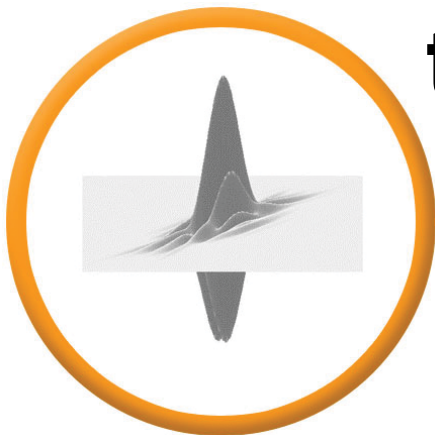


# Compressive sensing: a paradigm shift for the imaging sciences?

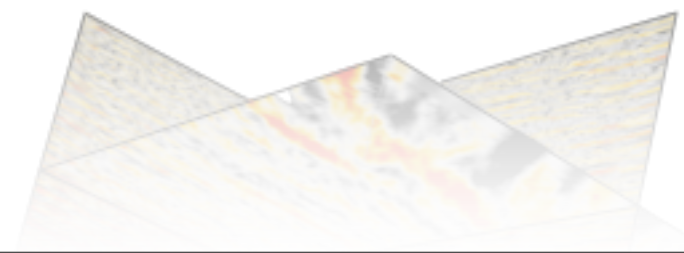
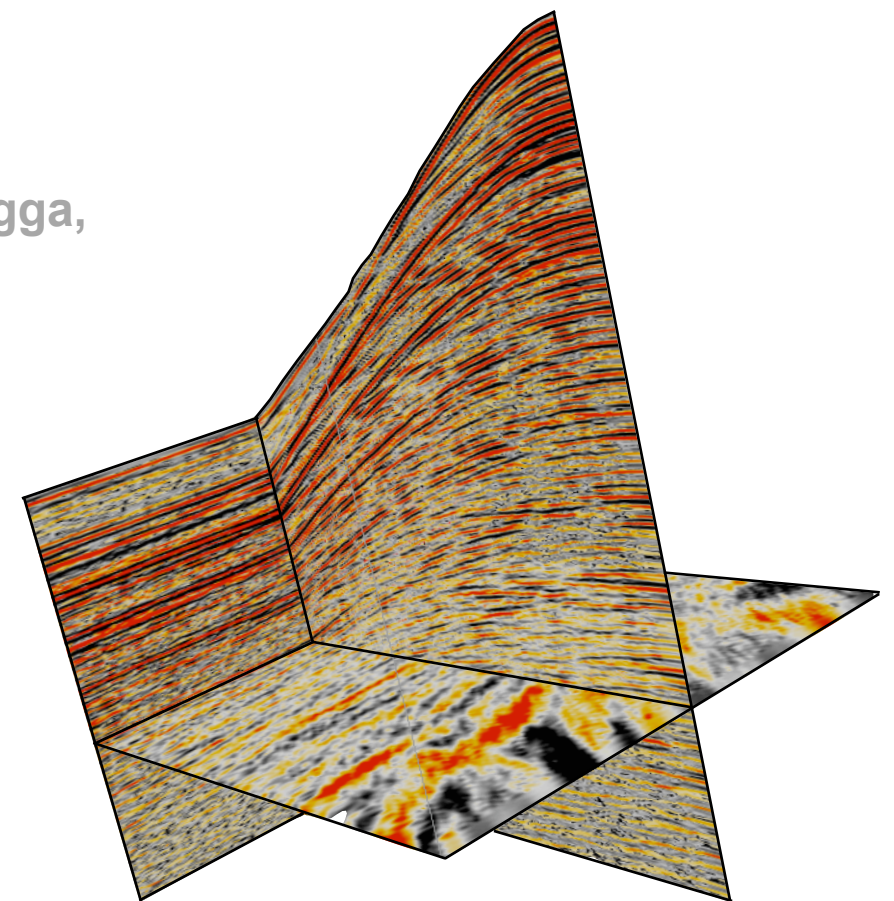


**Felix J. Herrmann\***

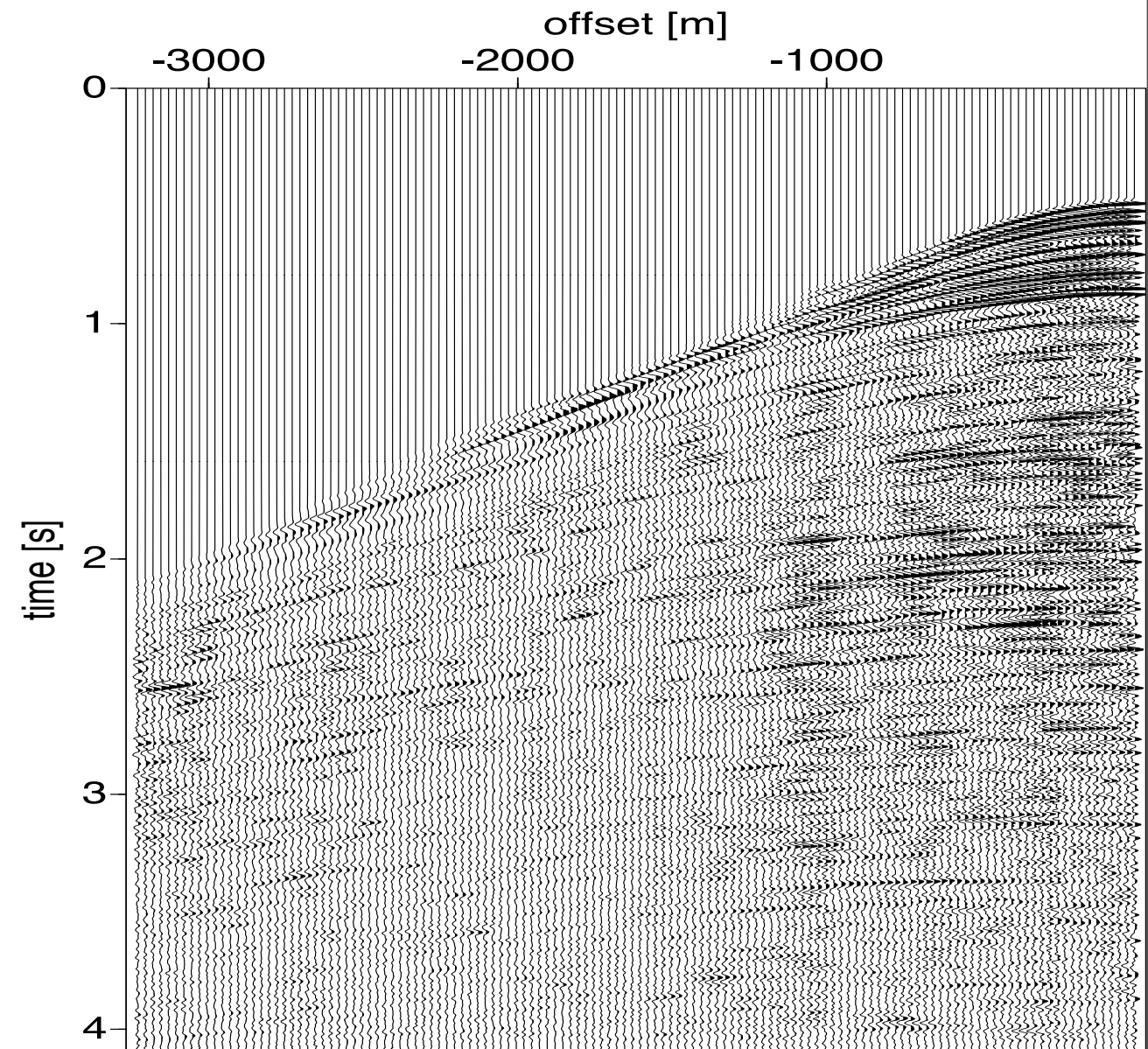
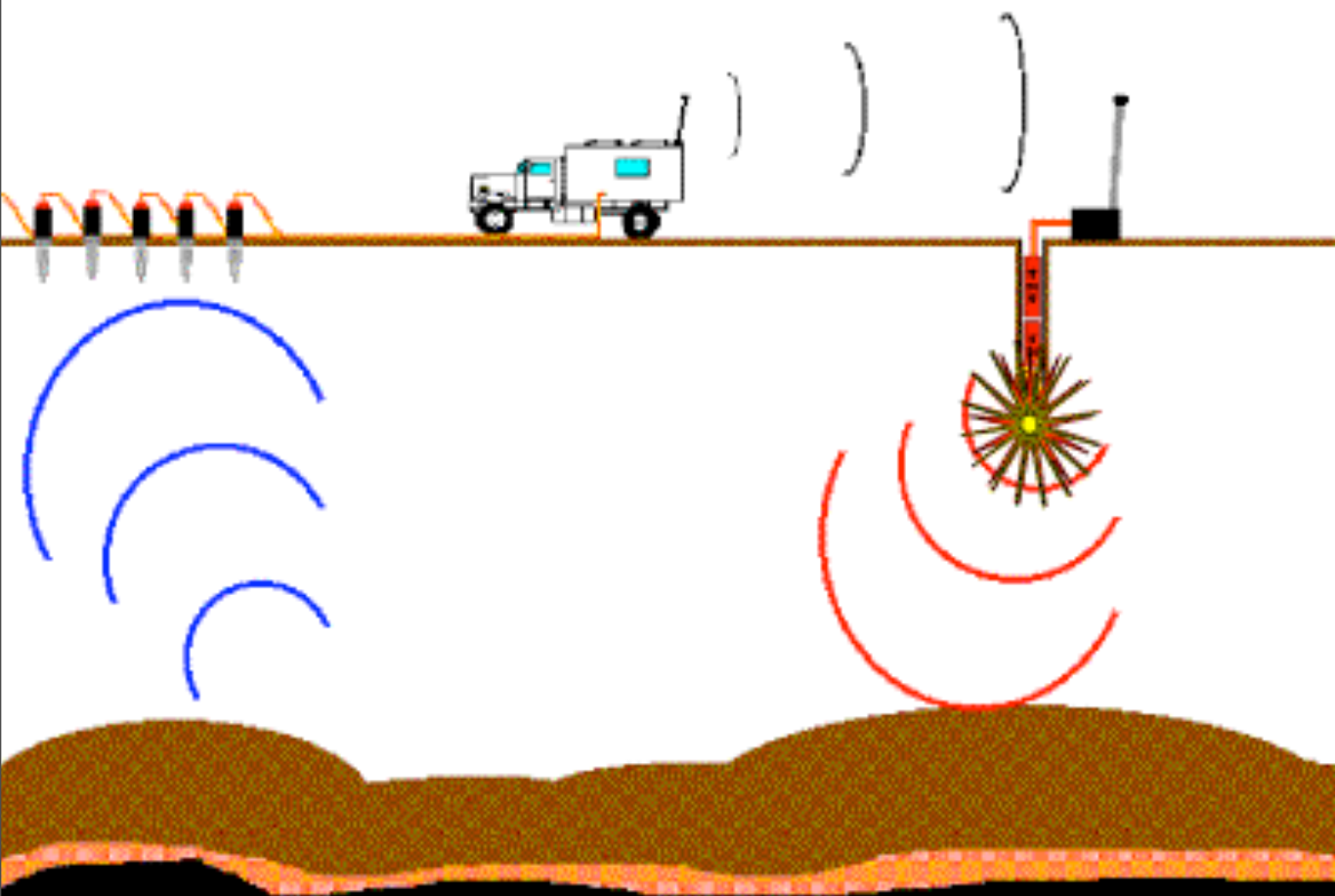
[fherrmann@eos.ubc.ca](mailto:fherrmann@eos.ubc.ca)

Joint work with Gilles Hennenfent, Yogi Erlangga,  
and Tim Lin

**\*Seismic Laboratory for Imaging & Modeling**  
Department of Earth & Ocean Sciences  
The University of British Columbia

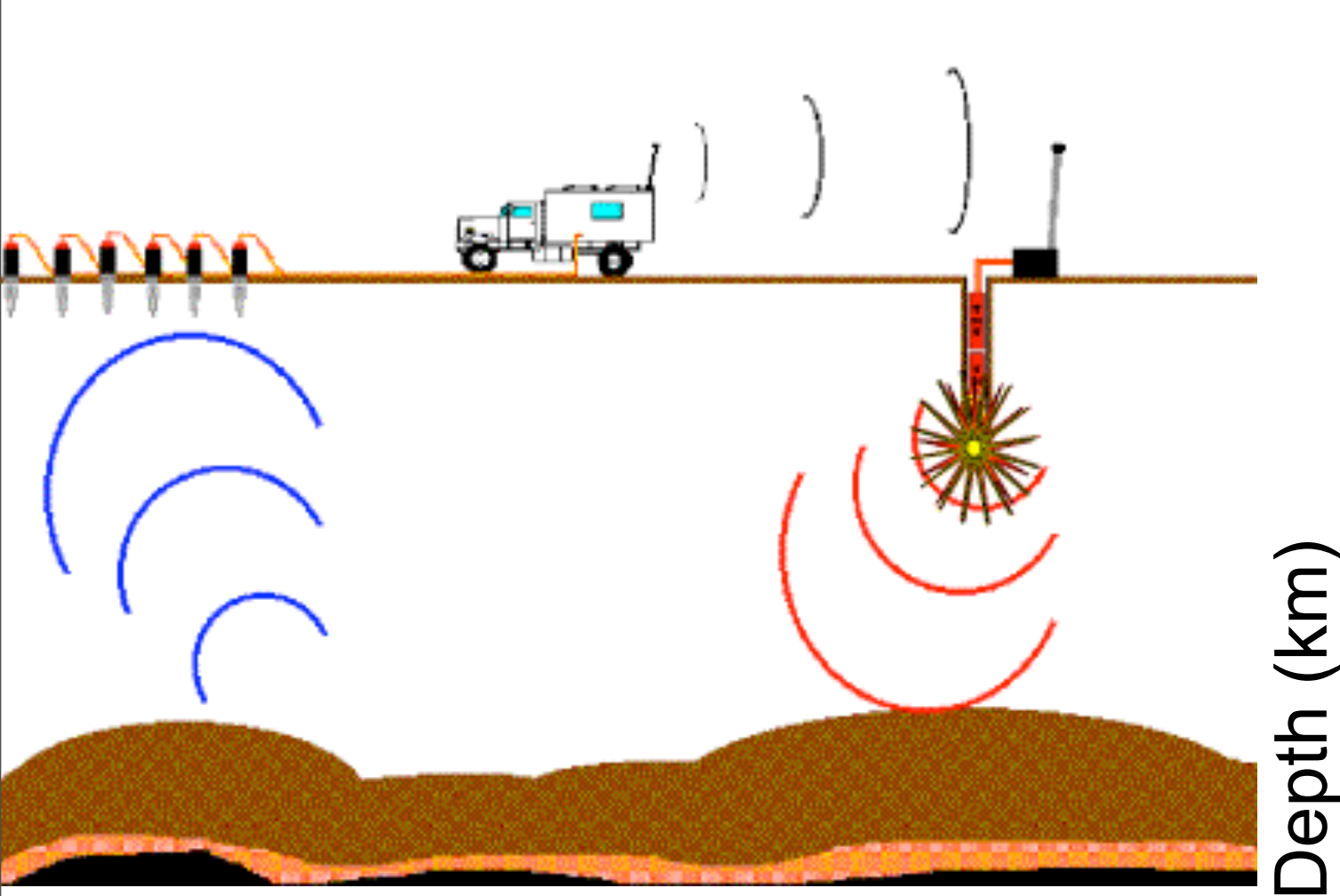


# Seismic data acquisition

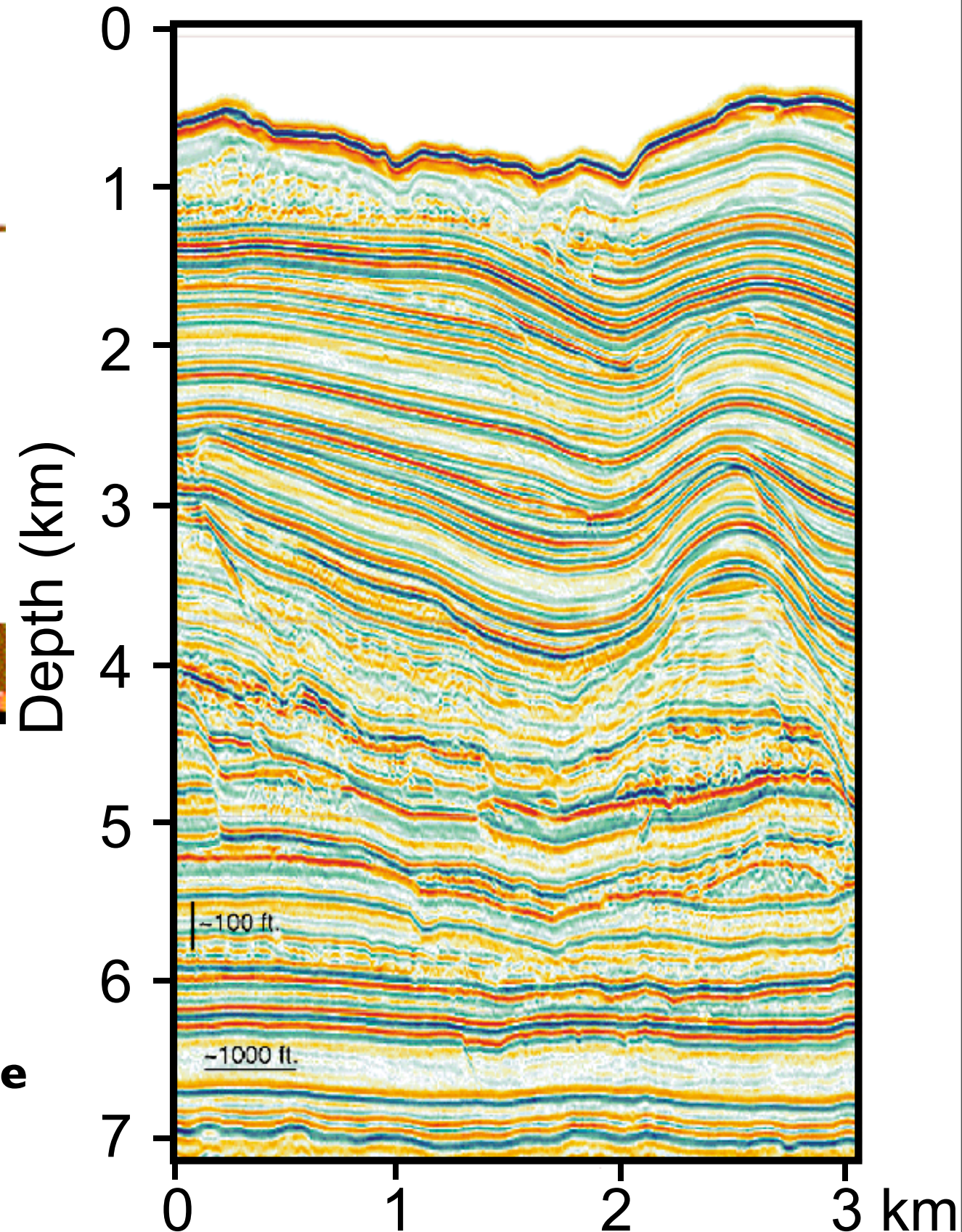




# Exploration seismology



- **create images of the subsurface**
- **need for higher resolution/deeper**
- **clutter, data incompleteness, and large data size are problems**



# Motivation

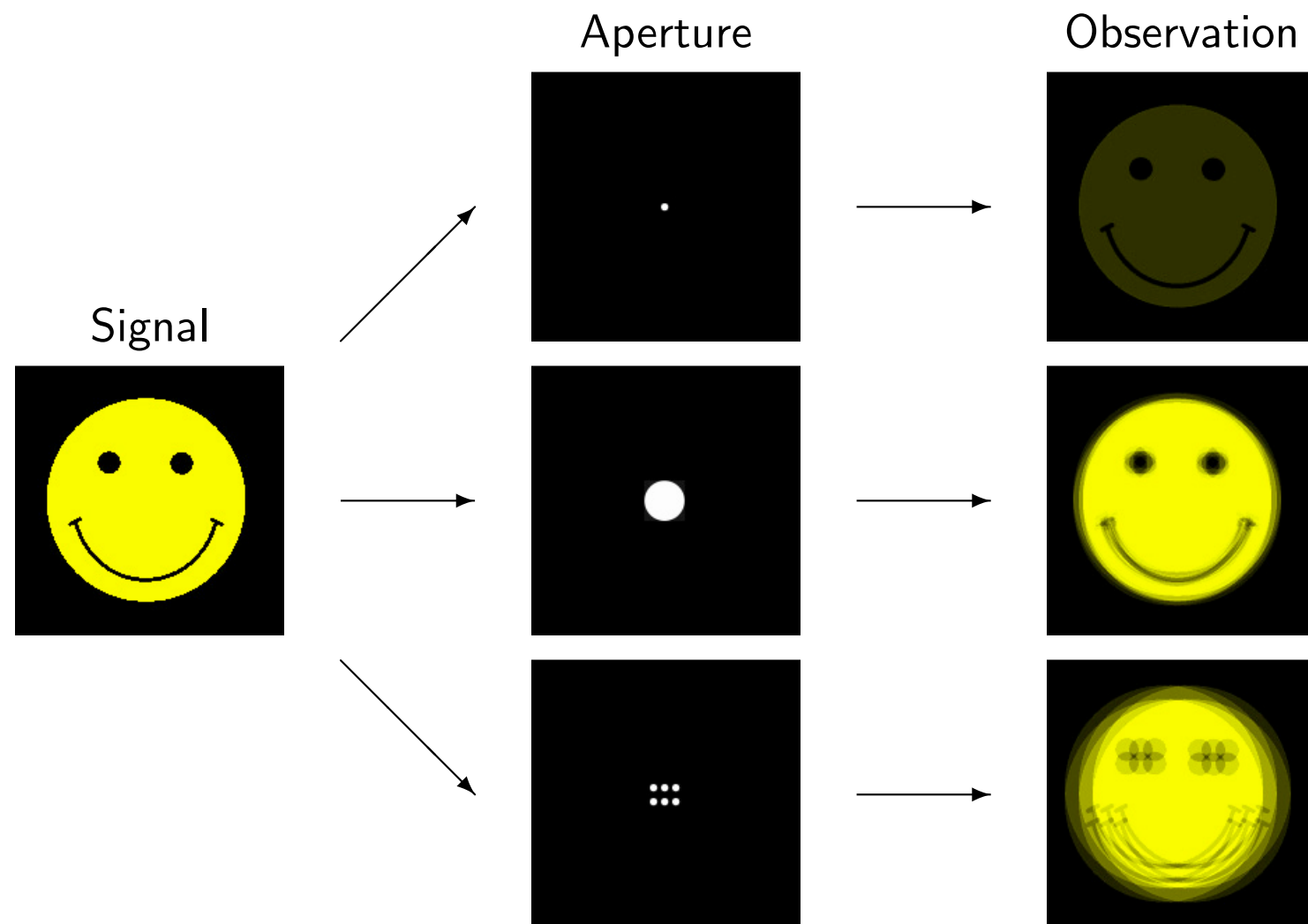
---

- Current state of affairs:
  - (Seismic) data *acquisition, processing, modeling, and imaging* are firmly rooted in the *paradigm* of regular **Nyquist** sampling
  - Acquisition is based on *regularly*-sampled & *source*-separated data volumes
- Major *impediment* related to the *size* of seismic data volumes
  - costs of acquisition & modeling dependent on size of the discretization
  - difficult to form *explicit* (imaging) operators
  - difficult to solve *implicit* (imaging) operators
- Recent theoretical developments
  - New *nonlinear* sampling theory--known as **Compressive Sensing** (CS)--that supersedes the overly *pessimistic Nyquist sampling criterion*
  - New CS-based acquisition techniques are being developed (MRI, AD, Radar, etc)
  - New *continuous* and *simultaneous* acquisition strategies  $\Leftrightarrow$  instances of CS
- Success of compressive sensing hinges on
  - transform-domain sparsity (e.g. sparsity attained by multiscale/directional curvelets)
  - linear subsampling schemes that reduce interferences
  - nonlinear recovery by sparsity promotion



# An example [adapted from Roummel F. Marcia and Rebecca M. Willett, 2008]

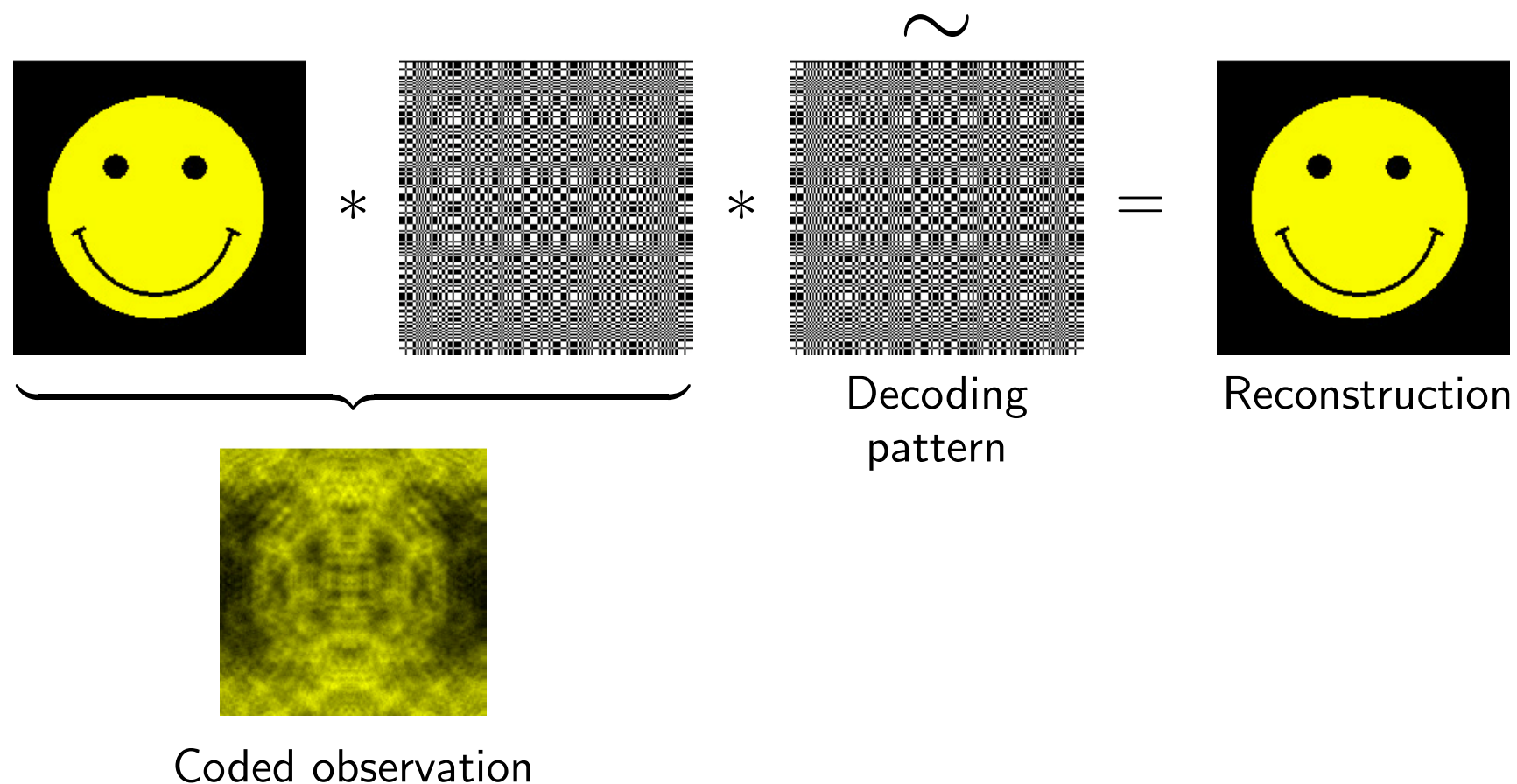
---



- Large pin holes (samples) blur
- Regularly-sampled multiple pinholes lead to coherent interferences

# An example [adapted from Roummel F. Marcia and Rebecca M. Willett, 2008]

---

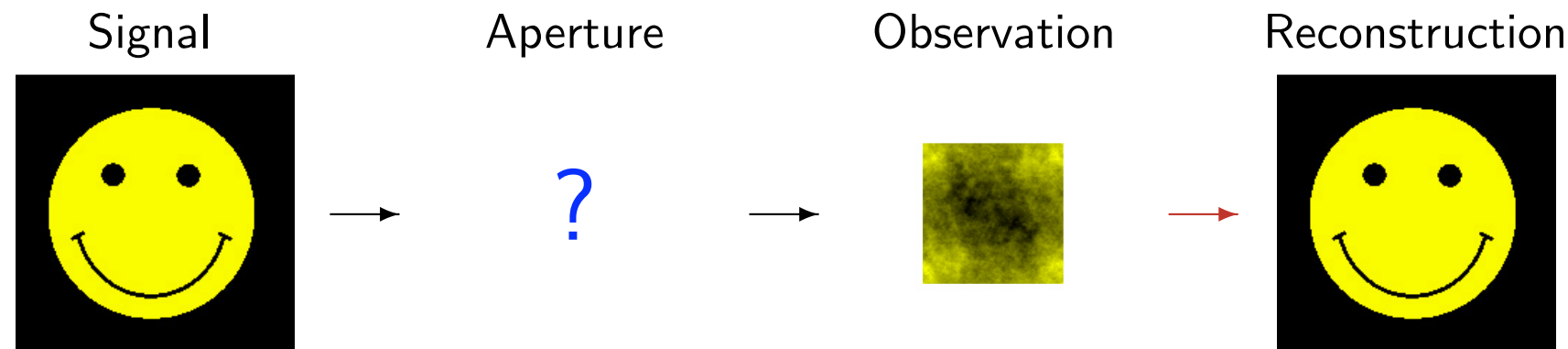


- Coded aperture gives brighter image
- Requires linear decoding
- ***No reduction*** in acquired data volumes



# An example [adapted from Roummel F. Marcia and Rebecca M. Willett, 2008]

---



- Reduce the dimensionality by subsampling
  - create observations that contain the same information (encoded)
  - facilitate recovery by nonlinear transform-domain sparsity promotion
- Design physically realizable encoding schemes that break interferences
- Design nonlinear recovery techniques that exploit transform-domain sparsity/compressibility of certain structured signals
  - multiscale & directional wavelets
  - multiscale, multidirectional, and anisotropic curvelets

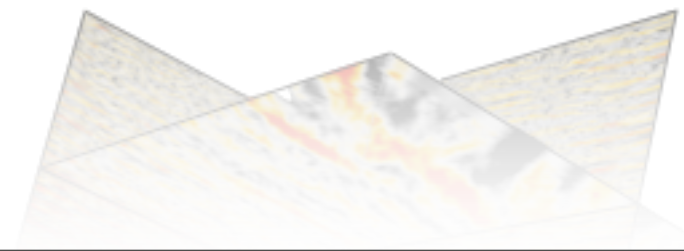
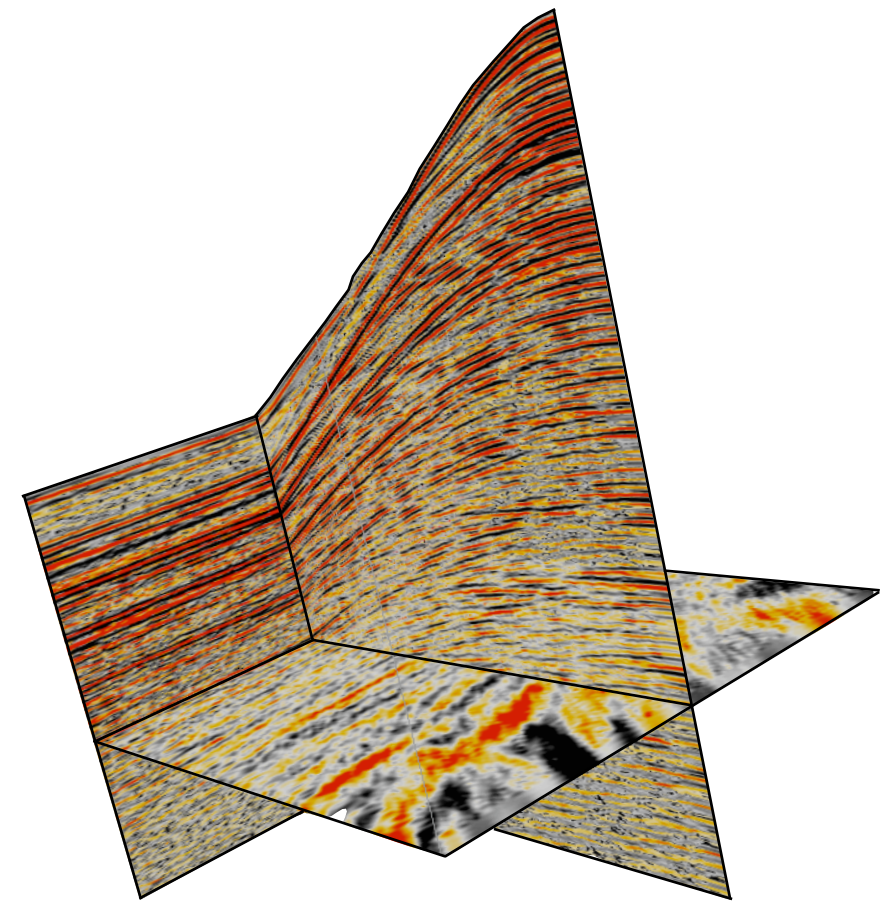
# Today's agenda

---

- Brief introduction to *compressive sensing*
  - sparsifying transform
  - favorable (random) acquisition (acquisition-grid and source-function design)
  - nonlinear recovery by sparsity promotion
- CS applied to wavefield reconstruction from incomplete acquisitions
  - use the “***Dirac***” ***basis*** as the ***sampling*** domain
  - reduction of the number of sources & receivers
- CS applied to ***explicit*** one-way wavefield computations
  - use of the ***modal*** domain as the ***sampling*** domain
  - reduction of the number of eigenvectors & frequencies
- CS applied to ***implicit*** simultaneous full-waveform simulation
  - use ***simultaneous sources*** as the ***sampling*** domain
  - reduction of the number of right-hand sides & frequencies



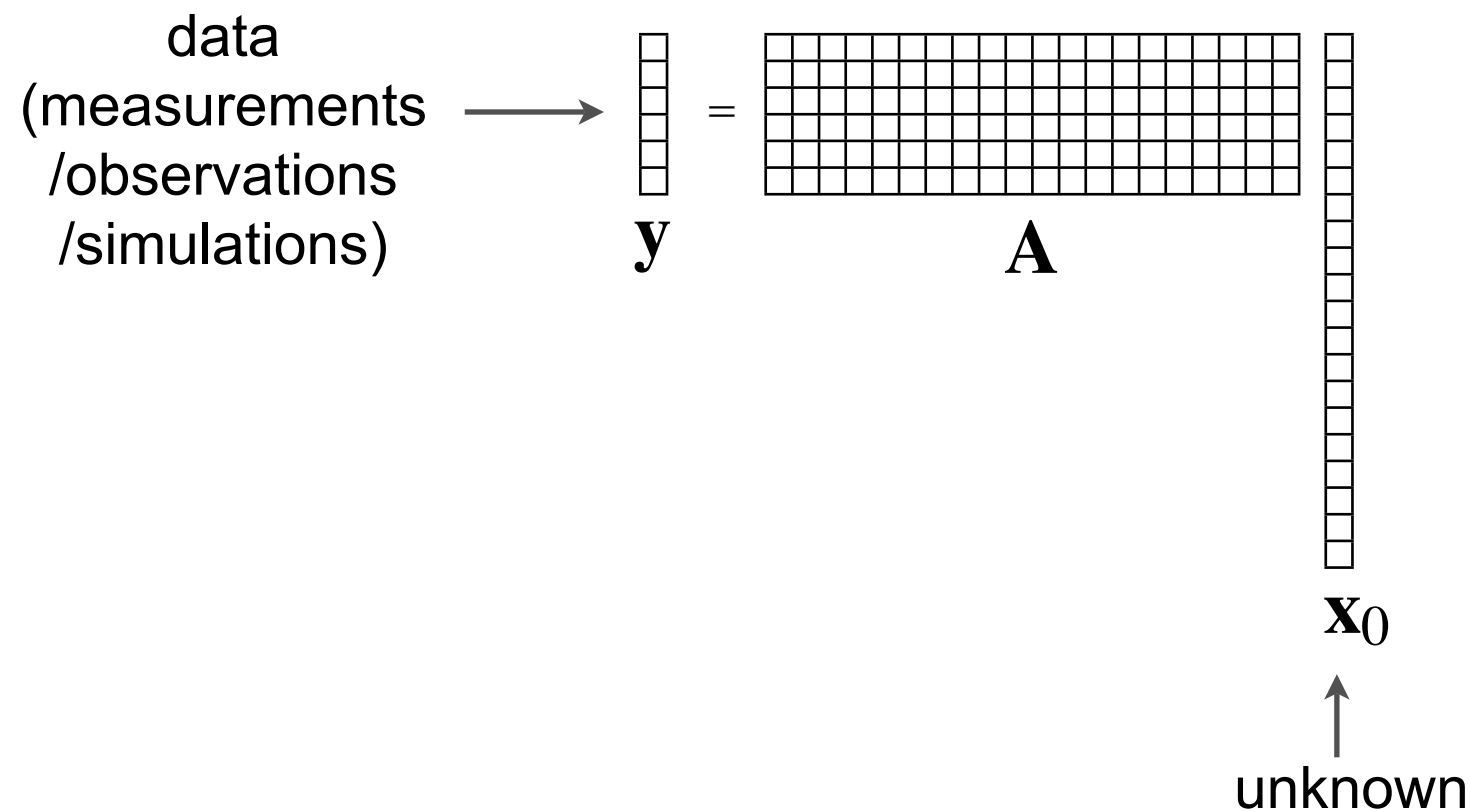
# Compressive sensing



# Problem statement

---

Consider the following (severely) underdetermined system of linear equations



Is it possible to recover  $\mathbf{x}_0$  accurately from  $\mathbf{y}$ ?



# Perfect recovery

---

$$\mathbf{y} = \mathbf{A} \mathbf{x}_0$$

- conditions

- $\mathbf{A}$  obeys the **uniform uncertainty principle**
- $\mathbf{x}_0$  is **sufficiently sparse**

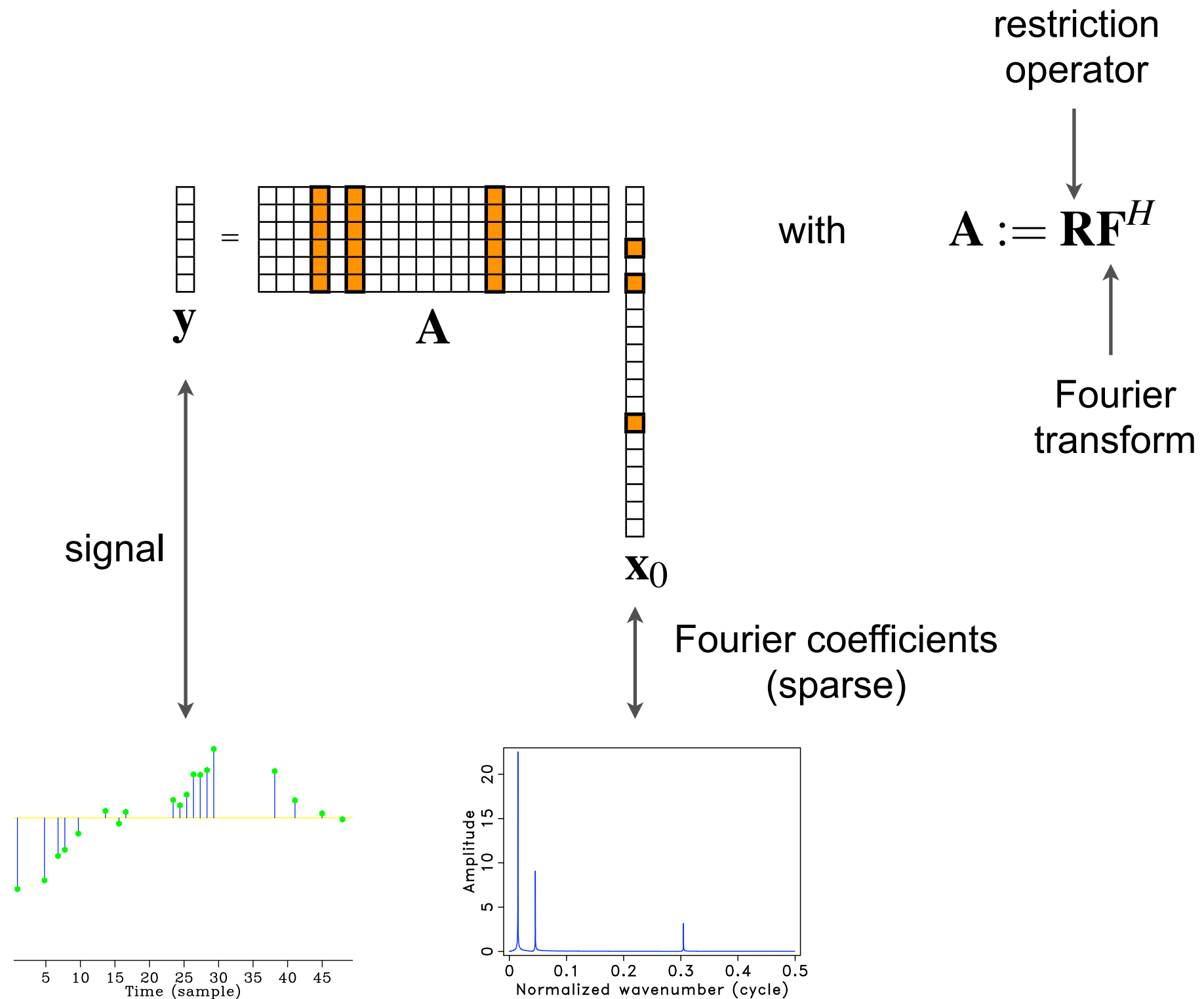
- procedure

$$\underbrace{\min_{\mathbf{x}} \|\mathbf{x}\|_1}_{\text{sparsity}} \quad \text{s.t.} \quad \underbrace{\mathbf{A}\mathbf{x} = \mathbf{y}}_{\text{perfect reconstruction}}$$

- performance

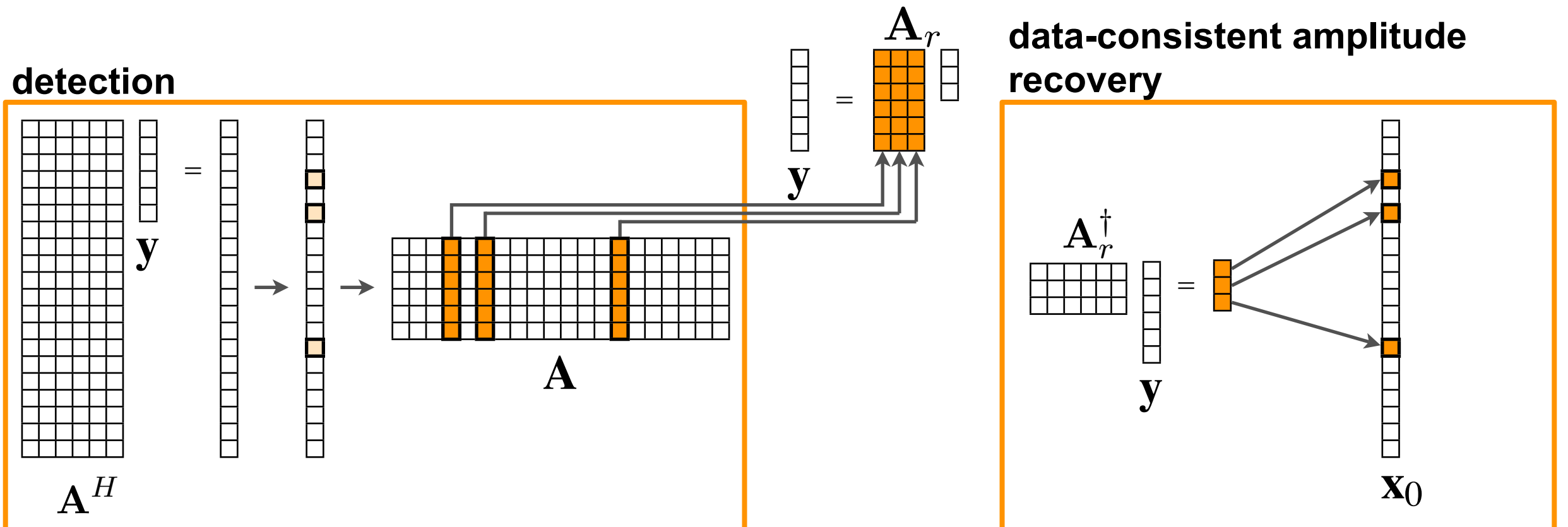
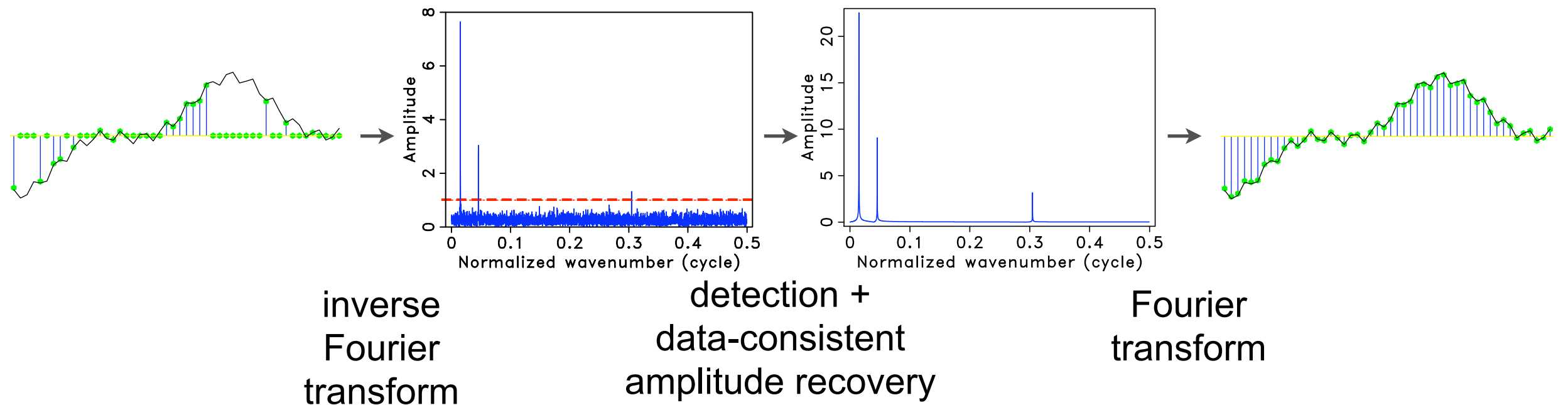
- **$S$ -sparse vectors recovered from roughly on the order of  $S$  measurements** (to within constant and  $\log$  factors)

# Simple example

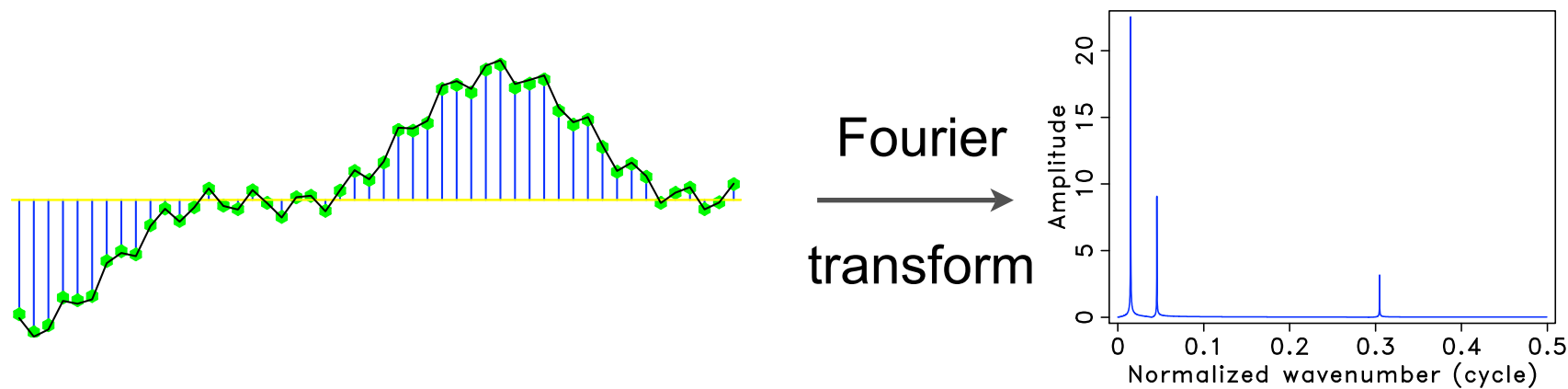




# NAIVE sparsity-promoting recovery

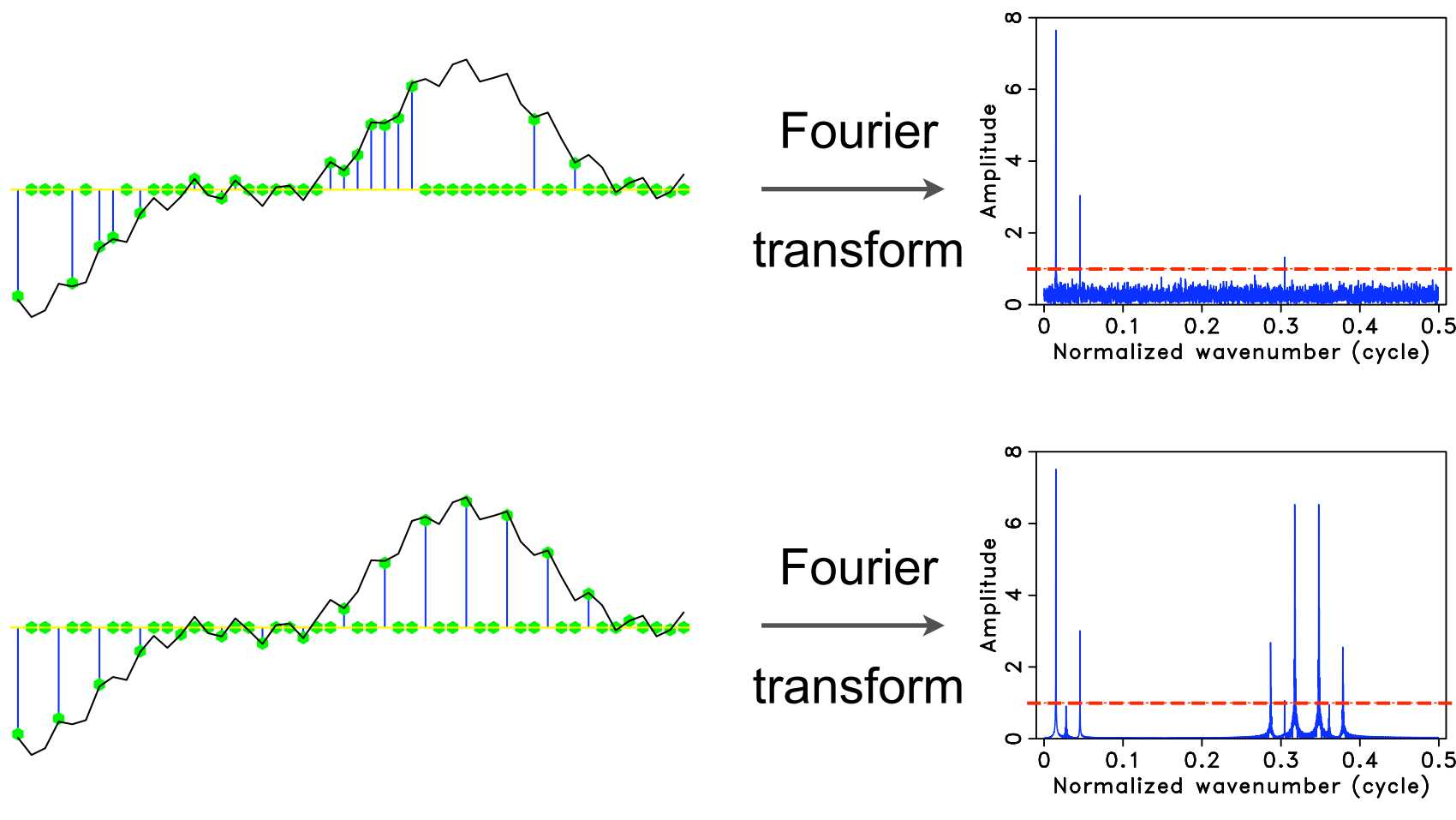


# Coarse sampling schemes



few significant coefficients

## 3-fold under-sampling



✓ significant coefficients detected

✗

ambiguity

# Extensions

---

Incomplete and noisy measurements:

$$\mathbf{y} = \underbrace{\mathbf{R}}_{\text{Restriction}} \underbrace{\mathbf{M}}_{\text{Measurement}} \mathbf{m} + \mathbf{n}$$

$\mathbf{y}$  *incomplete* (compressively sampled) and noisy data

$\mathbf{m}$  the *unknown* model

$\mathbf{M}$  “**arbitrary**” *measurement* matrix

Fourier, eigenfunctions

simultaneous sources

$\mathbf{R}$  *restriction* matrix

$\mathbf{n}$  Gaussian noise



# Extensions

---

- Use CS principles to select appropriate
  - measurement basis **M**
  - sparsifying transform **S**
  - driven by signal type, physics, and type of acquisition (e.g. fMRI vs seismic)
- Sparse signal representation:

$$\mathbf{y} = \mathbf{A}\mathbf{x}_0$$

with

$$\mathbf{A} = \mathbf{R}\mathbf{M}\mathbf{S}^H$$

restriction  
matrix

measurement  
matrix

sparsity  
matrix

Selection is aimed at turning *aliases/coherent subsampling artifacts* into harmless **noise** ...

# Extensions

---

- According to CS theory (valid for orthonormal bases for **M** & **S**) recovery depends on ***restriction***, ***mutual coherence***, and ***sparsity***
- ***Mutual coherence*** between **M** & **S** (off-diagonals of Gramm matrix),

$$\mu(\mathbf{M}, \mathbf{S}) = \sqrt{m} \max_{(k,l) \in [1 \cdots m] \times [1 \cdots m]} |\langle m_k, s_l \rangle|$$

and appropriate subsampling

- controls leakage
- maps interferences into noise
- importance sample in the band

- ***Compressibility***, i.e.,

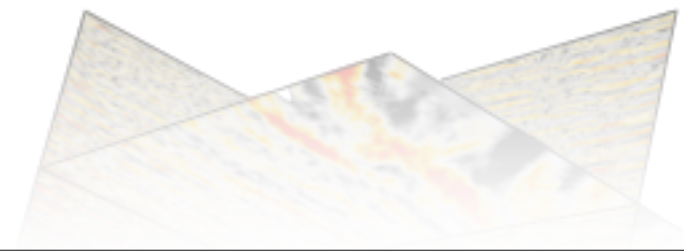
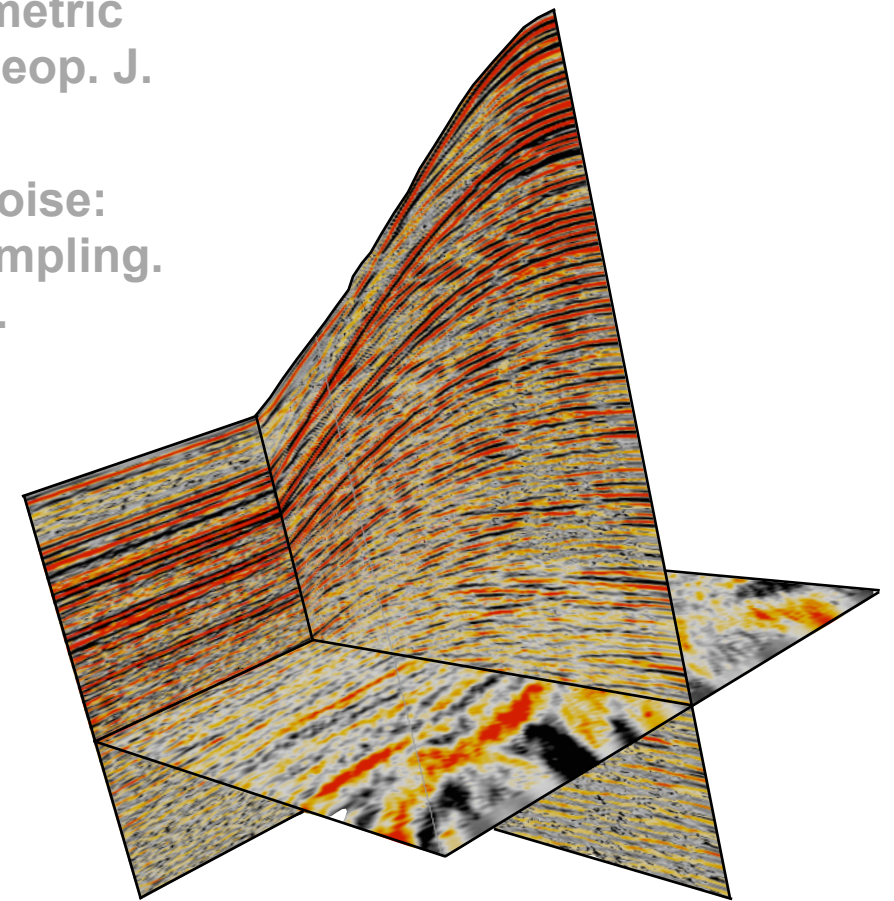
$$|\mathbf{x}_{i \in I}| \leq C i^{-r}, \quad r \geq 1 \quad \text{and} \quad x_{I(1)} \geq x_{I(2)} \geq \cdots \geq x_{I(m)}$$

# Wavefield reconstruction



Herrmann, F. J. and Hennenfent, G. Non-parametric seismic data recovery with curvelet frames, *Geop. J. Int.*, Vol. 173, No. 1, pp. 233-248, 2008

Hennefent, G. and Herrmann, F. J. Simply denoise: wavefield reconstruction via jittered under-sampling. *Geophysics*, Vol. 73, No. 3, pp. V19–V28, 2008.



# Key elements

---

## □ *sparsifying transform*

- typically **localized** in the time-space domain to handle the complexity of seismic data

## □ *advantageous coarse sampling*

- generates incoherent random undersampling “noise” in the sparsifying domain
- does not create large gaps
  - because of the limited spatiotemporal extent of transform elements used for the reconstruction

## □ *sparsity-promoting solver*

- requires few matrix-vector multiplications

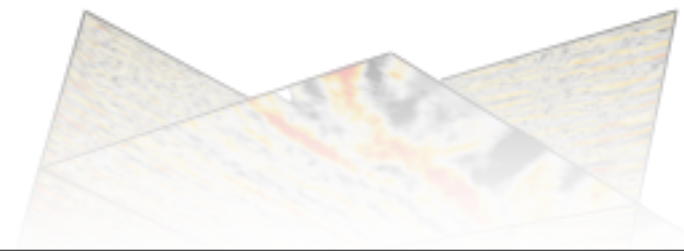
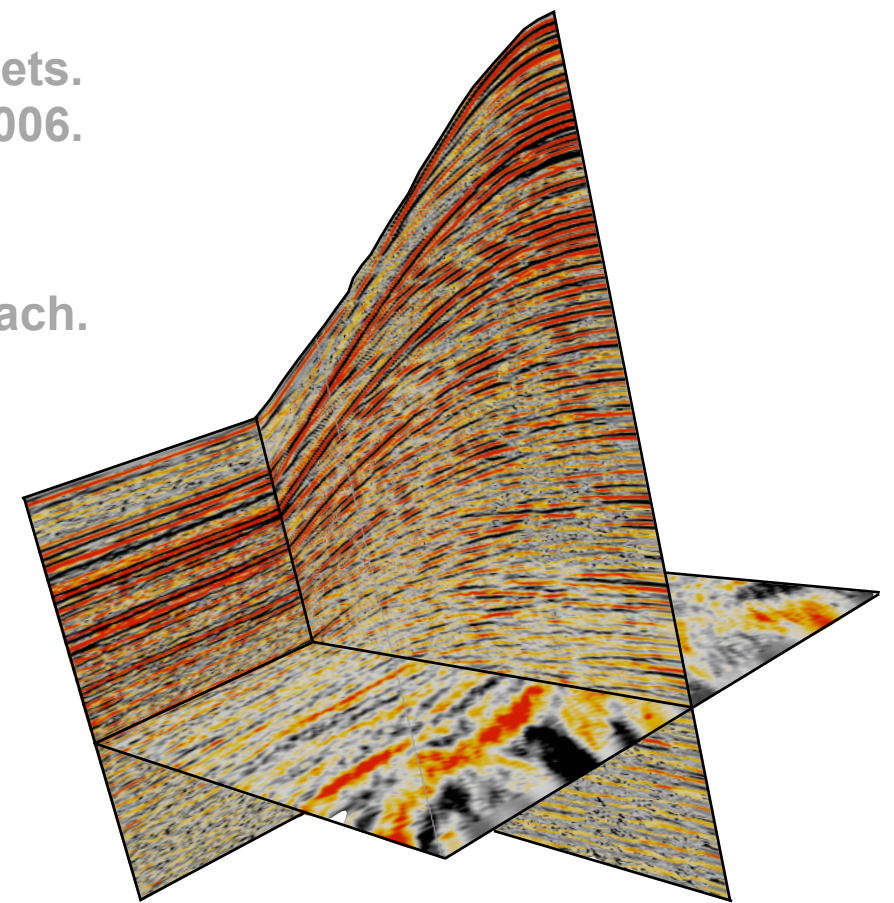


# Curvelet transform



Hennenfent, G and Herrmann, F. J., Seismic Denoising with Nonuniformly Sampled Curvelets. *Comp. in Sc. & Eng.*, vol. 8, no. 3, pp. 16-25, 2006.

Herrmann, F. J., Wang, D., Hennenfent, G. and Moghaddam, P. Curvelet-based seismic data processing: a multiscale and nonlinear approach. *Geophysics*, Vol. 73, No. 1, pp. A1–A5, 2008.

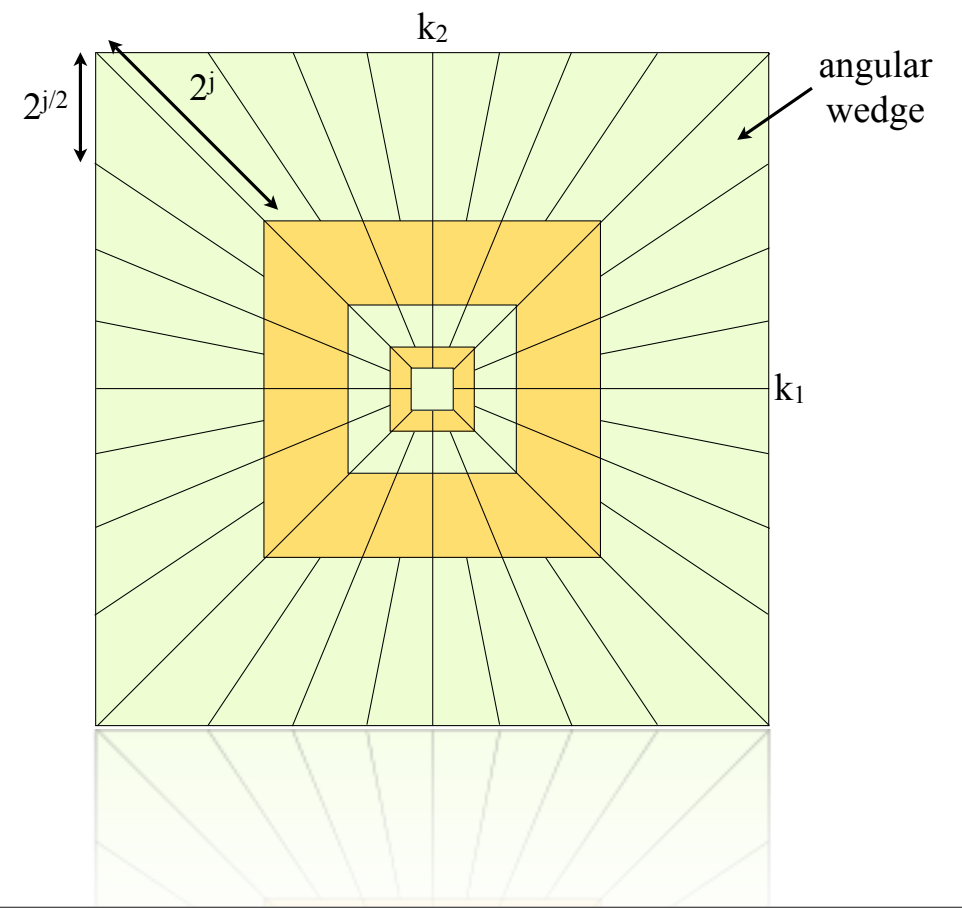


# Representations for seismic data

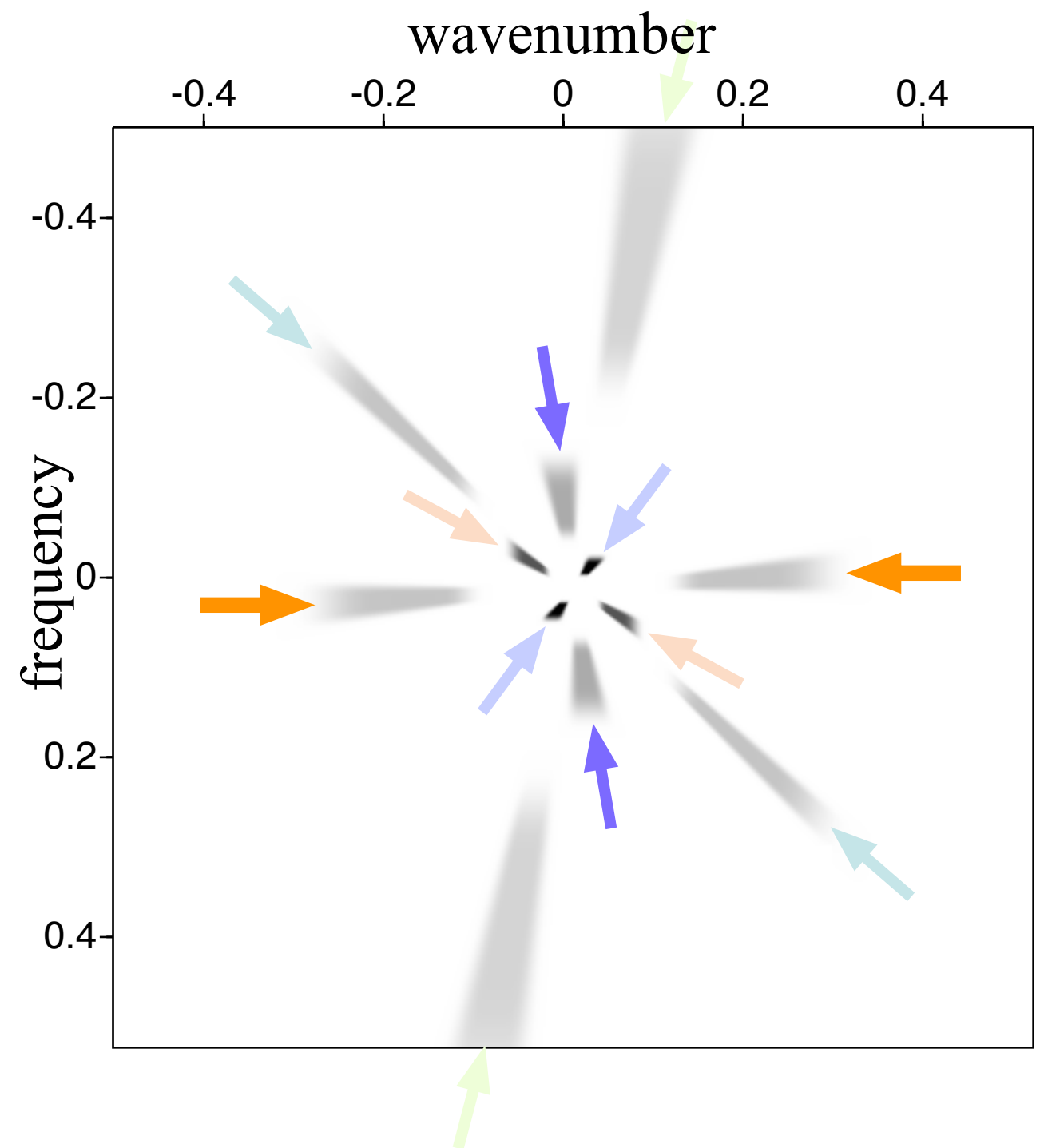
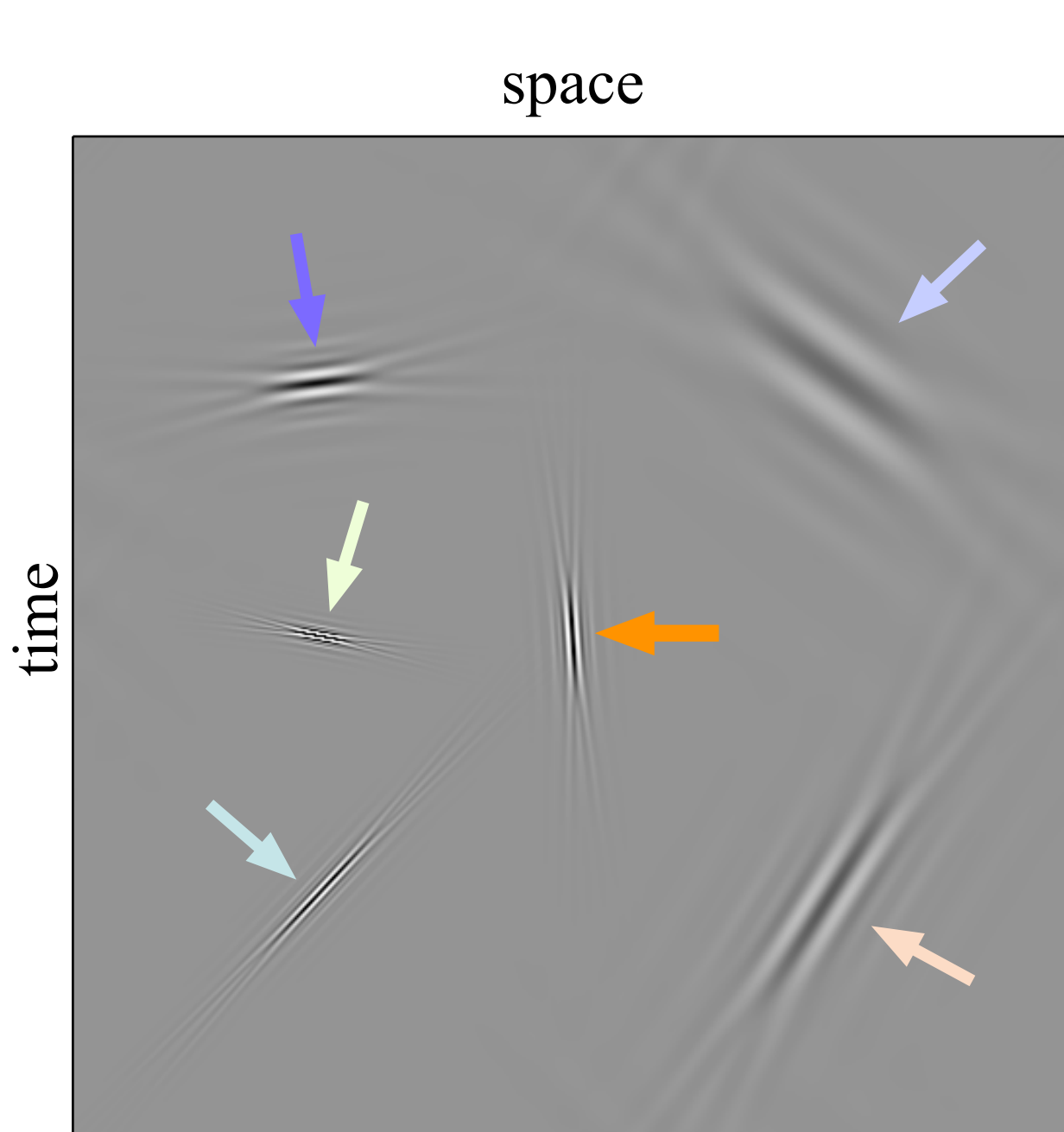
Transform	Underlying assumption
FK	plane waves
linear/parabolic Radon transform	linear/parabolic events
wavelet transform	point-like events (1D singularities)
<b>curvelet transform</b>	<b>curve-like events (2D singularities)</b>

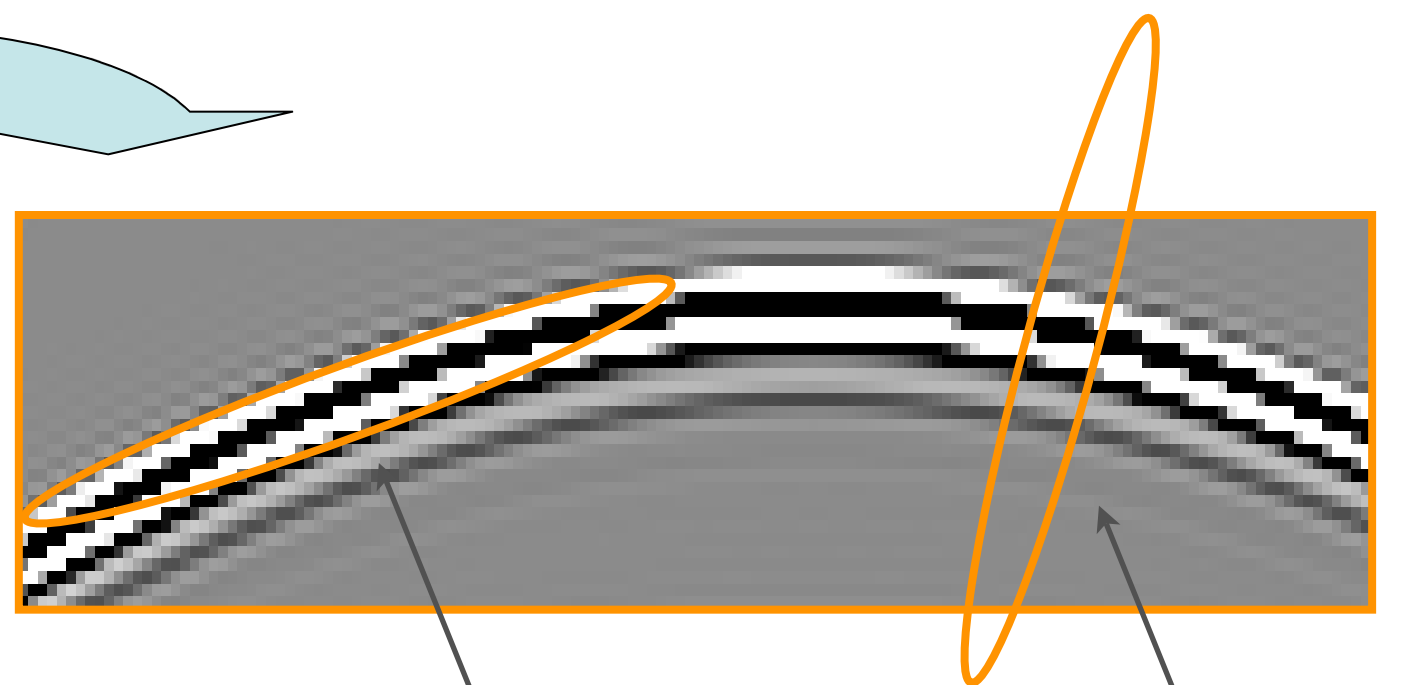
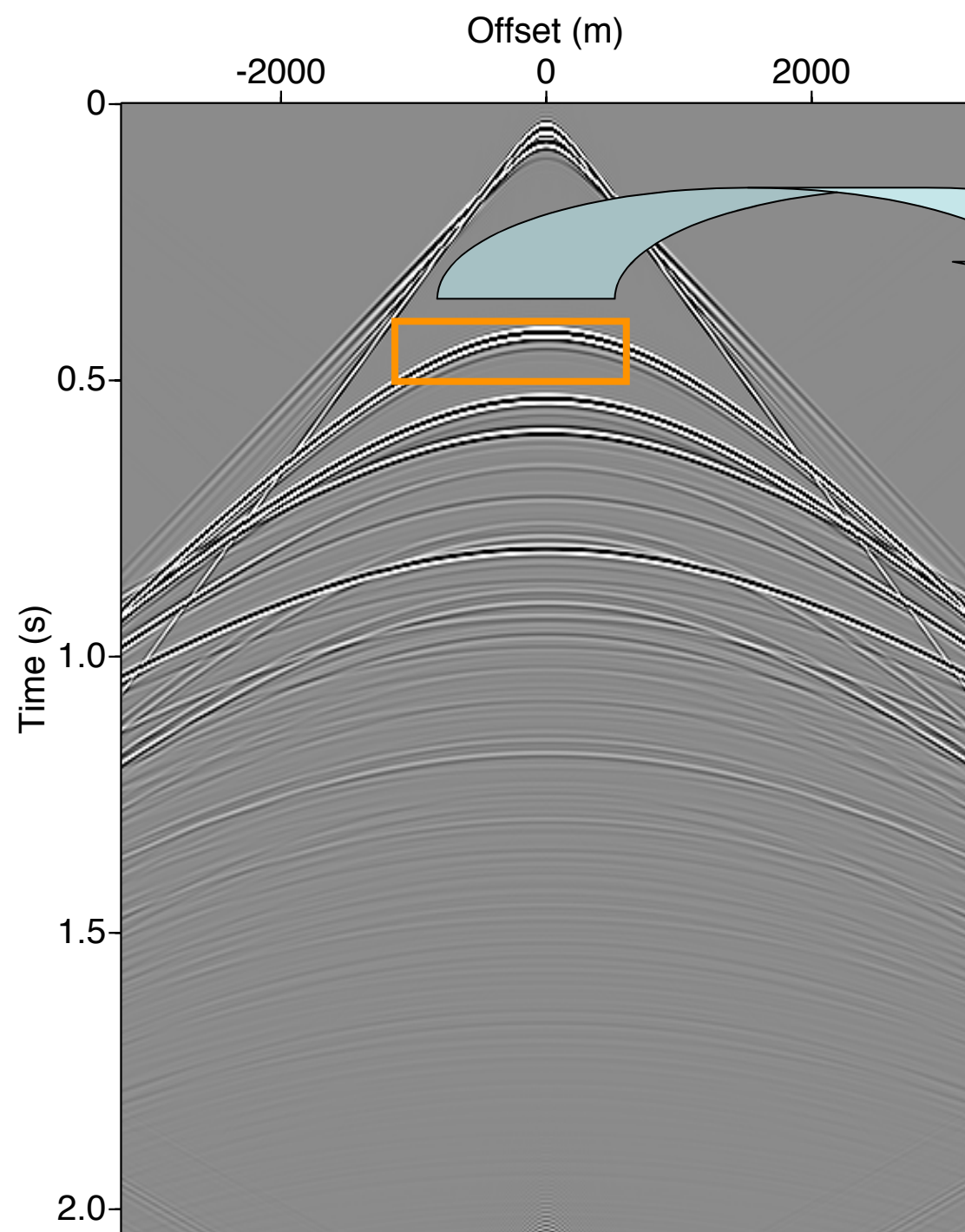
- curvelet transform

- **multiscale**: tiling of the FK domain into dyadic coronae
- **multidirectional**: coronae sub-partitioned into angular wedges, # of angles doubles every other scale
- **anisotropic**: parabolic scaling principle
- **local**



# 2D discrete curvelets



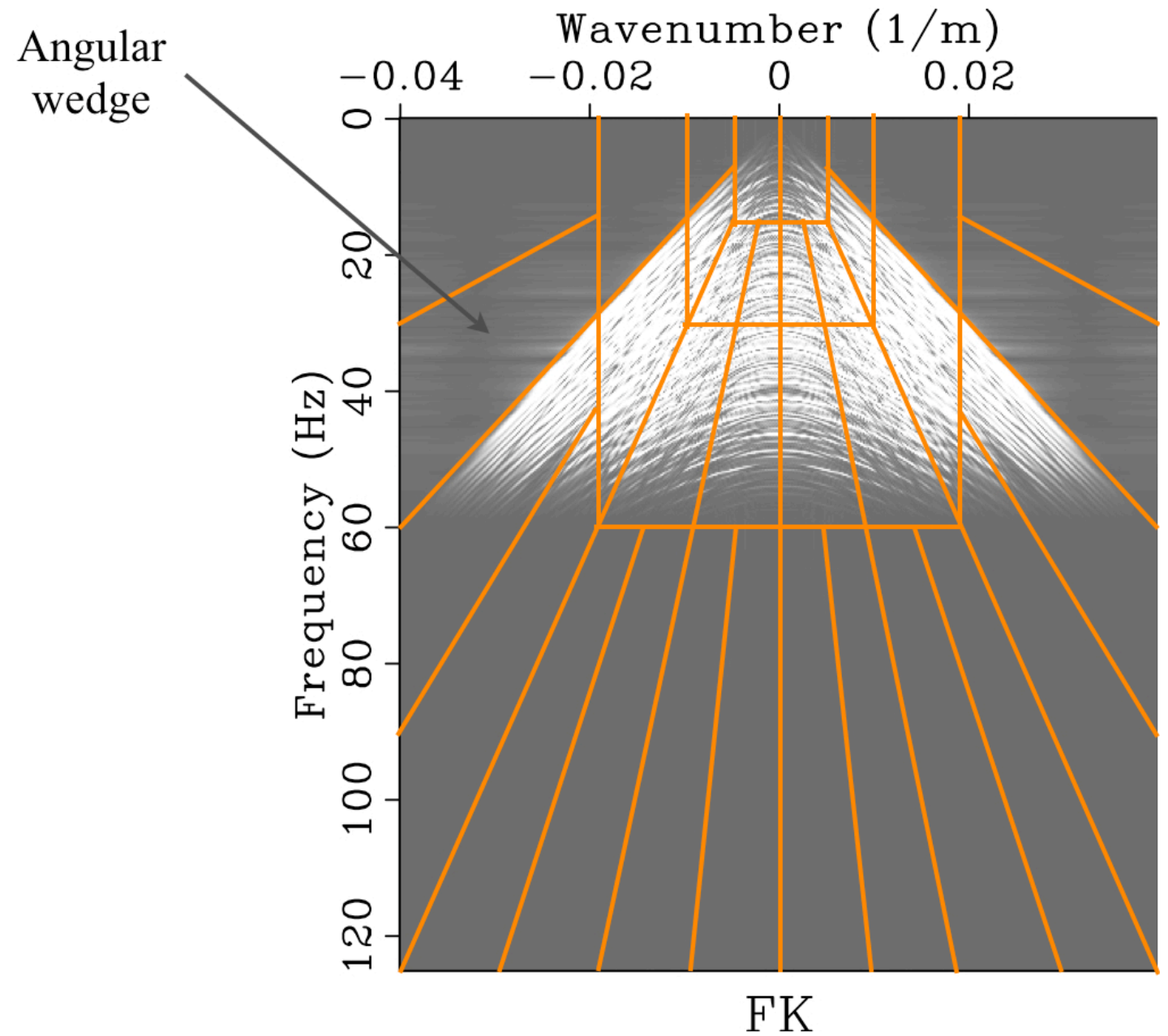
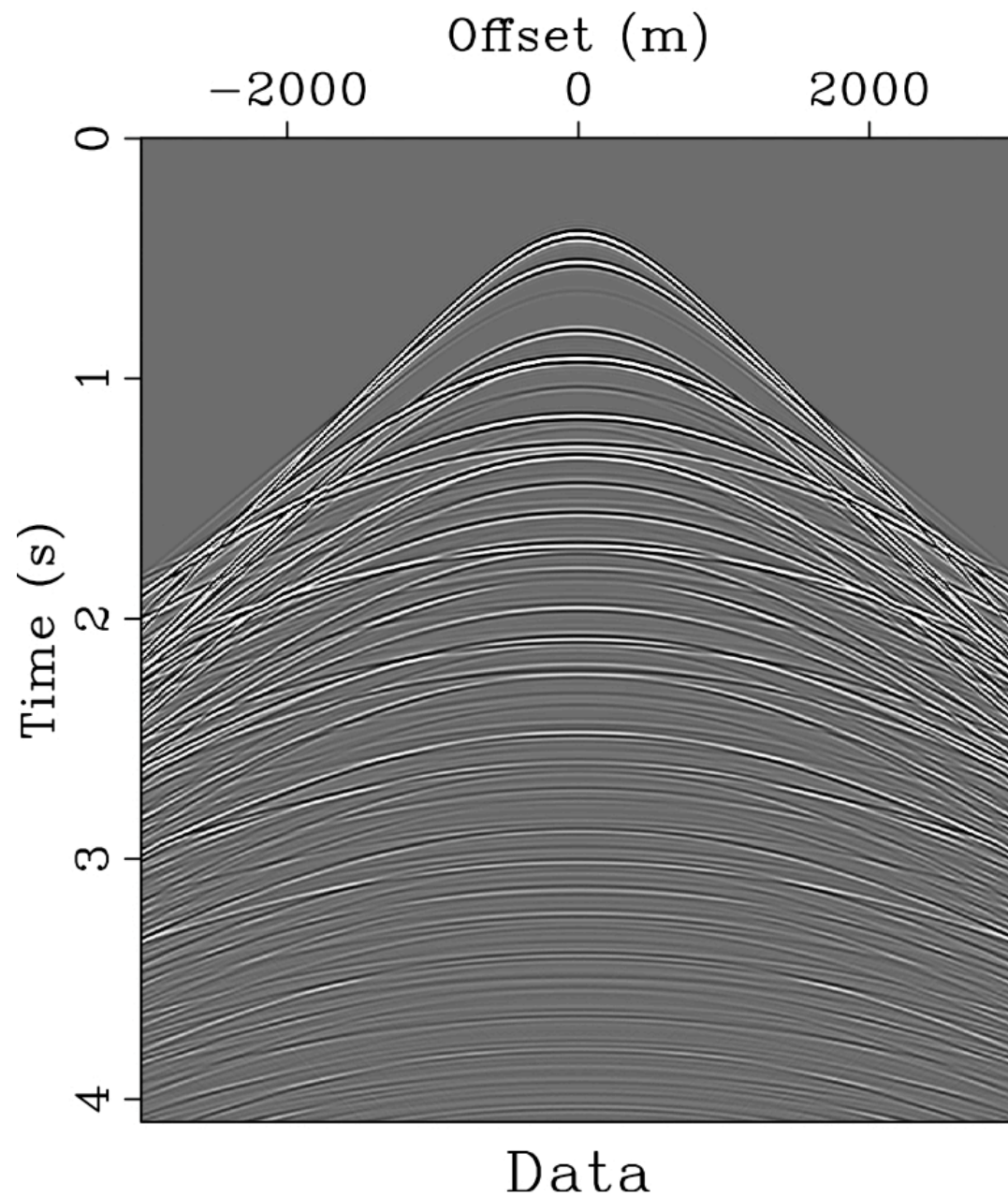


Significant  
curvelet coefficient

Curvelet  
coefficient~0



# Curvelet tiling & seismic data

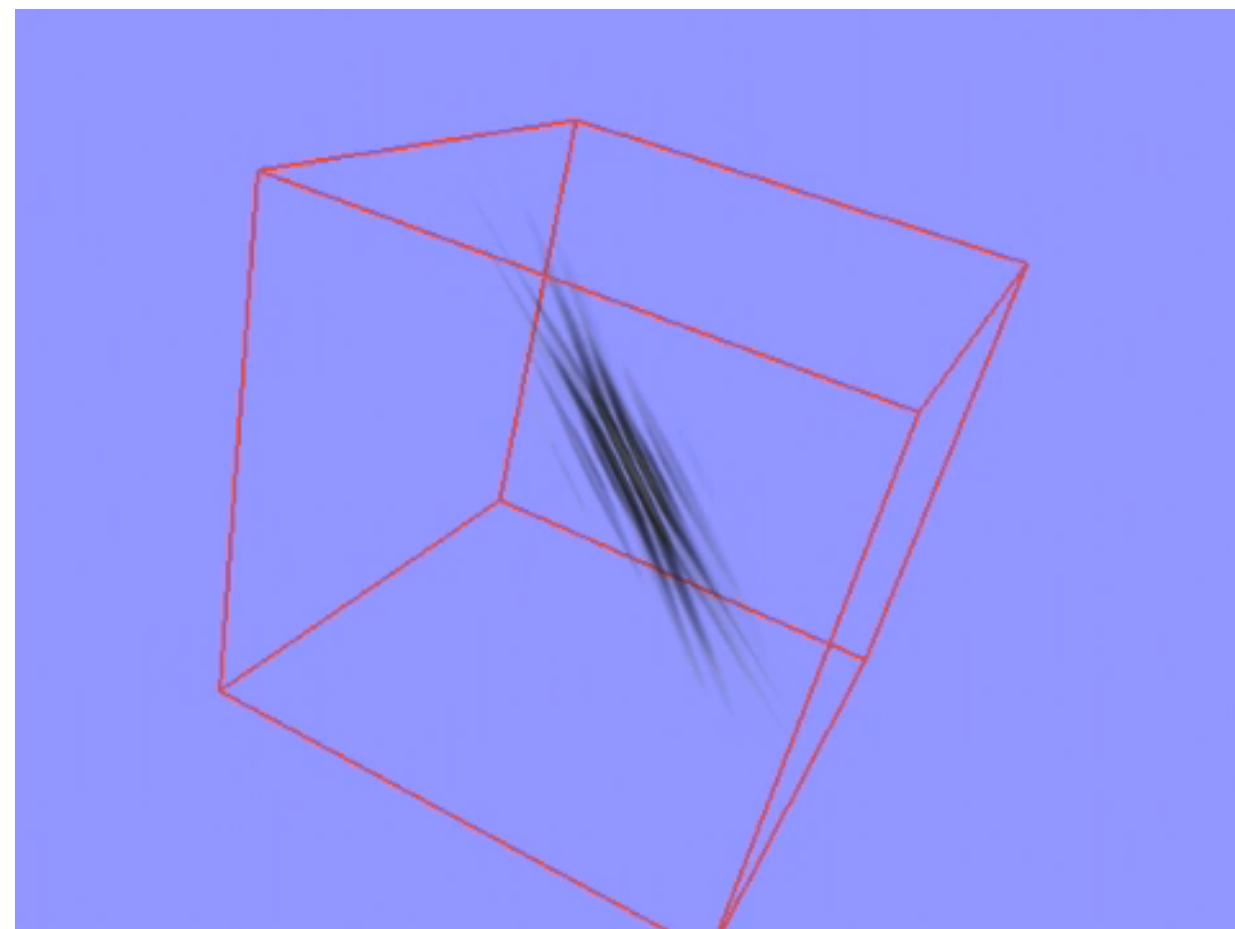
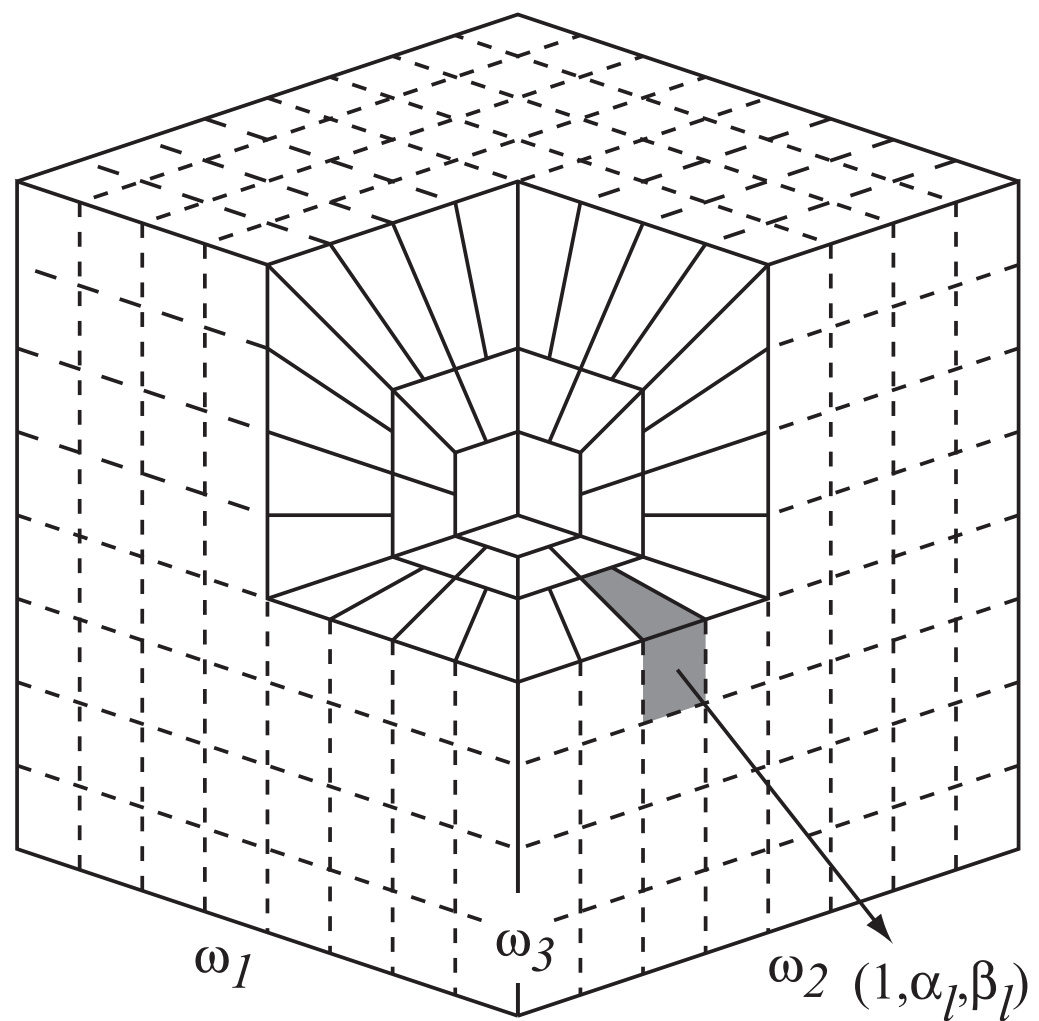


— Curvelet tiling

**Curvelet tiling superimposed on the FK domain**

# 3D discrete curvelets

---



# Key elements

---

## ☒ *sparsifying transform*

- typically **localized** in the time-space domain to handle the complexity of seismic data

## ☐ *advantageous coarse sampling*

- generates incoherent random undersampling “noise” in the sparsifying domain
- does not create large gaps
  - because of the limited spatiotemporal extent of transform elements used for the reconstruction

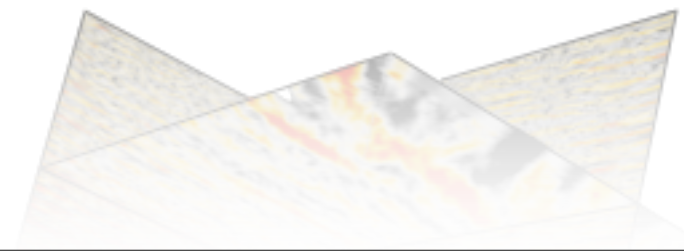
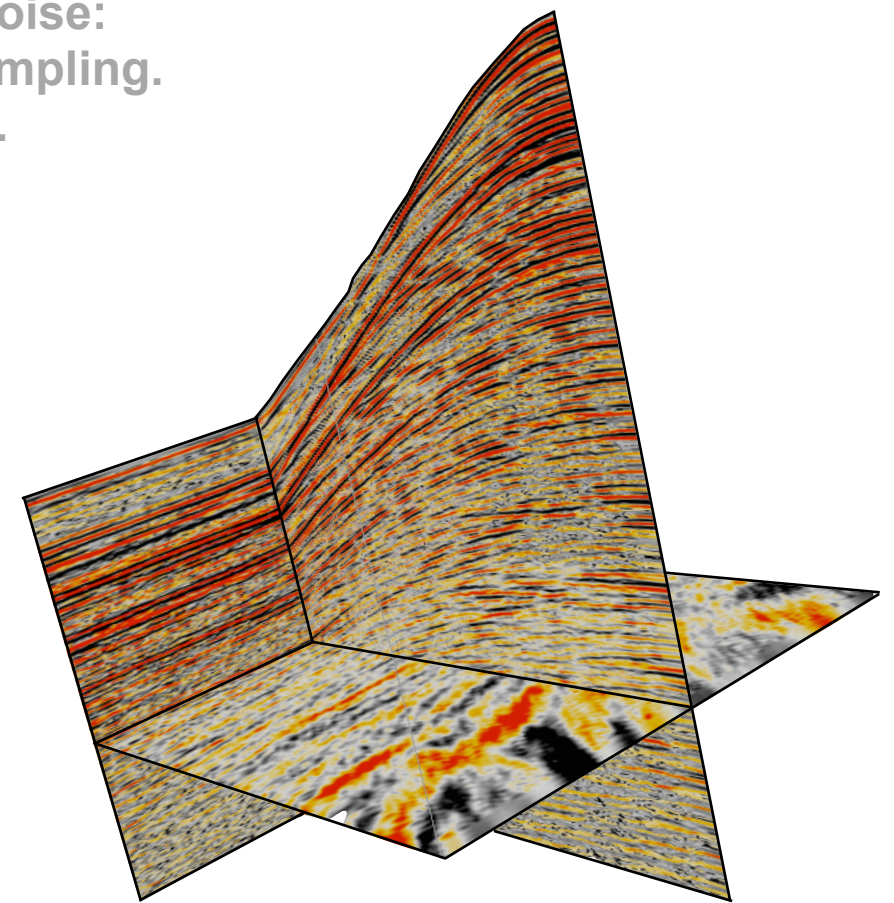
## ☐ *sparsity-promoting solver*

- requires few matrix-vector multiplications

# Jittered undersampling



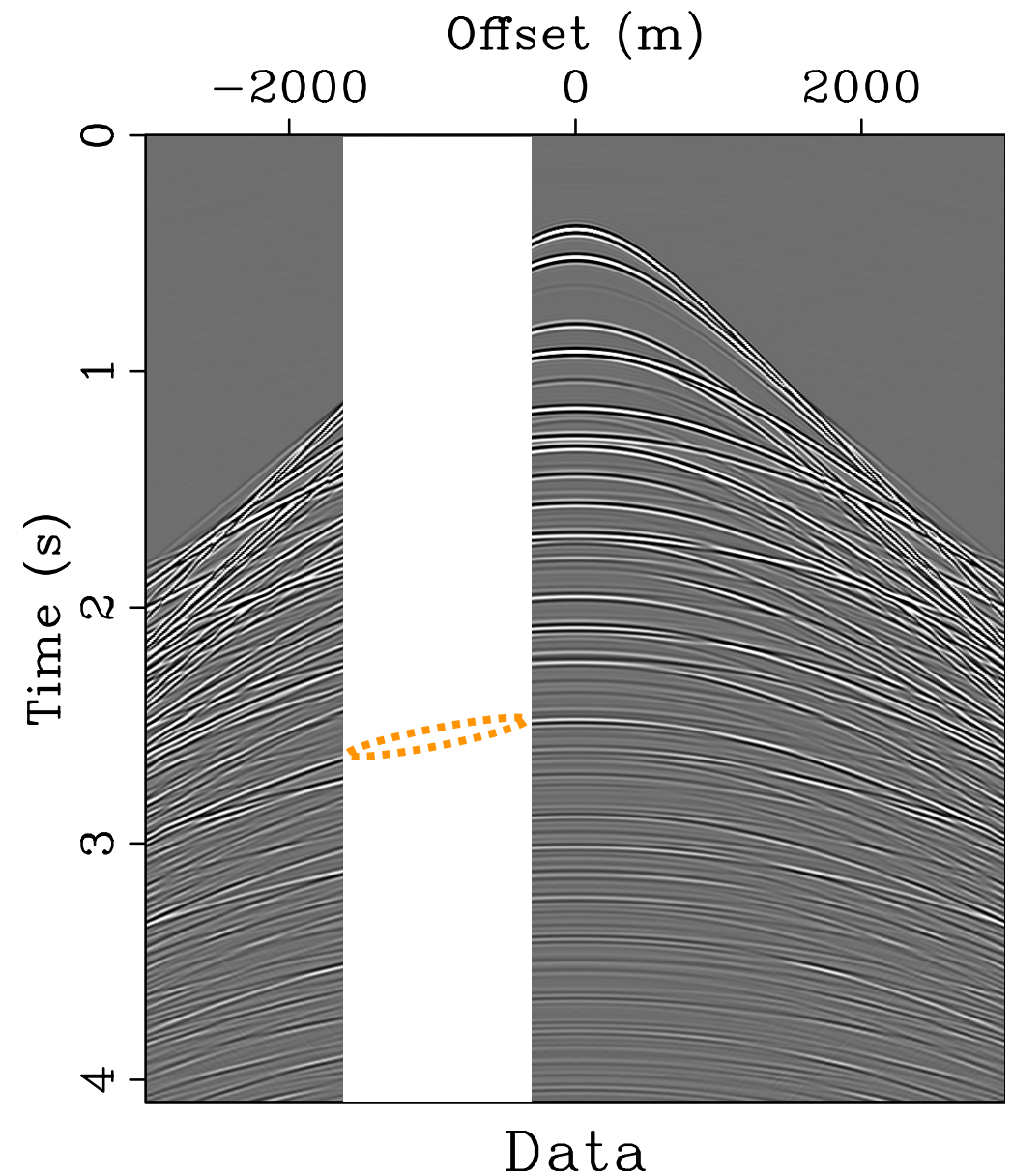
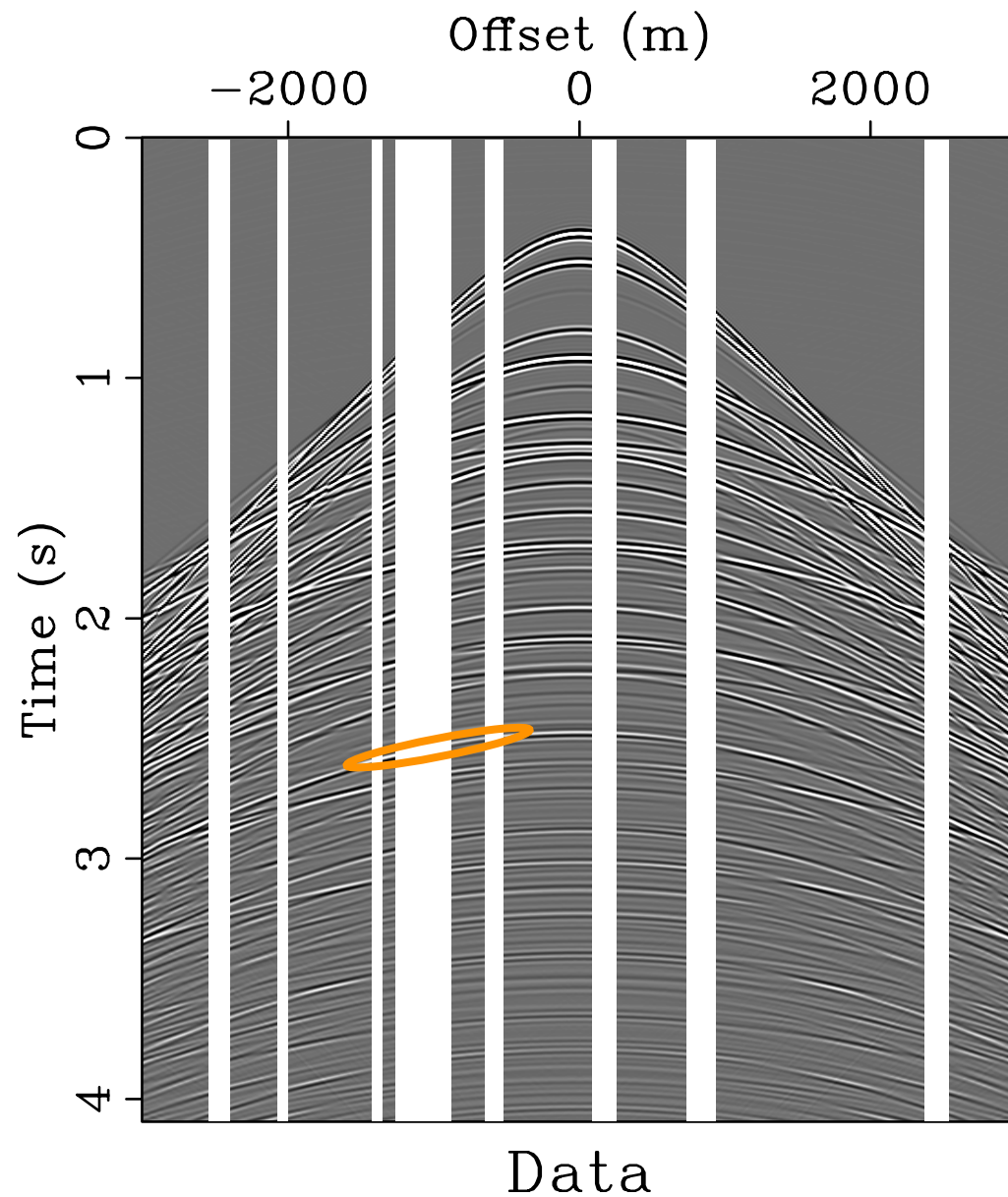
Hennefent, G. and Herrmann, F. J. Simply denoise:  
wavefield reconstruction via jittered under-sampling.  
Geophysics, Vol. 73, No. 3, pp. V19–V28, 2008.



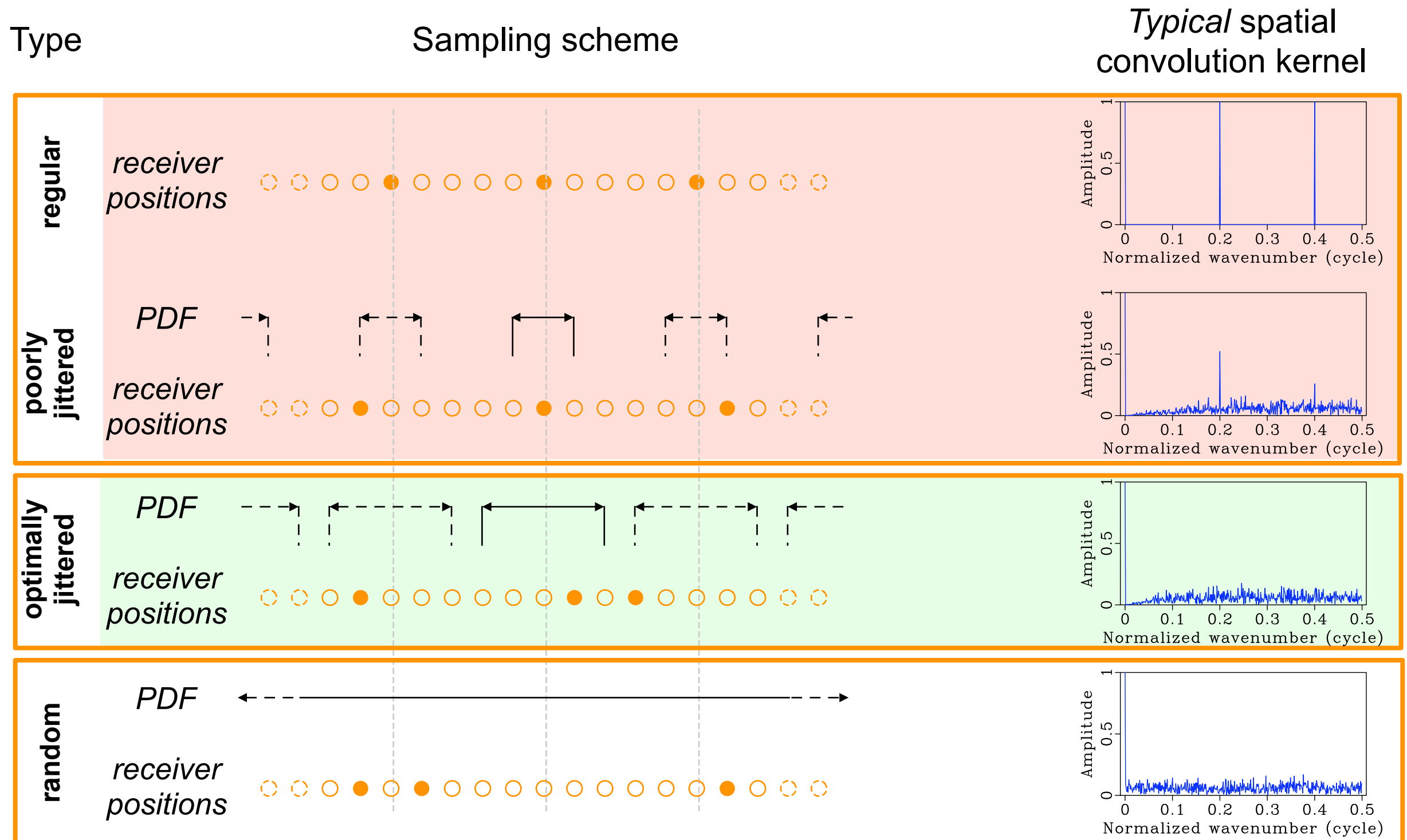


# Localized transform elements & gap size

$$\tilde{\mathbf{x}} = \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = \mathbf{A}\mathbf{x}$$



# Discrete random jittered undersampling



# Key elements

---

## ☒ *sparsifying transform*

- typically **localized** in the time-space domain to handle the complexity of seismic data

## ☒ *advantageous coarse sampling*

- generates incoherent random undersampling “noise” in the sparsifying domain
- does not create large gaps
  - because of the limited spatiotemporal extent of transform elements used for the reconstruction

## ☐ *sparsity-promoting solver*

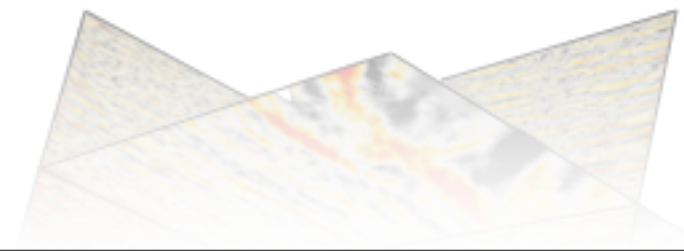
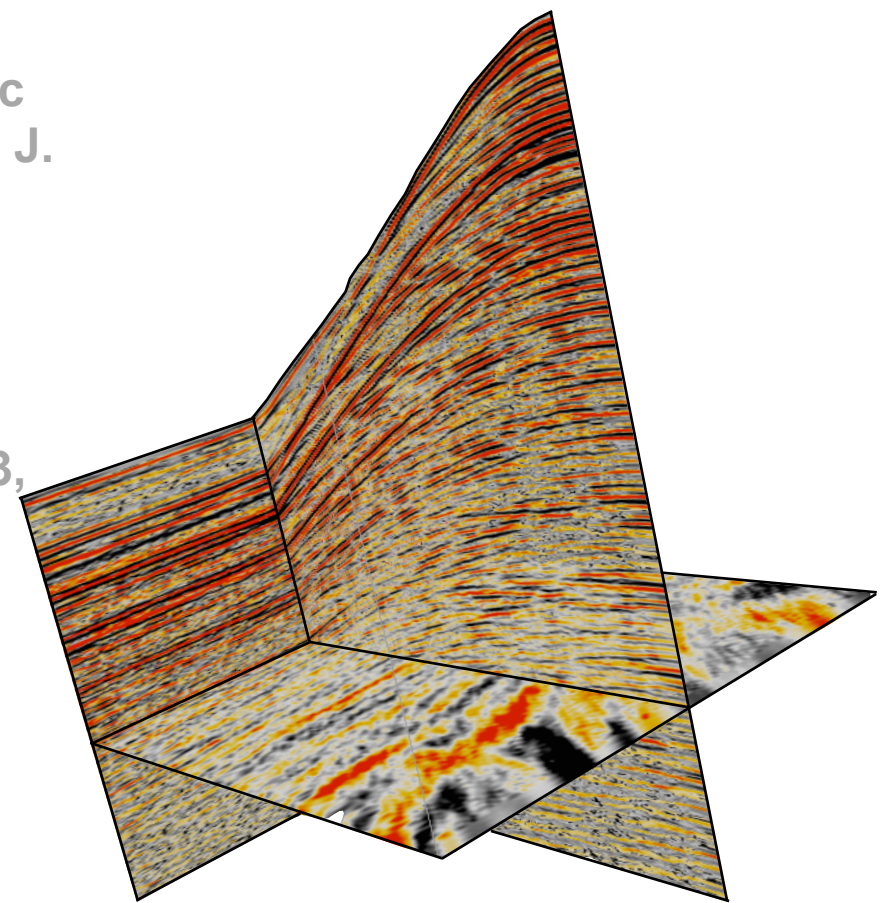
- requires few matrix-vector multiplications

# Sparsity-promoting solvers



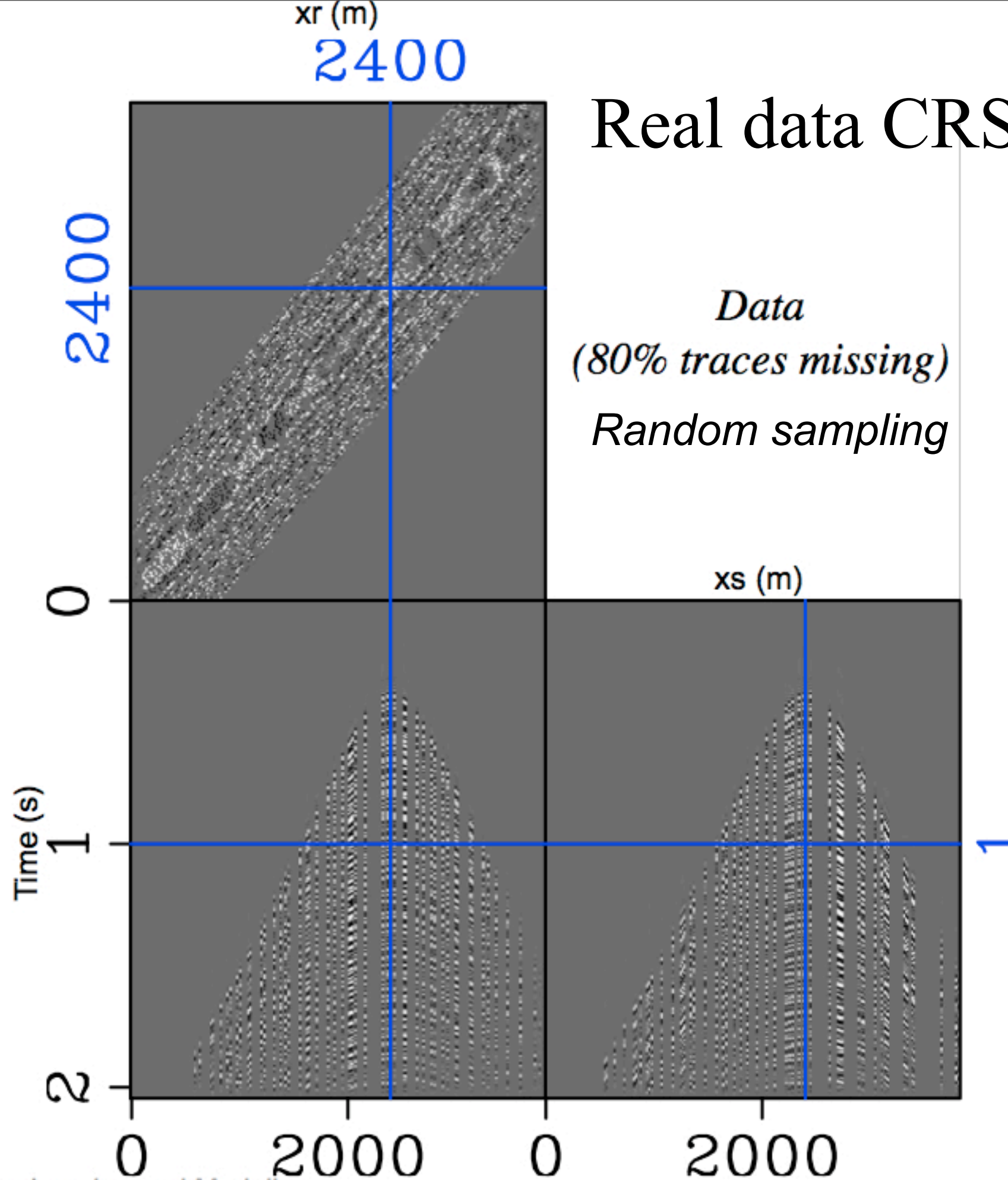
Herrmann, F. J. and Hennenfent, G. Non-parametric seismic data recovery with curvelet frames, *Geop. J. Int.*, Vol. 173, No. 1, pp. 233-248, 2008.

G. Hennenfent, E. van den Berg, M. P. Friedlander, and F. J. Herrmann. New insights into one-norm solvers from the Pareto curve. *Geophysics*, Vol. 73, No. 4, 2008.



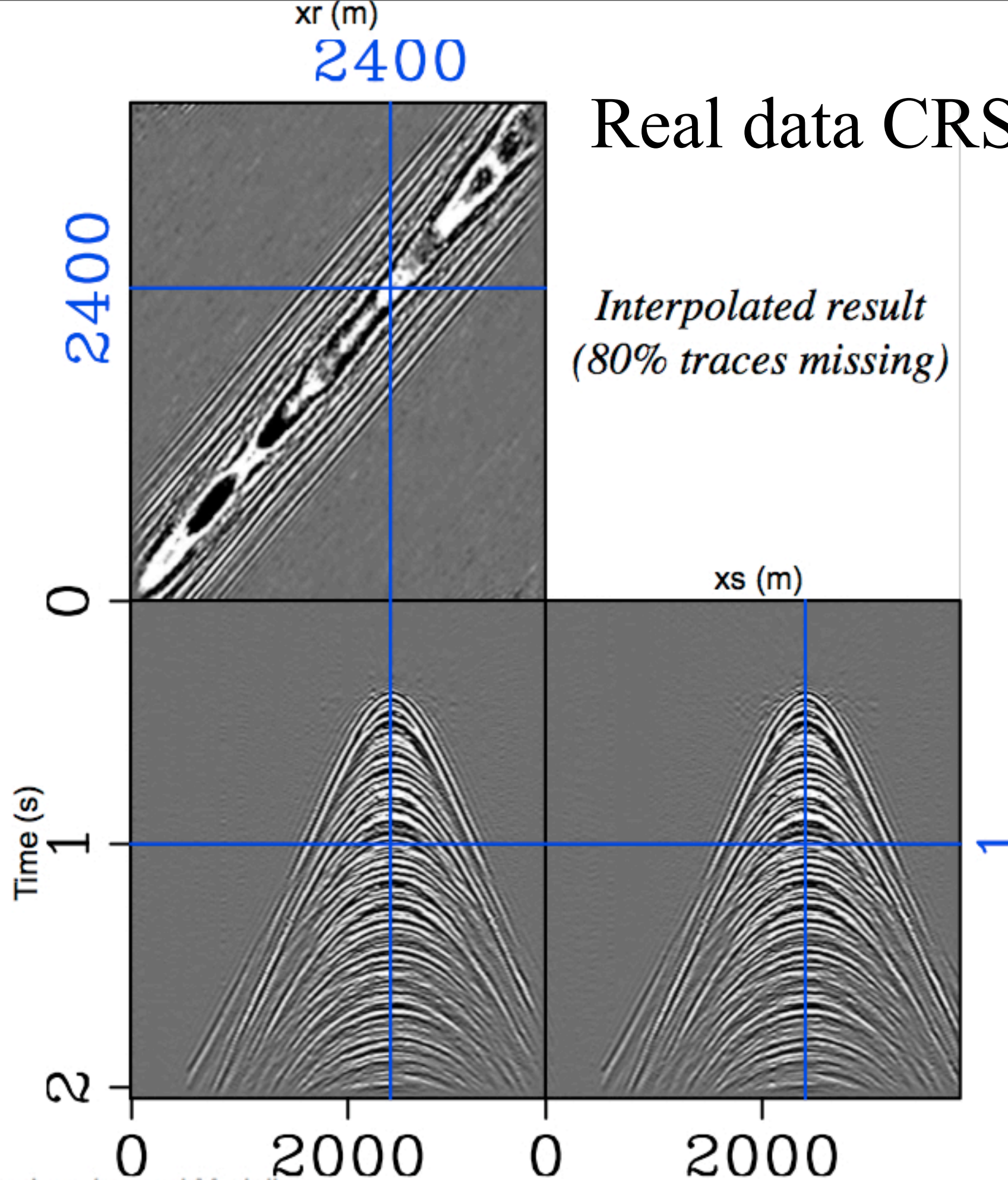


# Real data CRSI example





# Real data CRSI example



# Observations

---

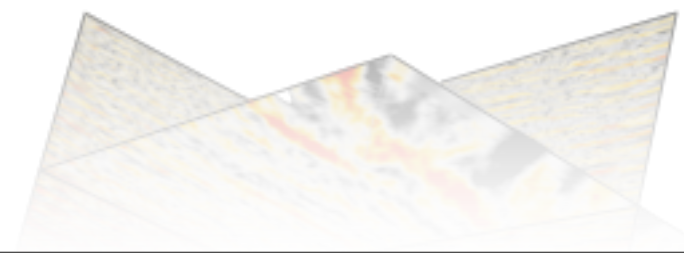
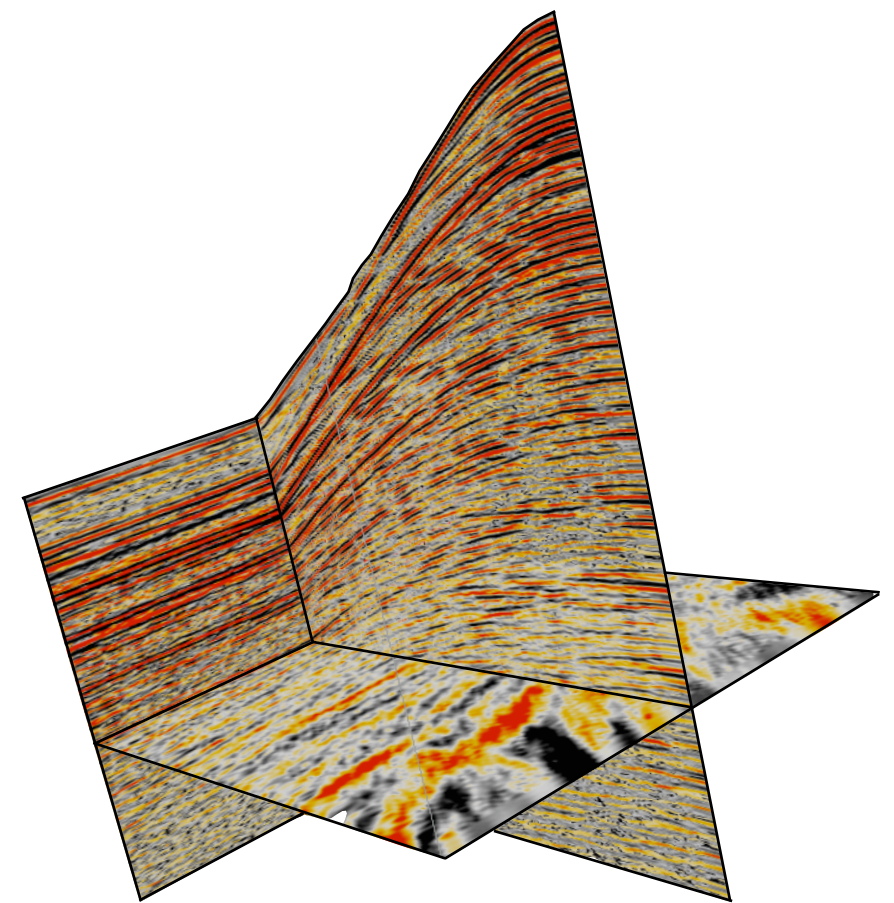
- Random subsampling breaks *constructive* interferences, i.e. *aliases*
- Turns *aliases* into incoherent *noise*
- Works by virtue of
  - *incoherence* (correlations) between the *rows* of the *Dirac* measurement basis and the columns of the *Fourier synthesis* basis
  - maximum *spreading* of Diracs in Fourier domain
  - maximum *leakage*
  - *independence* amongst columns of  $\mathbf{A}$ , i.e., there exists a subset of columns of  $\mathbf{A}$  that forms an orthonormal basis
- According to theory of compressive sensing
  - recovery stable w.r.t. noise
  - measurement & sparsity bases can be more general
- Apply these principles to compressive wavefield computations
  - reduce memory imprint
  - reduce the number of sources = number of right-hand sides of linear systems

# Compressive one-way wavefield extrapolation



T. T. Y. Lin and F. J. Herrmann. Compressed wavefield extrapolation. *Geophysics*, 72(5):SM77–SM93, 2007.

L. Demanet and G. Peyre. Compressive wave computation, 2008. Stanford. Submitted for publication.



# Introduction

- Goal: employ the complete one-Way Helmholtz operator for **w**

Grimbergen, J., F. Dessing, and C. Wapenaar, 1998, Modal expansion of one-way operator on laterally varying media: Geophysics, **63**, 995–1005.

$$\mathbf{w}^{\pm} = e^{\mp j \Delta x \mathbf{H}_1} \quad \mathbf{H}_2 = \mathbf{H}_1 \mathbf{H}_1$$

- Problem: computation & storage complexity
  - creating and storing  $\mathbf{H}_2$  is trivial
  - however  $\mathbf{H}_1$  is *not* trivial to compute and store

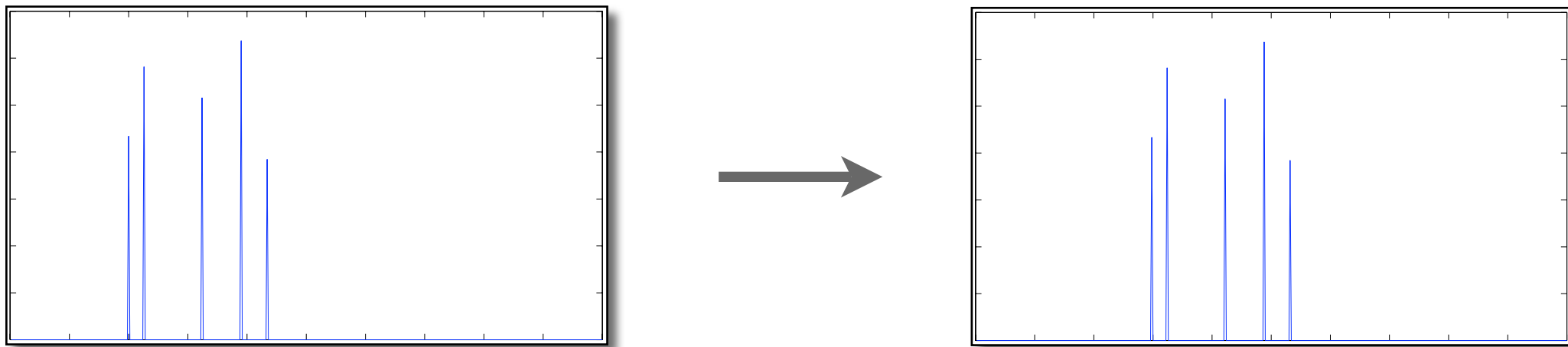
$$\mathbf{H}_2 = \begin{bmatrix} \diagdown \end{bmatrix}$$

$$\mathbf{H}_1 = \begin{bmatrix} | & | & | & | & | \end{bmatrix}$$

# Our approach

---

- Consider a related, but simpler problem: shifting (or translating) a signal



- operator is  $\mathbf{T}_{\Delta x} = e^{-j \frac{\Delta x}{2\pi}} \mathbf{D}$
- $\mathbf{D}$  is differential operator

$$\mathbf{D} = \left[ \begin{array}{c} \text{N} \end{array} \right]$$



# Our approach

- Computation requires similar approach to  $\mathbf{w}^\pm$

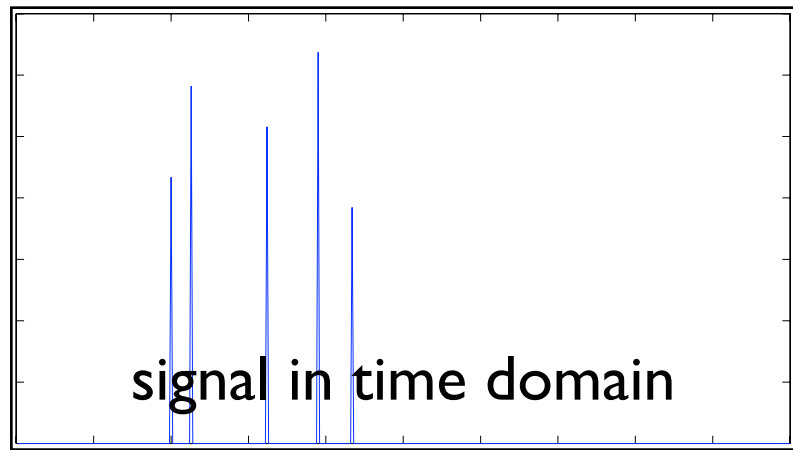
$$\mathbf{D} = \mathbf{L}\mathbf{\Lambda}\mathbf{L}^T = \begin{bmatrix} | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \end{bmatrix} \begin{bmatrix} \diagdown \\ \diagup \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$$

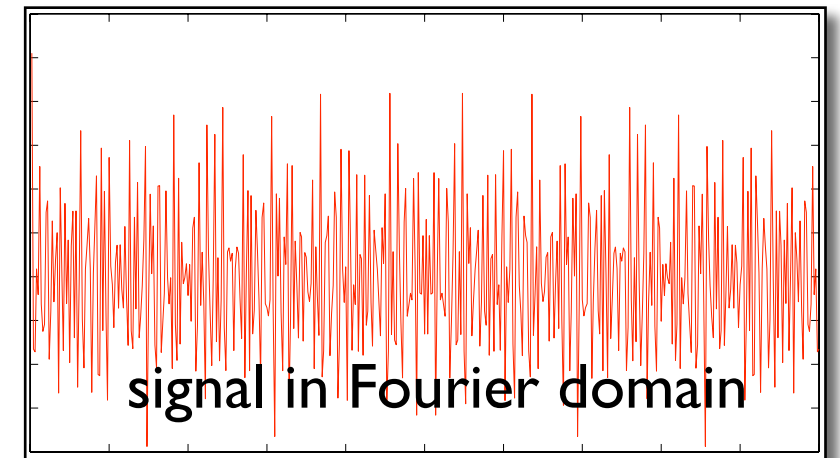
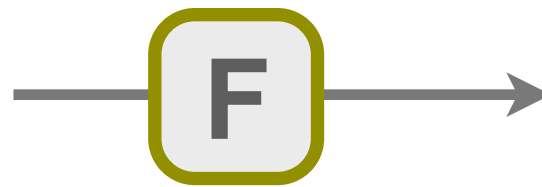
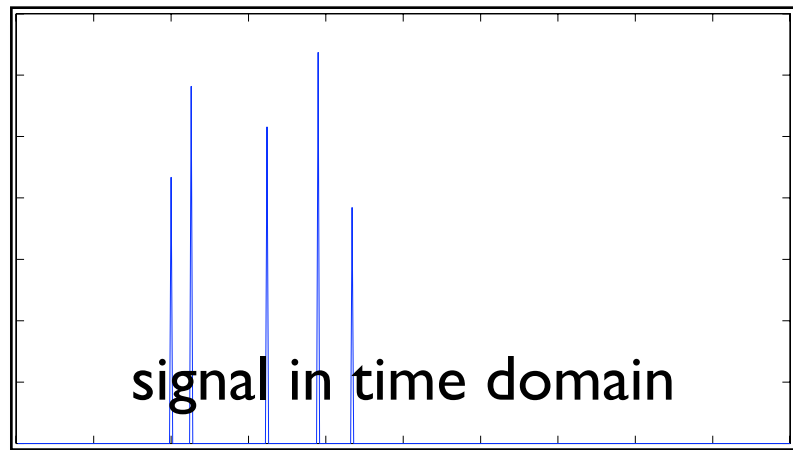
$\mathbf{L} \qquad \mathbf{\Lambda} \qquad \mathbf{L}^T$

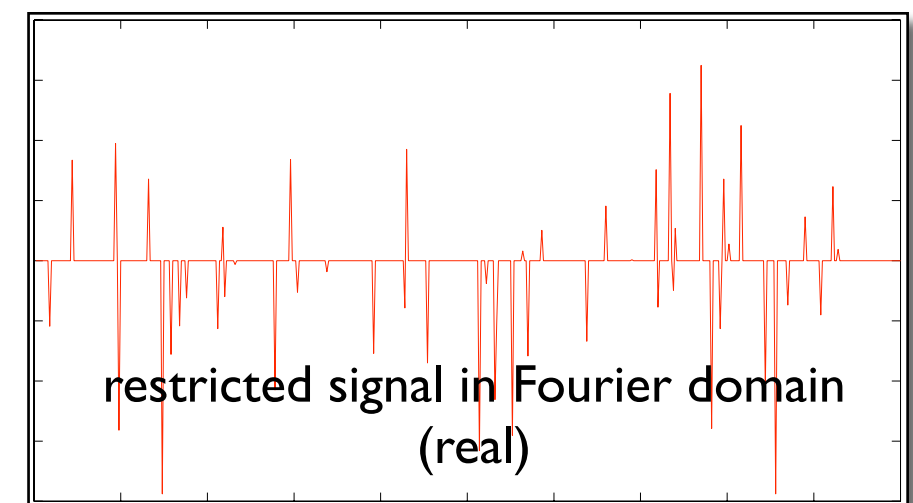
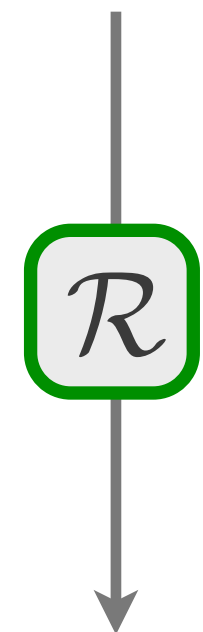
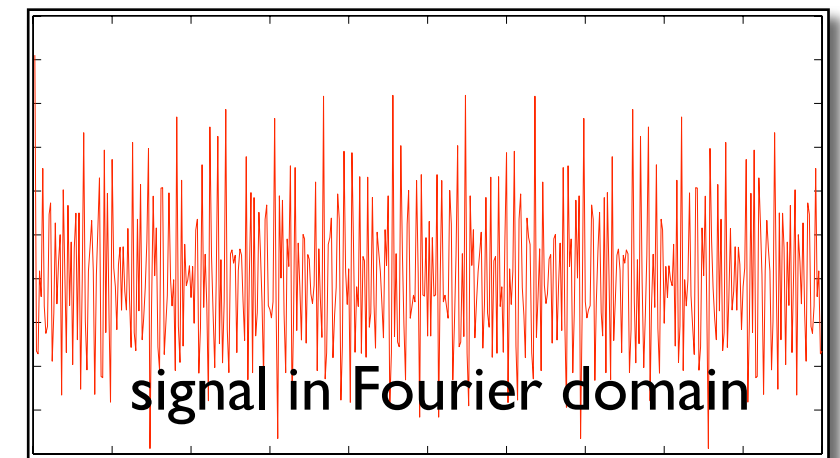
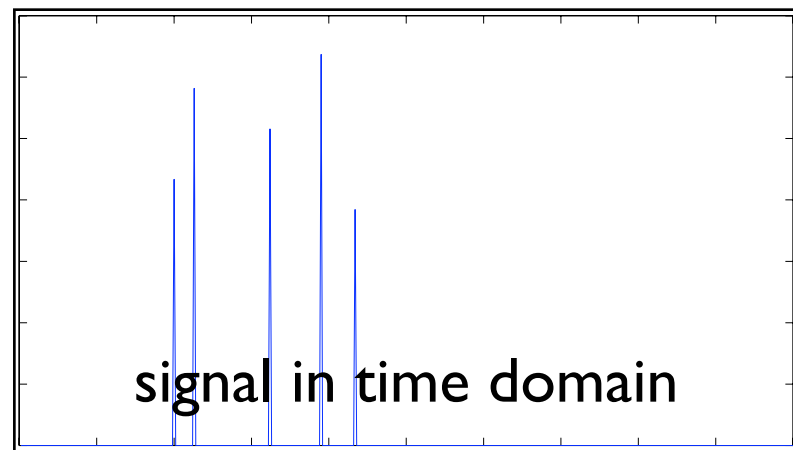
$$\mathbf{T}_{\Delta x} = \begin{bmatrix} | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \end{bmatrix} \begin{bmatrix} \diagdown \\ \diagup \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$$

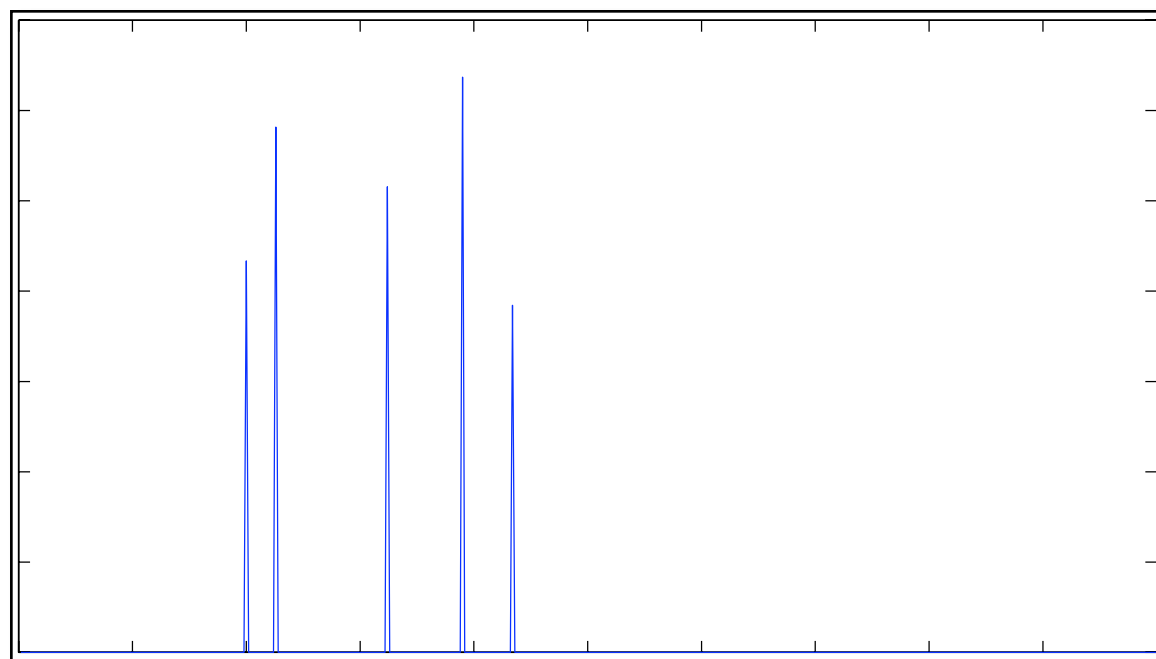
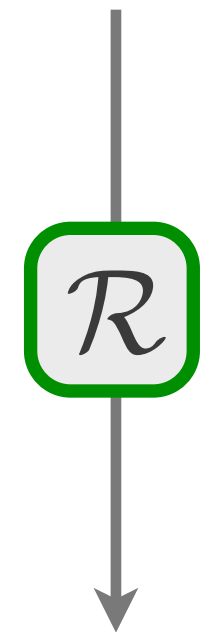
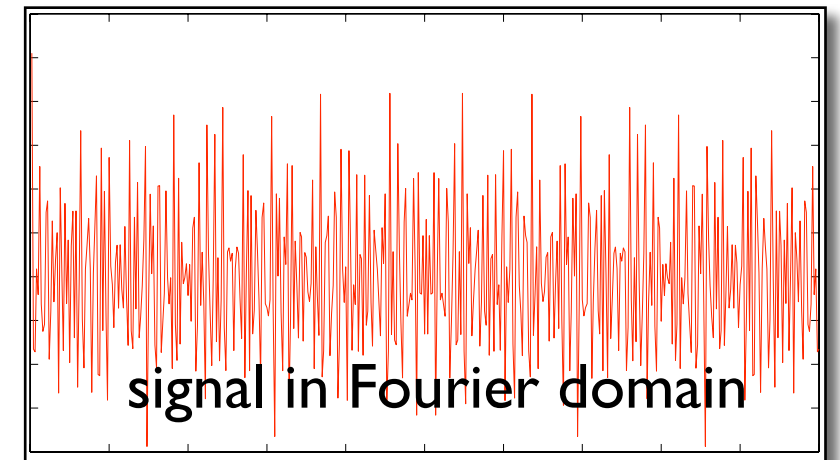
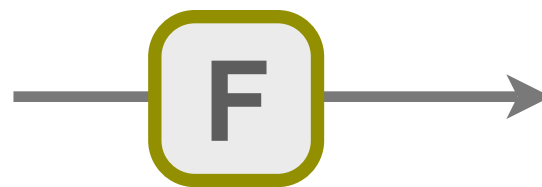
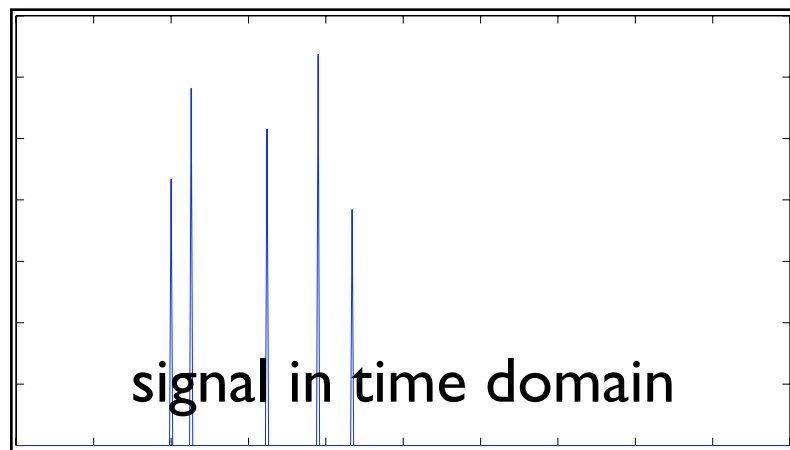
$\mathbf{L} \qquad e^{-j \frac{\Delta x}{2\pi}} \mathbf{\Lambda} \qquad \mathbf{L}^T$

- However, for  $\mathbf{D}$ ,  $\mathbf{L} = \text{DFT}$ , so computation trivial with FFT

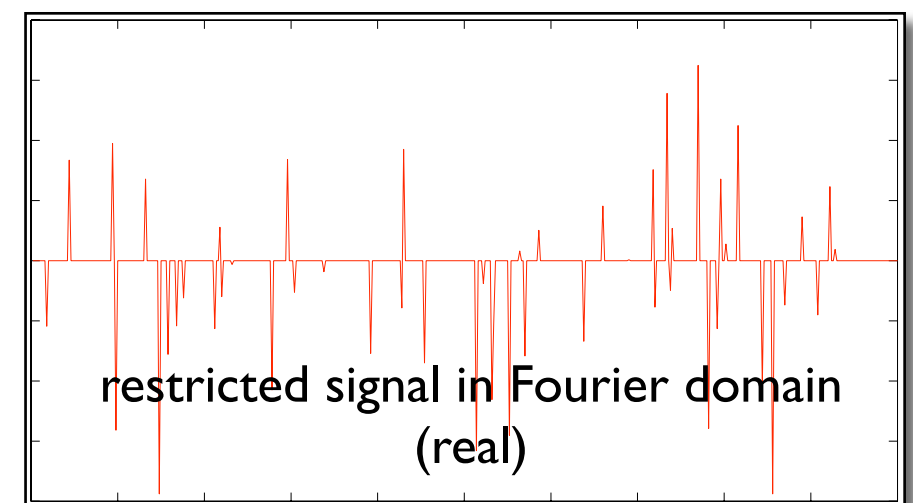
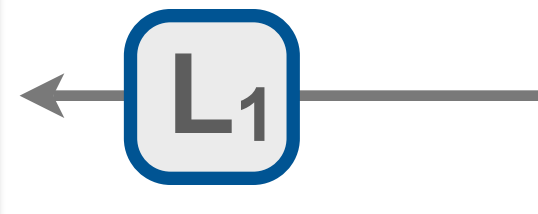






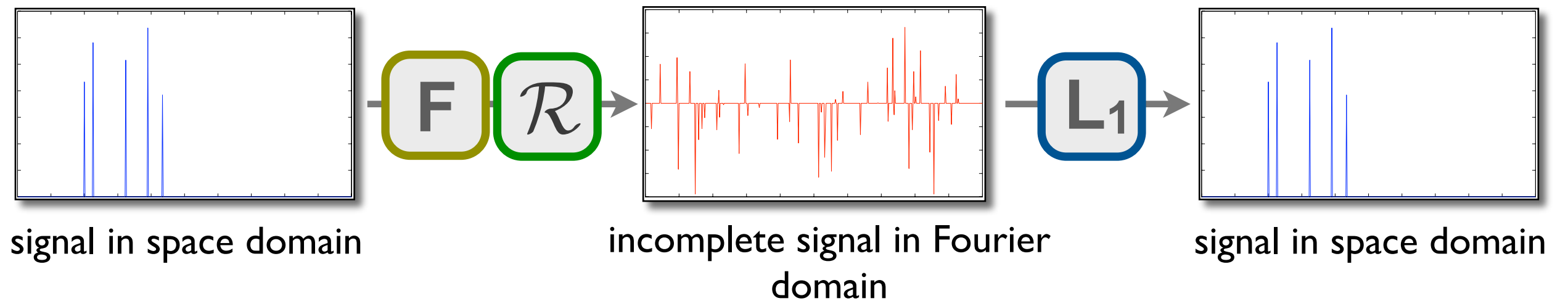


recovered signal in time domain

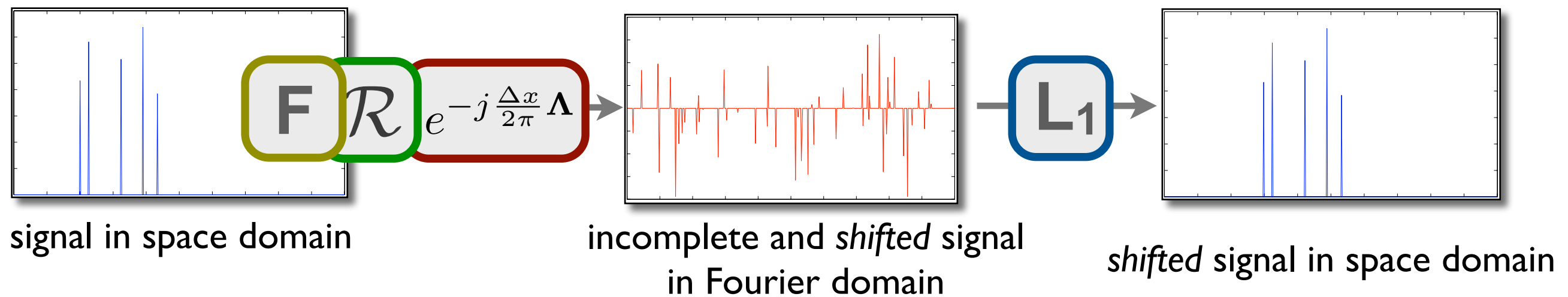




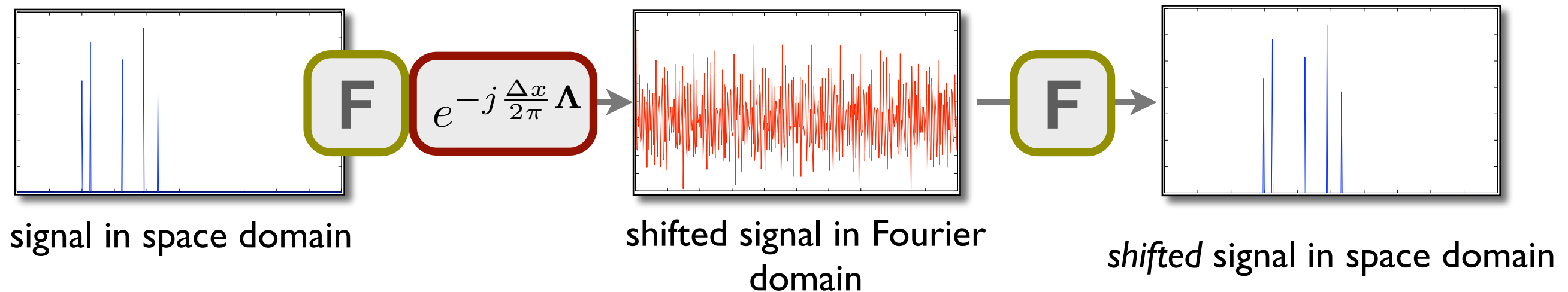
# Compressed Sensing



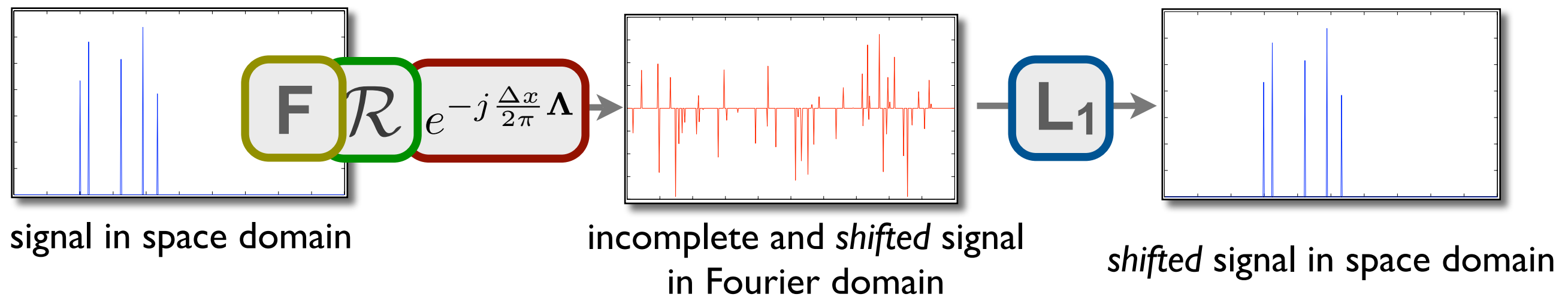
# Compressed Computations



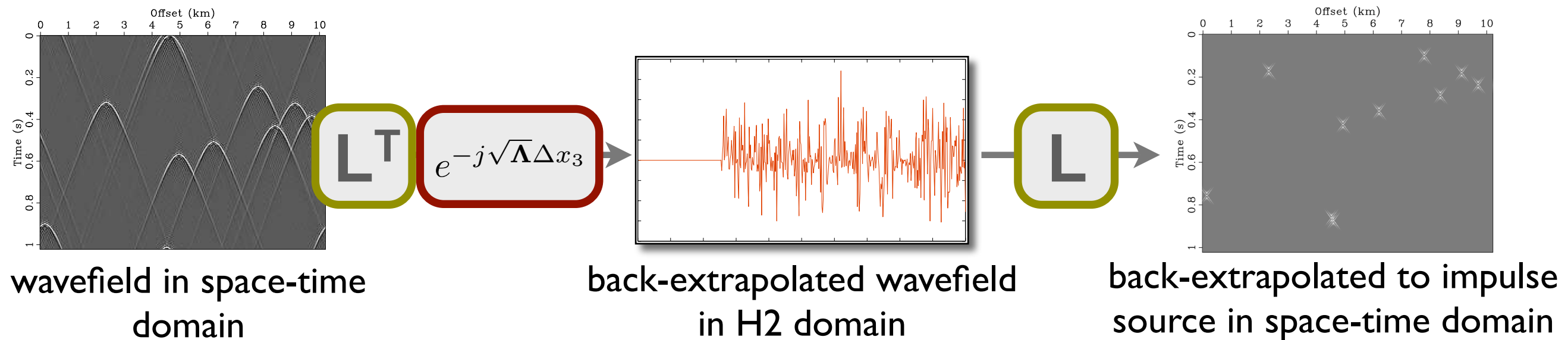
# Straightforward Computation



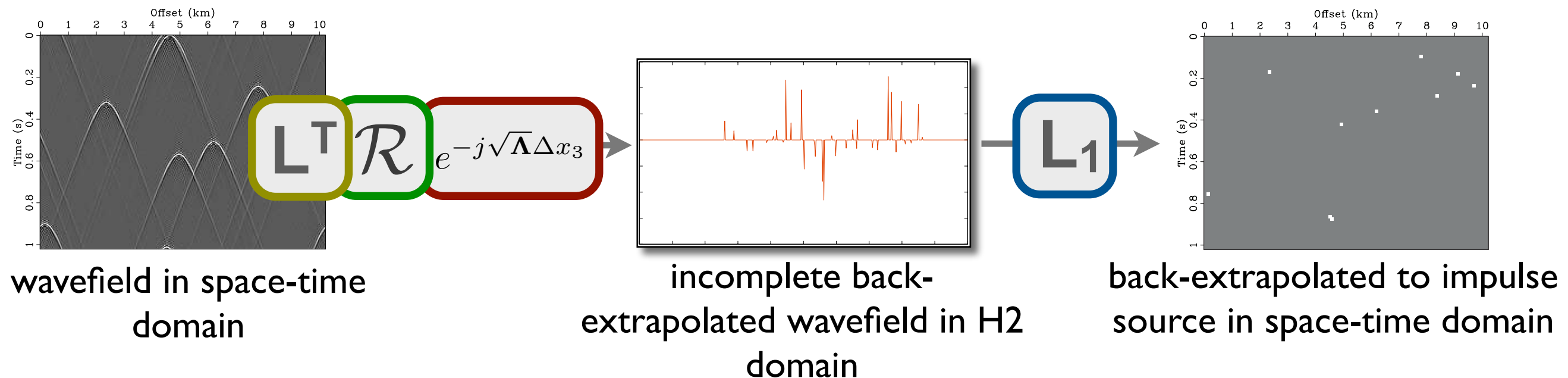
# Compressed Computation



# Straightforward 1-Way inverse Wavefield Extrapolation

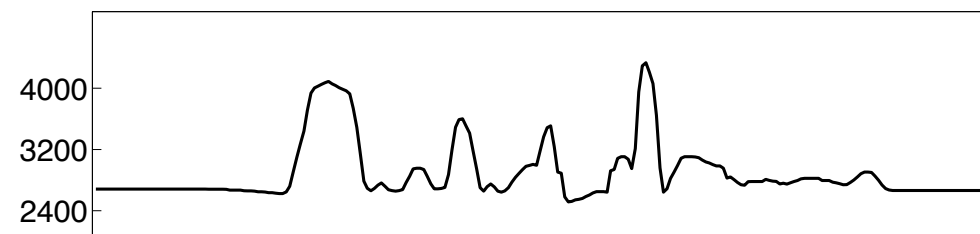
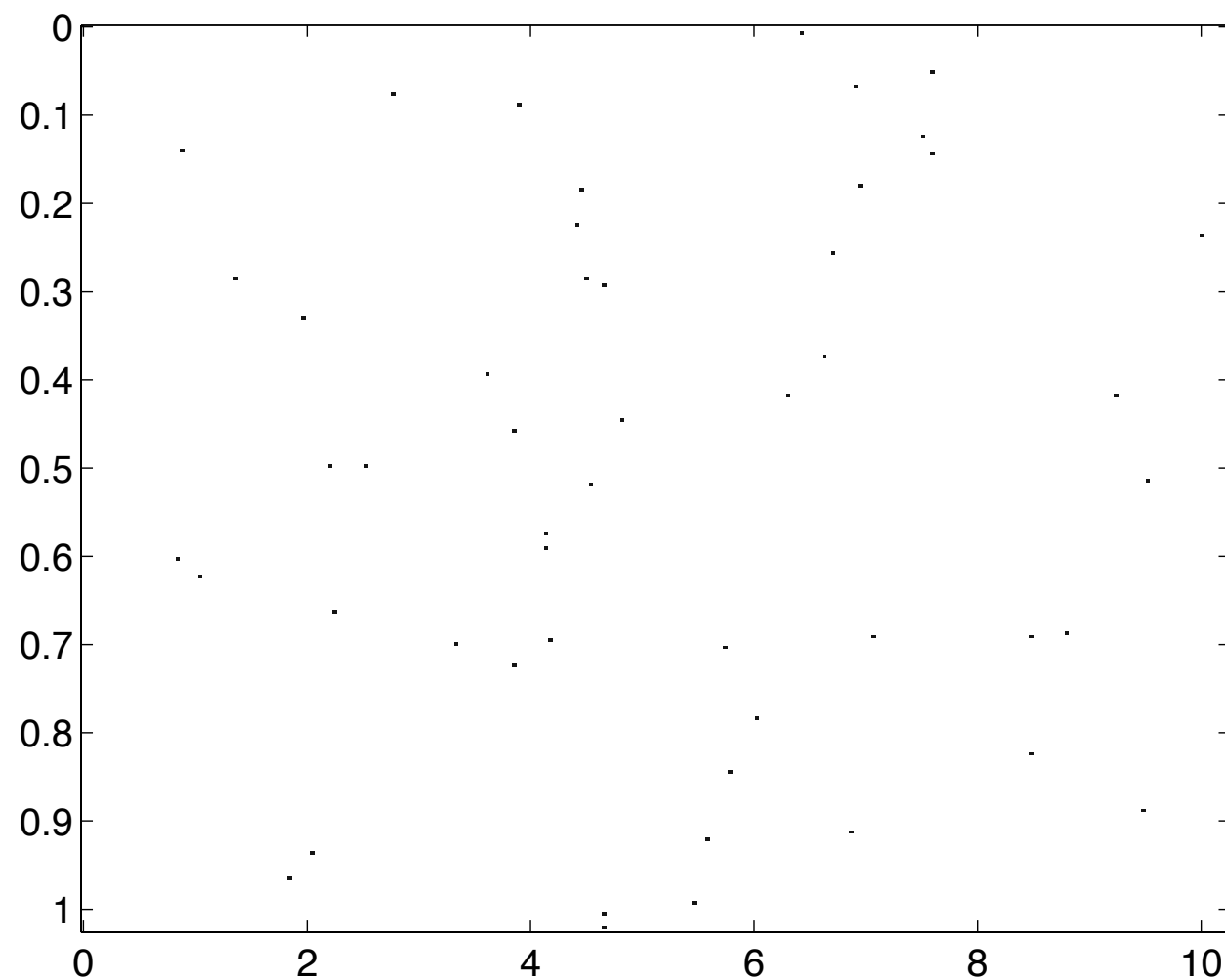


# Compressed 1-Way Wavefield Extrapolation



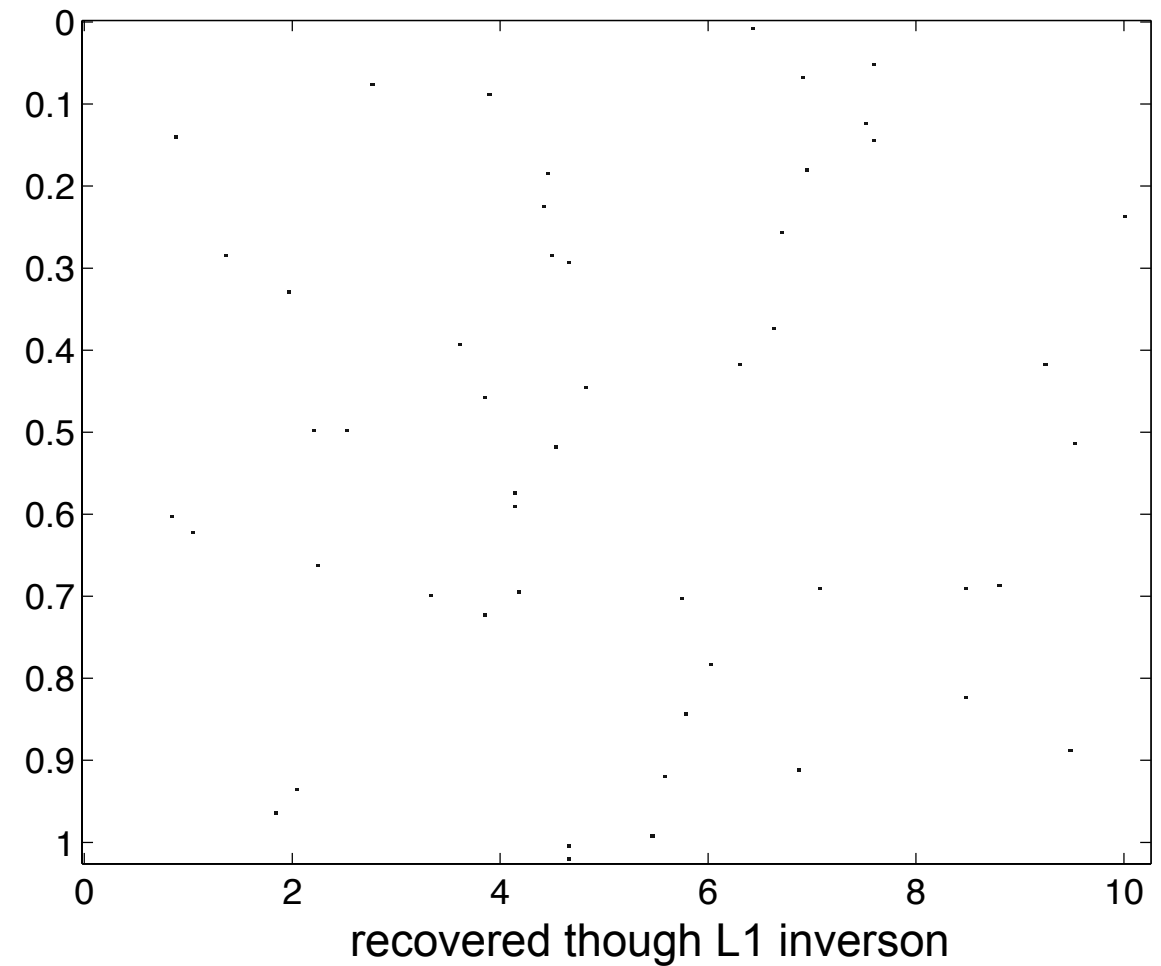
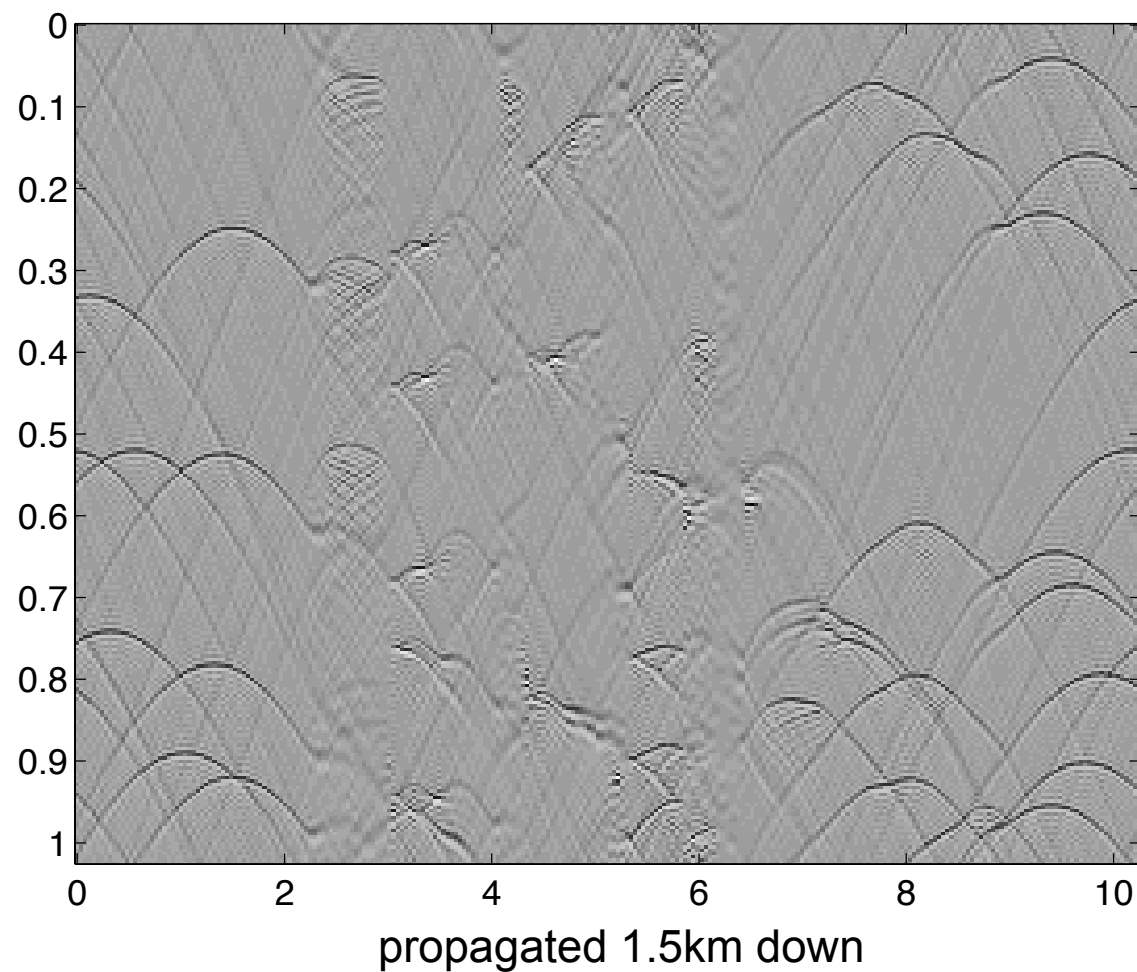
# Compressed wavefield extrapolation

simple 1-D space/time propagation example with point scatters



# Compressed wavefield extrapolation

simple 1-D space/time propagation example with point scatters



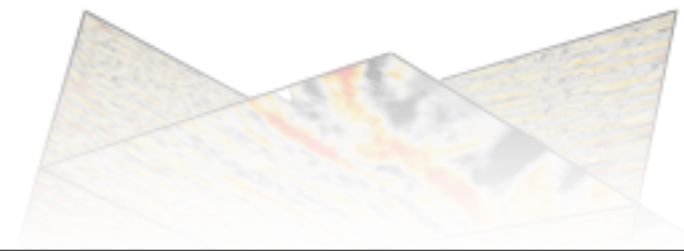
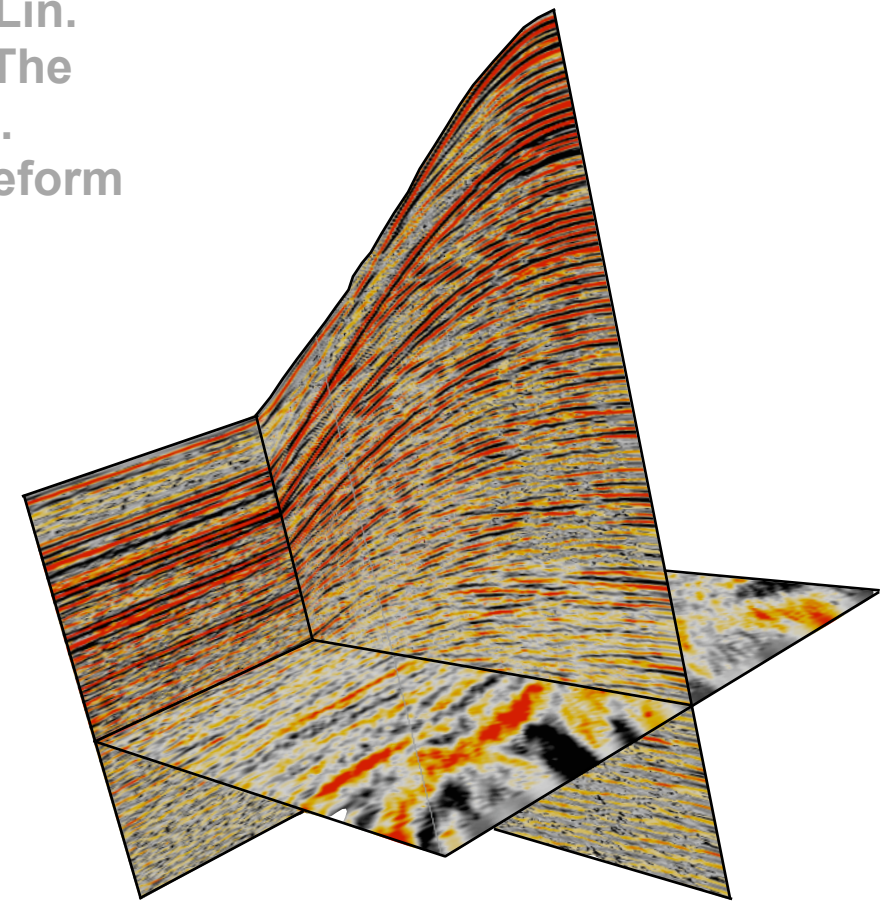
Restricted L transform to  $\sim 0.01$  of original coefficients



# Simultaneous simulation & recovery



Felix J. Herrmann, Yogi Erlangga, and Tim T. Y. Lin.  
Seismic Laboratory for Imaging and Modeling. The  
university of British Columbia Technical Report.  
TR-2008-3. Compressive simultaneous full-waveform  
simulation.



# Wavefield computations

- For  $n_s$  shots and  $n_f$  frequencies, the linear (Helmholtz) systems are independent
- The multi-shot and multi-frequency problem is embarrassingly parallel

$$\begin{bmatrix} \mathcal{H}_{\omega_1} & 0 & & \\ 0 & \mathcal{H}_{\omega_2} & \ddots & \\ & \ddots & \ddots & 0 \\ & & 0 & \mathcal{H}_{\omega_{n_f}} \end{bmatrix} \begin{bmatrix} \underbrace{[\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_{n_s}]_{\omega_1}}_{\mathbf{u}_{\omega_1}} \\ \vdots \\ \underbrace{[\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_{n_s}]_{\omega_{n_f}}}_{\mathbf{u}_{n_f}} \end{bmatrix} = \begin{bmatrix} \underbrace{[\mathbf{b}_1 \ \mathbf{b}_2 \ \cdots \ \mathbf{b}_{n_s}]_{\omega_1}}_{\mathbf{B}_{\omega_1}} \\ \vdots \\ \underbrace{[\mathbf{b}_1 \ \mathbf{b}_2 \ \cdots \ \mathbf{b}_{n_s}]_{\omega_{n_f}}}_{\mathbf{B}_{n_f}} \end{bmatrix}$$

$$\mathcal{H}_{\omega_j} := \mathcal{H}(\omega_j), \quad \omega_j = 2\pi j \Delta f, \quad j = 1, \dots, n_f$$

$\Delta f$  frequency sample interval

# Wavefield computations

---

$$\overbrace{\begin{bmatrix} \mathcal{H}_{\omega_1} & 0 & & \\ 0 & \mathcal{H}_{\omega_2} & \ddots & \\ & \ddots & \ddots & 0 \\ & & 0 & \mathcal{H}_{\omega_{n_f}} \end{bmatrix}}^{\mathbf{H}} \overbrace{\begin{bmatrix} \mathbf{U}_{\omega_1} \\ \mathbf{U}_{\omega_2} \\ \vdots \\ \mathbf{U}_{n_f} \end{bmatrix}}^{\mathbf{U}} = \overbrace{\begin{bmatrix} \mathbf{B}_{\omega_1} \\ \mathbf{B}_{\omega_2} \\ \vdots \\ \mathbf{B}_{n_f} \end{bmatrix}}^{\mathbf{B}}$$

$\Downarrow$

$$\mathbf{H}\mathbf{U} = \mathbf{B}$$

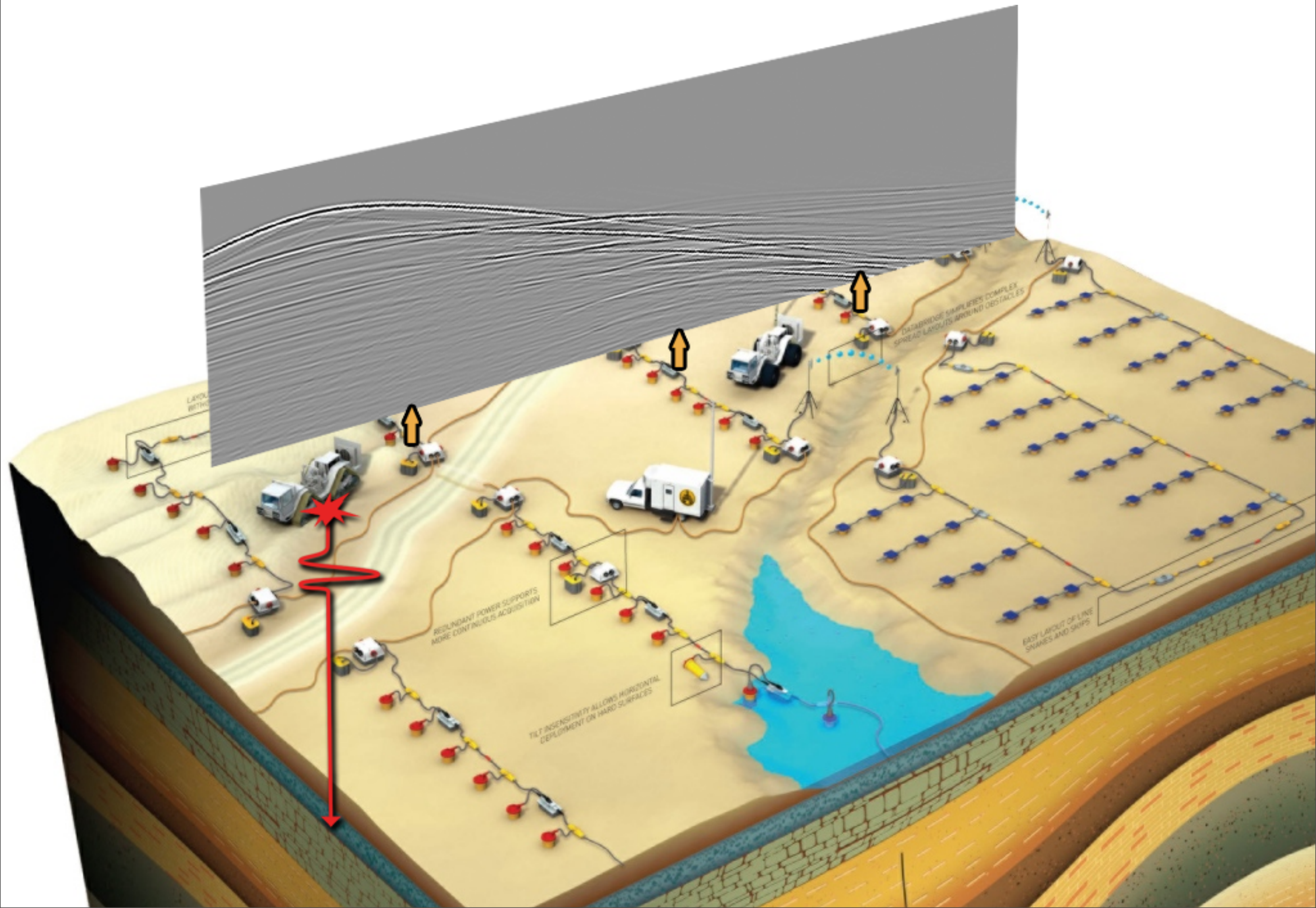
- Natural for CS setting!





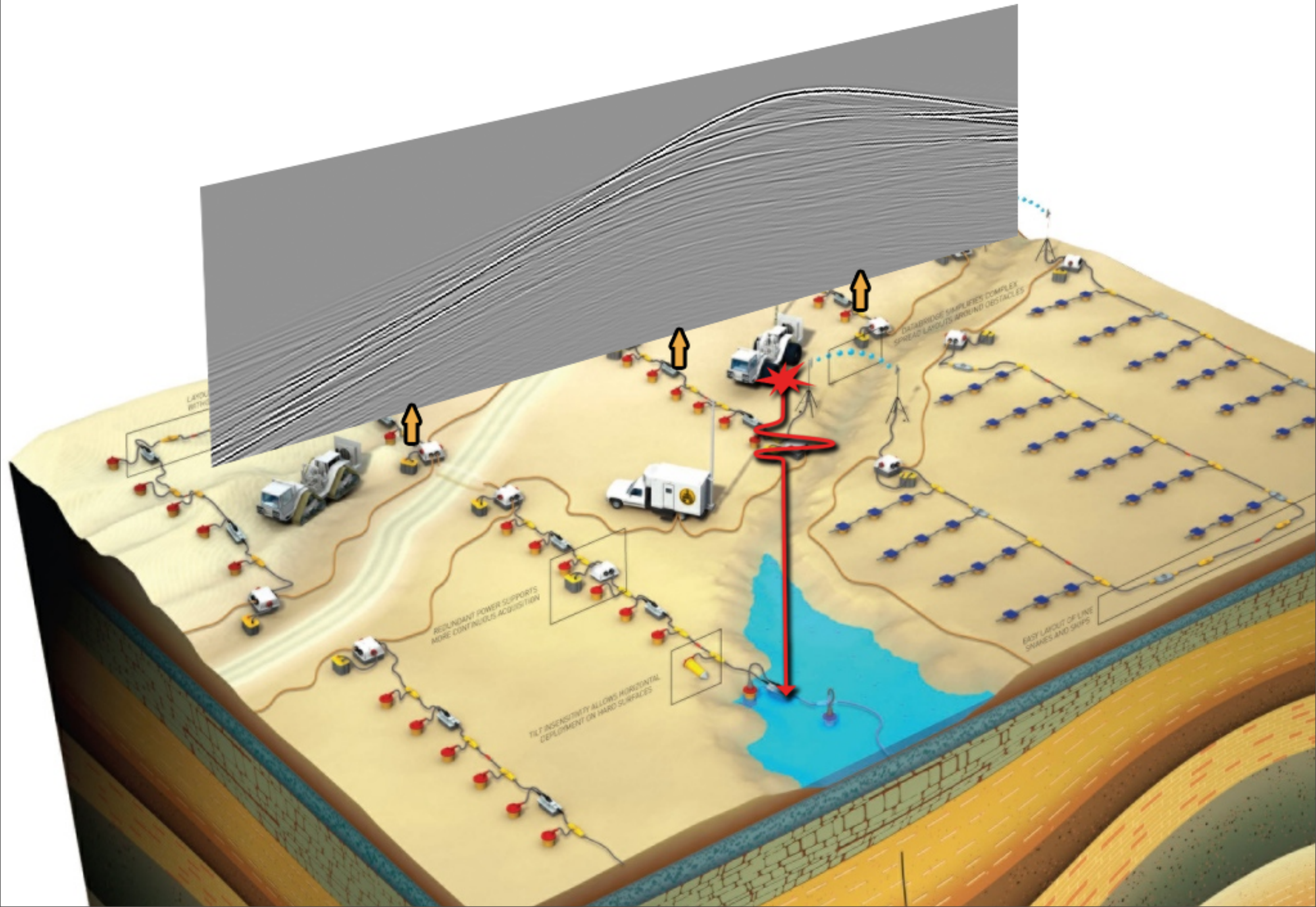


# Individual shots



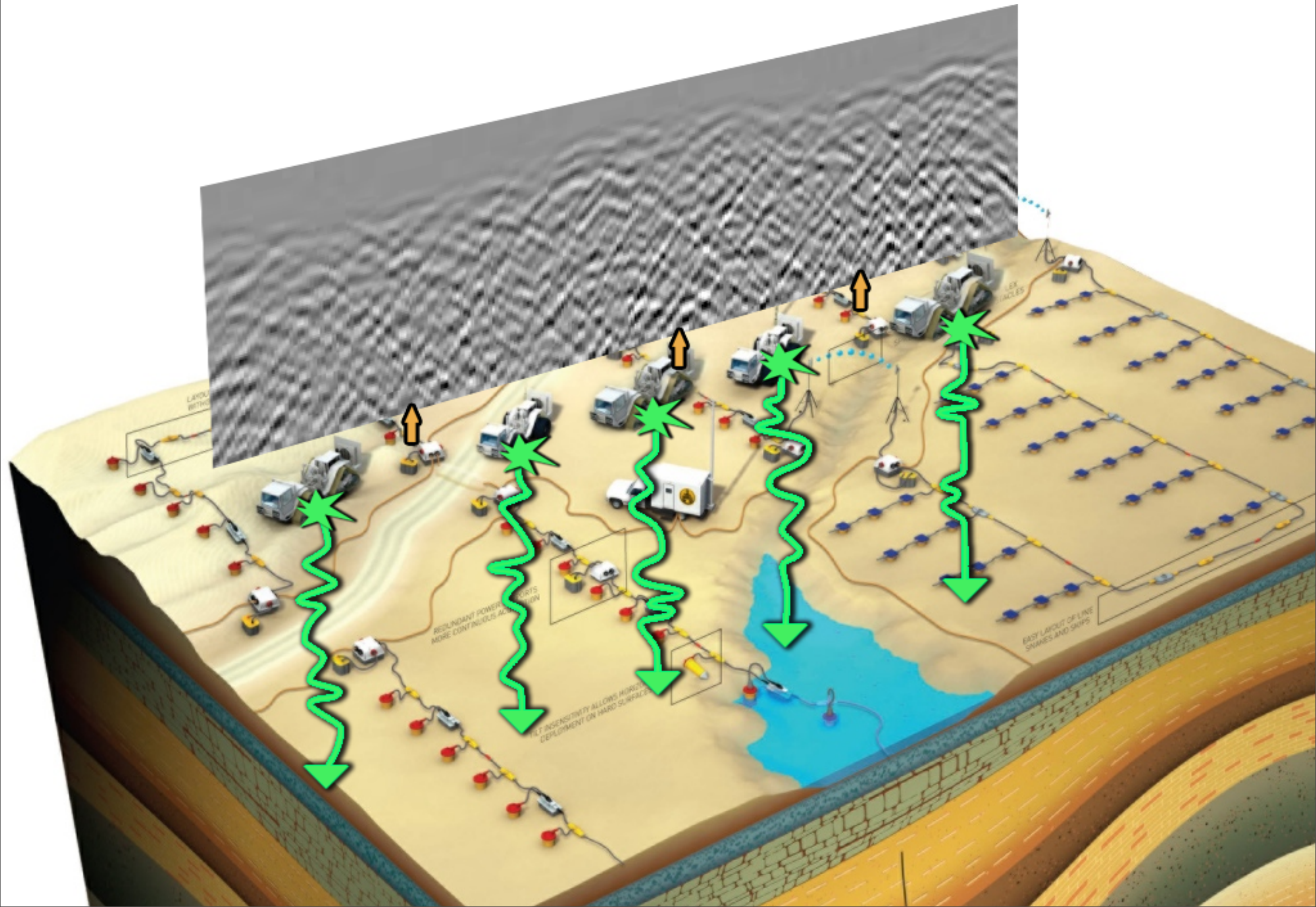


# Individual shots





# Simultaneous & continuous shots



# Simultaneous modeling & acquisition

---

- **Current paradigm:**
  - *separate* single-source experiments in the field
  - *separate* single-shot simulations in the computer
  - **Con:** expensive
- **New paradigm:**
  - *simultaneous & continuous* source experiments in the field
  - *simultaneous* (continuous) simulations in the computer
  - **continuous** simultaneous simulations are equivalent to **multiple** simultaneous experiments
  - **Con:** *postprocessing necessary to separate into individual shots*
- **Key observation: this is *really* another instance of CS ...**
  - **design new simultaneous acquisitions & recovery schemes!**

# CS sampling of frequencies and shots (rhs)

## ● CS with Random Convolution (Romberg '08)

- Replace Gaussian matrix along shots with restricted **random convolution** over the whole seismic data
- CS with 3D Fourier Transform  $\mathbf{F}_3$  and multiply each coefficient with a unit-norm complex number of randomly determined phase, followed by inverse 2D Fourier on shot-receiver plane, then restrict in both temporal-frequency and shot coordinates

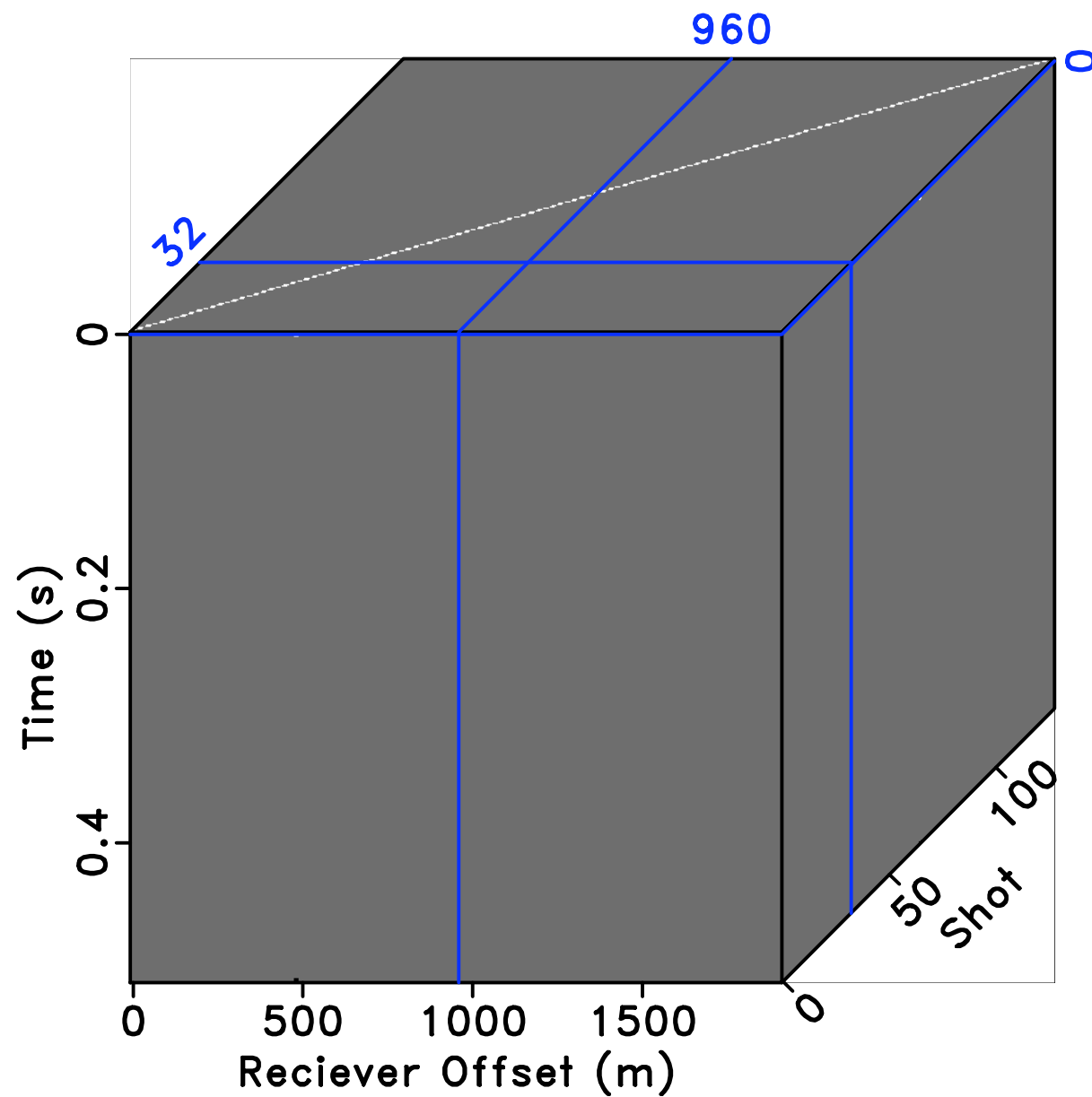
$$\mathbf{RM} = \overbrace{\begin{bmatrix} \mathbf{R}_1^\Sigma \otimes \mathbf{I} \otimes \mathbf{R}_1^\Omega \\ \vdots \\ \mathbf{R}_{n_{s'}}^\Sigma \otimes \mathbf{I} \otimes \mathbf{R}_{n_{s'}}^\Omega \end{bmatrix}}^{\text{sub sampler}} \overbrace{\left( \mathbf{F}_2^* \text{diag} \left( e^{i\hat{\theta}} \right) \otimes \mathbf{I} \right) \mathbf{F}_3,}^{\text{random phase encoder}}$$

$$\theta_w = \text{Uniform}([0, 2\pi])$$

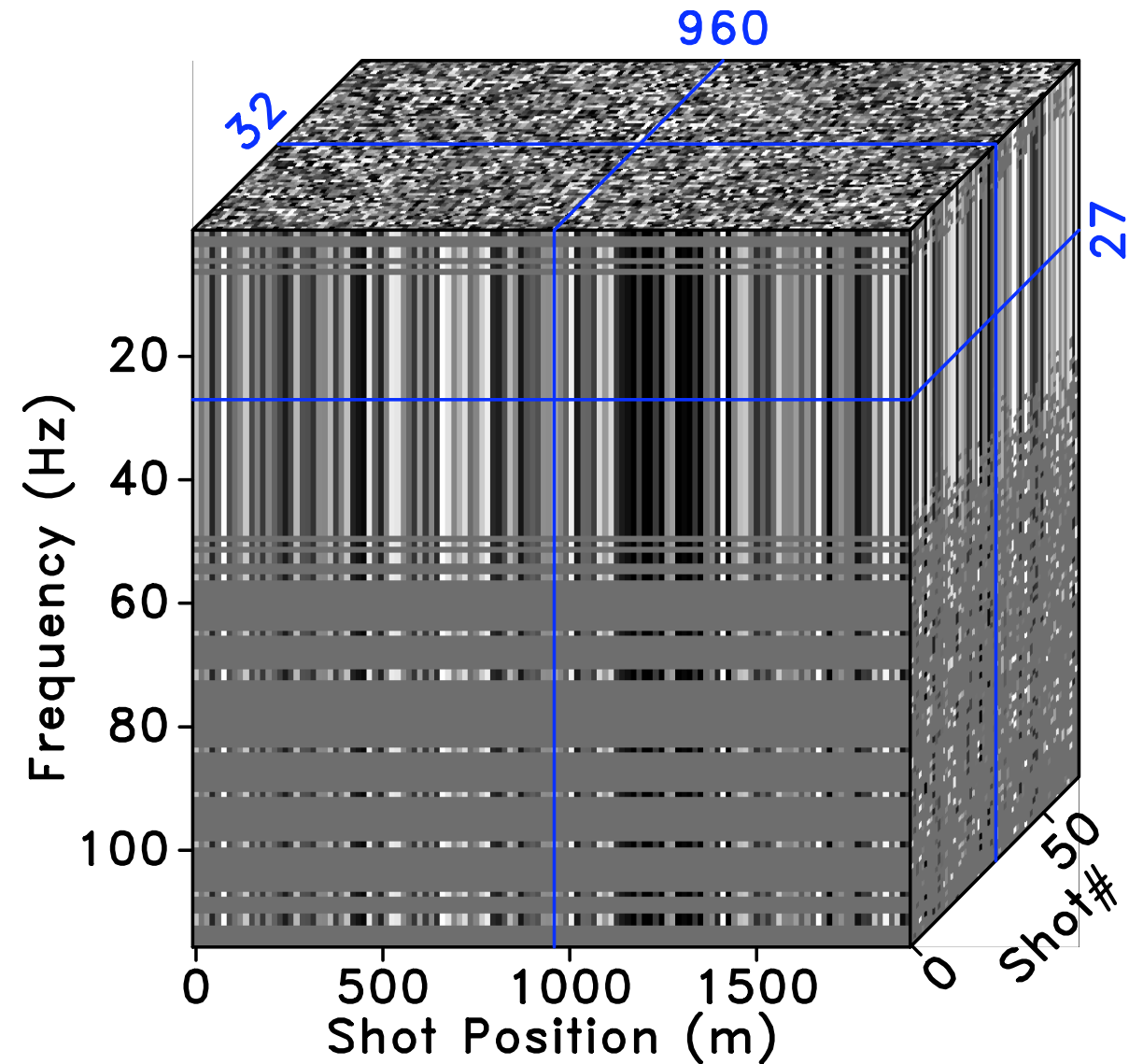


# Applying to Shot Sources

separated source



compressed source





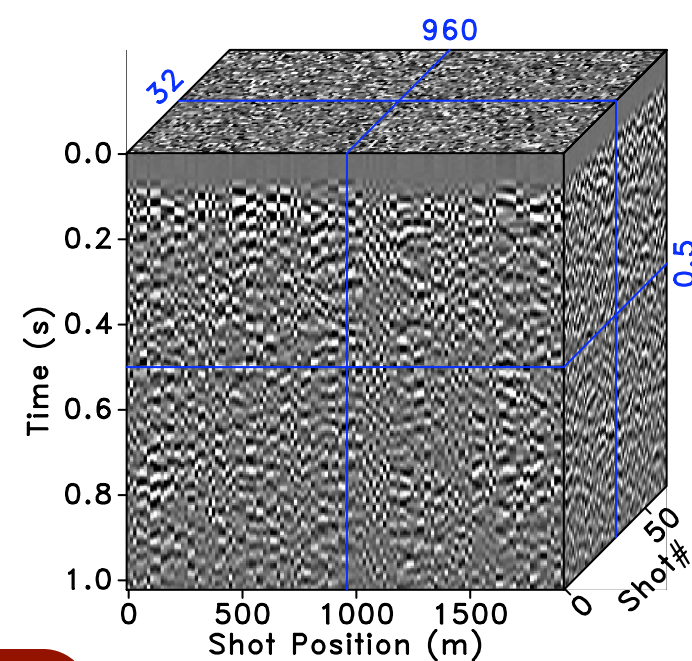
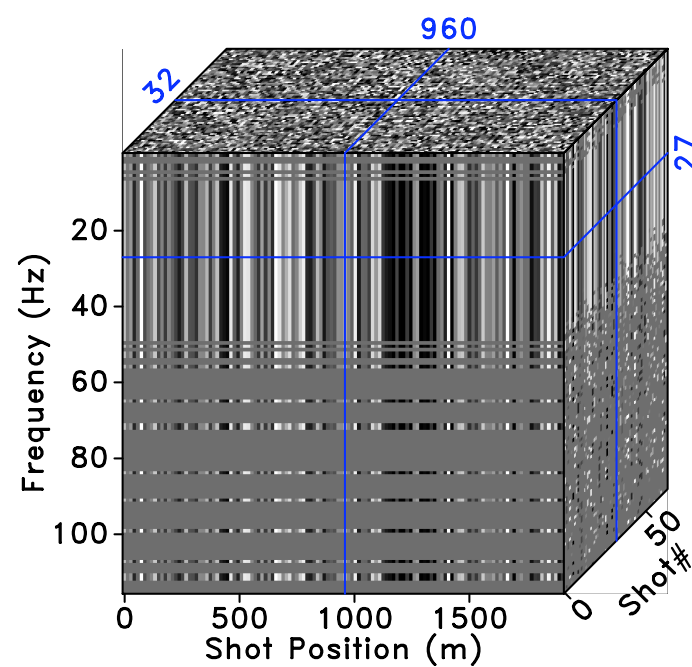
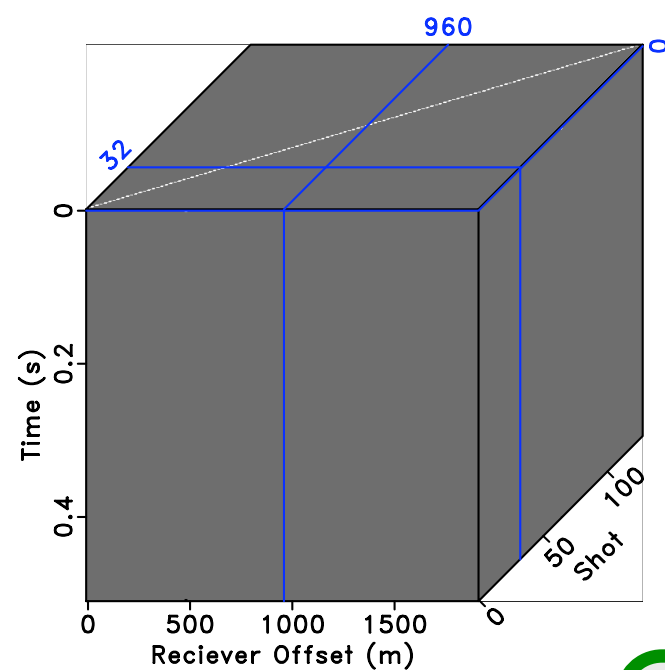
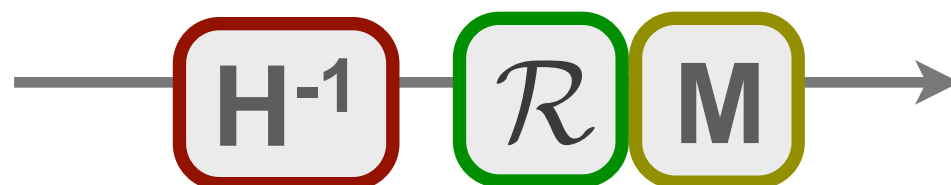
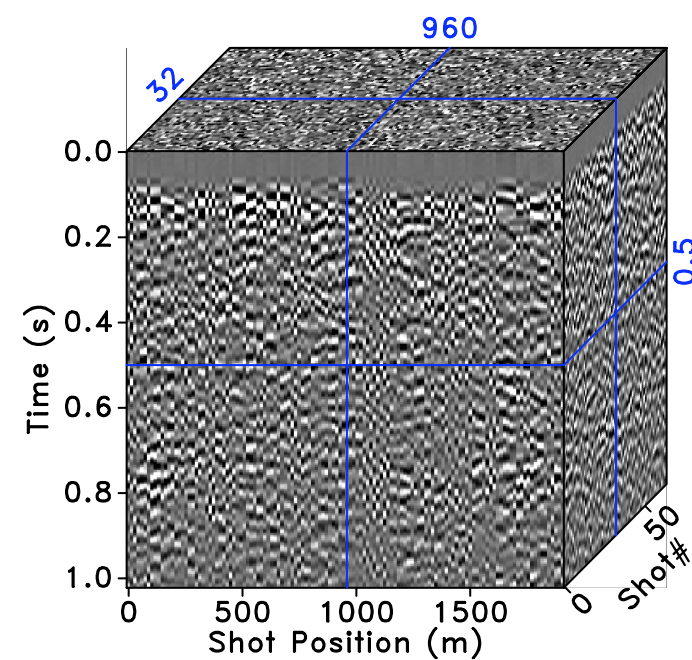
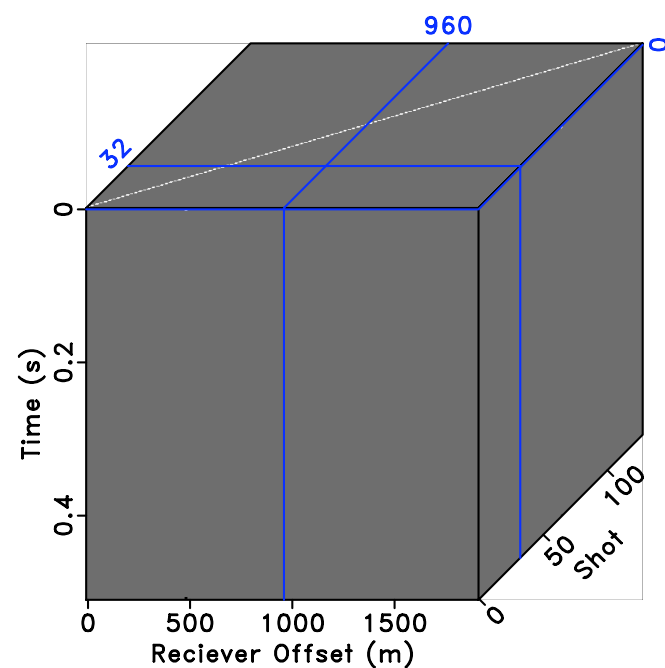
# Equivalence

Show equivalence between

- CS sampling of **full** solution for separate single-source (sweep) experiments
- Solution of **reduced** system after CS sampling the collective single-shot source wavefield => **simultaneous source experiments**

$$\left\{ \begin{array}{l} \mathbf{B} = \mathbf{D}^* \underbrace{\mathbf{s}}_{\text{single shots}} \\ \mathbf{H}\mathbf{U} = \mathbf{B} \\ \mathbf{y} = \mathbf{R}\mathbf{M}\mathbf{D}\mathbf{U} \end{array} \right. \iff \left\{ \begin{array}{l} \underline{\mathbf{B}} = \underline{\mathbf{D}}^* \underbrace{\mathbf{R}\mathbf{M}\mathbf{s}}_{\text{simul. shots}} \\ \underline{\mathbf{H}}\mathbf{U} = \underline{\mathbf{B}} \\ \underline{\mathbf{y}} = \underline{\mathbf{D}}\mathbf{U} \end{array} \right.$$

Show that  $\mathbf{y} = \underline{\mathbf{y}}$ .



# CS

$$\mathbf{P}_1 : \begin{cases} \mathbf{y} &= \mathbf{R}\mathbf{M}\mathbf{d} \\ \tilde{\mathbf{x}} &= \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{subject to} \quad \mathbf{A}\mathbf{x} = \mathbf{y} \\ \mathbf{A} &= \mathbf{R}\mathbf{M}\mathbf{S}^* \\ \tilde{\mathbf{d}} &= \mathbf{S}^* \tilde{\mathbf{x}} \end{cases}$$

CS provides conditions under which  $\mathbf{P}_1$  recovers  $\mathbf{d}$ :

- selection of CS-matrix (Measurement & Restriction matrices)
- ***selection of sparsifying transform***

Additional complications

- large-to-extremely large problem size
- projected gradient with root finding method (SPG $\ell_1$ , Friedlander & van den Berg, '07-'08)
- CS matrix has to lead to *physically **realizable*** source wavefield for modeling & acquisition

# Composite sparsity transform

Using Curvelet transform for shot and receiver coordinates

- **Frequency-domain** restrictions perform well under **Wavelet** transform for seismic data (Lin et. al. '08)
- **Spatial-domain** restrictions perform well under **Curvelet** transform for seismic data (Hennefent et. al. '07)

**Combine both transforms in the coordinate they are most suited for**

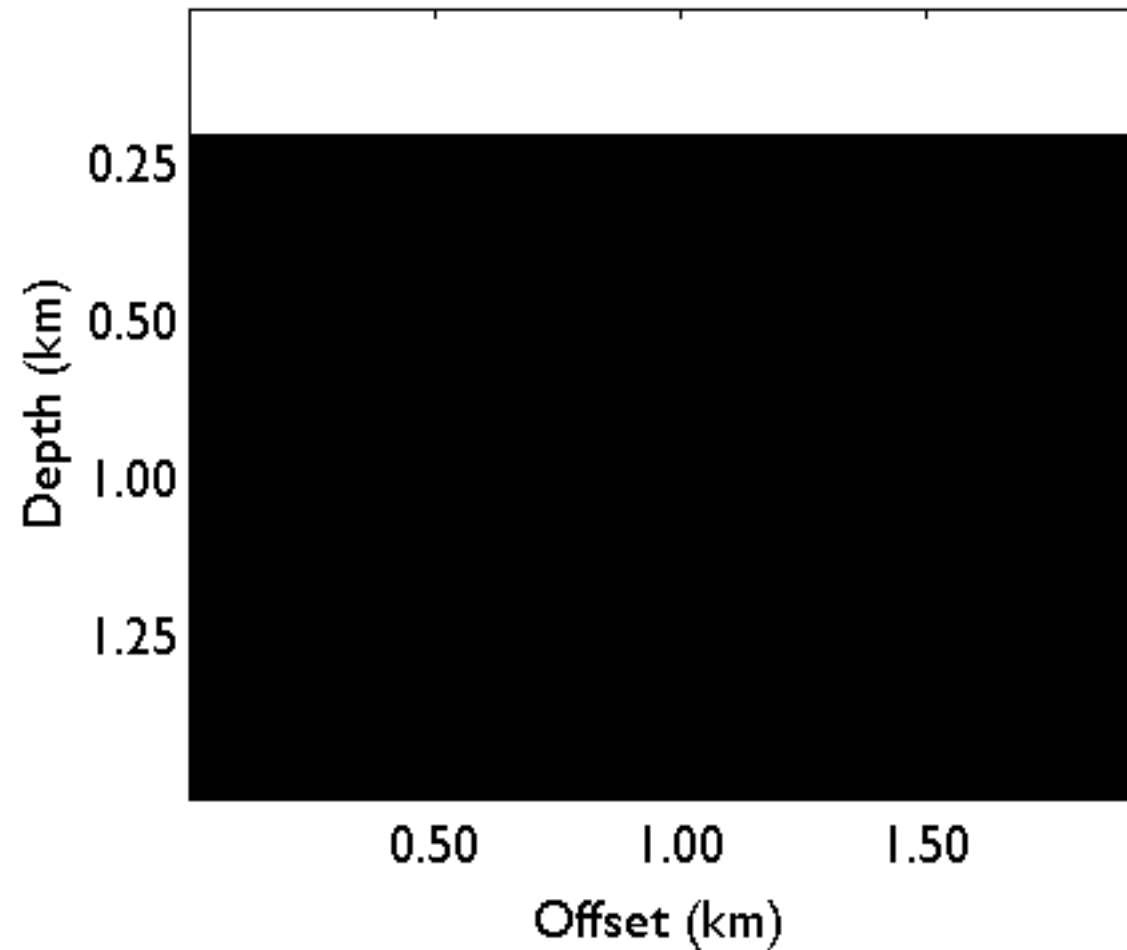
- Wavelet sparsity on temporal-frequency coordinate
- 2D Curvelet sparsity on shot and receiver plane

$$\mathbf{S} = \mathbf{C}_{2d} \otimes \mathbf{W}$$

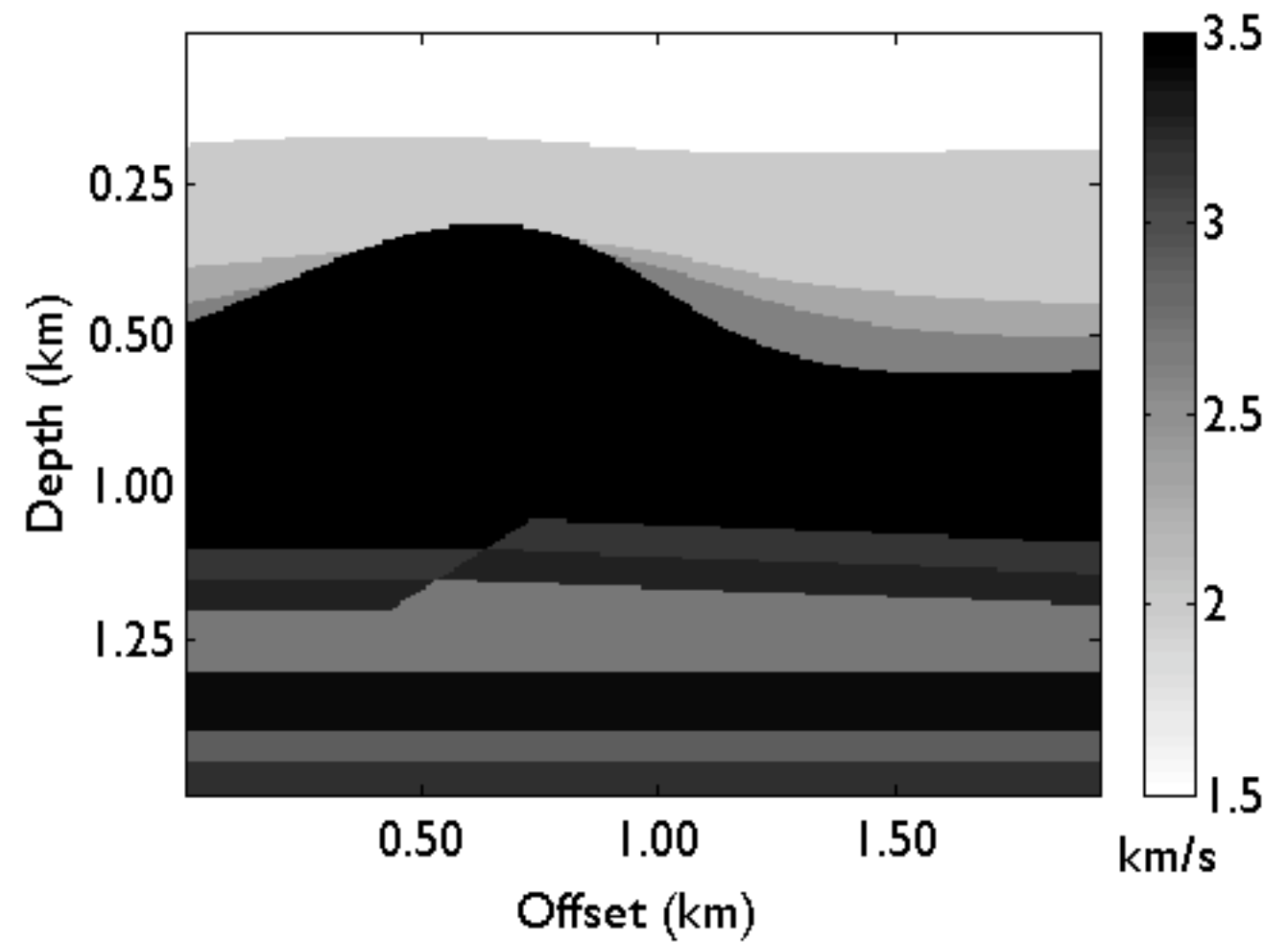
Complexity  $\mathcal{O}(n^3 \log n)$

# Velocity models

simple model

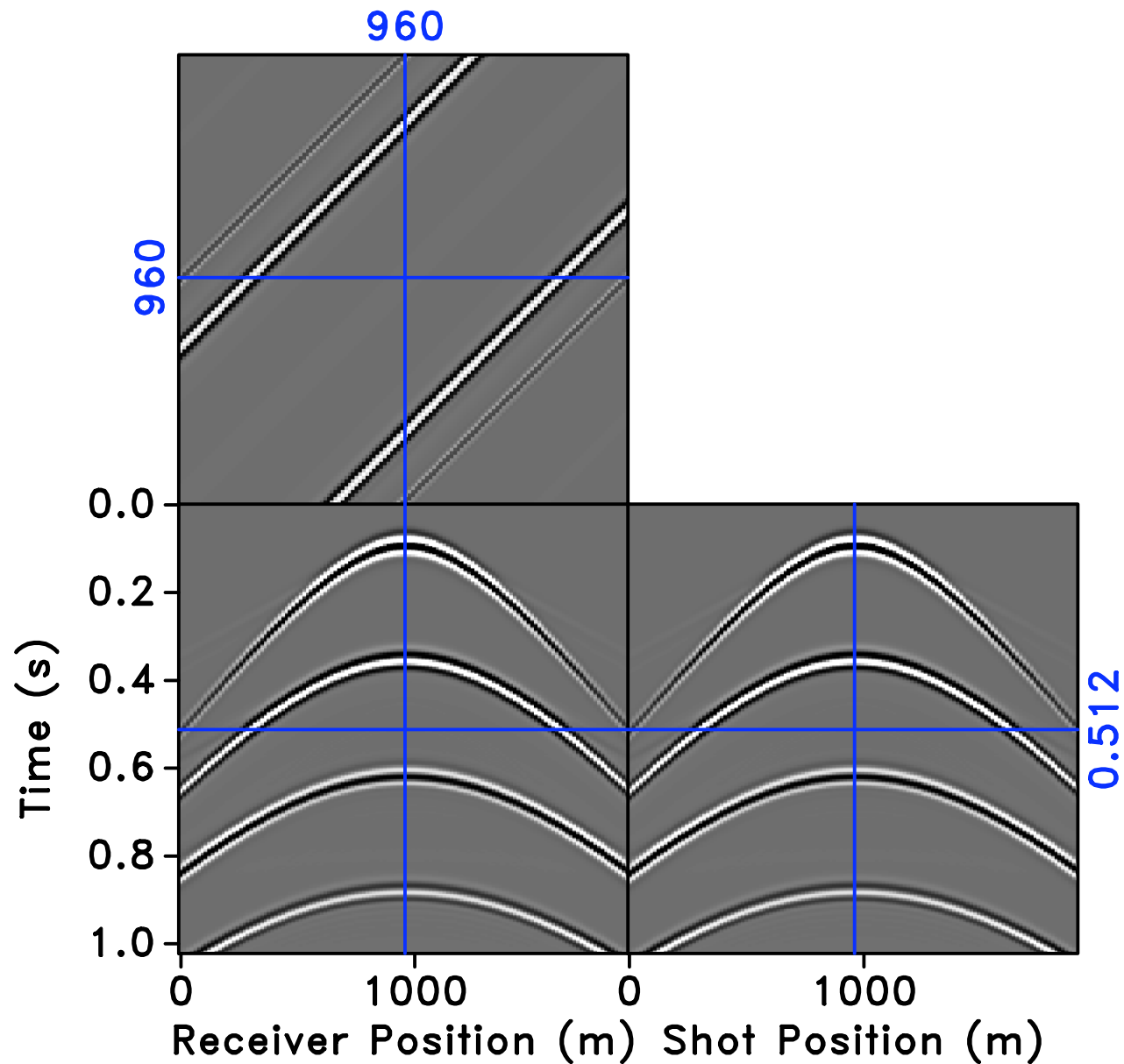


complex model

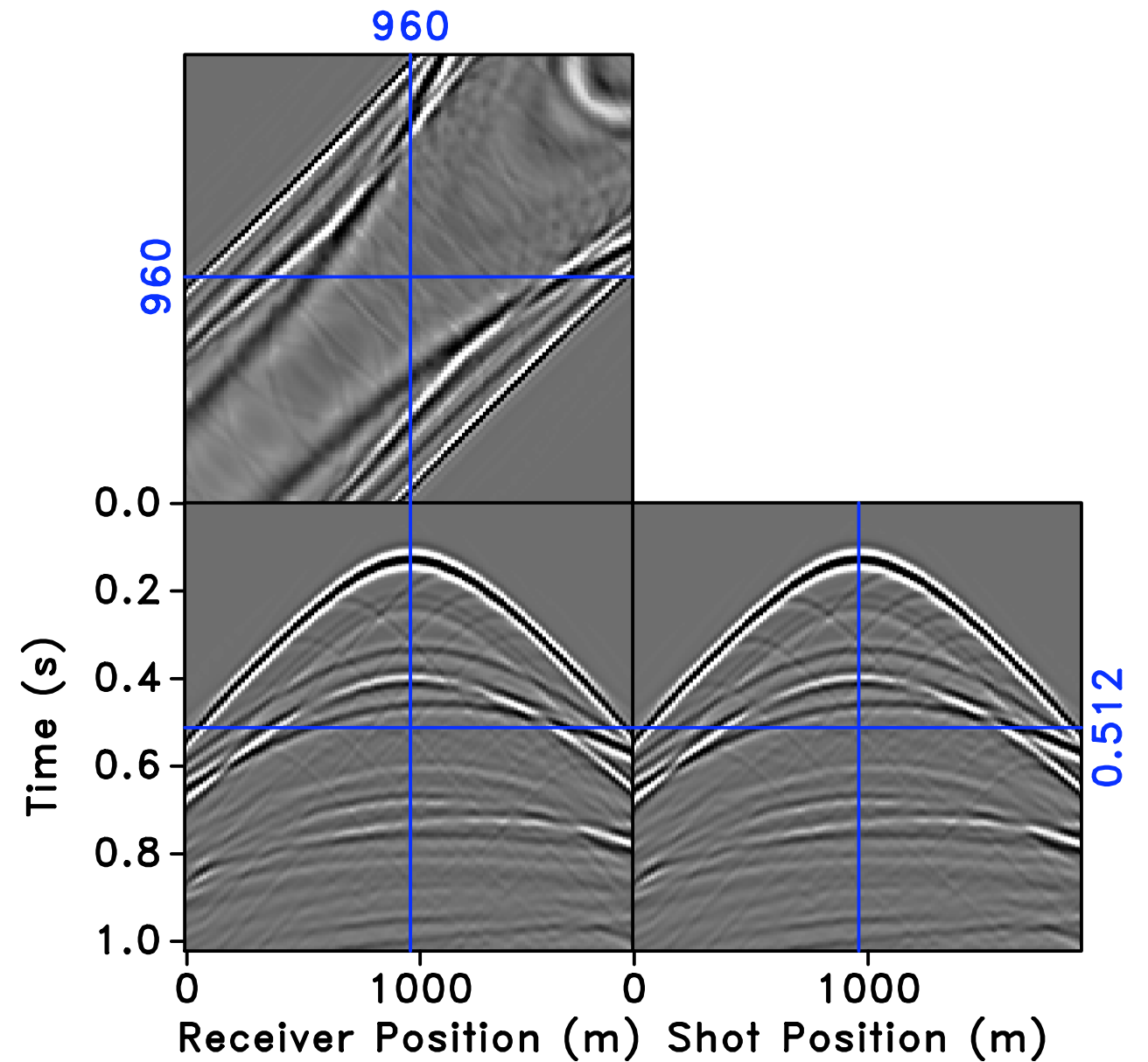


# Green's functions

simple model



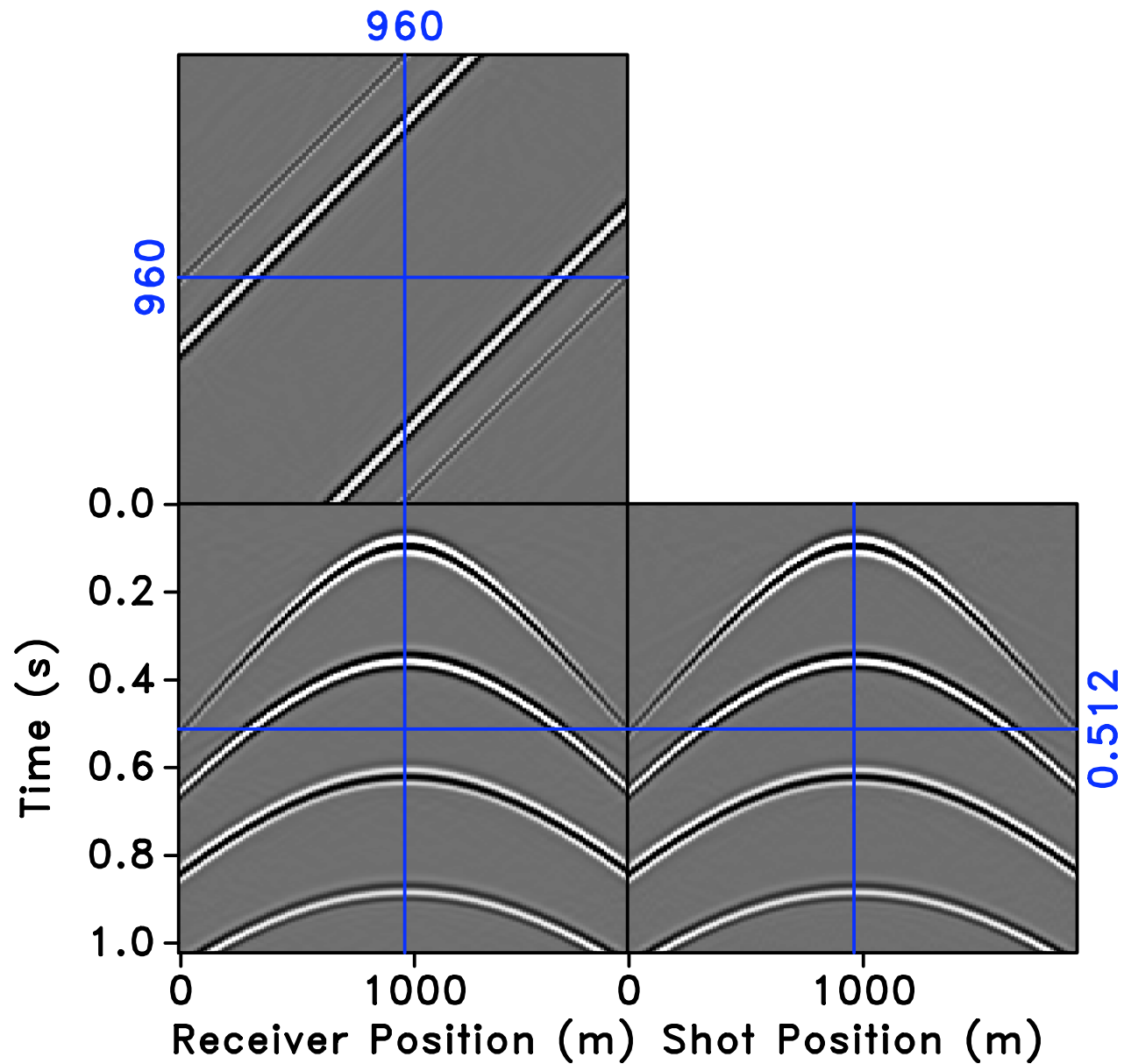
complex model





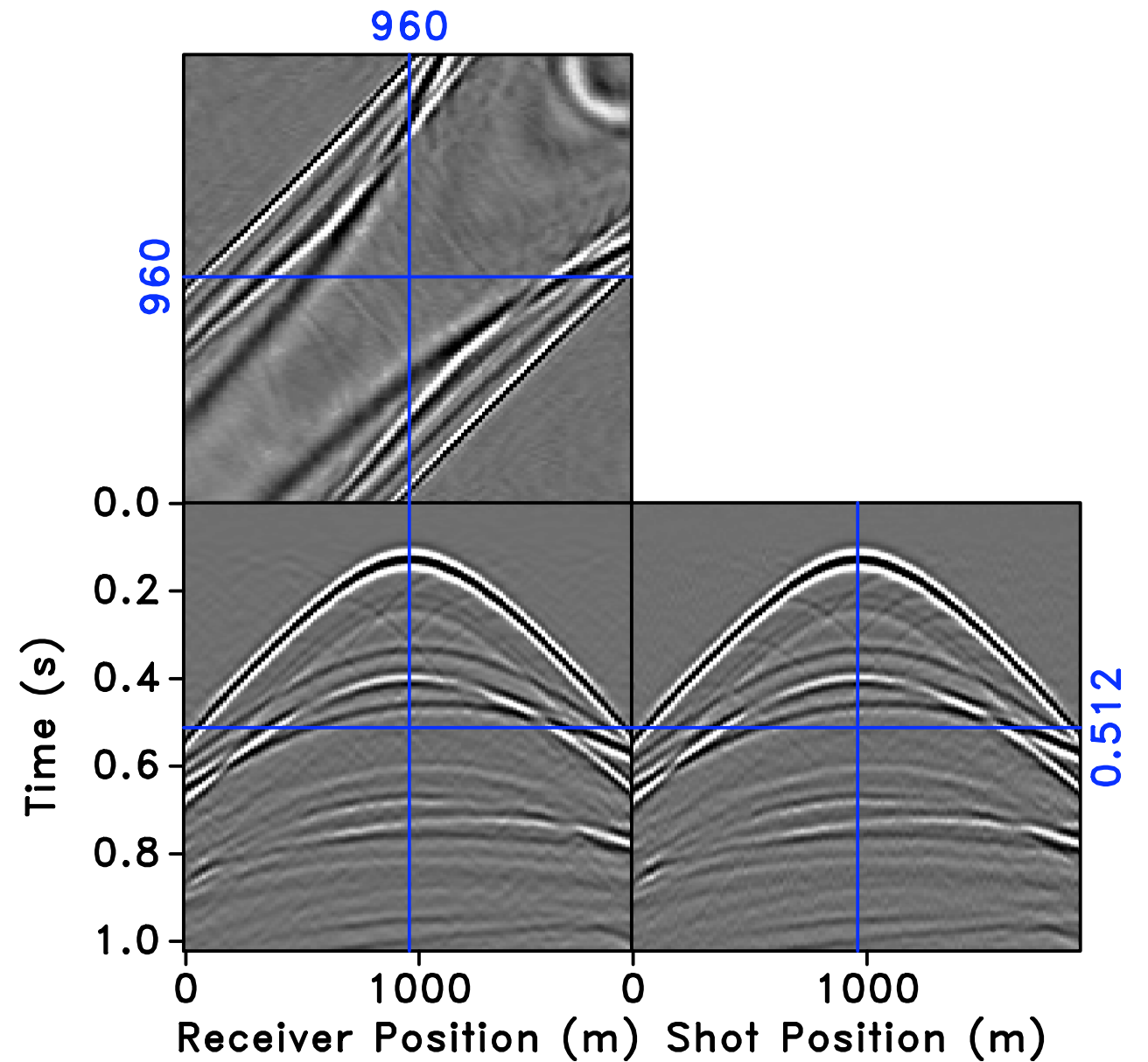
# Recovered data

simple model



28.1dB

complex model

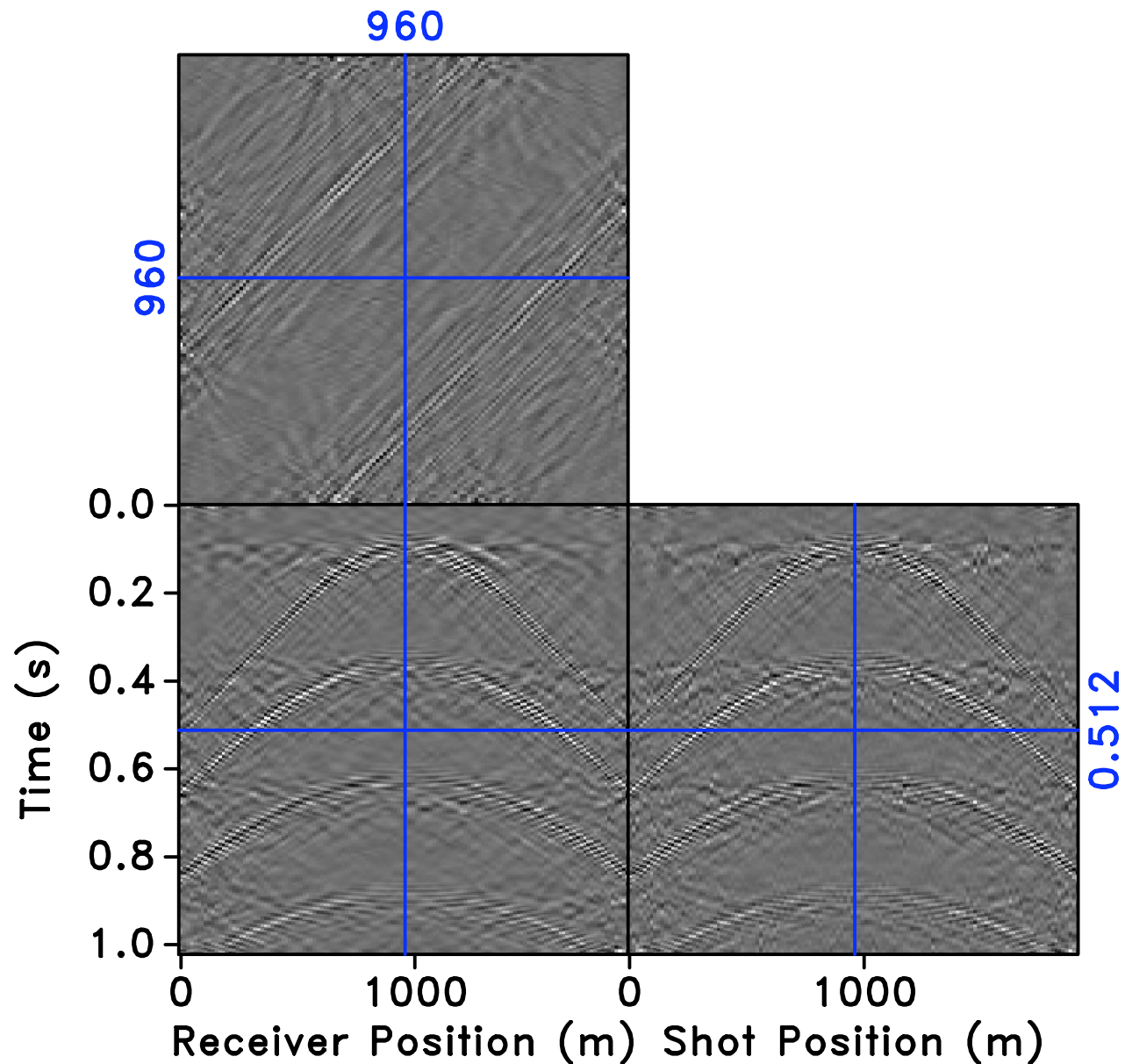


18.2dB

300 SPGL1 iteration

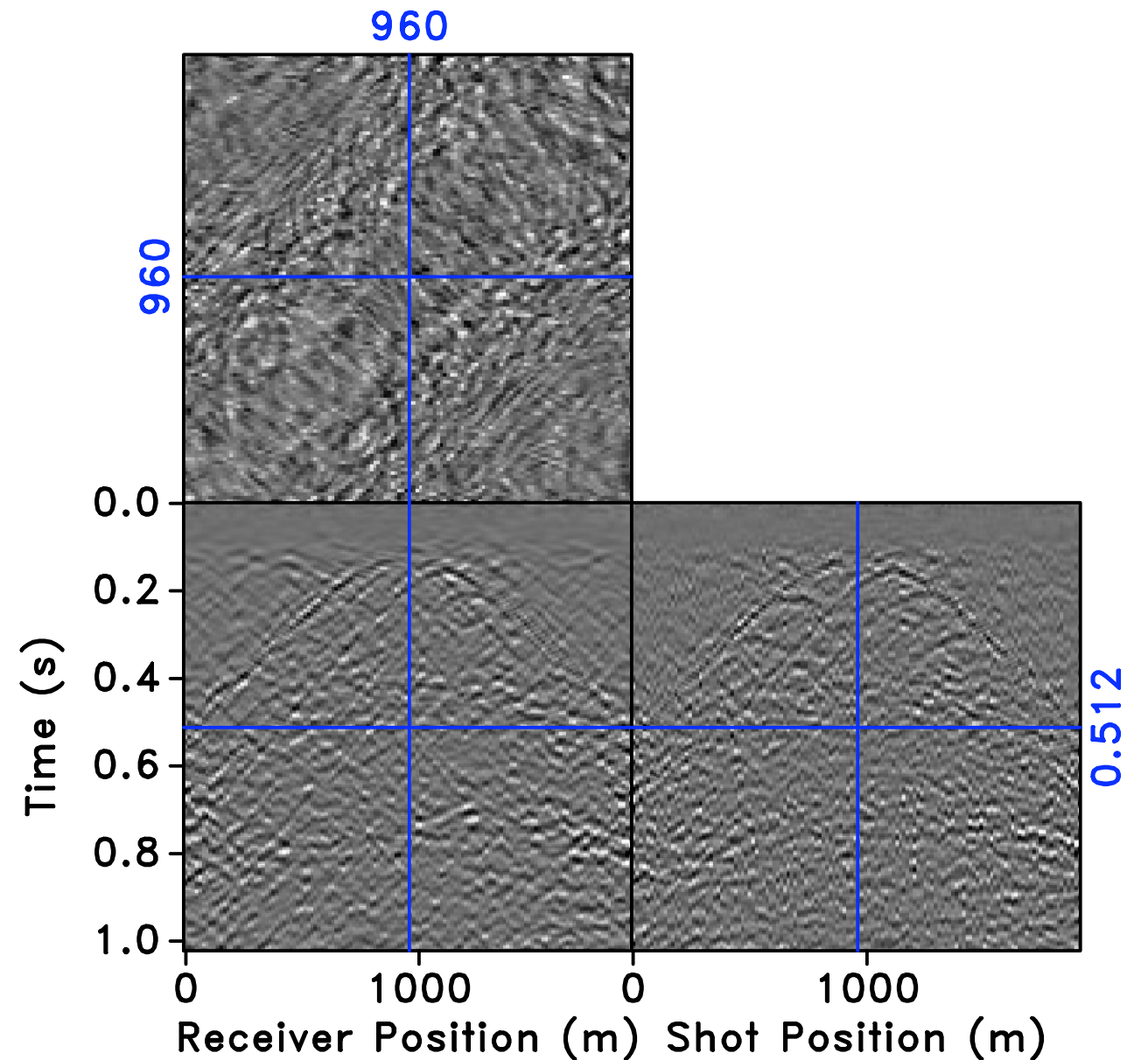
# Difference

simple model



28.1dB

complex model



18.2dB

300 SPGL1 iteration

# Conclusions & outlook

---

- **CS** provides a **new linear sampling paradigm**
  - **degree** of *subsampling commensurate* with transform-domain **sparsity**
  - subsampling of seismic data volumes
    - missing source-receiver locations
    - simultaneous acquisition
  - *subsampling* of solutions to PDEs
- **CS** leads to
  - acquisition of *smaller* data volumes that carry the **same information** or
  - to **improved inferences** from data using the *same* resources
- Bottom line: **acquisition & numerical modeling costs** are **no longer** determined by the **size** of the **discretization** but by the **transform-domain compressibility** of the **solution ...**

# Acknowledgments

---

- E. van den Berg and M. P. Friedlander for *SPGL1* ([www.cs.ubc.ca/labs/scl/spgl1](http://www.cs.ubc.ca/labs/scl/spgl1)) & *Sparco* ([www.cs.ubc.ca/labs/scl/sparco](http://www.cs.ubc.ca/labs/scl/sparco))
- Sergey Fomel and Yang Liu for Madagascar ([rsf.sf.net](http://rsf.sf.net))
- E. Candes and the Curvelab team

This work was carried out as part of the SINBAD project with financial support from the collaborative research & development (CRD) grant DNOISE (334810-05) funded by the Natural Science and Engineering Research Council (NSERC) and matching contributions from BG, BP, Chevron, ExxonMobil and Shell.

**`slim.eos.ubc.ca`**

**and... Thank you!**