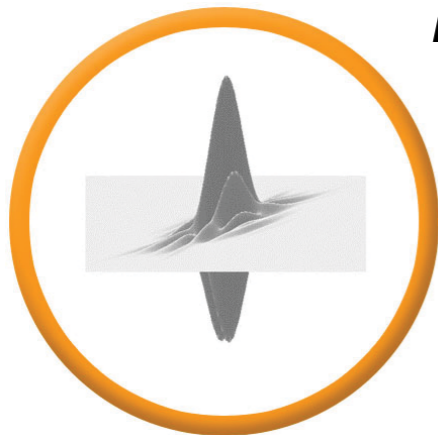




Beating Nyquist by randomized sampling



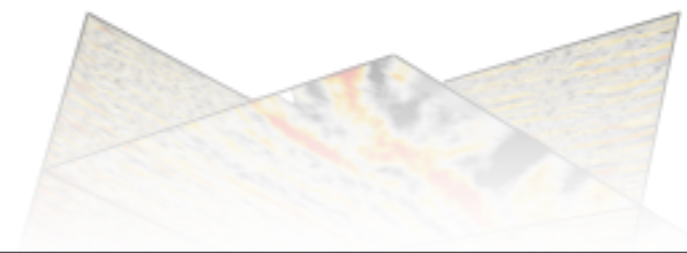
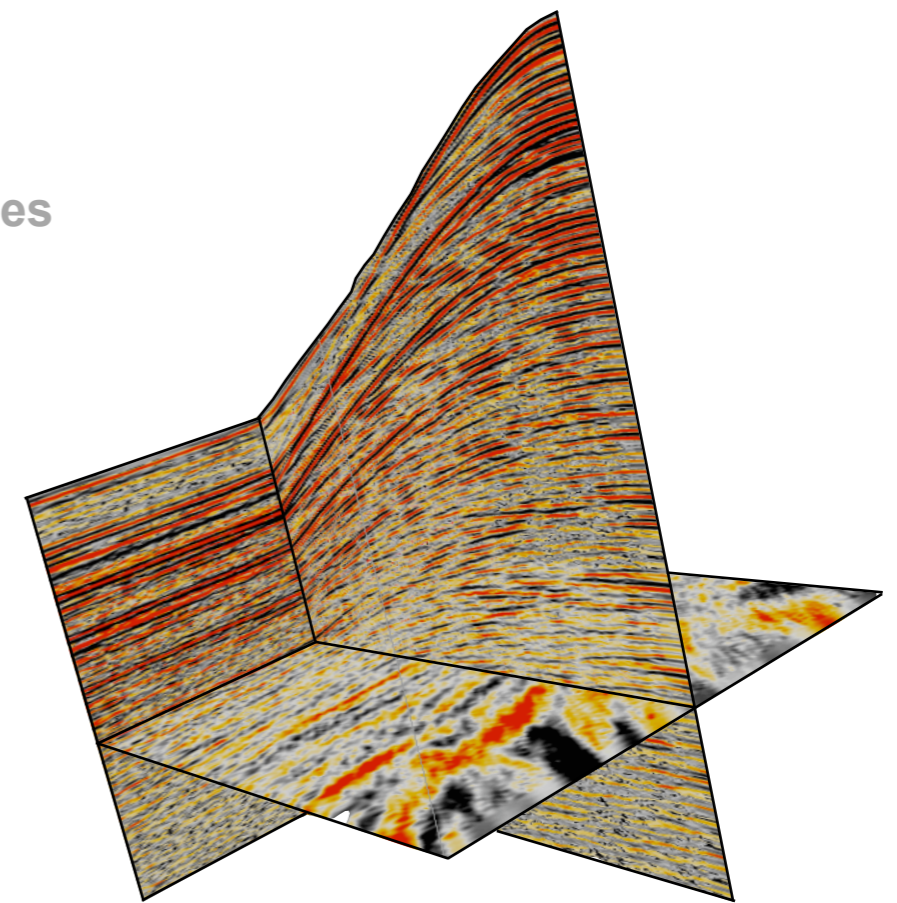
Felix J. Herrmann*

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Joint work with Gang Tang, Reza Shahidi, Gilles Hennenfent, and Tim Lin

***Seismic Laboratory for Imaging & Modeling**
Department of Earth & Ocean Sciences
The University of British Columbia

slim.eos.ubc.ca



EAGE Workshop: Reconstruction, Recovery and Interpolation of Multi-dimensional Seismic Wave Fields
Amsterdam, June 8th, 2009

Relation to existing work

- **filter-based methods** [Spitz'91, Fomel'00]
 - convolve the incomplete data with a data-adaptive interpolating filter
- **wavefield-operator-based methods** [Canning and Gardner'96, Biondi et al.'98, Stolt'02]
 - explicitly include wave propagation
 - require knowledge of velocity model
 - computationally intensive
- **transform-based methods** [Sacchi et al.'98, Trad et al.'03, Zwartjes and Sacchi'07]
 - non-adaptive and fast
 - no explicit link with wave propagation
 - related to recent developments in Compressive Sensing (CS)

Motivation

- **Seismic data processing, modeling & inversion:**
 - firmly rooted in Nyquist's sampling paradigm for high-dimensional wavefields
 - too *pessimistic* for signals with *structure*, i.e, there exists some sparsifying transform (e.g. Fourier, curvelets)
- **Recent theoretical & hardware developments**
 - Alternative multiscale, localized & directional transform domains that compress seismic data
 - New nonlinear sampling theory that supersedes the overly pessimistic Nyquist sampling criterion
 - New autonomous data acquisition devices that allow for more flexibility during acquisition
 - New simultaneous & continuous recording
- **Extensions to higher-D through blue-noise sampling**

Motivation cont'd

- **Solution strategy:**

- *leverage new paradigm of compressive sensing (CS)*
 - identify wavefield reconstruction from missing sources & receivers or from simultaneous acquisition as instances of CS
 - reduce acquisition, simulation, and inversion costs by **randomization** and deliberate **subsampling**
- recovery from sample **rates** \approx **computational cost** *proportional* to **transform-domain sparsity** of *data* or *model*

- **Remove the “curse of dimensionality” by removing constructive aliases/interferences**

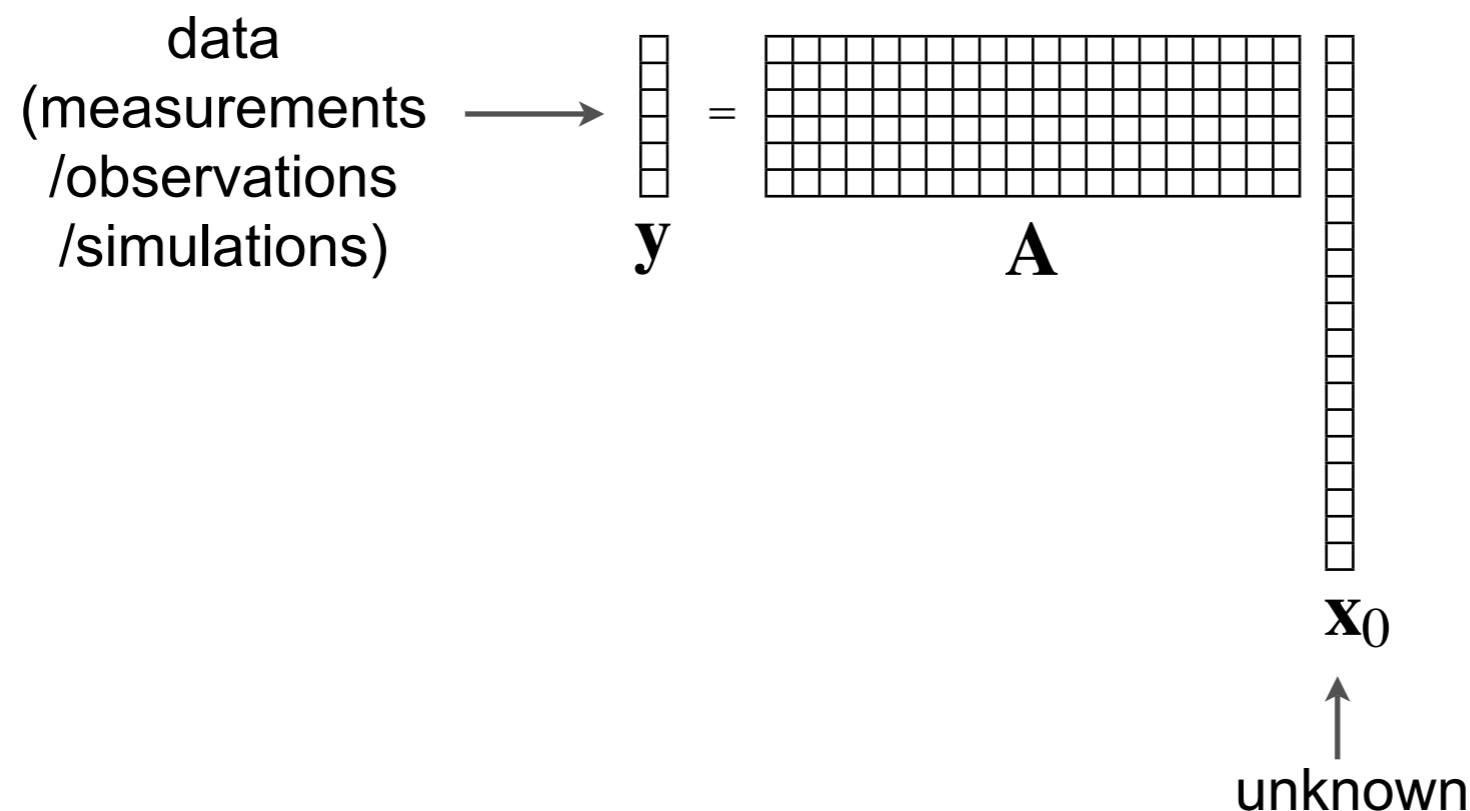
- breaking the *periodicity of regular sampling*
- using *incoherent sources*

- **Turn problem into a “simple” denoising problem**

- use blue-noise sampling techniques from computer graphics community

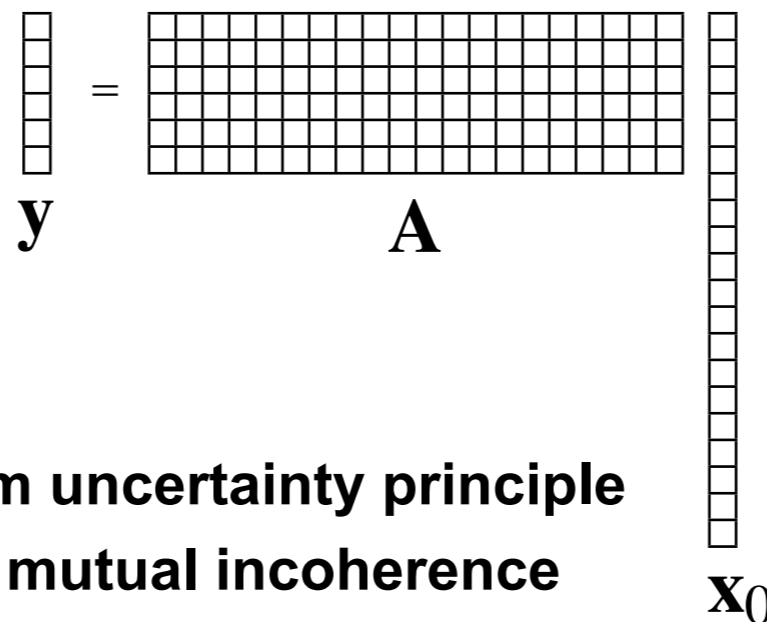
Problem statement

Consider the following (severely) underdetermined system of linear equations



Is it possible to recover \mathbf{x}_0 accurately from \mathbf{y} ?

Perfect recovery



- conditions

- A obeys the **uniform uncertainty principle**
- **randomized $A \iff$ mutual incoherence**
- x_0 is **sufficiently sparse**

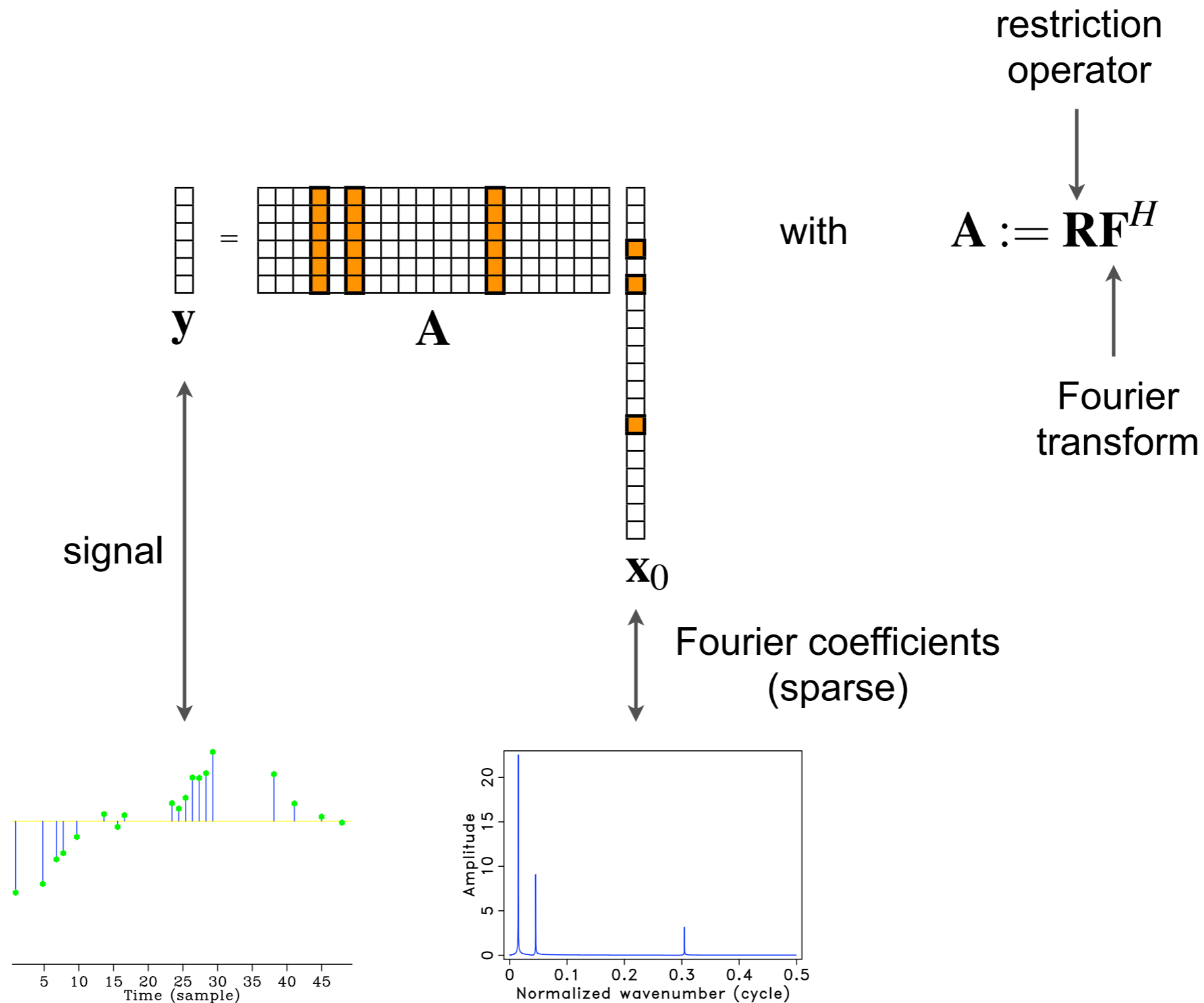
- **nonlinear** recovery procedure:

$$\underbrace{\min_{\mathbf{x}} \|\mathbf{x}\|_1}_{\text{sparsity}} \quad \text{s.t.} \quad \underbrace{\mathbf{Ax} = \mathbf{y}}_{\text{perfect reconstruction}}$$

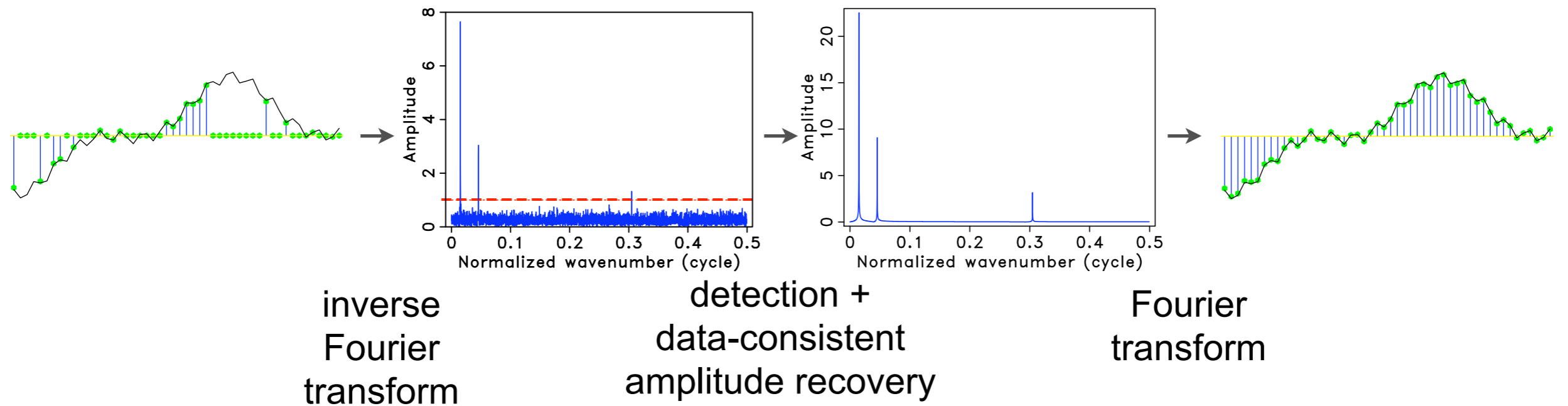
- performance

- **S -sparse vectors recovered from roughly on the order of S measurements** (to within constant and \log factors)

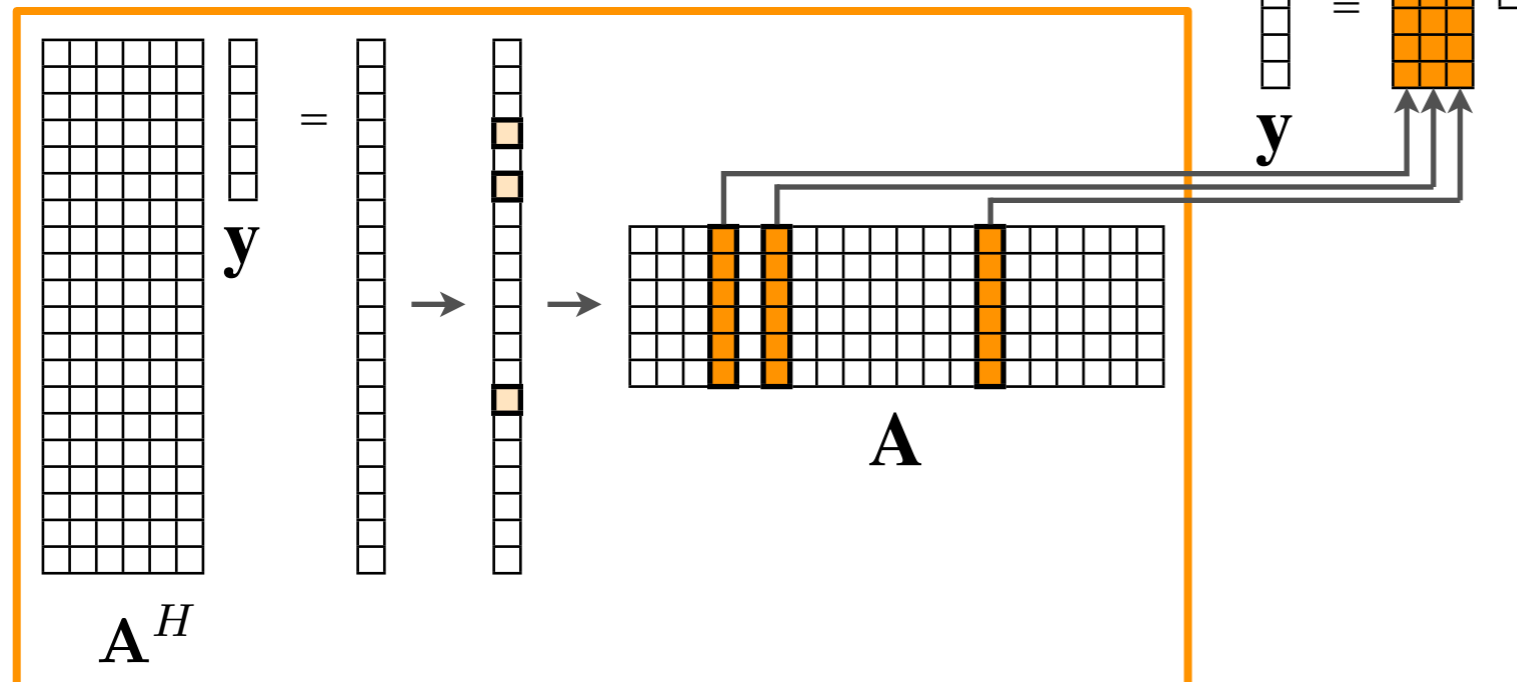
Simple example



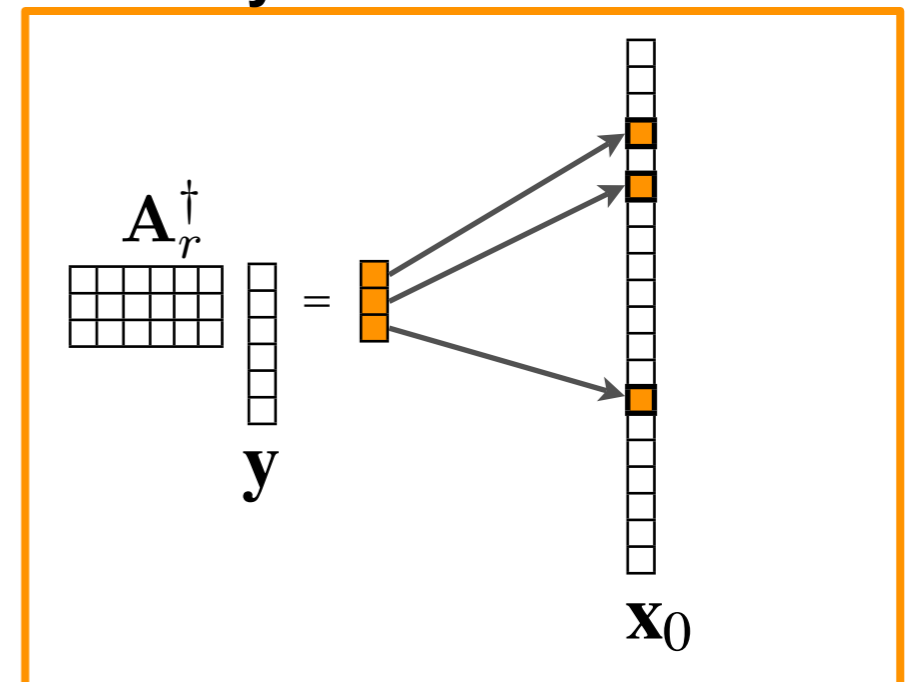
NAIVE sparsity-promoting recovery



detection



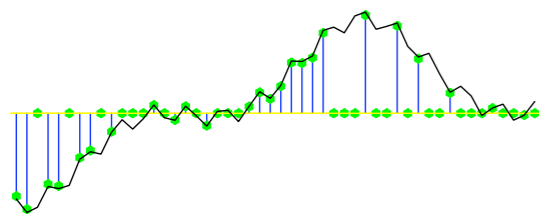
data-consistent amplitude recovery



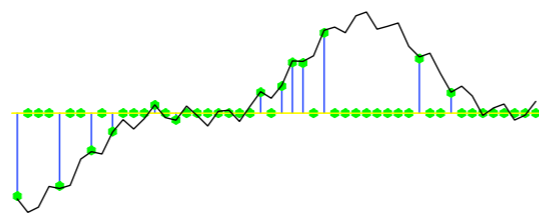
Undersampling “noise”

- “noise”
 - due to $\mathbf{A}^H\mathbf{A} \neq \mathbf{I}$
 - defined by $\mathbf{A}^H\mathbf{A}\mathbf{x}_0 - \mathbf{a}\mathbf{x}_0 = \mathbf{A}^H\mathbf{y} - \mathbf{a}\mathbf{x}_0$

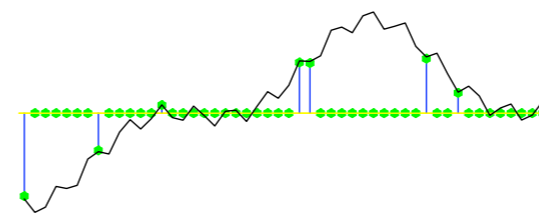
1 out of 2



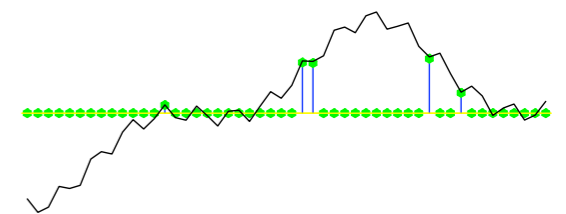
1 out of 4



1 out of 6



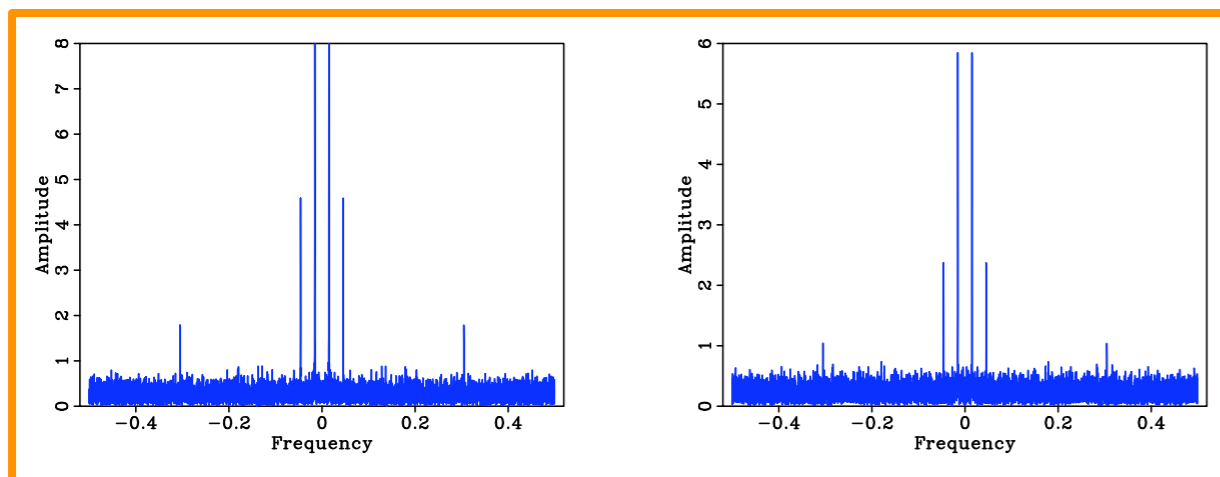
1 out of 8



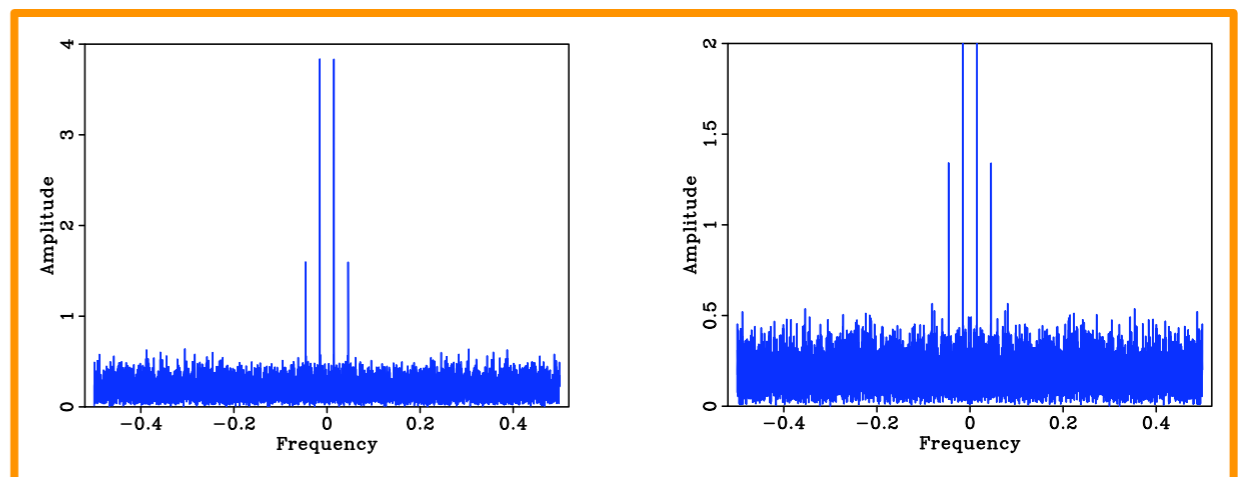
less acquired data



3 detectable Fourier modes



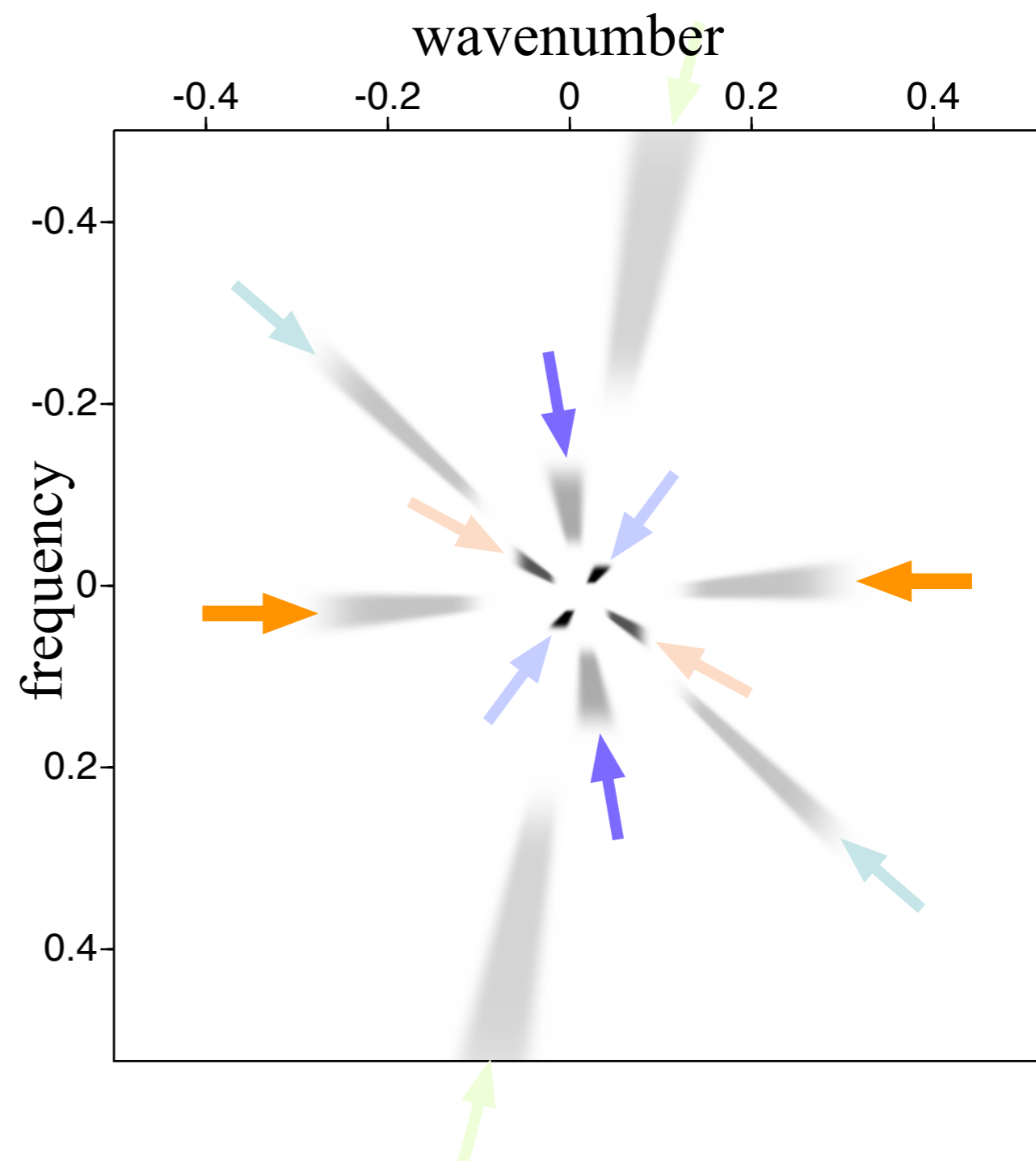
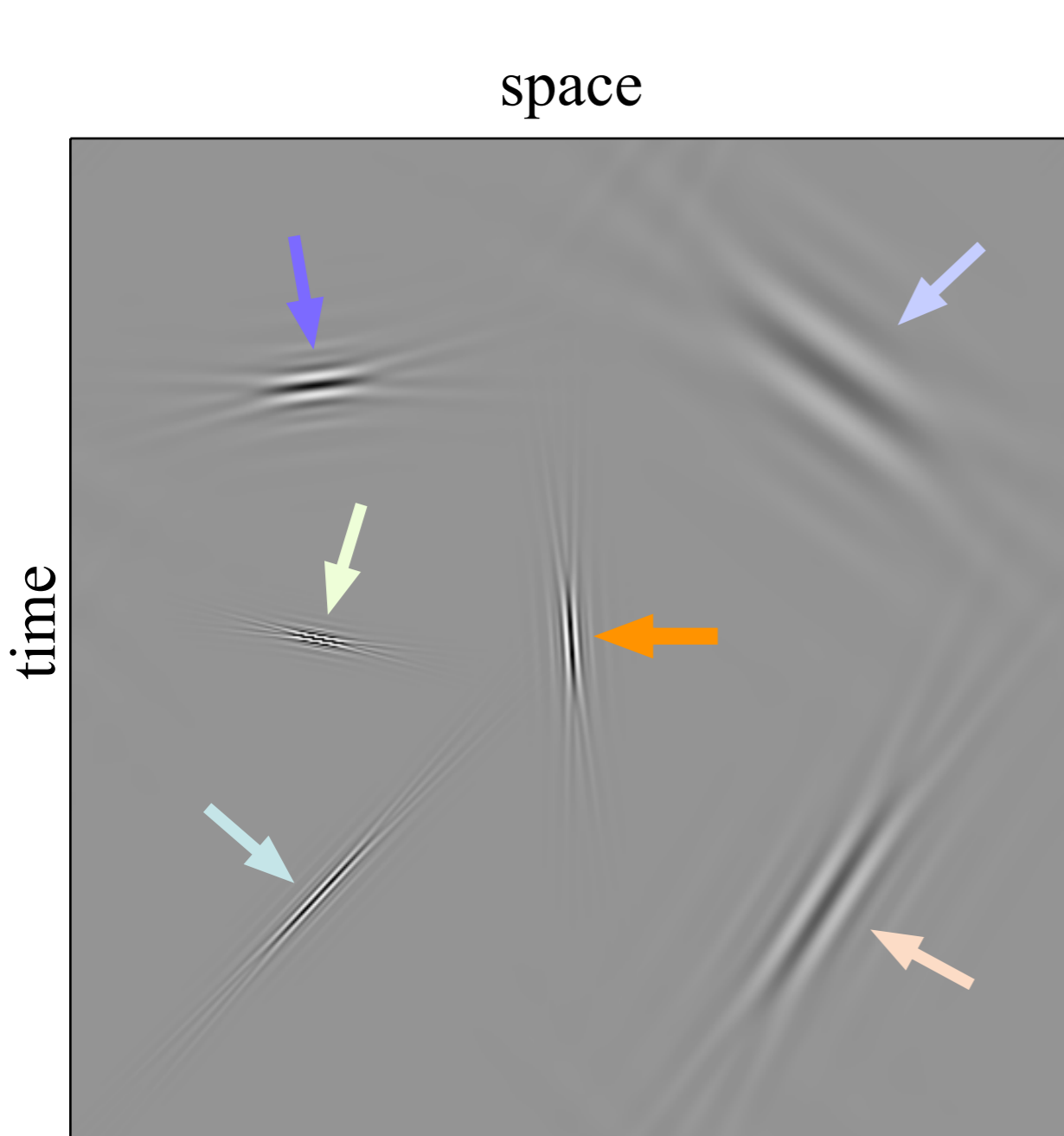
2 detectable Fourier modes



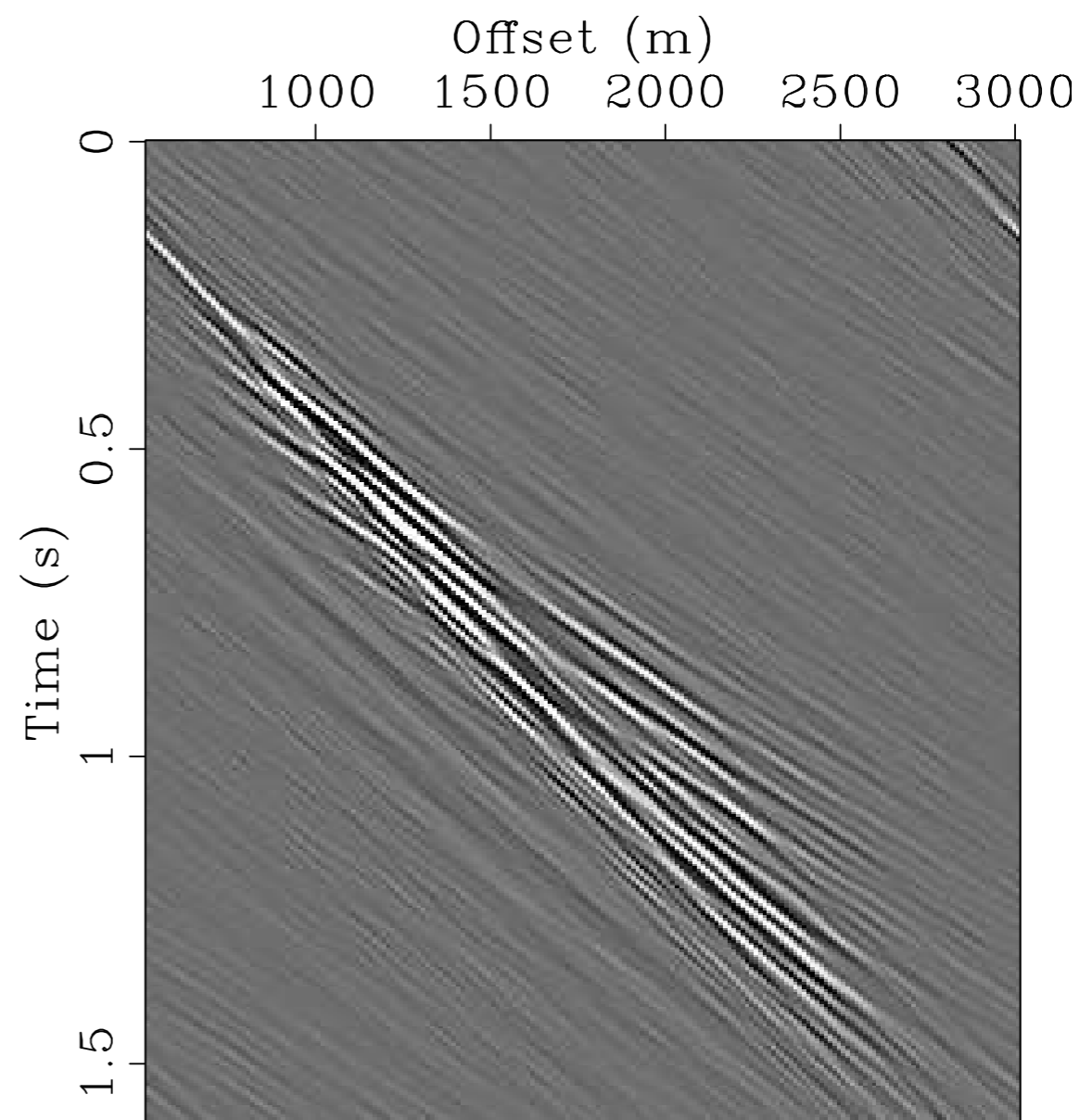
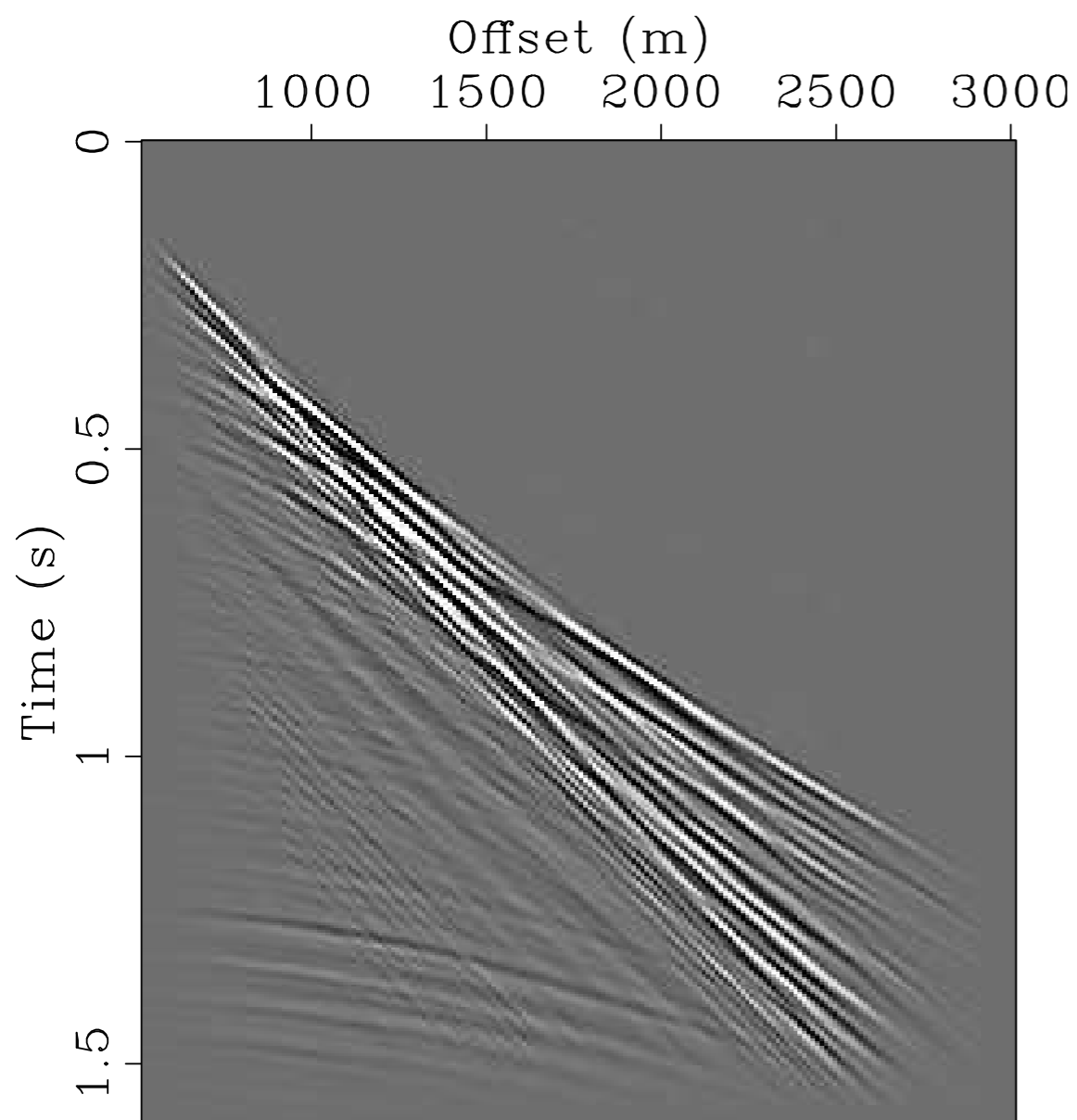
Wavefield sampling and nonlinear recovery

- *sparsifying transform*
 - typically **localized** in the time-space domain to handle the complexity of seismic data
 - curvelet transform (dyadic-parabolic partition of the f-k domain)
 - [windowed Fourier transform]
- *sampling scheme*
 - generates incoherent random undersampling “noise” in the sparsifying domain
 - do not create large gaps
 - because of the limited spatiotemporal extend of transform elements used for the reconstruction
- *sparsity-promoting solver*
 - requires few matrix-vector multiplications

2D discrete curvelets

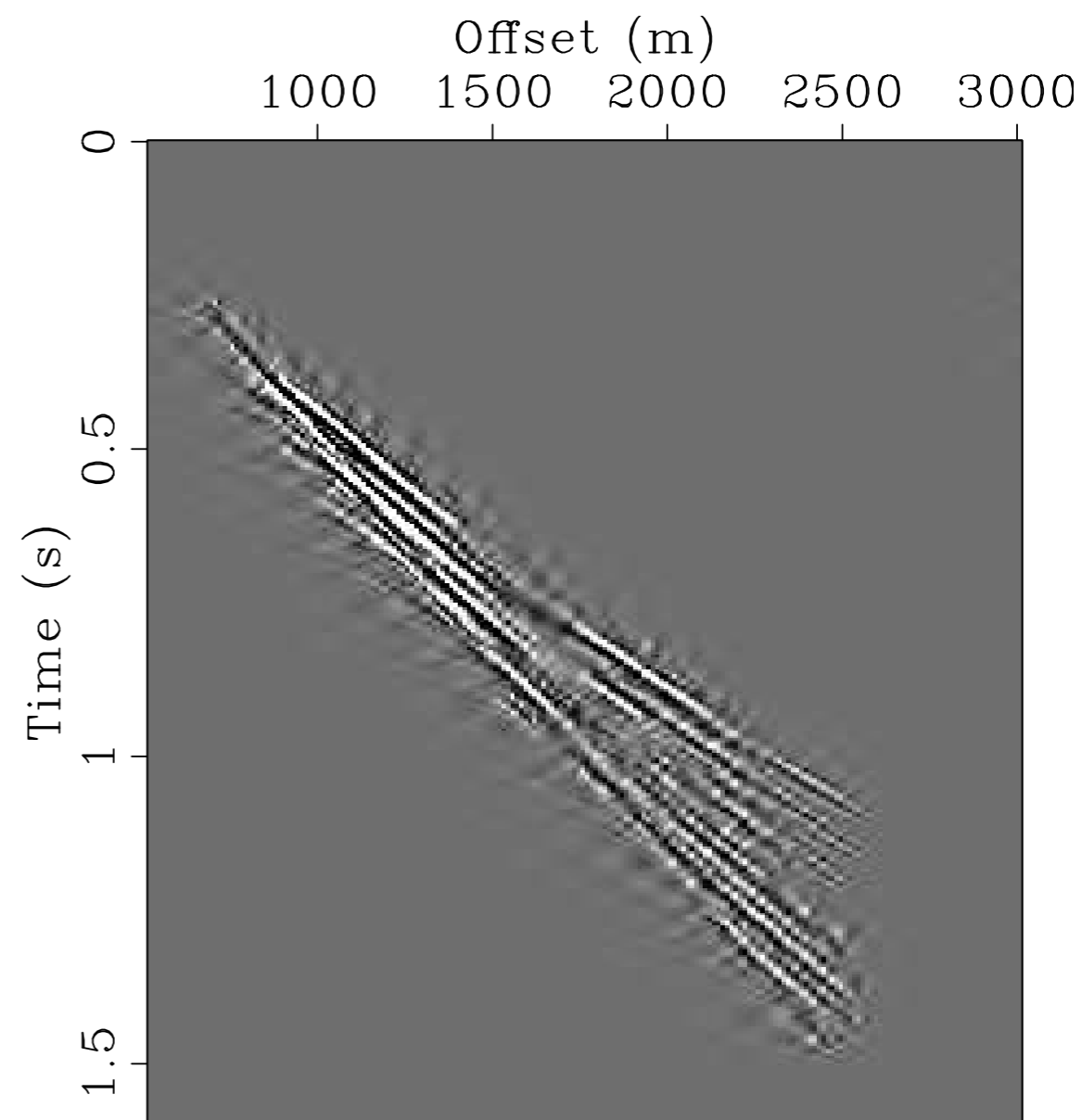
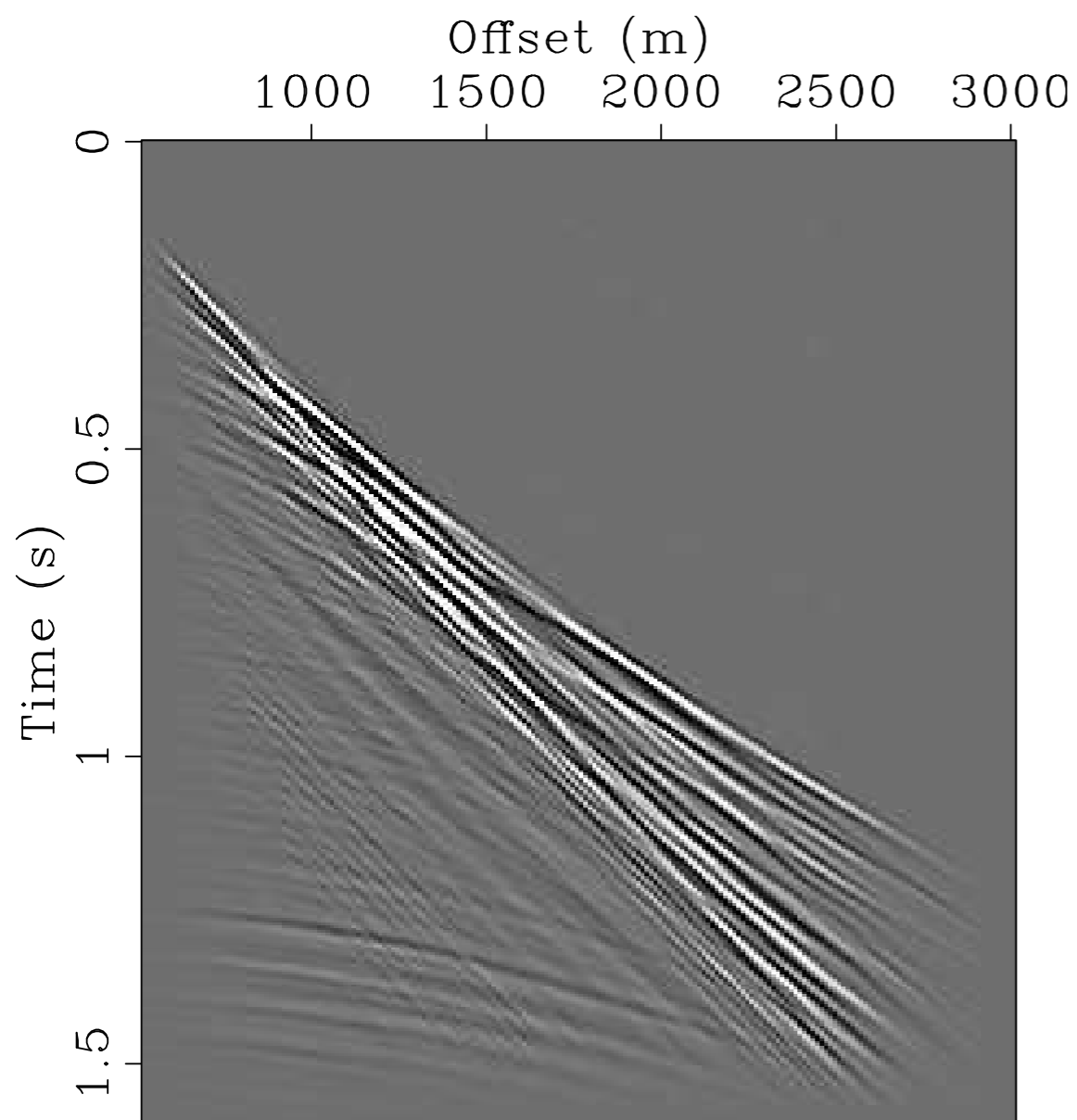


Fourier reconstruction



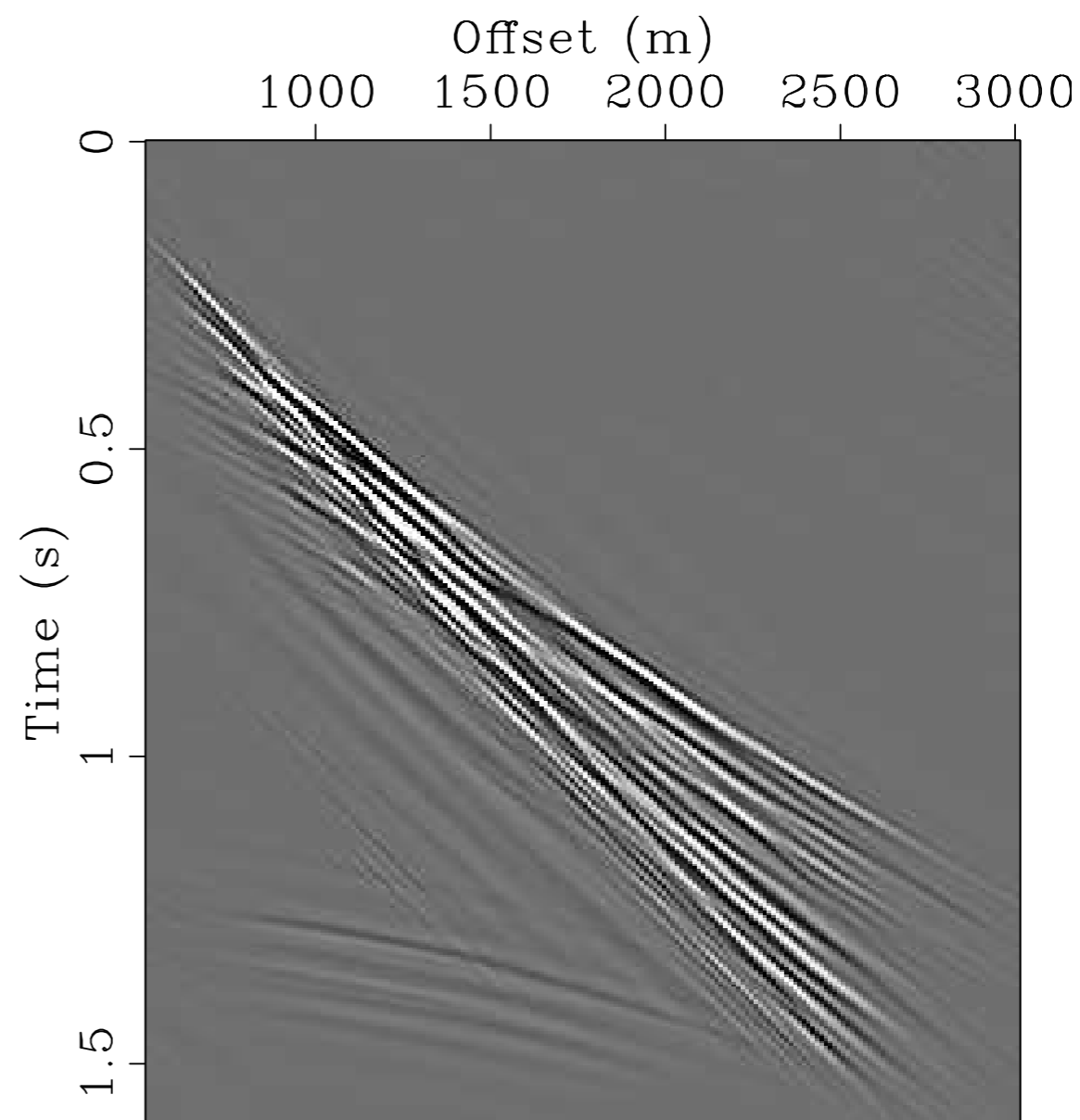
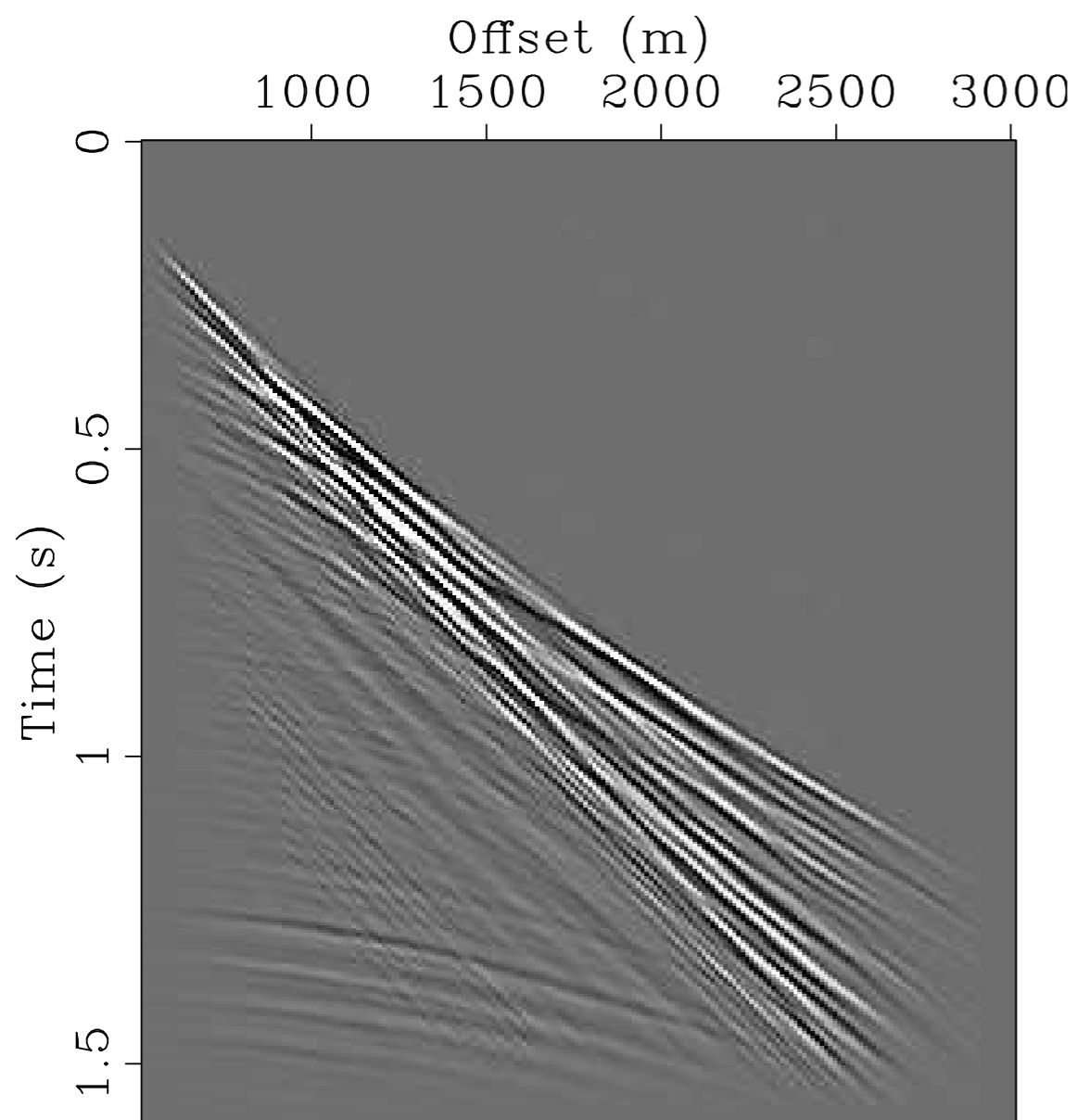
1 % of coefficients

Wavelet reconstruction



1 % of coefficients

Curvelet reconstruction



1 % of coefficients

Wavefield sampling and nonlinear recovery

- *sparsifying transform*

- typically **localized** in the time-space domain to handle the complexity of seismic data
 - curvelet transform (dyadic-parabolic partition of the f-k domain)
 - [windowed Fourier transform]

- *sampling scheme*

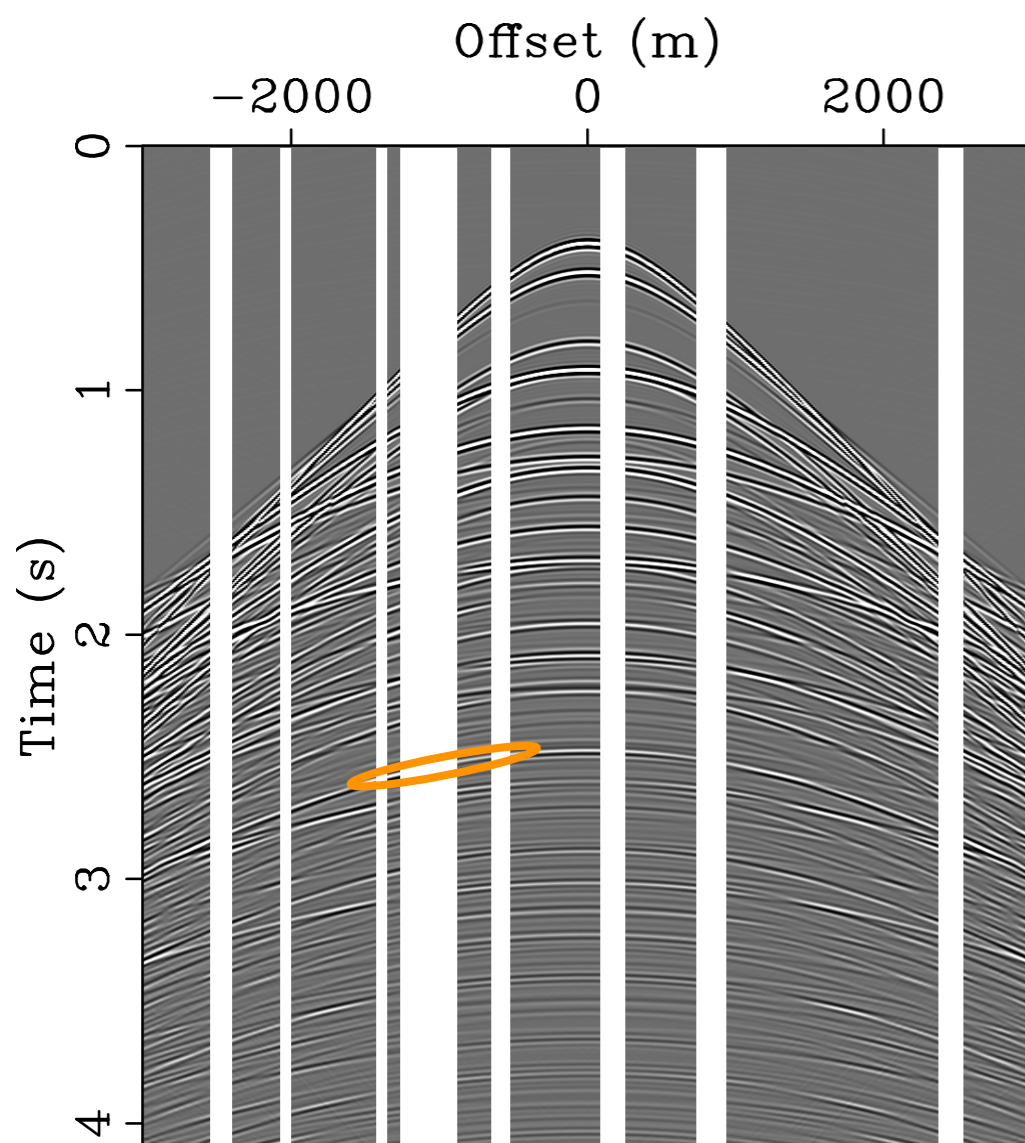
- generates incoherent random undersampling “noise” in the sparsifying domain
- do not create large gaps
 - because of the limited spatiotemporal extend of transform elements used for the reconstruction

- *sparsity-promoting solver*

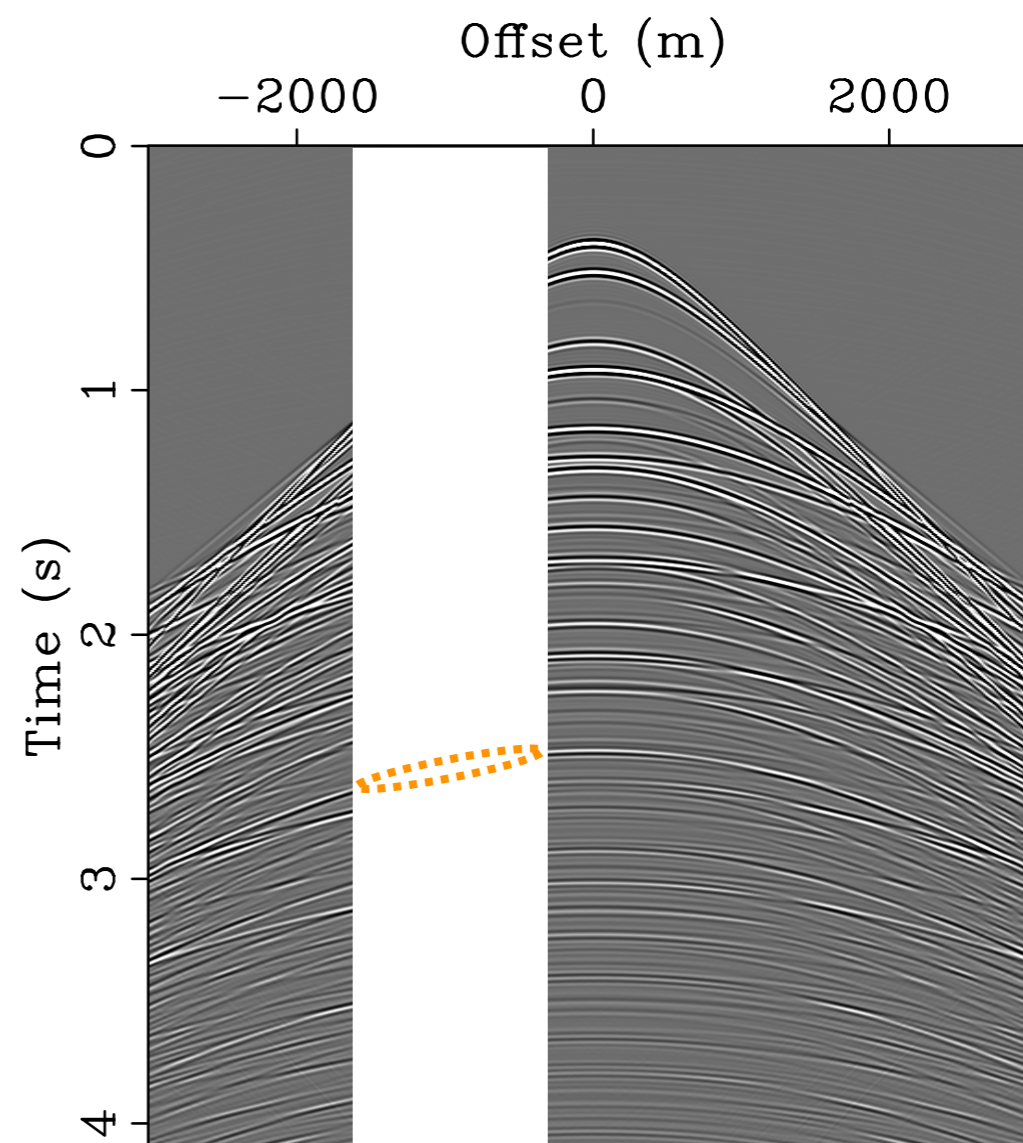
- requires few matrix-vector multiplications

Localized transform elements & gap size

$$\tilde{\mathbf{x}} = \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = \mathbf{A}\mathbf{x}$$



Data



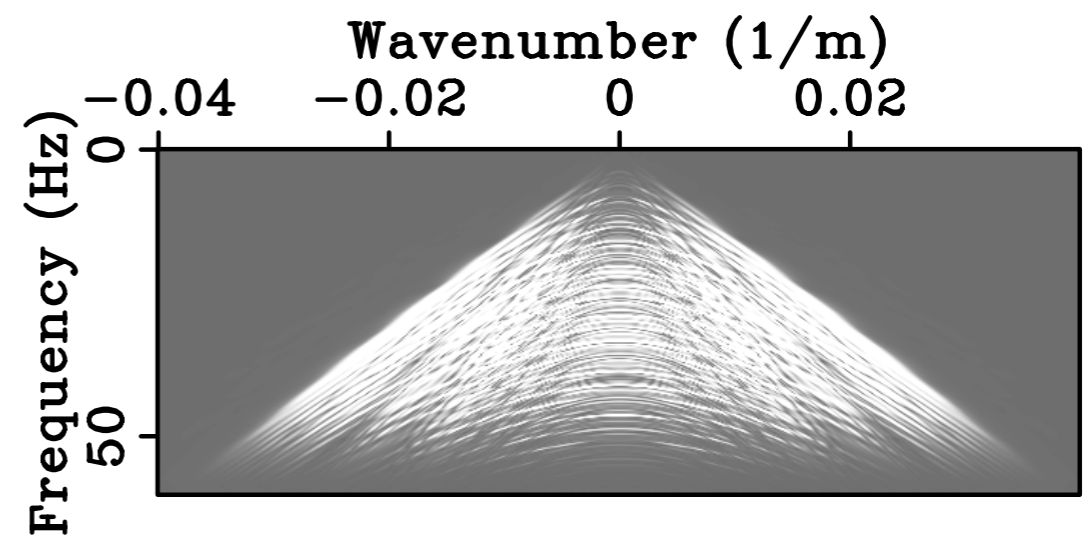
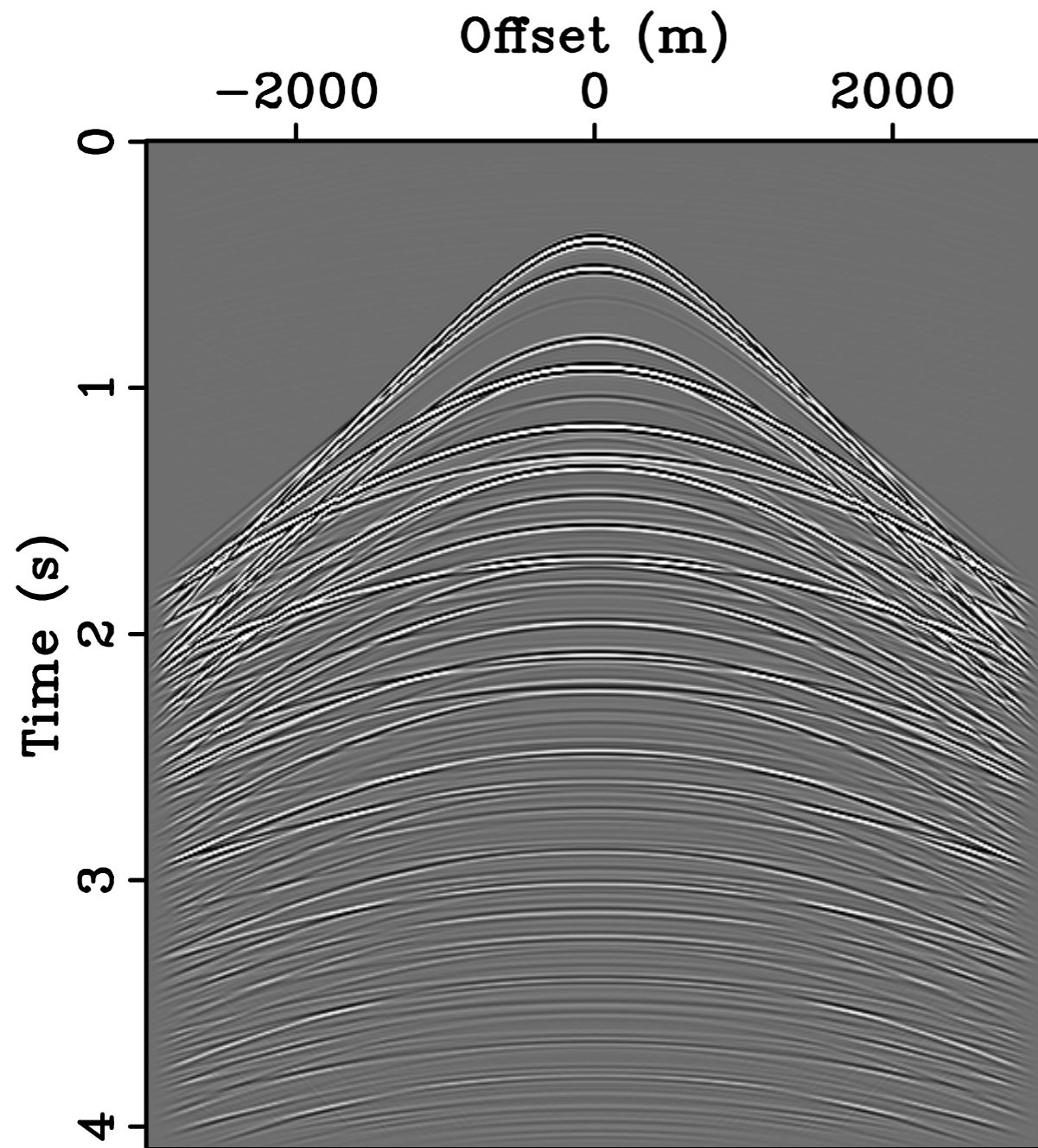
Data



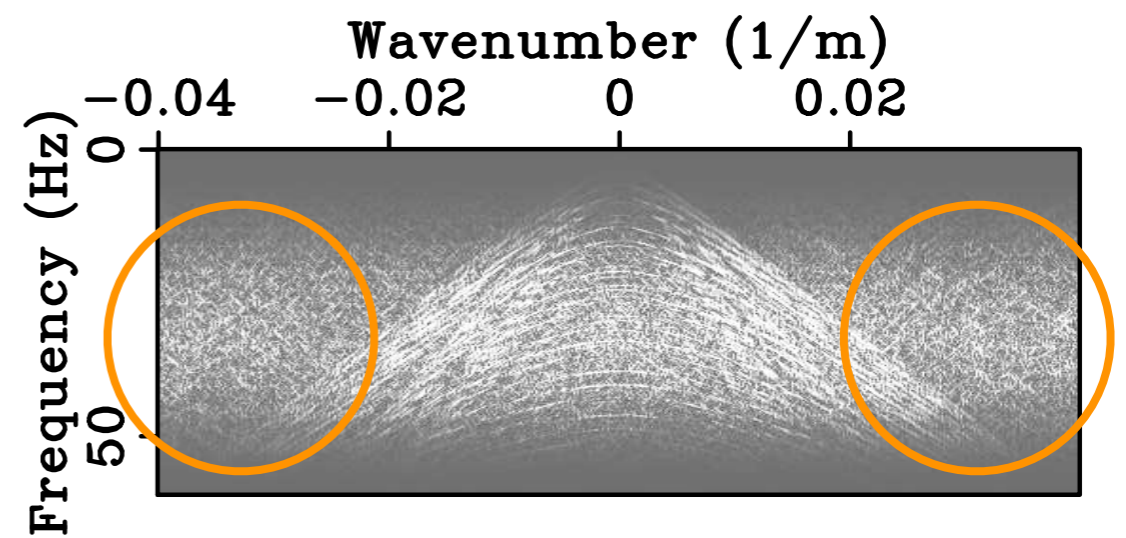
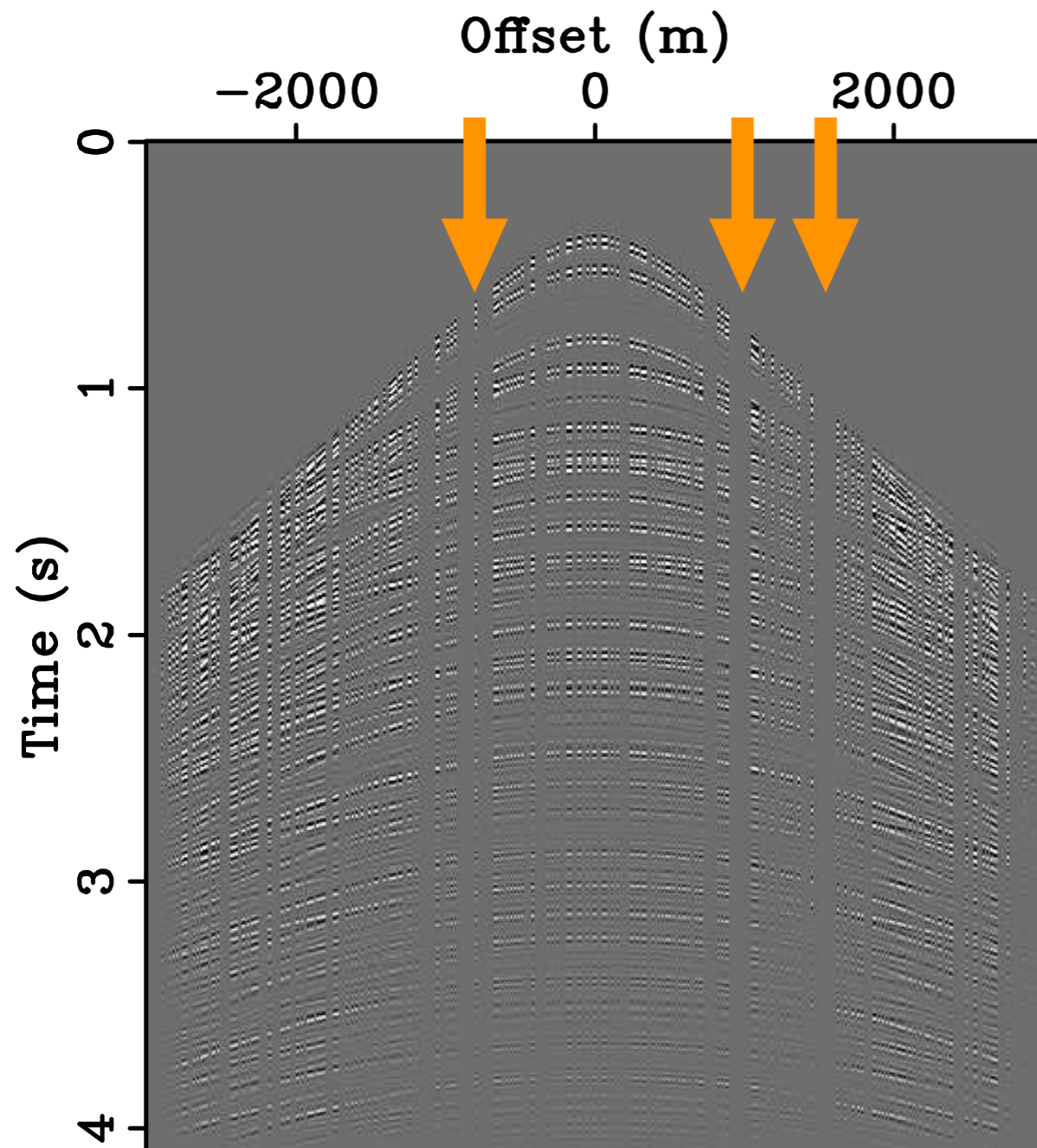
Discrete *randomized* jittered undersampling



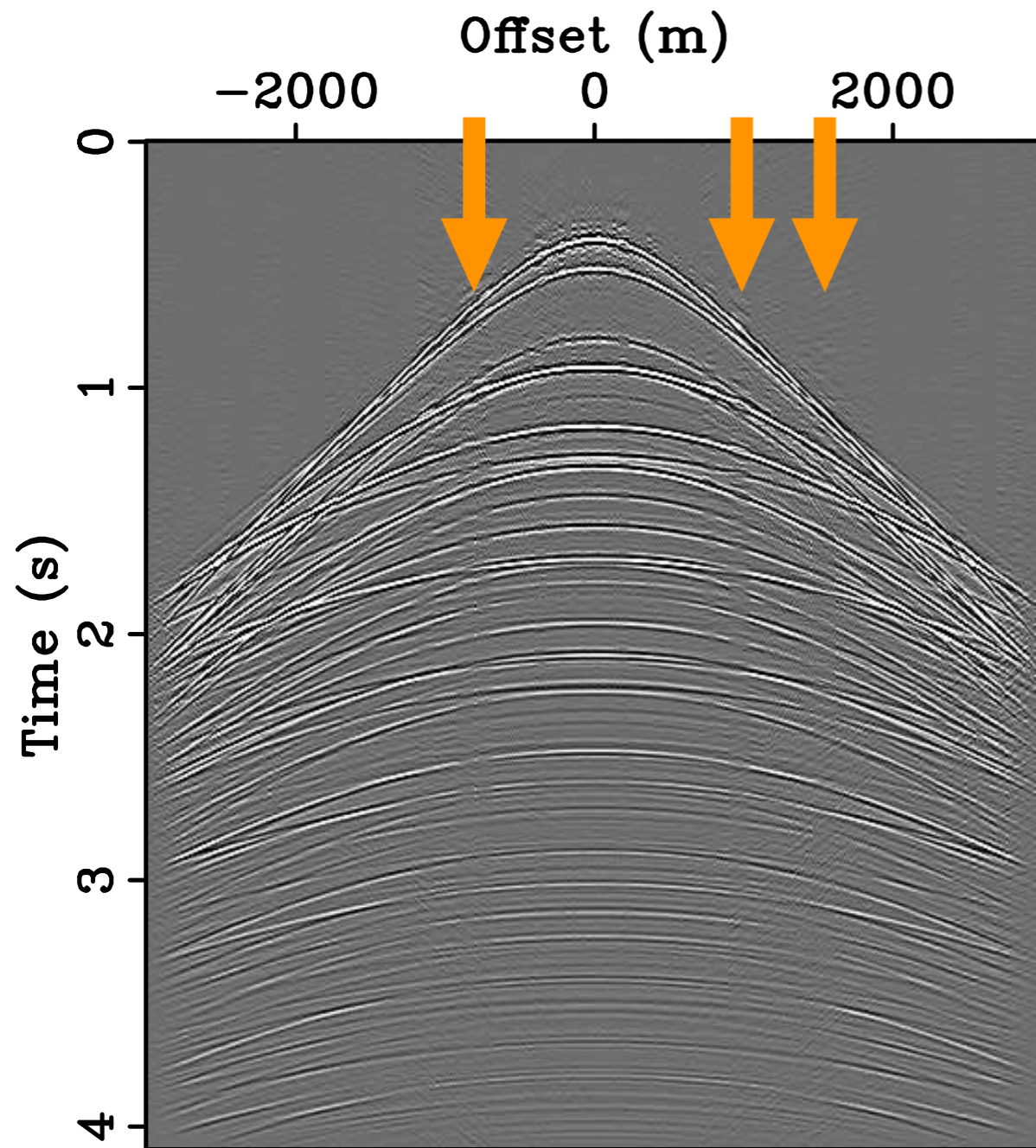
Model



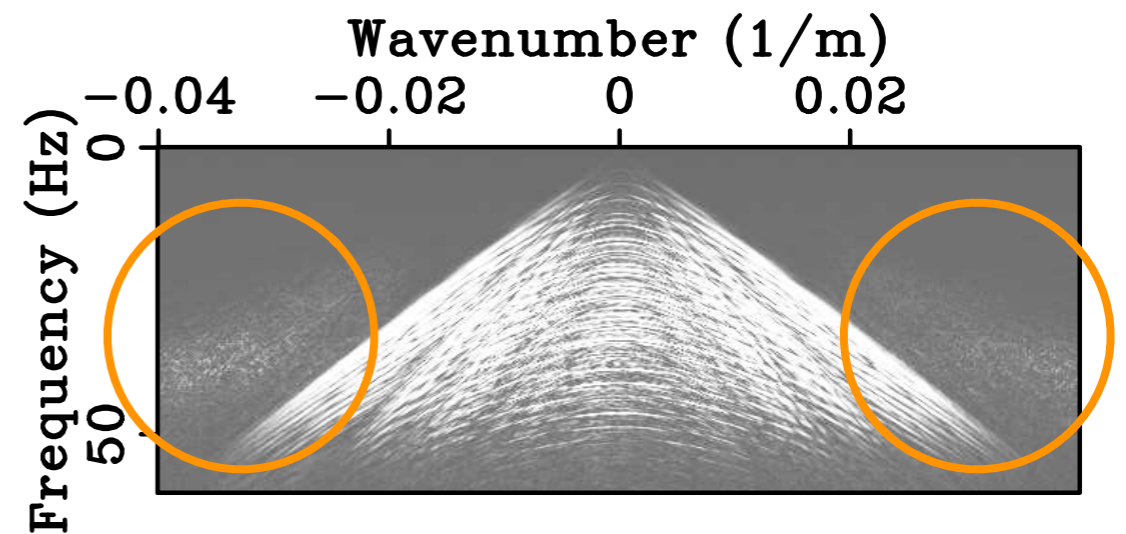
Random 3-fold undersampling



CRSI from random 3-fold undersampling

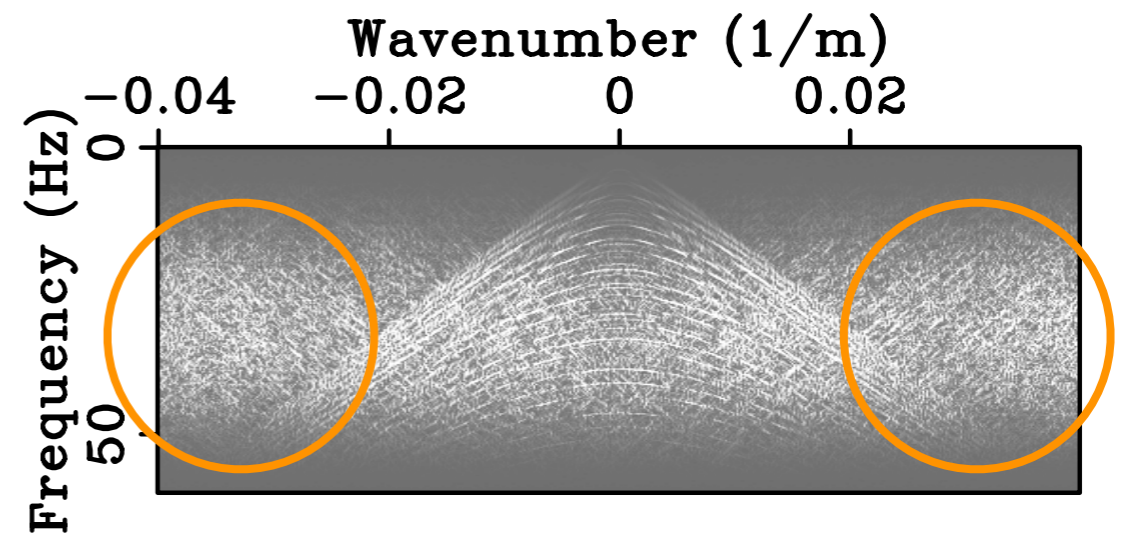
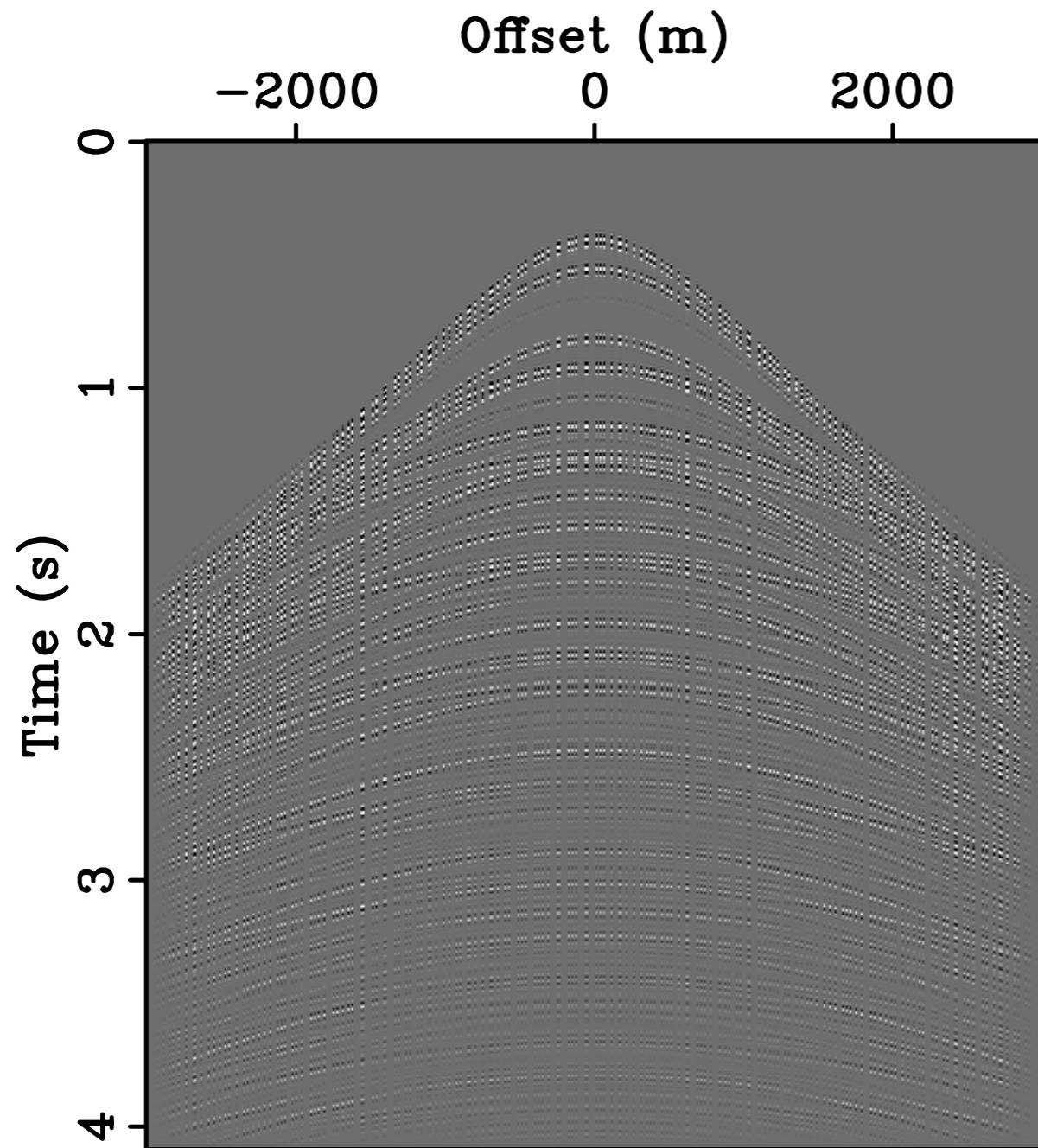


SNR = 9.72 dB

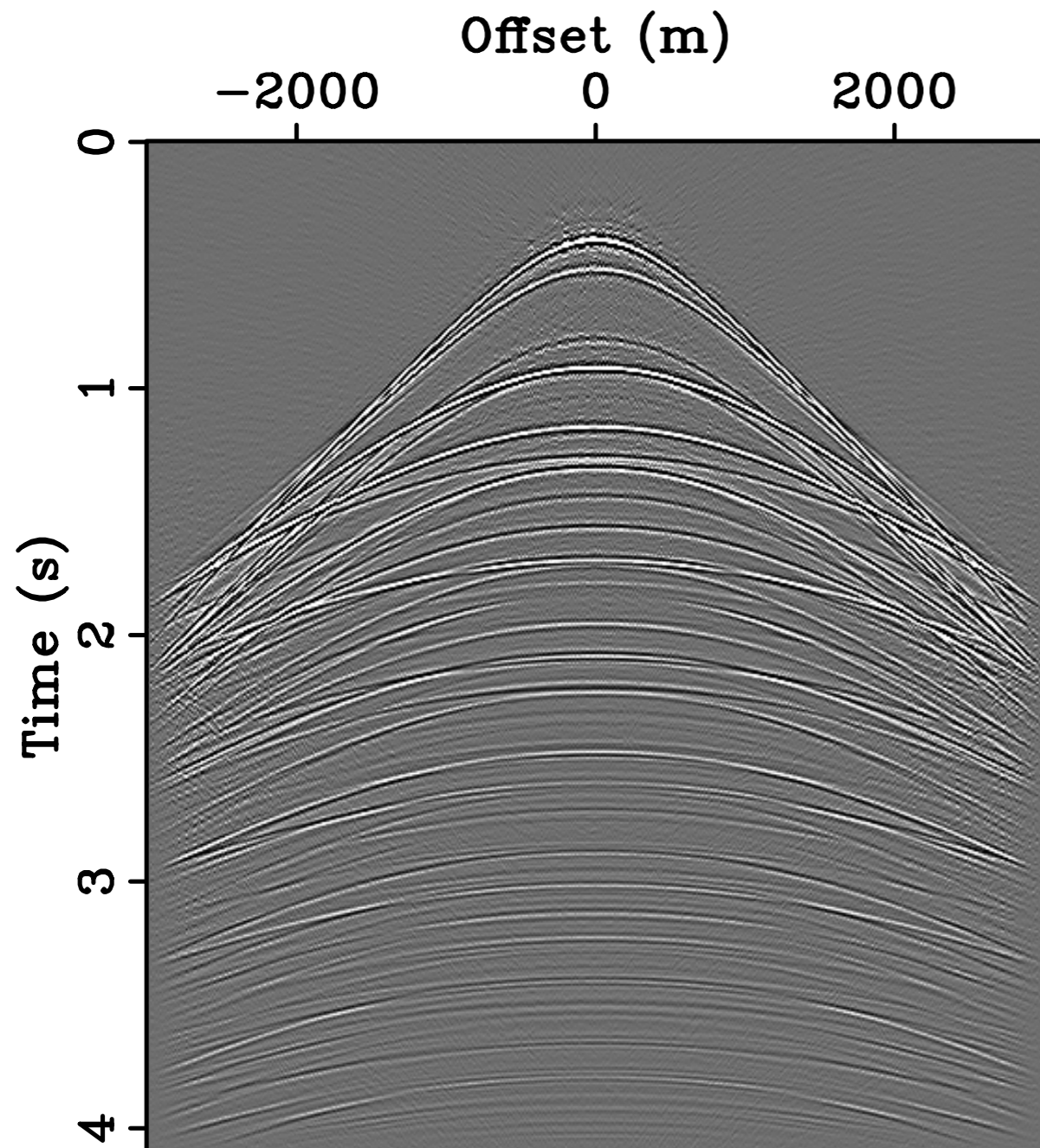


$$\text{SNR} = 20 \times \log_{10} \left(\frac{\|\text{model}\|_2}{\|\text{reconstruction error}\|_2} \right)$$

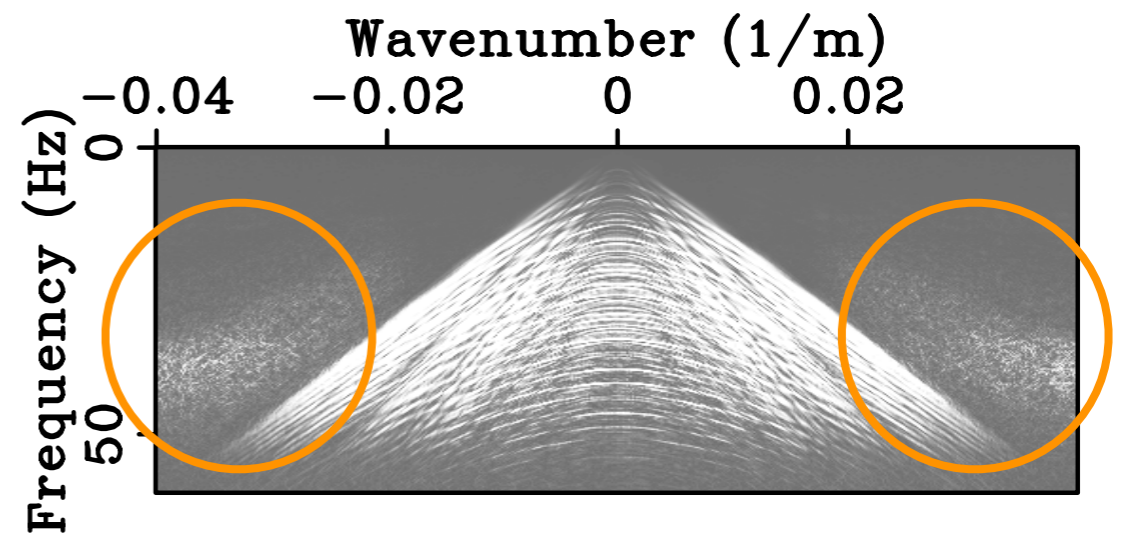
Optimally-jittered 3-fold undersampling



CRSI from opt.-jittered 3-fold undersampling



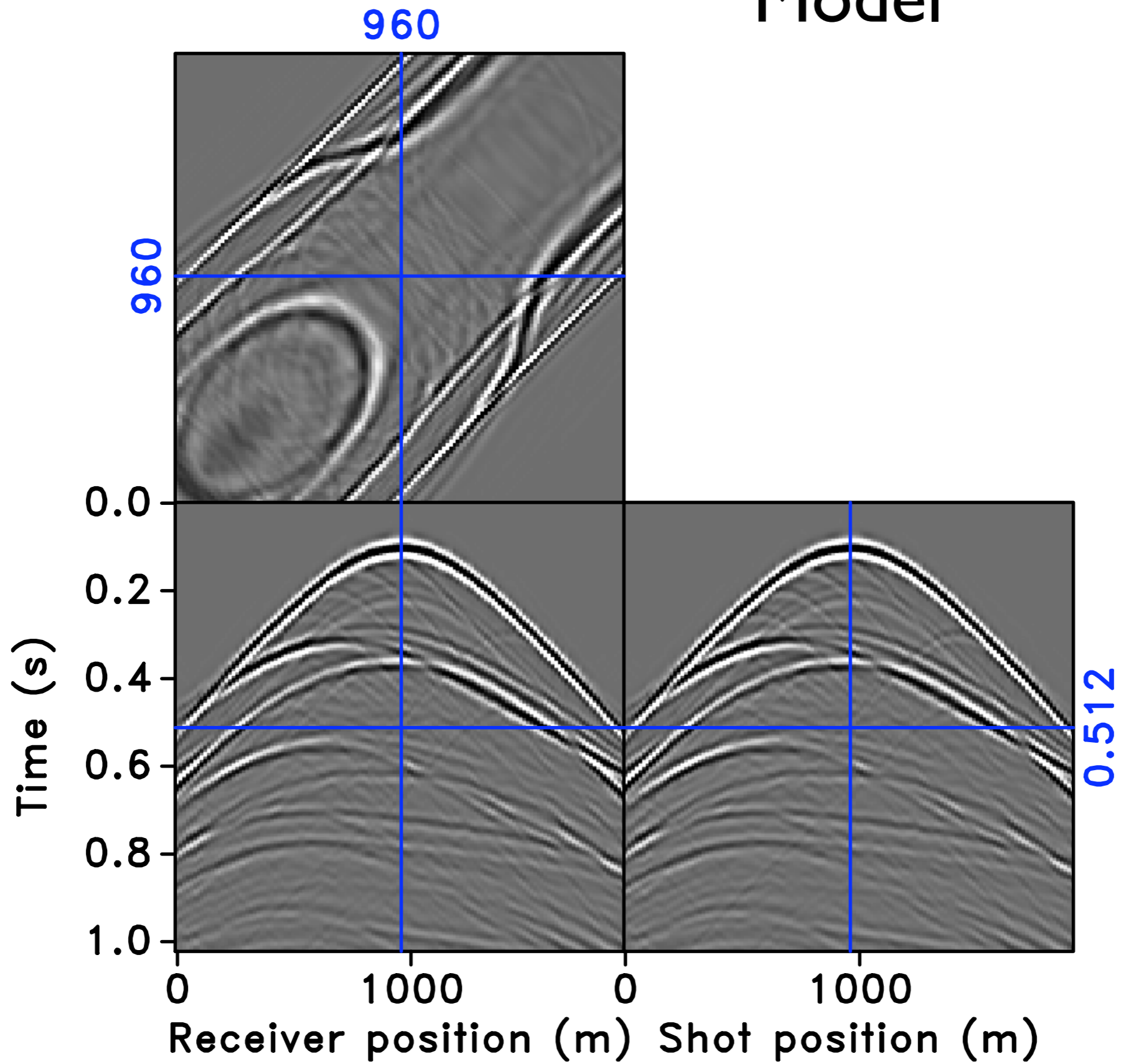
SNR = 10.42 dB



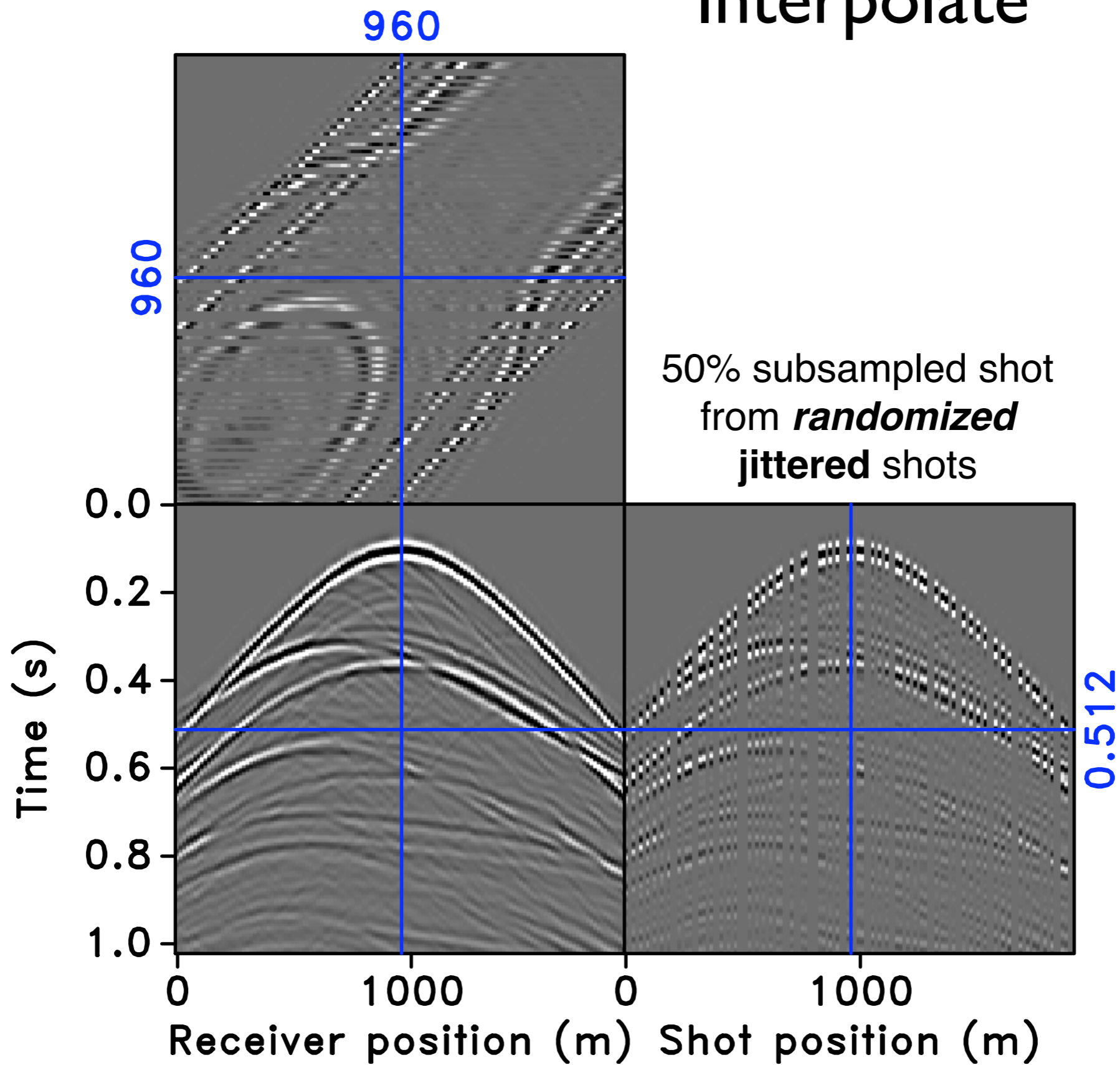
Question

- Question: What is better? Having missing *single-source* or *missing randomized simultaneous* experiments?
- Comparison between different undersampling strategies for source experiments:
 - *Randomized* jittered shot positions
 - *Randomized* simultaneous shots

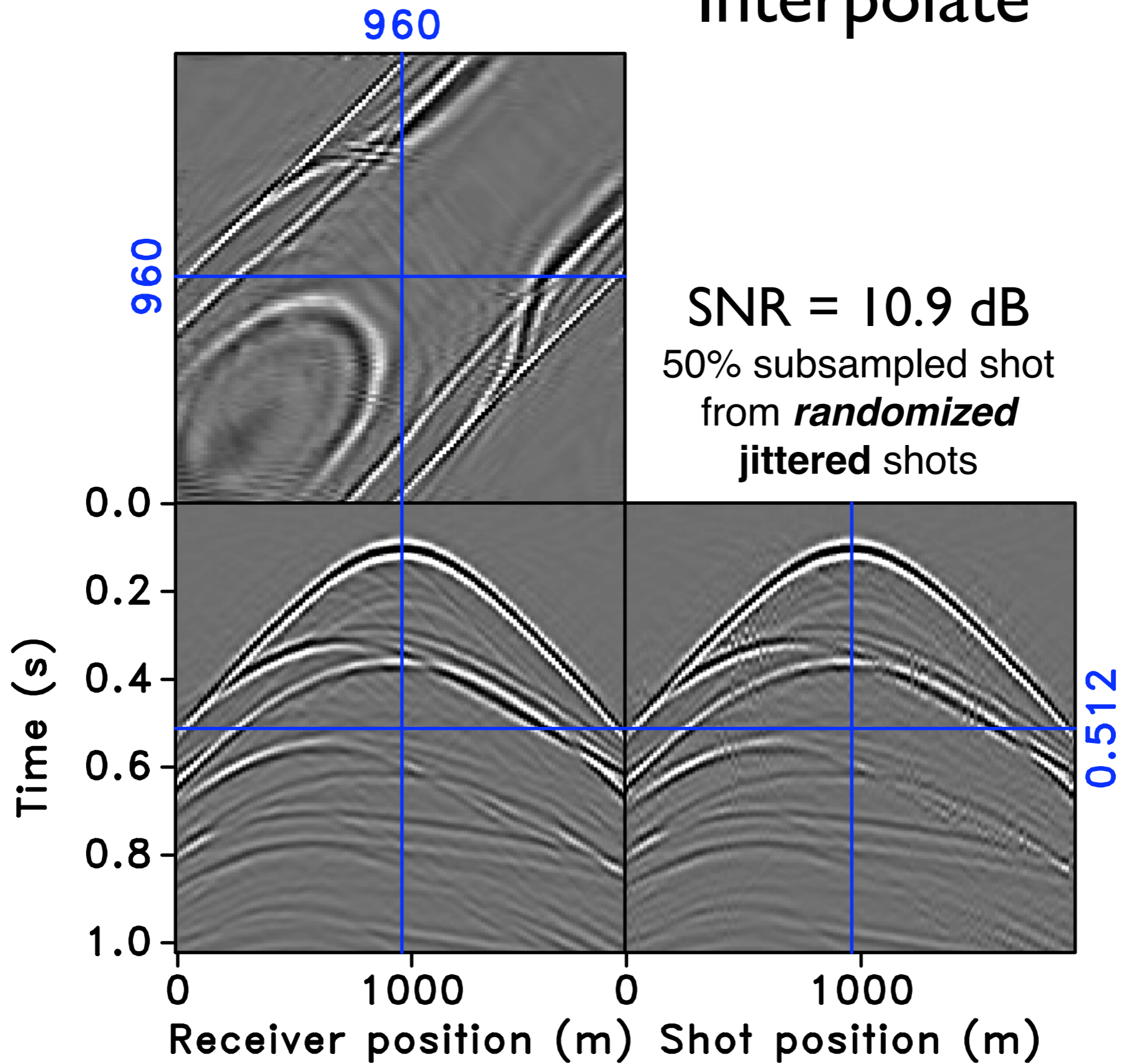
Model



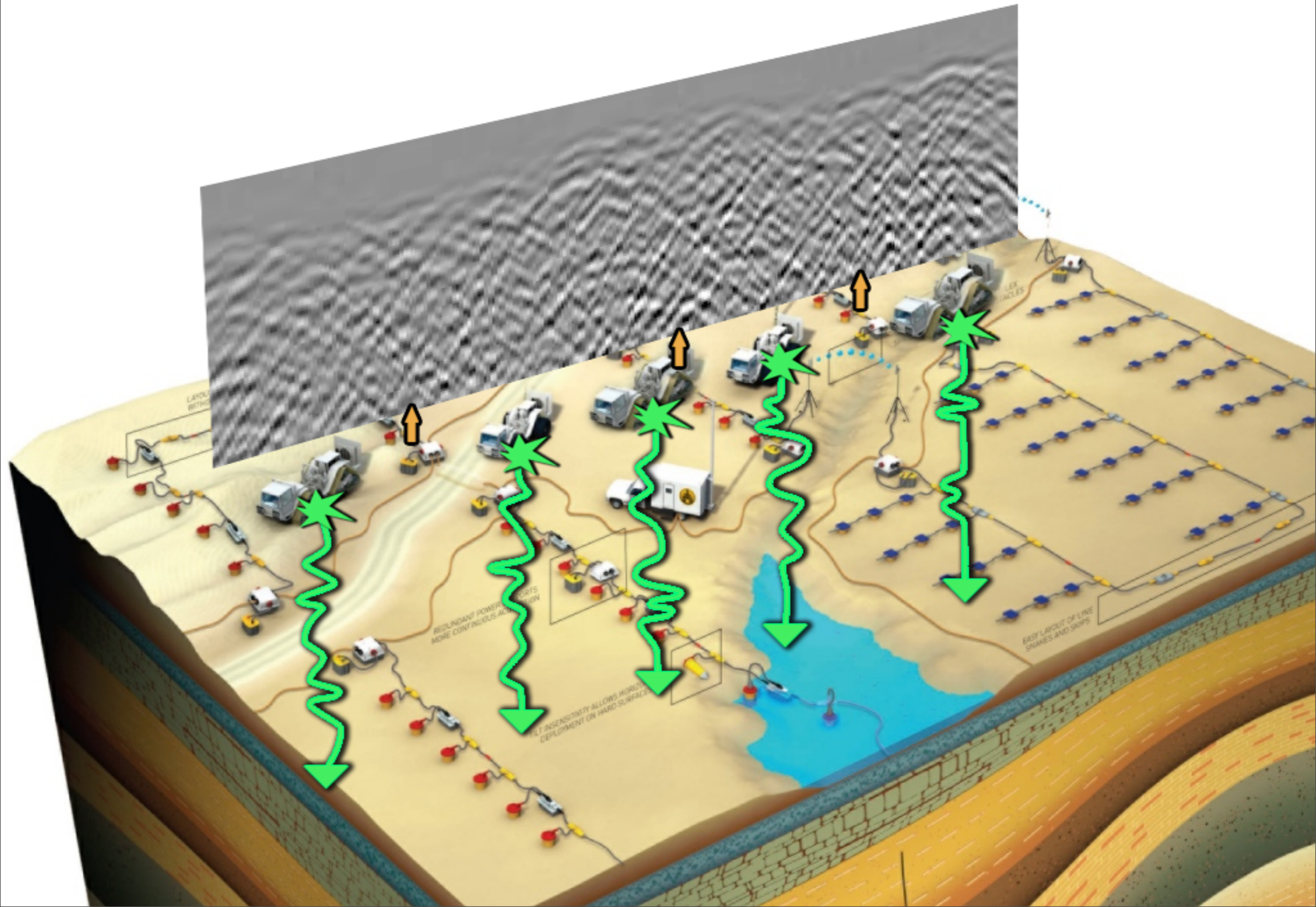
Interpolate



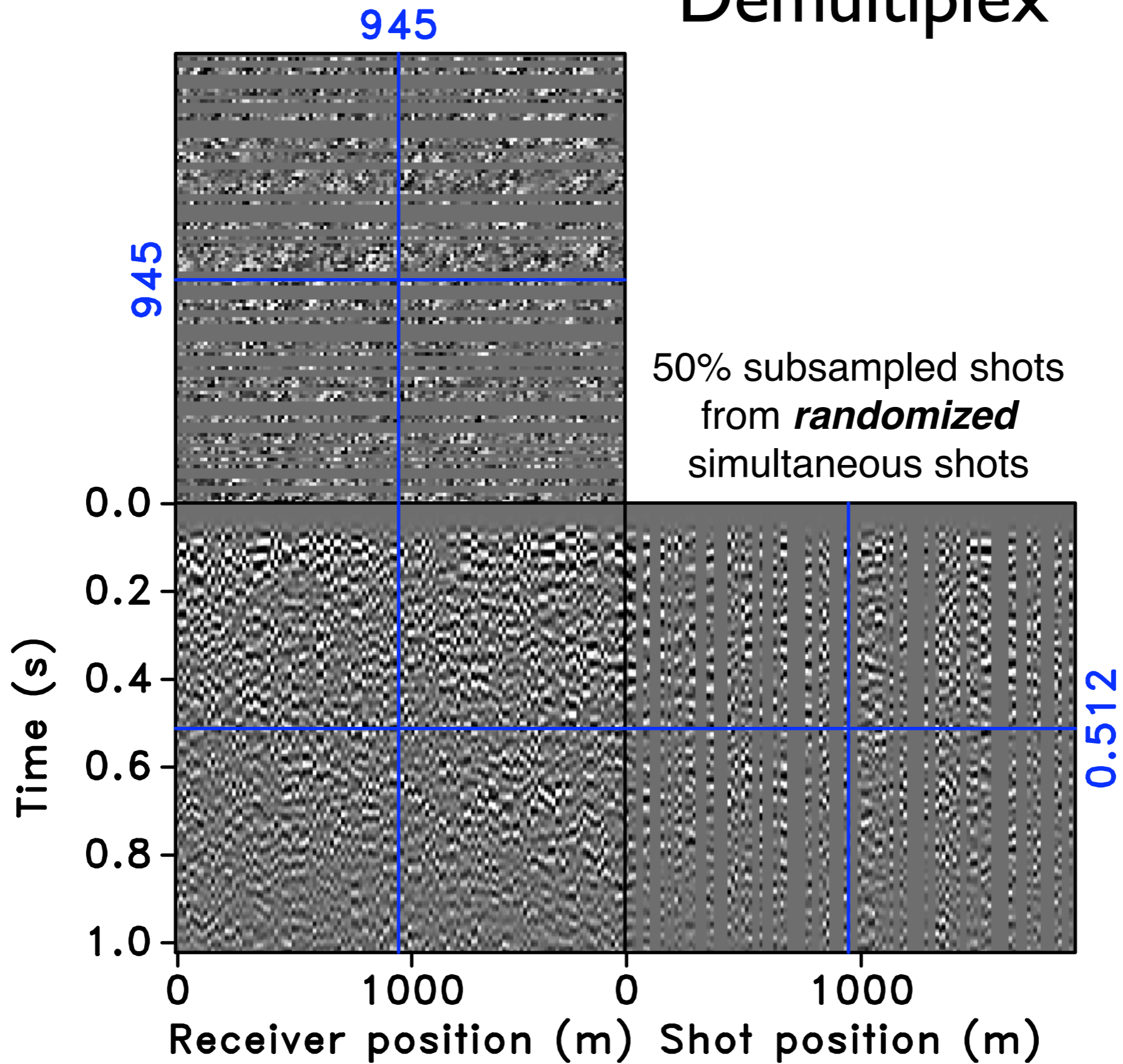
Interpolate



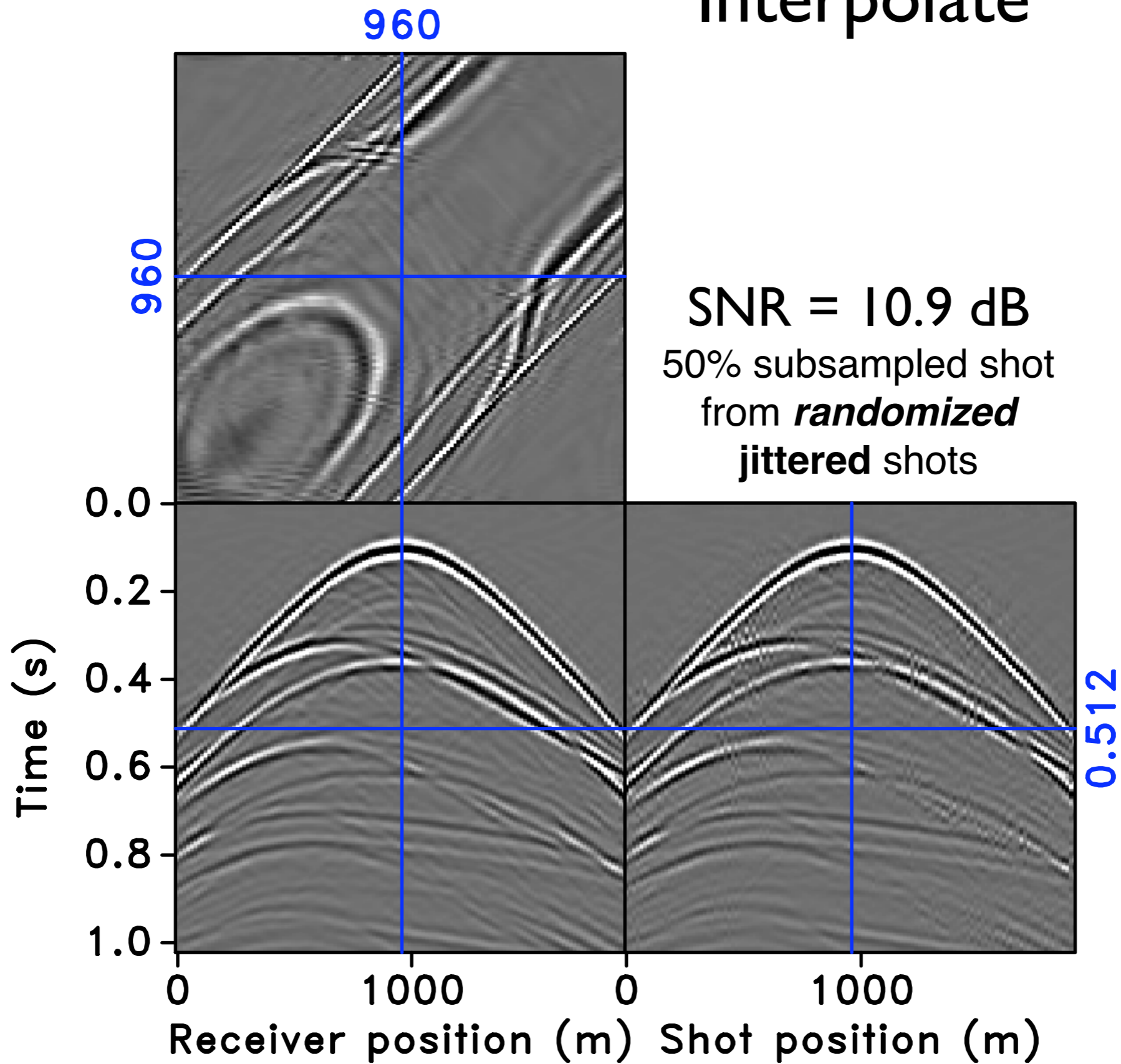
Simultaneous & continuous sources



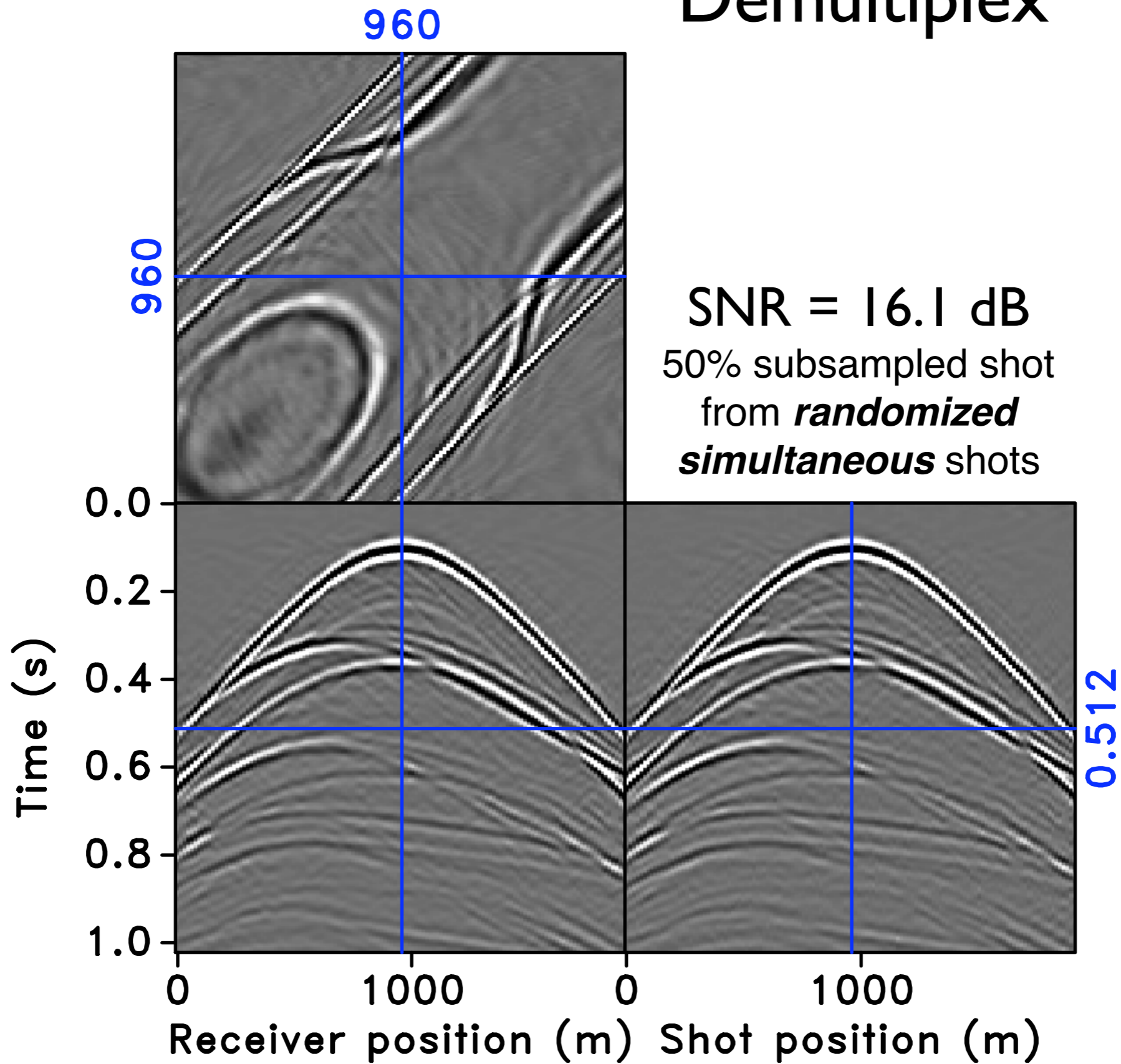
Demultiplex



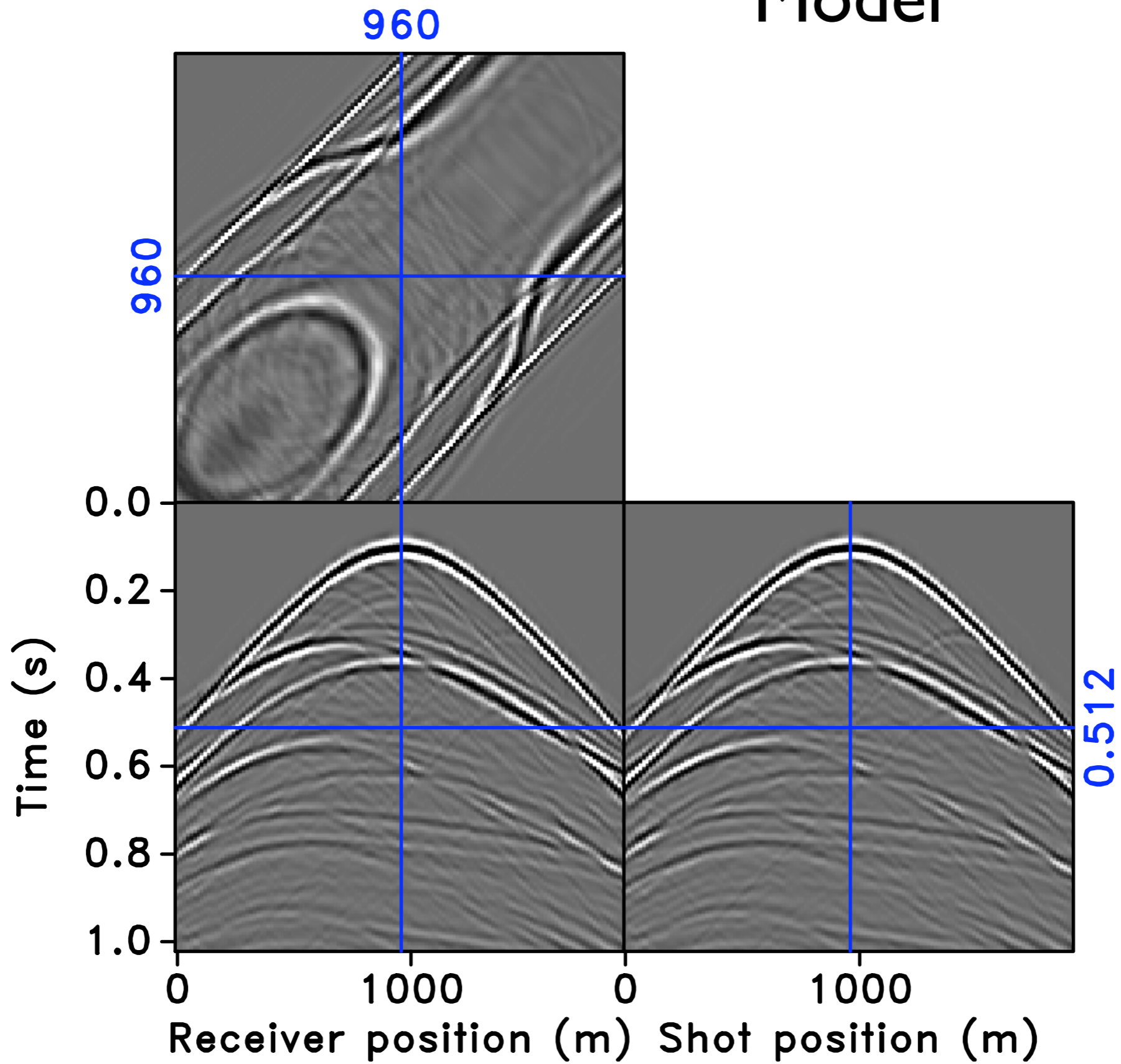
Interpolate



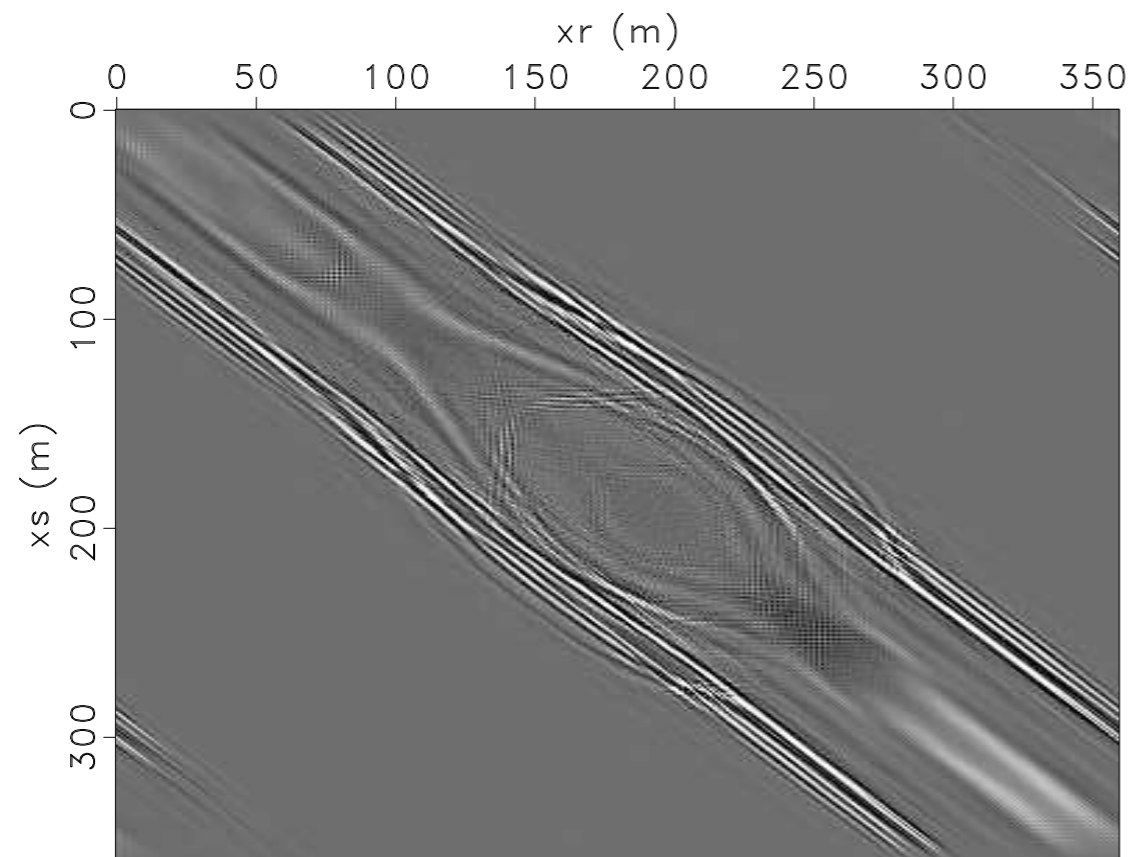
Demultiplex



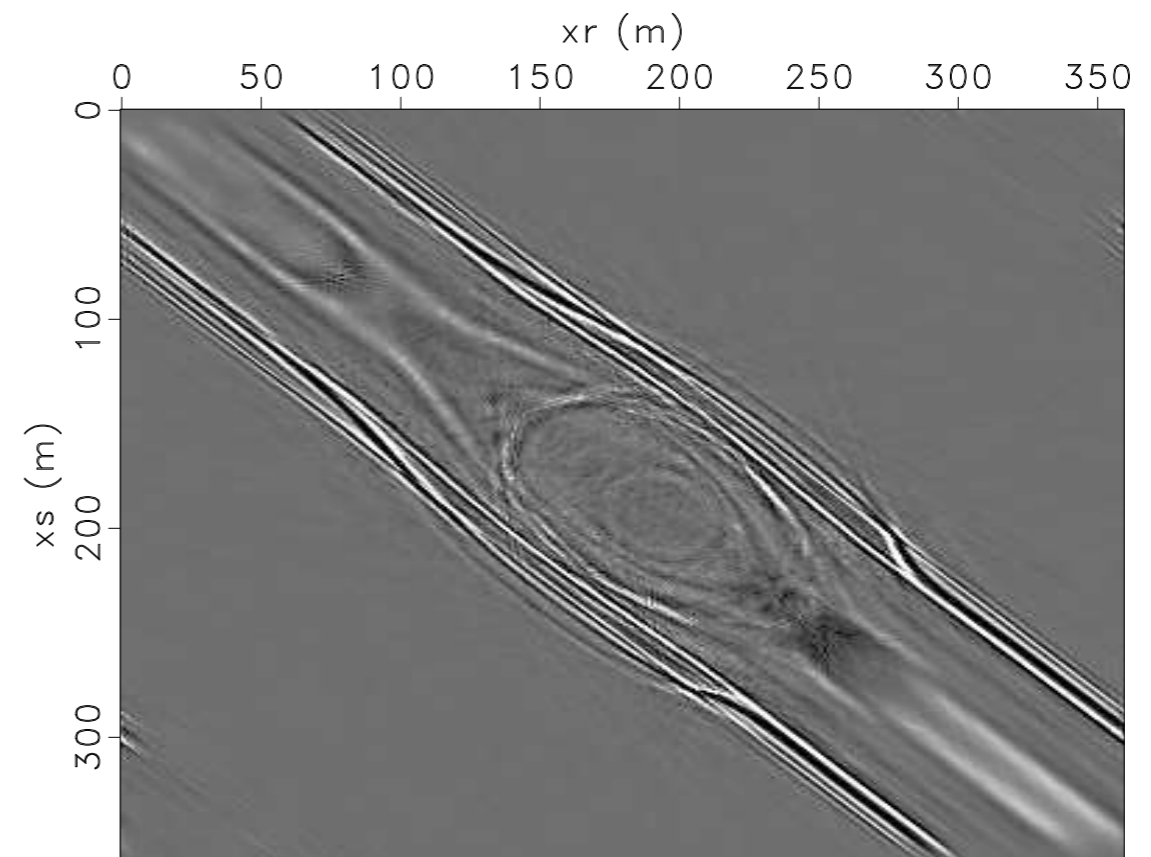
Model



Regular vs uniform randomized 2D sampling

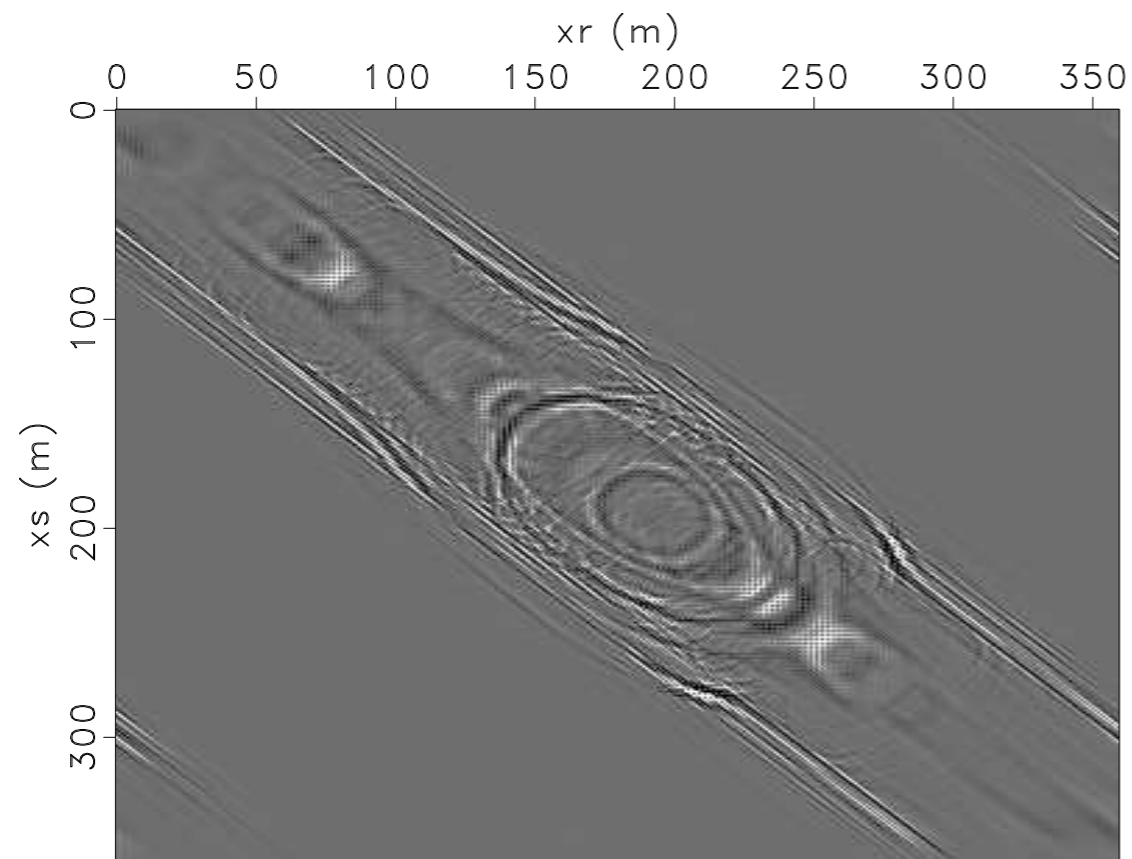


CRSI reconstruction from
regular 2-D sampling
(25% of data taken)
SNR: 4.161 dB

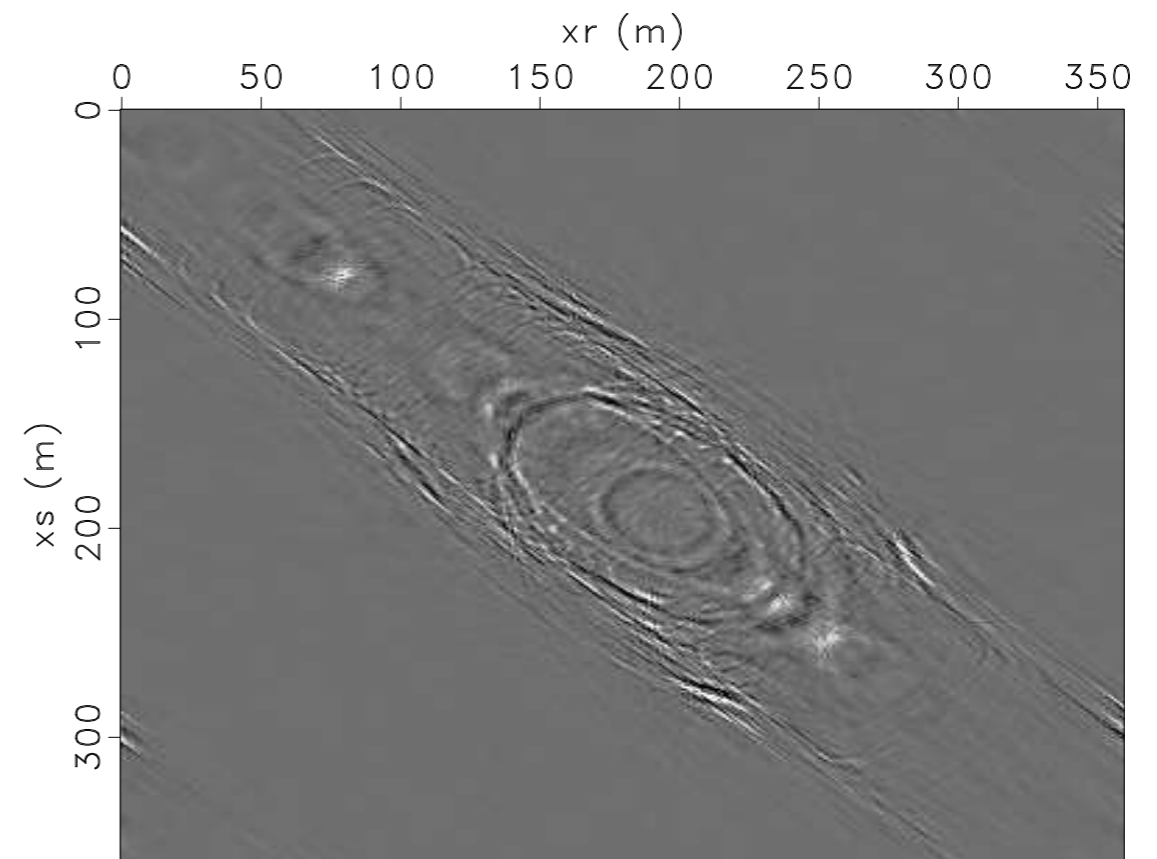


CRSI reconstruction from
randomized 2-D sampling
(25% of data taken)
SNR: 9.979 dB

Regular vs randomized sampling - residuals

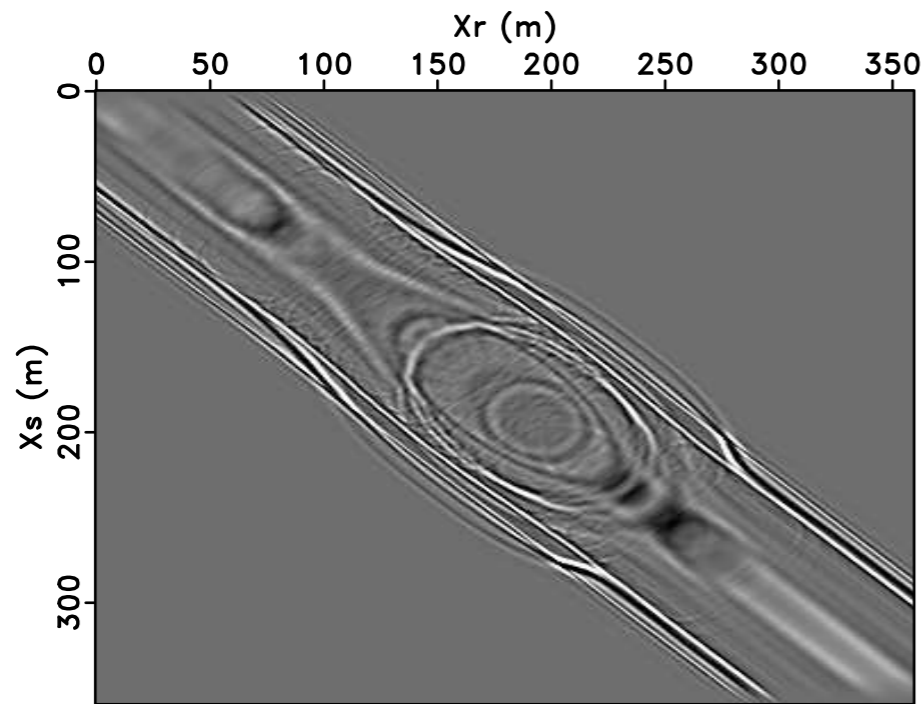


Regular sampling
residual

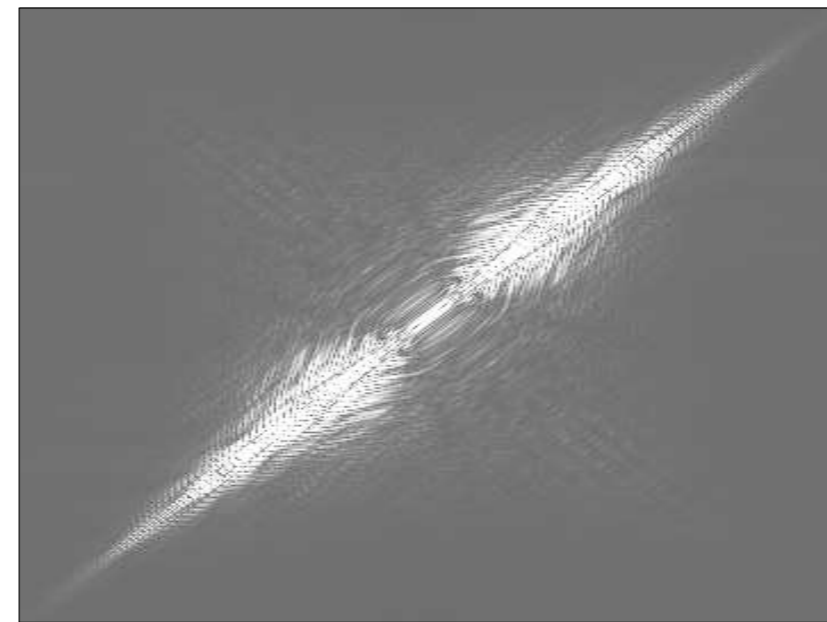


Random sampling
residual

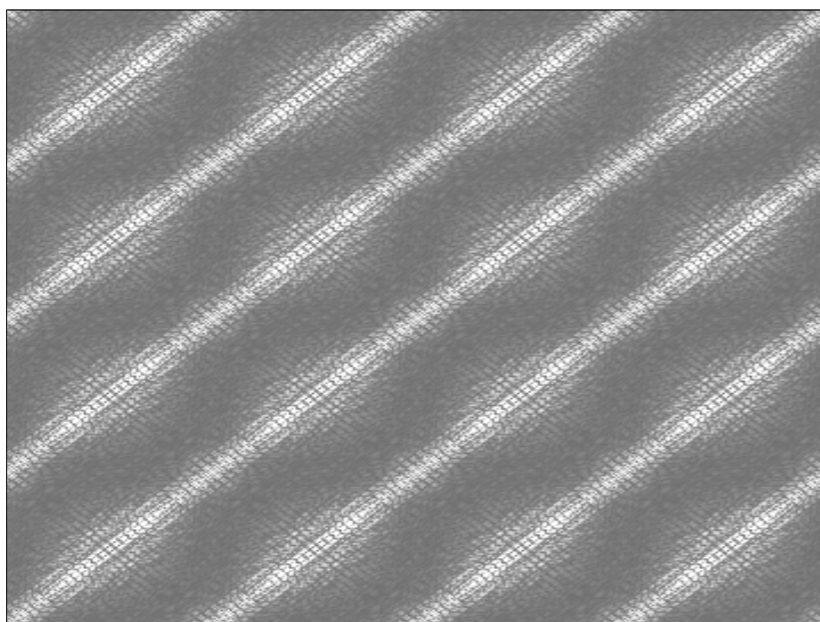
Regular vs. irregular sampling - freq. domain



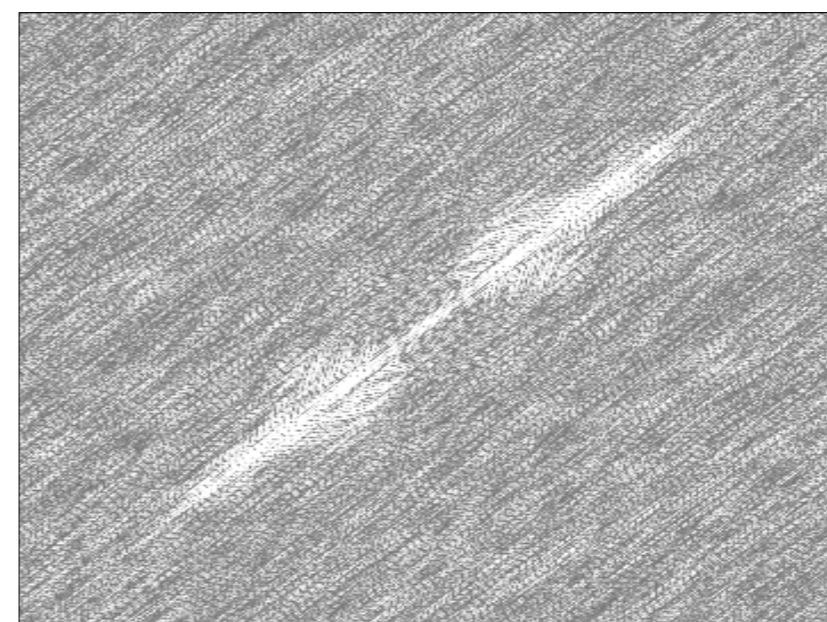
Original model



Original model spectrum



Reg. undersampled spectrum



Irreg. undersampled spectrum

2-D discrete random *jittered* sampling

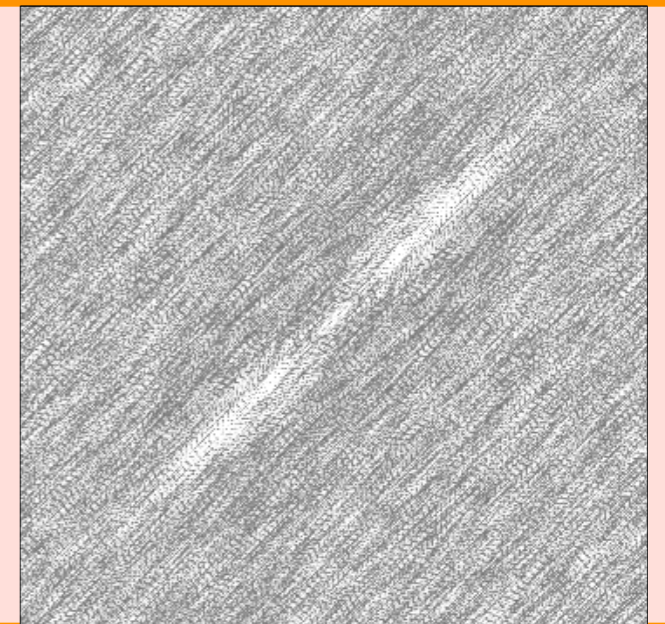
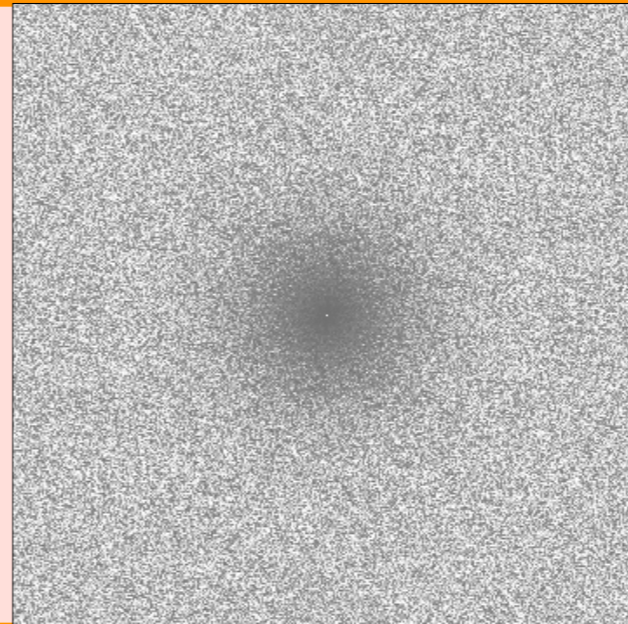
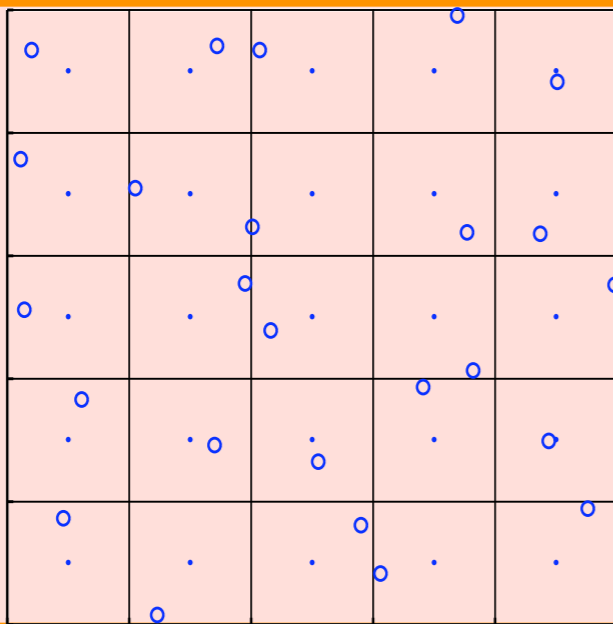
Type

Sampling scheme

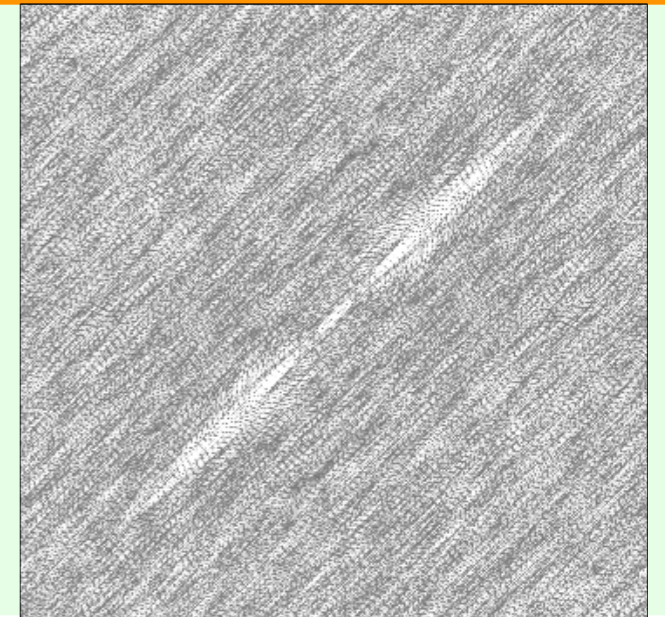
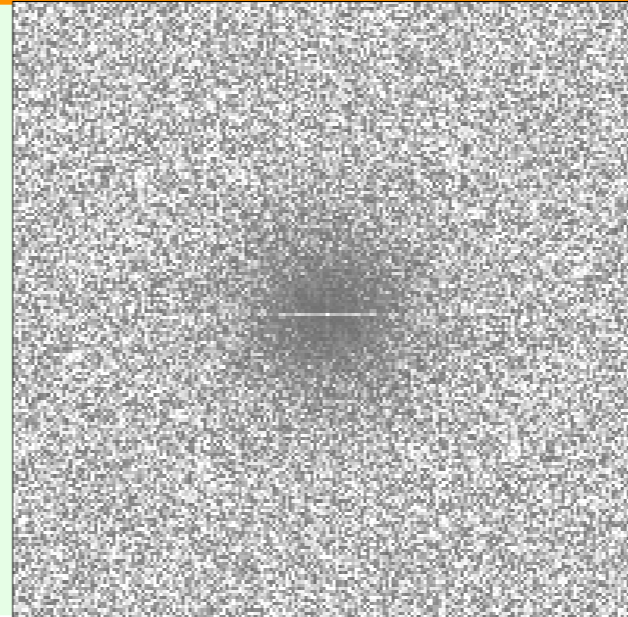
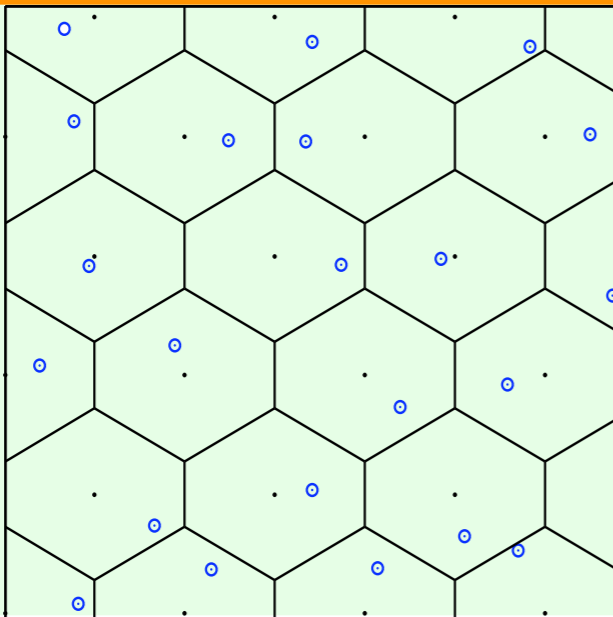
Mask's spectra

Samples' spectra

Square

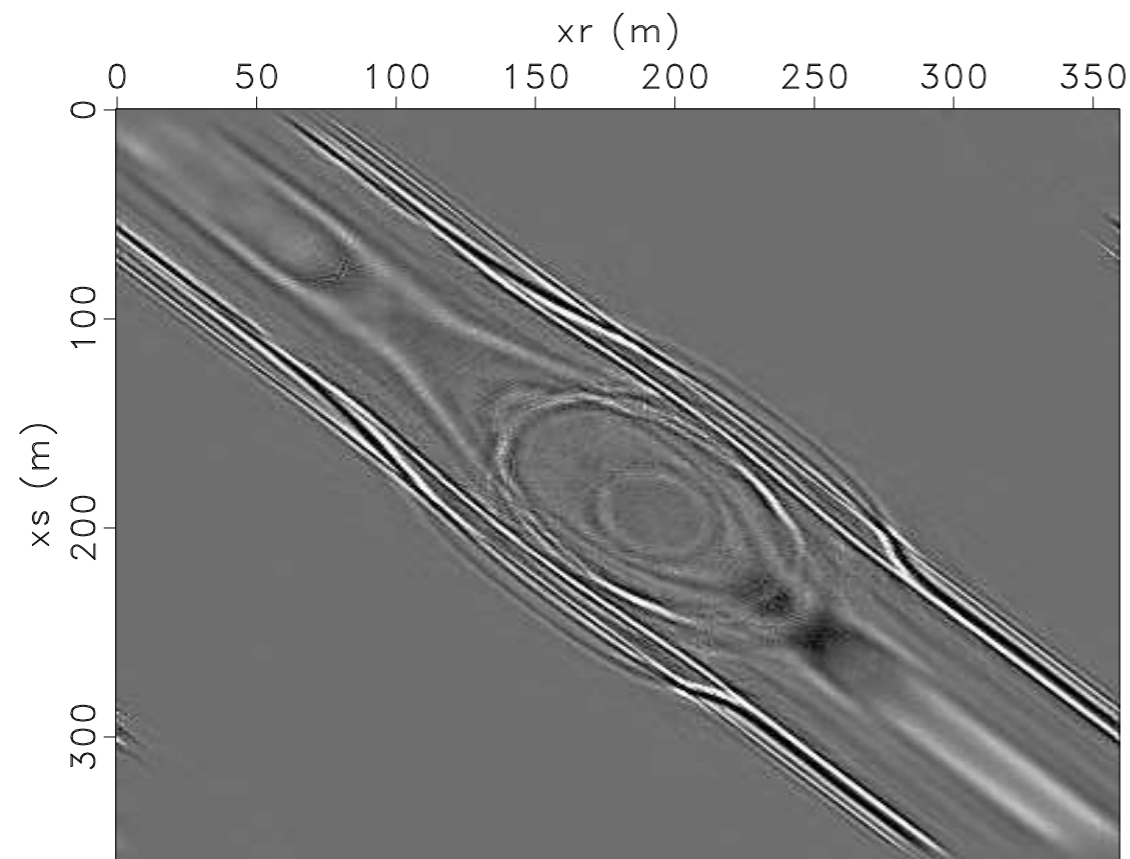


Hexagon

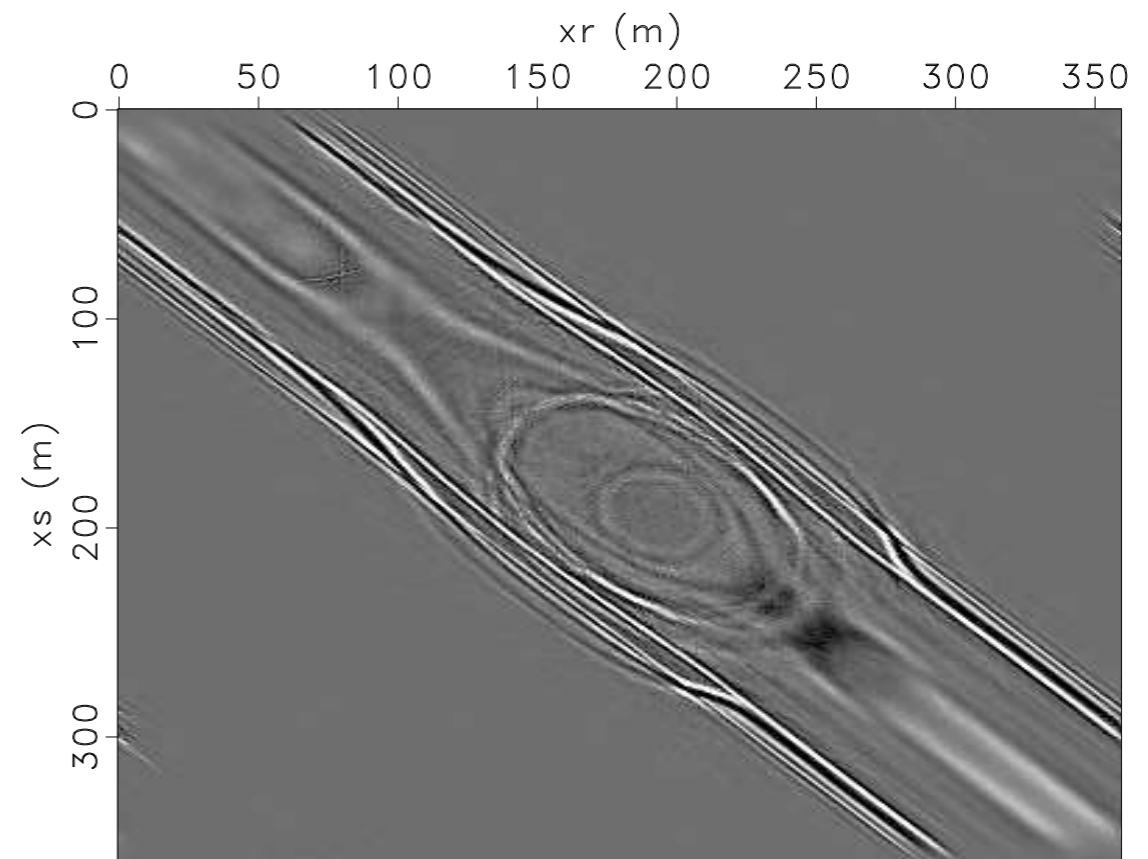


2-D discrete random jittered subsampling

- Cartesian & hexagonal jittered reconstructions almost the same.

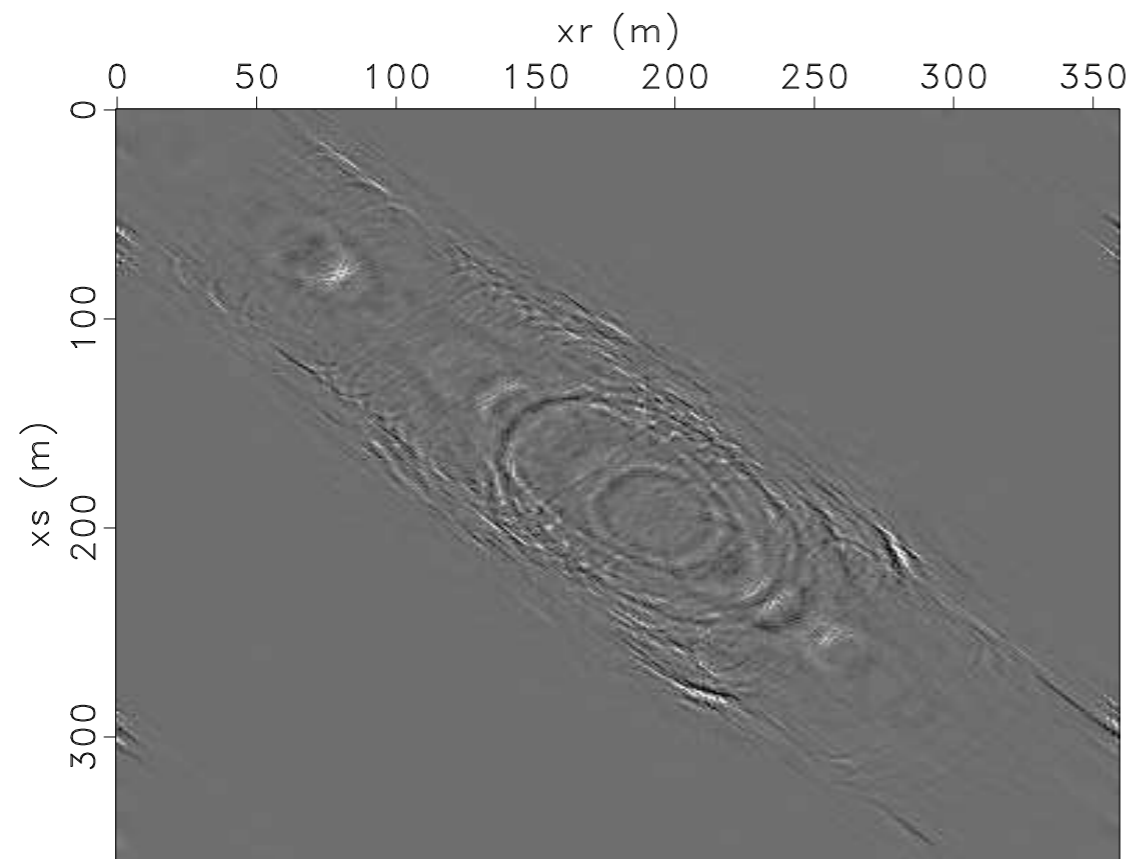


CRSI Recovery (Cartesian)
SNR = 10.820

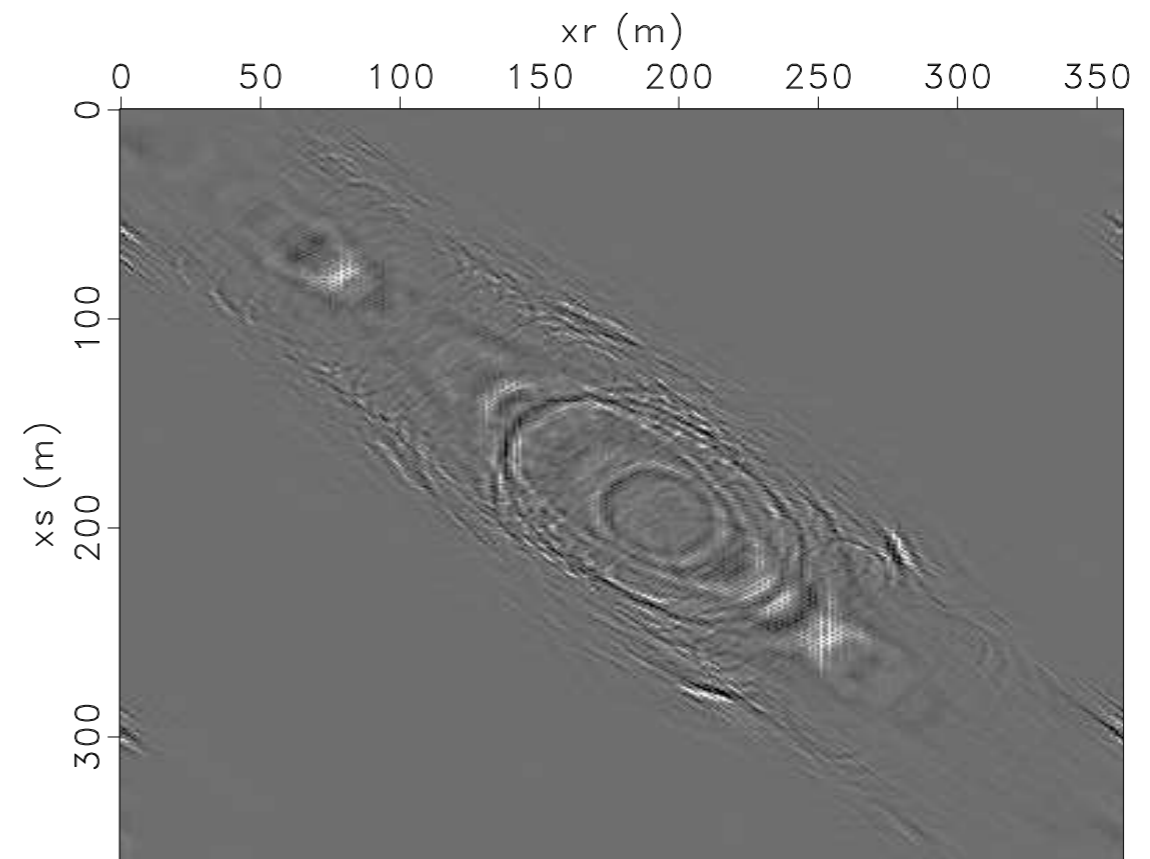


CRSI Recovery (Hexagonal)
SNR = 10.904

2-D discrete jittered subsampling



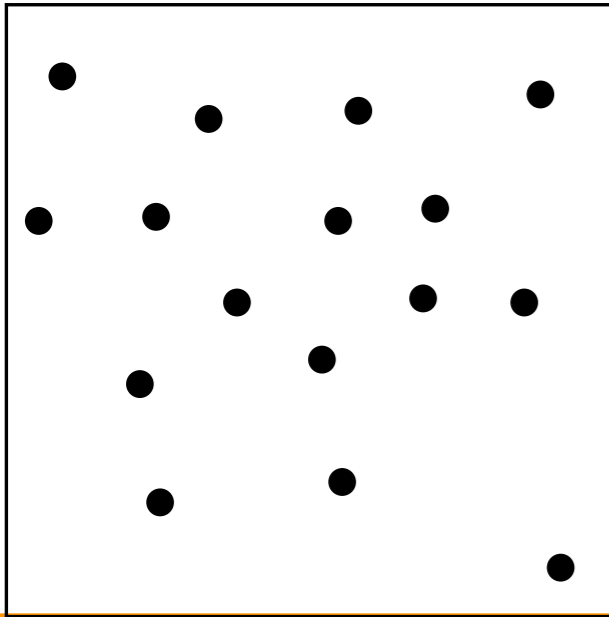
CRSI Residual (Cartesian)
SNR = 10.820



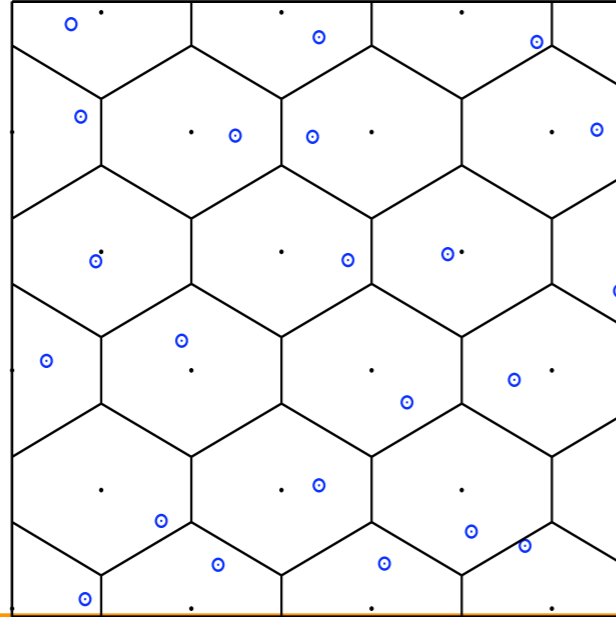
CRSI Residual (Hexagonal)
SNR = 10.904

Blue-noise spectra from 2D sampling methods

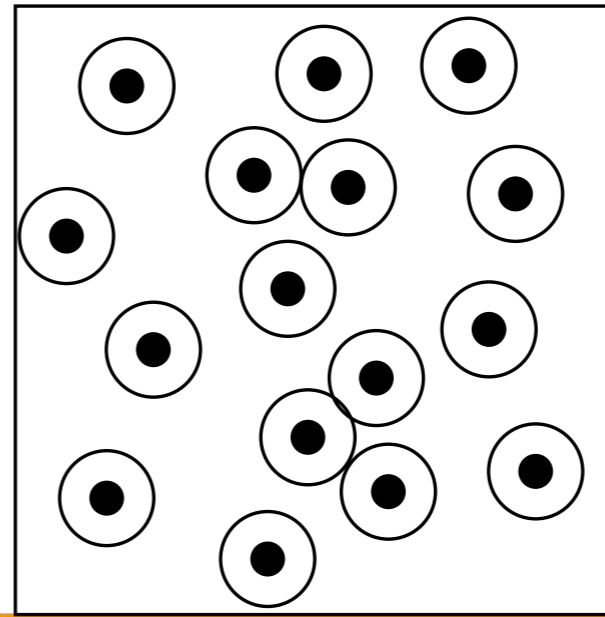
Uniform random



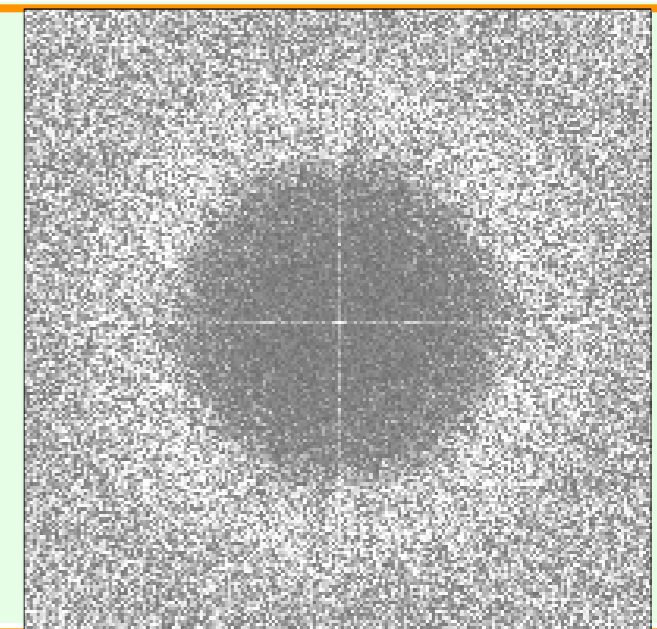
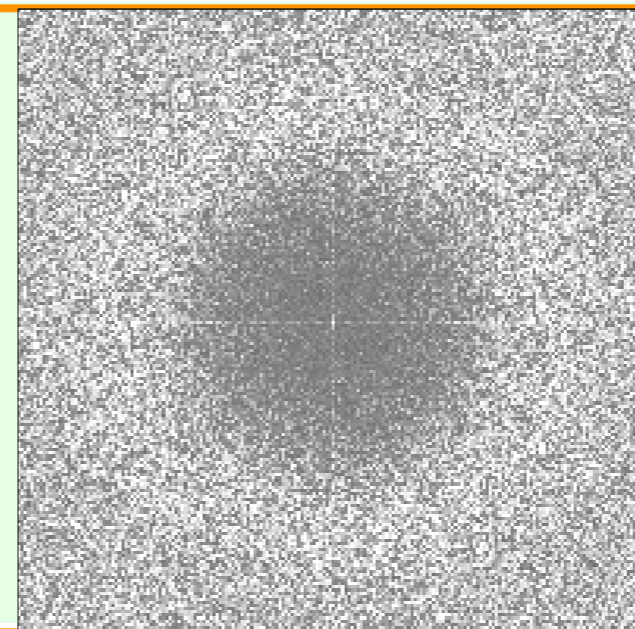
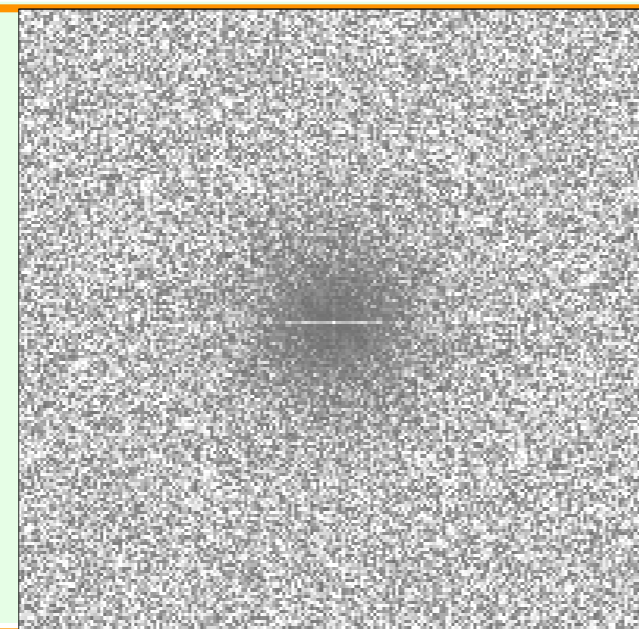
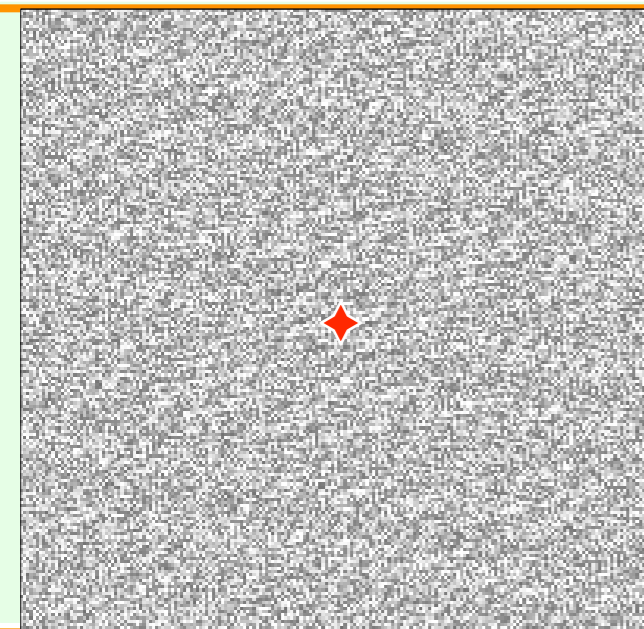
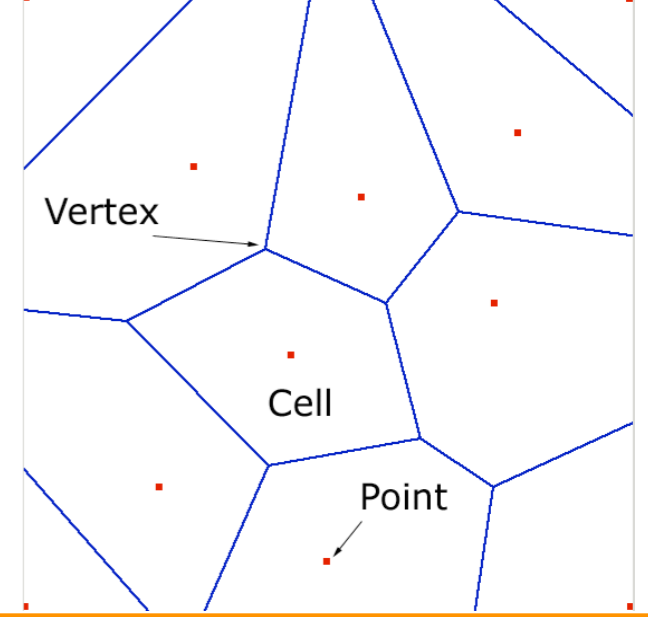
Jittered



Poisson Disk

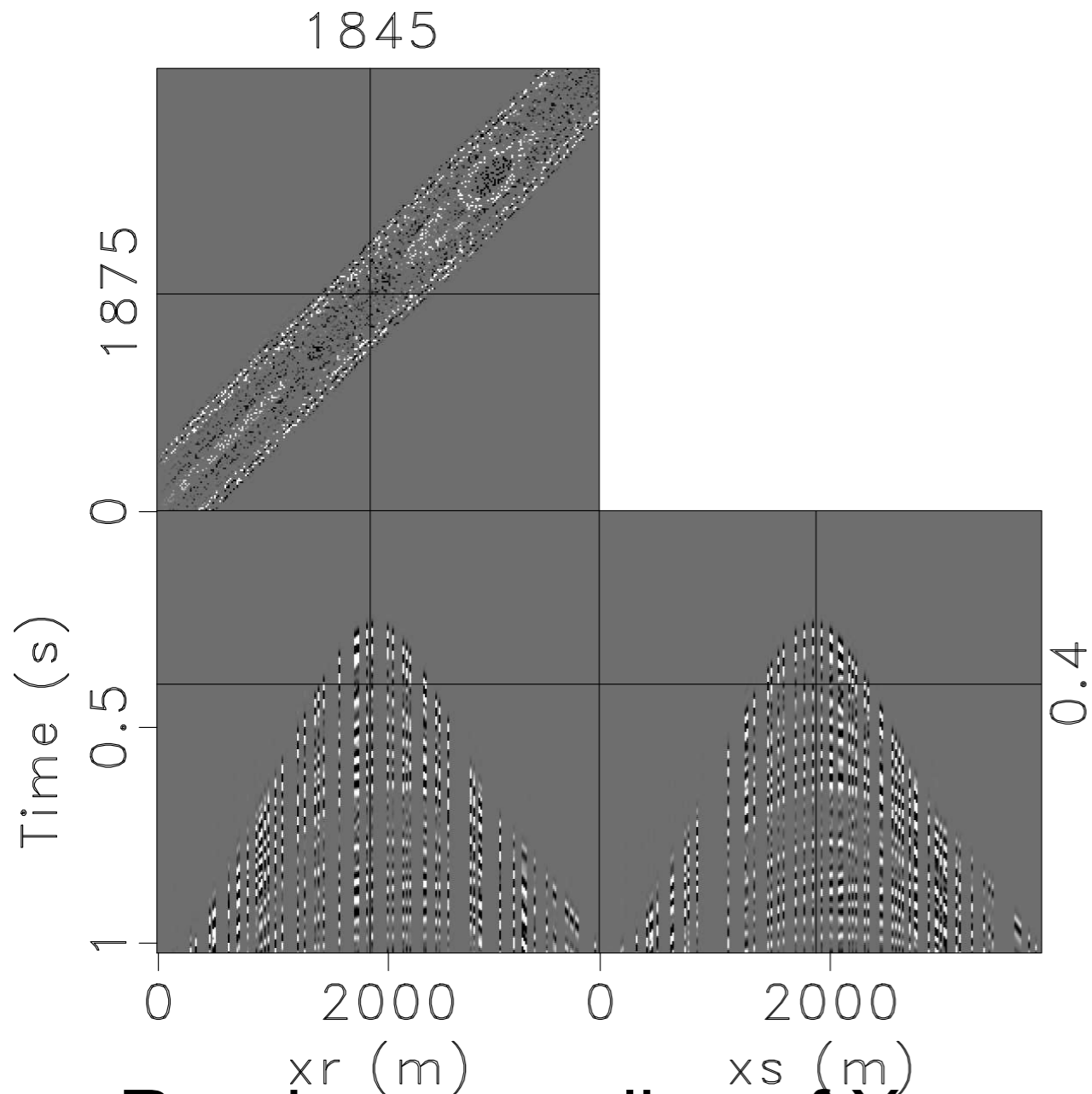


Farthest Point

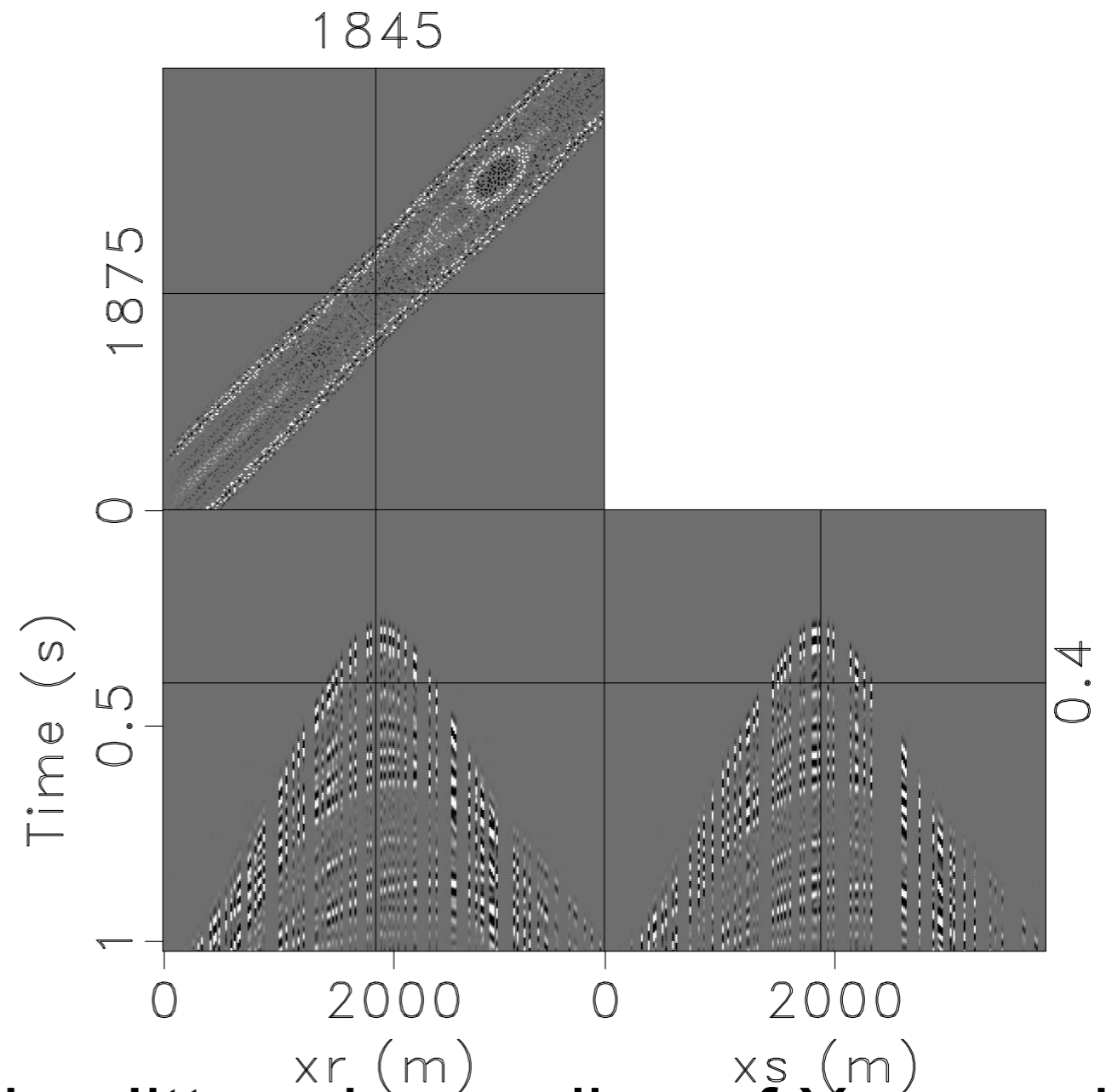


Spectra become increasingly *“blue”*

Randomized 2D uniform vs jittered

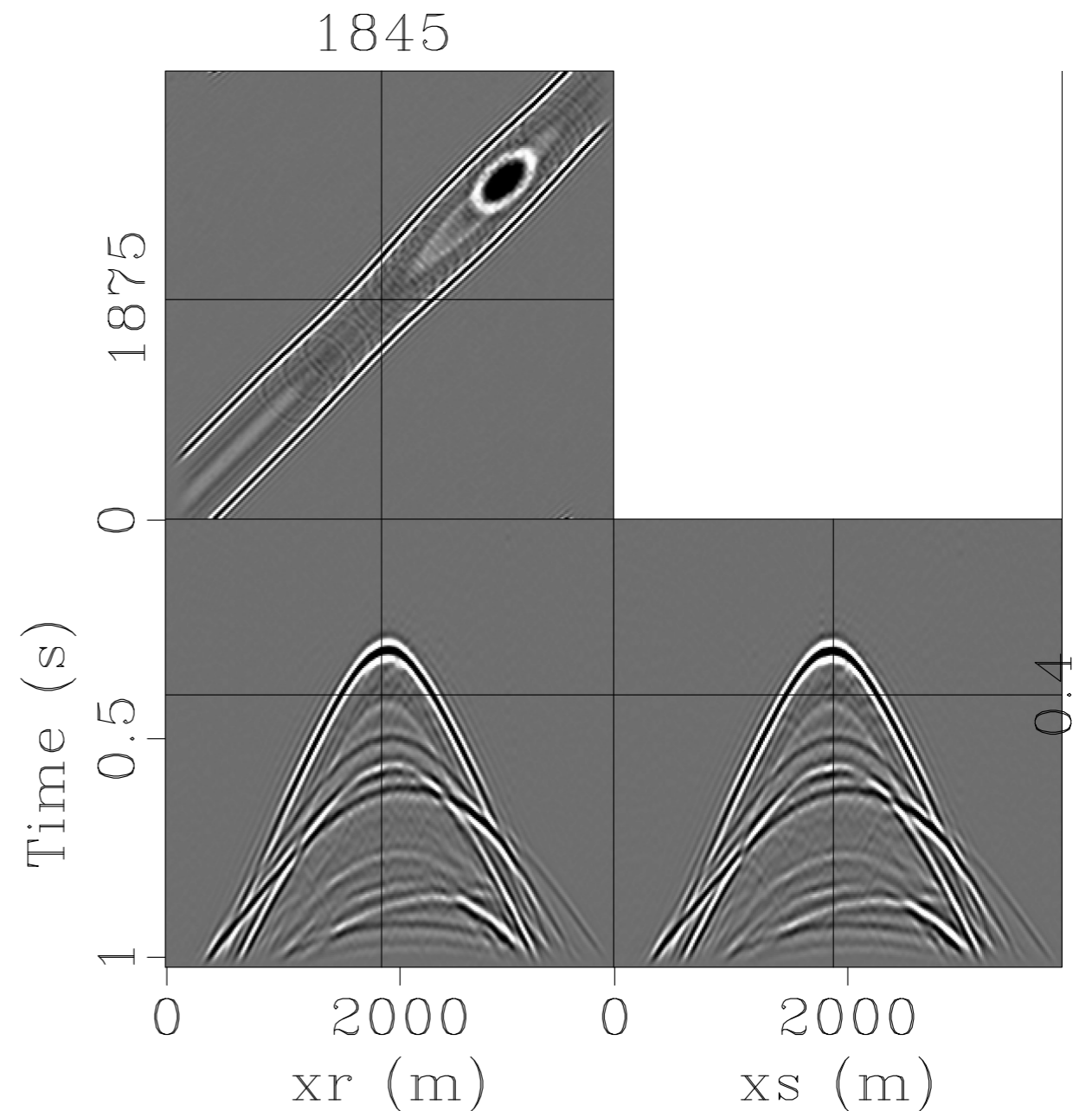
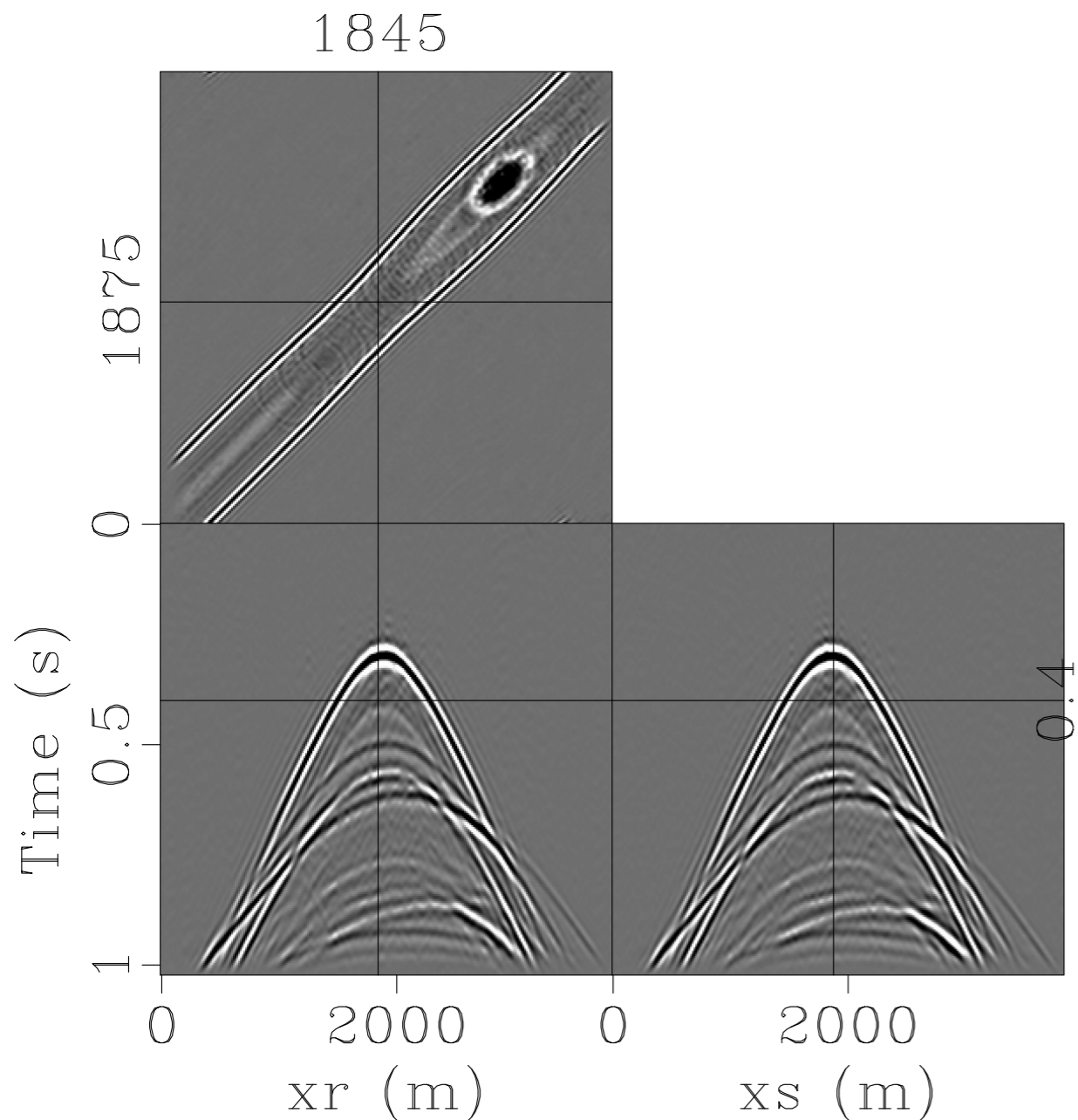


Random sampling of X-spread data (25% total data sampled)



Jittered sampling of X-spread data (25% sampled)

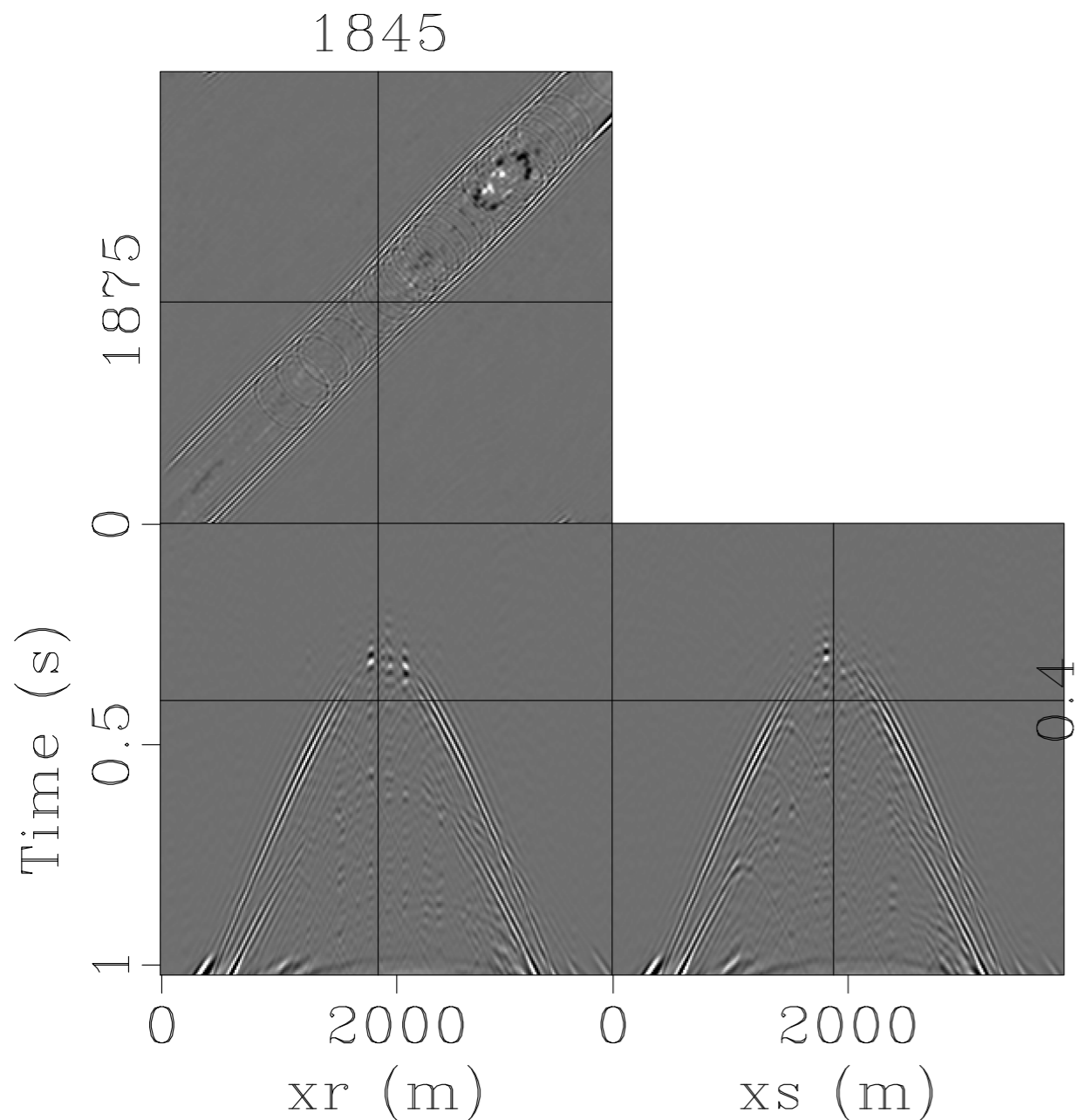
Randomized 2D uniform vs jittered - reconstruction



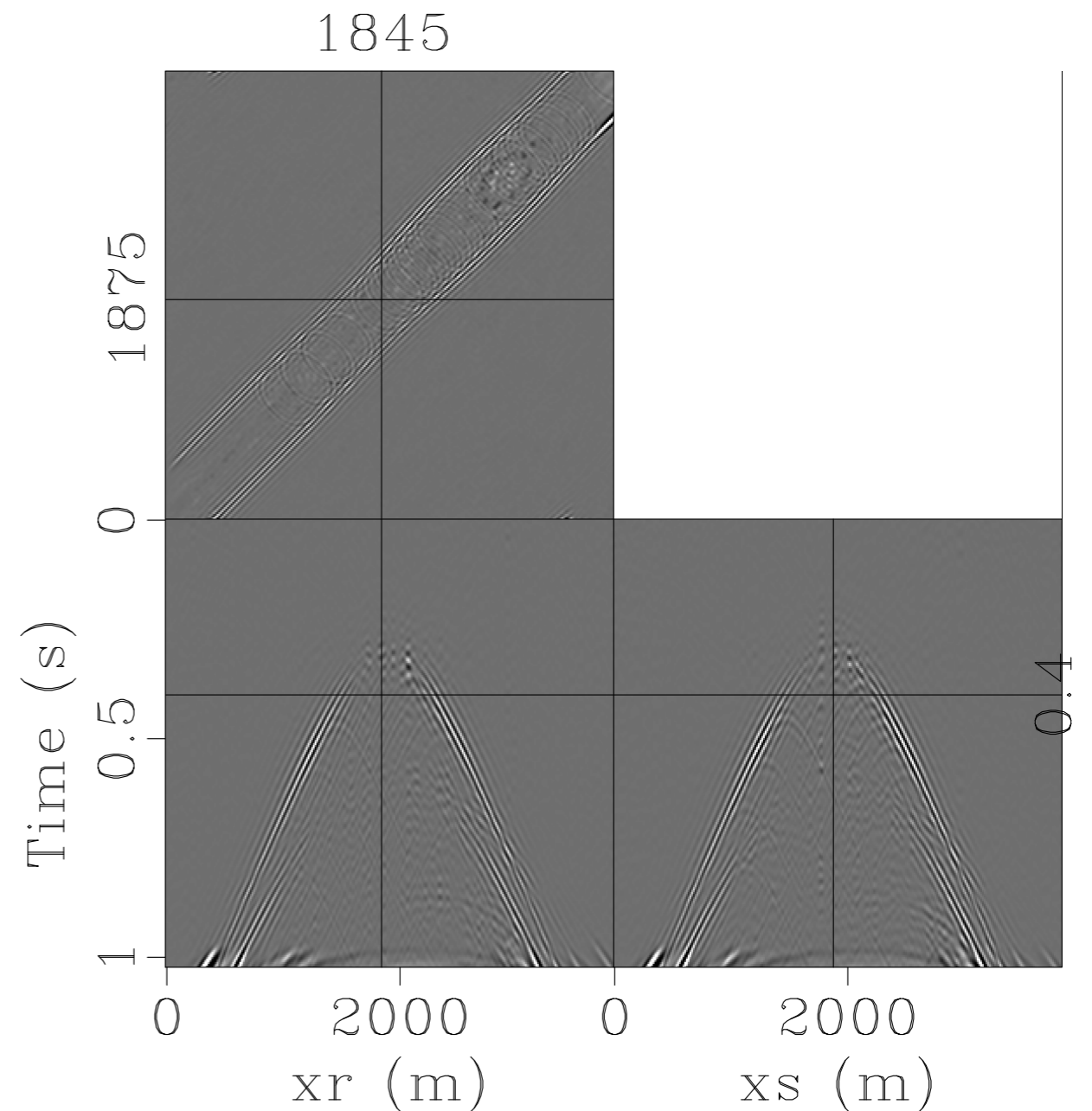
CRSI reconstruction from uniform samples
SNR=8.134

CRSI recon., 2D jittered (hexagonal) samples
SNR=8.434

Randomized 2D uniform vs jittered - residues

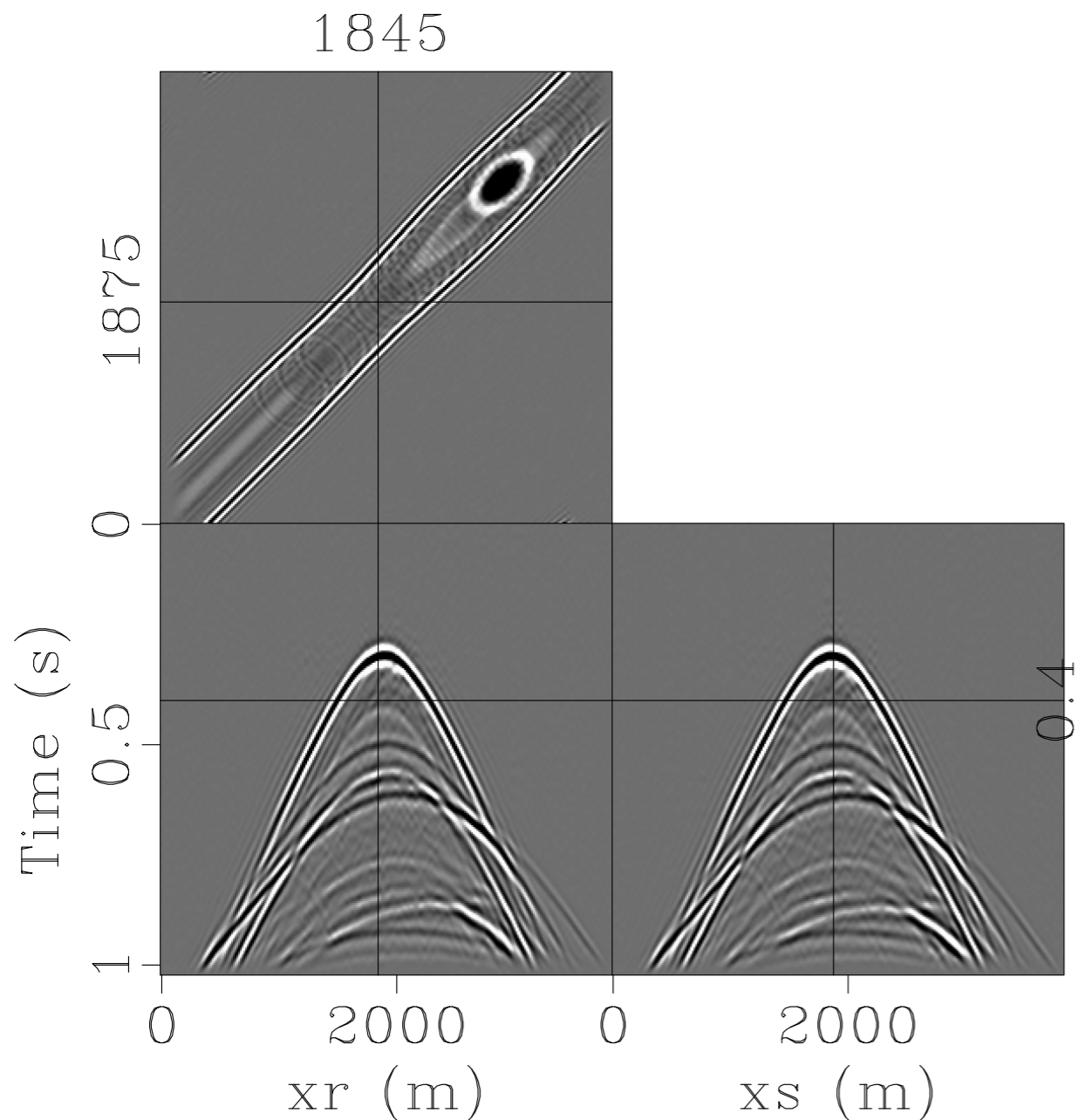


CRSI recon. residual from random samples

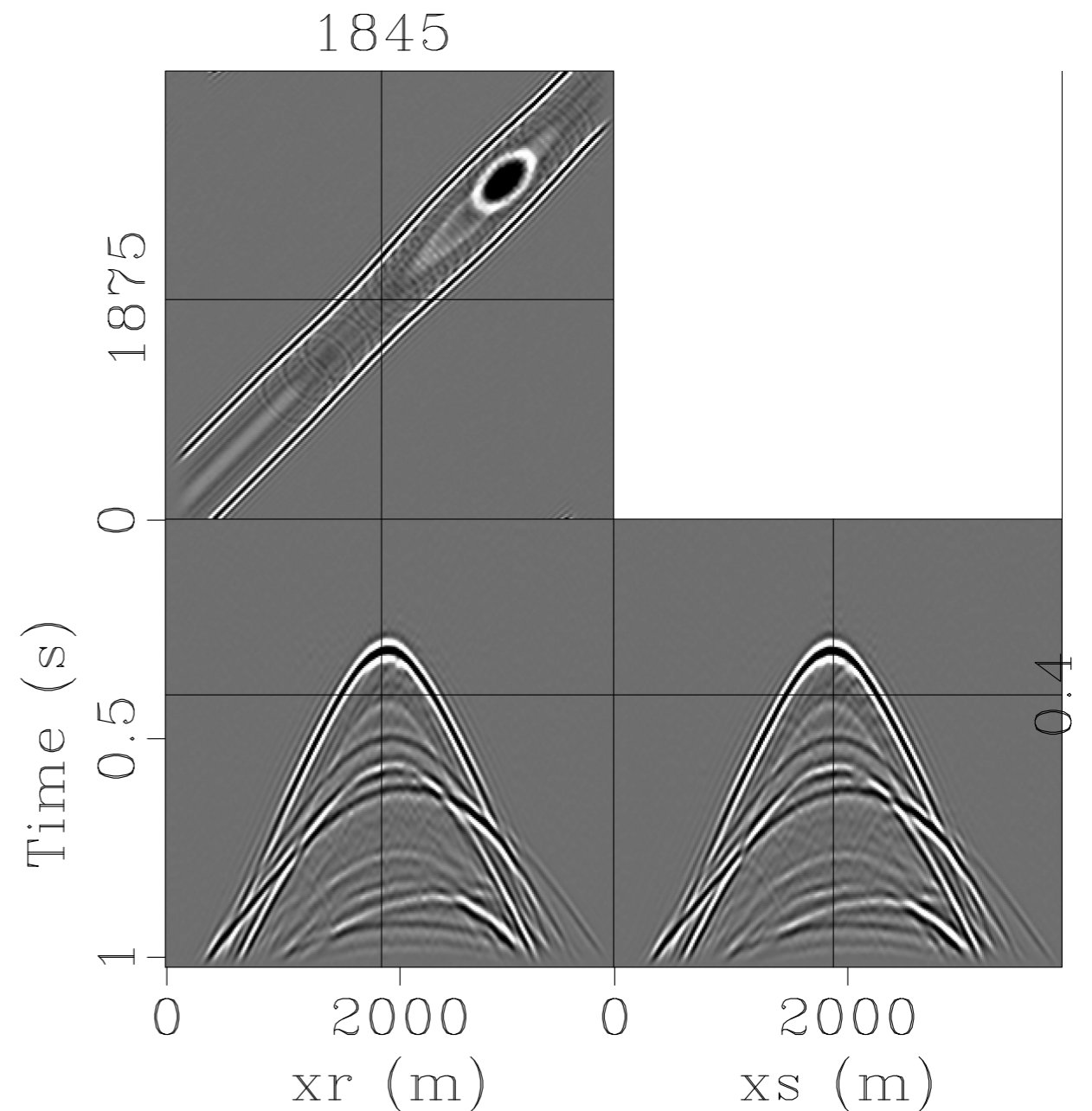


CRSI recon. residual from jittered
(hexagonal) samples

Farthest point vs Poisson disk - reconstruction

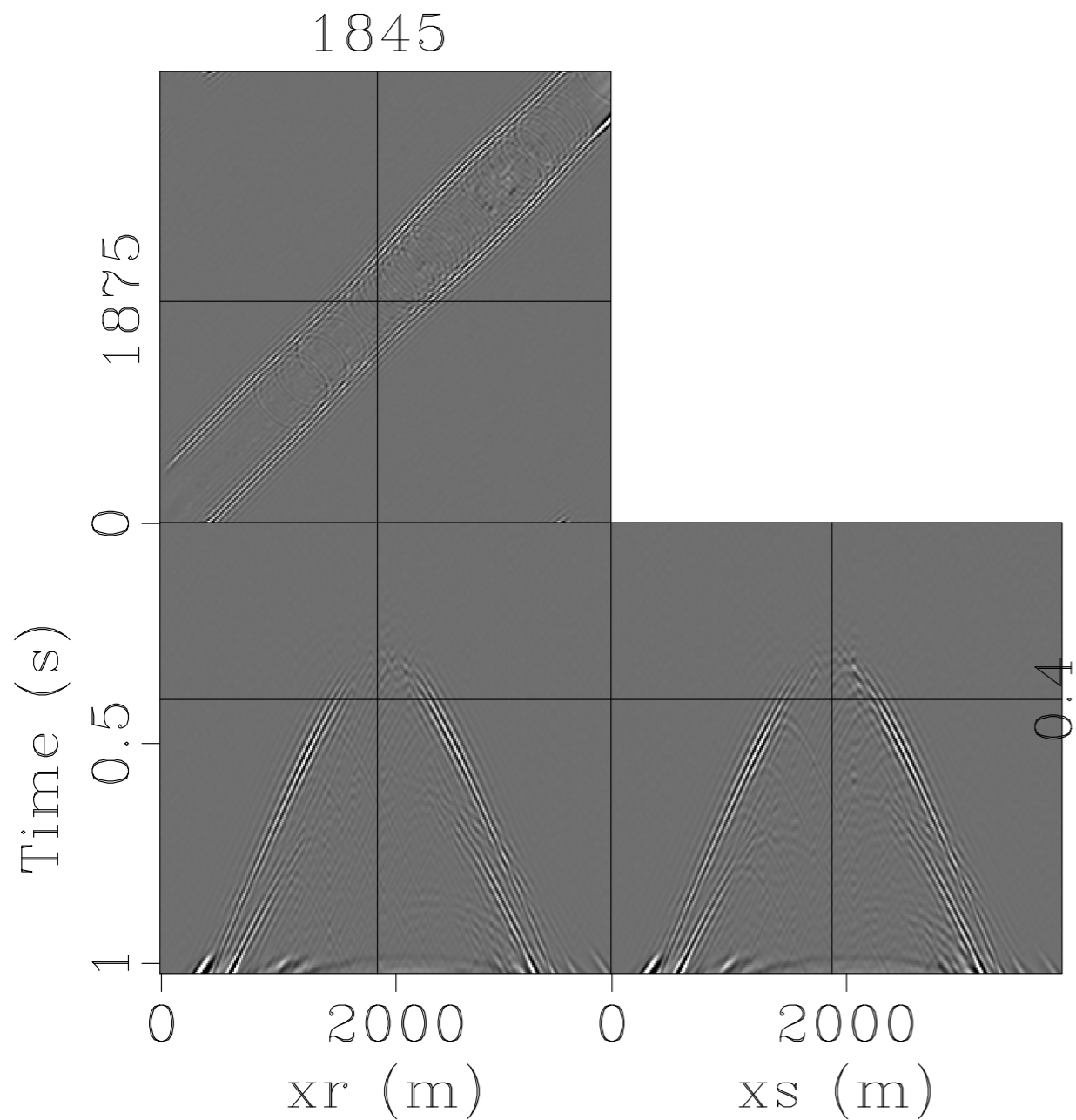


CRSI reconstruction from Farthest Point samples, SNR=8.496

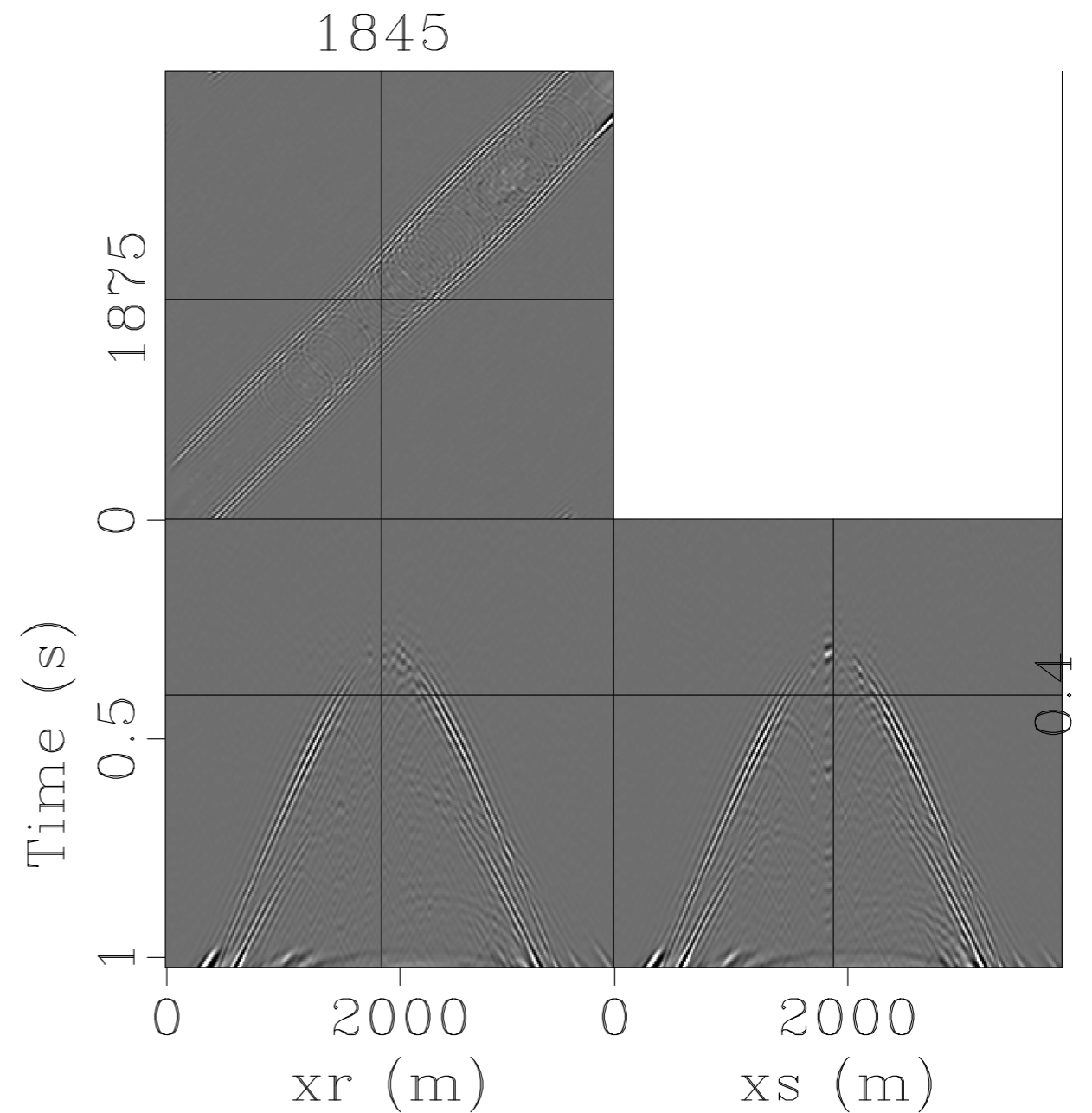


CRSI recon. from Poisson Disk samples SNR=8.483

Farthest point vs Poisson disk - residual



CRSI recon. residual from
Farthest Point samples



CRSI recon. residual from
Poisson Disk samples

Observation & extensions

- Findings from 1D jittered sampling extend to higher dimensions
 - randomized is better than regular subsampling
 - Cartesian versus hexagonal sampling are equivalent for optimal jittered sampling
 - Furthest point and Poisson sampling lead to similar results
- Gap-size control
 - jittered sampling gives explicit control max distance between adjacent samples
 - farthest point and Poisson disk also have bounds but not explicit
- Future extensions
 - variable density sampling
 - ungridded
 - exploring symmetry (e.g. reciprocity)

Conclusions

- **Randomization** is essential for recovery from incomplete data
- Good **randomized** sampling
 - with blue-noise characteristics give good curvelet recovery
 - with simultaneous sources gives excellent curvelet recovery
- **Randomization** leads to
 - “acquisition” of *smaller* data volumes that carry the **same information** or
 - to **improved inferences** from data using the *same* resources
- **Bottom line: acquisition costs** are no longer determined by the **size** of the **discretization** but by **transform-domain sparsity** of the sampled wavefield ...

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and... Thank you!