

# Hierarchical Tucker Tensor Optimization - Applications to 4D Seismic Data Interpolation EAGE 2013 London

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# Motivation

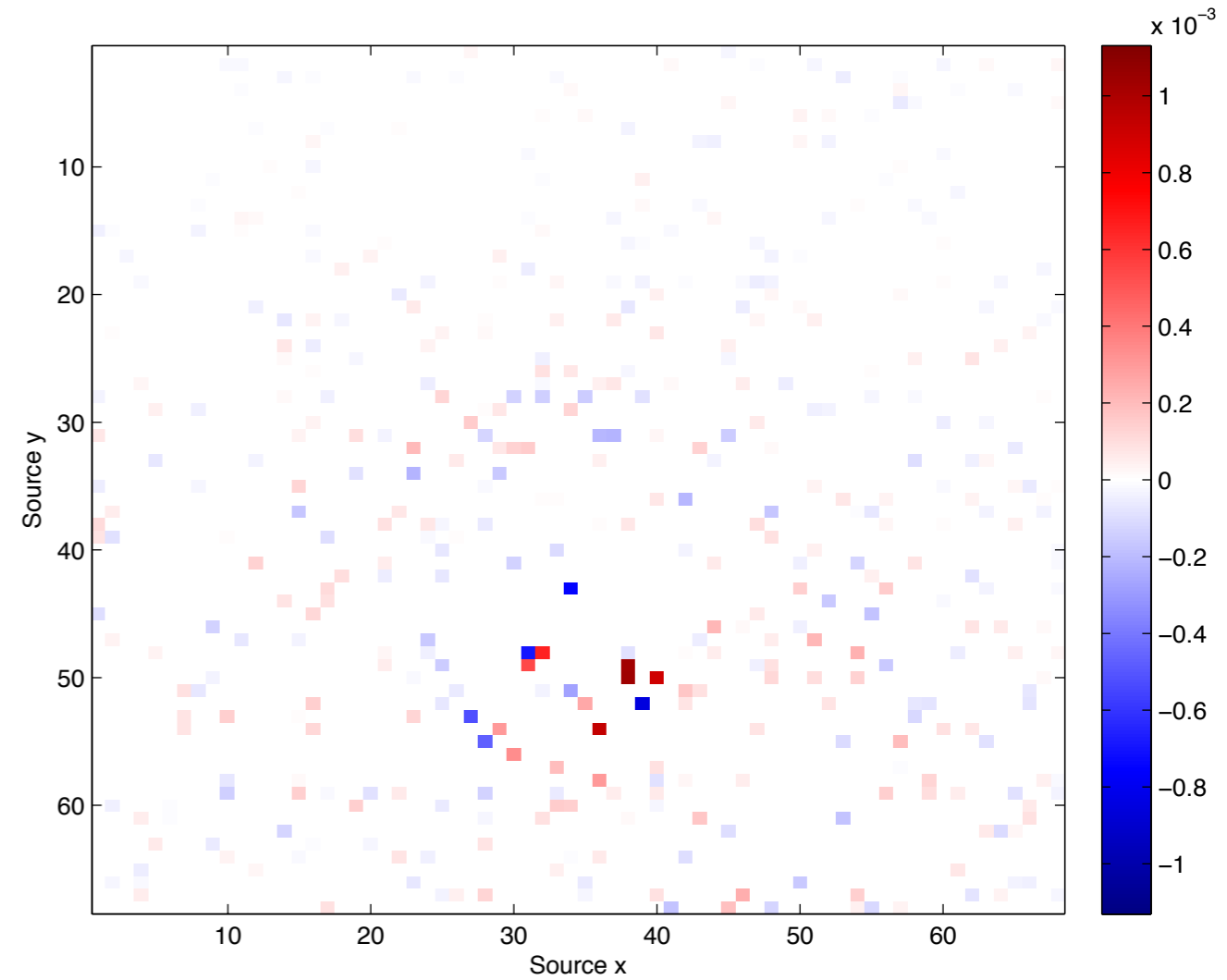
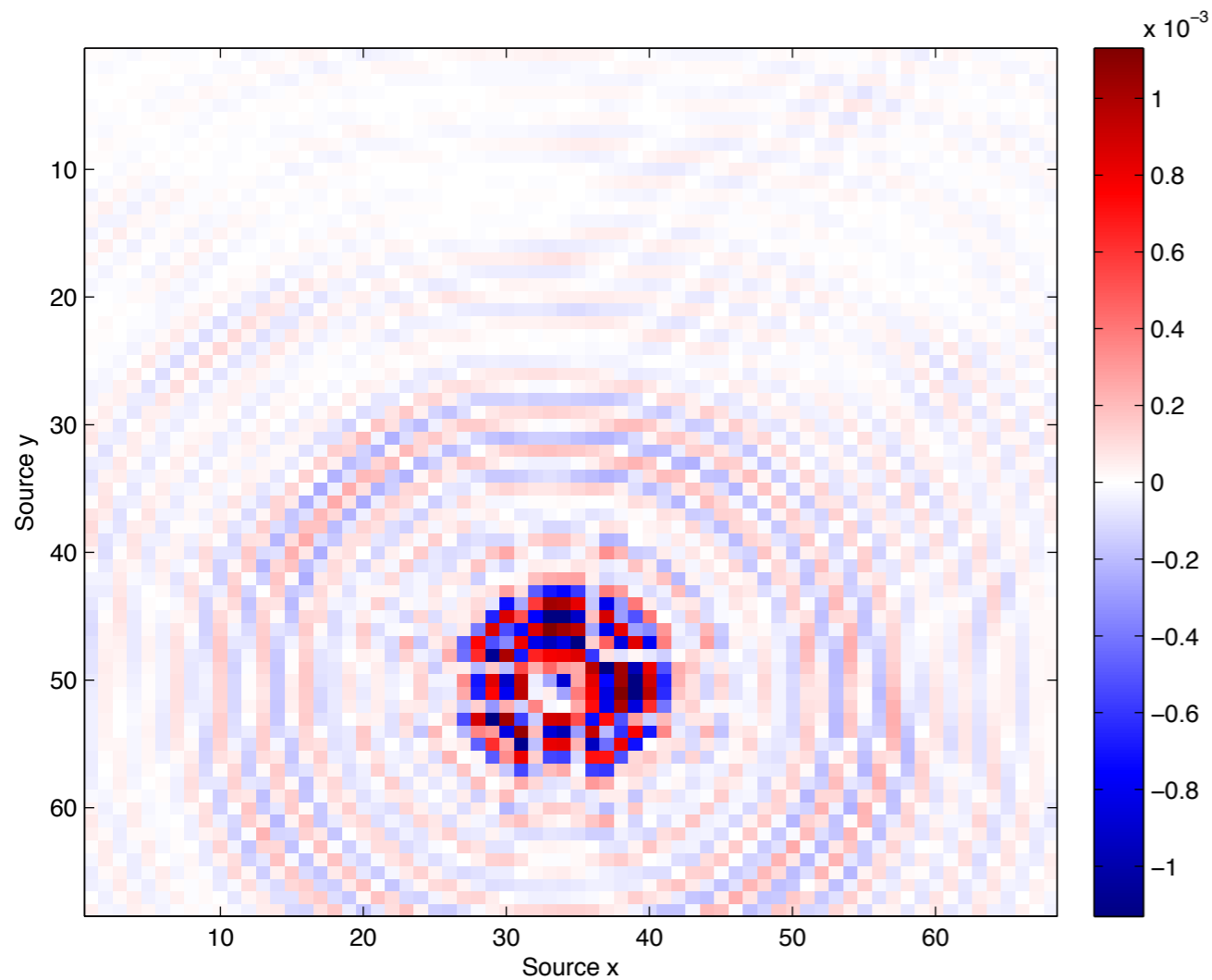
- 3D seismic experiments - 5D data
  - expensive to acquire, store
- Structured data - interpolation
- Fully sampled data
  - simultaneous sources in wave-equation based inversion
  - simulating multiples

# Goals

- Generalization of Compressive Sensing to multiple dimensions
- Randomized source/receiver acquisition
  - Reduce acquisition financial/time costs

# 7.34 Hz - 75% missing sources

Common receiver gather

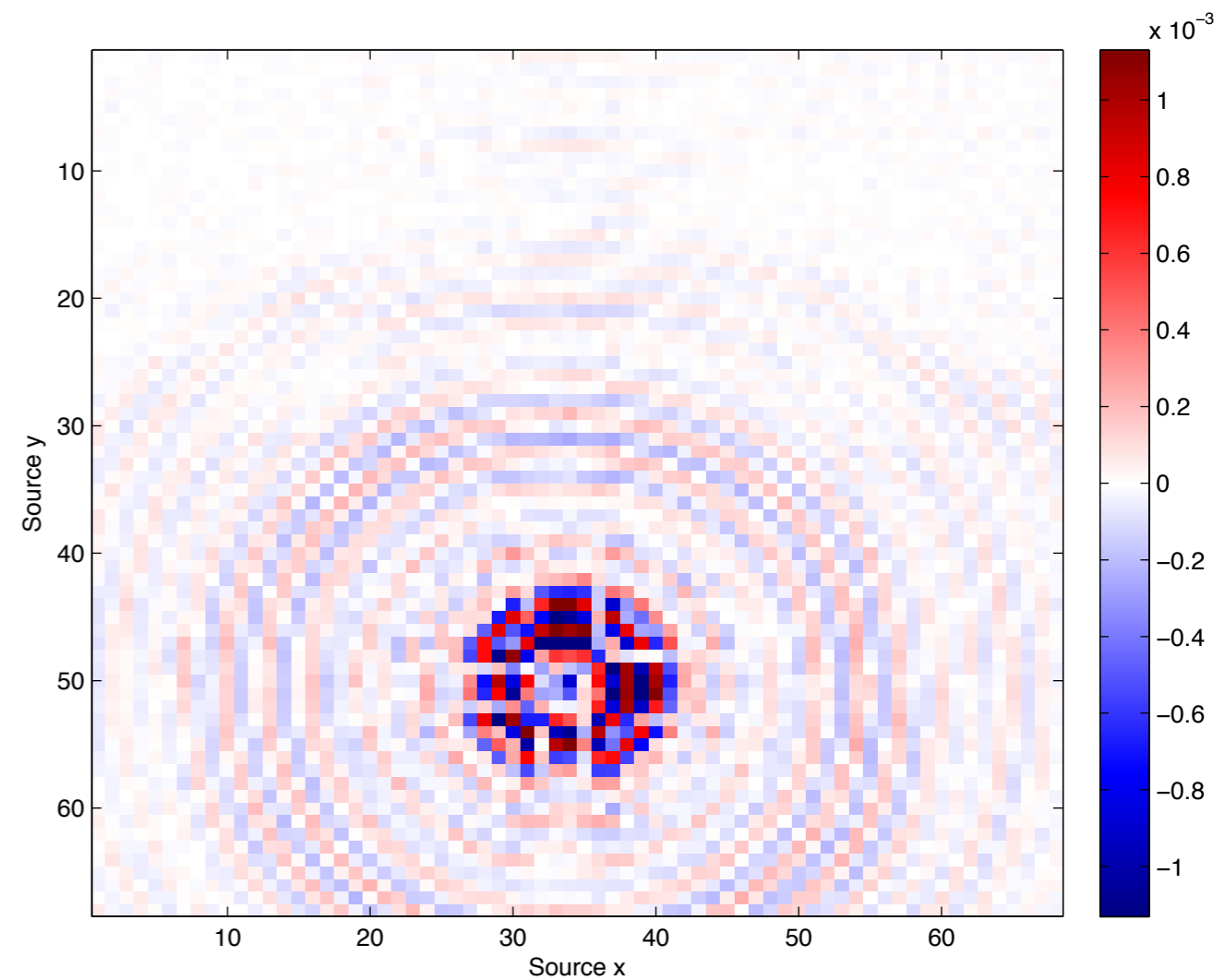
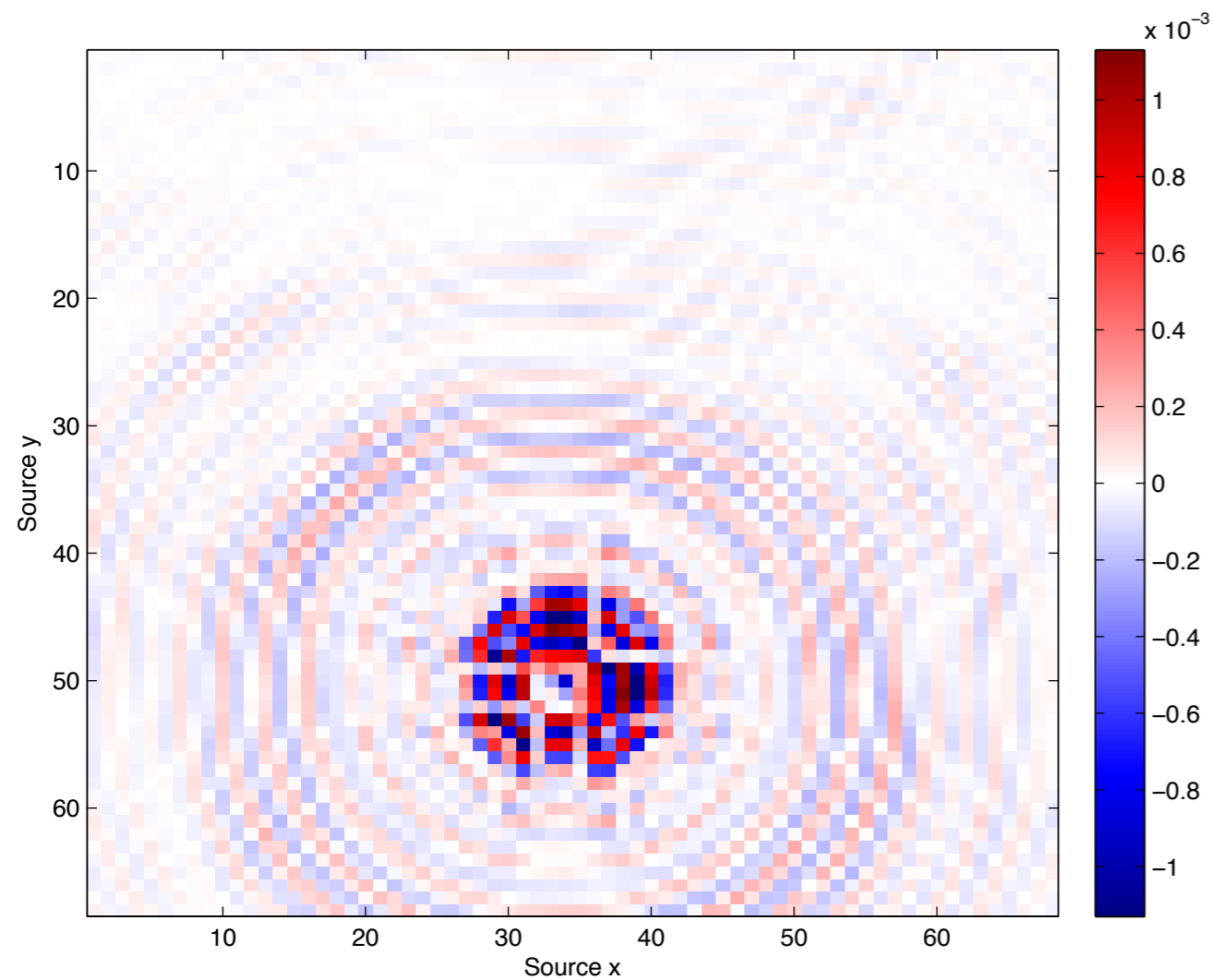


$$(x_{\text{rec}}, y_{\text{rec}}) = (75, 50)$$

Subsampled Data

# 7.34 Hz - 75% missing sources

Common receiver gather



$$(X_{\text{rec}}, Y_{\text{rec}}) = (75, 50)$$

Interpolated Data  
SNR 11.3 dB

# Compressive sensing

with sparsity promotion

Successful reconstruction scheme

- Signal structure - *sparsity*
- Sampling - *subsampling decreases sparsity*
- Optimization - *look for sparsest solution*

# Multidimensional interpolation

## with Hierarchical Tucker

Successful reconstruction scheme

- **Signal structure - *Hierarchical Tucker***
- Sampling - *subsampling increases h-rank*
- Optimization - *fit data in the Hierarchical Tucker format*

# Matricization

- The *matricization* of a tensor  $X$  with dimensions  $1, \dots, d$  along the dimensions  $t = (t_1, \dots, t_r)$  is the matrix formed by placing the dimensions  $t$  along the rows and dimensions  $t^c$  along the columns
- Denoted  $X^{(t)}$



# Example in Matlab

```
n1 = 20; n2 = 20; n3 = 20; n4 = 20;
% Tensor
x = randn(n1,n2,n3,n4);
% Matricization along dimensions 1 and 2
 $X^{(1,2)}$  x12 = reshape(x,n1 * n2, n3 * n4);
% Matricization along dimensions 3 and 4
 $X^{(3,4)}$  y34 = permute(x,[3 4 1 2]);
x34 = reshape(x, n3 * n4, n1 * n2);
% Matricization along dimensions 1 and 3
 $X^{(1,3)}$  y13 = permute(x,[1 3 2 4]);
x13 = reshape(x,n1 * n3, n2 * n4);
```

# Kronecker product

$A, B$  Matrices

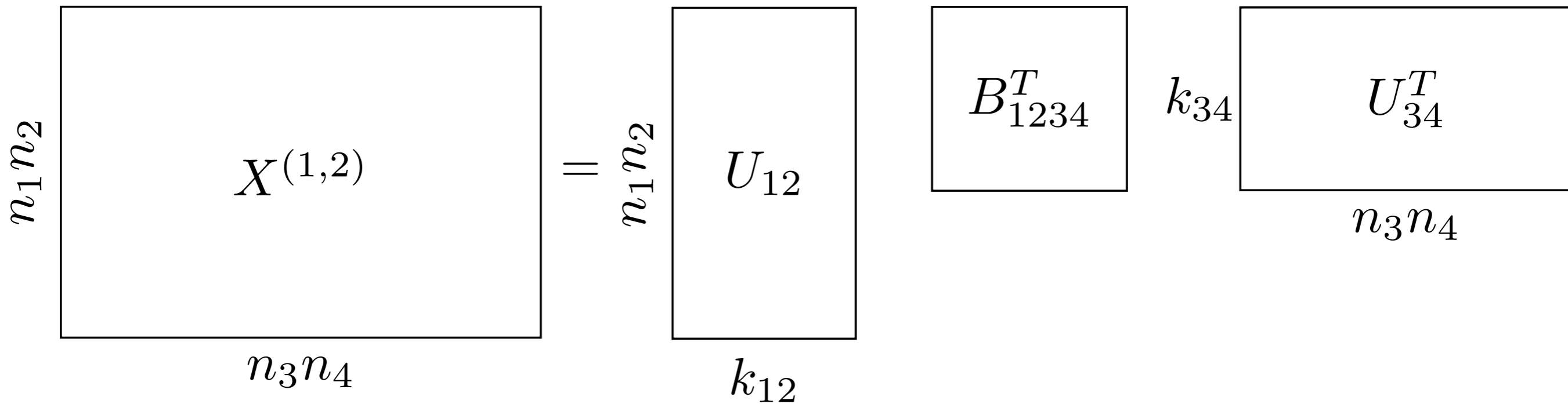
$B \otimes A$  Kronecker product

$$(B \otimes A) \text{vec}(X) = \text{vec}(AXB^T)$$

$A$  acts along the columns of  $X$

$B$  acts along the rows of  $X$

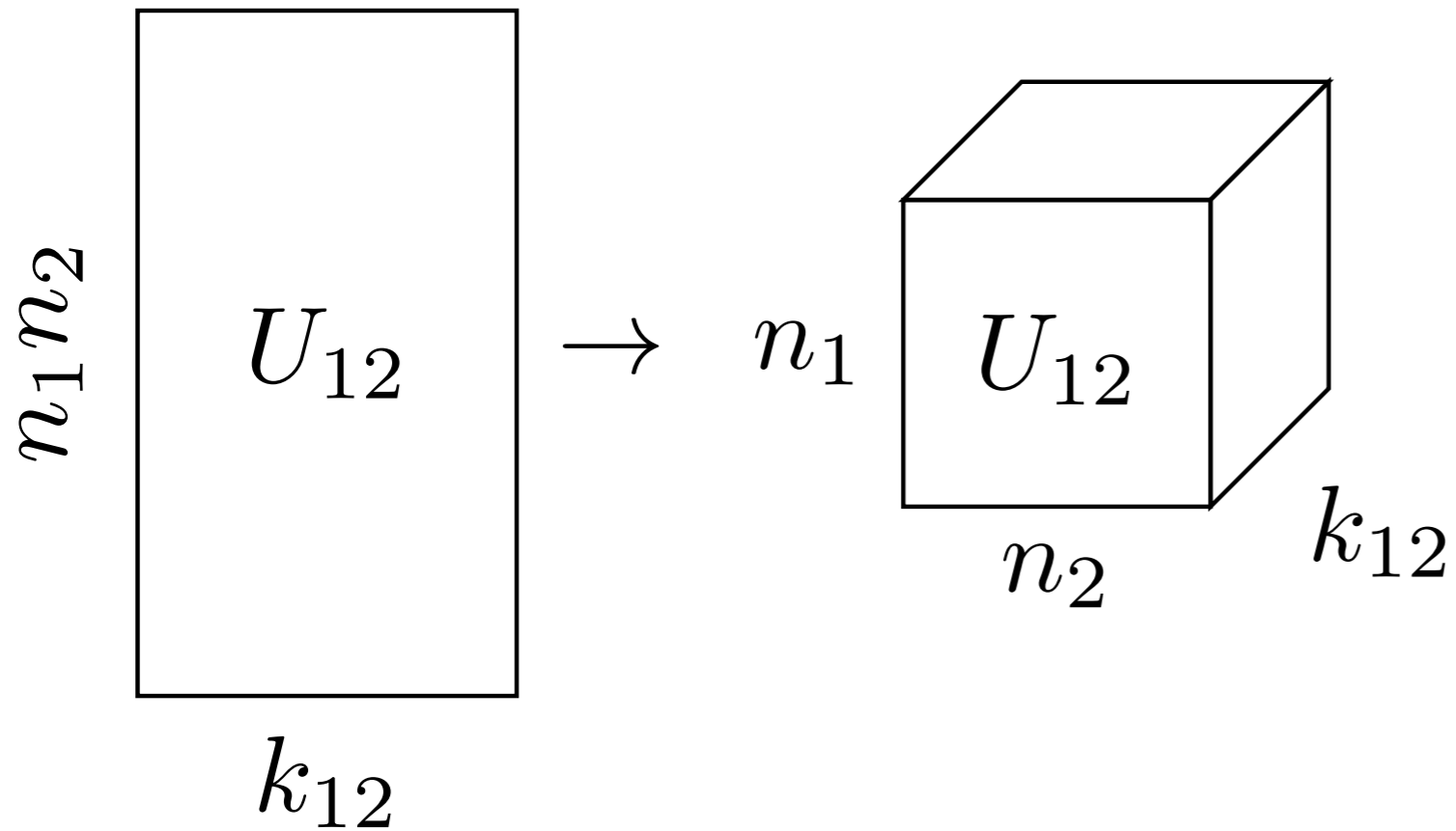
# HT Format $X - n_1 \times n_2 \times n_3 \times n_4$ tensor



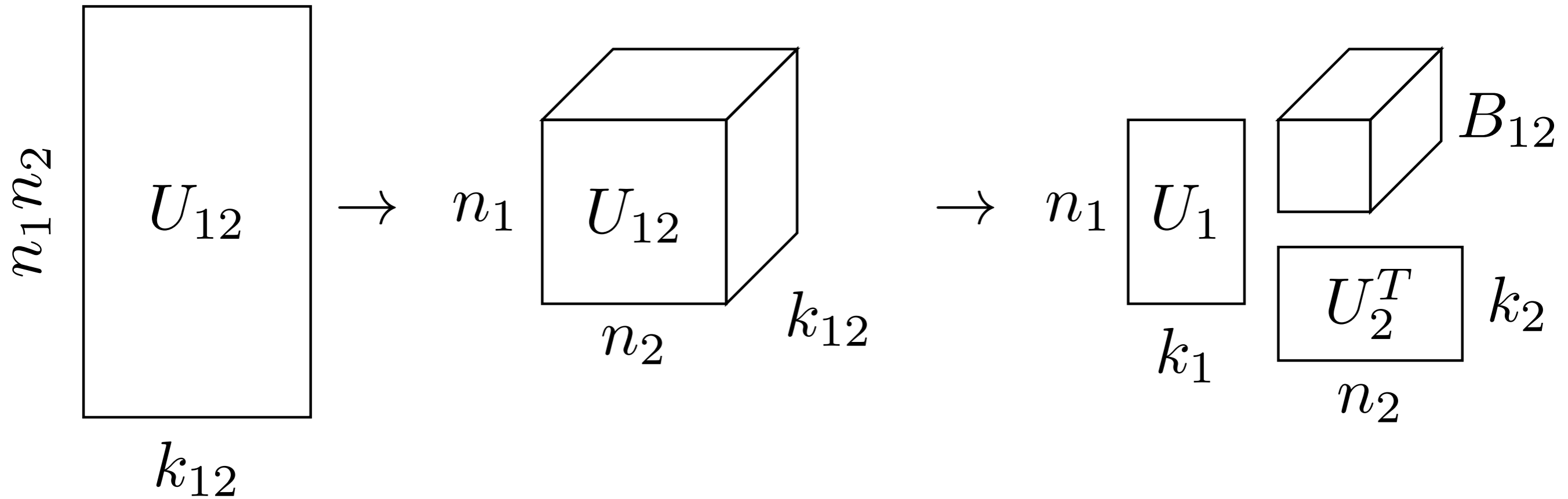
$$\text{vec}(X) = (U_{12} \otimes U_{34}) \text{vec}(B_{1234})$$

$$X^{(1,2)} = U_{12} B_{1234}^T U_{34}^T$$

# HT Format $X - n_1 \times n_2 \times n_3 \times n_4$ tensor



# HT Format $X - n_1 \times n_2 \times n_3 \times n_4$ tensor

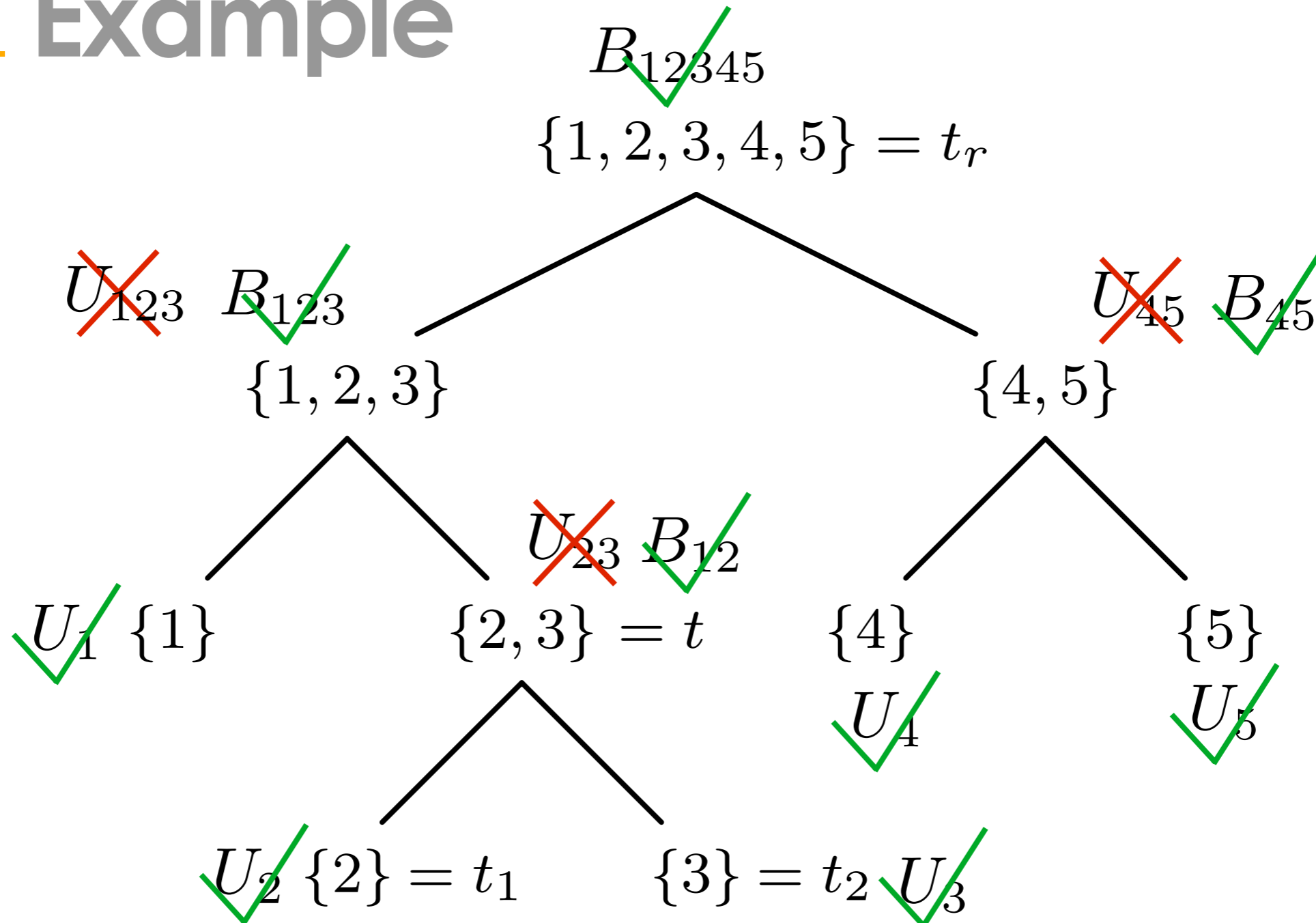


# Hierarchical Tucker Format

- Intermediate matrices don't need to be stored
- $U_t, B_t$  - small parameter matrices
  - specify the tensor completely

A. Uschmajew, B. Vandereycken. The geometry of algorithms using hierarchical tensors. 2012

# Example



# Hierarchical Tucker Format

- Storage  $\leq dNK + (d - 2)K^3 + K^2$
- Compare to  $N^d$  storage for the full tensor
- Effectively breaking the curse of dimensionality when  $K \ll N$
- Low frequency data compresses



# Hierarchical Tucker Format

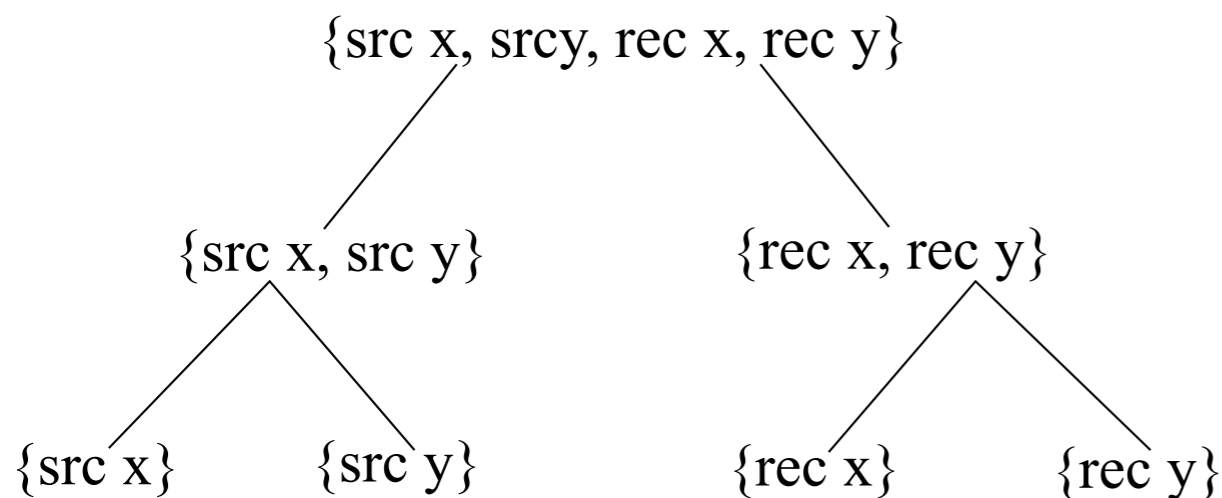
- E.g. for a  $100 \times 100 \times 100 \times 100$  cube with max rank 20,  $N = 100$   $d = 4$   $k = 20$   
Naive storage:  $N^d = 10^8$  parameters  
HTucker storage:  $= 24400$   
parameters  
Compression of a factor of **99.97%**

# Seismic HTucker

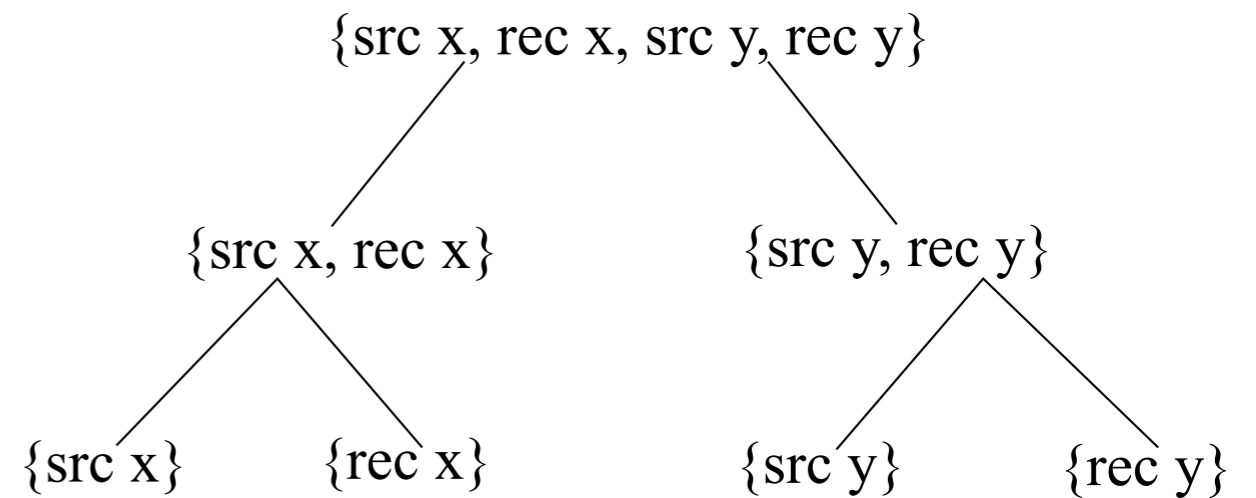
- We consider a 3D seismic survey with coordinates  
(src x, src y, rec x, rec y, time)
- We take a Fourier transform in time and restrict ourselves to a single frequency slice

# Seismic HTucker

For a frequency slice with coordinates (src x, src y, rec x, rec y), there are essentially two choices of dimension splitting (by reciprocity)

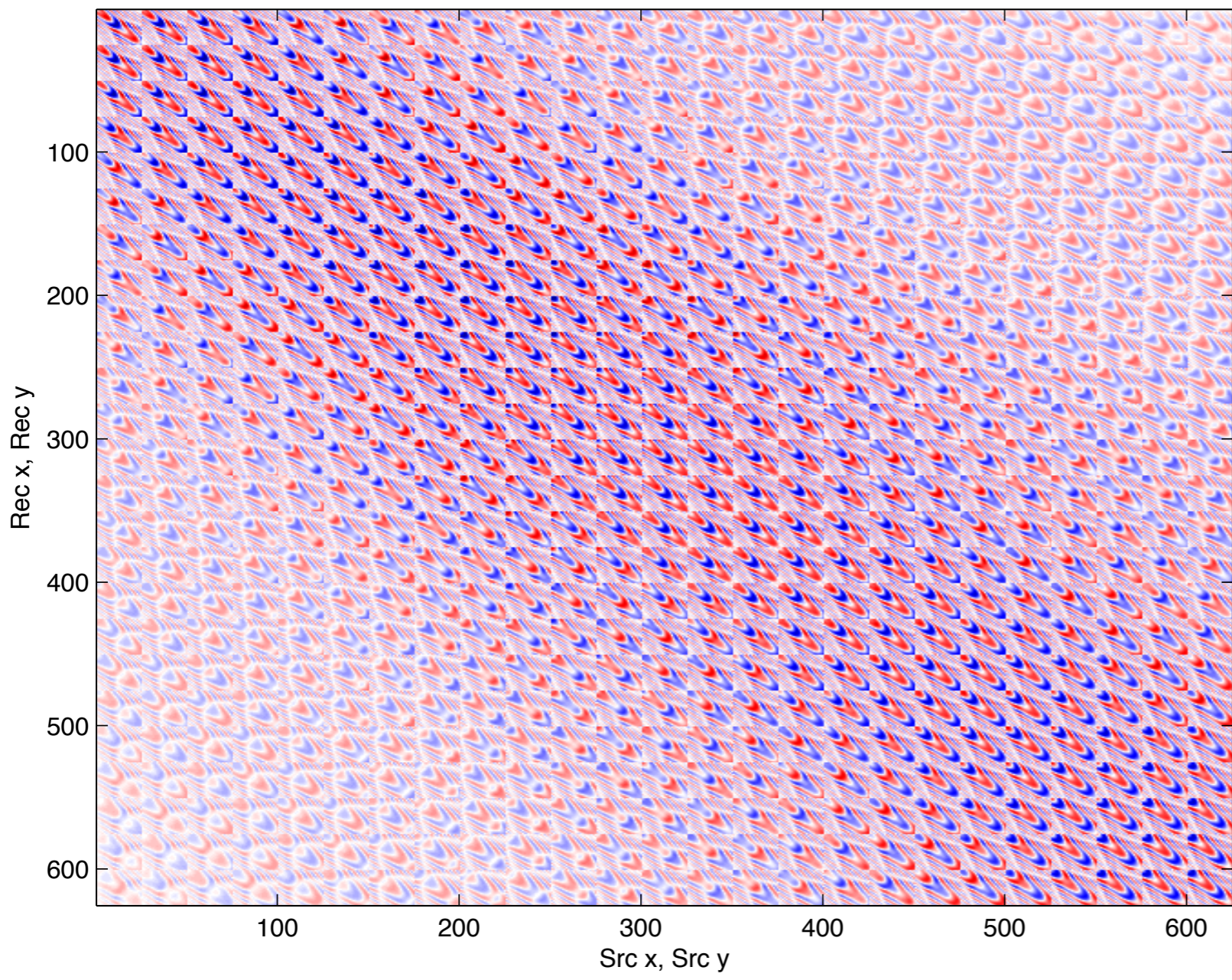


Canonical Decomposition

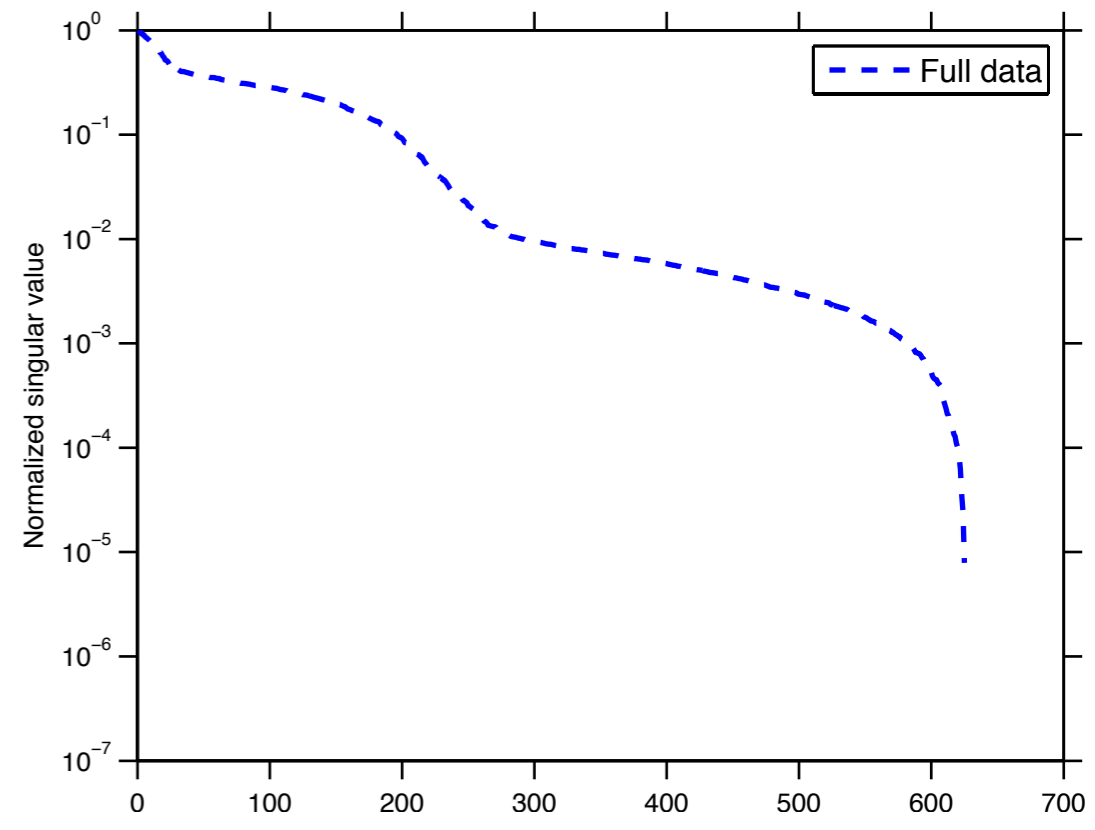
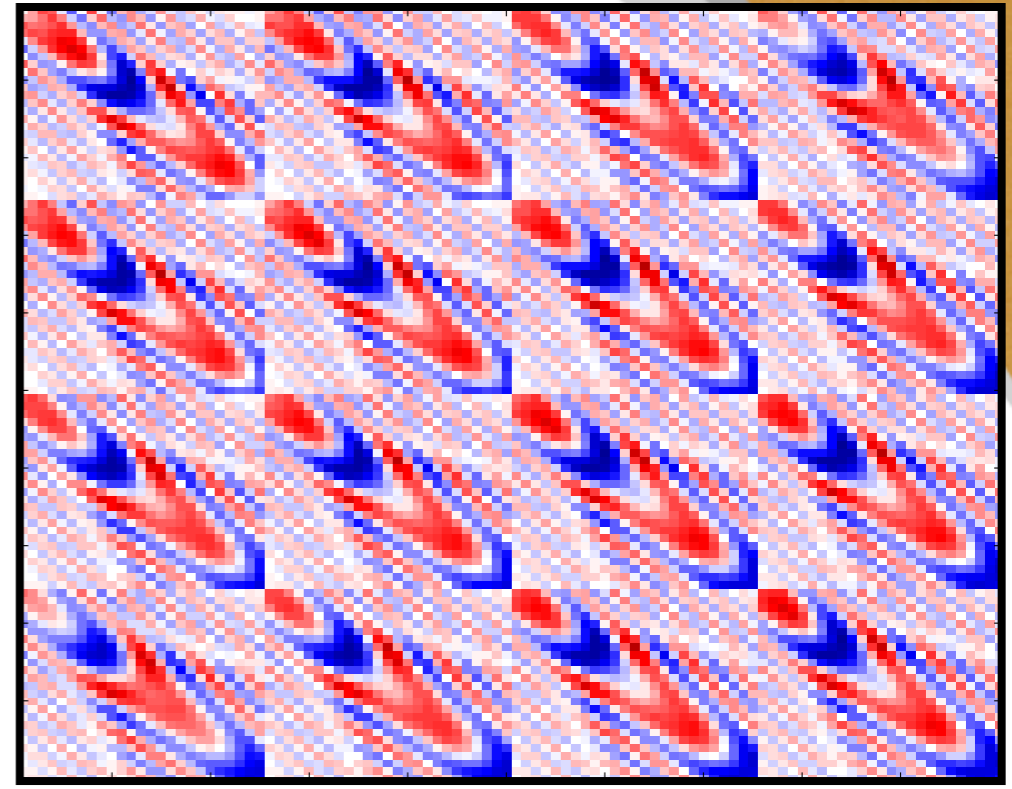


Non-canonical Decomposition

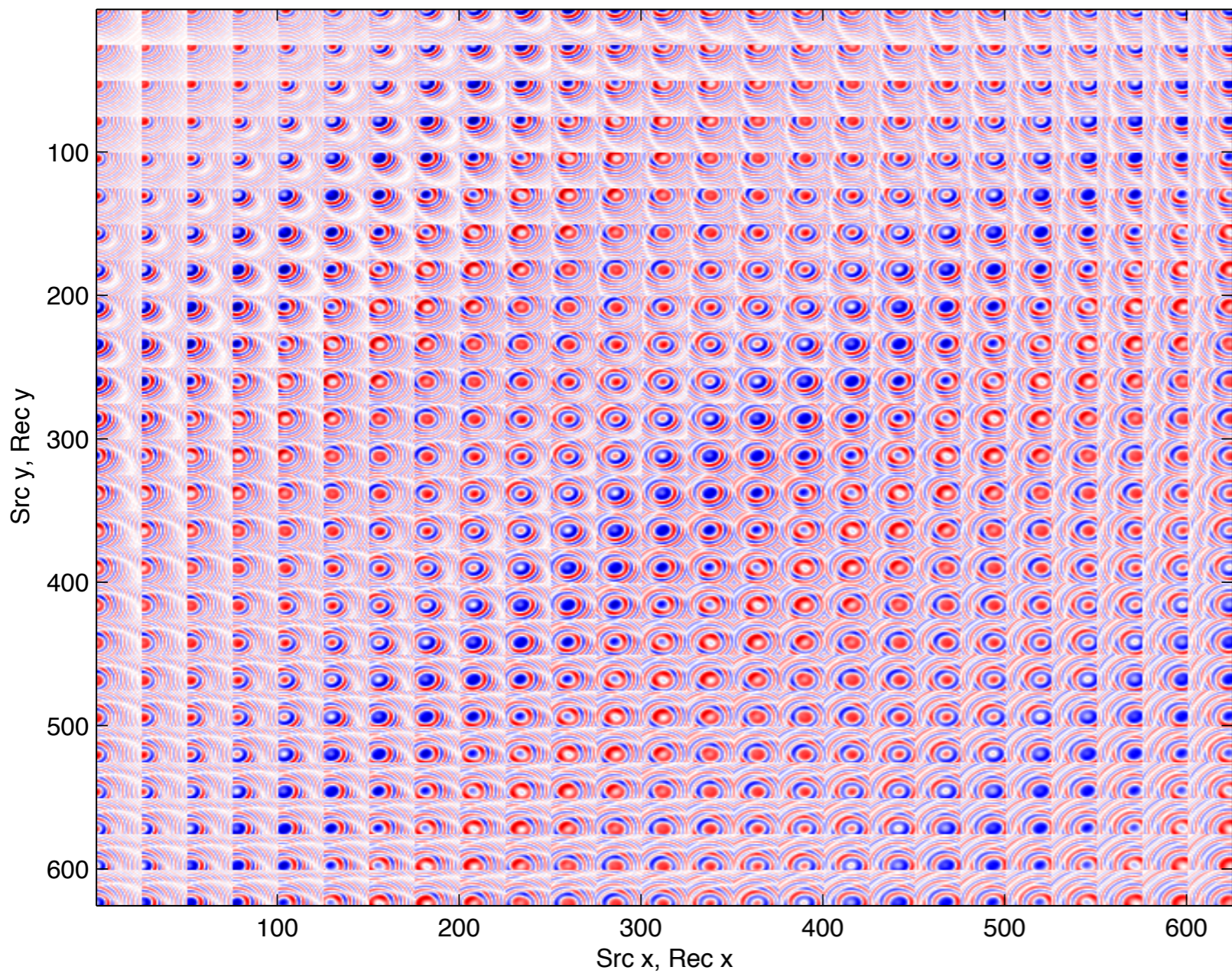
# Matricizations



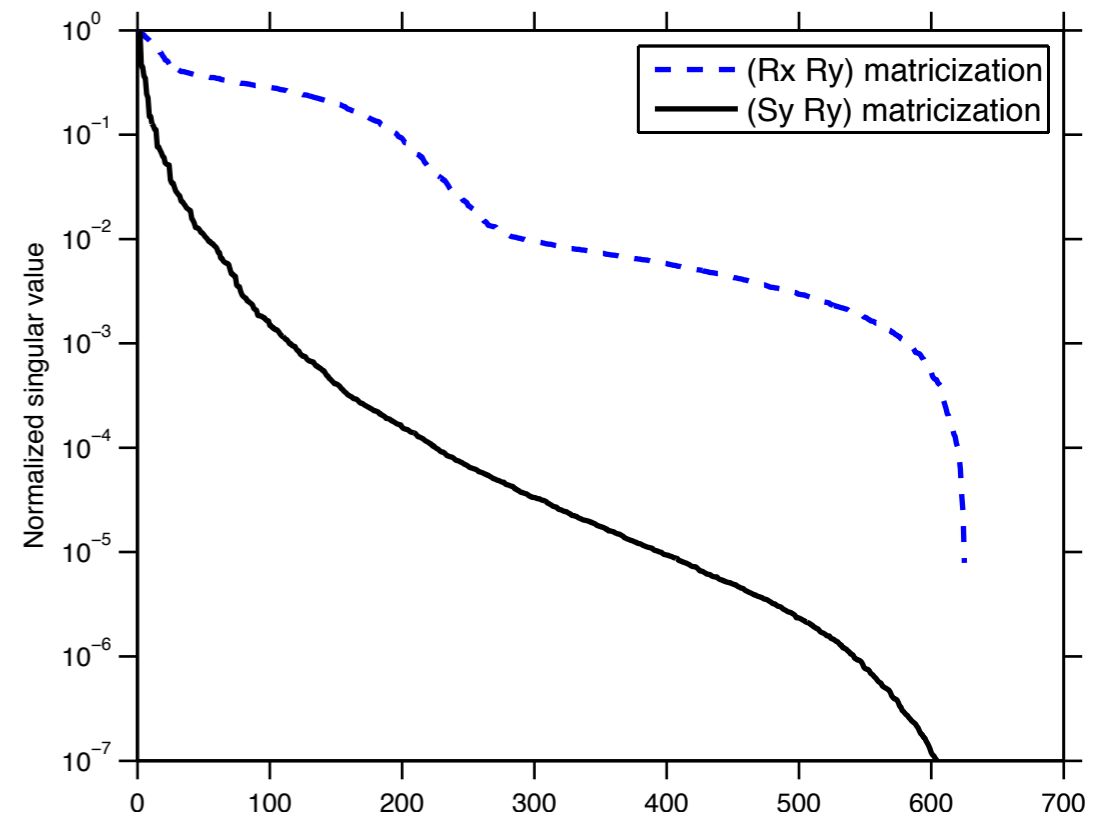
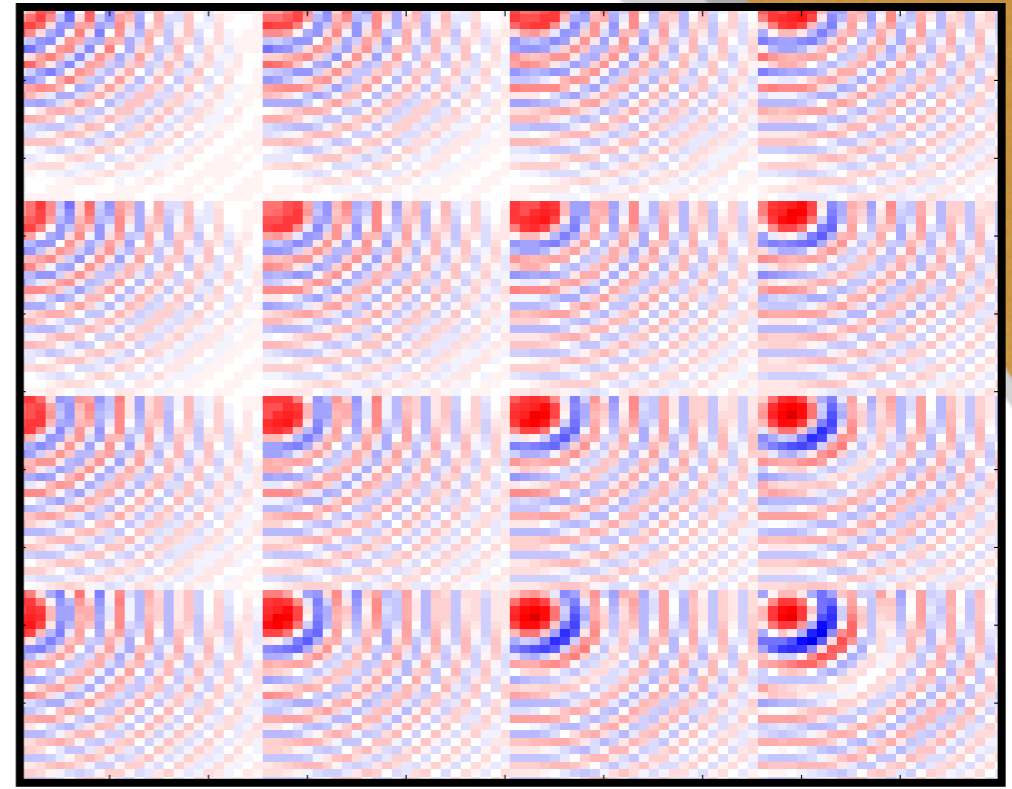
(Rec x, Rec y) matricization - full data



# Matricizations



(Src y, Rec y) matricization - full data

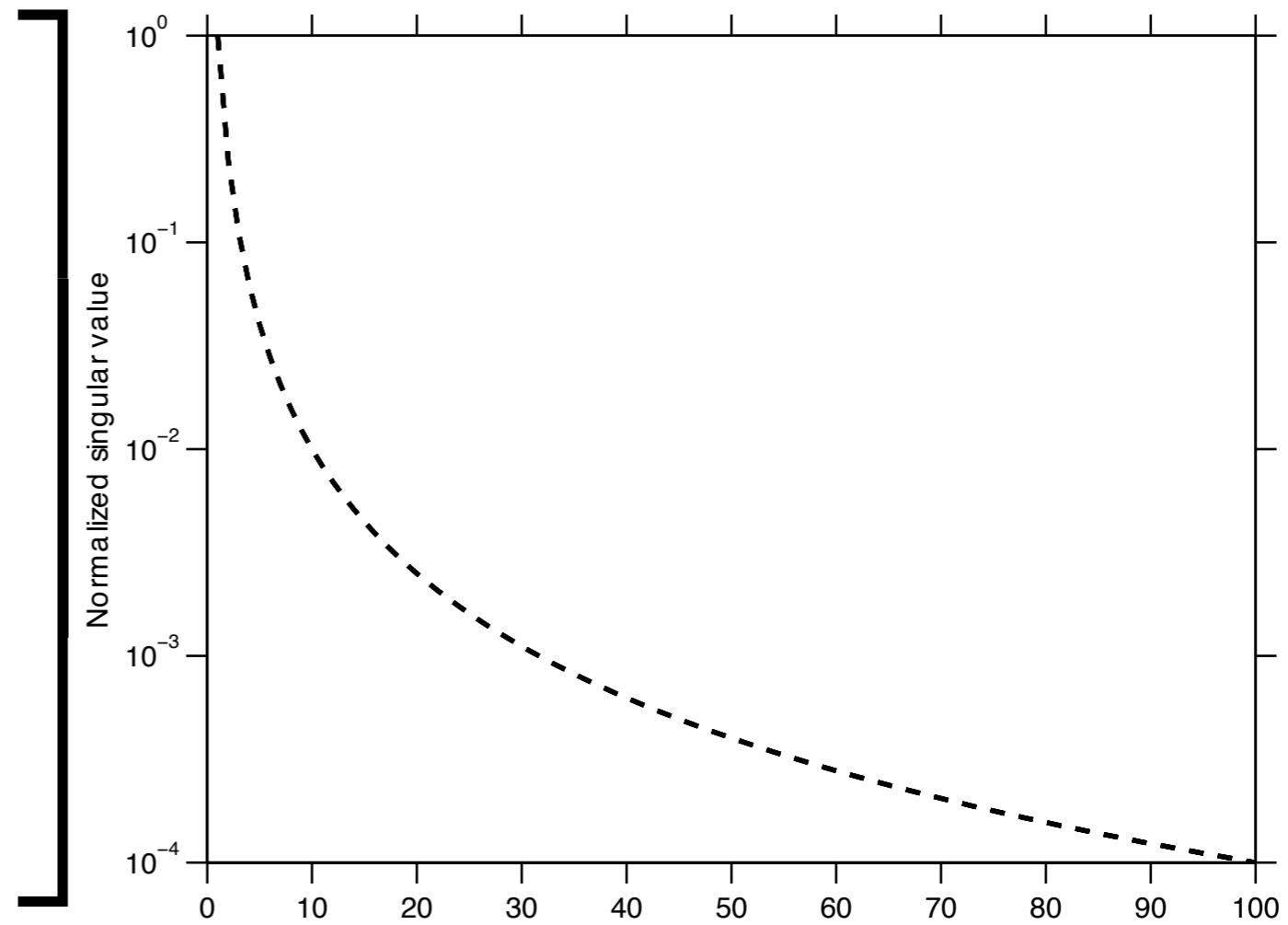
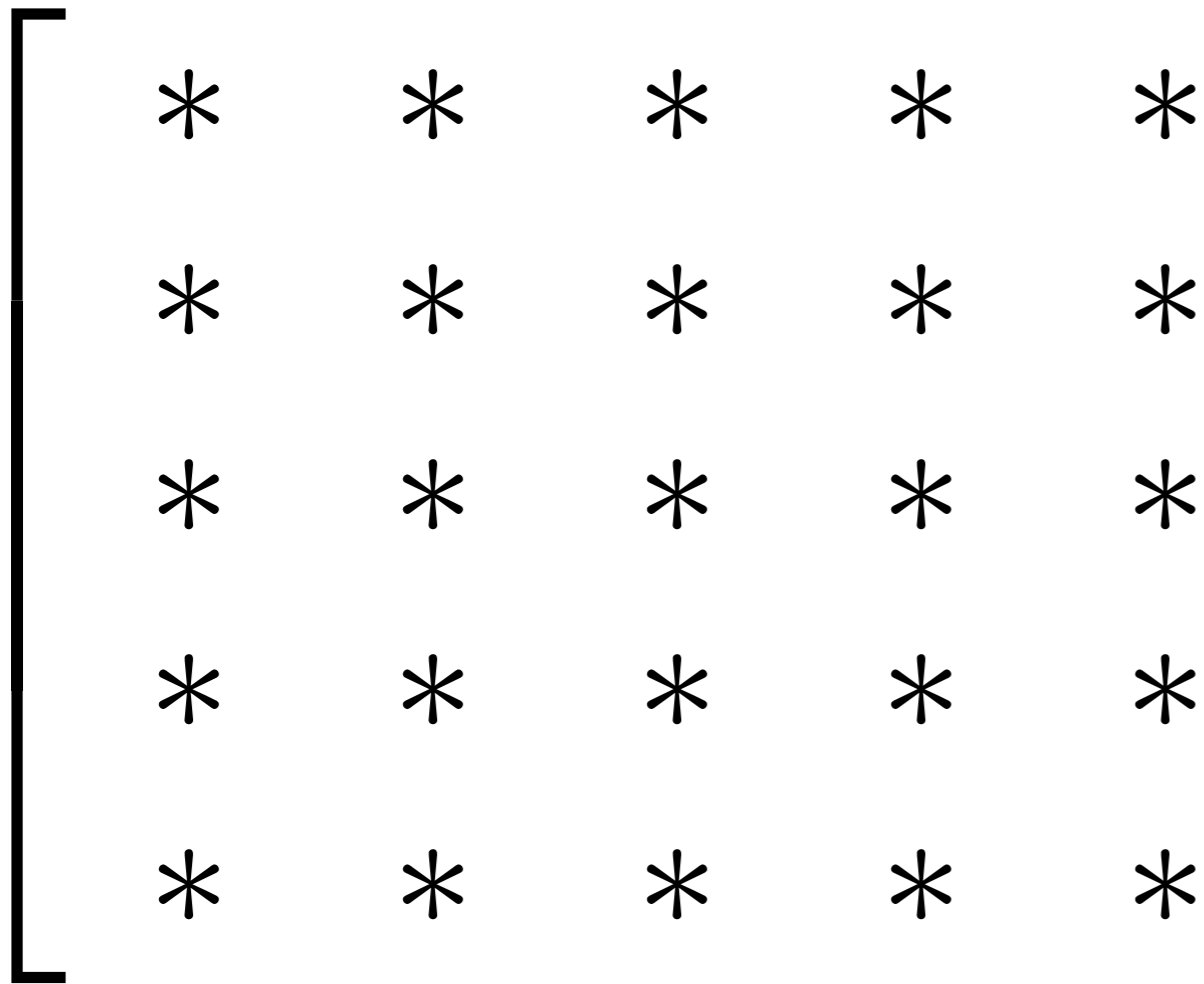


# Multidimensional interpolation

Successful reconstruction scheme

- Signal structure - *Hierarchical Tucker*
- **Sampling** - *subsampling increases h-rank*
- Optimization - *fit data in the Hierarchical Tucker format*

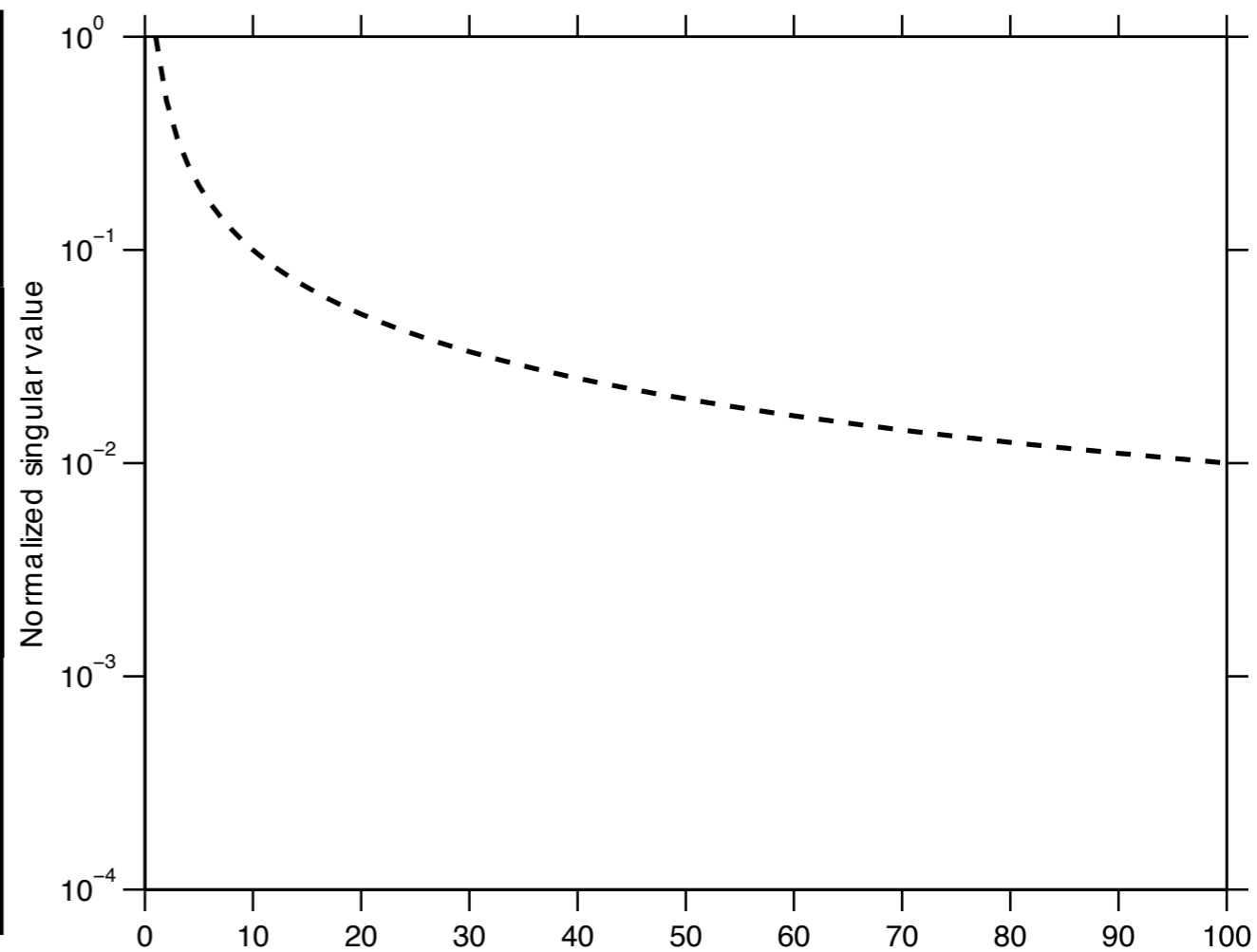
# Matrix Completion

 $X$ 

# Matrix Completion

 $\mathcal{A}(\mathbf{X})$ 

$$\begin{bmatrix} * & * & * & 0 & * \\ * & 0 & 0 & * & 0 \\ * & * & * & * & * \\ * & * & 0 & * & * \\ 0 & * & * & * & 0 \end{bmatrix}$$





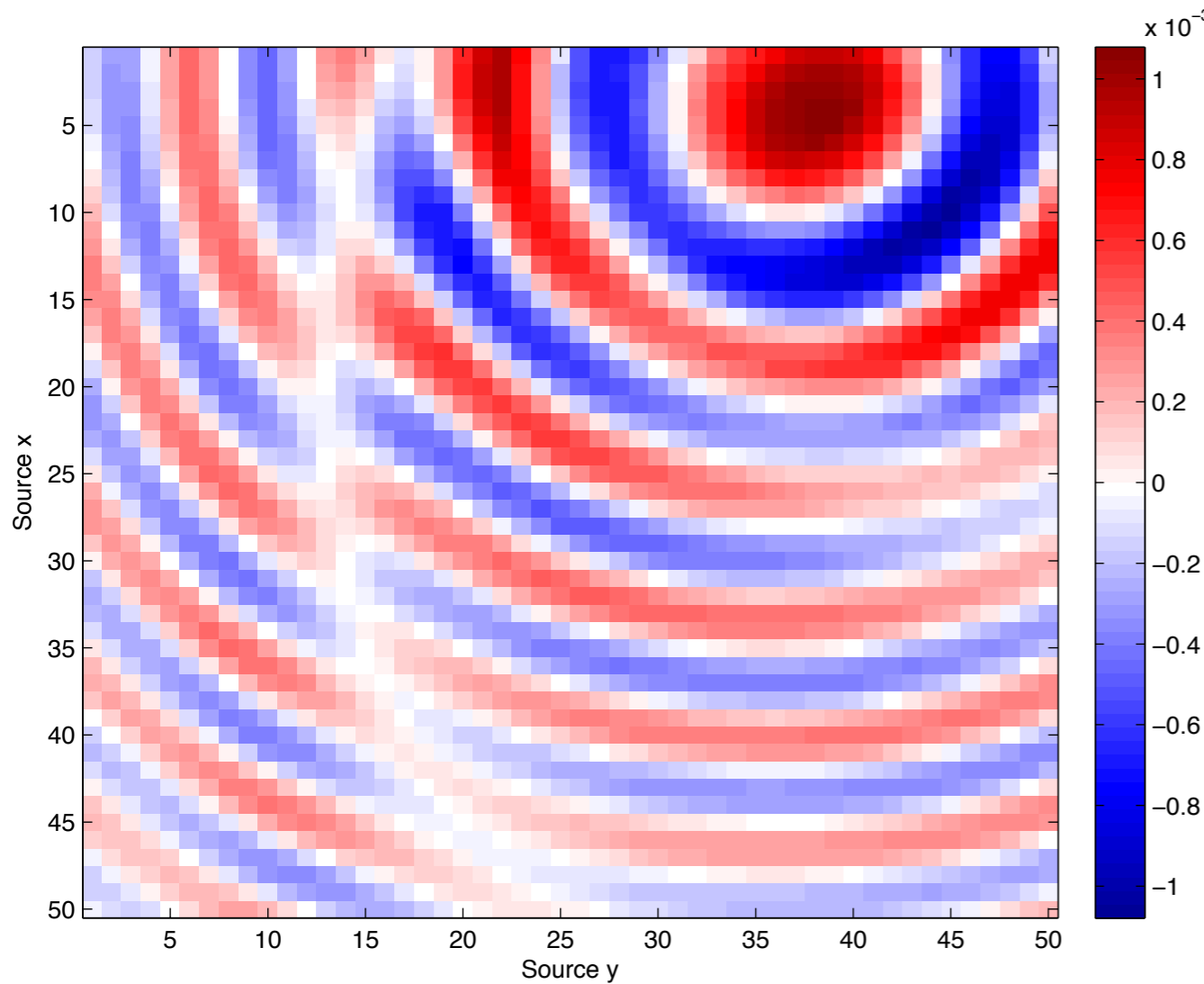
# Tensor Completion

- *Structure* - recover a *tensor*  $\mathbf{X}$  which has low *hierarchical* rank
  - Well represented in HT
- *Sampling* - random removal of points *increases* rank
  - Poorly represented in HT
  - Idealized sampling

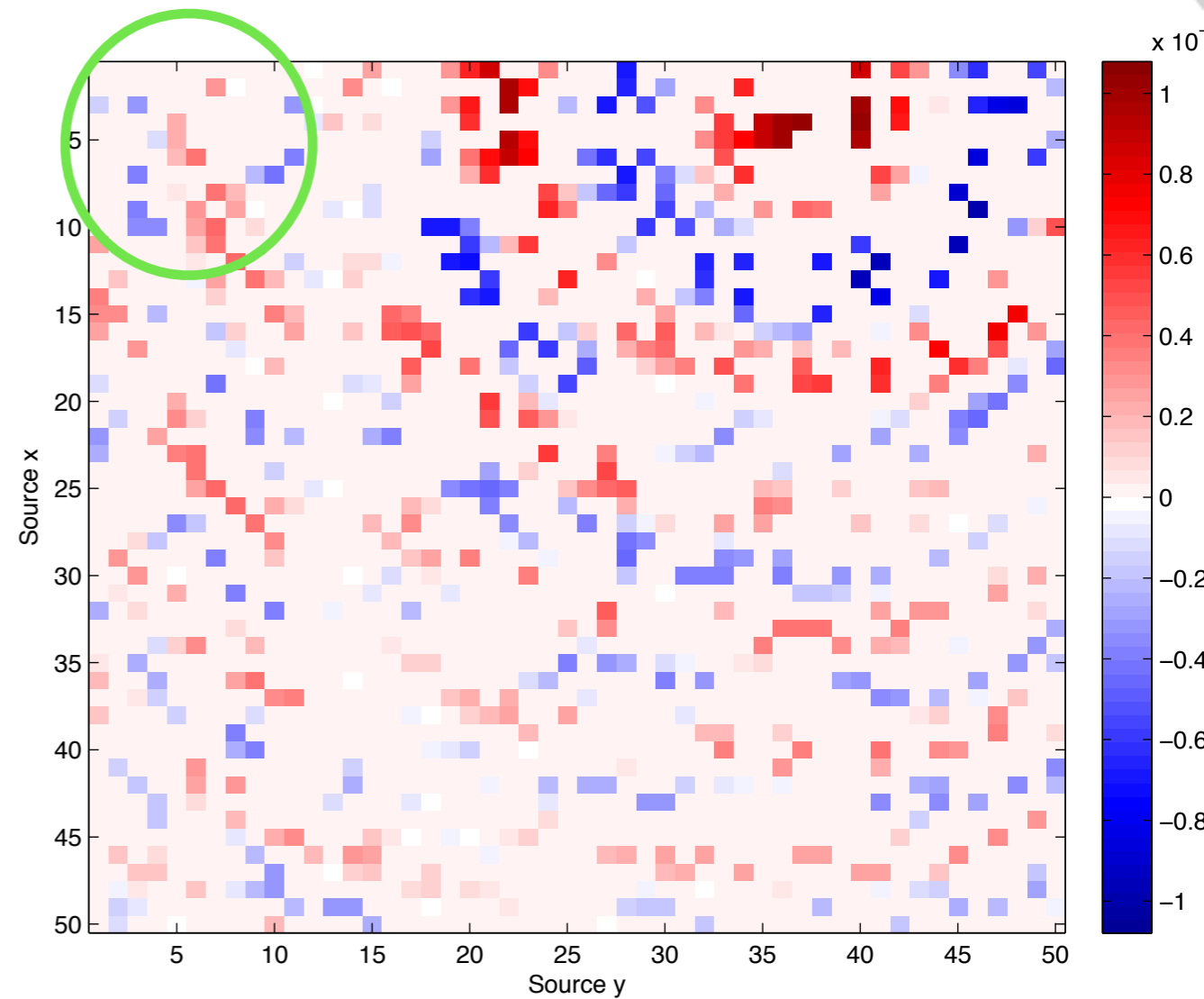
# Idealized recovery

75% random entries removed

Common shot gather



True Data

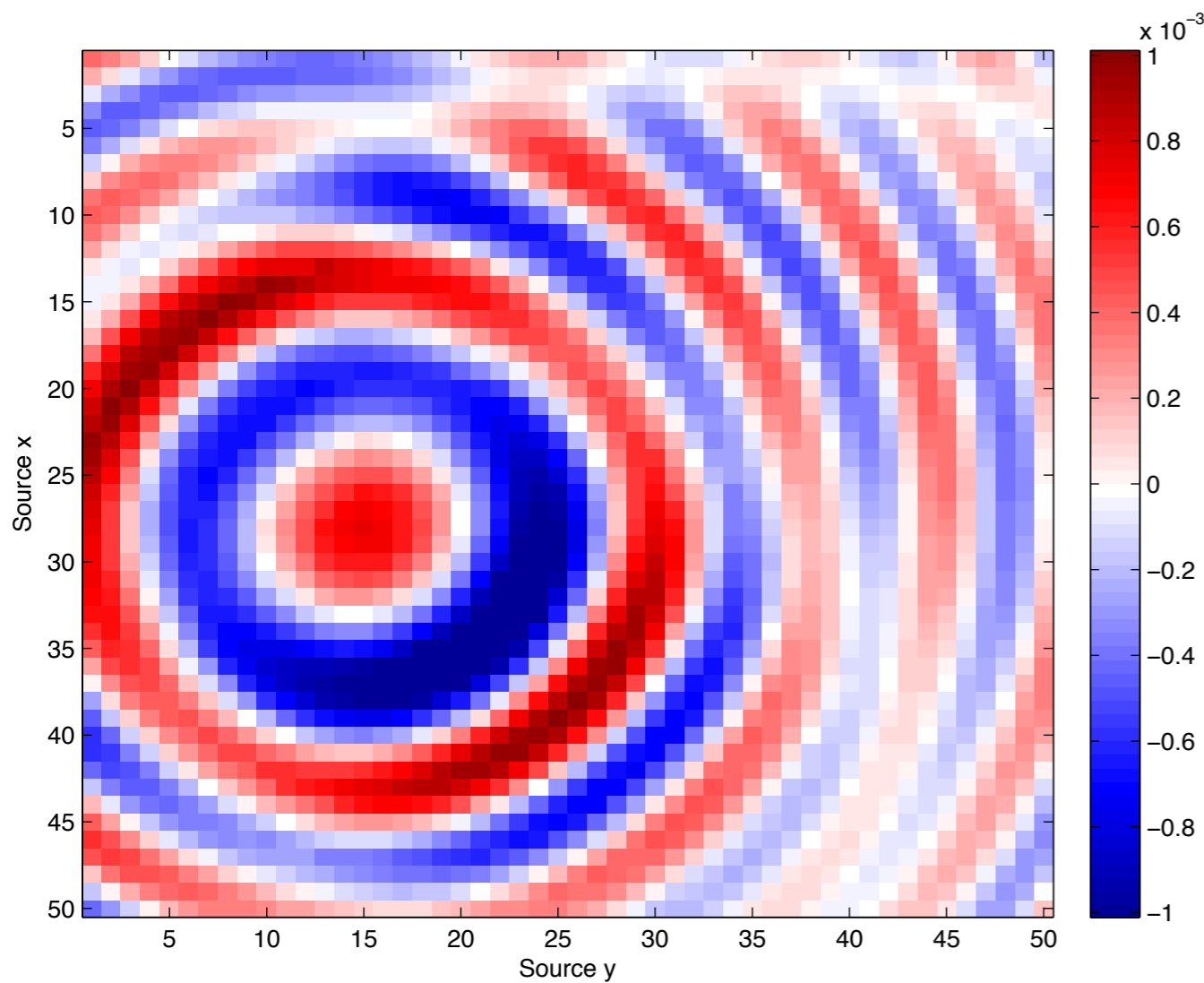


Subsampled Data

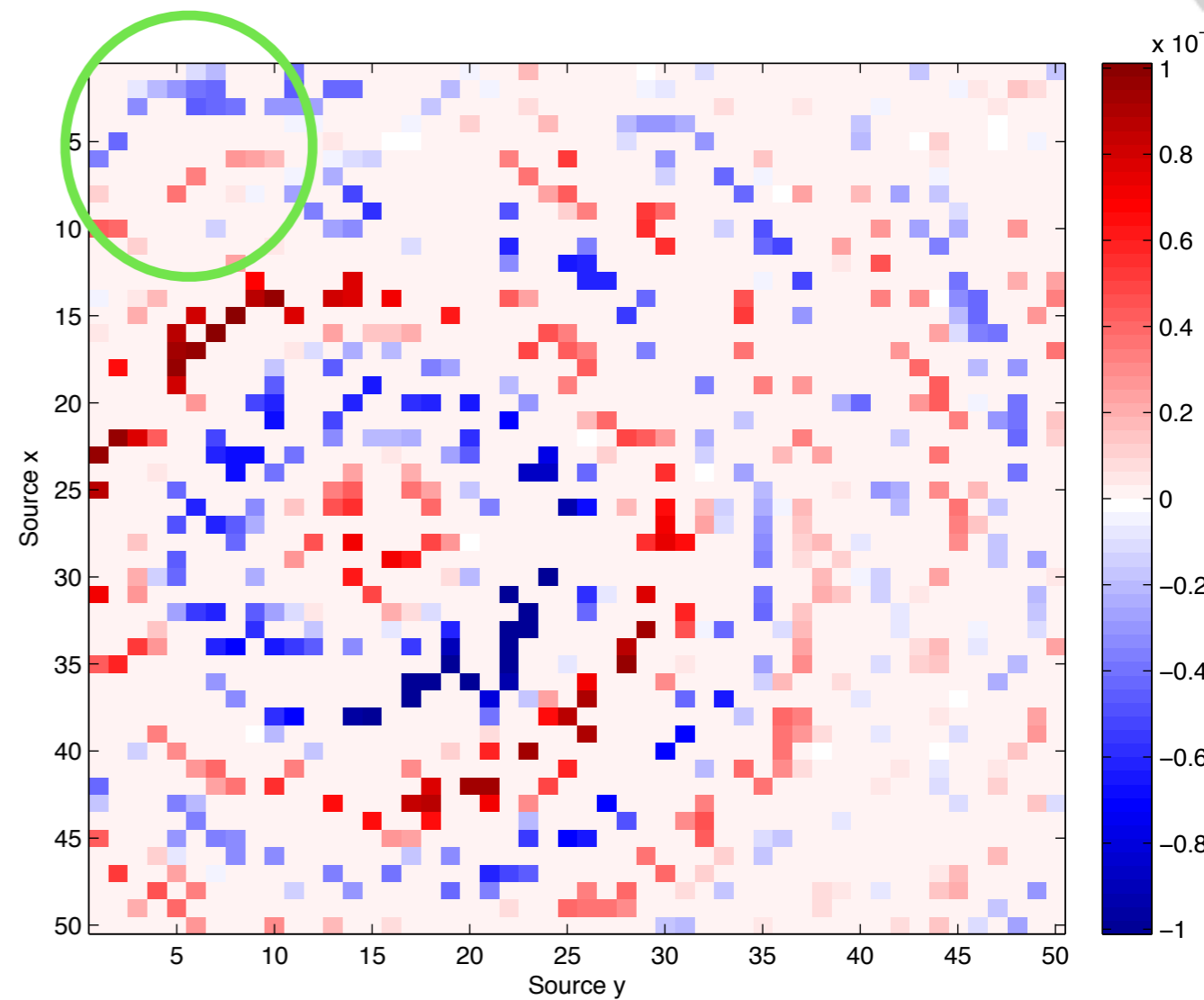
# Idealized recovery

75% random entries removed

Common shot gather



True Data

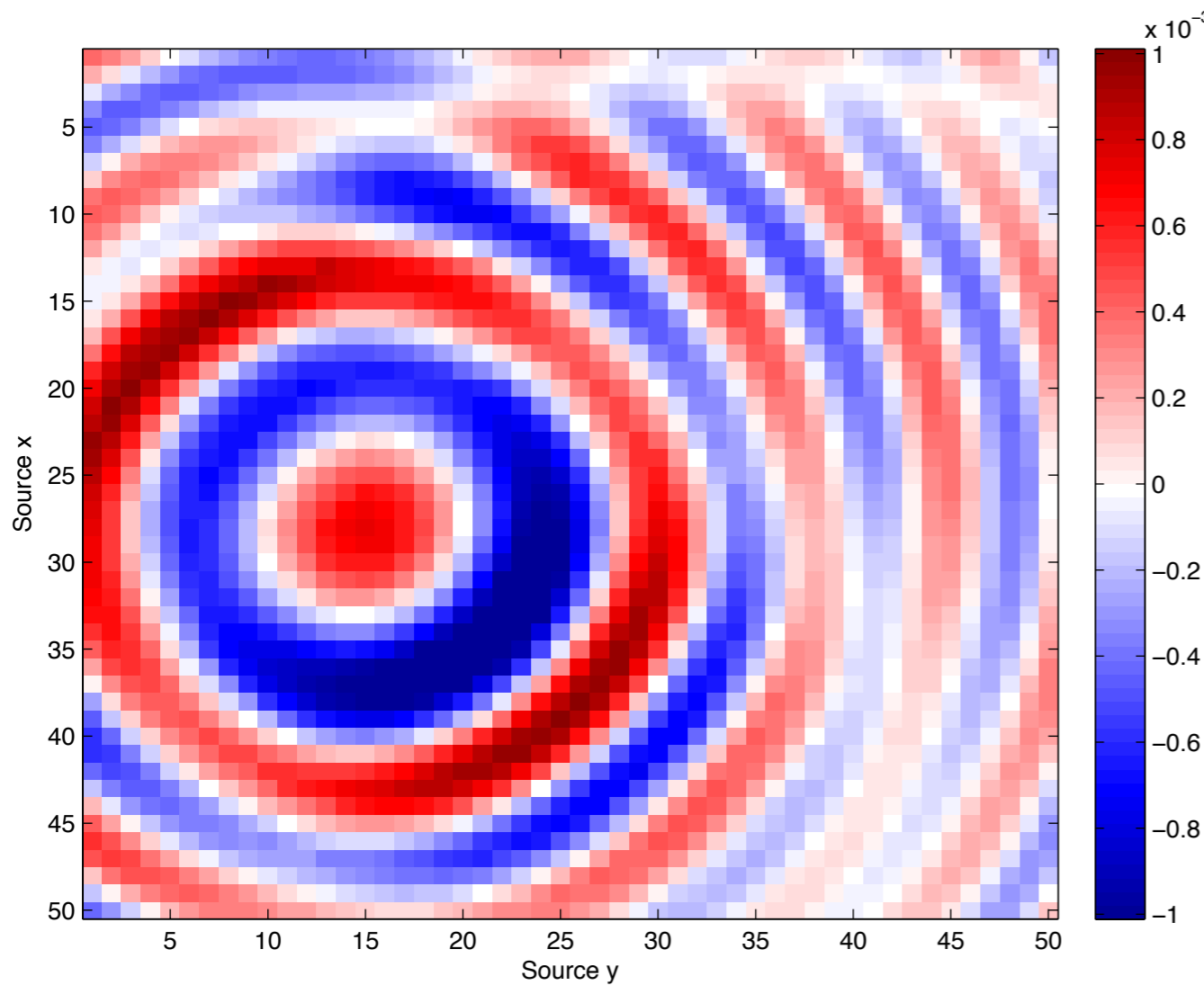


Subsampled Data

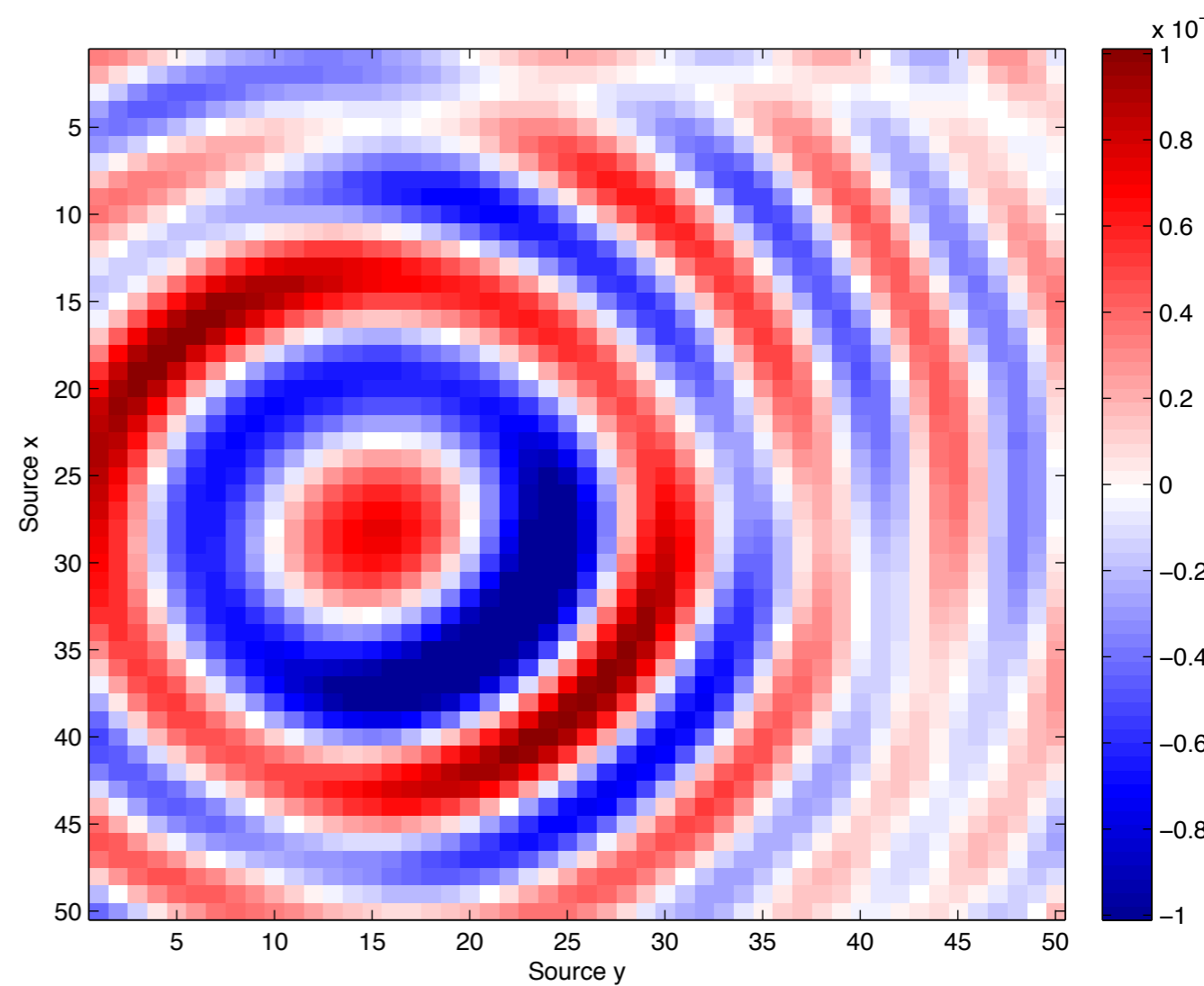
# Idealized recovery

75% random entries removed

Common shot gather



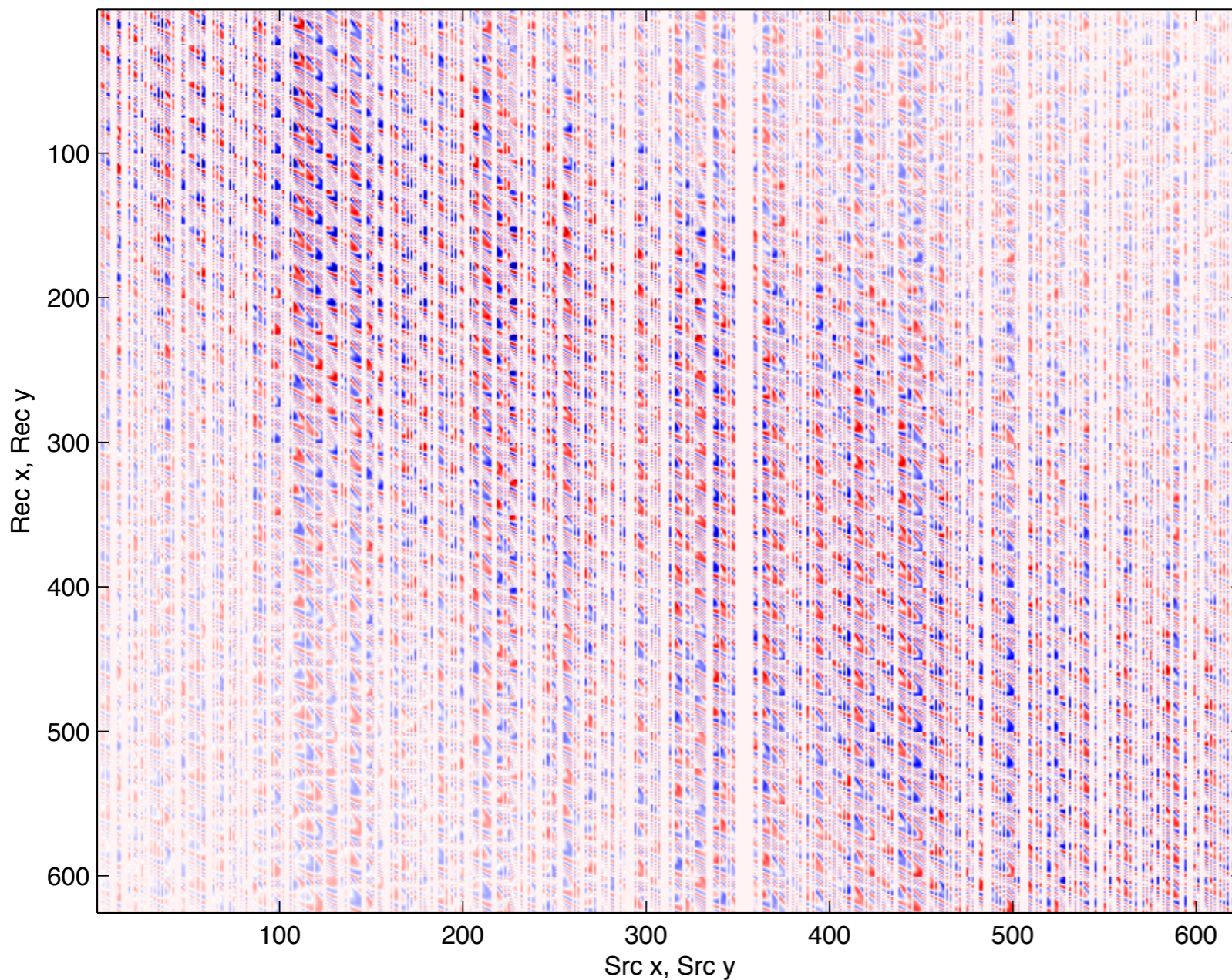
True Data



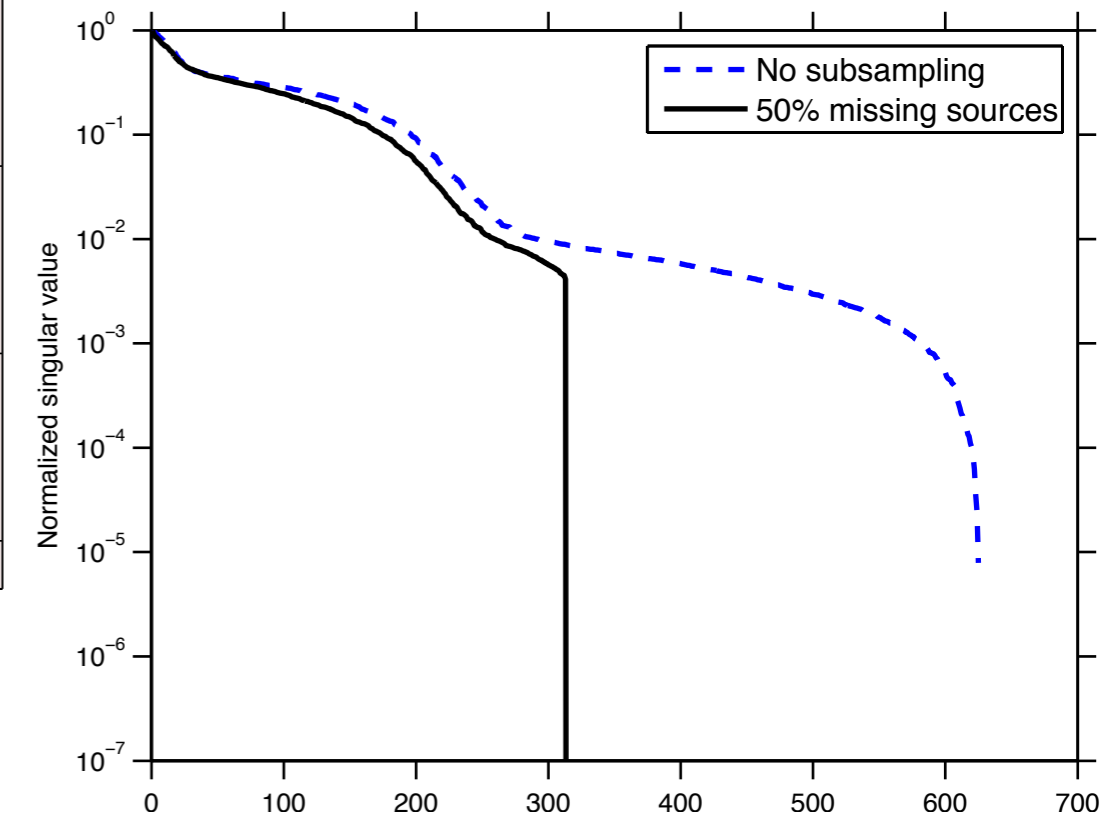
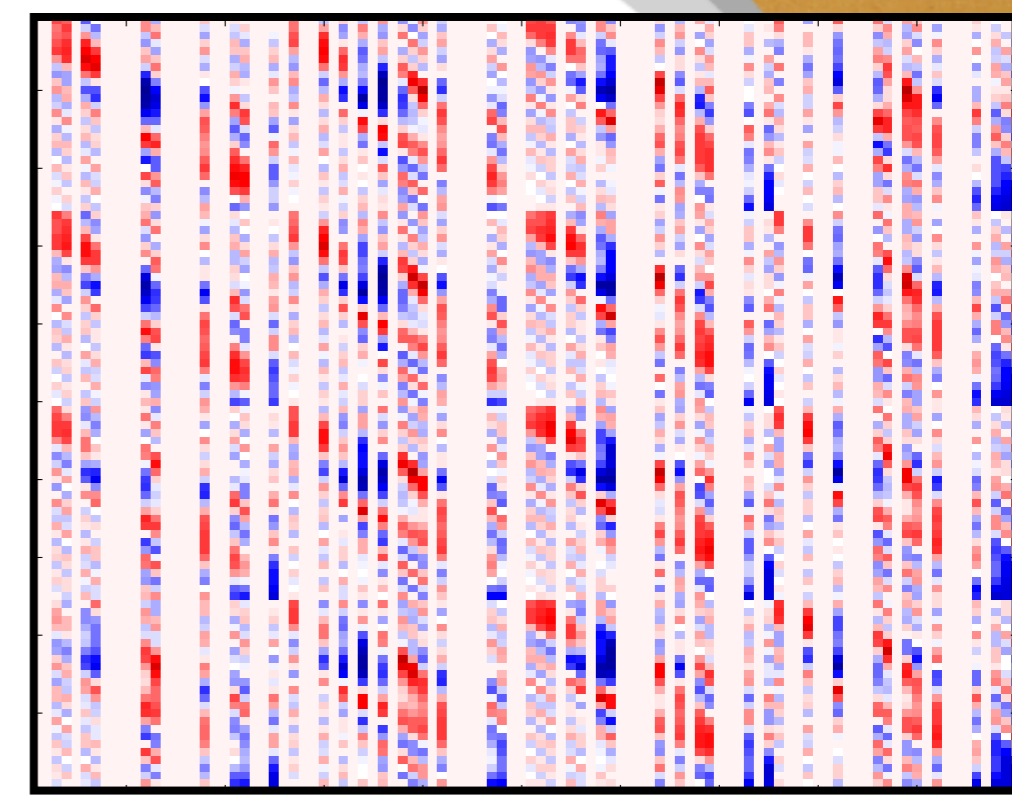
Recovered Shot

SNR 19.3 dB

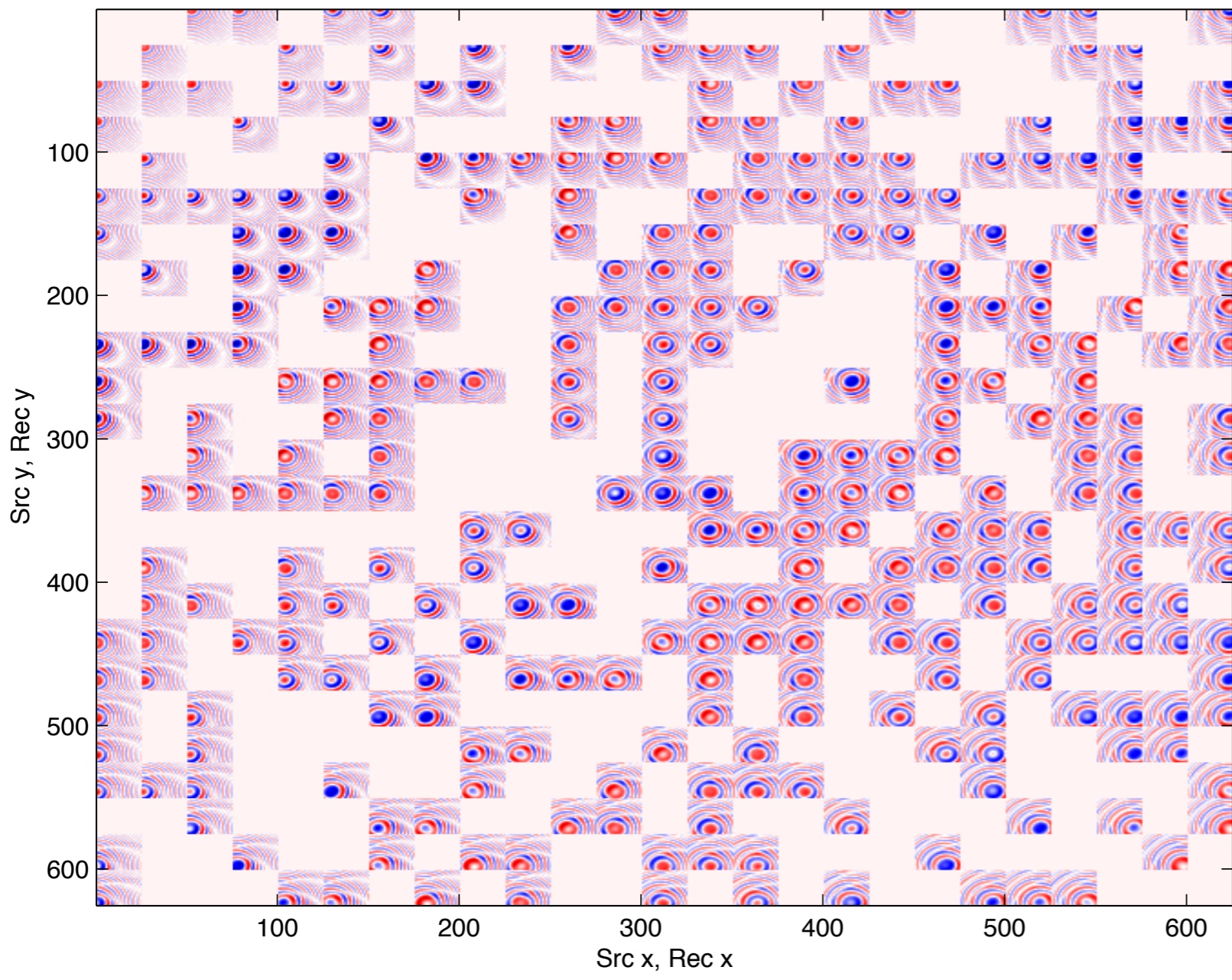
# Sampling



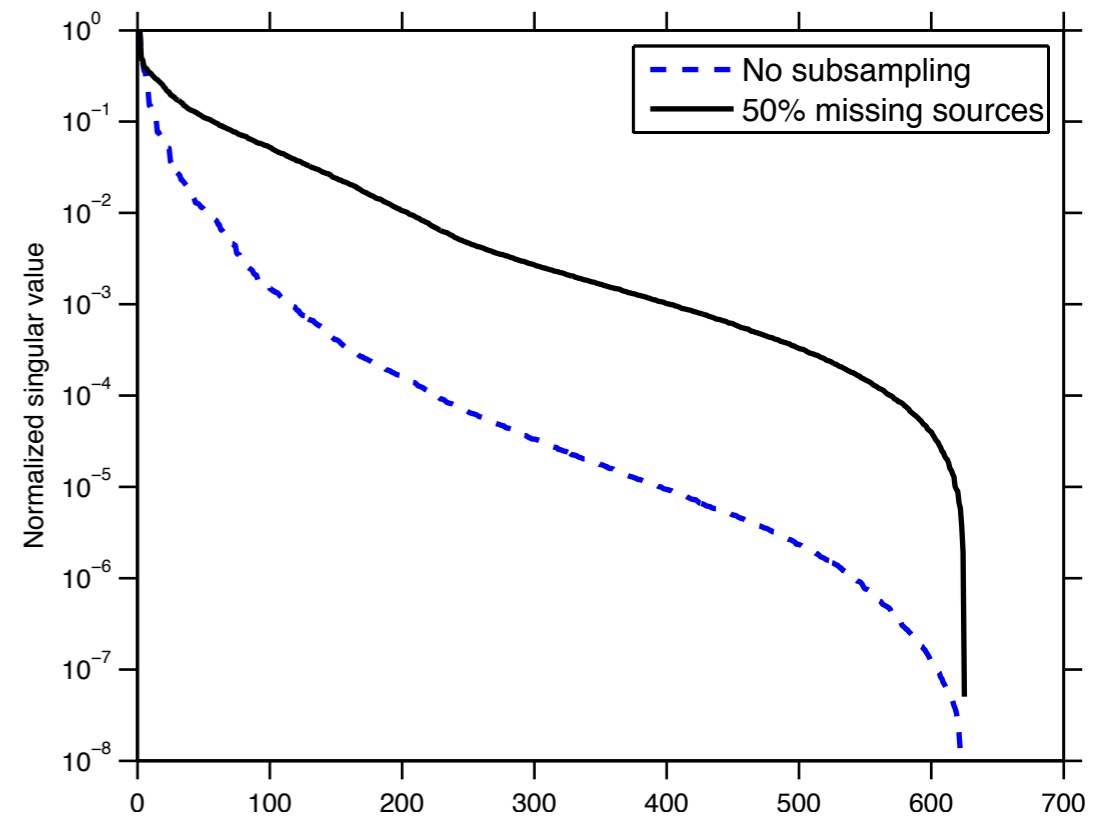
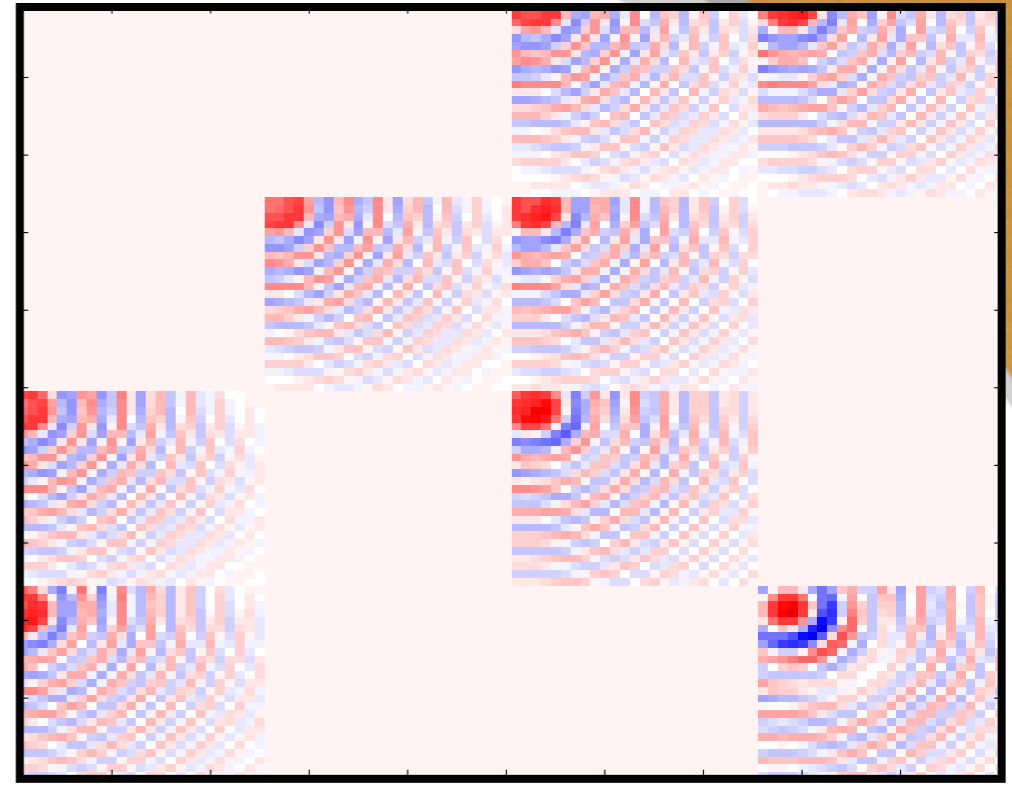
(Rec x, Rec y) matricization  
50% randomly missing sources



# Sampling



(Src y, Rec y) matricization  
50% randomly missing sources



# Data organization

- (rec x, rec y) organization
  - High rank
  - Missing sources operator - removes columns
  - Poor recovery scenario

# Data organization

- (src  $y$ , rec  $y$ ) decomposition
  - Low rank
  - Missing sources operator - removes blocks
  - Closer to ideal recovery scenario



# Multidimensional interpolation

Successful reconstruction scheme

- Signal structure - *Hierarchical Tucker*
- Sampling - *subsampling increases h-rank*
- **Optimization - *fit data in the Hierarchical Tucker format***

# Optimization Format

- Given data  $b$  with missing sources and/or receivers, subsampling operator  $A$ , full tensor expansion operator

$$\phi : (U_t, B_t) \rightarrow \mathbb{C}^{n_1 \times \cdots \times n_d}$$

solve

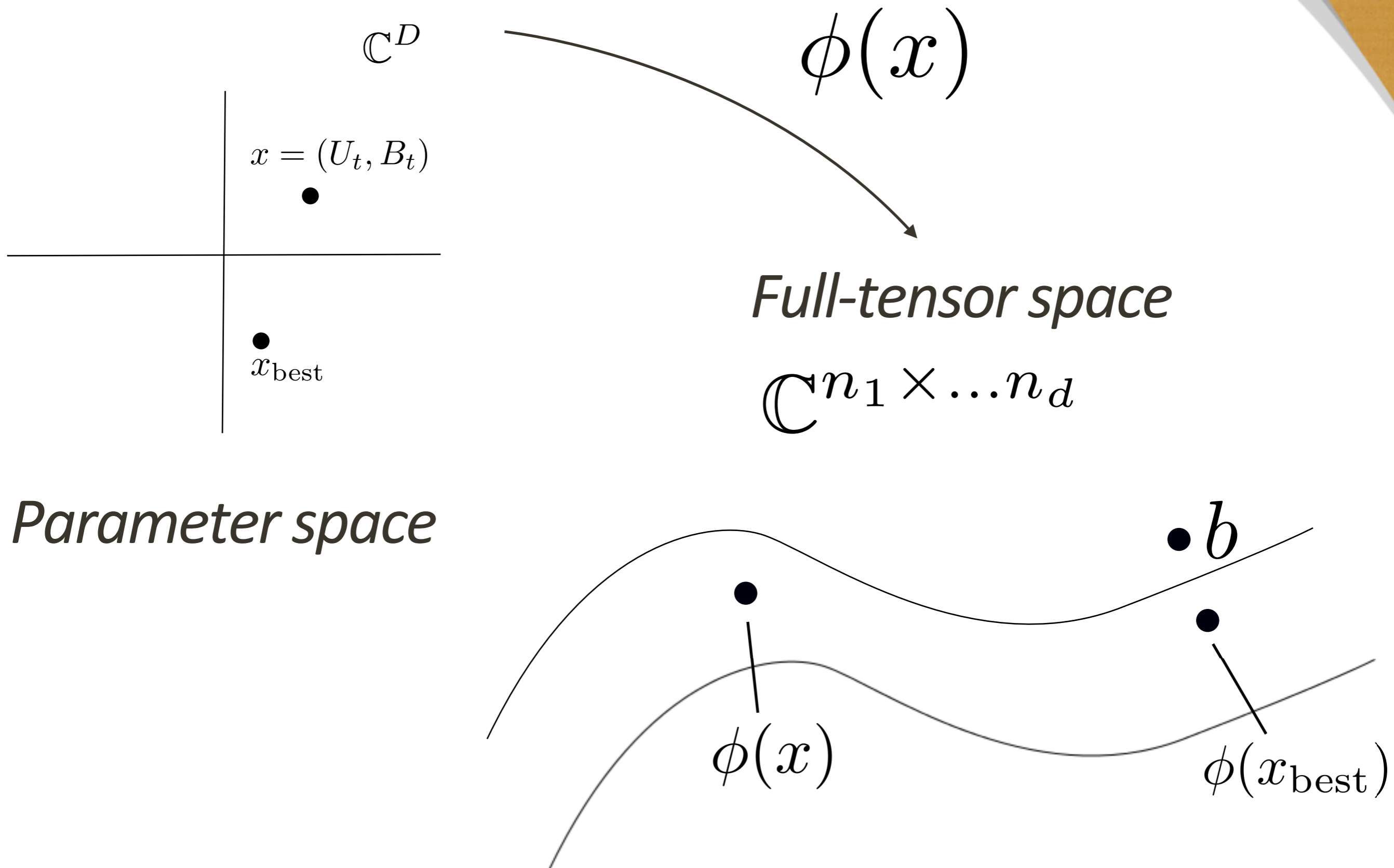
$$\min_{x=(U_t, B_t)} \|A\phi(x) - b\|_2^2$$

P.A. Absil, R. Mahony, and R. Sepulchre. *Optimization algorithms on matrix manifolds*. Princeton Univ Press, 2008.  
A. Uschmajew, B. Vandereycken. *The geometry of algorithms using hierarchical tensors*. 2012

# Differential Geometry

- *The geometry of algorithms using hierarchical tensors* - theoretical analysis of HT tensors
  - Nonlinear, nonconvex space
  - Steepest Descent, Conjugate gradient, Gauss-Newton

# Optimization program

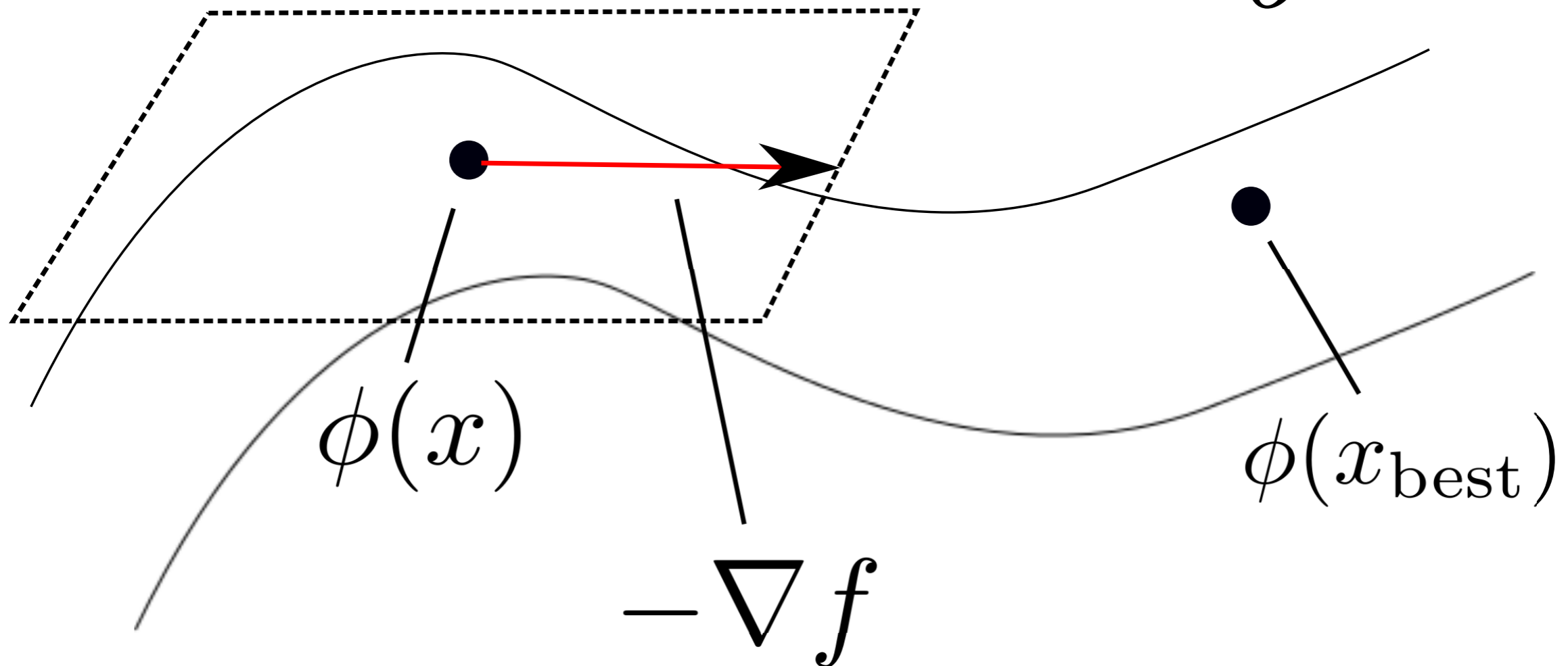


# Optimization program

$$\mathbb{C}^{n_1 \times \dots \times n_d}$$

$$A\phi(x)$$

$$b$$



# Derivatives

- Derivatives of a particular node with respect to its children can be computed efficiently
- The chain rule gives the gradient of the function  $\phi$

# Derivative code

```
function [dUdL,dUdR,dUdB] = dHTuck(Uleft, Uright, B)
    Bhat = matricize(B,1,[2 3]);
    Bhat = dematricize(Uright * Bhat,[nr,kl,k],1,[2,3]);
    Bhat = matricize(Bhat,[1 3],2);
    dUdL = opFunction(nl*nr*k, nl*kl, @(x,mode) dUdL_func(x,mode,
Bhat,nr,nl,k,kl));
    BhatR = dematricize( Uleft*matricize(permute(B,[2 1 3]),1, [2 3]),
[nl,kr,k],1,[2 3]);
    dUdR = opKron(matricize(BhatR,[1 3],2),opDirac(nr));
    dUdB = opKron(opDirac(k),Uleft,Uright);
end
function y = dUdL_func(x,mode,Bhat,nr,nl,k,kl)
    if mode == 1
        v = reshape(x,nl,kl);
        q = Bhat * v';
        result = reshape(q,nr,k,nl);
        result = permute(result,[1 3 2]);
        y = vec(result);
    else
        v = reshape(x,nr,nl,k);
        q = Bhat' * matricize(v,[1 3],2);
        q = reshape(q,kl,nl);
        y = vec(q');
    end
end
end
```

# Derivatives

- Only involve matrix-matrix multiplication of small matrices compared to the ambient, full-tensor space
- Immediately parallelizable - Kronecker products done in parallel



# Results

# Synthetic BG Data

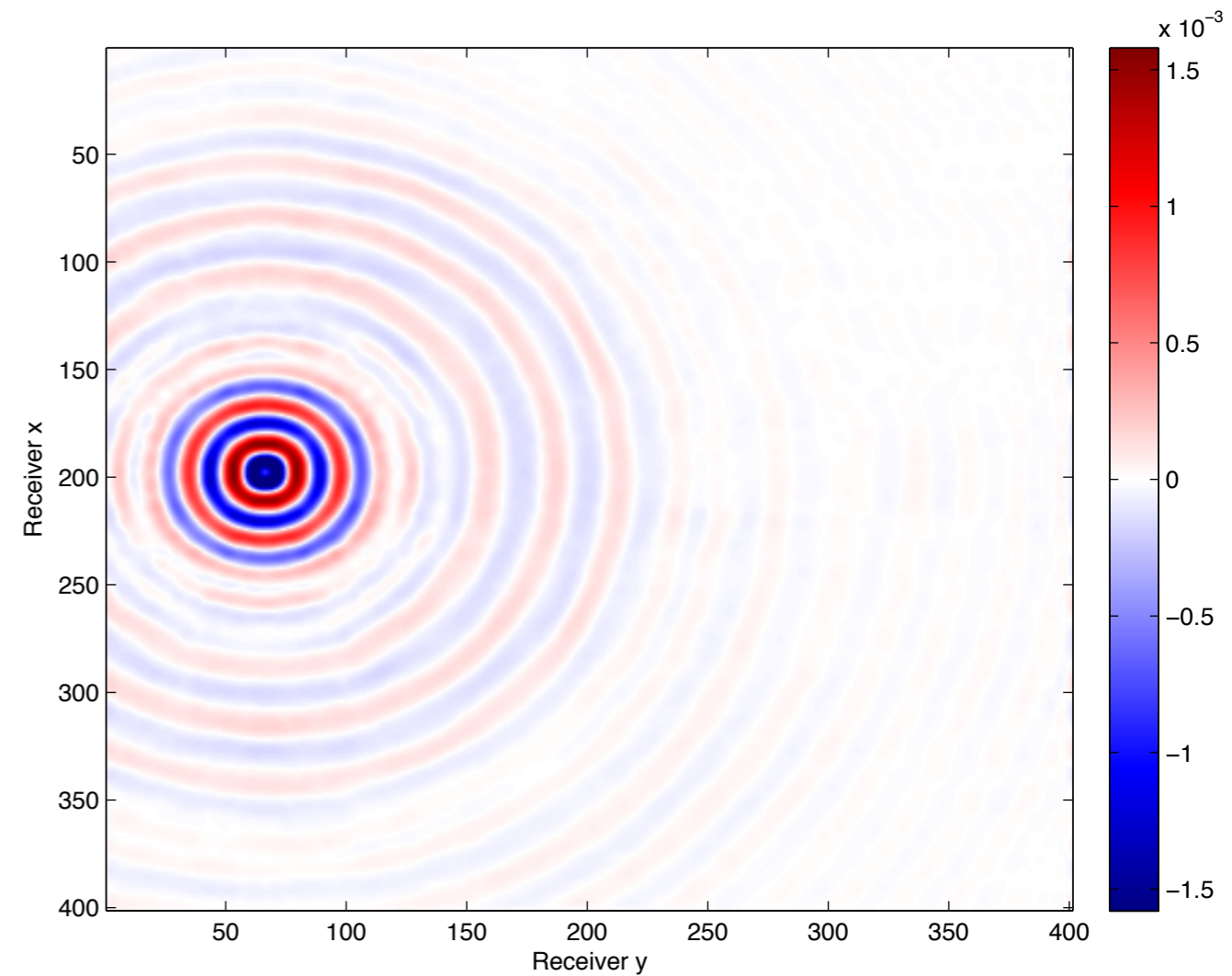
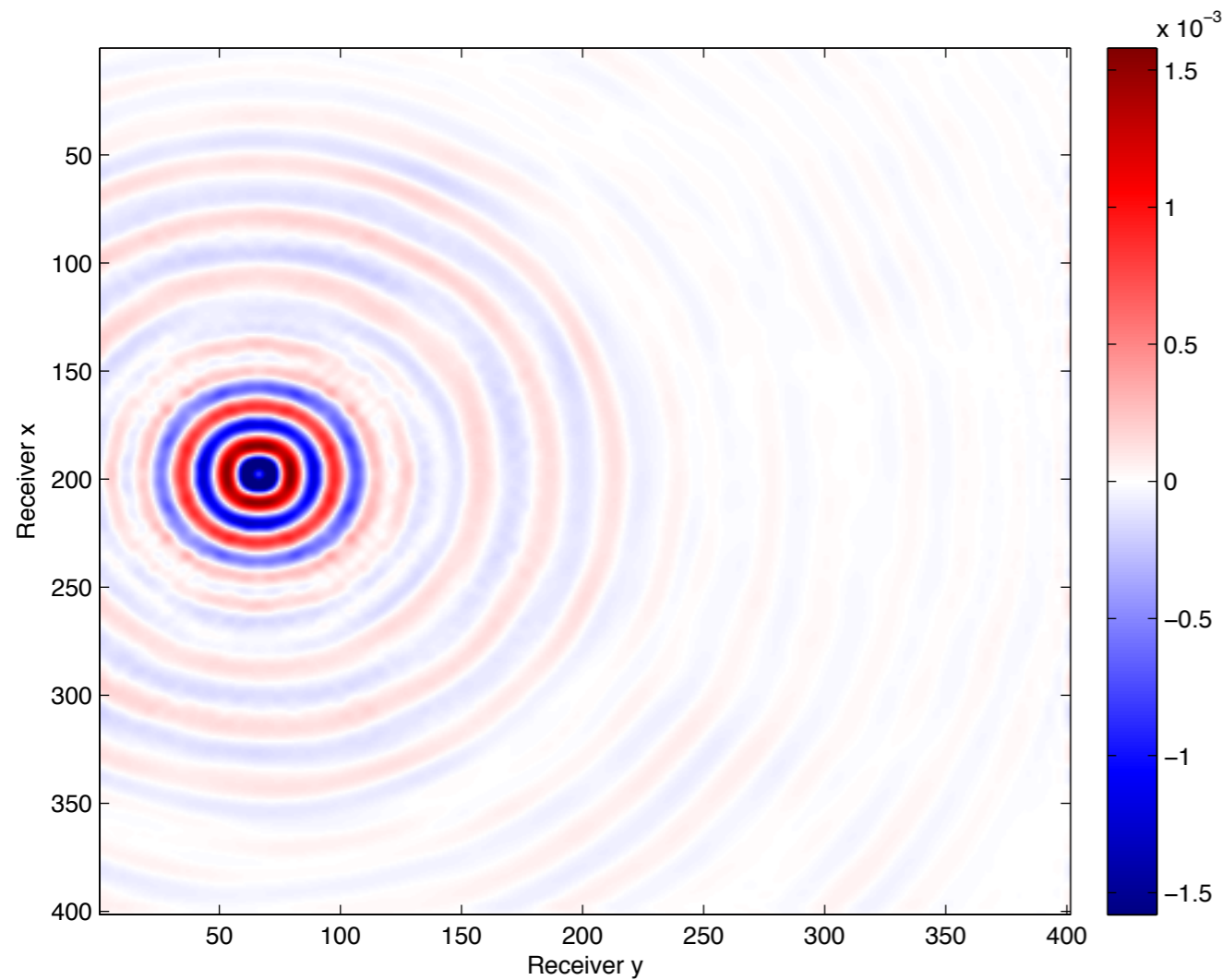
- Unknown model
- 68 x 68 sources with 401 x 401 receivers, data at 4.68Hz, 7.34 Hz
- Receivers subsampled to 101 x 101, Fourier interpolated back to 401 x 401 to produce figures (due to low frequency content of slice)

# Synthetic BG Data

- Single frequency slice (real part) - scaled to unit norm
- Varying percentages of sources have been randomly removed
- Recovered with nonlinear CG

# 4.86 Hz - 50% missing sources

Common source gather - no data originally

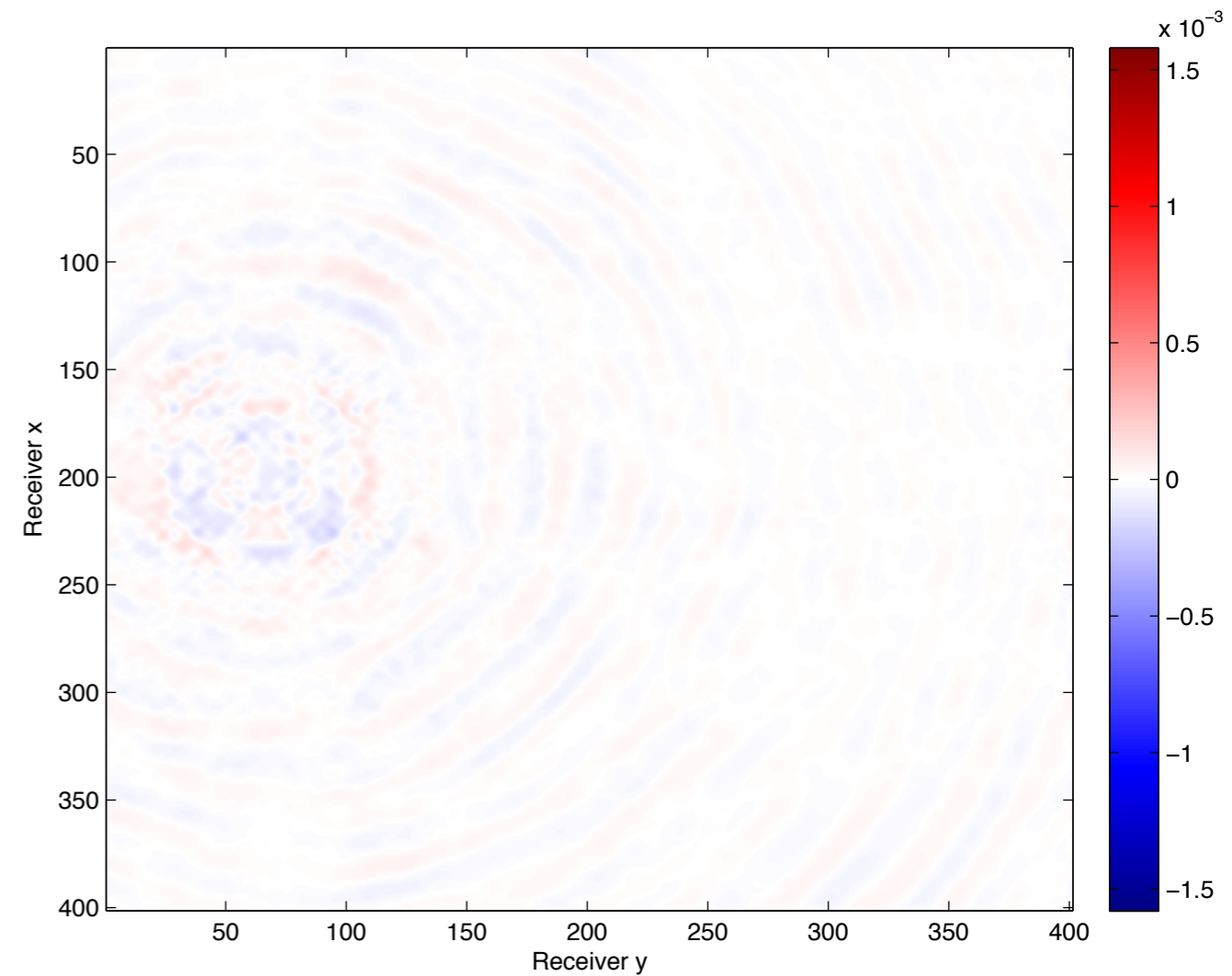
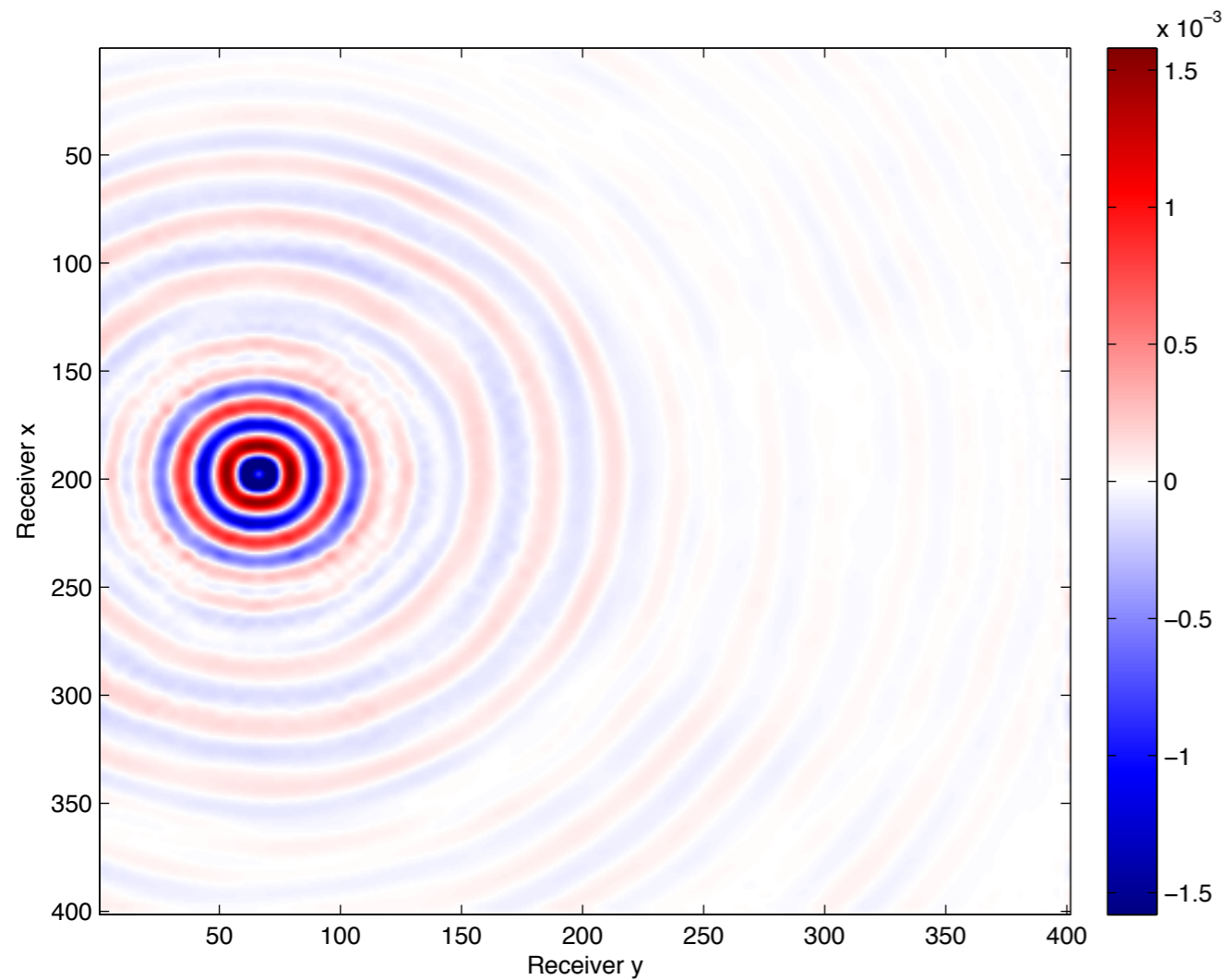


$$(x_{\text{src}}, y_{\text{src}}) = (34, 17)$$

Interpolated Data  
SNR 17.5 dB

# 4.86 Hz - 50% missing sources

Common source gather - no data originally

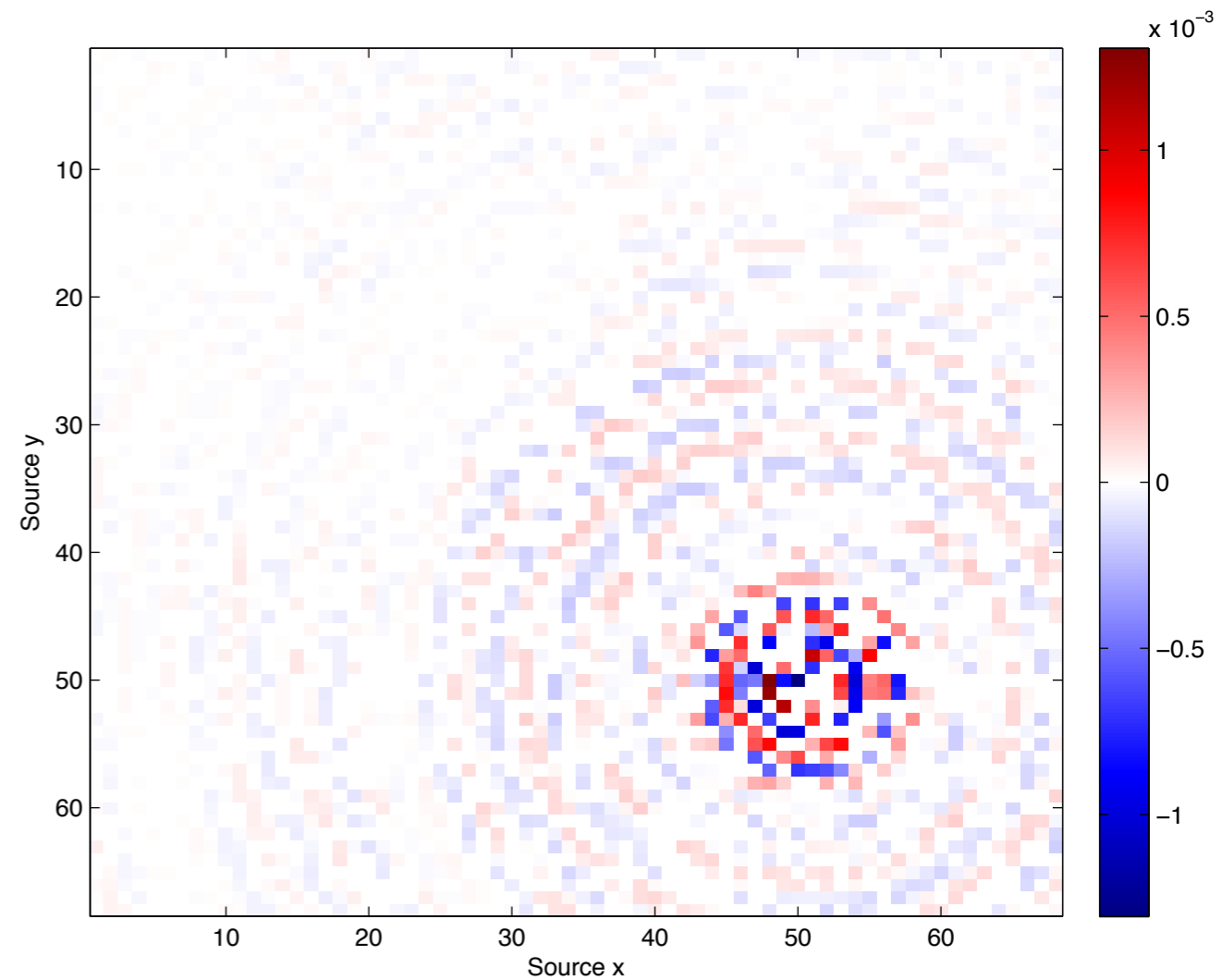
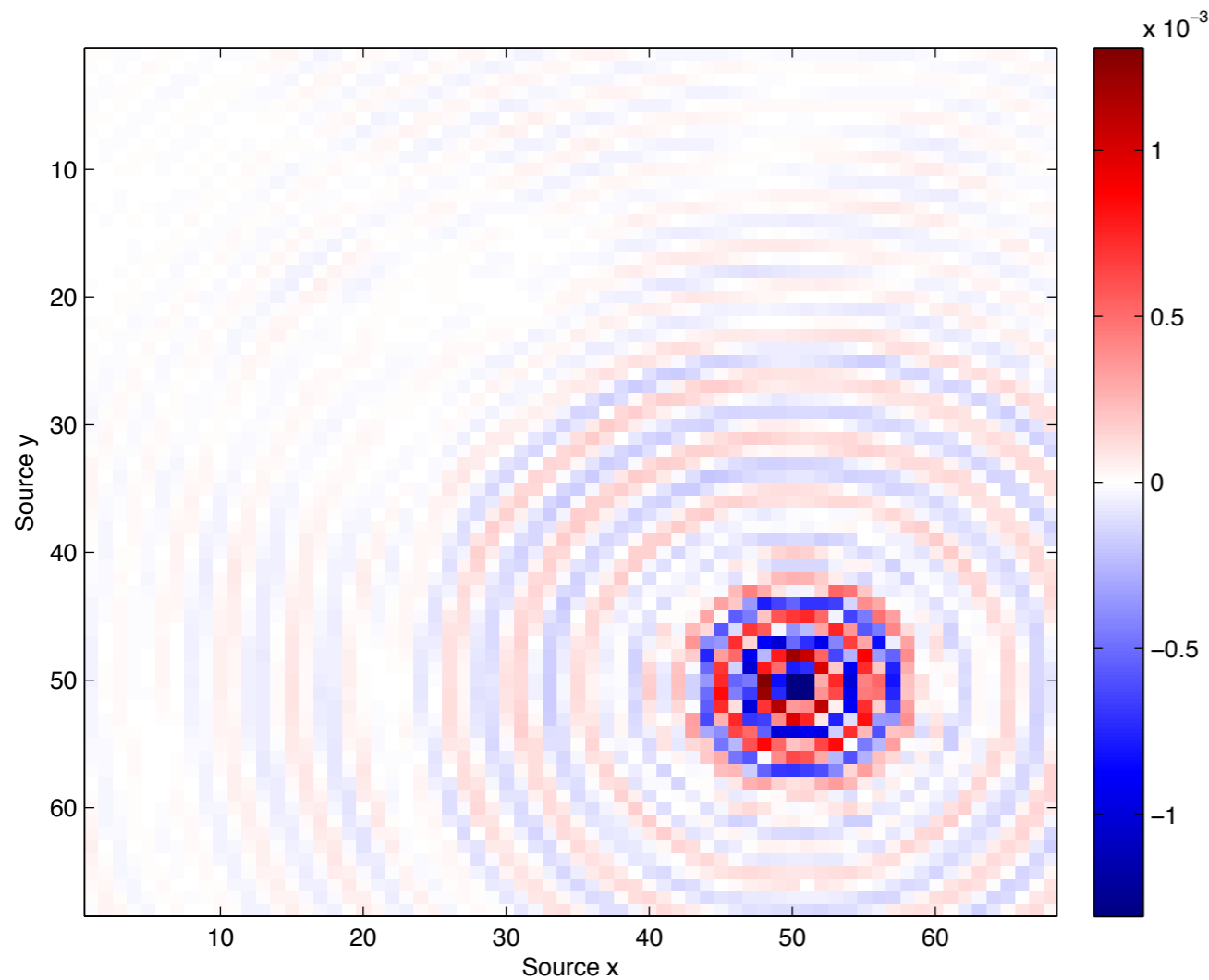


$$(x_{\text{src}}, y_{\text{src}}) = (34, 17)$$

Difference

# 4.86 Hz - 50% missing sources

Common receiver gather

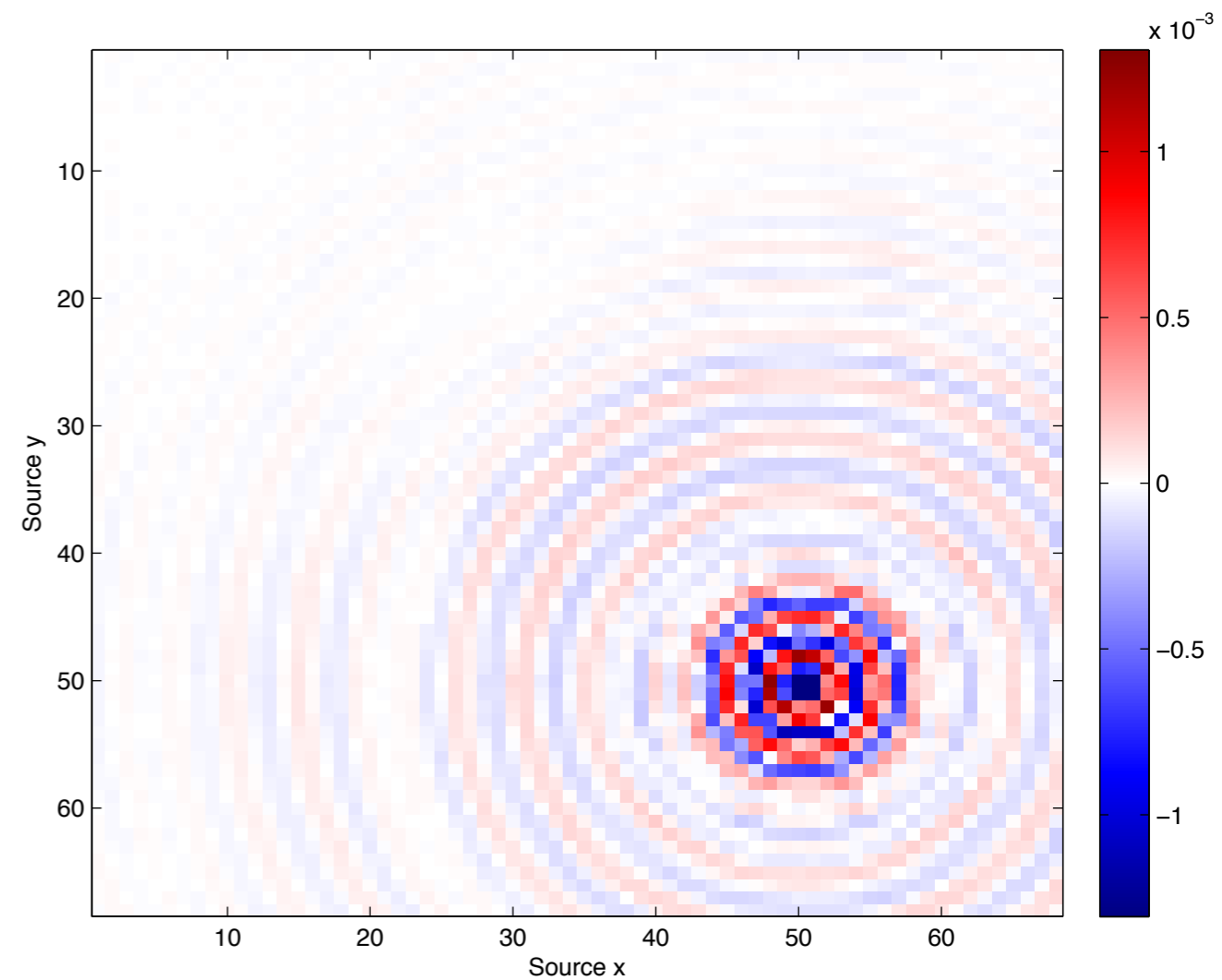
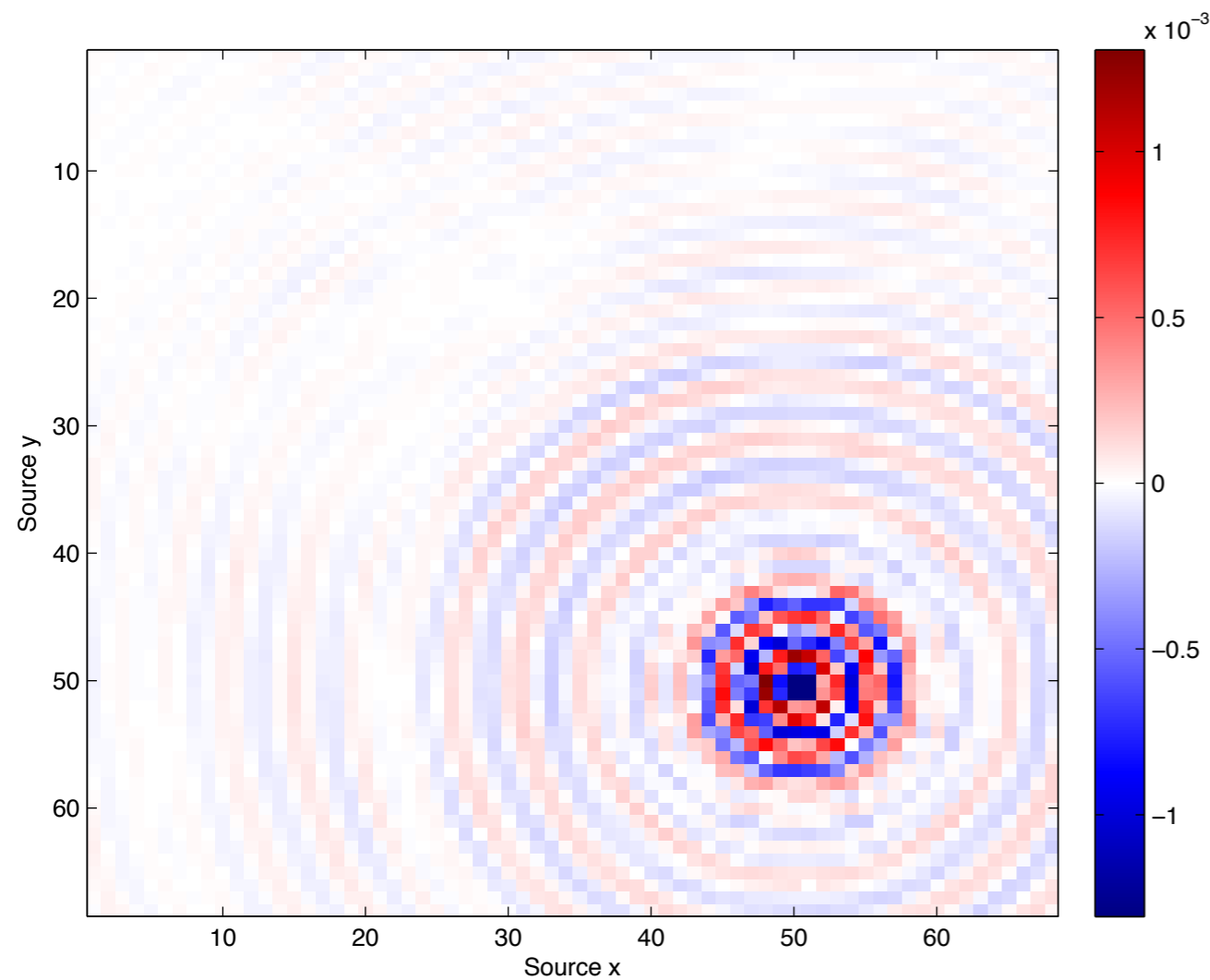


$(X_{\text{rec}}, Y_{\text{rec}}) = (75, 75)$

Subsampled Data

# 4.86 Hz - 50% missing sources

Common receiver gather

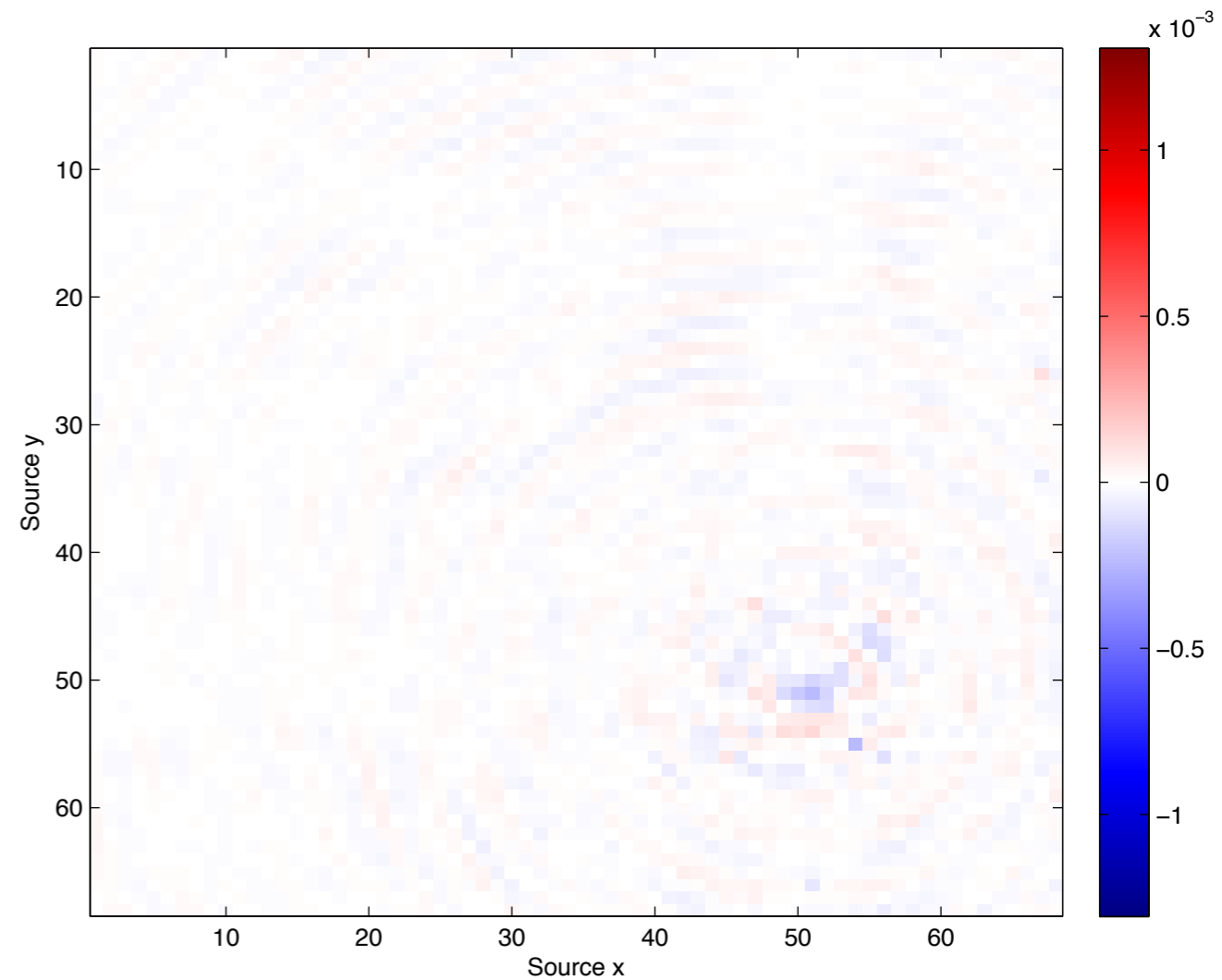
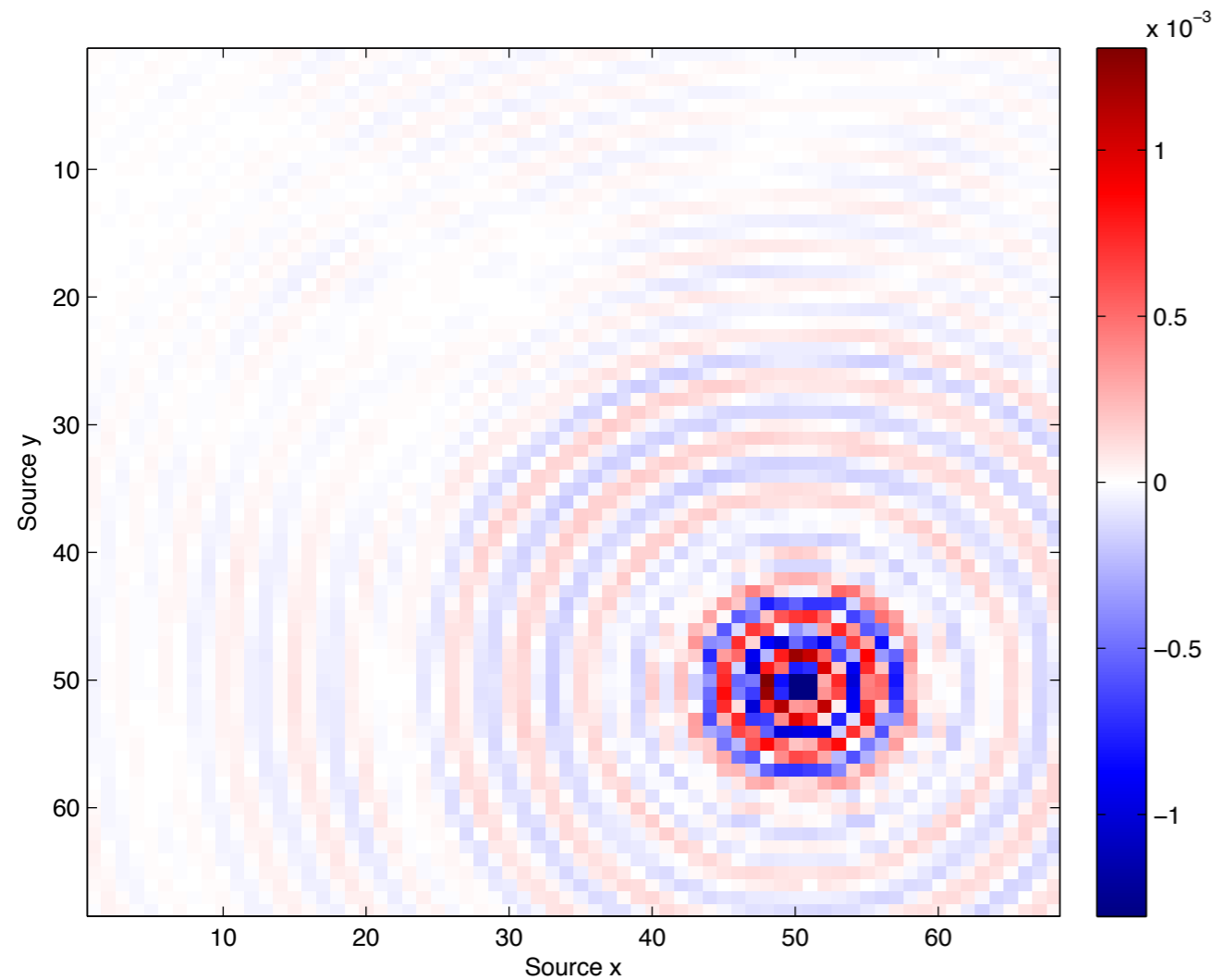


$$(X_{\text{rec}}, Y_{\text{rec}}) = (75, 75)$$

Interpolated Data  
SNR 17.3 dB

# 4.86 Hz - 50% missing sources

Common receiver gather



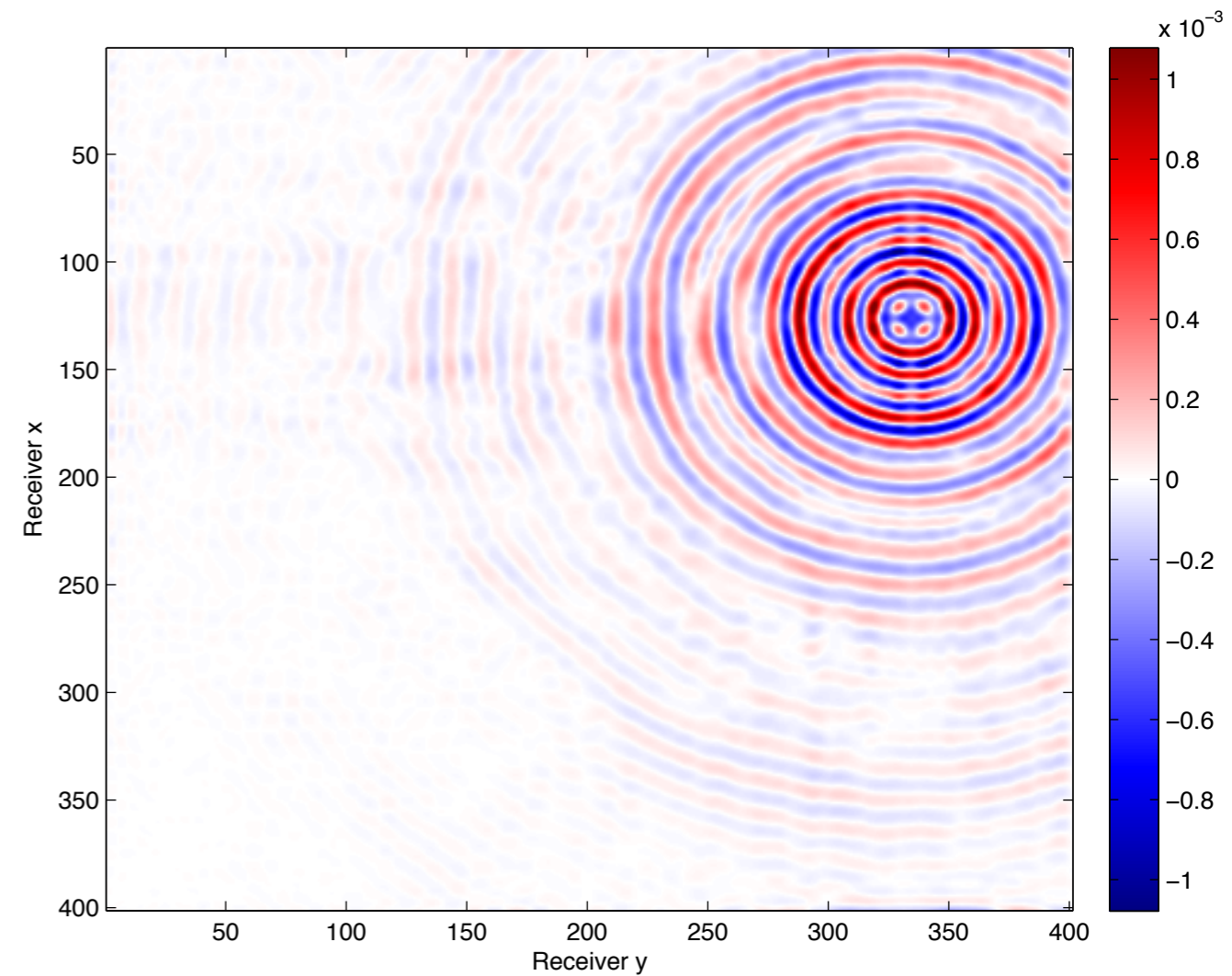
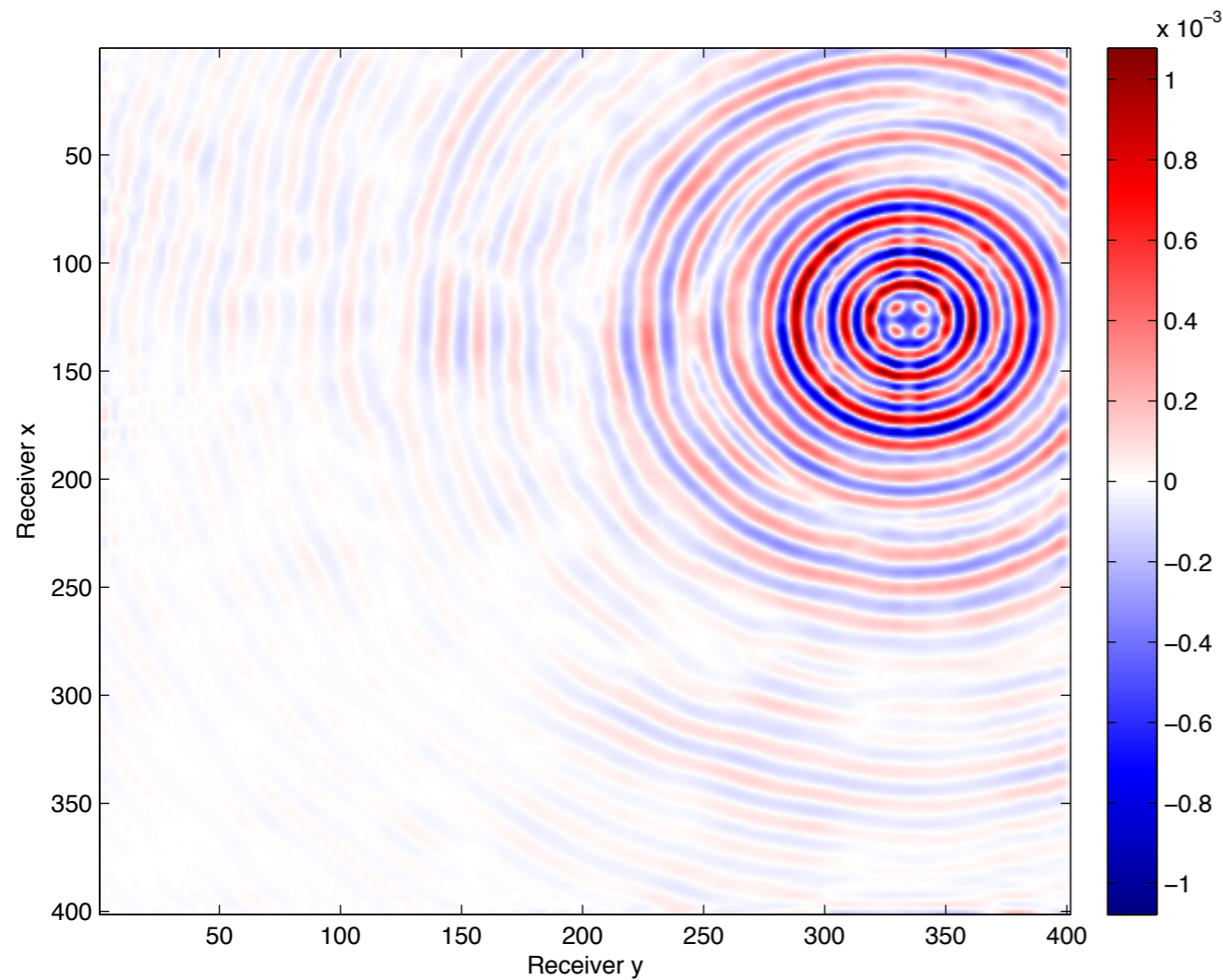
$$(X_{\text{rec}}, Y_{\text{rec}}) = (75, 75)$$

Difference



# 7.34 Hz - 75% missing sources

Common source gather - no data originally

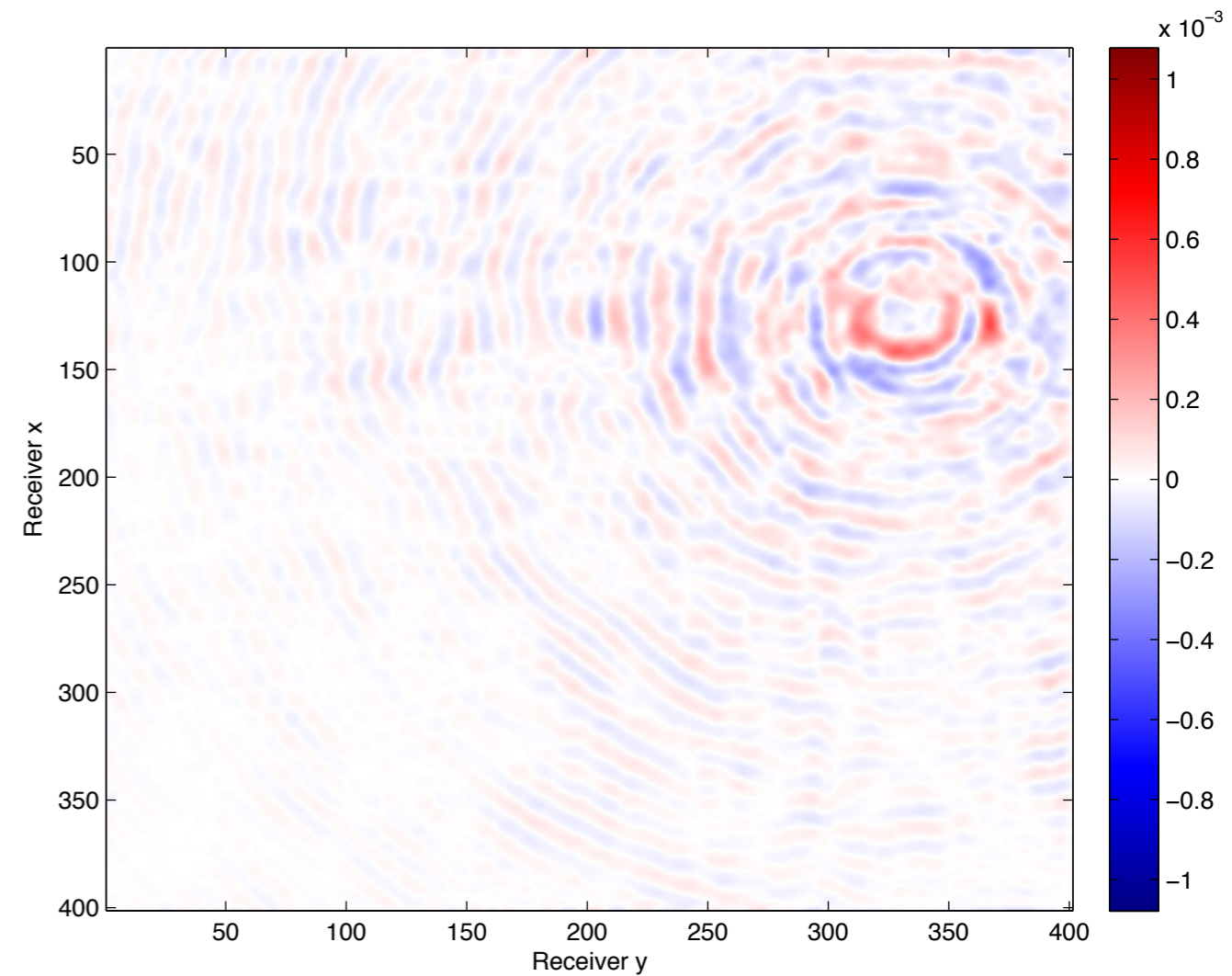
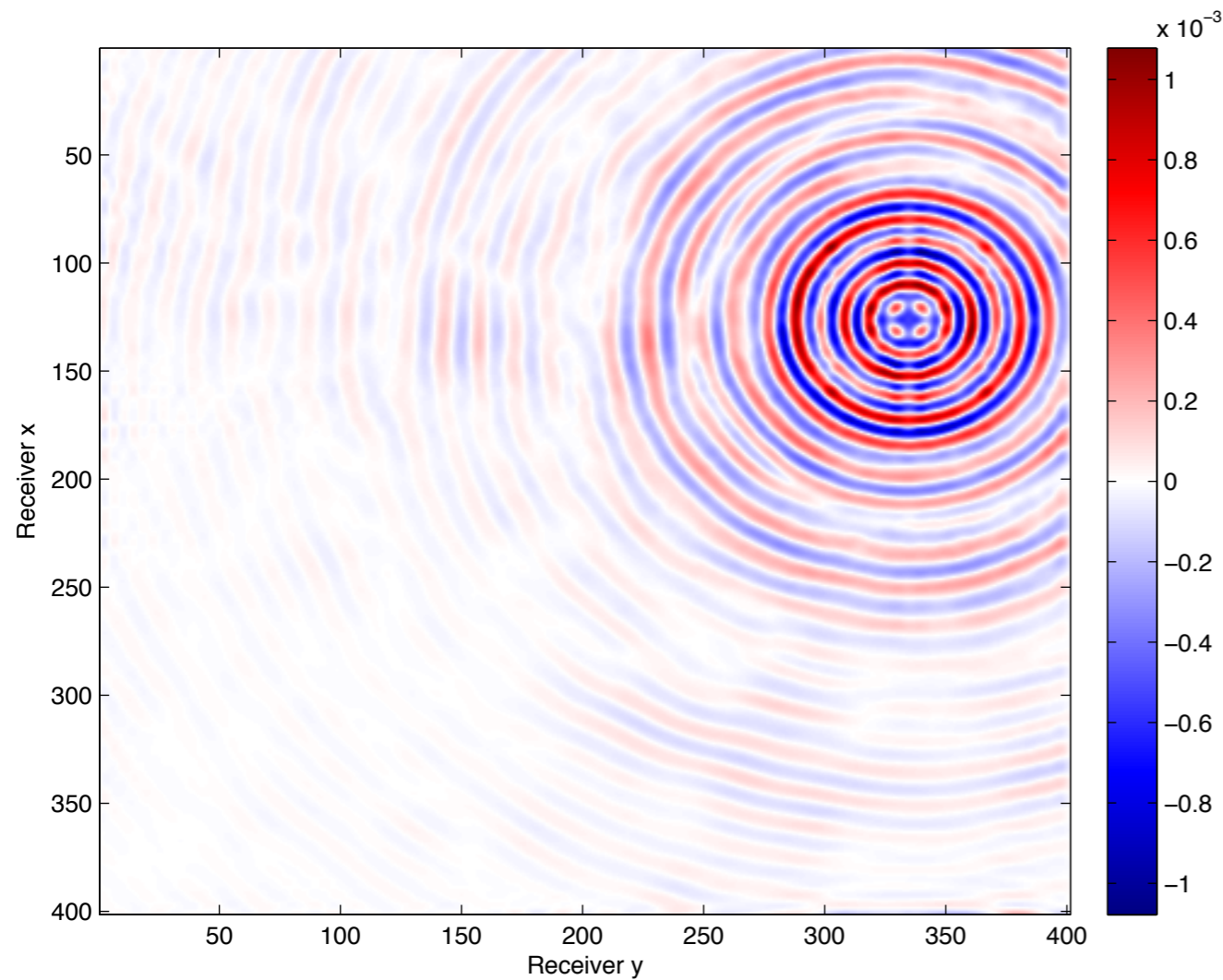


$$(x_{\text{src}}, y_{\text{src}}) = (22, 57)$$

Interpolated Data  
SNR 10.6 dB

# 7.34 Hz - 75% missing sources

Common source gather - no data originally

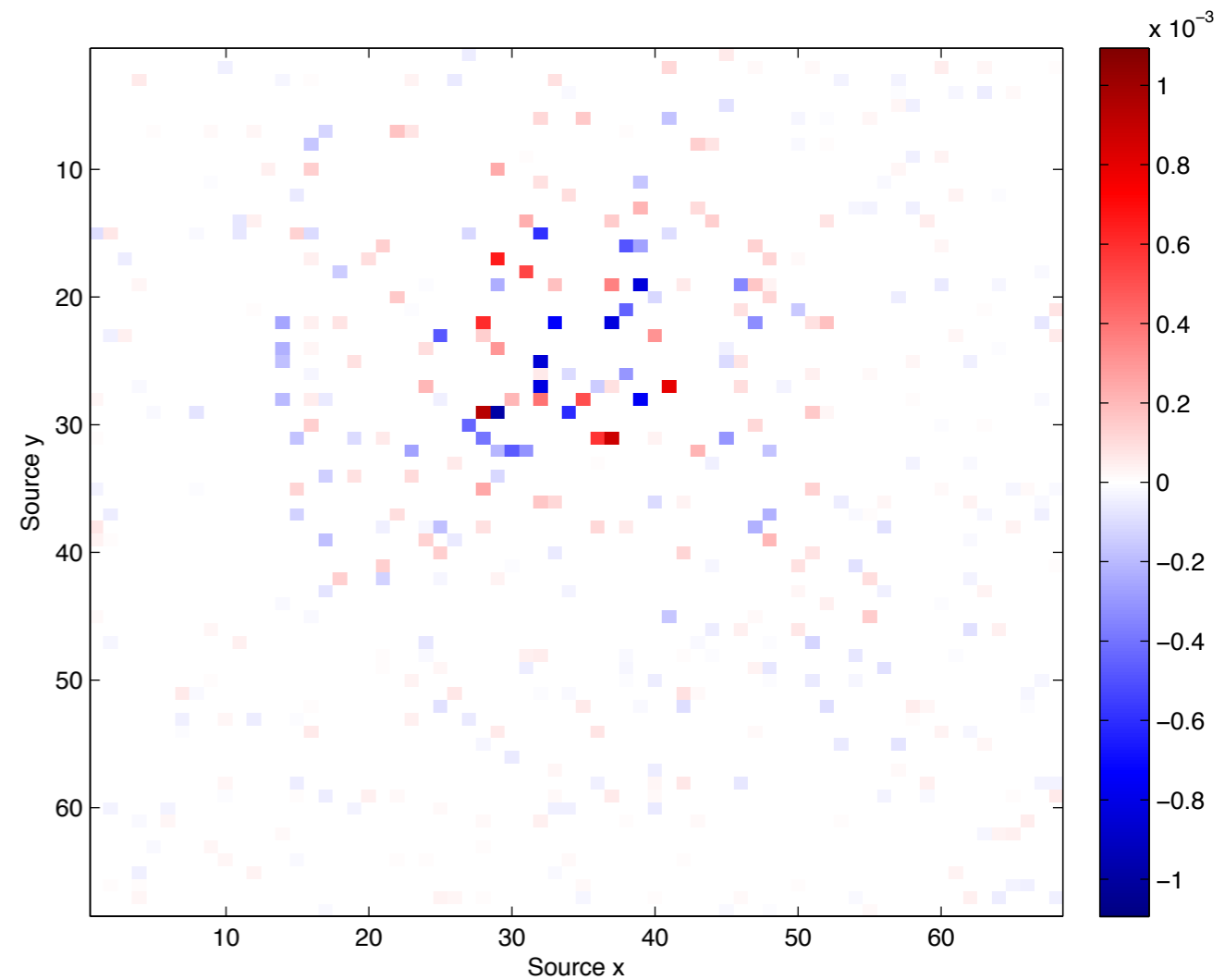
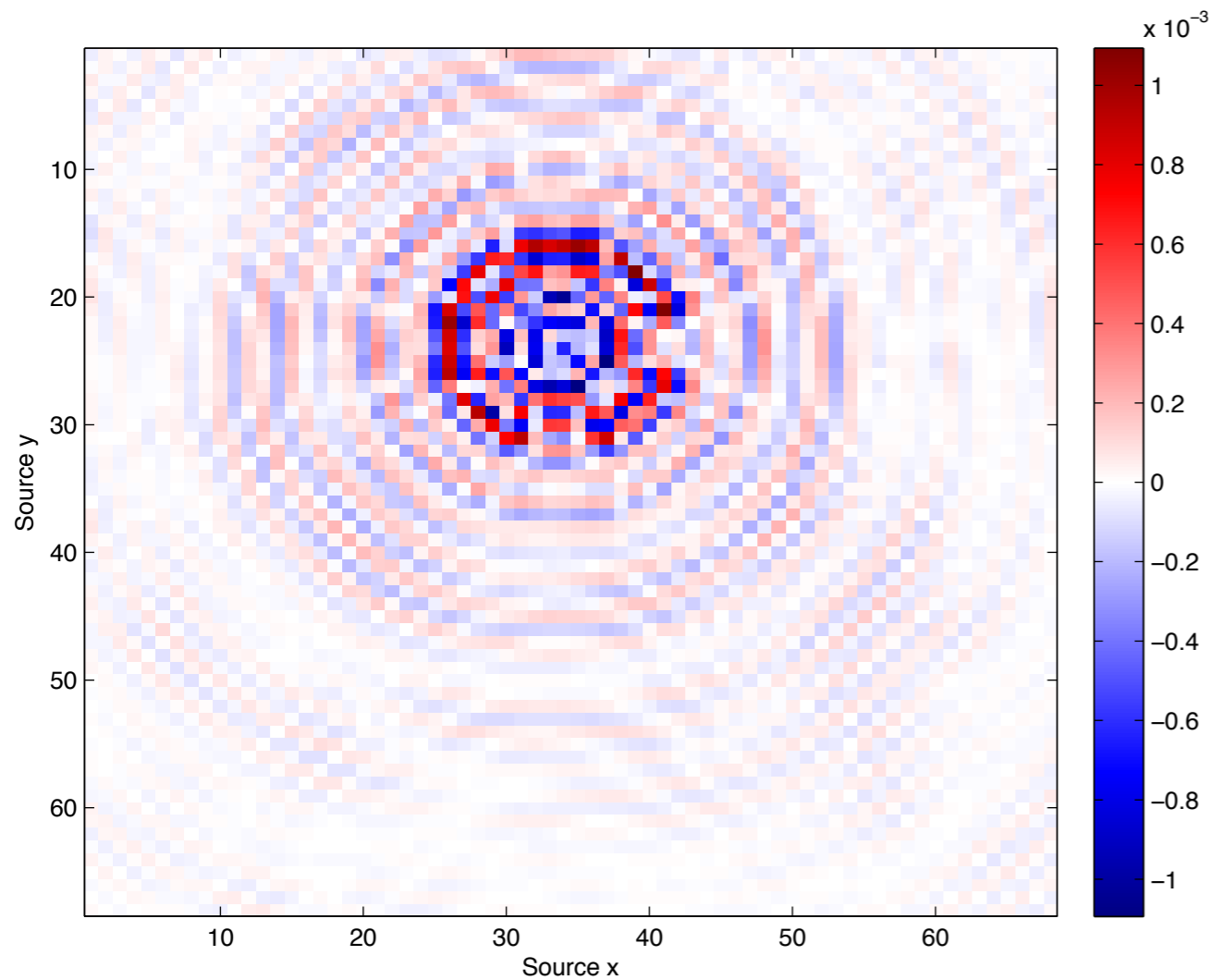


$$(x_{\text{src}}, y_{\text{src}}) = (22, 57)$$

Difference

# 7.34 Hz - 75% missing sources

Common receiver gather

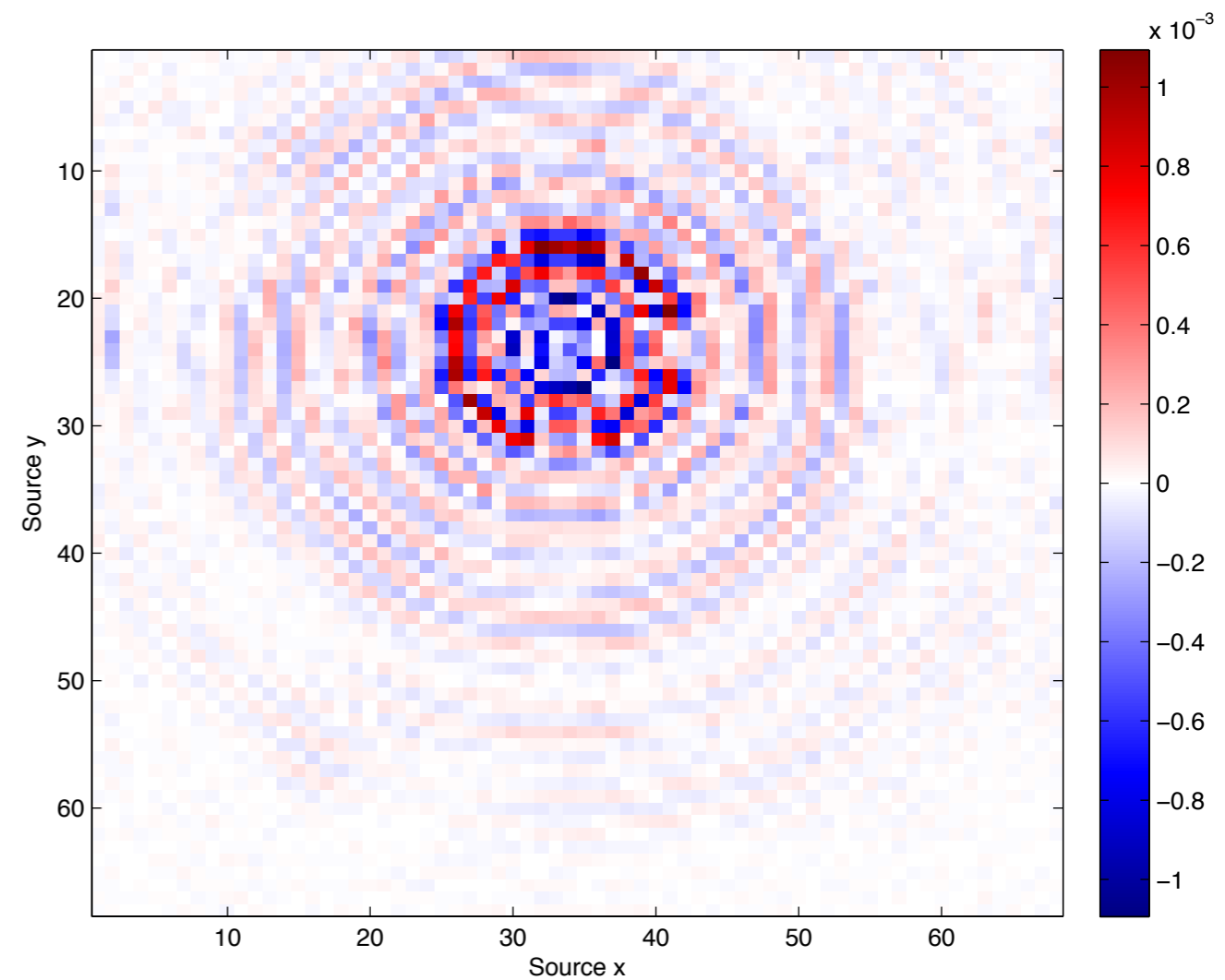
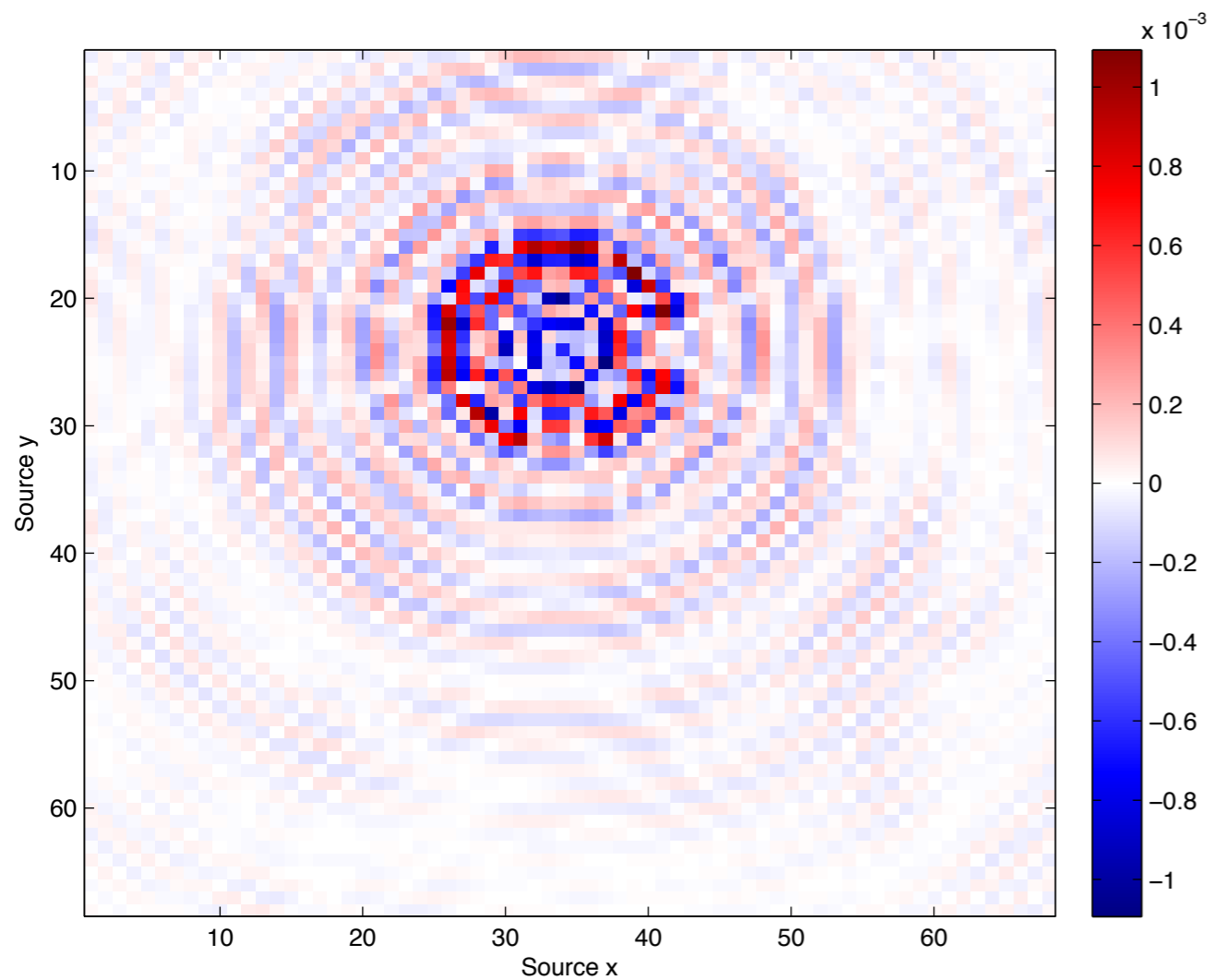


$$(x_{\text{rec}}, y_{\text{rec}}) = (35, 50)$$

Subsampled Data

# 7.34 Hz - 75% missing sources

Common receiver gather

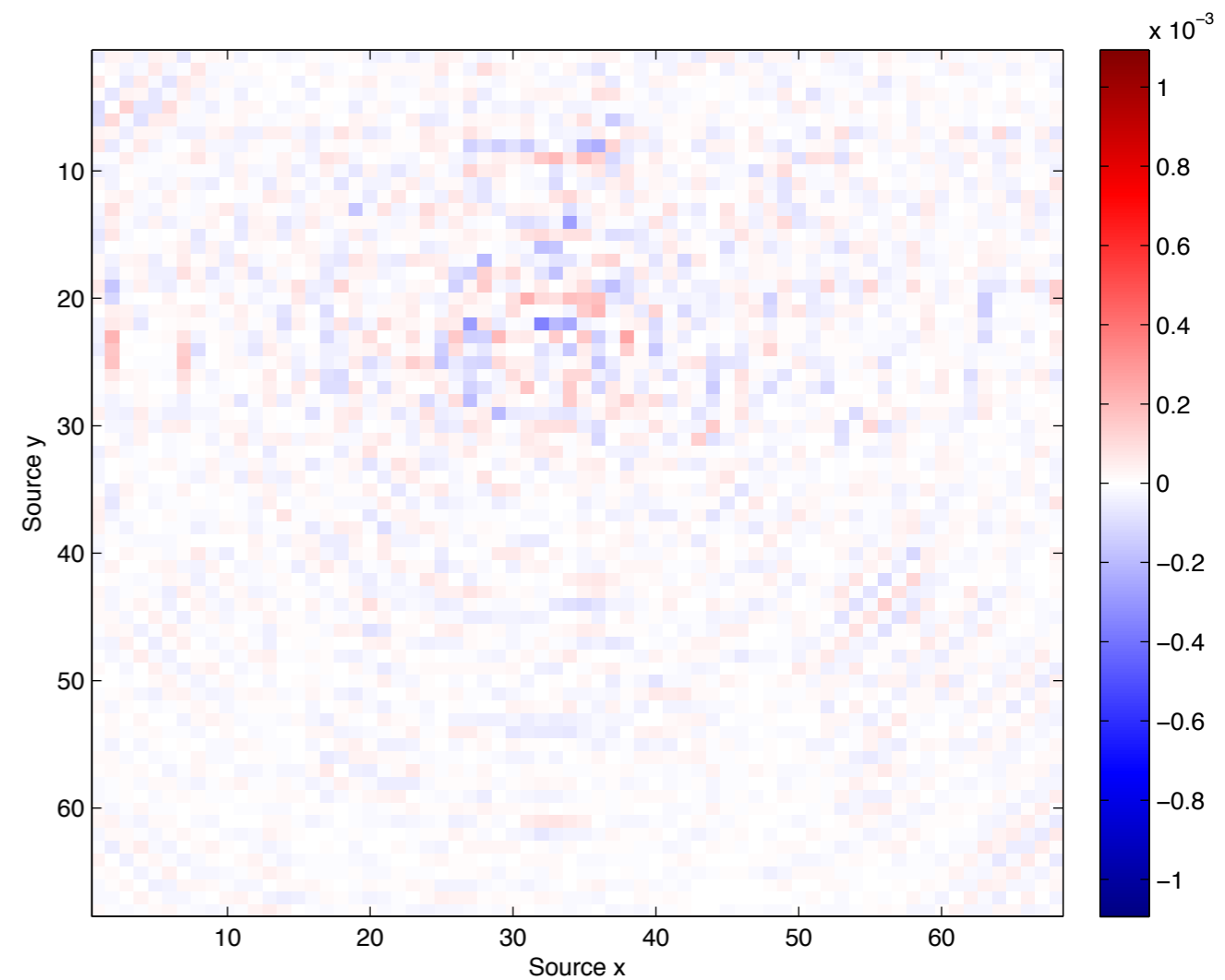
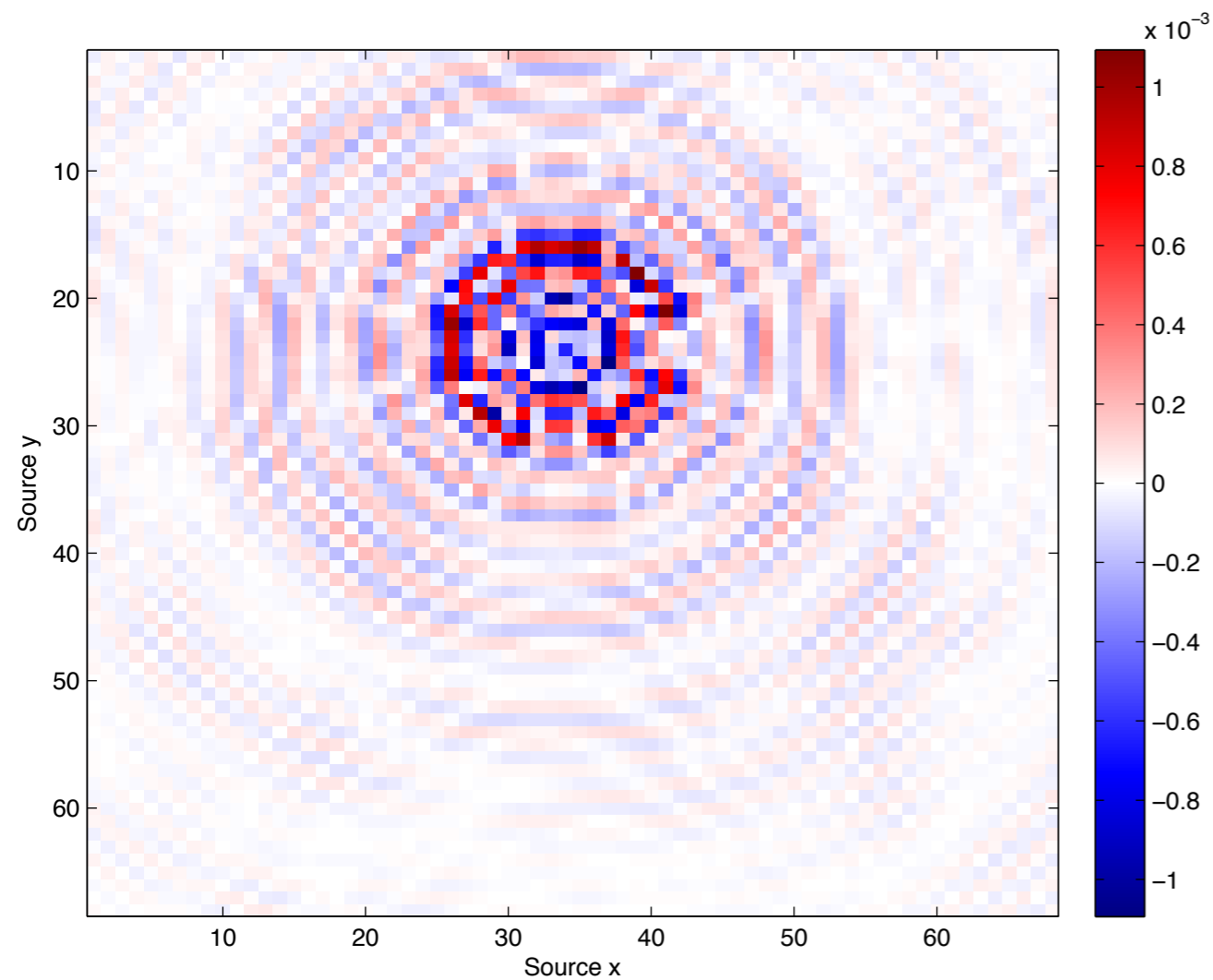


$$(X_{\text{rec}}, Y_{\text{rec}}) = (35, 50)$$

Interpolated Data  
SNR 12.1 dB

# 7.34 Hz - 75% missing sources

## Common receiver gather



$$(x_{\text{rec}}, y_{\text{rec}}) = (35, 50)$$

Difference

# Summary - SNR

	% MISSING SRCS	SNR RECOVERED (DB)
4.86 Hz	25%	18.9
	50%	17.0
	75%	16.2
7.34 Hz	25%	14.4
	50%	14.1
	75%	11.9

# Conclusion

- 3D seismic data has an underlying structure that we can exploit for interpolation (Hierarchical Tucker format)
- Different schemes for organizing data - important for recovery

# Conclusion

- We can interpolate HT tensors with missing entries using the *Riemannian manifold* structure of the HT format
- Achieve good results from largely subsampled data (75% missing sources)



# Acknowledgements

## Thank you for your attention

**SINBAD**



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