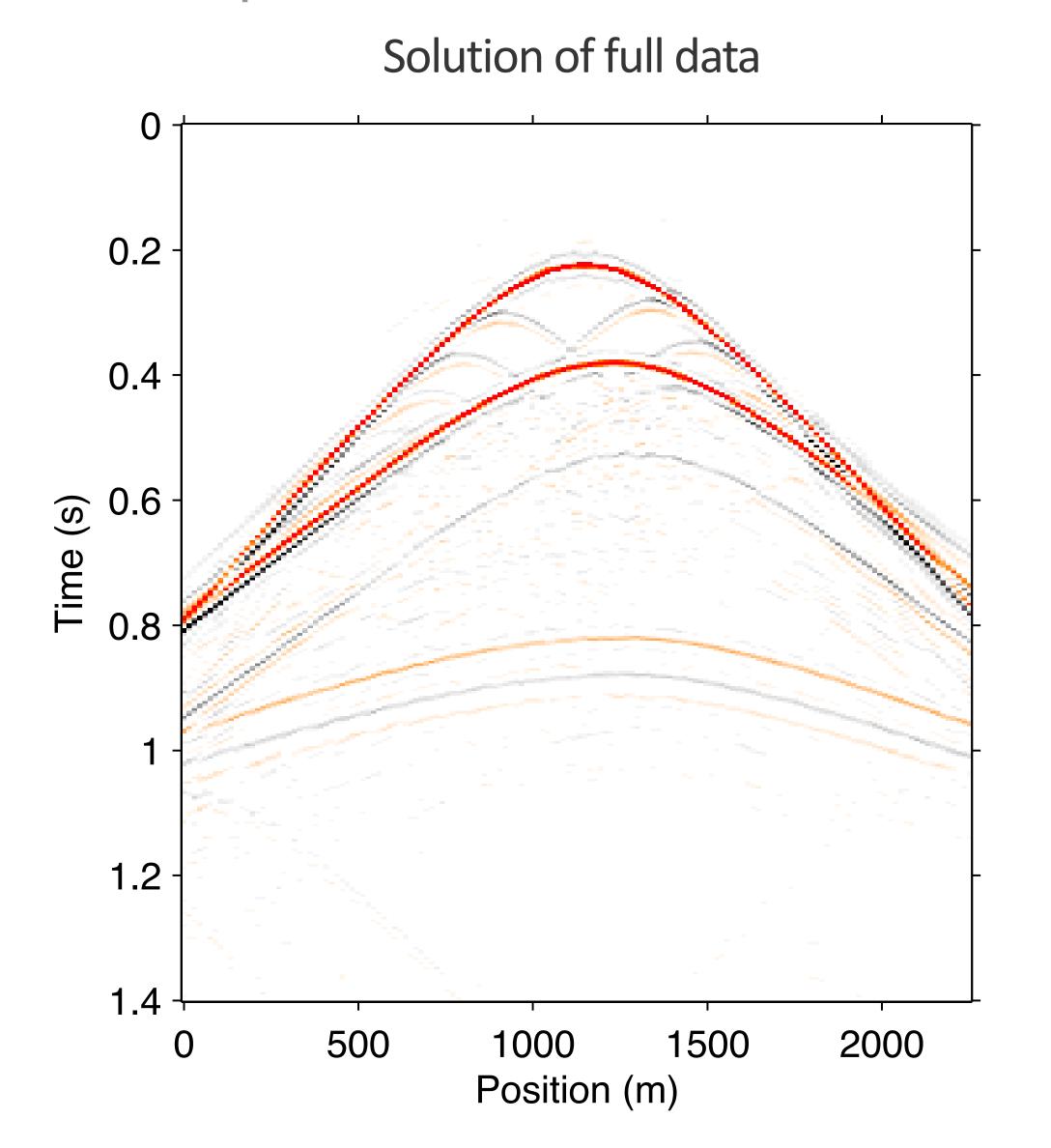


Solution on 2x dec data continuation from 4x dec solution

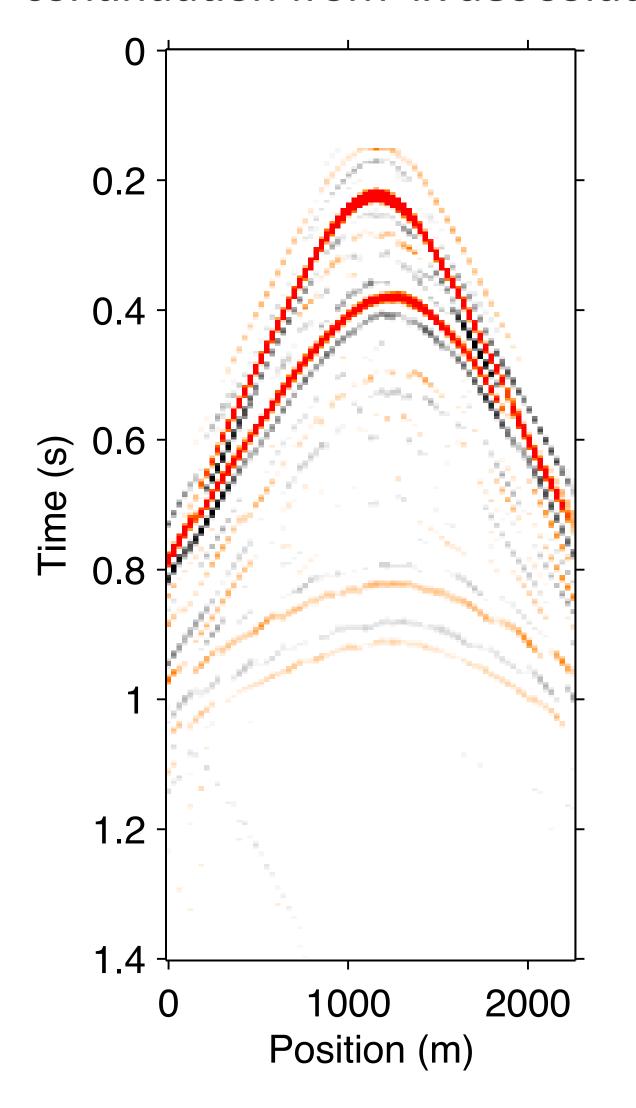




Example

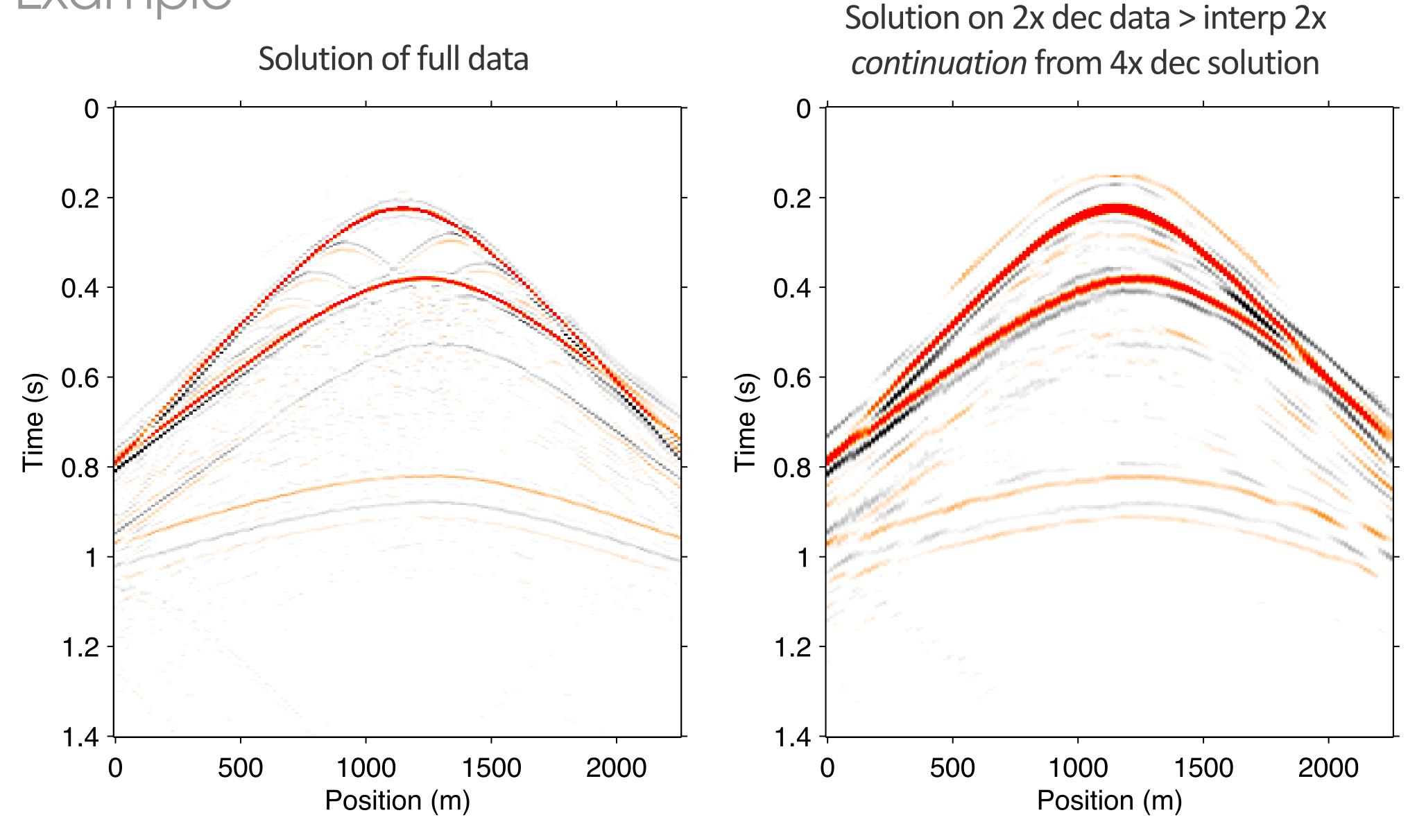


Solution on 2x dec data continuation from 4x dec solution



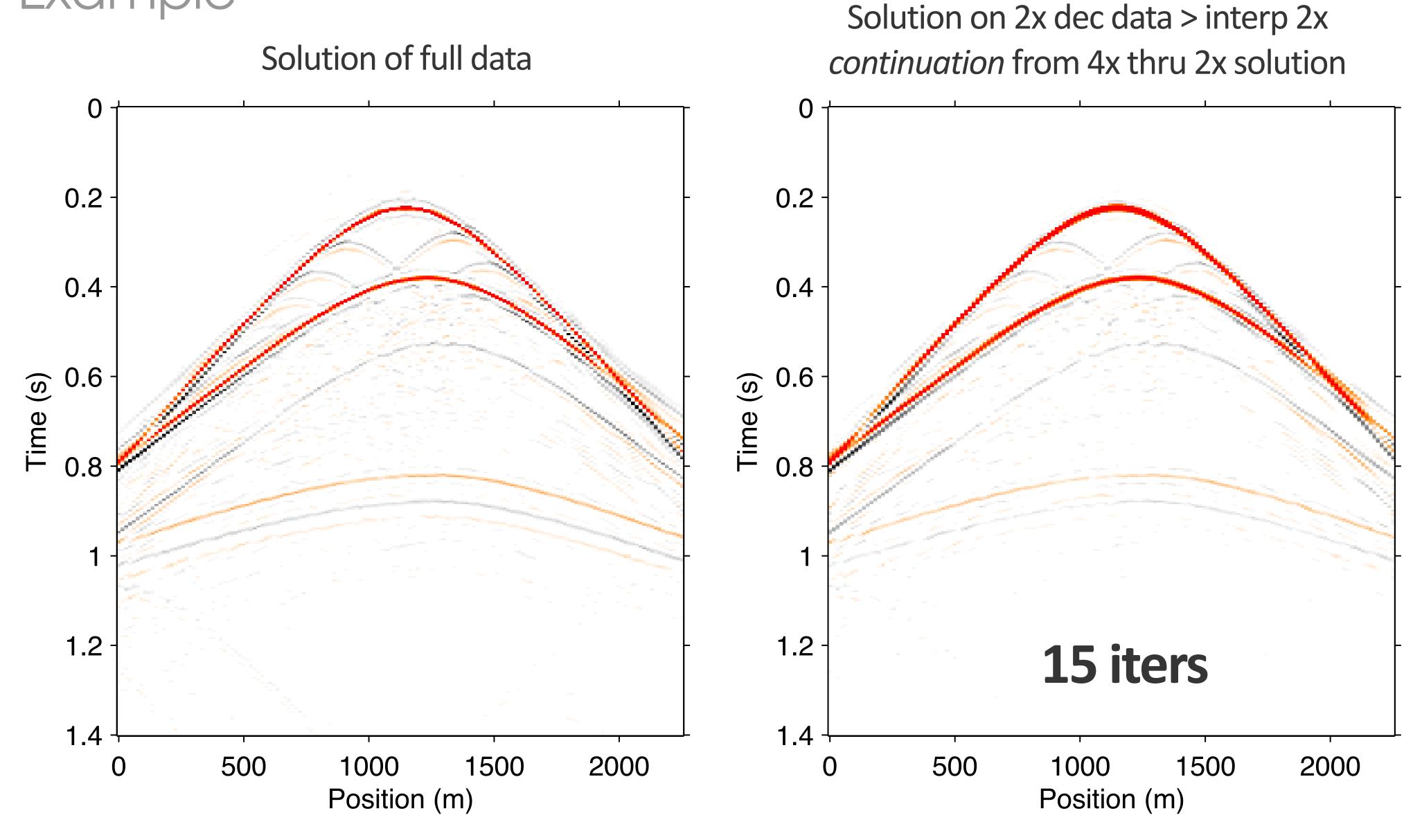


Example

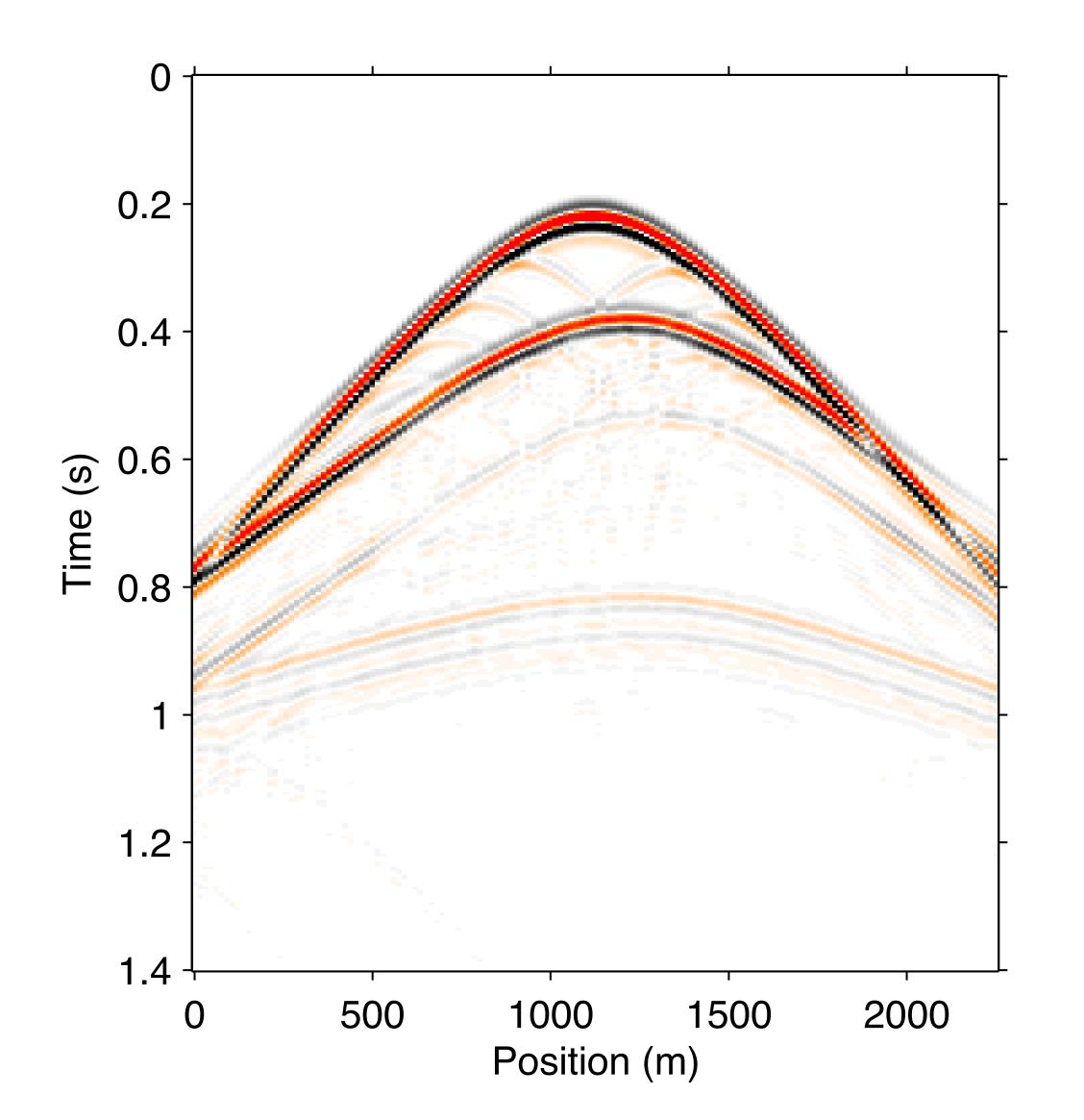




Example



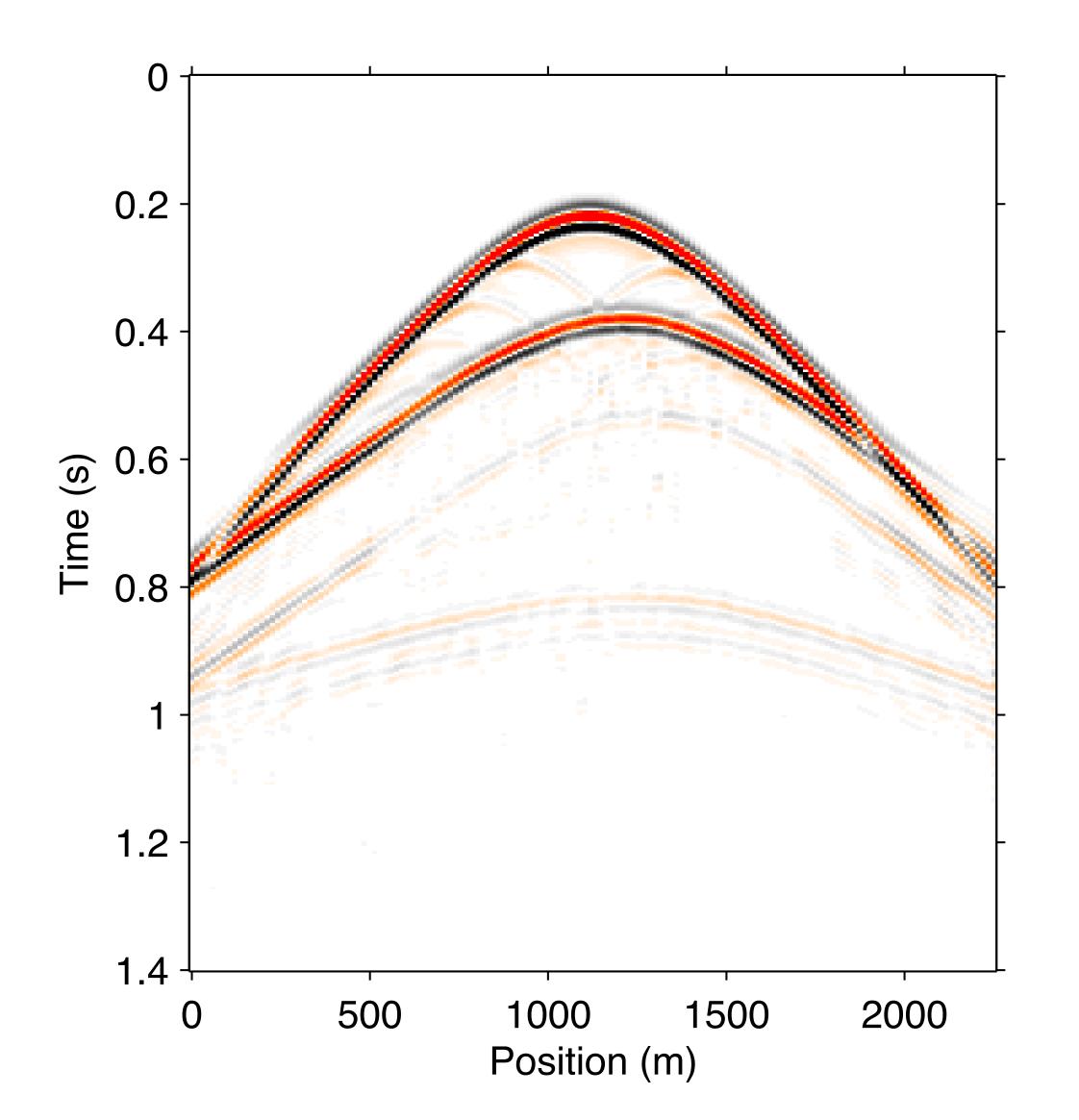




Direct Primary

Solved with plain algorithm from finest scale data

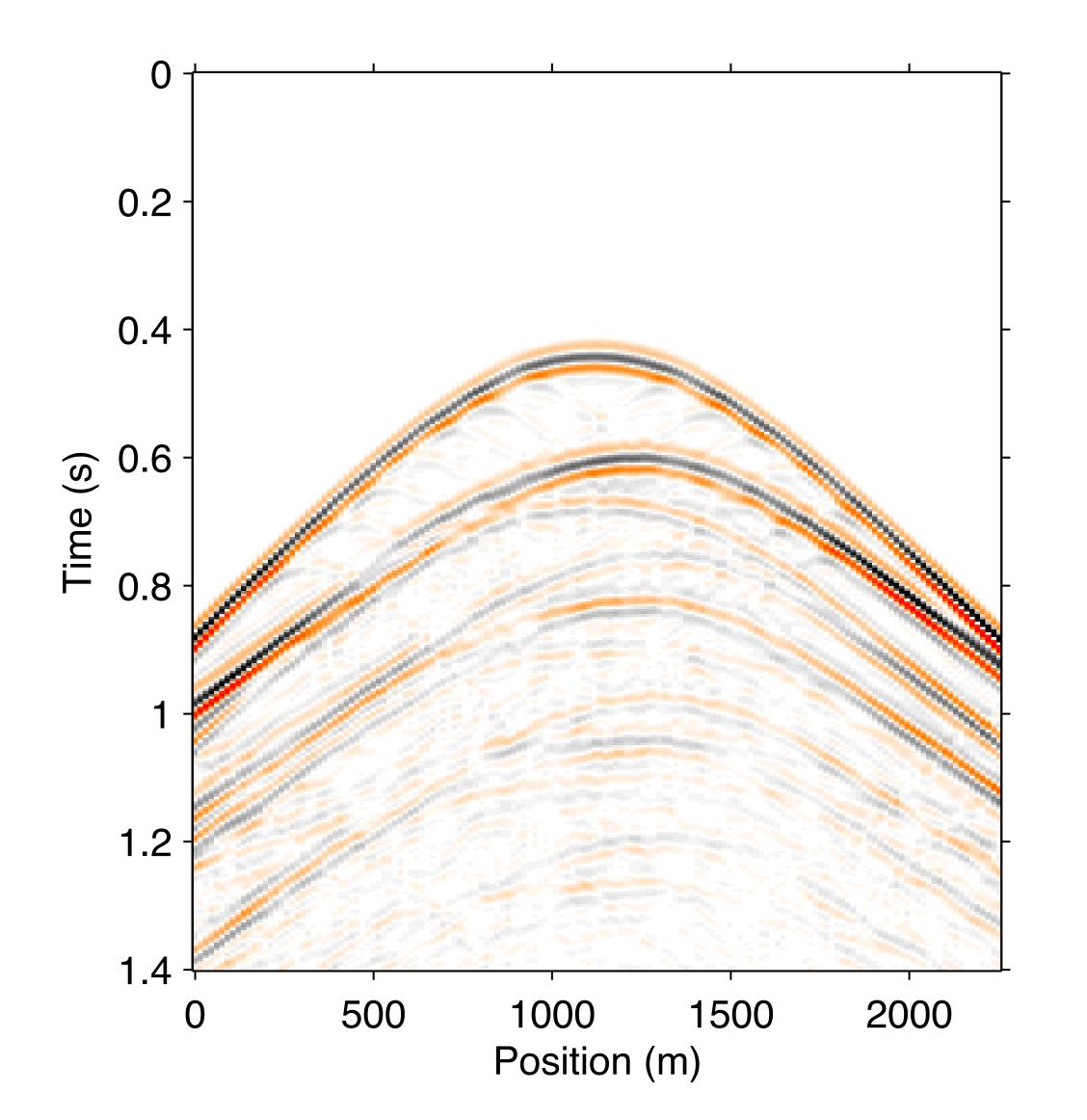




Direct Primary

Solved with spatial sampling continuation dx = 60m > 30m > 15m

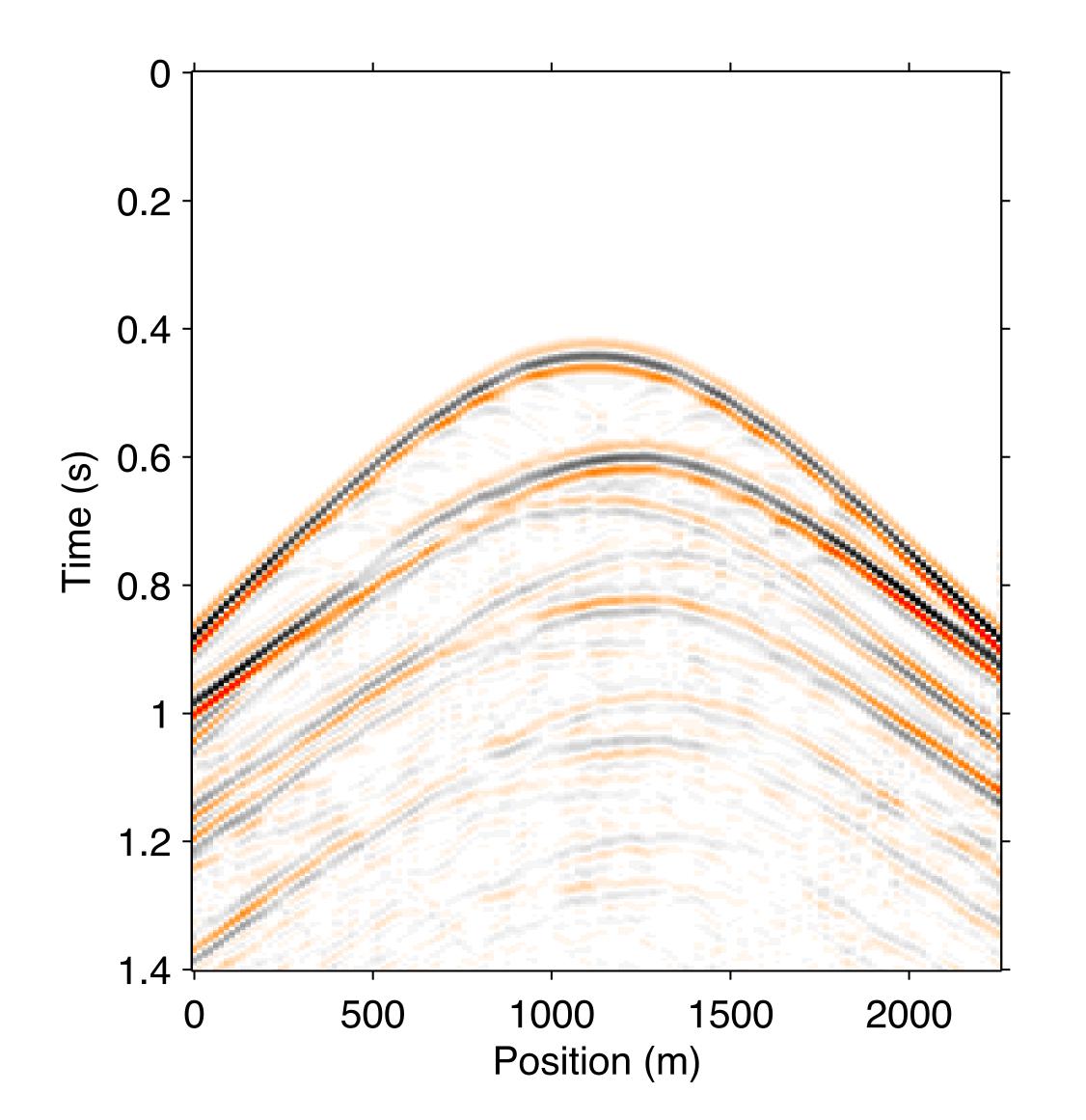




Predicted Surface Multiple

Solved with plain algorithm from finest scale data





Predicted Surface Multiple

Solved with spatial sampling continuation

$$dx = 60m > 30m > 15m$$

Significant speedup from bootstrapping (in 2D)

Per-iteration FLOPs cost (one forward/adjoint): $n=n_{
m rcv}=n_{
m src}$

$$\label{eq:cost} \begin{aligned} \mathsf{Cost}(n) &= \mathcal{O}(2n_t n^2 \log n_t) + \mathcal{O}(n_f n^3) \\ &\quad \mathsf{2\,times\,FFT} \end{aligned} \quad \text{computing\,MCG\,\&\,sum\,in\,FX}$$

$$\operatorname{Cost}\left(\frac{1}{2}n\right) = \frac{1}{4}\mathcal{O}(2n_t n^2 \log n_t) + \frac{1}{8}\mathcal{O}(n_f n^3)$$

$$\operatorname{Cost}\left(\frac{1}{4}n\right) = \frac{1}{16}\mathcal{O}(2n_t n^2 \log n_t) + \frac{1}{64}\mathcal{O}(n_f n^3)$$

Significant speedup from bootstrapping (in 2D)

Per-iteration FLOPs cost (one forward/adjoint): $n=n_{
m rcv}=n_{
m src}$

$$\label{eq:cost} \begin{aligned} \mathsf{Cost}(n) &= \mathcal{O}(2n_t n^2 \log n_t) + \mathcal{O}(n_f n^3) \\ &\quad \mathsf{2\,times\,FFT} \end{aligned} \quad \text{computing\,MCG\,\&\,sum\,in\,FX}$$

$$\operatorname{Cost}\left(\frac{1}{2}n, \frac{1}{2}n_f\right) = \frac{1}{4}\mathcal{O}(2n_t n^2 \log n_t) + \frac{1}{16}\mathcal{O}(n_f n^3)$$

Cost
$$\left(\frac{1}{4}n, \frac{1}{4}n_f\right) = \frac{1}{16}\mathcal{O}(2n_t n^2 \log n_t) + \frac{1}{128}\mathcal{O}(n_f n^3)$$

Significant speedup from bootstrapping (in 3D)

Per-iteration FLOPs cost (one forward/adjoint): $n=nx_{\rm rcv}=ny_{\rm rcv}=nx_{\rm src}=ny_{\rm src}$

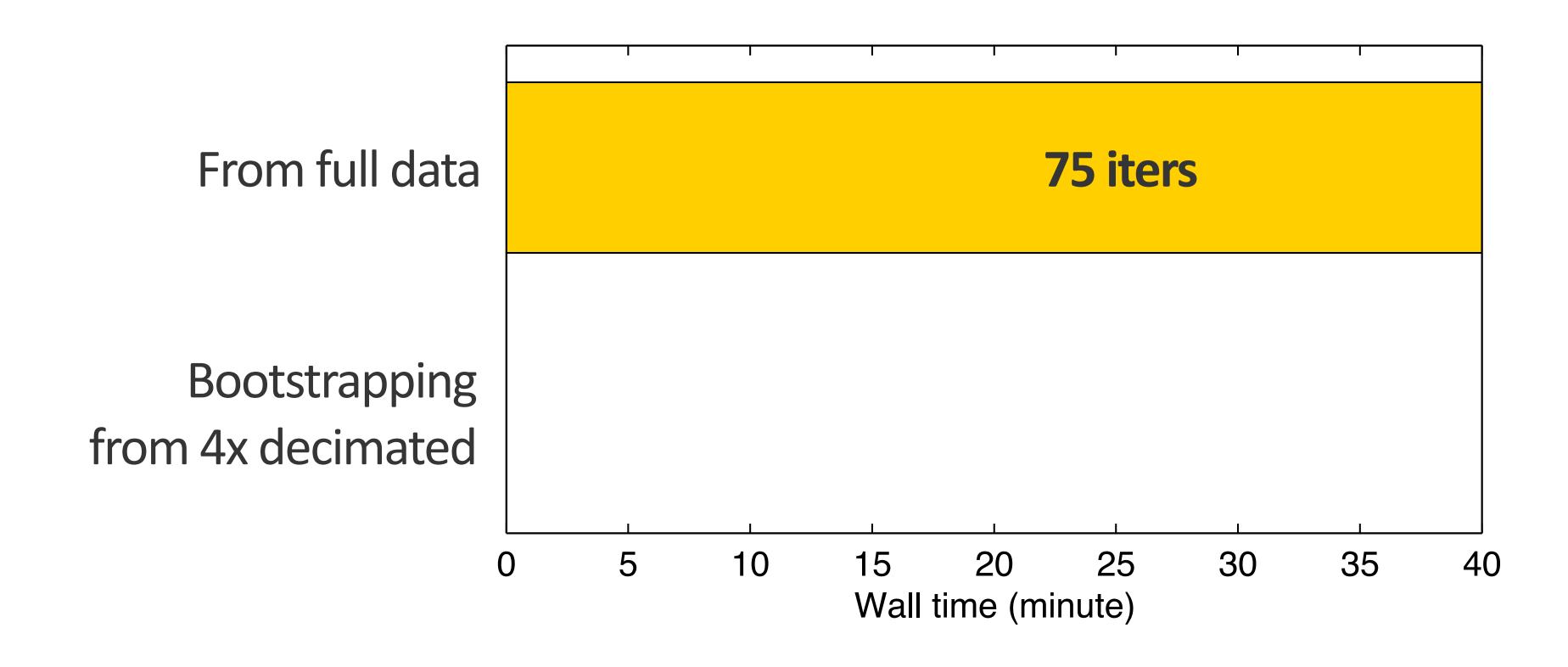
$$\label{eq:cost} \mathsf{Cost}(n) = \mathcal{O}(2n_t n^4 \log n_t) + \mathcal{O}(n_f n^6)$$

$$\text{2 times FFT} \qquad \text{computing MCG \& sum in FX}$$

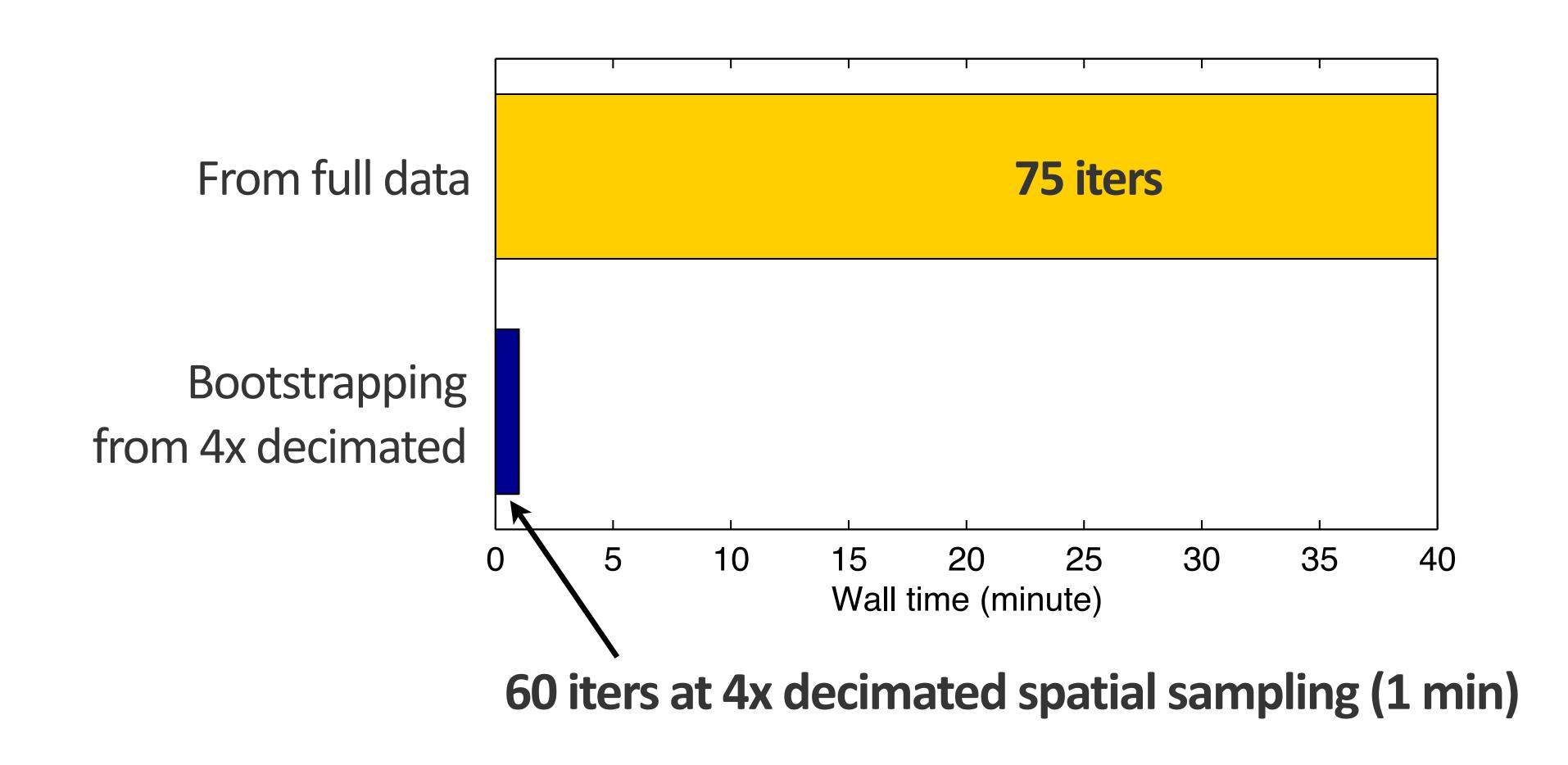
Cost
$$\left(\frac{1}{2}n, \frac{1}{2}n_f\right) = \frac{1}{16}\mathcal{O}(2n_t n^4 \log n_t) + \frac{1}{128}\mathcal{O}(n_f n^6)$$

$$\operatorname{Cost}\left(\frac{1}{4}n, \frac{1}{4}n_f\right) = \frac{1}{256}\mathcal{O}(2n_t n^4 \log n_t) + \frac{1}{8192}\mathcal{O}(n_f n^6)$$

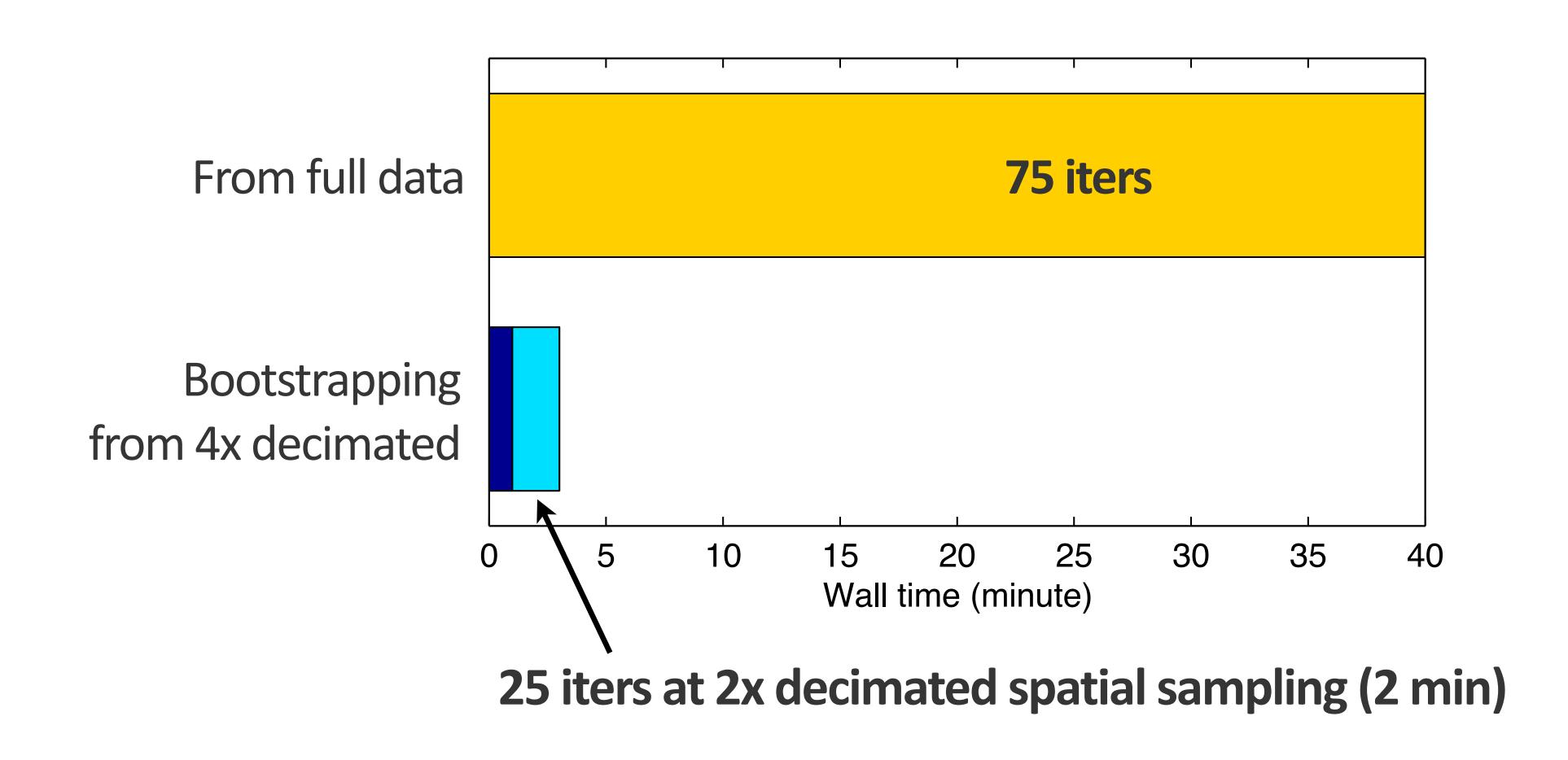




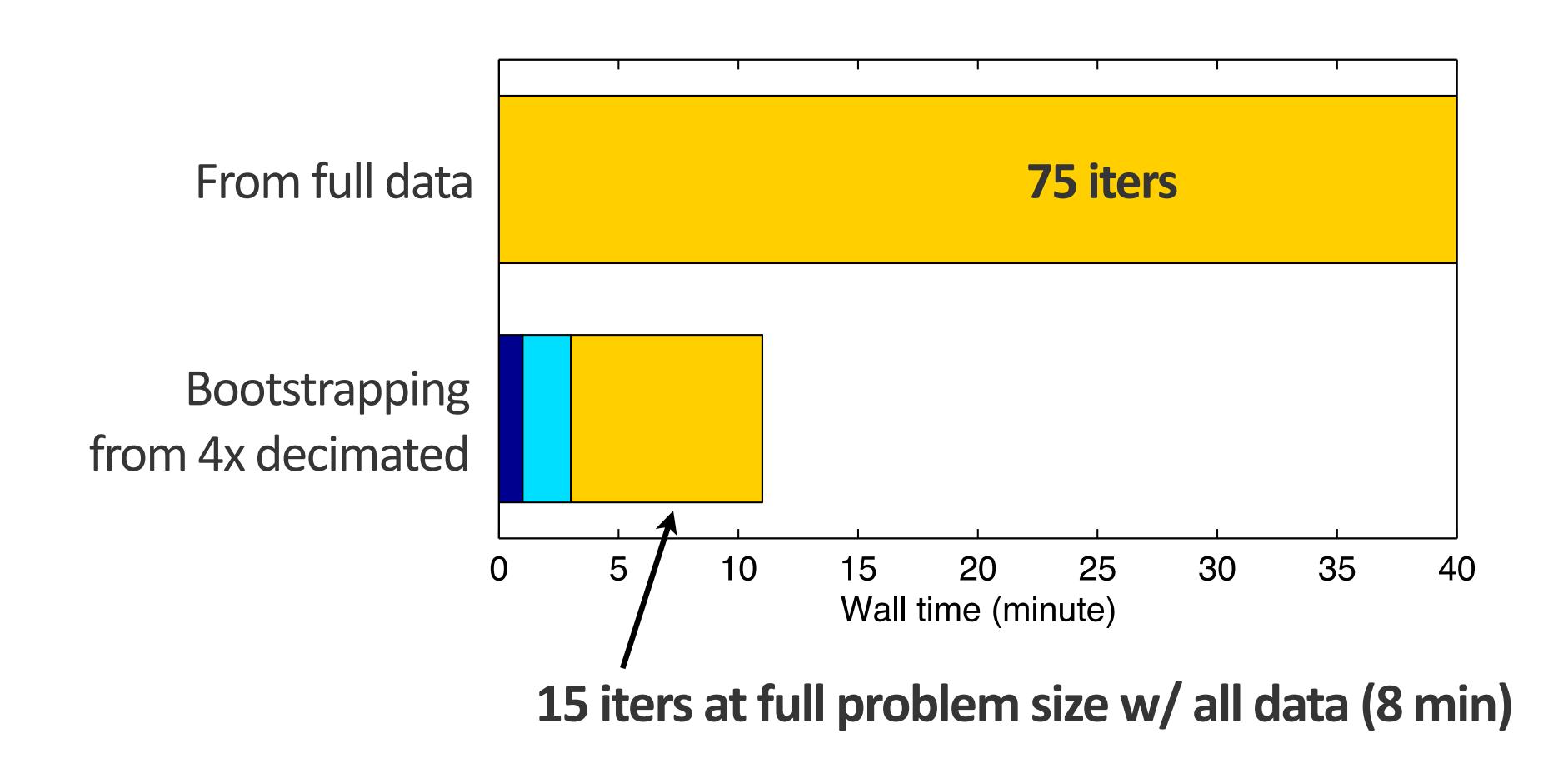




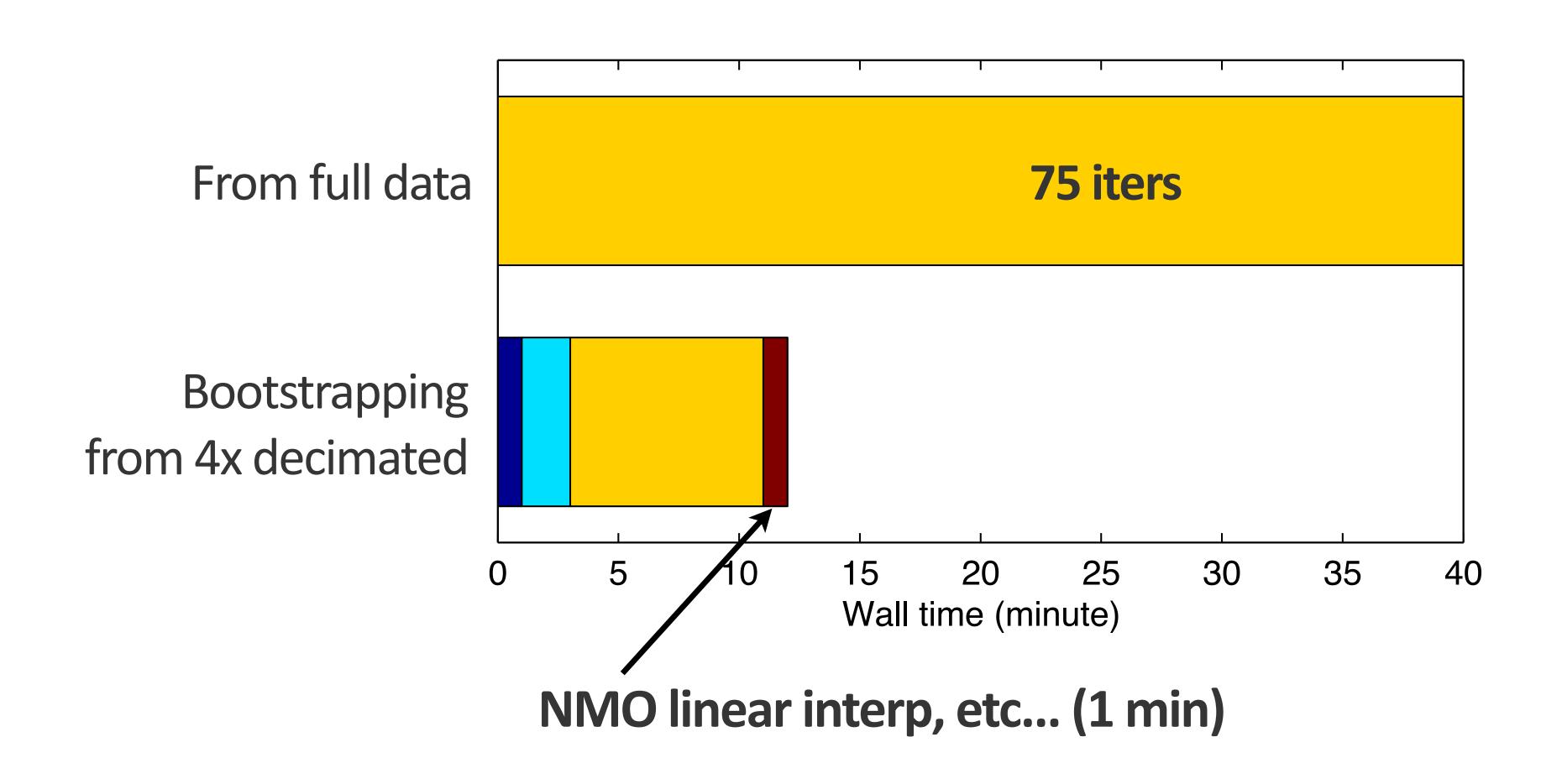




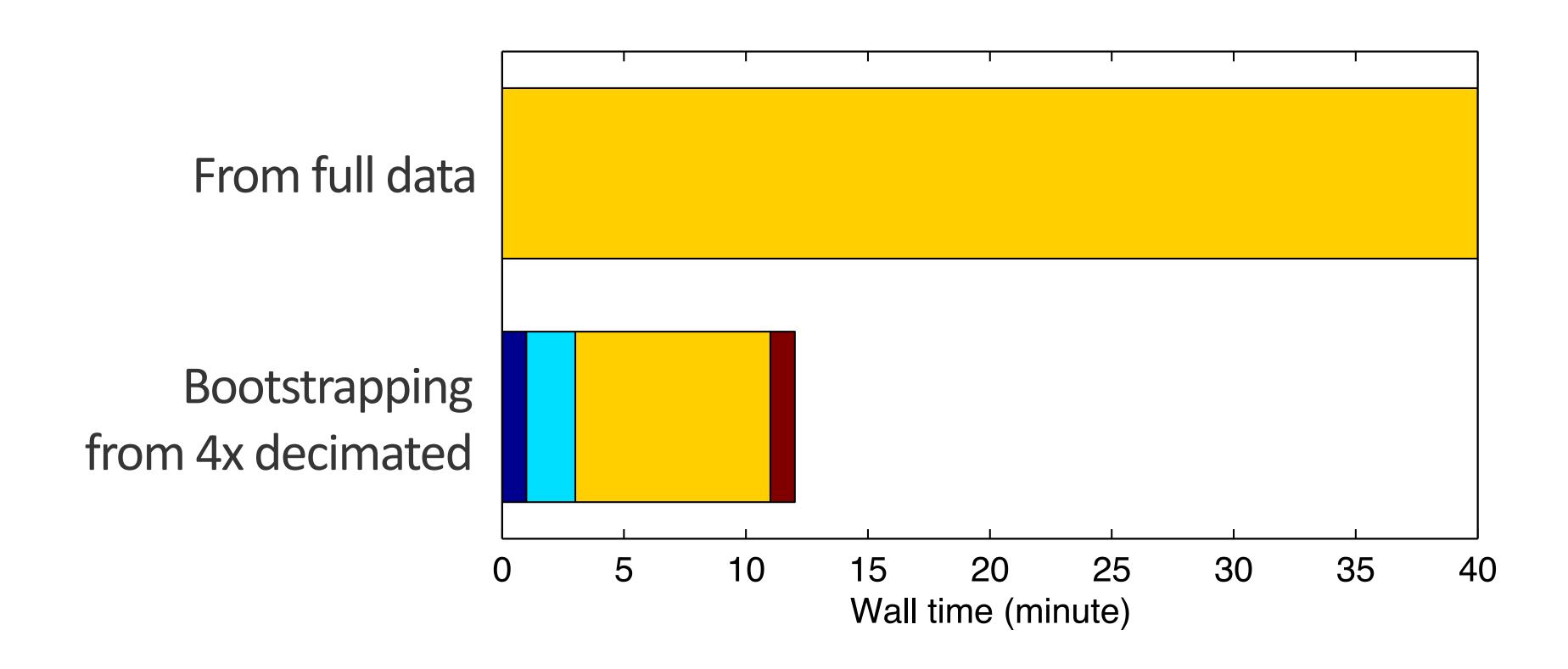










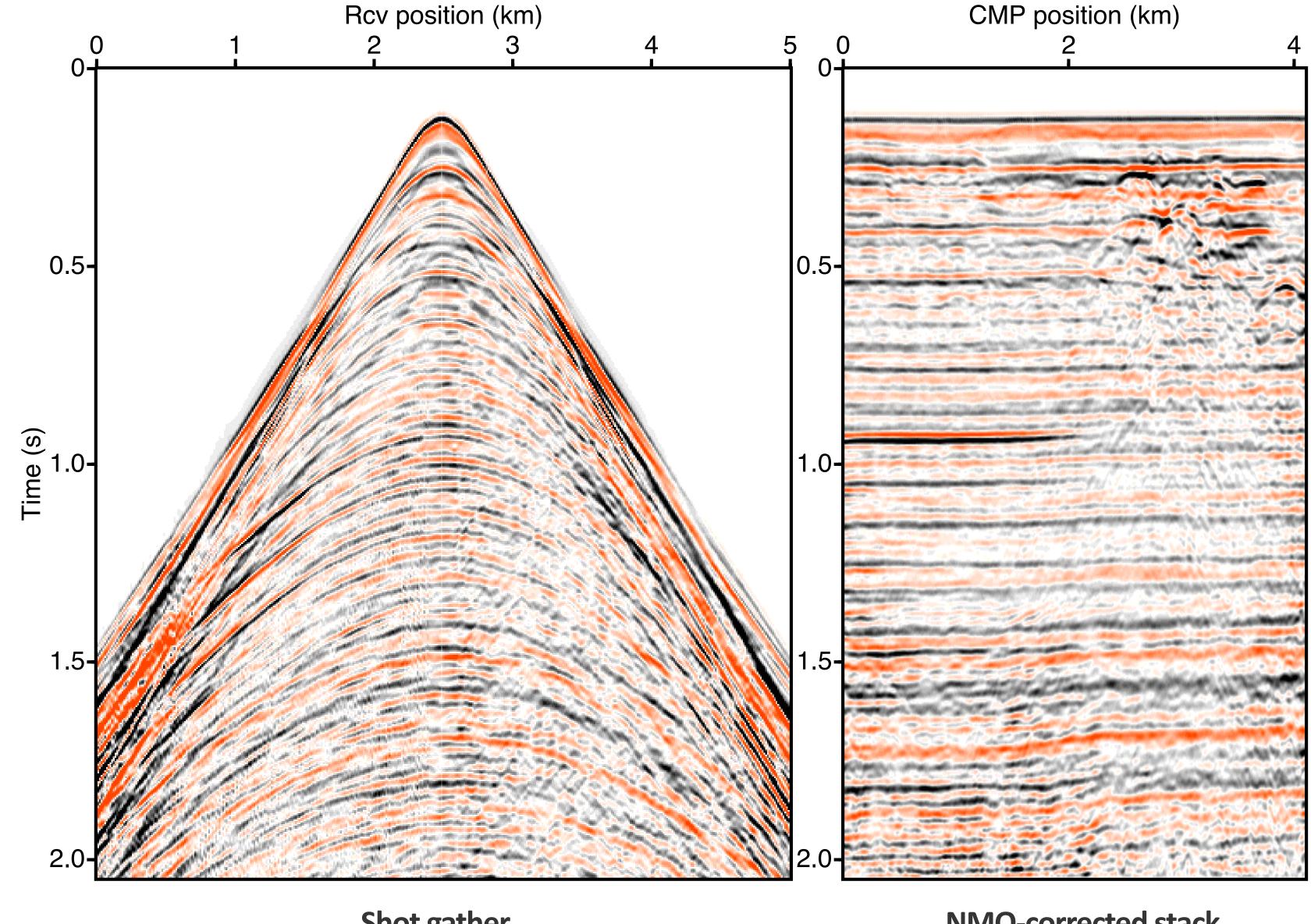




Field data example

North Sea dataset





North sea data

Shot gather and stack

Streamer data (regularized to fixed-spread data) 401 source and reciever 12.5 m spatial grid 4 ms time sampling

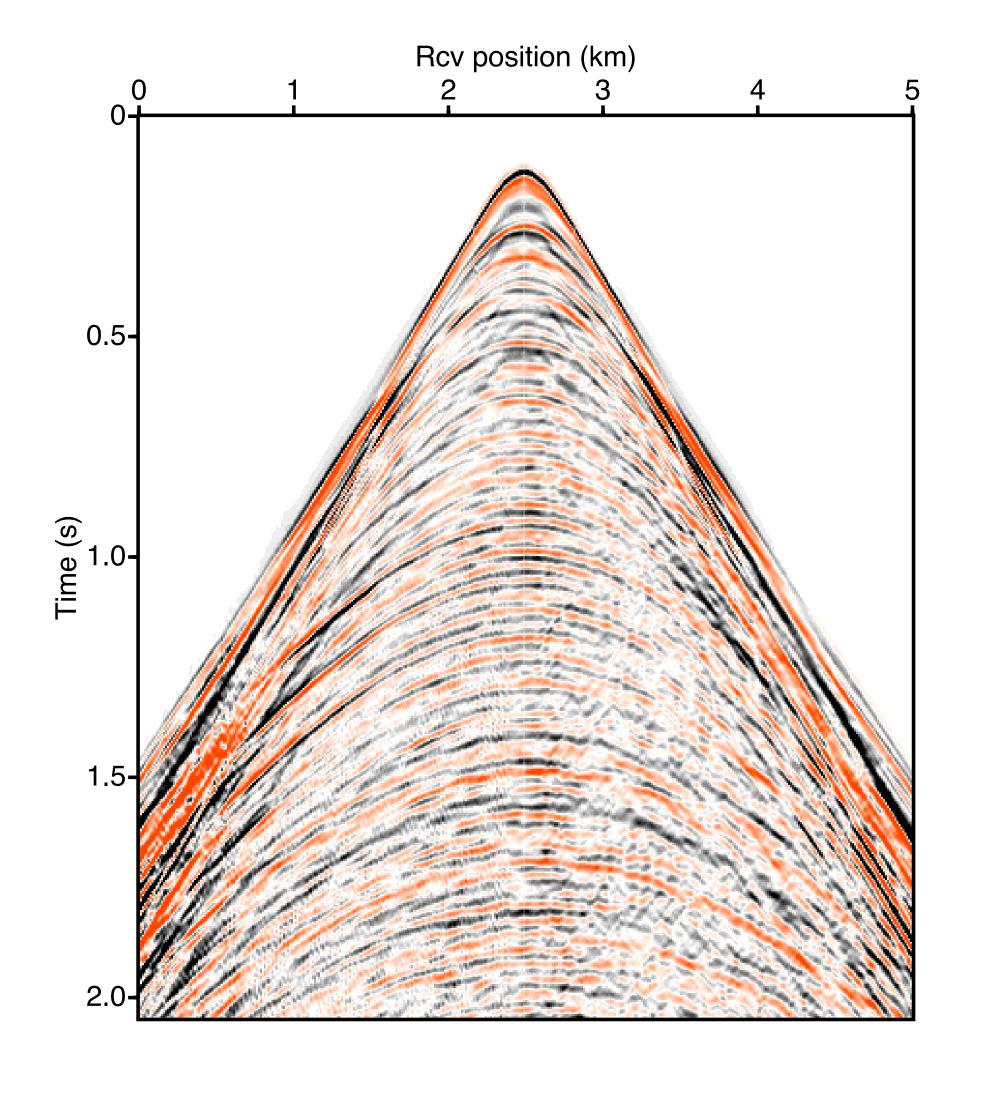
Shot gather

NMO-corrected stack

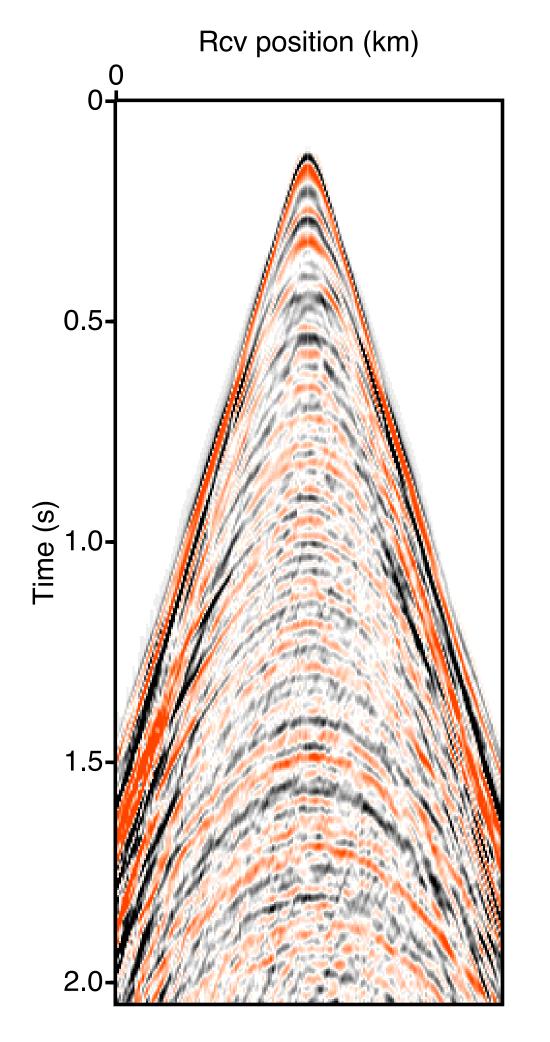


Decimated wavefields

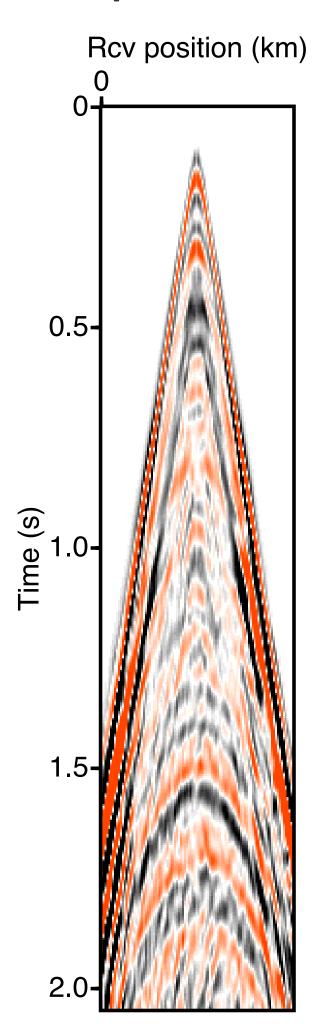




2x decimated lowpass 40Hz

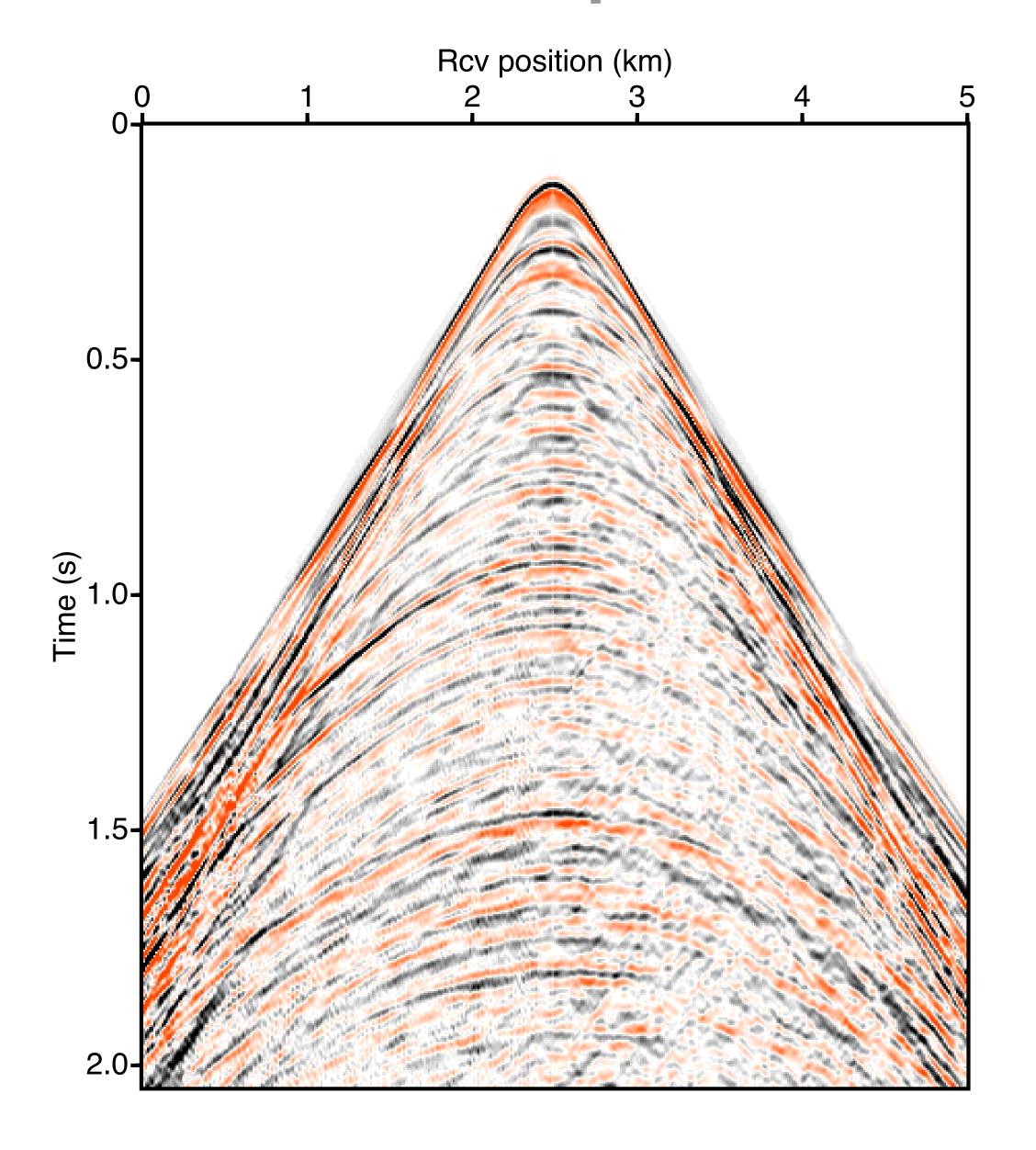


4x decimated lowpass 20Hz





Solution wavefield comparison

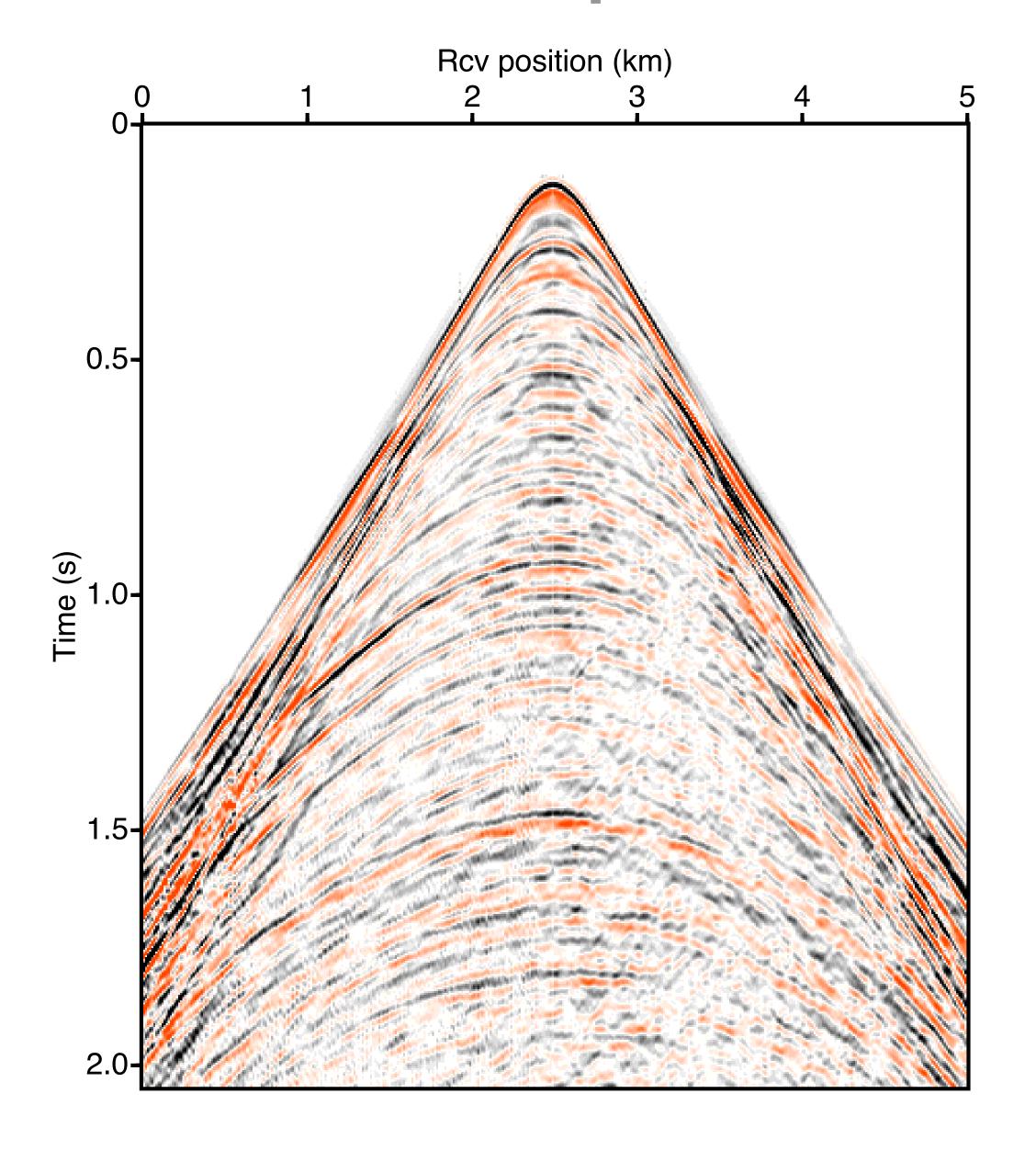


Direct Primary

Solved with plain algorithm from finest scale data



Solution wavefield comparison

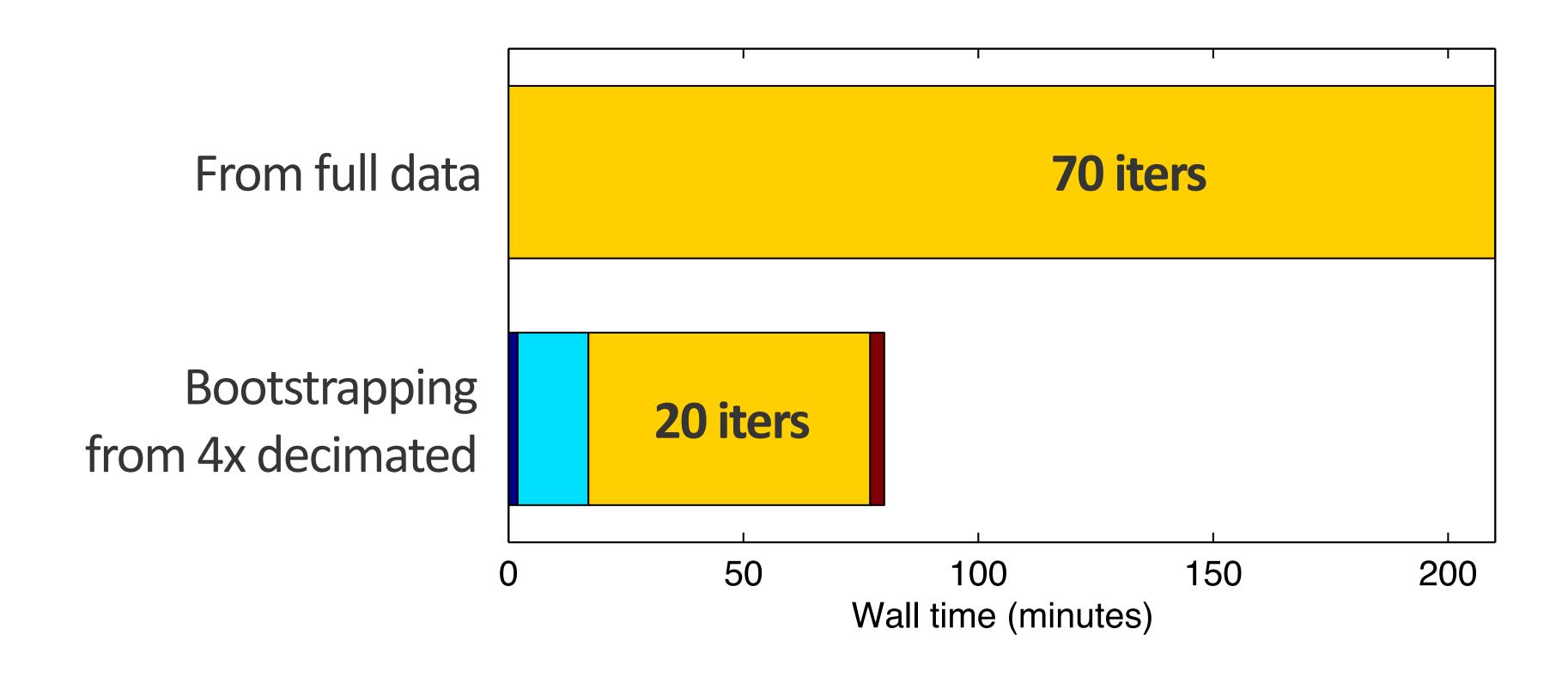


Direct Primary

Solved with spatial sampling continuation dx = 50m > 25m > 12.5m

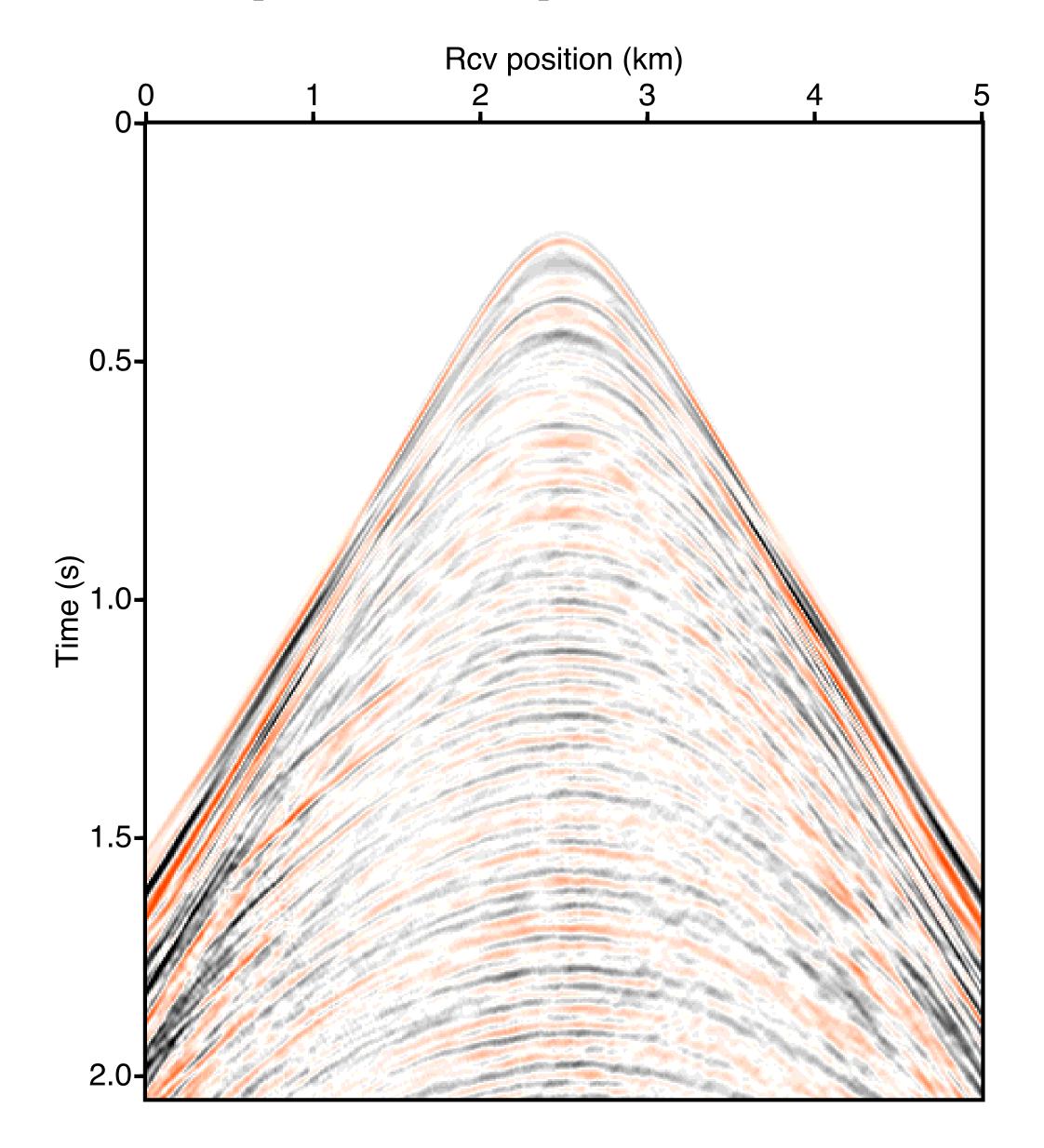


Runtime breakdown (wall time)





Solution multiple comparison

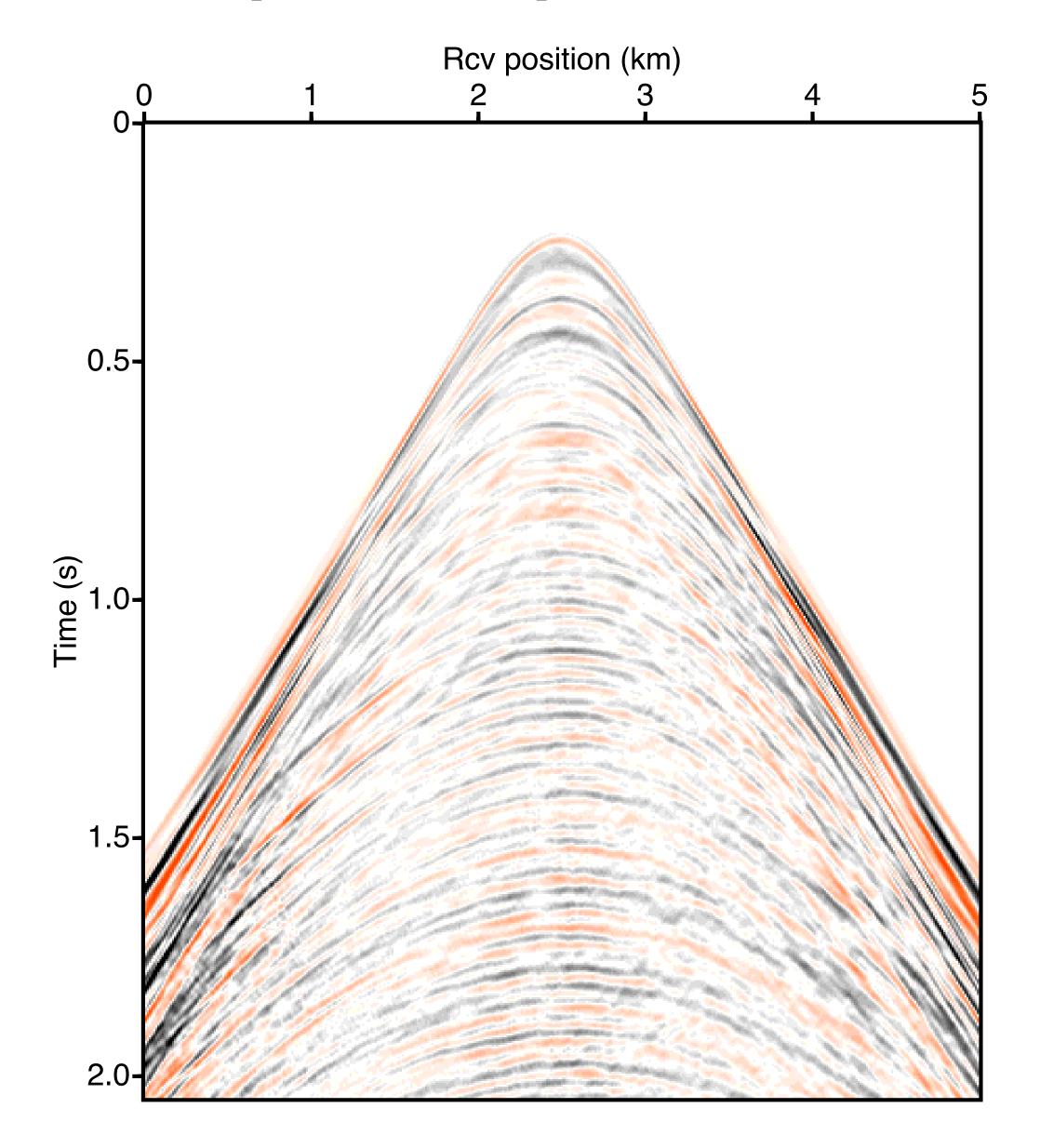


Predicted Surface Multiple

Solved with plain algorithm from finest scale data



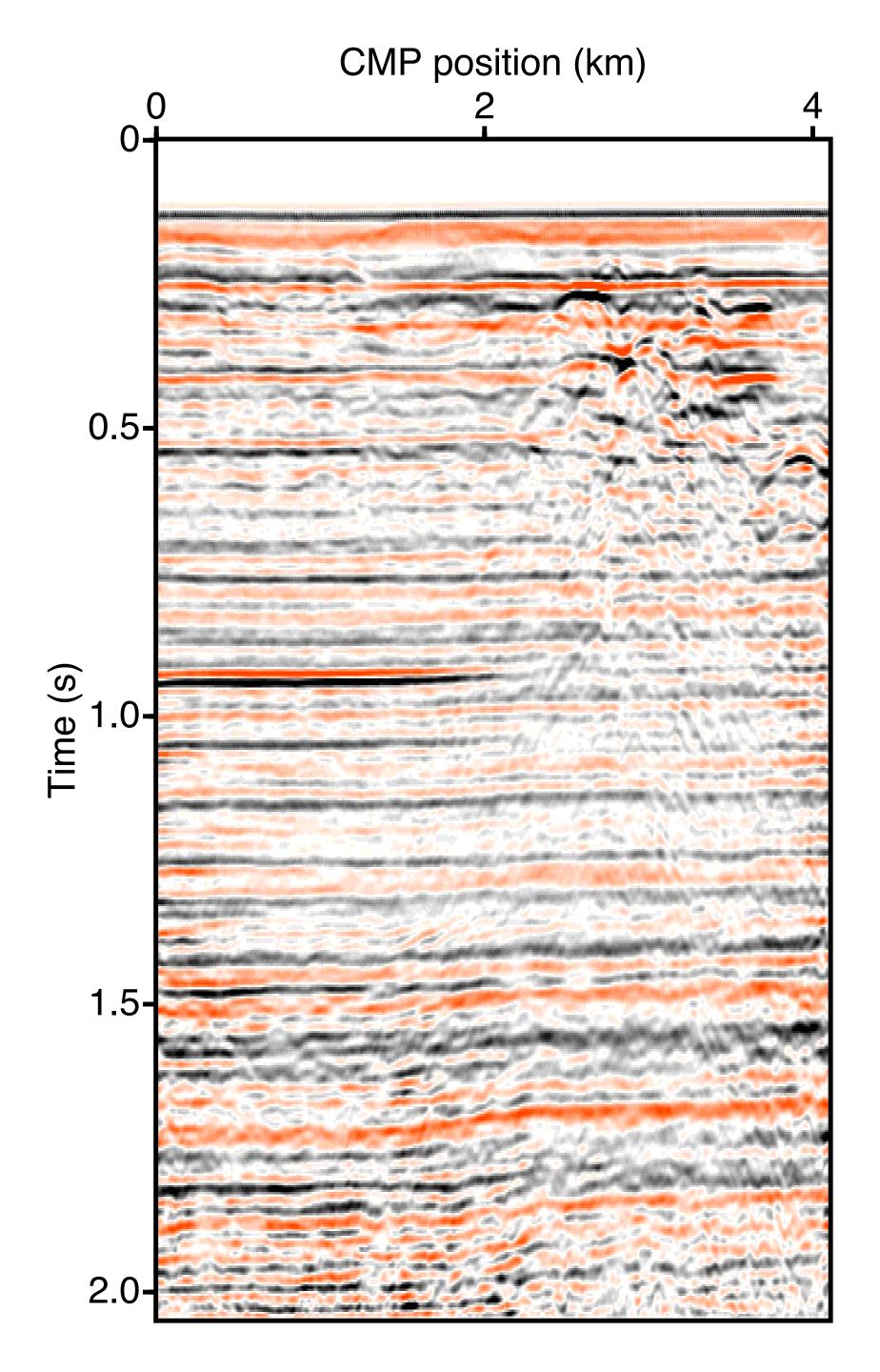
Solution multiple comparison



Predicted Surface Multiple

Solved with spatial sampling continuation dx = 50m > 25m > 12.5m

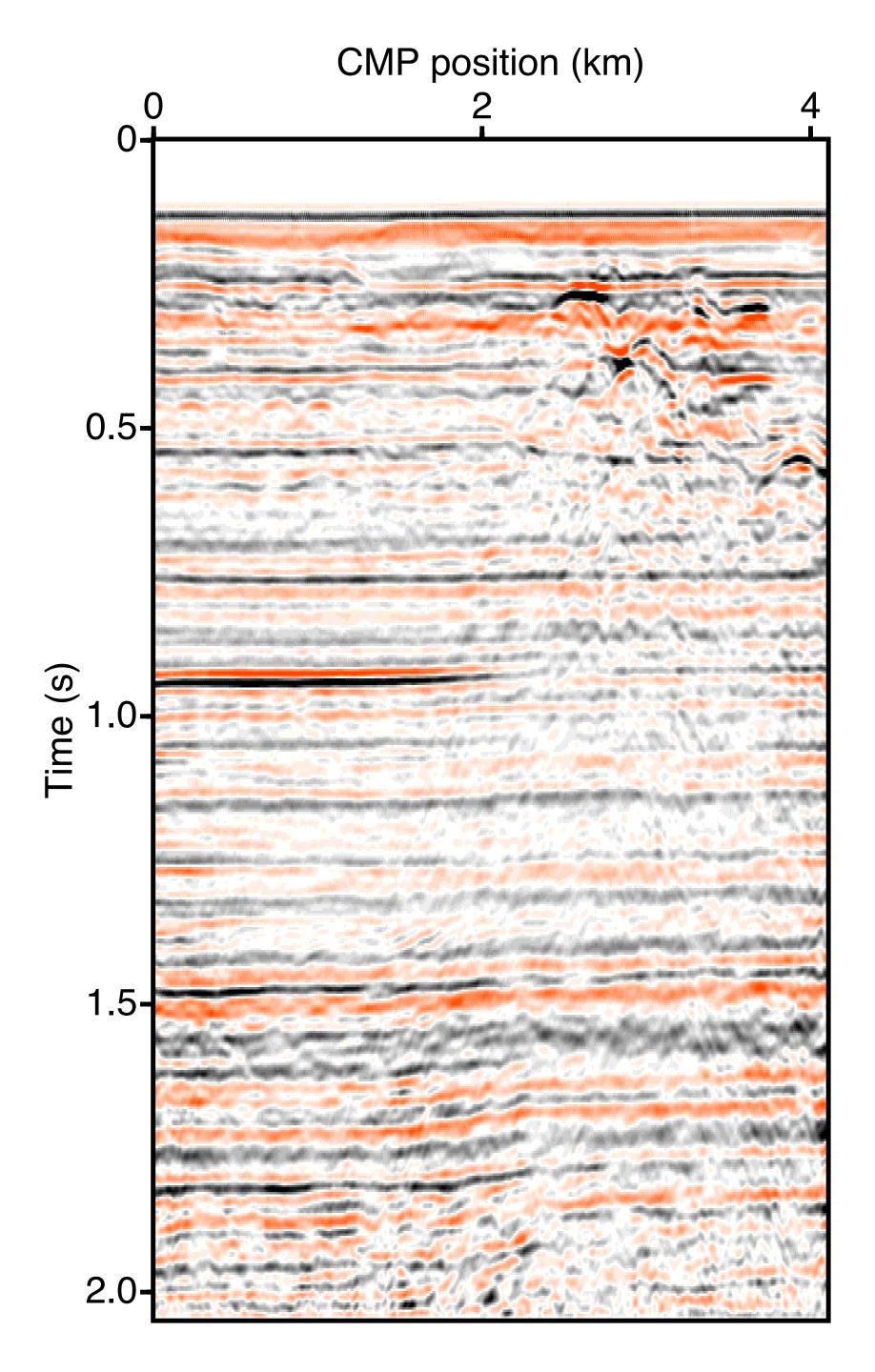
NMO Stack original data





REPSI Primaries NMO Stack

Solved with plain algorithm from finest scale data



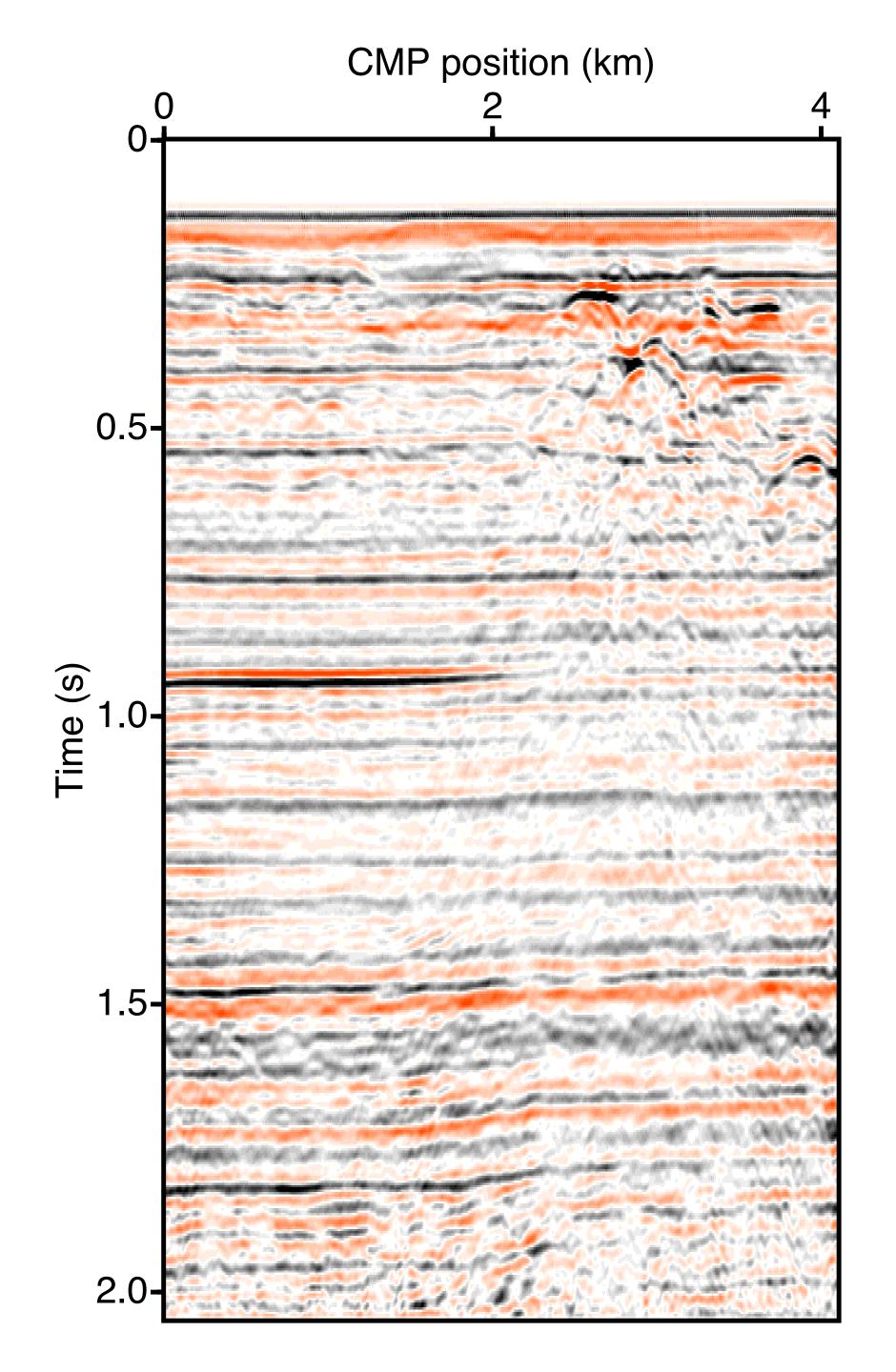




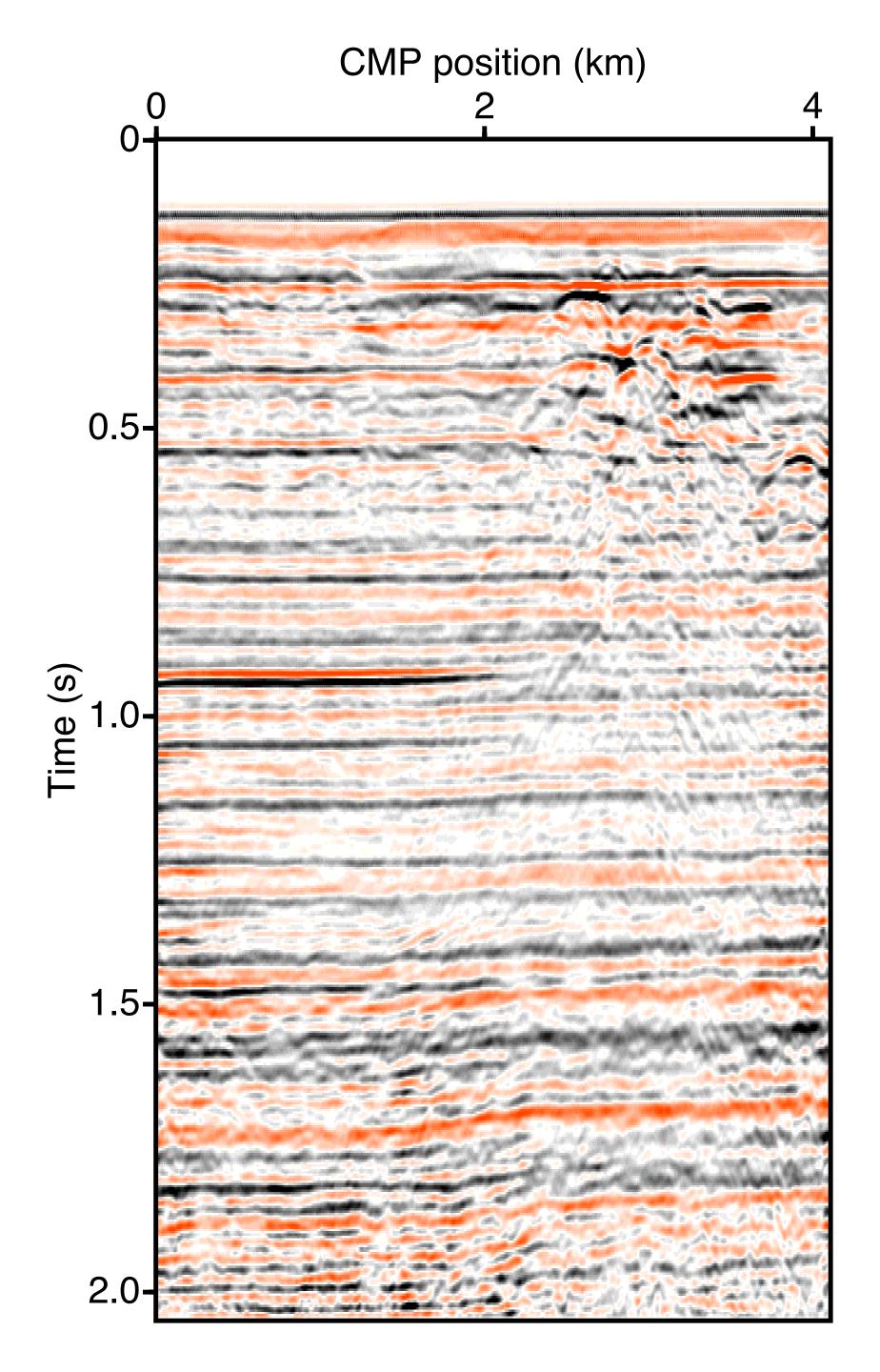
REPSI Primaries NMO Stack

Solved with spatial sampling continuation

dx = 50m > 25m > 12.5m



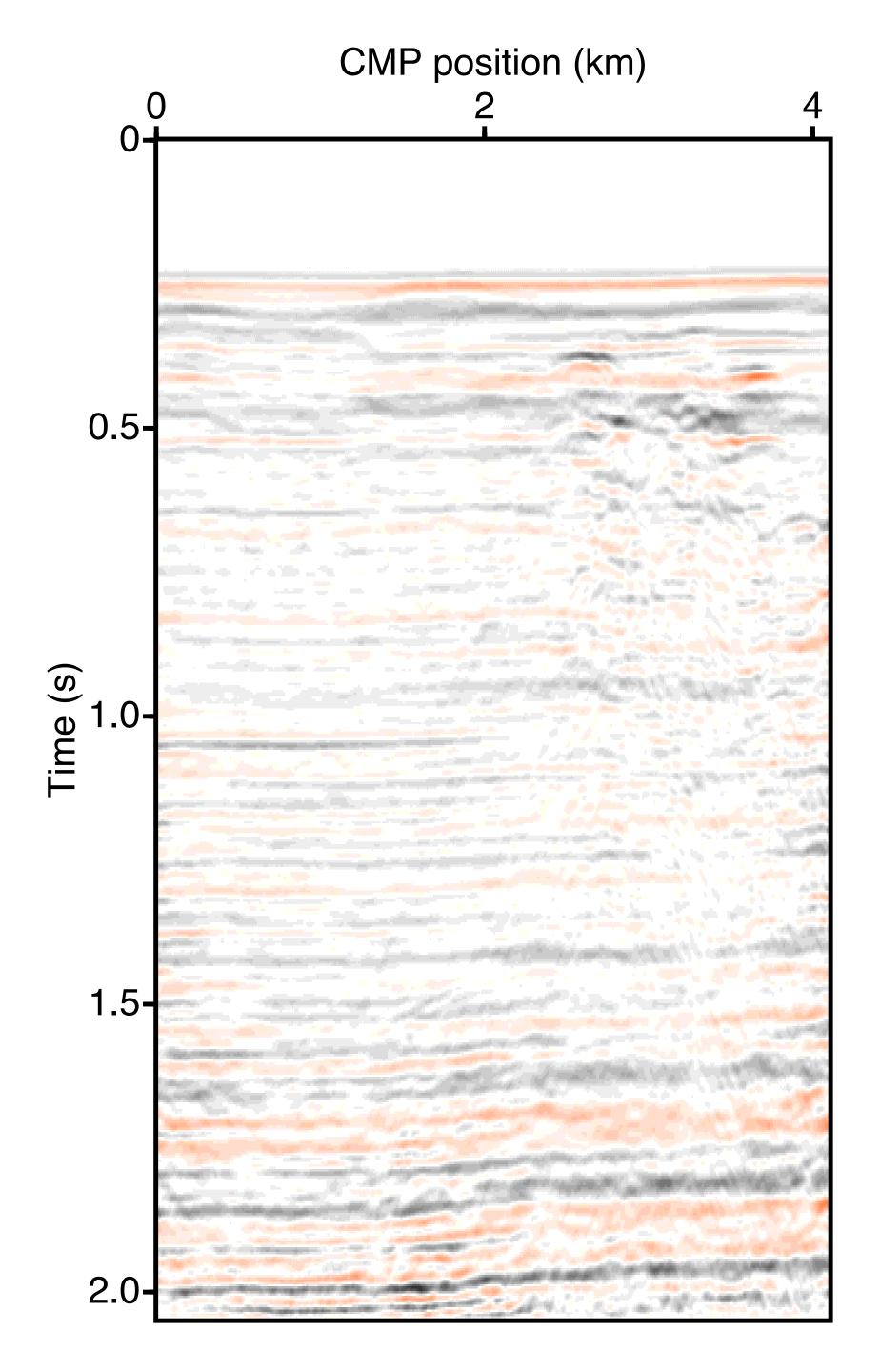
NMO Stack original data





REPSI Multiples NMO Stack

Solved with plain algorithm from finest scale data

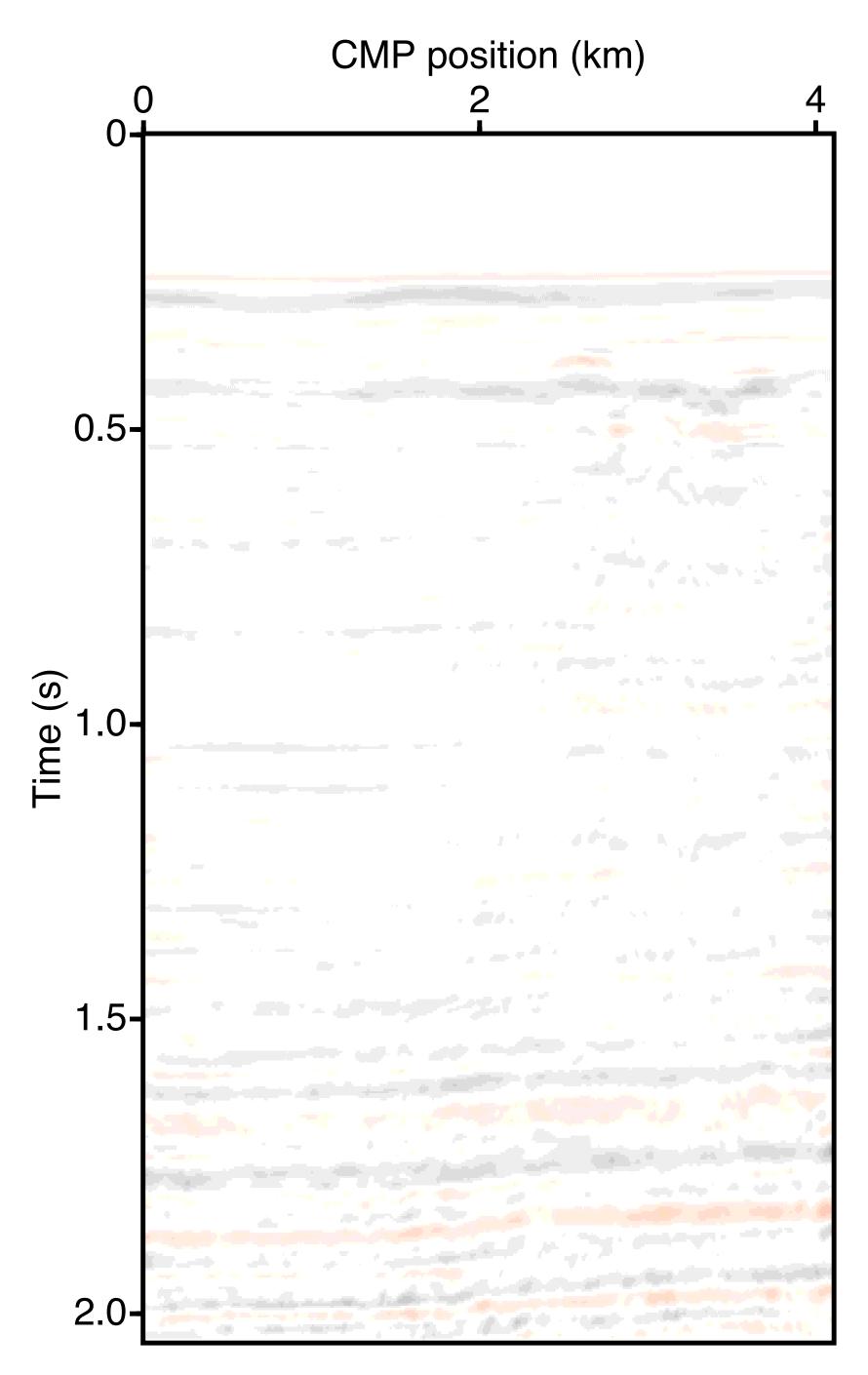






REPSI Multiples NMO Stack

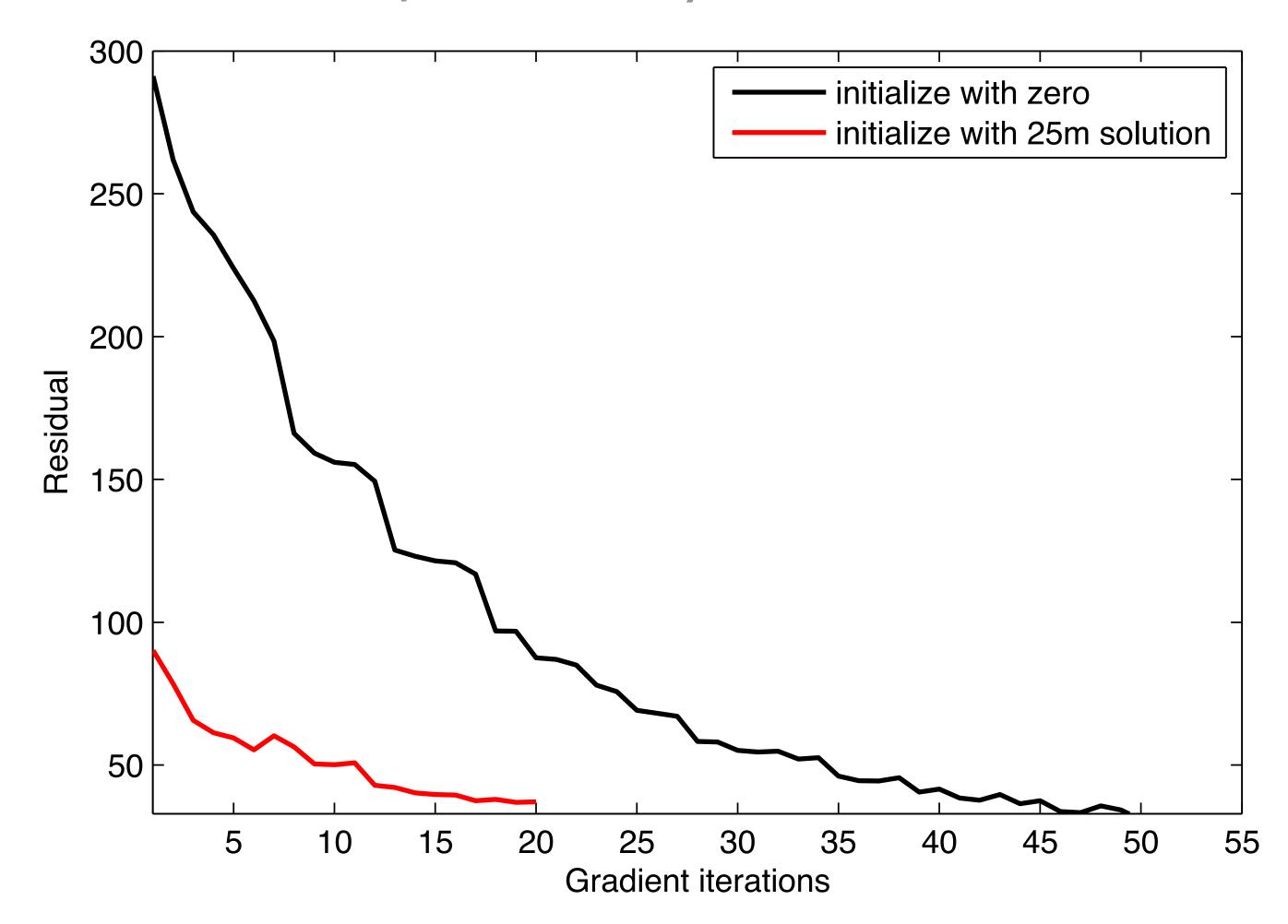
Difference:
plain algorithm
accelerated algorithm





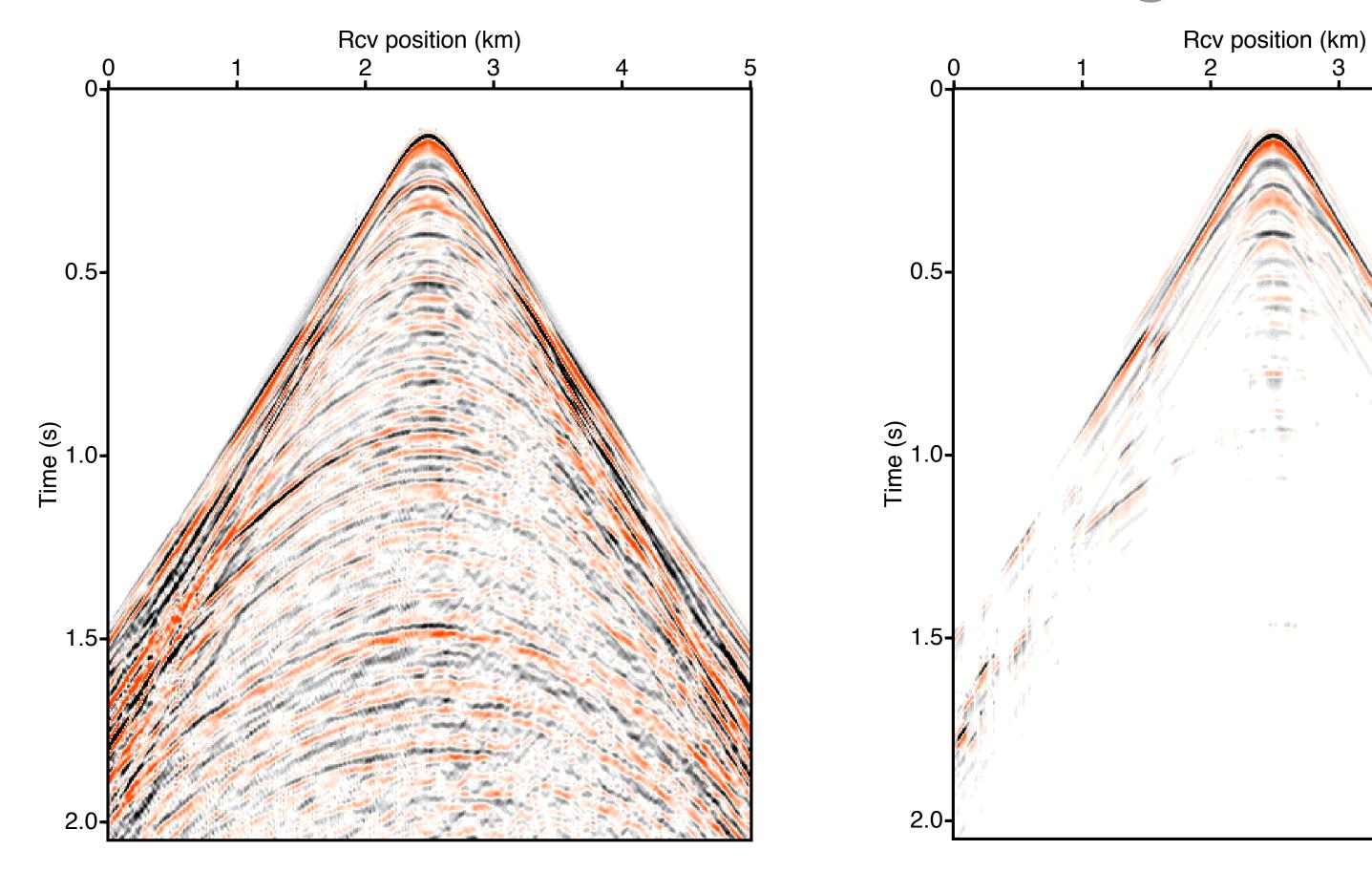


Warm-start vs from zero residual graph (for full scale problem)





Warm-start vs from zero 'G' shot gathers





Acceleration strategy summary

Start REPSI with decimated data, lowpass to avoid spatial aliasing

Once "enough" progress is made, continue with fine-scale data

Significant savings in computation cost, 100x to 200x SRMP becomes more like 20x to 30x

How low can we go? Depends on the ability of sparsity-regularized inversion to resolve wavefronts under reduced bandwidth.



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CRSNG

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