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Fast least-squares imaging with source estimation using multiples

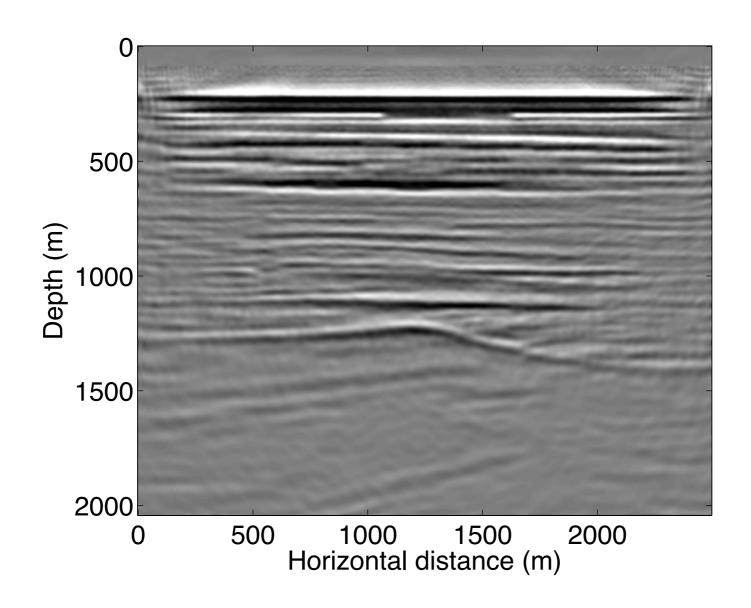
Ning Tu, Aleksandr Y. Aravkin, Tristan van Leeuwen, and Felix Herrmann



Motivation

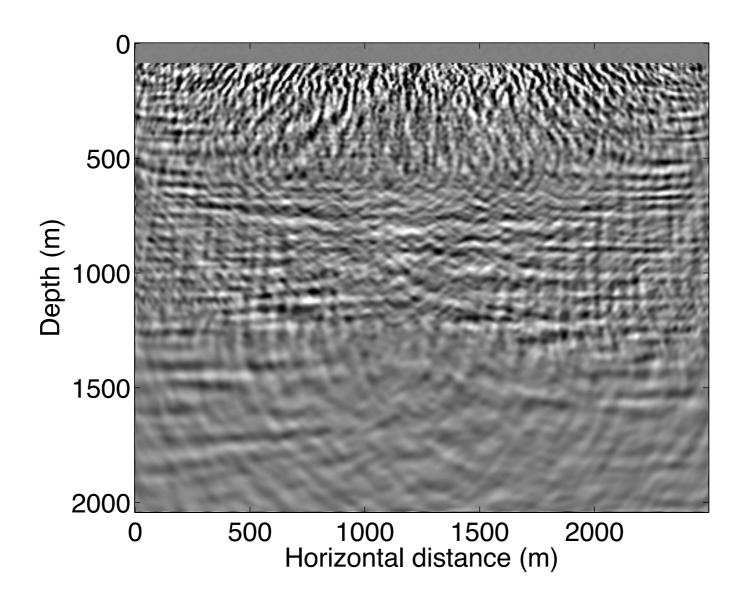
- high fidelity, true-amplitude seismic image by linearized inversion
- accurate source signature

How important is the source wavelet for linearized inversion?



Linearized inversion with the true wavelet

whereas...



Linearized inversion with a wrong wavelet



Theory

Least-squares migration with unknown source wavelet

$$\min_{\delta \mathbf{m}, \mathbf{q}} \sum_{i=1}^{n_f} \|\mathbf{d}_i - \nabla \mathbf{F}_i[\mathbf{m}_0, \mathbf{Q}(q_i)] \delta \mathbf{m}\|_2^2$$

 $\delta \mathbf{m}$: model perturbation

q: source wavelet spectra $\mathbf{q} = [q_1, \cdots, q_{n_f}]$

 d_i : vectorized primary wavefield

 $\nabla \mathbf{F}_i$: linearized demigration operator

m₀: background model

 $\mathbf{Q}(q_i)$: source wavefield $\mathbf{Q}(q_i) = q_i \mathbf{I}$

Major challenges

- preprocessing to remove coherent noise such as surface multiples
- expensive simulation cost
- nonlinearity with unknown source wavelet

Our solutions

- imaging with active contributions from surface multiples
- using dimensionality reduction techniques to speed up inversion
- estimating the source wavelet on the fly

Embracing surface multiples

- imaging primaries and multiples simultaneously
- removing amplitude/phase ambiguity using extra information from multiples
- exploiting higher-wavenumber components in multiples

$$\min_{\delta \mathbf{m}, \mathbf{q}} \sum_{i=1}^{n_f} \|\mathbf{d}_i - \nabla \mathbf{F}_i[\mathbf{m}_0, \mathbf{Q}(q_i)] \delta \mathbf{m}\|_2^2$$

- d_i : vectorized total up-going wavefield, primaries and surface multiples
- $\mathbf{Q}(q_i) = q_i \mathbf{I} \mathbf{D}_i$: generalized source wavefield containing the total downgoing wavefield

Dimensionality reduction with sparsity promotion

BPDN:
$$\underset{\mathbf{x},\mathbf{q}}{\text{minimize}} \|\mathbf{x}\|_1$$

subject to
$$\sum_{i \in \mathbb{F}} \|\underline{\mathbf{d}}_i - \nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{Q}}(q_i)] \mathbf{S}^* \mathbf{x} \|_2^2 \leq \sigma^2$$

frequency: select a random frequency subset source: forming randomized source aggregates

S*: Curvelet synthesis operator

 σ : tolerance for noise/modelling error, etc

Alternate formulation

LASSO:
$$\min_{\mathbf{x},\mathbf{q}} \sum_{i \in \mathbb{F}} \|\underline{\mathbf{d}}_i - \nabla \mathbf{F}_i[\mathbf{m}_0,\underline{\mathbf{Q}}(q_i)]\mathbf{S}^*\mathbf{x}\|_2^2$$
 subject to $\|\mathbf{x}\|_1 \leq \tau$

au: sparsity level

Further acceleration by rerandomization

- We draw a new subsampling operator for each LASSO subproblem:
 - new random subset of frequencies
 - new randomized source aggregates
- faster convergence

Source estimation

$$\min_{\mathbf{x},\mathbf{q}} \sum_{i \in \mathbb{F}} \|\underline{\mathbf{d}}_i - \nabla \mathbf{F}_i[\mathbf{m}_0,\underline{\mathbf{Q}}(q_i)] \mathbf{S}^* \mathbf{x} \|_2^2$$

subject to
$$\|\mathbf{x}\|_1 \leq \tau$$

- nonlinear by having two unknowns
- the two unknowns are separable
- alternating optimization

Wavefield matching

Given an \mathbf{x} , a least squares solution for \mathbf{q} can be determined:

primaries only:

$$\tilde{q}_i(\mathbf{x}) = \frac{\langle \nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{I}}] \mathbf{S}^* \mathbf{x}, \mathbf{d}_i \rangle}{\|\nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{I}}] \mathbf{S}^* \mathbf{x}\|_2^2}$$

with multiples:

$$\tilde{q}_i(\mathbf{x}) = \frac{\langle \nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{I}}] \mathbf{S}^* \mathbf{x}, \mathbf{d}_i + \nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{D}}_i] \mathbf{S}^* \mathbf{x} \rangle}{\|\nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{I}}] \mathbf{S}^* \mathbf{x}\|_2^2}$$

Variable projection

We now solve:

$$\min_{\mathbf{x}} \sum_{i \in \mathbb{F}} \|\underline{\mathbf{d}}_i - \nabla \mathbf{F}_i[\mathbf{m}_0, \underline{\mathbf{Q}}(\tilde{q}_i(\mathbf{x}))] \mathbf{S}^* \mathbf{x} \|_2^2$$

subject to
$$\|\mathbf{x}\|_1 \leq \tau$$



Example

Experiments setup

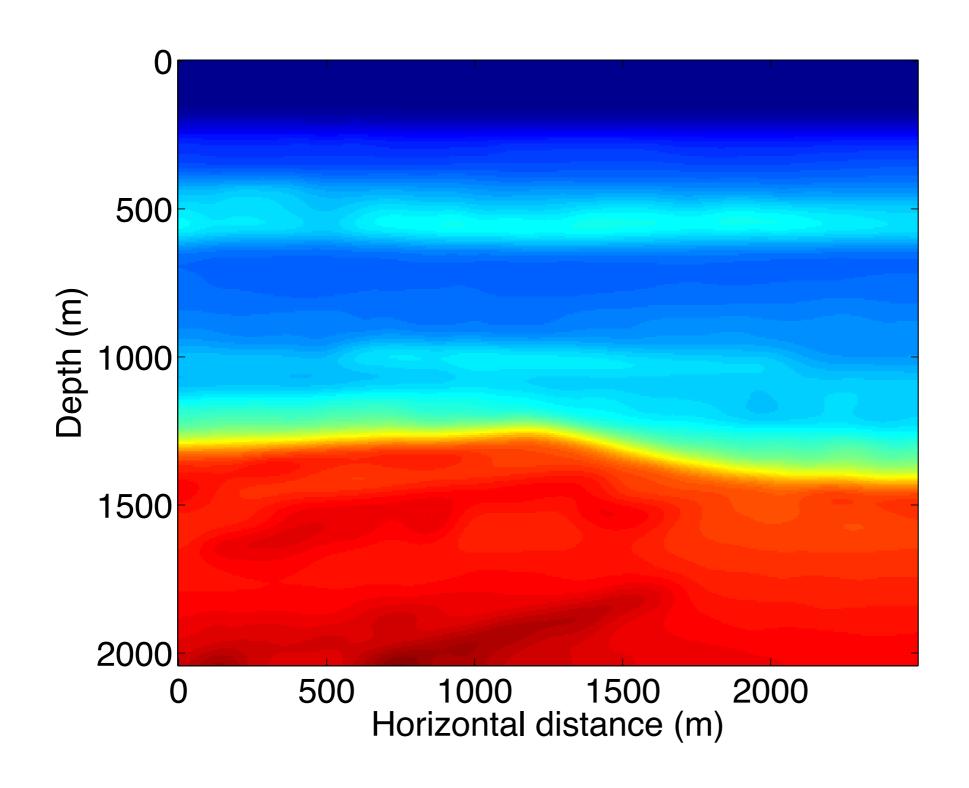
- synthetic BG Compass model (cropped)
- 209 co-located sources/receivers, 12m spacing, 6m depth
- linearized data, i.e., $\mathbf{d} = \nabla \mathbf{F} \delta \mathbf{m}$
- Ricker wavelet w. 20Hz peak freq.
- 30 composite sources, 15 frequencies in the inversion, 74X subsampling



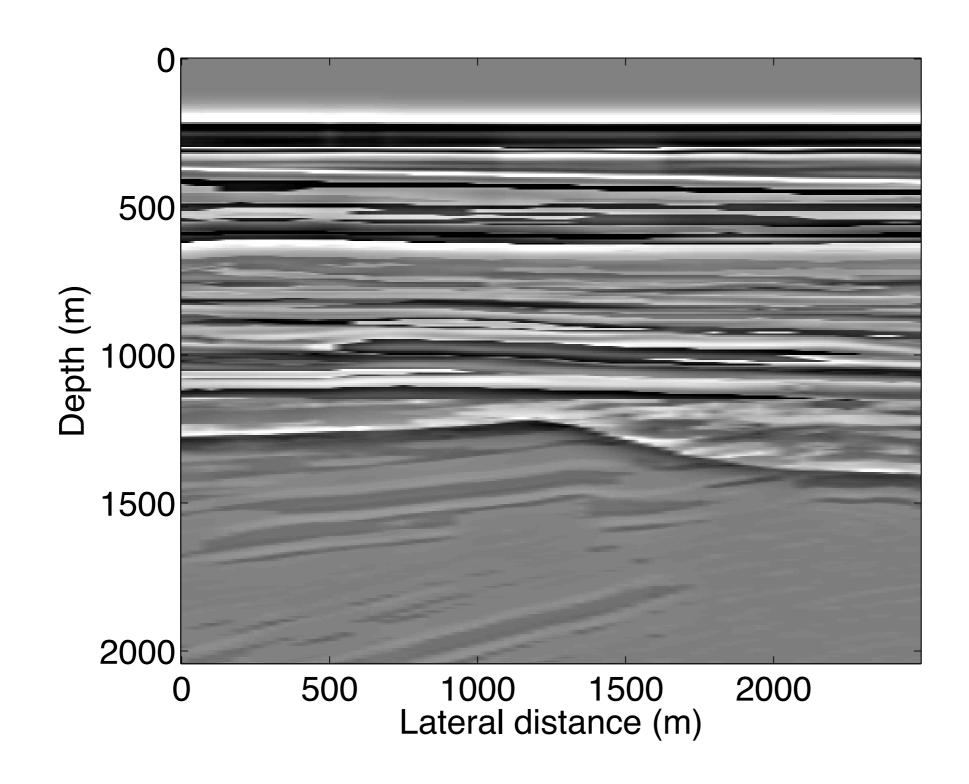
Experiments setup

	SOURCE WAVELET	
DATA TYPE	PRIMARY, TRUE SOURCE	PRIMARY, SOURCE ESTIMATION
	W. MULTIPLES, TRUE SOURCE	W. MULTIPLES, SOURCE ESTIMATION

Background velocity



True perturbation

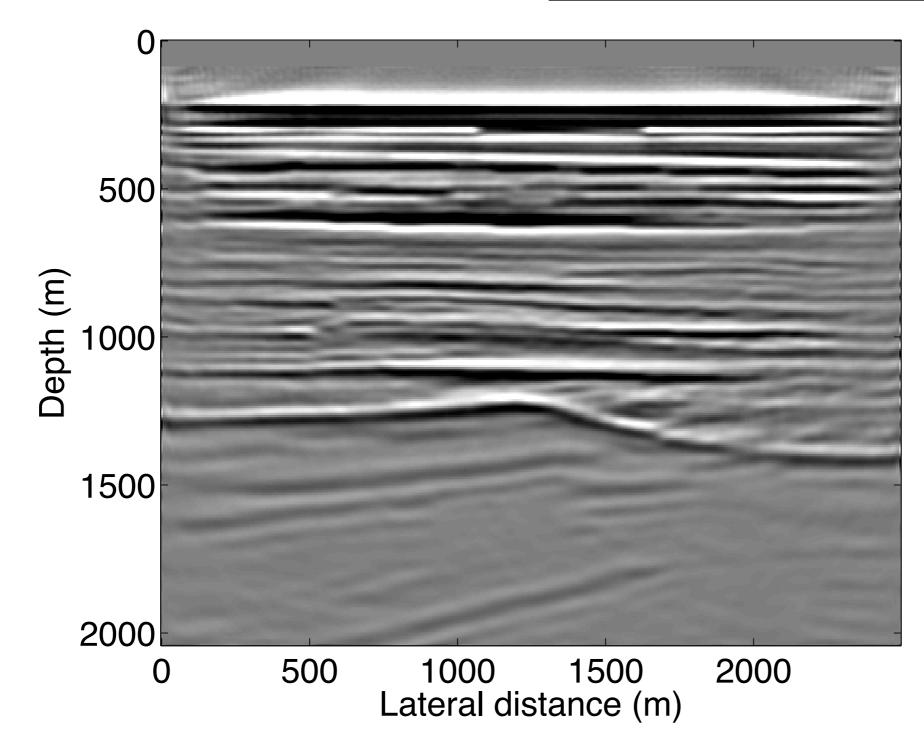


Using primaries

w. true source

PRIMARY,
TRUE SOURCE
ESTIMATION

W. MULTIPLES,
TRUE SOURCE
ESTIMATION

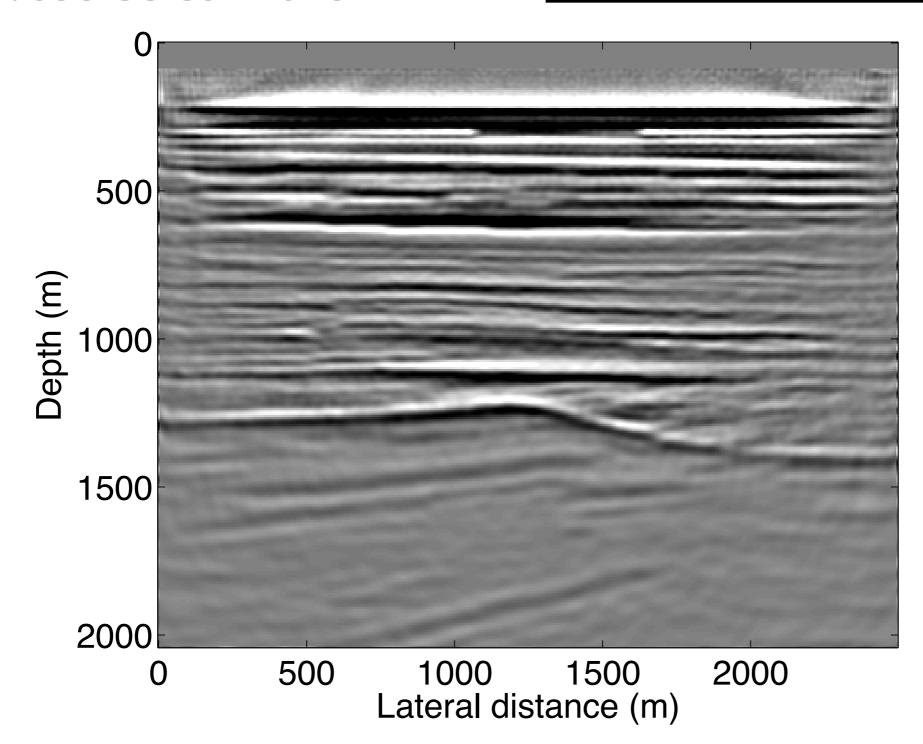


Using primaries

w. source estimation

PRIMARY,
SOURCE
ESTIMATION

W. MULTIPLES,
TRUE SOURCE
ESTIMATION



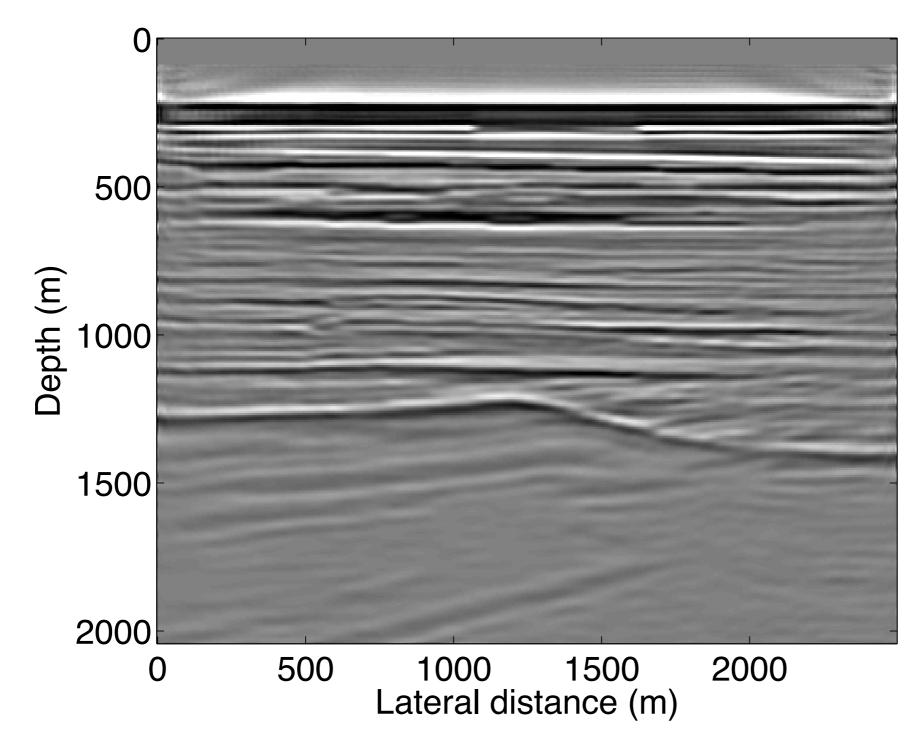
With multiples

w. true source

PRIMARY,
TRUE SOURCE

W. MULTIPLES,
TRUE SOURCE
ESTIMATION

W. MULTIPLES,
SOURCE
ESTIMATION



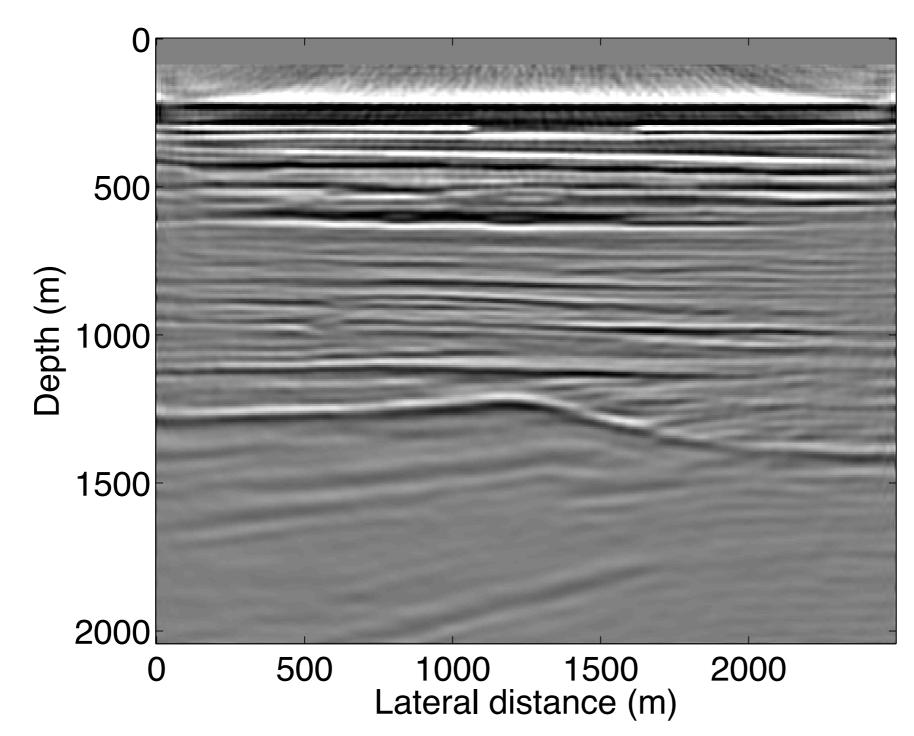
With multiples

w. source estimation

PRIMARY,
TRUE SOURCE

W. MULTIPLES,
TRUE SOURCE
ESTIMATION

W. MULTIPLES,
SOURCE
ESTIMATION

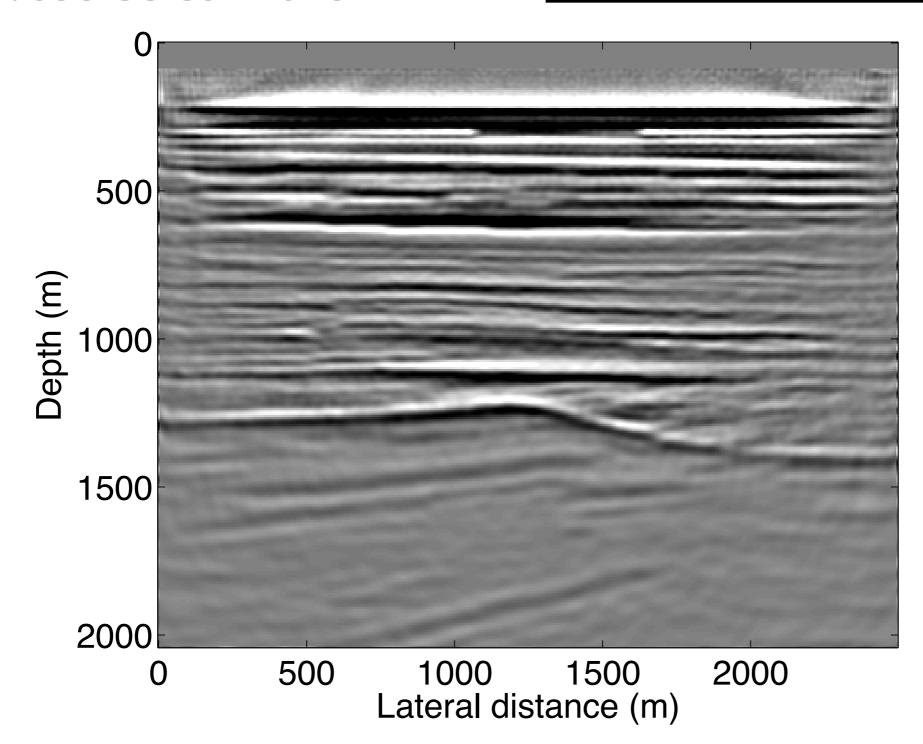


Using primaries

w. source estimation

PRIMARY,
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ESTIMATION

W. MULTIPLES,
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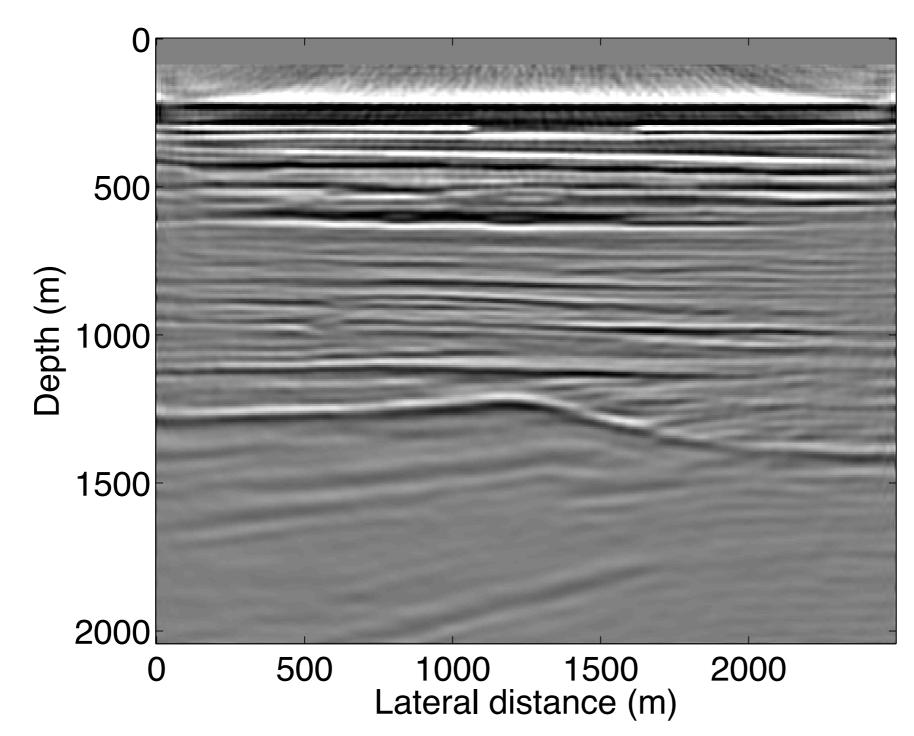
With multiples

w. source estimation

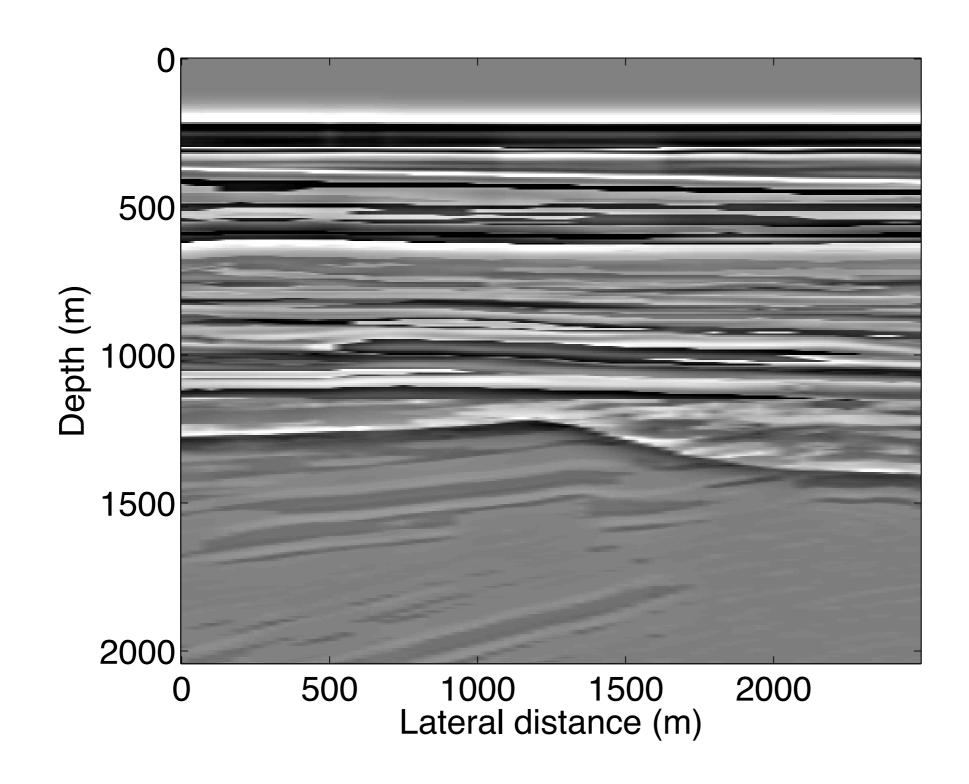
PRIMARY,
TRUE SOURCE

W. MULTIPLES,
TRUE SOURCE
ESTIMATION

W. MULTIPLES,
SOURCE
ESTIMATION

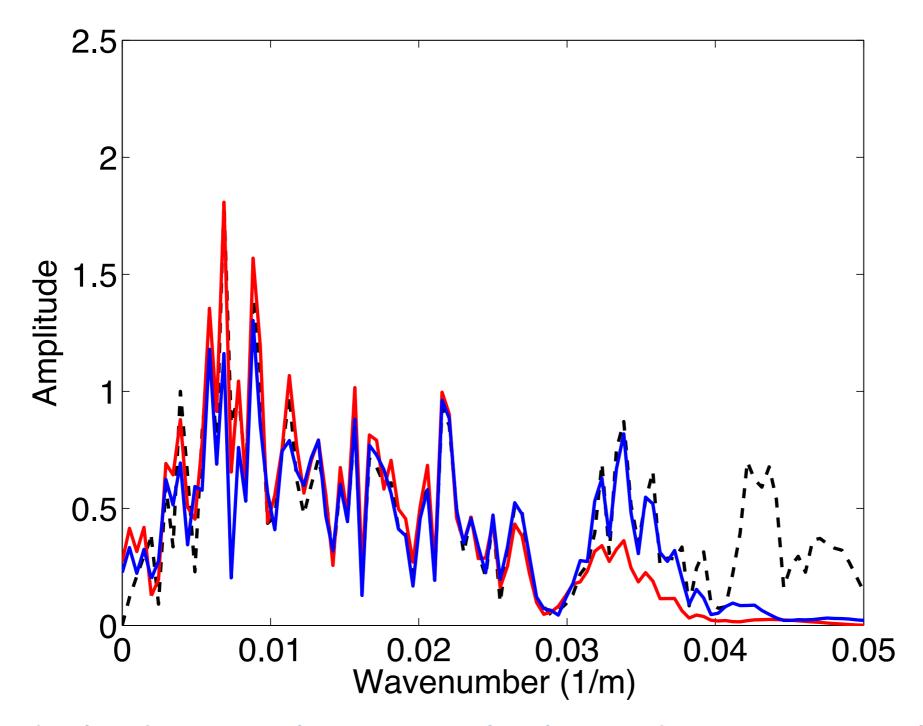


True perturbation



Wavenumber contents

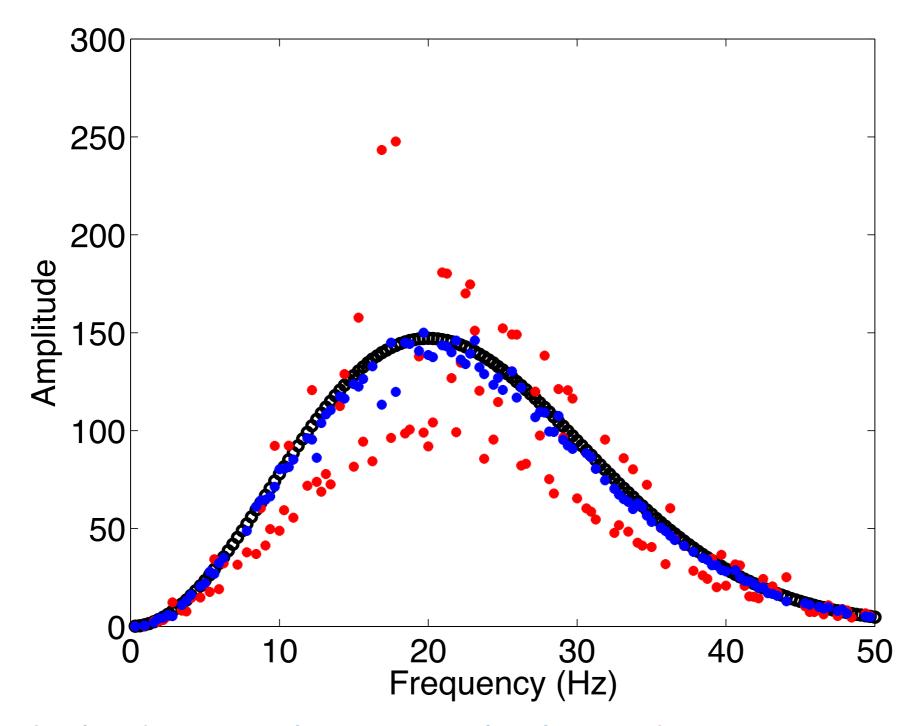
[of traces from images w. source estimation]



Black dashed: true; Blue: w. multiple; Red: primaries only (rescaled)

Estimated wavelet

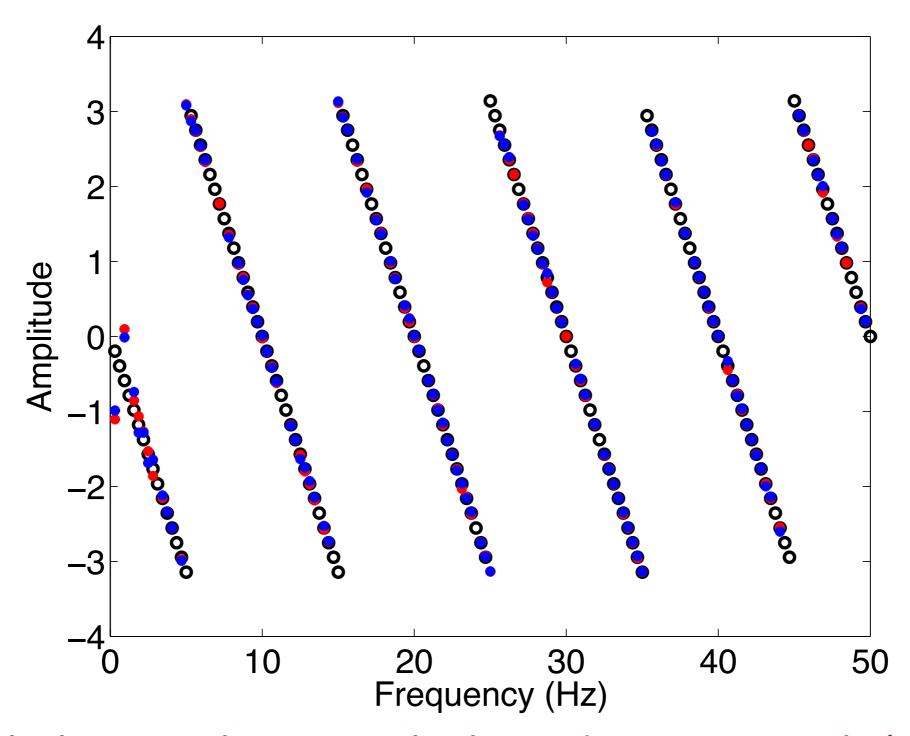
[amplitude spectrum]



Black dashed: true; Blue: w. multiple; Red: primaries only (rescaled)

Estimated wavelet

[phase spectrum]



Black: true; Blue: w. multiple; Red: primaries only (rescaled)

Conclusion

- The use of surface-related multiples improves both the image resolution, and the accuracy of estimated source wavelet.
- With sparse constraint and rerandomization, we greatly reduce the dimensionality of the system without compromising the image quality.
- The proposed source estimation works well in the linearized sparse inversion framework.



Acknowledgements RESERGE

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